

Power Booster Amplifier



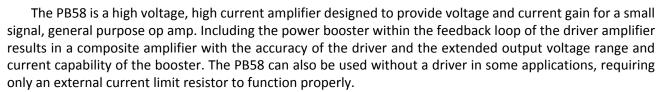
FEATURES

- Wide Supply Range ±15V to ±150V
- High Output Current —
 1.5A Continuous (PB58)
 2.0A Continuous (PB58A)
- Voltage and Current Gain
- High Slew Rate 50V/μs typical (PB58)
 75V/μs minimum (PB58A)
- Programmable Output Current Limit
- High Power Bandwidth 320 kHz typical
- Low Quiescent Current 12mA typical
- Evaluation Kit See EK50



- High Voltage Instrumentation
- Electrostatic Transducers & Deflection
- Programmable Power Supplies up to 280V p-p





The output stage utilizes complementary MOSFETs, providing symmetrical output impedance and eliminating second breakdown limitations imposed by Bipolar Transistors. Internal feedback and gainset resistors are provided for a pin-strapable gain of 3. Additional gain can be achieved with a single external resistor. Compensation is not required for most driver/gain configurations, but can be accomplished with a single external capacitor. Enormous flexibility is provided through the choice of driver amplifier, current limit, supply voltage, voltage gain, and compensation.

This hybrid circuit utilizes a beryllia (BeO) substrate, thick film resistors, ceramic capacitors and semiconductor chips to maximize reliability, minimize size and give top performance.

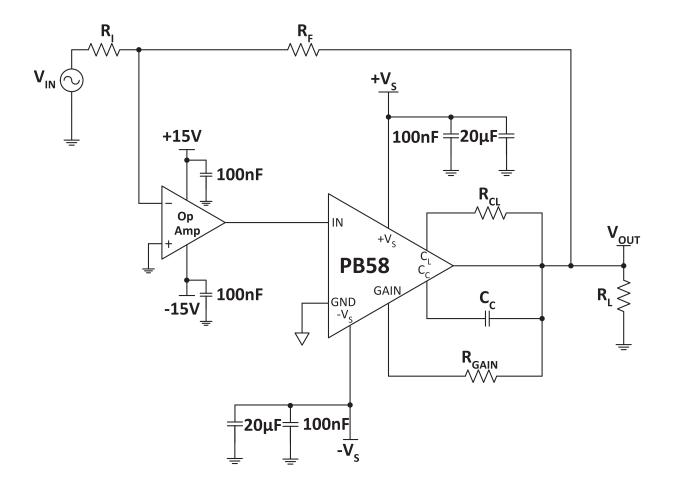
Ultrasonically bonded aluminum wires provide reliable interconnections at all operating temperatures. The 8-pin TO-3 package is electrically isolated and hermetically sealed using one-shot resistance welding. The use of compressible isolation washers voids the warranty.





TYPICAL CONNECTION

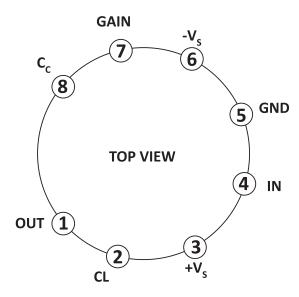
Figure 1: Typical Connection





PINOUT AND DESCRIPTION TABLE

Figure 2: External Connections



| Pin Number | Name | Description |
|------------|------|---|
| 1 | OUT | The output. Connect this pin to load and to the feedback resistors. |
| 2 | CL | Connect to the current limit resistor. Output current flows into/out of these pins through R_{CL} . The output pin and the load are connected to the other side of R_{CL} . |
| 3 | +Vs | The positive supply rail. |
| 4 | IN | The input. |
| 5 | GND | Ground. Connect to same ground as referenced by input amplifier. |
| 6 | -Vs | The negative supply rail. |
| 7 | GAIN | Gain resistor pin. Connect R _{GAIN} between GAIN and OUT. This will specify the gain for the power booster itself, not the composite amplifier. See applicable section. |
| 8 | СС | Compensation capacitor connection. Select value based on Phase Compensation. See applicable section. |

PB58 • PB58A



SPECIFICATIONS

The power supply voltage specified under typical (TYP) applies, $T_C = 25$ °C unless otherwise noted.

ABSOLUTE MAXIMUM RATINGS

| Parameter | Symbol | Min | Max | Units |
|---|------------------------------------|-----|------|-------|
| Supply Voltage, total | +V _s to -V _s | | 300 | V |
| Output Current, within SOA | I _O | | 2 | А |
| Power Dissipation, continuous @ $T_c = 25^{\circ}C^{1}$ | P _D | | 83 | W |
| Input Voltage, referred to COM | V _{IN} | | ±15 | V |
| Temperature, pin solder, 10s max. | | | 350 | °C |
| Temperature, junction ¹ | T _J | | 175 | °C |
| Temperature Range, storage | | -65 | +150 | °C |
| Operating Temperature Range, case | T _C | -55 | +125 | °C |

^{1.} Long term operation at the maximum junction temperature will result in reduced product life. Derate internal power dissipation to achieve high MTTF (Mean Time to Failure).



The PB58 is constructed from MOSFET transistors. ESD handling procedures must be observed. The internal substrate contains beryllia (BeO). Do not break the seal. If accidentally broken, do not crush, machine, or subject to temperatures in excess of 850°C to avoid generating toxic fumes.

INPUT

| Parameter | Test | PB58 | | | PB58A | | | Units |
|--------------------------------|--|------|-------|-------|-------|-----|------|--------|
| raidilletei | Conditions | Min | Тур | Max | Min | Тур | Max | Offics |
| Offset Voltage, initial | | | ±0.75 | ±1.75 | | * | ±1.0 | V |
| Offset Voltage vs. Temperature | Full temp range ¹ | | -4.5 | -7 | | * | * | mV/°C |
| Input Impedance, DC | | 25 | 50 | | * | * | | kΩ |
| Input Capacitance | | | 3 | | | * | | pF |
| Closed Loop Gain Range | | 3 | 10 | 25 | * | * | * | V/V |
| Gain Accuracy, internal Rg, Rf | A _V = 3 | | ±10 | ±15 | | * | * | % |
| Gain Accuracy, external Rf | A _V = 10 | | ±15 | ±25 | | * | * | % |
| Phase Shift | f = 10 kHz, AV _{CL} = 10, C _C = 22pF | | 10 | | | * | | o |
| Pridse Stillt | f = 200 kHz, AV _{CL} = 10, C _C = 22pF | | 60 | | | * | | o |

^{1.} Guaranteed by design but not tested.



OUTPUT

| Parameter | Test | PB58 | | | PB58A | | | Units |
|------------------------|---------------------------------------|--------------------|-------------------|-----|--------------------|--------------------|-----|-------|
| rarameter | Conditions | Min | Тур | Max | Min | Тур | Max | Units |
| Voltage Swing | Io = 1.5A (PB58), 2A (PB58A) | V _S -11 | V _S –8 | | V _S -15 | V _S -11 | | V |
| Voltage Swing | Io = 1A | V _S -10 | V _S –7 | | * | * | | V |
| Voltage Swing | Io = 0.1A | V _S –8 | V _S –5 | | * | * | | V |
| Current, continuous | | 1.5 | | | 2 | | | Α |
| Slew Rate | Full temp range | 50 | 100 | | 75 | * | | V/µs |
| Capacitive Load | Full temp range | | 2200 | | | * | | pF |
| Settling Time to 0.1% | R_L = 100 Ω, 2V step | | 2 | | | * | | μs |
| Power Bandwidth | V _C = 100 Vpp | 160 | 320 | | 240 | * | | kHz |
| Small Signal Bandwidth | $C_C = 22pF, A_V = 25,$ Vcc = ±100 | | 100 | | | * | | kHz |
| Small Signal Bandwidth | $C_C = 22pF, A_V = 3,$ Vcc = ±30 | | 1 | | | * | | MHz |

POWER SUPPLY

| Parameter | Test | PB58 | | | PB58A | | | Units |
|---------------------------------------|-----------------------|------------------|-----|------|-------|-----|-----|--------|
| raiametei | Conditions | Min | Тур | Max | Min | Тур | Max | Offics |
| Voltage, ±V _S ¹ | Full temp range | ±15 ² | ±60 | ±150 | * | * | * | V |
| | V _S = ±15 | | 11 | | | * | | mA |
| Current, quiescent | V _S = ±60 | | 12 | | | * | | mA |
| | V _S = ±150 | | 14 | 18 | | * | * | mA |

^{1.} $+V_S$ and $-V_S$ denote the positive and negative supply rail respectively.

^{2.} $+V_S/-V_S$ must be at least 15V above/below COM.

PB58 • PB58A



THERMAL

| Parameter | Test | PB58 | | | PB58A | | | Units |
|---|-------------------------------|------|-----|-----|-------|-----|-----|--------|
| raiametei | Conditions | Min | Тур | Max | Min | Тур | Max | Offics |
| Resistance, AC, junction to case ¹ | Full temp range, f > 60 Hz | | 1.2 | 1.3 | | * | * | °C/W |
| Resistance, DC, junction to case | Full temp range, f < 60 Hz | | 1.6 | 1.8 | | * | * | °C/W |
| Resistance, junction to air | Full temp range | | 30 | | | * | | °C/W |
| Temperature Range, case | Meets full range specs | -25 | 25 | 85 | * | * | * | °C |

^{1.} Rating applies if the output current alternates between both output transistors at a rate faster than 60 Hz.

Note: * The specification of PB58A is identical to the specification for PB58 in applicable column to the left.



TYPICAL PERFORMANCE GRAPHS

Figure 3: Power Derating

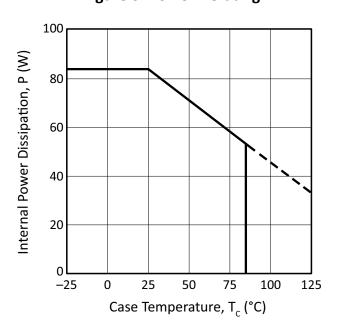


Figure 4: Current Limit

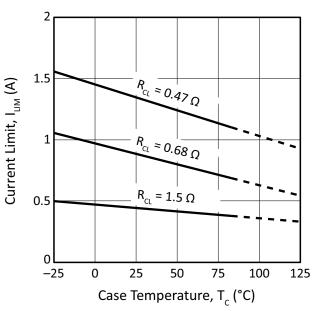


Figure 5: Output Voltage Swing

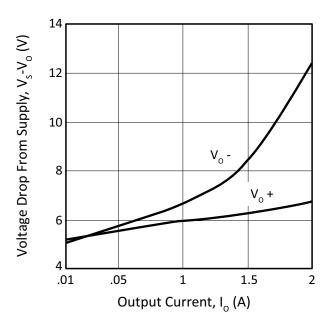


Figure 6: Small Signal Response

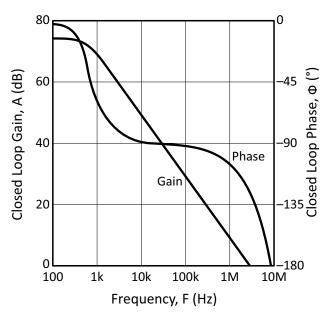




Figure 7: Small Signal Response

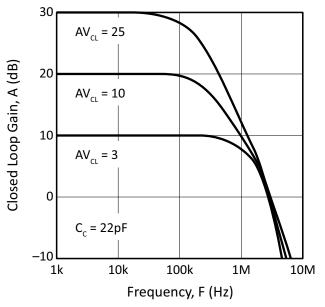


Figure 8: Small Signal Response

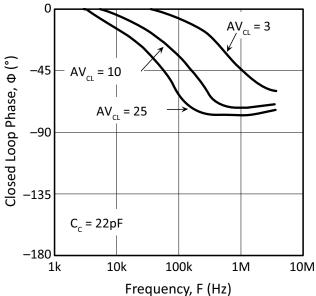


Figure 9: Quiescent Current

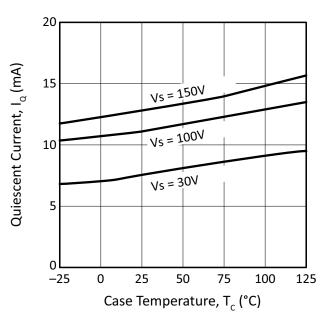


Figure 10: Input Offset Voltage

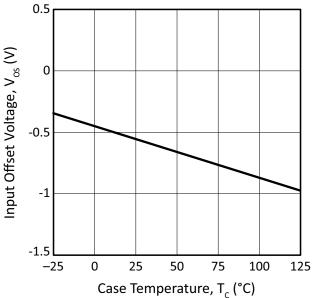




Figure 11: Slew Rate vs. Temperature

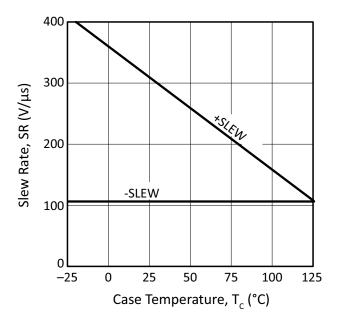


Figure 13: Pulse Response

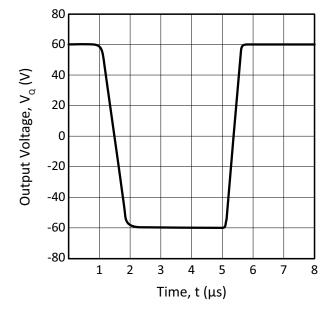


Figure 12: Power Response

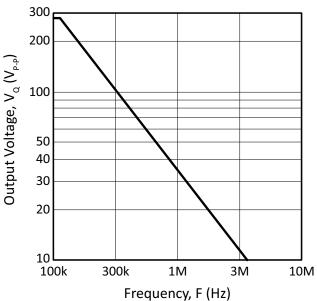
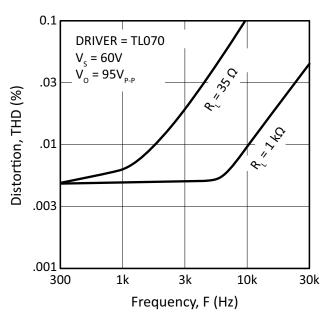


Figure 14: Harmonic Distortion

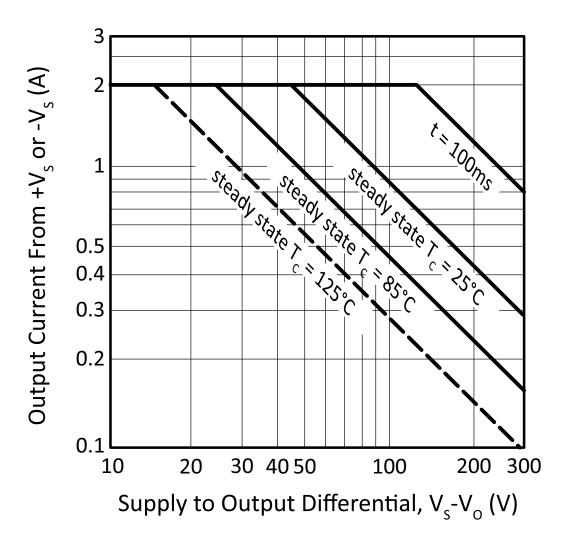




SAFE OPERATING AREA (SOA)

Note: The output stage is protected against transient flyback. However, for protection against sustained, high energy flyback, external fast-recovery diodes should be used.

Figure 15: SOA



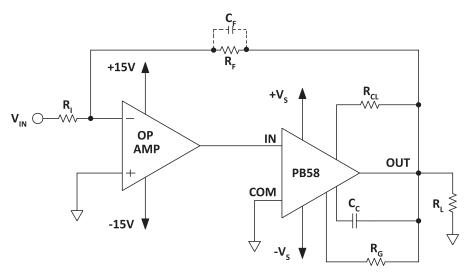


GENERAL

Please read Application Note 1 "General Operating Considerations" which covers stability, supplies, heat sinking, mounting, current limit, SOA interpretation, and specification interpretation. Visit www.apexanalog.com for Apex Microtechnology's complete Application Notes library, Technical Seminar Workbook, and Evaluation Kits.

TYPICAL APPLICATION

Figure 16: Typical Application



CURRENT LIMIT

For proper operation, the current limit resistor (R_{CL}) must be connected as shown in the external connection diagram. The minimum value is 0.33Ω with a maximum practical value of 47Ω . For optimum reliability the resistor value should be set as high as possible. The value is calculated as follows:

$$I_{CL} = \frac{0.65 V}{R_{CL}} + 0.01 A$$
 $-I_{CL} = \frac{0.65 V}{R_{CL}}$

COMPOSITE AMPLIFIER CONSIDERATIONS

Cascading two amplifiers within a feedback loop has many advantages, but also requires careful consideration of several amplifier and system parameters. The most important of these are gain, stability, slew rate, and output swing of the driver. Operating the booster amplifier in higher gains results in a higher slew rate and lower output swing requirement for the driver, but makes stability more difficult to achieve.



GAIN SET

$$R_G = [(Av-1) \cdot 3.1k] - 6.2k[\Omega]$$

$$Av = \frac{R_G + 6.2k}{3.1k} + 1$$

The booster's closed-loop gain is given by the equation above. The composite amplifier's closed loop gain is determined by the feedback network, that is: –Rf/Ri (inverting) or 1+Rf/Ri (non-inverting). The driver amplifier's "effective gain" is equal to the composite gain divided by the booster gain.

Example: Inverting configuration (figure 1) with

R i = 2 k, R f = 60 k, R g = 0:

Av (booster) = (6.2 k/ 3.1 k) + 1 = 3

Av (composite) = 60 k/2 k = -30

Av (driver) = -30/3 = -10

STABILITY

Stability can be maximized by observing the following guidelines:

- 1. Operate the booster in the lowest practical gain.
- 2. Operate the driver amplifier in the highest practical effective gain.
- 3. Keep gain-bandwidth product of the driver lower than the closed loop bandwidth of the booster.
- 4. Minimize phase shift within the loop.

A good compromise for (1) and (2) is to set booster gain from 3 to 10 with total (composite) gain at least a factor of 3 times booster gain. Guideline (3) implies compensating the driver as required in low composite gain configurations. Phase shift within the loop (4) is minimized through use of booster and loop compensation capacitors Cc and Cf when required. Typical values are 5pF to 33pF.

Stability is the most difficult to achieve in a configuration where driver effective gain is unity (ie; total gain = booster gain). For this situation, The table below gives compensation values for optimum square wave response with the op amp drivers listed.

| Driver | C _{CH} | C _F | C _C | FPBW | SR | |
|--------|---|----------------|----------------|--------|-----|--|
| 0P07 | - | 22p | 22p | 4 kHz | 1.5 | |
| 741 | - | 18p | 10p | 20 kHz | 7 | |
| LF155 | - | 4.7p | 10p | 60 kHz | >60 | |
| LF156 | - | 4.7p | 10p | 80 kHz | >60 | |
| TL070 | 22p | 15p | 10p | 80 kHz | >60 | |
| | For: R _r = 33 k, R _s = 3.3 k, R _o = 22 k | | | | | |



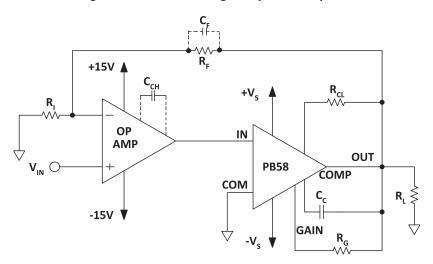


Figure 17: Non-Inverting Composite Amplifier

SLEW RATE

The slew rate of the composite amplifier is equal to the slew rate of the driver times the booster gain, with a maximum value equal to the booster slew rate.

OUTPUT SWING

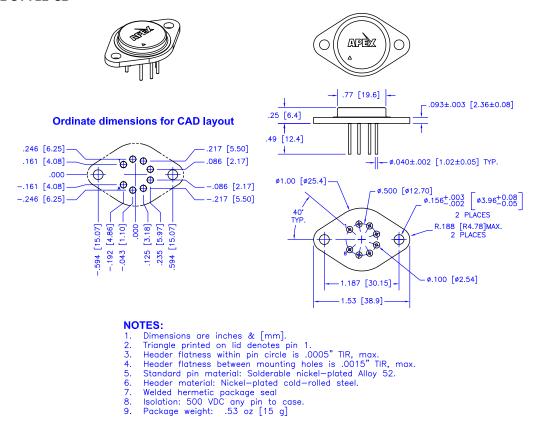
The maximum output voltage swing required from the driver op amp is equal to the maximum output swing from the booster divided by the booster gain. The Vos of the booster must also be supplied by the driver, and should be subtracted from the available swing range of the driver. Note also that effects of Vos drift and booster gain accuracy should be considered when calculating maximum available driver swing.



PACKAGE OPTIONS

| Part Number | Apex Package Style | Description |
|-------------|--------------------|-------------|
| PB58 | CE | 8-pin TO-3 |
| PB58A | CE | 8-pin TO-3 |

PACKAGE STYLE CE



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