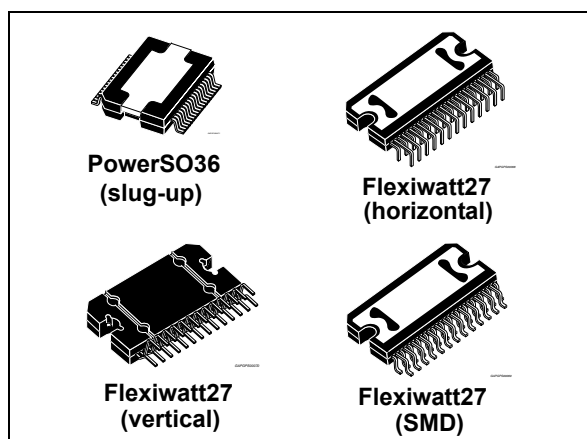


Digital input quad power amplifier with built-in diagnostics features

Datasheet - production data



- Two I²C bus addresses and 8-ch TDM mode (only in PowerSO package)
- Optional non I²C bus mode
- Offset detector (play or mute mode)
- Clipping detector (selectable level) and diagnostics pin
- CMOS compatible enable pin (3.3/5 V)
- Full fault protection
- Four independent short circuit protections
- Linear thermal protection (four thermal warnings)
- ESD protection

Features

- Integrated 110 dB D/A conversion
- I²S digital input (3.3/1.8 V) with TDM option
- Selectable input sampling frequency: 44.1 kHz, 48 kHz, 96 kHz, 192 kHz
- MOSFET power outputs
- High output power capability 4x28 W/ 4 Ω @ 14.4 V, 1 kHz, 10 % THD
- Max. output power 4x72 W/2 Ω
- Full I²C bus driving (3.3/5 V):
 - Independent front/rear soft play/ mute
 - Selectable gain (four levels) for very low noise line-out function
 - I²C bus digital diagnostics (including DC and AC load detection)

Description

The TDA7801 is a new BCD technology quad bridge amplifier for car audio applications.

Thanks to the BCD6 technology it is possible to integrate a high performance D/A converter together with powerful MOSFET outputs.

The possibility of having the D/A conversion on board allows the performance to reach an outstanding 115 dB S/N ratio with more than 105 dB of dynamic range.

This device is equipped with a full diagnostics array that communicates the status of each speaker through the I²C bus. The possibility to control the configuration and behavior of the device by means of the I²C bus makes TDA7801 a very flexible machine.

Table 1. Device summary

Order code	Package	Packing
TDA7801PD	PowerSO36 (slug-up)	Tube
TDA7801PDTR	PowerSO36 (slug-up)	Tape and reel
TDA7801	Flexiwatt27 (vertical)	Tube
TDA7801H	Flexiwatt27 (horizontal)	Tube
TDA7801SM	Flexiwatt27 (SMD)	Tube

Contents

1	Block diagram and pins description	6
1.1	Block diagram	6
2	Application diagrams	7
2.1	Pin description	9
3	Electrical specifications	12
3.1	Absolute maximum ratings	12
3.2	Thermal data	12
3.3	Electrical characteristics	13
3.4	Electrical characteristics typical curves	17
4	Operation mode	21
4.1	Standby mode	21
4.2	Tristate mode	21
4.3	Amplifier mode	21
5	"PLL-filter /enable" pin description	22
5.1	Functionality	22
5.2	Driving	22
6	Functional description	23
6.1	Voltage supplies timing	23
6.2	Turn-on diagnostic description	23
6.3	Permanent diagnostic	25
6.4	AC diagnostic	26
6.5	Output DC offset detection	26
6.6	Multiple faults	27
6.7	Faults availability	27
6.8	I ² C programming/reading sequence	27
6.9	Legacy mode	28
6.10	Thermal protection	28

6.11	Under-voltage threshold	29
6.11.1	Supply voltage auto-mute threshold	29
6.11.2	Digital mute disabling	29
6.11.3	Power-on reset threshold	29
6.12	Fast mute features	30
7	I²S bus interface	31
7.1	Interface timings requirements	32
7.2	Group delay	33
8	I²C bus interface	34
8.1	Writing procedure	35
8.2	Reading procedure	35
8.3	Data validity	35
8.4	Start and stop conditions	35
8.5	Byte format	35
8.6	Acknowledge	35
9	I²C registers	36
9.1	IB0-Addr:"00000"	36
9.2	IB1-Addr:"00001"	36
9.3	IB2-Addr:"00010"	37
9.4	IB3-Addr:"00011"	38
9.5	IB4-Addr:"00100"	38
9.6	DB0-Addr:"10000" - Channel 1 (left front)	39
9.7	DB1-Addr:"10001" - Channel 2 (left rear)	40
9.8	DB2-Addr:"10010" - Channel 3 (right front)	41
9.9	DB3-Addr:"10011" - Channel 4 (right rear)	42
9.10	DB4-Addr:"10100"	42
10	Package information	43
11	Revision history	47

List of tables

Table 1.	Device summary	1
Table 2.	Flexiwatt27 (vertical/SMD/horizontal) pin description	10
Table 3.	PowerSO36 pin description	11
Table 4.	Absolute maximum ratings	12
Table 5.	Thermal data	12
Table 6.	Electrical characteristics	13
Table 7.	Start-up diagnostic pulse typical timing	24
Table 8.	Multiple faults priority	27
Table 9.	System clock frequencies for common audio sampling frequencies	32
Table 10.	Example timing for $t_{ck} = 1/f_{SCK}$, where f_{SCK} is stated in the Table 9	33
Table 11.	IB0-Addr:"00000"	36
Table 12.	IB1-Addr:"00001"	36
Table 13.	IB3-Addr:"00010"	37
Table 14.	IB3-Addr:"00011"	38
Table 15.	IB4-Addr:"00100"	38
Table 16.	DB0-Addr:"10000" - Channel 1 (left front).	39
Table 17.	DB1-Addr:"10001" - Channel 2 (left rear)	40
Table 18.	DB2-Addr:"10010" - Channel 3 (right front).	41
Table 19.	DB3-Addr:"10011" - Channel 4 (right rear)	42
Table 20.	DB4-Addr:"10100".	42
Table 21.	Document revision history	47

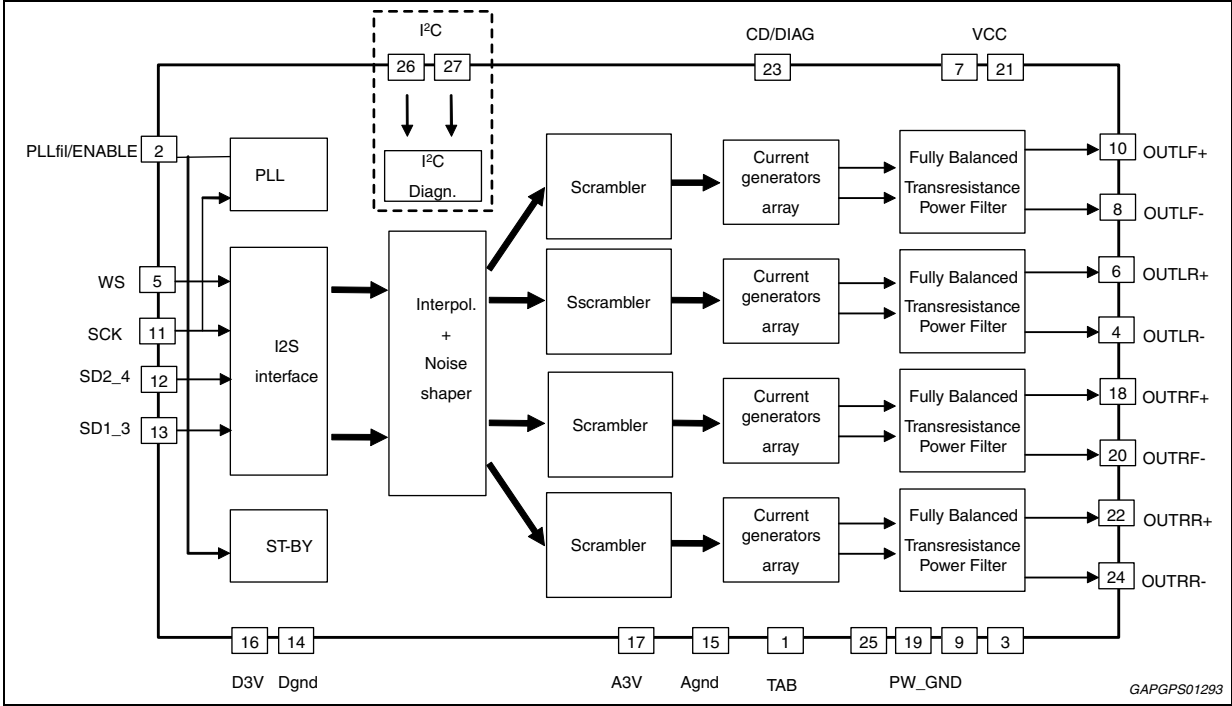
List of figures

Figure 1.	Block diagram (Flexiwatt27)	6
Figure 2.	I ² C bus mode application diagram (TDA7801/H/SM)	7
Figure 3.	I ² C bus mode application diagram (TDA7801PD)	7
Figure 4.	Legacy mode application diagram (TDA7801/H/SM)	8
Figure 5.	Legacy mode application diagram (TDA7801PD)	8
Figure 6.	Pin connection diagrams	9
Figure 7.	Quiescent current vs. supply voltage	17
Figure 8.	Output power vs. supply voltage (4 Ω)	17
Figure 9.	Output power vs. supply voltage (2 Ω)	17
Figure 10.	Distortion vs. output power (4 Ω)	17
Figure 11.	Distortion vs. output power (2 Ω)	18
Figure 12.	Distortion vs. frequency (4 Ω)	18
Figure 13.	Distortion vs. frequency (2 Ω)	18
Figure 14.	Vo vs. Vin (Gv1-2-3-4 settings)	18
Figure 15.	Vo vs. Vin (Gv1-2-3-4 settings + 6 dB dig. gain)	18
Figure 16.	Distortion vs. output voltage (LD-Gv2)	18
Figure 17.	Distortion vs. output voltage (LD-Gv3)	19
Figure 18.	Distortion vs. output voltage (LD-Gv4)	19
Figure 19.	Output attenuation vs. Vs	19
Figure 20.	Crosstalk vs. frequency	19
Figure 21.	Supply voltage rejection vs. frequency	19
Figure 22.	Total power dissipation & efficiency vs. Po (4 Ω)	19
Figure 23.	Power dissipation vs. average Po (audio program simulation, 4 Ω)	20
Figure 24.	Power dissipation vs. average Po (audio program simulation, 2 Ω)	20
Figure 25.	ITU R-ARM frequency response, weighting filter for transient pop.	20
Figure 26.	Standby driving circuit.	22
Figure 27.	Turn-on diagnostic cycle. Positive and negative output behaviour.	23
Figure 28.	Turn-on diag. cycle with transition in amp. mode. Positive and negative output behaviour	24
Figure 29.	Short to GND and short to V _s , threshold description	25
Figure 30.	Short across the speaker and open load threshold description, in amplifier mode.	25
Figure 31.	Short across the speaker and open load threshold description, in line driver mode.	25
Figure 32.	Thermal muting diagram.	28
Figure 33.	Low voltage mute attenuation, supply voltage variation (Vs); result digital attenuation (At)	29
Figure 34.	TDM setting	31
Figure 35.	I ² S format	31
Figure 36.	Audio data input format.	32
Figure 37.	Audio interface timing	32
Figure 38.	I ² C bus protocol description	34
Figure 39.	PowerSO36 (slug-up) mechanical data and package dimensions	43
Figure 40.	Flexiwatt27 (vertical) mechanical data and package dimensions.	44
Figure 41.	Flexiwatt27 (horizontal) mechanical data and package dimensions.	45
Figure 42.	Flexiwatt27 (SMD) mechanical data and package dimensions	46

1 Block diagram and pins description

1.1 Block diagram

Figure 1. Block diagram (Flexiwatt27)



2 Application diagrams

Figure 2. I²C bus mode application diagram (TDA7801/H/SM)

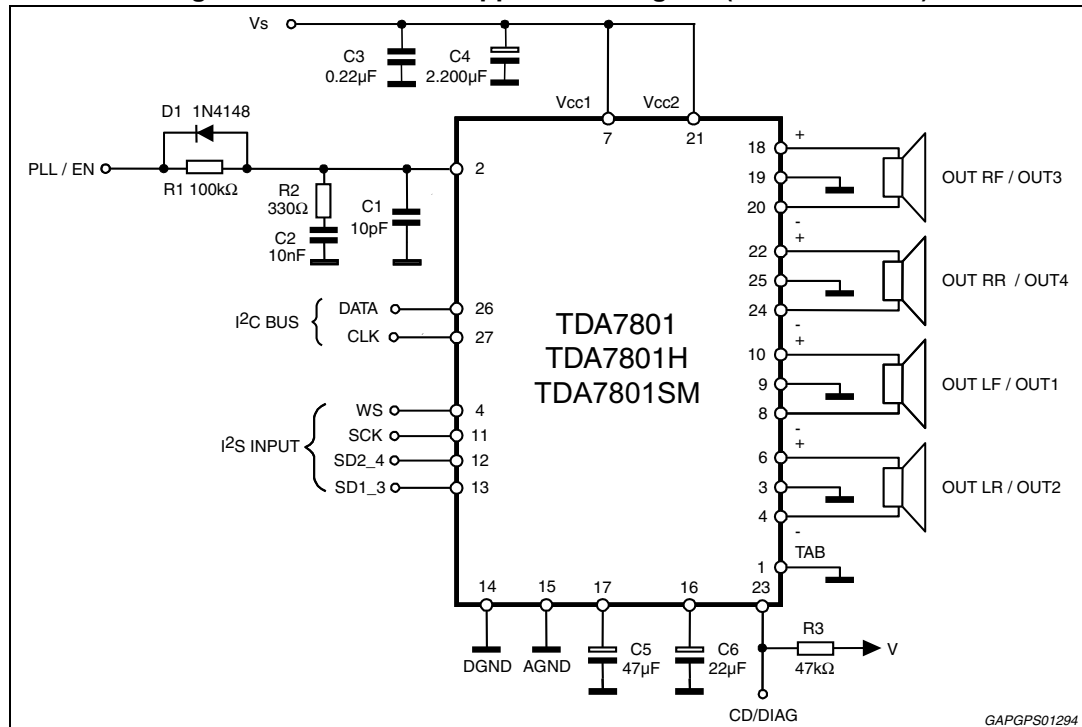


Figure 3. I²C bus mode application diagram (TDA7801PD)

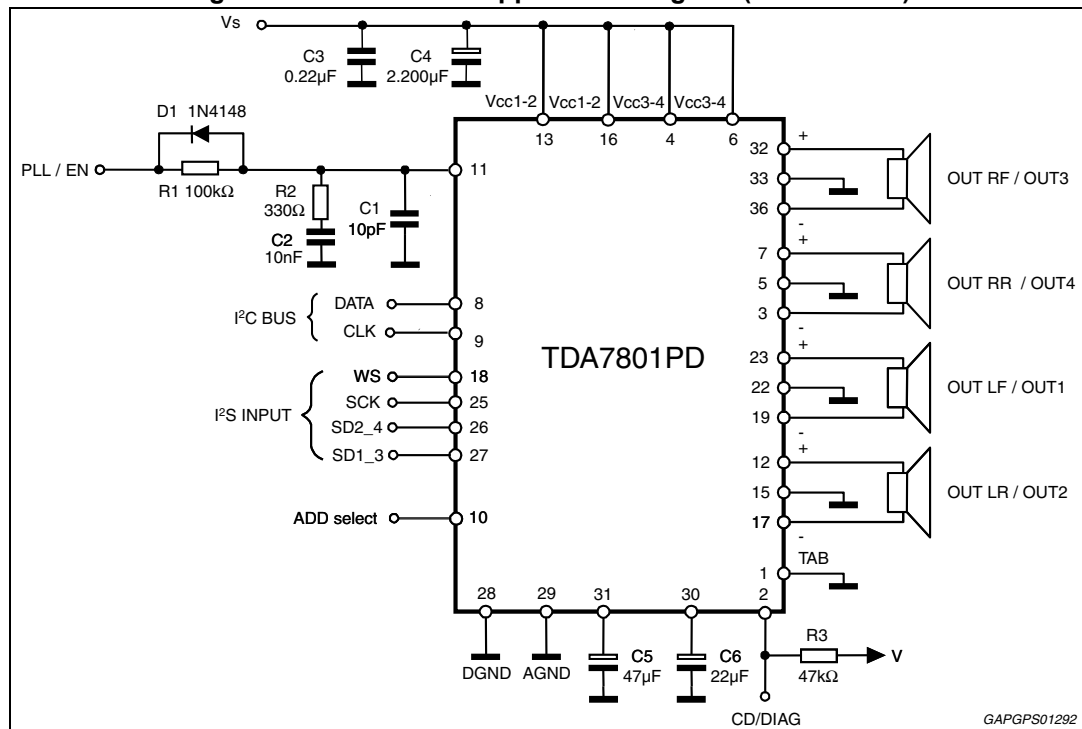


Figure 4. Legacy mode application diagram (TDA7801/H/SM)

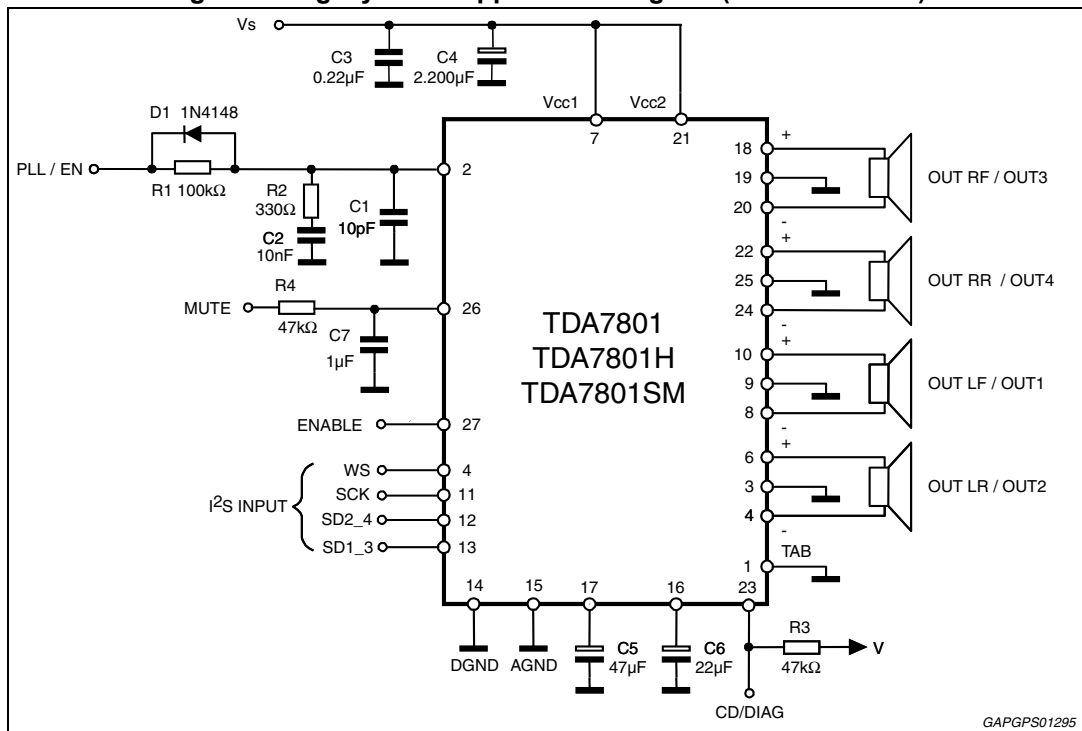
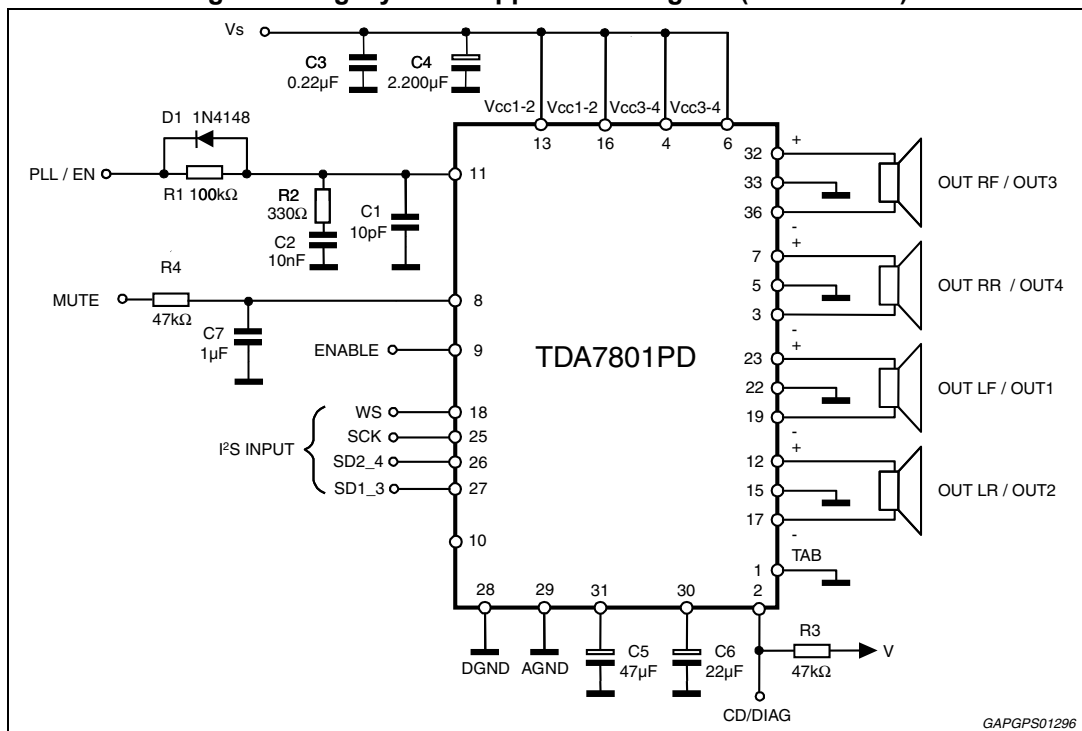
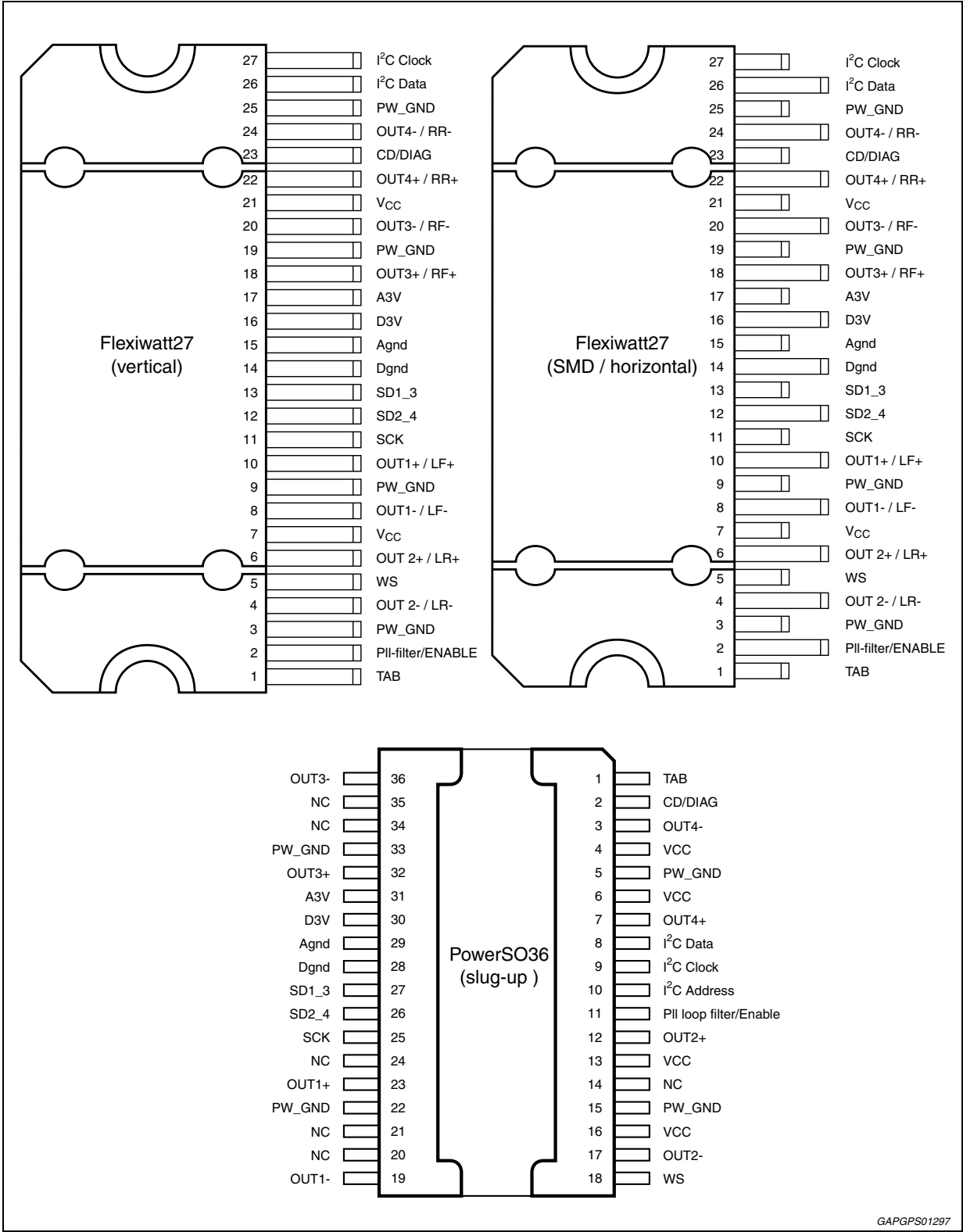


Figure 5. Legacy mode application diagram (TDA7801PD)



2.1 Pin description

Figure 6. Pin connection diagrams



GAPGPS01297

Table 2. Flexiwatt27 (vertical/SMD/horizontal) pin description

N°	Pin	Function
1	TAB	TAB connection (GND)
2	PII-filter / ENABLE	PII loop filter / ENABLE
3	PW_GND	Power ground channel 2
4	OUT 2- / LR-	Channel 2 (Left Rear) negative output
5	WS	Word select (I ² S bus, logic input)
6	OUT 2+ / LR+	Channel 2 (Left Rear) positive output
7	Vcc	Channel 1 and 2 positive supply
8	OUT 1- / LF-	Channel 1 (Left Front) negative output
9	PW_GND	Power ground channel 1
10	OUT 1+ / LF+	Channel 1 (Left Front) positive output
11	SCK	Serial clock (I ² S bus, logic input)
12	SD2_4	Serial data channels 2 and 4 (I ² S bus, logic input)
13	SD1_3	Serial data channels 1 and 3 (I ² S bus, logic input)
14	Dgnd	Digital ground
15	Agnd	Analog ground
16	D3V	Digital 3.3 V supply filter
17	A3V	Analog 3.3 V supply filter
18	OUT3+ / RF+	Channel 3 (right front) positive output
19	PW_GND	Power ground channel 3
20	OUT3- / RF-	Channel 3 (right front) negative output
21	Vcc	Channels 3 and 4 positive supply
22	OUT4+ / RR+	Channel 4 (right rear) positive output
23	CD/DIAG	Clip detector and diagnostic output: – Overcurrent protection intervention – Thermal warning – POR – (Open drain output)
24	OUT4- / RR-	Channel 4 (right rear) negative output
25	PW_GND	Power ground channel 4
26	I ² C Data	I ² C data/legacy mode mute
27	I ² C Clock	I ² C clock/enable legacy mode

Table 3. PowerSO36 pin description

N°	Pin	Function
1	TAB	TAB connection (GND)
2	CD/DIAG	Clip detector and diagnostic output: Overcurrent protection intervention Thermal warning Offset detection POR (Open drain output)
3	OUT4-	Channel 4 (right rear) negative output
4	VCC	Channels 3-4 positive supply
5	PW_GND	Power ground channel 4
6	VCC	Channels 3-4 positive supply
7	OUT4+	Channel 4 (right rear) positive output
8	I2C Data	I ² C Data / legacy mode mute
9	I2C Clock	I ² C Clock / enable legacy mode
10	I2C Address	I ² C Address
11	PII loop filter/Enable	PII loop filter / Enable
12	OUT2+	Channel 2 (left rear) positive output
13	VCC	Channel 1-2 positive supply
14	NC	Not connected
15	PW_GND	Power ground channel 2
16	VCC	Channel 1-2 positive supply
17	OUT2-	Channel 2 (left rear) negative output
18	WS	Word Select (I ² S bus, logic input)
19	OUT1-	Channel 1 (left front) negative output
20	NC	Not connected
21	NC	Not connected
22	PW_GND	Power ground channel 1
23	OUT1+	Channel 1 (left front) positive output
24	NC	Not connected
25	SCK	Serial clock (I ² S bus, logic input)
26	SD2_4	Serial data channels 2 and 4 (I ² S bus, logic input)
27	SD1_3	Serial data channels 1 and 3 (I ² S bus, logic input)
28	Dgnd	Digital ground
29	Agnd	Analog ground
30	D3V	Digital 3.3 V supply filter
31	A3V	Analog 3.3 V supply filter
32	OUT3+	Channel 3 (right front) positive output
33	PW_GND	Power ground channel 3
34	NC	Not connected
35	NC	Not connected
36	OUT3-	Channel 3 (right front) negative output

3 Electrical specifications

3.1 Absolute maximum ratings

Table 4. Absolute maximum ratings

Symbol	Parameter	Value	Unit
V_{op}	Operating supply voltage	18	V
V_S	DC supply voltage	28	V
V_{peak1}	Peak supply voltage (for $t = 50$ ms)	50	V
V_{peak2}	Peak supply voltage (for $t = 500$ ms)	34	V
$V_{i2cdata}$	I ² C bus data pin voltage / legacy mode mute	20	V
V_{i2ck}	I ² C bus clock pin voltage / enable legacy mode	50	V
V_{i2s}	I ² S bus pins voltage	3.6	V
I_O	Output peak current (not repetitive $t = 100$ μ s)	8	A
I_O	Output peak current (repetitive $f > 10$ Hz)	6	A
P_{tot}	Power dissipation $T_{case} = 70$ °C	85	W
F_s max	Maximum input sample rate	200	kHz
T_{amb}	Operative temperature range ⁽¹⁾	-40 to 105	°C
T_{stg}, T_j	Storage and junction temperature	-55 to 150	°C
C_{max}	Maximum capacitor vs. ground connected to the output	10	nF

1. A suitable heatsink/dissipation system should be used to keep T_j inside the specific limits.

3.2 Thermal data

Table 5. Thermal data

Symbol	Parameter	PowerSO36	Flexiwatt 27	Unit
$R_{th j-case}$	Thermal resistance junction-to-case Max	1	1	°C/W

3.3 Electrical characteristics

Refer to the test circuit, $V_S = 14.4\text{ V}$; $R_L = 4\ \Omega$; $f = 1\text{ kHz}$; $T_{\text{amb}} = 25\text{ }^\circ\text{C}$; unless otherwise specified.

Table 6. Electrical characteristics

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
V_S	Supply voltage range	-	8	-	18	V
I_d	Total quiescent drain current in amplifier mode	enable on amplifier mode muted	150	260	350	mA
I_t	Total quiescent drain current in tristate mode	enable on tristate mode	30	45	60	mA
P_O	Output power	$R_L = 4\ \Omega$; max power	41	45	-	W
		THD = 10 %	25	28	-	W
		THD = 1 %	20	22	-	W
		$R_L = 2\ \Omega$; max power	70	78	-	W
		$R_L = 2\ \Omega$; THD 10%	43	49	-	W
		$R_L = 2\ \Omega$; THD 1%	34	38	-	W
THD	Total harmonic distortion	$P_O = 1\text{ W to }10\text{ W}$, $f=1\text{ kHz}$, G_{V1}	-	0.03	0.05	%
		$P_O = 1\text{ W to }10\text{ W}$, $f=10\text{ kHz}$, G_{V1}	-	0.2	0.5	%
		$R_L = 100\ \Omega$, input=-10 dBFS, $f=1\text{ kHz}$, $G_{V1,2,3,4}$	-	0.01	0.02	%
C_T	Cross talk	$f = 1\text{ kHz to }10\text{ kHz}$	60	80	-	dB
G_{V1}	Voltage gain 1	Output voltage @ -10 dBFS	14.9	-	16.9	dB (Vp)
G_{V2}	Voltage gain 2		9.45	-	11.45	dB (Vp)
G_{V3}	Voltage gain 3		6.9	-	8.9	dB (Vp)
G_{V4}	Voltage gain 4		1.45	-	3.45	dB (Vp)
F_{SV1}	Full scale voltage G_{V1}	Output voltage @ 0 dBFS $V_S=18\text{ V}$; $R_L = 100\ \Omega$	12.7	-	-	Vrms
F_{SV2}	Full scale voltage G_{V2}	Output voltage @ 0 dBFS	6.65	-	8.35	Vrms
F_{SV3}	Full scale voltage G_{V3}		4.9	-	6.2	Vrms
F_{SV4}	Full scale voltage G_{V4}		2.65	-	3.35	Vrms
DG	Delta voltage gain 20 Hz – 20 kHz	$P_O=1\text{ W}$	-0.5	-	0.5	dB
DR	Dynamic range $G_V = G_{V1}$ $G_V = G_{V2}$ $G_V = G_{V3}$ $G_V = G_{V4}$	Bw=20 Hz to 20 kHz, un weighted	105	110	-	dB
			100	105		
			100	105		
			98	103		

Table 6. Electrical characteristics (continued)

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
E_{IN}	Output noise voltage $G_V = G_{V1}$ $G_V = G_{V2}$ $G_V = G_{V3}$ $G_V = G_{V4}$	Bw = 20 Hz to 20 kHz, unweighted	-	25 25 19 19	35 35 26 26	μV
SNR	Signal to noise ratio $G_V = G_{V1}$ $G_V = G_{V2}$ $G_V = G_{V3}$ $G_V = G_{V4}$	Bw = 20 Hz to 20 kHz, unweighted	111 105 105 100	115 109 109 104	-	dB
G_B	Gain balance		-1	-	+1	dB
SVR	Supply voltage rejection	$f = 1$ kHz; $V_r = 1$ Vpk;	50	70	-	dB
I_{SB}	Stand-by current	$V_{pin\ ENABLE} = 0V$	-	-	10	μA
A_M	Mute attenuation	-	80	-		dB
V_{OS}	Offset voltage	Mute & Play	-50	-	50	mV
V_{AM}	Supply automute range	Above this voltage the device is in play	7.8	-	-	V
		Below this voltage the device is in mute	-	-	6.8	V
$V_{POWONRESET}$	Supply voltage of power-on reset	-	-	4.5	5	V
$V_{OVERVOLTAGE}$	Over voltage shut-down	-	18		24	V
CD_{LK}	Clip det high Leakage current	CD off	-	0	5	μA
CD_{SAT}	Clip det sat. voltage	CD on; $I_{CD} = 1$ mA	-	150	300	mV
$CD1_{THD}$	Clip det THD level 1 %	-	-	1	2	%
$CD2_{THD}$	Clip det THD level 5 %	-	3	5	7	%
$CD3_{THD}$	Clip det THD level 10 %	-	7	10	13	%
T_{mute}	Mute and unmute commutation time	Programmable by I ² C bus register IB1(6:4) $F_s = 44.1$ kHz	-	1.45	-	ms
			-	5.8	-	
			-	11.6	-	
			-	23.2	-	
			-	34.8	-	
			-	69.6	-	
			-	140	-	
			-	278	-	
N_{GL}	Noise gating input level	Under this level the device is in mute	-	-102	-	dB

Table 6. Electrical characteristics (continued)

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
N_{GT}	Noise gating time	$F_s = 44100$ Hz	-	92	-	ms
E_{IN2}	Output noise voltage GV=GV1 GV=GV2 GV=GV3 GV=GV4	Bw=20 Hz to 20 kHz, unweighted, noise gating off, No input signal	-	44.2 42 31.2 21	88 84 63 42	μV
Turn on diagnostics speaker mode						
Pgnd	Short to GND det. (below this limit, the output is considered in short circuit to GND)	-	-	-	1	V
P_{Vs}	Short to V_s det. (above this limit, the output is considered in short circuit to V_s)	-	$V_s - 1$	-	-	V
Pnop	Normal operation thresholds. (Within these limits, the output is considered without faults).	-	2	-	$V_s - 2$	V
Lsc	Shorted load det.	-	-	-	0.5	Ω
Lop	Normal load det.	-	1.65	-	25	Ω
Lnop	Open load det.	-	75	-	-	Ω
Td	Max diagnostic time	Input sampling frequency $F_s = 44100$ Hz	-	-	190	ms
Turn on diagnostics booster mode						
Pgnd	Short to GND det. (below this limit, the output is considered in short circuit to GND)	-	-	-	1	V
Pvs	Short to V_s det. (above this limit, the output is considered in short circuit to V_s)	-	$V_s - 1$	-	-	V
Pnop	Normal operation thresholds. (Within these limits, the output is considered without faults).	-	2	-	$V_s - 2$	V
Lsc	Shorted load det.	-	-	-	15	Ω
Lop	Normal load det.	-	0.065	-	1	k Ω
Lnop	Open load det.	-	3.5	-	-	k Ω
AC-diagnostic						
$I_{ACTRESH}$	AC diagnostic current threshold	IB4 – D6= '0'	250	375	500	mA
		IB4 – D6= '1'	125	187	250	mA

Table 6. Electrical characteristics (continued)

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
Permanent diagnostics						
Pgnd	Short to GND det. (below this limit, the output is considered in short circuit to GND)	-	-	-	1	V
Pvs	Short to V_s det. (above this limit, the Output is considered in short circuit to V_s)	-	$V_s - 1$	-	-	V
Pnop	Normal operation thresholds. (Within these limits, the output is considered without faults)	-	2	-	$V_s - 2$	V
L _{SC}	Shorted load det.	Speaker mode	-	-	0.5	Ω
		Booster mode	-	-	15	Ω
Lop	Normal load det.	Speaker mode	1.65	-	-	Ω
		Booster mode	0.065	-	-	kΩ
V _O	Offset detection	Absolute value	1.5	-	2.5	V
T _{ph}	Thermal protection junction temperature	Gain attenuation of 60 dB	-	175	-	°C
T _{pl}		Gain attenuation of 0.5 dB	-	165	-	°C
T _{w1}	Thermal warning junction temperature	-	-	Tpl-10	-	°C
T _{w2}		-	-	Tpl-27	-	°C
T _{w3}		-	-	Tpl-45	-	°C
T _{w4}		-	-	Tpl-62	-	°C
Legacy mode						
V _{LM_MUTE}	Legacy mode mute threshold	Gain Attenuation of 80 dB	-	-	1.2	V
		Gain Attenuation of 0.1 dB	2.6	-	-	V
V _{LM_ON}	Legacy mode threshold	Device in legacy mode	Vs-2	-	Vs	V
I _{LKG_MUTE}	Mute pin leakage	-	-5	-	+5	μA
I ² C Bus interface						
f _{SCL}	Clock frequency	-	-	-	400	kHz
V _{IL}	Input low voltage	-	-	-	1.5	V
V _{IH}	Input high voltage	-	2.3	-	-	V
PII-filter /ENABLE pin						
V _{ILENB}	Input low voltage	-	-	-	1.5	V
V _{IHENB}	Input high voltage	-	2.3	-	-	V
I _{ILENB} ⁽¹⁾	Logic '0' output current	V _{IN} = 0.45 V	-	-	2	mA
I _{IHENB}	Logic '1' input current	V _{IN} = 2.3 V (IB0 D4=0)	-	-	2	μA

Table 6. Electrical characteristics (continued)

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
I²S pin						
V _{IL-I2S}	Input low voltage	-	-	-	0.8	V
V _{IH-I2S}	Input high voltage	-	1.3	-	-	V
I _{IH}	Input high current except WS pin	V _I = 3.3 V	-	-	5	μA
I _{IL}	Input low current	V _I = 0 V	-	-	5	μA
I _{IH_WS}	Input high current for WS	V _I = 3.3 V	-	70	150	μA

1. This has to be considered the maximum current value for a short time and not the standby current.

3.4 Electrical characteristics typical curves

Figure 7. Quiescent current vs. supply voltage Figure 8. Output power vs. supply voltage (4 Ω)

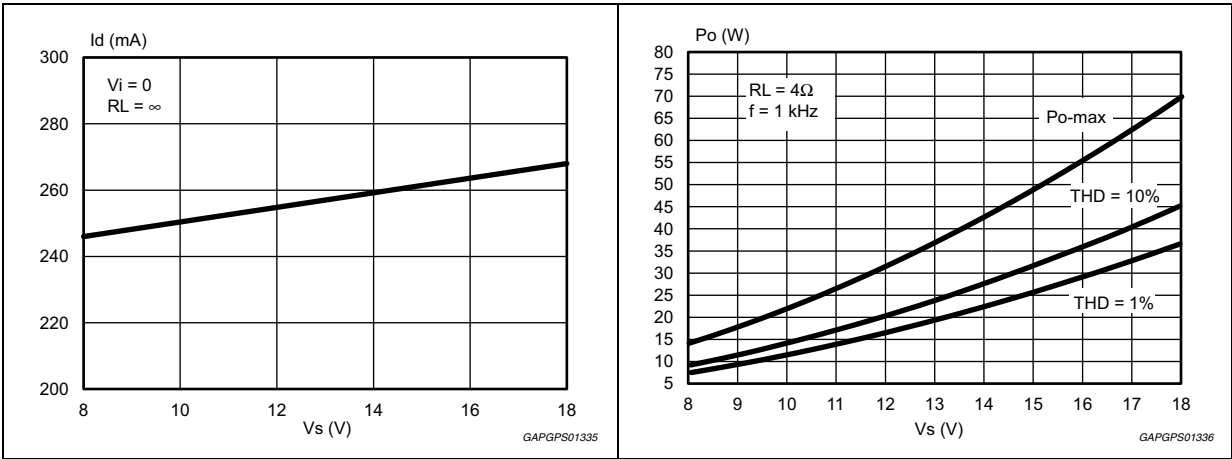


Figure 9. Output power vs. supply voltage (2 Ω) Figure 10. Distortion vs. output power (4 Ω)

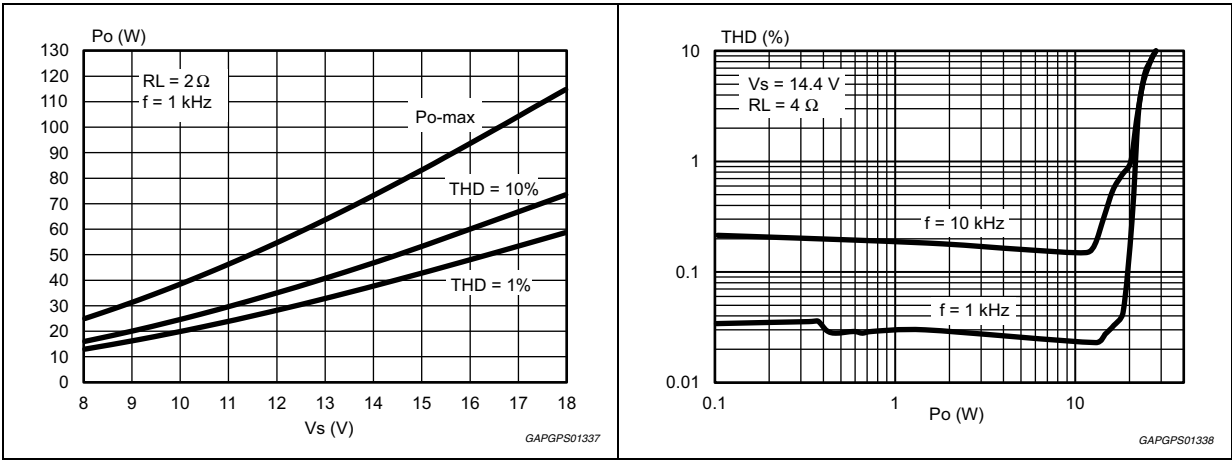


Figure 11. Distortion vs. output power (2 Ω)

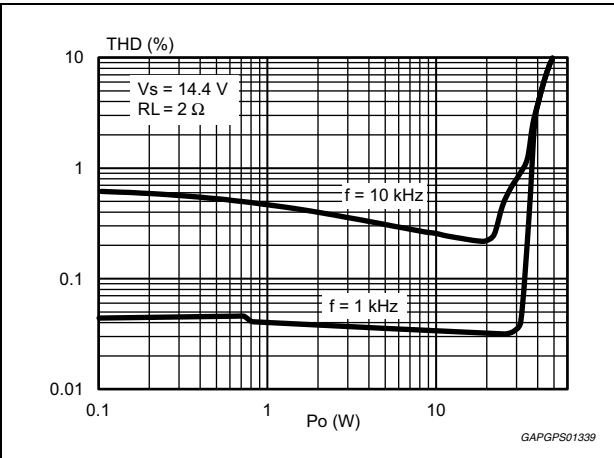


Figure 12. Distortion vs. frequency (4 Ω)

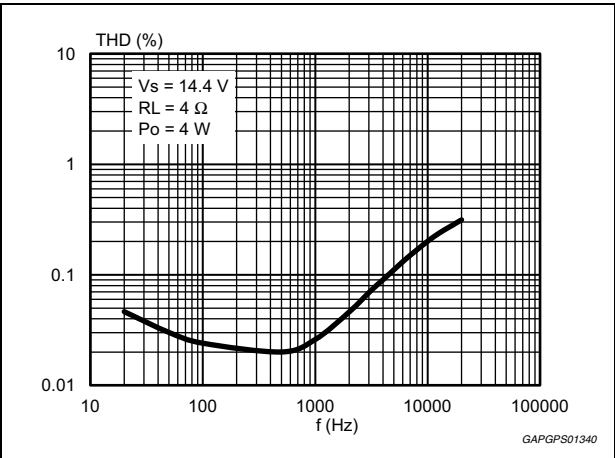


Figure 13. Distortion vs. frequency (2 Ω)

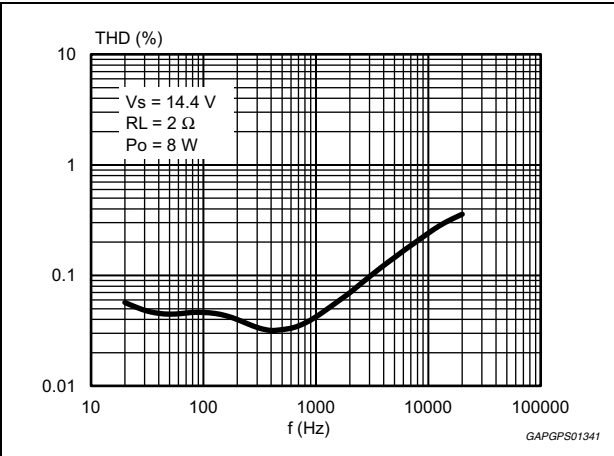


Figure 15. Vo vs. Vin (Gv1-2-3-4 settings + 6 dB dig. gain)

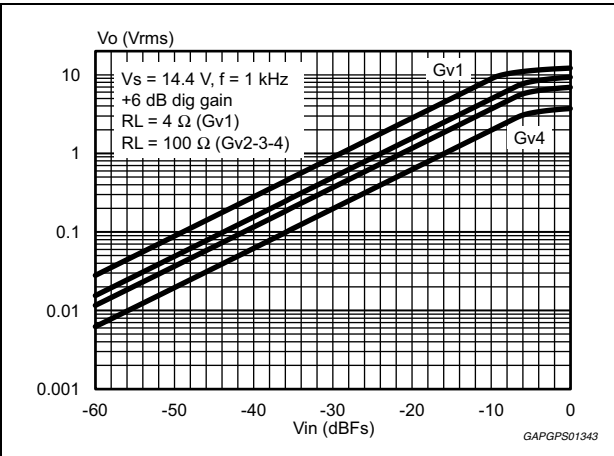


Figure 14. Vo vs. Vin (Gv1-2-3-4 settings)

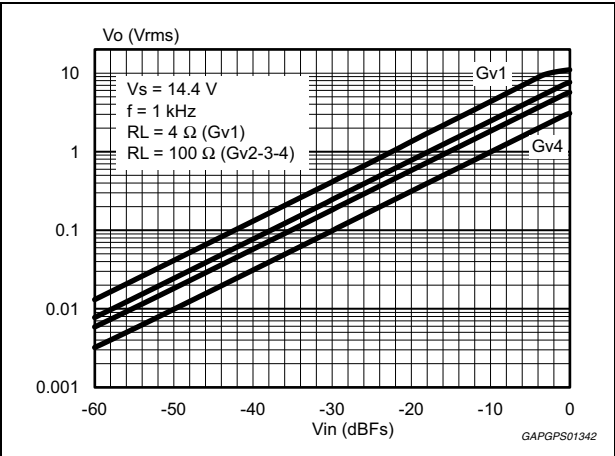


Figure 16. Distortion vs. output voltage (LD-Gv2)

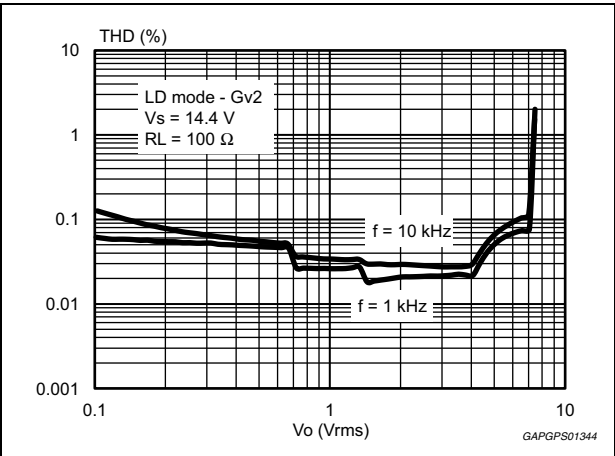


Figure 17. Distortion vs. output voltage (LD-Gv3)

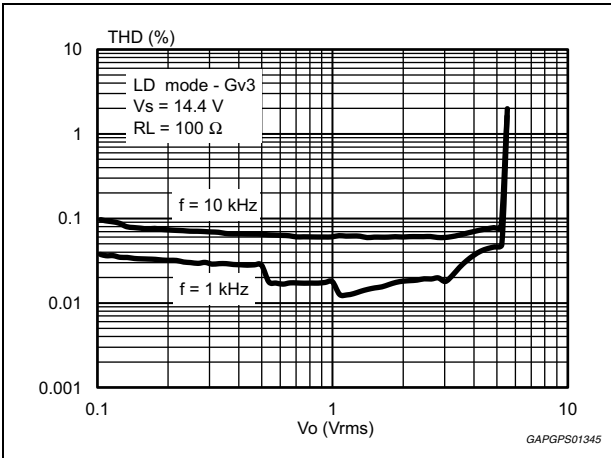


Figure 18. Distortion vs. output voltage (LD-Gv4)

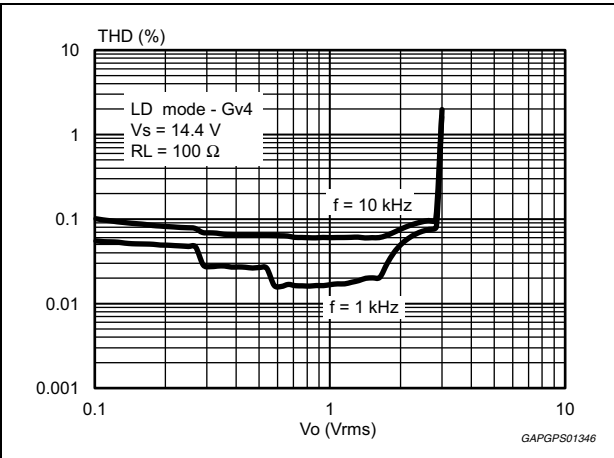


Figure 19. Output attenuation vs. Vs

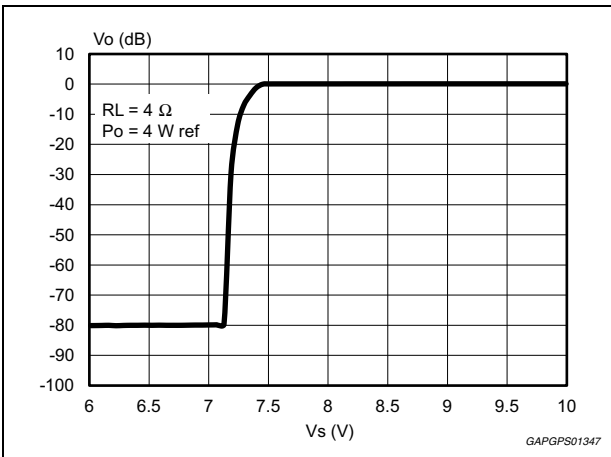


Figure 20. Crosstalk vs. frequency

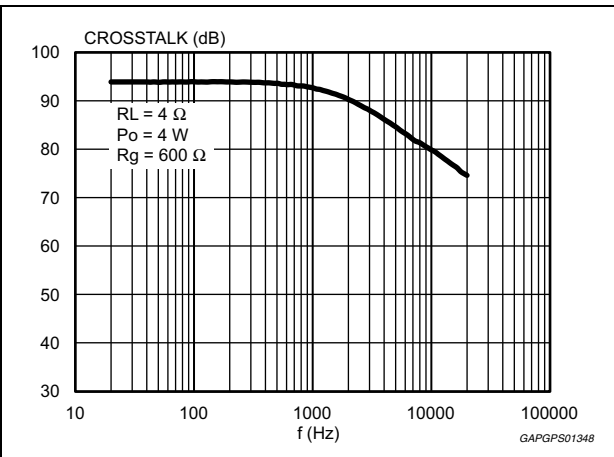


Figure 21. Supply voltage rejection vs. frequency

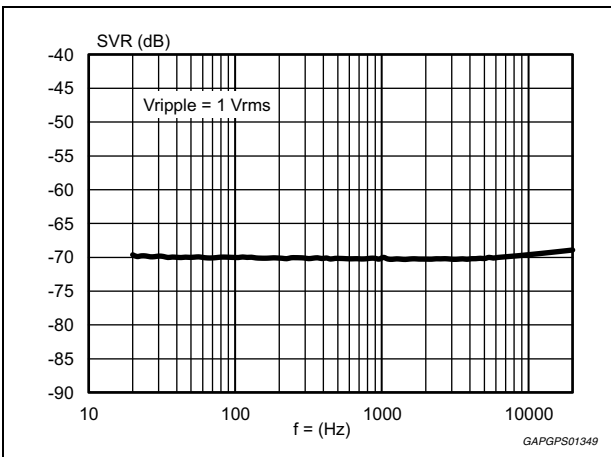


Figure 22. Total power dissipation & efficiency vs. Po (4 Ω)

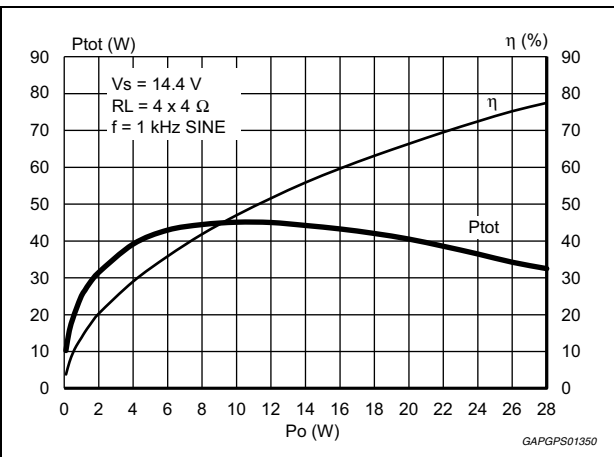


Figure 23. Power dissipation vs. average Po (audio program simulation, 4 Ω)

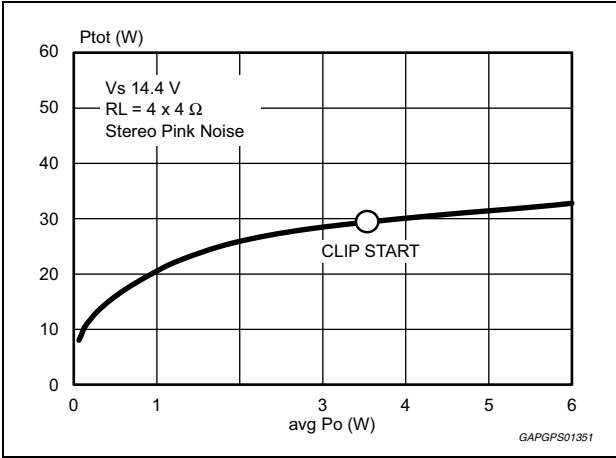


Figure 24. Power dissipation vs. average Po (audio program simulation, 2 Ω)

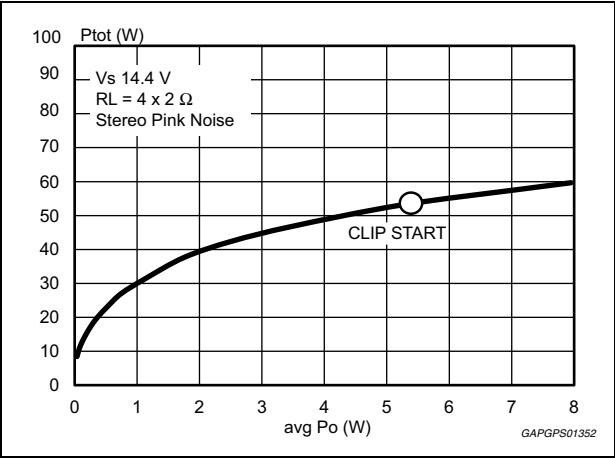
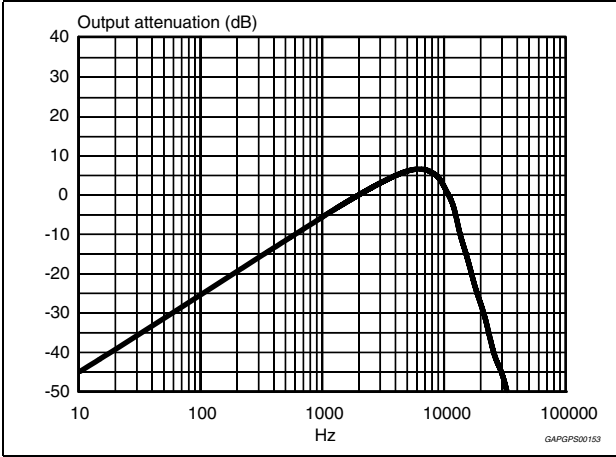


Figure 25. ITU R-ARM frequency response, weighting filter for transient pop



4 Operation mode

The device has three main operation modes:

- Standby mode
- Tristate mode
- Amplifier mode

4.1 Standby mode

When the ENABLE pin is low the device is in standby-mode. The current consumption is I_{SB} .

4.2 Tristate mode

When the ENABLE pin is high and the bit D7 of register DB0 is low the device is in tristate-mode. In that state the amplifier outputs are "high impedance", the I²C bus is ready to receive command.

4.3 Amplifier mode

When the ENABLE pin is high and the bit D7 of register DB0 is high the device is in amplifier-mode ready to play. To move the device in that state it is enough to write '1' on bit D7 of register IB1 from tristate-mode. Note that the device starts with all channels muted by default (see I²C registers description, [Section 9](#)).

5 "PLL-filter /enable" pin description

5.1 Functionality

The pin 2 has the functions to:

- ENABLE
- PLL filter

When the pin 2 is set to logic level low the TDA7801 is in standby-mode and the current consumption is ISB. The device is waked-up and put in tristate-mode setting the same pin to logic level high. In tristate-mode the TDA7801 is ready to receive I²C bus instructions. The device is set in amplifier-mode writing '1' on bit D7 of byte IB1.

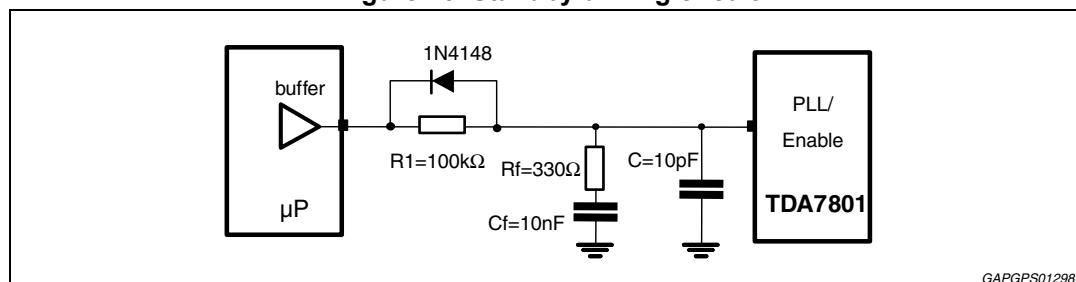
In amplifier-mode the PIN2 works as PLL filter pin. The TDA7801 will place this pin to have a precise voltage value.

During the transition from amplifier-mode to standby-mode, the device will try to force the Pin2 level sourcing a current I_{ILENB} .

5.2 Driving

In [Figure 26](#) an applicative schematic to drive the Pin 2 is reported. In the schematic, it is supposed that the TDA7801 is interfaced with a μP .

Figure 26. Standby driving circuit



The R_f and C_f components are respectively resistance and capacitance of the PLL filter. The resistance $R1$ and diode 1N4848 allows the Pin 2 to force to logic level low and the TDA7801 to force its voltage level in amplifier-mode. During the transition amplifier-mode/standby-mode the TDA7801 tries to forces the voltage on the PLL/Enable by sourcing a current flow. Since the PLL/ENABLE pin is forced at a voltage lower than V_{ILENB} in the above described conditions, the buffer input resistance should be chosen small enough to take this effect into account.

It's important to keep the PLL-Filter ground as close as possible to digital ground in the application board in order to minimize the PLL reference movement.

6 Functional description

6.1 Voltage supplies timing

TDA7801 internal voltage supplies rise time and fall time are determined by the two capacitors at pin 16 and 17, respectively digital supply pin (D3V3) and analog supply pin (A3V3). Capacitor on analog supply pin, (pin 17), and capacitor on digital supply, (pin 16), should respect the ratio 2:1. It is suggested to fix a minimum value of 22 μF on digital supply pin and 47 μF on analog supply pin, which correspond to a typical Turn-on time of 1.5 ms and a typical turn-off time of 8.5 ms.

6.2 Turn-on diagnostic description

Turn-on diagnostic is activated under I²C bus request. Detectable output faults are:

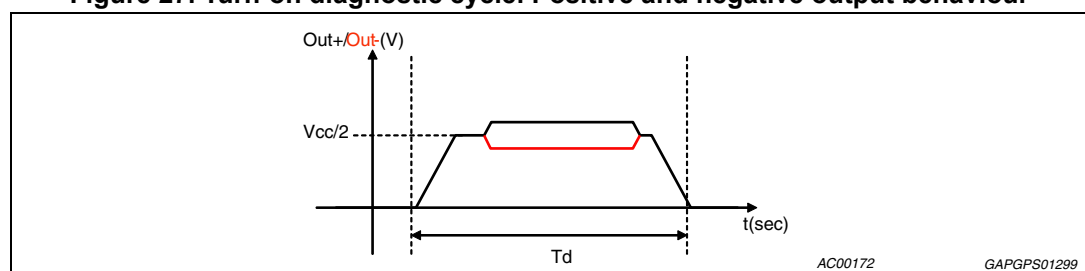
- Short to GND
- Short to V_s
- Short across the speaker
- Open load

In the TDA7801 a new diagnostic that exploits the presence of D/A converters has been implemented. To verify if some of the above connections are in place, a subsonic (inaudible) voltage pulse is digitally and internally generated and converted (*Figure 27*). The amplitude of this pulse is stopped when the current flowing through the speaker is the same as the prefixed one corresponding to a specified load. The exact knowledge of the voltage drop across the load in any phase of the diagnostic time gives the possibility to know the connected load.

During the observation time, the measured load is compared with tabled values in order to determine the result.

The turn-on diagnostic status is internally stored until a successive diagnostic pulse is requested.

Figure 27. Turn-on diagnostic cycle. Positive and negative output behaviour



A turn-on diagnostic cycle is activated writing '1' on the D7 of byte IB0 only when the amplifier is in Tristate-mode. Note that the turn-on diagnostic state machine is sensible to the rise edge of this bit. To run another cycle of turn-on diagnostic it is necessary to:

1. wait that the previous cycle ends;
2. clear the D7-IB0 bit.
3. write '1' on D7-IB0 bit.

It is possible to run the turn-on diagnostic several times by simply resetting the D7-IB0 meanwhile the amplifier is in amplifier mode and writing back '1' on D7-IB0 when the amplifier is in tristate mode.

Between two diagnostic sequences it is necessary to reset the data register by an I²C reading instruction. Note that the reading instruction has been placed during the second diagnostic pulse.

The μ P can program the TDA7801 in order to run a cycle of turn-on diagnostic and to move in amplifier-mode at the end of this cycle (Figure 28)); the I²C bus instructions needed to program this sequence are:

11011000 -00100000-1XXXXXXX-1XXXXXXX

Note: The diagnostic enable bit (D7-IB0) has to be set before the amplifier mode bit (D7-IB1)

Figure 28. Turn-on diag. cycle with transition in amp. mode. Positive and negative output behaviour

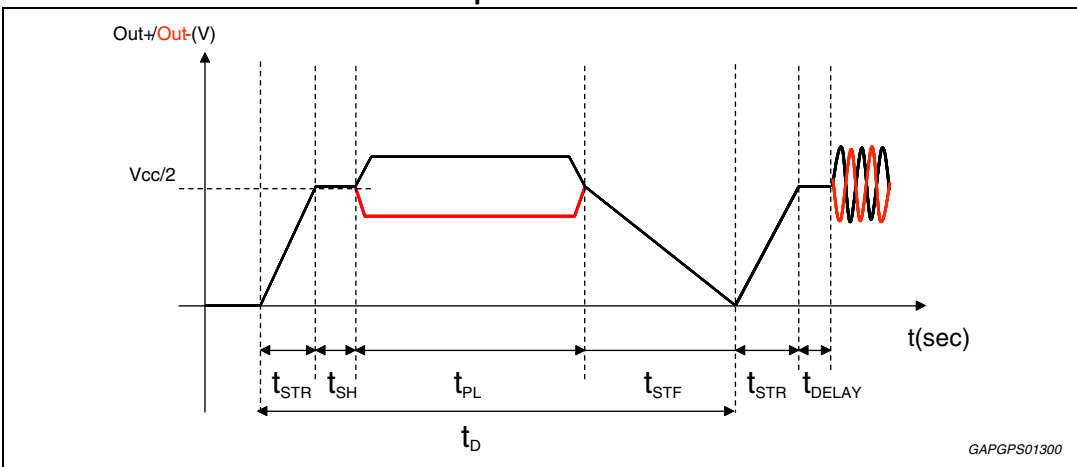


Table 7. Start-up diagnostic pulse typical timing

Symbol	Parameter	Value			Unit
		Min.	Typ.	Max	
$t_{STR}^{(1)}$	Start-up diagnostic rise	0.8	1.5	3	ms
$t_{SH}^{(2)}$	Short to Vcc/Gnd check		5		ms
$t_{PL}^{(2)}$	Plateau time		162		ms
$t_{STF}^{(1)}$	Start-up diagnostic fall	6	8.5	14	ms
$t_{DELAY}^{(2)}$	Delay time before play		5		ms
t_D	Diagnostic pulse		182	190	ms

1. These t_{STR} and t_{STF} values are relative to capacitors on A3V3 and D3V3 respectively equal to 47 μ F and 22 μ F. The t_{STR} and t_{STF} are proportional to capacitors value.

2. Values relative to $f_s = 44100$ Hz.

The information related to the outputs status is read and memorized at the end of the voltage pulse top. The diagnostic cycle last no more than T_d . No audible noise is generated in the process. As for short to GND / Vs the fault-detection thresholds remain unchanged independently of the gain setting. They are as in Figure 29.

Figure 29. Short to GND and short to V_s , threshold description

S.C. to GND	X	Normal Operation	X	S.C. to Vs	
0V	1.0V	2.0V	Vs-2.0V	Vs-1.0V	Vs

GAPGPS01301

Concerning short across the speaker / open speaker, the threshold varies from speaker mode to booster mode diagnostic setting, since different loads are expected (either normal speaker's impedance or high impedance). The speaker or booster mode is selected with bit D6-IB0 (channel 1 and 3) and bit D5-IB0 (channel 2 and 4). The values in case of speaker mode gain are as in [Figure 30](#).

Figure 30. Short across the speaker and open load threshold description, in amplifier mode.

S.C. across Load	X	Normal Load	X	Open Load	
0	0.5	1.65	25	75	infinite

GAPGPS01302

If the booster mode is selected, the same thresholds will change as in [Figure 31](#).

Figure 31. Short across the speaker and open load threshold description, in line driver mode.

When the amplifier is biased and the diagnostic is still enabled the permanent diagnostic takes place. The previous turn-on state is kept until a short appears at the outputs because only in this case a new diagnostic cycle can start.

6.3 Permanent diagnostic

Detectable conventional faults are:

- Short to GND
- Short to V_s
- Short across the speaker

The following additional features are provided:

- Output offset detection
- AC diagnostic

The TDA7801 diagnostic has 2 different cycles:

1. Restart cycle. It is a 1 ms pulse. During this period a check of the outputs is made.
2. Plateau cycle. It is a 100 ms pulse. During this period a check of the outputs is performed and the result of diagnostic analysis is communicated by means of I²C bus.

The TDA7801 has 2 different operating behaviors when a fault occurs:

1. Restart mode, (D6-IB0='0'). The diagnostic is not enabled. Each audio channel operates independently of each other. If any of the a.m. faults occurs, only the

channel(s) concerned are shut down. The diagnostic performs restart cycles every 1 ms until a fault condition is present. The amplifier restarts in play only once the overload is removed.

Diagnostic mode, (D6-IB0='1'). It is enabled via I²C bus and self activates if an output overload (so as to cause the intervention of the short-circuit protection) occurs to the speakers outputs. Once activated, the diagnostics procedure develops as below:

- The diagnostic performs 1 restart cycle in order to avoid momentary re-circulation spikes which could give erroneous diagnostic results. If normal situation (no overloads) is detected the channel returns active.
- Instead, if after 1 restart cycle an overload is detected then the diagnostic circuit performs a plateau cycle.
- After the plateau cycle, the fault audio channel generates restart cycles every 1 ms until a fault condition is present. The relevant data acquired during plateau cycle are stored and can be read by the microprocessor. A new plateau cycle can be activated by an I²C reading only if the fault condition persists. This is to ensure continuous diagnostics throughout the car-radio operating time.

The diagnostic performs another plateau cycle after each I²C bus registers read if the diagnostic bit is activated, (IB0-d7="1"). If I²C read is performed during the diagnostic permanent plateau cycle then, once the short is removed, the amplifier waits for another I²C read before starting to play again, in order to communicate the diagnostic plateau cycle results.

6.4 AC diagnostic

It is targeted at detecting accidental disconnection of tweeters in 2-way speaker and, more in general, presence of capacitive (AC) coupled loads. This diagnostic is based on the notion that the overall speaker's impedance (woofer + parallel tweeter) will tend to increase towards high frequencies if the tweeter gets disconnected, because the remaining speaker (woofer) would be out of its operating range (high impedance).

To determine the load impedance, a sinewave tone at a suitable ($F > 10$ kHz or even ultrasonic) frequency should be fed to the output pins. Depending on the test's result the AC diagnostic is able to determine if the tweeter is connected or not. The tweeter is not connected if for four consecutive sine wave the current threshold on the load is not surpassed.

AC diagnostic is managed by I²C commands. The AC diagnostic is enabled by bit D7 of register IB4, while the bit D6 is used to choose the current level threshold. The result of AC test are stored in the data register DB4 (bits D7:D4) which are set to logic level '1' if a tweeter is detected on the correspondent channel.

Note, the results on D7:D4 are valid only if the bit D3 is zero; in order to avoid this condition the pulse generated has to respect the condition $V_{out_peak} < V_{battery-4V}$.

6.5 Output DC offset detection

Any DC output offset exceeding $\pm V_O$ are signalled out. This inconvenient might occur as a consequence of improper DC input signal. The offset detection is performed at the end of the digital chain by a low pass digital filter. The offset detection is permanent, and also works in play mode. The results of the DC offset detection are obtained from the right pin for each channel (see I²C table in [Section 9](#)); the bits are continuously refreshed.

6.6 Multiple faults

Faults can occur simultaneously. If this happens, faults are read out according to a "priority table" (see [Table 8](#)); this guarantees that the most dangerous fault is signalled. This is true only for the turn-on diagnostic but not in case of permanent diagnostic (only the faults causing protection intervention are recognized).

Table 8. Multiple faults priority

	S. GND	S. Vs	S. Across L.	Open L.
S. GND	S. GND	S. Vs + S. GND	S. GND	S. GND
S. Vs	/	S. Vs	S. Vs	S. Vs
S. Across L.	/	/	S. Across L.	N.A.
Open L.	/	/	/	Open Load ⁽¹⁾

1. Only in Startup Diagnostic

In permanent diagnostic mode the table is the same, with only a difference concerning open load, which is not among the recognizable faults. If an open load is present during the device's normal operation, it should be detected at a subsequent turn-on diagnostic cycle (i.e. at the successive car radio turn-on).

6.7 Faults availability

All the results coming from I²C bus, by read operations, are the consequence of measurements inside a defined period of time. If the fault is stable throughout the whole period, it will be sent out.

The turn-on diagnostic faults are reported on the byte DB 0-3 at the bits D 4-0. The faults are consistent when the bit D6 of DB0 is '1'. The byte DB 0-3 is reset when read.

During Amplifier-mode, when the bit D4 of byte DB 0-3 is '1' an overload on the correspondent channel has been detected and a 100 ms permanent diagnostic cycle has been done. The data on the bits D 4-0 reports the results of this diagnostic cycle. If the bits are all zero it means that an overload event has been detected, a 100ms cycle has been performed and the fault has not been detected or removed.

6.8 I²C programming/reading sequence

A correct turn on/off sequence respectful of the diagnostic timings and producing no audible noises could be as follows (after battery connection):

- Turn-on:** (Stand-by out + Dlag Enable) → 200 ms (min.) → Muting out
- Turn-off:** Muting in → 10 ms → (Diag disable + stand-by in)
- Car radio installation:** Dlag enable (write) → 200 ms → I²C read (repeat until all faults disappear).

6.9 Legacy mode

In case of applications without the I²C bus the TDA7801 could be turned on in legacy mode.

In order to put the device in legacy mode it is enough to tie the IC clock pin (PIN 27) at Vcc. In this mode the device is turned on, as usual, with the ENABLE pin (PIN 2). The I²C Data pin (PIN26) acts as analog mute. The device is set with all the instruction registers equal to zero.

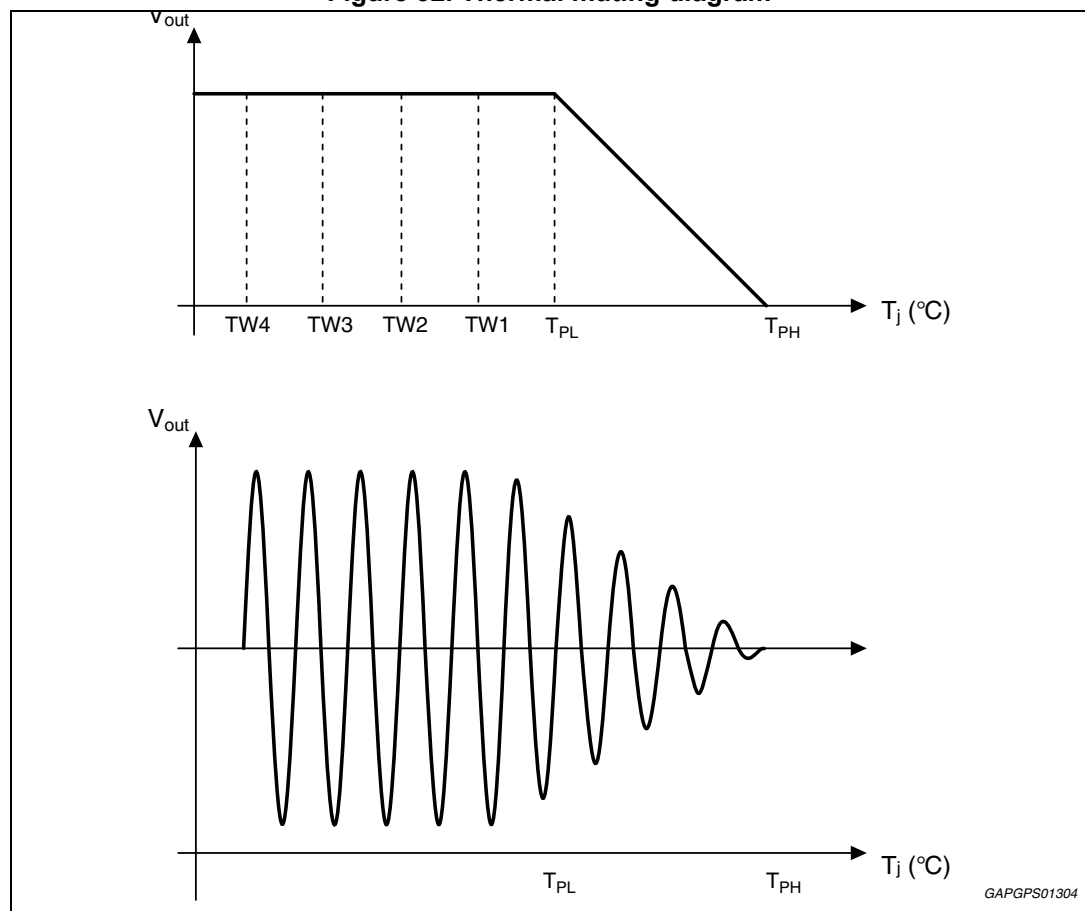
In legacy mode the I²S interface does not support the TDM format.

6.10 Thermal protection

The TDA7801 has four thermal warnings (Tw1, Tw2, Tw3, Tw4) at different temperatures which are stored on the I²C bus. Only one of the four thermal warnings could be sent to the DIAG pin. The selection is done by an I²C bus.

A mute function dependent on temperature is present in order to protect the junction by over-temperature with limited effects on the sound quality. For junction temperature over the thermal warning threshold T_{pl} , the device is gradually carried in mute. The mute level depends on the temperature: when the junction temperature reaches the T_{pl} threshold (refer to [Figure 32](#)), the output signal is attenuated of 0.5 dB, while when the junction temperature reaches T_{ph} the output attenuation is 60 dB. This attenuation is performed without output signal distortion.

Figure 32. Thermal muting diagram



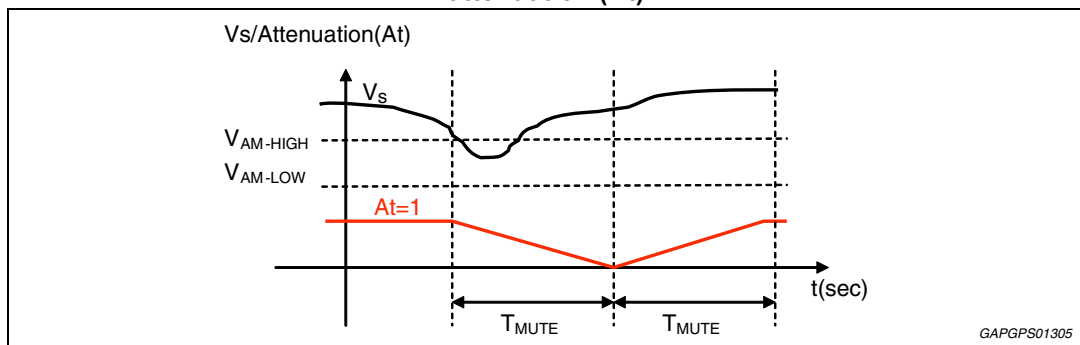
6.11 Under-voltage threshold

6.11.1 Supply voltage auto-mute threshold

The device in play-mode is put in mute when the supply voltage gets lower than the V_{AM} threshold.

When the supply voltage gets lower than the V_{AM} threshold the device is put in mute. The muting strategy in this case is reported in [Figure 33](#): once the supply voltage V_s becomes lower than V_{AM_HIGH} , analog mute and digital mute are activated. The analog mute attenuation is proportional to the V_s voltage and becomes equal to AM when the V_s gets lower than V_{AM_LOW} . Note that once the digital mute procedure is started, it cannot be stopped to move back the device in play, the procedure is going on until the attenuation level has reached AM. This mechanism avoids that a fast oscillation on V_s cause a similar oscillation on the output.

Figure 33. Low voltage mute attenuation, supply voltage variation (V_s); result digital attenuation (A_t)



6.11.2 Digital mute disabling

The digital mute is disabled in the following conditions:

- when TW1 threshold is trespassed (to avoid simultaneous intervention of digital mute and thermal mute)
- when the bit IB3-D5 is set to '1'
- during the start-up diagnostic

When the digital mute is disabled, the analog mute is kept active.

6.11.3 Power-on reset threshold

When the ENABLE pin is low or the supply voltage value doesn't guarantee the integrity of the I²C bus registers ($V_{POWERONRESET}$) the TDA7801 is put in tristate-mode and the registers are set to the initial state. The event is signalled by the low value of DIAG pin and the '0' value of bit D7 of byte DB0. The DIAG pin is set to high after a POR when the bit D7 of byte IB1 is set to '1' (amplifier mode on) if no other event on DIAG pin is present. The same I²C bus write operation automatically sets to '1' the bit D7 of byte DB0. When the device is programmed with the D7=1 of IB0 and D7=1 of byte IB1 the device turns-on after a diagnostic cycle and the DIAG pin stays low for the whole duration of the diagnostic cycle.

6.12 Fast mute features

The TDA7801 is put in mute by a fast-mute procedure by one of the following event:

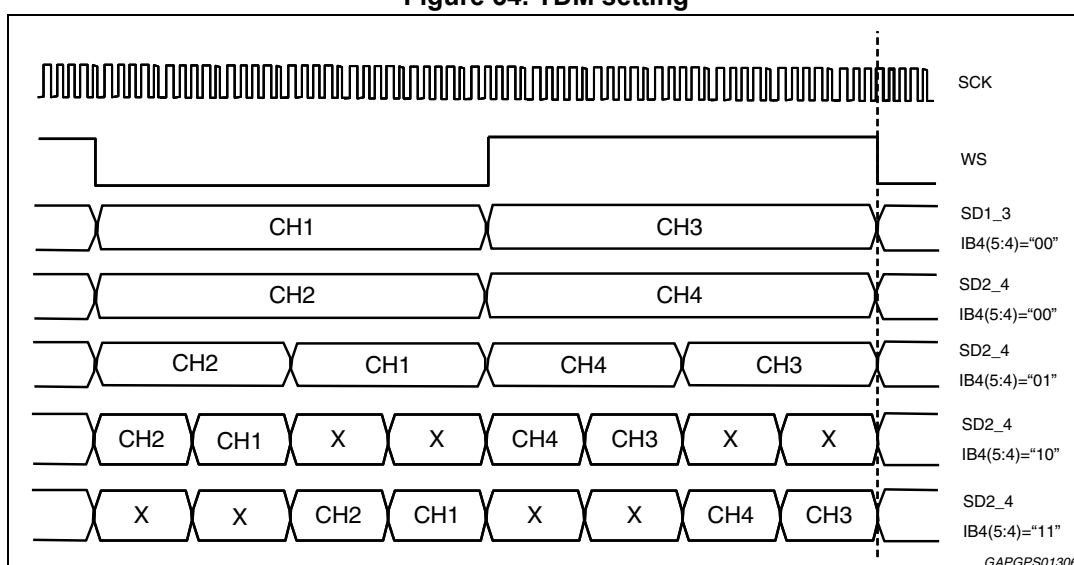
- the ENABLE pin is set to low
- the PLL loses the locking
- the V_S voltage level is under the auto-mute threshold.
- by an I²C programming

7 I²S bus interface

The TDA7801 accepts the I²S standard format that could be time division multiplexed (TDM), however the WS still needs a 50% duty-cycle to work correctly. The [Figure 34](#) shows the different I²C settings allowed for the I²S interface (2,4 or 8 channels transmission on a single serial data line (SD) can be selected). By I²C programming it is possible to choose between the following interface settings:

- channel 1 and channel 3 channel on SD1_3 and channel 2 and channel 4 on SD2_4
- all four channels on SD2_4. SD1_3 has not function.
- eight channels transferred on the SD2_4 line. This setting is feasible in the PowerSO36 and Flexiwatt27 package.

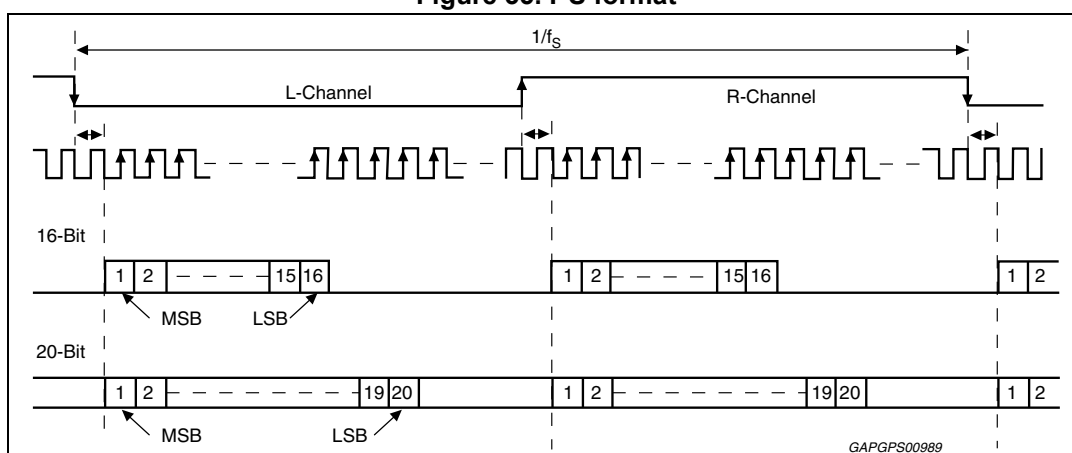
Figure 34. TDM setting



The TDA7801 accepts the I²S standard format with a bit clock (SCK) equal to 64 fs.

Note, TDM setting is guaranteed for a maximum $F_s = 96$ kHz.

Figure 35. I²S format



7.1 Interface timings requirements

The data interface timings are described below. In the TDA7801 the TDM format as shown in [Figure 34](#), is an I²S extended: if the four channels option is set then the serial clock is multiplied by two while it will be multiplied by four when the eight channels option is set. This means that it is important to keep a duty-cycle of 50% for the Word Select signal and moreover, all the timings for serial clock and data don't change in every I²S configuration.

Table 9. System clock frequencies for common audio sampling frequencies

Frequency sampling (f_s)	System clock frequency (f_{SCK}), (MHz)			
	I ² S standard ($f_s \times 64$)	TDM 4ch ($f_s \times 128$)	TDM 8ch md1 ($f_s \times 256$)	TDM 8ch md2 ($f_s \times 256$)
44.1 (kHz)	2.82	5.64	11.29	11.29
48.0 (kHz)	3.07	6.14	12.29	12.29
96.0 (kHz)	6.14	12.29	24.58	24.58
192.0 (kHz)	12.29	24.58	N.A.	N.A.

[Table 9](#) shows the values of system clock frequencies (serial clock SCK) for common audio sampling frequencies.

Figure 12 shows the detail of the audio input format as specified by the standard I²S specification. When more channels are sent the input format does not change and they follow the sequence as shown in [Figure 34](#).

Figure 36. Audio data input format

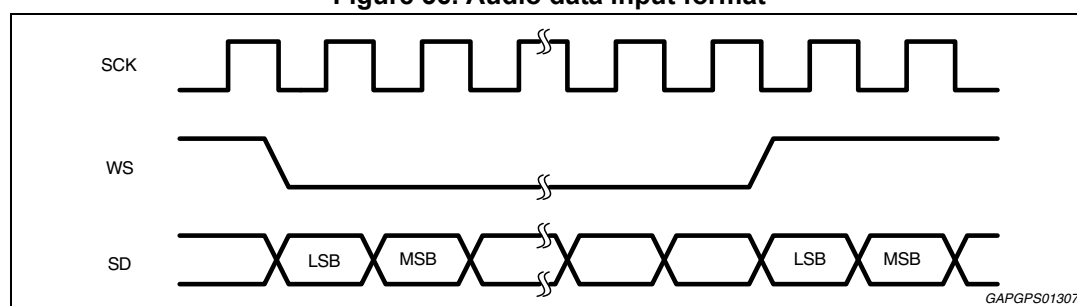


Figure 37. Audio interface timing

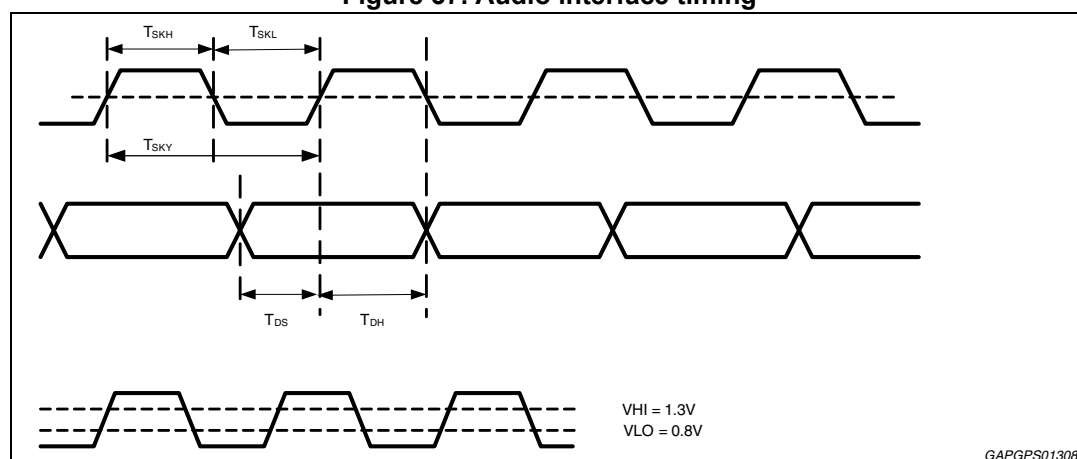


Table 10. Example timing for $t_{ck} = 1/f_{SCK}$, where f_{SCK} is stated in the [Table 9](#)

Parameter	MIN	TYP	MAX	Note
Clock period T_{SKY}	$0.9 \cdot T_{ck}$	T_{ck}	$1.1 \cdot T_{ck}$	
Clock HIGH T_{SKH}	$0.4 \cdot T_{ck}$			Measured from VHI to VHI
Clock LOW T_{SKL}	$0.4 \cdot T_{ck}$			Measured from VLO to VLO
Setup time SD to f_{SCK} rising edge T_{DS}	$0.2 \cdot T_{ck}$			
Hold time SD from f_{SCK} rising edge T_{HD}	$0.2 \cdot T_{ck}$		$0.8 \cdot T_{ck}^{(1)}$	
f_{SCK} duty-cycle	40%		60%	
VHI	1.3			
VLO			0.8	

1. Measured from VLO to VHI.

7.2 Group delay

The group delay of the amplifier is basically due the FIR filter of the interpolator and it is given by:

$$t_{DELAY} = \frac{32}{f_s}, (f_s < 48 \text{ kHz})$$

8 I²C bus interface

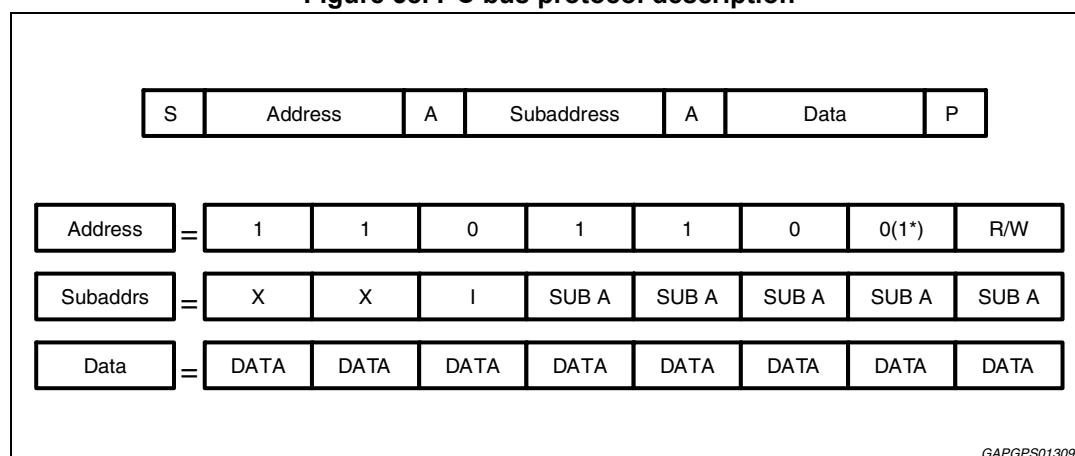
Data transmission from microprocessor to the TDA7801 and viceversa takes place through the 2 wires I²C bus interface, consisting of the two lines SDA and SCL (pull-up resistors to positive supply voltage must be connected).

When I²C bus is active any operating mode of the IC may be modified and the diagnostic may be controlled and results read back.

The protocol used for the bus is depicted in [Figure 38](#) and comprises:

- a start condition (S)
- a chip address byte (the LSB bit determines read/write transmission)
- a subaddress byte
- a sequence of data (N-bytes + acknowledge)
- a stop condition (P)

Figure 38. I²C bus protocol description



Description:

S = Start

R/W = '0' => Receive-Mode (Chip could be programmed by μ P)

I = Auto increment; when 1, the address is automatically increased for each byte transferred

X: not used

A = Acknowledge

P = Stop

MAX CLOCK SPEED 400kbit/sec

* = available in PowerSO36

8.1 Writing procedure

There are two possible procedures:

1. without increment: the I bit is set to 0 and the register is addressed by the subaddress. Only this register is written by the data following the subaddress byte.
2. with increment: the I bit is set to 1 and the first register written is the one addressed by subaddress. Then all the registers starting from the one indicated by this address up to stop bit (or up to last register) are written.

8.2 Reading procedure

There are two possible procedures:

1. without increment: the I bit is set to 0 and the register is addressed by the subaddress sent in the previous write procedure. Only this register is read by the data following the address.
2. with increment: the I bit is set to 1 and the first register read is the one addressed by subaddress sent in the previous write procedure. Then all registers starting from the one indicated by this address up to stop bit (or up to last register) are read.

Note: the reading procedure reset the register that has been read.

8.3 Data validity

The data on the SDA line must be stable during the high period of the clock. The high and low state of the data line can only change when the clock signal on the SCL line is low.

8.4 Start and stop conditions

A start condition is a high to low transition of the SDA line while SCL is high.
The stop condition is a low to high transition of the SDA line while SCL is high.

8.5 Byte format

Every byte transferred to the SDA line must contain 8 bits. Each byte must be followed by an acknowledge bit. The MSB is transferred first.

8.6 Acknowledge

The transmitter* puts a resistive HIGH level on the SDA line during the acknowledge clock pulse. The receiver** has to pull-down the SDA line during the acknowledge clock pulse, so that the SDA line is stable low using this clock pulse.

* Transmitter

- = master (μP) when it writes an address to the TDA7801
- = slave (TDA7801) when the μP reads a data byte from TDA7801

** Receiver

- = slave (TDA7801) when the μP writes an address to the TDA7801
- = master (μP) when it reads a data byte from TDA7801

9 I²C registers

9.1 IB0-Addr:"00000"

Table 11. IB0-Addr:"00000"

Bit	Instruction decoding bit
D7	0: diagnostic defeat 1: diagnostic enable
D6	0: Speaker mode diagnostic ch. 1 and 3 (FRONT) 1: Booster mode diagnostic ch. 1 and 3
D5	0: Speaker mode diagnostic ch. 2 and 4 (REAR) 1: Booster mode diagnostic ch. 2 and 4
D4	Gain channel 1 and 3 (FRONT) D4 D3
D3	00 GV1 01 GV2 10 GV3 11 GV4
D2	Gain channel 2 and 4 (REAR) D2 D1
D1	00 GV1 01 GV2 10 GV3 11 GV4
D0	0: No increase of digital gain 1: +6dB increase of digital gain

9.2 IB1-Addr:"00001"

Table 12. IB1-Addr:"00001"

Bit	Instruction decoding bit
D7	0: Amplifier mode off - Amplifier not working 1: Amplifier mode on - Amplifier working
D6	Mute Time Setting D6 D5 D4 mute timing(Fs=44.1kHz)
D5	000 1.45 ms 001 5.8 ms 010 11.6 ms 011 23.2 ms 100 34.8 ms 101 69.6 ms 110 140 ms 111 278 ms
D3	0: Mute channel 1 and 3 (FRONT) 1: Unmute channel 1 and 3

Table 12. IB1-Addr:"00001" (continued)

Bit	Instruction decoding bit	
D2	0: Mute channel 2 and 4 (REAR) 1: Unmute channel 2 and 4	
D1	Sample Frequency Range ⁽¹⁾ D1 D0	
D0	00	44.1/48 kHz
	01	44.1/48 kHz
	10	96 kHz
	11	192 kHz

1. When the amplifier is in Tristate Mode (IB0-D7=0 and IB1-D7=0), any accidental change of Frequency sample is ignored.

9.3 IB2-Addr:"00010"

Table 13. IB3-Addr:"00010"

Bit	Instruction decoding bit	
D7	0: no short fault information on diag. pin 1: short fault information on diag. pin	
D6	0: Offset information on diag pin 1: no offset information on diag pin	
D5	Temperature warning information on diag. pin D5 D4 D3	
D4	000	Tw1
	001	Tw2
D3	010	Tw3
	011	Tw4
	1xx	no thermal warning information on diag. pin
D2	Clip detection level D2 D1	
D1	00	1 %
	01	5 %
	10	10 %
	11	clip detection disabled
D0	0 (no selectable from user)	

9.4 IB3-Addr:"00011"

Table 14. IB3-Addr:"00011"

Bit	Instruction decoding bit
D7	0: Noise gating on 1: Noise gating off
D6	0 (not used)
D5	0: under-voltage digital mute on 1: under-voltage digital mute off
D4	Tristate channel 3 (right front) 0: ch.3 not in tristate 1: ch.3 in tristate
D3	Tristate channel 1 (left front) 0: ch.1 not in tristate 1: ch.1 in tristate
D2	Tristate channel 4 (right rear) 0: ch.4 not in tristate 1: ch.4 in tristate
D1	Tristate channel 2 (left rear) 0: ch.2 not in tristate 1: ch.2 in tristate
D0	0: Input high pass filter off 1: Input high pass filter on

9.5 IB4-Addr:"00100"

Table 15. IB4-Addr:"00100"

Bit	Instruction decoding bit
D7	AC diagnostic On (D7='1')
D6	AC diagnostic current threshold D6 = '0': high D6 = '1': low
D5	TDM 00 I2S standard
D4	01 I2S - 4 ch 10 I2S - 8 ch (first channels) 11 I2S - 8 ch (last channels)
D3	0 (not used)
D2	0 (not used)
D1	0 (not used)
D0	0 (not used)

9.6 DB0-Addr:"10000" - Channel 1 (left front)

Table 16. DB0-Addr:"10000" - Channel 1 (left front)

Bit	Instruction decoding bit
D7	Power on reset (POR) 0: After a POR the device is in tristate 1: The device has been put out of tristate at least one time after POR
D6	Start-up diagnostic status 0: Turn-On diag. cycle not activated or not terminated 1: Turn-On diag. cycle terminated
D5	Channel 1 offset detection 0: No output offset 1: Output offset detected
D4	Channel 1 ⁽¹⁾ 0: Permanent diagnostic cycle not activated or not terminated 1: Permanent diagnostic cycle terminated
D3	Channel 1 0: Normal load 1: Short load
D2	Channel 1 0: No open load 1: Open load detection (only during turn-on diagnostic)
D1	Channel 1 0: No short to Vcc 1: Short to Vcc
D0	Channel 1 0: No short to GND 1: Short to GND

1. The permanent diagnostic cycle is activated after each register reading if the permanent diagnostic is still present, (IB0-d7="1").

9.7 DB1-Addr:"10001" - Channel 2 (left rear)

Table 17. DB1-Addr:"10001" - Channel 2 (left rear)

Bit	Instruction decoding bit
D7	TW1 active 0: TW1 threshold not trespassed 1: TW1 threshold tress-passed
D6	TW2 active 0: TW2 threshold not trespassed 1: TW2 threshold tress-passed
D5	Channel 2 offset detection 0: No output offset 1: Output offset detected
D4	Channel 2 ⁽¹⁾ 0: permanent diag. cycle not activated or not terminated 1: Permanent diag. cycle terminated
D3	Channel 2 0: Normal load 1: Short load
D2	Channel 2 0: No open load 1: Open load detection (only during turn-on diagnostic)
D1	Channel 2 0: No short to Vcc 1: Short to Vcc
D0	Channel 2 0: No short to GND 1: Short to GND

1. The permanent diagnostic cycle is activated after each register reading if the permanent diagnostic is still present.

9.8 DB2-Addr:"10010"" - Channel 3 (right front)

Table 18. DB2-Addr:"10010"" - Channel 3 (right front)

Bit	Instruction decoding bit
D7	TW3 active 0: TW3 threshold not trespassed 1: TW3 threshold tress-passed
D6	TW4 active 0: TW4 threshold not trespassed 1: TW4 threshold tress-passed
D5	Channel 3 offset detection 0: No output offset 1: Output offset detected
D4	Channel 3 ⁽¹⁾ 0: Permanent diag. cycle not activated or not terminated 1: Permanent diag. cycle terminated
D3	Channel 3 0: Normal load 1: Short load
D2	Channel 3 0: No open load 1: Open load detection (only during turn-on diagnostic)
D1	Channel 3 0: No short to Vcc 1: Short to Vcc
D0	Channel 3 0: No short to GND 1: Short to GND

1. The permanent diagnostic cycle is activated after each register reading if the permanent diagnostic is still present.

9.9 DB3-Addr:"10011" - Channel 4 (right rear)

Table 19. DB3-Addr:"10011" - Channel 4 (right rear)

Bit	Instruction decoding bit
D7	0: channel 2 and 4 in play (FRONT) 1: channel 2 and 4 in mute
D6	0: channel 1 and 3 in play (REAR) 1: channel 1 and 3 in mute
D5	Channel 4 offset detection 0: No output offset 1: Output offset detected
D4	Channel 4 ⁽¹⁾ 0: permanent diag. cycle not activated or not terminated 1: Permanent diag. cycle terminated
D3	Channel 4 0: Normal load 1: Short load
D2	Channel 4 0: No open load 1: Open load detection (only during turn-on diagnostic)
D1	Channel 4 0: No short to Vcc 1: Short to Vcc
D0	Channel 4 0: No short to GND 1: Short to GND

1. The permanent diagnostic cycle is activated after each register reading if the permanent diagnostic is still present.

9.10 DB4-Addr:"10100"

Table 20. DB4-Addr:"10100"

Bit	Instruction decoding bit
D7	Ch1 tweeter present
D6	Ch2 tweeter present
D5	Ch3 tweeter present
D4	Ch4 tweeter present
D3	Signal to high
D2	0
D1	0
D0	0

10 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK[®] packages, depending on their level of environmental compliance. ECOPACK[®] specifications, grade definitions and product status are available at: www.st.com.

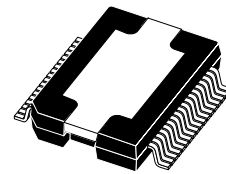
ECOPACK[®] is an ST trademark.

Figure 39. PowerSO36 (slug-up) mechanical data and package dimensions

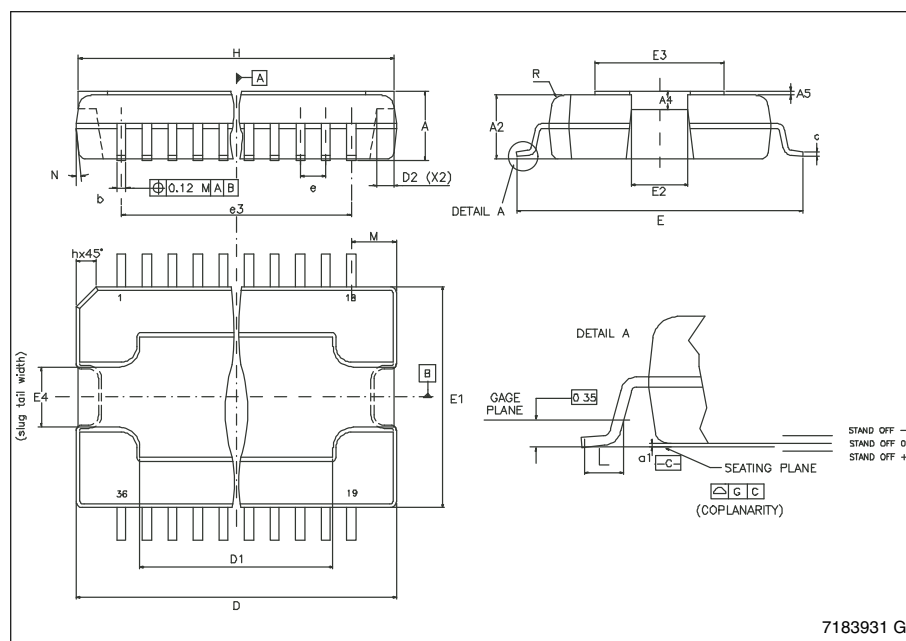
DIM.	mm			inch		
	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.
A	3.270	-	3.410	0.1287	-	0.1343
A2	3.100	-	3.180	0.1220	-	0.1252
A4	0.800	-	1.000	0.0315	-	0.0394
A5	-	0.200	-	-	0.0079	-
a1	0.030	-	-0.040	0.0012	-	-0.0016
b	0.220	-	0.380	0.0087	-	0.0150
c	0.230	-	0.320	0.0091	-	0.0126
D	15.800	-	16.000	0.6220	-	0.6299
D1	9.400	-	9.800	0.3701	-	0.3858
D2	-	1.000	-	-	0.0394	-
E	13.900	-	14.500	0.5472	-	0.5709
E1	10.900	-	11.100	0.4291	-	0.4370
E2	-	-	2.900	-	-	0.1142
E3	5.800	-	6.200	0.2283	-	0.2441
E4	2.900	-	3.200	0.1142	-	0.1260
e	-	0.650	-	-	0.0256	-
e3	-	11.050	-	-	0.4350	-
G	0	-	0.075	0	-	0.0031
H	15.500	-	15.900	0.6102	-	0.6260
h	-	-	1.100	-	-	0.0433
L	0.800	-	1.100	0.0315	-	0.0433
N	-	-	10°	-	-	10°
s	-	-	8°	-	-	8°

- (1) "D and E1" do not include mold flash or protrusions.
Mold flash or protrusions shall not exceed 0.15mm (0.006").
(2) No intrusion allowed inwards the leads.

OUTLINE AND MECHANICAL DATA



PowerSO36 (SLUG UP)



7183931 G

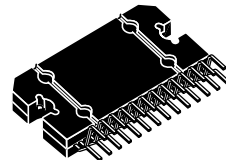
GAPGPS00098

Figure 40. Flexiwatt27 (vertical) mechanical data and package dimensions

DIM.	mm			inch		
	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.
A	4.45	4.50	4.65	0.175	0.177	0.183
B	1.80	1.90	2.00	0.070	0.074	0.079
C		1.40			0.055	
D	0.75	0.90	1.05	0.029	0.035	0.041
E	0.37	0.39	0.42	0.014	0.015	0.016
F ⁽¹⁾			0.57			0.022
G	0.80	1.00	1.20	0.031	0.040	0.047
G1	25.75	26.00	26.25	1.014	1.023	1.033
H ⁽²⁾	28.90	29.23	29.30	1.139	1.150	1.153
H1		17.00			0.669	
H2		12.80			0.503	
H3		0.80			0.031	
L ⁽²⁾	22.07	22.47	22.87	0.869	0.884	0.904
L1	18.57	18.97	19.37	0.731	0.747	0.762
L2 ⁽²⁾	15.50	15.70	15.90	0.610	0.618	0.626
L3	7.70	7.85	7.95	0.303	0.309	0.313
L4		5			0.197	
L5		3.5			0.138	
M	3.70	4.00	4.30	0.145	0.157	0.169
M1	3.60	4.00	4.40	0.142	0.157	0.173
N		2.20			0.086	
O		2			0.079	
R		1.70			0.067	
R1		0.5			0.02	
R2		0.3			0.12	
R3		1.25			0.049	
R4		0.50			0.019	
V	5° (Typ.)					
V1	3° (Typ.)					
V2	20° (Typ.)					
V3	45° (Typ.)					

(1): dam-bar protusion not included; (2): molding protusion included.

OUTLINE AND MECHANICAL DATA



Flexiwatt27 (vertical)

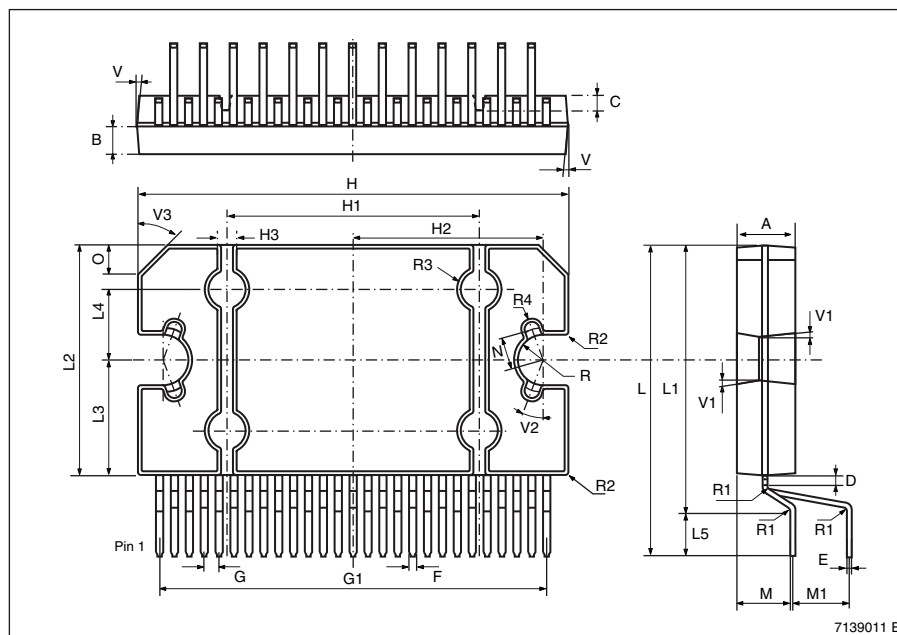
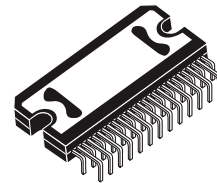
7139011 E
GAPGPS00096

Figure 41. Flexiwatt27 (horizontal) mechanical data and package dimensions

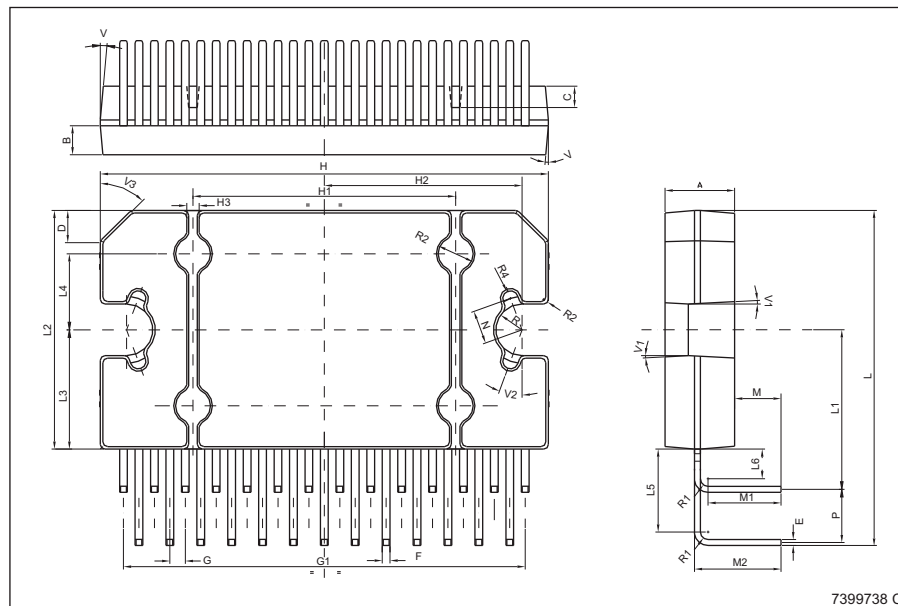
DIM.	mm			inch		
	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.
A	4.45	4.50	4.65	0.175	0.177	0.183
B	1.80	1.90	2.00	0.070	0.074	0.079
C		1.40			0.055	
D		2.00			0.079	
E	0.37	0.39	0.42	0.014	0.015	0.016
F (1)			0.57			0.022
G	0.75	1.00	1.25	0.0295	0.040	0.0492
G1	25.70	26.00	26.30	1.0118	1.023	1.0354
H (2)	28.90	29.23	29.30	1.139	1.150	1.153
H1		17.00			0.669	
H2		12.80			0.503	
H3		0.80			0.031	
L (2)	21.64	22.04	22.44	0.852	0.868	0.883
L1	10.15	10.5	10.85	0.40	0.413	0.427
L2 (2)	15.50	15.70	15.90	0.610	0.618	0.626
L3	7.70	7.85	7.95	0.303	0.309	0.313
L4		5			0.197	
L5	5.15	5.45	5.85	0.203	0.214	0.23
L6	1.80	1.95	2.10	0.070	0.077	0.083
M	2.75	3.00	3.50	0.108	0.118	0.138
M1		4.73			0.186	
M2		5.61			0.220	
N		2.20			0.086	
P	3.20	3.50	3.80	0.126	0.138	0.15
R		1.70			0.067	
R1		0.50			0.02	
R2		0.30			0.12	
R3		1.25			0.049	
R4		0.50			0.02	
V	5° (Typ.)					
V1	3° (Typ.)					
V2	20° (Typ.)					
V3	45° (Typ.)					

(1): dam-bar protusion not included; (2): molding protusion included

OUTLINE AND MECHANICAL DATA



Flexiwatt27 (Horizontal)



7399738 C

GAPGPS00095

Figure 42. Flexiwatt27 (SMD) mechanical data and package dimensions

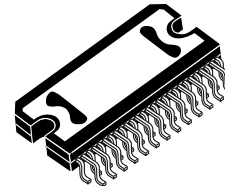
DIM.	mm			inch		
	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.
A	4.45	4.50	4.65	0.1752	0.1772	0.1831
B	2.12	2.22	2.32	0.0835	0.0874	0.0913
C		1.40			0.0551	
D		2.00			0.0787	
E	0.36	0.40	0.44	0.0142	0.0157	0.0173
F(**)	0.47	0.51	0.57	0.0185	0.0201	0.0224
G(**)	0.75	1.00	1.25	0.0295	0.0394	0.0492
G1	25.70	26.00	26.30	1.0118	1.0236	1.0354
G2(**)	1.75	2.00	2.25	0.0689	0.0787	0.0886
H(**)	28.85	29.23	29.40	1.1358	1.1508	1.1575
H1		17.00			0.6693	
H2		12.80			0.5039	
H3		0.80			0.0315	
L(**)	15.50	15.70	15.90	0.6102	0.6181	0.6260
L1	7.70	7.85	7.95	0.3031	0.3091	0.3130
L2	14.00	14.20	14.40	0.5512	0.5591	0.5669
L3	11.80	12.00	12.20	0.4646	0.4724	0.4803
L4	1.30	1.48	1.66	0.0512	0.0583	0.0654
L5	2.42	2.50	2.58	0.0953	0.0984	0.1016
L6	0.42	0.50	0.58	0.0165	0.0197	0.0228
M		1.50			0.0591	
N		2.20			0.0866	
N1	1.30	1.48	1.66	0.0512	0.0583	0.0654
N2(**)	2.73	2.83	2.93	0.1075	0.1114	0.1154
P(**)	4.73	4.83	4.93	0.1862	0.1902	0.1941
R		1.70			0.0669	
R1		0.30			0.0118	
R2	0.35	0.40	0.45	0.0138	0.0157	0.0177
R3	0.35	0.40	0.45	0.0138	0.0157	0.0177
R4		0.50			0.0197	
T(**)	-0.08		0.10	-0.0031		0.0039
aaa(**)		0.1			0.0039	
V		45°			45°	
V1		3°			3°	
V2	3°	5°	7°	3°	5°	7°
V3	12°	15°	18°	12°	15°	18°
V4		5°			5°	
V5		20°			20°	

(*) Golden parameters

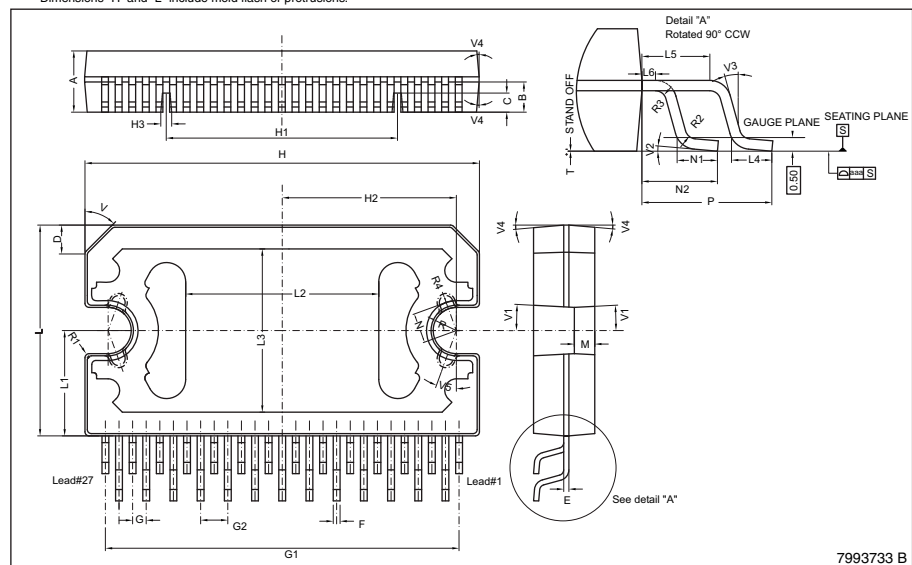
(**) – Dimension "F" doesn't include dam-bar protrusion.

– Dimensions "H" and "L" include mold flash or protrusions.

OUTLINE AND MECHANICAL DATA



Flexiwatt27 (SMD)



7993733 B

GAPGPS00097

11 Revision history

Table 21. Document revision history

Date	Revision	Changes
13-Feb-2012	1	Initial release.
11-Dec-2012	2	Corrected typeset error of the "a1" dimension on the Figure 39: PowerSO36 (slug-up) mechanical data and package dimensions on page 43 .
26-Feb-2013	3	Updated Table 4: Absolute maximum ratings on page 12 .
18-Sep-2013	4	Updated Disclaimer.

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