
LIN SBC⁽¹⁾ including LIN Transceiver and Voltage Regulator

DATASHEET

Features

- Supply voltage up to 40V
- Operating voltage $V_S = 5V$ to 28V
- Supply current
 - Sleep mode: typically 9 μ A
 - Silent mode: typically 47 μ A
 - Very low current consumption at low supply voltages ($2V < V_S < 5.5V$): typically 130 μ A
- Linear low-drop voltage regulator, 85mA current capability
 - MLC⁽²⁾ capacitor with 0 Ω ESR
 - Normal, fail-safe, and silent mode
 - ATA663254: $V_{CC} = 5.0V \pm 2\%$
 - ATA663231: $V_{CC} = 3.3V \pm 2\%$
 - Works down to $V_S = 2.3V$
 - Sleep mode: VCC is switched off
- VCC undervoltage detection with open drain reset output (NRES, 4ms reset time)
- Voltage regulator is short-circuit and over-temperature protected
- LIN physical layer according to LIN 2.0, 2.1, 2.2, 2.2A and SAEJ2602-2
- Wake-up capability via LIN bus (100 μ s dominant)
- Wake-up source recognition
- TXD time-out timer
- Bus pin is over-temperature and short-circuit protected versus GND and battery
- Advanced EMC and ESD performance
- Fulfills the OEM “Hardware Requirements for LIN in Automotive Applications Rev.1.3”
- Interference and damage protection according to ISO7637
- Package: DFN8

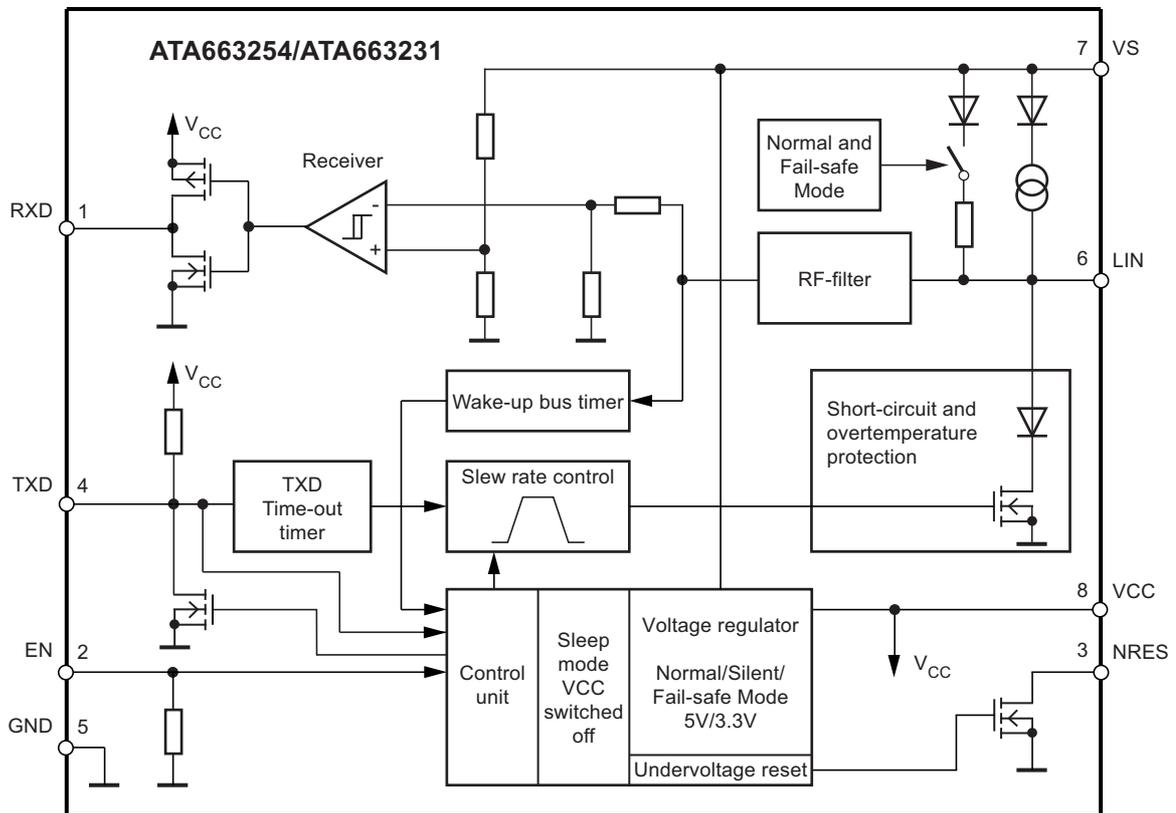
Notes: 1. LIN SBC: LIN system basis chip
2. Multi layer ceramic

1. Description

The Atmel® ATA663254/ATA663231 system basis chip is a fully integrated LIN transceiver, designed according to the LIN specification 2.0, 2.1, 2.2, 2.2A and SAEJ2602-2, with a low-drop voltage regulator 5V/3.3V/85mA. The combination of voltage regulator and bus transceiver makes it possible to develop simple but powerful slave nodes in LIN bus systems. Atmel ATA663254/ATA663231 is designed to handle the low-speed data communication in vehicles (for example, in convenience electronics). Improved slope control at the LIN driver ensures secure data communication up to 20Kbaud. The bus output is designed to withstand high voltage. Sleep mode and silent mode guarantee minimized current consumption even in the case of a floating or a shorted LIN bus.

The voltage regulator is a fully integrated low-drop voltage regulator, with 5V respectively 3.3V output voltage and 85mA current capability. It is especially designed for the automotive environment. A key feature is that the current consumption is always below 170µA (without load), even if the supply voltage is below the regulator's nominal output voltage.

Figure 1-1. Block Diagram of the Atmel ATA663254/ATA663231



2. Pin Configuration

Figure 2-1. Pinning DFN8

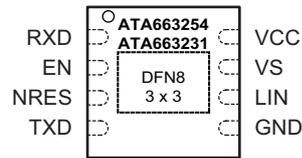


Table 2-1. Pin Description

Pin	Symbol	Function
1	RXD	Receive data output
2	EN	Enables normal mode if the input is high
3	NRES	VCC undervoltage output, open drain, low at reset
4	TXD	Transmit data input
5	GND	Ground, heat slug
6	LIN	LIN bus line input/output
7	VS	Supply voltage
8	VCC	Output voltage regulator 5V/3.3V/85mA
Backside		Heat slug, internally connected to the GND pin

3. Pin Description

3.1 Supply Pin (VS)

LIN operating voltage is $V_S = 5V$ to $28V$. Undervoltage detection is implemented to disable transmission if V_S falls below typ. $4.5V$, thereby avoiding false bus messages. After switching on V_S , the IC starts in fail-safe mode and the voltage regulator is switched on.

The supply current in sleep mode is typically $9\mu A$ and $47\mu A$ in silent mode.

3.2 Ground Pin (GND)

The IC does not affect the LIN bus in the event of GND disconnection. It is able to handle a ground shift of up to 11.5% of V_S .

3.3 Voltage Regulator Output Pin (VCC)

The internal $5V/3.3V$ voltage regulator is capable of driving loads up to $85mA$, supplying the microcontroller and other ICs on the PCB and is protected against overload by means of current limitation and overtemperature shutdown. Furthermore, the output voltage is monitored and causes a reset signal at the NRES output pin if it drops below a defined threshold

$V_{VCC_th_uv_down}$.

3.4 Undervoltage Reset Output (NRES)

If the V_{CC} voltage falls below the undervoltage detection threshold $V_{VCC_th_uv_down}$, NRES switches to low after t_{res_f} . NRES stays low even if $V_{CC} = 0V$ because NRES is internally driven from the V_S voltage. If V_S voltage ramps down, NRES stays low until $V_S < 1.5V$ and then becomes highly impedant.

The implemented undervoltage delay keeps NRES low for $t_{Reset} = 4ms$ after V_{CC} reaches its nominal value.

3.5 Bus Pin (LIN)

A low-side driver with internal current limitation and thermal shutdown as well as an internal pull-up resistor according to LIN specification 2.x is implemented. The voltage range is from $-27V$ to $+40V$. This pin exhibits no reverse current from the LIN bus to V_S , even in the event of a GND shift or V_{Bat} disconnection. The LIN receiver thresholds comply with the LIN protocol specification.

The fall time (from recessive to dominant) and the rise time (from dominant to recessive) are slope-controlled.

During a short circuit at LIN to V_{Bat} , the output limits the output current to I_{BUS_LIM} . Due to the power dissipation, the chip temperature exceeds T_{LINoff} and the LIN output is switched off. The chip cools down and after a hysteresis of T_{hys} , switches the output on again. RXD stays on high because LIN is high. The V_{CC} regulator works independently during LIN overtemperature switch-off.

During a short circuit from LIN to GND the IC can be switched into sleep or silent mode and even in this case the current consumption is lower than $100\mu A$ in sleep mode and lower than $120\mu A$ in silent mode. If the short-circuit disappears, the IC starts with a remote wake-up.

The reverse current is $< 2\mu A$ at pin LIN during loss of V_{Bat} . This is optimal behavior for bus systems where some slave nodes are supplied from battery or ignition.

3.6 Input/Output (TXD)

In normal mode the TXD pin is the microcontroller interface for controlling the state of the LIN output. TXD must be pulled to ground in order to drive the LIN bus low. If TXD is high or unconnected (internal pull-up resistor), the LIN output transistor is turned off and the bus is in the recessive state. If the TXD pin stays at GND level while switching into normal mode, it must be pulled to high level longer than 10 μ s before the LIN driver can be activated. This feature prevents the bus line from being accidentally driven to dominant state after normal mode has been activated (also in case of a short circuit at TXD to GND). During fail-safe mode, this pin is used as output and signals the fail-safe source.

The TXD input has an internal pull-up resistor to force the transceiver into recessive mode if TXD is disconnected.

An internal timer prevents the bus line from being driven permanently in the dominant state (not for the ATA666213). If TXD is forced to low longer than $t_{dom} > 20$ ms, the LIN bus driver is switched to the recessive state. Nevertheless, when switching to sleep mode, the actual level at the TXD pin is relevant.

To reactivate the LIN bus driver, switch TXD to high (> 10 μ s).

3.7 Output Pin (RXD)

In normal mode this pin reports the state of the LIN bus to the microcontroller. LIN high (recessive state) is indicated by a high level at RXD; LIN low (dominant state) is indicated by a low level at RXD.

The output is a push-pull stage switching between VCC and GND. The AC characteristics are measured by an external load capacitor of 20pF.

In silent mode the RXD output switches to high.

3.8 Enable Input Pin (EN)

The enable input pin controls the operating mode of the device. If EN is high, the circuit is in normal mode, with transmission paths from TXD to LIN and from LIN to RXD both active. The VCC voltage regulator operates with 5V/3.3V/85mA output capability.

If EN is switched to low while TXD is still high, the device is forced to silent mode. No data transmission is then possible, and current consumption is reduced to $I_{V_{Ssilent}}$ typ. 47 μ A. The VCC regulator retains its full functionality.

If EN is switched to low while TXD is low, the device is forced to sleep mode. No data transmission is possible, and the voltage regulator is switched off.

The EN pin provides a pull-down resistor to force the transceiver into recessive mode if EN is disconnected.

4. Functional Description

4.1 Physical Layer Compatibility

Because the LIN physical layer is independent of higher LIN layers (e.g., LIN protocol layer), all nodes with a LIN physical layer according to revision 2.x can be mixed with LIN physical layer nodes based on earlier versions (i.e., LIN 1.0, LIN 1.1, LIN 1.2, LIN 1.3) without any restrictions.

4.2 Operating Modes

Figure 4-1. Operating Modes

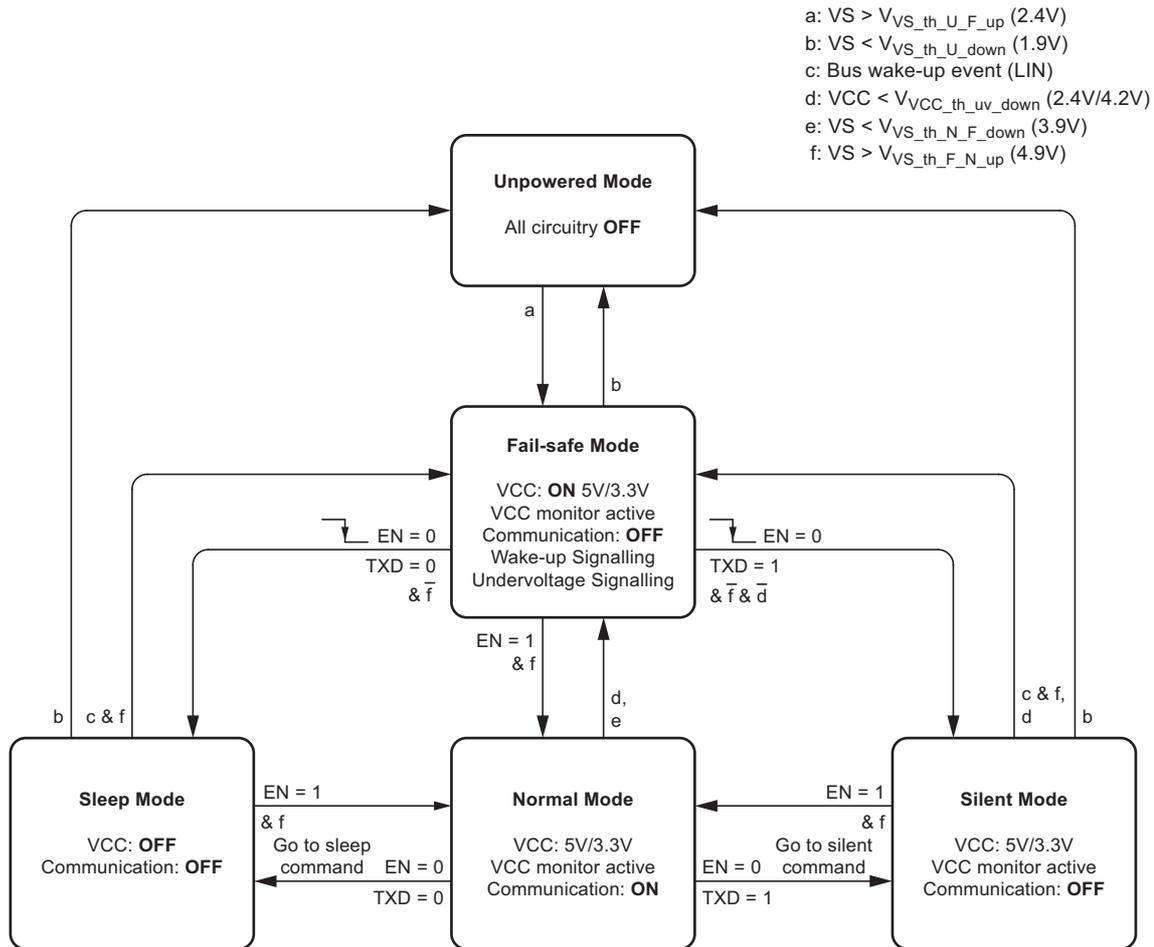


Table 4-1. Operating Modes

Operating Mode	Transceiver	V_{CC}	LIN	TXD	RXD
Fail-safe	OFF	5V/3.3V	Recessive	Signaling fail-safe sources (see Table 4-2)	
Normal	ON	5V/3.3V	TXD-dependent	Follows data transmission	
Silent (SBC only)	OFF	5V/3.3V	Recessive	High	High
Sleep/unpowered	OFF	0V	Recessive	Low	Low

4.2.1 Normal Mode

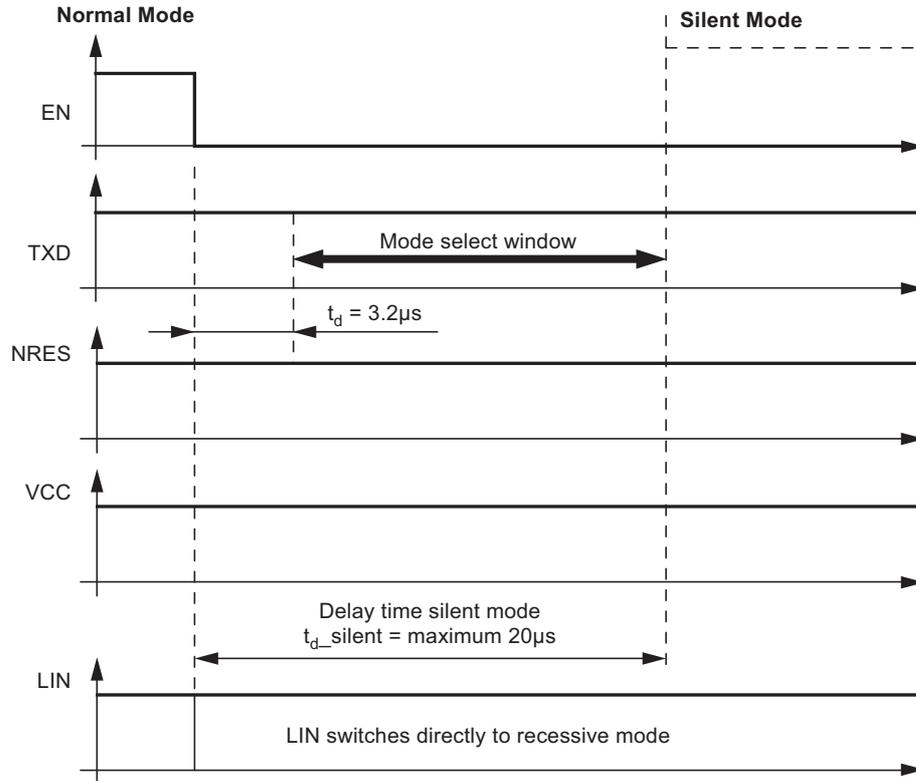
This is the normal transmitting and receiving mode of the LIN Interface, in accordance with LIN specification 2.x.

The VCC voltage regulator operates with 5V/3.3V output voltage, with a low tolerance of $\pm 2\%$ and a maximum output current of 85mA. If an undervoltage condition occurs, NRES is switched to low and the IC changes its state to fail-safe mode.

4.2.2 Silent Mode

A falling edge at EN while TXD is high switches the IC into silent mode. The TXD signal has to be logic high during the mode select window. The transmission path is disabled in silent mode. The voltage regulator is active. The overall supply current from V_{Bat} is a combination of the $I_{V_{S_{silent}}} = 47\mu A$ plus the V_{CC} regulator output current $I_{V_{CC}}$.

Figure 4-2. Switching to Silent Mode



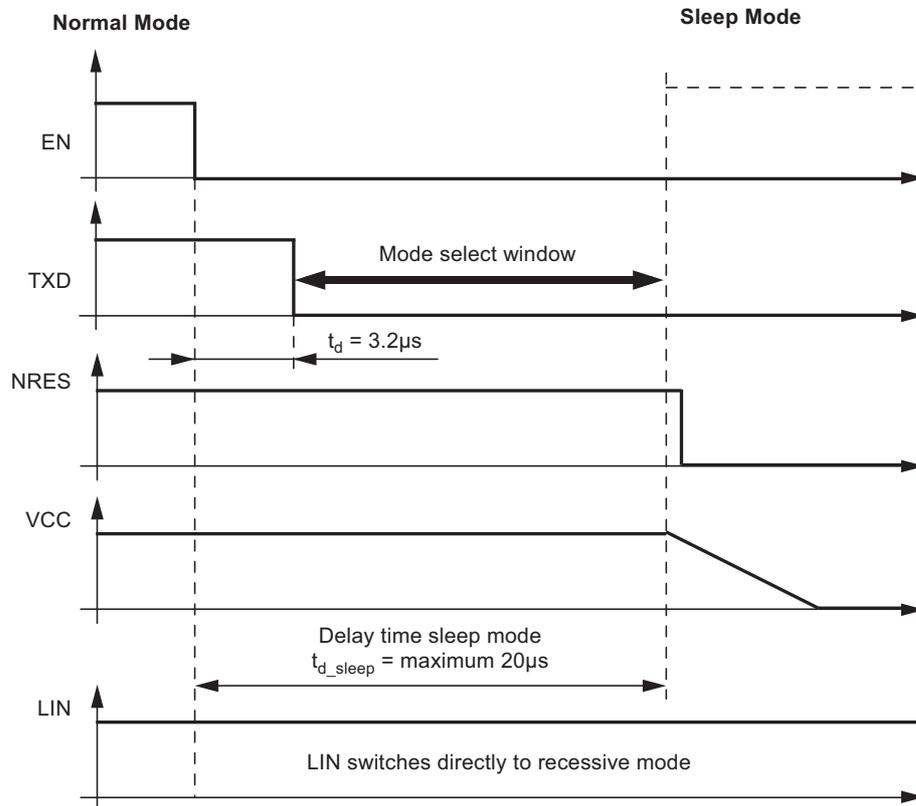
In silent mode the internal slave termination between the LIN pin and VS pin is disabled to minimize the current consumption in case the pin LIN is short-circuited to GND. Only a weak pull-up current (typically $10\mu A$) between the LIN pin and VS pin is present. Silent mode can be activated independently from the current level on pin LIN.

If an undervoltage condition occurs, NRES is switched to low and the Atmel[®] SBC changes its state to fail-safe mode.

4.2.3 Sleep Mode

A falling edge at EN while TXD is low switches the IC into sleep mode. The TXD signal has to be logic low during the mode select window (Figure 4-5).

Figure 4-3. Switching to Sleep Mode



In order to avoid any influence to the LIN pin when switching into sleep mode it is possible to switch the EN up to $3.2\mu\text{s}$ earlier to low than the TXD. The easiest and best way to do this is by having two falling edges at TXD and EN at the same time.

In sleep mode the transmission path is disabled. Supply current from V_{Bat} is typically $I_{V_{\text{Ssleep}}} = 12\mu\text{A}$. The V_{CC} regulator is switched off; NRES and RXD are low. The internal slave termination between the LIN pin and VS pin is disabled to minimize the current consumption in case the LIN pin is short-circuited to GND. Only a weak pull-up current (typically $10\mu\text{A}$) between the LIN pin and the VS pin is present. The sleep mode can be activated independently from the current level on the LIN pin. Voltage below the LIN pre-wake detection V_{LINL} at the LIN pin activates the internal LIN receiver and starts the wake-up detection timer.

If the TXD pin is short-circuited to GND, it is possible to switch to sleep mode via EN after $t > t_{\text{dom}}$.

4.2.4 Fail-Safe Mode

The device automatically switches to fail-safe mode at system power-up. The voltage regulator is switched on. The NRES output remains low for $t_{res} = 4\text{ms}$ and causes the microcontroller to be reset. LIN communication is switched off. The IC stays in this mode until EN is switched to high. The IC then changes to normal mode. A low at NRES switches the IC into fail-safe mode directly. During fail-safe mode the TXD pin is an output and, together with the RXD output pin, signals the fail-safe source.

If the device enters fail-safe mode coming from the normal mode ($EN=1$) due to an V_S undervoltage condition ($V_S < V_{VS_th_N_F_down}$), it is possible to switch into sleep or silent mode by a falling edge at the EN input. With this feature the current consumption can be further reduced.

A wake-up event from either silent or sleep mode is signalled to the microcontroller using the RXD pin and the TXD pin. A V_S undervoltage condition is also signalled at these two pins. The coding is shown in the table below.

A wake-up event switches the IC to fail-safe mode.

Table 4-2. Signaling in Fail-safe Mode

Fail-Safe Sources	TXD	RXD
LIN wake-up (LIN pin)	Low	Low
$V_{S_{th}}$ (battery) undervoltage detection ($V_S < 3.9V$)	High	Low

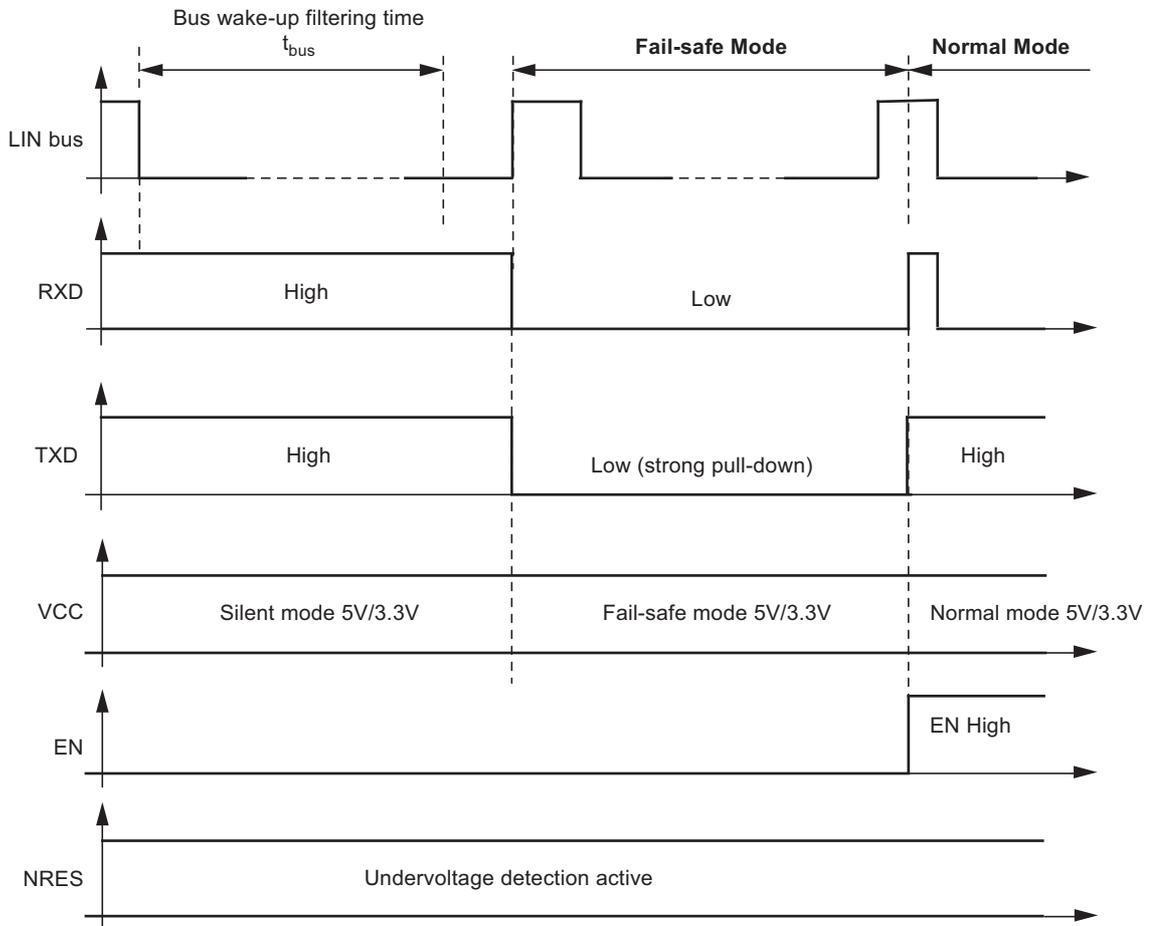
4.3 Wake-up Scenarios from Silent Mode or Sleep Mode

4.3.1 Remote Wake-up via LIN Bus

4.3.1.1 Remote Wake-up from Silent Mode

A remote wake-up from silent mode is only possible if TXD is high. A voltage less than the LIN pre-wake detection VLINL at the LIN pin activates the internal LIN receiver and starts the wake-up detection timer. A falling edge at the LIN pin followed by a dominant bus level maintained for a certain period of time ($> t_{bus}$) and the following rising edge at pin LIN (see [Figure 4-4](#)) result in a remote wake-up request. The device switches from silent mode to fail-safe mode, the VCC voltage regulator remains activated and the internal LIN slave termination resistor is switched on. The remote wake-up request is indicated by a low level at the RXD pin and TXD pin (strong pull-down at TXD). EN high can be used to switch directly to normal mode.

Figure 4-4. LIN Wake-up from Silent Mode



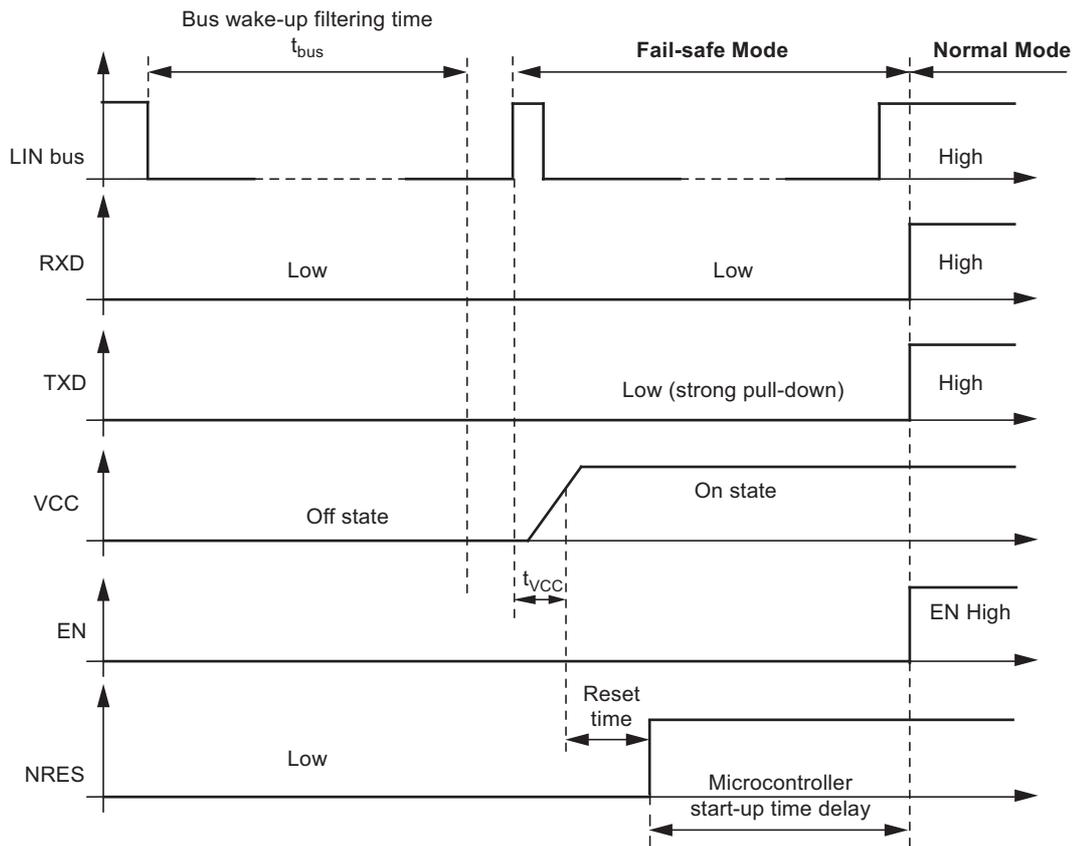
4.3.1.2 Remote Wake-up from Sleep Mode

A falling edge at the LIN pin followed by a dominant bus level maintained for a certain period of time ($> t_{bus}$) and a following rising edge at the LIN pin result in a remote wake-up request, causing the device to switch from sleep mode to fail-safe mode.

The V_{CC} regulator is activated, and the internal LIN slave termination resistor is switched on. The remote wake-up request is indicated by a low level at RXD and TXD (strong pull-down at TXD) (see Figure 4-5).

EN high can be used to switch directly from sleep/silent mode to fail-safe mode. If EN is still high after V_{CC} ramp-up and undervoltage reset time, the IC switches to normal mode.

Figure 4-5. LIN Wake-up from Sleep Mode



4.3.2 Wake-up Source Recognition

The device can distinguish between different wake-up sources. The wake-up source can be read on the TXD and RXD pin in fail-safe mode. These flags are immediately reset if the microcontroller sets the EN pin to high and the IC is in normal mode.

Table 4-3. Signaling in Fail-safe Mode

Fail-Safe Sources	TXD	RXD
LIN wake-up (LIN pin)	Low	Low
$V_{S_{th}}$ (battery) undervoltage detection ($V_S < 3.9V$)	High	Low

4.4 Behavior under Low Supply Voltage Condition

After the battery voltage has been connected to the application circuit, the voltage at the VS pin increases according to the block capacitor used in the application (see Figure 8-1 on page 22). If V_{VS} is higher than the minimum VS operation threshold $V_{VS_th_U_F_up}$, the IC mode changes from unpowered mode to fail-safe mode. As soon as V_{VS} exceeds the undervoltage threshold $V_{VS_th_F_N_up}$, the LIN transceiver can be activated.

The VCC output voltage reaches its nominal value after t_{VCC} . This parameter depends on the externally applied VCC capacitor and the load. The NRES output is low for the reset time delay t_{reset} . No mode change is possible during this time t_{reset} .

The behaviour of VCC, NRES and VS is shown in the following diagrams (ramp-up and ramp-down):

Figure 4-6. VCC and NRES versus VS (Ramp-up) for 3.3V

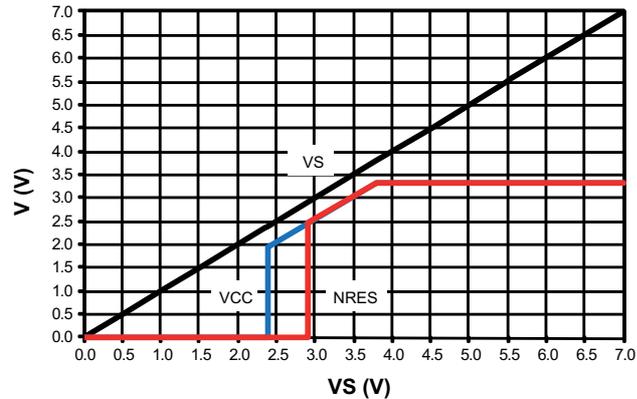


Figure 4-7. VCC and NRES versus VS (Ramp-down) for 3.3V

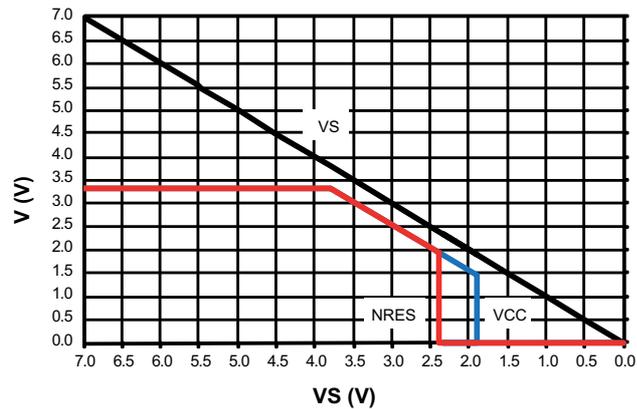


Figure 4-8. VCC and NRES versus VS (Ramp-up) for 5V

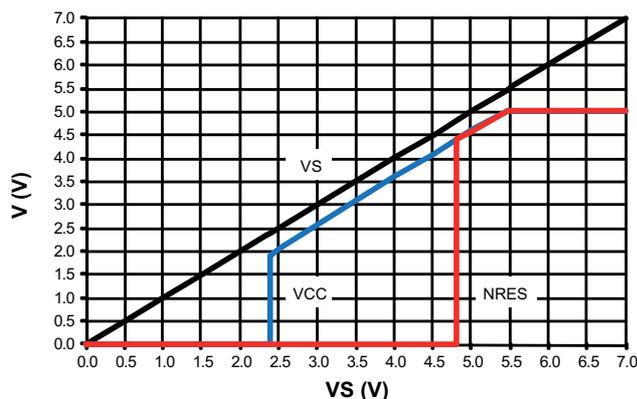
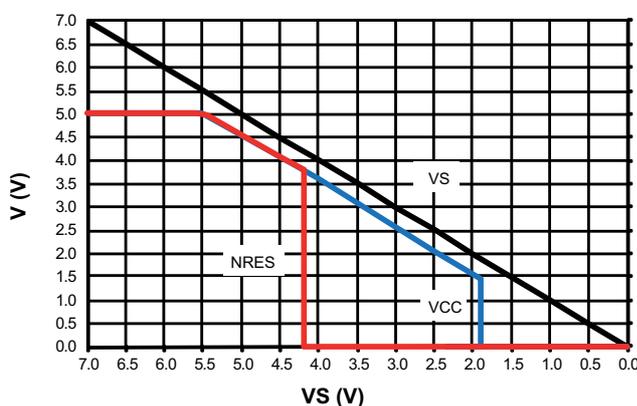


Figure 4-9. VCC and NRES versus VS (Ramp-down) for 5V



Please note that the upper graphs are only valid if the VS ramp-up and ramp-down times are much slower than the VCC ramp-up time t_{VCC} and the NRES delay time t_{reset} .

If during **sleep mode** the voltage level of V_{VS} drops below the undervoltage detection threshold $V_{VS_th_N_F_down}$ (typ. 4.3V), the operation mode is not changed and no wake-up is possible. Only if the supply voltage on pin VS drops below the VS operation threshold $V_{VS_th_U_down}$ (typ. 2.05V), does the IC switch to unpowered mode.

If during **silent mode** the VCC voltage drops below the VCC undervoltage threshold $V_{VCC_th_uv_down}$ the IC switches into fail-safe mode. If the supply voltage on pin VS drops below the VS operation threshold $V_{VS_th_U_down}$ (typ. 2.05V), does the IC switch to unpowered mode.

If during **normal mode** the voltage level on the VS pin drops below the VS undervoltage detection threshold $V_{VS_th_N_F_down}$ (typ. 4.3V), the IC switches to fail-safe mode. This means the LIN transceiver is disabled in order to avoid malfunctions or false bus messages. The voltage regulator remains active.

ATA663231: In this undervoltage situation it is possible to switch the device into sleep mode or silent mode by a falling edge at the EN input. For this feature, switching into these two current saving modes is always guaranteed, allowing current consumption to be reduced even further.

When the VCC voltage drops below the VCC undervoltage threshold $V_{VCC_th_uv_down}$ (typ. 2.6V) the IC switches into fail-safe mode.

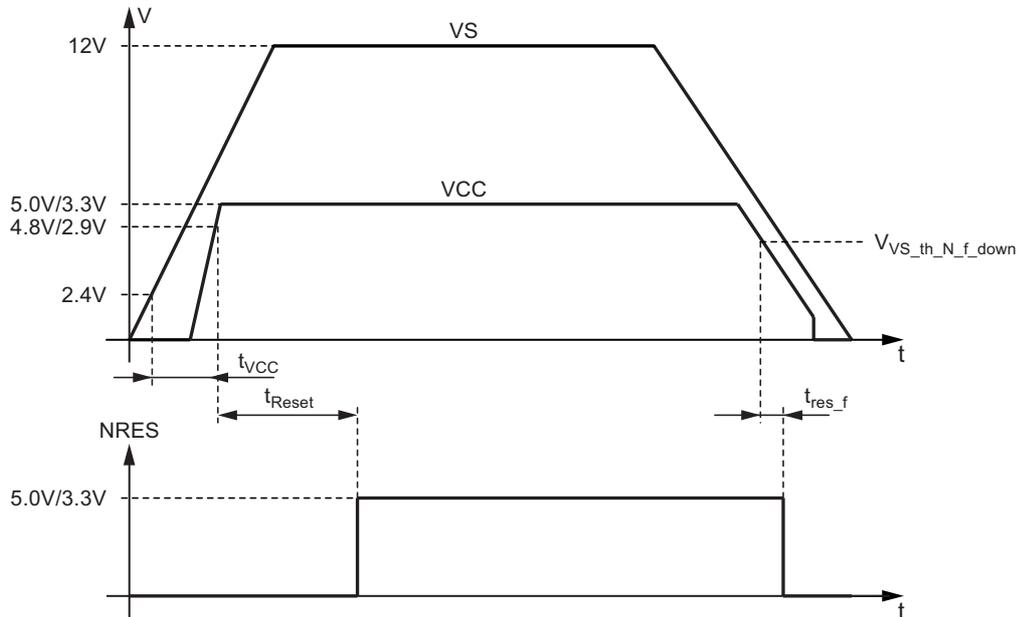
ATA663254: Because of the VCC undervoltage condition in this situation, the IC is in fail-safe mode and can be switched into sleep mode only.

Only when the supply voltage V_{VS} drops below the operation threshold $V_{VS_th_U_down}$ (typ. 2.05V) does the IC switch into unpowered mode.

The current consumption of the SBC in silent mode or in fail-safe mode is always below 170 μ A, even when the supply voltage VS is lower than the regulator's nominal output voltage VCC.

4.5 Voltage Regulator

Figure 4-10. Voltage Regulator: Supply Voltage Ramp-up and Ramp-down



The voltage regulator needs an external capacitor for compensation and to smooth the disturbances from the microcontroller. It is recommended to use a MLC capacitor with a minimum capacitance of 1.8 μ F together with a 100nF ceramic capacitor. Depending on the application, the values of these capacitors can be modified by the customer.

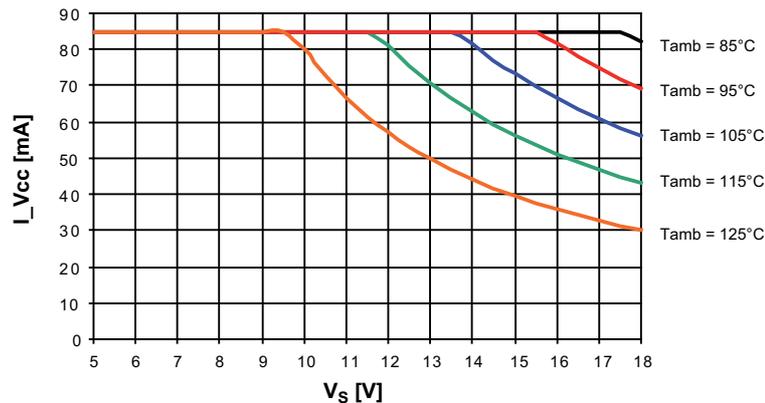
During a short circuit at VCC, the output limits the output current to I_{VCClim} . Because of undervoltage, NRES switches to low and sends a reset to the microcontroller. If the chip temperature exceeds the value T_{VCCoff} , the VCC output switches off. The chip cools down and, after a hysteresis of T_{hys} , switches the output on again.

When the Atmel ATA663254/ATA663231 is being soldered onto the PCB it is mandatory to connect the heat slug with a wide GND plate on the printed board to get a good heat sink.

The main power dissipation of the IC is created from the VCC output current I_{VCC} , which is needed for the application.

“Power Dissipation: Safe Operating Area: Regulator’s Output Current I_{VCC} versus Supply Voltage V_S ” is shown in [Figure 4-11](#).

Figure 4-11. Power Dissipation: Safe Operating Area: Regulator’s Output Current I_{VCC} versus Supply Voltage V_S at Different Ambient Temperatures ($R_{thja} = 50K/W$ assumed)



5. Absolute Maximum Ratings

Stresses beyond those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Parameters	Symbol	Min.	Typ.	Max.	Unit
Supply voltage V_S	V_S	-0.3		+40	V
Pulse time $\leq 500\text{ms}$ $T_a = 25^\circ\text{C}$ Output current $I_{VCC} \leq 85\text{mA}$	V_S			+43.5	V
Pulse time $\leq 2\text{min}$ $T_a = 25^\circ\text{C}$ Output current $I_{VCC} \leq 85\text{mA}$	V_S			28	V
Logic pins voltage levels (RxD, TxD, EN, NRES)		-0.3		+5.5	V
Logic pins output DC currents	I_{Logic}	-5		+5	mA
LIN					
- DC voltage		-27		+40	V
- Pulse time $< 500\text{ms}$				+43.5	V
V_{CC}					
- DC voltage	V_{VCC}	-0.3		+5.5	V
- DC input current	I_{VCC}			+200	mA
ESD according to IBEE LIN EMC Test specification 1.0 following IEC 61000-4-2 - Pin VS, LIN to GND (with ext. circuitry acc. applications diagram)			± 6		kV
ESD HBM following STM5.1 with $1.5\text{k}\Omega/100\text{pF}$ - Pin VS, LIN to GND			± 6		kV
HBM ESD ANSI/ESD-STM5.1 JESD22-A114 AEC-Q100 (002)			± 3		kV
CDM ESD STM 5.3.1			± 750		V
Machine Model ESD AEC-Q100-RevF(003)			± 200		V
Junction temperature	T_j	-40		+150	$^\circ\text{C}$
Storage temperature	T_s	-55		+150	$^\circ\text{C}$

6. Thermal Characteristics

Parameters	Symbol	Min.	Typ.	Max.	Unit
Thermal resistance junction to heat slug	R_{thjC}		10		K/W
Thermal resistance junction to ambient, where heat slug is soldered to PCB according to JEDEC	R_{thja}		50		K/W
Thermal shutdown of V_{CC} regulator	T_{VCCoff}	150	165	180	°C
Thermal shutdown of LIN output	T_{LINoff}	150	165	180	°C
Thermal shutdown hysteresis	T_{hys}		10		°C

7. Electrical Characteristics

$5V < V_S < 28V$, $-40^{\circ}C < T_j < 150^{\circ}C$; unless otherwise specified all values refer to GND pins.

No.	Parameters	Test Conditions	Pin	Symbol	Min.	Typ.	Max.	Unit	Type*
1	VS pin								
1.1	Nominal DC voltage range		VS	V_S	5	13.5	28	V	A
1.2	Supply current in sleep mode	Sleep mode $V_{LIN} > V_S - 0.5V$ $V_S < 14V$, $T = 27^{\circ}C$	VS	$I_{VSsleep}$	6	9	12	μA	B
		Sleep mode $V_{LIN} > V_S - 0.5V$ $V_S < 14V$	VS	$I_{VSsleep}$	3	10	15	μA	A
		Sleep mode, $V_{LIN} = 0V$ bus shorted to GND $V_S < 14V$	VS	$I_{VSsleep_short}$	20	50	100	μA	A
1.3	Supply current in silent mode	Bus recessive $5.5V < V_S < 14V$ without load at VCC $T = 27^{\circ}C$	VS	$I_{VSSilent}$	30	47	58	μA	B
		Bus recessive $5.5V < V_S < 14V$ without load at VCC	VS	$I_{VSSilent}$	30	50	64	μA	A
		Bus recessive $2.0V < V_S < 5.5V$ without load at VCC	VS	$I_{VSSilent}$	50	130	170	μA	A
		Silent mode $5.5V < V_S < 14V$ bus shorted to GND without load at VCC	VS	$I_{VSSilent_short}$	50	80	120	μA	A
1.4	Supply current in normal mode	Bus recessive $V_S < 14V$ without load at VCC	VS	I_{VSrec}	150	230	290	μA	A
1.5	Supply current in normal mode	Bus dominant (internal LIN pull-up resistor active) $V_S < 14V$ without load at VCC	VS	I_{VSdom}	200	700	950	μA	A

*) Type means: A = 100% tested, B = 100% correlation tested, C = Characterized on samples, D = Design parameter

7. Electrical Characteristics (Continued)

5V < V_S < 28V, -40°C < T_j < 150°C; unless otherwise specified all values refer to GND pins.

No.	Parameters	Test Conditions	Pin	Symbol	Min.	Typ.	Max.	Unit	Type*
1.6	Supply current in fail-safe mode	Bus recessive 5.5V < V _S < 14V without load at VCC	VS	I _{VSfail}	40	55	80	μA	A
		Bus recessive 2.0V < V _S < 5.5V without load at VCC	VS	I _{VSfail}	50	130	170	μA	A
1.7	VS undervoltage threshold (switching from normal to fail-safe mode)	Decreasing supply voltage	VS	V _{VS_th_N_F_down}	3.9	4.3	4.7	V	A
		Increasing supply voltage	VS	V _{VS_th_F_N_up}	4.1	4.6	4.9	V	A
1.8	VS undervoltage hysteresis		VS	V _{VS_hys_F_N}	0.1	0.25	0.4	V	A
1.9	VS operation threshold (switching to unpowered mode)	Switch to unpowered mode	VS	V _{VS_th_U_down}	1.9	2.05	2.3	V	A
		Switch from unpowered to fail-safe mode	VS	V _{VS_th_U_F_up}	2.0	2.25	2.4	V	A
1.10	VS undervoltage hysteresis		VS	V _{VS_hys_U}	0.1	0.2	0.3	V	A
2	RXD output pin (push-pull stage)								
2.1	Low-level output sink capability	Normal mode, V _{LIN} = 0V, I _{RXD} = 2mA	RXD	V _{RXDL}		0.2	0.4	V	A
2.2	High-level output source capability	Normal mode V _{LIN} = V _S , I _{RXD} = -2mA	RXD	V _{RXDH}	V _{CC} - 0.4V	V _{CC} - 0.2V		V	A
3	TXD input/output pin								
3.1	Low-level voltage input		TXD	V _{TXDL}	-0.3		+0.8	V	A
3.2	High-level voltage input		TXD	V _{TXDH}	2		V _{CC} + 0.3V	V	A
3.3	Pull-up resistor	V _{TXD} = 0V	TXD	R _{TXD}	40	70	100	kΩ	A
3.4	High-level leakage current	V _{TXD} = V _{CC}	TXD	I _{TXD}	-3		+3	μA	A
3.7	Low-level output sink current at LIN wake-up request	Fail-safe Mode V _{LIN} = V _S V _{TXD} = 0.4V	TXD	I _{TXD}	2	2.5	8	mA	A
4	EN input pin								
4.1	Low-level voltage input		EN	V _{ENL}	-0.3		+0.8	V	A
4.2	High-level voltage input		EN	V _{ENH}	2		V _{CC} + 0.3V	V	A
4.3	Pull-down resistor	V _{EN} = VCC	EN	R _{EN}	50	125	200	kΩ	A
4.4	Low-level input current	V _{EN} = 0V	EN	I _{EN}	-3		+3	μA	A
5	NRES open drain output pin								
5.1	Low-level output voltage	V _S ≥ 5.5V I _{NRES} = 2mA	NRES	V _{NRESL}		0.2	0.4	V	A
5.2	Undervoltage reset time	V _{VS} ≥ 5.5V C _{NRES} = 20pF	NRES	t _{Reset}	2	4	6	ms	A
5.3	Reset debounce time for falling edge	V _{VS} ≥ 5.5V C _{NRES} = 20pF	NRES	t _{res_f}	0.5		10	μs	A
5.4	Switch off leakage current	V _{NRES} = 5.5V	NRES	I _{NRES_L}	-3		+3	μA	A

*) Type means: A = 100% tested, B = 100% correlation tested, C = Characterized on samples, D = Design parameter

7. Electrical Characteristics (Continued)

5V < V_S < 28V, -40°C < T_j < 150°C; unless otherwise specified all values refer to GND pins.

No.	Parameters	Test Conditions	Pin	Symbol	Min.	Typ.	Max.	Unit	Type*
8 VCC voltage regulator ATA663231									
8.1	Output voltage VCC	4V < V _S < 18V (0mA to 50mA)	VCC	VCC _{nor}	3.234		3.366	V	A
		4.5V < V _S < 18V (0mA to 85mA)	VCC	VCC _{nor}	3.234		3.366	V	C
8.2	Output voltage V _{CC} at low V _S	3V < V _S < 4V	VCC	VCC _{low}	V _{VS} - V _D		3.366	V	A
8.3	Regulator drop voltage	V _S > 3V, I _{VCC} = -15mA	VCC	V _{D1}		100	150	mV	A
8.4	Regulator drop voltage	V _S > 3V, I _{VCC} = -50mA	VCC	V _{D2}		300	500	mV	A
8.5	Line regulation maximum	4V < V _S < 18V	VCC	VCC _{line}		0.1	0.2	%	A
8.6	Load regulation maximum	5mA < I _{VCC} < 50mA	VCC	VCC _{load}		0.1	0.5	%	A
8.7	Output current limitation	V _S > 4V	VCC	I _{VCClim}		-180	-120	mA	A
8.8	Load capacity	MLC capacitor	VCC	C _{load}	1.8	2.2		μF	D
8.9	VCC undervoltage threshold (NRES ON)	Referred to VCC V _S > 4V	VCC	V _{VCC_th_uv_down}	2.3	2.5	2.8	V	A
	VCC undervoltage threshold (NRES OFF)	Referred to VCC V _S > 4V	VCC	V _{VCC_th_uv_up}	2.5	2.6	2.9	V	A
8.10	Hysteresis of VCC undervoltage threshold	Referred to VCC V _S > 4V	VCC	V _{VCC_hys_uv}	100	200	300	mV	A
8.11	Ramp-up time V _S > 4V to VCC = 3.3V	C _{VCC} = 2.2μF I _{load} = -5mA at VCC	VCC	t _{VCC}		1	1.5	ms	A
9 VCC voltage regulator ATA663254									
9.1	Output voltage VCC	5.5V < V _S < 18V (0mA to 50mA)	VCC	VCC _{nor}	4.9		5.1	V	A
		6V < V _S < 18V (0mA to 85mA)	VCC	VCC _{nor}	4.9		5.1	V	C
9.2	Output voltage V _{CC} at low V _S	4V < V _S < 5.5V	VCC	VCC _{low}	V _{VS} - V _D		5.1	V	A
9.3	Regulator drop voltage	V _S > 4V, I _{VCC} = -20mA	VCC	V _{D1}		100	200	mV	A
9.4	Regulator drop voltage	V _S > 4V, I _{VCC} = -50mA	VCC	V _{D2}		300	500	mV	A
9.5	Regulator drop voltage	V _S > 3.3V, I _{VCC} = -15mA	VCC	V _{D3}			150	mV	A
9.6	Line regulation maximum	5.5V < V _S < 18V	VCC	VCC _{line}		0.1	0.2	%	A
9.7	Load regulation maximum	5mA < I _{VCC} < 50mA	VCC	VCC _{load}		0.1	0.5	%	A
9.8	Output current limitation	V _S > 5.5V	VCC	I _{VCClim}		-180	-120	mA	A
9.9	Load capacity	MLC (Multi layer ceramic capacitor)	VCC	C _{load}	1.8	2.2		μF	D
9.10	VCC undervoltage threshold (NRES ON)	Referred to VCC V _S > 4V	VCC	V _{VCC_th_uv_down}	4.2	4.4	4.6	V	A
	VCC undervoltage threshold (NRES OFF)	Referred to VCC V _S > 4V	VCC	V _{VCC_hys_uv}	4.3	4.6	4.8	V	A
9.11	Hysteresis of undervoltage threshold	Referred to VCC V _S > 5.5V	VCC	V _{VCC_hys_uv}	100	200	300	mV	A
9.12	Ramp-up time V _S > 5.5V to VCC > 4.8V	C _{VCC} = 2.2μF I _{load} = -5mA at VCC	VCC	t _{VCC}		1	1.5	ms	A

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7. Electrical Characteristics (Continued)

5V < V_S < 28V, -40°C < T_J < 150°C; unless otherwise specified all values refer to GND pins.

No.	Parameters	Test Conditions	Pin	Symbol	Min.	Typ.	Max.	Unit	Type*
10	LIN bus driver: bus load conditions: Load 1 (small): 1nF, 1kΩ; Load 2 (large): 10nF, 500Ω; C _{RXD} = 20pF, Load 3 (medium): 6.8nF, 660Ω characterized on samples 12.7 and 12.8 specifies the timing parameters for proper operation at 20kb/s and 12.9 and 12.10 at 10.4kb/s								
10.1	Driver recessive output voltage	Load1/Load2	LIN	V _{BUSrec}	0.9 × V _S		V _S	V	A
10.2	Driver dominant voltage	V _{VS} = 7V R _{load} = 500Ω	LIN	V _{LoSUP}			1.2	V	A
10.3	Driver dominant voltage	V _{VS} = 18V R _{load} = 500Ω	LIN	V _{HiSUP}			2	V	A
10.4	Driver dominant voltage	V _{VS} = 7V R _{load} = 1000Ω	LIN	V _{LoSUP_1k}	0.6			V	A
10.5	Driver dominant voltage	V _{VS} = 18V R _{load} = 1000Ω	LIN	V _{HiSUP_1k}	0.8			V	A
10.6	Pull-up resistor to V _S	The serial diode is mandatory	LIN	R _{LIN}	20	30	47	kΩ	A
10.7	Voltage drop at the serial diodes	In pull-up path with R _{slave} I _{SerDiode} = 10mA	LIN	V _{SerDiode}	0.4		1.0	V	D
10.8	LIN current limitation V _{BUS} = V _{Bat_max}		LIN	I _{BUS_LIM}	40	120	200	mA	A
10.9	Input leakage current at the receiver including pull-up resistor as specified	Input leakage current driver off V _{BUS} = 0V V _{Bat} = 12V	LIN	I _{BUS_PAS_dom}	-1	-0.35		mA	A
10.10	Leakage current LIN recessive	Driver off 8V < V _{Bat} < 18V 8V < V _{BUS} < 18V V _{BUS} ≥ V _{Bat}	LIN	I _{BUS_PAS_rec}		10	20	μA	A
10.11	Leakage current when control unit disconnected from ground. Loss of local ground must not affect communication in the residual network	GND _{Device} = V _S V _{Bat} = 12V 0V < V _{BUS} < 18V	LIN	I _{BUS_NO_gnd}	-10	+0.5	+10	μA	A
10.12	Leakage current at disconnected battery. Node has to sustain the current that can flow under this condition. Bus must remain operational under this condition.	V _{Bat} disconnected V _{SUP_Device} = GND 0V < V _{BUS} < 18V	LIN	I _{BUS_NO_bat}		0.1	2	μA	A
10.13	Capacitance on pin LIN to GND		LIN	C _{LIN}			20	pF	D

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7. Electrical Characteristics (Continued)

5V < V_S < 28V, -40°C < T_j < 150°C; unless otherwise specified all values refer to GND pins.

No.	Parameters	Test Conditions	Pin	Symbol	Min.	Typ.	Max.	Unit	Type*
11 LIN bus receiver									
11.1	Center of receiver threshold	$V_{BUS_CNT} = (V_{th_dom} + V_{th_rec})/2$	LIN	V _{BUS_CNT}	$0.475 \times V_S$	$0.5 \times V_S$	$0.525 \times V_S$	V	A
11.2	Receiver dominant state	V _{EN} = 5V/3.3V	LIN	V _{BUSdom}	-27		$0.4 \times V_S$	V	A
11.3	Receiver recessive state	V _{EN} = 5V/3.3V	LIN	V _{BUSrec}	$0.6 \times V_S$		40	V	A
11.4	Receiver input hysteresis	V _{hys} = V _{th_rec} - V _{th_dom}	LIN	V _{BUShys}	$0.028 \times V_S$	$0.1 \times V_S$	$0.175 \times V_S$	V	A
11.5	Pre-wake detection LIN high-level input voltage		LIN	V _{LINH}	V _S - 2V		V _S + 0.3V	V	A
11.6	Pre-wake detection LIN low-level input voltage	Activates the LIN receiver	LIN	V _{LINL}	-27		V _S - 3.3V	V	A
12 Internal timers									
12.1	Dominant time for wake-up via LIN bus	V _{LIN} = 0V	LIN	t _{bus}	50	100	150	μs	A
12.2	Time delay for mode change from fail-safe into normal mode via EN pin	V _{EN} = 5V/3.3V	EN	t _{norm}	5	15	20	μs	A
12.3	Time delay for mode change from normal mode to sleep mode via EN pin	V _{EN} = 0V	EN	t _{sleep}	5	15	20	μs	A
12.5	TXD dominant time-out time	V _{TXD} = 0V	TXD	t _{dom}	20	40	60	ms	A
12.6	Time delay for mode change from silent mode into normal mode via EN pin	V _{EN} = 5V/3.3V	EN	t _{s_n}	5	15	40	μs	A
12.7	Duty cycle 1	TH _{Rec(max)} = 0.744 × V _S TH _{Dom(max)} = 0.581 × V _S V _S = 7.0V to 18V t _{Bit} = 50μs D1 = t _{bus_rec(min)} / (2 × t _{Bit})	LIN	D1	0.396				A
12.8	Duty cycle 2	TH _{Rec(min)} = 0.422 × V _S TH _{Dom(min)} = 0.284 × V _S V _S = 7.6V to 18V t _{Bit} = 50μs D2 = t _{bus_rec(max)} / (2 × t _{Bit})	LIN	D2			0.581		A
12.9	Duty cycle 3	TH _{Rec(max)} = 0.778 × V _S TH _{Dom(max)} = 0.616 × V _S V _S = 7.0V to 18V t _{Bit} = 96μs D3 = t _{bus_rec(min)} / (2 × t _{Bit})	LIN	D3	0.417				A
12.10	Duty cycle 4	TH _{Rec(min)} = 0.389 × V _S TH _{Dom(min)} = 0.251 × V _S V _S = 7.6V to 18V t _{Bit} = 96μs D4 = t _{bus_rec(max)} / (2 × t _{Bit})	LIN	D4			0.590		A
12.11	Slope time falling and rising edge at LIN	V _S = 7.0V to 18V	LIN	t _{SLOPE_fall} t _{SLOPE_rise}	3.5		22.5	μs	A

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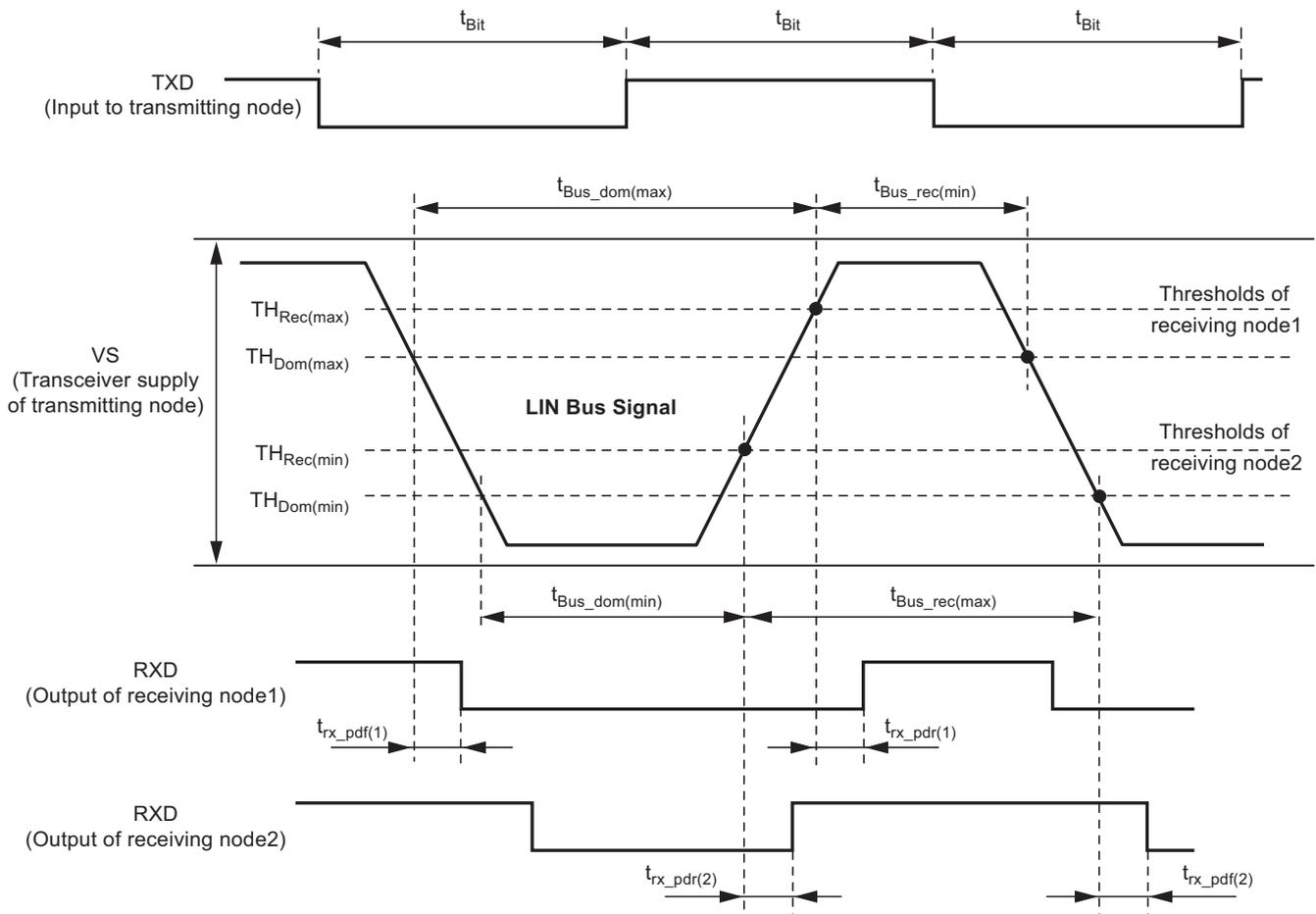
7. Electrical Characteristics (Continued)

$5V < V_S < 28V$, $-40^{\circ}C < T_j < 150^{\circ}C$; unless otherwise specified all values refer to GND pins.

No.	Parameters	Test Conditions	Pin	Symbol	Min.	Typ.	Max.	Unit	Type*
13	Receiver electrical AC parameters of the LIN physical layer LIN receiver, RXD load conditions: $C_{RXD} = 20pF$								
13.1	Propagation delay of receiver	$V_S = 7.0V$ to $18V$ $t_{rx_pd} = \max(t_{rx_pdr}, t_{rx_pdf})$	RXD	t_{rx_pd}			6	μs	A
13.2	Symmetry of receiver propagation delay rising edge minus falling edge	$V_S = 7.0V$ to $18V$ $t_{rx_sym} = t_{rx_pdr} - t_{rx_pdf}$	RXD	t_{rx_sym}	-2		+2	μs	A

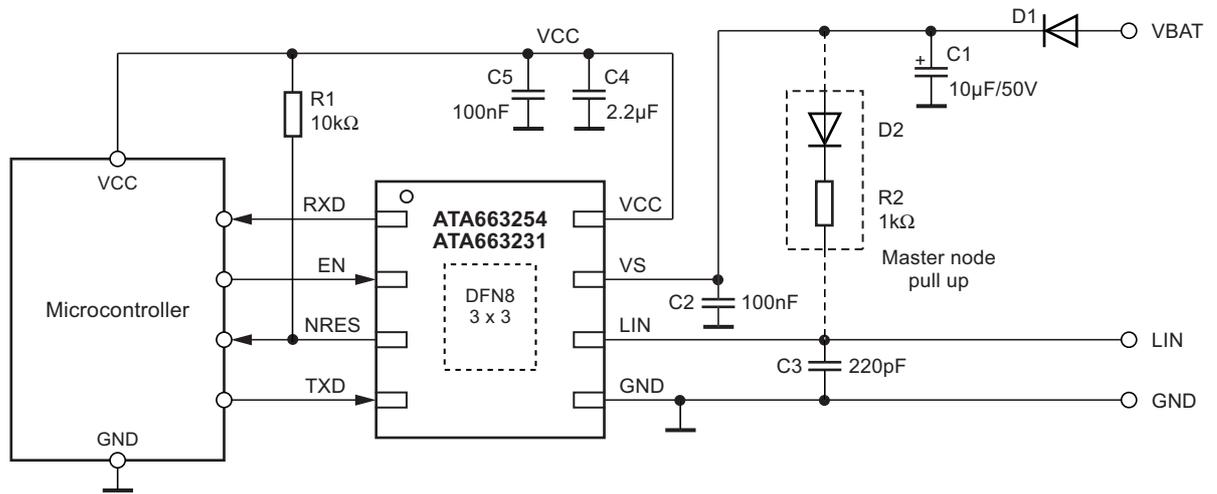
*) Type means: A = 100% tested, B = 100% correlation tested, C = Characterized on samples, D = Design parameter

Figure 7-1. Definition of Bus Timing Characteristics



8. Application Circuits

Figure 8-1. Typical Application Circuit

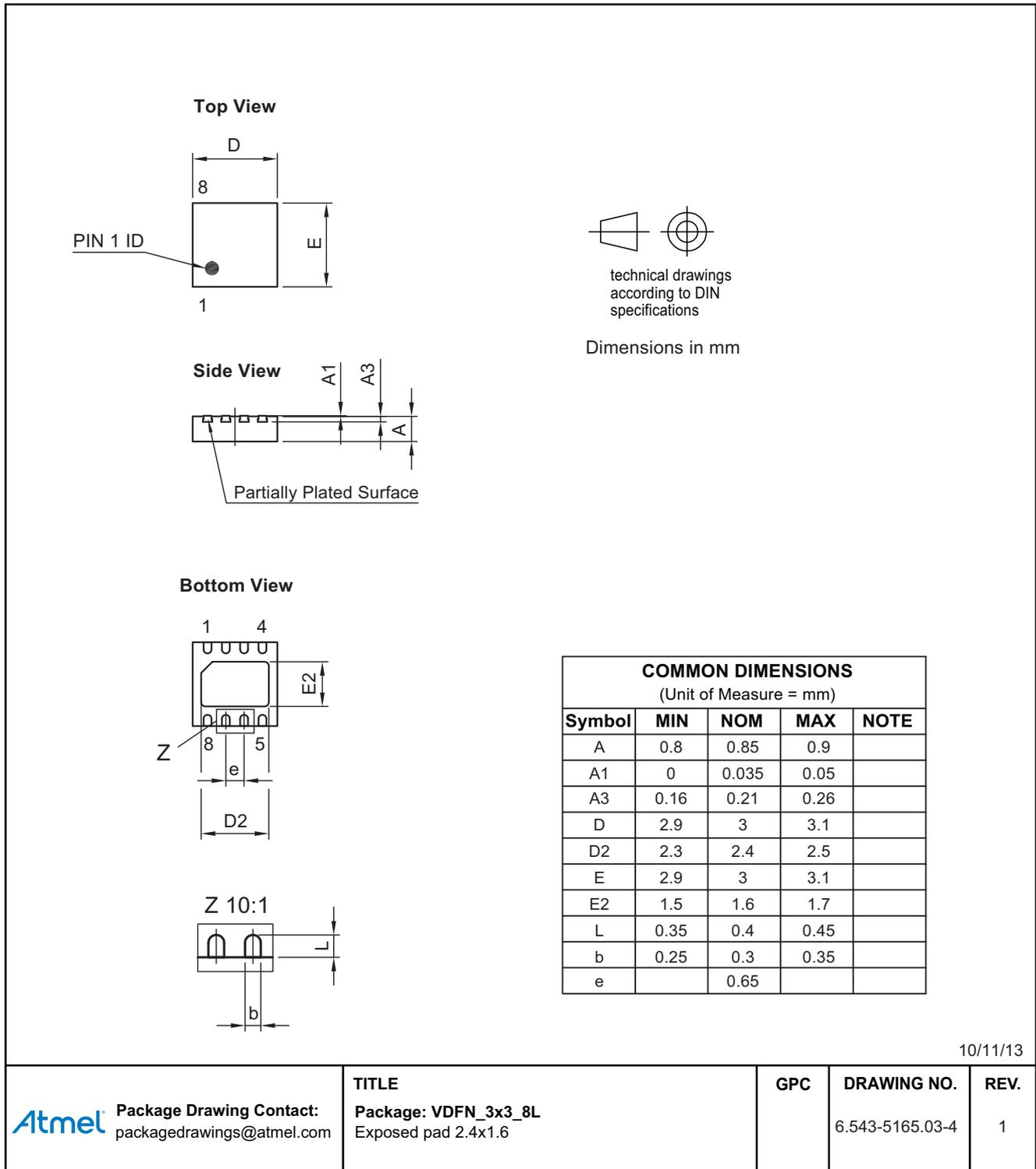


Note: Heat slug must always be connected to GND.

9. Ordering Information

Extended Type Number	Package	Remarks
ATA663254-FAQW	DFN8	5V LIN system basis chip, Pb-free, 6k, taped and reeled
ATA663231-FAQW	DFN8	3.3V LIN system basis chip, Pb-free, 6k, taped and reeled

10. Package Information



11. Revision History

Please note that the following page numbers referred to in this section refer to the specific revision mentioned, not to this document.

Revision No.	History
9337C-AUTO-05/14	<ul style="list-style-type: none">• ATA663231 implemented
9337B-AUTO-02/14	<ul style="list-style-type: none">• Features on page 1 updated• Section 1 “Description” on page 2 updated• Section 4.2.2 “Silent Mode” on page 7 updated• Section 4.5 “Voltage Regulator” on page 13 updated• Section 7 “Electrical Characteristics” number 1.6 on page 16 updated• Section 7 “Electrical Characteristics” number 12.3 on page 18 updated



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