

LM5574/LM5574-Q1 SIMPLE SWITCHER® 75V, 0.5A Step-Down Switching Regulator

Check for Samples: [LM5574](#), [LM5574-Q1](#)

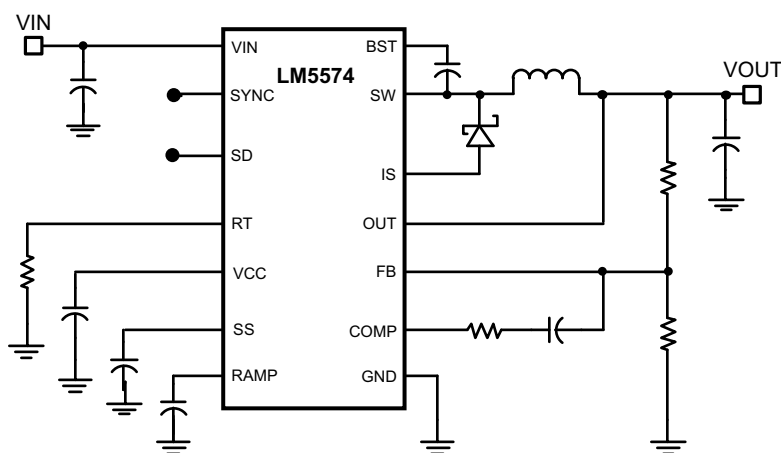
FEATURES

- **LM5574-Q1 is an Automotive Grade Product that is AEC-Q100 Grade 1 Qualified (–40°C to +125°C Operating Junction Temperature)**
- **Integrated 75V, 750mΩ N-channel MOSFET**
- **Ultra-Wide Input Voltage Range from 6V to 75V**
- **Adjustable Output Voltage as Low as 1.225V**
- **1.5% Feedback Reference Accuracy**
- **Operating Frequency Adjustable Between 50kHz and 500kHz with Single Resistor**
- **Master or Slave Frequency Synchronization**
- **Adjustable Soft-Start**
- **Emulated Current Mode Control Architecture**
- **Wide Bandwidth Error Amplifier**
- **Built-in Protection**
- **Automotive Grade Product Datasheet that is AEC-Q100 Grade 0 Qualified is Available Upon Request**
 - (–40°C to +150°C Operating Junction Temperature)

APPLICATIONS

- **Automotive**
- **Industrial**

Simplified Application Schematic



DESCRIPTION

The LM5574 is an easy to use SIMPLE SWITCHER® buck regulator which allows design engineers to design and optimize a robust power supply using a minimum set of components. Operating with an input voltage range of 6 - 75V, the LM5574 delivers 0.5A of continuous output current with an integrated 750mΩ N-Channel MOSFET. The regulator utilizes an Emulated Current Mode architecture which provides inherent line regulation, tight load transient response, and ease of loop compensation without the usual limitation of low-duty cycles associated with current mode regulators. The operating frequency is adjustable from 50kHz to 500kHz to allow optimization of size and efficiency. To reduce EMI, a frequency synchronization pin allows multiple IC's from the LM(2)557x family to self-synchronize or to synchronize to an external clock. The LM5574 ensures robustness with cycle-by-cycle current limit, short-circuit protection, thermal shut-down, and remote shut-down. The device is available in a TSSOP-16 package. The LM5574 is supported by the full suite of WEBENCH® On-Line design tools.

PACKAGE

- **TSSOP-16**

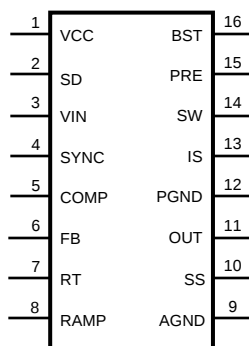


Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

WEBENCH is a registered trademark of Texas Instruments.

All other trademarks are the property of their respective owners.

Connection Diagram



**Figure 1. Top View
16-Lead TSSOP**

PIN DESCRIPTIONS

Pin(s)	Name	Description	Application Information
1	VCC	Output of the bias regulator	Vcc tracks Vin up to 9V. Beyond 9V, Vcc is regulated to 7 Volts. A 0.1uF to 1uF ceramic decoupling capacitor is required. An external voltage (7.5V – 14V) can be applied to this pin to reduce internal power dissipation.
2	SD	Shutdown or UVLO input	If the SD pin voltage is below 0.7V the regulator will be in a low power state. If the SD pin voltage is between 0.7V and 1.225V the regulator will be in standby mode. If the SD pin voltage is above 1.225V the regulator will be operational. An external voltage divider can be used to set a line undervoltage shutdown threshold. If the SD pin is left open circuit, a 5uA pull-up current source configures the regulator fully operational.
3	Vin	Input supply voltage	Nominal operating range: 6V to 75V
4	SYNC	Oscillator synchronization input or output	The internal oscillator can be synchronized to an external clock with an external pull-down device. Multiple LM5574 devices can be synchronized together by connection of their SYNC pins.
5	COMP	Output of the internal error amplifier	The loop compensation network should be connected between this pin and the FB pin.
6	FB	Feedback signal from the regulated output	This pin is connected to the inverting input of the internal error amplifier. The regulation threshold is 1.225V.
7	RT	Internal oscillator frequency set input	The internal oscillator is set with a single resistor, connected between this pin and the AGND pin.
8	RAMP	Ramp control signal	An external capacitor connected between this pin and the AGND pin sets the ramp slope used for current mode control. Recommended capacitor range 50pF to 2000pF.
9	AGND	Analog ground	Internal reference for the regulator control functions
10	SS	Soft-start	An external capacitor and an internal 10uA current source set the time constant for the rise of the error amp reference. The SS pin is held low during standby, Vcc UVLO and thermal shutdown.
11	OUT	Output voltage connection	Connect directly to the regulated output voltage.
12	PGND	Power ground	Low side reference for the PRE switch and the IS sense resistor.
13	IS	Current sense	Current measurement connection for the re-circulating diode. An internal sense resistor and a sample/hold circuit sense the diode current near the conclusion of the off-time. This current measurement provides the DC level of the emulated current ramp.
14	SW	Switching node	The source terminal of the internal buck switch. The SW pin should be connected to the external Schottky diode and to the buck inductor.

PIN DESCRIPTIONS (continued)

Pin(s)	Name	Description	Application Information
15	PRE	Pre-charge assist for the bootstrap capacitor	This open drain output can be connected to SW pin to aid charging the bootstrap capacitor during very light load conditions or in applications where the output may be pre-charged before the LM5574 is enabled. An internal pre-charge MOSFET is turned on for 250ns each cycle just prior to the on-time interval of the buck switch.
16	BST	Boost input for bootstrap capacitor	An external capacitor is required between the BST and the SW pins. A 0.022µF ceramic capacitor is recommended. The capacitor is charged from V _{CC} via an internal diode during the off-time of the buck switch.



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

Absolute Maximum Ratings⁽¹⁾⁽²⁾

V _{IN} to GND	76V
BST to GND	90V
PRE to GND	76V
SW to GND (Steady State)	-1.5V
BST to V _{CC}	76V
SD, V _{CC} to GND	14V
BST to SW	14V
OUT to GND	Limited to V _{in}
SYNC, SS, FB, RAMP to GND	7V
ESD Rating ⁽³⁾	Human Body Model
Storage Temperature Range	-65°C to +150°C

- (1) Absolute Maximum Ratings are limits beyond which damage to the device may occur. Operating Ratings are conditions under which operation of the device is intended to be functional. For ensured specifications and test conditions, see the [Electrical Characteristics](#).
- (2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/Distributors for availability and specifications.
- (3) The human body model is a 100pF capacitor discharged through a 1.5kΩ resistor into each pin.

Operating Ratings⁽¹⁾

V _{IN}	6V to 75V
Operation Junction Temperature	-40°C to + 125°C

- (1) Absolute Maximum Ratings are limits beyond which damage to the device may occur. Operating Ratings are conditions under which operation of the device is intended to be functional. For ensured specifications and test conditions, see the [Electrical Characteristics](#).

Electrical Characteristics

Specifications with standard typeface are for $T_J = 25^\circ\text{C}$, and those with **boldface** type apply over full **Operating Junction Temperature range**. $V_{IN} = 48\text{V}$, $R_T = 32.4\text{k}\Omega$ unless otherwise stated.⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Units
STARTUP REGULATOR						
VccReg	Vcc Regulator Output		6.85	7.15	7.45	V
	Vcc LDO Mode turn-off			9		V
	Vcc Current Limit	$V_{CC} = 0\text{V}$		25		mA
VCC SUPPLY						
	Vcc UVLO Threshold	(Vcc increasing)	5.03	5.35	5.67	V
	Vcc Undervoltage Hysteresis			0.35		V
	Bias Current (lin)	$FB = 1.3\text{V}$		3.7	4.5	mA
	Shutdown Current (lin)	$SD = 0\text{V}$		57	85	μA
SHUTDOWN THRESHOLDS						
	Shutdown Threshold	(SD Increasing)	0.47	0.7	0.9	V
	Shutdown Hysteresis			0.1		V
	Standby Threshold	(Standby Increasing)	1.17	1.225	1.28	V
	Standby Hysteresis			0.1		V
	SD Pull-up Current Source			5		μA
SWITCH CHARACTERISTICS						
	Buck Switch $R_{DS(on)}$			750	1500	m Ω
	BOOST UVLO			4		V
	BOOST UVLO Hysteresis			0.56		V
	Pre-charge Switch $R_{DS(on)}$			70		Ω
	Pre-charge Switch on-time			250		ns
CURRENT LIMIT						
	Cycle by Cycle Current Limit	$RAMP = 0\text{V}$	0.6	0.7	0.8	A
	Cycle by Cycle Current Limit Delay	$RAMP = 2.5\text{V}$		75		ns
SOFT-START						
	SS Current Source		7	10	14	μA
OSCILLATOR						
	Frequency1		180	200	220	kHz
	Frequency2	$R_T = 11\text{k}\Omega$	425	485	545	kHz
	SYNC Source Impedance			11		k Ω
	SYNC Sink Impedance			110		Ω
	SYNC Threshold (falling)			1.3		V
	SYNC Frequency	$R_T = 11\text{k}\Omega$	550			kHz
	SYNC Pulse Width Minimum		15			ns
RAMP GENERATOR						
	Ramp Current 1	$V_{IN} = 60\text{V}$, $V_{OUT} = 10\text{V}$	467	550	633	μA
	Ramp Current 2	$V_{IN} = 10\text{V}$, $V_{OUT} = 10\text{V}$	36	50	64	μA
PWM COMPARATOR						
	Forced Off-time		416	500	575	ns
	Min On-time			80		ns
	COMP to PWM Comparator Offset			0.7		V

(1) Min and Max limits are 100% production tested at 25°C . Limits over the operating temperature range are ensured through correlation using Statistical Quality Control (SQC) methods. Limits are used to calculate Texas Instruments' Average Outgoing Quality Level (AOQL).

Electrical Characteristics (continued)

Specifications with standard typeface are for $T_j = 25^\circ\text{C}$, and those with **boldface** type apply over full **Operating Junction Temperature range**. $V_{IN} = 48\text{V}$, $R_T = 32.4\text{k}\Omega$ unless otherwise stated.⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Units
ERROR AMPLIFIER						
	Feedback Voltage	$V_{fb} = \text{COMP}$	1.207	1.225	1.243	V
	FB Bias Current			17		nA
	DC Gain			70		dB
	COMP Sink / Source Current		3			mA
	Unity Gain Bandwidth			3		MHz
DIODE SENSE RESISTANCE						
D_{SENSE}				250		m Ω
THERMAL SHUTDOWN						
T_{sd}	Thermal Shutdown Threshold			165		$^\circ\text{C}$
	Thermal Shutdown Hysteresis			25		$^\circ\text{C}$
THERMAL RESISTANCE						
θ_{JC}	Junction to Case			30		$^\circ\text{C/W}$
θ_{JA}	Junction to Ambient			90		$^\circ\text{C/W}$

Typical Performance Characteristics

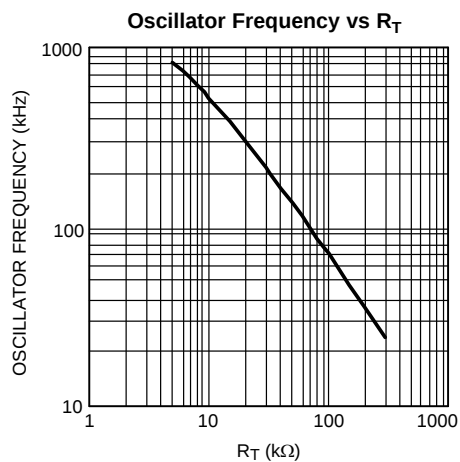


Figure 2.

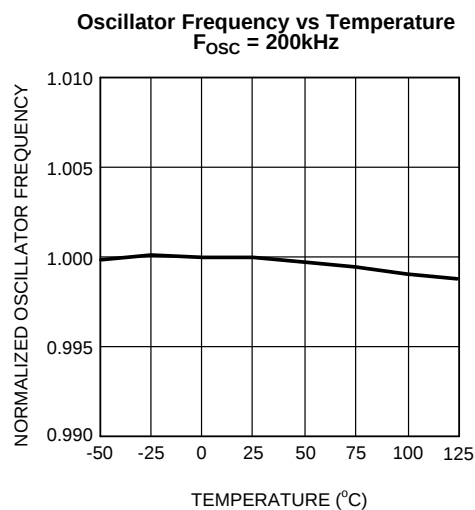


Figure 3.

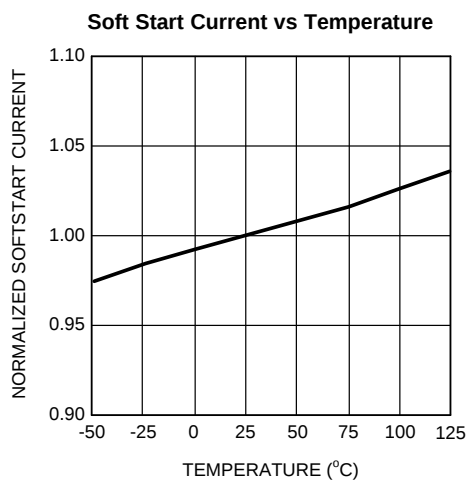


Figure 4.

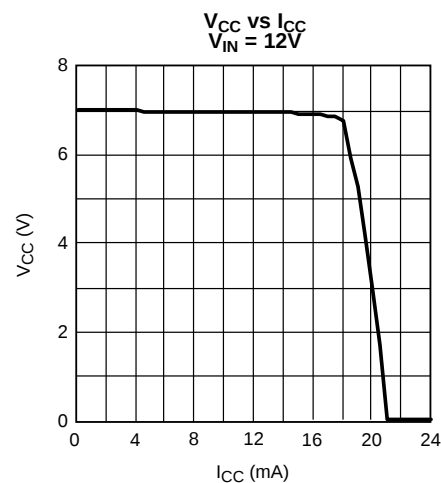


Figure 5.

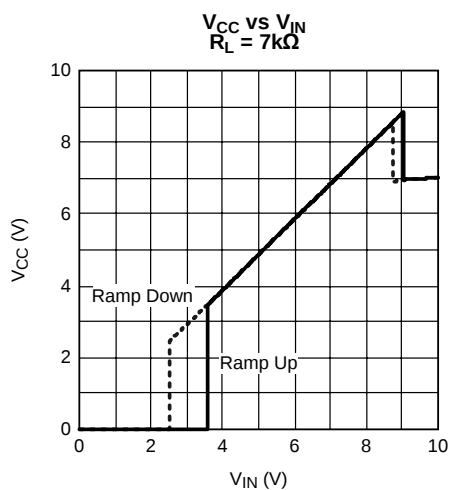


Figure 6.

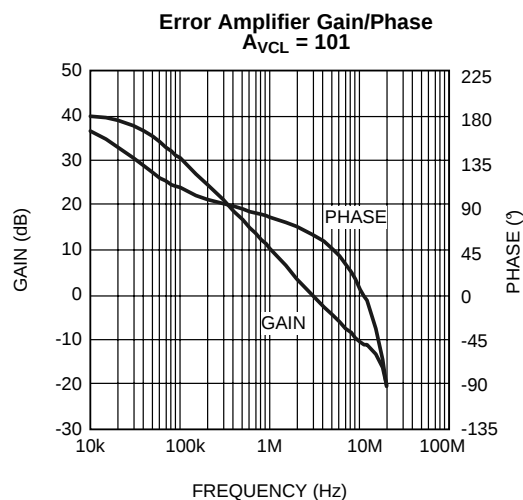


Figure 7.

Typical Performance Characteristics (continued)

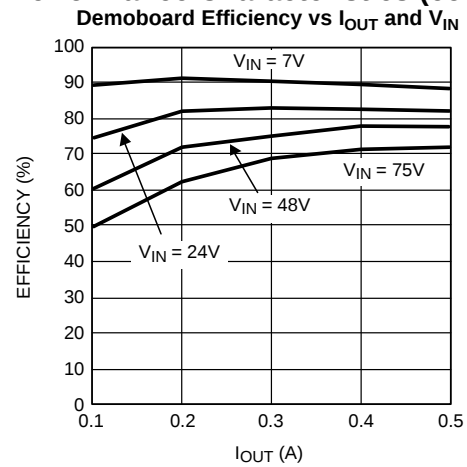


Figure 8.

TYPICAL APPLICATION CIRCUIT AND BLOCK DIAGRAM

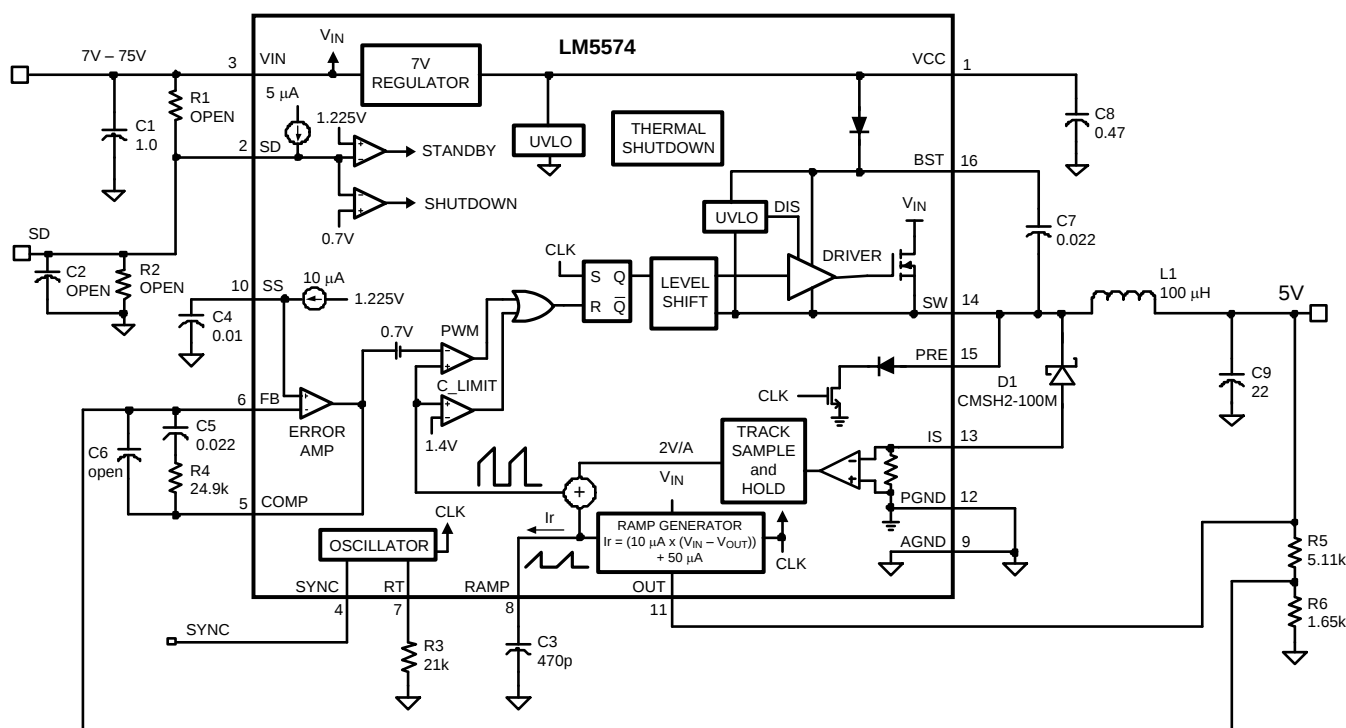


Figure 9. Functional Block Diagram

Detailed Operating Description

The LM5574 switching regulator features all of the functions necessary to implement an efficient high voltage buck regulator using a minimum of external components. This easy to use regulator integrates a 75V N-Channel buck switch with an output current capability of 0.5 Amps. The regulator control method is based on current mode control utilizing an emulated current ramp. Peak current mode control provides inherent line voltage feed-forward, cycle-by-cycle current limiting, and ease of loop compensation. The use of an emulated control ramp reduces noise sensitivity of the pulse-width modulation circuit, allowing reliable processing of very small duty cycles necessary in high input voltage applications. The operating frequency is user programmable from 50kHz to 500kHz. An oscillator synchronization pin allows multiple LM5574 regulators to self synchronize or be synchronized to an external clock. The output voltage can be set as low as 1.225V. Fault protection features include, current limiting, thermal shutdown and remote shutdown capability. The device is available in the TSSOP-16 package.

The functional block diagram and typical application of the LM5574 are shown in Figure 9. The LM5574 can be applied in numerous applications to efficiently step-down a high, unregulated input voltage. The device is well suited for telecom, industrial and automotive power bus voltage ranges.

High Voltage Start-Up Regulator

The LM5574 contains a dual-mode internal high voltage startup regulator that provides the Vcc bias supply for the PWM controller and boot-strap MOSFET gate driver. The input pin (VIN) can be connected directly to the input voltage, as high as 75 Volts. For input voltages below 9V, a low dropout switch connects Vcc directly to Vin. In this supply range, Vcc is approximately equal to Vin. For Vin voltage greater than 9V, the low dropout switch is disabled and the Vcc regulator is enabled to maintain Vcc at approximately 7V. The wide operating range of 6V to 75V is achieved through the use of this dual mode regulator.

The output of the Vcc regulator is current limited to 25mA. Upon power up, the regulator sources current into the capacitor connected to the VCC pin. When the voltage at the VCC pin exceeds the Vcc UVLO threshold of 5.35V and the SD pin is greater than 1.225V, the output switch is enabled and a soft-start sequence begins. The output switch remains enabled until Vcc falls below 5.0V or the SD pin falls below 1.125V.

An auxiliary supply voltage can be applied to the Vcc pin to reduce the IC power dissipation. If the auxiliary voltage is greater than 7.3V, the internal regulator will essentially shut off, reducing the IC power dissipation. The Vcc regulator series pass transistor includes a diode between Vcc and Vin that should not be forward biased in normal operation. Therefore the auxiliary Vcc voltage should never exceed the Vin voltage.

In high voltage applications extra care should be taken to ensure the VIN pin does not exceed the absolute maximum voltage rating of 76V. During line or load transients, voltage ringing on the Vin line that exceeds the Absolute Maximum Ratings can damage the IC. Both careful PC board layout and the use of quality bypass capacitors located close to the VIN and GND pins are essential.

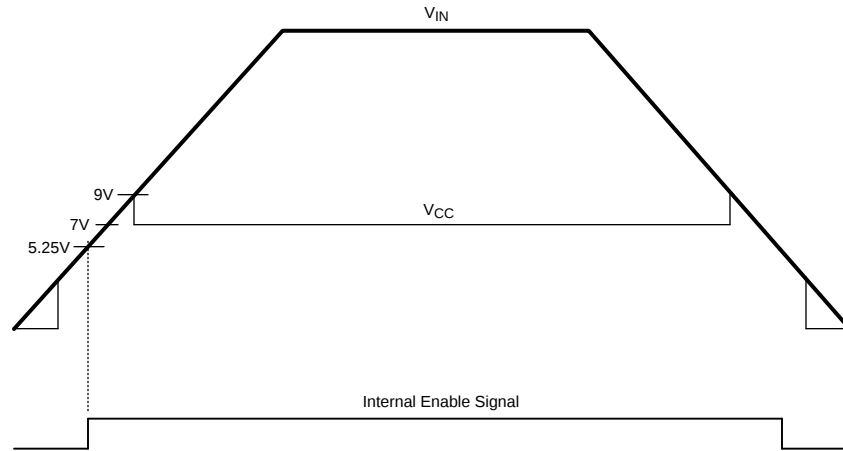


Figure 10. Vin and Vcc Sequencing

Shutdown / Standby

The LM5574 contains a dual level Shutdown (SD) circuit. When the SD pin voltage is below 0.7V, the regulator is in a low current shutdown mode. When the SD pin voltage is greater than 0.7V but less than 1.225V, the regulator is in standby mode. In standby mode the Vcc regulator is active but the output switch is disabled. When the SD pin voltage exceeds 1.225V, the output switch is enabled and normal operation begins. An internal 5μA pull-up current source configures the regulator to be fully operational if the SD pin is left open.

An external set-point voltage divider from VIN to GND can be used to set the operational input range of the regulator. The divider must be designed such that the voltage at the SD pin will be greater than 1.225V when Vin is in the desired operating range. The internal 5μA pull-up current source must be included in calculations of the external set-point divider. Hysteresis of 0.1V is included for both the shutdown and standby thresholds. The SD pin is internally clamped with a 1kΩ resistor and an 8V zener clamp. The voltage at the SD pin should never exceed 14V. If the voltage at the SD pin exceeds 8V, the bias current will increase at a rate of 1 mA/V.

The SD pin can also be used to implement various remote enable / disable functions. Pulling the SD pin below the 0.7V threshold totally disables the controller. If the SD pin voltage is above 1.225V the regulator will be operational.

Oscillator and Sync Capability

The LM5574 oscillator frequency is set by a single external resistor connected between the RT pin and the AGND pin. The RT resistor should be located very close to the device and connected directly to the pins of the IC (RT and AGND). To set a desired oscillator frequency (F), the necessary value for the RT resistor can be calculated from the following equation:

$$R_T = \frac{\frac{1}{F} - 580 \times 10^{-9}}{135 \times 10^{-12}} \quad (1)$$

The SYNC pin can be used to synchronize the internal oscillator to an external clock. The external clock must be of **higher frequency** than the free-running frequency set by the RT resistor. A clock circuit with an open drain output is the recommended interface from the external clock to the SYNC pin. The clock pulse duration should be greater than 15ns.

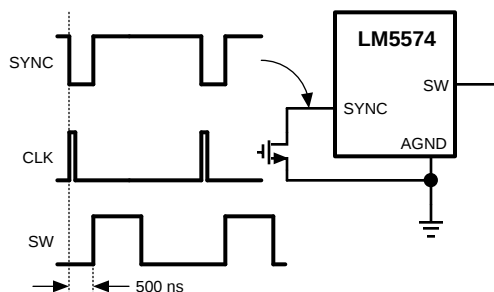


Figure 11. Sync from External Clock

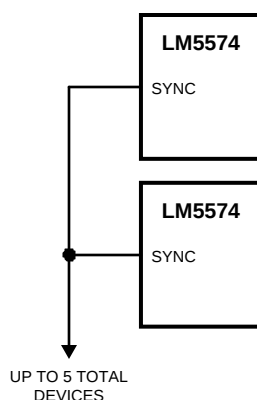


Figure 12. Sync from Multiple Devices

Multiple LM5574 devices can be synchronized together simply by connecting the SYNC pins together. In this configuration all of the devices will be synchronized to the highest frequency device. The diagram in [Figure 13](#) illustrates the SYNC input/output features of the LM5574. The internal oscillator circuit drives the SYNC pin with a strong pull-down / weak pull-up inverter. When the SYNC pin is pulled low either by the internal oscillator or an external clock, the ramp cycle of the oscillator is terminated and a new oscillator cycle begins. Thus, if the SYNC pins of several LM5574 IC's are connected together, the IC with the highest internal clock frequency will pull the connected SYNC pins low first and terminate the oscillator ramp cycles of the other IC's. The LM5574 with the highest programmed clock frequency will serve as the master and control the switching frequency of the all the devices with lower oscillator frequency.

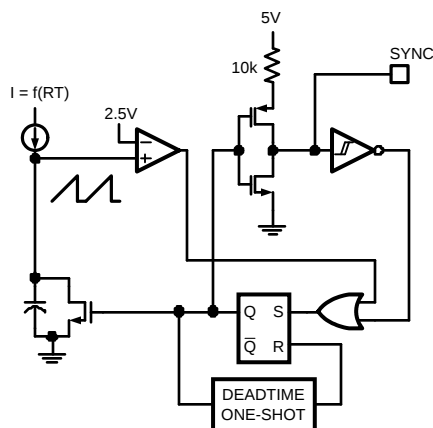


Figure 13. Simplified Oscillator Block Diagram and SYNC I/O Circuit

Error Amplifier and PWM Comparator

The internal high gain error amplifier generates an error signal proportional to the difference between the regulated output voltage and an internal precision reference (1.225V). The output of the error amplifier is connected to the COMP pin allowing the user to provide loop compensation components, generally a type II network, as illustrated in [Figure 9](#). This network creates a pole at DC, a zero and a noise reducing high frequency pole. The PWM comparator compares the emulated current sense signal from the RAMP generator to the error amplifier output voltage at the COMP pin.

RAMP Generator

The ramp signal used in the pulse width modulator for current mode control is typically derived directly from the buck switch current. This switch current corresponds to the positive slope portion of the output inductor current. Using this signal for the PWM ramp simplifies the control loop transfer function to a single pole response and provides inherent input voltage feed-forward compensation. The disadvantage of using the buck switch current signal for PWM control is the large leading edge spike due to circuit parasitics that must be filtered or blanked. Also, the current measurement may introduce significant propagation delays. The filtering, blanking time and propagation delay limit the minimum achievable pulsewidth. In applications where the input voltage may be relatively large in comparison to the output voltage, controlling small pulsewidths and duty cycles is necessary for regulation. The LM5574 utilizes a unique ramp generator, which does not actually measure the buck switch current but rather reconstructs the signal. Reconstructing or emulating the inductor current provides a ramp signal to the PWM comparator that is free of leading edge spikes and measurement or filtering delays. The current reconstruction is comprised of two elements; a sample & hold DC level and an emulated current ramp.

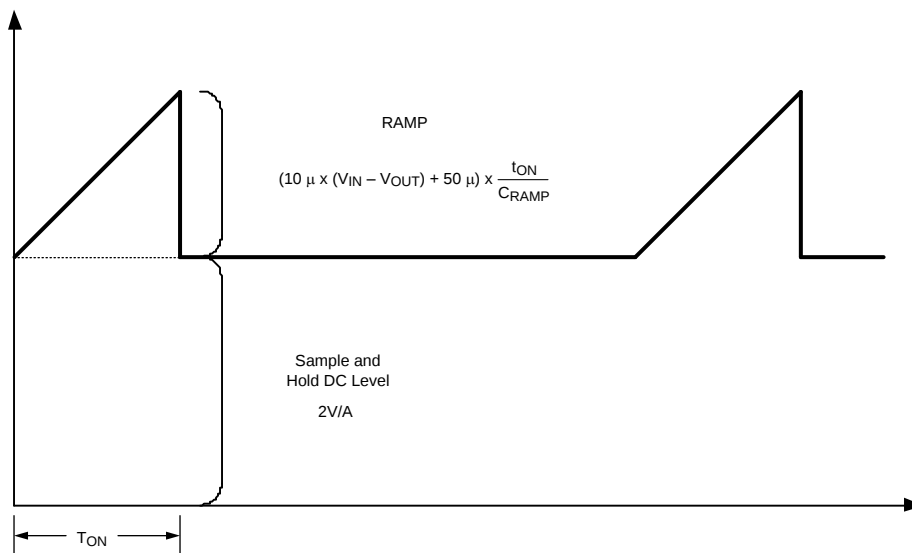


Figure 14. Composition of Current Sense Signal

The sample & hold DC level illustrated in [Figure 14](#) is derived from a measurement of the re-circulating Schottky diode anode current. The re-circulating diode anode should be connected to the IS pin. The diode current flows through an internal current sense resistor between the IS and PGND pins. The voltage level across the sense resistor is sampled and held just prior to the onset of the next conduction interval of the buck switch. The diode current sensing and sample & hold provide the DC level of the reconstructed current signal. The positive slope inductor current ramp is emulated by an external capacitor connected from the RAMP pin to AGND and an internal voltage controlled current source. The ramp current source that emulates the inductor current is a function of the Vin and Vout voltages per the following equation:

$$I_{RAMP} = (10 \mu \times (V_{in} - V_{out})) + 50 \mu A \quad (2)$$

Proper selection of the RAMP capacitor depends upon the selected value of the output inductor. The value of C_{RAMP} can be selected from: $C_{RAMP} = L \times 5 \times 10^{-6}$, where L is the value of the output inductor in Henrys. With this value, the scale factor of the emulated current ramp will be approximately equal to the scale factor of the DC level sample and hold (2.0V / A). The C_{RAMP} capacitor should be located very close to the device and connected directly to the pins of the IC (RAMP and AGND).

For duty cycles greater than 50%, peak current mode control circuits are subject to sub-harmonic oscillation. Sub-harmonic oscillation is normally characterized by observing alternating wide and narrow pulses at the switch node. Adding a fixed slope voltage ramp (slope compensation) to the current sense signal prevents this oscillation. The 50µA of offset current provided from the emulated current source adds some fixed slope to the ramp signal. In some high output voltage, high duty cycle applications, additional slope may be required. In these applications, a pull-up resistor may be added between the V_{CC} and RAMP pins to increase the ramp slope compensation.

For V_{OUT} > 7.5V:

Calculate optimal slope current, I_{OS} = V_{OUT} × 10µA/V.

For example, at V_{OUT} = 10V, I_{OS} = 100µA.

Install a resistor from the RAMP pin to V_{CC}:

$$R_{\text{RAMP}} = V_{\text{CC}} / (I_{\text{OS}} - 50\mu\text{A})$$

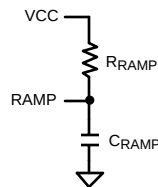


Figure 15. R_{RAMP} to V_{CC} for V_{OUT} > 7.5V

Maximum Duty Cycle / Input Drop-out Voltage

There is a forced off-time of 500ns implemented each cycle to ensure sufficient time for the diode current to be sampled. This forced off-time limits the maximum duty cycle of the buck switch. The maximum duty cycle will vary with the operating frequency.

$$D_{\text{MAX}} = 1 - F_s \times 500\text{ns} \quad (3)$$

Where F_s is the oscillator frequency. Limiting the maximum duty cycle will raise the input dropout voltage. The input dropout voltage is the lowest input voltage required to maintain regulation of the output voltage. An approximation of the input dropout voltage is:

$$V_{\text{inMIN}} = \frac{V_{\text{out}} + V_D}{1 - F_s \times 500 \text{ ns}} \quad (4)$$

Where V_D is the voltage drop across the re-circulatory diode. Operating at high switching frequency raises the minimum input voltage necessary to maintain regulation.

Current Limit

The LM5574 contains a unique current monitoring scheme for control and over-current protection. When set correctly, the emulated current sense signal provides a signal which is proportional to the buck switch current with a scale factor of 2.0 V / A. The emulated ramp signal is applied to the current limit comparator. If the emulated ramp signal exceeds 1.4V (0.7A) the present current cycle is terminated (cycle-by-cycle current limiting). In applications with small output inductance and high input voltage the switch current may overshoot due to the propagation delay of the current limit comparator. If an overshoot should occur, the diode current sampling circuit will detect the excess inductor current during the off-time of the buck switch. If the sample & hold DC level exceeds the 1.4V current limit threshold, the buck switch will be disabled and skip pulses until the diode current sampling circuit detects the inductor current has decayed below the current limit threshold. This approach prevents current runaway conditions due to propagation delays or inductor saturation since the inductor current is forced to decay following any current overshoot.

Soft-Start

The soft-start feature allows the regulator to gradually reach the initial steady state operating point, thus reducing start-up stresses and surges. The internal soft-start current source, set to 10µA, gradually increases the voltage of an external soft-start capacitor connected to the SS pin. The soft-start capacitor voltage is connected to the reference input of the error amplifier. Various sequencing and tracking schemes can be implemented using external circuits that limit or clamp the voltage level of the SS pin.

In the event a fault is detected (over-temperature, V_{CC} UVLO, SD) the soft-start capacitor will be discharged. When the fault condition is no longer present a new soft-start sequence will commence.

Boost Pin

The LM5574 integrates an N-Channel buck switch and associated floating high voltage level shift / gate driver. This gate driver circuit works in conjunction with an internal diode and an external bootstrap capacitor. A 0.022µF ceramic capacitor, connected with short traces between the BST pin and SW pin, is recommended. During the off-time of the buck switch, the SW pin voltage is approximately -0.5V and the bootstrap capacitor is charged from V_{CC} through the internal bootstrap diode. When operating with a high PWM duty cycle, the buck switch will be forced off each cycle for 500ns to ensure that the bootstrap capacitor is recharged.

Under very light load conditions or when the output voltage is pre-charged, the SW voltage will not remain low during the off-time of the buck switch. If the inductor current falls to zero and the SW pin rises, the bootstrap capacitor will not receive sufficient voltage to operate the buck switch gate driver. For these applications, the PRE pin can be connected to the SW pin to pre-charge the bootstrap capacitor. The internal pre-charge MOSFET and diode connected between the PRE pin and PGND turns on each cycle for 250ns just prior to the onset of a new switching cycle. If the SW pin is at a normal negative voltage level (continuous conduction mode), then no current will flow through the pre-charge MOSFET/diode.

Thermal Protection

Internal Thermal Shutdown circuitry is provided to protect the integrated circuit in the event the maximum junction temperature is exceeded. When activated, typically at 165°C, the controller is forced into a low power reset state, disabling the output driver and the bias regulator. This feature is provided to prevent catastrophic failures from accidental device overheating.

Application Information

EXTERNAL COMPONENTS

The procedure for calculating the external components is illustrated with the following design example. The Bill of Materials for this design is listed in [Table 1](#). The circuit shown in [Figure 9](#) is configured for the following specifications:

- V_{OUT} = 5V
- V_{IN} = 7V to 75V
- F_S = 300kHz
- Minimum load current (for CCM) = 100mA
- Maximum load current = 0.5A

R_T (R_T)

R_T sets the oscillator switching frequency. Generally, higher frequency applications are smaller but have higher losses. Operation at 300kHz was selected for this example as a reasonable compromise for both small size and high efficiency. The value of R_T for 300kHz switching frequency can be calculated as follows:

$$R_T = \frac{[(1 / 300 \times 10^3) - 580 \times 10^{-9}]}{135 \times 10^{-12}} \quad (5)$$

The nearest standard value of 21kΩ was chosen for R_T.

L1

The inductor value is determined based on the operating frequency, load current, ripple current, and the minimum and maximum input voltage ($V_{IN(min)}$, $V_{IN(max)}$).

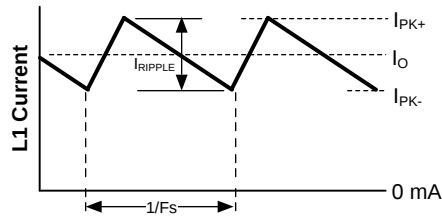


Figure 16. Inductor Current Waveform

To keep the circuit in continuous conduction mode (CCM), the maximum ripple current I_{RIPPLE} should be less than twice the minimum load current, or $0.2A_{p-p}$. Using this value of ripple current, the value of inductor ($L1$) is calculated using the following:

$$L1 = \frac{V_{OUT} \times (V_{IN(max)} - V_{OUT})}{I_{RIPPLE} \times F_S \times V_{IN(max)}} \quad (6)$$

$$L1 = \frac{5V \times (75V - 5V)}{0.2A \times 300 \text{ kHz} \times 75V} = 78 \mu H \quad (7)$$

This procedure provides a guide to select the value of $L1$. The nearest standard value ($100\mu H$) will be used. $L1$ must be rated for the peak current (I_{PK+}) to prevent saturation. During normal loading conditions, the peak current occurs at maximum load current plus maximum ripple. During an overload condition the peak current is limited to $0.7A$ nominal ($0.85A$ maximum). The selected inductor (see [Table 1](#)) has a conservative 1.0 Amp saturation current rating. For this manufacturer, the saturation rating is defined as the current necessary for the inductance to reduce by 30% , at $20^\circ C$.

C3 (C_{RAMP})

With the inductor value selected, the value of $C3$ (C_{RAMP}) necessary for the emulation ramp circuit is:

$$C_{RAMP} = L \times 5 \times 10^{-6} \quad (8)$$

Where L is in Henrys

With $L1$ selected for $100\mu H$ the recommended value for $C3$ is $470pF$ (nearest standard value).

C9

The output capacitor, $C9$ smoothes the inductor ripple current and provides a source of charge for transient loading conditions. For this design a $22\mu F$ ceramic capacitor was selected. The ceramic capacitor provides ultra low ESR to reduce the output ripple voltage and noise spikes. An approximation for the output ripple voltage is:

$$\Delta V_{OUT} = \Delta I_L \times \left(ESR + \frac{1}{8 \times F_S \times C_{OUT}} \right) \quad (9)$$

D1

A Schottky type re-circulating diode is required for all LM5574 applications. Ultra-fast diodes are not recommended and may result in damage to the IC due to reverse recovery current transients. The near ideal reverse recovery characteristics and low forward voltage drop are particularly important diode characteristics for high input voltage and low output voltage applications common to the LM5574. The reverse recovery characteristic determines how long the current surge lasts each cycle when the buck switch is turned on. The reverse recovery characteristics of Schottky diodes minimize the peak instantaneous power in the buck switch occurring during turn-on each cycle. The resulting switching losses of the buck switch are significantly reduced when using a Schottky diode. The reverse breakdown rating should be selected for the maximum V_{IN} , plus some safety margin.

The forward voltage drop has a significant impact on the conversion efficiency, especially for applications with a low output voltage. “Rated” current for diodes vary widely from various manufacturers. The worst case is to assume a short circuit load condition. In this case the diode will carry the output current almost continuously. For the LM5574 this current can be as high as 0.7A. Assuming a worst case 1V drop across the diode, the maximum diode power dissipation can be as high as 0.7W. For the reference design a 100V Schottky in a SMA package was selected.

C1

The regulator supply voltage has a large source impedance at the switching frequency. Good quality input capacitors are necessary to limit the ripple voltage at the VIN pin while supplying most of the switch current during the on-time. When the buck switch turns on, the current into the VIN pin steps to the lower peak of the inductor current waveform, ramps up to the peak value, then drops to zero at turn-off. The average current into VIN during the on-time is the load current. The input capacitance should be selected for RMS current rating and minimum ripple voltage. A good approximation for the required ripple current rating necessary is $I_{RMS} > I_{OUT} / 2$.

Quality ceramic capacitors with a low ESR should be selected for the input filter. To allow for capacitor tolerances and voltage effects, one 1.0μF, 100V ceramic capacitor will be used. If step input voltage transients are expected near the maximum rating of the LM5574, a careful evaluation of ringing and possible spikes at the device VIN pin should be completed. An additional damping network or input voltage clamp may be required in these cases.

C8

The capacitor at the VCC pin provides noise filtering and stability for the V_{CC} regulator. The recommended value of C8 should be no smaller than 0.1μF, and should be a good quality, low ESR, ceramic capacitor. A value of 0.47μF was selected for this design.

C7

The bootstrap capacitor between the BST and the SW pins supplies the gate current to charge the buck switch gate at turn-on. The recommended value of C7 is 0.022μF, and should be a good quality, low ESR, ceramic capacitor.

C4

The capacitor at the SS pin determines the soft-start time, i.e. the time for the reference voltage and the output voltage, to reach the final regulated value. The time is determined from:

$$t_{ss} = \frac{C4 \times 1.225V}{10 \mu A} \quad (10)$$

For this application, a C4 value of 0.01μF was chosen which corresponds to a soft-start time of 1ms.

R5, R6

R5 and R6 set the output voltage level, the ratio of these resistors is calculated from:

$$R5/R6 = (V_{OUT} / 1.225V) - 1 \quad (11)$$

For a 5V output, the R5/R6 ratio calculates to 3.082. The resistors should be chosen from standard value resistors, a good starting point is selection in the range of 1.0kΩ - 10kΩ. Values of 5.11kΩ for R5, and 1.65kΩ for R6 were selected.

R1, R2, C2

A voltage divider can be connected to the SD pin to set a minimum operating voltage $V_{IN(min)}$ for the regulator. If this feature is required, the easiest approach to select the divider resistor values is to select a value for R1 (between 10kΩ and 100kΩ recommended) then calculate R2 from:

$$R2 = 1.225 \times \left(\frac{R1}{V_{IN(min)} + (5 \times 10^{-6} \times R1) - 1.225} \right) \quad (12)$$

Capacitor C2 provides filtering for the divider. The voltage at the SD pin should never exceed 8V, when using an external set-point divider it may be necessary to clamp the SD pin at high input voltage conditions. The reference design utilizes the full range of the LM5574 (6V to 75V); therefore these components can be omitted. With the SD pin open circuit the LM5574 responds once the Vcc UVLO threshold is satisfied.

R4, C5, C6

These components configure the error amplifier gain characteristics to accomplish a stable overall loop gain. One advantage of current mode control is the ability to close the loop with only two feedback components, R4 and C5. The overall loop gain is the product of the modulator gain and the error amplifier gain. The DC modulator gain of the LM5574 is as follows:

$$\text{DC Gain}_{(\text{MOD})} = G_{m(\text{MOD})} \times R_{\text{LOAD}} = 0.5 \times R_{\text{LOAD}} \quad (13)$$

The dominant low frequency pole of the modulator is determined by the load resistance (R_{LOAD}) and output capacitance (C_{OUT}). The corner frequency of this pole is:

$$f_{p(\text{MOD})} = 1 / (2\pi R_{\text{LOAD}} C_{\text{OUT}}) \quad (14)$$

For $R_{\text{LOAD}} = 20\Omega$ and $C_{\text{OUT}} = 22\mu\text{F}$ then $f_{p(\text{MOD})} = 362\text{Hz}$

DC Gain_(MOD) = $0.5 \times 20 = 20\text{dB}$

For the design example of [Figure 9](#) the following modulator gain vs. frequency characteristic was measured as shown in [Figure 17](#).

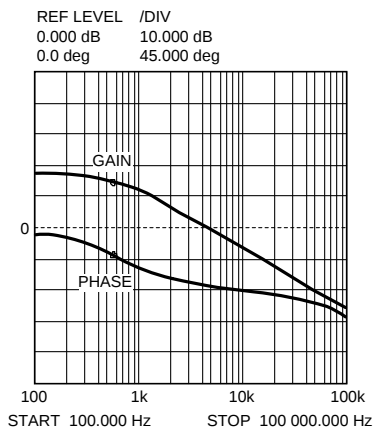


Figure 17. Gain and Phase of Modulator $R_{\text{LOAD}} = 20 \text{ Ohms}$ and $C_{\text{OUT}} = 22\mu\text{F}$

Components R4 and C5 configure the error amplifier as a type II configuration which has a pole at DC and a zero at $f_z = 1 / (2\pi R4 C5)$. The error amplifier zero cancels the modulator pole leaving a single pole response at the crossover frequency of the loop gain. A single pole response at the crossover frequency yields a very stable loop with 90 degrees of phase margin.

For the design example, a target loop bandwidth (crossover frequency) of 25kHz was selected. The compensation network zero (f_z) should be selected at least an order of magnitude less than the target crossover frequency. This constrains the product of R4 and C5 for a desired compensation network zero $1 / (2\pi R4 C5)$ to be less than 2kHz. Increasing R4, while proportionally decreasing C5, increases the error amp gain. Conversely, decreasing R4 while proportionally increasing C5, decreases the error amp gain. For the design example C5 was selected for $0.022\mu\text{F}$ and R4 was selected for $24.9\text{k}\Omega$. These values configure the compensation network zero at 290Hz. The error amp gain at frequencies greater than f_z is: $R4 / R5$, which is approximately 5 (14dB).

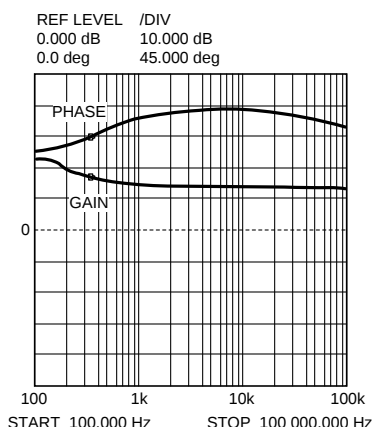


Figure 18. Error Amplifier Gain and Phase

The overall loop can be predicted as the sum (in dB) of the modulator gain and the error amp gain.

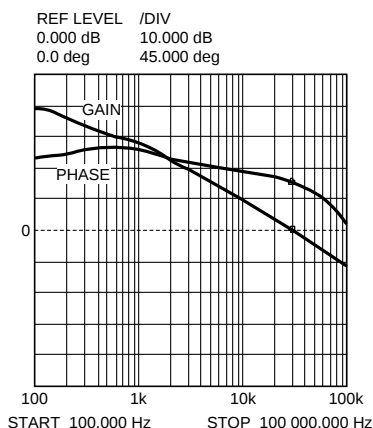


Figure 19. Overall Loop Gain and Phase

If a network analyzer is available, the modulator gain can be measured and the error amplifier gain can be configured for the desired loop transfer function. If a network analyzer is not available, the error amplifier compensation components can be designed with the guidelines given. Step load transient tests can be performed to verify acceptable performance. The step load goal is minimum overshoot with a damped response. C6 can be added to the compensation network to decrease noise susceptibility of the error amplifier. The value of C6 must be sufficiently small since the addition of this capacitor adds a pole in the error amplifier transfer function. This pole must be well beyond the loop crossover frequency. A good approximation of the location of the pole added by C6 is: $f_{p2} = f_z \times C5 / C6$.

BIAS POWER DISSIPATION REDUCTION

Buck regulators operating with high input voltage can dissipate an appreciable amount of power for the bias of the IC. The V_{CC} regulator must step-down the input voltage V_{IN} to a nominal V_{CC} level of 7V. The large voltage drop across the V_{CC} regulator translates into a large power dissipation within the V_{CC} regulator. There are several techniques that can significantly reduce this bias regulator power dissipation. Figure 20 and Figure 21 depict two methods to bias the IC from the output voltage. In each case the internal V_{CC} regulator is used to initially bias the V_{CC} pin. After the output voltage is established, the V_{CC} pin potential is raised above the nominal 7V regulation level, which effectively disables the internal V_{CC} regulator. The voltage applied to the V_{CC} pin should never exceed 14V. The V_{CC} voltage should never be larger than the V_{IN} voltage.

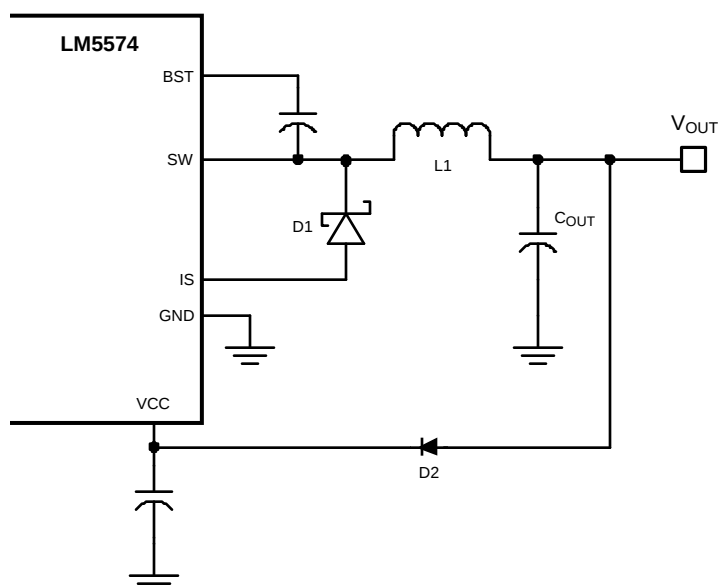


Figure 20. VCC Bias from VOUT for $8V < V_{OUT} < 14V$

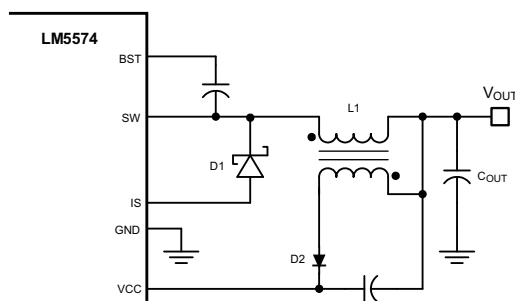


Figure 21. VCC Bias with Additional Winding on the Output Inductor

PCB LAYOUT AND THERMAL CONSIDERATIONS

The circuit in [Figure 9](#) serves as both a block diagram of the LM5574 and a typical application board schematic for the LM5574. In a buck regulator there are two loops where currents are switched very fast. The first loop starts from the input capacitors, to the regulator VIN pin, to the regulator SW pin, to the inductor then out to the load. The second loop starts from the output capacitor ground, to the regulator PGND pins, to the regulator IS pins, to the diode anode, to the inductor and then out to the load. Minimizing the loop area of these two loops reduces the stray inductance and minimizes noise and possible erratic operation. A ground plane in the PC board is recommended as a means to connect the input filter capacitors to the output filter capacitors and the PGND pins of the regulator. Connect all of the low power ground connections (C_{SS} , R_T , C_{RAMP}) directly to the regulator AGND pin. Connect the AGND and PGND pins together through the topside copper trace. Place several vias in this trace to the ground plane.

The two highest power dissipating components are the re-circulating diode and the LM5574 regulator IC. The easiest method to determine the power dissipated within the LM5574 is to measure the total conversion losses ($P_{in} - P_{out}$) then subtract the power losses in the Schottky diode, output inductor and snubber resistor. An approximation for the Schottky diode loss is $P = (1-D) \times I_{out} \times V_{fwd}$. An approximation for the output inductor power is $P = I_{OUT}^2 \times R \times 1.1$, where R is the DC resistance of the inductor and the 1.1 factor is an approximation for the AC losses. If a snubber is used, an approximation for the damping resistor power dissipation is $P = V_{in}^2 \times F_{sw} \times C_{snub}$, where F_{sw} is the switching frequency and C_{snub} is the snubber capacitor.

The most significant variables that affect the power dissipated by the LM5574 are the output current, input voltage and operating frequency. The power dissipated while operating near the maximum output current and maximum input voltage can be appreciable. The operating frequency of the LM5574 evaluation board has been designed for 300kHz. When operating at 0.5A output current with a 70V input the power dissipation of the LM5574 regulator is approximately 0.6W.

The junction-to-ambient thermal resistance of the LM5574 will vary with the application. The most significant variables are the area of copper in the PC board, and the amount of forced air cooling provided. The junction-to-ambient thermal resistance of the LM5574 mounted in the evaluation board varies from 90°C/W with no airflow to 60°C/W with 900 LFM (Linear Feet per Minute). With a 25°C ambient temperature and no airflow, the predicted junction temperature for the LM5574 will be $25 + ((90 \times 0.6) = 79^\circ\text{C}$. If the evaluation board is operated at 0.5A output current, 70V input voltage and high ambient temperature for a prolonged period of time the thermal shutdown protection within the IC may activate. The IC will turn off allowing the junction to cool, followed by restart with the soft-start capacitor reset to zero.

Table 1. 5V, 0.5A Demo Board Bill of Materials

Item		Part Number	Description	Value
C	1	C3225X7R2A105M	CAPACITOR, CER, TDK	1 μ , 100V
C	2	OPEN	NOT USED	
C	3	C0805A471K1GAC	CAPACITOR, CER, KEMET	470p, 100V
C	4	C2012X7R2A103K	CAPACITOR, CER, TDK	0.01 μ , 100V
C	5	C2012X7R2A223K	CAPACITOR, CER, TDK	0.022 μ , 100V
C	6	OPEN	NOT USED	
C	7	C2012X7R2A223K	CAPACITOR, CER, TDK	0.022 μ , 100V
C	8	C2012X7R1C474M	CAPACITOR, CER, TDK	0.47 μ , 16V
C	9	C3225X7R1C226M	CAPACITOR, CER, TDK	22 μ , 16V
D	1	CMSH2-100M	DIODE, 100V, CENTRAL	
L	1	DR74-101	INDUCTOR, COOPER	100 μ H
R	1	OPEN	NOT USED	
R	2	OPEN	NOT USED	
R	3	CRCW08052102F	RESISTOR	21k Ω
R	4	CRCW08052492F	RESISTOR	24.9k Ω
R	5	CRCW08055111F	RESISTOR	5.11k Ω
R	6	CRCW08051651F	RESISTOR	1.65k Ω
U	1	LM5574	REGULATOR, TEXAS INSTRUMENTS	

PCB Layout

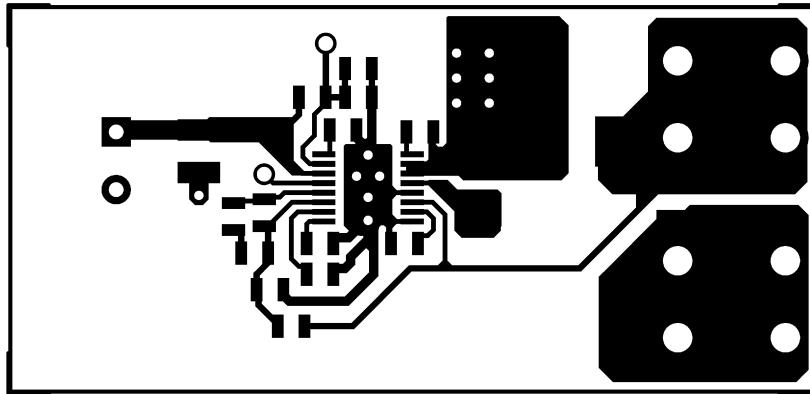


Figure 22. Component Side

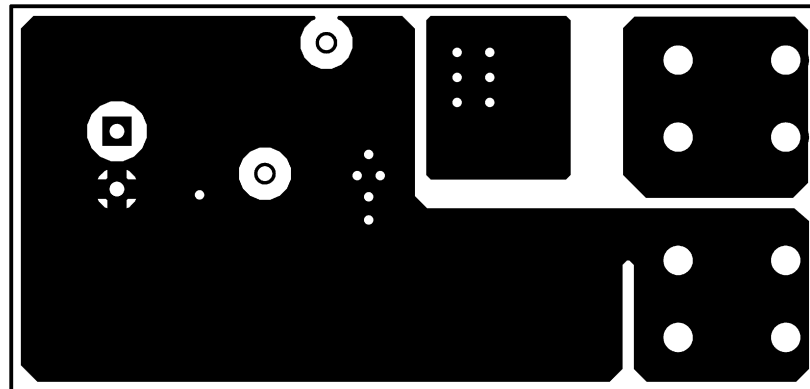


Figure 23. Solder Side

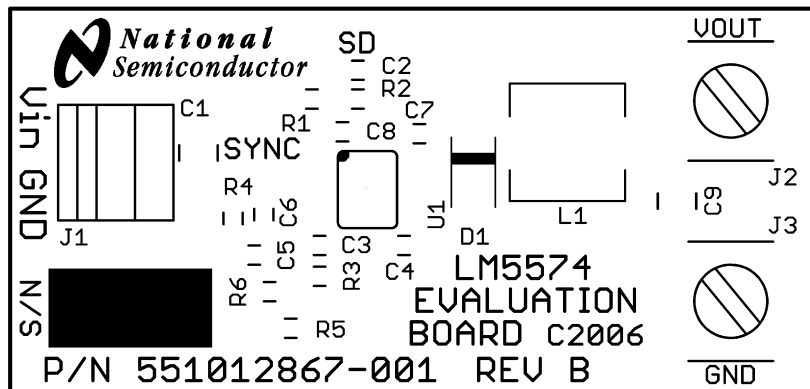


Figure 24. Silkscreen

REVISION HISTORY

Changes from Revision E (April 2013) to Revision F	Page
• Changed layout of National Data Sheet to TI format	21

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
LM5574MT	NRND	TSSOP	PW	16	92	TBD	Call TI	Call TI	-40 to 125	LM5574 MT	
LM5574MT/NOPB	ACTIVE	TSSOP	PW	16	92	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LM5574 MT	Samples
LM5574MTX/NOPB	ACTIVE	TSSOP	PW	16	2500	Green (RoHS & no Sb/Br)	CU NIPDAU CU SN	Level-1-260C-UNLIM	-40 to 125	LM5574 MT	Samples
LM5574Q0MT/NOPB	ACTIVE	TSSOP	PW	16	92	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM		LM5574 Q0MT	Samples
LM5574Q0MTX/NOPB	ACTIVE	TSSOP	PW	16	2500	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM		LM5574 Q0MT	Samples
LM5574QMT/NOPB	ACTIVE	TSSOP	PW	16	92	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LM5574 QMT	Samples
LM5574QMTX/NOPB	ACTIVE	TSSOP	PW	16	2500	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LM5574 QMT	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

⁽⁵⁾ Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "-" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

⁽⁶⁾ Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

OTHER QUALIFIED VERSIONS OF LM5574, LM5574-Q1 :

- Catalog: [LM5574](#)
- Automotive: [LM5574-Q1](#)

NOTE: Qualified Version Definitions:

- Catalog - TI's standard catalog product
- Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

TAPE AND REEL INFORMATION


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LM5574MTX/NOPB	TSSOP	PW	16	2500	330.0	12.4	6.95	8.3	1.6	8.0	12.0	Q1
LM5574Q0MTX/NOPB	TSSOP	PW	16	2500	330.0	12.4	6.95	8.3	1.6	8.0	12.0	Q1
LM5574QMTX/NOPB	TSSOP	PW	16	2500	330.0	12.4	6.95	8.3	1.6	8.0	12.0	Q1

TAPE AND REEL BOX DIMENSIONS

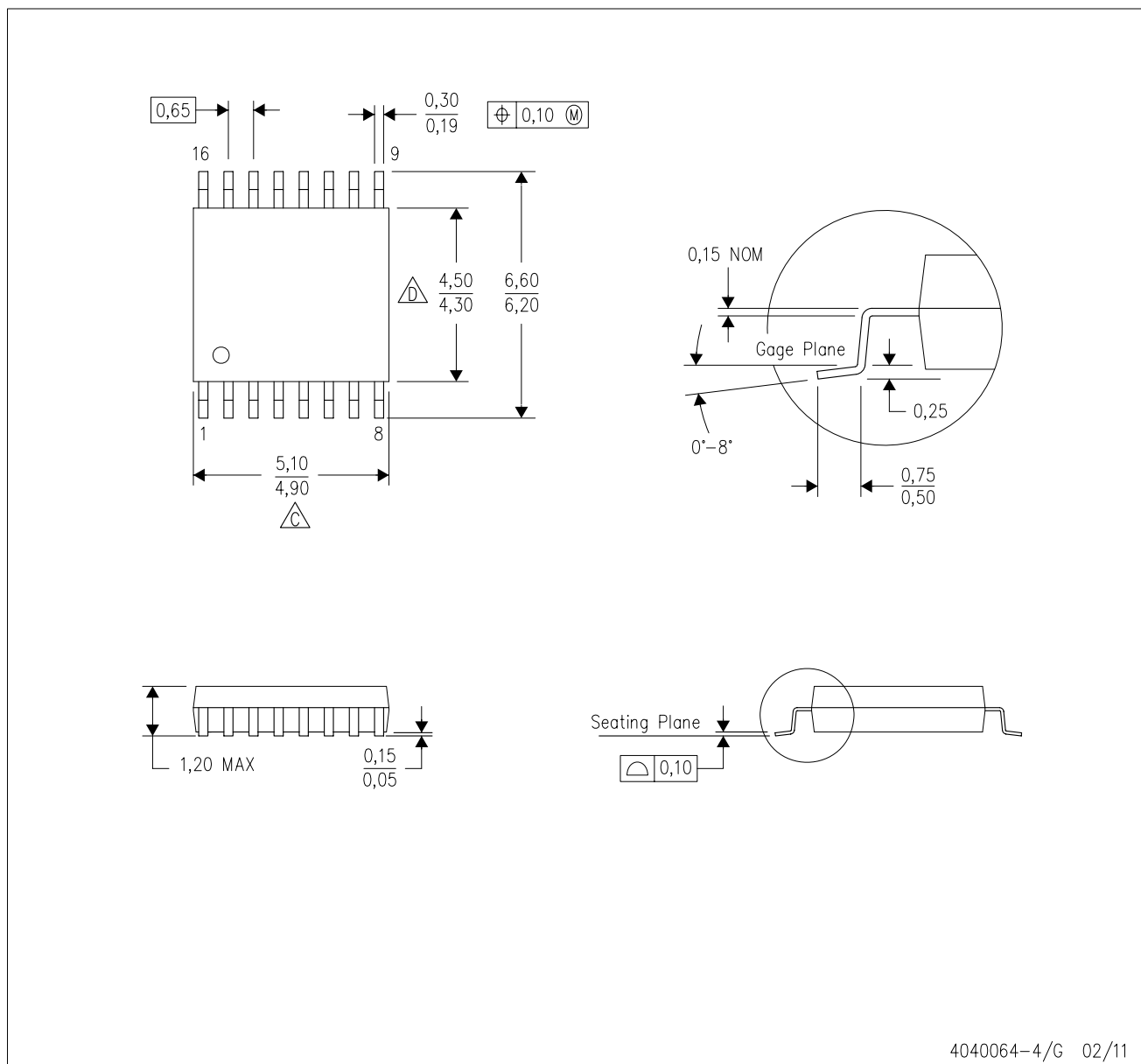


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LM5574MTX/NOPB	TSSOP	PW	16	2500	367.0	367.0	35.0
LM5574Q0MTX/NOPB	TSSOP	PW	16	2500	367.0	367.0	35.0
LM5574QMTX/NOPB	TSSOP	PW	16	2500	367.0	367.0	35.0

PW (R-PDSO-G16)

PLASTIC SMALL OUTLINE

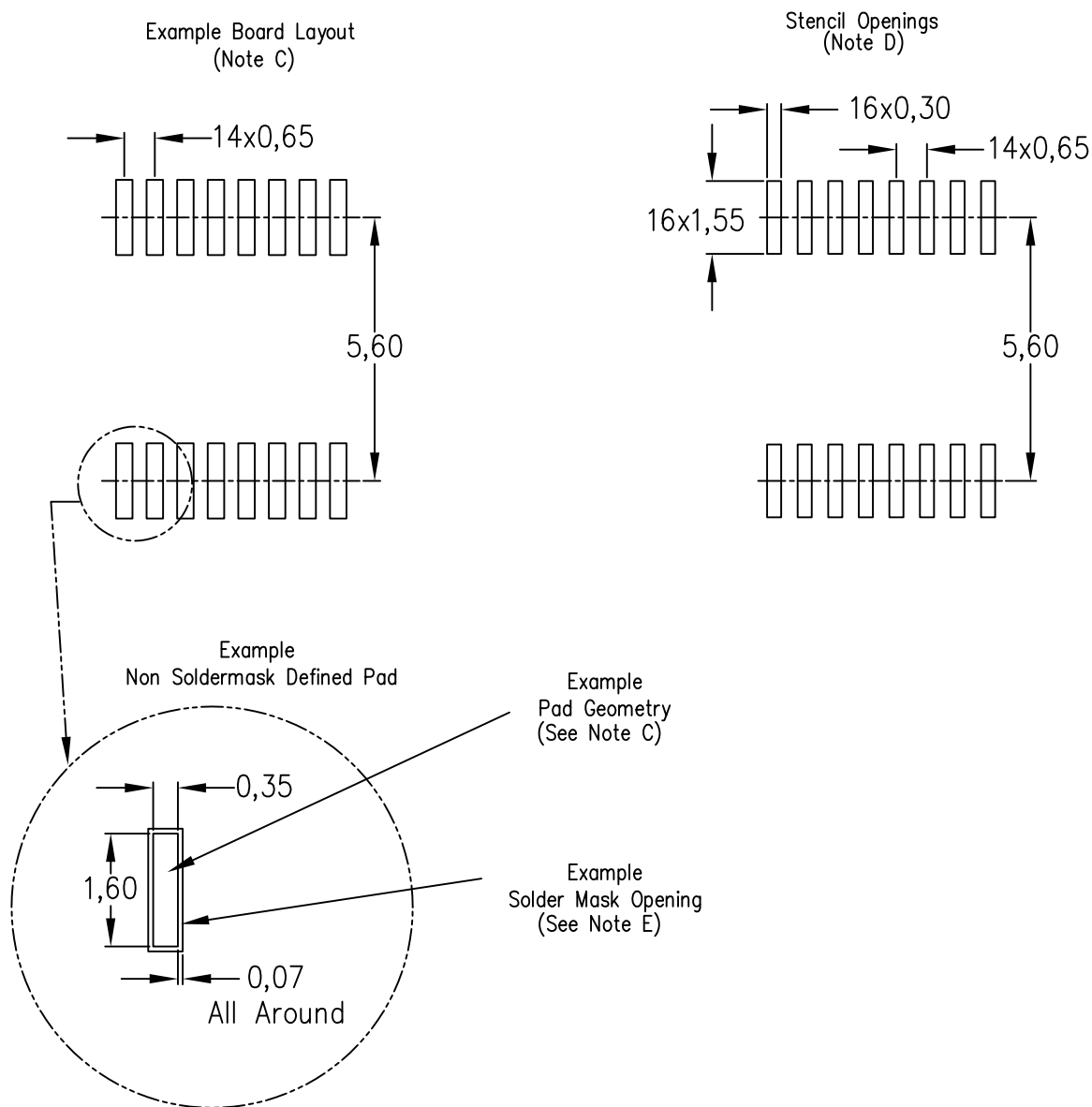


4040064-4/G 02/11

- NOTES:
- A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.
 - B. This drawing is subject to change without notice.
 - C. Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0,15 each side.
 - D. Body width does not include interlead flash. Interlead flash shall not exceed 0,25 each side.
 - E. Falls within JEDEC MO-153

PW (R-PDSO-G16)

PLASTIC SMALL OUTLINE



4211284-3/F 12/12

- NOTES:
- All linear dimensions are in millimeters.
 - This drawing is subject to change without notice.
 - Publication IPC-7351 is recommended for alternate designs.
 - Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525 for other stencil recommendations.
 - Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.

IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, enhancements, improvements and other changes to its semiconductor products and services per JESD46, latest issue, and to discontinue any product or service per JESD48, latest issue. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All semiconductor products (also referred to herein as "components") are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its components to the specifications applicable at the time of sale, in accordance with the warranty in TI's terms and conditions of sale of semiconductor products. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by applicable law, testing of all parameters of each component is not necessarily performed.

TI assumes no liability for applications assistance or the design of Buyers' products. Buyers are responsible for their products and applications using TI components. To minimize the risks associated with Buyers' products and applications, Buyers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right relating to any combination, machine, or process in which TI components or services are used. Information published by TI regarding third-party products or services does not constitute a license to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of significant portions of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI components or services with statements different from or beyond the parameters stated by TI for that component or service voids all express and any implied warranties for the associated TI component or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Buyer acknowledges and agrees that it is solely responsible for compliance with all legal, regulatory and safety-related requirements concerning its products, and any use of TI components in its applications, notwithstanding any applications-related information or support that may be provided by TI. Buyer represents and agrees that it has all the necessary expertise to create and implement safeguards which anticipate dangerous consequences of failures, monitor failures and their consequences, lessen the likelihood of failures that might cause harm and take appropriate remedial actions. Buyer will fully indemnify TI and its representatives against any damages arising out of the use of any TI components in safety-critical applications.

In some cases, TI components may be promoted specifically to facilitate safety-related applications. With such components, TI's goal is to help enable customers to design and create their own end-product solutions that meet applicable functional safety standards and requirements. Nonetheless, such components are subject to these terms.

No TI components are authorized for use in FDA Class III (or similar life-critical medical equipment) unless authorized officers of the parties have executed a special agreement specifically governing such use.

Only those TI components which TI has specifically designated as military grade or "enhanced plastic" are designed and intended for use in military/aerospace applications or environments. Buyer acknowledges and agrees that any military or aerospace use of TI components which have **not** been so designated is solely at the Buyer's risk, and that Buyer is solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI has specifically designated certain components as meeting ISO/TS16949 requirements, mainly for automotive use. In any case of use of non-designated products, TI will not be responsible for any failure to meet ISO/TS16949.

Products

Audio	www.ti.com/audio
Amplifiers	amplifier.ti.com
Data Converters	dataconverter.ti.com
DLP® Products	www.dlp.com
DSP	dsp.ti.com
Clocks and Timers	www.ti.com/clocks
Interface	interface.ti.com
Logic	logic.ti.com
Power Mgmt	power.ti.com
Microcontrollers	microcontroller.ti.com
RFID	www.ti-rfid.com
OMAP Applications Processors	www.ti.com/omap
Wireless Connectivity	www.ti.com/wirelessconnectivity

Applications

Automotive and Transportation	www.ti.com/automotive
Communications and Telecom	www.ti.com/communications
Computers and Peripherals	www.ti.com/computers
Consumer Electronics	www.ti.com/consumer-apps
Energy and Lighting	www.ti.com/energy
Industrial	www.ti.com/industrial
Medical	www.ti.com/medical
Security	www.ti.com/security
Space, Avionics and Defense	www.ti.com/space-avionics-defense
Video and Imaging	www.ti.com/video

TI E2E Community

e2e.ti.com