

Thyristor Modules

Thyristor/Diode Modules

$$I_{TRMS} = 2 \times 180 \text{ A}$$

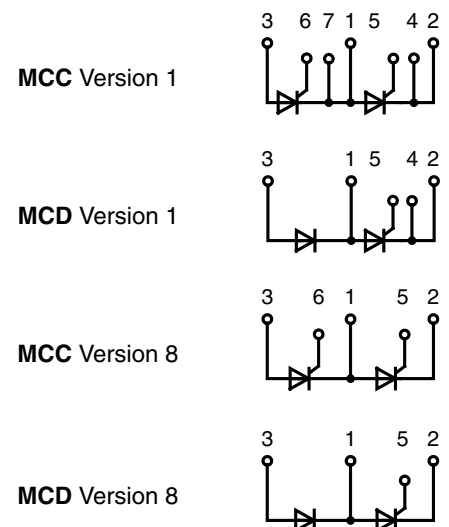
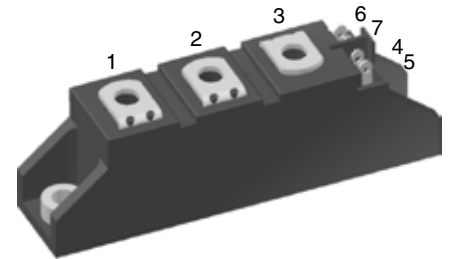
$$I_{TAVM} = 2 \times 116 \text{ A}$$

$$V_{RRM} = 800-1800 \text{ V}$$

V_{RSM} V_{DSM} V	V_{RRM} V_{DRM} V	Type	Version	1B	8B	Version	1B	8B
900	800	MCC 95-08	io1B / io8B			MCD 95-08	io1B / io8B	
1300	1200	MCC 95-12	io1B / io8B			MCD 95-12	io1B / io8B	
1500	1400	MCC 95-14	io1B / io8B			MCD 95-14	io1B / io8B	
1700	1600	MCC 95-16	io1B / io8B			MCD 95-16	io1B / io8B	
1900	1800	MCC 95-18	io1B / io8B			MCD 95-18	io1B / io8B	

Symbol	Conditions	Maximum Ratings			
I_{TRMS} , I_{FRMS}	$T_{VJ} = T_{VJM}$	180	A		
I_{TAVM} , I_{FAVM}	$T_C = 85^{\circ}\text{C}$; 180° sine	116	A		
I_{TSM} , I_{FSM}	$T_{VJ} = 45^{\circ}\text{C}$	$t = 10\text{ ms}$	(50 Hz)	2250	A
	$V_R = 0$	$t = 8.3\text{ ms}$	(60 Hz)	2400	A
	$T_{VJ} = T_{VJM}$	$t = 10\text{ ms}$	(50 Hz)	2000	A
	$V_R = 0$	$t = 8.3\text{ ms}$	(60 Hz)	2150	A
I^2t	$T_{VJ} = 45^{\circ}\text{C}$	$t = 10\text{ ms}$	(50 Hz)	25 300	A²s
	$V_R = 0$	$t = 8.3\text{ ms}$	(60 Hz)	23 900	A²s
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$	$t = 10\text{ ms}$	(50 Hz)	20 000	A²s
	$V_R = 0$	$t = 8.3\text{ ms}$	(60 Hz)	19 100	A²s
	$T_{VJ} = T_{VJM}$	repetitive, $I_T = 250\text{ A}$		150	A/μs
	$f = 50\text{ Hz}$; $t_p = 200\text{ μs}$; $V_D = \frac{2}{3} V_{DRM}$ $I_G = 0.45\text{ A}$ $di_G/dt = 0.45\text{ A/μs}$	non repetitive, $I_T = I_{TAVM}$		500	A/μs
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}$; $V_D = \frac{2}{3} V_{DRM}$ $R_{GK} = \infty$; method 1 (linear voltage rise)			1000	V/μs
P_{GM}	$T_{VJ} = T_{VJM}$; $t_p = 30\text{ μs}$ $I_T = I_{T(AV)M}$; $t_p = 500\text{ μs}$			10 5	W W
P_{GAV}				0.5	W
V_{RGM}				10	V
T_{VJ}				-40...+125	°C
T_{VJM}				125	°C
T_{stg}				-40...+125	°C
V_{ISOL}	50/60 Hz, RMS	$t = 1\text{ min}$		3000	V~
	$I_{ISOL} \leq 1\text{ mA}$	$t = 1\text{ s}$		3600	V~
M_d	Mounting torque (M5)			2.5 - 4	Nm
	Terminal connection torque (M5)			2.5 - 4	Nm
Weight	Typical including screws			85	g

Data according to IEC 60747 and refer to a single diode unless otherwise stated.



Features

- International standard package, JEDEC TO-240 AA
- Direct copper bonded Al_2O_3 -ceramic base plate
- Planar passivated chips
- Isolation voltage 3600 V~
- UL registered, E 72873
- Gate-cathode twin pins for version 1

Applications

- DC Motor control
- Softstart AC motor controller
- Light, heat and temperature control

Advantages

- Space and weight savings
- Simple mounting with two screws
- Improved temperature & power cycling
- Reduced protection circuits

Symbol	Conditions	Characteristic Values	
		typ.	max.
I_{RRM}, I_{DRM}	$V_R / V_D = V_{RRM} / V_{DRM}$	$T_{VJ} = T_{VJM}$	5 mA
V_T, V_F	$I_T / I_F = 300$ A	$T_{VJ} = 25^\circ\text{C}$	1.5 V
V_{T0}	For power-loss calculations only		0.8 V
r_t		$T_{VJ} = T_{VJM}$	2.4 mΩ
V_{GT}	$V_D = 6$ V	$T_{VJ} = 25^\circ\text{C}$	2.5 V
		$T_{VJ} = -40^\circ\text{C}$	2.6 V
I_{GT}	$V_D = 6$ V	$T_{VJ} = 25^\circ\text{C}$	150 mA
		$T_{VJ} = -40^\circ\text{C}$	200 mA
V_{GD}	$V_D = 2/3 V_{DRM}$	$T_{VJ} = T_{VJM}$	0.2 V
I_{GD}			10 mA
I_L	$t_p = 10 \mu\text{s}; V_D = 6$ V $I_G = 0.45$ A; $di_G/dt = 0.45$ A/ μs	$T_{VJ} = 25^\circ\text{C}$	450 mA
I_H	$V_D = 6$ V; $R_{GK} = \infty$;	$T_{VJ} = 25^\circ\text{C}$	200 mA
t_{gd}	$V_D = 1/2 V_{DRM}$ $I_G = 0.45$ A; $di_G/dt = 0.45$ A/ μs	$T_{VJ} = 25^\circ\text{C}$	2 μs
t_q	$V_D = 2/3 V_{DRM}$ $dv/dt = 20$ V/ μs ; $-di/dt = 10$ A/ μs $I_T = 150$ A; $V_R = 100$ V; $t_p = 200 \mu\text{s}$	$T_{VJ} = T_{VJM}$	185 μs
Q_S	$I_T / I_F = 50$ A; $-di/dt = 6$ A/ μs	$T_{VJ} = T_{VJM}$	170 μC
I_{RM}			45 A
R_{thJC}	per thyristor; DC current	other values see Fig. 8/9	0.22 K/W
	per module		0.11 K/W
R_{thJK}	per thyristor; DC current		0.42 K/W
	per module		0.21 K/W
d_s	Creeping distance on surface		12.7 mm
d_A	Creepage distance in air		9.6 mm
a	Maximum allowable acceleration		50 m/s ²

Optional accessories for modules

Coded gate/cathode twin plugs with wire length = 350 mm, gate = yellow, cathode = red

Type **ZY 200L** (L = Left for pin pair 4/5) } UL 758, style 1385,
Type **ZY 200R** (R = Right for pin pair 6/7) } CSA class 5851, guide 460-1-1

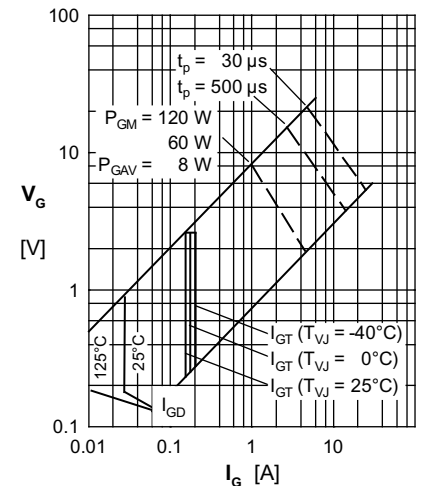


Fig. 1 Gate trigger characteristics

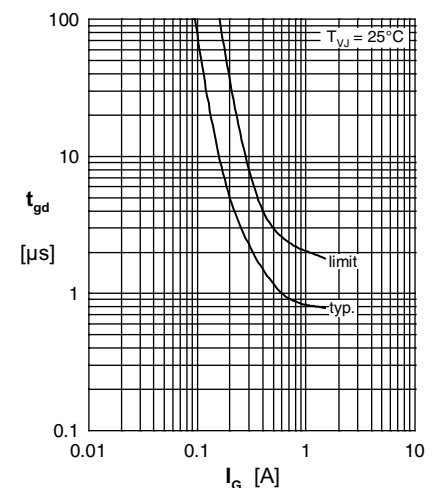
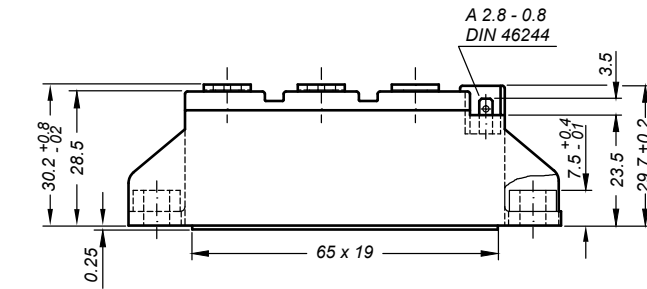


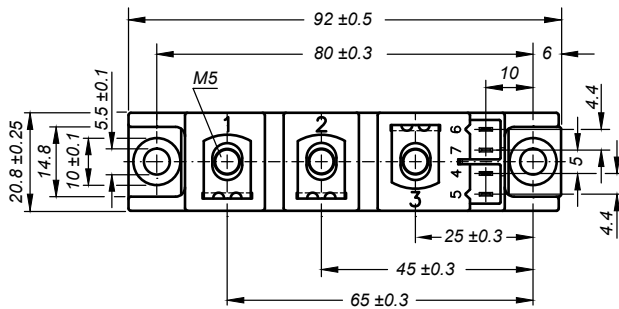
Fig. 2 Gate trigger delay time

Dimensions in mm (1 mm = 0.0394")

MCC... Version 1B

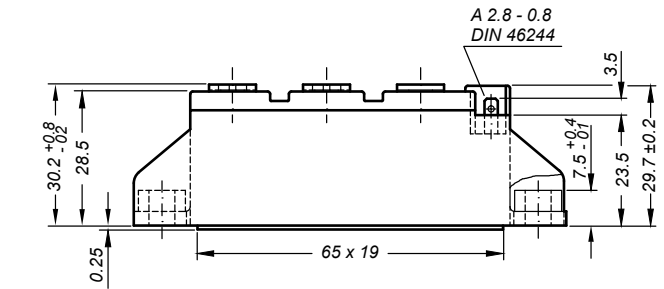


General tolerance: DIN ISO 2768 class „c“

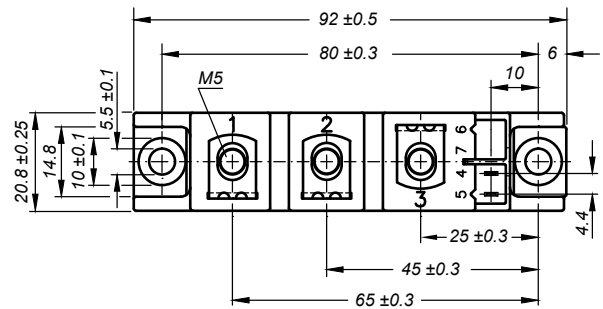


Optional accessories: Keyed gate/cathode twin plugs
 Wire length: 350 mm, gate = yellow, cathode = red
 UL 758, style 1385, CSA class 5851, guide 460-1-1
 Type ZY 200L (L = Left for pin pair 4/5)
 Type ZY 200R (R = Right for pin pair 6/7)

MCD... Version 1B

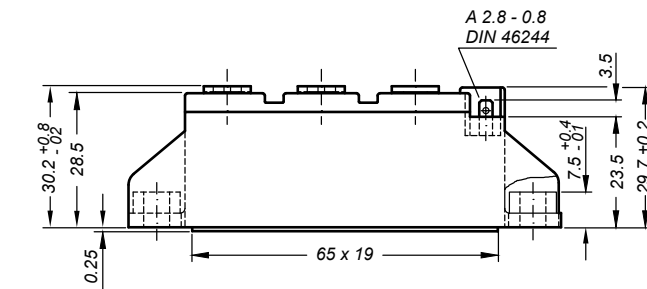


General tolerance: DIN ISO 2768 class „c“

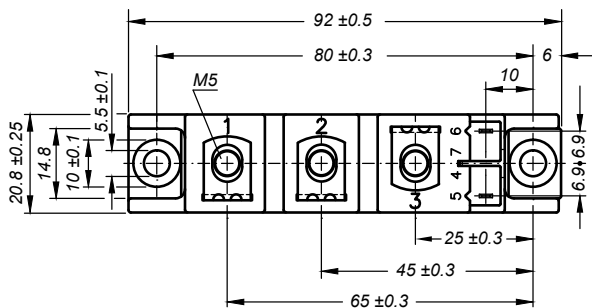


Optional accessories: Keyed gate/cathode twin plugs
 Wire length: 350 mm, gate = yellow, cathode = red
 UL 758, style 1385, CSA class 5851, guide 460-1-1
 Type ZY 200L (L = Left for pin pair 4/5)

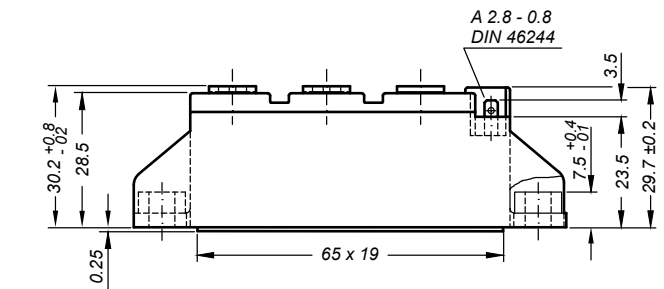
MCC... Version 8B



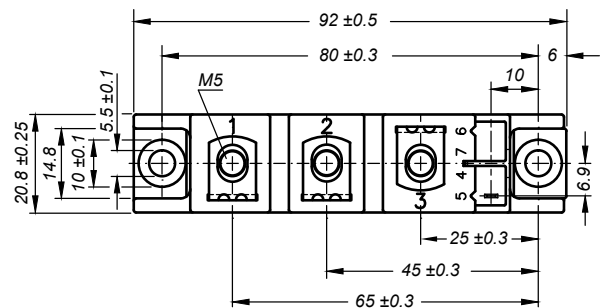
General tolerance: DIN ISO 2768 class „c“



MCD... Version 8B



General tolerance: DIN ISO 2768 class „c“



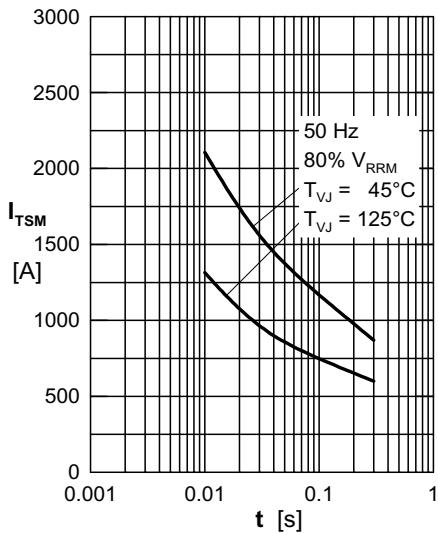


Fig. 3 Surge overload current I_{TSM} ,
 I_{FSM} : Crest value, t : duration

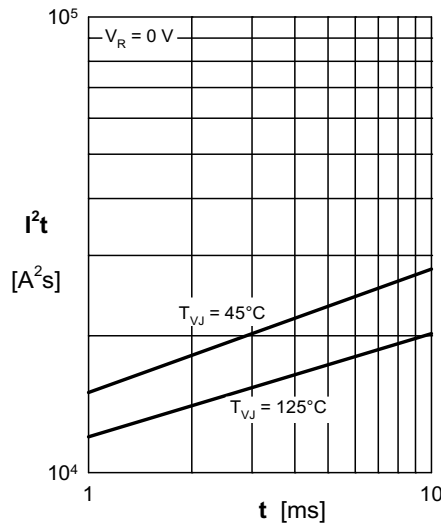


Fig. 4 I^2t versus time (1-10 ms)

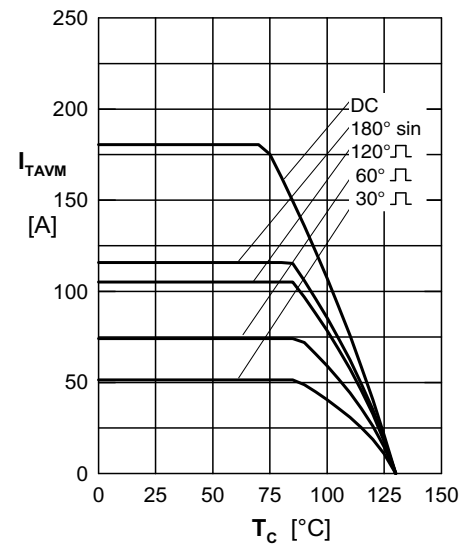


Fig. 4a Maximum forward current
at case temperature

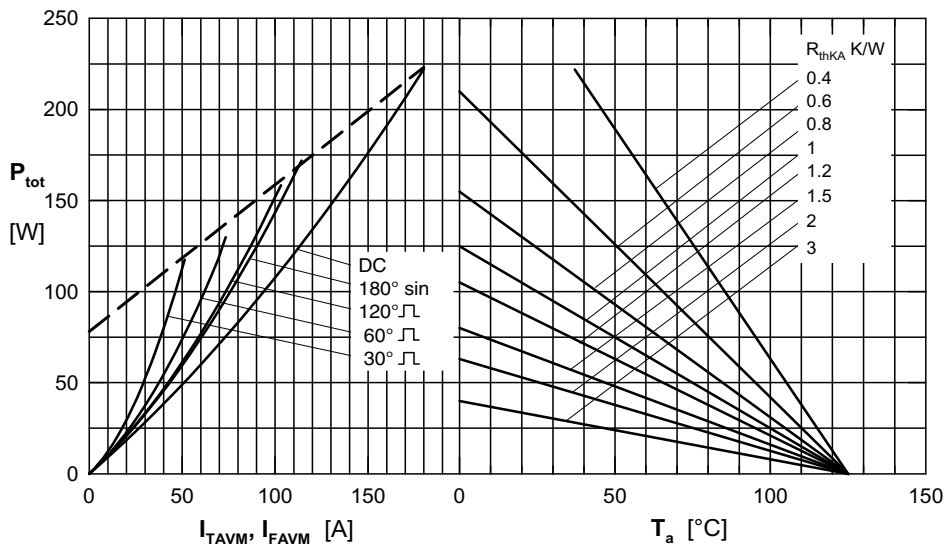


Fig. 5 Power dissipation versus
on-state current & ambient
temperature
(per thyristor or diode)

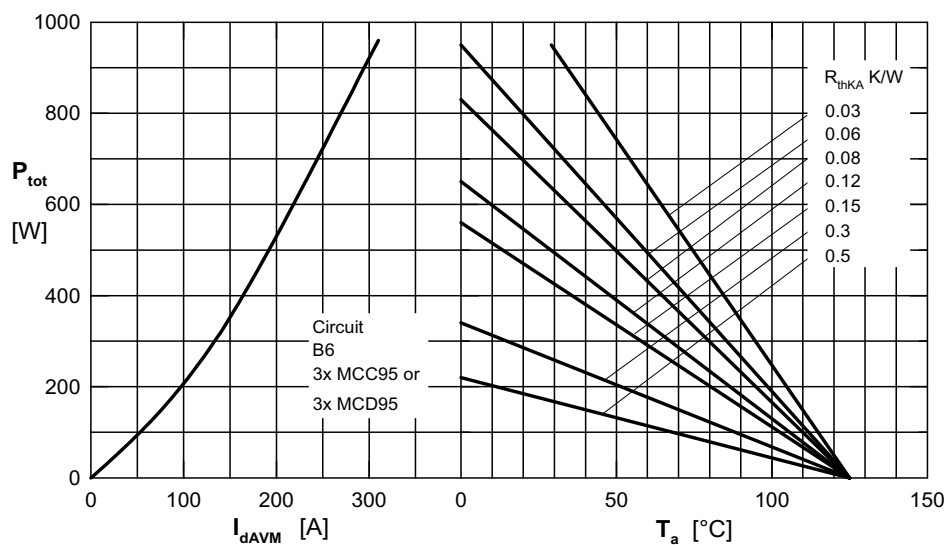


Fig. 6 Three phase rectifier bridge:
Power dissipation vs. direct
output current and ambient
temperature

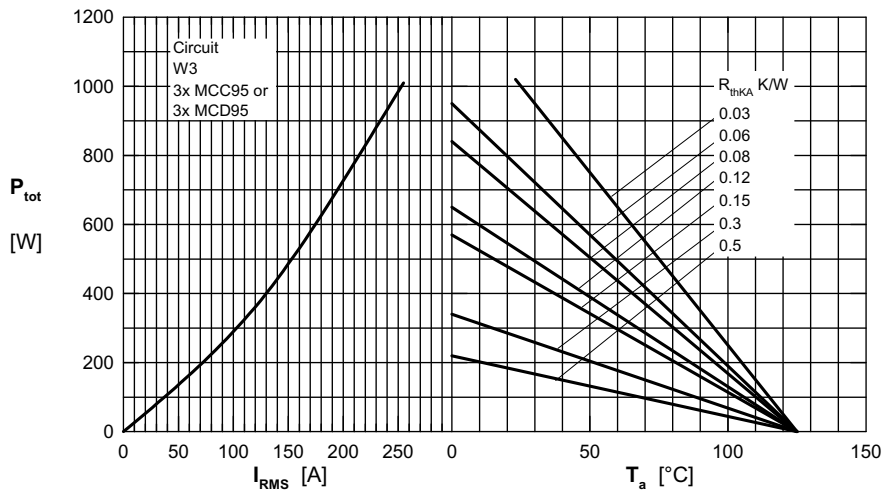


Fig. 7 Three phase AC-controller:
Power dissipation versus RMS
output current and ambient
temperature

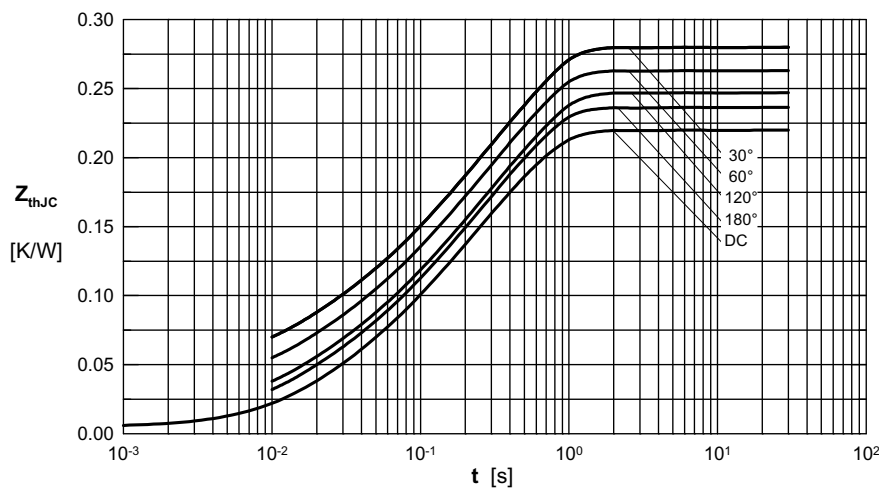


Fig. 8 Transient thermal impedance
junction to case
(per thyristor or diode)

R_{thJC} for various conduction angles d :

d	R_{thJC} (K/W)
DC	0.22
180°	0.23
120°	0.25
60°	0.27
30°	0.28

Constants for Z_{thJC} calculation:

i	R_{thi} (K/W)	t_i (s)
1	0.0066	0.0019
2	0.0678	0.0477
3	0.1456	0.344

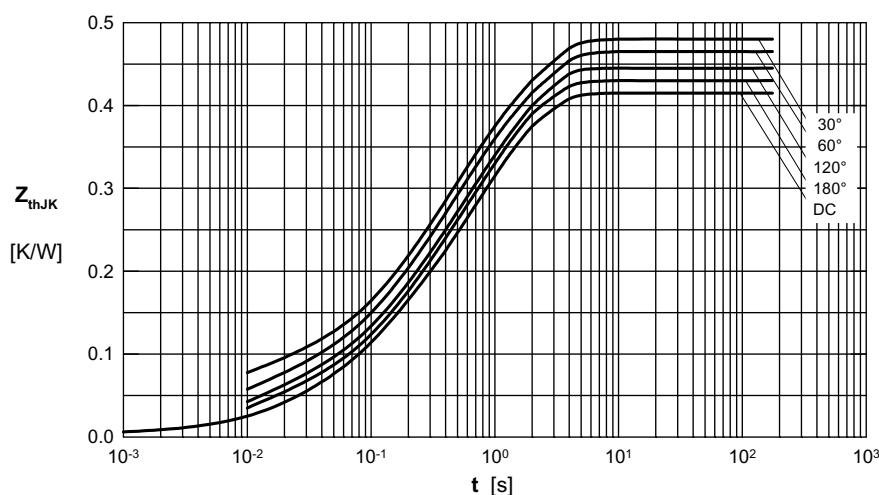


Fig. 9 Transient thermal impedance
junction to heatsink
(per thyristor or diode)

R_{thJK} for various conduction angles d :

d	R_{thJK} (K/W)
DC	0.42
180°	0.43
120°	0.45
60°	0.47
30°	0.48

Constants for Z_{thJK} calculation:

i	R_{thi} (K/W)	t_i (s)
1	0.0066	0.0019
2	0.0678	0.0477
3	0.1456	0.344
4	0.2	1.32

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