

- Low Supply Voltage Range 1.8 V to 3.6 V
- Ultralow Power Consumption
  - Active Mode: 220  $\mu$ A at 1 MHz, 2.2 V
  - Standby Mode: 0.5  $\mu$ A
  - Off Mode (RAM Retention): 0.1  $\mu$ A
- Five Power-Saving Modes
- Ultrafast Wake-Up From Standby Mode in Less Than 1  $\mu$ s
- 16-Bit RISC Architecture, 62.5 ns Instruction Cycle Time
- Basic Clock Module Configurations:
  - Internal Frequencies up to 16 MHz With One Calibrated Frequency
  - Internal Very Low Power LF Oscillator
  - 32-kHz Crystal
  - External Digital Clock Source
- 16-Bit Timer\_A With Two Capture/Compare Registers
- Brownout Detector
- On-Chip Comparator for Analog Signal Compare Function or Slope A/D (See Table 1)
- Serial Onboard Programming, No External Programming Voltage Needed
- Programmable Code Protection by Security Fuse
- On-Chip Emulation Logic With Spy-Bi-Wire Interface
- Family Members details see Table 1
- Available in a 14-Pin Plastic Small-Outline Thin Package (TSSOP), 14-Pin Plastic Dual Inline Package (PDIP), and 16-Pin QFN
- For Complete Module Descriptions, See the *MSP430x2xx Family User's Guide*

## description

The Texas Instruments MSP430 family of ultralow-power microcontrollers consists of several devices featuring different sets of peripherals targeted for various applications. The architecture, combined with five low-power modes, is optimized to achieve extended battery life in portable measurement applications. The device features a powerful 16-bit RISC CPU, 16-bit registers, and constant generators that contribute to maximum code efficiency. The digitally controlled oscillator (DCO) allows wake-up from low-power modes to active mode in less than 1  $\mu$ s.

The MSP430G2x01/11 series is an ultralow-power mixed signal microcontroller with a built-in 16-bit timer and ten I/O pins. The MSP430G2x11 family members have a versatile analog comparator. For configuration details see Table 1.

Typical applications include low-cost sensor systems that capture analog signals, convert them to digital values, and then process the data for display or for transmission to a host system.



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# MSP430G2x01, MSP430G2x11 MIXED SIGNAL MICROCONTROLLER

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**Table 1. Available Options - MSP430G2xxx Devices**

Device	BSL	EEM	Flash (KB)	RAM (B)	Timer_A	COMP_A+ Channel	CLOCK	I/O	Package Type
MSP430G2211IRSA16 MSP430G2211IPW14 MSP430G2211IN14	-	1	2	128	1x TA2	8	LF, DCO, VLO	10	16-QFN 14-TSSOP 14-PDIP
MSP430G2201IRSA16 MSP430G2201IPW14 MSP430G2201IN14	-	1	2	128	1x TA2	-	LF, DCO, VLO	10	16-QFN 14-TSSOP 14-PDIP
MSP430G2111IRSA16 MSP430G2111IPW14 MSP430G2111IN14	-	1	1	128	1x TA2	8	LF, DCO, VLO	10	16-QFN 14-TSSOP 14-PDIP
MSP430G2101IRSA16 MSP430G2101IPW14 MSP430G2101IN14	-	1	1	128	1x TA2	-	LF, DCO, VLO	10	16-QFN 14-TSSOP 14-PDIP
MSP430G2001IRSA16 MSP430G2001IPW14 MSP430G2001IN14	-	1	0.5	128	1x TA2	-	LF, DCO, VLO	10	16-QFN 14-TSSOP 14-PDIP

† For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI web site at [www.ti.com](http://www.ti.com).

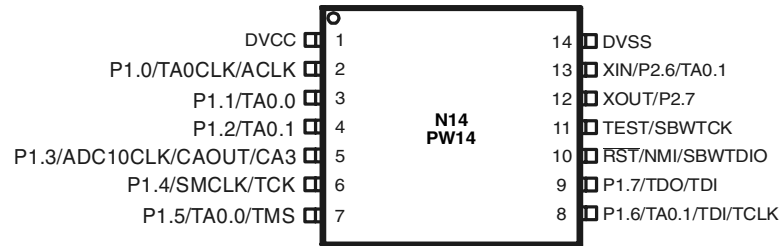
‡ Package drawings, thermal data, and symbolization are available at [www.ti.com/packaging](http://www.ti.com/packaging).

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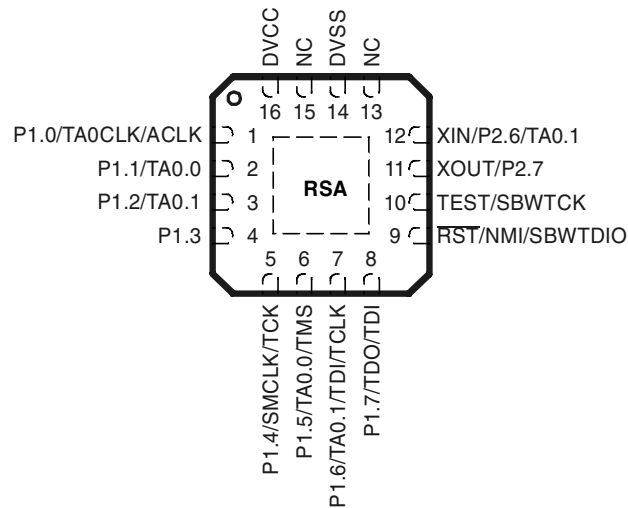


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## device pinout, MSP430G2x01



NOTE: See port schematics section for detailed I/O information.



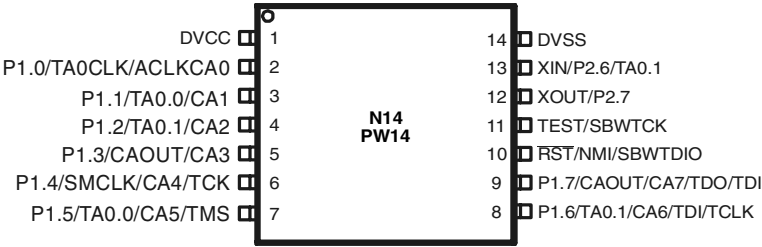
NOTE: See port schematics section for detailed I/O information.

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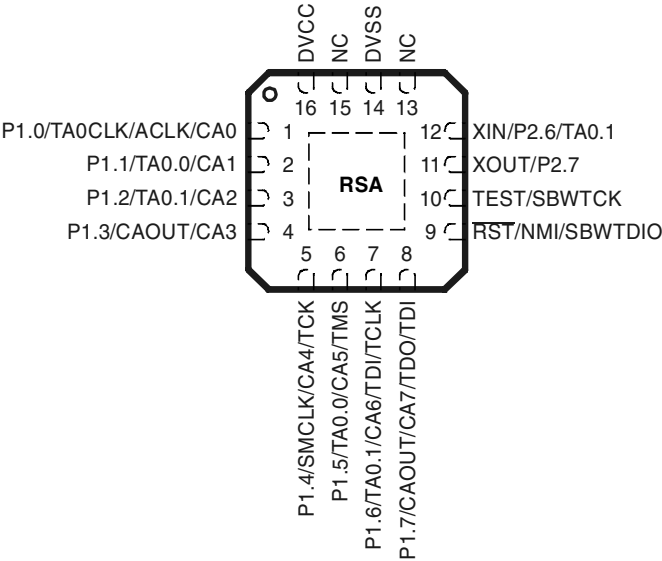
# MSP430G2x01, MSP430G2x11 MIXED SIGNAL MICROCONTROLLER

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## device pinout, MSP430G2x11

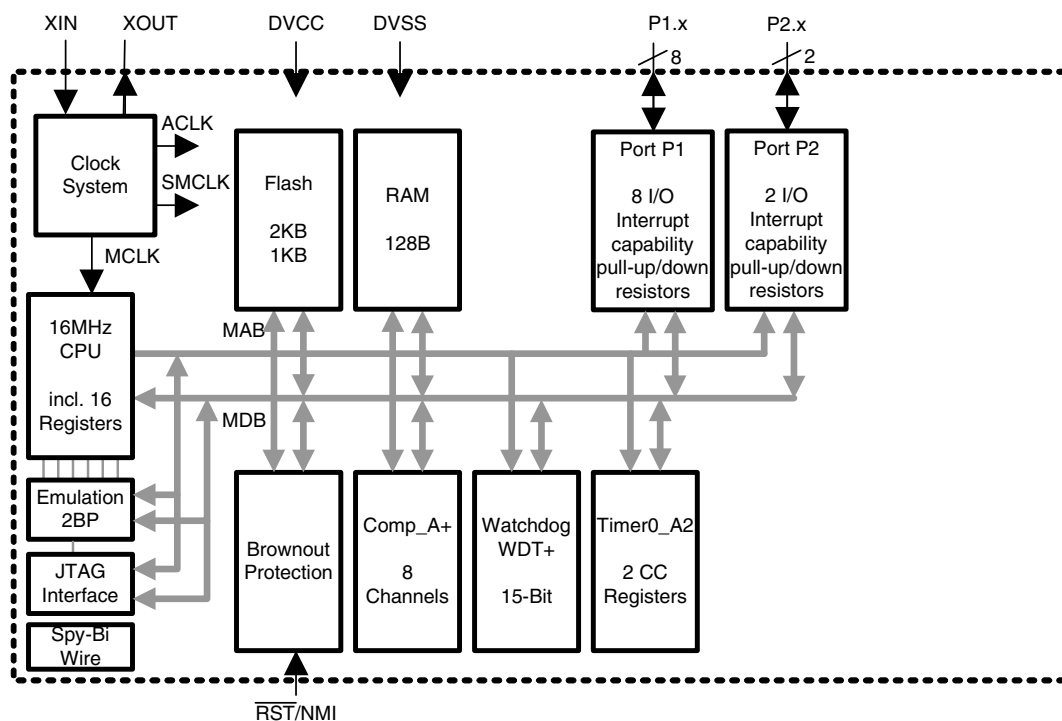


NOTE: See port schematics section for detailed I/O information.



NOTE: See port schematics section for detailed I/O information.

**functional block diagram, MSP430G2x11**

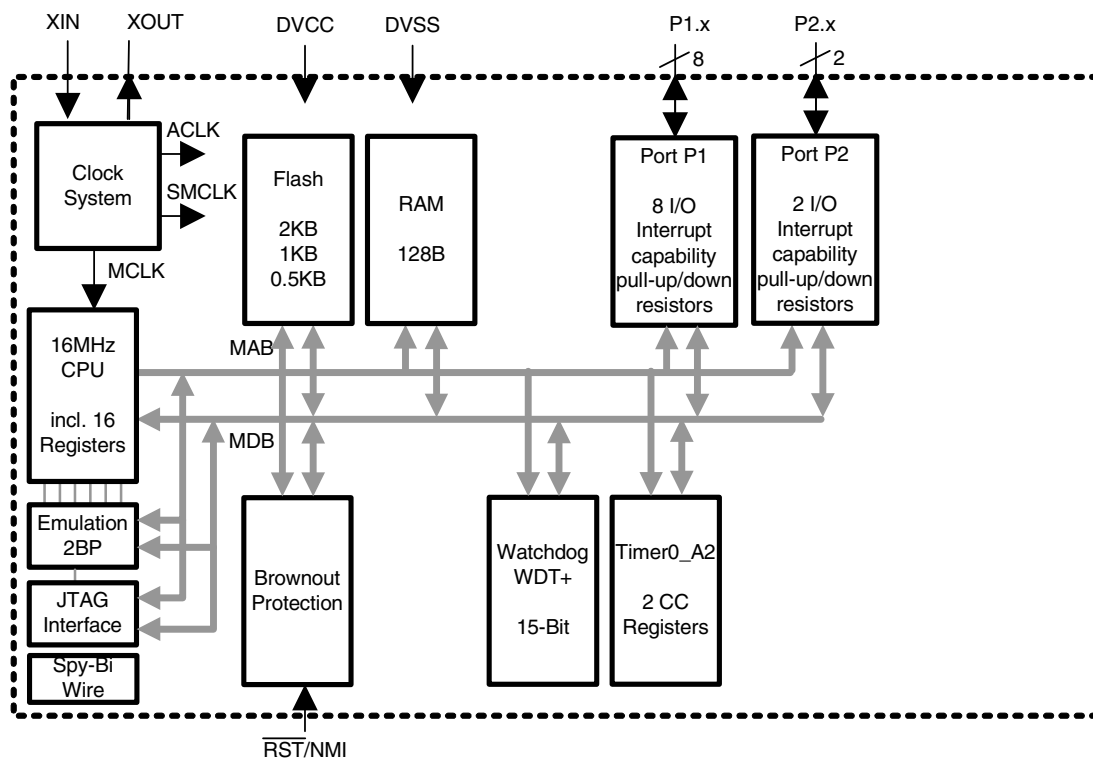


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# MSP430G2x01, MSP430G2x11 MIXED SIGNAL MICROCONTROLLER

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## functional block diagram, MSP430G2x01



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**Terminal Functions, MSP430G2x01 and MSP430G2x11**

TERMINAL				DESCRIPTION
NAME	14 N, PW	16 RSA	I/O	
	NO.	NO.		
P1.0/ TA0CLK/ ACLK/ CA0	2	1	I/O	General-purpose digital I/O pin Timer0_A, clock signal TACLK input ACLK signal ouput Comparator_A+, CA0 input (see Note 1)
P1.1/ TA0.0/ CA1	3	2	I/O	General-purpose digital I/O pin Timer0_A, capture: CCI0A input, compare: Out0 output Comparator_A+, CA1 input (see Note 1)
P1.2/ TA0.1/ CA2	4	3	I/O	General-purpose digital I/O pin Timer0_A, capture: CCI1A input, compare: Out1 output Comparator_A+, CA2 input (see Note 1)
P1.3/ CA3/ CAOUT	5	4	I/O	General-purpose digital I/O pin Comparator_A+, CA3 input (see Note 1) Comparator_A+, output (see Note 1)
P1.4/ SMCLK/ CA4/ TCK	6	5	I/O	General-purpose digital I/O pin SMCLK signal output Comparator_A+, CA4 input (see Note 1) JTAG test clock, input terminal for device programming and test
P1.5/ TA0.0/ CA5/ TMS	7	6	I/O	General-purpose digital I/O pin Timer0_A, compare: Out0 output Comparator_A+, CA5 input (see Note 1) JTAG test mode select, input terminal for device programming and test
P1.6/ TA0.1/ CA6/ TDI/ TCLK	8	7	I/O	General-purpose digital I/O pin Timer0_A, compare: Out1 output Comparator_A+, CA6 input (see Note 1) JTAG test data input or test clock input during programming and test
P1.7/ CA7/ CAOUT TDO/ TDI	9	8	I/O	General-purpose digital I/O pin CA7 input (see Note 1) Comparator_A+, output (see Note 1) JTAG test data output terminal or test data input during programming and test

NOTES: 1. MSP430G2x11 only.

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# MSP430G2x01, MSP430G2x11 MIXED SIGNAL MICROCONTROLLER

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## Terminal Functions, MSP430G2x01 and MSP430G2x11 (continued)

TERMINAL				DESCRIPTION
NAME	14 N, PW	16 RSA	I/O	
	NO.	NO.		
XIN/ P2.6/ TA0.1	13	12	I/O	Input terminal of crystal oscillator General-purpose digital I/O pin Timer0_A, compare: Out1 output
XOUT/ P2.7	12	11	I/O	Output terminal of crystal oscillator (see Note 1) General-purpose digital I/O pin
RST/ NMI/ SBWTDIO	10	9	I	Reset Nonmaskable interrupt input Spy-Bi-Wire test data input/output during programming and test
TEST/ SBWTCK	11	10	I	Selects test mode for JTAG pins on Port1. The device protection fuse is connected to TEST. Spy-Bi-Wire test clock input during programming and test
DVCC	1	16	NA	Supply voltage
DVSS	14	14	NA	Ground reference
NC	–	15 13	NA	Not connected.
QFN Pad	–	Pad	NA	QFN package pad connection to V <sub>SS</sub> recommended.

NOTES: 1. If XOUT/P2.7 is used as an input, excess current will flow until P2SEL.7 is cleared. This is due to the oscillator output driver connection to this pad after reset.

† TDO or TDI is selected via JTAG instruction.



## short-form description

### CPU

The MSP430 CPU has a 16-bit RISC architecture that is highly transparent to the application. All operations, other than program-flow instructions, are performed as register operations in conjunction with seven addressing modes for source operand and four addressing modes for destination operand.

The CPU is integrated with 16 registers that provide reduced instruction execution time. The register-to-register operation execution time is one cycle of the CPU clock.

Four of the registers, R0 to R3, are dedicated as program counter, stack pointer, status register, and constant generator respectively. The remaining registers are general-purpose registers.

Peripherals are connected to the CPU using data, address, and control buses, and can be handled with all instructions.

### instruction set

The instruction set consists of 51 instructions with three formats and seven address modes. Each instruction can operate on word and byte data. Table 2 shows examples of the three types of instruction formats; Table 3 shows the address modes.

Program Counter	PC/R0
Stack Pointer	SP/R1
Status Register	SR/CG1/R2
Constant Generator	CG2/R3
General-Purpose Register	R4
General-Purpose Register	R5
General-Purpose Register	R6
General-Purpose Register	R7
General-Purpose Register	R8
General-Purpose Register	R9
General-Purpose Register	R10
General-Purpose Register	R11
General-Purpose Register	R12
General-Purpose Register	R13
General-Purpose Register	R14
General-Purpose Register	R15

**Table 2. Instruction Word Formats**

Dual operands, source-destination	e.g., ADD R4,R5	R4 + R5 --> R5
Single operands, destination only	e.g., CALL R8	PC -->(TOS), R8--> PC
Relative jump, un/conditional	e.g., JNE	Jump-on-equal bit = 0

**Table 3. Address Mode Descriptions**

ADDRESS MODE	S	D	SYNTAX	EXAMPLE	OPERATION
Register	●	●	MOV Rs,Rd	MOV R10,R11	R10 --> R11
Indexed	●	●	MOV X(Rn),Y(Rm)	MOV 2(R5),6(R6)	M(2+R5) --> M(6+R6)
Symbolic (PC relative)	●	●	MOV EDE,TONI		M(EDE) --> M(TONI)
Absolute	●	●	MOV &MEM,&TCDAT		M(MEM) --> M(TCDAT)
Indirect	●		MOV @Rn,Y(Rm)	MOV @R10,Tab(R6)	M(R10) --> M(Tab+R6)
Indirect autoincrement	●		MOV @Rn+,Rm	MOV @R10+,R11	M(R10) --> R11 R10 + 2 --> R10
Immediate	●		MOV #X,TONI	MOV #45,TONI	#45 --> M(TONI)

NOTE: S = source D = destination

# MSP430G2x01, MSP430G2x11 MIXED SIGNAL MICROCONTROLLER

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## operating modes

The MSP430 has one active mode and five software-selectable low-power modes of operation. An interrupt event can wake up the device from any of the five low-power modes, service the request, and restore back to the low-power mode on return from the interrupt program.

The following six operating modes can be configured by software:

- Active mode (AM)
  - All clocks are active
- Low-power mode 0 (LPM0)
  - CPU is disabled
  - ACLK and SMCLK remain active. MCLK is disabled
- Low-power mode 1 (LPM1)
  - CPU is disabled
  - ACLK and SMCLK remain active. MCLK is disabled
  - DCO's dc-generator is disabled if DCO not used in active mode
- Low-power mode 2 (LPM2)
  - CPU is disabled
  - MCLK and SMCLK are disabled
  - DCO's dc-generator remains enabled
  - ACLK remains active
- Low-power mode 3 (LPM3)
  - CPU is disabled
  - MCLK and SMCLK are disabled
  - DCO's dc-generator is disabled
  - ACLK remains active
- Low-power mode 4 (LPM4)
  - CPU is disabled
  - ACLK is disabled
  - MCLK and SMCLK are disabled
  - DCO's dc-generator is disabled
  - Crystal oscillator is stopped

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## interrupt vector addresses

The interrupt vectors and the power-up starting address are located in the address range of 0FFFFh to 0FFC0h. The vector contains the 16-bit address of the appropriate interrupt handler instruction sequence.

If the reset vector (located at address 0FFFEh) contains 0FFFFh (e.g., flash is not programmed) the CPU will go into LPM4 immediately after power-up.

INTERRUPT SOURCE	INTERRUPT FLAG	SYSTEM INTERRUPT	WORD ADDRESS	PRIORITY
Power-up External reset Watchdog Timer+ Flash key violation PC out-of-range (see Note 1)	PORIFG RSTIFG WDTIFG KEYV (see Note 2)	Reset	0FFFEh	31, highest
NMI Oscillator fault Flash memory access violation	NMIIFG OFIFG ACCVIFG (see Notes 2 and 5)	(non)-maskable, (non)-maskable, (non)-maskable	0FFFCh	30
			0FFFAh	29
			0FFF8h	28
COMP_A+	CAIFG (see Note 3 and 4)	maskable	0FFF6h	27
Watchdog Timer+	WDTIFG	maskable	0FFF4h	26
Timer_A2	TACCR0 CCIFG (see Note 3)	maskable	0FFF2h	25
Timer_A2	TACCR1 CCIFG. TAIFG (see Notes 2 and 3)	maskable	0FFF0h	24
			0FFEEh	23
			0FFECCh	22
			0FFEAh	21
			0FFE8h	20
I/O Port P2 (two flags)	P2IFG.6 to P2IFG.7 (see Notes 2 and 3)	maskable	0FFE6h	19
I/O Port P1 (eight flags)	P1IFG.0 to P1IFG.7 (see Notes 2 and 3)	maskable	0FFE4h	18
			0FFE2h	17
			0FFE0h	16
(see Note 6)			0FFDEh ... 0FFC0h	15 ... 0, lowest

- NOTES: 1. A reset is generated if the CPU tries to fetch instructions from within the module register memory address range (0h to 01FFh) or from within unused address ranges.
2. Multiple source flags
3. Interrupt flags are located in the module
4. Devices with COMP\_A+ only.
5. (non)-maskable: the individual interrupt-enable bit can disable an interrupt event, but the general interrupt enable cannot.
6. The interrupt vectors at addresses 0FFDEh to 0FFC0h are not used in this device and can be used for regular program code if necessary.

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## special function registers

Most interrupt and module enable bits are collected into the lowest address space. Special function register bits not allocated to a functional purpose are not physically present in the device. Simple software access is provided with this arrangement.

### interrupt enable 1 and 2

Address	7	6	5	4	3	2	1	0
0h			ACCVIE	NMIIE			OFIE	WDTIE
			rw-0	rw-0			rw-0	rw-0

- WDTIE: Watchdog Timer interrupt enable. Inactive if watchdog mode is selected. Active if Watchdog Timer is configured in interval timer mode.
- OFIE: Oscillator fault enable
- NMIIE: (Non)maskable interrupt enable
- ACCVIE: Flash access violation interrupt enable

Address	7	6	5	4	3	2	1	0
01h								

### interrupt flag register 1 and 2

Address	7	6	5	4	3	2	1	0
02h				NMIIFG	RSTIFG	PORIFG	OFIFG	WDTIFG
			rw-0	rw-(0)	rw-(1)	rw-1	rw-1	rw-(0)

- WDTIFG: Set on Watchdog Timer overflow (in watchdog mode) or security key violation. Reset on V<sub>CC</sub> power-up or a reset condition at RST/NMI pin in reset mode.
- OFIFG: Flag set on oscillator fault
- RSTIFG: External reset interrupt flag. Set on a reset condition at RST/NMI pin in reset mode. Reset on V<sub>CC</sub> power-up
- PORIFG: Power-On Reset interrupt flag. Set on V<sub>CC</sub> power-up.
- NMIIFG: Set via RST/NMI-pin

Address	7	6	5	4	3	2	1	0
03h								

- Legend**
- rw: Bit can be read and written.
  - rw-0,1: Bit can be read and written. It is Reset or Set by PUC.
  - rw-(0,1): Bit can be read and written. It is Reset or Set by POR.
  -



## memory organization

		<b>MSP430G2001 MSP430G2011</b>	<b>MSP430G2101 MSP430G2111</b>	<b>MSP430G2201 MSP430G2211</b>
Memory	Size	512B	1kB	2kB
Main: interrupt vector	Flash	0xFFFF to 0xFFC0	0xFFFF to 0xFFC0	0xFFFF to 0xFFC0
Main: code memory	Flash	0xFFFF to 0xFE00	0xFFFF to 0xFC00	0xFFFF to 0xF800
Information memory	Size	256 Byte	256 Byte	256 Byte
	Flash	010FFh - 01000h	010FFh - 01000h	010FFh - 01000h
RAM	Size	128B	128B	128B
		027Fh - 0200h	027Fh - 0200h	027Fh - 0200h
Peripherals	16-bit	01FFh - 0100h	01FFh - 0100h	01FFh - 0100h
	8-bit	0FFh - 010h	0FFh - 010h	0FFh - 010h
	8-bit SFR	0Fh - 00h	0Fh - 00h	0Fh - 00h

## flash memory

The flash memory can be programmed via the Spy-Bi-Wire/JTAG port or in-system by the CPU. The CPU can perform single-byte and single-word writes to the flash memory. Features of the flash memory include:

- Flash memory has n segments of main memory and four segments of information memory (A to D) of 64 bytes each. Each segment in main memory is 512 bytes in size.
- Segments 0 to n may be erased in one step, or each segment may be individually erased.
- Segments A to D can be erased individually, or as a group with segments 0 to n. Segments A to D are also called *information memory*.
- Segment A contains calibration data. After reset segment A is protected against programming and erasing. It can be unlocked but care should be taken not to erase this segment if the device-specific calibration data is required.

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## peripherals

Peripherals are connected to the CPU through data, address, and control buses and can be handled using all instructions. For complete module descriptions, see the *MSP430x2xx Family User's Guide*.

## oscillator and system clock

The clock system is supported by the basic clock module that includes support for a 32768-Hz watch crystal oscillator, an internal very-low-power low-frequency oscillator, and an internal digitally controlled oscillator (DCO). The basic clock module is designed to meet the requirements of both low system cost and low power consumption. The internal DCO provides a fast turn-on clock source and stabilizes in less than 1  $\mu$ s. The basic clock module provides the following clock signals:

- Auxiliary clock (ACLK), sourced either from a 32768-Hz watch crystal or the internal LF oscillator.
- Main clock (MCLK), the system clock used by the CPU.
- Sub-Main clock (SMCLK), the sub-system clock used by the peripheral modules.

DCO CALIBRATION DATA (PROVIDED FROM FACTORY IN FLASH INFO MEMORY SEGMENT A)			
DCO FREQUENCY	CALIBRATION REGISTER	SIZE	ADDRESS
1 MHz	CALBC1_1MHZ	byte	010FFh
	CALDCO_1MHZ	byte	010FEh

## calibration data stored in information memory segment A

Calibration data is stored for the DCO organized in a tag-length-value structure.

TAGS USED BY THE ADC CALIBRATION TAGS			
NAME	ADDRESS	VALUE	DESCRIPTION
TAG_DCO_30†	0x10FC	0x01	DCO frequency calibration at $V_{CC} = 3$ V and $T_A = 30^\circ\text{C}$ at calibration
TAG_EMPTY†	-	0xFE	Identifier for empty memory areas

† Advanced information

LABELS USED BY THE ADC CALIBRATION TAGS			
LABEL	CONDITION AT CALIBRATION / DESCRIPTION	SIZE	ADDRESS OFFSET
CAL_BC1_1MHz†	-	byte	0x0001
CAL_DCO_1MHz†	-	byte	0x0000

† Advanced information

## brownout

The brownout circuit is implemented to provide the proper internal reset signal to the device during power on and power off.



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## digital I/O

There is one 8-bit I/O port implemented—port P1—and two bits of I/O port P2:

- All individual I/O bits are independently programmable.
- Any combination of input, output, and interrupt condition is possible.
- Edge-selectable interrupt input capability for all the eight bits of port P1 and the two bits of port P2.
- Read/write access to port-control registers is supported by all instructions.
- Each I/O has an individually programmable pull-up/pull-down resistor.

## WDT+ watchdog timer

The primary function of the watchdog timer (WDT+) module is to perform a controlled system restart after a software problem occurs. If the selected time interval expires, a system reset is generated. If the watchdog function is not needed in an application, the module can be disabled or configured as an interval timer and can generate interrupts at selected time intervals.

## Timer\_A2

Timer\_A2 is a 16-bit timer/counter with two capture/compare registers. Timer\_A2 can support multiple capture/compares, PWM outputs, and interval timing. Timer\_A2 also has extensive interrupt capabilities. Interrupts may be generated from the counter on overflow conditions and from each of the capture/compare registers.

TIMER_A2 SIGNAL CONNECTIONS - DEVICES WITH NO ANALOG							
INPUT PIN NUMBER		DEVICE INPUT SIGNAL	MODULE INPUT NAME	MODULE BLOCK	MODULE OUTPUT SIGNAL	OUTPUT PIN NUMBER	
PW, N	RSA					PW, N	RSA
2 - P1.0	1 - P1.0	TACLK	TACLK	Timer	NA		
		ACLK	ACLK				
		SMCLK	SMCLK				
2 - P1.0	1 - P1.0	TACLK	INCLK				
3 - P1.1	2 - P1.1	TA0	CC10A	CCR0	TA0	3 - P1.1	2 - P1.1
		ACLK (internal)	CC10B			7 - P1.5	6 - P1.5
		V <sub>SS</sub>	GND				
		V <sub>CC</sub>	V <sub>CC</sub>				
4 - P1.2	3 - P1.2	TA1	CC11A	CCR1	TA1	4 - P1.2	3 - P1.2
		TA1	CC11B			8 - P1.6	7 - P1.6
		V <sub>SS</sub>	GND			13 - P2.6	12 - P2.6
		V <sub>CC</sub>	V <sub>CC</sub>				

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TIMER_A2 SIGNAL CONNECTIONS - DEVICES WITH COMP_A+							
INPUT PIN NUMBER		DEVICE INPUT SIGNAL	MODULE INPUT NAME	MODULE BLOCK	MODULE OUTPUT SIGNAL	OUTPUT PIN NUMBER	
PW, N	RSA					PW, N	RSA
2 - P1.0	1 - P1.0	TACLK	TACLK	Timer	NA		
		ACLK	ACLK				
		SMCLK	SMCLK				
2 - P1.0	1 - P1.0	TACLK	INCLK				
3 - P1.1	2 - P1.1	TA0	CC10A	CCR0	TA0	3 - P1.1	2 - P1.1
		ACLK (internal)	CC10B			7 - P1.5	6 - P1.5
		VSS	GND				
		VCC	VCC				
4 - P1.2	3 - P1.2	TA1	CC11A	CCR1	TA1	4 - P1.2	3 - P1.2
		CAOUT (internal)	CC11B			8 - P1.6	7 - P1.6
		VSS	GND			13 - P2.6	12 - P2.6
		VCC	VCC				

## comparator\_A+ (MSP430G2x11 only)

The primary function of the comparator\_A+ module is to support precision slope analog-to-digital conversions, battery-voltage supervision, and monitoring of external analog signals.



**peripheral file map**

<b>PERIPHERALS WITH WORD ACCESS</b>			
<b>Timer_A</b>	Capture/compare register	TACCR1	0174h
	Capture/compare register	TACCR0	0172h
	Timer_A register	TAR	0170h
	Capture/compare control	TACCTL1	0164h
	Capture/compare control	TACCTL0	0162h
	Timer_A control	TACTL	0160h
	Timer_A interrupt vector	TAIV	012Eh
<b>Flash Memory</b>	Flash control 3	FCTL3	012Ch
	Flash control 2	FCTL2	012Ah
	Flash control 1	FCTL1	0128h
<b>Watchdog Timer+</b>	Watchdog/timer control	WDTCTL	0120h
<b>PERIPHERALS WITH BYTE ACCESS</b>			
<b>Comparator_A+ (MSP430G2x11 only)</b>	Comparator_A+ port disable	CAPD	05Bh
	Comparator_A+ control 2	CACTL2	05Ah
	Comparator_A+ control 1	CACTL1	059h
<b>Basic Clock System+</b>	Basic clock system control 3	BCSCTL3	053h
	Basic clock system control 2	BCSCTL2	058h
	Basic clock system control 1	BCSCTL1	057h
	DCO clock frequency control	DCOCTL	056h
<b>Port P2</b>	Port P2 resistor enable	P2REN	02Fh
	Port P2 selection	P2SEL	02Eh
	Port P2 interrupt enable	P2IE	02Dh
	Port P2 interrupt edge select	P2IES	02Ch
	Port P2 interrupt flag	P2IFG	02Bh
	Port P2 direction	P2DIR	02Ah
	Port P2 output	P2OUT	029h
	Port P2 input	P2IN	028h
<b>Port P1</b>	Port P1 resistor enable	P1REN	027h
	Port P1 selection	P1SEL	026h
	Port P1 interrupt enable	P1IE	025h
	Port P1 interrupt edge select	P1IES	024h
	Port P1 interrupt flag	P1IFG	023h
	Port P1 direction	P1DIR	022h
	Port P1 output	P1OUT	021h
	Port P1 input	P1IN	020h
<b>Special Function</b>	SFR interrupt flag 2	IFG2	003h
	SFR interrupt flag 1	IFG1	002h
	SFR interrupt enable 2	IE2	001h
	SFR interrupt enable 1	IE1	000h

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## absolute maximum ratings<sup>†</sup>

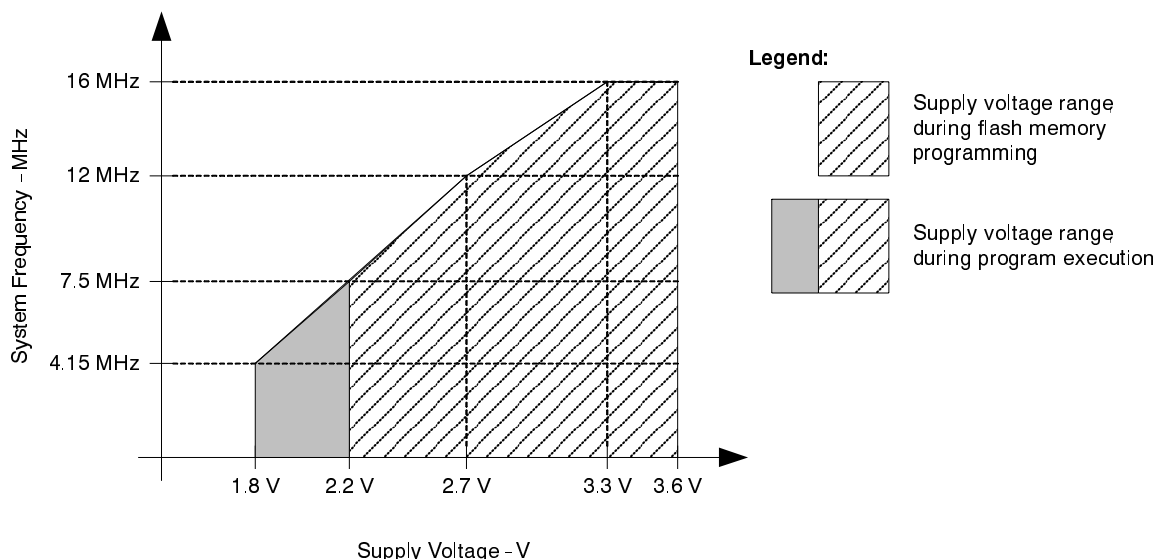
Voltage applied at $V_{CC}$ to $V_{SS}$	-0.3 V to 4.1 V
Voltage applied to any pin (see Note 2)	-0.3 V to $V_{CC}+0.3$ V
Diode current at any device terminal	$\pm 2$ mA
Storage temperature, $T_{stg}$ (unprogrammed device, see Note 3)	-55°C to 150°C
Storage temperature, $T_{stg}$ (programmed device, see Note 3)	-40°C to 85°C

- NOTES: 1. Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
2. All voltages referenced to  $V_{SS}$ . The JTAG fuse-blow voltage,  $V_{FB}$ , is allowed to exceed the absolute maximum rating. The voltage is applied to the TEST pin when blowing the JTAG fuse.
3. Higher temperature may be applied during board soldering process according to the current JEDEC J-STD-020 specification with peak reflow temperatures not higher than classified on the device label on the shipping boxes or reels.

## recommended operating conditions

		MIN	NOM	MAX	UNIT
Supply voltage during program execution, $V_{CC}$		1.8		3.6	V
Supply voltage during program/erase flash memory, $V_{CC}$		2.2		3.6	V
Supply voltage, $V_{SS}$			0		V
Operating free-air temperature range, $T_A$	I version	-40		85	°C
Processor frequency $f_{SYSTEM}$ (Maximum MCLK frequency)	$V_{CC} = 1.8$ V, Duty Cycle = 50% $\pm 10\%$	dc		4.15	MHz
	$V_{CC} = 2.7$ V, Duty Cycle = 50% $\pm 10\%$	dc		12	
	$V_{CC} \geq 3.3$ V, Duty Cycle = 50% $\pm 10\%$	dc		16	

- NOTES: 1. The MSP430 CPU is clocked directly with MCLK.  
Both the high and low phase of MCLK must not exceed the pulse width of the specified maximum frequency.
2. Modules might have a different maximum input clock specification. Refer to the specification of the respective module in this data sheet.



NOTE: Minimum processor frequency is defined by system clock. Flash program or erase operations require a minimum  $V_{CC}$  of 2.2 V.

Figure 1. Save Operating Area

electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

active mode supply current (into  $V_{CC}$ ) excluding external current (see Notes 1 and 2)

PARAMETER	TEST CONDITIONS	$T_A$	$V_{CC}$	MIN	TYP	MAX	UNIT
$I_{AM}$ , 1MHz Active mode (AM) current (1MHz)	$f_{DCO} = f_{MCLK} = f_{SMCLK} = 1\text{MHz}$ , $f_{ACLK} = 32.768\text{kHz}$ , Program executes in flash, BCSCTL1 = CALBC1_1MHz, DCOCTL = CALDCO_1MHz, CPUOFF = 0, SCG0 = 0, SCG1 = 0, OSCOFF = 0		2.2 V		220		$\mu\text{A}$
			3 V		300	370	

- NOTES: 1. All inputs are tied to 0 V or  $V_{CC}$ . Outputs do not source or sink any current.  
2. The currents are characterized with a Micro Crystal CC4V-T1A SMD crystal with a load capacitance of 9 pF. The internal and external load capacitance is chosen to closely match the required 9pF.

typical characteristics - active mode supply current (into  $V_{CC}$ )

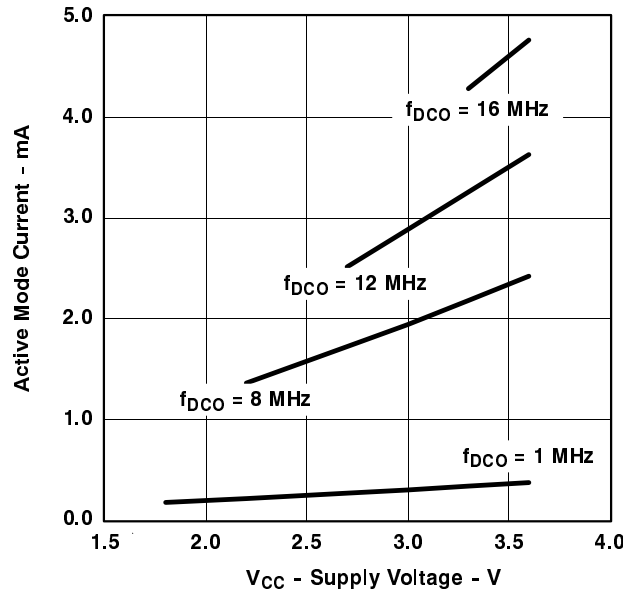


Figure 2. Active mode current vs  $V_{CC}$ ,  $T_A = 25^\circ\text{C}$

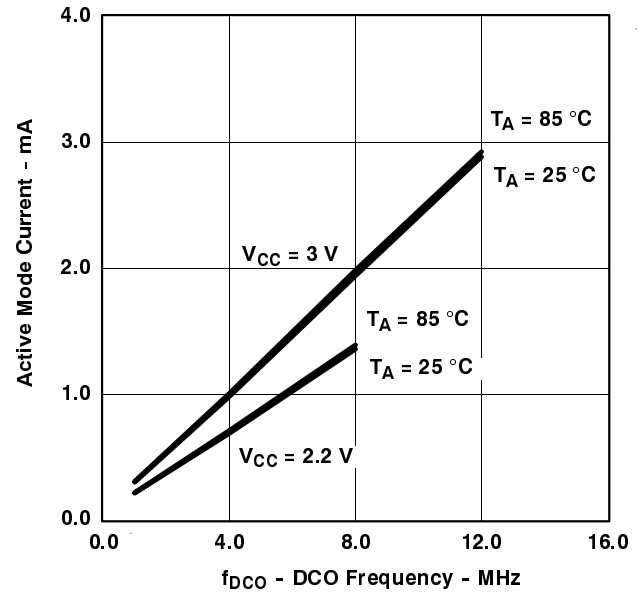


Figure 3. Active mode current vs DCO frequency

# MSP430G2x01, MSP430G2x11 MIXED SIGNAL MICROCONTROLLER

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electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (continued)

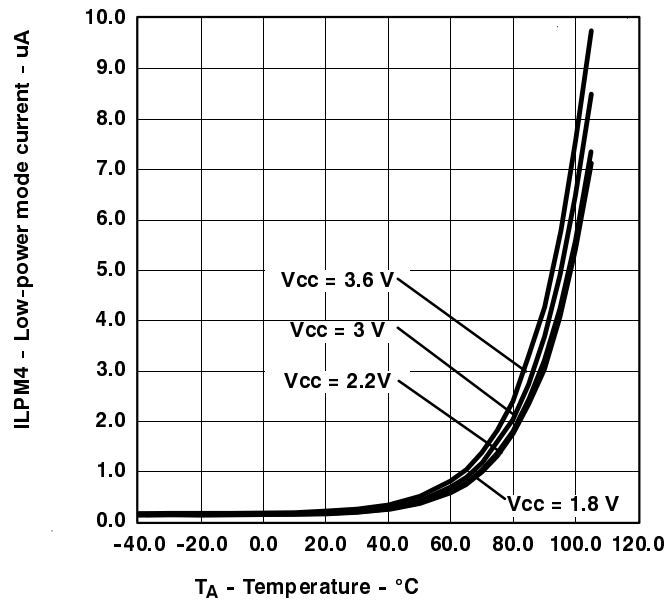
low-power mode supply currents (into  $V_{CC}$ ) excluding external current (see Notes 1 and 2)

PARAMETER	TEST CONDITIONS	$T_A$	$V_{CC}$	MIN	TYP	MAX	UNIT
$I_{LPM0, 1MHz}$ Low-power mode 0 (LPM0) current, see Note 3	$f_{MCLK} = 0$ MHz, $f_{SMCLK} = f_{DCO} = 1$ MHz, $f_{ACLK} = 32,768$ Hz, BCSCTL1 = CALBC1_1MHZ, DCOCTL = CALDCO_1MHZ, CPUOFF = 1, SCG0 = 0, SCG1 = 0, OSCOFF = 0	25°C	2.2 V		65		$\mu A$
$I_{LPM2}$ Low-power mode 2 (LPM2) current, see Note 4	$f_{MCLK} = f_{SMCLK} = 0$ MHz, $f_{DCO} = 1$ MHz, $f_{ACLK} = 32,768$ Hz, BCSCTL1 = CALBC1_1MHZ, DCOCTL = CALDCO_1MHZ, CPUOFF = 1, SCG0 = 0, SCG1 = 1, OSCOFF = 0	25°C	2.2 V		22		$\mu A$
$I_{LPM3, LFXT1}$ Low-power mode 3 (LPM3) current, see Note 4	$f_{DCO} = f_{MCLK} = f_{SMCLK} = 0$ MHz, $f_{ACLK} = 32,768$ Hz, CPUOFF = 1, SCG0 = 1, SCG1 = 1, OSCOFF = 0	25°C	2.2 V		0.7	1.5	$\mu A$
$I_{LPM3, VLO}$ Low-power mode 3 current, (LPM3) see Note 4	$f_{DCO} = f_{MCLK} = f_{SMCLK} = 0$ MHz, $f_{ACLK}$ from internal LF oscillator (VLO), CPUOFF = 1, SCG0 = 1, SCG1 = 1, OSCOFF = 0	25°C	2.2 V		0.5	0.7	$\mu A$
$I_{LPM4}$ Low-power mode 4 (LPM4) current, see Note 5	$f_{DCO} = f_{MCLK} = f_{SMCLK} = 0$ MHz, $f_{ACLK} = 0$ Hz, CPUOFF = 1, SCG0 = 1, SCG1 = 1, OSCOFF = 1	25°C	2.2 V		0.1	0.5	$\mu A$
		85°C	2.2 V		0.8	1.5	$\mu A$

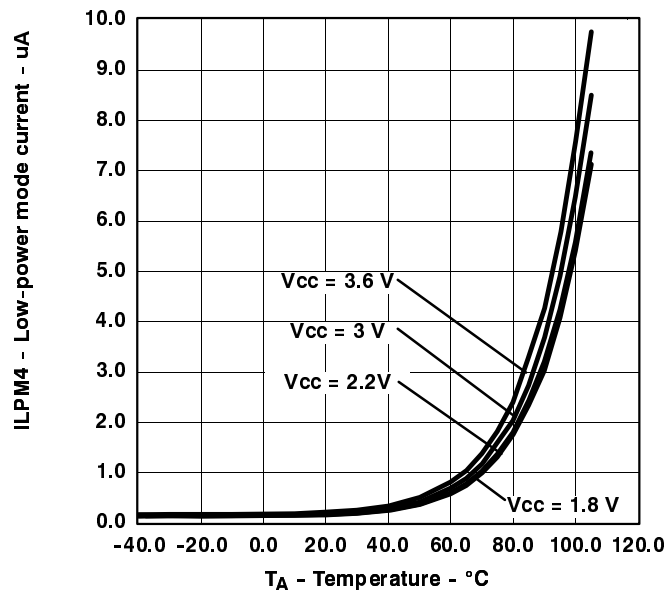
- NOTES: 1. All inputs are tied to 0 V or  $V_{CC}$ . Outputs do not source or sink any current.  
2. The currents are characterized with a Micro Crystal CC4V-T1A SMD crystal with a load capacitance of 9 pF.  
3. Current for brownout and WDT clocked by SMCLK included.  
4. Current for brownout and WDT clocked by ACLK included.  
5. Current for brownout included.

electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (continued)

typical characteristics - LPM3 current



typical characteristics - LPM4 current



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electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (continued)

## Schmitt-trigger inputs - Ports Px

PARAMETER	TEST CONDITIONS	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
V <sub>IT+</sub> Positive-going input threshold voltage			0.45		0.75	V <sub>CC</sub>
		3 V	1.35		2.25	V
V <sub>IT-</sub> Negative-going input threshold voltage			0.25		0.55	V <sub>CC</sub>
		3 V	0.75		1.65	V
V <sub>hys</sub> Input voltage hysteresis (V <sub>IT+</sub> - V <sub>IT-</sub> )		3 V	0.3		1.0	V
R <sub>Pull</sub> Pull-up/pull-down resistor	For pullup: V <sub>IN</sub> = V <sub>SS</sub> ; For pulldown: V <sub>IN</sub> = V <sub>CC</sub>	3V	20	35	50	kΩ
C <sub>I</sub> Input Capacitance	V <sub>IN</sub> = V <sub>SS</sub> or V <sub>CC</sub>			5		pF

NOTES: 1. An external signal sets the interrupt flag every time the minimum interrupt pulse width  $t_{(int)}$  is met. It may be set even with trigger signals shorter than  $t_{(int)}$ .

## leakage current - Ports Px

PARAMETER	TEST CONDITIONS	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
I <sub>lkg</sub> (Px.x) High-impedance leakage current	see Notes 1 and 2	3 V			±50	nA

NOTES: 1. The leakage current is measured with V<sub>SS</sub> or V<sub>CC</sub> applied to the corresponding pin(s), unless otherwise noted.  
2. The leakage of the digital port pins is measured individually. The port pin is selected for input and the pull-up/pull-down resistor is disabled.

## outputs - Ports Px

PARAMETER	TEST CONDITIONS	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
V <sub>OH</sub> High-level output voltage	I <sub>(OHmax)</sub> = -6 mA (see Notes 2)	2.2 V		V <sub>CC</sub> -0.3		V
V <sub>OL</sub> Low-level output voltage	I <sub>(OLmax)</sub> = 6 mA (see Notes 2)	2.2 V		V <sub>SS</sub> +0.3		V

NOTES: 1. The maximum total current, I<sub>OHmax</sub> and I<sub>OLmax</sub>, for all outputs combined, should not exceed ±12 mA to hold the maximum voltage drop specified.  
2. The maximum total current, I<sub>OHmax</sub> and I<sub>OLmax</sub>, for all outputs combined, should not exceed ±48 mA to hold the maximum voltage drop specified.

## output frequency - Ports Px

PARAMETER	TEST CONDITIONS	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
f <sub>Px.y</sub> Port output frequency (with load)	Px.y, C <sub>L</sub> = 20 pF, R <sub>L</sub> = 1 kΩ (see Note 1 and 2)	3 V		12		MHz
f <sub>Port_CLK</sub> Clock output frequency	Px.y, C <sub>L</sub> = 20 pF (see Note 2)	3 V		16		MHz

NOTES: 1. A resistive divider with 2 times 0.5 kΩ between V<sub>CC</sub> and V<sub>SS</sub> is used as load. The output is connected to the center tap of the divider.  
2. The output voltage reaches at least 10% and 90% V<sub>CC</sub> at the specified toggle frequency.



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electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (continued)

typical characteristics - outputs

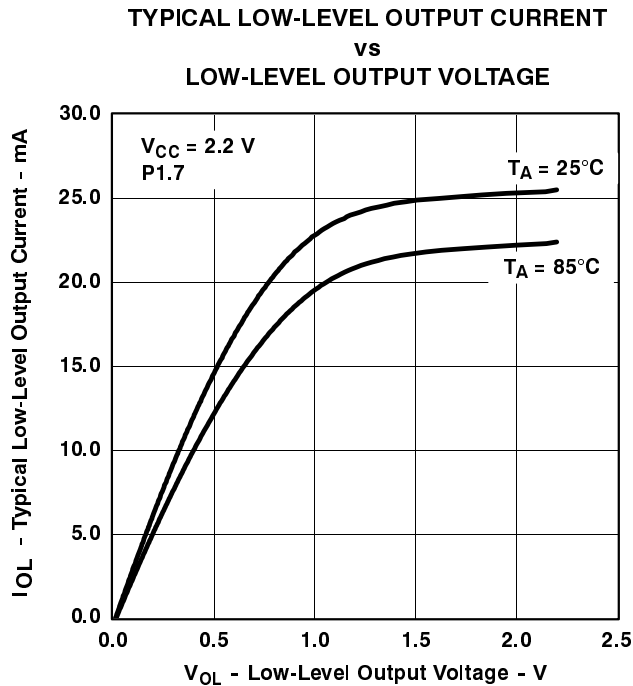


Figure 4

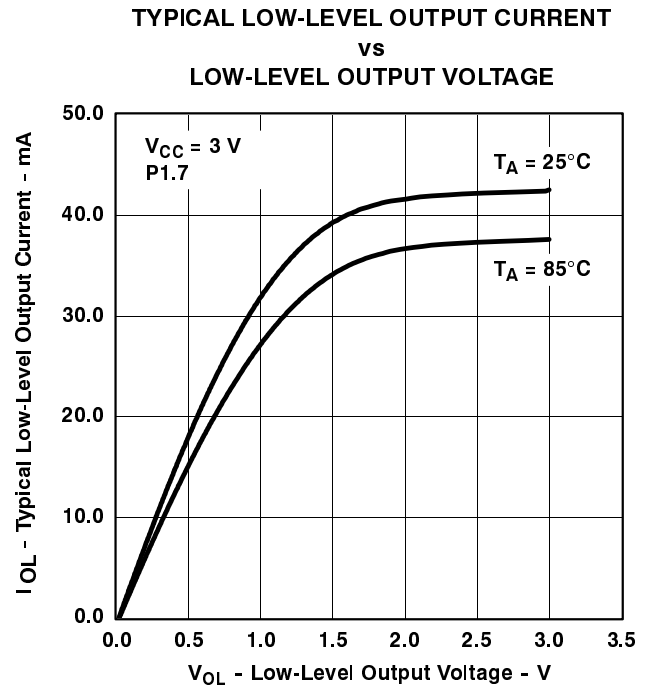


Figure 5

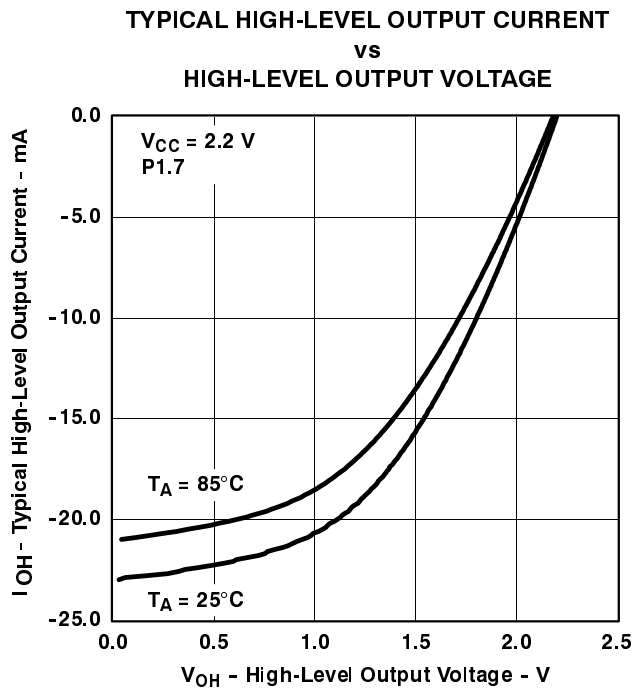


Figure 6

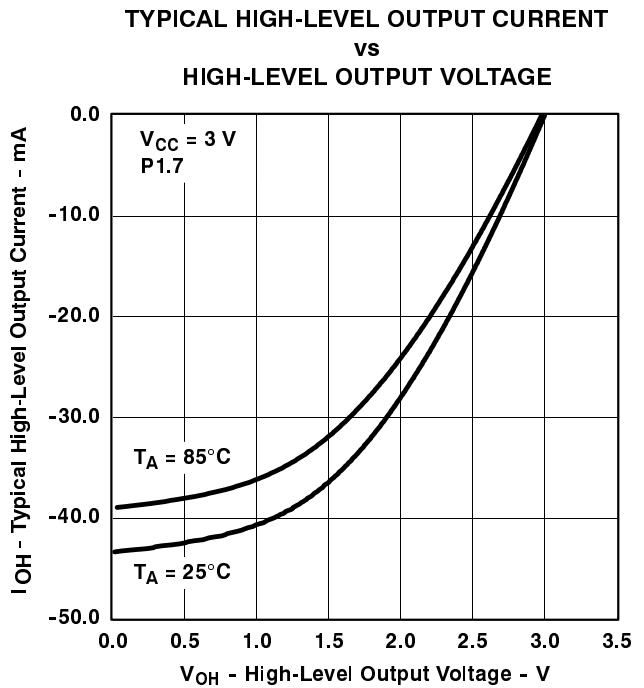


Figure 7

NOTE: One output loaded at a time.

# MSP430G2x01, MSP430G2x11

## MIXED SIGNAL MICROCONTROLLER

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electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (continued)

### POR/brownout reset (BOR) (see Notes 1 and 2)

PARAMETER	TEST CONDITIONS	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
V <sub>CC(start)</sub>	(see Figure 8)	dV <sub>CC</sub> /dt ≤ 3 V/s		0.7 × V <sub>(B_IT-)</sub>		V
V <sub>(B_IT-)</sub>	(see Figure 8 through Figure 10)	dV <sub>CC</sub> /dt ≤ 3 V/s		1.35		V
V <sub>hys(B_IT-)</sub>	(see Figure 8)	dV <sub>CC</sub> /dt ≤ 3 V/s		140		mV
t <sub>d(BOR)</sub>	(see Figure 8)			2000		μs
t <sub>(reset)</sub>	Pulse length needed at $\overline{\text{RST}}/\text{NMI}$ pin to accepted reset internally	2.2 V/3 V	2			μs

- NOTES: 1. The current consumption of the brownout module is already included in the I<sub>CC</sub> current consumption data. The voltage level V<sub>(B\_IT-)</sub> + V<sub>hys(B\_IT-)</sub> is ≤ 1.8V.
2. During power up, the CPU begins code execution following a period of t<sub>d(BOR)</sub> after V<sub>CC</sub> = V<sub>(B\_IT-)</sub> + V<sub>hys(B\_IT-)</sub>. The default DCO settings must not be changed until V<sub>CC</sub> ≥ V<sub>CC(min)</sub>, where V<sub>CC(min)</sub> is the minimum supply voltage for the desired operating frequency.

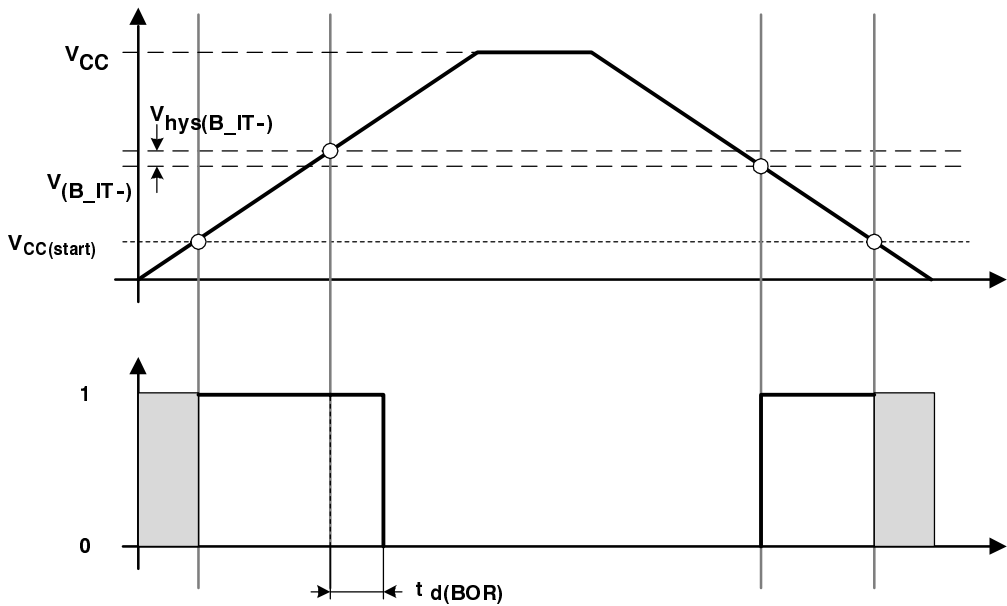


Figure 8. POR/Brownout Reset (BOR) vs Supply Voltage



electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (continued)

typical characteristics - POR/brownout reset (BOR)

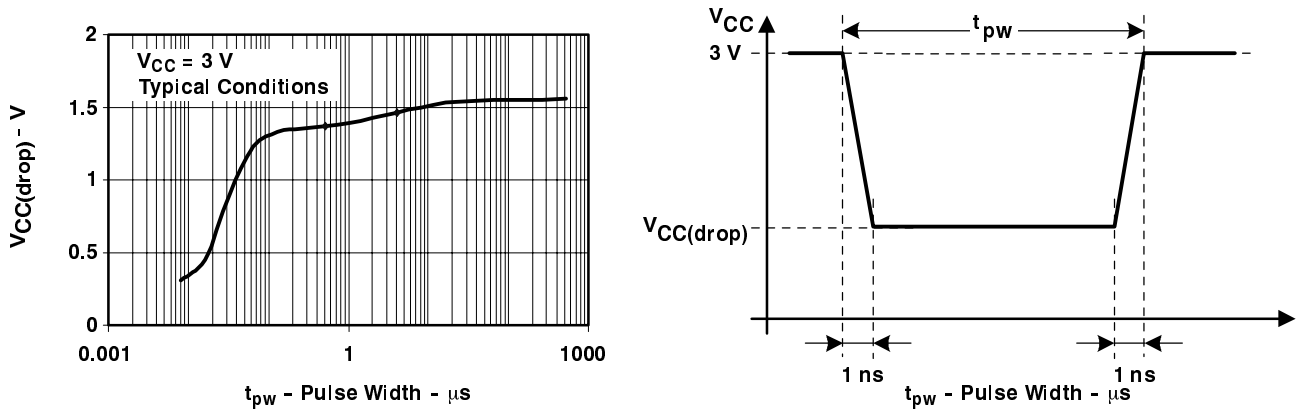


Figure 9.  $V_{CC(drop)}$  Level With a Square Voltage Drop to Generate a POR/Brownout Signal

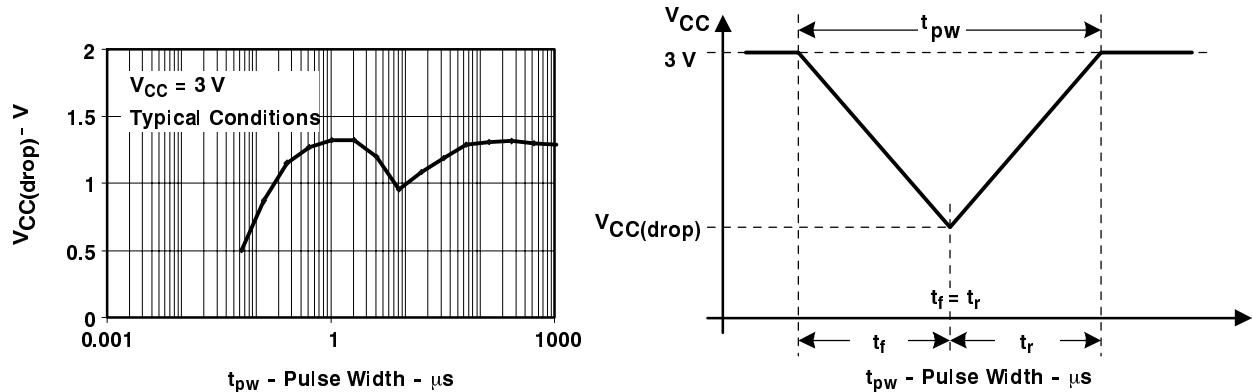


Figure 10.  $V_{CC(drop)}$  Level With a Triangle Voltage Drop to Generate a POR/Brownout Signal

PRODUCT PREVIEW

# MSP430G2x01, MSP430G2x11

## MIXED SIGNAL MICROCONTROLLER

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**electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (continued)**

### main DCO characteristics

- All ranges selected by RSELx overlap with RSELx + 1: RSELx = 0 overlaps RSELx = 1, ... RSELx = 14 overlaps RSELx = 15.
- DCO control bits DCOx have a step size as defined by parameter S<sub>DCO</sub>.
- Modulation control bits MODx select how often f<sub>DCO(RSEL,DCO+1)</sub> is used within the period of 32 DCOCLK cycles. The frequency f<sub>DCO(RSEL,DCO)</sub> is used for the remaining cycles. The frequency is an average equal to:

$$f_{average} = \frac{32 \times f_{DCO(RSEL,DCO)} \times f_{DCO(RSEL,DCO+1)}}{MOD \times f_{DCO(RSEL,DCO)} + (32 - MOD) \times f_{DCO(RSEL,DCO+1)}}$$

### DCO frequency

PARAMETER	TEST CONDITIONS	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
V <sub>CC</sub> Supply voltage range	RSELx < 14		1.8		3.6	V
	RSELx = 14		2.2		3.6	V
	RSELx = 15		3.0		3.6	V
f <sub>DCO(0,0)</sub> DCO frequency (0, 0)	RSELx = 0, DCOx = 0, MODx = 0	3 V	0.06		0.14	MHz
f <sub>DCO(0,3)</sub> DCO frequency (0, 3)	RSELx = 0, DCOx = 3, MODx = 0	3 V		0.12		MHz
f <sub>DCO(1,3)</sub> DCO frequency (1, 3)	RSELx = 1, DCOx = 3, MODx = 0	3 V		0.15		MHz
f <sub>DCO(2,3)</sub> DCO frequency (2, 3)	RSELx = 2, DCOx = 3, MODx = 0	3 V		0.21		MHz
f <sub>DCO(3,3)</sub> DCO frequency (3, 3)	RSELx = 3, DCOx = 3, MODx = 0	3 V		0.30		MHz
f <sub>DCO(4,3)</sub> DCO frequency (4, 3)	RSELx = 4, DCOx = 3, MODx = 0	3 V		0.41		MHz
f <sub>DCO(5,3)</sub> DCO frequency (5, 3)	RSELx = 5, DCOx = 3, MODx = 0	3 V		0.58		MHz
f <sub>DCO(6,3)</sub> DCO frequency (6, 3)	RSELx = 6, DCOx = 3, MODx = 0	3 V		0.80		MHz
f <sub>DCO(7,3)</sub> DCO frequency (7, 3)	RSELx = 7, DCOx = 3, MODx = 0	3 V	0.80		1.50	MHz
f <sub>DCO(8,3)</sub> DCO frequency (8, 3)	RSELx = 8, DCOx = 3, MODx = 0	3 V		1.60		MHz
f <sub>DCO(9,3)</sub> DCO frequency (9, 3)	RSELx = 9, DCOx = 3, MODx = 0	3 V		2.30		MHz
f <sub>DCO(10,3)</sub> DCO frequency (10, 3)	RSELx = 10, DCOx = 3, MODx = 0	3 V		3.40		MHz
f <sub>DCO(11,3)</sub> DCO frequency (11, 3)	RSELx = 11, DCOx = 3, MODx = 0	3 V		4.25		MHz
f <sub>DCO(12,3)</sub> DCO frequency (12, 3)	RSELx = 12, DCOx = 3, MODx = 0	3 V	4.30		7.30	MHz
f <sub>DCO(13,3)</sub> DCO frequency (13, 3)	RSELx = 13, DCOx = 3, MODx = 0	3 V		7.8		MHz
f <sub>DCO(14,3)</sub> DCO frequency (14, 3)	RSELx = 14, DCOx = 3, MODx = 0	3 V	8.60		13.9	MHz
f <sub>DCO(15,3)</sub> DCO frequency (15, 3)	RSELx = 15, DCOx = 3, MODx = 0	3 V		15.25		MHz
f <sub>DCO(15,7)</sub> DCO frequency (15, 7)	RSELx = 15, DCOx = 7, MODx = 0	3 V		21.00		MHz
S <sub>RSEL</sub> Frequency step between range RSEL and RSEL+1	S <sub>RSEL</sub> = f <sub>DCO(RSEL+1,DCO)</sub> /f <sub>DCO(RSEL,DCO)</sub>	3 V		1.35		ratio
S <sub>DCO</sub> Frequency step between tap DCO and DCO+1	S <sub>DCO</sub> = f <sub>DCO(RSEL,DCO+1)</sub> /f <sub>DCO(RSEL,DCO)</sub>	3 V		1.08		
Duty Cycle	Measured at SMCLK output	3 V		50		%



**electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (continued)**

**calibrated DCO frequencies - tolerance**

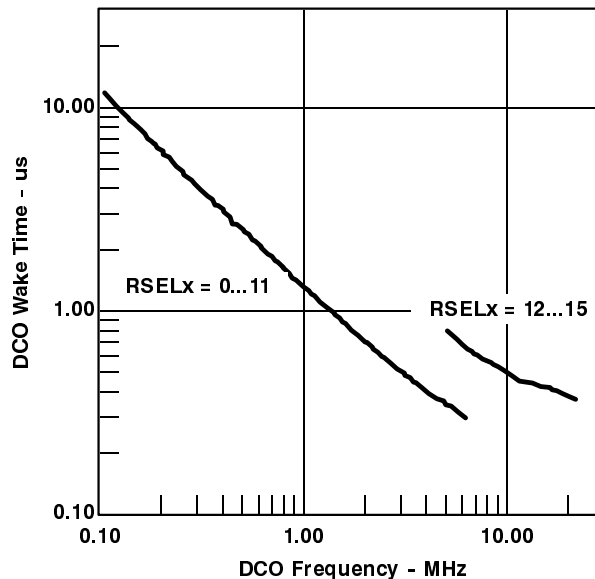
PARAMETER	TEST CONDITIONS	T <sub>A</sub>	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
1 MHz tolerance over temperature	BCSCTL1= CALBC1_1MHz DCOCTL = CALDCO_1MHz calibrated at 30°C and 3.0V	0 – 85°C	3.0 V	-3	±2	+3	%
1 MHz tolerance over V <sub>CC</sub>	BCSCTL1= CALBC1_1MHz DCOCTL = CALDCO_1MHz calibrated at 30°C and 3.0V	30°C	1.8 V – 3.6 V	-3	±2	+3	%
1 MHz tolerance overall	BCSCTL1= CALBC1_1MHz DCOCTL = CALDCO_1MHz calibrated at 30°C and 3.0V	-40 – 85°C	1.8 V – 3.6 V	-6	±3	+6	%

**wake-up from lower power modes (LPM3/4)**

PARAMETER	TEST CONDITIONS	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
t <sub>DCO,LPM3/4</sub> DCO clock wake-up time from LPM3/4 (see Note 1)	BCSCTL1= CALBC1_1MHz DCOCTL = CALDCO_1MHz	3 V		1		μs
t <sub>CPU,LPM3/4</sub> CPU wake-up time from LPM3/4 (see Note 2)				1/f <sub>MCLK</sub> + t <sub>Clock,LPM3/4</sub>		

NOTES: 1. The DCO clock wake-up time is measured from the edge of an external wake-up signal (e.g. port interrupt) to the first clock edge observable externally on a clock pin (MCLK or SMCLK).  
2. Parameter applicable only if DCOCLK is used for MCLK.

**typical characteristics - DCO clock wake-up time from LPM3/4**



**Figure 11. DCO wake-up time from LPM3 vs DCO frequency**

# MSP430G2x01, MSP430G2x11 MIXED SIGNAL MICROCONTROLLER

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**electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (continued)**

## crystal oscillator, LFXT1, low frequency modes (see Note 4)

PARAMETER		TEST CONDITIONS	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
f <sub>LFXT1,LF</sub>	LFXT1 oscillator crystal frequency, LF mode 0, 1	XTS = 0, LFXT1Sx = 0 or 1	1.8 V to 3.6 V	32768			Hz
f <sub>LFXT1,LF,logic</sub>	LFXT1 oscillator logic level square wave input frequency, LF mode	XTS = 0, XCAPx = 0, LFXT1Sx = 3	1.8 V to 3.6 V	10000	32768	50,000	Hz
O <sub>ALF</sub>	Oscillation allowance for LF crystals	XTS = 0, LFXT1Sx = 0, f <sub>LFXT1,LF</sub> = 32,768 kHz, C <sub>L,eff</sub> = 6 pF		500			kΩ
		XTS = 0, LFXT1Sx = 0, f <sub>LFXT1,LF</sub> = 32,768 kHz, C <sub>L,eff</sub> = 12 pF		200			
C <sub>L,eff</sub>	Integrated effective load capacitance, LF mode (see Note 1)	XTS = 0, XCAPx = 0		1			pF
		XTS = 0, XCAPx = 1		5.5			
		XTS = 0, XCAPx = 2		8.5			
		XTS = 0, XCAPx = 3		11			
Duty cycle	LF mode	XTS = 0, Measured at P2.0/ACLK, f <sub>LFXT1,LF</sub> = 32,768Hz	2.2 V	30	50	70	%
f <sub>Fault,LF</sub>	Oscillator fault frequency, LF mode (see Note 3)	XTS = 0, XCAPx = 0, LFXT1Sx = 3 (see Note 2)	2.2 V	10	10000		Hz

- NOTES: 1. Includes parasitic bond and package capacitance (approximately 2 pF per pin). Since the PCB adds additional capacitance it is recommended to verify the correct load by measuring the ACLK frequency. For a correct setup the effective load capacitance should always match the specification of the used crystal.
2. Measured with logic level input frequency but also applies to operation with crystals.
3. Frequencies below the MIN specification set the fault flag, frequencies above the MAX specification do not set the fault flag, and frequencies in between might set the flag.
4. To improve EMI on the LFXT1 oscillator the following guidelines should be observed.
- Keep the trace between the device and the crystal as short as possible.
  - Design a good ground plane around the oscillator pins.
  - Prevent crosstalk from other clock or data lines into oscillator pins XIN and XOUT.
  - Avoid running PCB traces underneath or adjacent to the XIN and XOUT pins.
  - Use assembly materials and praxis to avoid any parasitic load on the oscillator XIN and XOUT pins.
  - If conformal coating is used, ensure that it does not induce capacitive/resistive leakage between the oscillator pins.
  - Do not route the XOUT line to the JTAG header to support the serial programming adapter as shown in other documentation. This signal is no longer required for the serial programming adapter.

## internal very low power, low frequency oscillator (VLO)

PARAMETER	TEST CONDITIONS	T <sub>A</sub>	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
f <sub>VLO</sub>	VLO frequency	-40 – 85°C	3.0 V	4	12	20	kHz
df <sub>VLO</sub> /dT	VLO frequency temperature drift	-40 – 85°C	3.0 V		0.5		%/°C
df <sub>VLO</sub> /dV <sub>CC</sub>	VLO frequency supply voltage drift	25°C	1.8 V – 3.6 V		4		%/V



**electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (continued)**

**Timer\_A**

PARAMETER	TEST CONDITIONS	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
f <sub>TA</sub> Timer_A clock frequency	Internal: SMCLK, ACLK; External: TACLK, INCLK; Duty Cycle = 50% ±10%			f <sub>SYSTEM</sub>		MHz
t <sub>TA,cap</sub> Timer_A, capture timing	TA0, TA1	3.0 V	20			ns

**Comparator\_A+ (MSP430G2x11 only)**

PARAMETER	TEST CONDITIONS	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
I <sub>(DD)</sub>	CAON=1, CARSEL=0, CAREF=0	2.2 V		25		μA
I <sub>(Refladder/RefDiode)</sub>	CAON=1, CARSEL=0, CAREF=1/2/3, no load at CA0 and CA1	2.2 V		30		μA
V <sub>(IC)</sub> Common-mode input voltage	CAON=1	2.2 V	0	V <sub>CC</sub> -1		V
V <sub>(Ref025)</sub> $\frac{\text{Voltage @ } 0.25 V_{CC} \text{ node}}{V_{CC}}$	PCA0=1, CARSEL=1, CAREF=1, no load at CA0 and CA1	2.2 V		0.24		
V <sub>(Ref050)</sub> $\frac{\text{Voltage @ } 0.5 V_{CC} \text{ node}}{V_{CC}}$	PCA0=1, CARSEL=1, CAREF=2, no load at CA0 and CA1	2.2 V		0.48		
V <sub>(RefVT)</sub> (see Figure 12 and Figure 13)	PCA0=1, CARSEL=1, CAREF=3, no load at CA0 and CA1, T <sub>A</sub> = 85°C	2.2 V		480		mV
V <sub>(offset)</sub> Offset voltage	See Note 2	2.2 V		±10		mV
V <sub>hys</sub> Input hysteresis	CAON=1	2.2 V		0.7		mV
t <sub>(response)</sub> Response time (low-high and high-low)	T <sub>A</sub> = 25°C, Overdrive 10 mV, Without filter: CAF=0	2.2 V		165		ns
	T <sub>A</sub> = 25°C, Overdrive 10 mV, With filter: CAF=1	2.2 V		1.9		μs

- NOTES: 1. The leakage current for the Comparator\_A+ terminals is identical to I<sub>lkg(Px.x)</sub> specification.  
2. The input offset voltage can be cancelled by using the CAEX bit to invert the Comparator\_A+ inputs on successive measurements. The two successive measurements are then summed together.

MSP430G2x01, MSP430G2x11  
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electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (continued)

typical characteristics - Comparator\_A+

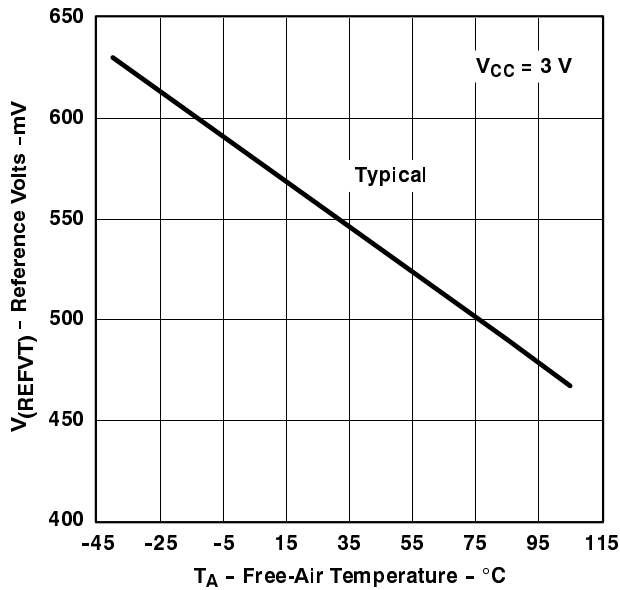


Figure 12.  $V_{(REFVT)}$  vs Temperature,  $V_{CC} = 3\text{ V}$

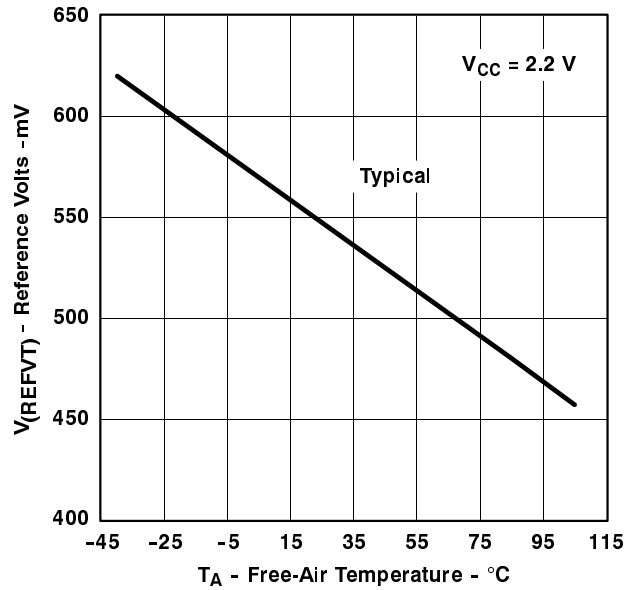


Figure 13.  $V_{(REFVT)}$  vs Temperature,  $V_{CC} = 2.2\text{ V}$

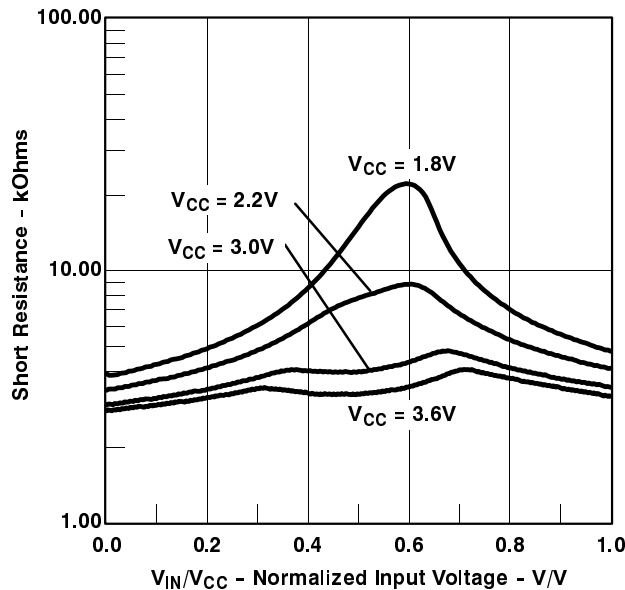


Figure 14. Short Resistance vs  $V_{IN}/V_{CC}$

**electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (continued)**

**flash memory**

PARAMETER	TEST CONDITIONS	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
V <sub>CC(PGM/ERASE)</sub> Program and Erase supply voltage			2.2		3.6	V
f <sub>FTG</sub> Flash Timing Generator frequency			257		476	kHz
I <sub>PGM</sub> Supply current from V <sub>CC</sub> during program		2.2 V/3.6 V		1	5	mA
I <sub>ERASE</sub> Supply current from V <sub>CC</sub> during erase		2.2 V/3.6 V		1	7	mA
t <sub>CPT</sub> Cumulative program time (see Note 1)		2.2 V/3.6 V			10	ms
t <sub>CMErase</sub> Cumulative mass erase time		2.2 V/3.6 V	20			ms
Program/Erase endurance			10 <sup>4</sup>	10 <sup>5</sup>		cycles
t <sub>Retention</sub> Data retention duration	T <sub>J</sub> = 25°C		100			years
t <sub>Word</sub> Word or byte program time	see Note 2			30		t <sub>FTG</sub>
t <sub>Block, 0</sub> Block program time for 1 <sup>st</sup> byte or word				25		
t <sub>Block, 1-63</sub> Block program time for each additional byte or word				18		
t <sub>Block, End</sub> Block program end-sequence wait time				6		
t <sub>Mass Erase</sub> Mass erase time				10593		
t <sub>Seq Erase</sub> Segment erase time				4819		

- NOTES: 1. The cumulative program time must not be exceeded when writing to a 64-byte flash block. This parameter applies to all programming methods: individual word/byte write and block write modes.  
2. These values are hardwired into the Flash Controller's state machine (t<sub>FTG</sub> = 1/f<sub>FTG</sub>).

**RAM**

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>(RAMh)</sub> RAM retention supply voltage (see Note 1)	CPU halted	1.6			V

NOTE 1: This parameter defines the minimum supply voltage V<sub>CC</sub> when the data in RAM remains unchanged. No program execution should happen during this supply voltage condition.

# MSP430G2x01, MSP430G2x11 MIXED SIGNAL MICROCONTROLLER

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electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (continued)

## JTAG and Spy-Bi-Wire interface

PARAMETER		TEST CONDITIONS	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
f <sub>SBW</sub>	Spy-Bi-Wire input frequency		2.2 V / 3 V	0		20	MHz
t <sub>SBW,Low</sub>	Spy-Bi-Wire low clock pulse length		2.2 V / 3 V	0.025		15	us
t <sub>SBW,En</sub>	Spy-Bi-Wire enable time (TEST high to acceptance of first clock edge, see Note 1)		2.2 V / 3 V			1	us
t <sub>SBW,Ret</sub>	Spy-Bi-Wire return to normal operation time		2.2 V / 3 V	15		100	us
f <sub>TCK</sub>	TCK input frequency - 4-wire JTAG (see Note 2)		2.2 V	0		5	MHz
			3 V	0		10	MHz
R <sub>Internal</sub>	Internal pull-down resistance on TEST		2.2 V / 3 V	25	60	90	kΩ

- NOTES: 1. Tools accessing the Spy-Bi-Wire interface need to wait for the maximum t<sub>SBW,En</sub> time after pulling the TEST/SBWTCK pin high before applying the first SBWTCK clock edge.  
2. f<sub>TCK</sub> may be restricted to meet the timing requirements of the module selected.

## JTAG fuse (see Note 1)

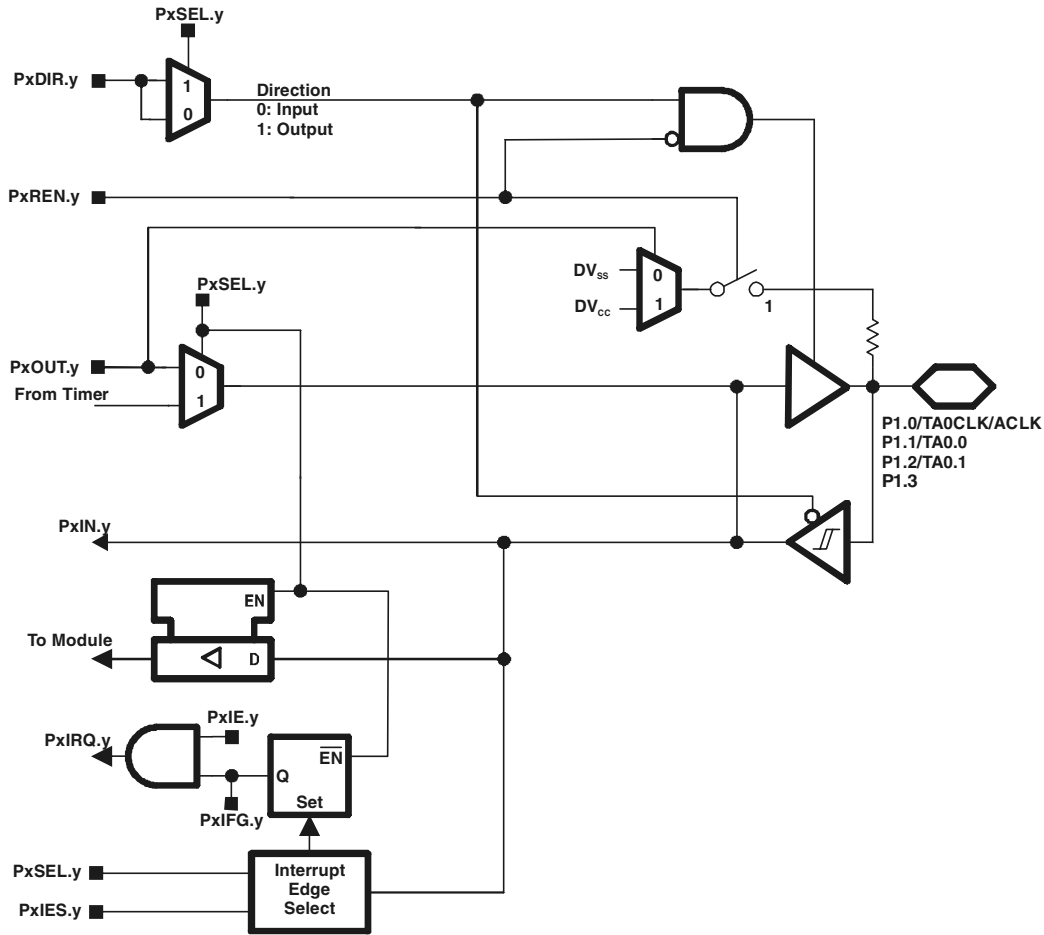
PARAMETER		TEST CONDITIONS	V <sub>CC</sub>	MIN	TYP	MAX	UNIT
V <sub>CC(FB)</sub>	Supply voltage during fuse-blow condition	T <sub>A</sub> = 25°C		2.5			V
V <sub>FB</sub>	Voltage level on TEST for fuse-blow			6		7	V
I <sub>FB</sub>	Supply current into TEST during fuse blow					100	mA
t <sub>FB</sub>	Time to blow fuse					1	ms

- NOTES: 1. Once the fuse is blown, no further access to the JTAG/Test, Spy-Bi-Wire, and emulation feature is possible and JTAG is switched to bypass mode.



**APPLICATION INFORMATION**

**Port P1 pin schematic: P1.0 to P1.3, input/output with Schmitt trigger - MSP430G2x10**



**Port P1 (P1.0 to P1.3) pin functions - MSP430G2x10**

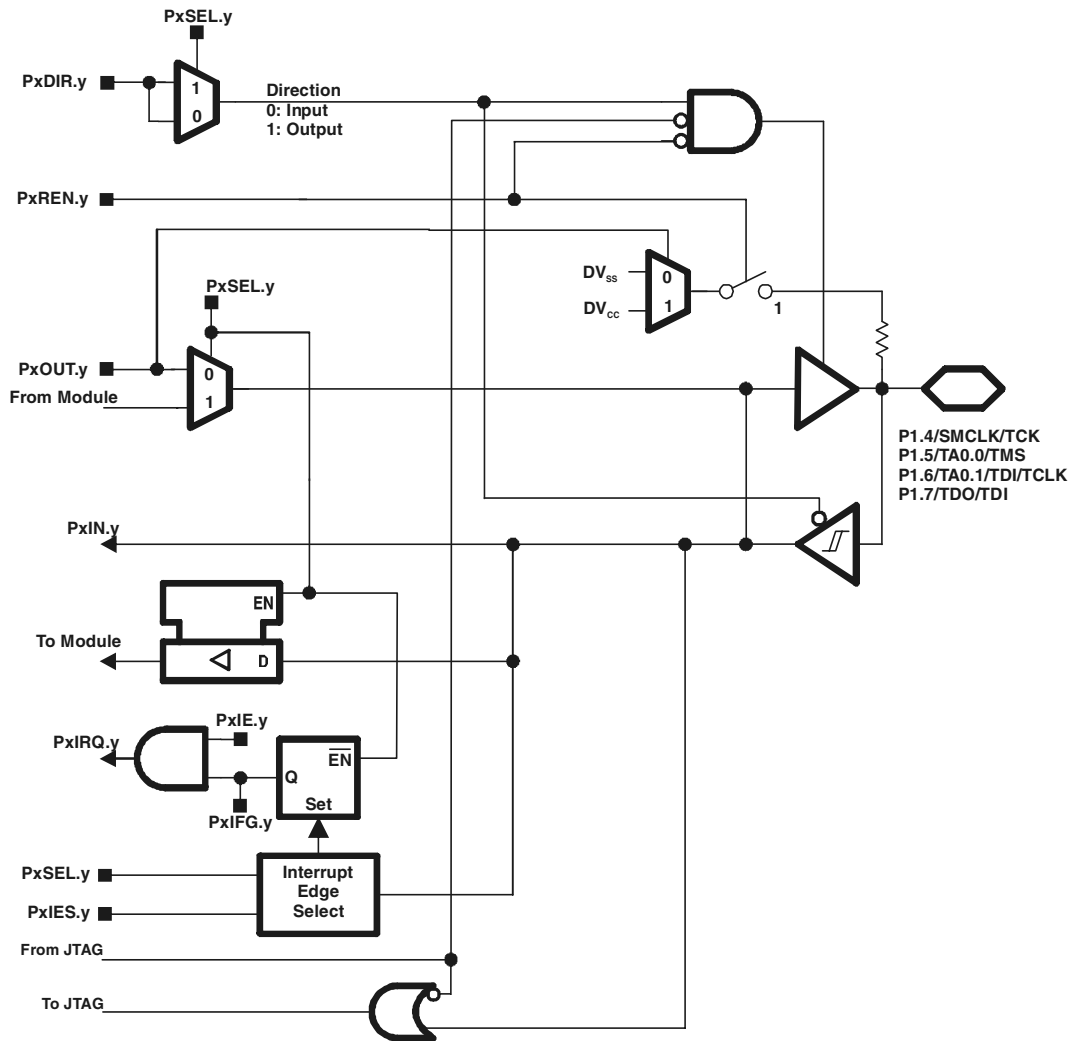
PIN NAME (P1.X)	X	FUNCTION	CONTROL BITS / SIGNALS	
			P1DIR.x	P1SEL.x
P1.0/ TA0CLK/ ACLK	0	P1.x (I/O)	I: 0; O: 1	0
		TA0.TACLK	0	1
		ACLK	1	1
P1.1/ TA0.0	1	P1.x (I/O)	I: 0; O: 1	0
		TA0.0	1	1
		TA0.CCI0A	0	1
P1.2/ TA0.1	2	P1.x (I/O)	I: 0; O: 1	0
		TA0.1	1	1
		TA0.CCI1A	0	1
P1.3/	3	P1.x (I/O)	I: 0; O: 1	0

**PRODUCT PREVIEW**

# MSP430G2x01, MSP430G2x11 MIXED SIGNAL MICROCONTROLLER

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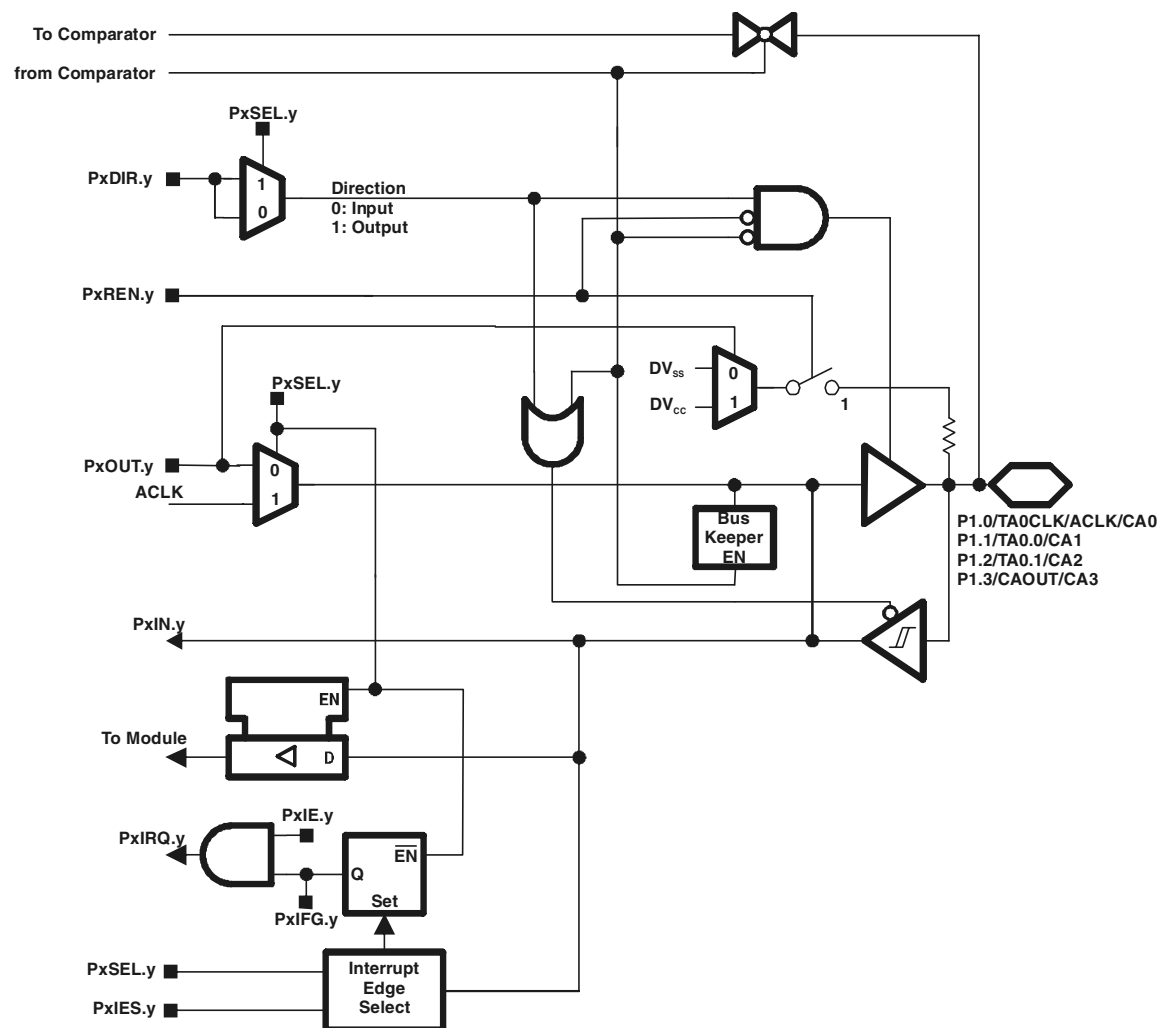
## Port P1 pin schematic: P1.4 to P1.7, input/output with Schmitt trigger - MSP430G2x10



## Port P1 (P1.4 to P1.7) pin functions - MSP430G2x10

PIN NAME (P1.X)	X	FUNCTION	CONTROL BITS / SIGNALS			
			P1DIR.x	P1SEL.x	JTAG Mode	CAPD.y
P1.4/ SMCLK/ TCK	4	P1.x (I/O)	I: 0; O: 1	0	0	0
		SMCLK	1	1	0	0
		TCK	x	x	1	0
P1.5/ TA0.0/ TMS	5	P1.x (I/O)	I: 0; O: 1	0	0	0
		TA0.0	1	1	0	0
		TMS	x	x	1	0
P1.6/ TA0.1/ TDI/TCLK	6	P1.x (I/O)	I: 0; O: 1	0	0	0
		TA0.1	1	1	0	0
		TDI/TCLK	x	x	1	0
P1.7/ TDO/TDI	7	P1.x (I/O)	I: 0; O: 1	0	0	0
		TDO/TDI	x	x	1	0

**Port P1 pin schematic: P1.0 to P1.3, input/output with Schmitt trigger - MSP430G2x11**



**PRODUCT PREVIEW**

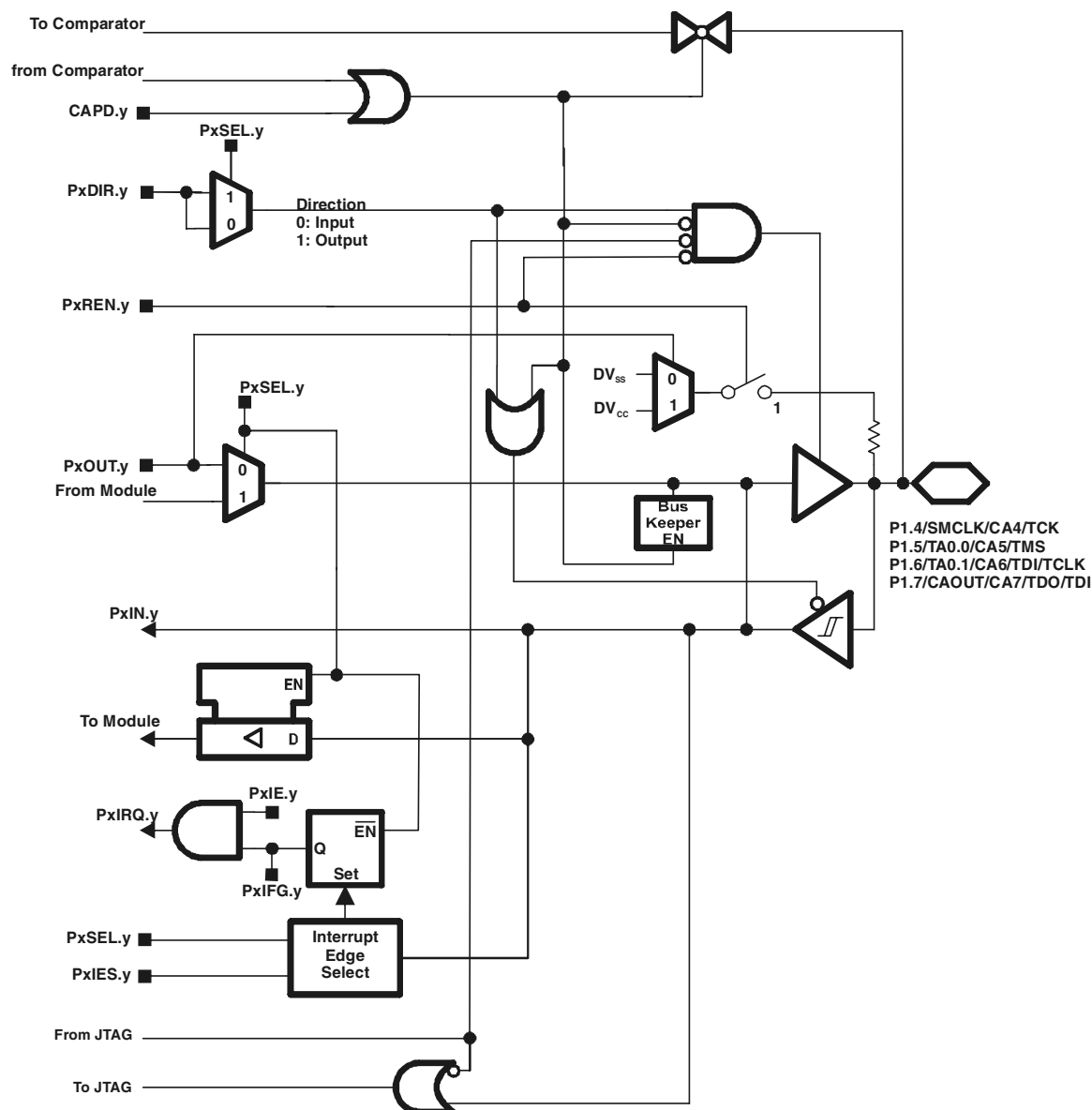
# MSP430G2x01, MSP430G2x11 MIXED SIGNAL MICROCONTROLLER

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## Port P1 (P1.0 to P1.3) pin functions - MSP430G2x11

PIN NAME (P1.X)	X	FUNCTION	CONTROL BITS / SIGNALS		
			P1DIR.x	P1SEL.x	CAPD.y
P1.0/ TA0CLK/ ACLK/ CA0	0	P1.x (I/O)	I: 0; O: 1	0	0
		TA0.TACLK	0	1	0
		ACLK	1	1	0
		CA0	x	x	1 (y = 0)
P1.1/ TA0.0/  CA1	1	P1.x (I/O)	I: 0; O: 1	0	0
		TA0.0	1	1	0
		TA0.CCI0A	0	1	0
		CA1	x	x	1 (y = 1)
P1.2/ TA0.1/  CA2	2	P1.x (I/O)	I: 0; O: 1	0	0
		TA0.1	1	1	0
		TA0.CCI1A	0	1	0
		CA2	x	x	1 (y = 2)
P1.3/ CAOUT/ CA3	3	P1.x (I/O)	I: 0; O: 1	0	0
		CAOUT	1	1	0
		CA3	x	x	1 (y = 3)

**Port P1 pin schematic: P1.4 to P1.7, input/output with Schmitt trigger - MSP430G2x11**



**PRODUCT PREVIEW**

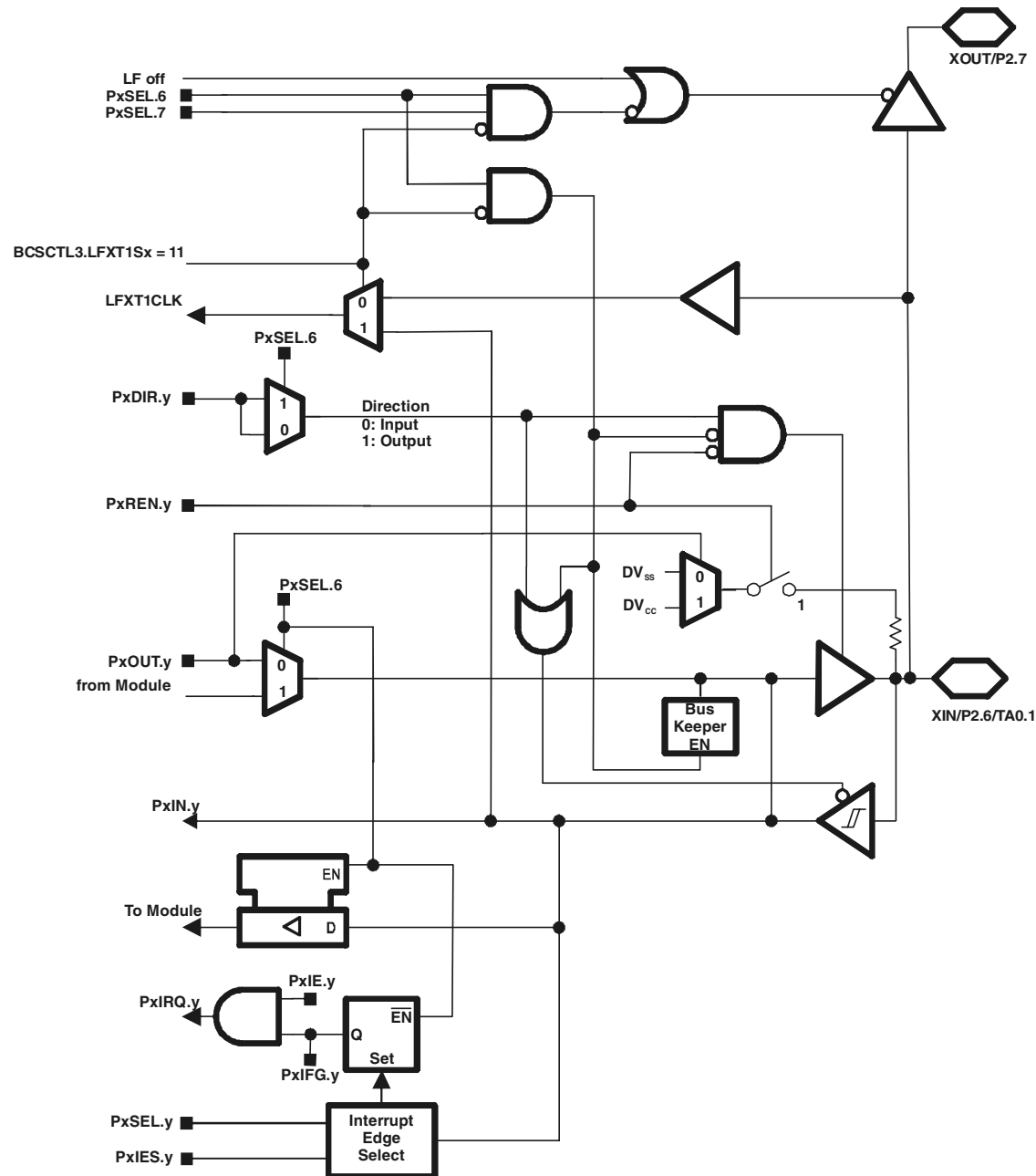
# MSP430G2x01, MSP430G2x11 MIXED SIGNAL MICROCONTROLLER

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## Port P1 (P1.4 to P1.7) pin functions - MSP430G2x11

PIN NAME (P1.X)	X	FUNCTION	CONTROL BITS / SIGNALS			
			P1DIR.x	P1SEL.x	JTAG Mode	CAPD.y
P1.4/ SMCLK/ CA4/ TCK	4	P1.x (I/O)	I: 0; O: 1	0	0	0
		SMCLK	1	1	0	0
		CA4	x	x	0	1 (y = 4)
		TCK	x	x	1	0
P1.5/ TA0.0/ CA5/ TMS	5	P1.x (I/O)	I: 0; O: 1	0	0	0
		TA0.0	1	1	0	0
		CA5	x	x	0	1 (y = 5)
		TMS	x	x	1	0
P1.6/ TA0.1/ CA6/ TDI/TCLK	6	P1.x (I/O)	I: 0; O: 1	0	0	0
		TA0.1	1	1	0	0
		CA6	x	x	0	1 (y = 6)
		TDI/TCLK	x	x	1	0
P1.7/ CAOUT/ CA7/ TDO/TDI	7	P1.x (I/O)	I: 0; O: 1	0	0	0
		CAOUT	1	1	0	0
		CA7	x	x	0	1 (y = 7)
		TDO/TDI	x	x	1	0

**Port P2 pin schematic: P2.6, input/output with Schmitt trigger - MSP430G2x10 and MSP430G2x11**



**Port P2 (P2.6) pin functions - MSP430G2x10 and MSP430G2x11**

PIN NAME (P2.X)	X	FUNCTION	CONTROL BITS / SIGNALS		
			P2DIR.x	P2SEL.6	PSEL2.7
XIN	6	XIN	0	1	1
P2.6		P2.x (I/O)	I: 0; O: 1	0	x
TA0.1		Timer0_A3.TA1	1	1	x

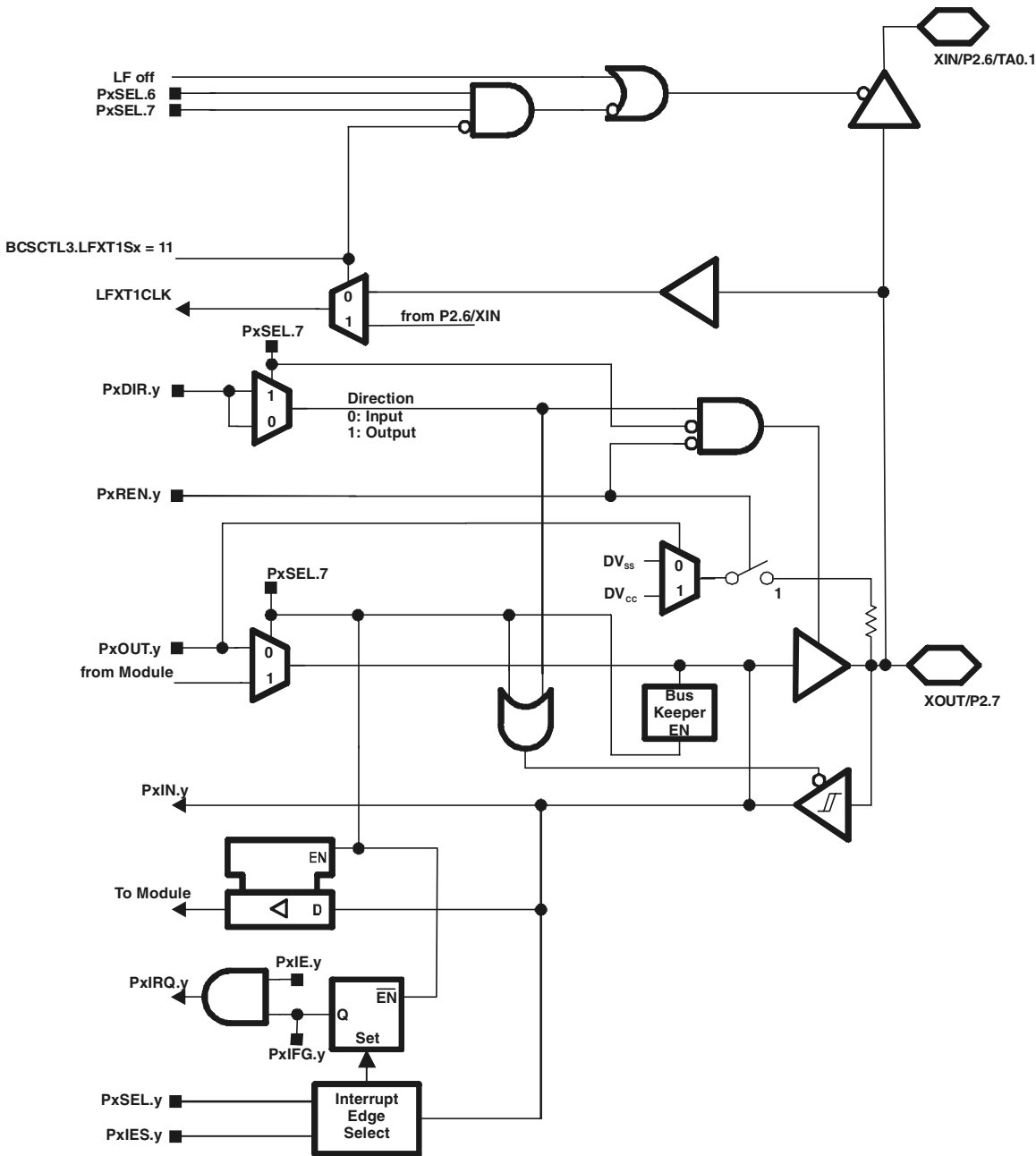
**PRODUCT PREVIEW**

# MSP430G2x01, MSP430G2x11

## MIXED SIGNAL MICROCONTROLLER

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Port P2 pin schematic: P2.7, input/output with Schmitt trigger - MSP430G2x10 and MSP430G2x11



Port P2 (P2.7) pin functions - MSP430G2x10 and MSP430G2x11

PIN NAME (P2.X)	X	FUNCTION	CONTROL BITS / SIGNALS		
			P2DIR.x	P2SEL.6 P2SEL.7	P2SEL.7
XOUT	7	XOUT	1	1	1
P2.7		P2.x (I/O)	I: 0; O: 1	0	x



**PACKAGING INFORMATION**

Orderable Device	Status <sup>(1)</sup>	Package Type	Package Drawing	Pins	Package Qty	Eco Plan <sup>(2)</sup>	Lead/Ball Finish	MSL Peak Temp <sup>(3)</sup>
MSP430G2001IN14	ACTIVE	PDIP	N	14	25	TBD	Call TI	Call TI
MSP430G2001IPW14R	PREVIEW	TSSOP	PW	14	2000	TBD	Call TI	Call TI
MSP430G2001IRSA16	ACTIVE	QFN	RSA	16	250	TBD	Call TI	Call TI
MSP430G2101IN14	ACTIVE	PDIP	N	14	25	TBD	Call TI	Call TI
MSP430G2101IPW14	ACTIVE	TSSOP	PW	14	90	TBD	Call TI	Call TI
MSP430G2101IRSA16	ACTIVE	QFN	RSA	16	250	TBD	Call TI	Call TI
MSP430G2111IN14	ACTIVE	PDIP	N	14	25	TBD	Call TI	Call TI
MSP430G2111IPW14	ACTIVE	TSSOP	PW	14	90	TBD	Call TI	Call TI
MSP430G2111IRSA16	ACTIVE	QFN	RSA	16	250	TBD	Call TI	Call TI
MSP430G2201IN14	ACTIVE	PDIP	N	14	25	TBD	Call TI	Call TI
MSP430G2201IPW14	ACTIVE	TSSOP	PW	14	90	TBD	Call TI	Call TI
MSP430G2201IRSA16	ACTIVE	QFN	RSA	16	250	TBD	Call TI	Call TI
MSP430G2211IPW14R	PREVIEW	TSSOP	PW	14	2000	TBD	Call TI	Call TI
MSP430G2211IRSA16R	PREVIEW	QFN	RSA	16	3000	TBD	Call TI	Call TI

<sup>(1)</sup> The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBsolete:** TI has discontinued the production of the device.

<sup>(2)</sup> Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

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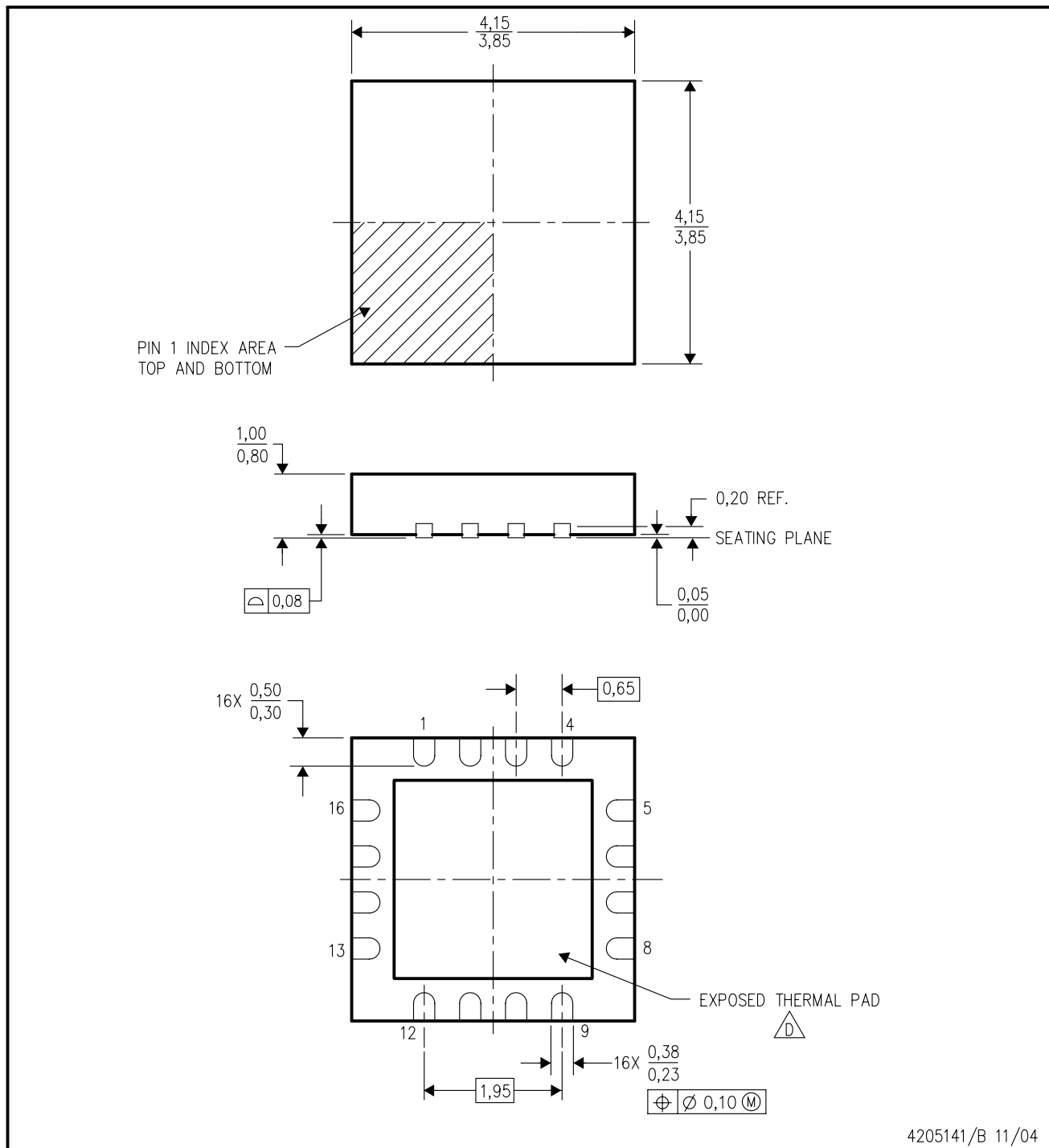
<sup>(3)</sup> MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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## RSA (S-PQFP-N16)

## PLASTIC QUAD FLATPACK



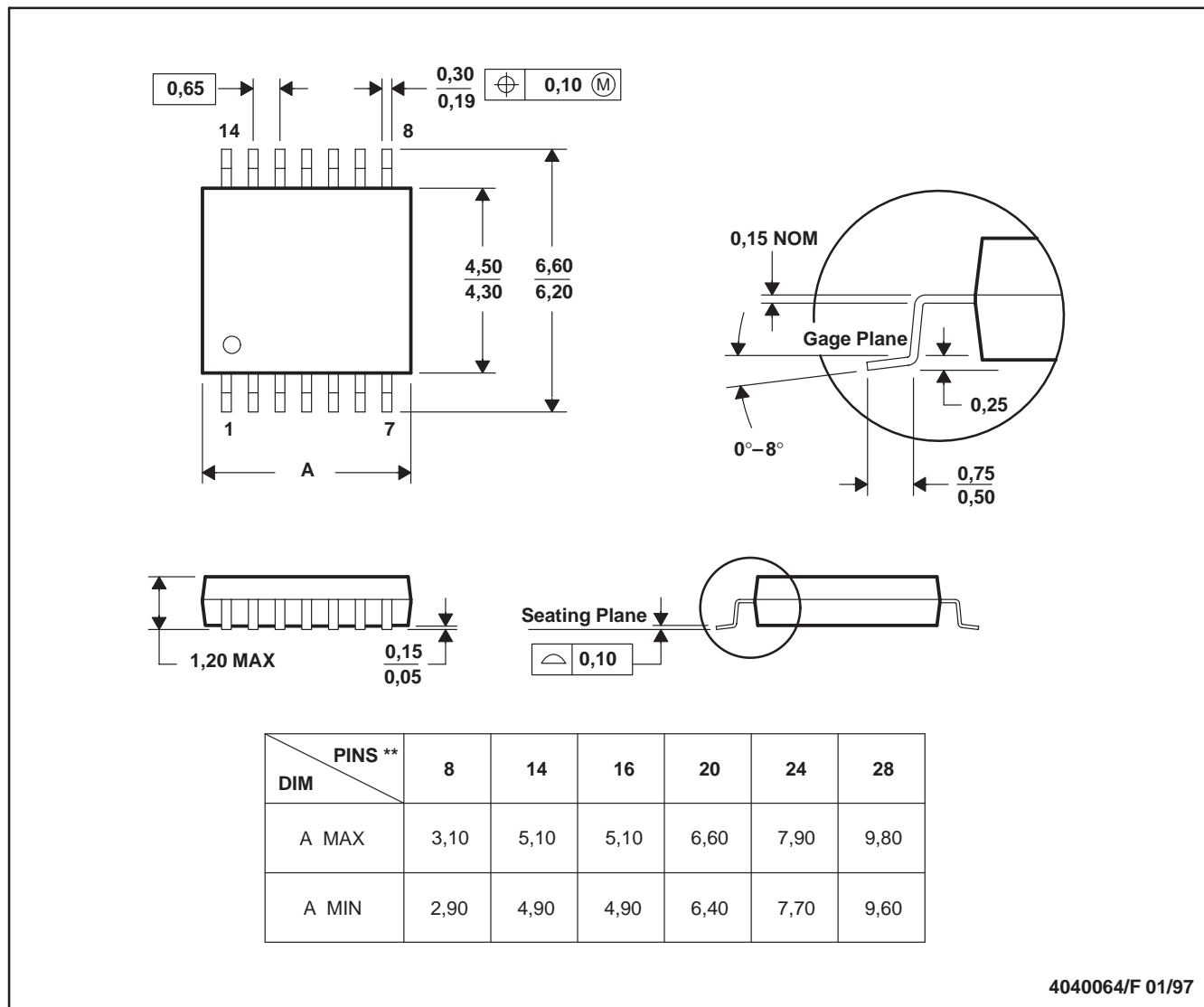
4205141/B 11/04

- NOTES:
- A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.
  - B. This drawing is subject to change without notice.
  - C. Quad Flatpack, No-leads (QFN) package configuration.
  -  The package thermal pad must be soldered to the board for thermal and mechanical performance. See the Product Data Sheet for details regarding the exposed thermal pad dimensions.
  - E. Falls within JEDEC MO-220.

## PW (R-PDSO-G\*\*)

## PLASTIC SMALL-OUTLINE PACKAGE

14 PINS SHOWN



- NOTES: A. All linear dimensions are in millimeters.  
 B. This drawing is subject to change without notice.  
 C. Body dimensions do not include mold flash or protrusion not to exceed 0,15.  
 D. Falls within JEDEC MO-153

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Data Converters	<a href="http://dataconverter.ti.com">dataconverter.ti.com</a>	Automotive	<a href="http://www.ti.com/automotive">www.ti.com/automotive</a>
DLP® Products	<a href="http://www.dlp.com">www.dlp.com</a>	Communications and Telecom	<a href="http://www.ti.com/communications">www.ti.com/communications</a>
DSP	<a href="http://dsp.ti.com">dsp.ti.com</a>	Computers and Peripherals	<a href="http://www.ti.com/computers">www.ti.com/computers</a>
Clocks and Timers	<a href="http://www.ti.com/clocks">www.ti.com/clocks</a>	Consumer Electronics	<a href="http://www.ti.com/consumer-apps">www.ti.com/consumer-apps</a>
Interface	<a href="http://interface.ti.com">interface.ti.com</a>	Energy	<a href="http://www.ti.com/energy">www.ti.com/energy</a>
Logic	<a href="http://logic.ti.com">logic.ti.com</a>	Industrial	<a href="http://www.ti.com/industrial">www.ti.com/industrial</a>
Power Mgmt	<a href="http://power.ti.com">power.ti.com</a>	Medical	<a href="http://www.ti.com/medical">www.ti.com/medical</a>
Microcontrollers	<a href="http://microcontroller.ti.com">microcontroller.ti.com</a>	Security	<a href="http://www.ti.com/security">www.ti.com/security</a>
RFID	<a href="http://www.ti-rfid.com">www.ti-rfid.com</a>	Space, Avionics & Defense	<a href="http://www.ti.com/space-avionics-defense">www.ti.com/space-avionics-defense</a>
RF/IF and ZigBee® Solutions	<a href="http://www.ti.com/lprf">www.ti.com/lprf</a>	Video and Imaging	<a href="http://www.ti.com/video">www.ti.com/video</a>
		Wireless	<a href="http://www.ti.com/wireless-apps">www.ti.com/wireless-apps</a>