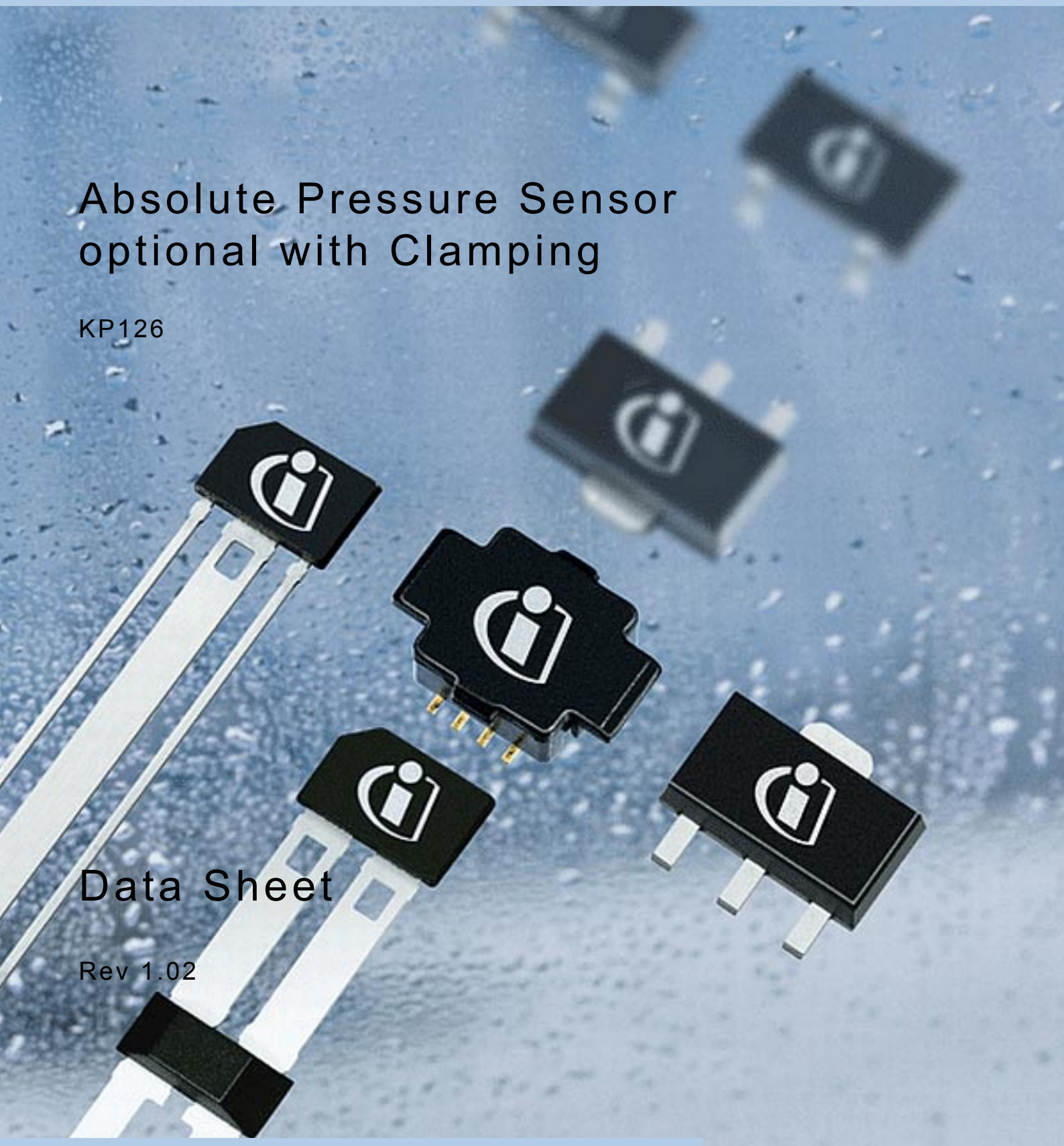
November 2007

Absolute Pressure Sensor optional with Clamping

KP126



Data Sheet

Rev 1.02

Sense & Control

infineon

Never stop thinking

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Absolute Pressure Sensor

Revision History: 2007-11-23, Rev 1.02

Previous Version: Rev 0.1	
Page	**Subjects (major changes since last revision)**
Page 5	Feature “green” package added.
Page 5	Paragraph about pressure range rephrased.
Page 10	ESD robustness corrected.
Page 10 Page 11	Symbol for input pressure range (max and operating) added/changed.
Page 12	Junction temperature added.
Page 12	Range for customized transfer functions added.
Page 12 Page 24	Clamping feature reworked.
Page 16	Definition ratiometric error rephrased. Formula added.
Page 18 Page 24	Misspelling corrected.
Page 20	Drawing updated.
Page 20	“Green” compliancy added in package chapter.
Page 23	Chapter EMC added.
Page 24	Chapter identification code added.
Previous Version: Rev 0.9	
Page 18	Changes in recommended application circuit.
Page 19 Page 20	Reorganization of chapters package outlines and cap.
Previous Version: Rev 1.0	
Page 6	Changes according to application circuit for GND connection and digital PINs.
Previous Version: Rev 1.01	
Page 12	Correction of sensor characteristics output referred noise.

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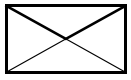
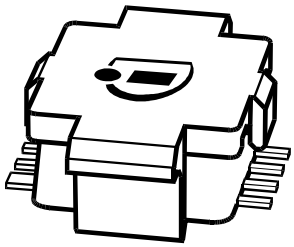


1 Overview

1.1 Features

- Ratiometric analog output
- Calibrated transfer function
- Clamping
- High accuracy over a large temperature range
- Maximum error ± 1.0 kPa
- “Green” 8-pin SMD housing
- On Board Diagnostics (OBD) for broken wire detection



PG-DSOF-8-12
with cap

1.2 Product Description

The KP126 is a miniaturized Absolute Pressure Sensor IC based on the capacitive principle. It is surface micromachined with a monolithic integrated signal conditioning circuit implemented in BiCMOS standard technology. Because the KP126 is a high-precision IC for cost-critical solutions, the chip is packaged in a “green” low-cost SMD housing. The sensor is developed for measurement of barometric air pressure (BAP).

High accuracy and high sensitivity enable the deployment of this device in automotive applications as well as in consumer applications.

As standard the calibrated transfer function converts a pressure range from 40 kPa to 115 kPa into an analog output voltage between 0.5 V and 4.5 V. Customized transfer functions and clamping can be realized as well.

Product Name	Product Type	Ordering Code	Package
KP126	Absolute Pressure Sensor	SP000239578	PG-DSOF-8-12

2 Pin Configuration

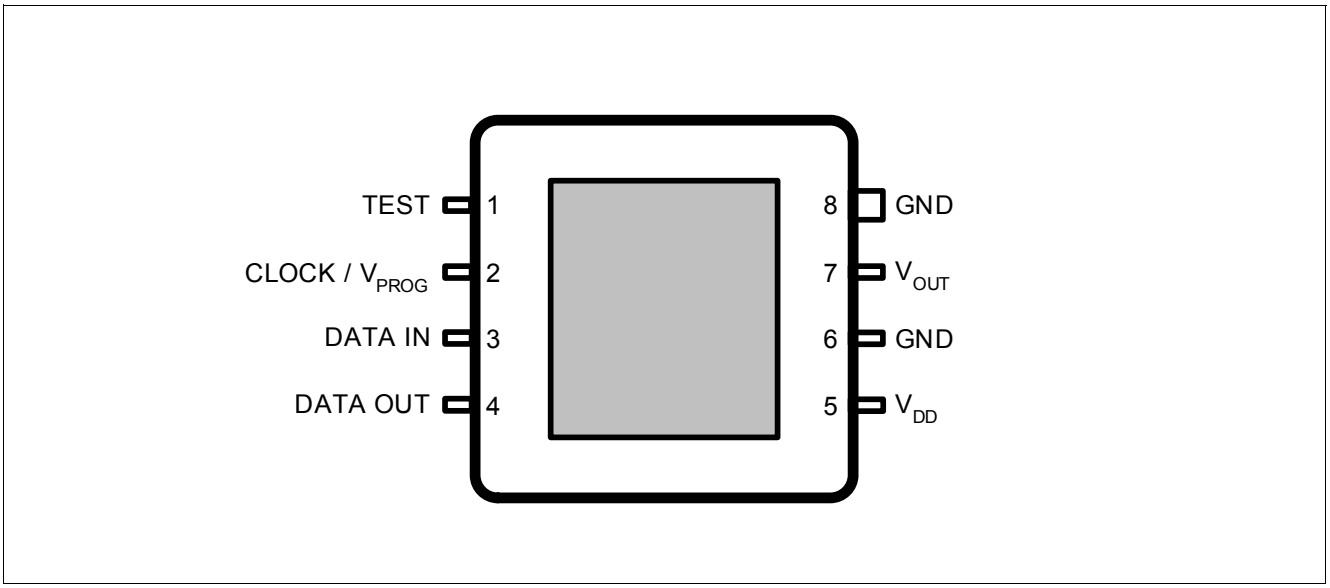


Figure 1 Pin Configuration (top view, figure not to scale)

Table 1 Pin Definitions and Functions

Pin No.	Name	Function
1	TEST	Test pin [1]
2	CLOCK / V_{PROG}	External Clock for Communication / Programming Voltage [1]
3	DATA IN	Serial data input pin [1]
4	DATA OUT	Serial data output pin [1]
5	V_{DD}	Supply Voltage
6	GND	0 Volt circuit ground potential [2]
7	V_{OUT}	Analog pressure signal output
8	GND	Alternative ground pin [2]

1) Digital pins are used only during calibration and test. It is recommended to leave these PINs floating.

2) It is recommended to connect both GND PINs.

3 Functional Block Diagram

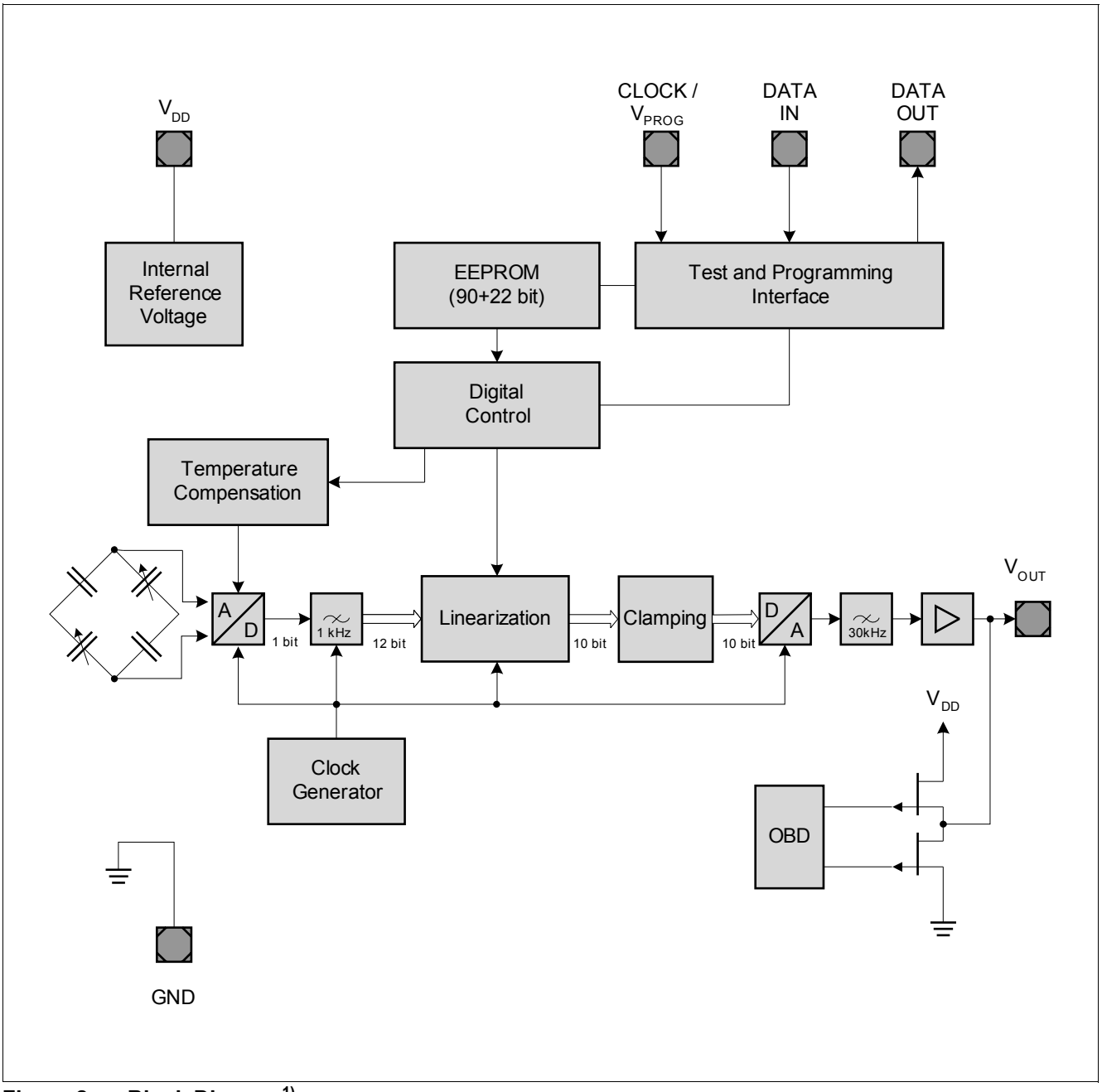


Figure 2 Block Diagram[1)]

1) Clamping feature is optional.

4 Functional Description

4.1 Sensor

Pressure is detected in a capacitive way by an array of surface micromachined sensor cells.

The sensor cell output is amplified, temperature compensated and linearized to obtain an output voltage that is proportional to the applied pressure.

The transfer function for linearization is calculated in the digital part of the sensor using third order polynomial calculation.

The KP126 sensor is available with different transfer functions.

The transfer function is given by the following parameters which can be chosen within the specified range:

- Minimum and maximum rated pressure
- Voltage at minimum rated pressure
- Voltage at maximum rated pressure
- Sensitivity
- Clamping levels

The output is analog and ratiometric with respect to the supply voltage.

All parameters needed for the complete calibration algorithm — such as offset, gain, temperature coefficients of offset and gain, and linearization parameters — are determined after assembly. The parameters are stored in internal registers in the EEPROM of the chip.

On Board Diagnostics

When the chip is not powered properly, the JFET transistors of the On Board Diagnostics (OBD) stage are self-conducting. For example, if the GND connection is interrupted, the output is drawn strongly to V_{DD}. The microcontroller can set a limit for valid output signals. In the case of an error, the output voltages will be too close to the V_{DD} or GND potential.

Clamping

If the clamping function is enabled, the output voltage is limited internally to the two clamping thresholds. In this case, the On Board Diagnostics (OBD) error detection is simplified and improved.

4.2 Transfer Function

The KP126 device is fully calibrated on delivery. The sensor has a linear transfer function between the applied pressure and the output signal:

$$V_{OUT} = V_{DD} \times (a \times P + b)$$

The output is ratiometric.

Gain **a** and Offset **b** are determined during calibration in order to create the required transfer function.

Standard Transfer Function

The following calibration is adjusted with the parameters **a** and **b**:

Table 2 Transfer Function (End Points)

Pressure			Output Voltage @ $V_{DD} = V_{DD;TYP}$		
Symbol	**Values**	**Unit**	**Symbol**	**Values**	**Unit**
$P_{IN,MIN}$	40	kPa	$V_{OUT,MIN}$	0.5	V
$P_{IN,MAX}$	115		$V_{OUT,MAX}$	4.5	

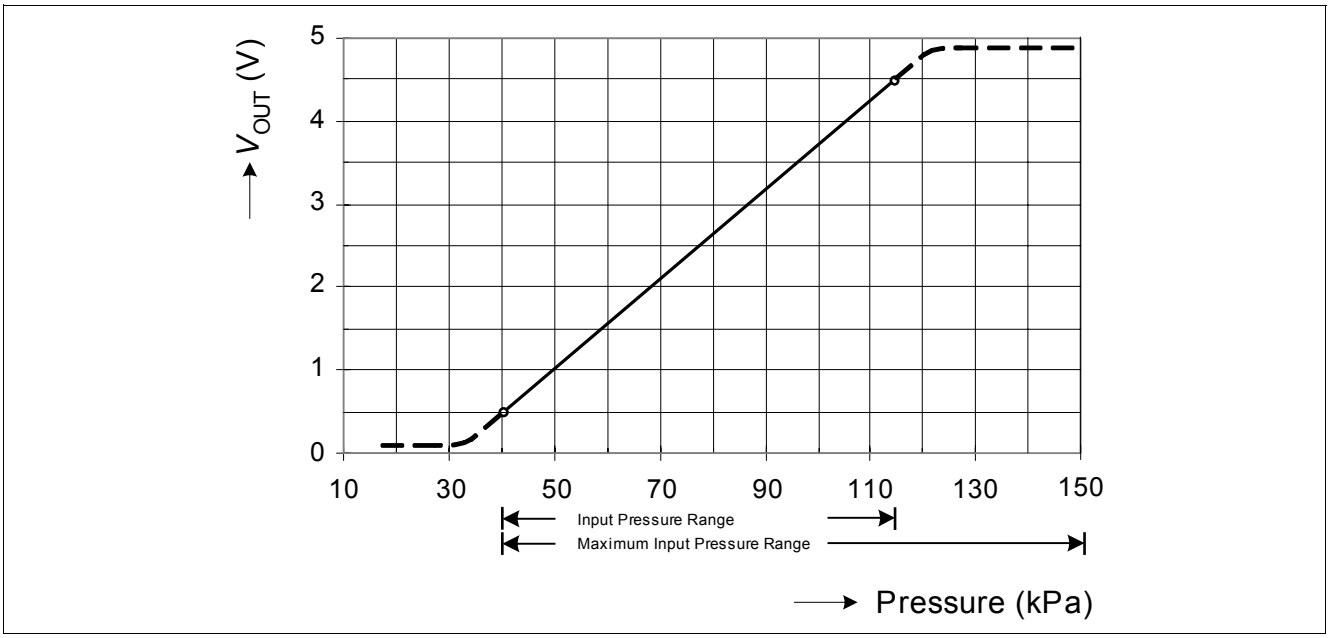


Figure 3 Transfer Function

Note: The application circuitry determines the current driven by the device and thus has an impact on the diagnostic ranges.

5 Electrical Characteristics

5.1 Absolute Maximum Ratings

Table 3 Absolute Maximum Ratings

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Supply voltage	V_{DD}	– 0.3	–	6.5	V	
		–	–	16.5		1h @ 70°C
		– 6.5 [1]	–	–		for max. 5 minutes
Output voltage	V_{OUT}	– 0.3	–	V_{DD}+ 0.3	V	
Maximum ambient temperature	T_A	– 40		125	°C	
Storage temperature	T_S	– 60		150	°C	
Maximum input pressure range	P_{MAX}	40 5.8	–	600 87	kPa psi	for max. 5 minutes
		40 5.8	–	150 21.75	kPa psi	
Voltage at CLOCK / V_{PROG} Pin	V_{CLK}	–	–	20	V	
Voltage at data pins (DATA IN, DATA OUT)	V_{DATA}	–	–	5.0	V	
ESD robustness [2]	$V_{ESD, HBM}$	–	–	± 2	kV	Analog pins: V_{DD}, Vout, GND
		–	–	± 2	kV	Digital pins: CLOCK / V_{PROG}, DATA OUT, DATA IN

1) Reverse polarity; I_{DD} < 300mA

2) HBM: 1.5kΩ, 100pF; according to EIA/JESD22-A114-B (covers MIL STD 883D)

Attention: Stresses above the max. values listed here may cause permanent damage to the device. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. Maximum ratings are absolute ratings; exceeding only one of these values may cause irreversible damage to the integrated circuit.

5.2 Operating Range

The following operating conditions must not be exceeded in order to ensure correct operation of the device.

All parameters specified in the following sections refer to these operating conditions, unless otherwise noticed.

Table 4 Operating Range

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Supply voltage	V_{DD}	4.5	5	5.5	V	V_{OUT} is ratiometric to V_{DD}
Output current[1)]	I_{OUT}	– 1	–	1	mA	
Lifetime	t_{LT}	15	–	–	years	
Maximum ambient temperature	T_A	– 40		125	°C	
Input pressure range	P_{IN}	40 5.8		115 16.7	kPa psi	

1) Negative values: Current into device (pull-up resistor used).
Positive values: Current out of the device (pull-down resistor used).

5.3 Sensor Characteristics

Table 5 Sensor Characteristics

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Output Voltage Range	V_{OUT_R}	0.10		4.85	V	More information in chapter **"Electrical Details" on Page 14**
Output voltage at min. rated pressure[1) 2)]	$V_{OUT,MIN}$	0.10	–	0.50	V	[3)]
Output voltage at max. rated pressure[1) 4)]	$V_{OUT,MAX}$	4.75 4.70	–	4.85	V	@ 25°C [3)] complete temperature range
Minimum rated pressure[1)]	$P_{IN,MIN}$	40 5.8	–	70 10.15	kPa psi	
Maximum rated pressure[1)]	$P_{IN,MAX}$	115 16.7	–	150 21.75	kPa psi	
Sensitivity	S	40.0[1)]	53.3	88.0[1)]	mV/ kPa	
Supply current	I_{DD}	–	8	10	mA	[5)]
Offset Voltage[1)]	V_{OFF}	1500	–	3500	mV	[6)]
Overall Accuracy Error	Err	–	–	± 1.0	kPa	[7)]
Ratiometric Error	E_{RAT}	–25	–	25	mV	[8)]
Output referred noise	V_{NOISE}	–	–	2.5	mV_{RMS}	@ f > 1kHz [9)])
		–	–	1.8		@ f < 1kHz
Response time [10)]	t_R	–	1.8	–	ms	10% to 90% of the final output value
Stabilization time [10)]	t_S	–	–	10	ms	For full accuracy
Power up time [10)]	t_{UP}	–	–	5	ms	90% of the final output value
Broken wire: diagnosis response time [11)]	t_{OBD}	–	–	1	ms	
OBD Transistor On Resistance	R_{DSON}	–	–	160	Ω	V_{OUT} to V_{DD} or V_{OUT} to GND, @ 25°C
Junction temperature[12)]	T_j	– 30.2		134.8	°C	
Thermal resistance	$R_{thj\text{-}amb}$		245		K/W	
Lower Clamping level[1)]	$V_{CL,LOW}$	0	–	0.63	V	only version KP126C
Upper Clamping level[1)]	$V_{CL,HI}$	4.37	–	5	V	
Clamping level error[1)]	ΔV_{CL}	–30	–	30	mV	Upper and lower clamping level.
Clamping level resolution[1)]	$\Delta V_{C,R}$	–	10	15	mV	@ 25°C [13)]

1) Valid for customized transfer function. On request only.

2) See: **Figure 5 "Minimum Output Voltage Limit at Minimum Rated Pressure with Pull-Up Load" on Page 14**

3) @ $V_{DD,TYP}$, V_{OUT} is ratiometric to V_{DD} within its specified range

4) See: **Figure 4 "Maximum Output Voltage Limit at Maximum Rated Pressure with Pull-Down Load" on Page 14**

5) A peak supply current of up to 22 mA is possible during power up.

6) Offset voltage is the analog output voltage of the sensor if the mid pressure of the desired transfer function is applied.
Example of a transfer function:
$p_{N,\,MIN}$ = 20kPa, $p_{N,\,MAX}$ = 110kPa,
$V_{OUT,\,MIN}$ = 0.300V, $V_{OUT,\,MAX}$ = 4.750V
> p_{MID} = 65kPa, V_{OFF} = 2.525V
> V_{OFF} is within 1500 ... 3500mV

7) More details in chapter **“Overall Accuracy” on Page 17**
8) More details in **“Supply Voltage Influence (Ratiometric Error)” on Page 16**
9) 200 measurements in sequence, bandwidth limited to 40kHz
10) More details in **“Timings” on Page 15**
11) In the event of a broken wire (broken V_{DD} line or broken GND line), the output changes to certain voltage levels within the broken wire response time.
The OBD ranges are determined by the application circuitry and the optional clamping levels.
12) $T_{junction} = T_{ambient} + \Delta T_{c,j}$ (in steady-state condition, typical operation conditions)
13) Clamping level resolution is included in accuracy.

5.4 Electrical Details

5.4.1 Output Voltage versus Load

The output voltage limits depend on:

- the value of the external load resistor
- the connection mode (pull-up or pull-down)

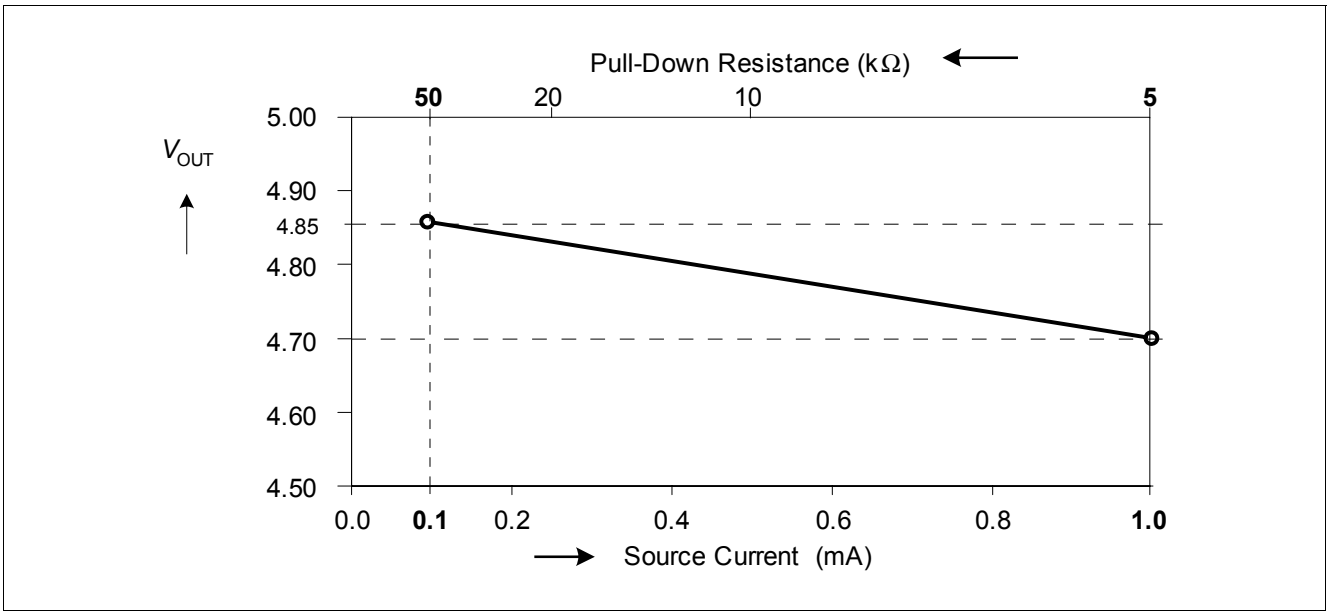


Figure 4 Maximum Output Voltage Limit at Maximum Rated Pressure with Pull-Down Load

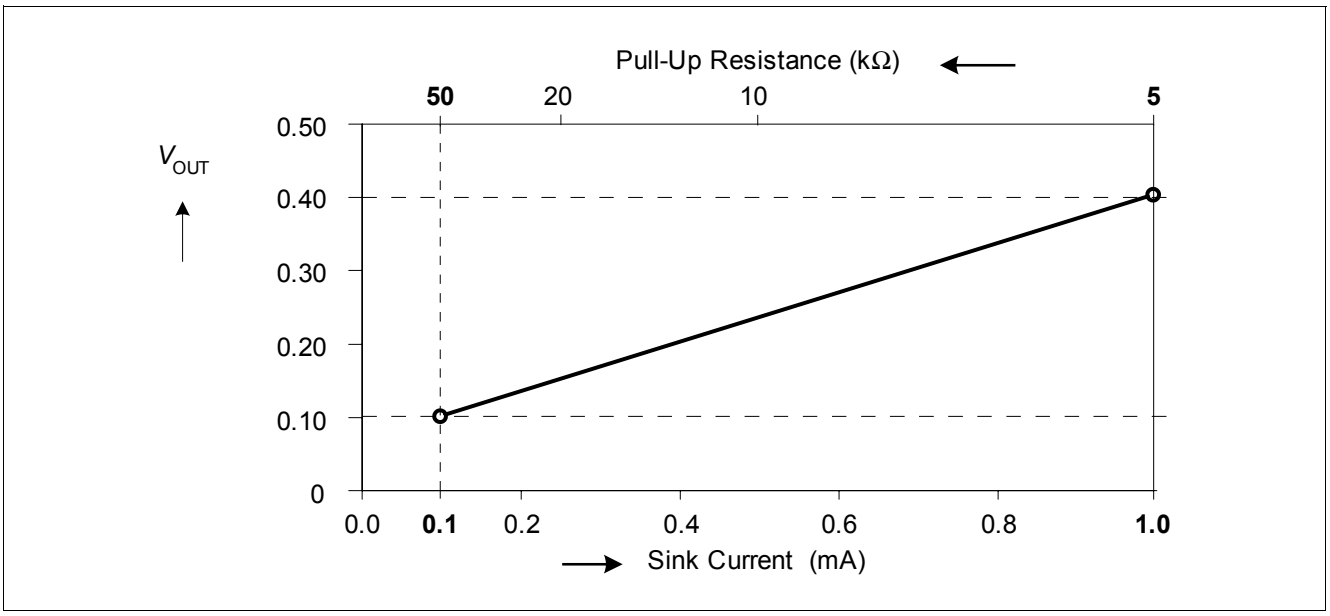


Figure 5 Minimum Output Voltage Limit at Minimum Rated Pressure with Pull-Up Load

Note: The values in the diagrams are valid for the entire specified temperature range.

5.4.2 Timings

Power-up Time

The power-on time t_{UP} is defined as the maximum time between the supply voltage reaching its operating range and the output voltage reaching 90% of its final value.

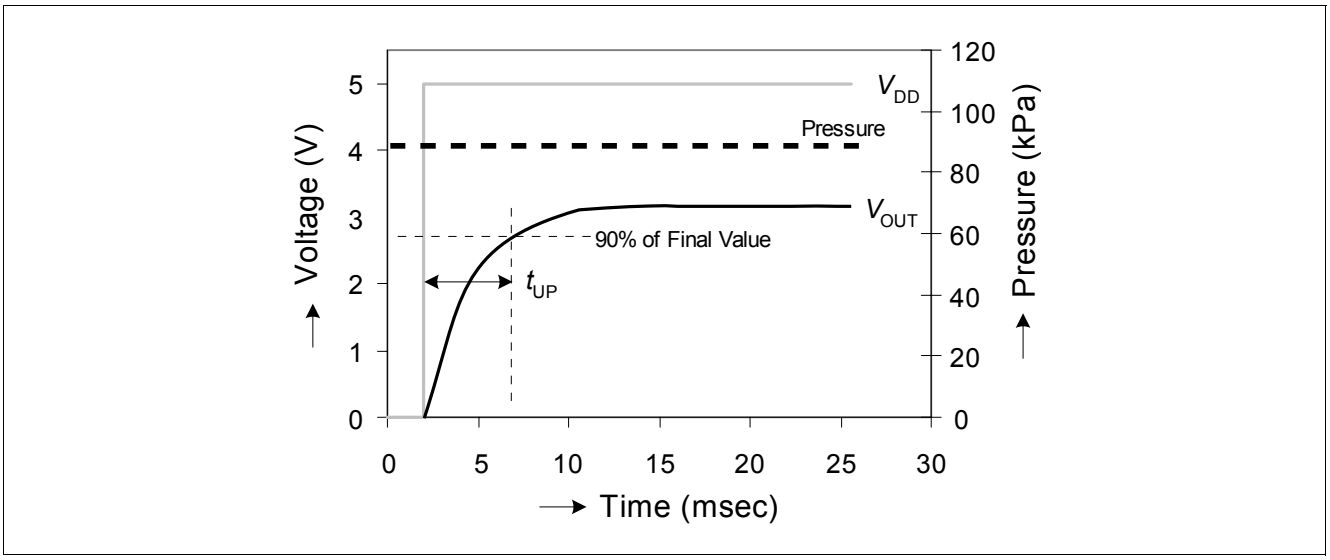


Figure 6 Power-up Time

Response Time and Stabilization Time

The Response Time t_R is defined as the time for the incremental output change to go from 10% to 90% of its final value after a specified pressure step.

The Stabilization Time t_S is defined as the time required for the output voltage to meet the specified accuracy after the pressure has been stabilized.

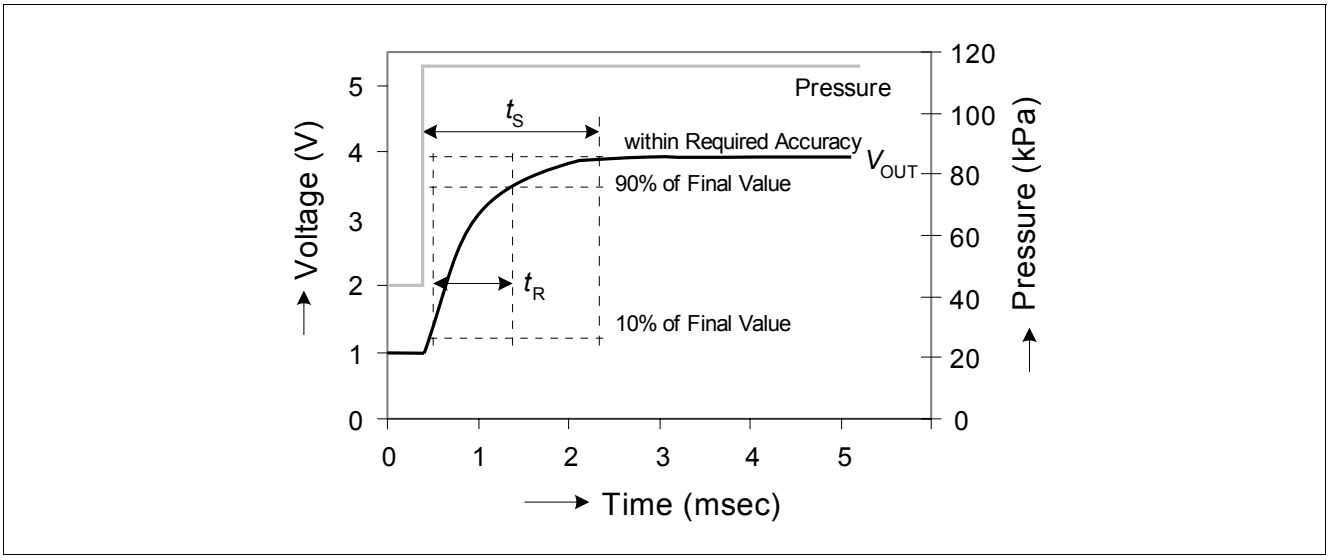


Figure 7 Response Time and Stabilization Time

6 Accuracy

The accuracy of the KP126 sensor is influenced by the supply voltage (ratiometric error) and by pressure, temperature and aging. The specified value represents the theoretical value, when the actual pressure is multiplied with the transfer function, see **Figure 3**. The error equals the deviation between the measured output voltage value and the specified output voltage value.

6.1 Supply Voltage Influence (Ratiometric Error)

Definition

Ideally, the sensor is ratiometric – the output (V_{OUT}) scales by the same ratio that V_{DD} increases or decreases. The ratiometric error is defined as the difference between the ratio that V_{DD} changed and the ratio that V_{OUT} changed, expressed as a percentage:

$$E_{RAT}(\%) = \frac{V_{OUT}(@V_{DD}) - V_{OUT}(@5V) \times \frac{V_{DD}}{5V}}{5V} \times 100\%$$

The output voltage V_{OUT} is ratiometric to V_{DD}, within the range provided in **Table 2**.
V_{DD} must be within the operating range specified in **Table 4**.

Table 6 Ratiometric Error

Supply Voltage (V)	Max. Ratiometric Error (% of $V_{DD,TYP}$)
$V_{DD,MIN}$	± 0.5
$V_{DD,TYP}$	0
$V_{DD,MAX}$	± 0.5

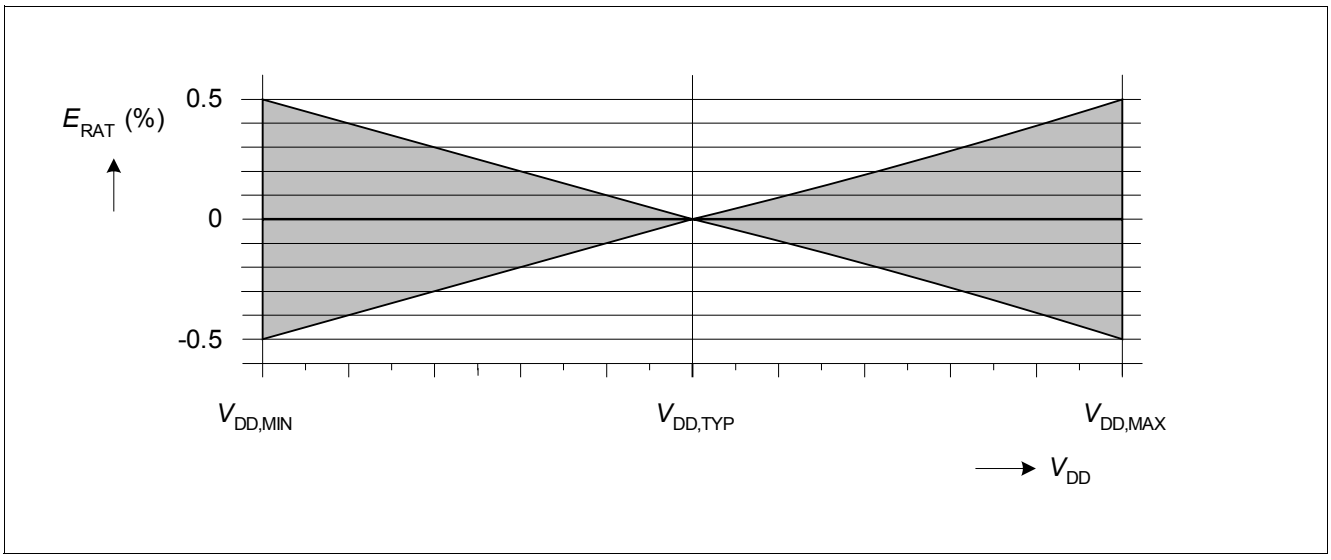


Figure 8 Ratiometric Error

6.2 Overall Accuracy

Overall accuracy covers the entire pressure and temperature range from all sources of error including the following:

- **Pressure**:
  Output deviation from target transfer function over the specified pressure range.
- **Temperature**:
  Output deviation over the temperature range.
- **Aging**
  All drifting parameters during operating time.

Note: Ratiometric signal error is not included in the overall accuracy. For error measurements, the supply voltage must have the nominal value ($V_{DD} = V_{DD,TYP}$).

The error band is determined by three continuous lines through four relevant break points:

Table 7 Accuracy

Temperature Point (°C)	Error (kPa)	Error Multiplier
– 40	± 2.0	2
0	± 1.0	1
85	± 1.0	1
125	± 2.0	2

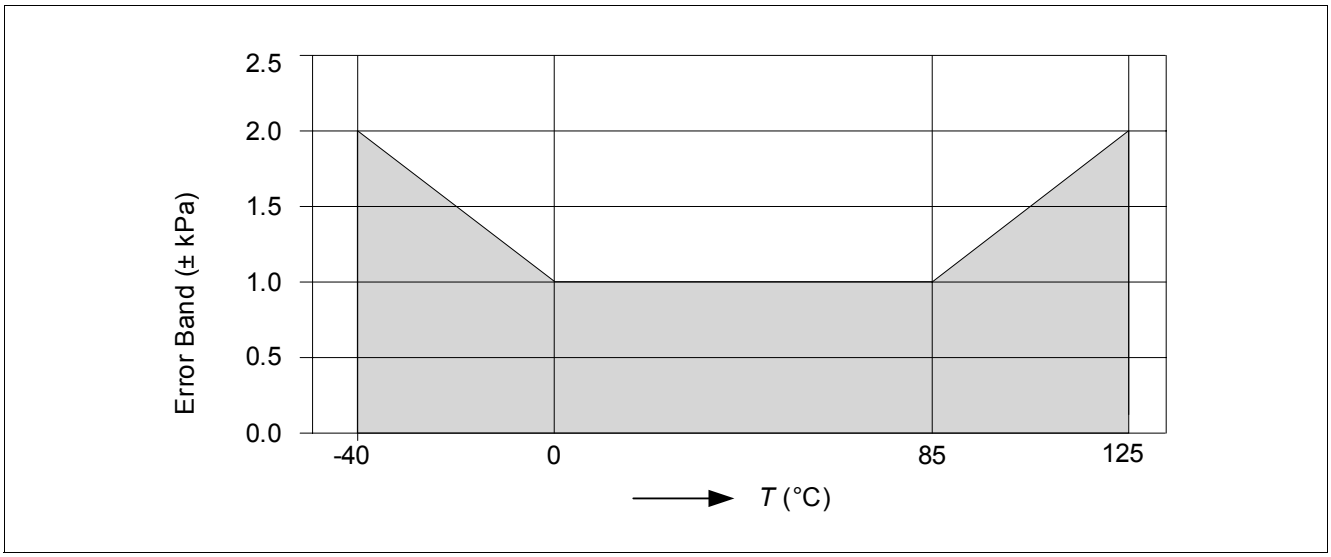


Figure 9 Overall Error Over Temperature

7 Application Circuit

It is recommended to protect the KP126 pressure sensor IC against overload voltage and electro-magnetic interference (as shown in **Figure 10**).

The output circuitry acts as a low-pass decoupling filter between the sensor IC output and the A/D input of the microcontroller.

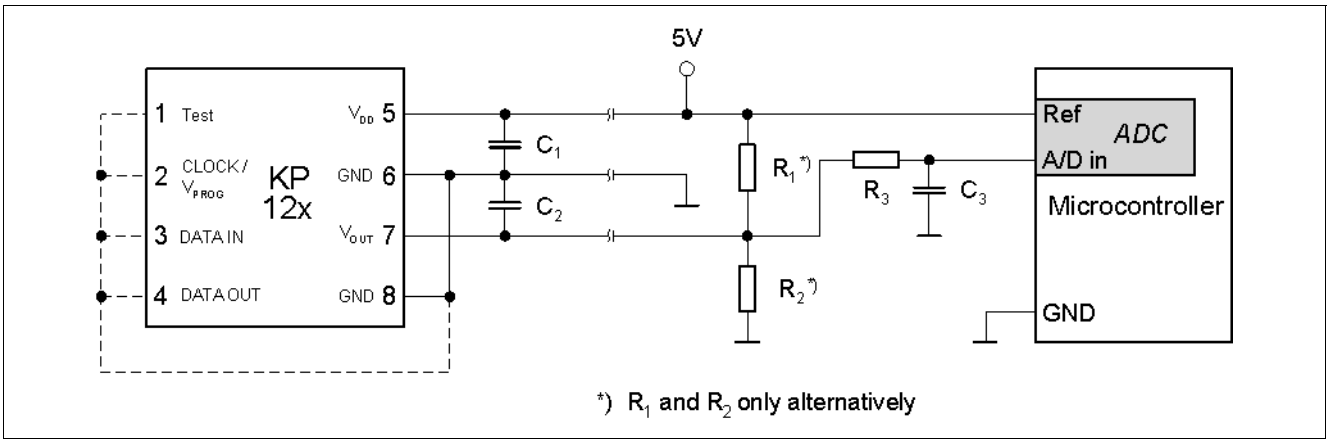


Figure 10 Application Circuitry for Evaluation

Note: It is recommended to leave digital PINs CLOCK/V_{PROG}, DATA IN and DATA OUT floating. If these PINs are grounded, it is recommended to connect both GND PINs.

Table 8 Component Values

Component	Symbol	Values			Unit	Note
		Min.	Typ.	Max.		
Pull-Up Resistor	R_1	5	59	100	kΩ	Only 1 resistor allowed
Pull-Down Resistor	R_2	5	59	100	kΩ	
Low Pass Resistor	R_3	3.9	22	100	kΩ	
Supply Blocking Capacitor	C_1	10	100	100	nF	
Output Blocking Capacitor	C_2	0	100	100	nF	
Low Pass Capacitor	C_3	10	100	100	nF	

Note: The value of load resistor R_1 or R_2 determines the current driven by the device.

8 Package

As well as using “green” materials, the P**G**-DSOF-8-12 package is optimized regarding mechanical stress influences. The package fulfills the solder conditions for lead-free board assembly.

In the application it is recommended to ensure that the same pressure is applied to the whole package.

The KP126 is supplied with a removable plastic cap (refer to **Figure 12**). The flat surface of this cap on top of the package allows handling with standard pick-and-place tools.

After soldering the device to the printed circuit board (PCB), the cap on the PG-DSOF-8-12 may be removed. When removing the protective cap, care should be taken to avoid damage to the device.

In some applications, such as for barometric measurements, it may be appropriate to leave the protective cap on the package after the soldering process. Damage to the gel is prevented. The four splits in the cap side allow a sufficient pressure coupling.

9 Package Outlines

9.1 Package Dimensions

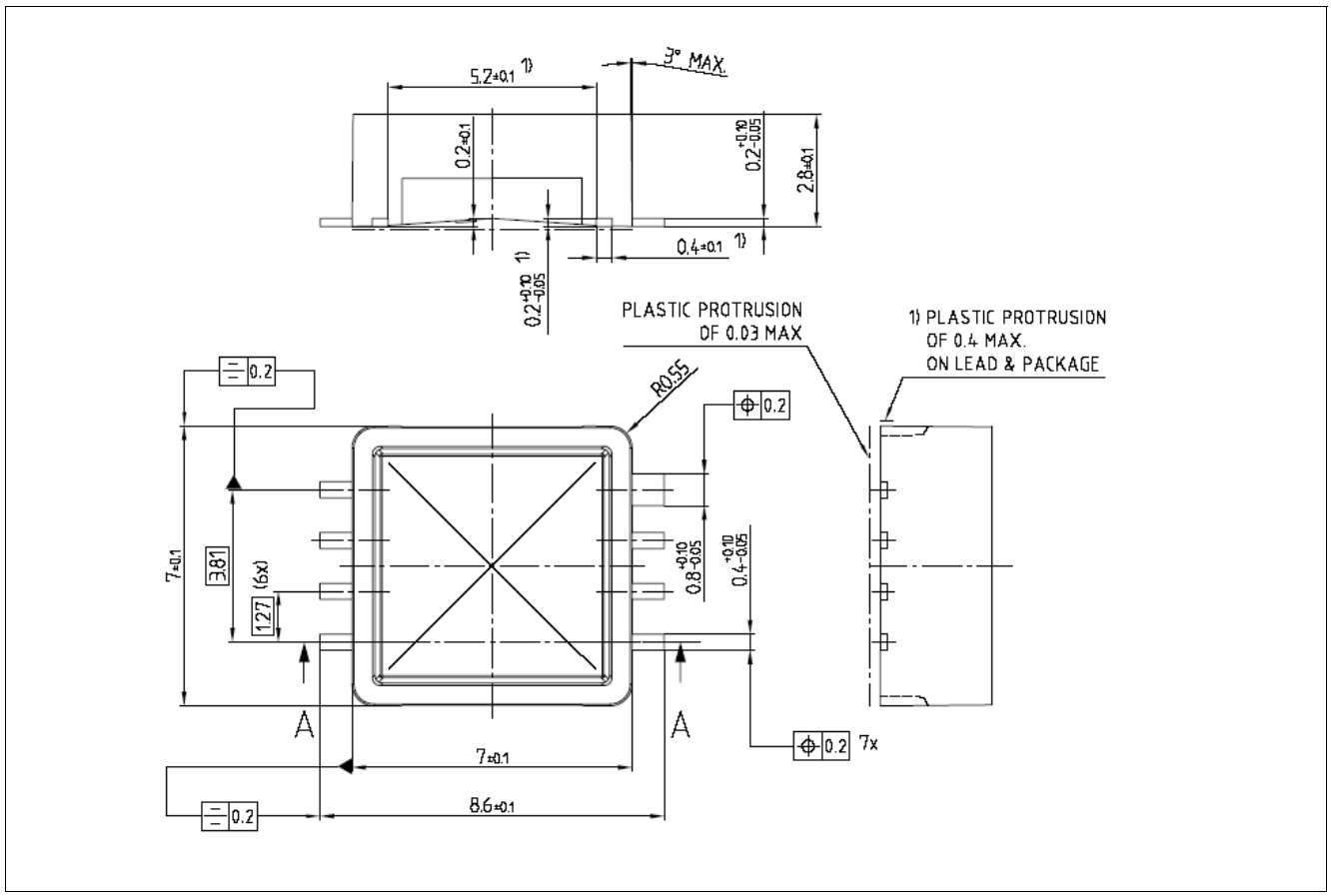


Figure 11 Package

9.2 Cap dimensions

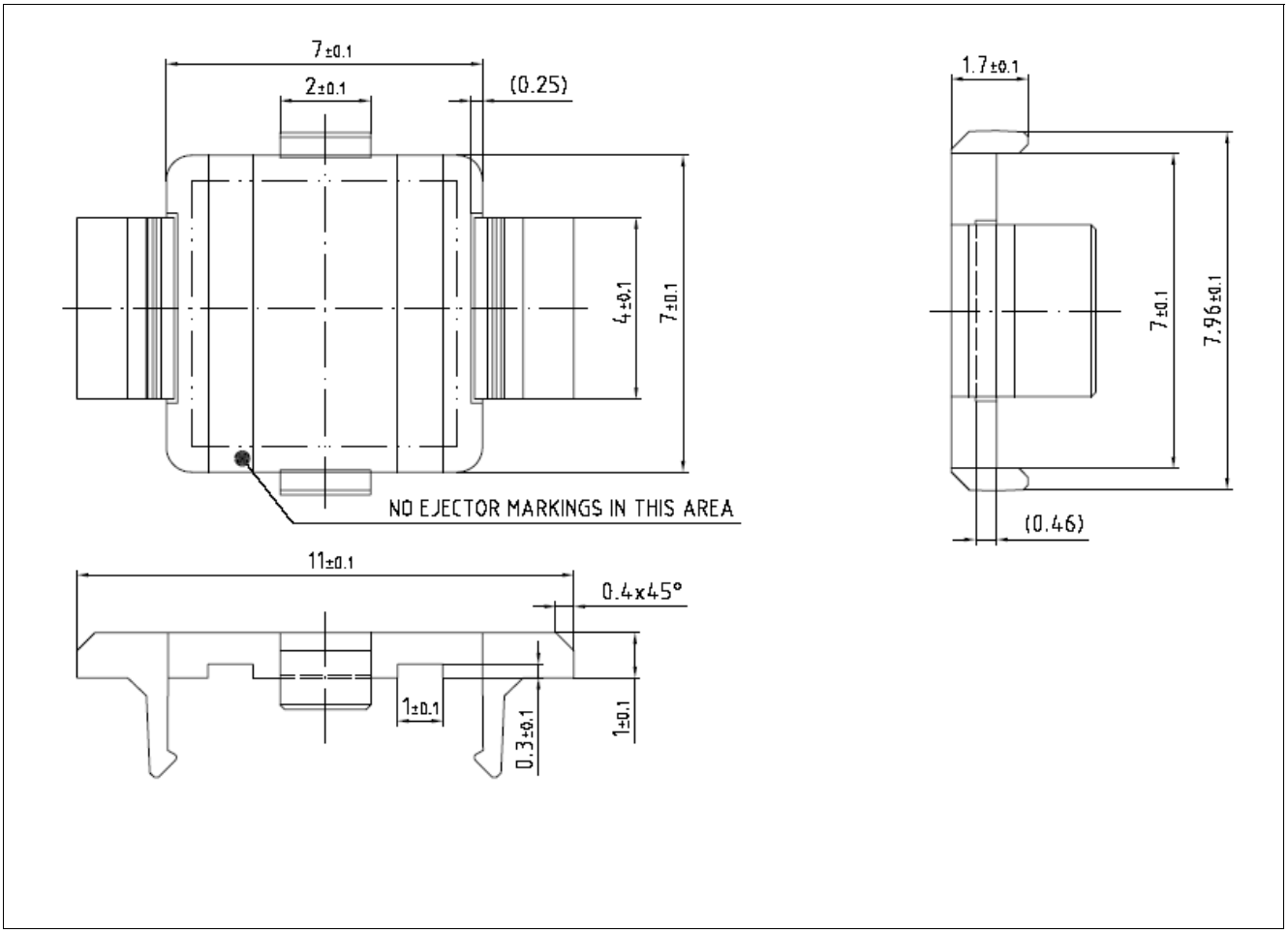


Figure 12 Cap Dimensions

9.3 Footprint

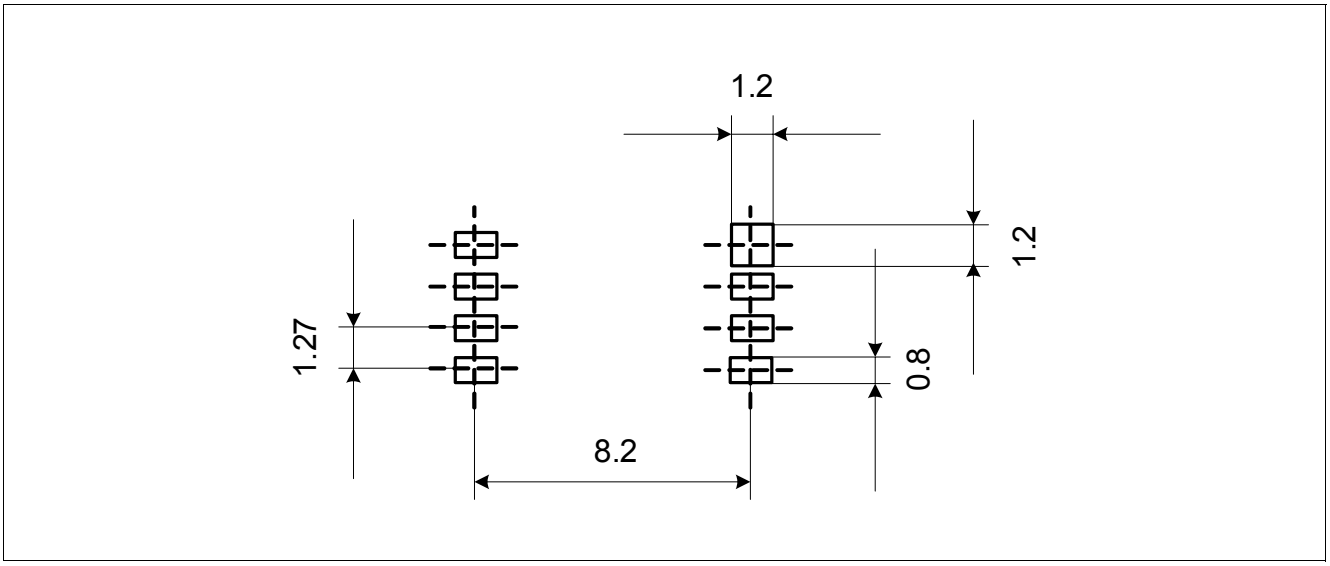


Figure 13 Footprint

10 EMC Requirements

10.1 EM Immunity by Direct Power Injection

The KP126 test is compliant to EMC requirements for Direct Power Injection (DPI) described in

- ISO 11452-7 11-95
- IEC 62132-3 01-00.

10.2 EM Immunity by Electrical Fast Transients

The KP126 test is compliant to EMC requirements for Electrical Fast Transients (EFT) according to the hardware set up shown in **Figure 14**, which is based on

- ISO 7637-1 08-00
- ISO/CD 7637-2 02-99
- ISO 7637-3 11-95

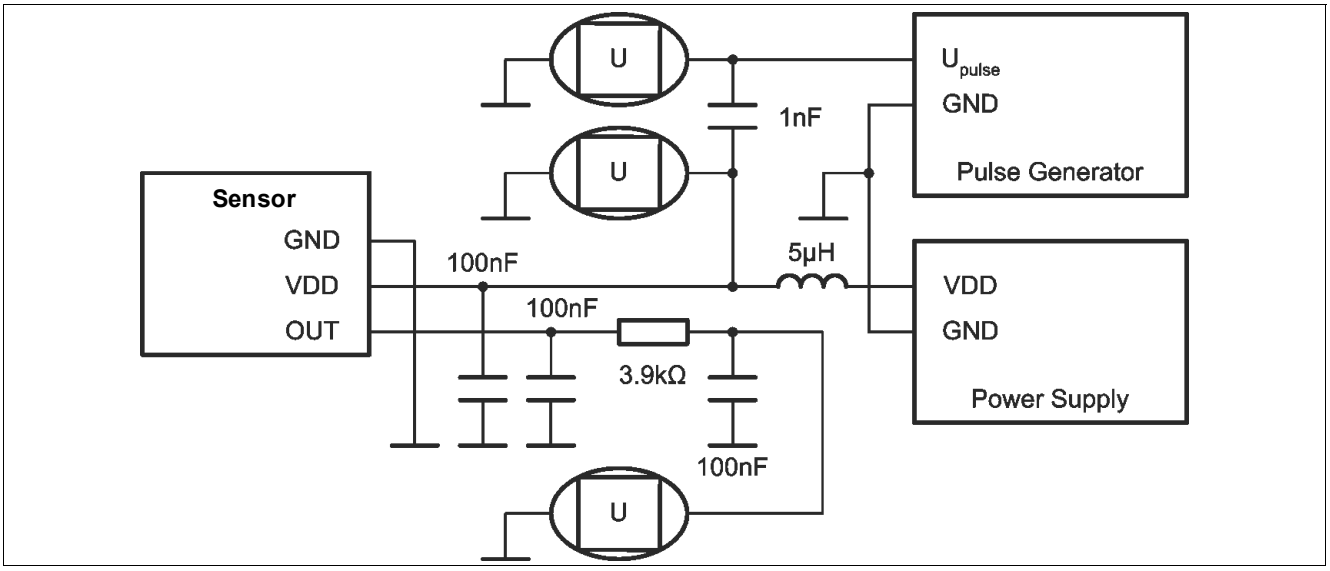


Figure 14 Hardware Set Up for Electrical Fast Transients

11 Identification Code

The identification code is provided in a machine-readable format. The date and sales code are provided in human-readable format.

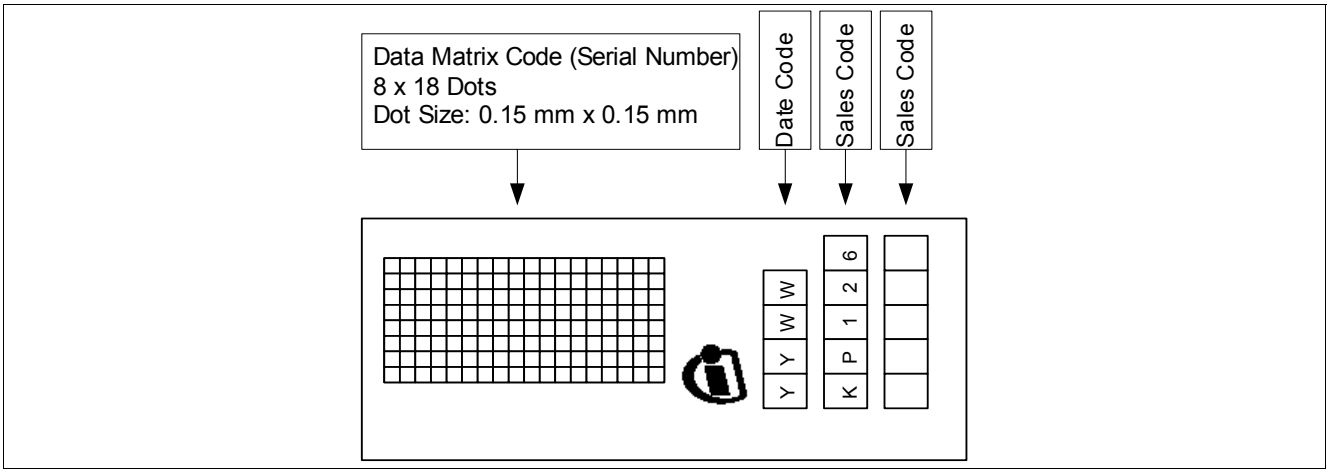


Figure 15 Sensor Identification Code

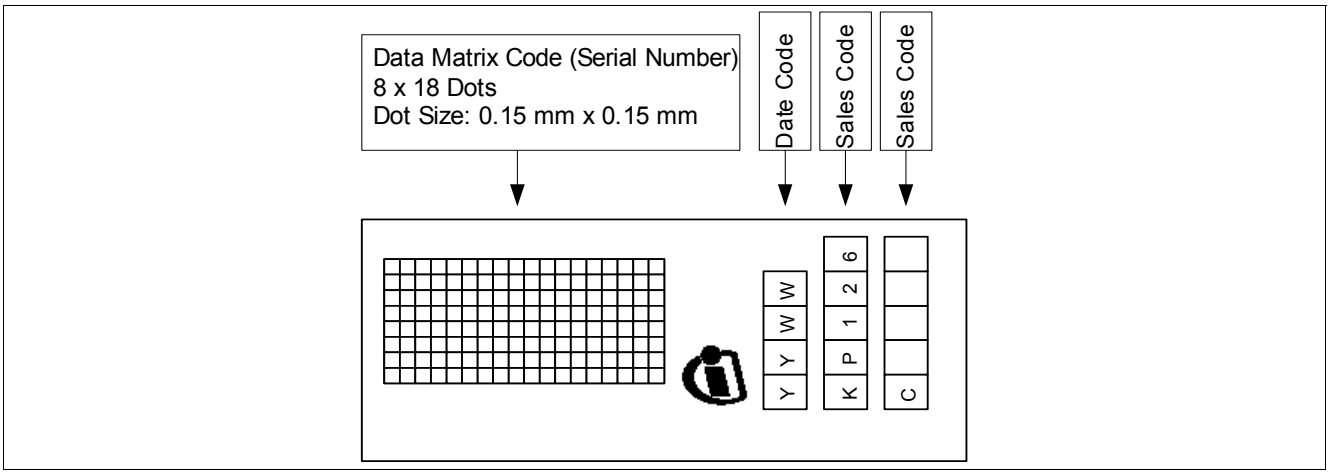


Figure 16 Sensor Identification Code with Clamping[1)]

The marking for the KP126 is on the same side of the package as pin 8.

Date code definition:

WW: work week (1…53)

YY: year (06…99)

Data Matrix Code: 8 x 18 Dots, Dot Size: 0.15 mm x 0.15 mm

1) Valid for customized transfer function. On request only.

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