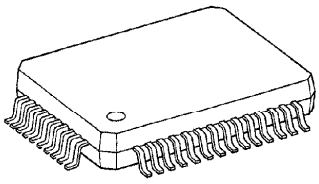
TENTATIVE TOSHIBA BIPOLAR LINEAR INTEGRATED CIRCUIT SILICON MONOLITHIC

TA2065F

CD FOCUS TRACKING SERVO LSI

The TA2065F is a 3-beam type PUH compatible focus tracking servo LSI to be used in the CD player system. In combination with a CMOS single chip processor TC9236AF / TC9263AF / TC9283F / TC9284AF, a CD player system can be composed very simply.



QFP48-P-1014-0.80

Weight : 0.83g (Typ.)

FEATURES

- Built-in RF amp, focus error amp, and tracking error amp.
- Built-in focus tracking servo amp.
- Built-in phase compensation amp and LPF amp.
- Built-in ALPC amp.
- Connections between PUH and power driver IC for motor driver allow simplified structuring of CD player system.
- Double speed operation is possible.
- Low voltage operation is possible. (3.5~5.5V)

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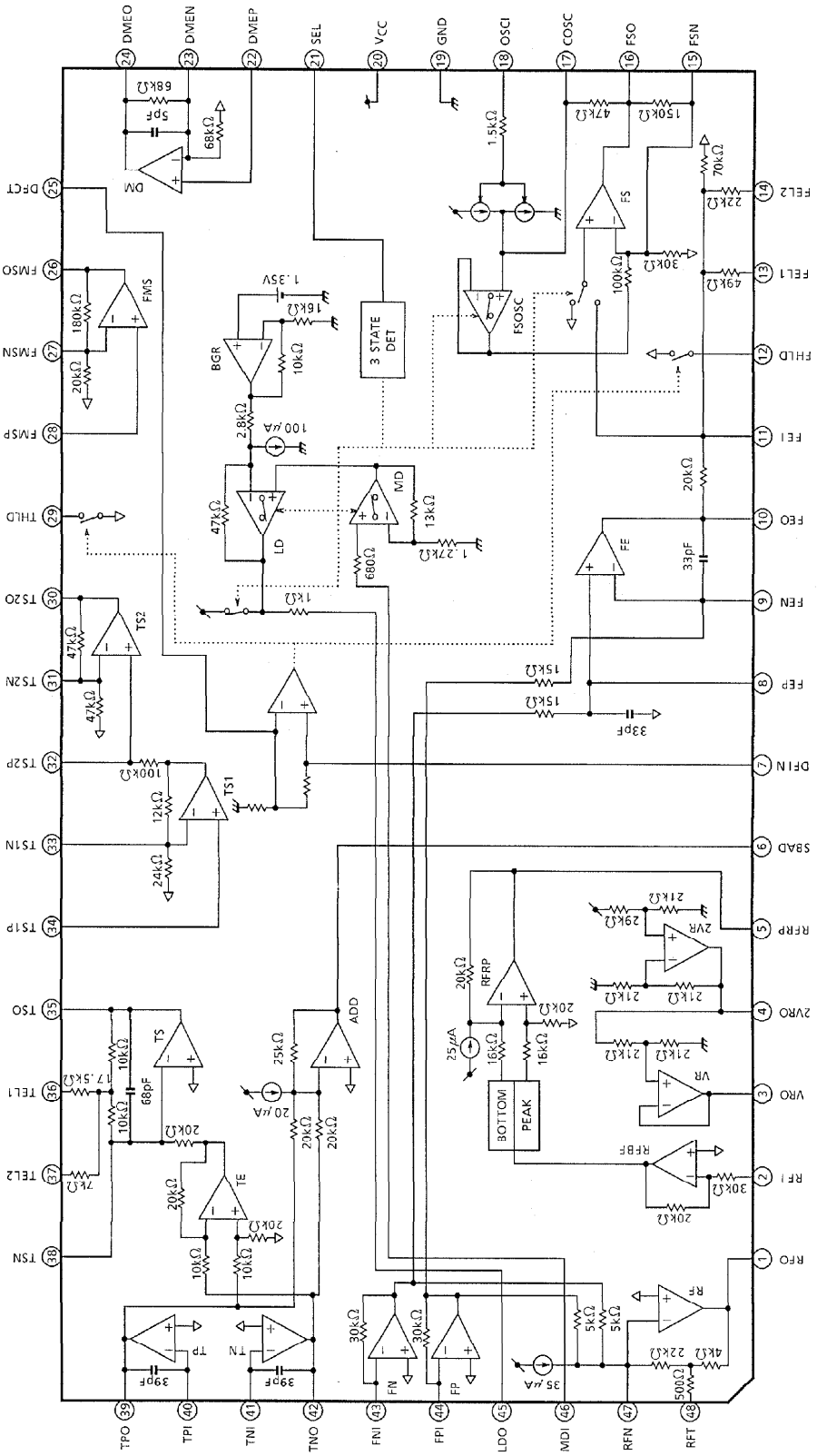
BLOCK DIAGRAM



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PIN FUNCTION

PIN No.	SYMBOL	I/O	FUNCTIONAL DESCRIPTION	REMARKS
1	RFO	O	RF amp (RF AMP) output terminal.	
2	RFI	I	RF ripple signal generating circuit input terminal.	Connected to RFO through C.
3	VRO	O	VR amp output terminal.	
4	2VRO	O	2VR amp output terminal.	
5	RFRP	O	RF ripple signal output terminal.	
6	SBAD	O	Defects detection signal output terminal.	
7	DFIN	I	Defect detecting comparator positive phase input terminal.	
8	FEP	I	Focus error balance adjusting input terminal.	Adjusting semi-fixed resistor is connected.
9	FEN	I	Focus error amp (FE AMP) negative phase input terminal.	
10	FEO	O	Focus error amp (FE AMP) output terminal.	
11	FEI	I	Focus output amp (FS AMP) positive phase input terminal.	
12	FHLD	I	Hold switch terminal for defect.	
13	FEL1	I	Focus gain adjusting terminal.	
14	FEL2	I	Focus gain adjusting terminal.	
15	FSN	I	Focus output amp (FS AMP) negative phase input terminal.	
16	FSO	O	Focus output amp (FS AMP) output terminal.	
17	COSC	O	Focus search signal generating capacitor connecting terminal.	
18	OSCI	I	Focus search signal generating built-in current source control input terminal.	
19	GND	—	Ground terminal.	
20	V_{CC}	—	Power source terminal.	
21	SEL	I	Analog switch control signal input terminal.	
22	DMEP	I	Disc motor amp (DM AMP) positive phase input terminal.	
23	DMEN	I	Disc motor amp (DM AMP) negative phase input terminal.	
24	DMEO	O	Disc motor amp (DM AMP) output terminal.	
25	DFCT	I	Defect detecting comparator negative phase input terminal.	
26	FMSO	O	Feed motor output amp (FMS AMP) output terminal.	
27	FMSN	I	Feed motor output amp (FMS AMP) negative phase input terminal.	

PIN No.	SYMBOL	I / O	FUNCTIONAL DESCRIPTION	REMARKS
28	FMSP	I	Feed motor output amp (FMS AMP) positive phase input terminal.	
29	THLD	I	Hold switch terminal for defect.	
30	TS2O	O	Tracking servo amp 2 (TS2 AMP) output terminal.	
31	TS2N	I	Tracking servo amp 2 (TS2 AMP) negative phase input terminal.	
32	TS2P	I	Tracking servo amp 2 (TS2 AMP) positive phase input terminal.	
33	TS1N	I	Tracking servo amp 1 (TS1 AMP) negative phase input terminal.	
34	TS1P	I	Tracking servo amp 1 (TS1 AMP) positive phase input terminal.	
35	TSO	O	Tracking output amp (TS AMP) output terminal.	
36	TEL1	I	Tracking gain adjusting terminal.	
37	TEL2	I	Tracking gain adjusting terminal.	
38	TSN	I	Tracking output amp (TS AMP) negative phase input terminal.	
39	TPO	O	Sub-beam I-V amp output terminal.	Connected to TPI through adjusting feedback resistor.
40	TPI	I	Sub-beam I-V amp input terminal.	Connected to PIN diode E.
41	TNI	I	Sub-beam I-V amp input terminal.	Connected to PIN diode F.
42	TNO	O	Sub-beam I-V amp output terminal.	Connected to TNI through adjusting feedback resistor.
43	FNI	I	Main-beam I-V amp input terminal.	Connected to PIN diode A + C.
44	FPI	I	Main-beam I-V amp input terminal.	Connected to PIN diode B + D.
45	LDO	O	Laser diode amp output terminal.	Connected to laser diode circuit.
46	MDI	I	Monitor photo diode amp input terminal.	Connected to monitor photo diode.
47	RFN	I	RF amp negative phase input terminal.	
48	RFT	I	RF amp peaking terminal.	

MAXIMUM RATINGS (Ta = 25°C)

CHARACTERISTIC	SYMBOL	RATING	UNIT
Power Supply Voltage	V_{CC}	−0.3~12.0	V
Power Dissipation	P_D	890 (*)	mW
Operating Temperature	T_{opr}	−35~85	°C
Storage Temperature	T_{stg}	−55~150	°C

(*) Derated above 25°C in the proportion of 7.1mW / °C.

ELECTRICAL CHARACTERISTICS (Unless otherwise specified, V_{CC} = 5V, Ta = 25°C)

CHARACTERISTIC		SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Power Source	Power Supply Voltage	V_{CC}	—		3.5	5.0	5.5	V
	Power Supply Current	I_{CC}	—	SEL = HiZ	14.0	24.0	32.0	mA
Reference Power Supply 2VREF [4]	Reference Voltage	2VR	—		4.0	4.2	4.4	V
	Output Current	I_{OH2}	—	ΔV = −0.1V	5.0	—	—	mA
	Input Current	I_{OL2}	—	ΔV = +0.1V	0.2	—	—	mA
Reference Power Supply VREF [3]	Reference Voltage	VR	—		2.0	2.1	2.2	V
	Reference Voltage Limit	ΔVR	—	2 × VR / 2VR − 1	−3.0	0.0	3.0	%
	Output Current	I_{OH1}	—	ΔV = −0.1V	5.0	—	—	mA
	Input Current	I_{OL1}	—	ΔV = +0.1V	5.0	—	—	mA
FS FEI [11] →FSO [16]	Voltage Gain	G_V	—	f = 1kHz	5.4	6.0	6.6	V / V
	Input Operating Voltage	VI	—		1.0	—	4.4	V
	Output Offset Voltage	V_{OS}	—	VR reference	−12	—	12	mV
	Total Harmonic Distortion	THD	—	f = 1kHz, V_{FSO} = $1V_{p-p}$	—	−65	—	dB
	Upper Limit Output Voltage	V_{OH}	—	GND reference	3.8	—	—	V
	Lower Limit Output Voltage	V_{OL}	—	GND reference	—	—	0.5	V
OSC OSCI [18] →FSO [16]	Output Amplitude	V_O	—	R (OSCI) = 15kΩ f (OSCI) = 0.5Hz (CMOS level)	—	1.6	—	V_{p-p}
	Output Offset Voltage	V_{OS}	—	OSCI = HiZ	−50	—	50	mV
	Output Switch Isolation	V_{ISO}	—	f_{COSC} = 1kHz, SEL = H	—	−65	—	dB

CHARACTERISTIC		SYMBOL	TEST CIR-CUIT	TEST CONDITION		MIN.	TYP.	MAX.	UNIT
APC MDI [46] →LDO [45]	Voltage Gain	G_V	—	f = 1kHz		170	200	230	V / V
	Operation Reference Voltage	V_{MDI}	—	V_{LDO} = 3.5V		170	178	192	mV
	LD Off Voltage	V_{LDOF}	—	V_{CC} reference, SEL = L		− 0.7	—	—	V
	Input Bias Current	I_I	—			− 200	—	200	nA
FE FNI (FPI) [43] (44) →FEO [10]	Transfer Resistance	R_T	—	f = 1kHz FEN − FEO = 68kΩ FEP − VR = 68kΩ		122	136	150	kΩ
	Gain Balance	GB	—	f = 1kHz FEN − FEO = 68kΩ FEP − VR = 68kΩ		− 1.0	—	1.0	dB
	Frequency Characteristic	fc	—			50	70	90	kHz
	Output Offset Voltage	V_{OS}	—			− 50	—	50	mV
	Total Harmonic Distortion	THD	—	f = 1kHz, V_{FEO} = 1.6V_{p-p}		—	− 65	—	dB
	Upper Limit Output Voltage	V_{OH}	—	GND reference		3.8	—	—	V
	Lower Limit Output Voltage	V_{OL}	—	GND reference		—	—	0.5	V
	Permissive Load Resistance	R_{LM}	—			10	—	—	kΩ
FE FEO [10] →FEI [11]	Voltage Gain 1	G_{V1}	—	f = 1kHz	FEL1 = FEL2 = VR	0.36	0.38	0.40	V / V
	Voltage Gain 2	G_{V2}			FEL1 = HiZ, FEL2 = VR	0.44	0.46	0.48	
	Voltage Gain 3	G_{V3}			FEL1 = VR, FEL2 = HiZ	0.56	0.59	0.62	
	Voltage Gain 4	G_{V4}			FEL1 = FEL2 = HiZ	0.74	0.78	0.82	
RF FPI (FNI) [44] (43) →RFO [1]	Transfer Resistance	R_T	—	f = 100kHz		125	156	187	kΩ
	Frequency Characteristic	fc	—			—	3.0	—	MHz
	Output Slew Rate	SR	—	C_{RFO} = 20pF		—	20	—	V / μs
	Total Harmonic Distortion	THD	—	f = 100kHz, V_{RF} = 1.4V_{p-p}		—	− 50	—	dB
	Operation Reference Voltage	V_{OPR}	—	VR reference		− 1.21	− 1.10	− 0.99	V

CHARACTERISTIC		SYMBOL	TEST CIR-CUIT	TEST CONDITION		MIN.	TYP.	MAX.	UNIT
RF FPI (FNI) [44] (43) →RFO [1]	Upper Limit Output Voltage	V_{OH}	—	GND reference		3.6	—	—	V
	Lower Limit Output Voltage	V_{OL}	—	GND reference		—	—	0.7	V
	Permissive Load Resistance	R_{LM}	—			10	—	—	kΩ
RFRP RFI [2] →RFRP [5]	Voltage Gain	G_V	—	f = 1kHz		0.75	0.83	0.92	V / V
	Input Operating Voltage	V_I	—	GND reference		1.0	—	3.4	V
	Peak Detecting Frequency Characteristic	f_{CPD}	—			—	80	—	kHz
	Bottom Detecting Frequency Characteristic	f_{CBD}	—			—	80	—	kHz
	Operation Reference Voltage 1	V_{OPR1}	—	VR reference No signal		− 0.55	− 0.50	− 0.45	V
	Operation Reference Voltage 2	V_{OPR2}	—	f = 700kHz, 1.4V_{p-p} VR reference		0.50	0.55	0.60	V
	Permissive Load Resistance	R_{LM}	—			10	—	—	kΩ
TS TPI (TNI) [40] (41) →TSO [35]	Transfer Resistance 1	R_{T1}	—	R_{NF} (TP, TN) = 180kΩ	TEL1 = TEL2 = HiZ	324	360	396	kΩ
	Transfer Resistance 2	R_{T2}			TEL1 = VR, TEL2 = HiZ	417	463	509	
	Transfer Resistance 3	R_{T3}			TEL1 = HiZ, TEL2 = VR	555	617	679	
	Transfer Resistance 4	R_{T4}			TEL1 = TEL2 = VR	648	720	792	
	Gain Balance	GB	—			− 1.0	—	1.0	dB
	Frequency Characteristic	fc	—			—	22	—	kHz
	Output Slew Rate	SR	—	C_{TSO} = 0.022μF		—	500	—	V / ms
	Output Offset Voltage	V_{OS}	—	VR reference		− 50	—	50	mV

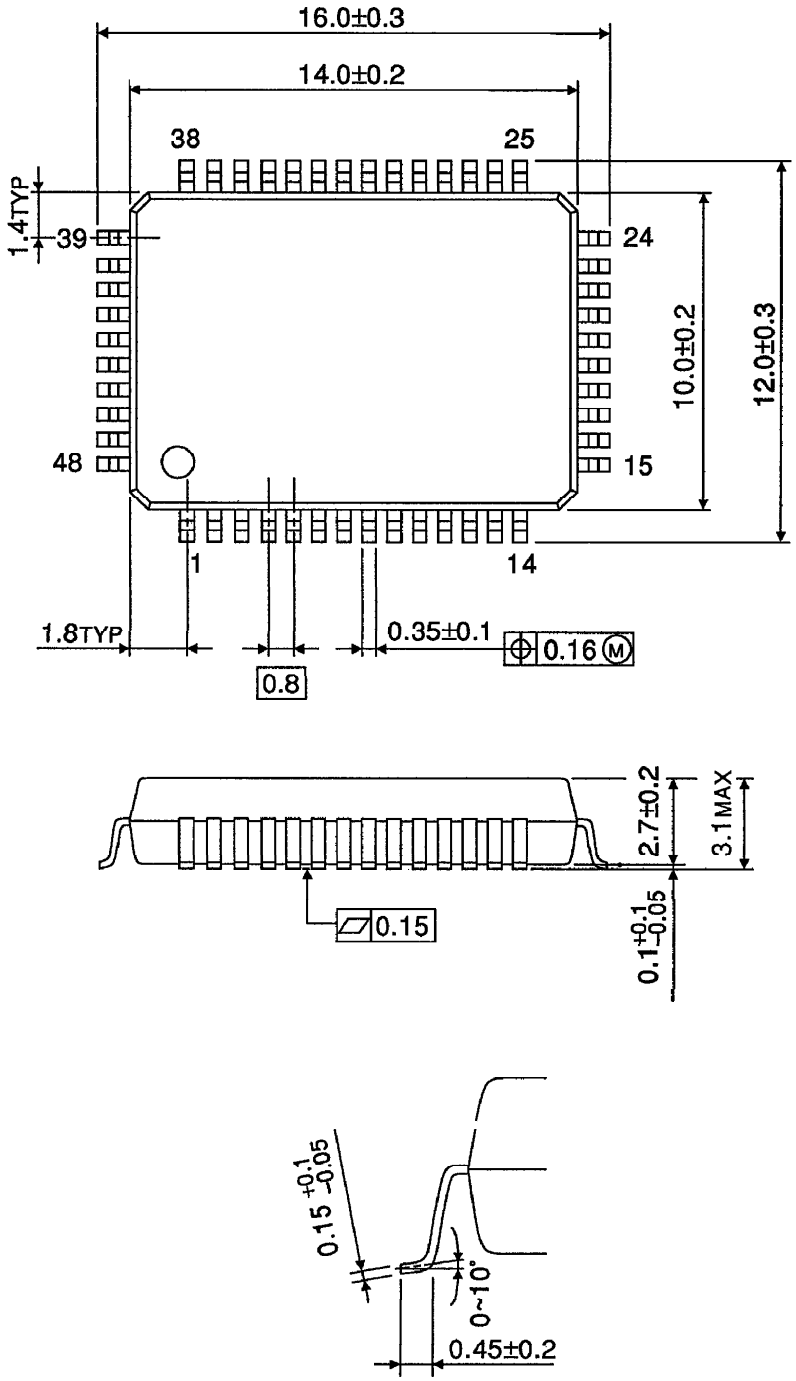
CHARACTERISTIC		SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
TS TPI (TNI) [40] (41) →TSO [35]	Total Harmonic Distortion	THD	—	f = 1kHz, V_{TS} = 0.8V_{p-p}	—	– 65	—	dB
	Upper Limit Output Voltage	V_{OH}	—	GND reference	3.8	—	—	V
	Lower Limit Output Voltage	V_{OL}	—	GND reference	—	—	0.5	V
	Permissive Load Resistance	R_{LM}	—		10	—	—	kΩ
SBAD TPI (TNI) [40] (41) →SBAD [6]	Transfer Resistance	R_T	—	f = 1kHz R_{NF} (TP, TN) = 180kΩ	203	225	248	kΩ
	Frequency Characteristic	fc	—		—	22	—	kHz
	Total Harmonic Distortion	THD	—	f = 1kHz V_{SBAD} = 1.0V_{p-p}	—	– 65	—	dB
	Operation Reference Voltage	V_{OPR}	—	VR reference	– 0.55	– 0.50	– 0.45	V
	Upper Limit Output Voltage	V_{OH}	—	GND reference	3.8	—	—	V
	Lower Limit Output Voltage	V_{OL}	—	GND reference	—	—	0.5	V
	Permissive Load Resistance	R_{LM}	—		10	—	—	kΩ
TS1 TS1P [34] →TS2P [32]	Voltage Gain 1	G_{V1}	—	f = 1kHz, TS2P = OPEN	1.43	1.50	1.58	V / V
	Voltage Gain 2	G_{V2}		f = 1kHz, TS2P – VR = 18kΩ	0.18	0.23	0.27	
	Input Operating Voltage	V_I	—		1.0	—	4.4	V
	Output Offset Voltage	V_{OS}	—		– 10	—	10	mV
	Total Harmonic Distortion	THD	—	f = 1kHz, V_{TS2P} = 1V_{p-p}	—	– 65	—	dB
	Upper Limit Output Voltage	V_{OH}	—		3.8	—	—	V
	Lower Limit Output Voltage	V_{OL}	—		—	—	0.5	V
	Input Bias Current	I_I	—		– 100	—	100	nA

CHARACTERISTIC		SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
TS2 TS2P (TS2N) [32] (31) →TS2O [30]	Voltage Gain	G_V	—	f = 1kHz	1.9	2.0	2.1	V / V
	Input Operating Voltage	V_I	—	GND reference	1.0	—	4.4	V
	Output Offset Voltage	V_{OS}	—	VR reference	− 10	—	10	mV
	Total Harmonic Distortion	THD	—	f = 1kHz, $V_{TS2O} = 1V_{p-p}$	—	− 65	—	dB
	Upper Limit Output Voltage	V_{OH}	—	GND reference	3.8	—	—	V
	Lower Limit Output Voltage	V_{OL}	—	GND reference	—	—	0.5	V
	Input Bias Current	I_I	—		− 100	—	100	nA
FMS FMSP [28] →FMSO [26]	Voltage Gain	G_V	—	f = 500Hz	9.5	10.0	10.5	V / V
	Frequency Characteristic	fc	—		—	200	—	kHz
	Input Operating Voltage	V_I	—	GND reference	1.0	—	4.4	V
	Output Offset Voltage	V_{OS}	—	VR reference	− 50	—	50	mV
	Total Harmonic Distortion	THD	—	f = 500Hz $V_{FMSO} = 1V_{p-p}$	—	− 65	—	dB
	Upper Limit Output Voltage	V_{OH}	—	GND reference	3.8	—	—	V
	Lower Limit Output Voltage	V_{OL}	—	GND reference	—	—	0.5	V
	Input Bias Current	I_I	—		− 100	—	100	nA

CHARACTERISTIC		SYMBOL	TEST CIR-CUIT	TEST CONDITION		MIN.	TYP.	MAX.	UNIT
DM DMEP [22] → DMEO [24]	Voltage Gain 1	G_{V1}	—	f = 1kHz	DMEN = OPEN	1.9	2.0	2.1	V / V
	Voltage Gain 2	G_{V2}			DMEN – VR = 15kΩ	5.23	6.53	7.84	
	Frequency Characteristic	fc	—			—	600	—	kHz
	Input Operating Voltage	V_I	—	GND reference		1.0	—	4.4	V
	Output Offset Voltage	V_{OS}	—	VR reference		– 10	—	10	mV
	Total Harmonic Distortion	THD	—	f = 1kHz V_{DMEO} = $1V_{p-p}$		—	– 65	—	dB
	Upper Limit Output Voltage	V_{OH}	—	GND reference		3.8	—	—	V
	Lower Limit Output Voltage	V_{OL}	—	GND reference		—	—	0.5	V
DFCT	Voltage Gain	G_V	—	GND reference, DFIN→DFCT		0.86	0.91	0.95	V / V
	Supply Voltage	V_I	—	GND reference FHLD, THLD		0.0	—	5.0	V
	Attenuation Level	ATT	—	VR reference f = 1kHz, $4V_{p-p}$		—	– 40	—	dB
	On Voltage	V_{ON}	—	VR reference		– 5	—	5	mV

OUTLINE DRAWING

QFP48-P-1014-0.80 Unit : mm



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