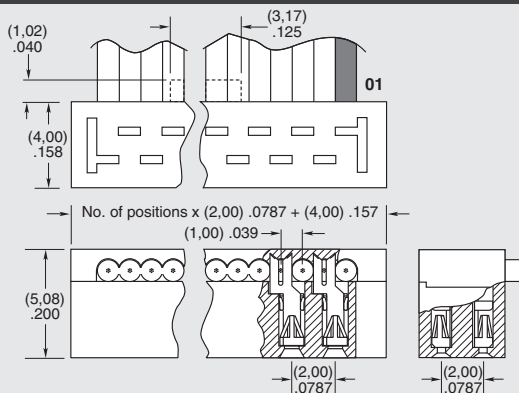


## TCSD SERIES

# TIGER EYE™ IDC SOCKET CABLE

Requires -DXX



A schematic diagram of a four-bar linkage mechanism. It consists of four rigid links connected by four revolute (pin) joints. The joints are arranged in a closed loop, forming a parallelogram shape. The top and bottom links are horizontal, while the left and right links are vertical. The joints are located at the corners of the parallelogram.

See EHT S



- Ejector headers
- Locking clips
- Strain relief option

See EHT Series.