# Panasonic ideas for life



Matsushita

Programmable Controller FP-e

## The universal compact PLC

Do this, do that, do everything.

# **All in One!**



#### 3-color Display

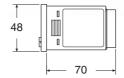
Simple characters and numerical values can be displayed. Simple messages as well as timer/counter settings and elapsed values can also be displayed.

#### Built-in operation switch

Setting values can be changed. The operation switch can also be used as an input.

#### Compact

Panel mountable, little space is taken up on the control panel. The size is only  $48 \times 48 \times 70$  mm (behind faceplate).



- Matches FP0 intelligence (equivalent to FP0-C14)
- Panel mounted type

   (in accordance with IP66,
   IEC standard)

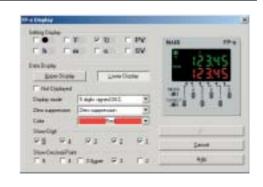
To match panel design, a black faceplate is available.



### Same programming tools used as with the FP Series

#### One programming software for all PLC types

Programming software and cables are common for all FP Series PLCs, so that any program created for the FP Series can be used by the FP-e as well. FPWIN Pro Ver.5 and FPWIN GR from Ver.2.3 offer a dialog to configure the screen display of the FP-e easily. You can check the result of the configuration directly with the display in the dialog.



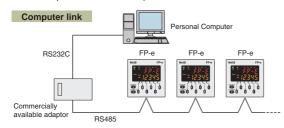


# Optimised for a wide range of applications

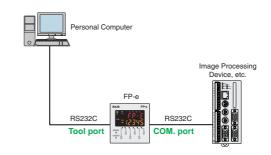
#### Equipped with RS485 and RS232C interfaces

#### Up to 99 computer link stations are possible with RS485. (RS485 type)

Up to 32 computer link stations are possible using a C-NET adaptor and up to 99 are possible using a commercially available adaptor. You can easily monitor operation status or perform control.



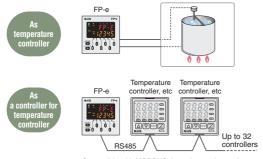
#### With RS232C, communication with up to two ports is possible. (RS232C type)



#### Can even handle temperature control

#### Two-point K-type thermocouple (-30 to 300°C) connection is possible. (equipped with thermocouple input)

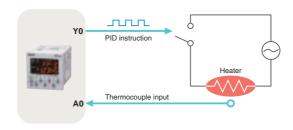
Can be used in place of a temperature controller or used to control them.



\*Compatible with MODBUS, it can be used as a slave.

#### PID instruction function

High-performance temperature control can be achieved with PID instruction.

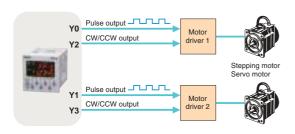


#### Equipped with high-speed counter for support of 2-axis independent positioning

#### Pulse output function

The unit comes equipped with 2 channels for pulse output of up to 10 kHz pulses.

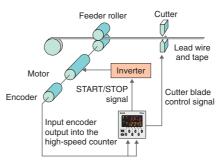
Since these two channels can be separately controlled, the FP-e is also suitable for 2-axis independent positioning.



#### High-speed counter function

In single phase, the 4-channel total is 10 kHz, and in 2-phase the 2-channel total is 2 kHz total speed, making the FP-e suitable for inverter control, etc.

(One half for the type with thermocouple input.)



## **FP-e Control Units**

## Decisive advantages in its class

## FP-e Control Unit

New Age, Advanced Controller!
Timer, Counter, Hour Meter, Temperature Controller and PLC in one Unit



#### ■ Type

| Name   | Туре                             | Calendar<br>timer | Thermocouple input | COM.<br>port | Product No. |
|--------|----------------------------------|-------------------|--------------------|--------------|-------------|
|        | Standard type (RS232C)           | Not available     | Not available      | RS232C       | AFPE224300  |
| FP-e   | Calendar timer type (RS232C)     | Available         | Not available      | RS232C       | AFPE224305  |
| contro | Thermocouple input type (RS232C) | Available         | Available          | RS232C       | AFPE214325  |
| unit   | Standard type (RS485)            | Not available     | Not available      | RS485        | AFPE224302  |
|        | Thermocouple input type (RS485)  | Not available     | Available          | RS485        | AFPE214322  |

#### **■** Features

# 5-character, 2-line, 3-color Display Simple characters and numerical values can be displayed. Simple error messages as well as operation instructions and timer/counter set values can be displayed.

#### 2. Front Operation Switch

Timer/Counter set values can be changed using front operation switches. The switches can also be used as input switches (X30 to X3F), so you need not install external switches.

## 3. Equivalent to FP0-C14 Intelligence of Small PLCs

In addition to the functions of programmable controller FP0, pulse output and high-speed counter functions can be used. The unit comes equipped with a tool port, and COM. port (RS232C/RS485) for communication.

#### 4. Easy Programming Using Wizard

Screen display instructions can be easily created using a programming tool wizard in FPWIN GR Ver. 2.3. or FPWIN Pro Ver. 5.0.

#### 5. Smooth Debugging

Monitoring memory area data and the I/O status facilitates debugging using the R (register) and I (I/O monitor) display modes.

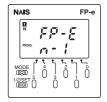
#### 6. Panel Mounted Type

The front of a unit is water-proof (in accordance with IP66, IEC standard).

#### ■ Display modes and functions



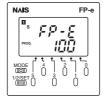
#### N mode (Normal mode)



Displays characters and numerical values, numerical data can be changed.



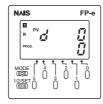
### S mode (Switch mode)



Can also display characters and numerical values. Operation switches can be used as inputs.



#### R mode (Register mode)

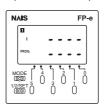


Operation memory in the controller can be monitored and its data changed.



#### I mode

(I/O monitor mode)



I/O status (X, Y) in the controller can be monitored.



## Specification table

#### **■** Performance specifications

| 1  | Model  |  | AFPE224300<br>Standard type   | AFPE224302<br>Standard type  | AFPE224305<br>Calendar timer type  | AFPE214325<br>Thermocouple input  | AFPE214322<br>Thermocouple inpu |
|--|--|--|---|--|--|---|---------------------------------|
| Item   |  | (RS232C)   | (RS485)   | (RS232C)   | type (RS232C)  | type (RS485)  |                                 |
| Programming method/Control method  |  | Relay symbol/Cyclic or   | peration  |  |  |   |                                 |
| Number of Control unit   |  |  | 14 points [Input: 8, Output: 6 (Tr. NPN: 5/Ry: 1)] 12 points [Input: 6, Output: 6 (Tr. NPN: 5/Ry: 1)  |  |  |   |                                 |
| controllable I/O points Front switch input   |  |  | 8 points  |  |  |   |                                 |
| Program memory Built-in memory   |  |  | Built-in EEP-ROM  |  |  |   |                                 |
| Program capacity   |  |  | 2,720 steps   |  |  |   |                                 |
| Rasic  |  | 83   |   |  |  |   |                                 |
| Number of instruction High-level   |  | 117  |   |  |  |   |                                 |
| Operation speed  |  |  | 0.9 μs/step (Basic instr  | ruction)   |  |   |                                 |
| I/O update and Base time   |  |  | Typical 2 ms  | ,  |  |   |                                 |
| Internal relay (R) Special internal relay (R) Special internal relay (R) Timer/Counter (T/C) Special data register (DT) Special data register (DT)   |  |  | 1,008 points (R0 to R62F)   |  |  |   |                                 |
|  |  |  | 64 points (R9000 to R9  |  |  |   |                                 |
|  |  |  |   |  | to T99/44 counter poir   | nts, C100 to C143 Note 1)   | )                               |
|  |  |  |   | ms, 100 ms, 1 s): selec  |  | .,  |                                 |
|  |  |  | 1,660 words (DT0 to D   | T1659)   |  |   |                                 |
|  |  |  | 112 words (DT9000 to  | DT9111)  |  |   |                                 |
| Q A  | Index registers (IX. IY)   |  | 2 points  |  |  |   |                                 |
| Differe  | ential points  |  | Unlimited number of po  | oints  |  |   |                                 |
|  | r control relay poi  | nts (MCR)  | 32 points   |  |  |   |                                 |
|  | er of labels (JP ar  |  | 64 labels   |  |  |   |                                 |
|  | er of step ladders   |  | 128 stages  |  |  |   |                                 |
|  | er of subroutines  |  | 16 subroutines  |  |  |   |                                 |
|  | er of interrupt prog   | grams  | 7 programs (external: 6   | 6, internal 1)   |  |   |                                 |
|  | iagnostic function   |  | Watchdog timer, progra  | · ,  |  |   |                                 |
| Clock/calendar function Note 2)  |  | Not available  |   | only be used when a l  | ek). However, this can   | Not available   |                                 |
| Battery life   |  | Not available  |   | installed.  220 days or more (act approx. 870 days (25° replacement interval: when no power is sup   | C). (Periodic<br>1 year). (Value applies   | Not available   |                                 |
| Pulse catch input  |  | 6 points in total (X0 an   | d X1: 50 μs, X2 to X5:  | 100 μs)  |  |   |                                 |
|  | port Note 3)   |  | RS232C  | RS485  | RS232C   | RS232C  | RS485                           |
|  | lical interrupt  |  | 0.5 ms to 30 s  | N3400  | N3232U   | N3232U  | N3400                           |
|  | ant scan   |  | Available   |  |  |   |                                 |
|  |  |  |   |  |  |   |                                 |
| Passwo   | /oru   |  | Available  Counter mode: Addition/subtraction (1-phase) Note 4) - Input points: 4 ch. (Max.)  |  |  |   |                                 |
|  |  | - Max. speed: 10 kHz (   | total of 4 ch.)   | unt input (ch. 1). X2: re  | : 5 kHz (total of 4ch.)<br>set input <sup>Note 5)</sup><br>set input <sup>Note 5)</sup>  |   |                                 |
| Hial   | ah-speed counter   | function   | Min input pulse width   | . V0 and V1. 50 us /10   |  | V0 and V1: 100 /E   | レロッ                             |
|  | gh-speed counter   |  | - Min. input pulse width  | n: X0 and X1: 50 μs (10  | ) kHz)   | X0 and X1: 100 μs (5  | kHz)                            |
| •  | he combinations  | 1-phase × 2 ch.  | - Min. input pulse width X3 and X4: 100 µs (5k  | n: X0 and X1: 50 µs (10<br>Hz)   | ) kHz)   | X0 and X1: 100 μs (5  | kHz)                            |
| •  | The combinations of 2-phase × 1 ch.  | 1-phase × 2 ch.<br>are also possible   | - Min. input pulse width<br>X3 and X4: 100 µs (5k<br>Counter mode: 2-phas   | n: X0 and X1: 50 µs (10<br>Hz)<br>e/individual/direction de  | ) kHz)<br>ecision (2-phase) - In   | X0 and X1: 100 µs (5  | kHz)                            |
|  | he combinations  | 1-phase × 2 ch.<br>are also possible   | - Min. input pulse width<br>X3 and X4: 100 µs (5k<br>Counter mode: 2-phas<br>- Max. speed: 2 kHz (to  | n: X0 and X1: 50 μs (10<br>Hz)<br>e/individual/direction de<br>otal of 2 ch.)  | ) kHz)<br>ecision (2-phase) - In   | X0 and X1: 100 μs (5<br>put points: 2 ch (Max.)<br>: 1 kHz (total of 2ch.)  | kHz)                            |
| tnuctions<br>and<br>for t  | The combinations of 2-phase × 1 ch.  | 1-phase × 2 ch.<br>are also possible   | - Min. input pulse width<br>X3 and X4: 100 µs (5k<br>Counter mode: 2-phas<br>- Max. speed: 2 kHz (to<br>- Input contact: X0: cou  | n: X0 and X1: 50 µs (10<br>Hz)<br>e/individual/direction de<br>otal of 2 ch.)<br>Int input (ch. 0), X1: co   | 0 kHz)<br>ecision (2-phase) - In<br>unt input (ch. 0), X2: re  | X0 and X1: 100 µs (5<br>pput points: 2 ch (Max.)<br>  : 1 kHz (total of 2ch.)<br>set input  | kHz)                            |
| ۲ * Th   | The combinations of 2-phase × 1 ch.  | 1-phase × 2 ch.<br>are also possible<br>ounter.  | - Min. input pulse width X3 and X4: 100 µs (5k Counter mode: 2-phas - Max. speed: 2- kHz (tr - Input contact: X0: cou X3: cou - Min. input pulse width X3 and X4: 100 µs (5 k   | n: XO and X1: 50 µs (10<br>Hz)<br>e/individual/direction de<br>otal of 2 ch.)<br>int input (ch. 0), X1: co<br>int input (ch. 2), X4: co<br>i: XO and X1: 50 µs (10<br>tHz)   | kHz) - Iracision (2-phase) - Ir - Iracision (2-phase) - Ir - Iracision (2-phase) - Iraci | X0 and X1: 100 µs (5<br>pput points: 2 ch (Max.)<br>  : 1 kHz (total of 2ch.)<br>set input  |                                 |
| * The and for the state of the  | The combinations of 2-phase × 1 ch. the high-speed or  | 1-phase × 2 ch.<br>are also possible   | - Min. input pulse width X3 and X4: 100 µs (5k Counter mode: 2-phas - Max. speed: 2 kHz (kt - Input contact: X0: cou X3: cou - Min. input pulse width X3 and X4: 100 µs (5 i 2 independent points (   | i: X0 and X1: 50 μs (10<br>Hz)<br>e/individual/direction de<br>stal of 2 ch.)<br>int input (ch. 0), X1: co<br>int input (ch. 2), X4: co<br>i: X0 and X1: 50 μs (10<br>Hz)<br>Y0 and Y1) (No interpo  | kHz) - Iracision (2-phase) - Ir - Iracision (2-phase) - Ir - Iracision (2-phase) - Iraci | X0 and X1: 100 μs (5<br>put points: 2 ch (Max.)<br> : 1 kHz (total of 2ch.)<br>set input<br>set input<br>  X0 and X1: 100 μs (5                     | kHz)                            |
| Special functions and for the second second for the second | The combinations of 2-phase × 1 ch. the high-speed or  | 1-phase × 2 ch.<br>are also possible<br>ounter.  | - Min. input pulse width X3 and X4: 100 µs (5k Counter mode: 2-phas - Max. speed: 2- kHz (tr - Input contact: X0: cou X3: cou - Min. input pulse width X3 and X4: 100 µs (5 k   | ix: X0 and X1: 50 µs (10: Hz) Hz) e/individual/direction de stal of 2 ch.) int input (ch. 0), X1: co int input (ch. 2), X4: co ix: X0 and X1: 50 µs (10: Hz) Y0 and Y1) (No interpol 1: 1-point) Note 6)   | kHz) - Iracision (2-phase) - Ir - Iracision (2-phase) - Ir - Iracision (2-phase) - Iraci | X0 and X1: 100 μs (5<br>put points: 2 ch (Max.)<br> : 1 kHz (total of 2ch.)<br>set input<br>set input   | kHz)                            |
| * The and for the and output   | he combinations of 2-phase × 1 ch. the high-speed of   | 1-phase × 2 ch.<br>are also possible<br>ounter.  | - Min. input pulse width X3 and X4: 100 µs (5k Counter mode: 2-phas - Max. speed: 2 kHz (tr - Input contact: X0: coo - X3: coo - Min. input pulse width X3 and X4: 100 µs (5 k 2 independent points (4 k 40 Hz to 10 kHz (Y0/Y  | ix: X0 and X1: 50 µs (10: Hz) Hz) e/individual/direction de stal of 2 ch.) int input (ch. 0), X1: co int input (ch. 2), X4: co ix: X0 and X1: 50 µs (10: Hz) Y0 and Y1) (No interpol 1: 1-point) Note 6)   | kHz) - Iracision (2-phase) - Ir - Iracision (2-phase) - Ir - Iracision (2-phase) - Iraci | X0 and X1: 100 µs (5<br>  put points: 2 ch (Max.)<br>  : 1 kHz (total of 2ch.)<br>  set input<br>  X0 and X1: 100 µs (5<br>  40 Hz to 5 kHz (1-poir | kHz)                            |
| * The and for the and output o | he combinations of d 2-phase × 1 ch. the high-speed of   | 1-phase × 2 ch. are also possible ounter.  Output points Output frequency  | - Min. input pulse width X3 and X4: 100 µs (5k Counter mode: 2-phas - Max. speed: 2 kHz (tr - Input contact: X0: cou - Min. input pulse width X3 and X4: 100 µs (5 l 2 independent points ( 40 Hz to 10 kHz (Y0/Y) 40 Hz to 5 kHz (Y0/Y)  | a: X0 and X1: 50 µs (10:<br>Hz)<br>e/individual/direction de<br>otal of 2 ch.)<br>int input (ch. 0), X1: co<br>int input (ch. 2), X4: co<br>a: X0 and X1: 50 µs (10:<br>Hz)<br>Y0 and Y1) (No interpo<br>1: 1-point) Note 6)<br>2-point)   | kHz) - Incision (2-phase) - Incustry - Incustry - Incustry - Incustry - Incustry - Incision - Incis | X0 and X1: 100 µs (5<br>  put points: 2 ch (Max.)<br>  : 1 kHz (total of 2ch.)<br>  set input<br>  X0 and X1: 100 µs (5<br>  40 Hz to 5 kHz (1-poir | kHz)                            |
| * The and for the output of th | he combinations d 2-phase x 1 ch. the high-speed of the high-speed | 1-phase × 2 ch. are also possible cunter.  Output points  Output frequency  Output points                            | - Min. input pulse width X3 and X4: 100 µs (5k Counter mode: 2-phas - Max. speed: 2 kHz (tr - Input contact: X0: cot - Min. input pulse width X3 and X4: 100 µs (5 k 2 independent points (40 Hz to 10 kHz (Y0/Y 40 Hz to 5 kHz (Y0/Y 2 points (Y0 and Y1)  | ta: X0 and X1: 50 µs (10: Hz) e/individual/direction debtal of 2 ch.) int input (ch. 0), X1: co int input (ch. 2), X4: co i: X0 and X1: 50 µs (10: Hz) Y0 and Y1) (No interpot: 1: 1-point) 1: 1-point) 1: 1 kHz Duty: 0.1 % t   | kHz) - Incision (2-phase) - Incustry - Incustry - Incustry - Incustry - Incustry - Incision - Incis | X0 and X1: 100 µs (5<br>  put points: 2 ch (Max.)<br>  : 1 kHz (total of 2ch.)<br>  set input<br>  X0 and X1: 100 µs (5<br>  40 Hz to 5 kHz (1-poir | kHz)                            |
| * The and for the output of th | he combinations d 2-phase x 1 ch. the high-speed of the high-speed | 1-phase × 2 ch. are also possible cunter.  Output points  Output frequency  Output points  Output frequency          | - Min. input pulse width X3 and X4: 100 µs (5k Counter mode: 2-phas - Max. speed: 2 kHz (tr - Input contact: X0: cot - X3: cot - Min. input pulse width X3 and X4: 100 µs (5t) 2 independent points ( 40 Hz to 10 kHz (Y0/Y 40 Hz to 5 kHz (Y0/Y 12 points (Y0 and Y1) Frequency: 0. 15 Hz to   | i: X0 and X1: 50 μs (10<br>Hz)<br>e/individual/direction de<br>stal of 2 ch.)<br>int input (ch. 0), X1: co<br>int input (ch. 2), X4: co<br>i: X0 and X1: 50 μs (10<br>Hz)<br>Y0 and Y1) (No interpo<br>1: 1-point) Note 6)<br>2-point)   | kHz) - Incision (2-phase) - Incustry - Incustry - Incustry - Incustry - Incustry - Incision - Incis | X0 and X1: 100 µs (5<br>  put points: 2 ch (Max.)<br>  : 1 kHz (total of 2ch.)<br>  set input<br>  X0 and X1: 100 µs (5<br>  40 Hz to 5 kHz (1-poir | kHz)                            |
| * The and for the  | lse tput function VM output tection neer uniter  | Output points Output points Output frequency Output frequency Non-hold type  | - Min. input pulse width X3 and X4: 100 µs (5k Counter mode: 2-phas - Max. speed: 2 kHz (tr - Input contact: X0: coo. X3: coo Min. input pulse width X3 and X4: 100 µs (5 H 2 independent points (40 Hz to 10 kHz (Y0/Y 40 Hz to 5 kHz (Y0/Y 40 Pz points (Y0 and Y1) Frequency: 0. 15 Hz tc Non-hold type: (all poir From set value to C13:  | i: X0 and X1: 50 µs (10 Hz) Hz) e/individual/direction de total of 2 ch.) int input (ch. 0), X1: co int input (ch. 2), X4: co i: X0 and X1: 50 µs (10 Hz) Y0 and Y1) (No interpod 1: 1-point) Note 6) 2-point)  1 kHz Duty: 0.1 % total its)   | kHz) - Incision (2-phase) - Incustry - Incustry - Incustry - Incustry - Incustry - Incision - Incis | X0 and X1: 100 µs (5<br>  put points: 2 ch (Max.)<br>  : 1 kHz (total of 2ch.)<br>  set input<br>  X0 and X1: 100 µs (5<br>  40 Hz to 5 kHz (1-poir | kHz)                            |
| * The and for the angle of the  | lse tput function  WM output function  with output function  which is the first function func | Output points Output frequency Output frequency Output frequency Non-hold type Hold type                             | - Min. input pulse width X3 and X4: 100 µs (5k Counter mode: 2-phas - Max. speed: 2 kHz (tr - Input contact: X0: cou - X3: cou - Min. input pulse width X3 and X4: 100 µs (5 k 2 independent points (40 Hz to 10 kHz (Y0/Y 40 Hz to 5 kHz (Y0/Y | ix X0 and X1: 50 µs (10 Hz) Hz) e/individual/direction de otal of 2 ch.) int input (ch. 0), X1: co int input (ch. 2), X4: co ix X0 and X1: 50 µs (10 Hz) Y0 and Y1) (No interpot 1: 1-point) Note 6) 2-point)  1 kHz Duty: 0.1 % to ix S0 and X1: 50 µs (10 Hz) S1 cond S1 con | ecision (2-phase) - In<br>unt input (ch. 0), X2: re<br>unt input (ch. 2), X5: re<br>kHz)<br>elation function)  | X0 and X1: 100 µs (5<br>  put points: 2 ch (Max.)<br>  : 1 kHz (total of 2ch.)<br>  set input<br>  X0 and X1: 100 µs (5<br>  40 Hz to 5 kHz (1-poir | kHz)                            |
| * The and for the angle of the  | lse tput function VM output tection neer uniter  | Output points Output frequency Output points Output frequency Output frequency Non-hold type Hold type Non-hold type | - Min. input pulse width X3 and X4: 100 µs (5k Counter mode: 2-phas - Max. speed: 2 kHz (tr - Input contact: X0: cot - Min. input pulse width X3 and X4: 100 µs (5 I 2 independent points ( 40 Hz to 10 kHz (Y0/Y 40 Hz to 5 kHz (Y0/Y 12 points (Y0 and Y1) Frequency: 0. 15 Hz tc Non-hold type: (all poir From set value to C13: 4 points (elapsed value 976 points (R0 to R60)  | a: X0 and X1: 50 µs (10.42)  H2)  e/individual/direction de  stal of 2 ch.)  int input (ch. 0), X1: co int input (ch. 2), X4: co i: X0 and X1: 50 µs (10.42)  Y0 and Y1) (No interpol i: 1-point) Note 6) : 2-point)  1 kHz Duty: 0.1 % to its) 3 ss) C140 to C143  F) 61 words (WR0 to  | ocision (2-phase) - In unt input (ch. 0), X2: re unt input (ch. 2), X5: re kHz)  lation function)  | X0 and X1: 100 µs (5<br>  put points: 2 ch (Max.)<br>  : 1 kHz (total of 2ch.)<br>  set input<br>  X0 and X1: 100 µs (5<br>  40 Hz to 5 kHz (1-poir | kHz)                            |
| * The and for the  | lse tput function  WM output function  with output function  which is the first function func | Output points Output frequency Output frequency Output frequency Non-hold type Hold type                             | - Min. input pulse width X3 and X4: 100 µs (5k Counter mode: 2-phas - Max. speed: 2 kHz (tr - Input contact: X0: cou - X3: cou - Min. input pulse width X3 and X4: 100 µs (5 k 2 independent points (40 Hz to 10 kHz (Y0/Y 40 Hz to 5 kHz (Y0/Y | 1: X0 and X1: 50 μs (10: Hz)  Hz)  e/individual/direction de stal of 2 ch.)  Int input (ch. 0), X1: co int input (ch. 2), X4: co in X0 and X1: 50 μs (10: Hz)  Y0 and Y1) (No interport: 1: 1-point) Note 6)  1: 2-point)  1 kHz Duty: 0.1 % to this  9 9  9 0 140 to C143  7 6 1 words (WR0 to CF)  2 words (WR0 to CF)   | ocision (2-phase) - In unt input (ch. 0), X2: re unt input (ch. 2), X5: re kHz)  lation function)  | X0 and X1: 100 µs (5<br>  put points: 2 ch (Max.)<br>  : 1 kHz (total of 2ch.)<br>  set input<br>  X0 and X1: 100 µs (5<br>  40 Hz to 5 kHz (1-poir | kHz)                            |

Note 1) The proportion of timer points to counter points can be changed using a system register.

Note 2) Precision of calendar timer:

- At 0°C/32°F, less than 200 seconds of error per month
- At 25°C/17°F, less than 200 seconds of error per month
- At 55°C/13°F, less than 240 seconds of error per month
- At 55°C/13°F, less than 240 seconds of error per month

Note 3) When using the COM. port for communication, retransmission is recommended.
The RS232C driver IC for the COM. port conforms completely to ElA/TIA-232E and
CCITT V. 28 standards

Note 4) The max. counting speed (10 kHz) is the counting speed with a rated input voltage of 24 V
DC and an ambient temperature of 25°C. The counting speed (frequency) will decrease depending on the voltage and temperature.

Note 5) If the unit is equipped with both reset inputs X0 and X1, X2 serves as the reset input for X1. If X3 and X4 are used, X5 serves as the reset input for X4.

Note 6) When the positioning control instruction "F168" is performed, the maximum output frequency is 9.5 kHz.

Note 7) The program, system registers and the hold type area (internal relay, data register, and timer/counter) are backed up by the built-in EEP-ROM.

When a battery is replaced with a new one in the FP-e unit with a calendar timer function, settings can be changed without installing a battery. The data cannot be stored even when the settings are changed using the system register.

Note 8) F180 (SCR) and F181 (DSP) instructions are supported from Control FPWIN GR Ver. 2.2. and FPWIN Pro V 4.1.



## Technical data

#### **■** General specifications

| Item                             | Description   |  |  |  |
|----------------------------------|---|--|--|--|
| Rated voltage                    | 24 V DC   |  |  |  |
| Operating voltage range          | 21.6 to 26.4 V DC   |  |  |  |
| Allowed momentary power off time | 10 ms   |  |  |  |
| Ambient temperature              | 0 to +55°C  |  |  |  |
| Storage temperature              | -20 to +70°C  |  |  |  |
| Ambient humidity                 | 30 to 85%RH (non-condensing)  |  |  |  |
| Storage humidity                 | 30 to 85%RH (non-condensing)  |  |  |  |
|                                  | Input terminals (COM, X0 to Xn) Output terminals (Y0 to Y4)  Power supply terminal, Function earth Input terminal (A0, A1) COM. (RS232C) terminal | 500 V AC for 1 minute                  |  |  |
| Breakdown voltage                | Output terminal (Y5)  Power supply terminal, Function earth Input terminal (COM, X0 to Xn, A0, A1) COM. (RS232C) terminal                         | 1500 V AC for 1 minute                 |  |  |
|                                  | Input terminals (COM, X0 to Xn) <> Output terminals (Y0 to Y4)  | 500 V AC for 1 minute                  |  |  |
| Insulation resistance            | Input terminals (COM, X0 to Xn) Output terminals (Y0 to Y5)  Power supply terminal, Function earth Input terminal (A0, A1) COM. (RS232C) terminal | Min. 100 M<br>(measured with 500 V DC) |  |  |
|                                  | Input terminals (COM, X0 to Xn)  Output terminals (Y0 to Y5)  |  |  |  |
| Vibration resistance             | 10 to 55 Hz, 1 cycle/min. Double amplitude: 0.75 mm, 10 min. on X, Y, and Z axes  |  |  |  |
| Shock resistance                 | 98 m/s <sup>2</sup> or more, 4 times on X, Y, and Z axes  |  |  |  |
| Noise resistance                 | 1000V (p-p) with pulse widths 50 ns and 1 µs (based on in-house measurements)   |  |  |  |
| Operating condition              | Free from corrosive gases and excessive dust  |  |  |  |
| Current consumption              | 200 mA or less (24 V DC)  |  |  |  |
| Protection                       | IP66-compliant front section (Only when a rubber packing is used.)  |  |  |  |
| Mass                             | Approx. 130 g   |  |  |  |

#### ■ DC input specifications (X0 to X7)

| Item                     |             | Description  |  |  |
|--------------------------|-------------|--|--|--|
| Number of input          |             | 8 points (6 points for thermocouple input type)  |  |  |
| Insulation method        |             | Optical coupler  |  |  |
| Rated input voltage      |             | 24 V DC  |  |  |
| Operating voltage range  |             | 21.6 to 26.4 V DC  |  |  |
| Rated input              | current     | Approx. 4.3 mA   |  |  |
| Input points per common  |             | 8 points/common (6 points/common for thermocouple input type) Either the positive or negative of the input power supply can be connected to common terminal. |  |  |
| ON voltage/ON current    |             | 19.2 V or less/4 mA or less  |  |  |
| OFF voltage              | OFF current | 2.4 V or more/1 mA or more   |  |  |
| Input impeda             | ance        | Approx. 5.1 k (X0, X1)<br>Approx. 5.6 k (X2 to X7)   |  |  |
|                          | OFF to ON   | 50 μs or less (X0, X1) Note 1)   |  |  |
|                          |             | 100 μs or less (X2 to X5) Note 1)  |  |  |
| Response                 |             | 2 ms or less (X6, X7)  |  |  |
| time                     | ON to OFF   | 50 µs or less (X0, X1) Note 1)   |  |  |
|                          |             | 100 μs or less (X2 to X5) Note 1)  |  |  |
|                          |             | 2 ms or less (X6, X7)  |  |  |
| Operating mode indicator |             | LCD display (I/O monitor mode)   |  |  |

X0 through X5 are inputs for the high-speed counter and have a fast response time. If used as normal inputs, you should insert a timer in the program as chattering and noise may be interpreted as an input signal. Also, the above specifications apply when the rated input voltage is 24V DC and the temperature is 25°C. Note 1)

#### **■** Thermocouple input specifications

| Item                                     | Description  |  |  |
|--|--|--|--|
| Number of input                          | 2 points (CH0: WX1, CH1: WX2)  |  |  |
| Temperature sensor type                  | Thermocouple type K  |  |  |
| Input range                              | -30.0 to 300.0°C *1) (-22 to 572°F)  |  |  |
| Accuracy                                 | ±0.5%FS±1.5°C (FS = -30 to 300°C)  |  |  |
| Resolution                               | 0.1°C  |  |  |
| Conversion time                          | 250 ms/2CH *2)   |  |  |
| Insulation method                        | Between internal circuit and thermocouple input circuit: noninsulated *3) Between CH0 and CH1 of thermocouple input: PhotoMOS insulation |  |  |
| Detection function of wire disconnection | Available  |  |  |

- Temperature can be measured up to 330°C (626°F). When the measured temperature exceeds 330°C (626°F) or the thermocouple wiring is disconnected, "K20000" is written
- to the register.

  2) Temperature conversion for thermocouple input is performed every 250 ms. The conversion data is updated on the internal data register after the scan is completed.

  3) The internal circuit and thermocouple input circuit are not insulated. Therefore, use the nongrounding type thermocouples and sheath tubes.



## Technical data

#### **■** Transistor NPN output specifications (For Y0 to Y4)

| 14)       |  |  |  |
|-----------|--|--|--|
|           | Description  |  |  |
|           | Optical coupler  |  |  |
|           | Open collector   |  |  |
|           | 5 to 24 V DC   |  |  |
| ge range  | 4.75 to 26.4 V DC  |  |  |
|           | 0.5 A  |  |  |
|           | 1 A  |  |  |
| mmon      | 5 points/common  |  |  |
| urrent    | 100 μA or less   |  |  |
| р         | 1.5 V or less  |  |  |
| OFF to ON | 50 μs or less (For Y0 and Y1),<br>1 ms or less (For Y2, Y3 and Y4) |  |  |
| ON to OFF | 50 µs or less (For Y0 and Y1),<br>1 ms or less (For Y2,Y3 and Y4)  |  |  |
| Voltage   | 21.6 to 26.4 V DC  |  |  |
| Current   | 6 mA/point (For Y0 and Y1)<br>3 mA/point (For Y2, Y3, and Y4)      |  |  |
|           | Zener diode  |  |  |
|           | LCD display (I/O monitor mode)                                     |  |  |
|           | ge range  mmon urrent op  OFF to ON ON to OFF                      |  |  |

#### ■ Relay output specifications (Y5)

| Item                     |            | Description                                      |  |  |
|--------------------------|------------|--|--|--|
| Output type              |            | Normally open (1 Form A)                         |  |  |
| Rated control capacity   |            | 2 A 250 V AC, 2 A 30 V DC                        |  |  |
| Output points per common |            | 1 point/common                                   |  |  |
| Response time            | OFF to ON  | Approx. 10 ms                                    |  |  |
| riesponse une            | ON to OFF  | Approx. 8 ms                                     |  |  |
| Life time                | Mechanical | Min. 2 × 10 <sup>7</sup> operations              |  |  |
| Life tillle              | Electrical | Min. 10 <sup>5</sup> operations (resistive load) |  |  |
| Surge absorber           |            | None   |  |  |
| Operating indicator      |            | LCD display (I/O monitor mode)                   |  |  |

#### ■ COM, port communication specifications \*1)

| COM. port communication specifications     |   |                      |  |
|--|---|----------------------|--|
| Item                                       | Description   |                      |  |
| COM. port type                             | RS232C *2)  | RS485                |  |
| Isolation status with the internal circuit | Non-isolated  | Isolated             |  |
| Transmission distance                      | 15 m  | 1200 m               |  |
| Baud rate *3)                              | 300, 600, 1200, 2400,<br>4800, 9600, 19200 bit/s            | 9600,19200 bit/s *4) |  |
| Communication method                       | Half-duplex   |                      |  |
| Synchro system                             | Synchronous communication method                            |                      |  |
|  | Stop bit: 1 bit/2 bit                                       |                      |  |
|  | Parity: Not available/Available<br>(Odd number/Even number) |                      |  |
| Transmission format                        | Data length 7 bit/8 bit                                     |                      |  |
|  | Beginning code: STX available/STX not available             |                      |  |
|  | Ending code: CR/CR+LF                                       | /not available/ETX   |  |
| Data output order                          | Starting from 0 bits per character                          |                      |  |
| No. of connected units                     | — 99 *5) *6)  |                      |  |
| Communication mode                         | General-purpose communication     Computer link             |                      |  |

- \*1) When communicating between FP-e and other devices, it is recommneded to perform resend processing.

  \*2) For RS232C wiring, be sure to use shielded wires for higher noise immunity.

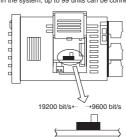
  \*3) Set the baud rate of RS485 with the FP-e system register and FP-e internal switch. Set the baud rate of RS232C with the FP-e system register.

  \*4) When sending a command from the FP-e is completed in RS485 communication, send a response from the receiving device to the FP-e after the following time has elapsed: 9600 bit/s: 2 ms or longer It takes at least 1 scan time (at least 2 ms) for the FP-e to send back a response after received the command.

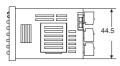
  \*5) When our C-NET Adapter or RS485 device other than recommended is connected in the system, the maximum connection number is limited to 32 units.

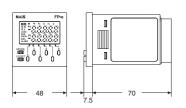
  \*6) For a RS485 converter on the computer side, SI-35 (from LINE EYE Co., Ltd.) is recommended.

- recommended. When SI-35 is used in the system, up to 99 units can be connected.



#### **■** Dimensions

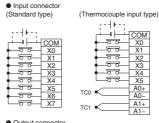


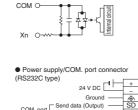




(mm)

#### **■** Wiring diagram





| 4 O O O O O O O O O O O O O O O O O O O |
|---|
| M C Intern                              |
|   |

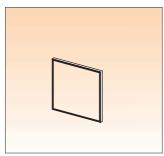
# FP-e Options

#### Options



Backup battery
Included with calendar timer type

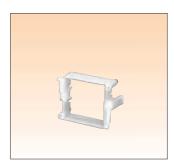
Part No.: AFPG804



Rubber gasket

Included with unit

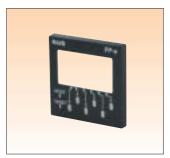
Part No.: ATC18002



Mounting frame

Included with unit

Part No.: AT8-DA4



Panel cover

Color: Black

Part No.: AFPE803

(20 sets)



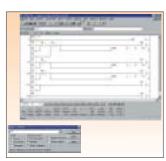
Protective cover

Part No.: AQM4803



**Terminal socket set** 4 type sockets, additional part

Part No.: AFPE804



Programming tool software

## Programming tool software Control FPWIN Pro

Part No.: FPWINPROSEN5 (Small version, English manual) FPWINPROSFR5 (Small version, French manual) FPWINPROSDE5 (Small version, German manual) FPWINPROFEN5

(Full version, English manual) FPWINPROFFR5 (Full version, French manual)

FPWINPROFDE5 (Full version, German manual)

Control FPWIN GR Part No.: FPWINGRF2 (Full version)

Programming cable Part No.: AFC8513

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