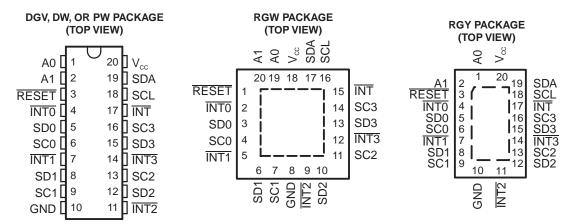
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FEATURES

- 1-of-4 Bidirectional Translating Switches
- I²C Bus and SMBus Compatible
- Four Active-Low Interrupt Inputs
- Active-Low Interrupt Output
- Active-Low Reset Input
- Two Address Pins, Allowing up to Four Devices on the I²C Bus
- Channel Selection Via I²C Bus, In Any Combination
- Power Up With All Switch Channels Deselected
- Low R_{ON} Switches
- Allows Voltage-Level Translation Between 1.8-V, 2.5-V, 3.3-V, and 5-V Buses

- No Glitch on Power Up
- Supports Hot Insertion
- Low Standby Current
- Operating Power-Supply Voltage Range of 2.3 V to 5.5 V
- 5.5-V Tolerant Inputs
- 0 to 400-kHz Clock Frequency
- Latch-Up Performance Exceeds 100 mA Per JESD 78
- ESD Protection Exceeds JESD 22
 - 2000-V Human-Body Model (A114-A)
 - 200-V Machine Model (A115-A)
 - 1000-V Charged-Device Model (C101)



DESCRIPTION/ORDERING INFORMATION

The PCA9545A is a quad bidirectional translating switch controlled via the I^2C bus. The SCL/SDA upstream pair fans out to four downstream pairs, or channels. Any individual SCn/SDn channel or combination of channels can be selected, determined by the contents of the programmable control register. Four interrupt inputs ($\overline{INT3}$ – $\overline{INT0}$), one for each of the downstream pairs, are provided. One interrupt (\overline{INT}) output acts as an AND of the four interrupt inputs.

An active-low reset (\overline{RESET}) input allows the PCA9545A to recover from a situation in which one of the downstream I²C buses is stuck in a low state. Pulling \overline{RESET} low resets the I²C state machine and causes all the channels to be deselected, as does the internal power-on reset function.

The pass gates of the switches are constructed such that the V_{CC} pin can be used to limit the maximum high voltage, which will be passed by the PCA9545A. This allows the use of different bus voltages on each pair, so that 1.8-V, 2.5-V, or 3.3-V parts can communicate with 5-V parts, without any additional protection. External pullup resistors pull the bus up to the desired voltage level for each channel. All I/O pins are 5.5-V tolerant.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

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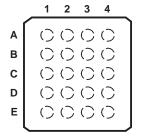
DESCRIPTION/ORDERING INFORMATION (CONTINUED)

ORDERING INFORMATION

T _A	PACKA	GE ⁽¹⁾	ORDERABLE PART NUMBER	TOP-SIDE MARKING	
	QFN – RGW	Reel of 3000	PCA9545ARGWR	PD545A	
	QFN – RGY	Reel of 1000	PCA9545ARGYR	PD545A	
		Tube of 25	PCA9545ADW	DCA0545A	
	SOIC - DW	Reel of 2000	PCA9545ADWR	PCA9545A	
		Reel of 250	PCA9545ADWT	PCA9545A	
		Tube of 70	PCA9545APW	PD545A	
	TOCOD DW	Tube of 70	PCA9545APWE4		
-40°C to 85°C		Reel of 2000	PCA9545APWR	PD545A	
	TSSOP – PW	Reel of 2000	PCA9545APWRE4		
		Dool of 250	PCA9545APWT	PD545A	
		Reel of 250	PCA9545APWTE4		
	TVSOP – DGV	Reel of 2000	PCA9545ADGVR	PD545A	
	TVSOP - DGV	Reel of 250	PCA9545ADGVT	PD545A	
	VFBGA – GQN	Reel of 1000	PCA9545AGQNR	PD545A	
	VFBGA – ZQN (Pb-free) Reel of 1000		PCA9545AZQNR	PD545A	

⁽¹⁾ Package drawings, standard packing quantities, thermal data, symbolization, and PCB design guidelines are available at www.ti.com/sc/package.

GQN OR ZQN PACKAGE (TOP VIEW)



TERMINAL ASSIGNMENTS

	1	2	3	4
Α	A1	A0	V _{CC}	SDA
В	ĪNT0	ĪNT	RESET	SCL
С	SC0	SD0	SD3	SC3
D	SD1	SC2	ĪNT1	ĪNT3
Е	GND	SC1	ĪNT2	SD2

PCA9545A 4-CHANNEL I²C AND SMBus SWITCH WITH INTERRUPT LOGIC AND RESET FUNCTIONS

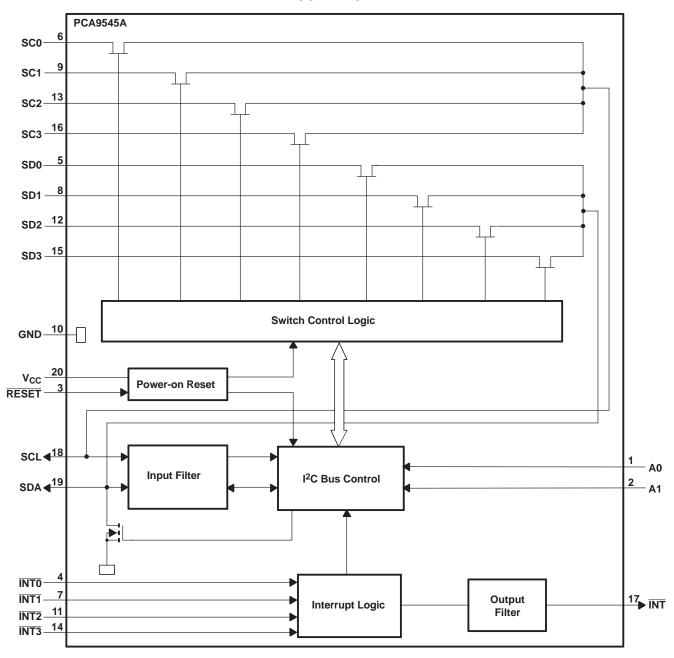
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TERMINAL FUNCTIONS

	NO.			
DGV, DW, PW, AND RGY	RGW	GQN AND ZQN	NAME	DESCRIPTION
1	19	A2	A0	Address input 0. Connect directly to V _{CC} or ground.
2	20	A1	A1	Address input 1. Connect directly to V _{CC} or ground.
3	1	В3	RESET	Active-low reset input. Connect to V_{CC} through a pullup resistor, if not used.
4	2	B1	ĪNT0	Active-low interrupt input 0. Connect to V _{CC} through a pullup resistor.
5	3	C2	SD0	Serial data 0. Connect to V _{CC} through a pullup resistor.
6	4	C1	SC0	Serial clock 0. Connect to V _{CC} through a pullup resistor.
7	5	D3	ĪNT1	Active-low interrupt input 1. Connect to V _{CC} through a pullup resistor.
8	6	D1	SD1	Serial data 1. Connect to V _{CC} through a pullup resistor.
9	7	E2	SC1	Serial clock 1. Connect to V _{CC} through a pullup resistor.
10	8	E1	GND	Ground
11	9	E3	ĪNT2	Active-low interrupt input 2. Connect to V _{CC} through a pullup resistor.
12	10	E4	SD2	Serial data 2. Connect to V _{CC} through a pullup resistor.
13	11	D2	SC2	Serial clock 2. Connect to V _{CC} through a pullup resistor.
14	12	D4	ĪNT3	Active-low interrupt input 3. Connect to V _{CC} through a pullup resistor.
15	13	C3	SD3	Serial data 3. Connect to V _{CC} through a pullup resistor.
16	14	C4	SC3	Serial clock 3. Connect to V _{CC} through a pullup resistor.
17	15	B2	ĪNT	Active-low interrupt output. Connect to V_{CC} through a pullup resistor.
18	16	B4	SCL	Serial clock line. Connect to V _{CC} through a pullup resistor.
19	17	A4	SDA	Serial data line. Connect to V _{CC} through a pullup resistor.
20	18	A3	V _{CC}	Supply power



BLOCK DIAGRAM



Pin numbers shown are for DGV, DW, PW, and RGY packages.

WITH INTERRUPT LOGIC AND RESET FUNCTIONS

PCA9545A

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Device Address

Following a start condition, the bus master must output the address of the slave it is accessing. The address of the PCA9545A is shown in Figure 1. To conserve power, no internal pullup resistors are incorporated on the hardware-selectable address pins, and they must be pulled high or low.

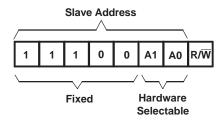


Figure 1. PCA9545A Address

The last bit of the slave address defines the operation to be performed. When set to a logic 1, a read is selected, while a logic 0 selects a write operation.

Control Register

Following the successful acknowledgment of the slave address, the bus master sends a byte to the PCA9545A, which is stored in the control register (see Figure 2). If multiple bytes are received by the PCA9545A, it saves the last byte received. This register can be written and read via the I²C bus.

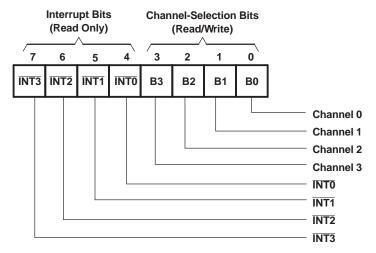


Figure 2. Control Register

Control Register Definition

One or several SCn/SDn downstream pairs, or channels, are selected by the contents of the control register (see Table 1). After the PCA9545A has been addressed, the control register is written. The four LSBs of the control byte are used to determine which channel or channels are to be selected. When a channel is selected, the channel becomes active after a stop condition has been placed on the I2C bus. This ensures that all SCn/SDn lines are in a high state when the channel is made active, so that no false conditions are generated at the time of connection. A stop condition must occur always right after the acknowledge cycle.

PCA9545A 4-CHANNEL I²C AND SMBus SWITCH WITH INTERRUPT LOGIC AND RESET FUNCTIONS

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Table 1. Control Register Write (Channel Selection), Control Register Read (Channel Status)⁽¹⁾

ĪNT3	INT2	INT1	INT0	D3	B2	B1	В0	COMMAND	
Х	Х	Х	X	Х	X	Х	0	Channel 0 disabled	
^	^	^	^	^	^	^	1	Channel 0 enabled	
Х	X	X	X		X	0	Х	Channel 1 disabled	
^	^	^	^	X	^	1	^	Channel 1 enabled	
Х	X	X	Х	Х	0	X	Х	Channel 2 disabled	
^		^		^	1 X		^	Channel 2 enabled	
Х	Х	V	X	Х	0	X	Х	Х	Channel 3 disabled
^	^	^	^	1	^	^	^	Channel 3 enabled	
0	0	0	0	0	0	Х	0	No channel selected, power-up/reset default state	

⁽¹⁾ Several channels can be enabled at the same time. For example, B3 = 0, B2 = 1, B1 = 1, B0 = 0 means that channels 0 and 3 are disabled, and channels 1 are 2 and enabled. Care should be taken not to exceed the maximum bus capacity.

Interrupt Handling

The PCA9545A provides four interrupt inputs (one for each channel) and one open-drain interrupt output (see Table 2). When an interrupt is generated by any device, it is detected by the PCA9545A and the interrupt output is driven low. The channel does not need to be active for detection of the interrupt. A bit also is set in the control register.

Bits 4–7 of the control register correspond to channels 0–3 of the PCA9545A, respectively. Therefore, if an interrupt is generated by any device connected to channel 1, the state of the interrupt inputs is loaded into the control register when a read is accomplished. Likewise, an interrupt on any device connected to channel 0 would cause bit 4 of the control register to be set on the read. The master then can address the PCA9545A and read the contents of the control register to determine which channel contains the device generating the interrupt. The master then can reconfigure the PCA9545A to select this channel and locate the device generating the interrupt and clear it.

It should be noted that more than one device can provide an interrupt on a channel, so it is up to the master to ensure that all devices on a channel are interrogated for an interrupt.

The interrupt inputs can be used as general-purpose inputs if the interrupt function is not required.

If unused, interrupt input(s) must be connected to V_{CC}.

Table 2. Control Register Read (Interrupt)⁽¹⁾

ĪNT3	ĪNT2	ĪNT1	ĪNT0	D3	B2	B1	В0	COMMAND	
Х	X	X	0		X	Х		No interrupt on channel 0	
^	^	^	1	^	^	^	^	Interrupt on channel 0	
V	X	0	X	V	V	Х	Х	V	No interrupt on channel 1
X		1	^	^		^	^	Interrupt on channel 1	
V	0	V	V	V	V	V	V	No interrupt on channel 2	
X	1	X	X	Χ	Χ	X	X	Interrupt on channel 2	
0	V	V	V	V	V	V	V	No interrupt on channel 3	
1	^	^	X	^	X	^	^	Interrupt on channel 3	

⁽¹⁾ Several interrupts can be active at the same time. For example, $\overline{INT3} = 0$, $\overline{INT2} = 1$, $\overline{INT1} = 1$, $\overline{INT0} = 0$ means that there is no interrupt on channels 0 and 3, and there is interrupt on channels 1 and 2.

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RESET Input

The $\overline{\text{RESET}}$ input can be used to recover the PCA9545A from a bus-fault condition. The registers and the I²C state machine within this device initialize to their default states if this signal is asserted low for a minimum of t_{WL} . All channels also are deselected in this case. $\overline{\text{RESET}}$ must be connected to V_{CC} through a pullup resistor.

Power-On Reset

When power is applied to V_{CC} , an internal power-on reset holds the PCA9545A in a reset condition until V_{CC} has reached V_{POR} . At this point, the reset condition is released and the PCA9545A registers and I^2C state machine are initialized to their default states, all zeroes, causing all the channels to be deselected. Thereafter, V_{CC} must be lowered below 0.2 V to reset the device.

Voltage Translation

The pass-gate transistors of the PCA9545A are constructed such that the V_{CC} voltage can be used to limit the maximum voltage that is passed from one I^2C bus to another.

Figure 3 shows the voltage characteristics of the pass-gate transistors (note that the graph was generated using data specified in the *electrical characteristics* section of this data sheet). In order for the PCA9545A to act as a voltage translator, the V_{pass} voltage must be equal to or lower than the lowest bus voltage. For example, if the main bus is running at 5 V and the downstream buses are 3.3 V and 2.7 V, V_{pass} must be equal to or below 2.7 V to effectively clamp the downstream bus voltages. As shown in Figure 3, V_{pass} (max) is at 2.7 V when the PCA9545A supply voltage is 3.5 V or lower, so the PCA9545A supply voltage could be set to 3.3 V. Pullup resistors then can be used to bring the bus voltages to their appropriate levels (see Figure 13).

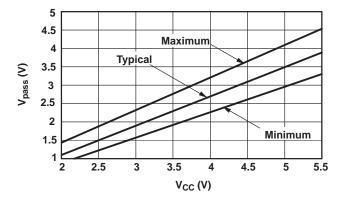


Figure 3. V_{pass} Voltage vs V_{CC}

I²C Interface

The I^2C bus is for two-way two-line communication between different ICs or modules. The two lines are a serial data line (SDA) and a serial clock line (SCL). Both lines must be connected to a positive supply via a pullup resistor when connected to the output stages of a device. Data transfer can be initiated only when the bus is not busy.

One data bit is transferred during each clock pulse. The data on the SDA line must remain stable during the high period of the clock pulse, as changes in the data line at this time are interpreted as control signals (see Figure 4).



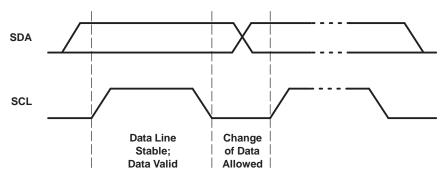


Figure 4. Bit Transfer

Both data and clock lines remain high when the bus is not busy. A high-to-low transition of the data line while the clock is high is defined as the start condition (S). A low-to-high transition of the data line while the clock is high is defined as the stop condition (P) (see Figure 5).

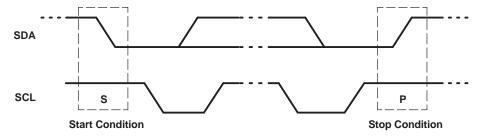


Figure 5. Definition of Start and Stop Conditions

A device generating a message is a transmitter; a device receiving a message is the receiver. The device that controls the message is the master, and the devices that are controlled by the master are the slaves (see Figure 6).

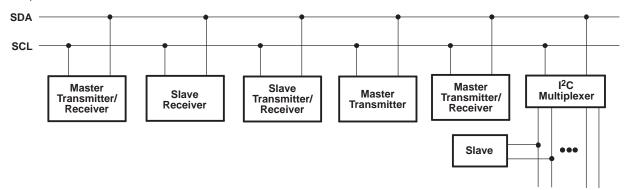


Figure 6. System Configuration

The number of data bytes transferred between the start and the stop conditions from transmitter to receiver is not limited. Each byte of eight bits is followed by one acknowlege (ACK) bit. The transmitter must release the SDA line before the receiver can send an ACK bit.

When a slave receiver is addressed, it must generate an ACK after the reception of each byte. Also, a master must generate an ACK after the reception of each byte that has been clocked out of the slave transmitter. The device that acknowledges must pull down the SDA line during the ACK clock pulse so that the SDA line is stable low during the high pulse of the ACK-related clock period (see Figure 7). Setup and hold times must be taken into account.



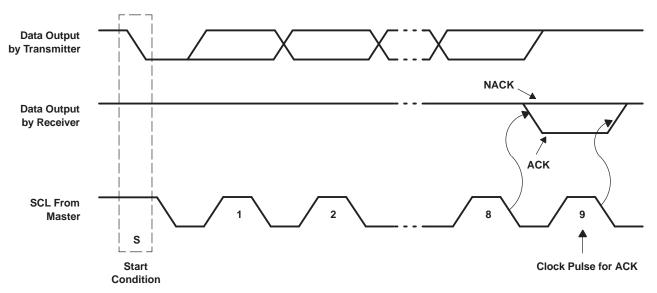


Figure 7. Acknowledgment on the I²C Bus

A master receiver must signal an end of data to the transmitter by not generating an acknowledge (NACK) after the last byte has been clocked out of the slave. This is done by the master receiver by holding the SDA line high. In this event, the transmitter must release the data line to enable the master to generate a stop condition.

Data is transmitted to the PCA9545A control register using the write mode shown in Figure 8.

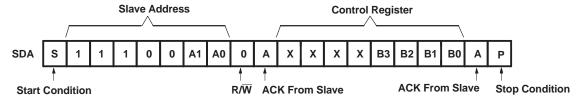


Figure 8. Write Control Register

Data is read from the PCA9545A control register using the read mode shown in Figure 9.

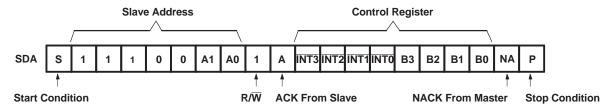


Figure 9. Read Control Register

PCA9545A 4-CHANNEL I²C AND SMBus SWITCH WITH INTERRUPT LOGIC AND RESET FUNCTIONS

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Absolute Maximum Ratings⁽¹⁾

over operating free-air temperature range (unless otherwise noted)

			MIN	MAX	UNIT
V_{CC}	Supply voltage range		-0.5	7	V
V_{I}	Input voltage range (2)		-0.5	7	V
I	Input current			±20	mA
Io	Output current			±25	mA
	Continuous current through V _{CC}			±100	mA
	Continuous current through GND			±100	mA
		DGV package		92	92
		DW package		58	
Δ	Package thermal impedance (3)	GQN/ZQN package		78	°C/W
θ_{JA}	Fackage mermai impedance (%)	PW package		83	C/VV
		RGW package		TBD	
		RGY package		47	
P _{tot}	Total power dissipation			400	mW
T _{stg}	Storage temperature range		-65	150	°C
T_A	Operating free-air temperature range		-40	85	°C

⁽¹⁾ Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

Recommended Operating Conditions⁽¹⁾

			MIN	MAX	UNIT
V_{CC}	Supply voltage		2.3	5.5	V
V	High level input voltage	SCL, SDA	$0.7 \times V_{CC}$	6	V
V _{IH}	High-level input voltage	A1, A0, INT3–INT0, RESET	0.7 × V _{CC}	V _{CC} + 0.5	
V	Low loval input valtage	SCL, SDA	-0.5	$0.3 \times V_{CC}$	V
V_{IL}	Low-level input voltage	A1, A0, ĪNT3–ĪNT0, RESET	-0.5	$0.3 \times V_{CC}$	V
T_A	Operating free-air temperature		-40	85	°C

All unused inputs of the device must be held at V_{CC} or GND to ensure proper device operation. Refer to the TI application report, Implications of Slow or Floating CMOS Inputs, literature number SCBA004.

⁽²⁾ The input negative-voltage and output voltage ratings may be exceeded if the input and output current ratings are observed.

⁽³⁾ The package thermal impedance is calculated in accordance with JESD 51-7.

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Electrical Characteristics

over recommended operating free-air temperature range (unless otherwise noted)

	PARAMETEI	R	TEST C	ONDITIONS	V _{cc}	MIN	TYP ⁽¹⁾	MAX	UNIT
V_{POR}	Power-on reset v	oltage (2)	No load,	$V_I = V_{CC}$ or GND	V _{POR}		1.6	2.1	V
					5 V		3.6		
					4.5 V to 5.5 V	2.6		4.5	
					3.3 V		1.9		
V_{pass}	Switch output vol	tage	$V_{SWin} = V_{CC}$	$I_{SWout} = -100 \mu A$	3 V to 3.6 V	1.6		2.8	V
					2.5 V		1.5		
					2.3 V to 2.7 V	1.1		2	
I _{OH}	ĪNT		$V_O = V_{CC}$		2.3 V to 5.5 V			10	μΑ
0			V _{OL} = 0.4 V			3	7		•
I _{OL}	SCL, SDA		V _{OL} = 0.6 V		2.3 V to 5.5 V	6	10		mA
OL .	ĪNT		V _{OL} = 0.4 V			3			
	SCL, SDA		OL .					±1	
	SC3-SC0, SD3-	SD0						±1	
I _I	A1, A0		$V_I = V_{CC}$ or GND	1	2.3 V to 5.5 V			±1	μΑ
	INT3-INT0							±1	
	RESET		_					±1	
					5.5 V		3	12	
	Operating mode	f _{SCL} = 100 kHz	$V_I = V_{CC}$ or GND	$I_0 = 0$	3.6 V		3	11	μА
		002		. 0	2.7 V		3	10	
		Low inputs		I _O = 0	5.5 V		0.3	1	
I _{CC}			V _I = GND,		3.6 V		0.1	1	
				O .	2.7 V		0.1	1	
	Standby mode	andby mode		5.5 V		0.3	1	•	
		High inputs	$V_1 = V_{CC},$ $I_0 =$	$I_O = 0$	3.6 V		0.1	1	
					2.7 V		0.1	1	
			One INT3-INT0 Other inputs at V	input at 0.6 V, _{CC} or GND			8	15	
	Supply-current	INT3-INT0		input at V _{CC} – 0.6 V,			8	15	
ΔI_{CC}	change	CCL CDA	SCL or SDA inpu Other inputs at V		2.3 V to 5.5 V		8	15	μΑ
		SCL, SDA	SCL or SDA inpu Other inputs at V	ut at V _{CC} – 0.6 V, V _{CC} or GND			8	15	
	A1, A0						4.5	6	
C _i	INT3-INT0		$V_I = V_{CC}$ or GND)	2.3 V to 5.5 V		4.5	6	pF
	RESET						4.5	5.5	
C (3)	SCL, SDA		\/ _ \/ _ a= CND	Switch OFF	2.2.V.to F.F.V		15	19	۵۲
C _{io(OFF)} (3)	SC3-SC0, SD3-	SD0	$V_I = V_{CC}$ or GND	, SWILCTI OFF	2.3 V to 5.5 V		6	8	pF
	•		V 04V	1 4E ^	4.5 V to 5.5 V	4	9	16	
R _{ON}	Switch on-state r	esistance	$V_0 = 0.4 V,$	$I_O = 15 \text{ mA}$	3 V to 3.6 V	5	11	20	Ω
			V _O = 0.4 V,	I _O = 10 mA	2.3 V to 2.7 V	7	16	45	

 ⁽¹⁾ All typical values are at nominal supply voltage (2.5-V, 3.3-V, or 5-V V_{CC}), T_A = 25°C.
 (2) The power-on reset circuit resets the I²C bus logic with V_{CC} < V_{POR}. V_{CC} must be lowered to 0.2 V to reset the device.
 (3) C_{io(ON)} depends on the device capacitance and load that is downstream from the device.

PCA9545A 4-CHANNEL I2C AND SMBus SWITCH WITH INTERRUPT LOGIC AND RESET FUNCTIONS

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I²C Interface Timing Requirements

over recommended operating free-air temperature range (unless otherwise noted) (see Figure 10)

			STANDARD I ² C BU		FAST MODE I ² C BUS		UNIT
			MIN	MAX	MIN	MAX	
f _{scl}	I ² C clock frequency		0	100	0	400	kHz
t _{sch}	I ² C clock high time		4		0.6		μs
t _{scl}	I ² C clock low time		4.7		1.3		μs
t _{sp}	I ² C spike time			50		50	ns
t _{sds}	I ² C serial-data setup time		250		100		ns
t _{sdh}	I ² C serial-data hold time		0(1)		0 ⁽¹⁾		μs
t _{icr}	I ² C input rise time			1000	20 + 0.1C _b ⁽²⁾	300	ns
t _{icf}	I ² C input fall time			300	20 + 0.1C _b ⁽²⁾	300	ns
t _{ocf}	I ² C output fall time	10-pF to 400-pF bus		300	$20 + 0.1C_b^{(2)}$	300	ns
t _{buf}	I ² C bus free time between stop an	d start	4.7		1.3		μs
t _{sts}	I ² C start or repeated start conditio	n setup	4.7		0.6		μs
t _{sth}	I ² C start or repeated start conditio	n hold	4		0.6		μs
t _{sps}	I ² C stop condition setup		4		0.6		μs
t _{vdL(Data)}	Valid-data time (high to low) ⁽³⁾	SCL low to SDA output low valid		1		1	μs
t _{vdH(Data)}	Valid-data time (low to high) ⁽³⁾	SCL low to SDA output high valid		0.6		0.6	μs
t _{vd(ack)}	Valid-data time of ACK condition	ACK signal from SCL low to SDA output low		1		1	μs
C _b	I ² C bus capacitive load			400		400	pF

⁽¹⁾ A device internally must provide a hold time of at least 300 ns for the SDA signal (referred to as the V_{IH} min of the SCL signal), in order to bridge the undefined region of the falling edge of SCL. $C_b = total$ bus capacitance of one bus line in pF

Switching Characteristics

over recommended operating free-air temperature range, $C_L \le 100 \text{ pF}$ (unless otherwise noted) (see Figure 12)

	PARAMET	FROM (INPUT)	TO (OUTPUT)	MIN MAX	UNIT	
t _{pd} ⁽¹⁾	Propagation delay time	R_{ON} = 20 Ω , C_L = 15 pF	SDA or SCL	SDn or SCn	0.3	nc
'pd`'	Fropagation delay time	R_{ON} = 20 Ω , C_L = 50 pF	SDA 01 SCL	3011 01 3011	1	ns
t_{iv}	Interrupt valid time (2)		<u>INTn</u>	ĪNT	4	μs
t _{ir}	Interrupt reset delay time(2)		<u>INTn</u>	ĪNT	2	μs

The propagation delay is the calculated RC time constant of the typical ON-state resistance of the switch and the specified load capacitance, when driven by an ideal voltage source (zero output impedance).

⁽³⁾ Data taken using a 1-kΩ pullup resistor and 50-pF load (see Figure 10)

Data taken using a 4.7-kΩ pullup resistor and 100-pF load (see Figure 12)



PCA9545A 4-CHANNEL I²C AND SMBus SWITCH WITH INTERRUPT LOGIC AND RESET FUNCTIONS

SCPS147C-OCTOBER 2005-REVISED OCTOBER 2006

Interrupt and Reset Timing Requirements

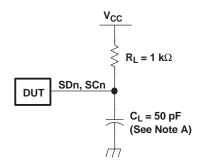
over recommended operating free-air temperature range (unless otherwise noted) (see Figure 12)

	PARAMETER	MIN	MAX	UNIT
t _{PWRL}	Low-level pulse duration rejection of INTn inputs	1		μs
t _{PWRH}	High-level pulse duration rejection of INTn inputs	0.5		μs
t _{WL}	Pulse duration, RESET low	6		ns
t _{rst} ⁽¹⁾	RESET time (SDA clear)		500	ns
t _{REC(STA)}	Recovery time from RESET to start	0		ns

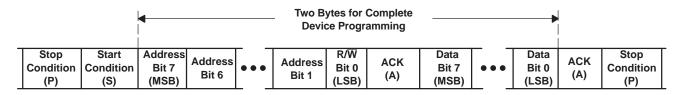
⁽¹⁾ t_{rst} is the propagation delay measured from the time the \overline{RESET} pin is first asserted low to the time the SDA pin is asserted high, signaling a stop condition. It must be a minimum of t_{WL} .



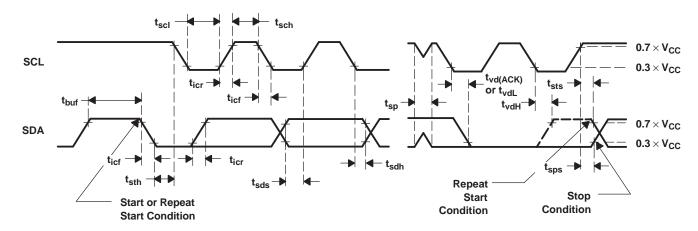
PARAMETER MEASUREMENT INFORMATION



I²C PORT LOAD CONFIGURATION



BYTE	DESCRIPTION
1	I ² C address + R/W
2	Control register data



VOLTAGE WAVEFORMS

- A. C_L includes probe and jig capacitance.
- B. All input pulses are supplied by generators having the following characteristics: PRR \leq 10 MHz, $Z_O = 50 \Omega$, $t_r/t_f = 30 \text{ ns}$.
- C. The outputs are measured one at a time, with one transition per measurement.

Figure 10. I²C Interface Load Circuit, Byte Descriptions, and Voltage Waveforms



PARAMETER MEASUREMENT INFORMATION (continued)

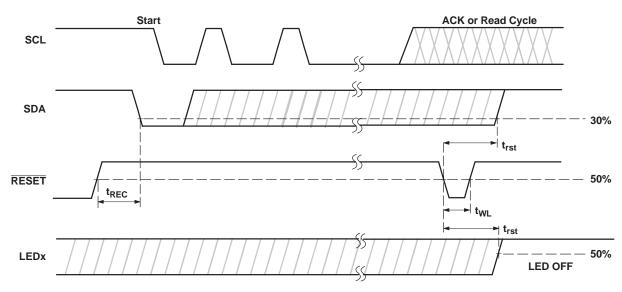
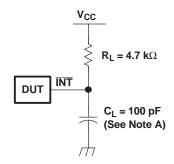
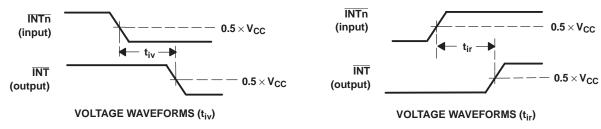


Figure 11. Reset Timing



INTERRUPT LOAD CONFIGURATION



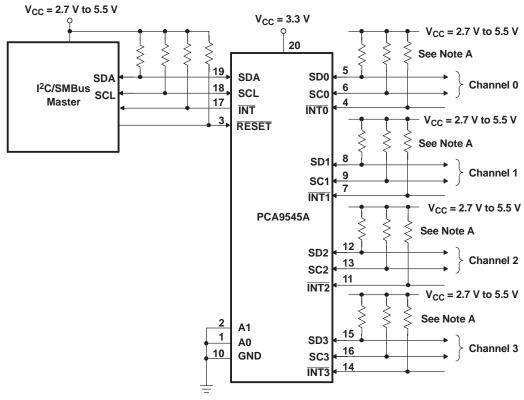
- A. C_L includes probe and jig capacitance.
- B. All input pulses are supplied by generators having the following characteristics: PRR \leq 10 MHz, $Z_O = 50 \Omega$, $t_r/t_f = 30 \text{ ns}$.

Figure 12. Interrupt Load Circuit and Voltage Waveforms



APPLICATION INFORMATION

Figure 13 shows an application in which the PCA9545A can be used.



- A. If the device generating the interrupt has an open-drain output structure or can be 3-stated, a pullup resistor is required. If the device generating the interrupt has a totem-pole output structure and cannot be 3-stated, a pullup resistor is not required. The interrupt inputs should not be left floating.
- B. Pin numbers shown are for DGV, DW, PW, and RGY packages.

Figure 13. Typical Application

PACKAGE OPTION ADDENDUM

21-Dec-2009 www.ti.com

PACKAGING INFORMATION

Orderable Device	Status ⁽¹⁾	Package Type	Package Drawing	Pins	Package Qty	e Eco Plan ⁽²⁾	Lead/Ball Finish	MSL Peak Temp (3)
PCA9545ADGVR	ACTIVE	TVSOP	DGV	20	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9545ADGVRG4	ACTIVE	TVSOP	DGV	20	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9545ADW	ACTIVE	SOIC	DW	20	25	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9545ADWG4	ACTIVE	SOIC	DW	20	25	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9545ADWR	ACTIVE	SOIC	DW	20	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9545ADWRG4	ACTIVE	SOIC	DW	20	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9545AGQNR	NRND	BGA MI CROSTA R JUNI OR	GQN	20	1000	TBD	SNPB	Level-1-240C-UNLIM
PCA9545APW	ACTIVE	TSSOP	PW	20	70	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9545APWE4	ACTIVE	TSSOP	PW	20	70	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9545APWG4	ACTIVE	TSSOP	PW	20	70	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9545APWR	ACTIVE	TSSOP	PW	20	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9545APWRE4	ACTIVE	TSSOP	PW	20	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9545APWRG4	ACTIVE	TSSOP	PW	20	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9545APWT	ACTIVE	TSSOP	PW	20	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9545APWTE4	ACTIVE	TSSOP	PW	20	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9545APWTG4	ACTIVE	TSSOP	PW	20	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9545ARGYR	ACTIVE	VQFN	RGY	20	3000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
PCA9545ARGYRG4	ACTIVE	VQFN	RGY	20	3000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
PCA9545AZQNR	ACTIVE	BGA MI CROSTA R JUNI OR	ZQN	20	1000	Green (RoHS & no Sb/Br)	SNAGCU	Level-1-260C-UNLIM

(1) The marketing status values are defined as follows: **ACTIVE:** Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check



PACKAGE OPTION ADDENDUM

www.ti.com 21-Dec-2009

http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

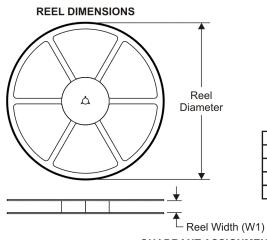
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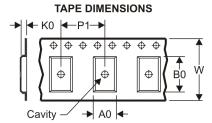
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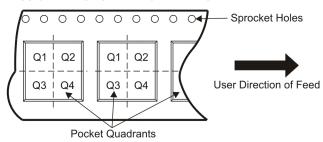
TAPE AND REEL INFORMATION





A0	Dimension designed to accommodate the component width
	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

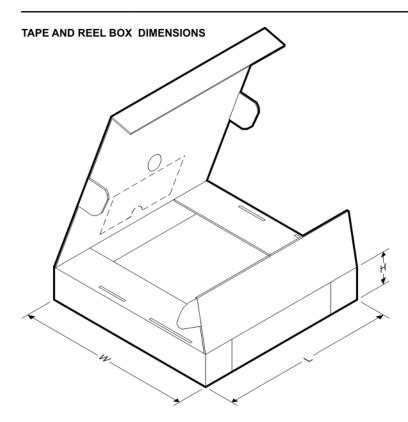


*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
PCA9545ADGVR	TVSOP	DGV	20	2000	330.0	12.4	7.0	5.6	1.6	8.0	12.0	Q1
PCA9545ADWR	SOIC	DW	20	2000	330.0	24.4	10.8	13.0	2.7	12.0	24.0	Q1
PCA9545AGQNR	BGA MI CROSTA R JUNI OR	GQN	20	1000	330.0	12.4	3.3	4.3	1.6	8.0	12.0	Q1
PCA9545APWR	TSSOP	PW	20	2000	330.0	16.4	6.95	7.1	1.6	8.0	16.0	Q1
PCA9545ARGYR	VQFN	RGY	20	3000	180.0	12.4	3.8	4.8	1.6	8.0	12.0	Q1
PCA9545AZQNR	BGA MI CROSTA R JUNI OR	ZQN	20	1000	330.0	12.4	3.3	4.3	1.6	8.0	12.0	Q1

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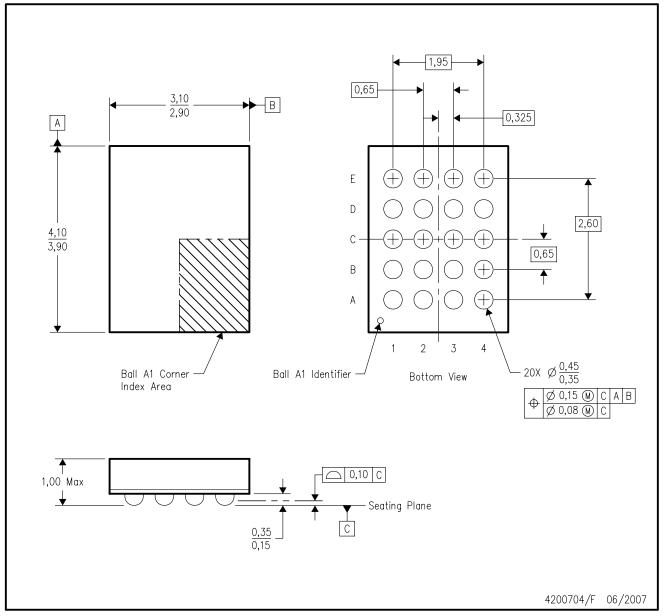


*All dimensions are nomina

All diffiensions are nominal							
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
PCA9545ADGVR	TVSOP	DGV	20	2000	346.0	346.0	29.0
PCA9545ADWR	SOIC	DW	20	2000	346.0	346.0	41.0
PCA9545AGQNR	BGA MICROSTAR JUNIOR	GQN	20	1000	340.5	338.1	20.6
PCA9545APWR	TSSOP	PW	20	2000	346.0	346.0	33.0
PCA9545ARGYR	VQFN	RGY	20	3000	190.5	212.7	31.8
PCA9545AZQNR	BGA MICROSTAR JUNIOR	ZQN	20	1000	340.5	338.1	20.6

GQN (R-PBGA-N20)

PLASTIC BALL GRID ARRAY



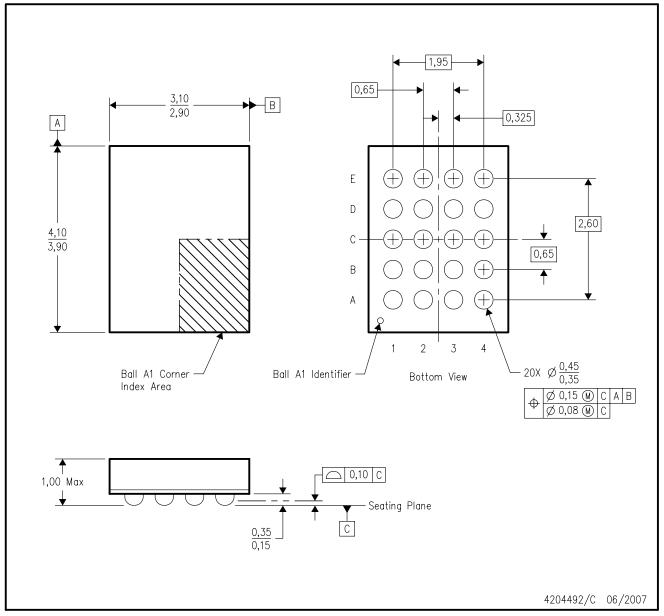
NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

- B. This drawing is subject to change without notice.
- C. Falls within JEDEC MO-285 variation BC-2.
- D. This package is tin-lead (SnPb). Refer to the 20 ZQN package (drawing 4204492) for lead-free.



ZQN (R-PBGA-N20)

PLASTIC BALL GRID ARRAY



NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

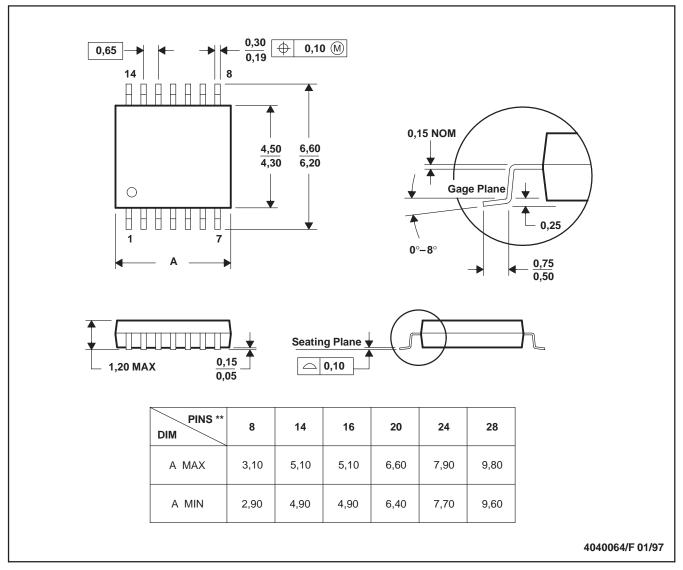
- B. This drawing is subject to change without notice.
- C. Falls within JEDEC MO-285 variation BC-2.
- D. This package is lead-free. Refer to the 20 GQN package (drawing 4200704) for tin-lead (SnPb).



PW (R-PDSO-G**)

14 PINS SHOWN

PLASTIC SMALL-OUTLINE PACKAGE

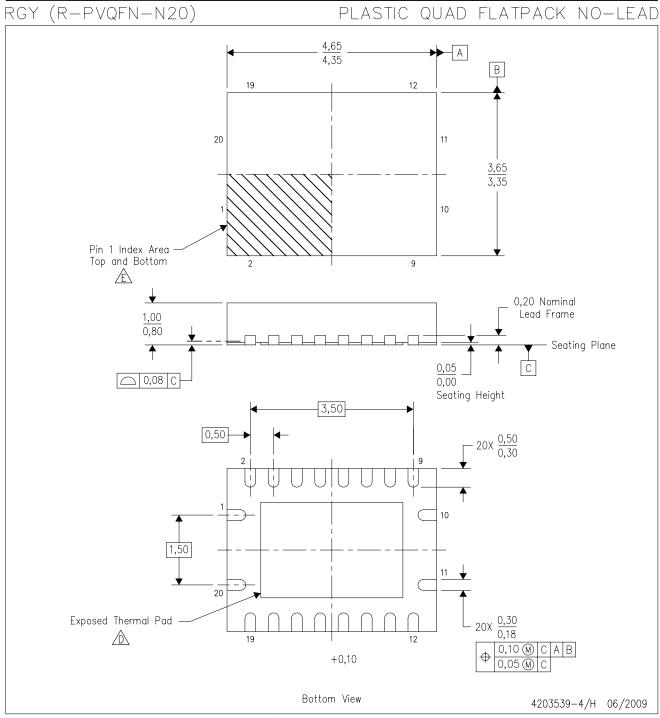


NOTES: A. All linear dimensions are in millimeters.

B. This drawing is subject to change without notice.

C. Body dimensions do not include mold flash or protrusion not to exceed 0,15.

D. Falls within JEDEC MO-153



NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

- B. This drawing is subject to change without notice.
- C. QFN (Quad Flatpack No-Lead) package configuration.
- The package thermal pad must be soldered to the board for thermal and mechanical performance.

 See the Product Data Sheet for details regarding the exposed thermal pad dimensions.
- Pin 1 identifiers are located on both top and bottom of the package and within the zone indicated. The Pin 1 identifiers are either a molded, marked, or metal feature.
- F. Package complies to JEDEC MO-241 variation BC.



THERMAL PAD MECHANICAL DATA



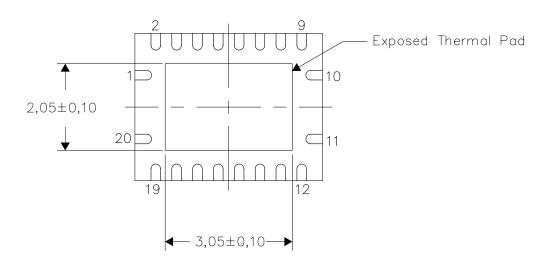
RGY (R-PVQFN-N20)

THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No—Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.

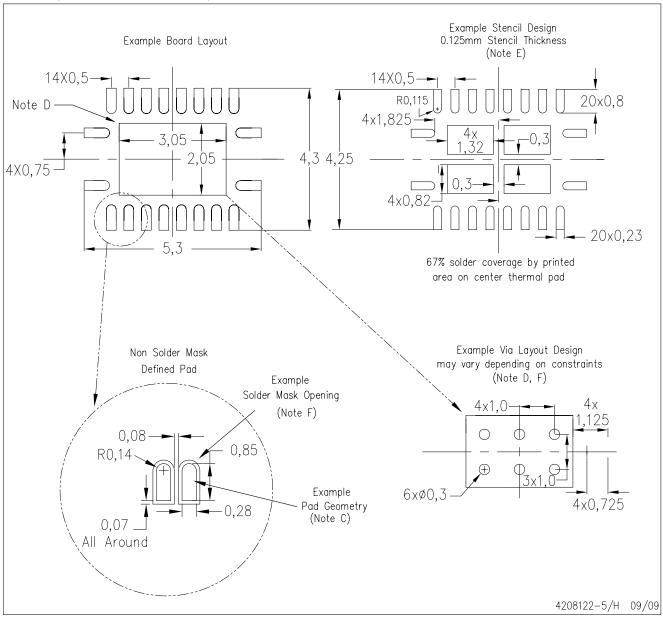


Bottom View

NOTE: All linear dimensions are in millimeters

Exposed Thermal Pad Dimensions

RGY (R-PVQFN-N20)



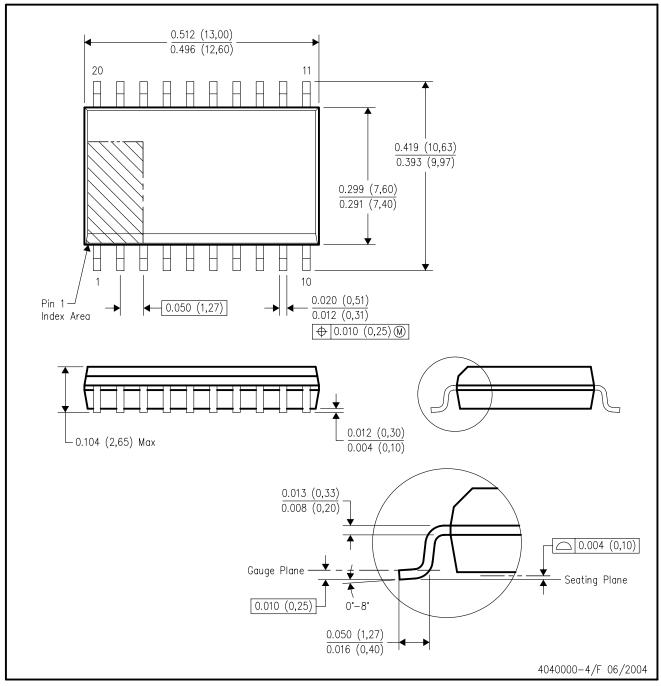
NOTES:

- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, Quad Flat—Pack QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com http://www.ti.com.
- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
- F. Customers should contact their board fabrication site for minimum solder mask web tolerances between signal pads.



DW (R-PDSO-G20)

PLASTIC SMALL-OUTLINE PACKAGE



NOTES:

- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).
- D. Falls within JEDEC MS-013 variation AC.



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