



Integrated Power Hybrid IC for
Appliance Motor Drive Applications

IRAM336-025SB

*i*MOTION™ Series

3 Phase Inverter HIC

2A, 500V

Description

International Rectifier's IRAM336-025SB is a multi-chip Hybrid IC developed for low power appliance motor control applications such as Fans, Pumps, and refrigerator compressors. The compact Single in line (SIP-S) package minimizes PCB space.

Several built-in protection features such as temperature feedback, shoot through prevention, under voltage lockout, and shutdown input makes this a very robust solution. The combination of highly efficient high voltage MOSFETs and the industry benchmark 3-phase HVIC driver (3.3V/5V input compatible) and thermally enhanced package makes this a highly competitive solution.

The bootstrapped power supplies for the high side drivers can be generated using internal bootstrap diodes eliminating the need for isolated power supplies. This feature reduces the component count, board space, and cost of the system.

Features

- Motor Power up to 250W / 85~253 Vac.
- Integrated Gate Drivers and Bootstrap Diodes.
- Over-current Shut-Down function.
- Under-voltage lockout for all switches.
- Matched propagation delay for all channels.
- Schmitt-triggered input logic.
- Cross-conduction prevention logic.
- Lower di/dt gate driver for better noise immunity.



Absolute Maximum Ratings

Absolute maximum ratings indicate sustained limits beyond which damage to the device may occur. All voltage parameters are absolute voltages referenced to V_{SS} .

V_{DSS}	MOSFET Blocking Voltage	500	V
V_{bus}	Positive DC Bus Input Voltage	400	V
I_o @ $T_C=25^\circ C$	RMS Phase Current	2.0	A
I_o @ $T_C=100^\circ C$	RMS Phase Current (Note 1)	1.0	
I_{pk} @ $T_C=25^\circ C$	Maximum Peak Current ($t_p < 100\mu s$)	6.0	
P_d	Maximum Power dissipation per Fet @ $T_C = 25^\circ C$	15	W
T_J (MOSFET & IC)	Maximum Operating Junction Temperature	+150	$^\circ C$
T_C	Operating Case temperature Range	-20 to +100	
T_{STG}	Storage Temperature Range	-40 to +125	
T	Mounting torque (M3 screw)	0.6	Nm

Note 1: Sinusoidal Modulation at $V^+ = 360V$, $T_J = 150^\circ C$, $F_{PWM} = 20kHz$, $F_{MOD} = 50Hz$, $MI = 0.8$, $PF = 0.6$, See Figure 5.

Absolute Maximum Ratings (Continued)

Absolute Maximum Ratings indicate substained limits beyond which damage to the device may occur. All voltage paramaters are absolute voltages referenced to V_{SS} .

$V_{S1,2,3}$	High side floating supply offset voltage	$V_{B1,2,3} - 20$	$V_{B1,2,3} + 0.3$	V	
$V_{B1,2,3}$	High side floating supply voltage	-0.3	500	V	
V_{DD}	Low Side and logic fixed supply voltage	-0.3	20	V	
$V_{IN}, V_{F/EN}, V_{ITRIP}$	Input voltage LIN, HIN, Fault/EN, I_{TRIP}	-0.3	Lower of ($V_{SS}+15V$) or $V_{DD}+0.3V$	V	

MOSFET Characteristics

$V_{BIAS} (V_{CC}, V_B) = 15V$ and $T_A = 25^\circ C$ unless otherwise specified. The V_{DD} parameter is referenced to V_{SS} .

Symbol	Parameter	Min	Typ	Max	Units	Conditions
$V_{(BR)DSS}$	Drain-to-Source Breakdown Voltage	500	---	---	V	$V_{IN}=5V, I_D=250\mu A$
I_{DSS}	Drain-to-Source Leakage Current	---	5	100	μA	$V_{IN}=5V, V^+=500V$
$R_{DS(ON)}$	Drain-to-Source On Resistance	---	2.2	2.7	Ω	$I_D=1.0A, V_{DD}=15V$
		---	5.5	---		$I_D=1.0A, V_{DD}=15V, T_J=150^\circ C$
V_{FM}	Diode Forward Voltage Drop	---	0.87	1.0	V	$I_F=1.0A$
		---	0.76	---		$I_F=1.0A, T_J=150^\circ C$

Recommended Operating Conditions

The Input/Output logic timing diagram is shown in Figure 1. For proper operation the device should be used within the recommended conditions. All voltages are absolute referenced to V_{SS} . The V_S offset is tested with all supplies biased at 15V differential.

Symbol	Definition	Min	Typ	Max	Units
V^+	Positive Bus Input Voltage	---	---	360	V
$V_{B1,2,3}$	High side floating supply voltage	V_S+10	V_S+15	V_S+20	
V_{DD}	Low side and logic fixed supply voltage	10	15	20	V
V_{ITRIP}	I_{TRIP} input voltage	V_{SS}	---	$V_{SS}+5$	
$V_{IN}, V_{F/EN}, V_{ITRIP}$	Logic input voltage LIN, HIN, Fault/EN, I_{TRIP} - Note 2	V_{SS}	---	$V_{SS}+5$	V
F_p	Maximum PWM Carrier Frequency	---	---	20	KHz

Note 2: Logic operational for V_S from COM-5V to $V_{SS}+500V$. Logic state held for V_S from $V_{SS}-5V$ to $V_{SS}-V_{BS}$. (please refer to DT97-3 for more details).

Static Electrical Characteristics (T_J= 25°C Unless Otherwise Specified)

V_{BIAS} (V_{DD}, V_{BS1,2,3})=15V, unless otherwise specified. The V_{IN} and I_{IN} parameters are referenced to V_{SS} and are applicable to all six channels (Static Electrical Characteristics are Based on Driver IC Data Sheet).

Symbol	Definition	Min	Typ	Max	Units
V _{EN,th+}	Enable Positive going threshold	---	---	2.5	V
V _{EN,th-}	Enable Negative going threshold	0.8	---	---	V
V _{DDUV+} , V _{BSUV+}	V _{DD} and V _{BS} supply undervoltage, Positive going threshold	8	8.9	9.8	V
V _{DDUV-} , V _{BSUV-}	V _{DD} and V _{BS} supply undervoltage, Negative going threshold	7.4	8.2	9	V
I _{QBS}	Quiescent V _{BS} supply current	---	70	120	μA
I _{QDD}	Quiescent V _{DD} supply current	---	3	4	mA
I _{LK}	Offset Supply Leakage Current	---	---	50	μA
R _B	Internal BS Diode R _{ON} (see Integrated BS Functionality page 10)	---	200	---	Ω

Dynamic Electrical Characteristics (T_J= 25°C Unless Otherwise Specified)

Symbol	Parameter	Min	Typ	Max	Units	Conditions
T _{ON}	Input to Output propagation turn-on delay time (see fig.13a)	---	750	---	ns	I _D =1.5A, V ⁺ =360V
T _{OFF}	Input to Output propagation turn-off delay time (see fig. 13b)	---	920	---	ns	

Thermal and Mechanical Characteristics

Symbol	Parameter	Min	Typ	Max	Units	Conditions
R _{th(J-C)}	Thermal resistance, per FET	---	5.8	8.0	°C/W	Flat, Insulation Material.

Internal NTC - Thermistor Characteristics

Parameter	Definition	Min	Typ	Max	Units	Conditions
R ₂₅	Resistance	97	100	103	kΩ	T _C = 25°C
R ₁₂₅	Resistance	2.25	2.52	2.8	kΩ	T _C = 125°C
B	B-constant (25-50°C)	4208	4250	4293	k	R ₂ = R ₁ e ^[B(1/T₂ - 1/T₁)]
Temperature Range		-40	---	125	°C	
Typ. Dissipation constant		---	1	---	mW/°C	T _C = 25°C

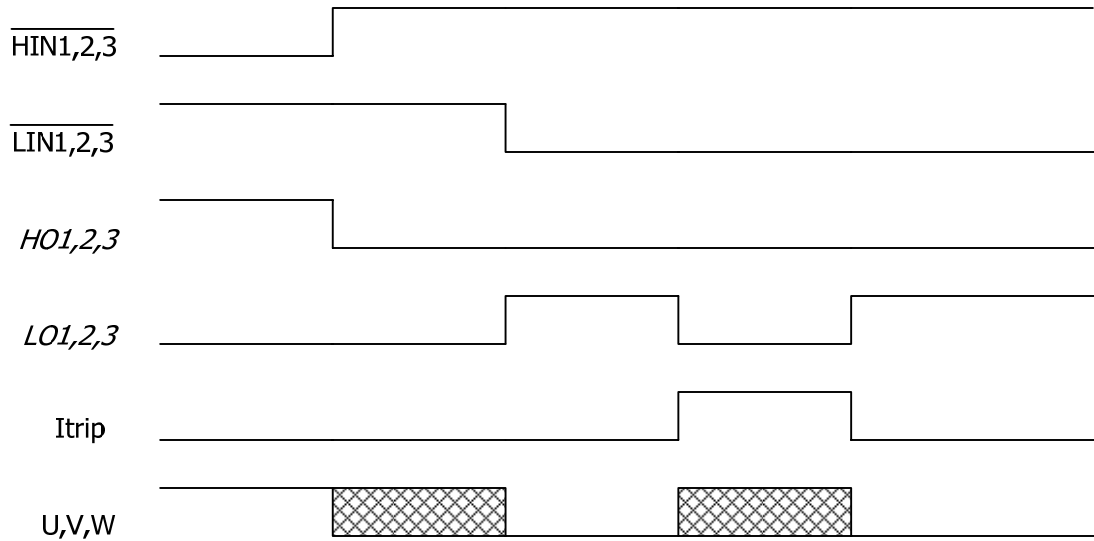
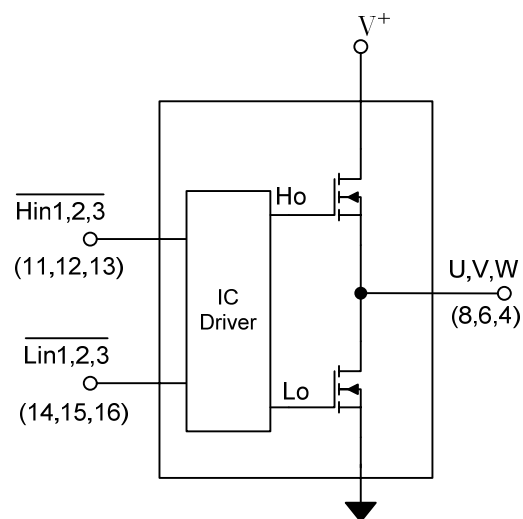


Figure 1. Input/Output Timing Diagram

Note 3: The shaded area indicates that both high-side and low-side switches are off and therefore the half-bridge output voltage would be determined by the direction of current flow in the load.



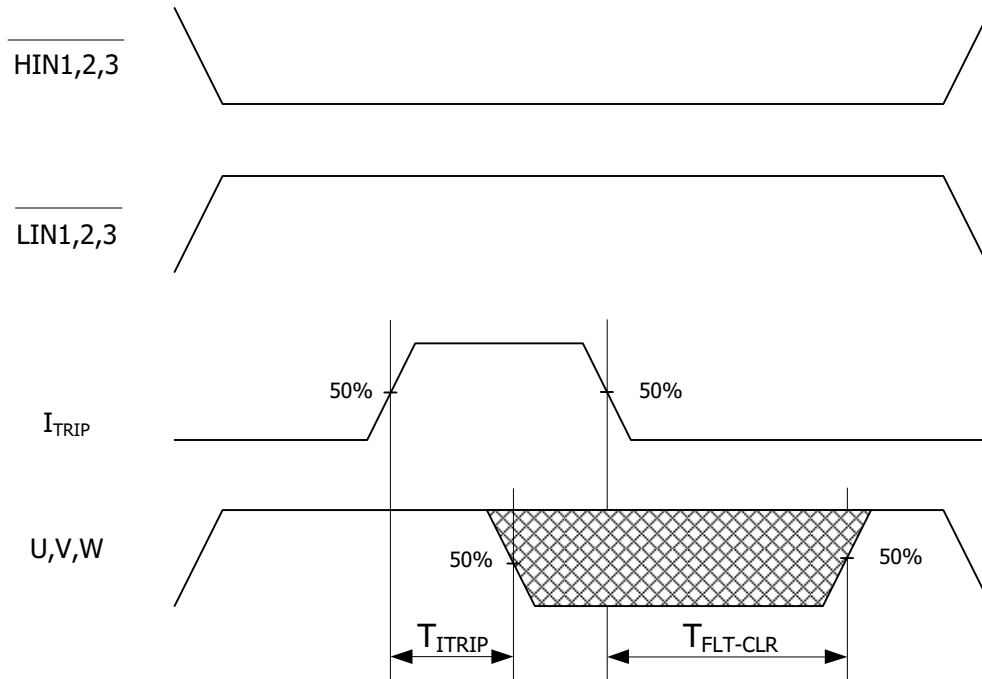


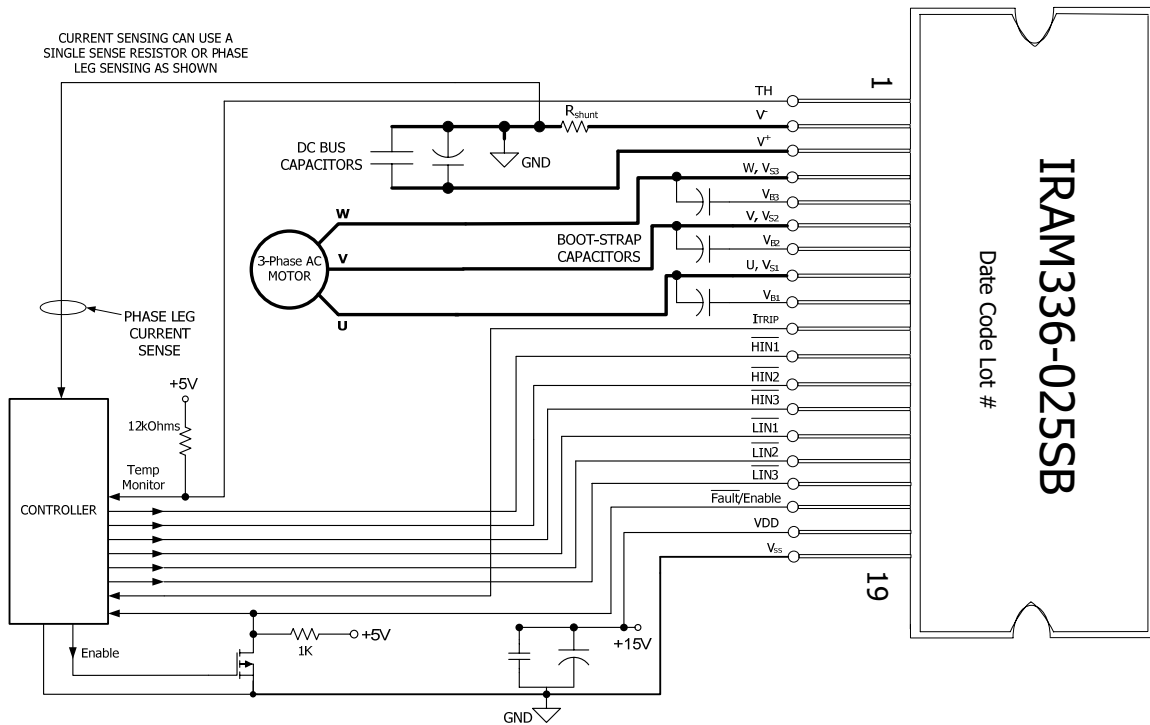
Figure 2. ITRIP Timing Waveform

Note 4: The shaded area indicates that both high-side and low-side switches are off and therefore the half-bridge output voltage would be determined by the direction of current flow in the load.

Input-Output Logic Level Table

$\overline{\text{FLT-EN}}$	ITRIP	$\overline{\text{HIN1,2,3}}$	$\overline{\text{LIN1,2,3}}$	U,V,W
1	0	0	1	V^+
1	0	1	0	0
1	0	1	1	Off
1	1	X	X	Off
0	X	X	X	Off

Typical Application Circuit – Iram336-025SB



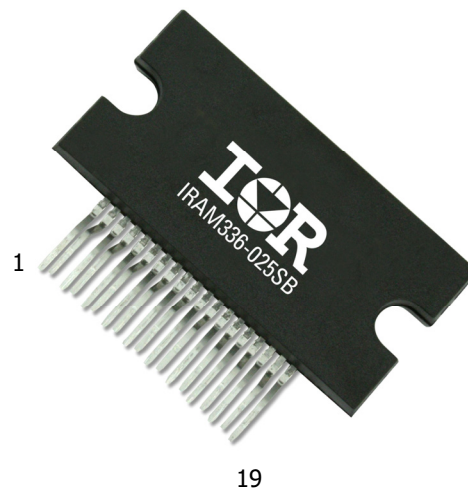
Application Circuit Recommendation

1. Electrolytic bus capacitors should be mounted as close to the module bus terminals as possible to reduce ringing and EMI problems. Additional high frequency ceramic capacitor mounted close to the module pins will further improve performance.
2. In order to provide good decoupling between VCC-VSS and Vb-Vs terminals, the capacitors shown connected between these terminals should be located very close to the module pins. Additional high frequency capacitors, typically 0.1μF, are strongly recommended.
3. Value of the boot-strap capacitors depends upon the switching frequency. Their selection should be made based on IR design tip DN 98-2a or application note AN-1044 or Figure 12.
4. **WARNING!** Please note that after approx. 8ms the FAULT is automatically reset (see Dynamic Characteristics Table on page 5). PWM generator must be disabled within automatic reset time ($T_{FLT-CLR}$) to guarantee shutdown of the system, over-current condition must be cleared before resuming operation.
5. **The case of the module is connected to the negative DC Bus and is NOT Isolated. It is recommended to provide isolation material between case and heat sink to avoid electrical shock.**

IRAM336-025SB

Module Pin-Out Description

Pin	Name	Description
1	TH	Temperature Feedback
2	V ⁻	Negative Bus Input Voltage
3	V ⁺	Positive Bus Input Voltage
4	W, V _{S3}	Output 3 - High Side Floating Supply Offset Voltage
5	V _{B3}	High Side Floating Supply Voltage 3
6	V, V _{S2}	Output 2 - High Side Floating Supply Offset Voltage
7	V _{B2}	High Side Floating Supply voltage 2
8	U, V _{S1}	Output 1 - High Side Floating Supply Offset Voltage
9	V _{B1}	High Side Floating Supply voltage 1
10	I _{TRIP}	Current Feedback & Shut-down Function
11	H _{IN1}	Logic Input High Side Gate Driver - Phase 1
12	H _{IN2}	Logic Input High Side Gate Driver - Phase 2
13	H _{IN3}	Logic Input High Side Gate Driver - Phase 3
14	L _{IN1}	Logic Input Low Side Gate Driver - Phase 1
15	L _{IN2}	Logic Input Low Side Gate Driver - Phase 2
16	L _{IN3}	Logic Input Low Side Gate Driver - Phase 3
17	FAULT/EN	Fault Indicator & Enable Function
18	V _{DD}	+15V Main Supply
19	V _{SS}	Negative Main Supply



Integrated Bootstrap Functionality

The internal Driver IC in the Iram336-025SB embeds an integrated bootstrap FET that allows an alternative drive of the bootstrap supply for a wide range of applications.

There is one bootstrap FET for each channel and it is connected between each of the floating supply (V_{B1} , V_{B2} , V_{B3}) and V_{CC} as shown in Figure 3.

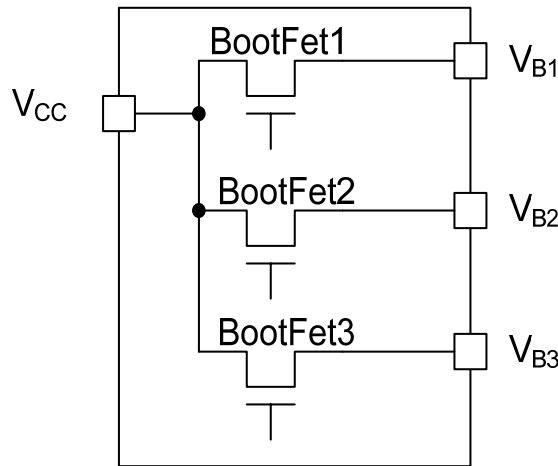


Figure 3. Simplified BootFet Connection

The Bootstrap FET of each channel follows the state of the respective low side output stage (i.e., bootFet is ON when LO is high, it is OFF when LO is low), unless the V_B voltage is higher than approximately $1.1(V_{CC})$. In that case the bootstrap FET stays off until the V_s voltage returns below that threshold (see Fig. 4).

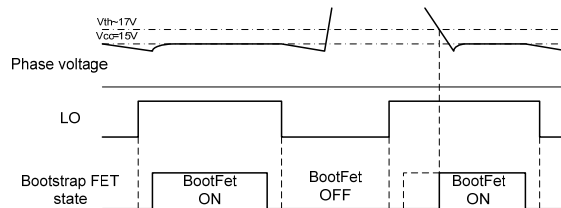


Figure 4. State Diagram

Bootstrap FET is suitable for most PWM modulation schemes and can be used either in parallel with the external bootstrap network (diode+resistor) or as a replacement of it. The use of the integrated bootstrap as a replacement of the external bootstrap network may have some limitations in the following situations:

- When used in non-complementary PWM schemes (typically 6-step modulations).
- At a very high PWM duty cycle due to the bootstrap FET equivalent resistance (R_{BS} , see page 5).

In these cases, better performances can be achieved by using an external bootstrap network.

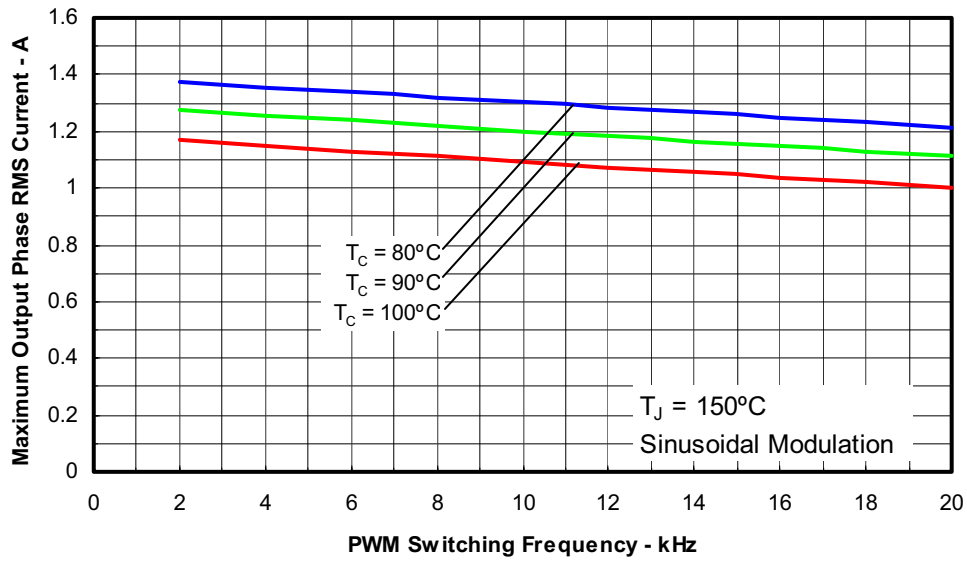


Figure 5. Maximum Sinusoidal Phase Current vs. PWM Switching Frequency
 Sinusoidal Modulation, $V^+ = 360\text{V}$, $T_j = 150^\circ\text{C}$, $F_{\text{MOD}} = 50\text{Hz}$, $\text{MI} = 0.8$, $\text{PF} = 0.6$

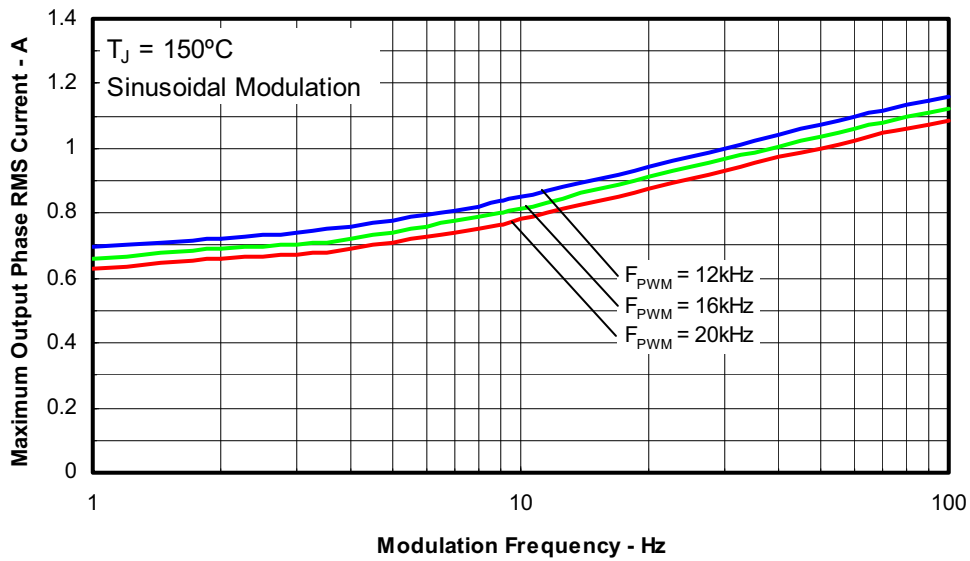


Figure 6. Maximum Sinusoidal Phase Current vs. Modulation Frequency
 Sinusoidal Modulation, $V^+ = 360\text{V}$, $T_j = 150^\circ\text{C}$, $\text{MI} = 0.8$, $\text{PF} = 0.6$

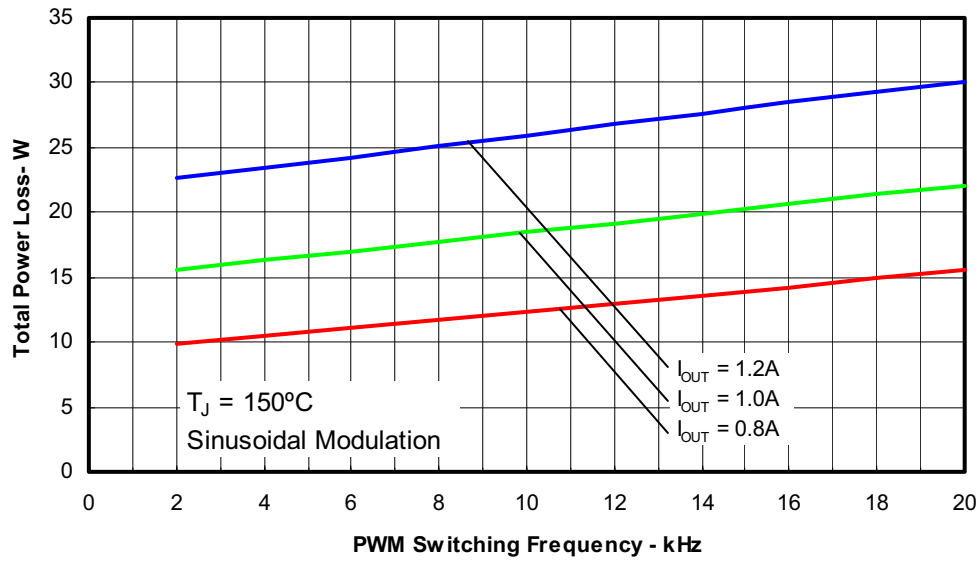


Figure 7. Total Power Losses vs. PWM Switching Frequency
Sinusoidal Modulation, $V^+ = 360V$, $T_J = 150^\circ C$, $MI = 0.8$, $PF = 0.6$

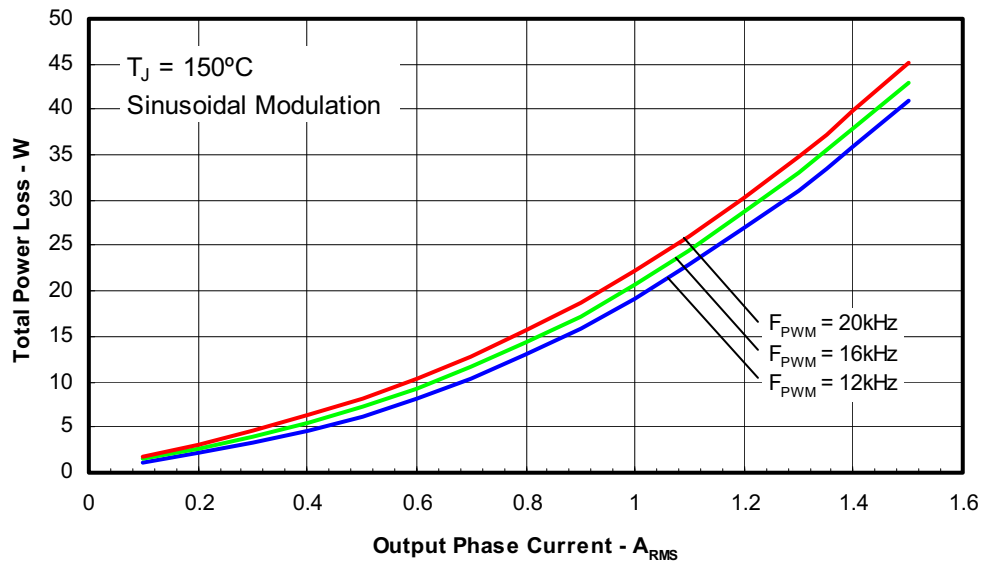


Figure 8. Total Power Losses vs. Output Phase Current
Sinusoidal Modulation, $V^+ = 360V$, $T_J = 150^\circ C$, $MI = 0.8$, $PF = 0.6$

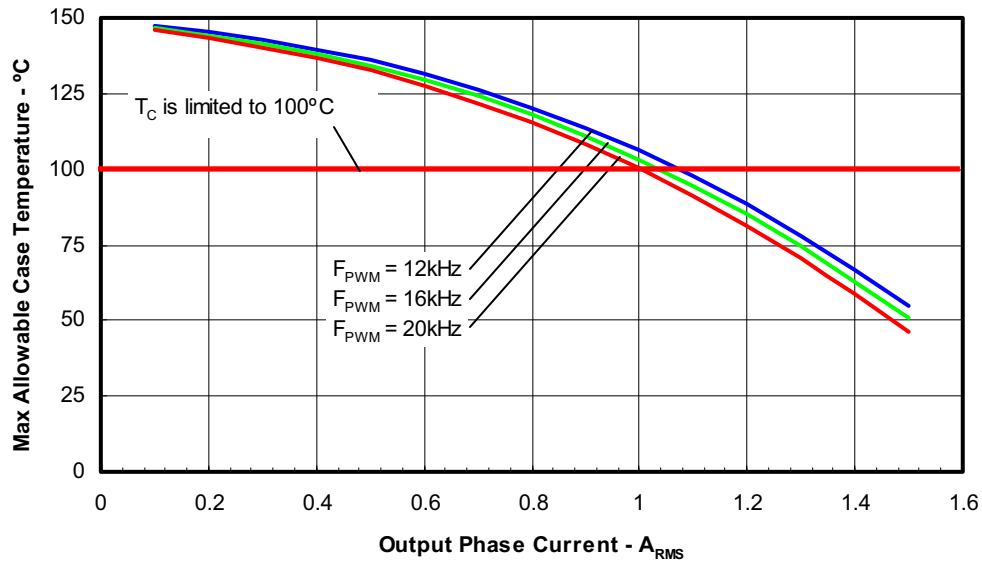


Figure 9. Maximum Allowable Case Temperature vs. Output RMS Current per Phase
Sinusoidal Modulation, $V^+ = 360V$, $T_J = 150^{\circ}C$, $MI = 0.8$, $PF = 0.6$

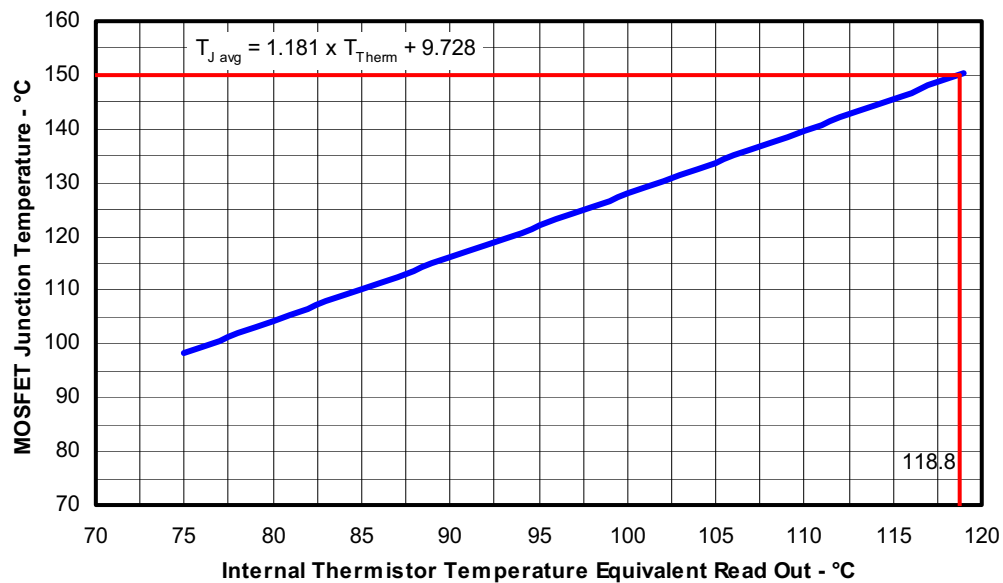


Figure 10. Estimated Maximum MOSFET Junction Temperature vs. Thermistor Temperature
Sinusoidal Modulation, $V^+ = 360V$, $T_J = 150^{\circ}C$, $F_{PWM} = 20kHz$, $F_{MOD} = 50Hz$, $MI = 0.8$, $PF = 0.6$

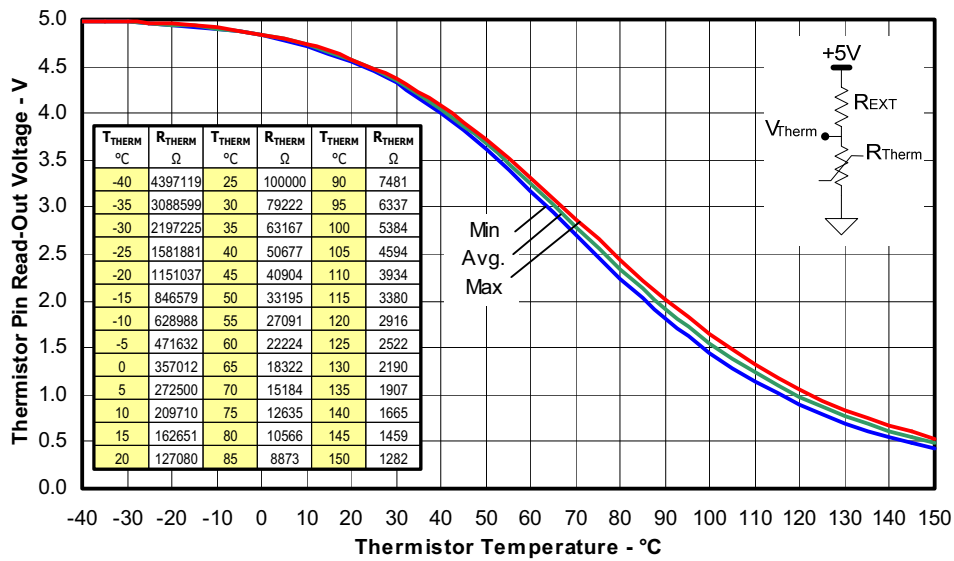


Figure 11. Thermistor Readout vs. Temperature (12Kohm pull-up resistor, 5V) and Normal Thermistor Resistance values vs. Temperature Table.

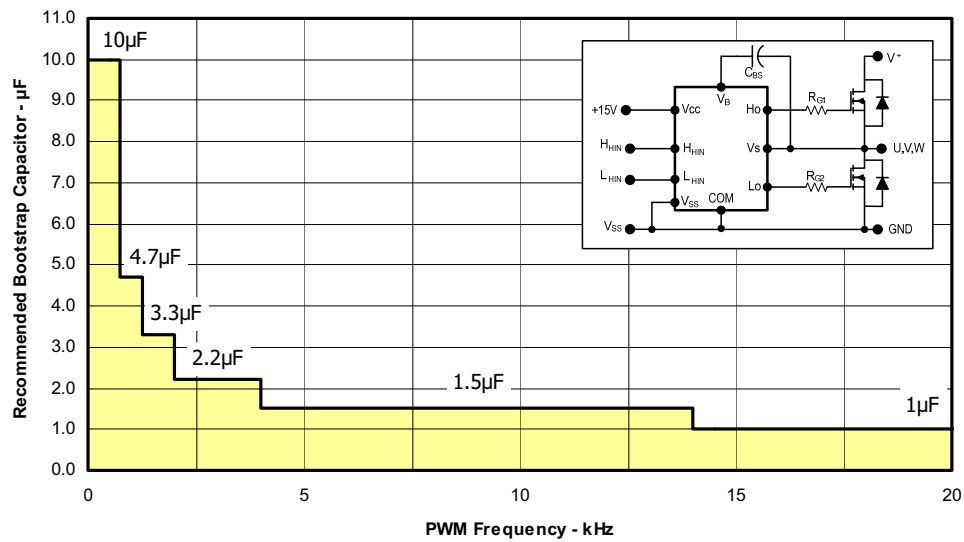


Figure 12. Recommended Bootstrap Capacitor Value vs. Switching Frequency

Figure 13. Switching Parameter Definitions

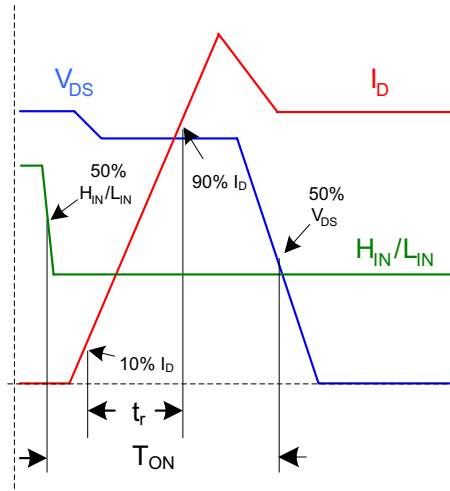


Figure 13a. Input to Output propagation turn-on delay time.

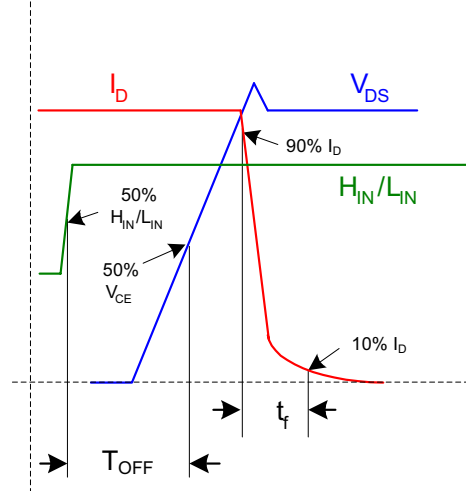


Figure 13b. Input to Output propagation turn-off delay time.

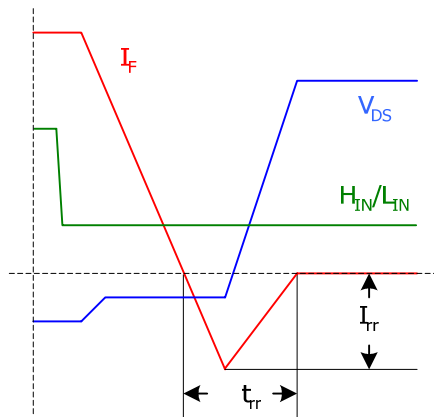


Figure 13c. Diode Reverse Recovery.

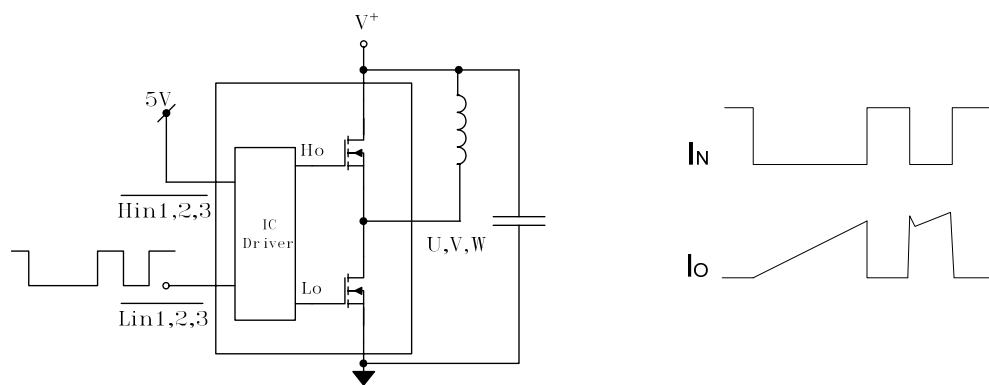


Figure CT1. Switching Loss Circuit

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The drawing consists of three views: a top view, a side view, and a detail view of the pins.

- Top View:** Shows the module's footprint. Overall dimensions are 29.2 (width) and 12.9 (height). The central area is 25.6 wide and 14.5 high. There are four mounting holes, each with a diameter of $2 \times \phi 2.0$. The distance between the centers of the top two holes is 20.47. The distance between the centers of the bottom two holes is 18.0, with a pin pitch of 1.0. The distance from the left edge to the first pin is 5.6, and from the last pin to the right edge is 5.6. The distance from the left edge to the first hole is 5.0, and from the last hole to the right edge is 5.0. A radius of R1.7 is indicated at the bottom corners. A note points to a mirror surface mark on the left edge.
- Side View:** Shows the module's profile. The total height is 14.4. The top section is 4.5 high with a tolerance of $+0.15/-0.05$. The bottom section is 8.2 high. The distance from the top surface to the start of the pins is 7.2. The distance from the bottom surface to the start of the pins is 4.2. The distance from the bottom surface to the top of the pins is 11.0. A note points to the non-isolated back side.
- Detail View:** Shows the pins with a diameter of $\phi 0.35$ and a tolerance of ± 0.05 . The distance between the centers of the pins is 18.0, with a pin pitch of 1.0. The distance from the left edge to the first pin is 5.6, and from the last pin to the right edge is 5.6. The distance from the bottom surface to the top of the pins is 11.0. The distance from the bottom surface to the start of the pins is 4.2. The distance from the bottom surface to the top of the pins is 11.0. The distance from the bottom surface to the start of the pins is 4.2. The distance from the bottom surface to the top of the pins is 11.0.

Notes:

- note1: Unit Tolerance is $\pm 0.4\text{mm}$, Unless Otherwise Specified.
- note2: Mirror Surface Mark indicates Pin1 Identification.
- note3: Characters Font in this drawing differs from Font shown on Module.
- note4: Lot Code Marking. Characters Font in this drawing differs from Font shown on Module.
- note5: Non-Isolated Back Side.

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