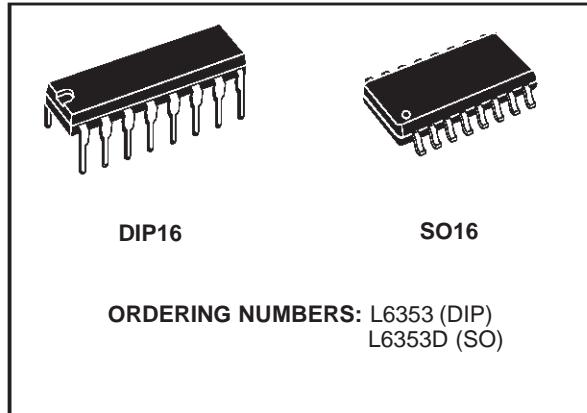


SMART DRIVER FOR POWER MOS & IGBT

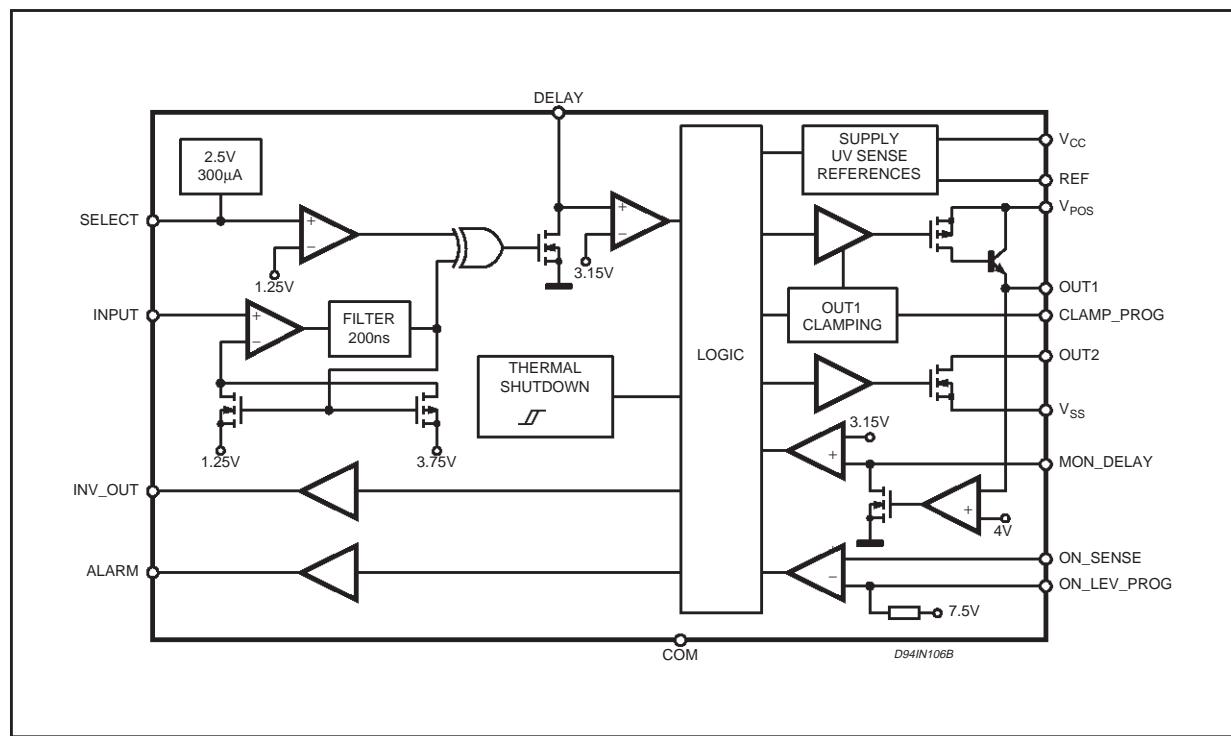
- PEAK HIGH OUTPUT CURRENT CAPABILITY ($\pm 8A$)
- WIDE SUPPLY VOLTAGE RANGE (12.5 TO 18V)
- 0 TO -7.5V NEGATIVE BIAS VOLTAGE SUPPLY RANGE
- OVER CURRENT AND DESATURATION PROTECTION OF THE EXTERNAL POWER DEVICE (EXTERNALLY PROGRAMMABLE)
- LATCH-UP PROTECTION (FOR IGBT)
- TWO STEPS TURN-ON (PROGRAMMABLE)
- PROTECTION AGAINST POSITIVE SUPPLY UNDER-VOLTAGE
- INPUT COMPATIBLE WITH OPTOCOUPLER OR PULSE TRANSFORMER
- PROGRAMMABLE TURN-ON DELAY
- THERMAL PROTECTION WITH ON-CHIP OVER-TEMPERATURE ALARM AND TURN-OFF PROCEDURE
- OPERATING FREQUENCY UP TO 100kHz



DESCRIPTION

The L6353 device is a smart driver, with all the drive and protection know-how "on board". Available in both DIP and SO package, it can be triggered with a logic level or with the signal from an optocoupler or a pulse transformer. It filters parasitic input signals and drives any MOS or IGBT.

BLOCK DIAGRAM



DESCRIPTION (continued)

It monitors the on-state voltage drop of the driven power device and protects it against overload and short circuit.

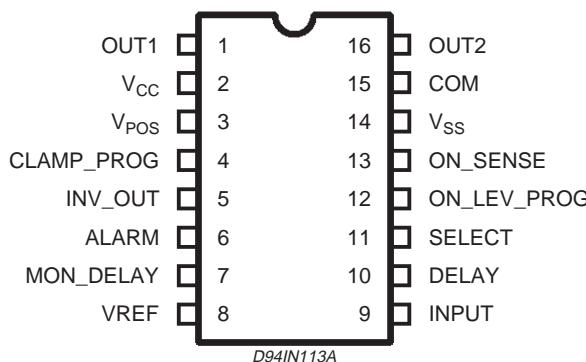
The on-state voltage drop level is externally programmable from 5 to 15V. This function is inhibited during the turn-on of the external power device for an externally programmable period.

An internal inhibition time of 200ns avoids false triggering.

Overload or overheating are signalled on an alarm output. If temperature continues to increase the power output is switched off and maintained in the off-state until the temperature decreases below the low threshold. A programmable turn-on delay avoids cross conduction in bridge configurations.

To preserve the external power device (especially IGBT) from the risk of latch-up, the gate voltage can be risen in two different steps (of which the first is externally programmable from 7 to 11V).

PIN CONNECTION (top view)



ABSOLUTE MAXIMUM RATINGS

| Symbol | Parameter | Value | Unit |
|---------------------------------------|---|----------------------------|------|
| V _{CC} | Supply Voltage referred to COM pin | 20 | V |
| V _{SS} | Negative Supply Voltage referred to COM pin | -8 to 0 | V |
| V _{PPOS} - V _{OUT1} | Collector-Emitter Voltage of High Side NPN | 25 | V |
| V _{OUT2} - V _{SS} | Drain-Source Voltage of Low Side DMOS | 25 | V |
| V _{EXT1} | Externally Forced Voltage (pin 9) | -0.3 to V _{CC} | V |
| V _{EXT2} | Externally Forced Voltage (pins 4,7,10, 11, 12) | -0.3 to 7 | V |
| I _{DELAY} | Sink Current pin Delay | 3 | mA |
| I _{MON_DELAY} | Sink Current Pin Mon_Delay | 3 | mA |
| V _{ON_SENSE} | Voltage on ON_SENSE Pin | VSS-0.3 to V _{CC} | V |
| I _{OUT1} | Positive Output Current (tp ≤1ms) (peak) | 8 | A |
| I _{OUT2} | Negative Output Current (tp ≤1ms) (peak) | 8 | A |
| I _{INV_OUT} | Output Current in INV_OUT Pin | ±20 | mA |
| I _{ALARM} | Output Current in ALARM Pin | ±20 | mA |
| P _{tot} | Total Power Dissipation | internally limited | |
| T _{amb} | Operating Temperature Range | -25 to +85 | °C |
| T _{stg} | Storage Temperature | -50 to +150 | °C |

THERMAL DATA

| Symbol | Parameter | DIP16 | SO16 | Unit |
|--------------------------|-------------------------------------|-------|------|------|
| R _{thj-ambient} | Thermal Resistance Junction-ambient | Max | 80 | °C/W |

PIN FUNCTIONS

| N. | Name | Function |
|----|------------------|---|
| 1 | OUT1 | Output of high side driver (emitter of power NPN transistor). |
| 2 | V _{CC} | Positive Supply Voltage (referred to COM). See under voltage lockout functioning |
| 3 | V _{POS} | Positive Bias Voltage (collector of the NPN power transistor). |
| 4 | CLAMP_PROG | First Step of the Gate Voltage Programming. The programming is achieved setting an appropriate voltage on this pin (i.e. using a resistance voltage divider). |
| 5 | INV-OUT | Inverted Output Driver Status. The buffer output is able to drive some auxiliary circuit (i.e. a LED). |
| 6 | ALARM | Diagnostic Output Signal. A fault condition is signalled by this output buffer. |
| 7 | MON_DELAY | V _{ON} Monitor Delay. An R-C network connected between this, the COM and the V _{REF} pins, define t _{MON_DELAY} time interval (see fig 4) |
| 8 | V _{REF} | Output of the 5V/10mA internal voltage reference. |
| 9 | INPUT | Input signal. The driving signal can be a logic level either active LOW (inverted mode) or HIGH (direct mode) in the Logic Level or a pulse in the Pulse Transformer Mode (see Figure 2) |
| 10 | DELAY | On Triggering Delay. An R-C network connected between this, the COM and the V _{REF} pins, definethe t _{DELAY} time interval (see fig 4) |
| 11 | SELECT | Select the direct/inverted mode in the Logic Level Mode. It's also the reference pin in Pulse transformer mode. |
| 12 | ONLEV_PROG | V _{ON} level programming. This pin is used to set the V _{ON} monitor level. The programming is achieved setting an appropriate voltage on this pin (i.e. using a resistive divider). |
| 13 | ON_SENSE | On State Monitor. This pin is used to monitor the turning on of the external power device. |
| 14 | V _{SS} | Negative supply voltage (referred to the COM). This pin is the source of the low side driver DMOS. |
| 15 | COM | Ground |
| 16 | OUT2 | Output of the low side driver (drain of the DMOS). |

DC ELECTRICAL CHARACTERISTICS ($V_{POS} = V_{CC} = 15V$; $V_{SS} = -5$ to $0V$; $T_j = -25$ to $+125^\circ C$; unless otherwise specified)

| Symbol | Pin | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|-----------------|----------|--------------------------------------|---|------|------|--------------|-----------|
| V_{drop} | 1 | $V_{POS} - V_{OUT1}$ | $I_{OUT1} = 2A$ | | 2.5 | | V |
| V_{CC} | 2 | Operating Supply Voltage | (referred to COM pin) | 12.5 | | 18 | V |
| V_{CCth1} | | Under Voltage Upper Threshold | | 10.5 | 11.5 | 12.5 | V |
| V_{CCth2} | | Under Voltage Lower Threshold | | 10 | 11 | 12 | V |
| V_{CChys} | | Under Voltage Hysteresis | | 0.3 | 0.5 | 0.7 | V |
| I_{CCq} | | Quiescent Supply Current | | | 5 | | mA |
| V_d | 4, 12 | Output Voltage | pin floating | | 1.26 | | V |
| I_{SO} | | Sourced Current | pin grounding | | 20 | | μA |
| I_{SI} | | Sinked Current | pin at $+5V$ | | -20 | | μA |
| V_{drop_sig} | 5, 6 | High State Output Voltage Drop | $I_{out} = 20mA$ | | | $V_{CC} - 3$ | V |
| | | Low State Output Voltage Drop | | | | 3 | V |
| V_{ref} | 8 | Output of Internal Voltage Reference | $I_{ref} = 0A; T_j = 25^\circ C$ | 4.9 | 5 | 5.1 | V |
| | | | $I_{ref} \leq 10mA; T_j = 25^\circ C$ | 4.8 | | 5.2 | mA |
| R_{in} | 7, 10 | Comparator Input Resistance | | | | 100 | Ω |
| V_{dth} | | Comparator Threshold | | | | 3.15 | V |
| R_{ins} | 13 | Input Resistance | | | 75 | | $K\Omega$ |
| I_{outs} | | Output Current | pin grounded | | 200 | | μA |
| V_{SS} | 14 | Operating Negative Bias Voltage | (referred to COM) | -7 | | 0 | V |
| R_{ON} | 16 | On Resistance | $OUT2$ to V_{SS} ; $I_{OUT2} = 2A$ | | 0.5 | | Ω |
| V_{il} | 9 | Low Level Voltage | (Logic Level Mode) | 0 | | 1 | V |
| | | High Level Voltage | (Logic Level Mode) | 4 | | V_{CC} | V |
| | I_{in} | Input Current | $0 < V_{in} < V_{CC}$ (Logic Level Mode) | -10 | | 10 | μA |
| | | Inhibited Parasitic Pulse Duration | (Logic Level Mode) | | 200 | 300 | ns |
| V_{ton} | | Turn-on Threshold Voltage | Referred to V_{sel} (Pulse Transformer Mode) | | | 1.5 | V |
| V_{toff} | | Turn-off Threshold Voltage | Referred to V_{sel} (Pulse Transformer Mode) | -1.5 | | | V |
| V_{sl} | 11 | Low Level Voltage | (Logic Level Mode) | 0 | | 1 | V |
| | | High Level Voltage | (Logic Level Mode) | 2 | | V_{REF} | V |
| | I_{sl} | Current Output of SELECT Pin | $V_{sl} = 0V$ (Logic Level Mode) | | 300 | | μA |
| | | Output Voltage of SELECT Pin | (Pulse Transformer Mode) | 2.25 | 2.5 | 2.75 | V |

AC ELECTRICAL CHARACTERISTICS

| Symbol | Pin | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|-------------|---------|---------------------------------|----------------|------|------|------|------|
| t_{on} | 9 vs 1 | Turn on Propagation Delay Time | | | 400 | | ns |
| t_{off} | 9 vs 16 | Turn off propagation delay time | | | 400 | | ns |
| t_r | 1,16 | Rise Time | | | 50 | | ns |
| | | Fall Time | | | 50 | | ns |
| t_{fault} | | Delay Time for Fault Detection | | | | 400 | ns |

THERMAL PROTECTION

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|------------|---------------------------------------|---------------------|------|------|------|------|
| T_{th1} | Over Temperature Threshold | (Thermal Procedure) | | 130 | | °C |
| T_{hys1} | Over Temperature Threshold Hysteresis | | | 20 | | °C |
| T_{th2} | Over Temperature Shutdown | | | 160 | | °C |
| T_{hys2} | Over Temperature Shutdown Hysteresis | | | 20 | | °C |

Figure 1: Switching waveforms and test circuit

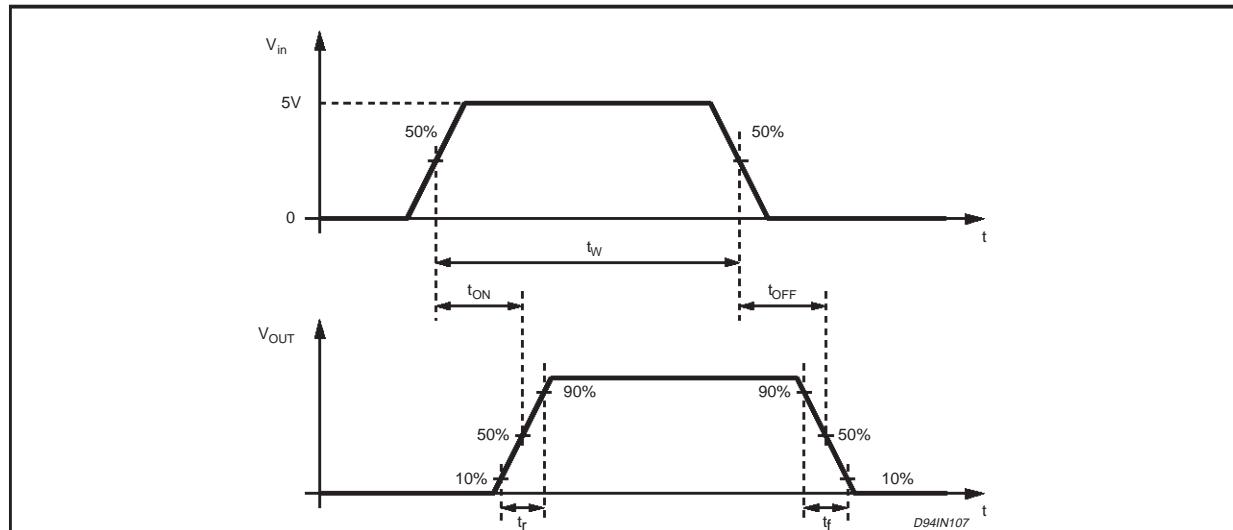


Figure 1a : Switching waveforms and test circuit

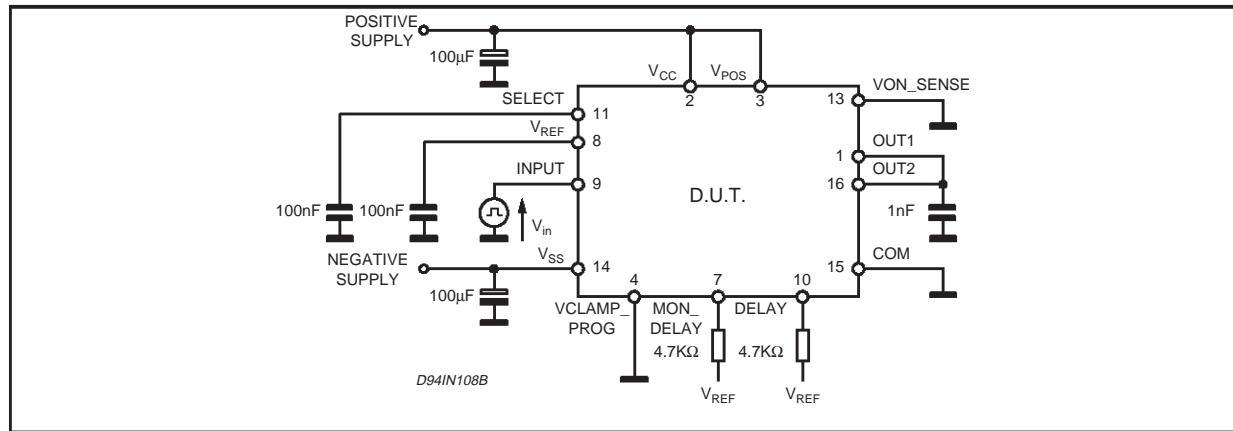


Figure 2. Pulse Transformer mode operation.

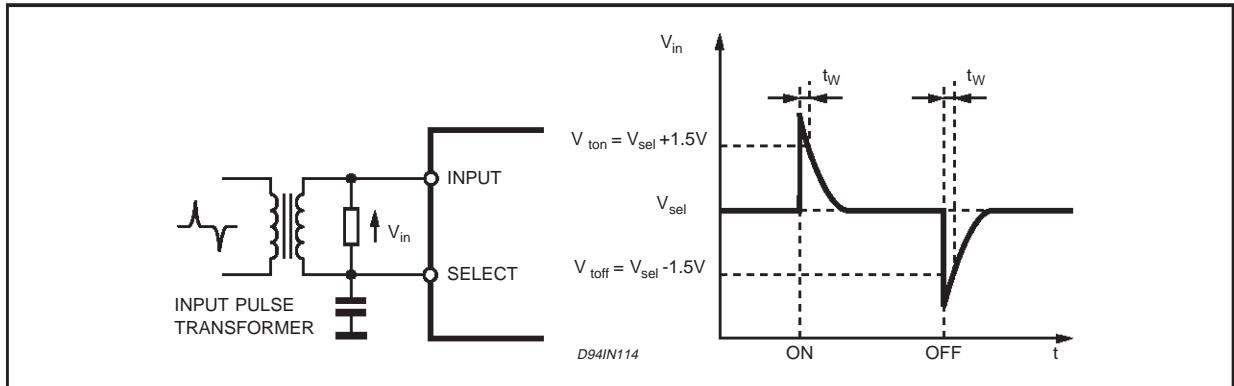


Figure 3. Gate driving voltage waveforms.

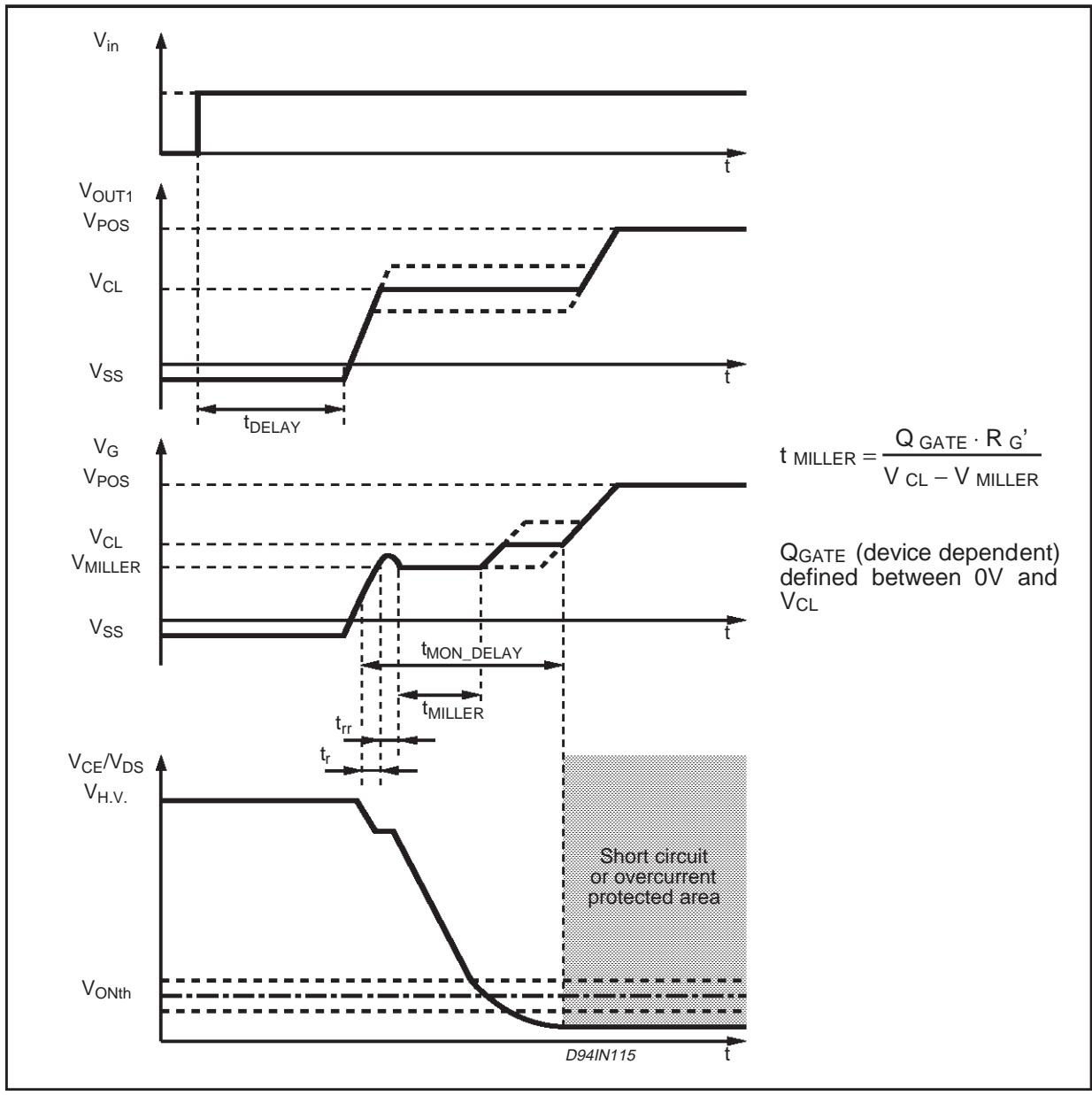
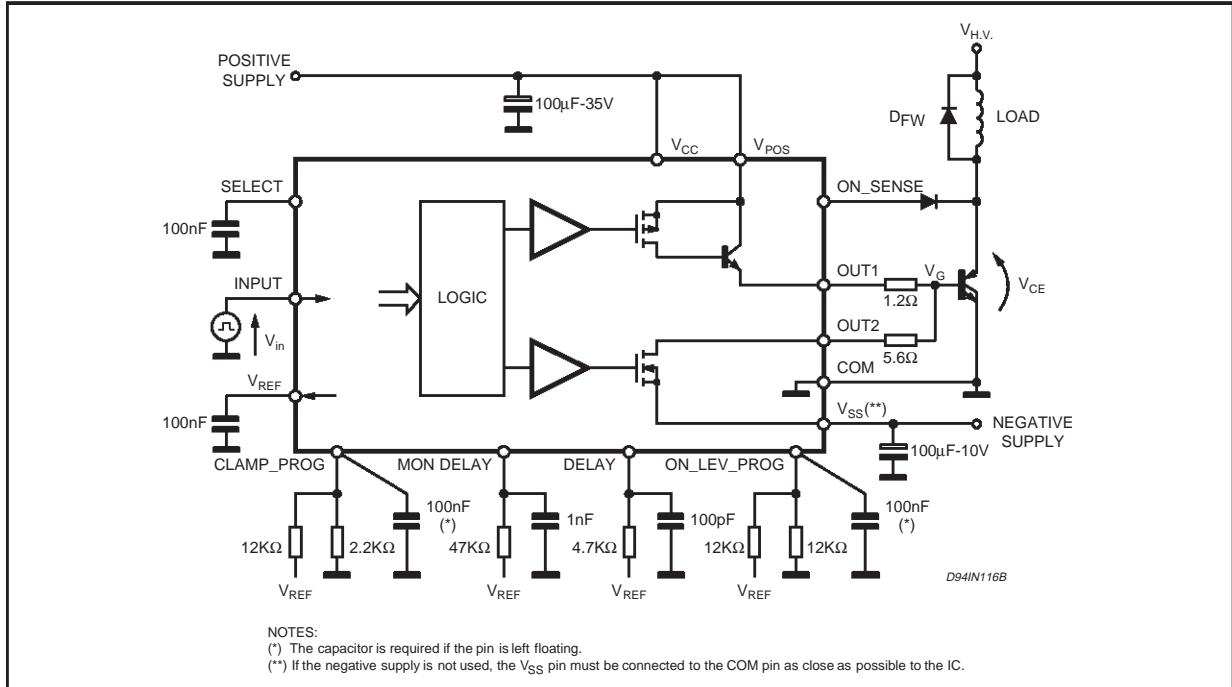


Figure 4. Gate driving waveforms test circuit.

INPUT INTERFACE

To drive the external power device three different possibilities are allowed:

The Logic Level Mode, either direct or inverted, and the Pulse Transformer Mode

Using the Logic Level Mode (direct) an high level (referred to COM), at the INPUT pin will start the Turn on Procedure (i.e. firing an N channel external device). A low level (referred to COM) will instead close the OUT2 pin to V_{ss}.

The functioning is reversed in the inverted mode. To select the direct mode the SELECT pin must be connected via a capacitor to COM. The inverted mode is chosen by connecting the SELECT pin to COM.

In logic Level Mode pulses lasting less than t_{inh} (200ns typ.) are filtered out.

In the Pulse Transformer Mode the SELECT pin will be the reference pin for the signal applied to the INPUTpin. The positive pulse will start the TURN ON PROCEDURE, while the negative pulse will close OUT2 to V_{ss}. The duration of this pulses (t_w, see fig.2) must be again t_w > t_{inh}.

TURN-ON PROCEDURE

The firing of the external power device is performed in three steps in order to avoid the most common problems that can arise.

In each of these steps there are a number of parameters that can be easily externally presetted to

the requested values.

First Step

Parameter: t_{DELAY}

In order to avoid cross-conduction between the external power device in half bridge arrangement the driver output is activated after an externally programmable delay time (t_{DELAY}, see fig. 3) after the input signal. To set the t_{DELAY} interval an R-C network has to be connected between the DELAY, V_{REF} and COM pins (see fig.4) giving:

$$t_{DELAY} (\mu\text{sec}) = R_{EXT} (\text{K}\Omega) \cdot C_{EXT} (\text{nF}) + t_{on}$$

To minimize this interval only a resistor has to be connected between the DELAY and the V_{REF} limiting thus the duration to the internal propagation delay t_{on}.

Second step

Parameters: t_{MON_DELAY}, V_{CL}

To protect the driven device from latch-up at turn-on (IGBT) after the t_{DELAY} time interval a second externally programmable time interval t_{MON_DELAY} (presettable using the same technique used to set the t_{DELAY} interval, see fig.4)

$$t_{MON-DELAY} (\mu\text{sec}) = R_{EXT} (\text{K}\Omega) \cdot C_{EXT} (\text{nF})$$

during the t_{MON_DELAY} the voltage on the V_{OUT1} is limited to the V_{CL} level. To program this value an appropriate voltage drop has to be imposed, by mean of a resistive voltage divider, at the CLAMP_PROG pin according to the following formula:

$$V_{CLAMP_PROG} = \frac{V_{CL}}{6}$$

with

$$7V \leq V_{CL} \leq 11V$$

Leaving the CLAMP_PROG pin floating the V_{CL} level is set to 9V. If the pin is grounded the function is inhibited (i.e. no intermediate step during the firing).

Third step

Parameter: V_{ONth}

At the end of the t_{MON_DELAY} the gate of the driven device is pulled toward the V_{POS} level in order to ensure an appropriate drive to minimize the power losses. The external power device is considered in overload whenever the voltage on its output, sensed via the V_{ON_SENSE} pin, is above V_{ONth} . The comparison value is programmable setting at a certain level, by means of a resistive divider, the ONLEV_PROG pin according to the following formula:

$$V_{ON_LEV_PROG} = V_{ONth} \cdot 0.17$$

with

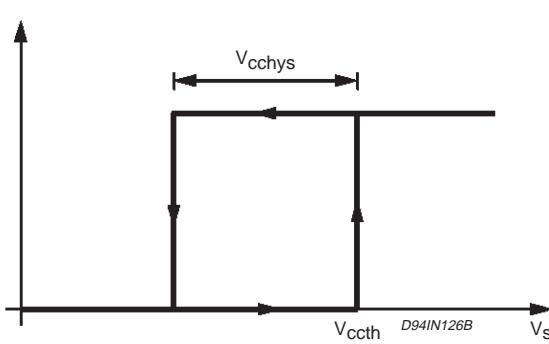
$$5V \leq V_{ONth} \leq 15V$$

and

$$V_{ONth} < V_{CC} - 1V.$$

If the ONLEV_PROG pin is left floating the V_{ONth} .

Undervoltage Comparator Hysteresis



level is set to 7.5V.

The overload status is signalled via the ALARM pin, active LOW. To inhibit the V_{ON} Monitor function, the V_{SENSE} pins must be grounded.

THERMAL PROCEDURE

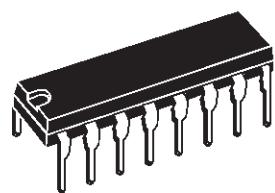
As the junction temperature raises, two different events will take place. When the Over Temperature Threshold (T_{th1}), set at 130°C is reached, the ALARM output is activated (low level). If the temperature keeps on raising, up to the Over Temperature Shutdown ($T_{th2} = 160^{\circ}\text{C}$ Typ) the output power device is turned off until the temperature decrease. To prevent an oscillating behaviour both the thresholds have a built-in hysteresis of 20°C .

UNDERVOLTAGE LOCK OUT

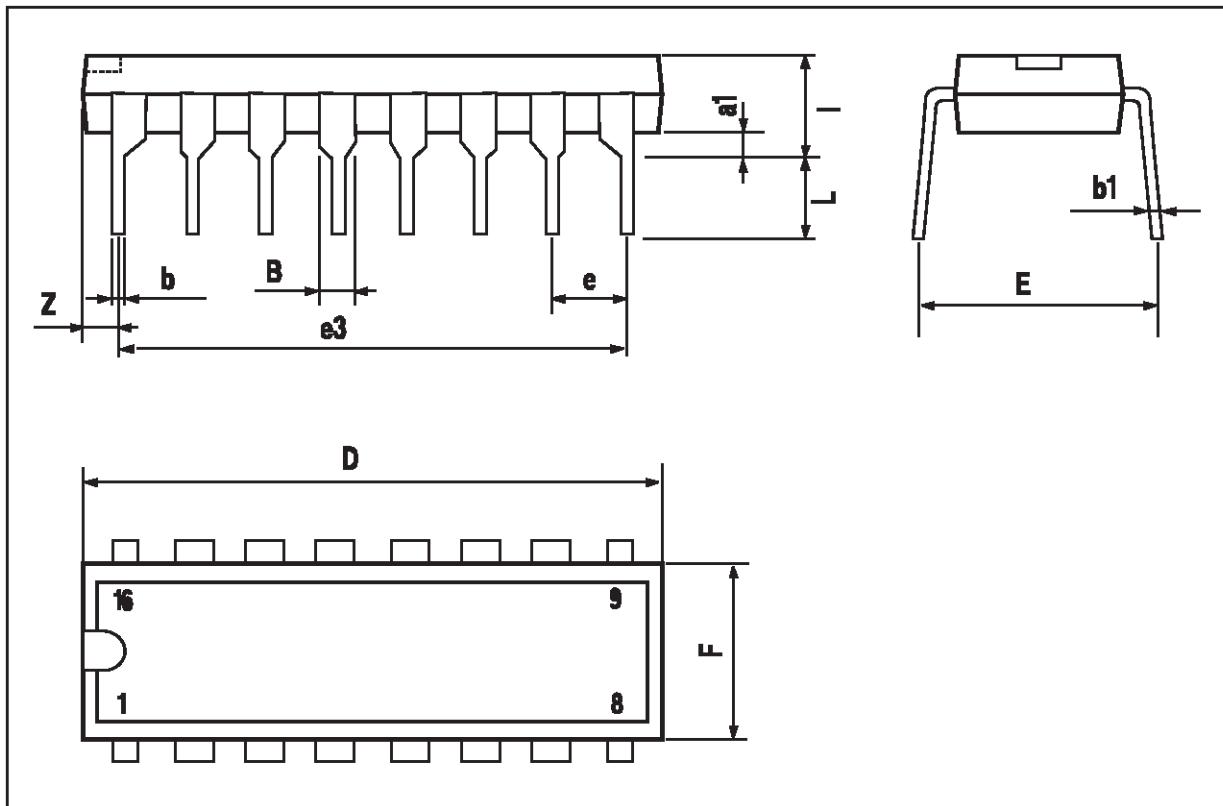
To avoid operation with non optimal drive of the external power device, an Undervoltage Lockout function is implemented. The OUT1 pin is forced close to V_{SS} until the V_{CC} supply voltage has reached the Undervoltage Upper Threshold (V_{CCth2}) value. If the supply voltage falls below the lower hysteresis value (i.e. $V_{CCth1} - V_{CCchys}$) the OUT1 will be again forced close to V_{SS} . The built-in hysteresis will thus avoid intermittent functioning of the device at low supply voltage that may have a superimposed ripple.

| DIM. | mm | | | inch | | |
|------|------|-------|------|-------|-------|-------|
| | MIN. | TYP. | MAX. | MIN. | TYP. | MAX. |
| a1 | 0.51 | | | 0.020 | | |
| B | 0.77 | | 1.65 | 0.030 | | 0.065 |
| b | | 0.5 | | | 0.020 | |
| b1 | | 0.25 | | | 0.010 | |
| D | | | 20 | | | 0.787 |
| E | | 8.5 | | | 0.335 | |
| e | | 2.54 | | | 0.100 | |
| e3 | | 17.78 | | | 0.700 | |
| F | | | 7.1 | | | 0.280 |
| I | | | 5.1 | | | 0.201 |
| L | | 3.3 | | | 0.130 | |
| Z | | | 1.27 | | | 0.050 |

OUTLINE AND MECHANICAL DATA

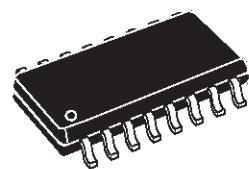


DIP16



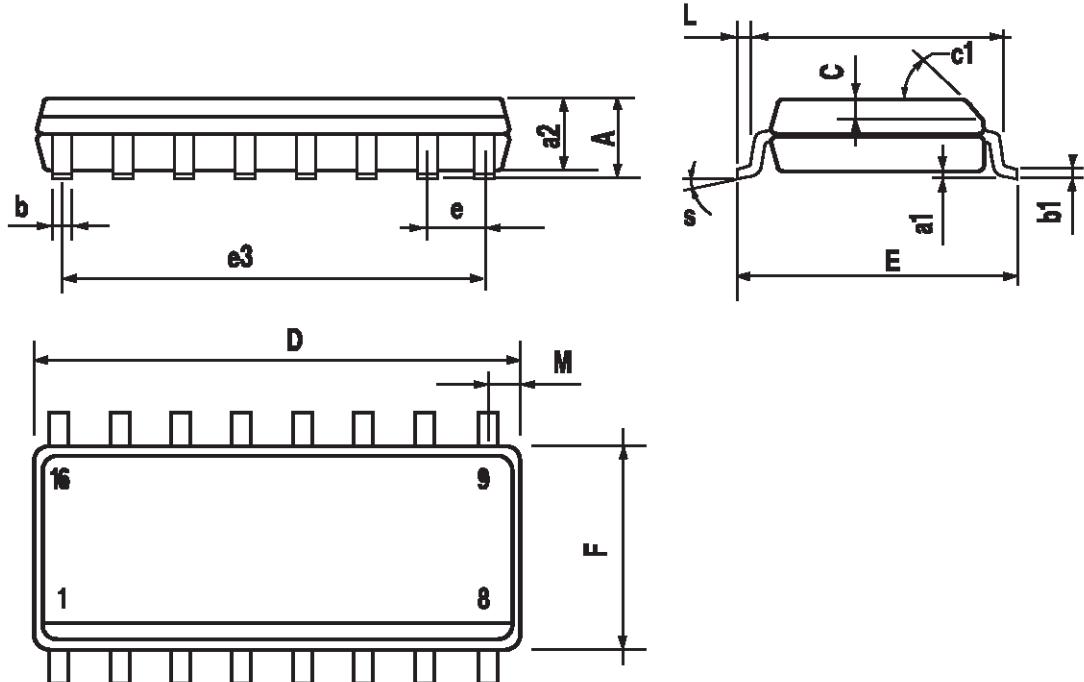
| DIM. | mm | | | inch | | |
|-------|------------|------|------|-------|-------|-------|
| | MIN. | TYP. | MAX. | MIN. | TYP. | MAX. |
| A | | | 1.75 | | | 0.069 |
| a1 | 0.1 | | 0.25 | 0.004 | | 0.009 |
| a2 | | | 1.6 | | | 0.063 |
| b | 0.35 | | 0.46 | 0.014 | | 0.018 |
| b1 | 0.19 | | 0.25 | 0.007 | | 0.010 |
| C | | 0.5 | | | 0.020 | |
| c1 | 45° (typ.) | | | | | |
| D (1) | 9.8 | | 10 | 0.386 | | 0.394 |
| E | 5.8 | | 6.2 | 0.228 | | 0.244 |
| e | | 1.27 | | | 0.050 | |
| e3 | | 8.89 | | | 0.350 | |
| F (1) | 3.8 | | 4 | 0.150 | | 0.157 |
| G | 4.6 | | 5.3 | 0.181 | | 0.209 |
| L | 0.4 | | 1.27 | 0.016 | | 0.050 |
| M | | | 0.62 | | | 0.024 |
| S | 8°(max.) | | | | | |

OUTLINE AND MECHANICAL DATA



SO16 Narrow

(1) D and F do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15mm (.006inch).



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