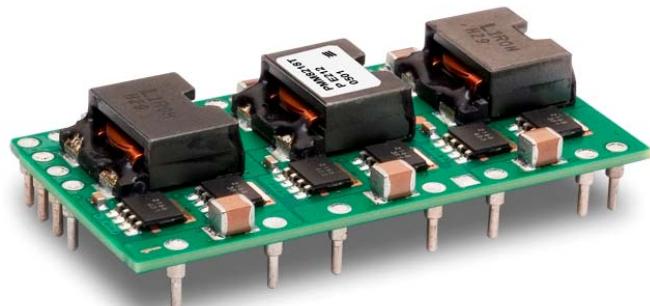


PMM 4000 series POL regulator, Input 2.95-5.5 V, Output 60 A/150 W	EN/LZT 146 337 R1A April 2006 © Ericsson Power Modules AB
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**Key Features**

- 60A output current
- 2.95 -5.5 V input voltage range
- Output voltages from 0.8V up to 2.5V
- Industry standard POLA™ compatible
- 52 x 26.7 x 9.07 mm (2.05 x 1.05 x 0.357 in.)
- High efficiency, up to. 93%
- Auto Track™ sequencing pin
- Differential output voltage sense
- More than 1.12 million hours MTBF

**General Characteristics**

- Operating temperature: -40°C to 85 °C
- Start up into a pre-biased output safe
- Output short-circuit protection
- Over temperature protection
- On/Off inhibit control
- Margin up/down control
- Highly automated manufacturing ensures quality
- ISO 9001/14001 certified supplier

**Safety Approvals****Design for Environment**

Meets requirements in high-temperature lead-free soldering processes.

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PMM 4000 series POL regulator, Input 2.95-5.5 V, Output 60 A/150 W	EN/LZT 146 337 R1A April 2006 © Ericsson Power Modules AB
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## General Information

### Ordering Information

See Contents for individual product ordering numbers.

Option	Suffix	Ordering No.
Through hole pin	P	PMM 4218T WP
SMD pin	S	PMM 4218T WS
SMD pin, leadfree reflow temperature capable	R	PMM 4218T WSR

### Reliability

The Mean Time Between Failure (MTBF) is calculated at full output power and an operating ambient temperature ( $T_A$ ) of +40°C, which is a typical condition in Information and Communication Technology (ICT) equipment. Different methods could be used to calculate the predicted MTBF and failure rate which may give different results. Ericsson Power Modules currently uses Telcordia SR332.

Predicted MTBF for the series is:

- 1.12 million hours according to Telcordia SR332, issue 1, Black box technique.

Telcordia SR332 is a commonly used standard method intended for reliability calculations in ICT equipment. The parts count procedure used in this method was originally modelled on the methods from MIL-HDBK-217F, Reliability Predictions of Electronic Equipment. It assumes that no reliability data is available on the actual units and devices for which the predictions are to be made, i.e. all predictions are based on generic reliability parameters.

### Compatibility with RoHS requirements

The products are compatible with the relevant clauses and requirements of the RoHS directive 2002/95/EC and have a maximum concentration value of 0.1% by weight in homogeneous materials for lead in other applications other than lead in solder, lead in high melting temperature type solder, lead in glass of electronics components, lead in electronic ceramic parts and lead as an alloying element in copper containing up to 4% lead by weight, mercury, hexavalent chromium, PBB and PBDE and of 0.01% by weight in homogeneous materials for cadmium.

Exemptions in the RoHS directive utilized in the products:

- Lead as an alloying element in copper alloy containing up to 4% lead by weight (used in connection pins made of Brass)
- Lead in high melting temperature type solder (used to solder the die in semiconductor packages)
- Lead in glass of electronics components and in electronic ceramic parts (e.g. fill material in chip resistors)
- Lead in solder for servers, storage and storage array systems, network infrastructure equipment for switching, signaling, transmission as well as network management for telecommunication  
(Note: the products are manufactured in lead-free soldering processes and the lead present in the solder is only located in the terminal plating finishes on some components)

### Quality Statement

The products are designed and manufactured in an industrial environment where quality systems and methods like ISO 9000, 6σ (sigma), and SPC are intensively in use to boost the continuous improvements strategy. Infant mortality or early failures in the products are screened out and they are subjected to an ATE-based final test. Conservative design rules, design reviews and product qualifications, plus the high competence of an engaged work force, contribute to the high quality of our products.

### Warranty

Warranty period and conditions are defined in Ericsson Power Modules General Terms and Conditions of Sale.

### Limitation of Liability

Ericsson Power Modules does not make any other warranties, expressed or implied including any warranty of merchantability or fitness for a particular purpose (including, but not limited to, use in life support applications, where malfunctions of product can cause injury to a person's health or life).

PMM 4000 series POL regulator, Input 2.95-5.5 V, Output 60 A/150 W	EN/LZT 146 337 R1A April 2006 © Ericsson Power Modules AB
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## Safety Specification

### General information

Ericsson Power Modules DC/DC converters and DC/DC regulators are designed in accordance with safety standards IEC/EN/UL60950, *Safety of Information Technology Equipment*.

IEC/EN/UL60950 contains requirements to prevent injury or damage due to the following hazards:

- Electrical shock
- Energy hazards
- Fire
- Mechanical and heat hazards
- Radiation hazards
- Chemical hazards

On-board DC-DC converters are defined as component power supplies. As components they cannot fully comply with the provisions of any Safety requirements without "Conditions of Acceptability". It is the responsibility of the installer to ensure that the final product housing these components complies with the requirements of all applicable Safety standards and Directives for the final product.

Component power supplies for general use should comply with the requirements in IEC60950, EN60950 and UL60950 "Safety of information technology equipment".

There are other more product related standards, e.g. IEEE802.3af "Ethernet LAN/MAN Data terminal equipment power", and ETS300132-2 "Power supply interface at the input to telecommunications equipment; part 2: DC", but all of these standards are based on IEC/EN/UL60950 with regards to safety.

Ericsson Power Modules DC/DC converters and DC/DC regulators are UL60950 recognized and certified in accordance with EN60950.

The flammability rating for all construction parts of the products meets requirements for V-0 class material according to IEC 60695-11-10.

The products should be installed in the end-use equipment, in accordance with the requirements of the ultimate application. Normally the output of the DC/DC converter is considered as SELV (Safety Extra Low Voltage) and the input source must be isolated by minimum Double or Reinforced Insulation from the primary circuit (AC mains) in accordance with IEC/EN/UL60950.

### Isolated DC/DC converters

It is recommended that a slow blow fuse with a rating twice the maximum input current per selected product be used at the input of each DC/DC converter. If an input filter is used in the circuit the fuse should be placed in front of the input filter.

In the rare event of a component problem in the input filter or in the DC/DC converter that imposes a short circuit on the input source, this fuse will provide the following functions:

- Isolate the faulty DC/DC converter from the input power source so as not to affect the operation of other parts of the system.
- Protect the distribution wiring from excessive current and power loss thus preventing hazardous overheating.

The galvanic isolation is verified in an electric strength test. The test voltage ( $V_{iso}$ ) between input and output is 1500 Vdc or 2250 Vdc for 60 seconds (refer to product specification).

Leakage current is less than 1  $\mu$ A at nominal input voltage.

### 24 V DC systems

The input voltage to the DC/DC converter is SELV (Safety Extra Low Voltage) and the output remains SELV under normal and abnormal operating conditions.

### 48 and 60 V DC systems

If the input voltage to Ericsson Power Modules DC/DC converter is 75 Vdc or less, then the output remains SELV (Safety Extra Low Voltage) under normal and abnormal operating conditions.

Single fault testing in the input power supply circuit should be performed with the DC/DC converter connected to demonstrate that the input voltage does not exceed 75 Vdc.

If the input power source circuit is a DC power system, the source may be treated as a TINV2 circuit and testing has demonstrated compliance with SELV limits and isolation requirements equivalent to Basic Insulation in accordance with IEC/EN/UL60950.

### Non-isolated DC/DC regulators

The input voltage to the DC/DC regulator is SELV (Safety Extra Low Voltage) and the output remains SELV under normal and abnormal operating conditions.

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POL regulator, Input 2.95-5.5 V, Output 60 A/150 W	© Ericsson Power Modules AB

### Absolute Maximum Ratings

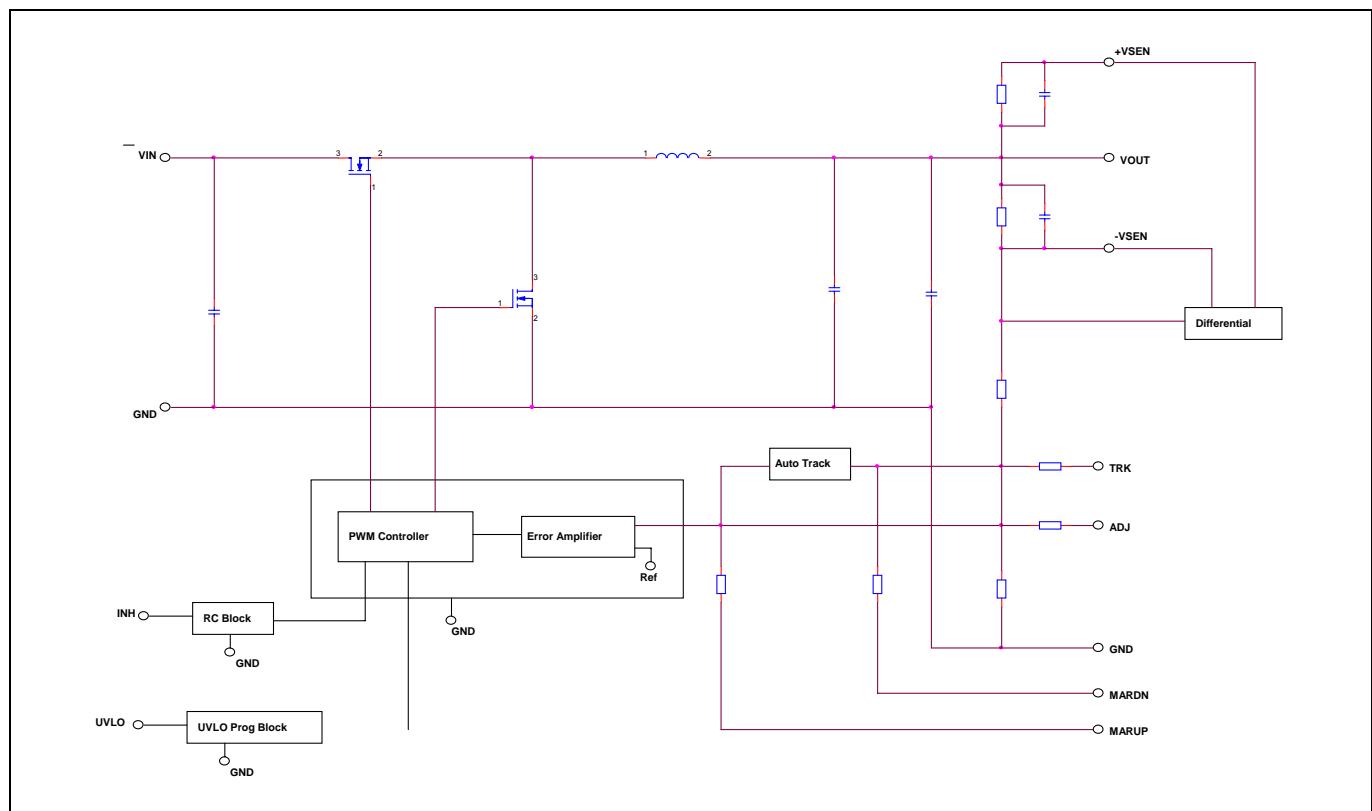
Characteristics		min	typ	max	Unit
$T_{amb}$	Operating Temperature (see Thermal Consideration section)	-40		85	°C
$T_s$	Storage temperature	-40		125	°C
$V_i$	Input voltage	2.95	3.3	4.5 <sup>(1)</sup>	V
		4.5	5.0	5.5 <sup>(2)</sup>	
$V_{inh}$	Inhibit On/Off pin voltage (see Operating Information section)	Positive logic option	2.5	Open	V
		Negative logic option	N/A	N/A	V

Stress in excess of Absolute Maximum Ratings may cause permanent damage. Absolute Maximum Ratings, sometimes referred to as no destruction limits, are normally tested with one parameter at a time exceeding the limits of Output data or Electrical Characteristics. If exposed to stress above these limits, function and performance may degrade in an unspecified manner.

Note 1: For input voltage between 2.95-4.5 V, the output adjust range is limited to 0.8-1.65 V.

Note 2: For input voltage between 4.5-5.5 V, the output adjust range is limited to 0.8-2.5 V.

### Fundamental Circuit Diagram



PMM 4000 series POL regulator, Input 2.95-5.5 V, Output 60 A/150 W	EN/LZT 146 337 R1A April 2006 © Ericsson Power Modules AB
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## 1.0 V/60 A Electrical Specification

PMM 4218T

 $T_{ref} = -40$  to  $+85^\circ\text{C}$ ,  $V_i = 2.95$  to  $5.5$  V,  $R_{adj} = 36.5$  k $\Omega$ , unless otherwise specified under Conditions.Typical values given at:  $T_{ref} = +25^\circ\text{C}$ ,  $V_i = 3.3/5.0$  V, max  $I_o$ , unless otherwise specified under Conditions.Additional  $C_{in} = 1000\mu\text{F}$  and  $C_{out} = 660\mu\text{F}$ . See Operating Information section for selection of capacitor types.

Connect the sense pin, where available, to the output pin.

Characteristics		Conditions	min	typ	max	Unit	
$V_i$	Input voltage range		2.95		5.5	V	
UVLO	Undervoltage lockout	Pin 8 open	On-threshold	2.6		V	
			Hysteresis	0.6			
$C_i$	Internal input capacitance			180		$\mu\text{F}$	
$P_o$	Output power		0		60	W	
$\eta$	Efficiency	$V_i = 3.3$ V	50 % of max $I_o$	89.5		%	
			max $I_o$	84.9			
		$V_i = 5.0$ V	50 % of max $I_o$	86.0			
			max $I_o$	83.4			
$P_d$	Power Dissipation	$V_i = 3.3$ V, max $I_o$		10.7		W	
		$V_i = 5.0$ V, max $I_o$		11.9			
$P_{il}$	Input idling power	$I_o = 0$ , $V_i = 3.3$ V		840		mW	
		$I_o = 0$ , $V_i = 5.0$ V		930			
$P_{inh}$	Input standby power	$V_i = 3.3$ V (turned off with INHIBIT)		198		mW	
		$V_i = 5.0$ V (turned off with INHIBIT)		300			
$I_s$	Static Input current	$V_i = 3.3$ V, max $I_o$		21.6		A	
		$V_i = 5.0$ V, max $I_o$		14.5			
$f_s$	Switching frequency	0-100 % of max $I_o$	675	825	975	kHz	

$V_{oi}$	Output voltage initial setting and accuracy	$T_{ref} = +25^\circ\text{C}$ , $V_i = 5.0$ V, max $I_o$	0.980	1.000	1.020	V
$V_o$	Output voltage tolerance band	10-100 % of max $I_o$	0.970		1.030	V
	Idling voltage	$I_o = 0$ , $V_i = 3.3$ V		1.005		V
		$I_o = 0$ , $V_i = 5.0$ V		1.005		
	Line regulation	max $I_o$		$\pm 5$		mV
$V_{tr}$	Load transient voltage deviation	$V_i = 3.3$ V, Load step 50-100-50 % of max $I_o$ , $di/dt = 1$ A/ $\mu\text{s}$ , see Note 1		$\pm 80$		mV
		$V_i = 5.0$ V, Load step 50-100-50 % of max $I_o$ , $di/dt = 1$ A/ $\mu\text{s}$ , see Note 1		$\pm 50$		
	Load transient recovery time	$V_i = 3.3$ V, Load step 50-100-50 % of max $I_o$ , $di/dt = 1$ A/ $\mu\text{s}$ , see Note 1		160		$\mu\text{s}$
		$V_i = 5.0$ V, Load step 50-100-50 % of max $I_o$ , $di/dt = 1$ A/ $\mu\text{s}$ , see Note 1		150		
$t_r$	Ramp-up time (from 10..90 % of $V_o$ )	$V_i = 3.3$ V, max $I_o$		3.3		ms
		$V_i = 5.0$ V, max $I_o$		3.4		
$t_s$	Start-up time (from $V_i$ connection to 90 % of $V_o$ )	$V_i = 3.3$ V, max $I_o$		9.0		ms
		$V_i = 5.0$ V, max $I_o$		8.8		

PMM 4000 series POL regulator, Input 2.95-5.5 V, Output 60 A/150 W			EN/LZT 146 337 R1A April 2006
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Characteristics		Conditions	min	typ	max	Unit	
$t_f$	Ramp-down time (from 90. 10 % of $V_o$ )	$V_i = 3.3 \text{ V}$	Max $I_o$	180		$\mu\text{s}$	
			$I_o = 0.1 \text{ A}$	24.6		ms	
	INHIBIT shutdown fall time (From INHIBIT off to 10 % of $V_o$ )	$V_i = 5.0 \text{ V}$	Max $I_o$	150		$\mu\text{s}$	
			$I_o = 0.1 \text{ A}$	21.2		ms	
$T_{inh}$	INHIBIT start-up time		$V_i = 3.3 \text{ V}, \text{Max } I_o$	6.7		ms	
			$V_i = 5.0 \text{ V}, \text{Max } I_o$	6.7			
	INHIBIT shutdown fall time (From INHIBIT off to 10 % of $V_o$ )	$V_i = 3.3 \text{ V}$	Max $I_o$	30		$\mu\text{s}$	
			$I_o = 0.1 \text{ A}$	6.5		ms	
		$V_i = 5.0 \text{ V}$	Max $I_o$	30		$\mu\text{s}$	
			$I_o = 0.1 \text{ A}$	6.6		ms	
$I_o$	Output current		0		60	A	
$I_{lim}$	Current limit threshold		$T_{ref} < \text{max } T_{ref}$	90		A	
$V_{Oac}$	Output ripple & noise		See ripple & noise section, max $I_o, V_{oi}$	15		mVp-p	

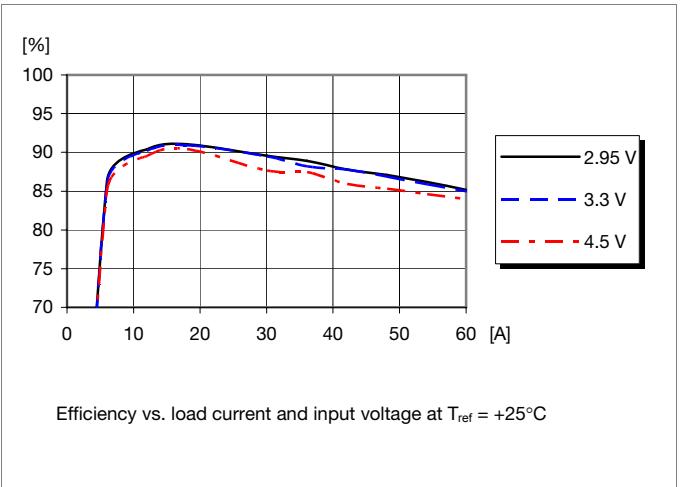
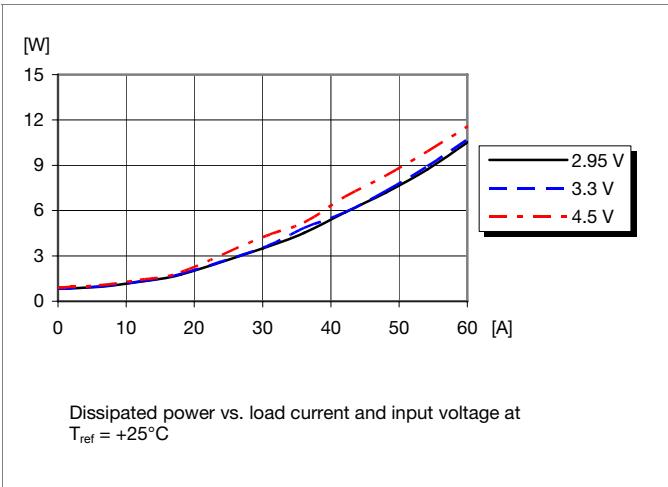
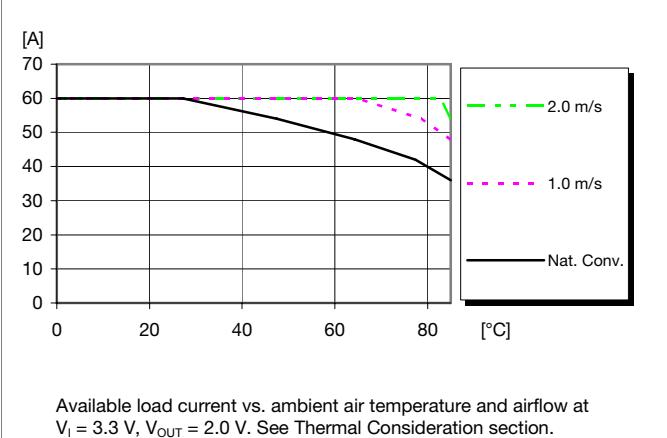
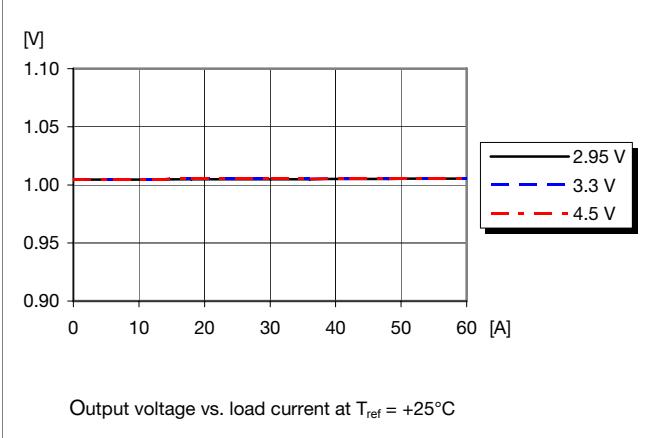
Note 1: Output filter according to Ripple & Noise section

PMM 4000 series

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POL regulator, Input 2.95-5.5 V, Output 60 A/150 W

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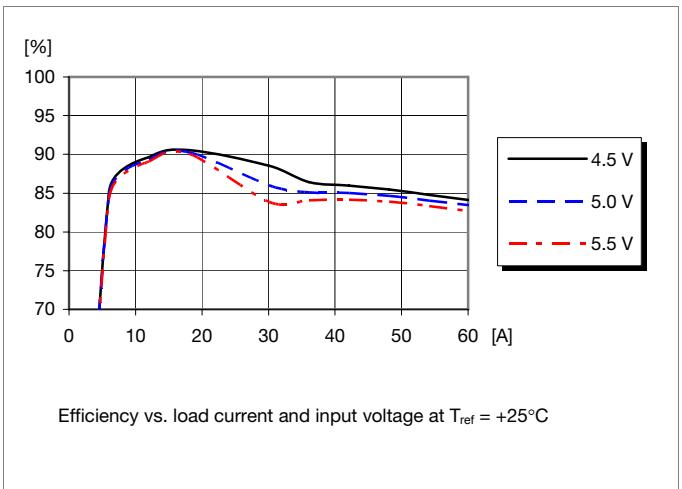
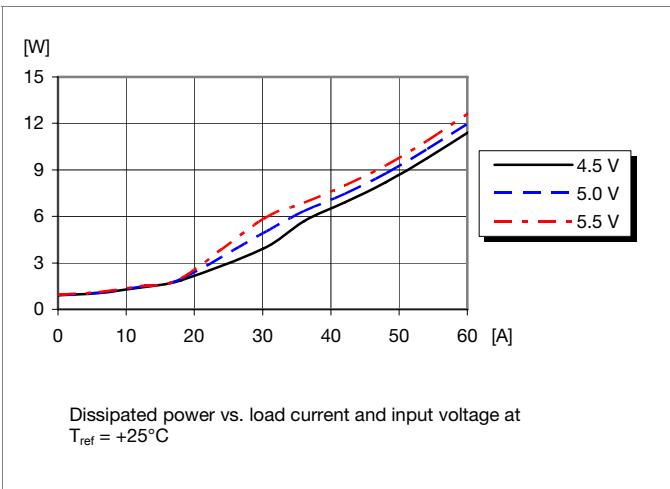
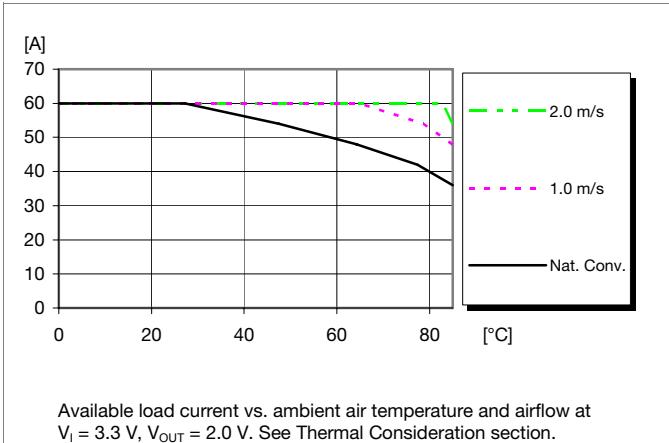
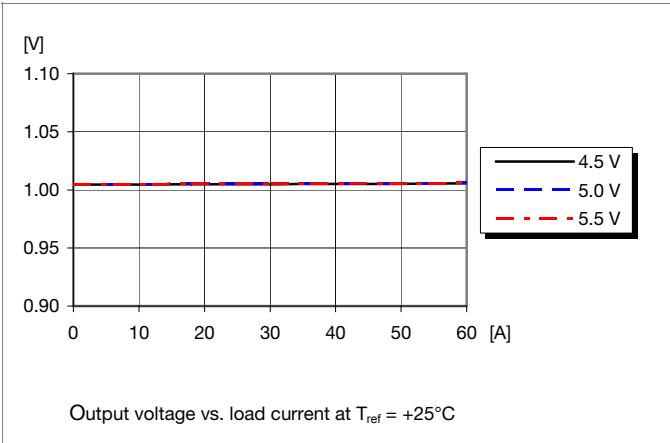
**1.0 V/60 A Typical Characteristics ( $V_i = 2.95\text{-}4.5\text{ V}$ )****PMM 4218T****Efficiency****Power Dissipation****Output Current Derating****Output Characteristics**

PMM 4000 series

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POL regulator, Input 2.95-5.5 V, Output 60 A/150 W

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**1.0 V/60 A Typical Characteristics ( $V_i = 4.5\text{-}5.5\text{ V}$ )****PMM 4218T****Efficiency****Power Dissipation****Output Current Derating****Output Characteristics**

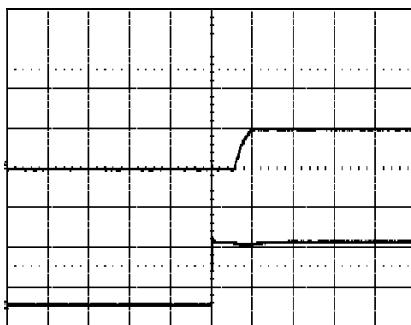
PMM 4000 series  
POL regulator, Input 2.95-5.5 V, Output 60 A/150 W

EN/LZT 146 337 R1A April 2006  
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### 1.0 V/60 A Typical Characteristics ( $V_i = 2.95-4.5$ V)

PMM 4218T

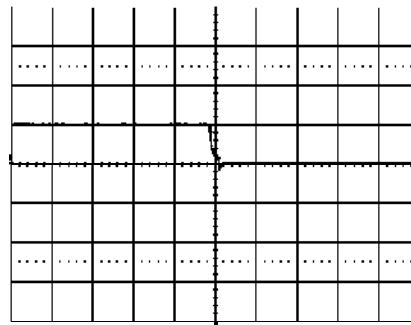
#### Start-up



Start-up enabled by connecting  $V_i$  at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_o = 60$  A resistive load,  
 $V_i = 3.3$  V.

Top trace: output voltage (1.0 V/div.).  
Bottom trace: input voltage (2.0 V/div.).  
Time scale: 10 ms/div.

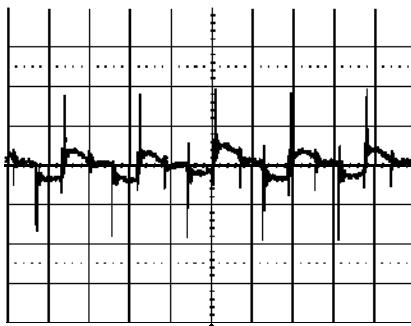
#### Shut-down



Shut-down enabled by disconnecting  $V_i$  at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_o = 60$  A resistive load,  
 $V_i = 3.3$  V.

Top trace: output voltage (1.0 V/div.).  
Time scale: 1.0 ms/div.

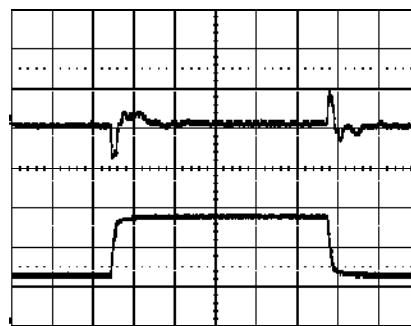
#### Output Ripple & Noise



Output voltage ripple (20 mV/div.) at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_o = 60$  A resistive load,  
 $V_i = 3.3$  V. Time scale: 2 μs/div.

See the filter in the Output ripple and noise section (EMC Specification).

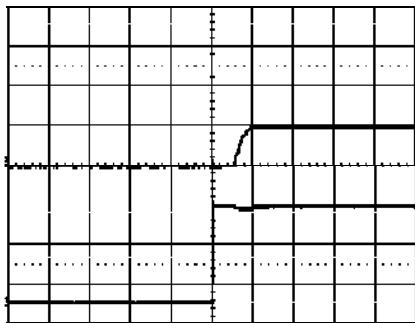
#### Output Load Transient Response



Output voltage response to load current step-change (30-60-30 A) at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $V_i = 3.3$  V.

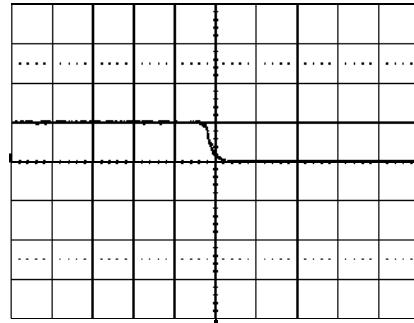
Top trace: output voltage (100 mV/div.).  
Bottom trace: load current (20 A/div.).  
Time scale: 0.1 ms/div.

PMM 4000 series
POL regulator, Input 2.95-5.5 V, Output 60 A/150 W

**1.0 V/60 A Typical Characteristics ( $V_i = 4.5-5.5$  V)****PMM 4218T****Start-up**

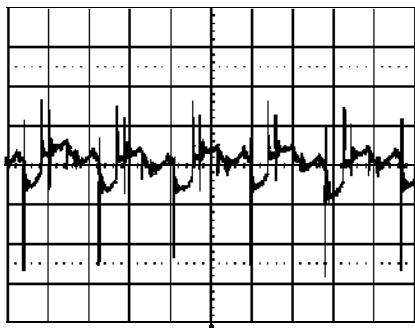
Start-up enabled by connecting  $V_i$  at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_o = 60$  A resistive load,  
 $V_i = 5.0$  V.

Top trace: output voltage (1.0 V/div.).  
Bottom trace: input voltage (2.0 V/div.).  
Time scale: 10 ms/div.

**Shut-down**

Shut-down enabled by disconnecting  $V_i$  at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_o = 60$  A resistive load,  
 $V_i = 5.0$  V.

Top trace: output voltage (1.0 V/div.).  
Time scale: 0.5 ms/div.

**Output Ripple & Noise**

Output voltage ripple (20 mV/div.) at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_o = 60$  A resistive load,  
 $V_i = 5.0$  V. Time scale: 2 μs/div.

See the filter in the Output ripple and noise section (EMC Specification).

**Output Load Transient Response**

Output voltage response to load current step-change (30-60-30 A) at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $V_i = 5.0$  V.

Top trace: output voltage (100 mV/div.).  
Bottom trace: load current (20 A/div.).  
Time scale: 0.2 ms/div.

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## 1.2 V/60 A Electrical Specification

PMM 4218T

 $T_{ref} = -40$  to  $+85^\circ\text{C}$ ,  $V_i = 2.95$  to  $5.5$  V,  $R_{adj} = 17.4$  k $\Omega$ , unless otherwise specified under Conditions.Typical values given at:  $T_{ref} = +25^\circ\text{C}$ ,  $V_i = 3.3/5.0$  V, max  $I_o$ , unless otherwise specified under Conditions.Additional  $C_{in} = 1000\mu\text{F}$  and  $C_{out} = 660\mu\text{F}$ . See Operating Information section for selection of capacitor types.

Connect the sense pin, where available, to the output pin.

Characteristics		Conditions	min	typ	max	Unit	
$V_i$	Input voltage range		2.95		5.5	V	
UVLO	Undervoltage lockout	Pin 8 open	On-threshold	2.6		V	
			Hysteresis	0.6			
$C_i$	Internal input capacitance			180		$\mu\text{F}$	
$P_o$	Output power		0		72	W	
$\eta$	Efficiency	$V_i = 3.3$ V	50 % of max $I_o$	90.5		%	
			max $I_o$	87.1			
		$V_i = 5.0$ V	50 % of max $I_o$	86.8			
			max $I_o$	85.6			
$P_d$	Power Dissipation	$V_i = 3.3$ V, max $I_o$		10.8		W	
		$V_i = 5.0$ V, max $I_o$		12.0			
$P_{ii}$	Input idling power	$I_o = 0$ , $V_i = 3.3$ V		880		mW	
		$I_o = 0$ , $V_i = 5.0$ V		1000			
$P_{inh}$	Input standby power	$V_i = 3.3$ V (turned off with INHIBIT)		198		mW	
		$V_i = 5.0$ V (turned off with INHIBIT)		300			
$I_s$	Static Input current	$V_i = 3.3$ V, max $I_o$		25.2		A	
		$V_i = 5.0$ V, max $I_o$		16.9			
$f_s$	Switching frequency	0-100 % of max $I_o$	675	825	975	kHz	

$V_{oi}$	Output voltage initial setting and accuracy	$T_{ref} = +25^\circ\text{C}$ , $V_i = 5.0$ V, max $I_o$	1.176	1.200	1.224	V
$V_o$	Output voltage tolerance band	10-100 % of max $I_o$	1.164		1.236	V
	Idling voltage	$I_o = 0$ , $V_i = 3.3$ V		1.202		V
		$I_o = 0$ , $V_i = 5.0$ V		1.202		
	Line regulation	max $I_o$		$\pm 5$		mV
$V_{tr}$	Load transient voltage deviation	$V_i = 3.3$ V, Load step 50-100-50 % of max $I_o$ , $di/dt = 1$ A/ $\mu\text{s}$ , see Note 1		$\pm 80$		mV
		$V_i = 5.0$ V, Load step 50-100-50 % of max $I_o$ , $di/dt = 1$ A/ $\mu\text{s}$ , see Note 1		$\pm 50$		
	Load transient recovery time	$V_i = 3.3$ V, Load step 50-100-50 % of max $I_o$ , $di/dt = 1$ A/ $\mu\text{s}$ , see Note 1		160		$\mu\text{s}$
		$V_i = 5.0$ V, Load step 50-100-50 % of max $I_o$ , $di/dt = 1$ A/ $\mu\text{s}$ , see Note 1		150		
$t_r$	Ramp-up time (from 10..90 % of $V_o$ )	$V_i = 3.3$ V, max $I_o$		3.4		ms
		$V_i = 5.0$ V, max $I_o$		3.4		
$t_s$	Start-up time (from $V_i$ connection to 90 % of $V_o$ )	$V_i = 3.3$ V, max $I_o$		9.1		ms
		$V_i = 5.0$ V, max $I_o$		8.9		

PMM 4000 series POL regulator, Input 2.95-5.5 V, Output 60 A/150 W	EN/LZT 146 337 R1A April 2006
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Characteristics		Conditions	min	typ	max	Unit	
$t_f$	Ramp-down time (from 90. 10 % of $V_o$ )	$V_i = 3.3 \text{ V}$	Max $I_o$	180		$\mu\text{s}$	
			$I_o = 0.1 \text{ A}$	24.6		ms	
	INHIBIT start-up time (From INHIBIT off to 10 % of $V_o$ )	$V_i = 5.0 \text{ V}$	Max $I_o$	200		$\mu\text{s}$	
			$I_o = 0.1 \text{ A}$	24.4		ms	
$T_{inh}$	INHIBIT shutdown fall time		$V_i = 3.3 \text{ V}, \text{Max } I_o$	6.7		ms	
			$V_i = 5.0 \text{ V}, \text{Max } I_o$	6.7			
	INHIBIT shutdown fall time (From INHIBIT off to 10 % of $V_o$ )	$V_i = 3.3 \text{ V}$	Max $I_o$	40		$\mu\text{s}$	
			$I_o = 0.1 \text{ A}$	7.8		ms	
		$V_i = 5.0 \text{ V}$	Max $I_o$	40		$\mu\text{s}$	
			$I_o = 0.1 \text{ A}$	7.8		ms	
$I_o$	Output current		0		60	A	
$I_{lim}$	Current limit threshold		$T_{ref} < \text{max } T_{ref}$	90		A	
$V_{Oac}$	Output ripple & noise		See ripple & noise section, max $I_o, V_{oi}$	15		mVp-p	

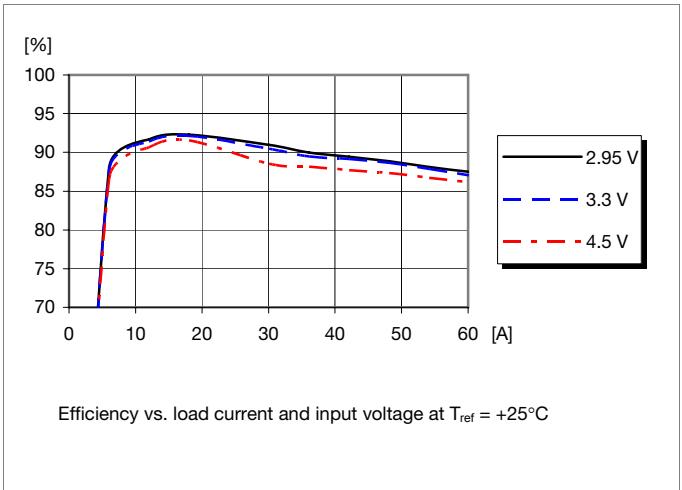
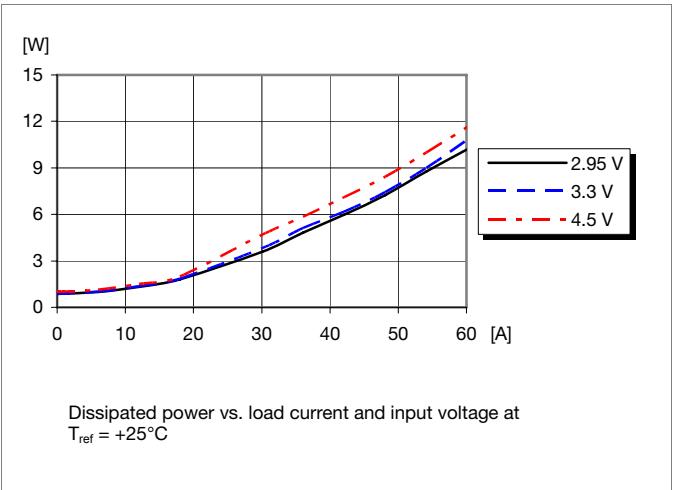
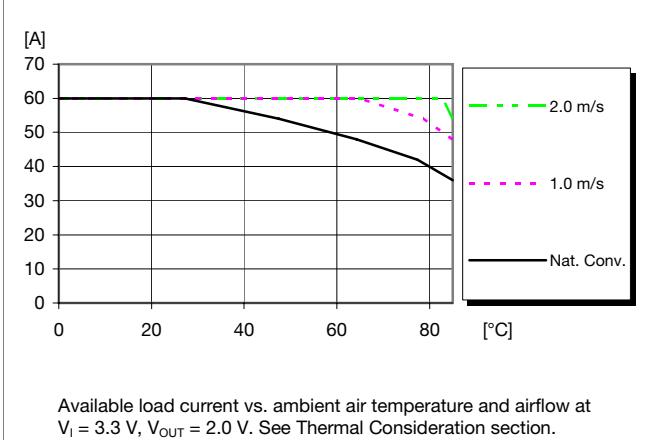
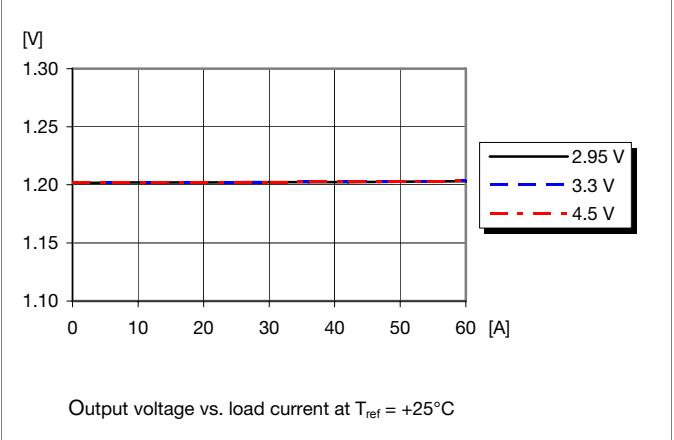
Note 1: Output filter according to Ripple & Noise section

PMM 4000 series

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POL regulator, Input 2.95-5.5 V, Output 60 A/150 W

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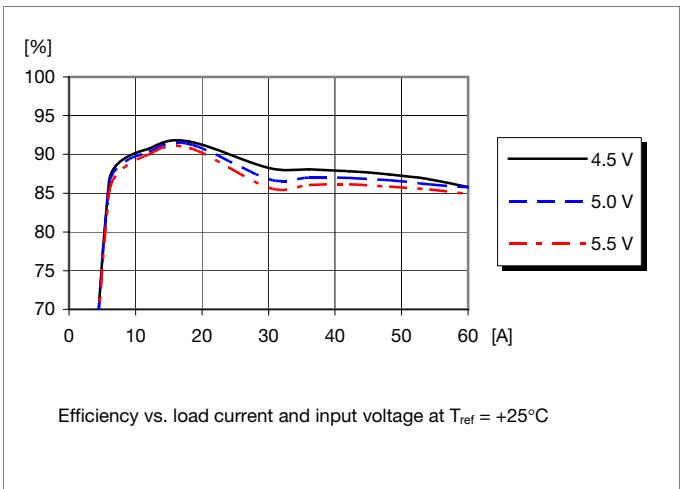
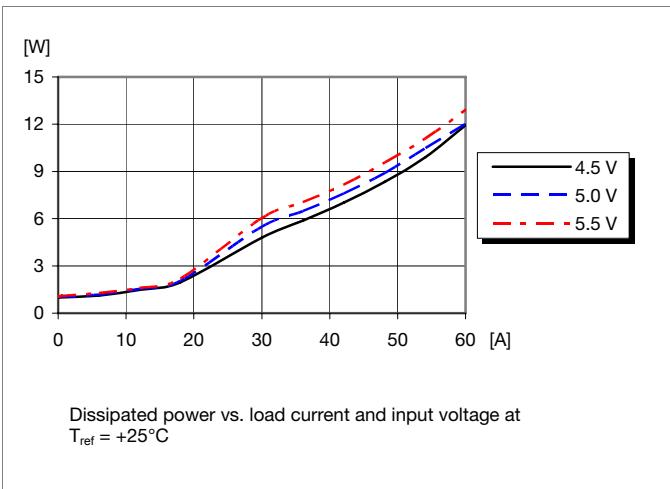
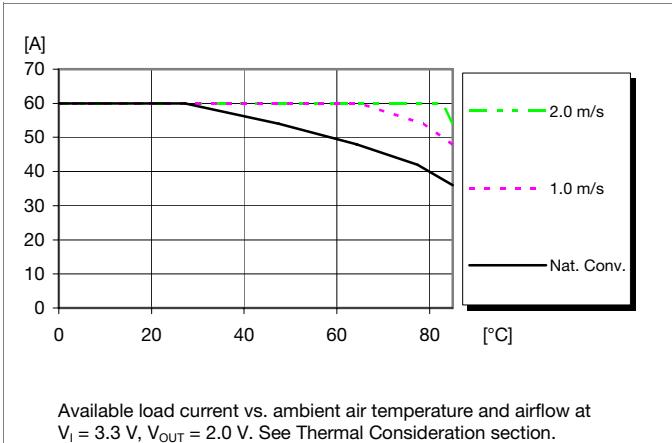
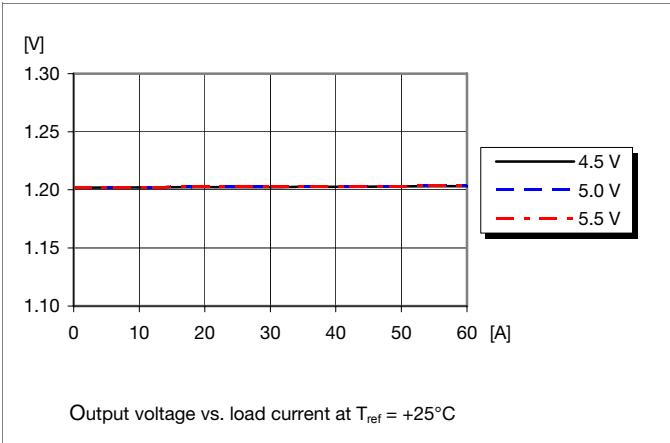
**1.2 V/60 A Typical Characteristics ( $V_i = 2.95\text{-}4.5\text{ V}$ )****PMM 4218T****Efficiency****Power Dissipation****Output Current Derating****Output Characteristics**

PMM 4000 series

EN/LZT 146 337 R1A April 2006

POL regulator, Input 2.95-5.5 V, Output 60 A/150 W

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**1.2 V/60 A Typical Characteristics ( $V_i = 4.5\text{-}5.5\text{ V}$ )****PMM 4218T****Efficiency****Power Dissipation****Output Current Derating****Output Characteristics**

PMM 4000 series

EN/LZT 146 337 R1A April 2006

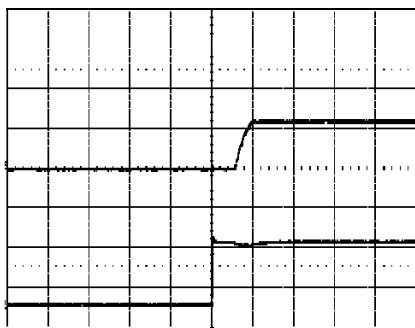
POL regulator, Input 2.95-5.5 V, Output 60 A/150 W

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1.2 V/60 A Typical Characteristics ( $V_i = 2.95-4.5$  V)

PMM 4218T

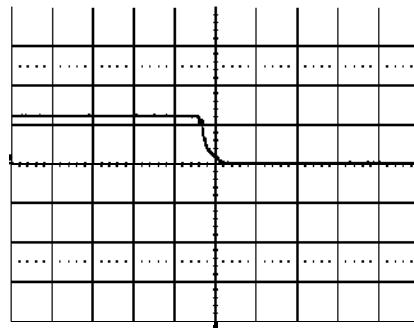
## Start-up



Start-up enabled by connecting  $V_i$  at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_0 = 60$  A resistive load,  
 $V_i = 3.3$  V.

Top trace: output voltage (1.0 V/div.).  
Bottom trace: input voltage (2.0 V/div.).  
Time scale: 10 ms/div.

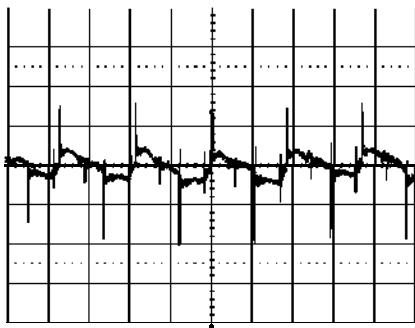
## Shut-down



Shut-down enabled by disconnecting  $V_i$  at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_0 = 60$  A resistive load,  
 $V_i = 3.3$  V.

Top trace: output voltage (1.0 V/div.).  
Time scale: 1.0 ms/div.

## Output Ripple &amp; Noise



Output voltage ripple (20 mV/div.) at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_0 = 60$  A resistive load,  
 $V_i = 3.3$  V. Time scale: 2  $\mu$ s/div.

See the filter in the Output ripple and noise section (EMC Specification).

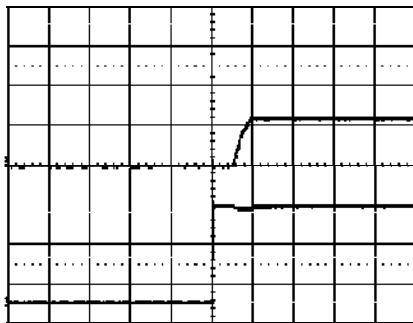
## Output Load Transient Response



Output voltage response to load current step-change (30-60-30 A) at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $V_i = 3.3$  V.

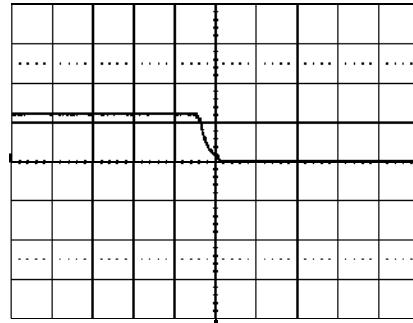
Top trace: output voltage (100 mV/div.).  
Bottom trace: load current (20 A/div.).  
Time scale: 0.1 ms/div.

PMM 4000 series
POL regulator, Input 2.95-5.5 V, Output 60 A/150 W

**1.2 V/60 A Typical Characteristics ( $V_i = 4.5-5.5$  V)****PMM 4218T****Start-up**

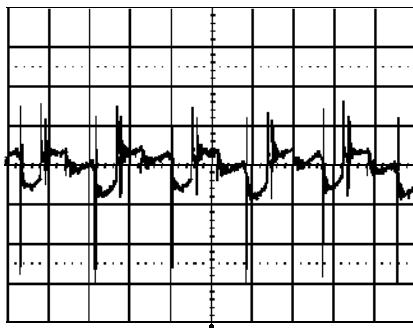
Start-up enabled by connecting  $V_i$  at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_o = 60$  A resistive load,  
 $V_i = 5.0$  V.

Top trace: output voltage (1.0 V/div.).  
Bottom trace: input voltage (2.0 V/div.).  
Time scale: 10 ms/div.

**Shut-down**

Shut-down enabled by disconnecting  $V_i$  at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_o = 60$  A resistive load,  
 $V_i = 5.0$  V.

Top trace: output voltage (1.0 V/div.).  
Time scale: 0.5 ms/div.

**Output Ripple & Noise**

Output voltage ripple (20 mV/div.) at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_o = 60$  A resistive load,  
 $V_i = 5.0$  V. Time scale: 2  $\mu\text{s}/\text{div}$ .

See the filter in the Output ripple and noise section (EMC Specification).

**Output Load Transient Response**

Output voltage response to load current step-change (30-60-30 A) at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $V_i = 5.0$  V.

Top trace: output voltage (100 mV/div.).  
Bottom trace: load current (20 A/div.).  
Time scale: 0.2 ms/div.

PMM 4000 series POL regulator, Input 2.95-5.5 V, Output 60 A/150 W	EN/LZT 146 337 R1A April 2006 © Ericsson Power Modules AB
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## 1.5 V/60 A Electrical Specification

PMM 4218T

 $T_{ref} = -40$  to  $+85^\circ\text{C}$ ,  $V_i = 2.95$  to  $5.5$  V,  $R_{adj} = 8.87$  k $\Omega$ , unless otherwise specified under Conditions.Typical values given at:  $T_{ref} = +25^\circ\text{C}$ ,  $V_i = 3.3/5.0$  V, max  $I_o$ , unless otherwise specified under Conditions.Additional  $C_{in} = 1000\mu\text{F}$  and  $C_{out} = 660\mu\text{F}$ . See Operating Information section for selection of capacitor types.

Connect the sense pin, where available, to the output pin.

Characteristics		Conditions	min	typ	max	Unit	
$V_i$	Input voltage range		2.95		5.5	V	
UVLO	Undervoltage lockout	Pin 8 open	On-threshold	2.6		V	
			Hysteresis	0.6			
$C_i$	Internal input capacitance			180		$\mu\text{F}$	
$P_o$	Output power		0		90	W	
$\eta$	Efficiency	$V_i = 3.3$ V	50 % of max $I_o$	91.6		%	
			max $I_o$	89.4			
		$V_i = 5.0$ V	50 % of max $I_o$	90.4			
			max $I_o$	88.0			
$P_d$	Power Dissipation	$V_i = 3.3$ V, max $I_o$		11.0		W	
		$V_i = 5.0$ V, max $I_o$		12.2			
$P_{il}$	Input idling power	$I_o = 0$ , $V_i = 3.3$ V		940		mW	
		$I_o = 0$ , $V_i = 5.0$ V		1200			
$P_{inh}$	Input standby power	$V_i = 3.3$ V (turned off with INHIBIT)		198		mW	
		$V_i = 5.0$ V (turned off with INHIBIT)		300			
$I_s$	Static Input current	$V_i = 3.3$ V, max $I_o$		30.8		A	
		$V_i = 5.0$ V, max $I_o$		20.6			
$f_s$	Switching frequency	0-100 % of max $I_o$	675	825	975	kHz	

$V_{oi}$	Output voltage initial setting and accuracy	$T_{ref} = +25^\circ\text{C}$ , $V_i = 5.0$ V, max $I_o$	1.470	1.500	1.530	V
$V_o$	Output voltage tolerance band	10-100 % of max $I_o$	1.455		1.545	V
	Idling voltage	$I_o = 0$ , $V_i = 3.3$ V		1.505		V
		$I_o = 0$ , $V_i = 5.0$ V		1.505		
	Line regulation	max $I_o$		$\pm 5$		mV
$V_{tr}$	Load transient voltage deviation	$V_i = 3.3$ V, Load step 50-100-50 % of max $I_o$ , $di/dt = 1$ A/ $\mu\text{s}$ , see Note 1		$\pm 80$		mV
		$V_i = 5.0$ V, Load step 50-100-50 % of max $I_o$ , $di/dt = 1$ A/ $\mu\text{s}$ , see Note 1		$\pm 60$		
	Load transient recovery time	$V_i = 3.3$ V, Load step 50-100-50 % of max $I_o$ , $di/dt = 1$ A/ $\mu\text{s}$ , see Note 1		160		$\mu\text{s}$
		$V_i = 5.0$ V, Load step 50-100-50 % of max $I_o$ , $di/dt = 1$ A/ $\mu\text{s}$ , see Note 1		150		
$t_r$	Ramp-up time (from 10..90 % of $V_o$ )	$V_i = 3.3$ V, max $I_o$		3.3		ms
		$V_i = 5.0$ V, max $I_o$		3.3		
$t_s$	Start-up time (from $V_i$ connection to 90 % of $V_o$ )	$V_i = 3.3$ V, max $I_o$		9.1		ms
		$V_i = 5.0$ V, max $I_o$		8.8		

PMM 4000 series POL regulator, Input 2.95-5.5 V, Output 60 A/150 W			EN/LZT 146 337 R1A April 2006
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Characteristics		Conditions	min	typ	max	Unit	
$t_f$	Ramp-down time (from 90. 10 % of $V_o$ )	$V_i = 3.3 \text{ V}$	Max $I_o$	190		$\mu\text{s}$	
			$I_o = 0.1 \text{ A}$	29.6		ms	
	INHIBIT shutdown fall time (From INHIBIT off to 10 % of $V_o$ )	$V_i = 5.0 \text{ V}$	Max $I_o$	220		$\mu\text{s}$	
			$I_o = 0.1 \text{ A}$	29.3		ms	
$T_{inh}$	INHIBIT start-up time		$V_i = 3.3 \text{ V}, \text{Max } I_o$	6.7		ms	
			$V_i = 5.0 \text{ V}, \text{Max } I_o$	6.8			
	INHIBIT shutdown fall time (From INHIBIT off to 10 % of $V_o$ )	$V_i = 3.3 \text{ V}$	Max $I_o$	180		$\mu\text{s}$	
			$I_o = 0.1 \text{ A}$	9.7		ms	
		$V_i = 5.0 \text{ V}$	Max $I_o$	180		$\mu\text{s}$	
			$I_o = 0.1 \text{ A}$	9.7		ms	
$I_o$	Output current		0		60	A	
$I_{lim}$	Current limit threshold		$T_{ref} < \text{max } T_{ref}$	90		A	
$V_{Oac}$	Output ripple & noise		See ripple & noise section, max $I_o, V_{oi}$	15		mVp-p	

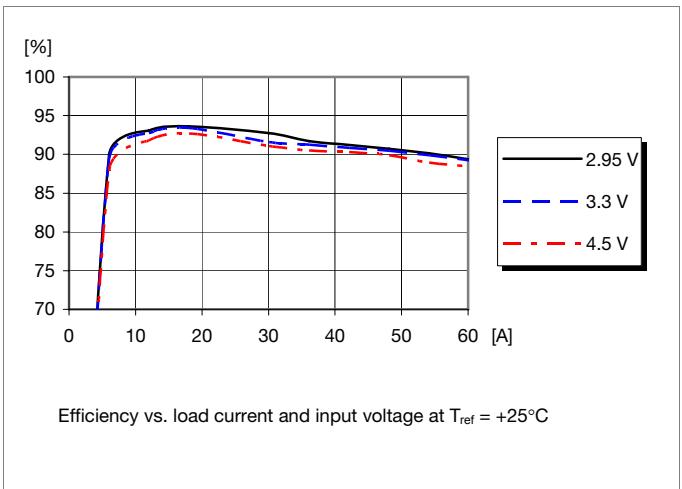
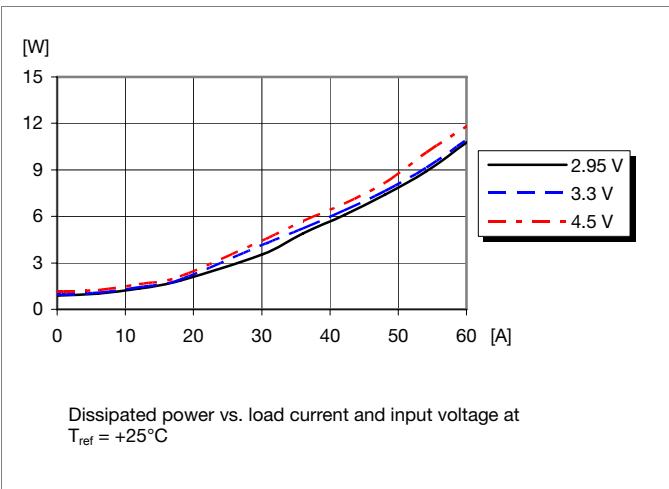
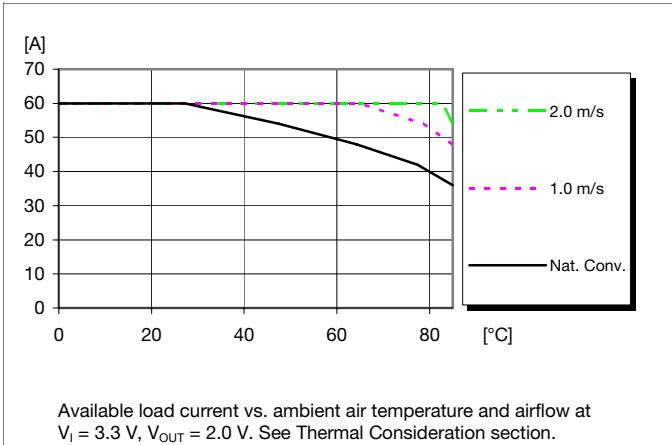
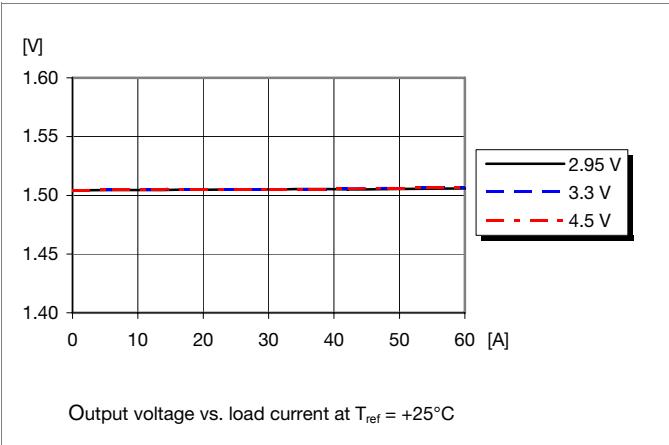
Note 1: Output filter according to Ripple & Noise section

PMM 4000 series

EN/LZT 146 337 R1A April 2006

POL regulator, Input 2.95-5.5 V, Output 60 A/150 W

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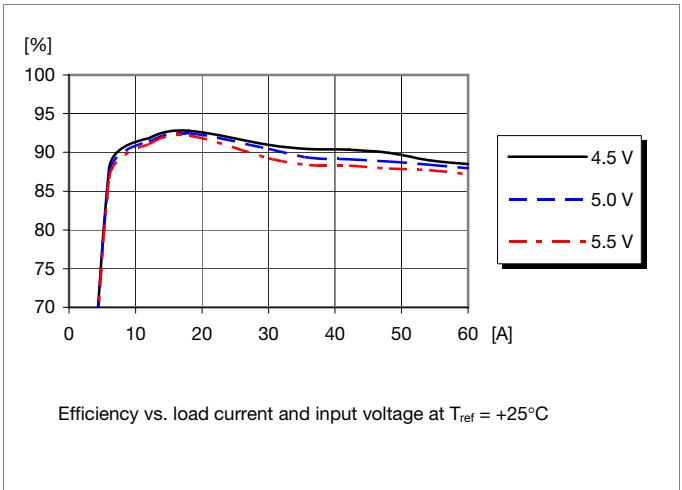
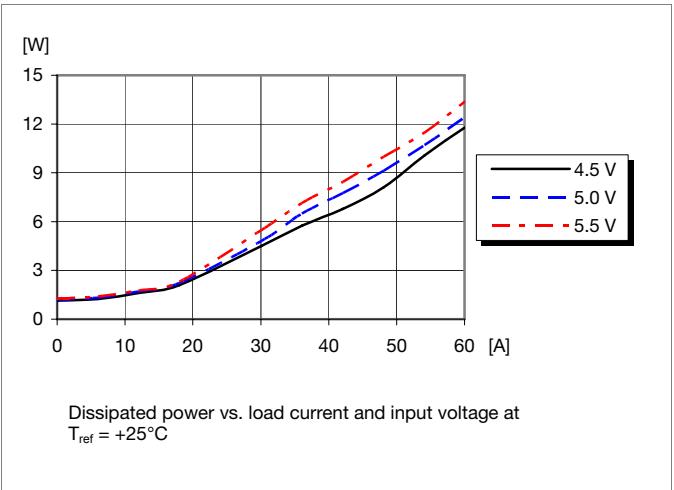
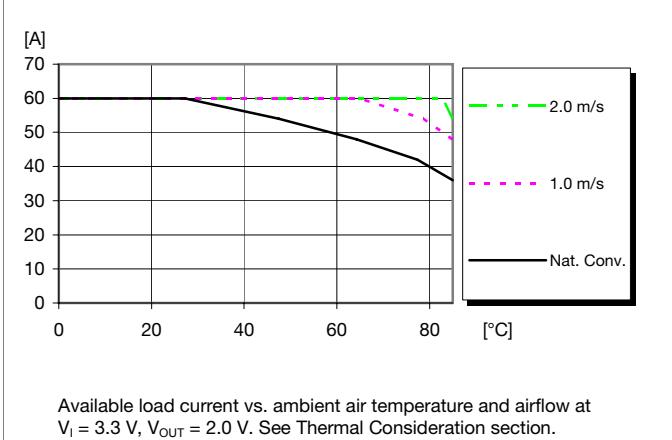
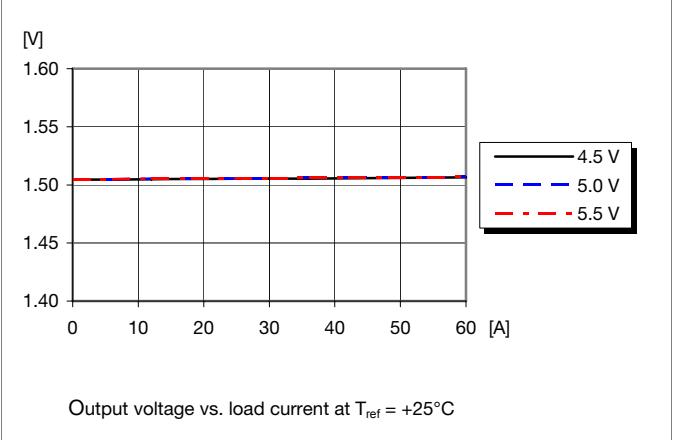
**1.5 V/60 A Typical Characteristics ( $V_i = 2.95\text{-}4.5 \text{ V}$ )****PMM 4218T****Efficiency****Power Dissipation****Output Current Derating****Output Characteristics**

PMM 4000 series

EN/LZT 146 337 R1A April 2006

POL regulator, Input 2.95-5.5 V, Output 60 A/150 W

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**1.5 V/60 A Typical Characteristics ( $V_i = 4.5\text{-}5.5\text{ V}$ )****PMM 4218T****Efficiency****Power Dissipation****Output Current Derating****Output Characteristics**

PMM 4000 series

EN/LZT 146 337 R1A April 2006

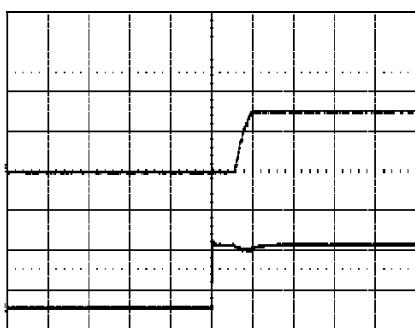
POL regulator, Input 2.95-5.5 V, Output 60 A/150 W

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1.5 V/60 A Typical Characteristics ( $V_i = 2.95-4.5$  V)

PMM 4218T

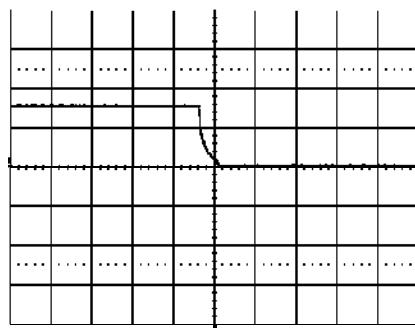
## Start-up



Start-up enabled by connecting  $V_i$  at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_0 = 60$  A resistive load,  
 $V_i = 3.3$  V.

Top trace: output voltage (1.0 V/div.).  
Bottom trace: input voltage (2.0 V/div.).  
Time scale: 10 ms/div.

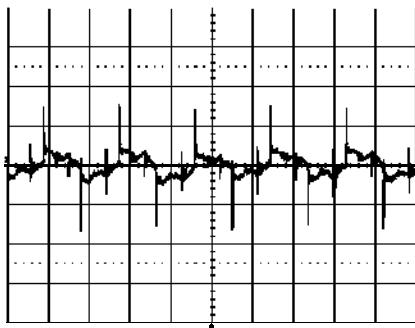
## Shut-down



Shut-down enabled by disconnecting  $V_i$  at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_0 = 60$  A resistive load,  
 $V_i = 3.3$  V.

Top trace: output voltage (1.0 V/div.).  
Time scale: 1.0 ms/div.

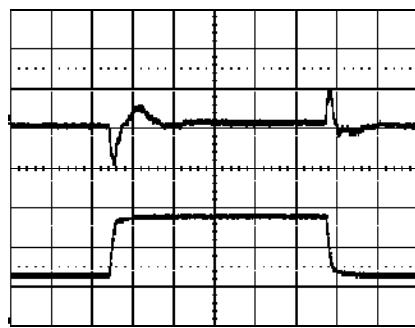
## Output Ripple &amp; Noise



Output voltage ripple (20 mV/div.) at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_0 = 60$  A resistive load,  
 $V_i = 3.3$  V. Time scale: 2 μs/div.

See the filter in the Output ripple and noise section (EMC Specification).

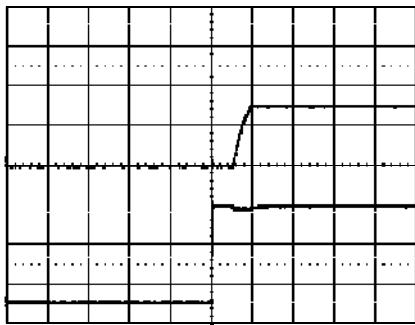
## Output Load Transient Response



Output voltage response to load current step-change (30-60-30 A) at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $V_i = 3.3$  V.

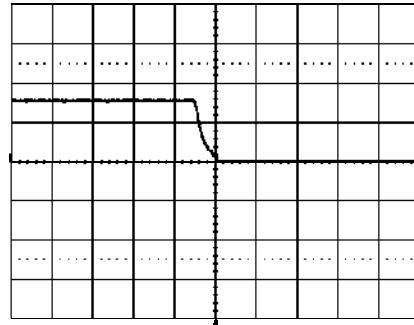
Top trace: output voltage (100 mV/div.).  
Bottom trace: load current (20 A/div.).  
Time scale: 0.1 ms/div.

PMM 4000 series
POL regulator, Input 2.95-5.5 V, Output 60 A/150 W

**1.5 V/60 A Typical Characteristics ( $V_i = 4.5-5.5$  V)****PMM 4218T****Start-up**

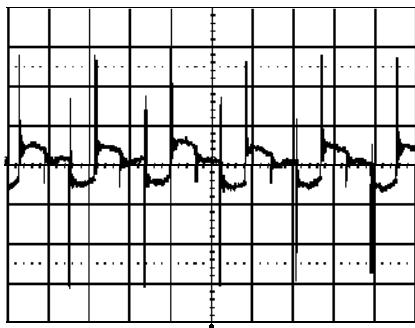
Start-up enabled by connecting  $V_i$  at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_O = 60$  A resistive load,  
 $V_i = 5.0$  V.

Top trace: output voltage (1.0 V/div.).  
Bottom trace: input voltage (2.0 V/div.).  
Time scale: 10 ms/div.

**Shut-down**

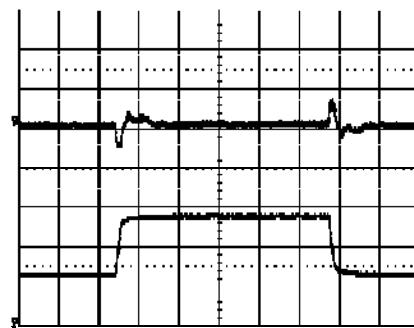
Shut-down enabled by disconnecting  $V_i$  at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_O = 60$  A resistive load,  
 $V_i = 5.0$  V.

Top trace: output voltage (1.0 V/div.).  
Time scale: 0.5 ms/div.

**Output Ripple & Noise**

Output voltage ripple (20 mV/div.) at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_O = 60$  A resistive load,  
 $V_i = 5.0$  V. Time scale: 2  $\mu\text{s}/\text{div}$ .

See the filter in the Output ripple and noise section (EMC Specification).

**Output Load Transient Response**

Output voltage response to load current step-change (30-60-30 A) at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $V_i = 5.0$  V.

Top trace: output voltage (100 mV/div.).  
Bottom trace: load current (20 A/div.).  
Time scale: 0.2 ms/div.

PMM 4000 series POL regulator, Input 2.95-5.5 V, Output 60 A/150 W	EN/LZT 146 337 R1A April 2006 © Ericsson Power Modules AB
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## 1.8 V/60 A Electrical Specification

PMM 4218T

 $T_{ref} = -40$  to  $+85^\circ\text{C}$ ,  $V_i = 4.5$  to  $5.5$  V,  $R_{adj} = 5.49$  k $\Omega$ , unless otherwise specified under Conditions.Typical values given at:  $T_{ref} = +25^\circ\text{C}$ ,  $V_i = 5.0$  V,  $\max I_o$ , unless otherwise specified under Conditions.Additional  $C_{in} = 1000\mu\text{F}$  and  $C_{out} = 660\mu\text{F}$ . See Operating Information section for selection of capacitor types.

Connect the sense pin, where available, to the output pin.

Characteristics		Conditions	min	typ	max	Unit
$V_i$	Input voltage range		4.5		5.5	V
UVLO	Undervoltage lockout	Pin 8 open	On-threshold	2.6		V
			Hysteresis	0.6		
$C_i$	Internal input capacitance			180		$\mu\text{F}$
$P_o$	Output power		0		108	W
$\eta$	Efficiency	50 % of max $I_o$		91.8		%
		max $I_o$		89.6		
$P_d$	Power Dissipation	max $I_o$		12.5		W
$P_{il}$	Input idling power	$I_o = 0$ , $V_i = 5.0$ V		1300		mW
$P_{inh}$	Input standby power	$V_i = 5.0$ V (turned off with INHIBIT)		300		mW
$I_s$	Static Input current	$V_i = 5.0$ V, max $I_o$		24.2		A
$f_s$	Switching frequency	0-100 % of max $I_o$	675	825	975	kHz

$V_{oi}$	Output voltage initial setting and accuracy	$T_{ref} = +25^\circ\text{C}$ , $V_i = 5.0$ V, max $I_o$	1.764	1.800	1.836	V
$V_o$	Output voltage tolerance band	10-100 % of max $I_o$	1.746		1.854	V
	Idling voltage	$I_o = 0$		1.804		V
	Line regulation	max $I_o$		$\pm 5$		mV
	Load regulation	$V_i = 5.0$ V, 0-100 % of max $I_o$		$\pm 5$		mV
$V_{tr}$	Load transient voltage deviation	$V_i = 5.0$ V, Load step 50-100-50 % of max $I_o$ , $di/dt = 1$ A/ $\mu\text{s}$ , see Note 1		$\pm 60$		mV
$t_{tr}$	Load transient recovery time			150		$\mu\text{s}$
$t_r$	Ramp-up time (from 10. 90 % of $V_o$ )	max $I_o$		3.4		ms
$t_s$	Start-up time (from $V_i$ connection to 90% of $V_o$ )			8.8		ms
$t_f$	Ramp-down time (from 90. 10 % of $V_o$ )	Max $I_o$		260		$\mu\text{s}$
		$I_o = 0.1$ A		31.2		ms
$t_{inh}$	INHIBIT start-up time	Max $I_o$		6.7		ms
	INHIBIT shutdown fall time (From INHIBIT off to 10% of $V_o$ )	Max $I_o$		200		$\mu\text{s}$
		$I_o = 0.1$ A		11.5		ms
$I_o$	Output current		0		60	A
$I_{lim}$	Current limit threshold	$T_{ref} < \max T_{ref}$		90		A
$V_{oac}$	Output ripple & noise	See ripple & noise section, max $I_o$ , $V_{oi}$		15		mVp-p

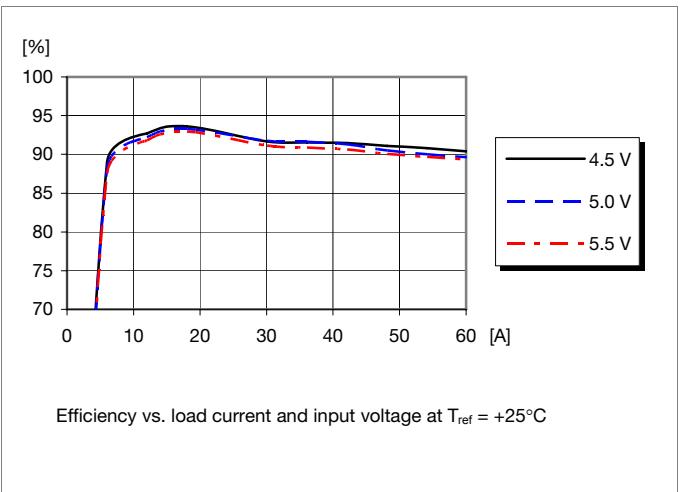
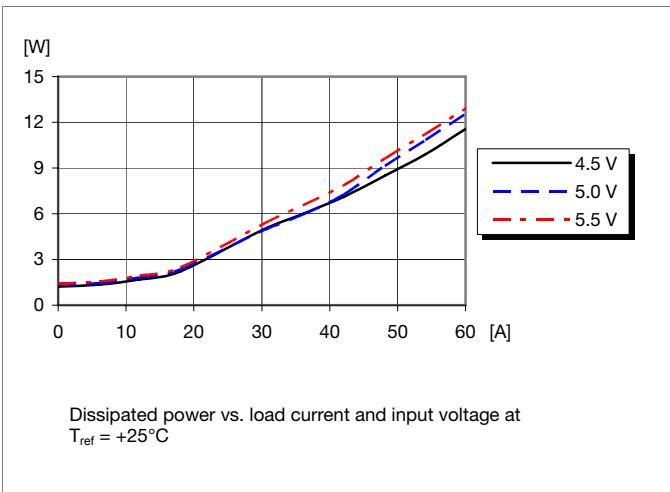
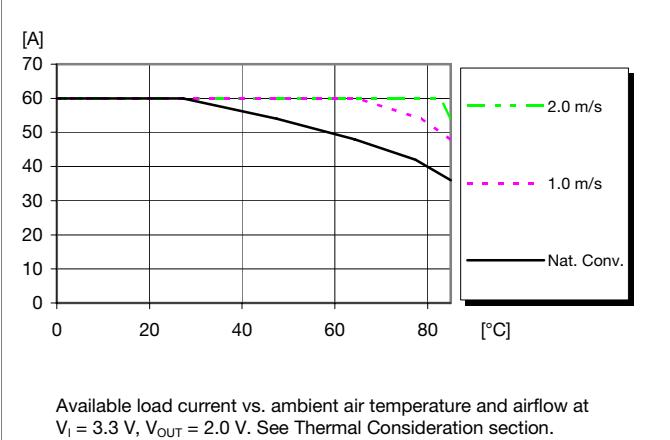
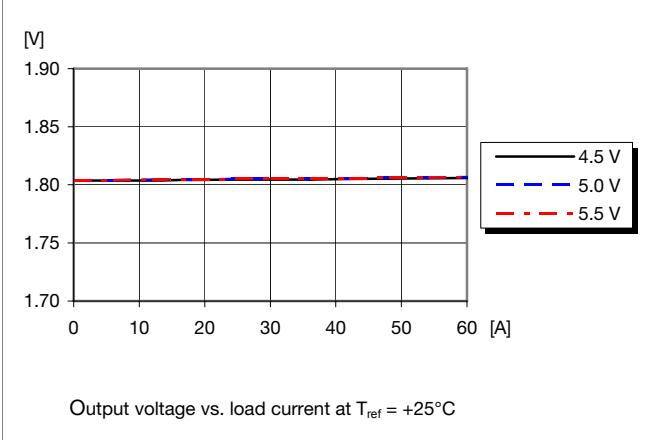
Note 1: Output filter according to Ripple &amp; Noise section

PMM 4000 series

EN/LZT 146 337 R1A April 2006

POL regulator, Input 2.95-5.5 V, Output 60 A/150 W

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**1.8 V/60 A Typical Characteristics****PMM 4218T****Efficiency****Power Dissipation****Output Current Derating****Output Characteristics**

PMM 4000 series

POL regulator, Input 2.95-5.5 V, Output 60 A/150 W

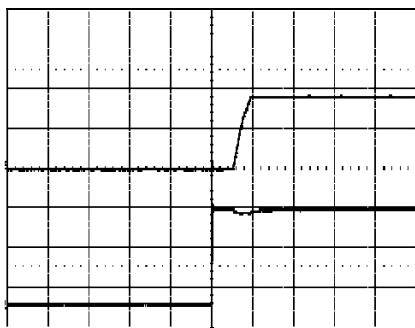
EN/LZT 146 337 R1A April 2006

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## 1.8 V/60 A Typical Characteristics

PMM 4218T

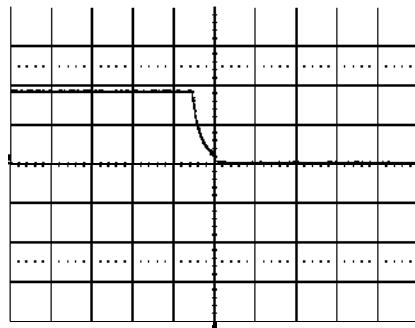
## Start-up



Start-up enabled by connecting V<sub>o</sub> at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_o = 60 \text{ A}$  resistive load,  
 $V_i = 5.0 \text{ V}$ .

Top trace: output voltage (1.0 V/div.).  
Bottom trace: input voltage (2 V/div.).  
Time scale: 10 ms/div.

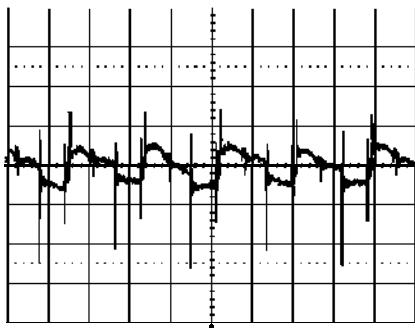
## Shut-down



Shut-down enabled by disconnecting V<sub>o</sub> at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_o = 60 \text{ A}$  resistive load,  
 $V_i = 5.0 \text{ V}$ .

Top trace: output voltage (1.0 V/div.).  
Time scale: 0.5 ms/div.

## Output Ripple &amp; Noise



See the filter in the Output ripple and noise section (EMC Specification).

## Output Load Transient Response



Output voltage response to load current step-change (30-60-30 A) at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $V_i = 5.0 \text{ V}$ .

Top trace: output voltage (100 mV/div.).  
Bottom trace: load current (20 A/div.).  
Time scale: 0.2 ms/div.

PMM 4000 series POL regulator, Input 2.95-5.5 V, Output 60 A/150 W	EN/LZT 146 337 R1A April 2006 © Ericsson Power Modules AB
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## 2.5 V/60 A Electrical Specification

PMM 4218T

 $T_{ref} = -40$  to  $+85^\circ\text{C}$ ,  $V_i = 4.5$  to  $5.5$  V,  $R_{adj} = 2.21$  k $\Omega$ , unless otherwise specified under Conditions.Typical values given at:  $T_{ref} = +25^\circ\text{C}$ ,  $V_i = 5.0$  V,  $\max I_o$ , unless otherwise specified under Conditions.Additional  $C_{in} = 1000\mu\text{F}$  and  $C_{out} = 660\mu\text{F}$ . See Operating Information section for selection of capacitor types.

Connect the sense pin, where available, to the output pin.

Characteristics		Conditions	min	typ	max	Unit
$V_i$	Input voltage range		4.5		5.5	V
UVLO	Undervoltage lockout	Pin 8 open	On-threshold	2.6		V
			Hysteresis	0.6		
$C_i$	Internal input capacitance			180		$\mu\text{F}$
$P_o$	Output power		0		150	W
$\eta$	Efficiency	50 % of max $I_o$		94.0		%
		max $I_o$		91.6		
$P_d$	Power Dissipation	max $I_o$		13.5		W
$P_{il}$	Input idling power	$I_o = 0$ , $V_i = 5.0$ V		1500		mW
$P_{inh}$	Input standby power	$V_i = 5.0$ V (turned off with INHIBIT)		300		mW
$I_s$	Static Input current	$V_i = 5.0$ V, max $I_o$		32.7		A
$f_s$	Switching frequency	0-100 % of max $I_o$	675	825	975	kHz

$V_{oi}$	Output voltage initial setting and accuracy	$T_{ref} = +25^\circ\text{C}$ , $V_i = 5.0$ V, max $I_o$	2.450	2.500	2.550	V
$V_o$	Output voltage tolerance band	10-100 % of max $I_o$	2.425		2.575	V
	Idling voltage	$I_o = 0$		2.506		V
	Line regulation	max $I_o$		$\pm 5$		mV
	Load regulation	$V_i = 5.0$ V, 0-100 % of max $I_o$		$\pm 5$		mV
$V_{tr}$	Load transient voltage deviation	$V_i = 5.0$ V, Load step 50-100-50 % of max $I_o$ , $di/dt = 1$ A/ $\mu\text{s}$ , see Note 1		$\pm 80$		mV
$t_{tr}$	Load transient recovery time			180		$\mu\text{s}$
$t_r$	Ramp-up time (from 10. 90 % of $V_o$ )	max $I_o$		3.4		ms
$t_s$	Start-up time (from $V_i$ connection to 90% of $V_o$ )			8.9		ms
$t_f$	Ramp-down time (from 90. 10 % of $V_o$ )	Max $I_o$		280		$\mu\text{s}$
		$I_o = 0.1$ A		34.6		ms
$t_{inh}$	INHIBIT start-up time	Max $I_o$		6.8		ms
	INHIBIT shutdown fall time (From INHIBIT off to 10% of $V_o$ )	Max $I_o$		220		$\mu\text{s}$
		$I_o = 0.1$ A		15.3		ms
$I_o$	Output current		0		60	A
$I_{lim}$	Current limit threshold	$T_{ref} < \max T_{ref}$		90		A
$V_{oac}$	Output ripple & noise	See ripple & noise section, max $I_o$ , $V_{oi}$		15		mVp-p

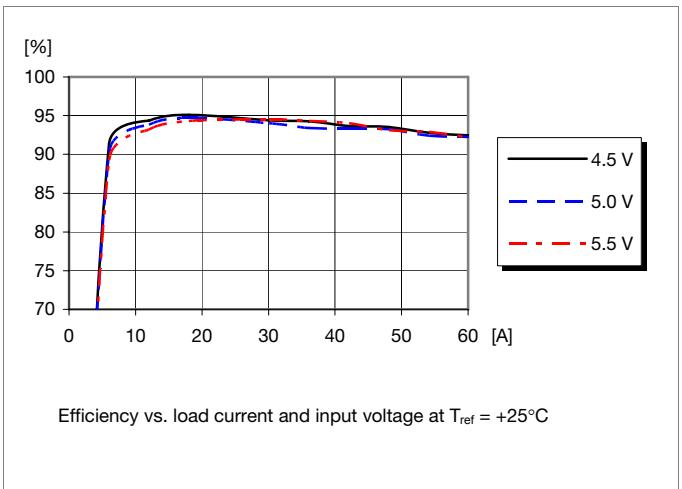
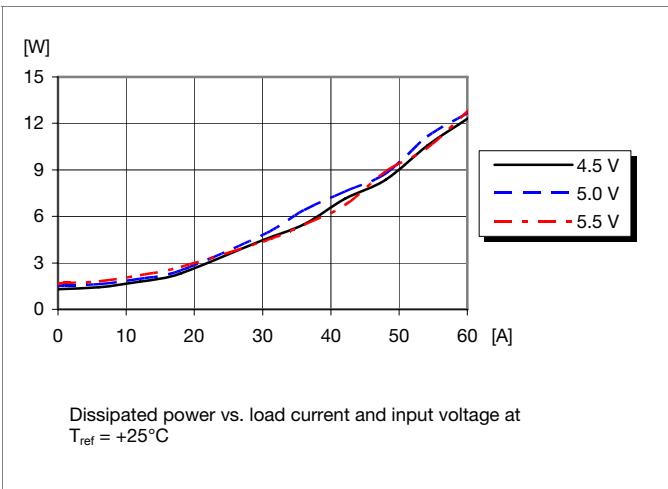
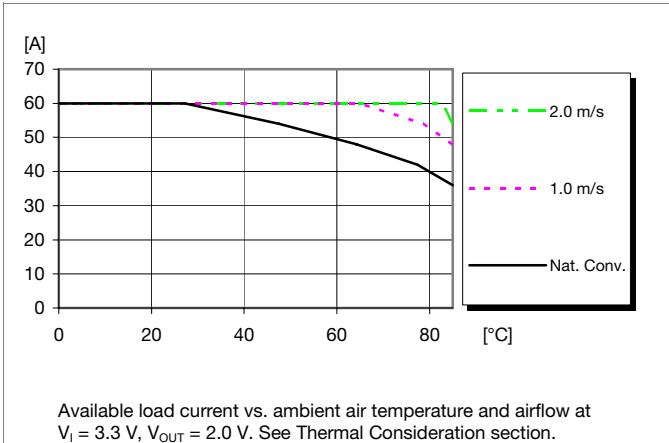
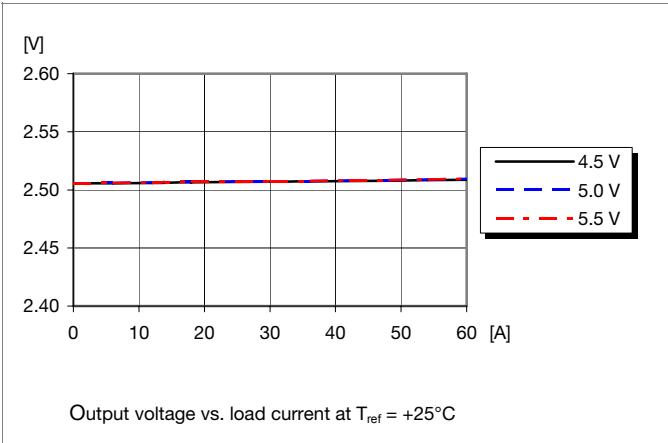
Note 1: Output filter according to Ripple &amp; Noise section

PMM 4000 series

EN/LZT 146 337 R1A April 2006

POL regulator, Input 2.95-5.5 V, Output 60 A/150 W

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**2.5 V/60 A Typical Characteristics****PMM 4218T****Efficiency****Power Dissipation****Output Current Derating****Output Characteristics**

PMM 4000 series

POL regulator, Input 2.95-5.5 V, Output 60 A/150 W

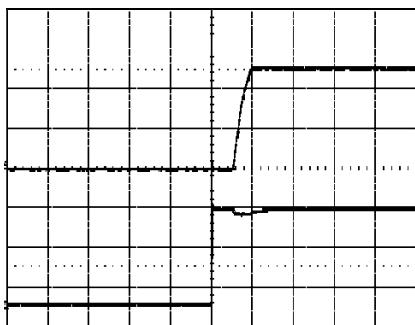
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## 2.5 V/60 A Typical Characteristics

PMM 4218T

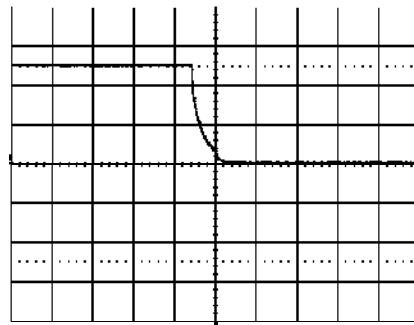
## Start-up



Start-up enabled by connecting  $V_i$  at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_0 = 60 \text{ A}$  resistive load,  
 $V_i = 5.0 \text{ V}$ .

Top trace: output voltage (1.0 V/div.).  
Bottom trace: input voltage (2 V/div.).  
Time scale: 10 ms/div.

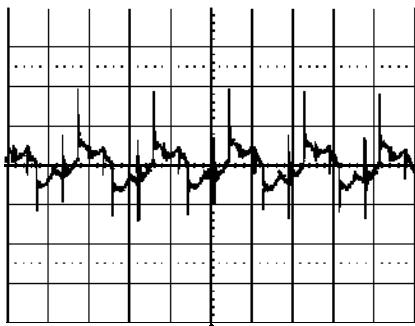
## Shut-down



Shut-down enabled by disconnecting  $V_i$  at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_0 = 60 \text{ A}$  resistive load,  
 $V_i = 5.0 \text{ V}$ .

Top trace: output voltage (1.0 V/div.).  
Time scale: 0.5 ms/div.

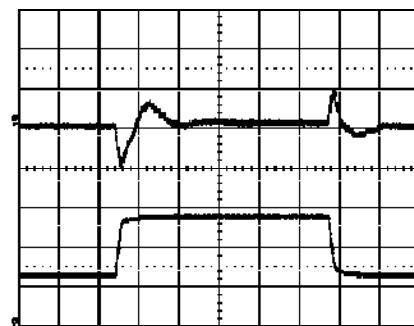
## Output Ripple &amp; Noise



Output voltage ripple (20 mV/div.) at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $I_0 = 60 \text{ A}$  resistive load,  
 $V_i = 5.0 \text{ V}$ . Time scale: 2  $\mu\text{s}/\text{div}$ .

See the filter in the Output ripple and noise section (EMC Specification).

## Output Load Transient Response



Output voltage response to load current step-change (30-60-30 A) at:  
 $T_{ref} = +25^\circ\text{C}$ ,  $V_i = 5.0 \text{ V}$ .

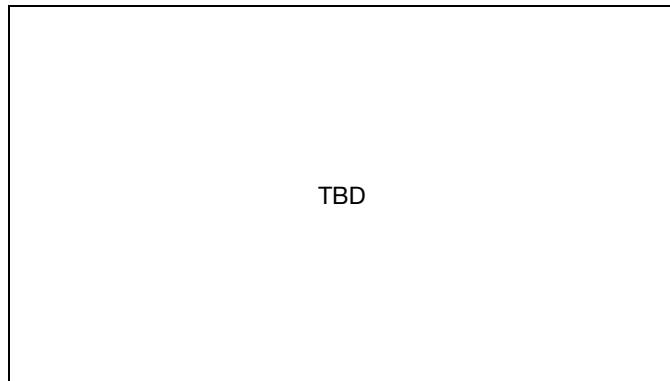
Top trace: output voltage (100 mV/div.).  
Bottom trace: load current (20 A/div.).  
Time scale: 0.2 ms/div.

PMM 4000 series POL regulator, Input 2.95-5.5 V, Output 60 A/150 W	EN/LZT 146 337 R1A April 2006 © Ericsson Power Modules AB
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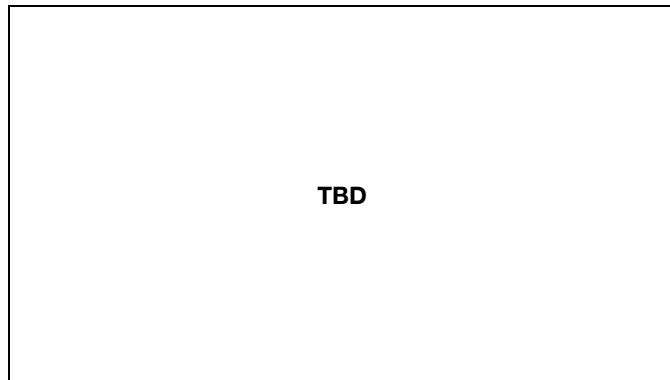
## EMC Specification

Conducted EMI measured according to test set-up.  
The fundamental switching frequency is 825 kHz for PMM 4218T @  $V_i = 3.3V$  or 5 V, max  $I_o$ .

### Conducted EMI Input terminal value (typ)



EMI without filter



Test set-up

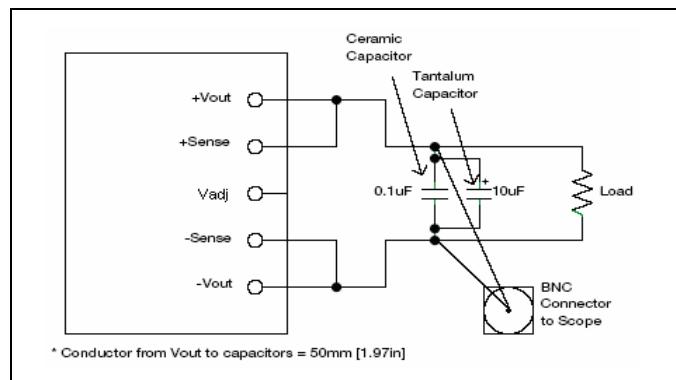
### Layout recommendation

The radiated EMI performance of the POL regulator will depend on the PCB layout and ground layer design. It is also important to consider the stand-off of the POL regulator. If a ground layer is used, it should be connected to the output of the POL regulator and the equipment ground or chassis.

A ground layer will increase the stray capacitance in the PCB and improve the high frequency EMC performance.

## Output ripple and noise

Output ripple and noise measured according to figure below. See Design Note 022 for detailed information.



Output ripple and noise test setup

## Operating information

Extended information for POLA products is found in Application Note POLA (AN205).

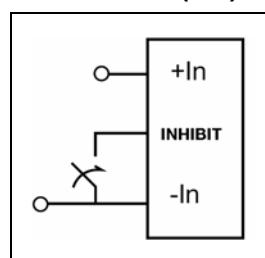
### Input Voltage

The input voltage range 2.95 to 5.5 Vdc makes the product easy to use in intermediate bus applications when powered by a regulated 3.3 V or 5 V bus converter. The PMM product family is also available with 12  $V_{in}$ .

### Turn on/off Input Voltage

The POL regulators monitor the input voltage and will turn on and turn off at predetermined levels. The typical hysteresis between turn on and turn off input voltage is 0.6 V.

### Inhibit Control (INH)



The products are equipped with a Inhibit control function referenced to the primary negative input connection (- In), positive logic. The INHIBIT function allows the regulator to be turned on/off by an external device like a semiconductor or mechanical switch.

The regulator will turn on when the input voltage is applied with the INHIBIT pin open. Turn off is achieved by connecting the INHIBIT pin to the - In. To ensure safe turn off, the voltage difference between INHIBIT pin and the - In pin shall be less than 0.5V. The regulator will restart automatically when this connection is opened.

PMM 4000 series POL regulator, Input 2.95-5.5 V, Output 60 A/150 W	EN/LZT 146 337 R1A April 2006 © Ericsson Power Modules AB
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## External Capacitors

### Input capacitors:

The recommended input capacitors are determined by the 940  $\mu$ F minimum capacitance and 400 mArms minimum ripple current rating. For high performance applications, or wherever the transient capability of the input source is limited, 2200  $\mu$ F of input capacitance is recommended.

### Output capacitors (optional):

The recommended output capacitance of 660  $\mu$ F will allow the module to meet its transient response specification as defined in the electrical specification.

When using one or more non-ceramic capacitors, the calculated equivalent ESR should be no lower than 4 m $\Omega$  (7m $\Omega$  using the manufacturer's maximum ESR for a single capacitor).

## Input And Output Impedance

The impedance of both the input source and the load will interact with the impedance of the POL regulator. It is important that the input source has low characteristic impedance. The regulators are designed for stable operation without external capacitors connected to the input or output. The performance in some applications can be enhanced by addition of external capacitance as described under External Decoupling Capacitors. If the input voltage source contains significant inductance, the addition of a 100  $\mu$ F capacitor across the input of the POL regulator will ensure stable operation. The capacitor is not required when powering the POL regulator from an input source with an inductance below 10  $\mu$ H.

## External Decoupling Capacitors

When powering loads with significant dynamic current requirements, the voltage regulation at the point of load can be improved by addition of decoupling capacitors at the load. The most effective technique is to locate low ESR ceramic and electrolytic capacitors as close to the load as possible, using several parallel capacitors to lower the effective ESR. The ceramic capacitors will handle high-frequency dynamic load changes while the electrolytic capacitors are used to handle low frequency dynamic load changes. Ceramic capacitors will also reduce any high frequency noise at the load.

It is equally important to use low resistance and low inductance PCB layouts and cabling.

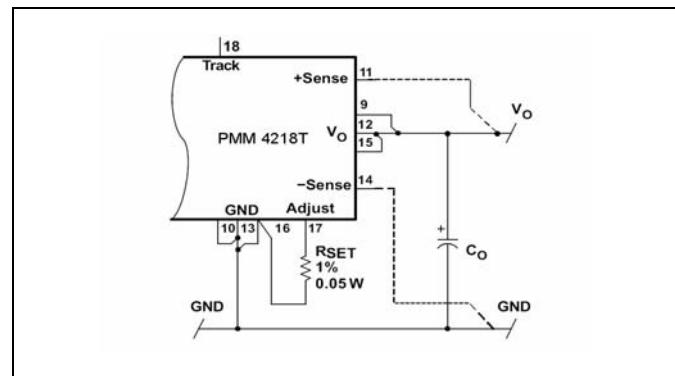
External decoupling capacitors will become part of the control loop of the POL regulator and may affect the stability margins. As a "rule of thumb", 100  $\mu$ F/A of output current can be added without any additional analysis. The ESR of the capacitors is a very important parameter. Power Modules guarantee stable operation with a verified ESR value of  $>10$  m $\Omega$  across the output connections.

For further information please contact your local Ericsson Power Modules representative.

## Output Voltage Adjust (V<sub>adj</sub>)

The output voltage can be set by means of an external resistor, connected to the V<sub>adj</sub> pin. Nominal output voltage 0.8 V is set by leaving the V<sub>adj</sub> pin open. Adjustment can only be made to increase the output voltage setting.

To increase the voltage a resistor should be connected between the V<sub>adj</sub> pin and GND pin. The resistor value of the Output voltage adjust function is according to information given under the Output section for the respective product.



## UVLO Adjustment

The UVLO feature of the PMM family module allows for limited adjustment of both the on threshold and hysteresis voltages. The adjustment is made via the UVLO Prog control pin. When the UVLO Prog pin is left open circuit, the on threshold and hysteresis voltages are internally set to their default values. The on threshold has a nominal voltage of 2.63 V, and the hysteresis is 0.62 V. This ensures that the module produces a regulated output when the minimum input voltage is applied. The combination correlates to an off threshold of approximately 2.0 V. The adjustments are limited. The on threshold can only be adjusted higher, and the hysteresis voltage can only be reduced in magnitude.

## Parallel Operation

Two POL regulators may be paralleled for redundancy if the total power is equal or less than P<sub>O</sub> max. It is not recommended to parallel the POL regulators without using external current sharing circuits.

## Remote Sense

The POL regulators have remote sense that can be used to compensate for voltage drops between the output and the point of load. The sense traces should be located close to the PCB ground layer to reduce noise susceptibility. The remote sense circuitry will compensate for up to 0.3v voltage drop between output pins and the point of load.

If the remote sense is not needed +Sense and -Sense should be left open.

PMM 4000 series POL regulator, Input 2.95-5.5 V, Output 60 A/150 W	EN/LZT 146 337 R1A April 2006 © Ericsson Power Modules AB
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### Over Temperature Protection (OTP)

The PMM family of POL regulators are protected from thermal overload by an internal over temperature shutdown circuit. When the internal temperature exceeds the OTP threshold, the POL regulator will shut down. The POL regulator will make continuous attempts to start up (soft-start mode) and resume normal operation automatically when the temperature has dropped  $>10^{\circ}\text{C}$  below the temperature threshold.

### Over Current Protection (OCP)

The POL regulators include current limiting circuitry for protection at continuous overload. The output voltage will decrease towards zero for output currents in excess of the over-current threshold. The regulator will resume normal operation after removal of the overload. The load distribution should be designed for the maximum output short circuit current specified. The current limit operation is a "hick up" mode current limit.

### Soft-start Power Up

From the moment a valid input voltage is applied, the soft-start control introduces a short time-delay (typically 5-10 ms) before allowing the output voltage to rise. The initial rise in input current when the input voltage first starts to rise is the charge current drawn by the input capacitors. Power-up is complete within 15 ms.

### Auto-Track™ Function

The AutoTrack function is designed so that 2 or more POL regulators can track each others output voltage tightly together. This can be accomplished by connection the AutoTrack pin to the output of another POL regulator or by feeding an external voltage ramp on the pin. The AutoTrack will automatically track any external voltage that is applied within the given rules in Application Note POLA (AN205).

### Margin Up/Down controls

The margin control allows the input voltage to be momentarily adjusted, either up or down, by a nominal 5 %. This provides a convenient method for dynamically testing the operation of the load circuit over its supply margin or range. It can also be used to verify the function of supply voltage supervisors.

### Pre-Bias Startup Capability

This often occurs in complex digital systems when current from another power source is backfed through a dual-supply logic component, such as FPGA or ASIC.

The PMM family incorporate synchronous rectifiers, but will not sink current during startup, or whenever the Inhibit pin is held low. However, to ensure satisfactory operation of this function, the input voltage must always be greater than the output voltage throughout the power-up and power down sequence.

### Thermal Consideration

#### General

The POL regulators are designed to operate in different thermal environments and sufficient cooling must be provided to ensure reliable operation. Cooling is achieved mainly by conduction, from the pins to the host board, and convection, which is dependant on the airflow across the regulator. Increased airflow enhances the cooling of the POL regulator.

The Output Current Derating graph found in the Output section for each model provides the available output current vs. ambient air temperature and air velocity at  $V_{in} = 3.3$  V.

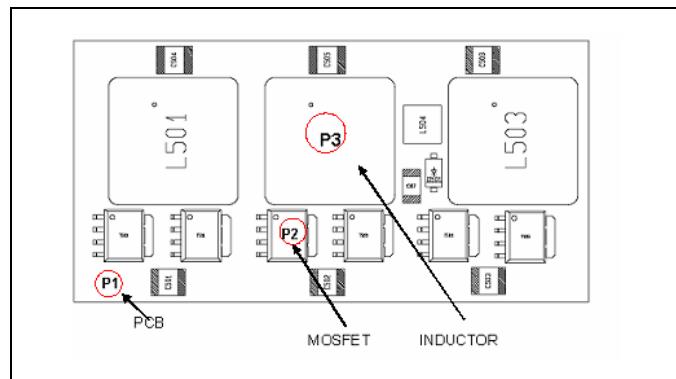
The POL regulator is tested on a 254 x 254 mm, 35  $\mu\text{m}$  (1 oz), 8-layer test board mounted vertically in a wind tunnel with a cross-section of 305 x 305 mm.

Proper cooling of the POL regulator can be verified by measuring the temperature at positions P1, P2 and P3. The temperature at these positions should not exceed the max values provided in the table below.

Note that the max value is the absolute maximum rating (non destruction) and that the electrical Output data is guaranteed up to  $T_{amb} +85^{\circ}\text{C}$ .

See Design Note 019 for further information.

Position	Device	Designation	max value
P <sub>1</sub>	Pcb		130° C
P <sub>2</sub>	Mosfet	T <sub>ref</sub>	135° C
P <sub>3</sub>	Inductor		125° C



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## Thermal Consideration continued

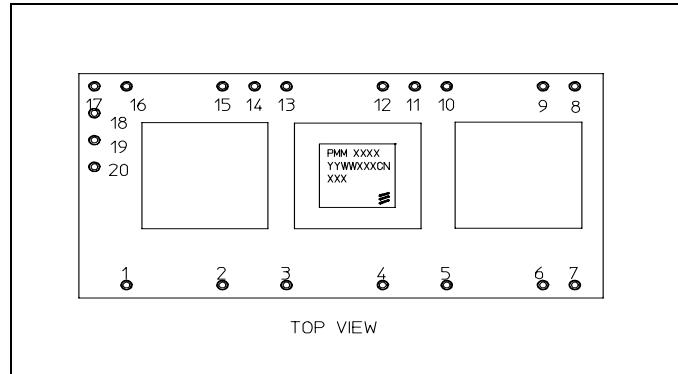
### Definition of reference temperature ( $T_{ref}$ )

The reference temperature is used to monitor the temperature limits of the product. Temperatures above maximum  $T_{ref}$  are not allowed and may cause degradation or permanent damage to the product.  $T_{ref}$  is also used to define the temperature range for normal operating conditions.  $T_{ref}$  is defined by the design and used to guarantee safety margins, proper operation and high reliability of the module.

### Ambient Temperature Calculation

TBD

## Connections



Pin	Designation	Function
1, 3, 5, 10, 13, 16	GND	Common ground connection for the $V_{in}$ and $V_{out}$ power connections.
2, 4, 6	$V_{in}$	The positive input voltage power node to the module.
7	Inhibit	Applying a low-level ground signal to this input disables the module's output.
8	UVLO Prog	Connecting a resistor from this pin to ground allows the on threshold of the input undervoltage lockout (UVLO) to be adjusted higher than the default value.
9, 12, 15	$V_{out}$	The regulated positive power output with respect to the GND node.
11	+Sense	The sense input allows the regulation circuit to compensate for voltage drop between the module and the load. If used, it should be connected to $V_o$ .
14	-Sense	If used, -Sense should be connected to the ground return at the load.
17	$V_o$ Adjust	A 0.05 W 1% resistor must be directly connected between this pin and GND to set the output voltage.
18	Track	This is an analog control input that enables the output voltage to follow an external voltage.
19	Margin Up	When this input is asserted to GND, the output voltage is increased by 5%.
20	Margin Down	When this input is asserted to GND, the output voltage is decreased by 5% from the nominal.

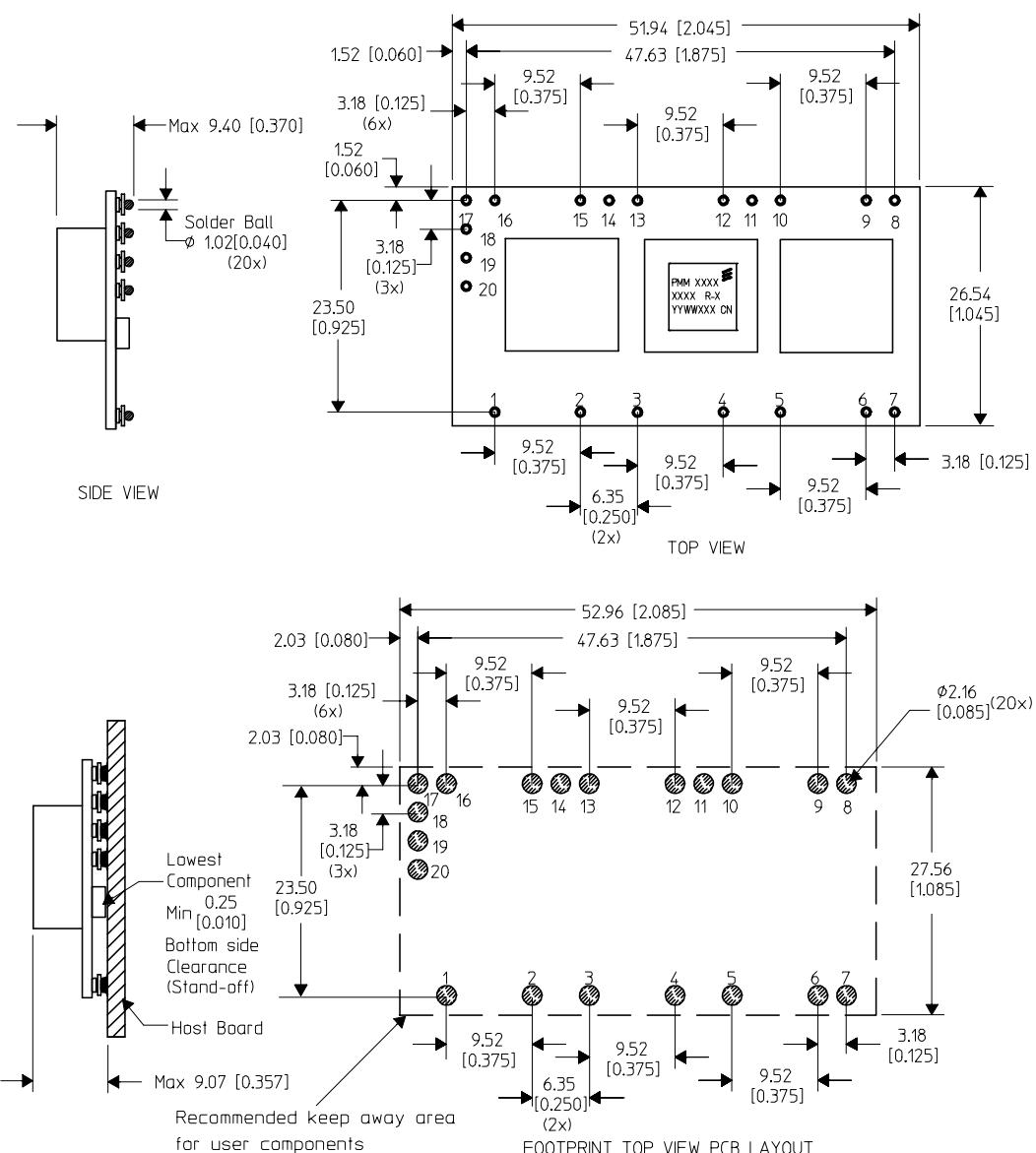
PMM 4000 series

EN/LZT 146 337 R1A April 2006

POL regulator, Input 2.95-5.5 V, Output 60 A/150 W

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## Mechanical Information (Surface mount version)



NOTES:

- A. All linear dimensions are in mm [inch].
- B. This drawing is subject to change without notice.
- C. 1 place decimals are  $\pm 0.76$  [ $\pm 0.030$ ].
- D. 2 place decimals are  $\pm 0.25$  [ $\pm 0.010$ ].
- E. Recommended keep out area for user components.
- F. Power pin connection should utilize four or more vias to the interior power plane of 0.64 [0.025] I.D. per input, ground and output pin (or the electrical equivalent).

G. Paste screen opening: 2.03 [0.080] to 2.16 [0.085].  
Paste screen thickness: 0.15 [0.006].

H. Pad type: Solder mask defined.

I. All pins: Material - Copper Alloy  
Plating - 10 $\mu$ m Tin over 4 $\mu$ m Nickel  
Solder Ball - See product data sheet.

J. Dimension prior to reflow solder.  
Weight : 16.8 g

Use recommended footprint and solder recommendations together with solder reflow recommendation to ensure a reliable interconnection.



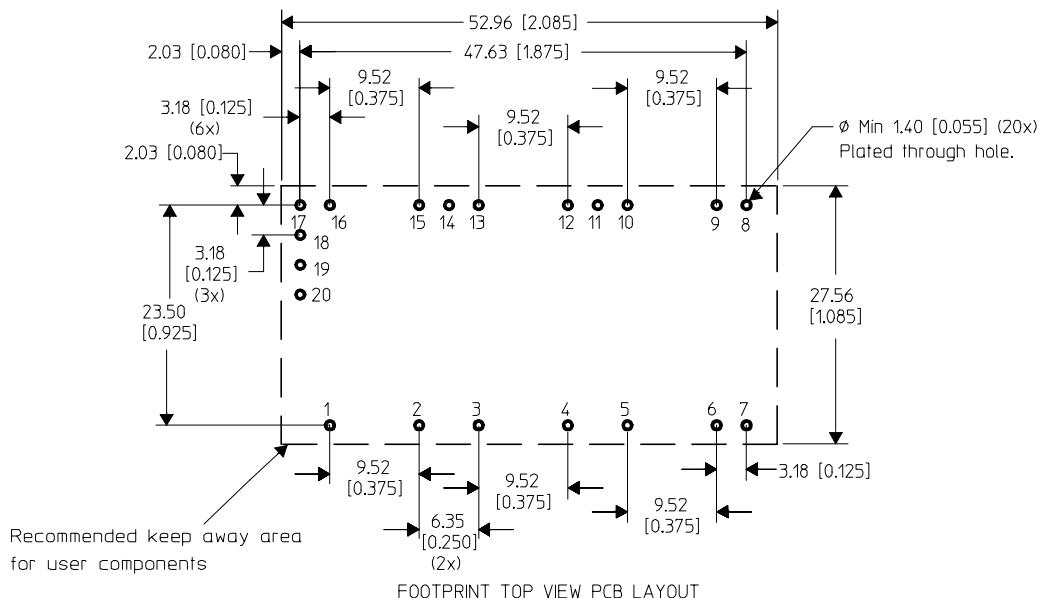
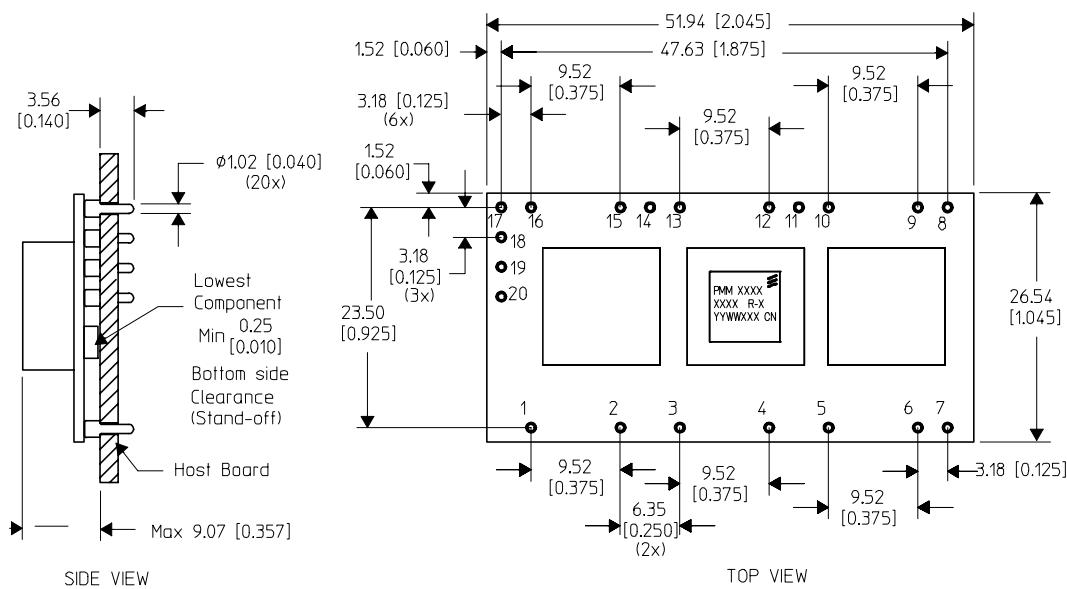
PMM 4000 series

EN/LZT 146 337 R1A April 2006

POL regulator, Input 2.95-5.5 V, Output 60 A/150 W

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## Mechanical Information (Through hole mount version)



NOTES:

- A. All linear dimensions are in mm [inch].
- B. This drawing is subject to change without notice.
- C. 1 place decimals are  $\pm 0.76$  [ $\pm 0.030$ ].
- D. 2 place decimals are  $\pm 0.25$  [ $\pm 0.010$ ].
- E. Recommended keep out area for user components.



- F. Pins are 1.02 [0.040] diameter with 1.78 [0.070] diameter standoff shoulder.
- G. All pins: Material - Copper Alloy  
Plating - 10 $\mu$ m Tin over 4 $\mu$ m Nickel  
Weight : 17.6 g

Use recommended footprint and solder recommendations together with solder reflow recommendation to ensure a reliable interconnection.

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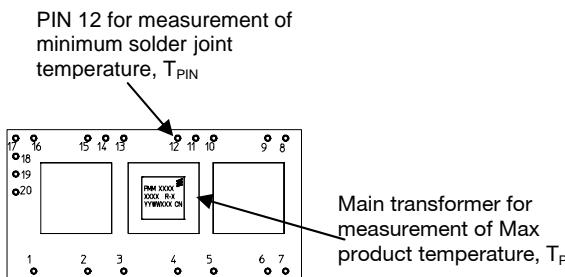
### Soldering Information - Surface mounting

The surface mount version of product is intended for convection or vapor phase reflow Pb-free processes. To achieve a good and reliable soldering result, make sure to follow the recommendations from the solder paste supplier, to use state-of-the-art reflow equipment and reflow profiling techniques as well as the following guidelines.

A no-clean flux is recommended to avoid entrapment of cleaning fluids in cavities inside of the DC/DC regulator. The cleaning residues may affect long time reliability and isolation voltage.

### Minimum pin temperature recommendations

Pin number 12 is recommended as reference location for the minimum pin temperature recommendations since this will be the coolest solder joint during the reflow process.



### SnPb solder processes

For Pb solder processes, a pin temperature ( $T_{PIN}$ ) in excess of the solder melting temperature, ( $T_L$ , +183 °C for Sn63/Pb37) for more than 30 seconds, and a peak temperature of +210 °C is recommended to ensure a reliable solder joint.

### Lead-free (Pb-free) solder processes

For Pb-free solder processes, a pin temperature ( $T_{PIN}$ ) in excess of the solder melting temperature ( $T_L$ , +217 to +221 °C for Sn/Ag/Cu solder alloys) for more than 30 seconds, and a peak temperature of +235 °C on all solder joints is recommended to ensure a reliable solder joint.

### Maximum regulator temperature requirements

To avoid damage or performance degradation of the product, the reflow profile should be optimized to avoid excessive heating. The maximum product temperature shall be monitored by attaching a thermal coupler to the top of the main transformer.

A sufficiently extended preheat time is recommended to ensure an even temperature across the host PCB, for both small and large devices. To reduce the risk of excessive heating is also recommended to reduce the time in the reflow zone as much as possible.

### SnPb solder processes

For conventional SnPb solder processes, the product is qualified for MSL 1 according to IPC/JEDEC standard J-STD-020C.

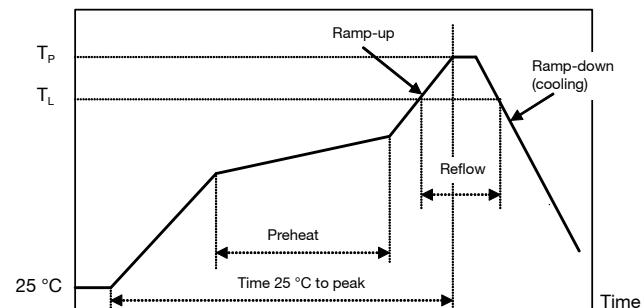
During reflow,  $T_P$  must not exceed +225 °C at any time.

### Lead-free (Pb-free) solder processes

For Pb-free solder processes, the product is qualified for MSL 3 according to IPC/JEDEC standard J-STD-020C.

During reflow,  $T_P$  must not exceed +260 °C at any time.

Temperature



Profile features	Sn/Pb eutectic assembly	Pb-free assembly
Average ramp-up rate	3 °C/s max	3 °C/s max
Solder melting temperature (typical)	$T_L$	+183 °C
Peak converter temperature	$T_P$	+225 °C
Average ramp-down rate		6 °C/s max
Time 25 °C to peak temperature	6 minutes max	8 minutes max

PMM 4000 series POL regulator, Input 2.95-5.5 V, Output 60 A/150 W	EN/LZT 146 337 R1A April 2006 © Ericsson Power Modules AB
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### Soldering Information – Through Hole Mounting

The through hole mount version of the product is intended for through hole mounting on a PCB. When wave soldering is used, the temperature on the pins is specified to maximum 260 °C for maximum 10 seconds.

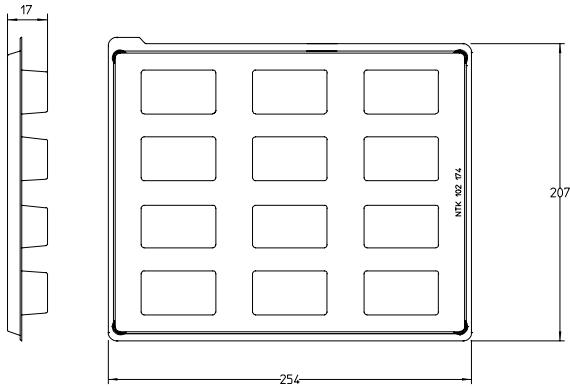
Maximum preheat rate of 4 °C/s and temperature of max 150 °C is suggested. When hand soldering, care should be taken to avoid direct contact between the hot soldering iron tip and the pins for more than a few seconds in order to prevent overheating.

A no-clean (NC) flux is recommended to avoid entrapment of cleaning fluids in cavities inside of the DC/DC power module. The residues may affect long time reliability and isolation voltage.

### Delivery package information

The products are delivered antistatic trays.

Tray specifications	
<b>Material</b>	PET
<b>Surface resistance</b>	10E3 to 10E5 ohms/square
<b>Bake ability</b>	The trays cannot be baked
<b>Tray capacity</b>	12 converters/tray
<b>Box capacity</b>	60 converters (full trays/box)



### Dry pack information

The products are delivered in trays. These inner shipment containers are dry packed in standard moisture barrier bags according to IPC/JEDEC standard J-STD-033A (Handling, packing, shipping and use of moisture/reflow sensitivity surface mount devices).

Using products in high temperature Pb-free soldering processes requires dry pack storage and handling. In case the products have been stored in an uncontrolled environment and no longer can be considered dry, the modules must be baked according to the referred IPC/JEDEC standard.

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**Product Qualification Specification (pending)**

Characteristics			
Visual inspection	JESD22-B101		
Temperature cycling	JESD22-A104-B	Dwell time Transfer time Temperature range Number of cycles	30 min 0-1 min -40 °C to +125 °C 300 cycles
High temperature storage life	JESD22-A103-B	Temperature Duration	125 °C 1000 h
Cold (in operation)	IEC 68-2-1A, test Ad	Temperature T <sub>A</sub> Duration	-45 °C 72 h
Lead integrity	JESD22-B105-C	Test condition A Weight Duration	1000 g 30 s
Solder ability(only apply to through hole version)	IEC 68-2-54	Solder immersion depth Duration of immersion (F <sub>C</sub> time) T <sub>A</sub> (time for onset of wetting) Time to F <sub>B</sub> Wetting strength F <sub>B</sub> Stability F <sub>C</sub> /F <sub>B</sub>	1 mm 15 s <4 s 8 s >100 mN/m >0.8
Steady State Temperature Humidity Bias Life Test	JESD22-A101-B	Temperature Humidity Duration Input Voltage	+85 °C 85 % RH 1000 hours Maximum
Mechanical shock	JESD22-B104-B	Peak acceleration Duration Number of shocks	200 g 1.5 ms 5 in each of two directions of three axes
Vibration, variable freq	JESD22-B103-B	Frequency range Acceleration amplitude	10-1000 Hz 10 g or displacement amplitude 1.0 mm
Random vibration	JESD22-B103-B	Frequency Acceleration density	2-500 Hz 0.008-0.2 g <sup>2</sup> /Hz
Operational life test		Temperature Load ON OFF Test duration	85 °C Maximum 9 min 3 min 1000 h
Moisture reflow sensitivity classification test	J-STD-020C	SnPb eutectic MSL 1	225 °C
		Pb free MSL 3	260 °C
Resistance to cleaning agents	IEC 68-2-45 Xa Method 2	Water Glycol ether Isopropyl alcohol	+55 ±5 °C +35 ±5 °C +35 ±5 °C