

FEATURES AND BENEFITS

- · AEC-Q100 Grade 1 qualified
- Typical of 2.5 µs output response time
- 3.3 V supply operation
- Ultra-low power loss: $100 \,\mu\Omega$ internal conductor resistance
- Reinforced galvanic isolation allows use in economical, high-side current sensing in high-voltage systems
- 4800 Vrms dielectric strength certified under UL60950-1
- Industry-leading noise performance with greatly improved bandwidth through proprietary amplifier and filter design techniques
- Integrated shield greatly reduces capacitive coupling from current conductor to die due to high dV/dt signals, and prevents offset drift in high-side, high-voltage applications
- Greatly improved total output error through digitally programmed and compensated gain and offset over the full operating temperature range
- · Small package size, with easy mounting capability
- · Monolithic Hall IC for high reliability
- Output voltage proportional to AC or DC currents
- · Factory-trimmed for accuracy
- Extremely stable output offset voltage

PACKAGE: 5-pin package (suffix CB)



Not to scale

DESCRIPTION

The AllegroTM ACS773 family of current sensor ICs provide economical and precise solutions for AC or DC current sensing, ideal for motor control, load detection and management, power supply and DC-to-DC converter control, and inverter control. The 2.5 μs response time enables overcurrent fault detection in safety-critical applications.

The device consists of a precision, low-offset linear Hall circuit with a copper conduction path located near the die. Applied current flowing through this copper conduction path generates a magnetic field which the Hall IC converts into a proportional voltage. Device accuracy is optimized through the close proximity of the magnetic signal to the Hall transducer. A precise, proportional output voltage is provided by the low-offset, chopper-stabilized BiCMOS Hall IC, which is programmed for accuracy at the factory. Proprietary digital temperature compensation technology greatly improves the IC accuracy and temperature stability.

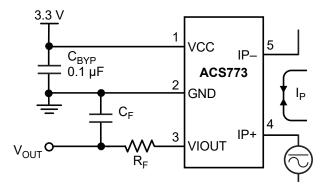
High-level immunity to current conductor dV/dt and stray electric fields is offered by Allegro proprietary integrated shield technology for low output voltage ripple and low offset drift in high-side, high-voltage applications.

The output of the device increases when an increasing current flows through the primary copper conduction path (from terminal 4 to terminal 5), which is the path used for current sampling. The internal resistance of this conductive path is $100~\mu\Omega$ typical, providing low power loss.

The thickness of the copper conductor allows survival of the device at high overcurrent conditions. The terminals of the conductive path are electrically isolated from the signal leads (pins 1 through 3). This allows the ACS773 family of sensor

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Application 1: the ACS773 outputs an analog signal, V_{OUT} , that varies linearly with the bidirectional AC or DC primary sensed current, I_P , within the range specified. R_F and C_F are for optimal noise management, with values that depend on the application.



Typical Application

ACS773

DESCRIPTION (continued)

ICs to be used in applications requiring electrical isolation without the use of opto-isolators or other costly isolation techniques.

The device is fully calibrated prior to shipment from the factory. The ACS773 family is lead (Pb) free. All leads are plated with 100% matte tin, and there is no Pb inside the package. The heavy gauge leadframe is made of oxygen-free copper.

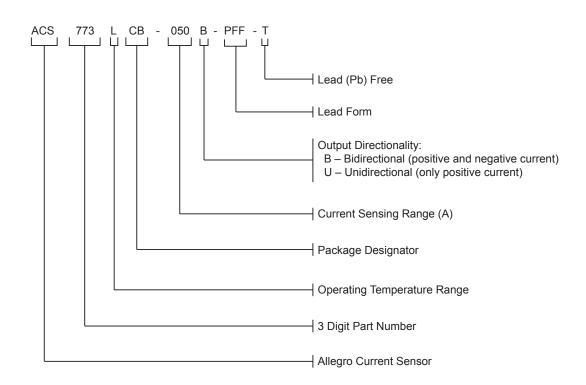


SELECTION GUIDE

	Package		Primary Sampled	Sensitivity	т	
Part Number [1]	Terminals	Signal Pins	Current , I _P (A)	Sens (Typ.) (mV/A) ^[2]	T _A (°C)	Packing ^[3]
ACS773LCB-050B-PFF-T	Formed	Formed	±50	26.4	-40 to 150	
ACS773LCB-100B-PFF-T	Formed	Formed	±100	13.2	-40 to 150	- · ·
ACS773KCB-150B-PFF-T	Formed	Formed	±150	8.8	-40 to 125	34 pieces per tube
ACS773ECB-200B-PFF-T	Formed	Formed	±200	6.6	-40 to 85	por tabo
ACS773ECB-250U-PSF-T	Straight	Formed	250	10.56	-40 10 65	

^[1] Additional leadform options available for qualified volumes.

^[3] Contact Allegro for additional packing options.



 $^{^{[2]}}$ Measured at V_{CC} = 3.3 V.

ABSOLUTE MAXIMUM RATINGS

Characteristic	Symbol	Notes	Rating	Unit
Supply Voltage	V _{cc}		6.5	V
Reverse Supply Voltage	V _{RCC}		-0.5	V
Output Voltage	V _{IOUT}		6.5	V
Reverse Output Voltage	V _{RIOUT}		-0.5	V
Output Source Current	I _{OUT(Source)}	VIOUT to GND	3	mA
Output Sink Current	I _{OUT(Sink)}	Minimum pull-up resistor of 500 Ω from VCC to VIOUT	10	mA
		Range E	-40 to 85	°C
Nominal Operating Ambient Temperature [1]	T _A	Range K	-40 to 125	°C
		Range L	-40 to 150	°C
Maximum Junction Temperature	T _{J(max)}		165	°C
Storage Temperature	T _{stg}		-65 to 165	°C

^[1] All ACS773 devices are production tested and guaranteed to 150°C. T_A is derated for continuous operation above I_P = 100 A. See thermal application section for more information.

ISOLATION CHARACTERISTICS

Characteristic	Characteristic Symbol Notes		Rating	Unit
Dielectric Surge Strength Test Voltage $V_{SURGE} = V_{SURGE} = V$		8000	V	
Dielectric Strength Test Voltage [2]	V _{ISO}	Agency type-tested for 60 seconds per UL standard 60950-1, 2nd Edition. Tested at 3000 V _{RMS} for 1 second in production.	4800	V _{RMS}
Working Voltage for Basic Isolation	V	For basic (single) isolation per UL standard 60950-1, 2nd	990	V _{PK} or V _{DC}
Working Voltage for basic Isolation	V_{WVBI}	Edition	700	V _{RMS}
Working Voltage for Reinforced Isolation	V	For reinforced (double) isolation per UL standard	636	V _{PK} or V _{DC}
vvoiking voitage for ixemiorced isolation	V_{WFRI}	60950-1, 2nd Edition	450	V _{RMS}

^[2] Allegro does not conduct 60-second testing. It is done only during the UL certification process.

THERMAL CHARACTERISTICS: May require derating at maximum conditions

Characteristic	Symbol	Test Conditions [3]	Value	Unit
Package Thermal Resistance	R _{θJA}	Mounted on the Allegro evaluation board with 2800 mm ² (1400 mm ² on component side and 1400 mm ² on opposite side) of 4 oz. copper connected to the primary leadframe and with thermal vias connecting the copper layers. Performance is based on current flowing through the primary leadframe and includes the power consumed by the PCB.	7	°C/W

^[3] Additional thermal information available on the Allegro website

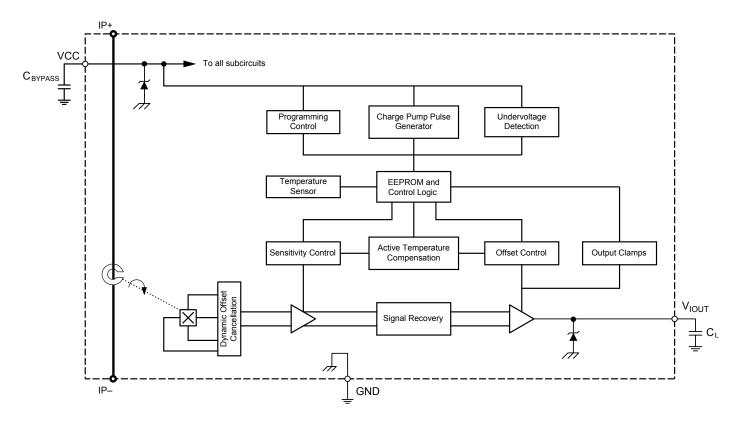
TYPICAL OVERCURRENT CAPABILITIES [4][5]

Characteristic	Symbol	Notes	Rating	Unit
		T _A = 25°C, current is on for 1 second and off for 99 seconds, 100 pulses applied	1200	Α
Overcurrent	I _{POC}	T _A = 85°C, current is on for 1 second and off for 99 seconds, 100 pulses applied	900	Α
		T _A = 150°C, current is on for 1 second and off for 99 seconds, 100 pulses applied	600	Α

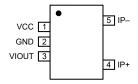
 $^{^{[4]}}$ Test was done with Allegro evaluation board. The maximum allowed current is limited by $T_{J(max)}$ only.

^[5] For more overcurrent profiles, please see FAQ on the Allegro website, www.allegromicro.com.





Functional Block Diagram



Pinout Diagram

Terminal List Table

Number	Name	Description
1	VCC	Device power supply terminal
2	GND	Signal ground terminal
3	VIOUT	Analog output signal
4	IP+	Terminal for current being sampled
5	IP-	Terminal for current being sampled

COMMON OPERATING CHARACTERISTICS: Valid at T_A = -40°C to 150°C, C_{BYP} = 0.1 μF , and V_{CC} = 3.3 V, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Тур.	Max.	Unit					
ELECTRICAL CHARACTERISTICS											
Supply Voltage	V _{cc}		3	3.3	3.6	V					
Supply Current	I _{cc}	V _{CC} ≤ 5 V, no load on output	_	10	15	mA					
Power-On Delay	t _{POD}	T _A = 25°C	_	64	_	μs					
Power On Poset Voltage	V _{PORH}	V _{CC} rising at 1 V/ms	_	2.9	_	V					
Power-On Reset Voltage	V _{PORL}	V _{CC} falling at 1 V/ms	_	2.5	-	V					
POR Hysteresis	V _{HYS(POR)}		250	-	-	mV					
Internal Bandwidth	BWi	Small signal –3 dB, C _L = 4.7 nF	_	200	-	kHz					
Rise Time	t _r	I_P step = 50% of I_P +, 10% to 90% rise time, T_A = 25°C, C_{OUT} = 470 pF	_	2.4	_	μs					
Propagation Delay Time	t _{PROP}	T _A = 25°C, C _L = 470 pF, IP step = 50% of IP+	_	1.2	_	μs					
Response Time	t _{RESPONSE}	T _A = 25°C, C _L = 470 pF, IP step = 50% of IP+, 90% input to 90% output	_	2.5	_	μs					
DC Output Impedance	R _{OUT}	T _A = 25°C	_	3.3	_	Ω					
Output Load Resistance	R _{LOAD(MIN)}	VIOUT to GND, VIOUT to VCC	4.7	-	_	kΩ					
Output Load Capacitance	C _{LOAD(MAX)}	VIOUT to GND	_	1	10	nF					
Primary Conductor Resistance	R _{PRIMARY}	T _A = 25°C	_	100	_	μΩ					
Output Saturation Voltage	V _{SAT(HIGH)}	$T_A = 25$ °C, $R_{L(PULLDWN)} = 10$ kΩ to GND	V _{CC} - 0.2	_	_	V					
Output Saturation voltage	V _{SAT(LOW)}	$T_A = 25$ °C, $R_{L(PULLUP)} = 10 \text{ k}\Omega$ to VCC	_	_	200	mV					
ERROR COMPONENTS											
QVO Ratiometry Error [1]	Rat _{ERRQVO}	V _{CC} = 3.15 to 3.45 V	_	±0.15	_	%					
Sens Ratiometry Error [1]	Rat _{ERRSens}	V _{CC} = 3.15 to 3.45 V	_	±0.3	_	%					
Nicion		Input referenced noise density; T _A = 25°C, C _L = 1 nF	_	0.2	_	mA/√(Hz)					
Noise	I _N	Input referenced noise at 200 kHz; T _A = 25°C, C _L = 1 nF	_	120	_	mA _{RMS}					
Nonlinearity [1]	E _{LIN}	Up to full scale of I _P	-0.9	±0.5	0.9	%					
Symmetry [1]	E _{SYM}	Over half-scale I _P	-0.8	±0.4	0.8	%					

 $[\]ensuremath{^{[1]}}$ See Characteristic Definitions section of this datasheet.



X050B PERFORMANCE CHARACTERISTICS: $T_A = -40$ °C to 150°C, $V_{CC} = 3.3$ V, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ. ^[2]	Max.	Unit
NOMINAL PERFORMANCE						
Current Sensing Range [1]	I _{PR}		-50	_	50	А
Sensitivity	Sens	$I_{PR(min)} < I_{P} < I_{PR(max)}$	_	26.4 × V _{CC} / 3.3	_	mV/A
Zero Current Output Voltage	V _{IOUT(Q)}	Bidirection; I _P = 0 A	_	V _{CC} /2	_	V
ACCURACY PERFORMANCE			`			
Neter	.,	T _A = 25°C, C _L = 1 nF	_	19.2	_	mV _{p-p}
Noise	V _N	T _A = 25°C, C _L = 1 nF	_	3.2	_	mV _{RMS}
		Full scale of I _P , T _A = 25°C	-1	±0.5	1	%
Sensitivity Error	E _{Sens}	Full scale of I _P , T _A = 25°C to 150°C	-1.25	±1	1.25	%
		Full scale of I _P , T _A = -40°C to 25°C	-3.5	±1.5	3.5	%
	V _{OE(TA)}	I _P = 0 A, T _A = 25°C	-8	±4	8	mV
Electrical Offset Error	V _{OE(TA)HT}	I _P = 0 A, T _A = 25°C to 150°C	-8	±4	8	mV
	V _{OE(TA)LT}	$I_P = 0 \text{ A}, T_A = -40^{\circ}\text{C to } 25^{\circ}\text{C}$	-20	±6	20	mV
Magnetic Offset Error	I _{ERROM}	I _P = 0 A, T _A = 25°C, after excursion of I _{PR(max)}	_	210	250	mA
Total Output From	E _{TOT(HT)}	Full scale of I _p , T _A = 25°C to 150°C	-1.5	±1	1.5	%
Total Output Error	E _{TOT(LT)}	Full scale of I _P , T _A = -40°C to 25°C	-3.5	±1.5	3.5	%
LIFETIME ACCURACY CHARACTE	RISTICS [3]					
Sensitivity Error Including Lifetime	E _{Sens(LIFE)(HT)}	T _A = 25°C to 150°C	-2.1	±1.6	2.1	%
Sensitivity Error including Lifetime	E _{Sens(LIFE)(LT)}	$T_A = -40^{\circ}\text{C to } 25^{\circ}\text{C}$	-3.5	±2.5	3.5	%
Total Output Error Including Lifetime	E _{TOT(LIFE)(HT)}	T _A = 25°C to 150°C	-2.1	±1.7	2.1	%
Total Output Error including Lifetime	E _{TOT(LIFE)(LT)}	$T_A = -40$ °C to 25°C	-3.5	±2.6	3.5	%
Electric Offset Error Including Lifetime	E _{OFF(LIFE)(HT)}	T _A = 25°C to 150°C	-10	±7	10	mV
Liectife Offset Effor including Effetime	E _{OFF(LIFE)(LT)}	$T_A = -40^{\circ}\text{C to } 25^{\circ}\text{C}$	-20	±8.9	20	mV

^[1] Device may be operated at higher primary current levels, I_P, ambient, T_A, and internal leadframe temperatures, provided that the Maximum Junction Temperature, T_{J(max)}, is not exceeded.



^[2] Typical values are ±3 sigma values.

^[3] Min/max limits come from AEC-Q100 Grade 1 testing.

X100B PERFORMANCE CHARACTERISTICS: $T_A = -40$ °C to 150°C, $V_{CC} = 3.3$ V, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ.[2]	Max.	Unit
NOMINAL PERFORMANCE	,		'			
Current Sensing Range [1]	I _{PR}		-100	_	100	Α
Sensitivity	Sens	$I_{PR(min)} < I_{P} < I_{PR(max)}$	_	13.2 × V _{CC} / 3.3	_	mV/A
Zero Current Output Voltage	V _{IOUT(Q)}	Bidirection; I _P = 0 A	_	V _{CC} /2	_	V
ACCURACY PERFORMANCE						
Nicion		T _A = 25°C, C _L = 1 nF	_	9.6	_	mV _{p-p}
Noise	V _N	T _A = 25°C, C _L = 1 nF	_	1.6	_	mV _{RMS}
Sensitivity Error		Full scale of I _P , T _A = 25°C	-1	±0.5	1	%
	E _{Sens}	Full scale of I _P , T _A = 25°C to 150°C	-1.25	±1	1.25	%
		Full scale of I _P , T _A = -40°C to 25°C	-3.5	±1.5	3.5	%
	V _{OE(TA)}	I _P = 0 A, T _A = 25°C	-8	±4	8	mV
Electrical Offset Error	V _{OE(TA)HT}	I _P = 0 A, T _A = 25°C to 150°C	-8	±4	8	mV
	V _{OE(TA)LT}	$I_P = 0 \text{ A}, T_A = -40^{\circ}\text{C to } 25^{\circ}\text{C}$	-20	±6	20	mV
Magnetic Offset Error	I _{ERROM}	$I_P = 0 \text{ A}, T_A = 25^{\circ}\text{C}, \text{ after excursion of } I_{PR(max)}$	_	280	400	mA
Total Output From	E _{TOT(HT)}	Full scale of I _P , T _A = 25°C to 150°C	-1.5	±1	1.5	%
Total Output Error	E _{TOT(LT)}	Full scale of I _P , T _A = -40°C to 25°C	-3.5	±1.5	3.5	%
LIFETIME ACCURACY CHARACTE	RISTICS [3]					
Sensitivity Error Including Lifetime	E _{Sens(LIFE)(HT)}	T _A = 25°C to 150°C	-2.1	±1.6	2.1	%
Sensitivity Error including Lifetime	E _{Sens(LIFE)(LT)}	T _A = -40°C to 25°C	-3.5	±2.5	3.5	%
Total Output Error Including Lifetime	E _{TOT(LIFE)(HT)}	T _A = 25°C to 150°C	-2.1	±1.7	2.1	%
Total Output Error including Lifetime	E _{TOT(LIFE)(LT)}	T _A = -40°C to 25°C	-3.5	±2.6	3.5	%
Floatria Officet Franchischich Lifetine	E _{OFF(LIFE)(HT)}	T _A = 25°C to 150°C	-10	±7	10	mV
Electric Offset Error Including Lifetime	E _{OFF(LIFE)(LT)}	T _A = -40°C to 25°C	-20	±8.9	20	mV

^[1] Device may be operated at higher primary current levels, I_P, ambient, T_A, and internal leadframe temperatures, provided that the Maximum Junction Temperature, T_{J(max)}, is not exceeded.



^[2] Typical values are ±3 sigma values.

^[3] Min/max limits come from AEC-Q100 Grade 1 testing.

X150B PERFORMANCE CHARACTERISTICS: $T_A = -40$ °C to 125°C, $V_{CC} = 3.3$ V, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ.[2]	Max.	Unit
NOMINAL PERFORMANCE						
Current Sensing Range [1]	I _{PR}		-150	_	150	А
Sensitivity	Sens	$I_{PR(min)} < I_{P} < I_{PR(max)}$	-	8.8 × V _{CC} / 3.3	_	mV/A
Zero Current Output Voltage	V _{IOUT(Q)}	Bidirection; I _P = 0 A	_	V _{CC} /2	_	V
ACCURACY PERFORMANCE			•			
Naiss	.,	T _A = 25°C, C _L = 1 nF	_	9.6	_	mV _{p-p}
Noise	V _N	T _A = 25°C, C _L = 1 nF	_	1.6	_	mV _{RMS}
		Full scale of I _P , T _A = 25°C	-1	±0.7	1	%
Sensitivity Error	E _{Sens}	Full scale of I _P , T _A = 25°C to 125°C	-1.25	±0.8	1.25	%
		Full scale of I _P , T _A = -40°C to 25°C	-3.5	±1.7	3.5	%
	V _{OE(TA)}	I _P = 0 A, T _A = 25°C	-8	±4	8	mV
Electrical Offset Error	V _{OE(TA)HT}	I _P = 0 A, T _A = 25°C to 125°C	-8	±4	8	mV
	V _{OE(TA)LT}	$I_P = 0 \text{ A}, T_A = -40^{\circ}\text{C to } 25^{\circ}\text{C}$	-20	±6	20	mV
Magnetic Offset Error	I _{ERROM}	I _P = 0 A, T _A = 25°C, after excursion of I _{PR(max)}	_	280	450	mA
Total Output From	E _{TOT(HT)}	Full scale of I _P , T _A = 25°C to 125°C	-1.5	±0.9	1.5	%
Total Output Error	E _{TOT(LT)}	Full scale of I _P , T _A = -40°C to 25°C	-3.5	±1.7	3.5	%
LIFETIME ACCURACY CHARACTE	RISTICS [3]		1			
Consitivity From Including Lifetime	E _{Sens(LIFE)(HT)}	T _A = 25°C to 125°C	-2.1	±1.6	2.1	%
Sensitivity Error Including Lifetime	E _{Sens(LIFE)(LT)}	$T_A = -40$ °C to 25°C	-3.5	±2.5	3.5	%
Total Output Error Including Lifetime	E _{TOT(LIFE)(HT)}	T _A = 25°C to 125°C	-2.1	±1.7	2.1	%
Total Output Error Including Lifetime	E _{TOT(LIFE)(LT)}	$T_A = -40$ °C to 25°C	-3.5	±2.6	3.5	%
Electric Offset Error Including Lifetime	E _{OFF(LIFE)(HT)}	T _A = 25°C to 125°C	-10	±7	10	mV
Electric Offset Effor including Effetime	E _{OFF(LIFE)(LT)}	T _A = -40°C to 25°C	-20	±8.9	20	mV

^[1] Device may be operated at higher primary current levels, I_P, ambient, T_A, and internal leadframe temperatures, provided that the Maximum Junction Temperature, T_{J(max)}, is not exceeded.



^[2] Typical values are ±3 sigma values.

^[3] Min/max limits come from AEC-Q100 Grade 1 testing.

χ 200B PERFORMANCE CHARACTERISTICS: T_A = -40°C to 85°C, V_{CC} = 3.3 V, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ.[2]	Max.	Unit
NOMINAL PERFORMANCE			·			
Current Sensing Range [1]	I _{PR}		-200	_	200	Α
Sensitivity	Sens	$I_{PR(min)} < I_{P} < I_{PR(max)}$	_	6.6 × V _{CC} / 3.3	-	mV/A
Zero Current Output Voltage	V _{IOUT(Q)}	Bidirection; I _P = 0 A	_	V _{CC} /2	_	V
ACCURACY PERFORMANCE				,		-
Neise		T _A = 25°C, C _L = 1 nF	_	4.8	_	mV _{p-p}
Noise	V _N	T _A = 25°C, C _L = 1 nF	_	0.8	_	mV _{RMS}
		Full scale of I _P , T _A = 25°C	-1	±0.5	1	%
Sensitivity Error	E _{Sens}	Full scale of I _P , T _A = 25°C to 85°C	-1.25	±1	1.25	%
		Full scale of I _P , T _A = -40°C to 25°C	-3.5	±1.5	3.5	%
	V _{OE(TA)}	I _P = 0 A, T _A = 25°C	-8	±4	8	mV
Electrical Offset Error	V _{OE(TA)HT}	I _P = 0 A, T _A = 25°C to 85°C	-8	±4	8	mV
	V _{OE(TA)LT}	$I_P = 0 \text{ A}, T_A = -40^{\circ}\text{C to } 25^{\circ}\text{C}$	-20	±6	20	mV
Magnetic Offset Error	I _{ERROM}	$I_P = 0 \text{ A}, T_A = 25^{\circ}\text{C}, \text{ after excursion of } I_{PR(max)}$	_	380	450	mA
Total Output Error	E _{TOT(HT)}	Full scale of I _P , T _A = 25°C to 85°C	-1.5	±1	1.5	%
Total Output Elloi	E _{TOT(LT)}	Full scale of I _P , T _A = -40°C to 25°C	-3.5	±1.5	3.5	%
LIFETIME ACCURACY CHARACTE	RISTICS [3]					
Sensitivity Error Including Lifetime	E _{Sens(LIFE)(HT)}	T _A = 25°C to 85°C	-2.1	±1.6	2.1	%
Sensitivity Error including Lifetime	E _{Sens(LIFE)(LT)}	$T_A = -40$ °C to 25°C	-3.5	±2.5	3.5	%
Total Output Error Including Lifetime	E _{TOT(LIFE)(HT)}	T _A = 25°C to 85°C	-2.1	±1.7	2.1	%
Total Output Error Including Lifetime	E _{TOT(LIFE)(LT)}	$T_A = -40$ °C to 25°C	-3.5	±2.6	3.5	%
Electric Offset Error Including Lifetime	E _{OFF(LIFE)(HT)}	T _A = 25°C to 85°C	-10	±7	10	mV
Liebtile Offset Effor including Effetime	E _{OFF(LIFE)(LT)}	T _A = -40°C to 25°C	-20	±8.9	20	mV

^[1] Device may be operated at higher primary current levels, I_P, ambient, T_A, and internal leadframe temperatures, provided that the Maximum Junction Temperature, T_{J(max)}, is not exceeded.



^[2] Typical values are ±3 sigma values.
[3] Min/max limits come from AEC-Q100 Grade 1 testing.

X250U PERFORMANCE CHARACTERISTICS: $T_A = -40^{\circ}$ C to 85°C, $V_{CC} = 3.3$ V, unless otherwise specified

Characteristic	Symbol	Test Conditions	Min.	Typ.[2]	Max.	Unit
NOMINAL PERFORMANCE			·			
Current Sensing Range [1]	I _{PR}		0	_	250	Α
Sensitivity	Sens	$I_{PR(min)} < I_{P} < I_{PR(max)}$	_	10.56 × V _{CC} / 3.3	_	mV/A
Zero Current Output Voltage	V _{IOUT(Q)}	Bidirection; I _P = 0 A	_	V _{CC} /10	_	V
ACCURACY PERFORMANCE						
Noise	.,	T _A = 25°C, C _L = 1 nF		11.52	_	mV _{p-p}
Noise	V _N	T _A = 25°C, C _L = 1 nF	_	1.28	_	mV _{RMS}
		Full scale of I _P , T _A = 25°C	-1	±0.5	1	%
Sensitivity Error	E _{Sens}	Full scale of I _P , T _A = 25°C to 85°C	-1.25	±1	1.25	%
		Full scale of I _P , T _A = -40°C to 25°C	-3.5	±1.5	3.5	%
	V _{OE(TA)}	I _P = 0 A, T _A = 25°C	-8	±4	8	mV
Electrical Offset Error	V _{OE(TA)HT}	I _P = 0 A, T _A = 25°C to 85°C	-8	±4	8	mV
	V _{OE(TA)LT}	$I_P = 0 \text{ A}, T_A = -40^{\circ}\text{C to } 25^{\circ}\text{C}$	-20	±6	20	mV
Magnetic Offset Error	I _{ERROM}	I _P = 0 A, T _A = 25°C, after excursion of I _{PR(max)}	_	380	450	mA
Total Output Error	E _{TOT(HT)}	Full scale of I _P , T _A = 25°C to 85°C	-1.5	±1	1.5	%
Total Output Error	E _{TOT(LT)}	Full scale of I _P , T _A = -40°C to 25°C	-3.5	±1.5	3.5	%
LIFETIME ACCURACY CHARACTE	RISTICS [3]					
Considiuity From Including Lifetime	E _{Sens(LIFE)(HT)}	T _A = 25°C to 85°C	-2.1	±1.6	2.1	%
Sensitivity Error Including Lifetime	E _{Sens(LIFE)(LT)}	T _A = -40°C to 25°C	-3.5	±2.5	3.5	%
Total Output Freez Including Lifetime	E _{TOT(LIFE)(HT)}	T _A = 25°C to 85°C	-2.1	±1.7	2.1	%
Total Output Error Including Lifetime	E _{TOT(LIFE)(LT)}	$T_A = -40$ °C to 25°C	-3.5	±2.6	3.5	%
Floatric Officet Franchischer Lifeting	E _{OFF(LIFE)(HT)}	T _A = 25°C to 85°C	-10	±7	10	mV
Electric Offset Error Including Lifetime	E _{OFF(LIFE)(LT)}	$T_A = -40$ °C to 25°C	-20	±8.9	20	mV

^[1] Device may be operated at higher primary current levels, I_P, ambient, T_A, and internal leadframe temperatures, provided that the Maximum Junction Temperature, T_{J(max)}, is not exceeded.



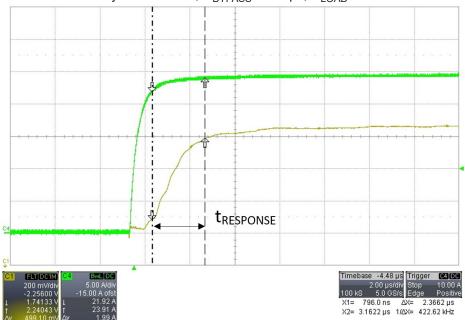
^[2] Typical values are ±3 sigma values.

^[3] Min/max limits come from AEC-Q100 Grade 1 testing.

CHARACTERISTIC PERFORMANCE DATA

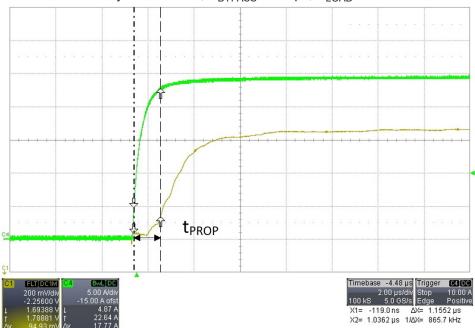
Response Time (t_{RESPONSE})

25 A excitation signal with 10%-90% rise time = 1 μs Sensitivity = 26.4 mV/A, C_{BYPASS} = 0.1 $\mu F,\,C_{LOAD}$ = 1 nF



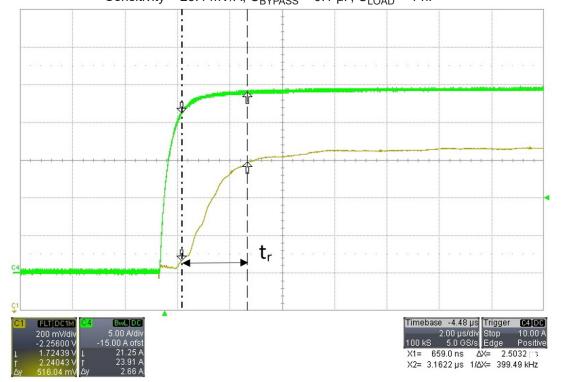
Propagation Delay (t_{PROP})

25 A excitation signal with 10%-90% rise time = 1 μ s Sensitivity = 26.4 mV/A, C_{BYPASS} = 0.1 μ F, C_{LOAD} = 1 nF

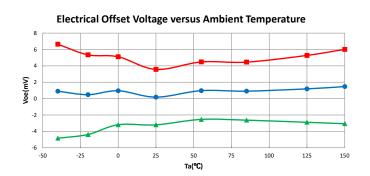


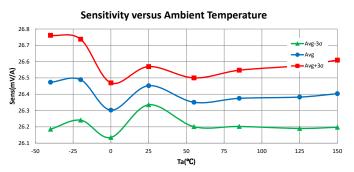


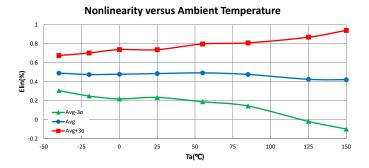
Rise Time (t_r) 25 A excitation signal with 10%-90% rise time = 1 μ s Sensitivity = 26.4 mV/A, C_{BYPASS} = 0.1 μ F, C_{LOAD} = 1 nF

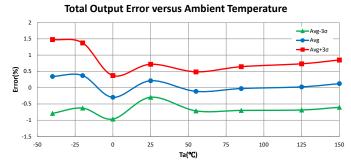


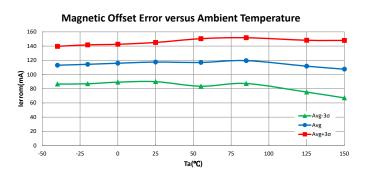
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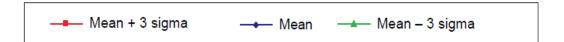






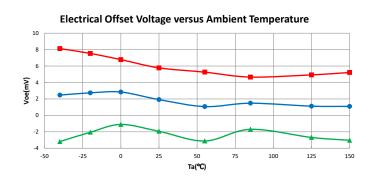


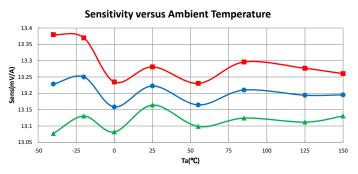


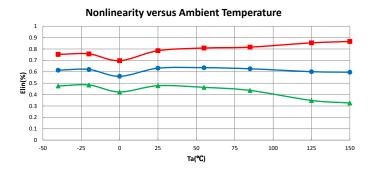


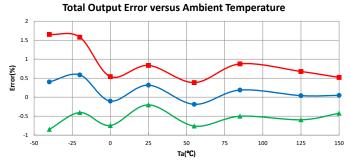


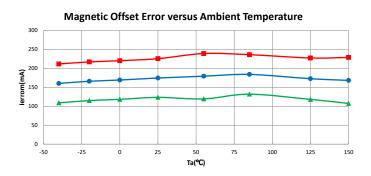
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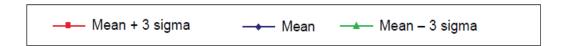




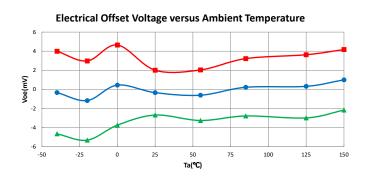


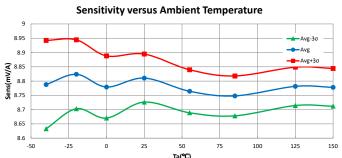


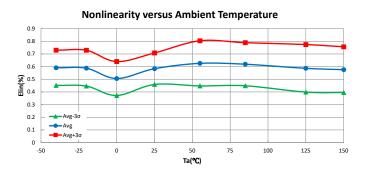


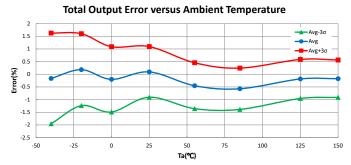


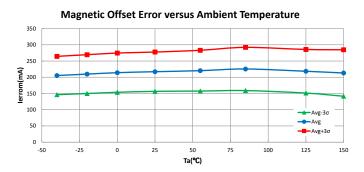
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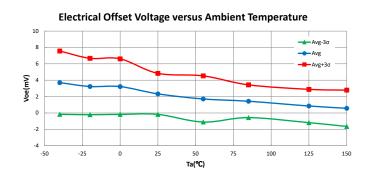


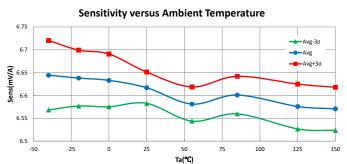


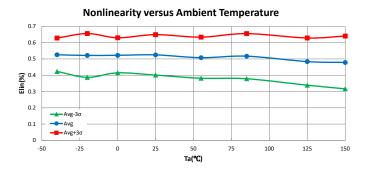


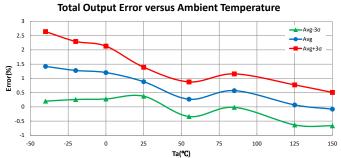


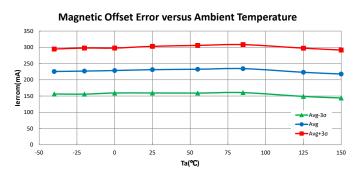
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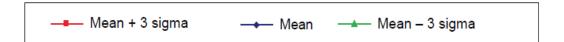














CHARACTERISTIC DEFINITIONS

Definitions of Accuracy Characteristics SENSITIVITY (Sens)

The change in sensor IC output in response to a 1 A change through the primary conductor. The sensitivity is the product of the magnetic circuit sensitivity (G/A; 1 G=0.1 mT) and the linear IC amplifier gain (mV/G). The linear IC amplifier gain is programmed at the factory to optimize the sensitivity (mV/A) for the full-scale current of the device.

SENSITIVITY ERROR (E_{Sens})

The sensitivity error is the percent difference between the measured sensitivity and the ideal sensitivity. For example, in the case of $V_{CC} = 3.3 \text{ V}$:

$$E_{\rm Sens} = \frac{Sens_{\rm Meas(3.3V)} - Sens_{\rm Ideal(3.3V)}}{Sens_{\rm IDEAL(3.3V)}} \times 100 \, (\%)$$

NOISE (V_N)

The noise floor is derived from the thermal and shot noise observed in Hall elements. Dividing the noise (mV) by the sensitivity (mV/A) provides the smallest current that the device is able to resolve.

NONLINEARITY (ELIN)

The ACS773 is designed to provide a linear output in response to a ramping current. Consider two current levels: I1 and I2. Ideally, the sensitivity of a device is the same for both currents, for a given supply voltage and temperature. Nonlinearity is present when there is a difference between the sensitivities measured at I1 and I2. Nonlinearity is calculated separately for the positive (E_{LINpos}) and negative (E_{LINneg}) applied currents as follows:

$$\begin{split} E_{LINpos} &= 100 \ (\%) \times \{1 - (Sens_{IPOS2} / Sens_{IPOS1}) \} \\ E_{LINneg} &= 100 \ (\%) \times \{1 - (Sens_{INEG2} / Sens_{INEG1}) \} \end{split}$$

where:

$$Sens_{Ix} = (V_{IOUT(Ix)} - V_{IOUT(Q)})/Ix$$

and I_{POSx} and I_{NEGx} are positive and negative currents.

Then:

$$E_{LIN} = max(E_{LINpos}, E_{LINneg})$$

SYMMETRY (ESYM)

The degree to which the absolute voltage output from the IC var-

ies in proportion to either a positive or negative half-scale primary current. The following equation is used to derive symmetry:

$$100 imes \left(rac{V_{IOUT_+half\text{-}scale\ amperes} - V_{IOUT(Q)}}{V_{IOUT(Q)} - V_{IOUT_-half\text{-}scale\ amperes}}
ight)$$

RATIOMETRY ERROR

The device features a ratiometric output. This means that the quiescent voltage output, $V_{\rm IOUTQ}$, and the magnetic sensitivity, Sens, are proportional to the supply voltage, $V_{\rm CC}$. The ratiometric change (%) in the quiescent voltage output is defined as:

$$Rat_{ErrQVO} = \left[1 - \frac{(V_{IOUTQ(VCC)} / V_{IOUTQ(3.3V)})}{V_{CC} / 3.3 V}\right] \times 100\%$$

and the ratiometric change (%) in sensitivity is defined as:

$$Rat_{ErrSens} = \left[I - \frac{(Sens_{(I'CC)} / Sense_{(3.3V)})}{V_{CC} / 3.3 V} \right] \times 100\%$$

ZERO CURRENT OUTPUT VOLTAGE (VIOUT(Q))

The output of the sensor when the primary current is zero. It nominally remains at $0.5 \times V_{CC}$ for a bidirectional device and $0.1 \times V_{CC}$ for a unidirectional device. For example, in the case of a bidirectional output device, $V_{CC} = 3.3$ V translates into $V_{IOUT(Q)} = 1.65$ V. Variation in $V_{IOUT(Q)}$ can be attributed to the resolution of the Allegro linear IC quiescent voltage trim and thermal drift.

ELECTRICAL OFFSET VOLTAGE (VOF)

The deviation of the device output from its ideal quiescent value of $0.5 \times V_{CC}$ (bidirectional) or $0.1 \times V_{CC}$ (unidirectional) due to nonmagnetic causes. To convert this voltage to amperes, divide by the device sensitivity, Sens.

MAGNETIC OFFSET ERROR (I_{ERROM})

The magnetic offset is due to the residual magnetism (remnant field) of the core material. The magnetic offset error is highest when the magnetic circuit has been saturated, usually when the device has been subjected to a full-scale or high-current overload condition. The magnetic offset is largely dependent on the material used as a flux concentrator. The larger magnetic offsets are observed at the lower operating temperatures.



TOTAL OUTPUT ERROR (E_{TOT})

The difference between the current measurement from the sensor IC and the actual current (IP), relative to the actual current. This is equivalent to the difference between the ideal output voltage and the actual output voltage, divided by the ideal sensitivity, relative to the current flowing through the primary conduction path:

$$E_{TOT}(I_P) = \frac{V_{IOUT(IP)} - V_{IOUT(ideal)(IP)}}{Sens_{ideal} \times I_P} \times 100(\%)$$

where

$$V_{IOUT(ideal)(IP)} = V_{IOUT(Q)} + (Sens_{IDEAL} \times I_P)$$

Accuracy Across
Temperature

Accuracy at 25°C Only

IPR(min)

IPR(min)

IPR(min)

IPR(max)

Figure 1: Output Voltage versus Sensed Current

Decreasing

V_{IOUT} (V)

0 A

Accuracy Across Temperature The Total Output Error incorporates all sources of error and is a function of IP.

At relatively high currents, E_{TOT} will be mostly due to sensitivity error, and at relatively low currents, E_{TOT} will be mostly due to Offset Voltage (V_{OE}). In fact, as I_P approaches zero, E_{TOT} approaches infinity due to the offset voltage. This is illustrated in Figure 1 and Figure 2. Figure 1 shows a distribution of output voltages versus I_P at 25°C and across temperature. Figure 2 shows the corresponding E_{TOT} versus I_P .

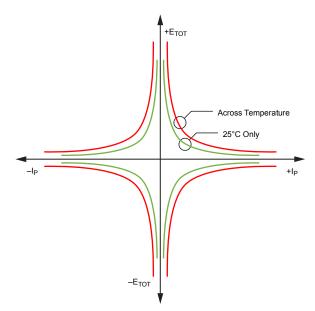


Figure 2: Total Output Error versus Sensed Current

DEFINITIONS OF DYNAMIC RESPONSE CHARACTERISTICS

POWER-ON DELAY (t_{POD})

When the supply is ramped to its operating voltage, the device requires a finite time to power its internal components before responding to an input magnetic field. Power-On Delay, t_{POD} , is defined as the time it takes for the output voltage to settle within $\pm 10\%$ of its steady-state value under an applied magnetic field, after the power supply has reached its minimum specified operating voltage, V_{CC} (min), as shown in the chart at right.

RISE TIME (t_r)

The time interval between a) when the sensor reaches 10% of its full-scale value, and b) when it reaches 90% of its full-scale value.

PROPAGATION DELAY (t_{PROP})

The time interval between a) when the sensed current reaches 20% of its full-scale value, and b) when the sensor output reaches 20% of its full-scale value.

RESPONSE TIME (t_{RESPONSE})

The time interval between a) when the applied current reaches 90% of its final value, and b) when the sensor reaches 90% of its output corresponding to the applied current.

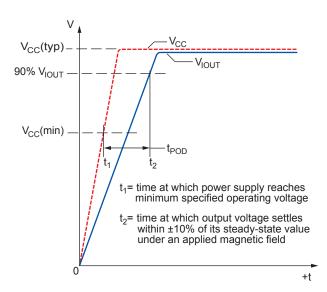


Figure 3: Power-On Delay (t_{POD})

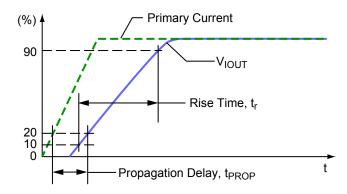


Figure 4: Rise Time (t_r) and Propagation Delay (t_{PROP})

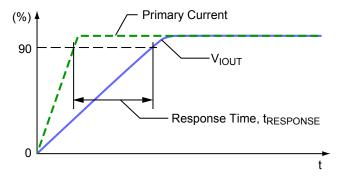


Figure 5: Response Time (t_{RESPONSE})



FUNCTIONAL DESCRIPTION

Power-On Reset (POR)

The descriptions in this section assume: temperature = 25°C, no output load (R_L , C_L), and I_P = 0 A.

Power-Up

At power-up, as V_{CC} ramps up, the output is in a high-impedance state. When V_{CC} crosses V_{PORH} (location [1] in Figure 6 and [1'] in Figure 7), the POR Release counter starts counting for t_{PO} [2, 2']. At this point, the output will go to $V_{CC}/2$.

V_{CC} drops below V_{CC} (min) = 3 V

If V_{CC} drops below V_{PORH} [3'] but remains higher than V_{PORL} [4'], the output will continue to be $V_{CC}/2$.

Power-Down

As V_{CC} ramps down below V_{PORL} [3, 5'], the output will enter a high-impedance state.

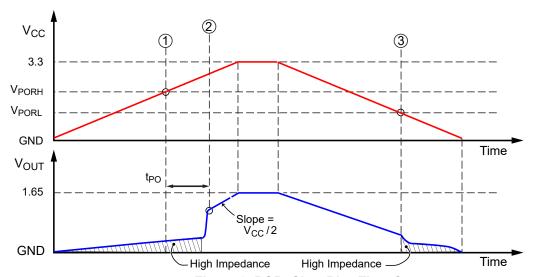


Figure 6: POR: Slow Rise Time Case

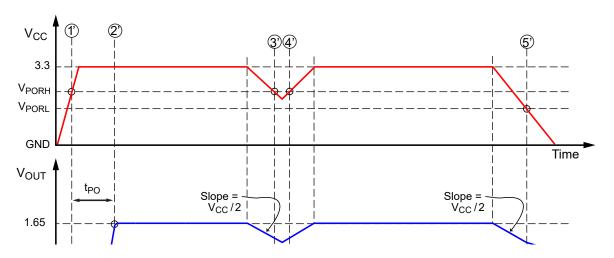


Figure 7: POR: Fast Rise Time Case



ACS773

High Accuracy, Hall-Effect-Based, 200 kHz Bandwidth, Galvanically Isolated Current Sensor IC with 100 μΩ Current Conductor

EEPROM Error Checking And Correction

Hamming code methodology is implemented for EEPROM checking and correction. The device has ECC enabled after power-up. If an uncorrectable error has occurred, the VOUT pin will go to high impedance and the device will not respond to applied magnetic field.



Chopper Stabilization Technique

When using Hall-effect technology, a limiting factor for switchpoint accuracy is the small signal voltage developed across the Hall element. This voltage is disproportionally small relative to the offset that can be produced at the output of the Hall sensor IC. This makes it difficult to process the signal while maintaining an accurate, reliable output over the specified operating temperature and voltage ranges.

Chopper stabilization is a unique approach used to minimize Hall offset on the chip. Allegro employs a technique to remove key sources of the output drift induced by thermal and mechanical stresses. This offset reduction technique is based on a signal modulation-demodulation process. The undesired offset signal is separated from the magnetic field-induced signal in the frequency domain, through modulation. The subsequent demodulation acts as a modulation process for the offset, causing the magnetic field-induced signal to recover its original spectrum at baseband, while the DC offset becomes a high-frequency signal. The magnetic-

sourced signal then can pass through a low-pass filter, while the modulated DC offset is suppressed.

In addition to the removal of the thermal and stress related offset, this novel technique also reduces the amount of thermal noise in the Hall sensor IC while completely removing the modulated residue resulting from the chopper operation. The chopper stabilization technique uses a high-frequency sampling clock. For demodulation process, a sample-and-hold technique is used. This high-frequency operation allows a greater sampling rate, which results in higher accuracy and faster signal-processing capability. This approach desensitizes the chip to the effects of thermal and mechanical stresses, and produces devices that have extremely stable quiescent Hall output voltages and precise recoverability after temperature cycling. This technique is made possible through the use of a BiCMOS process, which allows the use of low-offset, low-noise amplifiers in combination with high-density logic integration and sample-and-hold circuits.

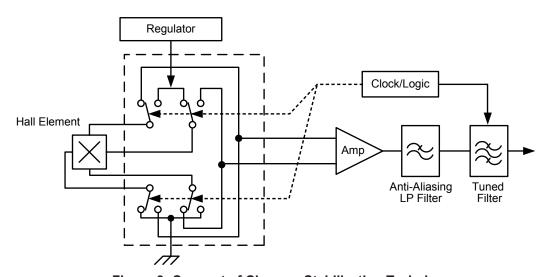


Figure 8: Concept of Chopper Stabilization Technique



APPLICATION INFORMATION

Thermal Rise vs. Primary Current

Self-heating due to the flow of current should be considered during the design of any current sensing system. The sensor, printed circuit board (PCB), and contacts to the PCB will generate heat as current moves through the system.

The thermal response is highly dependent on PCB layout, copper thickness, cooling techniques, and the profile of the injected current. The current profile includes peak current, current "on-time", and duty cycle. While the data presented in this section was collected with direct current (DC), these numbers may be used to approximate thermal response for both AC signals and current pulses.

The plot in Figure 9 shows the measured rise in steady-state die temperature of the ACS773 versus DC input current at an ambient temperature, T_A , of 25°C. The thermal offset curves may be directly applied to other values of T_A .

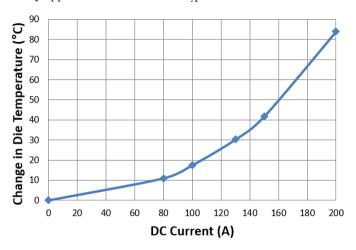
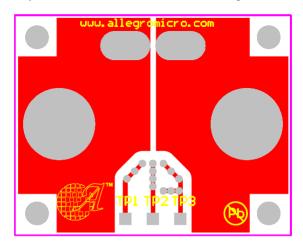


Figure 9: Self-Heating in the CB Package
Due to Current Flow

The thermal capacity of the ACS773 should be verified by the end user in the application's specific conditions. The maximum junction temperature, $T_{J(max)}$, should not be exceeded. Further information on this application testing is available in the DC Current Capability and Fuse Characteristics of Current Sensor ICs with 50 to 200 A Measurement Capability application note on the Allegro website (https://www.allegromicro.com/en/Design-Center/Technical-Documents/Hall-Effect-Sensor-IC-Publications/DC-Current-Capability-Fuse-Characteristics-Current-Sensor-ICs-50-200-A.aspx).

ASEK773 Evaluation Board Layout

Thermal data shown in Figure 9 was collected using the ASEK773 Evaluation Board (TED-85-0385-001). This board includes 1500 mm² of 2 oz. (0.0694 mm) copper connected to pins 4 and 5, with thermal vias connecting the layers. Top and bottom layers of the PCB are shown below in Figure 10.



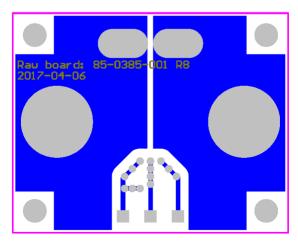


Figure 10: Top and Bottom Layers for ASEK773 Evaluation Board

Gerber files for the ASEK773 evaluation board are available for download from the Allegro website; see the technical documents section of the ACS773 webpage (https://www.allegromicro.com/en/Products/Current-Sensor-ICs/Fifty-To-Two-Hundred-Amp-Integrated-Conductor-Sensor-ICs/Acs773.aspx).



PACKAGE OUTLINE DRAWINGS

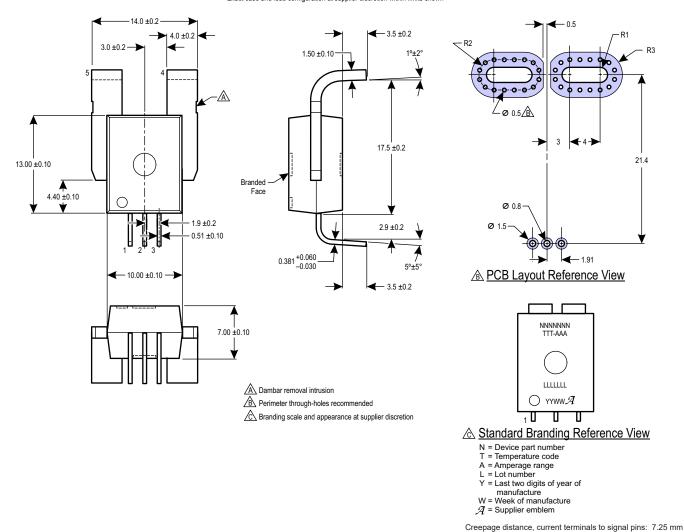
For Reference Only — Not for Tooling Use (Reference DWG-9111 & DWG-9110) Dimensions in millimeters — NOT TO SCALE

(Reference DWG-9111 & DWG-9110)

Dimensions in millimeters – NOT TO SCALE

Dimensions exclusive of mold flash, gate burs, and dambar protrusions

Exact case and lead configuration at supplier discretion within limits shown



Clearance distance, current terminals to signal pins: 7.25 mm Package mass: 4.63 g typical

Figure 11: Package CB, 5-Pin, Leadform PFF

For Reference Only — Not for Tooling Use
(Reference DWG-9111, DWG-9110)
Dimensions in millimeters — NOT TO SCALE Dimensions exclusive of mold flash, gate burs, and dambar protrusions Exact case and lead configuration at supplier discretion within limits shown

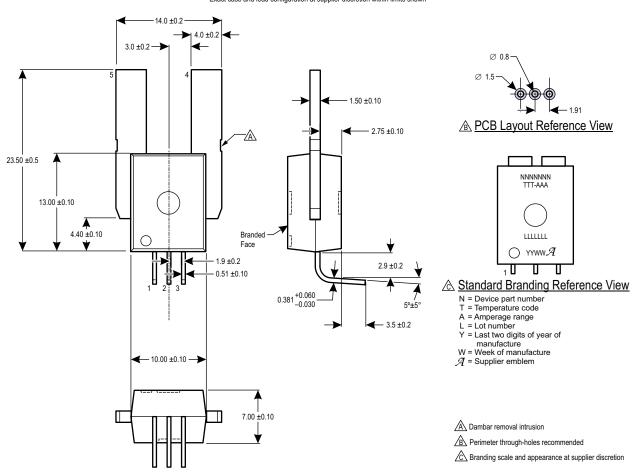


Figure 12: Package CB, 5-Pin, Leadform PSF

ACS773

High Accuracy, Hall-Effect-Based, 200 kHz Bandwidth, Galvanically Isolated Current Sensor IC with 100 $\mu\Omega$ Current Conductor

Revision History

Number	Date	Description
_	December 12, 2017	Initial release
1	February 9, 2018	Added Dielectric Surge Strength Test Voltage characteristic (page 3) and EEPROM Error Checking and Correction section (page 15). Updated Power-On Reset (POR) section (page 14).
2	May 29, 2018	Added Characteristic Performance plots and -150B part variant.
3	November 2, 2018	Added -PSF leadform option and Applications Information section (page 22); updated Typical Application (page 1), pinout diagram (page 4), T _{OP} to T _A (pages 2 and 5-9), and Character Performance plots (page 11-12).

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