

MC74HC161A, MC74HC163A

Presettable Counters High-Performance Silicon-Gate CMOS

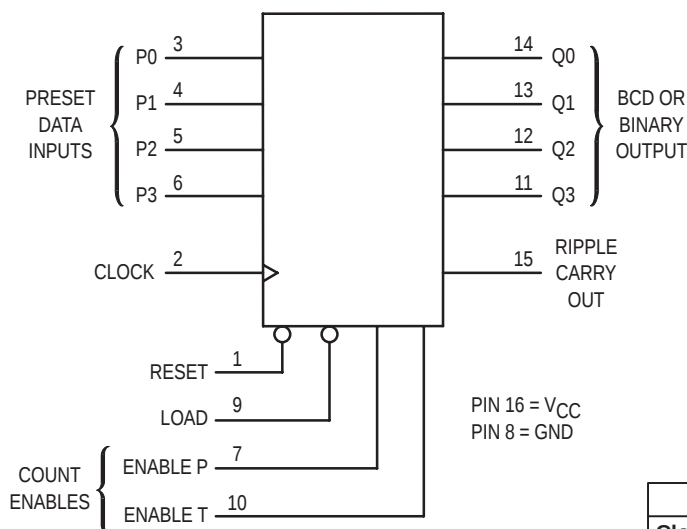
The MC74HC161A and HC163A are identical in pinout to the LS161 and LS163. The device inputs are compatible with standard CMOS outputs; with pullup resistors, they are compatible with LSTTL outputs.

The HC161A and HC163A are programmable 4-bit binary counters with asynchronous and synchronous reset, respectively.

- Output Drive Capability: 10 LSTTL Loads
- Outputs Directly Interface to CMOS, NMOS, and TTL
- Operating Voltage Range: 2.0 to 6.0 V
- Low Input Current: 1.0 μ A
- High Noise Immunity Characteristic of CMOS Devices
- In Compliance with the Requirements Defined by JEDEC Standard No. 7A
- Chip Complexity: 192 FETs or 48 Equivalent Gates

Device	Count Mode	Reset Mode
HC161A	Binary	Asynchronous
HC163A	Binary	Synchronous

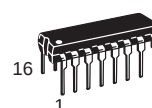
LOGIC DIAGRAM



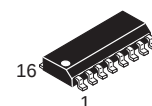
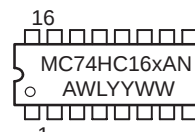
ON Semiconductor

<http://onsemi.com>

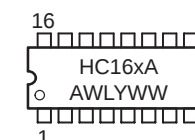
MARKING DIAGRAMS



PDIP-16
N SUFFIX
CASE 648



SO-16
D SUFFIX
CASE 751B

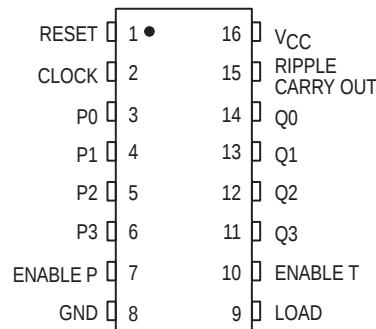


A = Assembly Location
WL = Wafer Lot
YY = Year
WW = Work Week

ORDERING INFORMATION

Device	Package	Shipping
MC74HC16xAN	PDIP-16	2000 / Box
MC74HC16xAD	SOIC-16	48 / Rail
MC74HC16xADR2	SOIC-16	2500 / Reel

PIN ASSIGNMENT



FUNCTION TABLE

Inputs					Output Q
Clock	Reset*	Load	Enable P	Enable T	
	L	X	X	X	Reset
	H	L	X	X	Load Preset Data
	H	H	H	H	Count
	H	H	L	X	No Count
	H	H	X	L	No Count

*HC163A only. HC161A is an Asynchronous Reset Device
H = high level, L = low level, X = don't care

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MAXIMUM RATINGS*

Symbol	Parameter	Value	Unit
V _{CC}	DC Supply Voltage (Referenced to GND)	– 0.5 to + 7.0	V
V _{in}	DC Input Voltage (Referenced to GND)	– 0.5 to V _{CC} + 0.5	V
V _{out}	DC Output Voltage (Referenced to GND)	– 0.5 to V _{CC} + 0.5	V
I _{in}	DC Input Current, per Pin	± 20	mA
I _{out}	DC Output Current, per Pin	± 25	mA
I _{CC}	DC Supply Current, V _{CC} and GND Pins	± 50	mA
P _D	Power Dissipation in Still Air, Plastic DIP† SOIC Package†	750 500	mW
T _{stg}	Storage Temperature	– 65 to + 150	°C
T _L	Lead Temperature, 1 mm from Case for 10 Seconds (Plastic DIP or SOIC Package)	260	°C

This device contains protection circuitry to guard against damage due to high static voltages or electric fields. However, precautions must be taken to avoid applications of any voltage higher than maximum rated voltages to this high-impedance circuit. For proper operation, V_{in} and V_{out} should be constrained to the range GND ≤ (V_{in} or V_{out}) ≤ V_{CC}. Unused inputs must always be tied to an appropriate logic voltage level (e.g., either GND or V_{CC}). Unused outputs must be left open.

*Maximum Ratings are those values beyond which damage to the device may occur.

Functional operation should be restricted to the Recommended Operating Conditions.

†Derating — Plastic DIP: – 10 mW/°C from 65° to 125°C

SOIC Package: – 7 mW/°C from 65° to 125°C

For high frequency or heavy load considerations, see Chapter 2 of the ON Semiconductor High-Speed CMOS Data Book (DL129/D).

RECOMMENDED OPERATING CONDITIONS

Symbol	Parameter	Min	Max	Unit
V _{CC}	DC Supply Voltage (Referenced to GND)	2.0	6.0	V
V _{in} , V _{out}	DC Input Voltage, Output Voltage (Referenced to GND)	0	V _{CC}	V
T _A	Operating Temperature, All Package Types	– 55	+ 125	°C
t _r , t _f	Input Rise and Fall Time (Figure 1)	V _{CC} = 2.0 V 0 V _{CC} = 3.0 V 0 V _{CC} = 4.5 V 0 V _{CC} = 6.0 V 0	1000 600 500 400	ns

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DC ELECTRICAL CHARACTERISTICS (Voltages Referenced to GND)

Symbol	Parameter	Test Conditions	V _{CC} V	Guaranteed Limit			Unit
				– 55 to 25°C	≤ 85°C	≤ 125°C	
V _{IH}	Minimum High-Level Input Voltage	V _{out} = 0.1 V or V _{CC} – 0.1 V I _{out} ≤ 20 μA	2.0 3.0 4.5 6.0	1.5 2.1 3.15 4.2	1.5 2.1 3.15 4.2	1.5 2.1 3.15 4.2	V
V _{IL}	Maximum Low-Level Input Voltage	V _{out} = 0.1 V or V _{CC} – 0.1 V I _{out} ≤ 20 μA	2.0 3.0 4.5 6.0	0.5 0.9 1.35 1.8	0.5 0.9 1.35 1.8	0.5 0.9 1.35 1.8	V
V _{OH}	Minimum High-Level Output Voltage	V _{in} = V _{IH} or V _{IL} I _{out} ≤ 20 μA	2.0 4.5 6.0	1.9 4.4 5.9	1.9 4.4 5.9	1.9 4.4 5.9	V
		V _{in} = V _{IH} or V _{IL} I _{out} ≤ 3.6 mA	3.0	2.48	2.34	2.2	
		I _{out} ≤ 4.0 mA	4.5	3.98	3.84	3.7	
		I _{out} ≤ 5.2 mA	6.0	5.48	5.34	5.2	
V _{OL}	Maximum Low-Level Output Voltage	V _{in} = V _{IH} or V _{IL} I _{out} ≤ 20 μA	2.0 4.5 6.0	0.1 0.1 0.1	0.1 0.1 0.1	0.1 0.1 0.1	V
		V _{in} = V _{IH} or V _{IL} I _{out} ≤ 3.6 mA	3.0	0.26	0.33	0.4	
		I _{out} ≤ 4.0 mA	4.5	0.26	0.33	0.4	
		I _{out} ≤ 5.2 mA	6.0	0.26	0.33	0.4	
I _{in}	Maximum Input Leakage Current	V _{in} = V _{CC} or GND	6.0	± 0.1	± 1.0	± 1.0	μA
I _{CC}	Maximum Quiescent Supply Current (per Package)	V _{in} = V _{CC} or GND I _{out} = 0 μA	6.0	4.0	40	160	μA

NOTE: Information on typical parametric values can be found in Chapter 2 of the ON Semiconductor High-Speed CMOS Data Book (DL129/D).

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AC ELECTRICAL CHARACTERISTICS (C_L = 50 pF, Input t_r = t_f = 6.0 ns)

Symbol	Parameter	Fig.	V _{CC} V	Guaranteed Limit			Unit
				– 55 to 25°C	≤ 85°C	≤ 125°C	
f _{max}	Maximum Clock Frequency (50% Duty Cycle)*	1, 7	2.0 3.0 4.5 6.0	6 15 30 35	5 12 24 28	4 10 20 24	MHz
t _{PLH}	Maximum Propagation Delay, Clock to Q	1, 7	2.0 3.0 4.5 6.0	120 75 20 16	160 120 23 20	200 150 28 22	ns
t _{PHL}			2.0 3.0 4.5 6.0	145 100 22 18	185 135 25 20	220 150 30 23	ns
t _{PHL}	Maximum Propagation Delay, Reset to Q (HC161A Only)	2, 7	2.0 3.0 4.5 6.0	145 100 20 17	185 135 22 19	220 150 25 21	ns
t _{PLH}	Maximum Propagation Delay, Enable T to Ripple Carry Out	3, 7	2.0 3.0 4.5 6.0	110 60 16 14	150 115 18 15	190 140 20 17	ns
t _{PHL}			2.0 3.0 4.5 6.0	135 100 18 15	175 130 20 16	210 160 22 20	ns
t _{PLH}	Maximum Propagation Delay, Clock to Ripple Carry Out	1, 7	2.0 3.0 4.5 6.0	120 75 22 18	160 135 27 22	200 150 30 25	ns
t _{PHL}			2.0 3.0 4.5 6.0	145 100 22 20	185 135 28 24	220 150 35 28	ns
t _{PHL}	Maximum Propagation Delay, Reset to Ripple Carry Out (HC161A Only)	2, 7	2.0 3.0 4.5 6.0	155 120 22 18	190 140 26 22	230 155 30 25	ns
t _{TLH} , t _{THL}	Maximum Output Transition Time, Any Output	2, 7	2.0 3.0 4.5 6.0	75 30 15 13	95 40 19 16	110 55 22 19	ns
C _{in}	Maximum Input Capacitance	1, 7	—	10	10	10	pF

*Applies to noncascaded/nonsynchronous clocked configurations only with synchronously cascaded counters. (1) Clock to Ripple Carry Out propagation delays. (2) Enable T or Enable P to Clock setup times and (3) Clock to Enable T or Enable P hold times determine f_{max}. However, if Ripple Carry out of each stage is tied to the Clock of the next stage (nonsynchronously clocked) the f_{max} in the table above is applicable. See Applications information in this data sheet.

NOTE: For propagation delays with loads other than 50 pF, and information on typical parametric values, see Chapter 2 of the ON Semiconductor High-Speed CMOS Data Book (DL129/D).

C _{PD}	Power Dissipation Capacitance (Per Gate)*	Typical @ 25°C, V _{CC} = 5.0 V	
		45	pF

* Used to determine the no-load dynamic power consumption: P_D = C_{PD} V_{CC}² f + I_{CC} V_{CC}. For load considerations, see Chapter 2 of the ON Semiconductor High-Speed CMOS Data Book (DL129/D).

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TIMING REQUIREMENTS ($C_L = 50$ pF, Input $t_r = t_f = 6.0$ ns)

Symbol	Parameter	Fig.	V _{CC} V	Guaranteed Limit			Unit
				– 55 to 25°C	≤ 85°C	≤ 125°C	
t _{su}	Minimum Setup Time, Preset Data Inputs to Clock	5	2.0	40	60	80	ns
			3.0	20	30	40	
			4.5	15	20	30	
			6.0	12	18	20	
t _{su}	Minimum Setup Time, Load to Clock	5	2.0	60	75	90	ns
			3.0	25	30	40	
			4.5	15	20	30	
			6.0	12	18	20	
t _{su}	Minimum Setup Time, Reset to Clock (HC163A Only)	4	2.0	60	75	90	ns
			3.0	25	30	40	
			4.5	20	25	35	
			6.0	17	23	25	
t _{su}	Minimum Setup Time, Enable T or Enable P to Clock	6	2.0	80	95	110	ns
			3.0	35	40	50	
			4.5	20	25	35	
			6.0	17	23	25	
t _h	Minimum Hold Time, Clock to Load or Preset Data Inputs	5	2.0	3	3	3	ns
			3.0	3	3	3	
			4.5	3	3	3	
			6.0	3	3	3	
t _h	Minimum Hold Time, Clock to Reset (HC163A Only)	4	2.0	3	3	3	ns
			3.0	3	3	3	
			4.5	3	3	3	
			6.0	3	3	3	
t _h	Minimum Hold Time, Clock to Enable T or Enable P	6	2.0	3	3	3	ns
			3.0	3	3	3	
			4.5	3	3	3	
			6.0	3	3	3	
t _{rec}	Minimum Recovery Time, Reset Inactive to Clock (HC161A Only)	2	2.0	80	95	110	ns
			3.0	35	40	50	
			4.5	15	20	26	
			6.0	12	17	23	
t _{rec}	Minimum Recovery Time, Load Inactive to Clock	5	2.0	80	95	110	ns
			3.0	35	40	50	
			4.5	15	20	26	
			6.0	12	17	23	
t _w	Minimum Pulse Width, Clock	1	2.0	60	75	90	ns
			3.0	25	30	40	
			4.5	12	15	18	
			6.0	10	13	15	
t _w	Minimum Pulse Width, Reset (HC161A Only)	2	2.0	60	75	90	ns
			3.0	25	30	40	
			4.5	12	15	18	
			6.0	10	13	15	
t _r , t _f	Maximum Input Rise and Fall Times		2.0	1000	1000	1000	ns
			3.0	800	800	800	
			4.5	500	500	500	
			6.0	400	400	400	

FUNCTION DESCRIPTION

The HC161A/163A are programmable 4-bit synchronous counters that feature parallel Load, synchronous or asynchronous Reset, a Carry Output for cascading and count-enable controls.

The HC161A and HC163A are binary counters with asynchronous Reset and synchronous Reset, respectively.

INPUTS

Clock (Pin 2)

The internal flip-flops toggle and the output count advances with the rising edge of the Clock input. In addition, control functions, such as resetting and loading occur with the rising edge of the Clock input.

Preset Data Inputs P0, P1, P2, P3 (Pins 3, 4, 5, 6)

These are the data inputs for programmable counting. Data on these pins may be synchronously loaded into the internal flip-flops and appear at the counter outputs. P0 (Pin 3) is the least-significant bit and P3 (Pin 6) is the most-significant bit.

OUTPUTS

Q0, Q1, Q2, Q3 (Pins 14, 13, 12, 11)

These are the counter outputs. Q0 (Pin 14) is the least-significant bit and Q3 (Pin 11) is the most-significant bit.

Ripple Carry Out (Pin 15)

When the counter is in its maximum state 1111, this output goes high, providing an external look-ahead carry pulse that may be used to enable successive cascaded counters. Ripple Carry Out remains high only during the maximum count state. The logic equation for this output is:

$$\text{Ripple Carry Out} = \text{Enable T} \bullet \text{Q0} \bullet \text{Q1} \bullet \text{Q2} \bullet \text{Q3}$$

CONTROL FUNCTIONS

Resetting

A low level on the Reset pin (Pin 1) resets the internal flip-flops and sets the outputs (Q0 through Q3) to a low

level. The HC161A resets asynchronously, and the HC163A resets with the rising edge of the Clock input (synchronous reset).

Loading

With the rising edge of the Clock, a low level on Load (Pin 9) loads the data from the Preset Data input pins (P0, P1, P2, P3) into the internal flip-flops and onto the output pins, Q0 through Q3. The count function is disabled as long as Load is low.

Count Enable/Disable

These devices have two count-enable control pins: Enable P (Pin 7) and Enable T (Pin 10). The devices count when these two pins and the Load pin are high. The logic equation is:

$$\text{Count Enable} = \text{Enable P} \bullet \text{Enable T} \bullet \text{Load}$$

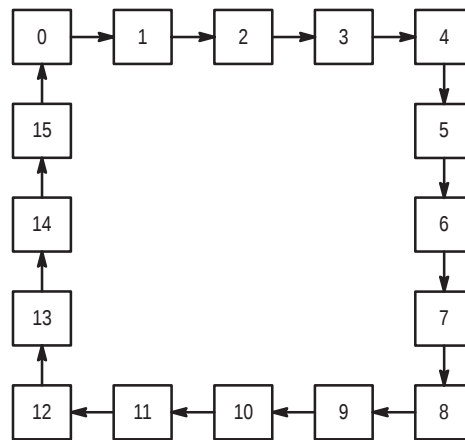
The count is either enabled or disabled by the control inputs according to Table 1. In general, Enable P is a count-enable control: Enable T is both a count-enable and a Ripple-Carry Output control.

Table 1. Count Enable/Disable

Control Inputs			Result at Outputs	
Load	Enable P	Enable T	Q0 – Q3	Ripple Carry Out
H	H	H	Count	High when Q0–Q3 are maximum*
L	H	H	No Count	
X	L	H	No Count	High when Q0–Q3 are maximum*
X	X	L	No Count	L

*Q0 through Q3 are maximum when Q3 Q2 Q1 Q0 = 1111.

OUTPUT STATE DIAGRAMS



Binary Counters

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SWITCHING WAVEFORMS

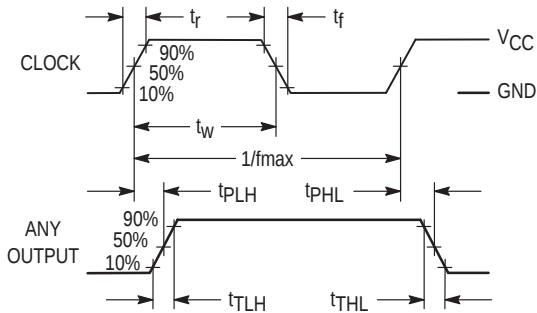


Figure 1.

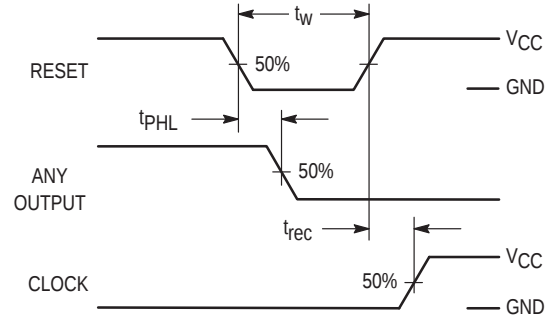


Figure 2.

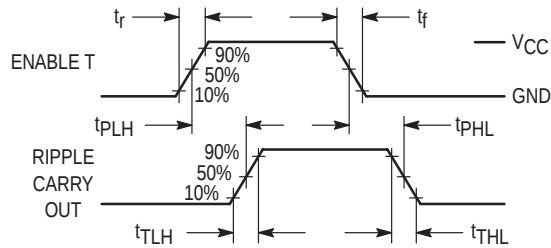


Figure 3.

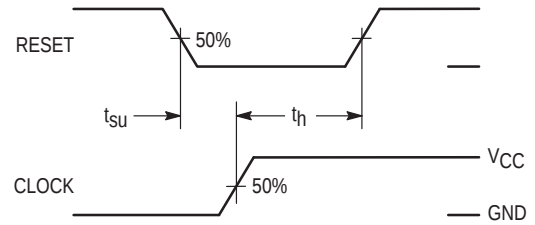


Figure 4. HC163A Only

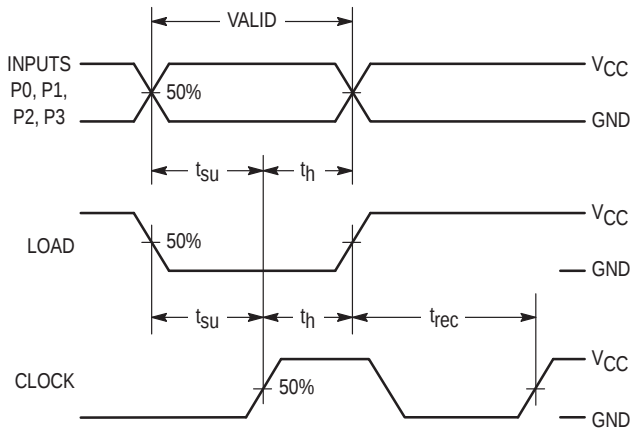


Figure 5.

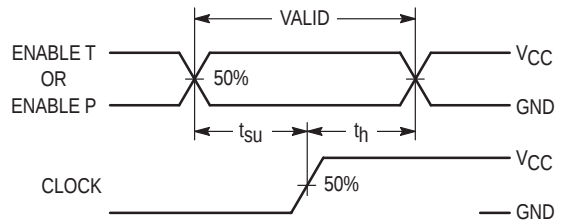
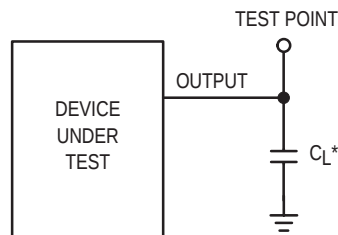


Figure 6.

TEST CIRCUIT



*Includes all probe and jig capacitance

Figure 7.

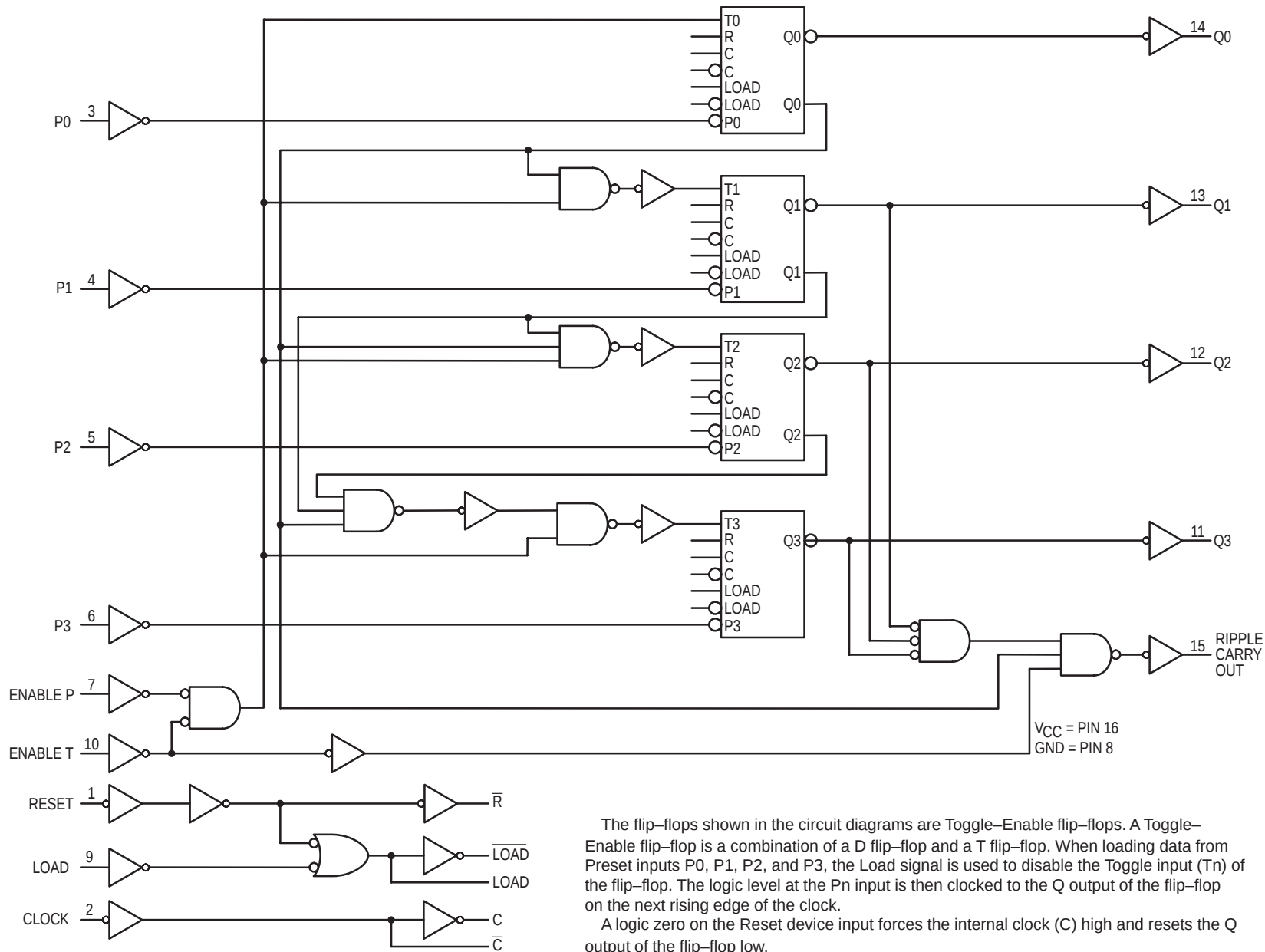


Figure 8. 4-Bit Binary Counter with Asynchronous Reset (MC74HC161A)

The flip-flops shown in the circuit diagrams are Toggle-Enable flip-flops. A Toggle-Enable flip-flop is a combination of a D flip-flop and a T flip-flop. When loading data from Preset inputs P0, P1, P2, and P3, the Load signal is used to disable the Toggle input (Tn) of the flip-flop. The logic level at the Pn input is then clocked to the Q output of the flip-flop on the next rising edge of the clock.

A logic zero on the Reset device input forces the internal clock (C) high and resets the Q output of the flip-flop low.

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Sequence illustrated in waveforms:

1. Reset outputs to zero.
2. Preset to binary twelve.
3. Count to thirteen, fourteen, fifteen, zero, one and two.
4. Inhibit.

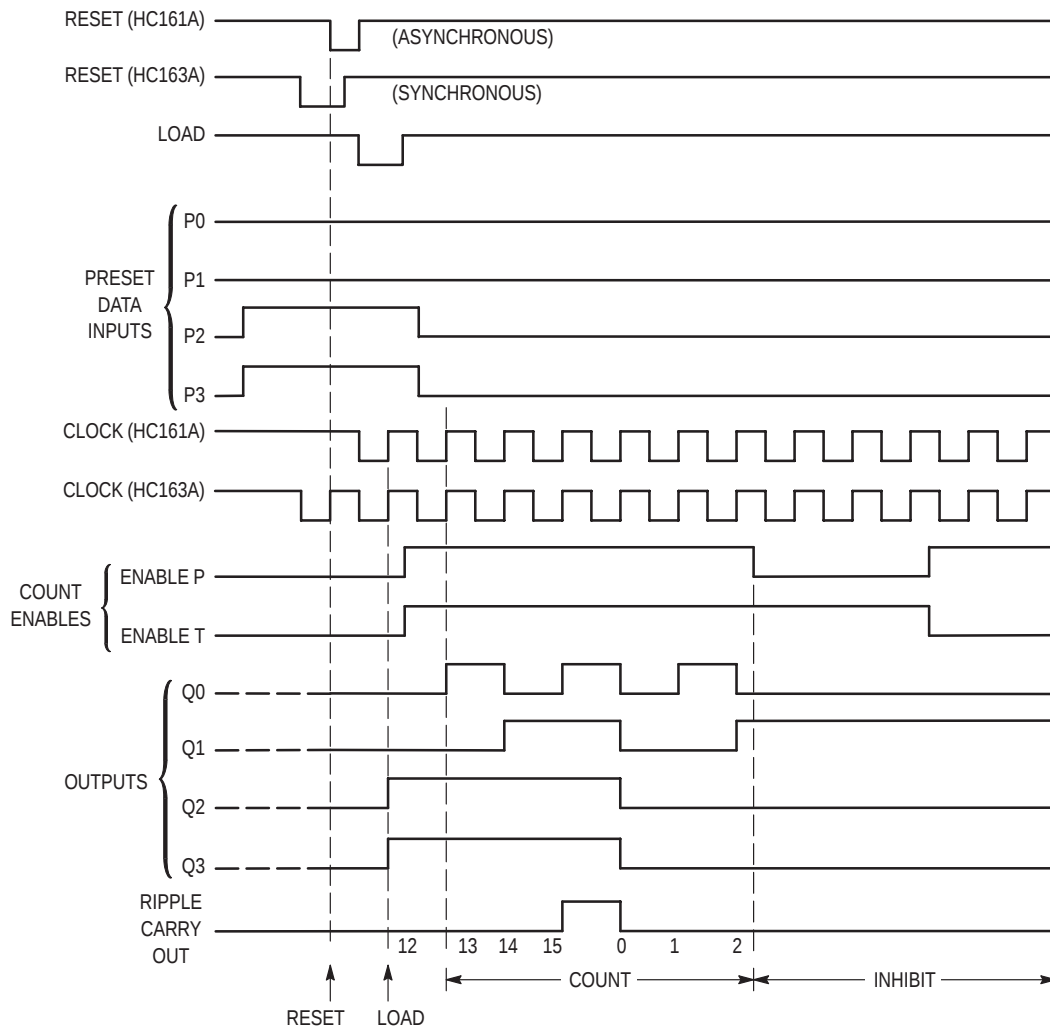


Figure 9. Timing Diagram

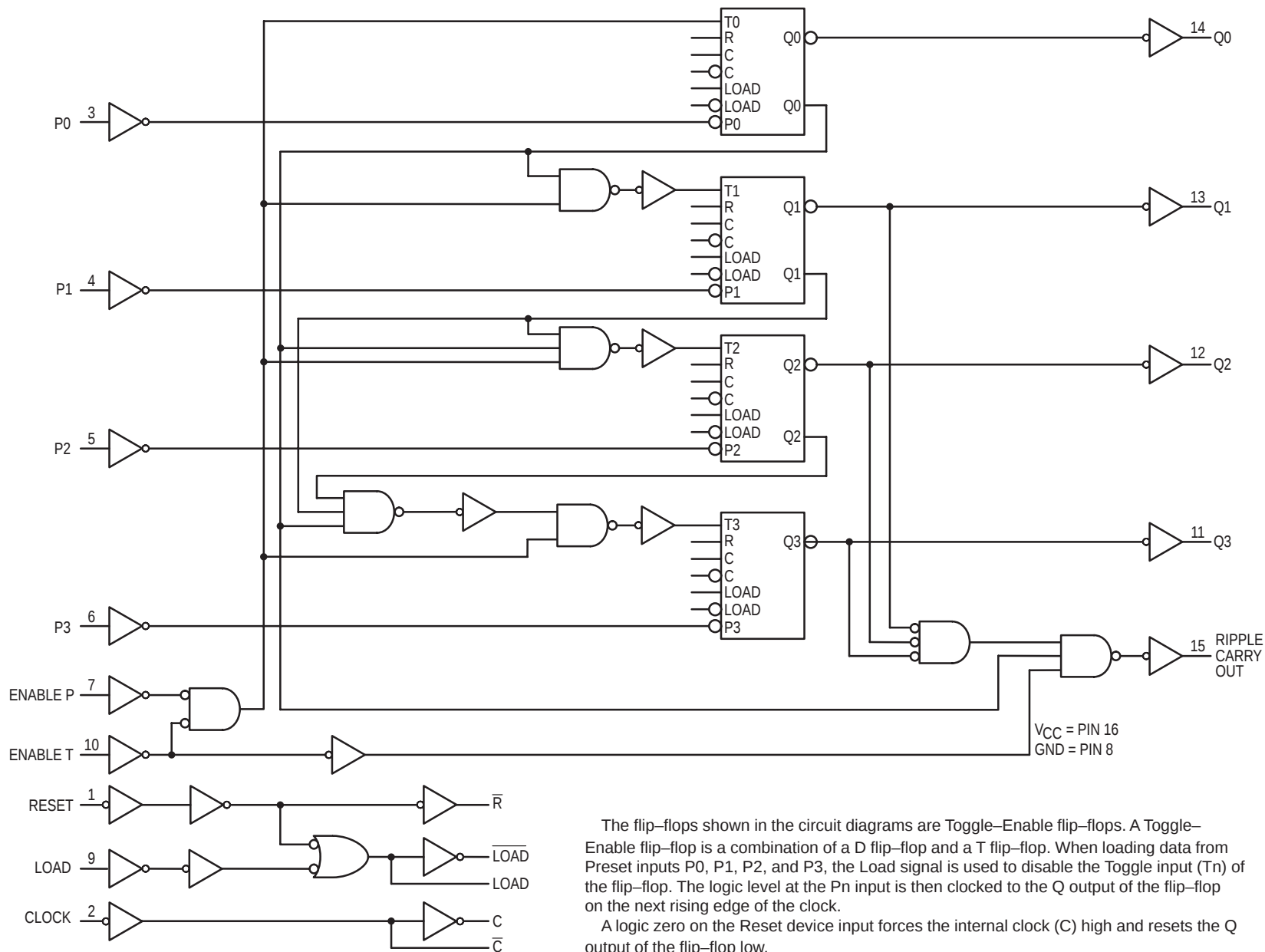


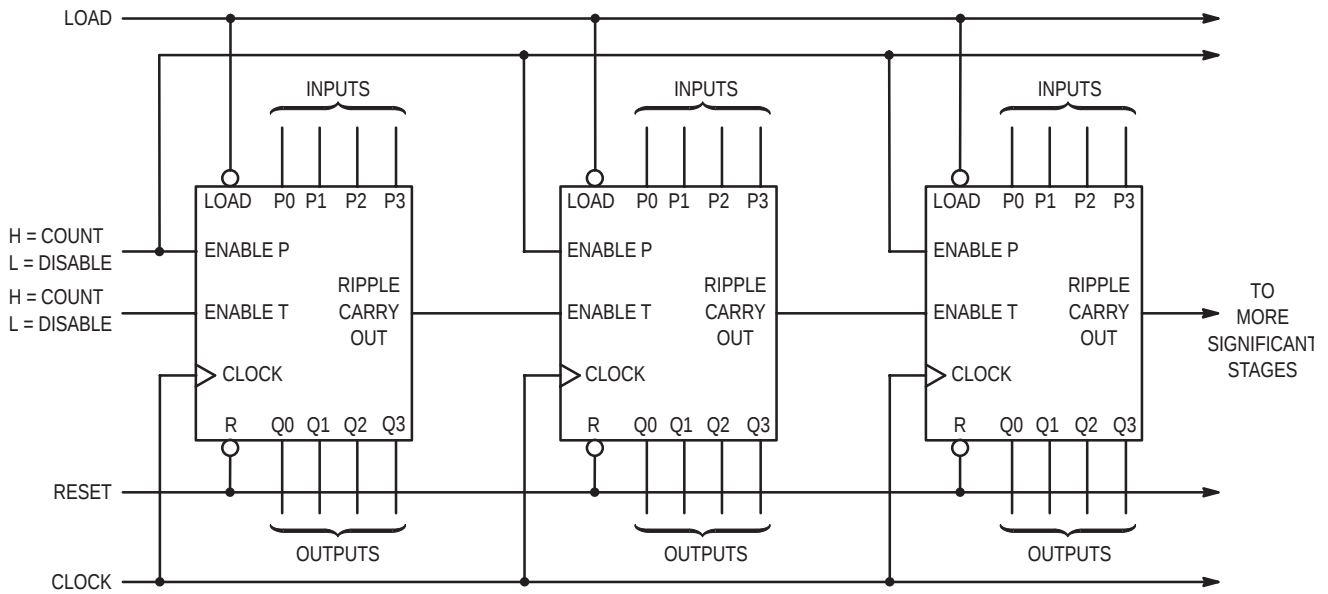
Figure 10. 4-Bit Binary Counter with Synchronous Reset (MC74HC163A)

The flip-flops shown in the circuit diagrams are Toggle-Enable flip-flops. A Toggle-Enable flip-flop is a combination of a D flip-flop and a T flip-flop. When loading data from Preset inputs P0, P1, P2, and P3, the Load signal is used to disable the Toggle input (Tn) of the flip-flop. The logic level at the Pn input is then clocked to the Q output of the flip-flop on the next rising edge of the clock.

A logic zero on the Reset device input forces the internal clock (C) high and resets the Q output of the flip-flop low.

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TYPICAL APPLICATIONS CASCADING



NOTE: When used in these cascaded configurations the clock f_{max} guaranteed limits may not apply. Actual performance will depend on number of stages. This limitation is due to set up times between Enable (Port) and Clock.

Figure 11. N-Bit Synchronous Counters

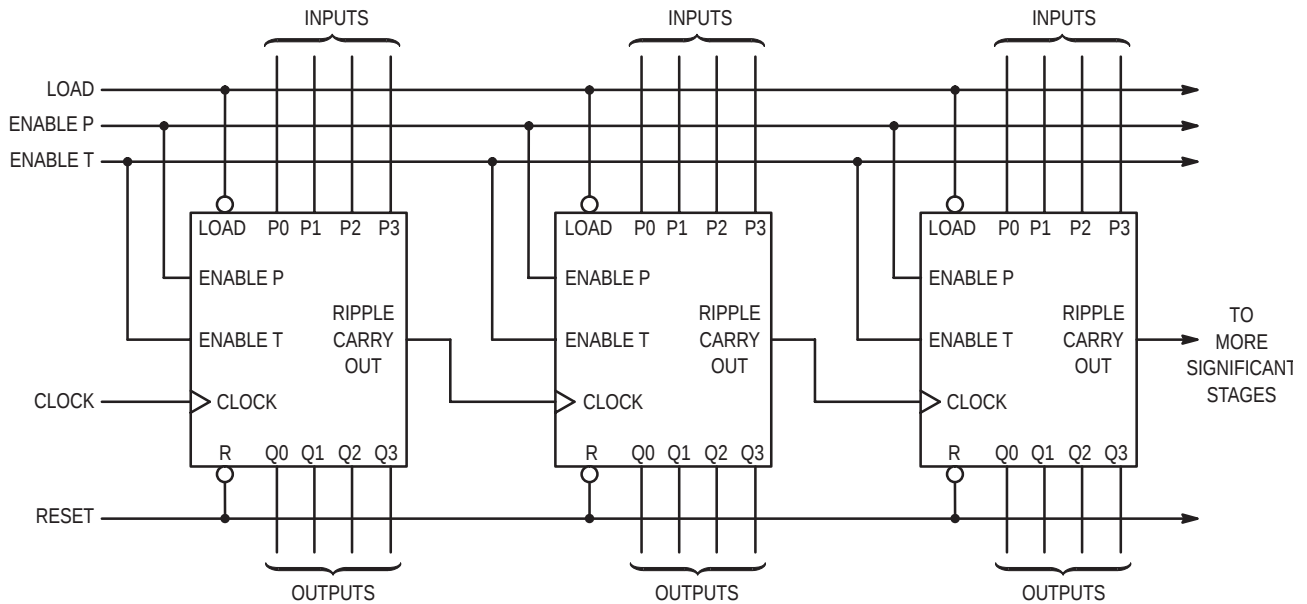


Figure 12. Nibble Ripple Counter

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TYPICAL APPLICATIONS VARYING THE MODULUS

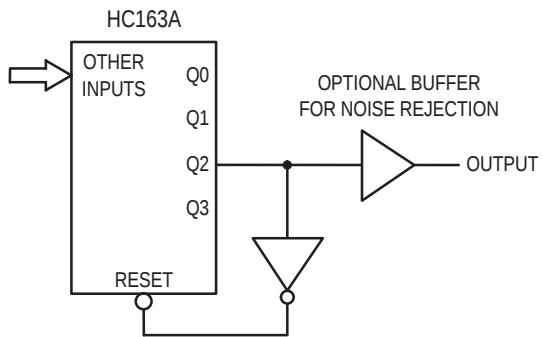


Figure 13. Modulo-5 Counter

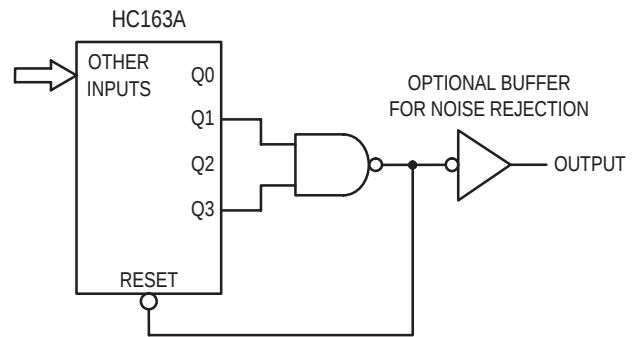


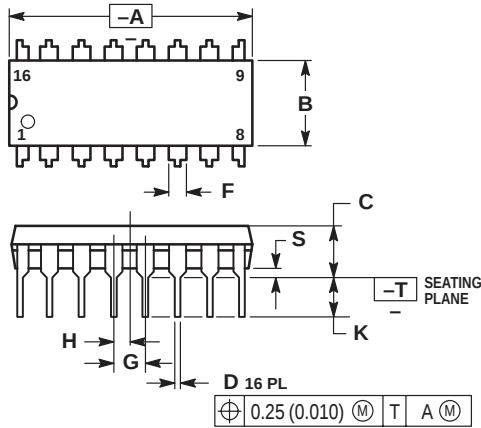
Figure 14. Modulo-11 Counter

The HC163A facilitates designing counters of any modulus with minimal external logic. The output is glitch-free due to the synchronous Reset.

MC74HC161A, MC74HC163A

PACKAGE DIMENSIONS

PDIP-16
N SUFFIX
CASE 648-08
ISSUE R

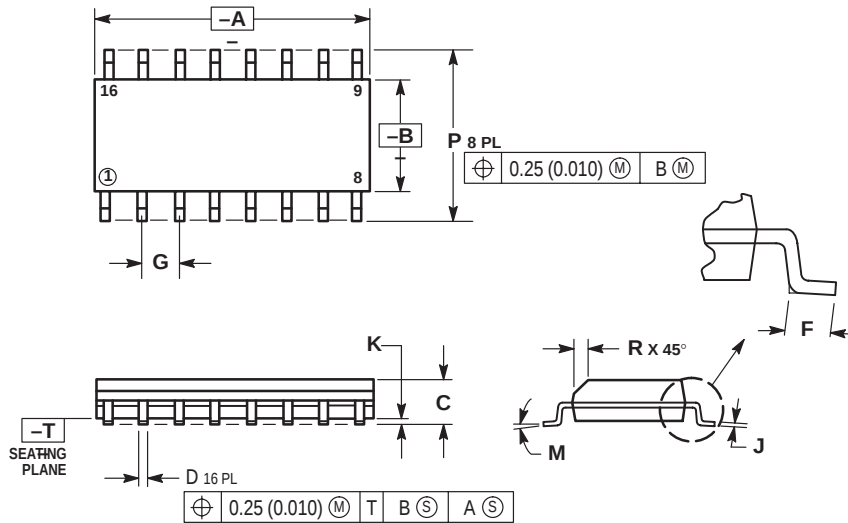


NOTES:

1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: INCH.
3. DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL.
4. DIMENSION B DOES NOT INCLUDE MOLD FLASH.
5. ROUNDED CORNERS OPTIONAL.

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	0.740	0.770	18.80	19.55
B	0.250	0.270	6.35	6.85
C	0.145	0.175	3.69	4.44
D	0.015	0.021	0.39	0.53
F	0.040	0.070	1.02	1.77
G	0.100 BSC		2.54 BSC	
H	0.050 BSC		1.27 BSC	
J	0.008	0.015	0.21	0.38
K	0.110	0.130	2.80	3.30
L	0.295	0.305	7.50	7.74
M	0°	10°	0°	10°
S	0.020	0.040	0.51	1.01

SOIC-16
D SUFFIX
CASE 751B-05
ISSUE J



NOTES:

1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: MILLIMETER.
3. DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION.
4. MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.
5. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	9.80	10.00	0.386	0.393
B	3.80	4.00	0.150	0.157
C	1.35	1.75	0.054	0.068
D	0.35	0.49	0.014	0.019
F	0.40	1.25	0.016	0.049
G	1.27 BSC		0.050 BSC	
J	0.19	0.25	0.008	0.009
K	0.10	0.25	0.004	0.009
M	0°	7°	0°	7°
P	5.80	6.20	0.229	0.244
R	0.25	0.50	0.010	0.019

Notes

Notes

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