

## 200 Msps, 14-Bit Low-Power Single-Channel ADC

### Features

- Sample Rates: 200 Msps
- Signal-to-Noise Ratio (SNR) with  $f_{IN} = 15$  MHz and -1 dBFS:
  - 67.8 dBFS (typical) at 200 Msps
- Spurious-Free Dynamic Range (SFDR) with  $f_{IN} = 15$  MHz and -1 dBFS:
  - 96 dBc (typical) at 200 Msps
- Power Dissipation with LVDS Digital I/O:
  - 346 mW at 200 Msps
- Power Dissipation with CMOS Digital I/O:
  - 304 mW at 200 Msps, output clock = 100 MHz
- Power Dissipation Excluding Digital I/O:
  - 256 mW at 200 Msps
- Power-Saving Modes:
  - 89 mW during Standby
  - 24 mW during Shutdown
- Supply Voltage:
  - Digital Section: 1.2V, 1.8V
  - Analog Section: 1.2V, 1.8V
- Selectable Full-Scale Input Range: up to 1.8 V<sub>P-P</sub>
- Analog Input Bandwidth: 650 MHz
- Output Interface:
  - Parallel CMOS, DDR LVDS
- Output Data Format:
  - Two's complement or offset binary
- Optional Output Data Randomizer

- Digital Signal Post-Processing (DSPP) Options:
  - Decimation filters for improved SNR
  - Offset and Gain adjustment
  - Digital Down-Conversion (DDC) with I/Q or  $f_s/8$  output (MCP37D20-200)
- Built-In ADC Linearity Calibration Algorithms:
  - Harmonic Distortion Correction (HDC)
  - DAC Noise Cancellation (DNC)
  - Dynamic Element Matching (DEM)
  - Flash Error Calibration
- Serial Peripheral Interface (SPI)
- Package Options:
  - VTLA-124 (9 mm x 9 mm x 0.9 mm)
  - TFBGA-121 (8 mm x 8 mm)
- No external reference decoupling capacitor required for TFBGA Package
- Industrial Temperature Range: -40°C to +85°C

### Typical Applications

- Communication Instruments
- Microwave Digital Radio
- Cellular Base Stations
- Radar
- Scanners and Low-Power Portable Instruments
- Industrial and Consumer Data Acquisition System

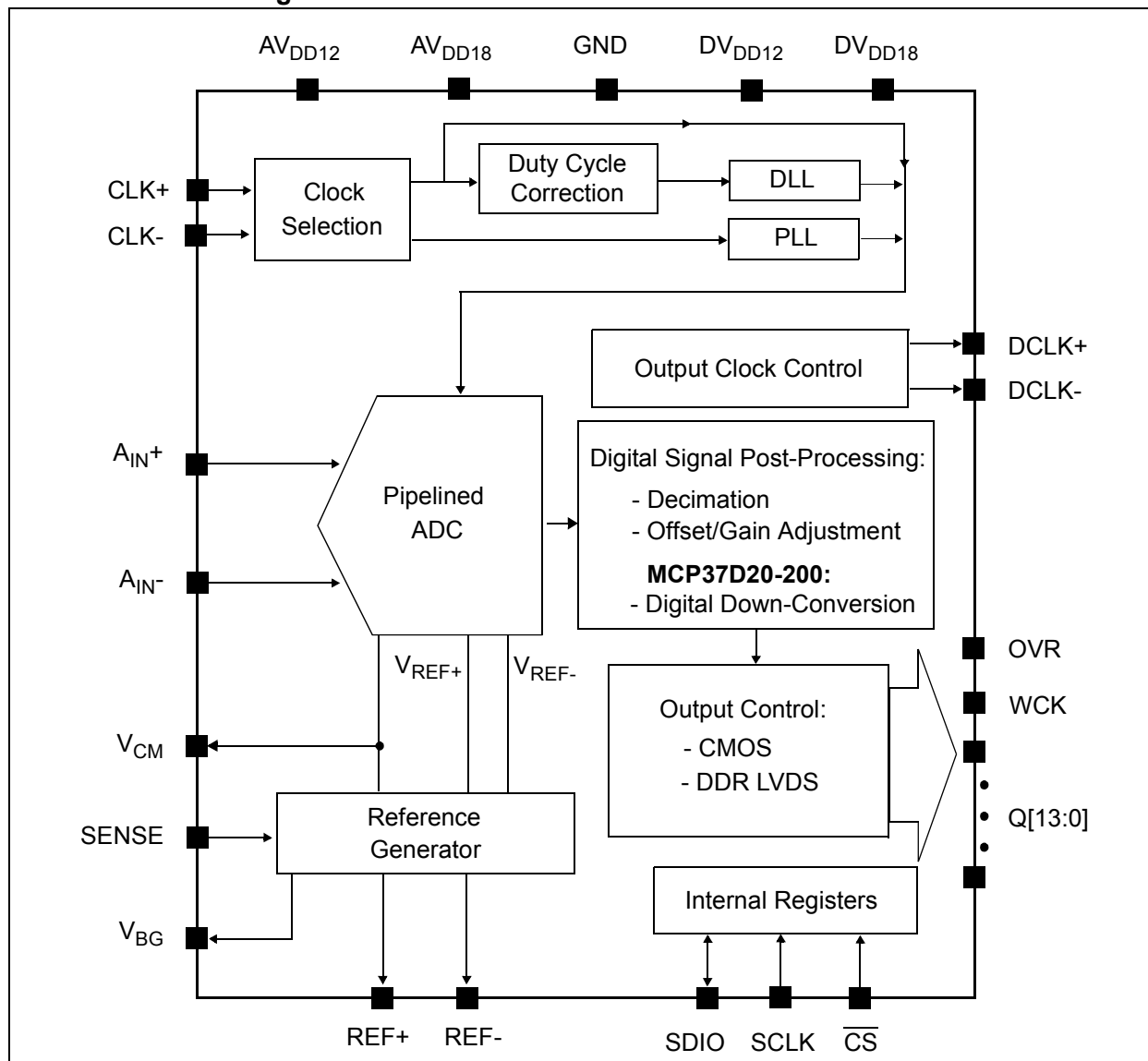
### Device Offering<sup>(1)</sup>

Part Number	Sample Rate	Resolution	Digital Decimation (FIR Filters)	Digital Down-Conversion	Noise-Shaping Requantizer
MCP37220-200	200 Msps	14	Yes	No	No
MCP37D20-200	200 Msps	14	Yes	Yes	No
MCP37210-200	200 Msps	12	Yes	No	Yes
MCP37D10-200	200 Msps	12	Yes	Yes	Yes

1: Devices in the same package type are pin-compatible.

# MCP37220-200 AND MCP37D20-200

Functional Block Diagram



# MCP37220-200 AND MCP37D20-200

## Description

The MCP37220-200 is a single-channel 200 Msps 14-bit pipelined ADC, with built-in high-order digital decimation filters, gain and offset adjustment.

The MCP37D20-200 is also a single-channel 200 Msps 14-bit pipelined ADC, with built-in digital down-conversion in addition to the features offered by the MCP37220-200.

Both devices feature harmonic distortion correction and DAC noise cancellation that enables high-performance specifications with SNR of 67.8 dBFS (typical) and SFDR of 96 dBc (typical).

The output decimation filter option improves SNR performance up to 83.9 dBFS with the 512x decimation setting.

The digital down-conversion option in the MCP37D20-200 can be utilized with the decimation and quadrature output (I and Q data) options and offers great flexibility in digital communication system design, including cellular base-stations and narrow-band communication systems.

These A/D converters exhibit industry-leading low-power performance with only 348 mW operation while using the LVDS output interface at 200 Msps. This superior low-power operation, coupled with high dynamic performance, makes these devices ideal for portable communication devices, sonar, radar and high-speed data acquisition systems.

These devices also include various features designed to maximize flexibility in the user's applications and minimize system cost, such as a programmable PLL clock, output data rate control and phase alignment, and programmable digital pattern generation. The device's operational modes and feature sets are configured by setting up the user-programmable internal registers.

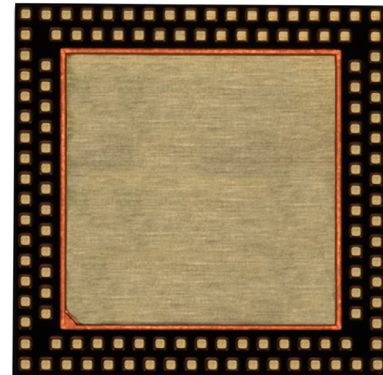
The device samples the analog input on the rising edge of the clock. The digital output code is available after 23 clock cycles of data latency. Latency will increase if any of the digital signal post-processing (DSPP) options are enabled.

The differential full-scale analog input range is programmable up to  $1.8 V_{P-P}$ . The ADC output data can be coded in two's complement or offset binary representation, with or without the data randomizer option. The output data is available with a full-rate CMOS or Double-Data-Rate (DDR) LVDS interface.

The device is available in Pb-free VTLA-124 and TFBGA-121 packages. The device operates over the commercial temperature range of  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ .

## Package Types

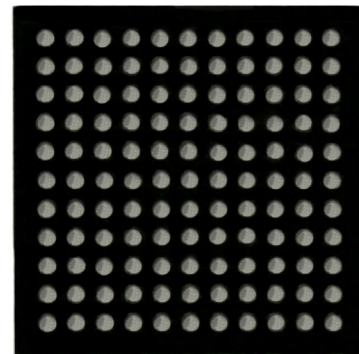
Bottom View



Dimension: 9 mm x 9 mm x 0.9 mm

(a) VTLA-124 Package.

Bottom View



Dimension: 8 mm x 8 mm x 1.08 mm  
Ball Pitch: 0.65 mm  
Ball Diameter: 0.4 mm

(b) TFBGA-121 Package.

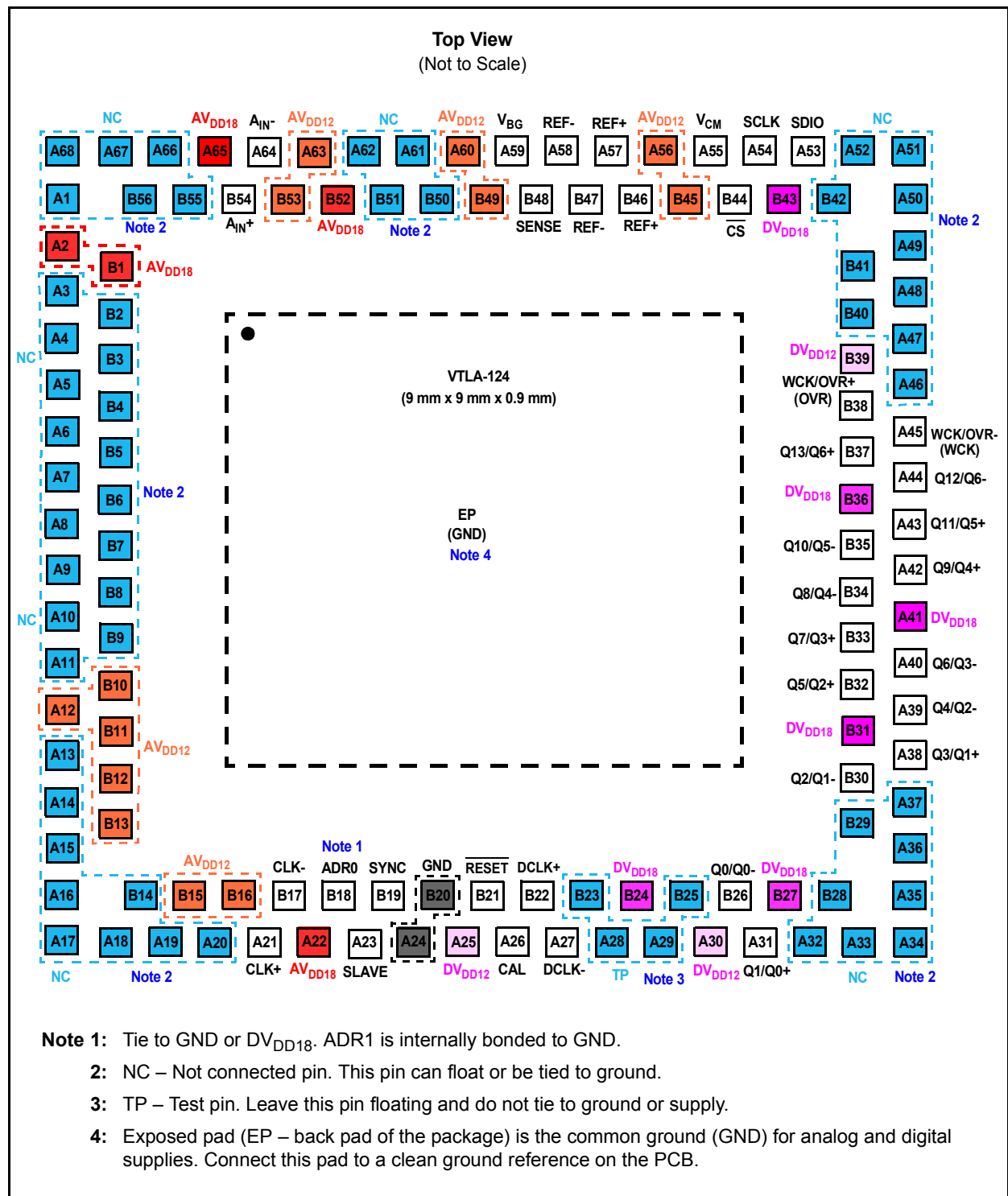
# MCP37220-200 AND MCP37D20-200

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NOTES:

# MCP37220-200 AND MCP37D20-200

## 1.0 PACKAGE PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS



**FIGURE 1-1:** VTLA-124 Package.

# MCP37220-200 AND MCP37D20-200

TABLE 1-1: PIN FUNCTION TABLE FOR VTLA-124

Pin No.	Name	I/O Type	Description
Power Supply Pins			
A2, A22, A65, B1, B52	AV <sub>DD18</sub>	Supply	Supply voltage input (1.8V) for analog section
A12, A56, A60, A63, B10, B11, B12, B13, B15, B16, B45, B49, B53	AV <sub>DD12</sub>		Supply voltage input (1.2V) for analog section
A25, A30, B39	DV <sub>DD12</sub>		Supply voltage input (1.2V) for digital section
A41, B24, B27, B31, B36, B43	DV <sub>DD18</sub>		Supply voltage input (1.8V) for digital section and all digital I/O
EP	GND		Exposed pad: Common ground pin for digital and analog sections
ADC Analog Input Pins			
B54	A <sub>IN</sub> <sup>+</sup>	Analog Input	Differential analog input (+)
A64	A <sub>IN</sub> <sup>-</sup>		Differential analog input (-)
A21	CLK <sup>+</sup>		Differential clock input (+)
B17	CLK <sup>-</sup>		Differential clock input (-)
Reference Pins <sup>(1)</sup>			
A57, B46	REF <sup>+</sup>	Analog Output	Differential reference voltage (+)
A58, B47	REF <sup>-</sup>		Differential reference voltage (-)
SENSE, Bandgap and Common-Mode Voltage Pins			
B48	SENSE	Analog Input	Analog input full-scale range selection. See Table 4-2 for SENSE voltage settings.
A59	V <sub>BG</sub>	Analog Output	Internal bandgap output voltage. Connect a decoupling capacitor (2.2 μF)
A55	V <sub>CM</sub>		Common-mode output voltage for analog input signal. Connect a decoupling capacitor (0.1 μF) <sup>(2)</sup>
Digital I/O Pins			
B18	ADR0	Digital Input	SPI address selection pin (A0 bit). Tie to GND or DV <sub>DD18</sub> <sup>(3)</sup>
A23	SLAVE		Not used. Tie to GND <sup>(9)</sup>
B19	SYNC	Digital Input/Output	Not used. Leave this pin floating <sup>(9)</sup>
B21	RESET	Digital Input	Reset control input: <b>High:</b> Normal operating mode <b>Low:</b> Reset mode <sup>(4)</sup>
A26	CAL	Digital Output	Calibration status flag digital output: <b>High:</b> Calibration is complete <b>Low:</b> Calibration is not complete <sup>(5)</sup>
B22	DCLK <sup>+</sup>		<b>LVDS:</b> Differential digital clock output (+) <b>CMOS:</b> Digital clock output <sup>(6)</sup>
A27	DCLK <sup>-</sup>		<b>LVDS:</b> Differential digital clock output (-) <b>CMOS:</b> Unused (leave floating)

# MCP37220-200 AND MCP37D20-200

**TABLE 1-1: PIN FUNCTION TABLE FOR VTLA-124 (CONTINUED)**

Pin No.	Name	I/O Type	Description
ADC Output Pins <sup>(7)</sup>			
B26	Q0/Q0-	Digital Output	Digital data output: CMOS = Q0 DDR LVDS = Q0-
A31	Q1/Q0+		Digital data output: CMOS = Q1 DDR LVDS = Q0+
B30	Q2/Q1-		Digital data output: CMOS = Q2 DDR LVDS = Q1-
A38	Q3/Q1+		Digital data output: CMOS = Q3 DDR LVDS = Q1+
A39	Q4/Q2-		Digital data output: CMOS = Q4 DDR LVDS = Q2-
B32	Q5/Q2+		Digital data output: CMOS = Q5 DDR LVDS = Q2+
A40	Q6/Q3-		Digital data output: CMOS = Q6 DDR LVDS = Q3-
B33	Q7/Q3+		Digital data output: CMOS = Q7 DDR LVDS = Q3+
B34	Q8/Q4-		Digital data output: CMOS = Q8 DDR LVDS = Q4-
A42	Q9/Q4+		Digital data output: CMOS = Q9 DDR LVDS = Q4+
B35	Q10/Q5-		Digital data output: CMOS = Q10 DDR LVDS = Q5-
A43	Q11/Q5+		Digital data output: CMOS = Q11 DDR LVDS = Q5+
A44	Q12/Q6-		Digital data output: CMOS = Q12 DDR LVDS = Q6-
B37	Q13/Q6+		Digital data output: CMOS = Q13 DDR LVDS = Q6+
B38	WCK/ OVR+ (OVR)		<b>OVR:</b> Input overrange indication digital output <sup>(8)</sup> <b>WCK:</b> - <b>MCP37220:</b> No output - <b>MCP37D20:</b> Word clock synchronizes with digital output in I/Q data mode
A45	WCK/OVR- (WCK)		
SPI Interface Pins			
A53	SDIO	Digital Input/ Output	SPI data input/output
A54	SCLK	Digital Input	SPI serial clock input
B44	$\overline{\text{CS}}$		SPI Chip Select input

# MCP37220-200 AND MCP37D20-200

**TABLE 1-1: PIN FUNCTION TABLE FOR VTLA-124 (CONTINUED)**

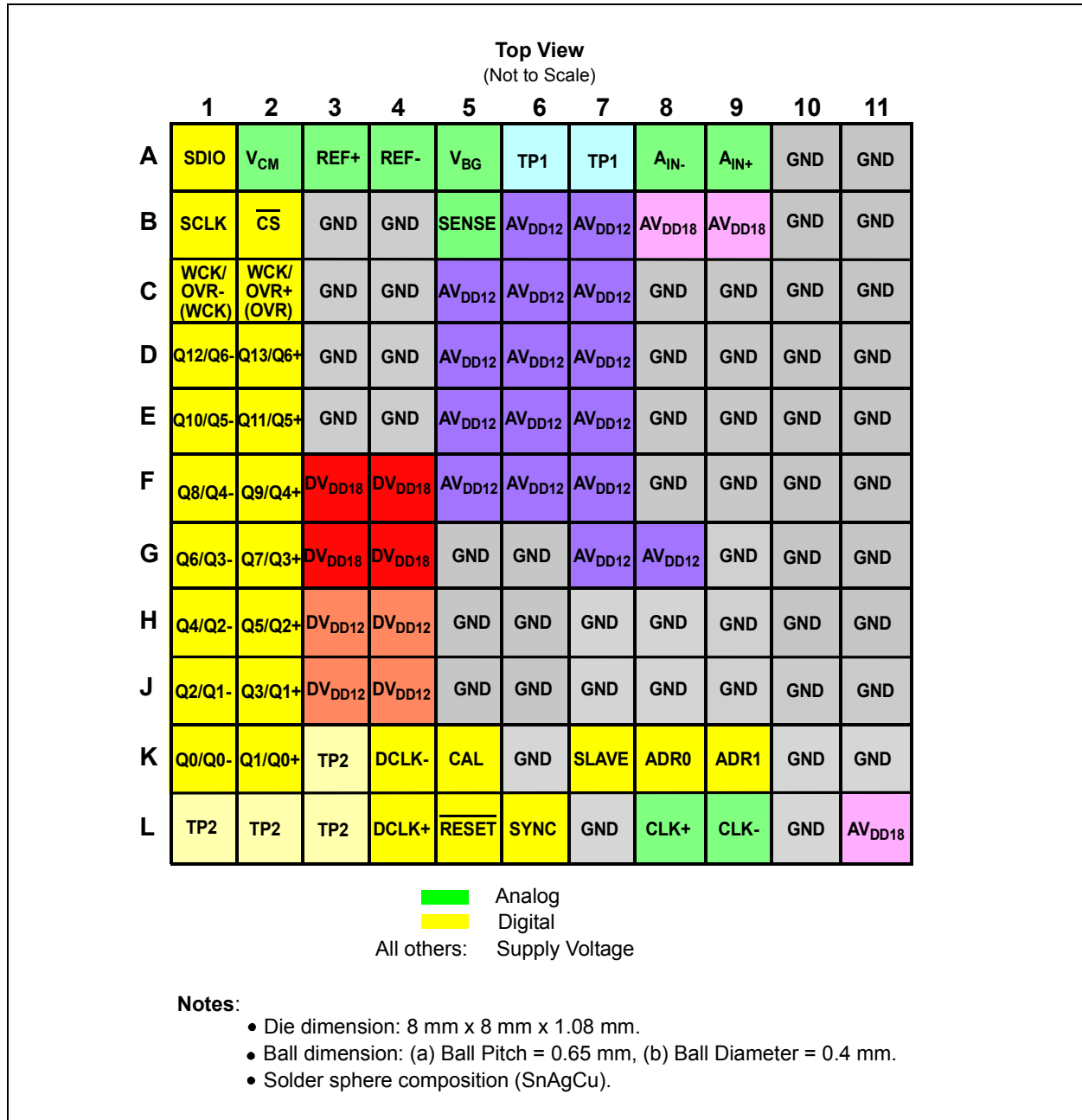
Pin No.	Name	I/O Type	Description
<b>Not Connected Pins</b>			
A1, A3 - A7, A8 - A11, A13 - A20, A32 - A37, A46 - A52, A61 - A62, A66 - A68, B2 - B9, B14, B28, B29, B40, B41, B42, B50 - B51, B55, B56	NC		These pins can be tied to ground or left floating.
<b>Pins that need to be grounded</b>			
A24, A64, B20, B54	GND		These pins are not supply pins, but need to be tied to ground.
<b>Output Test Pins</b>			
A28 - A29, B23, B25	TP	Digital Output	Output test pins. Do not use. Always leave these pins floating. Do not tie to ground or supply.

**Notes:**

- These pins are for the internal reference voltage output. They should not be driven. External decoupling circuit is required. See [Section 4.3.3 “Decoupling Circuits for Internal Voltage Reference and Bandgap Output”](#) for details.
- When  $V_{CM}$  output is used for the common-mode voltage of analog inputs (i.e. by connecting to the center-tap of a balun),  $V_{CM}$  pin should be decoupled with a 0.1  $\mu$ F capacitor.
- ADR1 (for A1 bit) is internally bonded to GND ('0'). If ADR0 is dynamically controlled, ADR0 must be held constant while  $\overline{CS}$  is “Low”.
- The device is in Reset mode while this pin stays “Low”. On the rising edge of  $\overline{RESET}$ , the device exits the Reset mode, initializes all internal user registers to default values and begins power-up calibration.
- CAL pin stays “Low” at power-up until the first power-up calibration is completed. When the first calibration has completed, this pin has “High” output. It stays “High” until the internal calibration is restarted by hardware or a Soft Reset command. In Reset mode, this pin is “Low”. In Standby and Shutdown modes, this pin will maintain the prior condition.
- The phase of DCLK relative to the data output bits may be adjusted depending on the operating mode. This is controlled differently depending on the configuration of the digital signal post-processing (DSPP) and PLL (or DLL). See also Addresses 0x52, 0x64 and 0x6D ([Registers 5-7](#), [5-22](#) and [5-28](#)) for more details.
- DDR LVDS:** Two data bits are multiplexed onto each differential output pair. The output pins shown here are for the “Even bit first” setting, which is the default setting of OUTPUT\_MODE<1:0> in Address 0x62 ([Register 5-20](#)). The even data bits (Q0, Q2, Q4, Q6, Q8, Q10, Q12) appear when DCLK+ is “High”. The odd data bits (Q1, Q3, Q5, Q7, Q9, Q11, Q13) appear when DCLK+ is “Low”. See Addresses 0x65 ([Register 5-23](#)) and 0x68 ([Register 5-26](#)) for output polarity control. See [Figure 2-2](#) for LVDS output timing diagrams.
- OVR:** OVR will be held “High” when analog input overrange is detected. Digital signal post-processing (DSPP) will cause OVR to assert early relative to the output data. See [Figure 2-2](#) for LVDS timing of these bits.  
**WCK:** Available for the I/Q output mode only in the MCP37D20. WCK is normally “Low” in I/Q output mode, and “High” when it outputs in-phase (I) data.  
**(a) MCP37220 and MCP37D20 operating outside I/Q output mode:** WCK/OVR+ is OVR and WCK/OVR- is logic '0' (not used). In DDR LVDS output mode, the rising edge of DCLK+ is OVR.  
**(b) I/Q output mode in the MCP37D20:** In CMOS output mode, WCK/OVR+ is OVR and WCK/OVR- is WCK. WCK is synchronized to in-phase (I) data. In DDR LVDS output mode, WCK/OVR+ and WCK/OVR- are multiplexed. The rising edge of DCLK+ is OVR and the falling edge is WCK.
- This pin function is not released yet.



# MCP37220-200 AND MCP37D20-200



**FIGURE 1-2:** TFBGA-121 Package. Decoupling capacitors for reference pins and V<sub>BG</sub> are embedded in the package.

# MCP37220-200 AND MCP37D20-200

**TABLE 1-2: PIN FUNCTION TABLE FOR TFBGA-121**

Ball No.	Name	I/O Type	Description
A1	SDIO	Digital Input/Output	SPI data input/output
A2	V <sub>CM</sub>	Analog Output	Common-mode output voltage for analog input signal Connect a decoupling capacitor (0.1 $\mu$ F) <sup>(1)</sup>
A3	REF+		Differential reference voltage (+/-). Decoupling capacitors are embedded in the TFBGA package. Leave these pins floating.
A4	REF-		
A5	V <sub>BG</sub>		Internal bandgap output voltage A decoupling capacitor (2.2 $\mu$ F) is embedded in the TFBGA package. Leave this pin floating.
A6	TP1	Analog Output	Analog test pins. Leave these pins floating.
A7			
A8	A <sub>IN-</sub>	Analog Input	Differential analog input (-)
A9	A <sub>IN+</sub>		Differential analog input (+)
A10	GND	Supply	Common ground for analog and digital sections
A11			
B1	SCLK	Digital Input	SPI serial clock input
B2	$\overline{\text{CS}}$		SPI chip select input
B3	GND	Supply	Common ground for analog and digital sections
B4			
B5	SENSE	Analog Input	Analog input range selection. See Table 4-2 for SENSE voltage settings.
B6	AV <sub>DD12</sub>	Supply	Supply voltage input (1.2V) for analog section
B7			
B8	AV <sub>DD18</sub>		Supply voltage input (1.8V) for analog section
B9			
B10	GND	Supply	Common ground for analog and digital sections
B11			
C1	WCK/OVR- (WCK)	Digital Output	<b>OVR:</b> Input overrange indication digital output <sup>(2)</sup> <b>WCK:</b> <ul style="list-style-type: none"> <li>- <b>MCP37220:</b> No output</li> <li>- <b>MCP37D20:</b> Word clock synchronizes with digital output in I/Q data mode</li> </ul>
C2	WCK/OVR+ (OVR)		
C3	GND	Supply	Common ground for analog and digital sections
C4			
C5			
C6			
C7			
C8	GND		Common ground pin for analog and digital sections
C9			
C10			
C11			

# MCP37220-200 AND MCP37D20-200

**TABLE 1-2: PIN FUNCTION TABLE FOR TFBGA-121 (CONTINUED)**

Ball No.	Name	I/O Type	Description
D1	Q12/Q6-	Digital Output	Digital data output <sup>(3)</sup> CMOS = Q12 DDR LVDS = Q6-
D2	Q13/Q6+		Digital data output <sup>(3)</sup> CMOS = Q13 DDR LVDS = Q6+
D3	GND	Supply	Common ground for analog and digital sections
D4			
D5	AV <sub>DD12</sub>	Supply	Supply voltage input (1.2V) for analog section
D6			
D7			
D8	GND	Supply	Common ground for analog and digital sections
D9			
D10			
D11			
E1	Q10/Q5-	Digital Output	Digital data output <sup>(3)</sup> CMOS = Q10 DDR LVDS = Q5-
E2	Q11/Q5+		Digital data output <sup>(3)</sup> CMOS = Q11 DDR LVDS = Q5+
E3	GND	Supply	Common ground for analog and digital sections
E4			
E5	AV <sub>DD12</sub>	Supply	Supply voltage input (1.2V) for analog section
E6			
E7			
E8	GND	Supply	Common ground for analog and digital sections
E9			
E10			
E11			
F1	Q8/Q4-	Digital Output	Digital data output <sup>(3)</sup> CMOS = Q8 DDR LVDS = Q4-
F2	Q9/Q4+		Digital data output <sup>(3)</sup> CMOS = Q9 DDR LVDS = Q4+
F3	DV <sub>DD18</sub>	Supply	Supply voltage input (1.8V) for digital section. All digital input pins are driven by the same DV <sub>DD18</sub> potential.
F4			
F5	AV <sub>DD12</sub>	Supply	Supply voltage input (1.2V) for analog section
F6			
F7			
F8	GND	Supply	Common ground for analog and digital sections
F9			
F10			
F11			

# MCP37220-200 AND MCP37D20-200

**TABLE 1-2: PIN FUNCTION TABLE FOR TFBGA-121 (CONTINUED)**

Ball No.	Name	I/O Type	Description
G1	Q6/Q3-	Digital Output	Digital data output <sup>(3)</sup> CMOS = Q6 DDR LVDS = Q3-
G2	Q7/Q3+		Digital data output <sup>(3)</sup> CMOS = Q7 DDR LVDS = Q3+
G3	DV <sub>DD18</sub>	Supply	Supply voltage input (1.8V) for digital section. All digital input pins are driven by the same DV <sub>DD18</sub> potential
G4			Common ground for analog and digital sections
G5	GND		
G6			
G7	AV <sub>DD12</sub>	Supply	Supply voltage input (1.2V) for analog section
G8	GND		Common ground for analog and digital sections
G9			
G10			
G11			
H1	Q4/Q2-	Digital Output	Digital data output <sup>(3)</sup> CMOS = Q4 DDR LVDS = Q2-
H2	Q5/Q2+		Digital data output <sup>(3)</sup> CMOS = Q5 DDR LVDS = Q2+
H3	DV <sub>DD12</sub>	Supply	Supply voltage input (1.2V) for digital section
H4			Common ground for analog and digital sections
H5	GND		
H6			
H7			
H8			
H9			
H10			
H11			
J1	Q2/Q1-	Digital Output	Digital data output <sup>(3)</sup> CMOS = Q2 DDR LVDS = Q1-
J2	Q3/Q1+		Digital data output <sup>(3)</sup> CMOS = Q3 DDR LVDS = Q1+
J3	DV <sub>DD12</sub>	Supply	DC supply voltage input pin for digital section (1.2V)
J4	GND		Common ground for analog and digital sections
J5			
J6			
J7			
J8			
J9			
J10			
J11			

# MCP37220-200 AND MCP37D20-200

**TABLE 1-2: PIN FUNCTION TABLE FOR TFBGA-121 (CONTINUED)**

Ball No.	Name	I/O Type	Description
K1	Q0/Q0-	Digital Output	Digital data output <sup>(3)</sup> CMOS = Q0 DDR LVDS = Q0-
K2	Q1/Q0+		Digital data output <sup>(3)</sup> CMOS = Q1 DDR LVDS = Q0+
K3	TP2		Output test pin. Do not use. Do not tie to ground or supply. Always leave this pin floating.
K4	DCLK-		<b>LVDS:</b> Differential digital clock output (-) <b>CMOS:</b> Unused (leave floating)
K5	CAL		Calibration status flag digital output <sup>(4)</sup> <b>High:</b> Calibration is complete <b>Low:</b> Calibration is not complete
K6	GND	Supply	Common ground pin for analog and digital sections
K7	SLAVE	Digital Input	Not used. Tie this pin to GND <sup>(8)</sup>
K8	ADR0		SPI address selection pin (A0 bit). Tie to GND or DV <sub>DD18</sub> <sup>(5)</sup>
K9	ADR1		SPI address selection pin (A1 bit). Tie to GND or DV <sub>DD18</sub> <sup>(5)</sup>
K10	GND	Supply	Common ground for analog and digital sections
K11			
L1	TP2	Digital Output	Output test pins. Do not use. Do not tie to ground or supply. Always leave these pins floating.
L2			
L3			
L4	DCLK+		<b>LVDS:</b> Differential digital clock output (+) <b>CMOS:</b> Digital clock output <sup>(6)</sup>
L5	RESET	Digital Input	Reset control input: <b>High:</b> Normal operating mode <b>Low:</b> Reset mode <sup>(7)</sup>
L6	SYNC	Digital Input/ Output	Not used. Leave this pin floating <sup>(8)</sup>
L7	GND	Supply	Common ground for analog and digital sections
L8	CLK+	Analog Input	Differential clock input (+)
L9	CLK-		Differential clock input (-)
L10	GND	Supply	Common ground for analog and digital sections
L11	AV <sub>DD18</sub>	Analog Input	Supply voltage input (1.8V) for analog section

# MCP37220-200 AND MCP37D20-200

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## Notes:

1. When  $V_{CM}$  output is used for the common-mode voltage of analog inputs (i.e. by connecting to the center-tap of a balun), the  $V_{CM}$  pin should be decoupled with a 0.1  $\mu F$  capacitor.
2. **OVR:** OVR will be held “High” when analog input overrange is detected. Digital signal post-processing (DSPP) will cause OVR to assert early relative to the output data. See [Figure 2-2](#) for LVDS timing of these bits.  
**WCK:** Available for the I/Q output mode only in the MCP37D20. In the I/Q output mode, WCK is normally “Low”, and “High” when it outputs in-phase (I) data.  
**(a) MCP37220 and MCP37D20 operating outside I/Q output mode:** WCK/OVR+ is OVR and WCK/OVR- is logic ‘0’ (not used). In DDR LVDS output mode, the rising edge of DCLK+ is OVR.  
**(b) I/Q output mode in the MCP37D20:** In CMOS output mode, WCK/OVR+ is OVR and WCK/OVR- is WCK. WCK is synchronized to in-phase (I) data. In DDR LVDS output mode, WCK/OVR+ and WCK/OVR- are multiplexed. The rising edge of DCLK+ is OVR and the falling edge is WCK.
3. **DDR LVDS:** Two data bits are multiplexed onto each differential output pair. The output pins shown here are for the “Even bit first” setting, which is the default setting of OUTPUT\_MODE<1:0> in Address 0x62 ([Register 5-20](#)). The even data bits (Q0, Q2, Q4, Q6, Q8, Q10, Q12) appear when DCLK+ is “High”. The odd data bits (Q1, Q3, Q5, Q7, Q9, Q11, Q13) appear when DCLK+ is “Low”. See Addresses 0x65 ([Register 5-23](#)) and 0x68 ([Register 5-26](#)) for output polarity control. See [Figure 2-2](#) for LVDS output timing diagram.
4. CAL pin stays “Low” at power-up until the first power-up calibration is completed. When the first calibration has completed, this pin has “High” output. It stays “High” until the internal calibration is restarted by hardware or a Soft Reset command. In Reset mode, this pin is “Low”. In Standby and Shutdown modes this pin will maintain the prior condition.
5. If the SPI address is dynamically controlled, the Address pin must be held constant while  $\overline{CS}$  is “Low”.
6. The phase of DCLK relative to the data output bits may be adjusted depending on the operating mode. This is controlled differently depending on the configuration of the digital signal post-processing (DSPP) and PLL (or DLL). See also Addresses 0x52, 0x64 and 0x6D ([Registers 5-7, 5-22 and 5-28](#)) for more details.
7. The device is in Reset mode while this pin stays “Low”. On the rising edge of RESET, the device exits the Reset mode, initializes all internal user registers to default values, and begins power-up calibration.
8. This pin function is not released yet.

# MCP37220-200 AND MCP37D20-200

## 2.0 ELECTRICAL CHARACTERISTICS

### 2.1 Absolute Maximum Ratings †

Analog and Digital Supply Voltage ( $AV_{DD12}$ , $DV_{DD12}$ )	-0.3V to 1.32V
Analog and Digital Supply Voltage ( $AV_{DD18}$ , $DV_{DD18}$ )	-0.3V to 1.98V
All Inputs and Outputs with respect to GND	-0.3V to $AV_{DD18} + 0.3V$
Differential Input Voltage	$ AV_{DD18} - GND $
Current at Input Pins	$\pm 2$ mA
Current at Output and Supply Pins	$\pm 250$ mA
Storage Temperature	-65°C to +150°C
Ambient Temperature with Power Applied ( $T_A$ )	-55°C to +125°C
Maximum Junction Temperature ( $T_J$ )	+150°C
ESD Protection on all Pins	2 kV HBM
Solder Reflow Profile	See Microchip Application Note AN233 (DS00233)

† **Notice:** Stresses above those listed under “Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

### 2.2 Electrical Specifications

**TABLE 2-1: ELECTRICAL CHARACTERISTICS**

<b>Electrical Specifications:</b> Unless otherwise specified, all parameters apply for T <sub>A</sub> = -40°C to +85°C, AV <sub>DD18</sub> = DV <sub>DD18</sub> = 1.8V, AV <sub>DD12</sub> = DV <sub>DD12</sub> = 1.2V, GND = 0V, SENSE = AV <sub>DD12</sub> , Differential Analog Input (A <sub>IN</sub> ) = Sine wave with amplitude of -1 dBFS, f <sub>IN</sub> = 70 MHz, Clock Input = 200 MHz, f <sub>S</sub> = 200 Msps, PLL and decimation filters are disabled, Output load: CMOS data pin = 10 pF, LVDS = 100Ω termination, LVDS driver current setting = 3.5 mA, +25°C is applied for typical value.						
Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
Power Supply Requirements						
Analog Supply Voltage	AV <sub>DD18</sub>	1.71	1.8	1.89	V	
	AV <sub>DD12</sub>	1.14	1.2	1.26	V	
Digital Supply Voltage	DV <sub>DD18</sub>	1.71	1.8	1.89	V	Note 1
	DV <sub>DD12</sub>	1.14	1.2	1.26	V	
Analog Supply Current						
Analog Supply Current during Conversion	I <sub>DD_A18</sub>	—	0.03	0.1	mA	at AV <sub>DD18</sub> Pin
	I <sub>DD_A12</sub>	—	141	159	mA	at AV <sub>DD12</sub> Pin
Digital Supply Current						
Digital Supply Current during Conversion	I <sub>DD_D12</sub>	—	72	109	mA	at DV <sub>DD12</sub> Pin
Digital I/O Current in CMOS Output Mode	I <sub>DD_D18</sub>	—	27	—	mA	at DV <sub>DD18</sub> Pin DCLK = 100 MHz
Digital I/O Current in LVDS Mode	I <sub>DD_D18</sub>	Measured at DV <sub>DD18</sub> Pin				
		—	50	75	mA	3.5 mA mode
			35	—	mA	1.8 mA mode
			62			5.4 mA mode
Supply Current during Power-Saving Modes						
During Standby Mode	I <sub>STANDBY_AN</sub>	—	45	—	mA	Address 0x00<4:3> = 1, 1 <sup>(2)</sup>
	I <sub>STANDBY_DIG</sub>	—	29	—		
During Shutdown Mode	I <sub>DD_SHDN</sub>	—	20	—	mA	Address 0x00<7,0> = 1, 1 <sup>(3)</sup>

# MCP37220-200 AND MCP37D20-200

**TABLE 2-1: ELECTRICAL CHARACTERISTICS (CONTINUED)**

<b>Electrical Specifications:</b> Unless otherwise specified, all parameters apply for T <sub>A</sub> = -40°C to +85°C, AV <sub>DD18</sub> = DV <sub>DD18</sub> = 1.8V, AV <sub>DD12</sub> = DV <sub>DD12</sub> = 1.2V, GND = 0V, SENSE = AV <sub>DD12</sub> , Differential Analog Input (A <sub>IN</sub> ) = Sine wave with amplitude of -1 dBFS, f <sub>IN</sub> = 70 MHz, Clock Input = 200 MHz, f <sub>S</sub> = 200 Msps, PLL and decimation filters are disabled, Output load: CMOS data pin = 10 pF, LVDS = 100Ω termination, LVDS driver current setting = 3.5 mA, +25°C is applied for typical value.						
Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
<b>PLL Circuit</b>						
PLL Circuit Current	I <sub>DD_PLL</sub>	—	17	—	mA	PLL enabled. Included in analog supply current specification.
<b>Total Power Dissipation<sup>(4)</sup></b>						
Power Dissipation during Conversion, excluding Digital I/O	P <sub>DISS_ADC</sub>	—	256	—	mW	
Total Power Dissipation during Conversion with CMOS Output Mode	P <sub>DISS_CMOS</sub>	—	304	—	mW	f <sub>S</sub> = 200 Msps, DCLK = 100 MHz
Total Power Dissipation during Conversion with LVDS Output Mode	P <sub>DISS_LVDS</sub>	—	346	—	mW	3.5 mA mode
			319			1.8 mA mode
			367			5.4 mA mode
During Standby Mode	P <sub>DISS_STANDBY</sub>	—	89	—	mW	Address 0x00<4:3> = 1, 1 <sup>(2)</sup>
During Shutdown Mode	P <sub>DISS_SHDN</sub>	—	24	—	mW	Address 0x00<7,0> = 1, 1 <sup>(3)</sup>
<b>Power-On Reset (POR) Voltage</b>						
Threshold Voltage	V <sub>POR</sub>	—	800	—	mV	Applicable to AV <sub>DD12</sub> only (POR tracks AV <sub>DD12</sub> )
Hysteresis	V <sub>POR_HYST</sub>	—	40	—	mV	
<b>SENSE Input<sup>(5,7,13)</sup></b>						
SENSE Input Voltage	V <sub>SENSE</sub>	GND	—	AV <sub>DD12</sub>	V	V <sub>SENSE</sub> selects reference
SENSE Pin Input Resistance	R <sub>IN_SENSE</sub>	—	694	—	Ω	V <sub>SENSE</sub> = 0.8V
		—	154.8	—	kΩ	V <sub>SENSE</sub> = 1.2V
Current Sink into SENSE Pin	I <sub>SENSE</sub>	—	360	—	μA	V <sub>SENSE</sub> = 0.8V
		—	4.2	—	μA	V <sub>SENSE</sub> = 1.2V
<b>Reference and Common-Mode Voltages</b>						
Internal Reference Voltage <sup>(7,8)</sup>	V <sub>REF</sub>	—	0.4	—	V	V <sub>SENSE</sub> = GND
		—	0.8	—		V <sub>SENSE</sub> = AV <sub>DD12</sub>
		—	V <sub>SENSE</sub>	—		400 mV < V <sub>SENSE</sub> < 800 mV
Common-Mode Voltage Output	V <sub>CM</sub>	—	0.55	—	V	Available at V <sub>CM</sub> pin
Bandgap Voltage Output	V <sub>BG</sub>	—	0.55	—	V	Available at V <sub>BG</sub> pin



# MCP37220-200 AND MCP37D20-200

**TABLE 2-1: ELECTRICAL CHARACTERISTICS (CONTINUED)**

<b>Electrical Specifications:</b> Unless otherwise specified, all parameters apply for $T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$ , $AV_{DD18} = DV_{DD18} = 1.8\text{V}$ , $AV_{DD12} = DV_{DD12} = 1.2\text{V}$ , $\text{GND} = 0\text{V}$ , $\text{SENSE} = AV_{DD12}$ , Differential Analog Input ( $A_{IN}$ ) = Sine wave with amplitude of -1 dBFS, $f_{IN} = 70\text{ MHz}$ , Clock Input = 200 MHz, $f_S = 200\text{ Msp}$ s, PLL and decimation filters are disabled, Output load: CMOS data pin = 10 pF, LVDS = 100 $\Omega$ termination, LVDS driver current setting = 3.5 mA, $+25^{\circ}\text{C}$ is applied for typical value.						
Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
<b>Analog Inputs</b>						
Full-Scale Differential Analog Input Range <sup>(5,7)</sup>	$A_{FS}$	—	0.9	—	$V_{P-P}$	$V_{SENSE} = \text{GND}$
		—	1.8	—		$V_{SENSE} = AV_{DD12}$
		—	$2.25 \times V_{SENSE}$	—		$400\text{ mV} < V_{SENSE} < 800\text{ mV}$
Analog Input Bandwidth	$f_{IN\_3dB}$	—	650	—	MHz	$A_{IN} = -3\text{ dBFS}$
Differential Input Capacitance	$C_{IN}$	—	1.6	—	pF	<a href="#">Note 5</a> , <a href="#">Note 9</a>
Analog Input Leakage Current ( $A_{IN+}$ , $A_{IN-}$ pins)	$I_{LI\_AH}$	—	—	+50	$\mu\text{A}$	$V_{IH} = AV_{DD12}$
	$I_{LI\_AL}$	-50	—	—	$\mu\text{A}$	$V_{IL} = \text{GND}$
<b>ADC Conversion Rate</b>						
Conversion Rate	$f_S$	—	—	200	Msp	Tested at 200 Msp
<b>Clock Inputs (CLK+, CLK-)<sup>(10)</sup></b>						
Clock Input Frequency	$f_{CLK}$	—	—	250	MHz	<a href="#">Note 5</a>
Differential Input Voltage	$V_{CLK\_IN}$	300	—	800	mV <sub>P-P</sub>	<a href="#">Note 5</a>
Clock Jitter	$CLK_{JITTER}$	—	175	—	fS <sub>RMS</sub>	<a href="#">Note 5</a>
Clock Input Duty Cycle <sup>(5)</sup>		49	50	51	%	Duty cycle correction disabled
		30	50	70	%	Duty cycle correction enabled
Input Leakage Current at CLK input pin	$I_{LI\_CLKH}$	—	—	+110	$\mu\text{A}$	$V_{IH} = AV_{DD12}$
	$I_{LI\_CLKL}$	-20	—	—	$\mu\text{A}$	$V_{IL} = \text{GND}$
<b>Converter Accuracy<sup>(6)</sup></b>						
ADC Resolution (with no missing code)		—	—	14	bits	
Offset Error		—	$\pm 15$	$\pm 45$	LSb	
Gain Error	$G_{ER}$	—	$\pm 0.5$	—	% of FS	
Integral Nonlinearity	INL	—	$\pm 1.5$	—	LSb	
Differential Nonlinearity	DNL	—	$\pm 0.4$	—	LSb	
Analog Input Common-Mode Rejection Ratio	$CMRR_{DC}$	—	70	—	dB	DC measurement

# MCP37220-200 AND MCP37D20-200

**TABLE 2-1: ELECTRICAL CHARACTERISTICS (CONTINUED)**

<b>Electrical Specifications:</b> Unless otherwise specified, all parameters apply for $T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$ , $AV_{DD18} = DV_{DD18} = 1.8\text{V}$ , $AV_{DD12} = DV_{DD12} = 1.2\text{V}$ , $\text{GND} = 0\text{V}$ , $\text{SENSE} = AV_{DD12}$ , Differential Analog Input ( $A_{IN}$ ) = Sine wave with amplitude of -1 dBFS, $f_{IN} = 70\text{ MHz}$ , Clock Input = 200 MHz, $f_S = 200\text{ Msp}$ s, PLL and decimation filters are disabled, Output load: CMOS data pin = 10 pF, LVDS = 100 $\Omega$ termination, LVDS driver current setting = 3.5 mA, $+25^{\circ}\text{C}$ is applied for typical value.						
Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
<b>Dynamic Accuracy<sup>(6,14)</sup></b>						
Spurious Free Dynamic Range	SFDR	82	96	—	dBc	$f_{IN} = 15\text{ MHz}$
		—	80	—	dBc	$f_{IN} = 70\text{ MHz}$
Signal-to-Noise Ratio (for all resolutions)	SNR	66.1	67.8	—	dBFS	$f_{IN} = 15\text{ MHz}$
		—	67.2	—		$f_{IN} = 70\text{ MHz}$
Effective Number of Bits (ENOB) <sup>(11)</sup>	ENOB	—	10.9	—	bits	$f_{IN} = 15\text{ MHz}$
		—	10.9	—		$f_{IN} = 70\text{ MHz}$
Total Harmonic Distortion (first 13 harmonics)	THD	83	89	—	dBc	$f_{IN} = 15\text{ MHz}$
			81	—	dBc	$f_{IN} = 70\text{ MHz}$
Worst Second or Third Harmonic Distortion	HD2 or HD3	—	95.8	—	dBc	$f_{IN} = 15\text{ MHz}$
		—	82	—	dBc	$f_{IN} = 70\text{ MHz}$
Two-Tone Intermodulation Distortion $f_{IN1} = 15\text{ MHz}$ , $f_{IN2} = 17\text{ MHz}$	IMD	—	92.7	—	dBc	$A_{IN} = -7\text{ dBFS}$ , with two input frequencies
<b>Digital Logic Input and Output (Except LVDS Output)</b>						
Schmitt Trigger High-Level Input Voltage	$V_{IH}$	0.7 $DV_{DD18}$	—	$DV_{DD18}$	V	
Schmitt Trigger Low-Level Input Voltage	$V_{IL}$	GND	—	0.3 $DV_{DD18}$	V	
Hysteresis of Schmitt Trigger Inputs (All digital inputs)	$V_{HYST}$	—	0.05 $DV_{DD18}$	—	V	
Low-Level Output Voltage	$V_{OL}$	—	—	0.3	V	$I_{OL} = -3\text{ mA}$ , all digital I/O pins
High-Level Output Voltage	$V_{OH}$	$DV_{DD18} - 0.5$	1.8	—	V	$I_{OL} = +3\text{ mA}$ , all digital I/O pins
<b>Digital Data Output (CMOS Mode)</b>						
Maximum External Load Capacitance	$C_{Load}$	—	10	—	pF	From output pin to GND
Internal I/O Capacitance	$C_{INT}$	—	4	—	pF	<b>Note 5</b>
<b>Digital Data Output (LVDS Mode)<sup>(5)</sup></b>						
LVDS High-Level Differential Output Voltage	$V_{H\_LVDS}$	200	300	400	mV	100 $\Omega$ differential termination, LVDS bias = 3.5 mA
LVDS Low-Level Differential Output Voltage	$V_{L\_LVDS}$	-400	-300	-200	mV	100 $\Omega$ differential termination, LVDS bias = 3.5 mA

# MCP37220-200 AND MCP37D20-200

**TABLE 2-1: ELECTRICAL CHARACTERISTICS (CONTINUED)**

<b>Electrical Specifications:</b> Unless otherwise specified, all parameters apply for $T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$ , $AV_{DD18} = DV_{DD18} = 1.8\text{V}$ , $AV_{DD12} = DV_{DD12} = 1.2\text{V}$ , $\text{GND} = 0\text{V}$ , $\text{SENSE} = AV_{DD12}$ , Differential Analog Input ( $A_{IN}$ ) = Sine wave with amplitude of -1 dBFS, $f_{IN} = 70\text{ MHz}$ , Clock Input = 200 MHz, $f_S = 200\text{ Msp}$ s, PLL and decimation filters are disabled, Output load: CMOS data pin = 10 pF, LVDS = 100 $\Omega$ termination, LVDS driver current setting = 3.5 mA, $+25^{\circ}\text{C}$ is applied for typical value.						
Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
LVDS Common-Mode Voltage	$V_{CM\_LVDS}$	1	1.15	1.4	V	
Output Capacitance	$C_{INT\_LVDS}$	—	4	—	pF	Internal capacitance from output pin to GND
Differential Load Resistance (LVDS)	$R_{LVDS}$	—	100	—	$\Omega$	Across LVDS output pairs
<b>Input Leakage Current on Digital I/O Pins</b>						
Data Output Pins	$I_{LI\_DH}$	—	—	+1	$\mu\text{A}$	$V_{IH} = DV_{DD18}$
	$I_{LI\_DL}$	-1	—	—	$\mu\text{A}$	$V_{IL} = \text{GND}$
I/O Pins except Data Output Pins	$I_{LI\_DH}$	—	—	+6	$\mu\text{A}$	$V_{IH} = DV_{DD18}$
	$I_{LI\_DL}$	-35	—	—	$\mu\text{A}$	$V_{IL} = \text{GND}^{(12)}$

**Notes:**

- This 1.8V digital supply voltage is used for the digital I/O circuit, including SPI, CMOS and LVDS data output drivers.
- Standby mode: Most of the internal circuits are turned-off except internal reference, clock, bias circuits and SPI interface.
- Shutdown mode: All circuits, including reference and clock, are turned-off except the SPI interface.
- Power dissipation is calculated by using the following equation.
  - During operation:  
 $P_{DISS} = V_{DD18} \times (I_{DD\_A18} + I_{DD\_D18}) + V_{DD12} \times (I_{DD\_A12} + I_{DD\_D12})$ , where  $I_{DD\_D18}$  is the digital I/O current for LVDS or CMOS output.  $V_{DD18} = 1.8\text{V}$  and  $V_{DD12} = 1.2\text{V}$  are used for typical value calculation.
  - During Standby mode:  
 $P_{DISS\_STANDBY} = (I_{STANDBY\_AN} + I_{STANDBY\_DIG}) \times 1.2\text{V}$
  - During Shutdown mode:  
 $P_{DISS\_SHDN} = I_{DD\_SHDN} \times 1.2\text{V}$
- This parameter is ensured by design, but not 100% tested in production.
- This parameter is ensured by characterization, but not 100% tested in production.
- See [Table 4-1](#) for details.
- Differential reference voltage output at REF+/REF- pins:  $V_{REF} = V_{REF+} - V_{REF-}$ .
- Input capacitance refers to the effective capacitance between differential input pin pair.
- See [Figure 4-8](#) for details of clock input circuit.
- $\text{ENOB} = (\text{SINAD} - 1.76)/6.02$ .
- This leakage current is due to internal pull-up resistor.
- $R_{IN\_SENSE}$  is calculated from SENSE pin to virtual ground at 0.55V for  $400\text{ mV} < V_{SENSE} < 800\text{ mV}$ .  
 $R_{SENSE} = (V_{SENSE} - 0.55\text{V})/I_{SENSE}$ .
- Dynamic performance is characterized with  $\text{DIG\_GAIN} \langle 7:0 \rangle = 0011-1000$ .

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**TABLE 2-2: TIMING REQUIREMENTS – LVDS AND CMOS OUTPUTS**

**Electrical Specifications:** Unless otherwise specified, all parameters apply for  $T_A = -40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ ,  $AV_{DD18} = DV_{DD18} = 1.8\text{V}$ ,  $AV_{DD12} = DV_{DD12} = 1.2\text{V}$ ,  $\text{GND} = 0\text{V}$ ,  $\text{SENSE} = AV_{DD12}$ , Differential analog input ( $A_{IN}$ ) = -1 dBFS sine wave,  $f_{IN} = 70\text{ MHz}$ , Clock input = 200 MHz,  $f_S = 200\text{ Msp}$ s, PLL and decimation filters are disabled, Output load: CMOS data pin = 10 pF, LVDS = 100 $\Omega$  termination, LVDS driver current setting = 3.5 mA,  $\text{DCLK\_PHDLY\_DLL}<2:0> = 000$ ,  $+25^{\circ}\text{C}$  is applied for typical value.

Parameters	Symbol	Min.	Typ.	Max.	Units	Conditions
Aperture Delay	$t_A$	—	1	—	ns	<a href="#">Note 1</a>
Out-of-Range Recovery Time	$t_{OVR}$	—	1	—	Clocks	<a href="#">Note 1</a>
Output Clock Duty Cycle		—	50	—	%	<a href="#">Note 1</a>
Pipeline Latency	$T_{\text{LATENCY}}$	—	23	—	Clocks	<a href="#">Note 2</a> , <a href="#">Note 4</a>
<b>System Calibration<sup>(1)</sup></b>						
Power-Up Calibration Time	$T_{\text{PCAL}}$	—	$3 \times 2^{26}$	—	Clocks	First $3 \times 2^{26}$ sample clocks after power-up
Background Calibration Update Rate	$T_{\text{BCAL}}$	—	$2^{30}$	—	Clocks	Per $2^{30}$ sample clocks after $T_{\text{PCAL}}$
RESET Low Time	$T_{\text{RESET}}$	5	—	—	ns	See <a href="#">Figure 2-6</a> for details <sup>(1)</sup>
<b>LVDS Data Output Mode<sup>(1,5)</sup></b>						
Input Clock to Output Clock Propagation Delay	$t_{\text{CPD}}$	—	5.7	—	ns	
Output Clock to Data Propagation Delay	$t_{\text{DC}}$	—	0.5	—	ns	
Input Clock to Output Data Propagation Delay	$t_{\text{PD}}$	—	5.8	—	ns	
<b>CMOS Data Output Mode<sup>(1)</sup></b>						
Input Clock to Output Clock Propagation Delay	$t_{\text{CPD}}$	—	3.8	—	ns	
Output Clock to Data Propagation Delay	$t_{\text{DC}}$	—	0.7	—	ns	
Input Clock to Output Data Propagation Delay	$t_{\text{PD}}$	—	4.5	—	ns	

**Note 1:** This parameter is ensured by design, but not 100% tested in production.

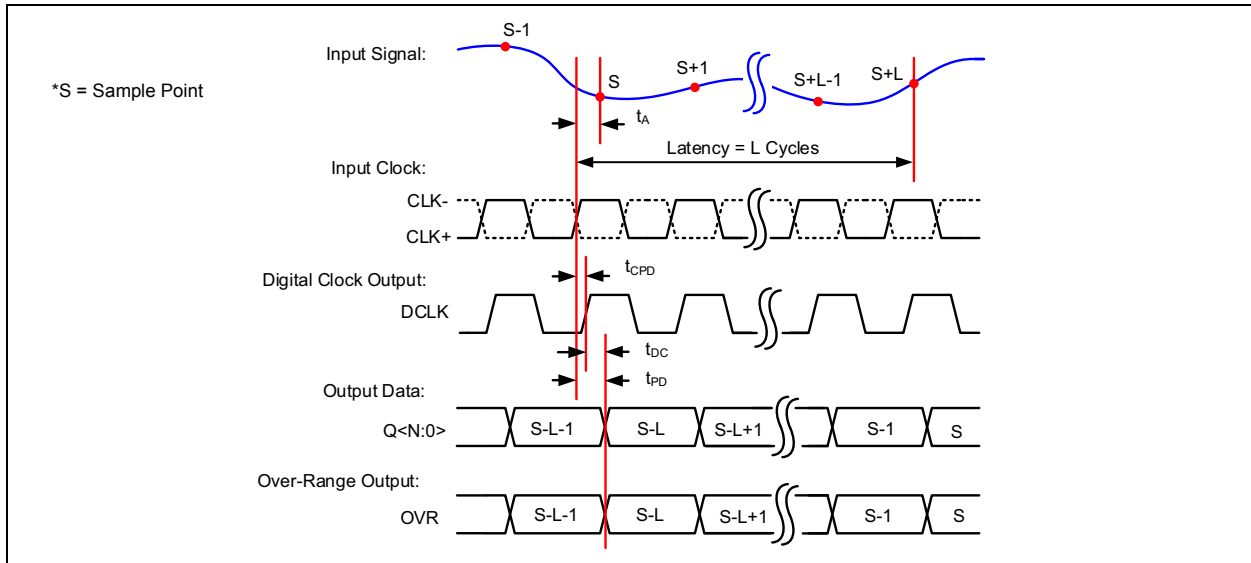
**2:** This parameter is ensured by characterization, but not 100% tested in production.

**3:**  $t_{\text{RISE}}$  = approximately less than 10% of duty cycle.

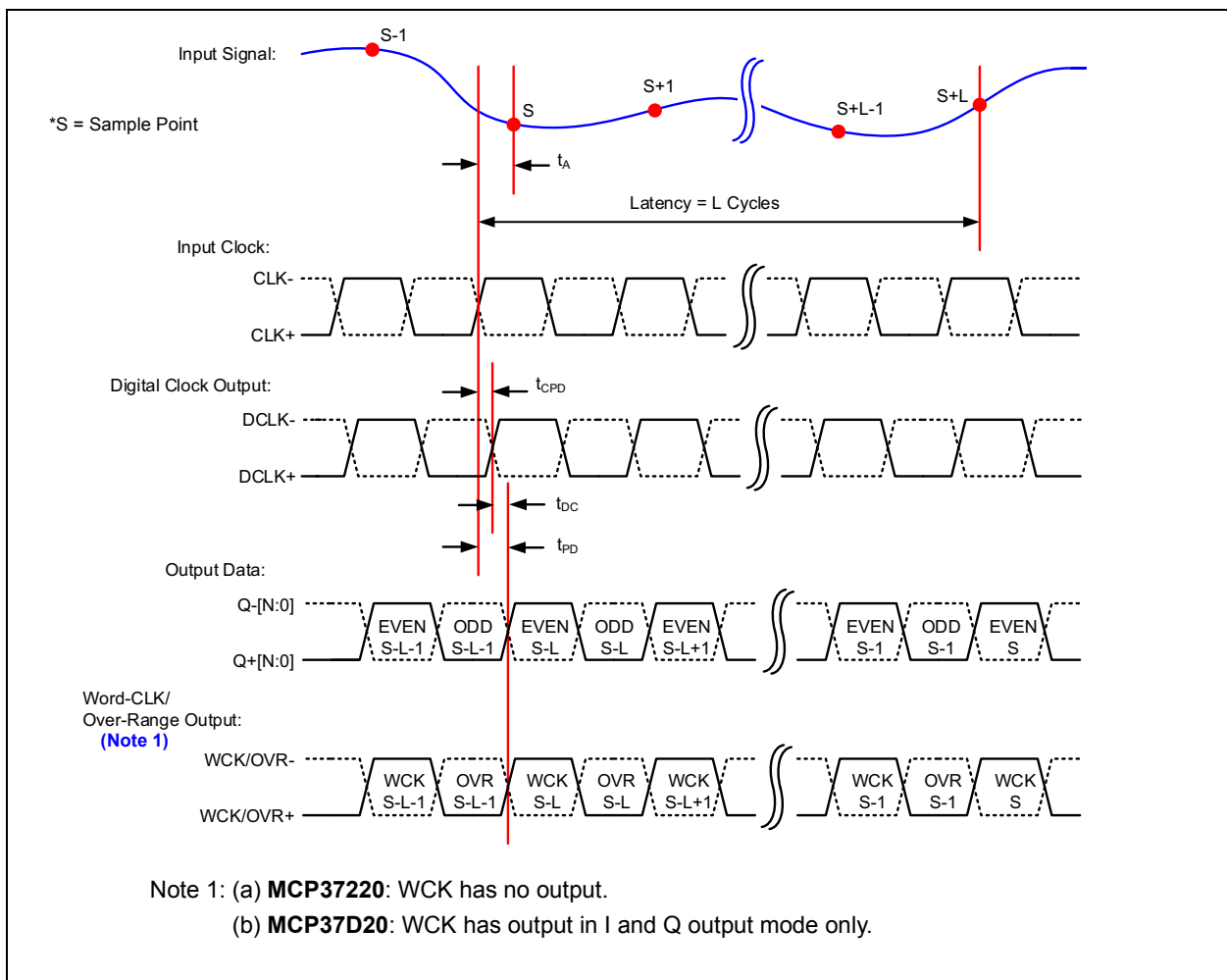
**4:** Output latency is measured without using decimation filter and digital down-converter options.

**5:** The time delay can be adjusted with the  $\text{DCLK\_PHDLY\_DLL}<2:0>$  setting.

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**FIGURE 2-1:** Timing Diagram – CMOS Output.



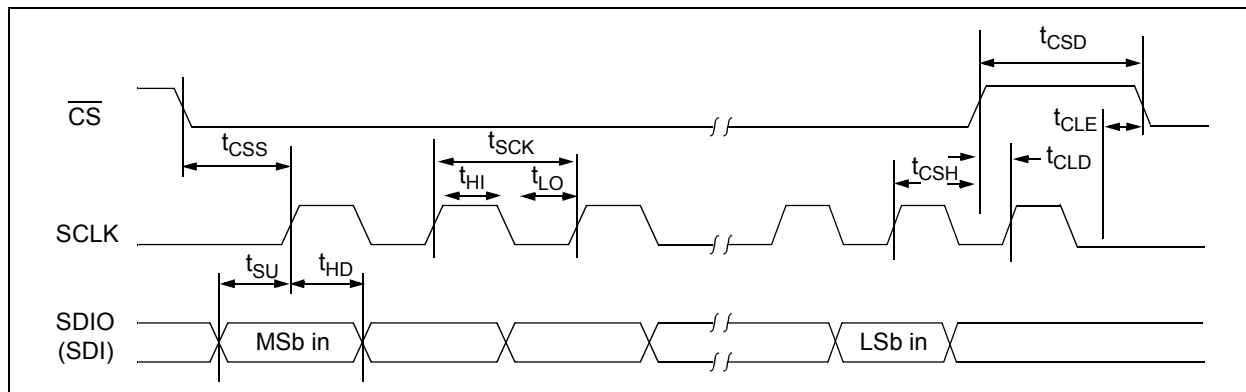
**FIGURE 2-2:** Timing Diagram – LVDS Output with Even Bit First.

# MCP37220-200 AND MCP37D20-200

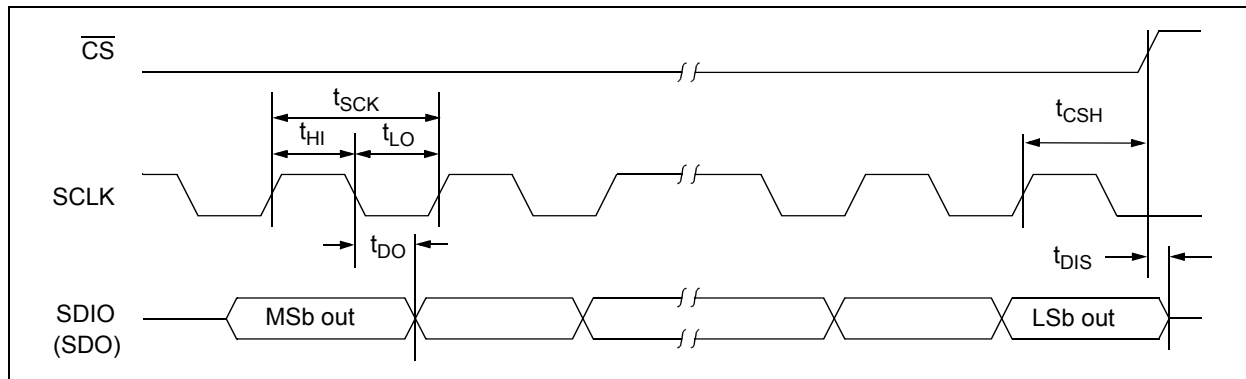
**TABLE 2-3: SPI SERIAL INTERFACE TIMING SPECIFICATIONS**

<b>Electrical Specifications:</b> Unless otherwise specified, all parameters apply for $T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$ , $AV_{DD18} = DV_{DD18} = 1.8\text{V}$ , $AV_{DD12} = DV_{DD12} = 1.2\text{V}$ , $\text{GND} = 0\text{V}$ , $\text{SENSE} = AV_{DD12}$ , Differential analog input ( $A_{IN}$ ) = -1 dBFS sine wave, $f_{IN} = 70\text{ MHz}$ , Clock input = 200 MHz, $f_S = 200\text{ Msp}$ s (ADC core), PLL and decimation filters are disabled, Output load: CMOS data pin = 10 pF, LVDS = 100 $\Omega$ termination, LVDS driver current setting = 3.5 mA, $+25^{\circ}\text{C}$ is applied for typical value. All timings are measured at 50%.						
Parameters	Symbol	Min.	Typ.	Max.	Units	Conditions
<b>Serial Clock Frequency, <math>f_{SCK} = 50\text{ MHz}</math></b>						
$\overline{\text{CS}}$ Setup Time	$t_{CSS}$	10	—	—	ns	
$\overline{\text{CS}}$ Hold Time	$t_{CSH}$	20	—	—	ns	
$\overline{\text{CS}}$ Disable Time	$t_{CSD}$	20	—	—	ns	
Data Setup Time	$t_{SU}$	2	—	—	ns	
Data Hold Time	$t_{HD}$	4	—	—	ns	
Serial Clock High Time	$t_{HI}$	8	—	—	ns	
Serial Clock Low Time	$t_{LO}$	8	—	—	ns	Note 1
Serial Clock Delay Time	$t_{CLD}$	20	—	—	ns	
Serial Clock Enable Time	$t_{CLE}$	20	—	—	ns	
Output Valid from SCK Low	$t_{DO}$	—	—	20	ns	
Output Disable Time	$t_{DIS}$	—	—	10	ns	Note 1

**Note 1:** This parameter is ensured by design, but not 100% tested in production.

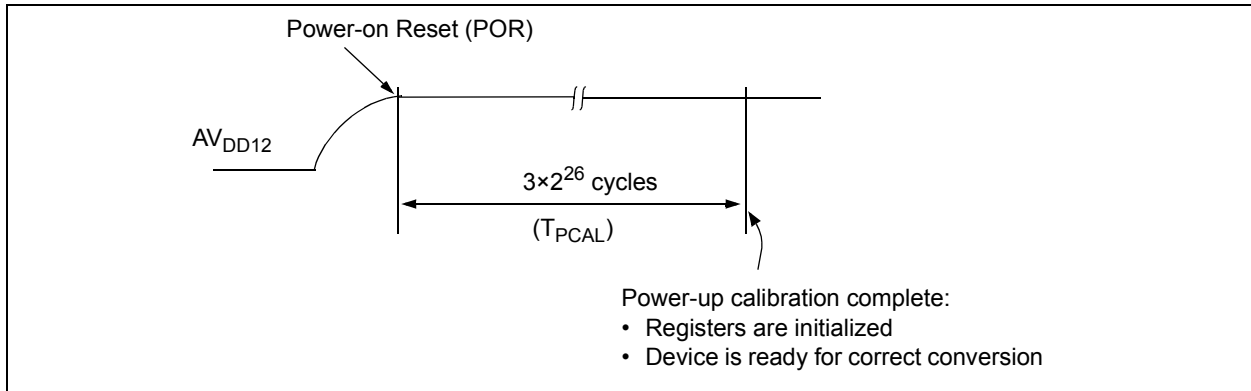


**FIGURE 2-3:** SPI Serial Input Timing Diagram.

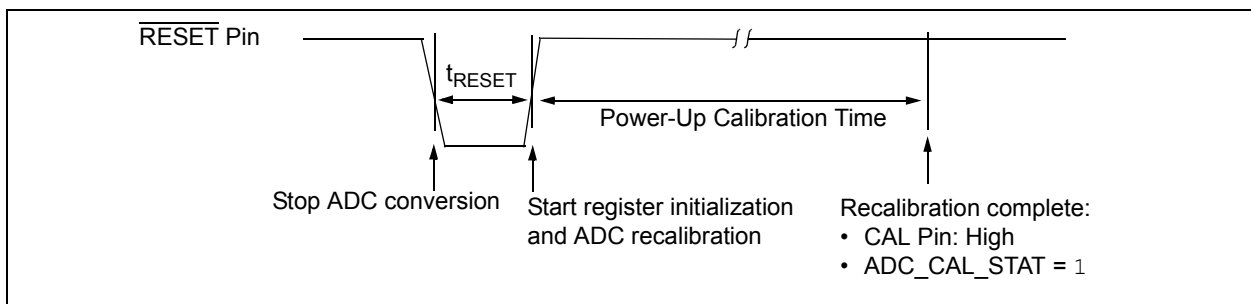


**FIGURE 2-4:** SPI Serial Output Timing Diagram.

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**FIGURE 2-5:** POR-Related Events: Register Initialization and Power-Up Calibration.



**FIGURE 2-6:** RESET Pin Timing Diagram.

**TABLE 2-4: TEMPERATURE CHARACTERISTICS**

**Electrical Specifications:** Unless otherwise specified, all parameters apply for  $T_A = -40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ ,  $AV_{DD18} = DV_{DD18} = 1.8\text{V}$ ,  $AV_{DD12} = DV_{DD12} = 1.2\text{V}$ ,  $\text{GND} = 0\text{V}$ ,  $\text{SENSE} = AV_{DD12}$ , Differential analog input ( $A_{IN}$ ) = -1 dBFS sine wave,  $f_{IN} = 70\text{ MHz}$ , Clock input = 200 MHz,  $f_S = 200\text{ Msps}$ , PLL and decimation filters are disabled, Output load: CMOS data pin = 10 pF, LVDS = 100 $\Omega$  termination, LVDS driver current setting = 3.5 mA,  $+25^{\circ}\text{C}$  is applied for typical value.

Parameters		Sym.	Min.	Typ.	Max.	Units	Conditions
<b>Temperature Ranges<sup>(1)</sup></b>							
Operating Temperature Range		$T_A$	-40	—	+85	$^{\circ}\text{C}$	
<b>Thermal Package Resistances<sup>(2)</sup></b>							
121L Ball-TFBGA (8 mm x 8 mm)	Junction-to-Ambient Thermal Resistance	$\theta_{JA}$	—	40.2	—	$^{\circ}\text{C/W}$	
	Junction-to-Case Thermal Resistance	$\theta_{JC}$	—	8.4	—	$^{\circ}\text{C/W}$	
124L VTLA (9 mm x 9 mm)	Junction-to-Ambient Thermal Resistance	$\theta_{JA}$	—	21	—	$^{\circ}\text{C/W}$	
	Junction-to-Case (top) Thermal Resistance	$\theta_{JC}$	—	8.7	—	$^{\circ}\text{C/W}$	

**Note 1:** Maximum allowed power dissipation ( $P_{D\text{MAX}}$ ) =  $(T_{J\text{MAX}} - T_A)/\theta_{JA}$ .

**2:** This parameter value is achieved by package simulations.

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NOTES:

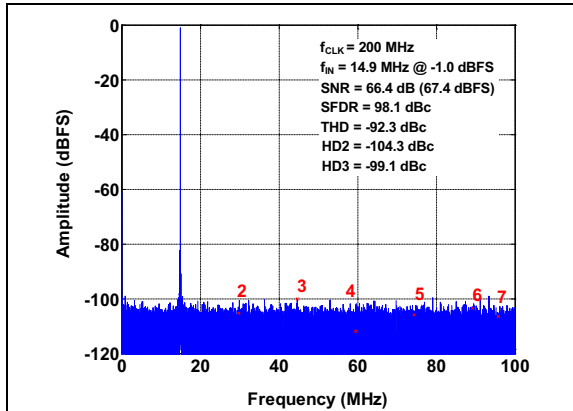


# MCP37220-200 AND MCP37D20-200

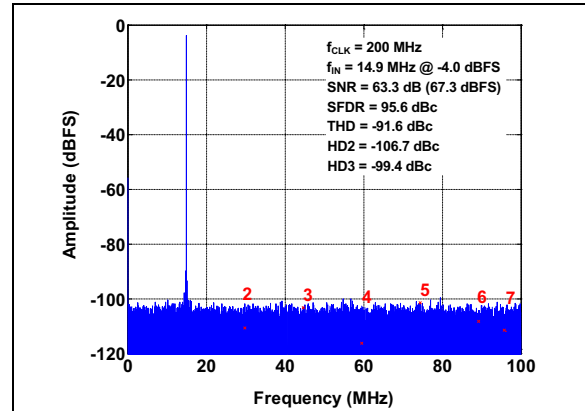
## 3.0 TYPICAL PERFORMANCE CURVES

**Note:** The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore outside the warranted range.

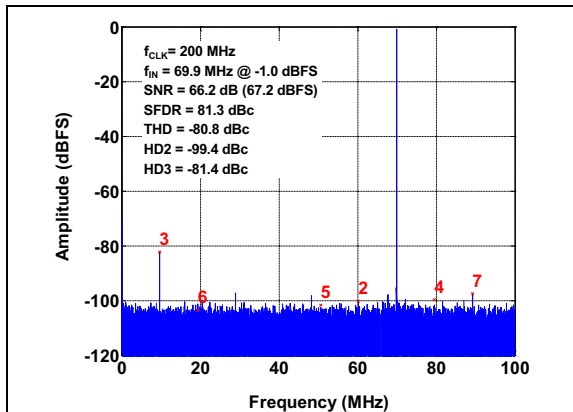
**Note:** Unless otherwise specified, all parameters apply for  $T_A = -40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ ,  $AV_{DD18} = DV_{DD18} = 1.8\text{V}$ ,  $AV_{DD12} = DV_{DD12} = 1.2\text{V}$ ,  $\text{GND} = 0\text{V}$ ,  $\text{SENSE} = AV_{DD12}$ , Differential Analog Input ( $A_{IN}$ ) = sine wave with amplitude of  $-1\text{ dBFS}$ ,  $f_{IN} = 70\text{ MHz}$ , Clock Input =  $200\text{ MHz}$ ,  $f_S = 200\text{ Mpsps}$ , PLL and decimation filters are disabled,  $\text{DIG\_GAIN}\langle 7:0 \rangle = 0011-1000$ .



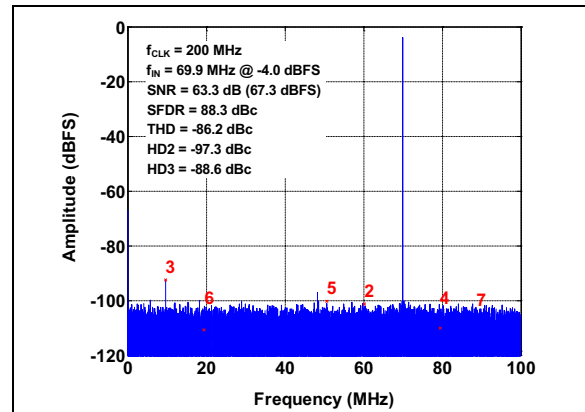
**FIGURE 3-1:** FFT for 14.9 MHz Input  
Signal:  $f_S = 200\text{ Mpsps}$ ,  $A_{IN} = -1\text{ dBFS}$ .



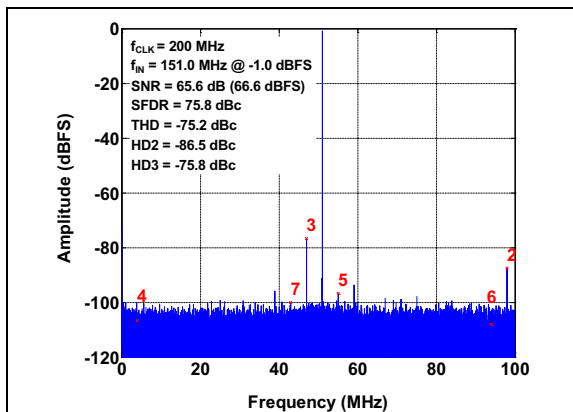
**FIGURE 3-4:** FFT for 14.9 MHz Input  
Signal:  $f_S = 200\text{ Mpsps}$ ,  $A_{IN} = -4\text{ dBFS}$ .



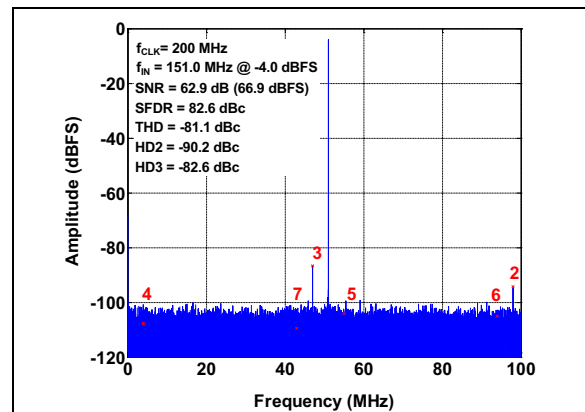
**FIGURE 3-2:** FFT for 69.9 MHz Input  
Signal:  $f_S = 200\text{ Mpsps}$ ,  $A_{IN} = -1\text{ dBFS}$ .



**FIGURE 3-5:** FFT for 69.9 MHz Input  
Signal:  $f_S = 200\text{ Mpsps}$ ,  $A_{IN} = -4\text{ dBFS}$ .



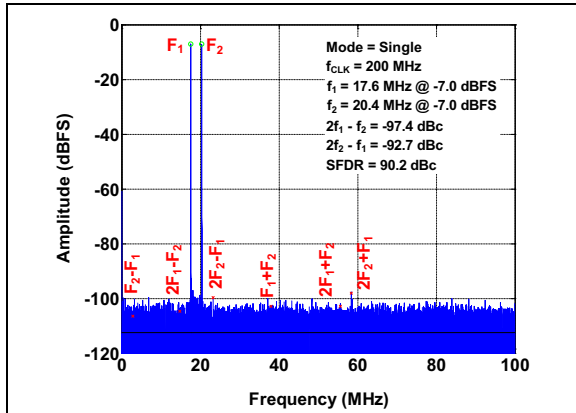
**FIGURE 3-3:** FFT for 151 MHz Input  
Signal:  $f_S = 200\text{ Mpsps}$ ,  $A_{IN} = -1\text{ dBFS}$ .



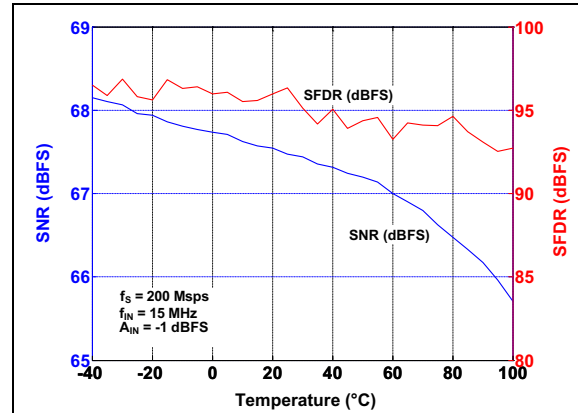
**FIGURE 3-6:** FFT for 151 MHz Input  
Signal:  $f_S = 200\text{ Mpsps}$ ,  $A_{IN} = -4\text{ dBFS}$ .

# MCP37220-200 AND MCP37D20-200

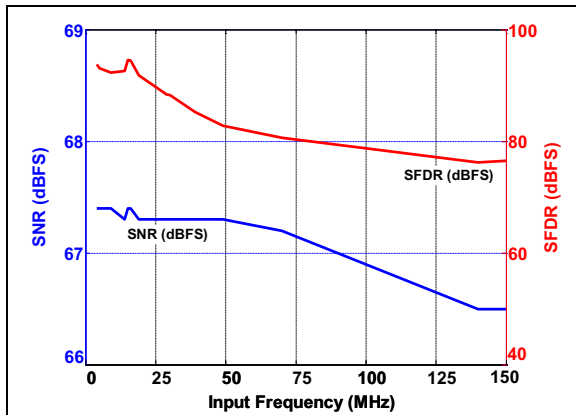
**Note:** Unless otherwise specified, all parameters apply for  $T_A = -40^\circ\text{C}$  to  $+85^\circ\text{C}$ ,  $AV_{DD18} = DV_{DD18} = 1.8\text{V}$ ,  $AV_{DD12} = DV_{DD12} = 1.2\text{V}$ ,  $\text{GND} = 0\text{V}$ ,  $\text{SENSE} = AV_{DD12}$ , Differential Analog Input ( $A_{IN}$ ) = sine wave with amplitude of  $-1\text{ dBFS}$ ,  $f_{IN} = 70\text{ MHz}$ , Clock Input =  $200\text{ MHz}$ ,  $f_S = 200\text{ Msp}$ s, PLL and decimation filters are disabled,  $\text{DIG\_GAIN}\langle 7:0 \rangle = 0011-1000$ .



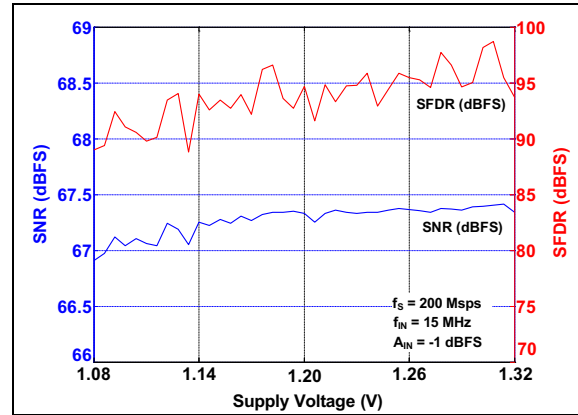
**FIGURE 3-7:** Two-Tone FFT:  
 $f_{IN1} = 17.6\text{ MHz}$  and  $f_{IN2} = 20.4\text{ MHz}$ ,  
 $A_{IN} = -7\text{ dBFS}$  per Tone,  $f_S = 200\text{ Msp}$ s.



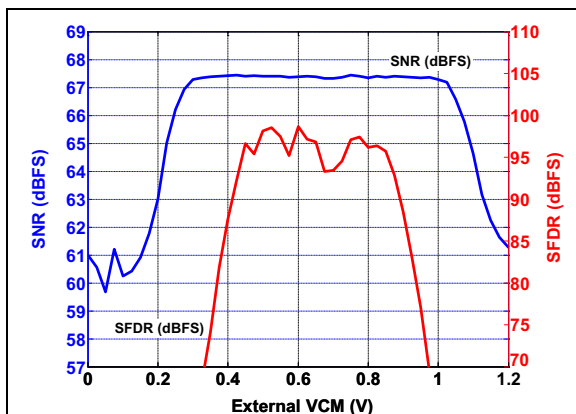
**FIGURE 3-10:** SNR/SFDR vs. Temperature:  
 $f_S = 200\text{ Msp}$ s,  $f_{IN} = 15\text{ MHz}$ .



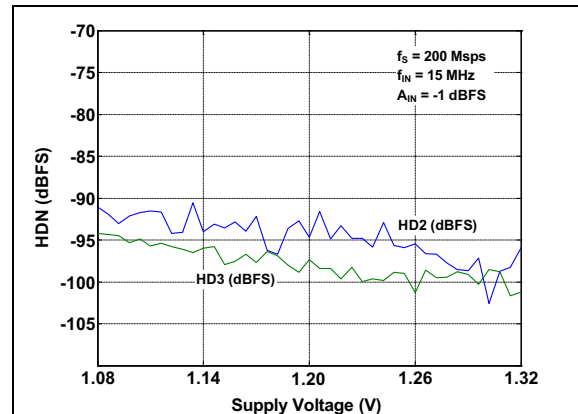
**FIGURE 3-8:** SNR/SFDR vs. Input Frequency.



**FIGURE 3-11:** SNR/SFDR vs. Supply Voltage:  $f_S = 200\text{ Msp}$ s,  $f_{IN} = 15\text{ MHz}$ .



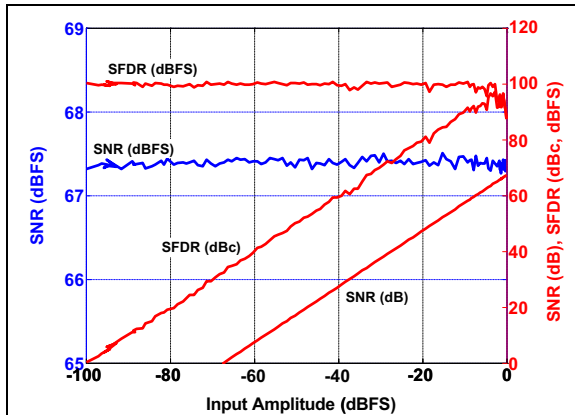
**FIGURE 3-9:** SNR/SFDR vs.  $V_{CM}$  Voltage  
(Externally Applied):  $f_S = 200\text{ Msp}$ s,  
 $f_{IN} = 15\text{ MHz}$ .



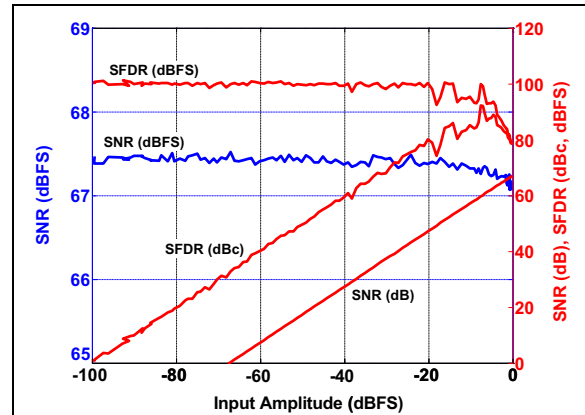
**FIGURE 3-12:** HD2/HD3 vs. Supply Voltage:  $f_S = 200\text{ Msp}$ s,  $f_{IN} = 15\text{ MHz}$ .

# MCP37220-200 AND MCP37D20-200

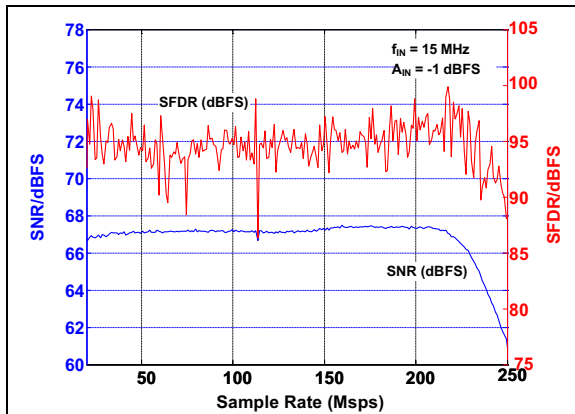
**Note:** Unless otherwise specified, all parameters apply for  $T_A = -40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ ,  $AV_{DD18} = DV_{DD18} = 1.8\text{V}$ ,  $AV_{DD12} = DV_{DD12} = 1.2\text{V}$ ,  $\text{GND} = 0\text{V}$ ,  $\text{SENSE} = AV_{DD12}$ , Differential Analog Input ( $A_{IN}$ ) = sine wave with amplitude of  $-1\text{ dBFS}$ ,  $f_{IN} = 70\text{ MHz}$ , Clock Input =  $200\text{ MHz}$ ,  $f_S = 200\text{ Mpsps}$ , PLL and decimation filters are disabled,  $\text{DIG\_GAIN}<7:0> = 0011-1000$ .



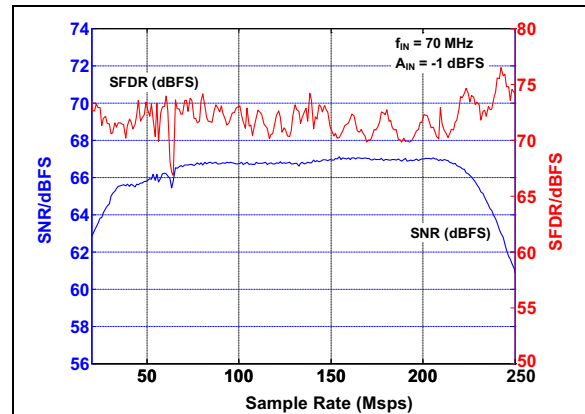
**FIGURE 3-13:** SNR/SFDR vs. Analog Input Amplitude:  $f_S = 200\text{ Mpsps}$ ,  $f_{IN} = 15\text{ MHz}$ .



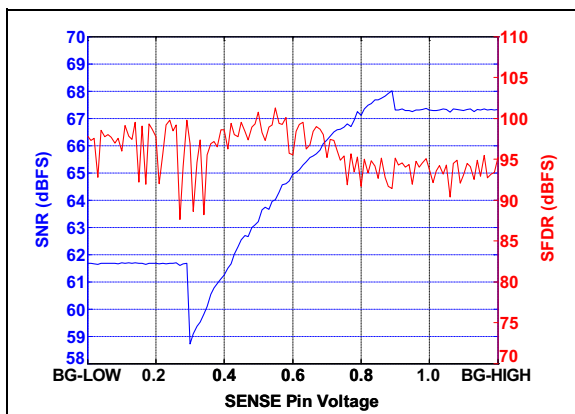
**FIGURE 3-16:** SNR/SFDR vs. Analog Input Amplitude:  $f_S = 200\text{ Mpsps}$ ,  $f_{IN} = 70\text{ MHz}$ .



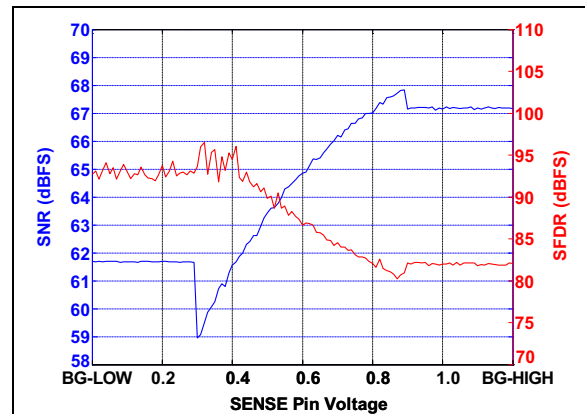
**FIGURE 3-14:** SNR/SFDR vs. Sample Rate (Mpsps):  $f_{IN} = 15\text{ MHz}$ .



**FIGURE 3-17:** SNR/SFDR vs. Sample Rate (Mpsps):  $f_{IN} = 70\text{ MHz}$ .



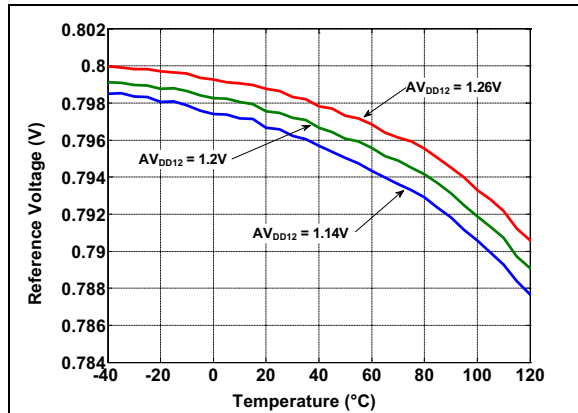
**FIGURE 3-15:** SNR/SFDR vs. SENSE Pin Voltage:  $f_S = 200\text{ Mpsps}$ ,  $f_{IN} = 15\text{ MHz}$ .



**FIGURE 3-18:** SNR/SFDR vs. SENSE Pin Voltage:  $f_S = 200\text{ Mpsps}$ ,  $f_{IN} = 70\text{ MHz}$ .

# MCP37220-200 AND MCP37D20-200

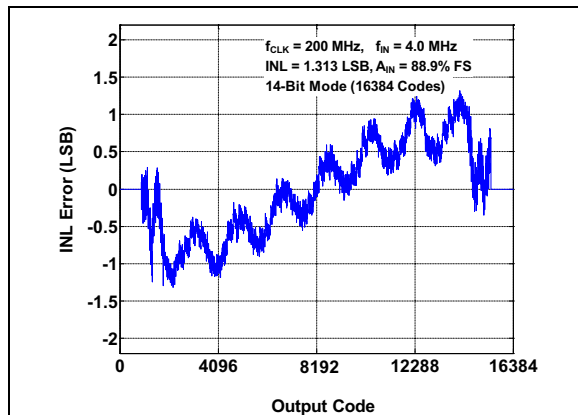
**Note:** Unless otherwise specified, all parameters apply for  $T_A = -40^\circ\text{C}$  to  $+85^\circ\text{C}$ ,  $AV_{DD18} = DV_{DD18} = 1.8\text{V}$ ,  $AV_{DD12} = DV_{DD12} = 1.2\text{V}$ ,  $\text{GND} = 0\text{V}$ ,  $\text{SENSE} = AV_{DD12}$ , Differential Analog Input ( $A_{IN}$ ) = sine wave with amplitude of  $-1\text{ dBFS}$ ,  $f_{IN} = 70\text{ MHz}$ , Clock Input =  $200\text{ MHz}$ ,  $f_S = 200\text{ Msp}$ s, PLL and decimation filters are disabled,  $\text{DIG\_GAIN}\langle 7:0 \rangle = 0011-1000$ .



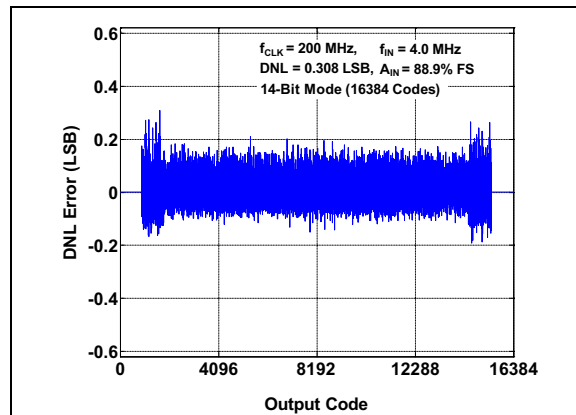
**FIGURE 3-19:**  $V_{REF}$  vs. Temperature.



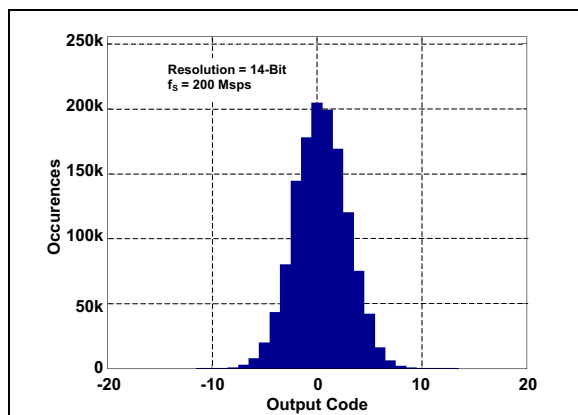
**FIGURE 3-22:** Gain and Offset Error Drifts vs. Temperature using Internal Reference, with Respect to  $25^\circ\text{C}$ :  $f_S = 200\text{ Msp}$ s.



**FIGURE 3-20:** INL Error vs. Output Code:  $f_S = 200\text{ Msp}$ s,  $f_{IN} = 4\text{ MHz}$ .



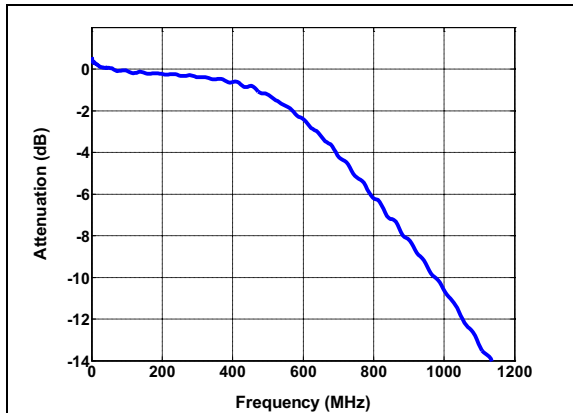
**FIGURE 3-23:** DNL Error vs. Output Code:  $f_S = 200\text{ Msp}$ s,  $f_{IN} = 4\text{ MHz}$ .



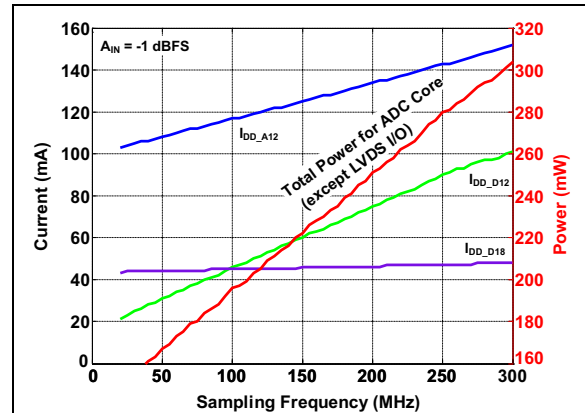
**FIGURE 3-21:** Shorted Input Histogram:  $f_S = 200\text{ Msp}$ s.

# MCP37220-200 AND MCP37D20-200

**Note:** Unless otherwise specified, all parameters apply for  $T_A = -40^\circ\text{C}$  to  $+85^\circ\text{C}$ ,  $AV_{DD18} = DV_{DD18} = 1.8\text{V}$ ,  $AV_{DD12} = DV_{DD12} = 1.2\text{V}$ ,  $GND = 0\text{V}$ ,  $SENSE = AV_{DD12}$ , Differential Analog Input ( $A_{IN}$ ) = sine wave with amplitude of  $-1\text{ dBFS}$ ,  $f_{IN} = 70\text{ MHz}$ , Clock Input =  $200\text{ MHz}$ ,  $f_S = 200\text{ Msp}$ s, PLL and decimation filters are disabled,  $DIG\_GAIN<7:0> = 0011-1000$ .



**FIGURE 3-24:** Input Bandwidth.



**FIGURE 3-25:** Power Consumption vs. Sampling Frequency (LVDS Mode).

# MCP37220-200 AND MCP37D20-200

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NOTES:

# MCP37220-200 AND MCP37D20-200

## 4.0 THEORY OF OPERATION

The MCP37220-200 and MCP37D20-200 devices are single-channel, low-power, 14-bit, 200 Msps Analog-to-Digital Converters (ADC) with built-in patented features that maximize performance. The features include Harmonic Distortion Correction (HDC), DAC Noise Cancellation (DNC), Dynamic Element Matching (DEM) and flash error calibration.

These devices include various built-in digital signal post-processing features. The MCP37220-200 includes FIR decimation filters and the MCP37D20-200 includes both FIR decimation filters and Digital Down-Conversion (DDC). Digital gain and offset correction features are also offered in both devices. These built-in advanced digital signal post-processing sub-blocks, which are individually enabled and controlled, can be used for various special applications such as I/Q demodulation, digital down-conversion, and imaging.

When the device is first powered-up, it performs internal calibrations by itself and is running with default settings. From this point, the user can configure the device registers using the SPI command.

The device samples the analog input on the rising edge of the clock. The digital output code is available after 23 clock cycles of data latency. Latency will increase if any of the digital signal post-processing (DSPP) options are enabled.

The output data can be coded in two's complement or offset binary format and can be randomized using the user option. The output data is available through the CMOS or LVDS (Low-Voltage Differential Signaling) interface.

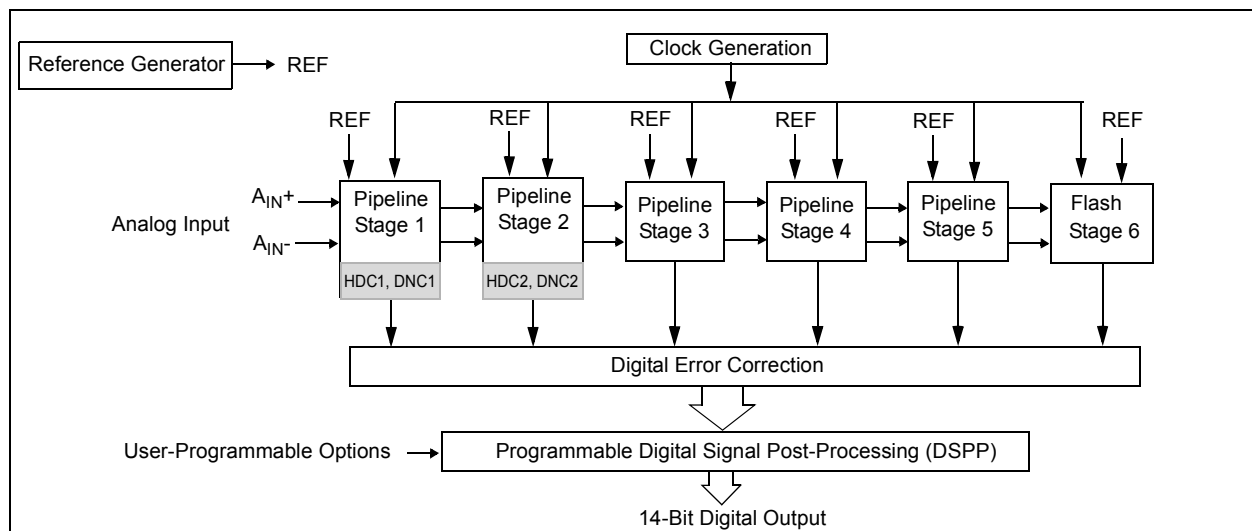
## 4.1 ADC Core Architecture

Figure 4-1 shows the simplified block diagram of the ADC core. The ADC core consists of six stages. All stages consist of a multi-level flash ADC and DAC. Except the last stage, all have a residue amplifier with a gain of 4. Dither is added in each of the first two stages. The digital outputs from all six stages are combined in a digital error correction logic block and digitally processed for the final 14-bit output.

The first two stages include patented digital calibration features:

- Harmonic Distortion Correction (HDC) algorithm that digitally measures and cancels ADC errors arising from distortions introduced by the residue amplifiers
- DAC Noise Cancellation (DNC) algorithm that corrects DAC's nonlinearity errors
- Dynamic Element Matching (DEM) which randomizes DAC errors, thereby converting harmonic distortion to white noise

These digital correction algorithms are first applied during the Power-on Reset sequence and then operate in the background during normal operation of the pipelined ADC. These algorithms automatically track and correct any environmental changes in the ADC. More details of the system correction algorithms are shown in [Section 4.10 "System Calibration"](#).



**FIGURE 4-1:** ADC Core Block Diagram.

# MCP37220-200 AND MCP37D20-200

## 4.2 Supply Voltage (DV<sub>DD</sub>, AV<sub>DD</sub>, GND)

The device operates from two sets of supplies and a common ground:

- Digital Supplies (DV<sub>DD</sub>) for the digital section: 1.8V and 1.2V
- Analog Supplies (AV<sub>DD</sub>) for the analog section: 1.8V and 1.2V
- Ground (GND): Common ground for both digital and analog sections.

The supply pins require an appropriate bypass capacitor (ceramic) to attenuate high-frequency noise present in most application environments. The ground pins provide the current return path. These ground pins must connect to the ground plane of the PCB through a low-impedance connection. A ferrite bead can be used to separate analog and digital supply lines if a common power supply is used for both analog and digital sections.

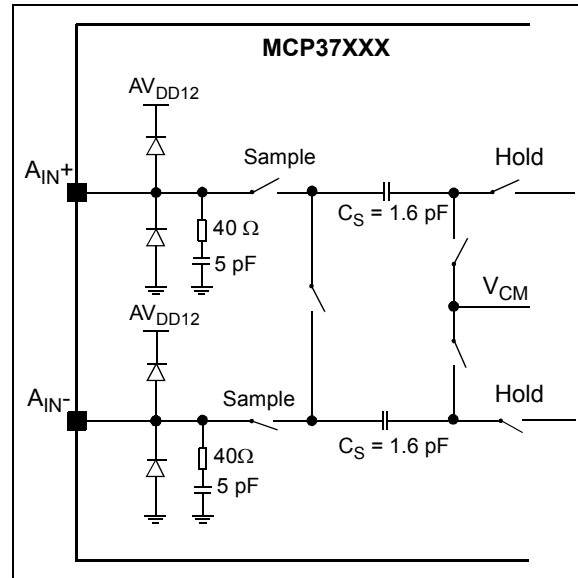
The voltage regulators for each supply need to have sufficient output current capabilities to support a stable ADC operation.

## 4.3 Analog Input Circuit

The analog inputs (A<sub>IN</sub>) of all MCP37XXX devices are a differential CMOS switched capacitor sample-and-hold circuit. [Figure 4-2](#) shows the equivalent input structure of the device.

The input impedance of the device is mostly governed by the input sampling capacitor ( $C_S = 1.6 \text{ pF}$ ) and input sampling frequency ( $f_S$ ). The performance of the device can be affected by the input signal conditioning network (see [Figure 4-3](#)). The analog input signal source must have sufficiently low output impedance to charge the sampling capacitors ( $C_S = 1.6 \text{ pF}$ ) within one clock cycle. A small external resistor (e.g.  $5\Omega$ ) in series with each input is recommended as it helps reduce transient currents and dampens ringing behavior. A small differential shunt capacitor at the chip side of the resistors may be used to provide dynamic charging currents and may improve performance. The resistors form a low-pass filter with the capacitor and their values must be determined by application requirements and input frequency.

The V<sub>CM</sub> pin provides a common-mode voltage reference (0.55V), which can be used for a center-tap voltage of an RF transformer or balun. If the V<sub>CM</sub> pin voltage is not used, the user may provide a common-mode voltage (0.55V) from another supply.



**FIGURE 4-2:** Equivalent Input Circuit.



# MCP37220-200 AND MCP37D20-200

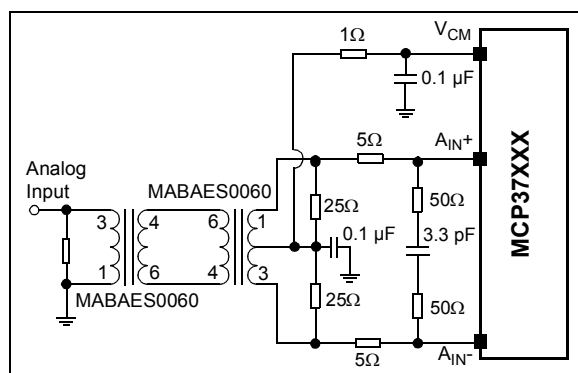
## 4.3.1 ANALOG INPUT DRIVING CIRCUIT

### 4.3.1.1 Differential Input Configuration

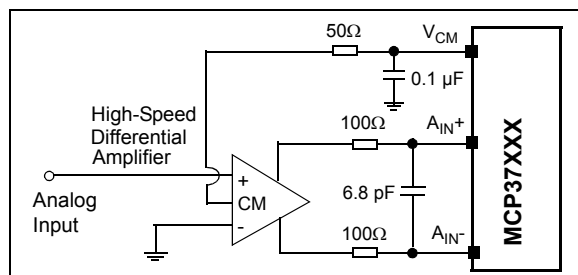
The device achieves optimum performance when the input is driven differentially, where common-mode noise immunity and even-order harmonic rejection are significantly improved. If the input is single-ended, it must be converted to a differential signal in order to properly drive the ADC input. The differential conversion and common-mode application can be accomplished by using an RF transformer or balun with a center-tap. Additionally, one or more anti-aliasing filters may be added for optimal noise performance and should be tuned such that the corner frequency is appropriate for the system.

Figure 4-3 shows an example of the differential input circuit with transformer. Note that the input driving circuits are terminated by  $50\Omega$  near the ADC side through a pair of  $25\Omega$  resistors from each input to the common-mode ( $V_{CM}$ ) from the device. The RF transformer must be carefully selected to avoid artificially high harmonic distortion. The transformer can be damaged if a strong RF input is applied or an RF input is applied while the MCP37XXX is powered off. The transformer has to be selected to handle sufficient RF input power.

Figure 4-4 shows an input configuration example when a differential output amplifier is used.



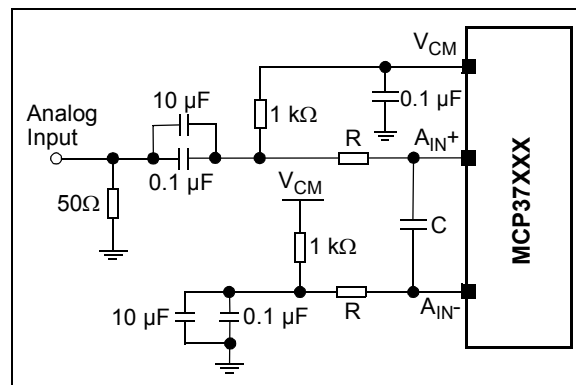
**FIGURE 4-3:** Transformer Coupled Input Configuration.



**FIGURE 4-4:** DC-Coupled Input Configuration with Preamplifier: the external signal conditioning circuit and associated component values are for reference only. Typically, the amplifier manufacturer provides reference circuits and component values.

### 4.3.1.2 Single-Ended Input Configuration

Figure 4-5 shows an example of a single-ended input configuration. SNR and SFDR performance degrades significantly when the device is operated in a single-ended configuration. The unused negative side of the input should be AC-coupled to ground using a capacitor.

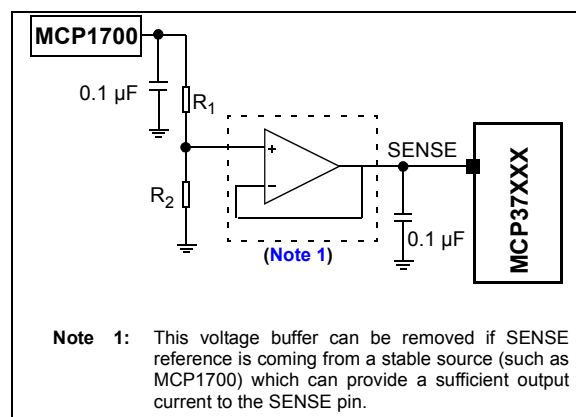


**FIGURE 4-5:** Single-Ended Input Configuration.

## 4.3.2 SENSE VOLTAGE AND INPUT FULL-SCALE RANGE

The device has a bandgap-based differential internal reference voltage. The SENSE pin voltage is used to select the reference voltage source and configures the input full-scale range. A comparator detects the SENSE pin voltage and configures the full-scale input range into one of the three possible modes which are summarized in Table 4-1. Figure 4-6 shows an example of how the SENSE pin should be driven.

The SENSE pin can sink or source currents as high as  $360\mu A$  across all operational conditions. Therefore, it may require a driver circuit, unless the SENSE reference source provides sufficient output current.



**FIGURE 4-6:** SENSE Pin Voltage Setup.

# MCP37220-200 AND MCP37D20-200

**TABLE 4-1: SENSE PIN VOLTAGE AND INPUT FULL-SCALE RANGE**

SENSE Pin Voltage ( $V_{\text{SENSE}}$ )	Selected Reference Voltage ( $V_{\text{REF}}$ )	Full-Scale Input Voltage Range ( $A_{\text{FS}}$ )	LSb Size ( $A_{\text{FS}}/2^{14}$ )	Condition
Tied to GND	0.4V	$0.9 V_{\text{P-P}}$	54.93 $\mu\text{V}$	Low-Reference Mode <sup>(2)</sup>
0.4V – 0.8V	0.4V – 0.8V	$0.9 V_{\text{P-P}}$ to $1.8 V_{\text{P-P}}$ <sup>(1)</sup>	Adjustable	Sense Mode <sup>(3)</sup>
Tied to $AV_{\text{DD12}}$	0.8V	$1.8 V_{\text{P-P}}$	109.86 $\mu\text{V}$	High-Reference Mode <sup>(2)</sup>

**Note 1:**  $A_{\text{FS}} = 2.25 V_{\text{P-P}} \times (V_{\text{SENSE}}) = 0.9 V_{\text{P-P}}$  to  $1.8 V_{\text{P-P}}$

**2:** Based on internal bandgap voltage

**3:** Based on  $V_{\text{SENSE}}$

## 4.3.2.1 SENSE Selection Vs. SNR/SFDR Performance

The SENSE pin is used to configure the full-scale input range of the ADC. Depending on the application conditions, the SNR, SFDR and dynamic range performance are affected by the SENSE pin configuration. [Table 4-2](#) summarizes these settings.

### • High-Reference Mode

This mode is enabled by setting the SENSE pin to  $AV_{\text{DD12}}$  (1.2V). This mode provides the highest input full-scale range ( $1.8 V_{\text{P-P}}$ ) and the highest SNR performance. [Figures 3-15](#) and [Figure 3-18](#) show SNR/SFDR versus input amplitude in High-Reference mode.

### • Low-Reference Mode

This mode is enabled by setting the SENSE pin to ground. This mode is suitable for applications which have a smaller input full-scale range.

This mode provides improved SFDR characteristics, but SNR is reduced by -6 dB compared to the High-Reference mode.

### • SENSE Mode

This mode is enabled by driving the SENSE pin with an external voltage source between 0.4V and 0.8V. This mode allows the user to adjust the input full-scale range such that SNR and dynamic range are optimized in a given application system environment.

**TABLE 4-2: SENSE VS. SNR/SFDR PERFORMANCE**

SENSE	Descriptions
High-Reference Mode (SENSE pin = $AV_{\text{DD12}}$ )	High-input full-scale range ( $1.8 V_{\text{P-P}}$ ) and optimized SNR
Low-Reference Mode (SENSE pin = ground)	Low-input full-scale range ( $0.9 V_{\text{P-P}}$ ) and reduced SNR, but optimized SFDR
Sense Mode (SENSE pin = 0.4V to 0.8V)	Adjustable-input full-scale range ( $0.9 V_{\text{P-P}}$ - $1.8 V_{\text{P-P}}$ ). Dynamic trade-off between High-Reference and Low-Reference modes can be used.

# MCP37220-200 AND MCP37D20-200

## 4.3.3 DECOUPLING CIRCUITS FOR INTERNAL VOLTAGE REFERENCE AND BANDGAP OUTPUT

### 4.3.3.1 Decoupling Circuits for REF Pins

The internal reference is available at REF pins. This internal reference requires external capacitors for stable operation.

**VTLA-124 Package Device:** Figure 4-7 shows the recommended circuit for the REF pins. A 2.2  $\mu\text{F}$  ceramic capacitor with two optional capacitors (22 nF and 220 nF) is recommended between the positive and negative reference pins. The negative reference pin (REF-) is then grounded through a 220 nF capacitor. The capacitors should be placed as close to the ADC as possible with short and thick traces. Vias on the PCB are not recommended for this reference pin circuit.

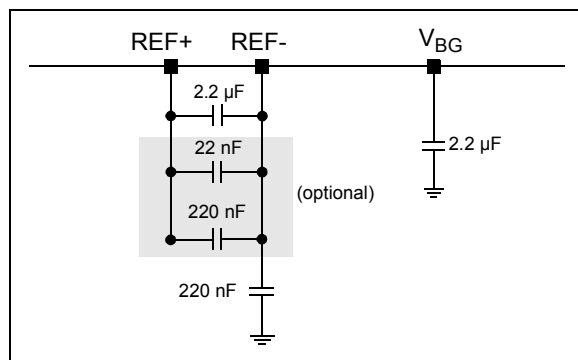
**TFBGA-121 Package Device:** The decoupling capacitor is embedded in the package. Therefore, no external circuit is required on the PCB.

### 4.3.3.2 Decoupling Circuit for $V_{BG}$ Pin

The bandgap circuit is a part of the reference circuit and the output is available at the  $V_{BG}$  pin.

**VTLA-124 Package Device:**  $V_{BG}$  pin needs an external decoupling capacitor (2.2  $\mu\text{F}$ ) as shown in Figure 4-7.

**TFBGA-121 Package Device:** The decoupling capacitor is embedded in the package. Therefore, no external circuit is required on the PCB.

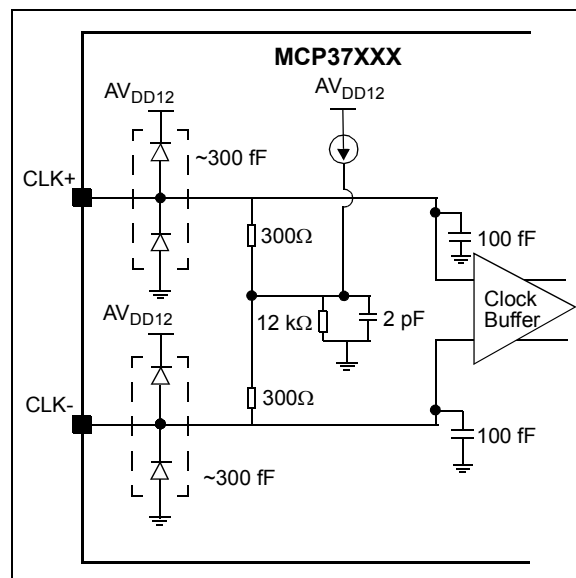


**FIGURE 4-7:** External Circuit for Voltage Reference and VBG pins for the VTLA-124 Package. Note that this external circuit is not required for the TFBGA-121 package.

**Note:** The internal reference output (REF+/REF-) and bandgap voltage output ( $V_{BG}$ ) should not be driven.

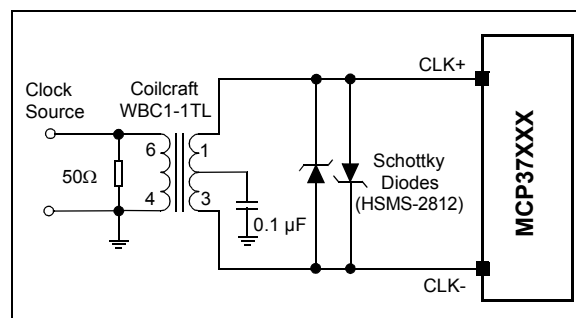
## 4.4 External Clock Input

For optimum performance, the MCP37XXX requires a low-jitter differential clock input at the CLK+ and CLK- pins. Figure 4-8 shows the equivalent clock input circuit.



**FIGURE 4-8:** Equivalent Clock Input Circuit.

The clock input amplitude range is between 300 mV<sub>P-P</sub> and 800 mV<sub>P-P</sub>. When a single-ended clock source is used, an RF transformer or balun can be used to convert the clock into a differential signal for the best ADC performance. Figure 4-9 shows an example clock input circuit. The common-mode voltage is internally generated and a center-tap is not required. The back-to-back Schottky diodes across the transformer's secondary current limit the clock amplitude to approximately 0.8 V<sub>P-P</sub> differential. This limiter helps prevent large voltage swings of the input clock while preserving the high slew rate that is critical for low jitter.



**FIGURE 4-9:** Transformer-Coupled Differential Clock Input Configuration.

# MCP37220-200 AND MCP37D20-200

## 4.4.1 CLOCK JITTER AND SNR PERFORMANCE

In a high-speed pipelined ADC, the SNR performance is directly limited by thermal noise and clock jitter. Thermal noise is independent of input clock and a dominant term at low input frequency. On the other hand, the clock jitter becomes a dominant term as input frequency increases. Equation 4-1 shows the SNR jitter component, which is expressed in terms of the input frequency ( $f_{IN}$ ) and the total amount of clock jitter ( $T_{Jitter}$ ), where  $T_{Jitter}$  is a sum of the following two components:

- Input clock jitter (phase noise)
- Internal aperture jitter (due to noise of the clock input buffer).

### EQUATION 4-1: SNR VS. CLOCK JITTER

$$SNR_{Jitter}(dBc) = -20 \times \log_{10}(2\pi \times f_{IN} \times T_{Jitter})$$

where the total jitter term ( $T_{jitter}$ ) is given by:

$$T_{Jitter} = \sqrt{(t_{Jitter, Clock Input})^2 + (t_{Aperture, ADC})^2}$$

The clock jitter can be minimized by using a high-quality clock source and jitter cleaners as well as a band-pass filter at the external clock input, while a faster clock slew rate improves the ADC aperture jitter.

With a fixed amount of clock jitter, the SNR degrades as the input frequency increases. This is illustrated in Figure 4-10. If the input frequency increases from 10 MHz to 20 MHz, the maximum achievable SNR degrades about 6 dB. For every decade (e.g. 10 MHz to 100 MHz), the maximum achievable SNR due to clock jitter is reduced by 20 dB.

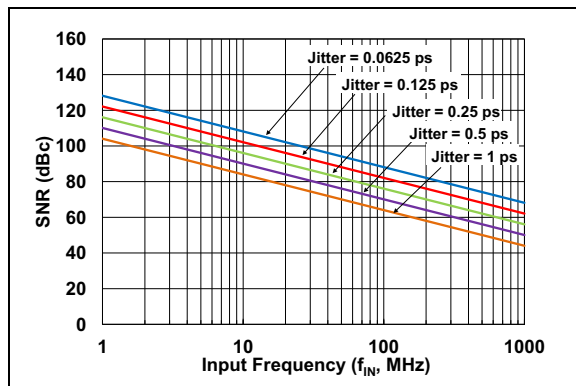


FIGURE 4-10: SNR vs. Clock Jitter.

# MCP37220-200 AND MCP37D20-200

## 4.5 ADC Clock Selection

This section describes the ADC clock selection and how to use the built-in Delay-Locked Loop (DLL) and Phase-Locked Loop (PLL) blocks.

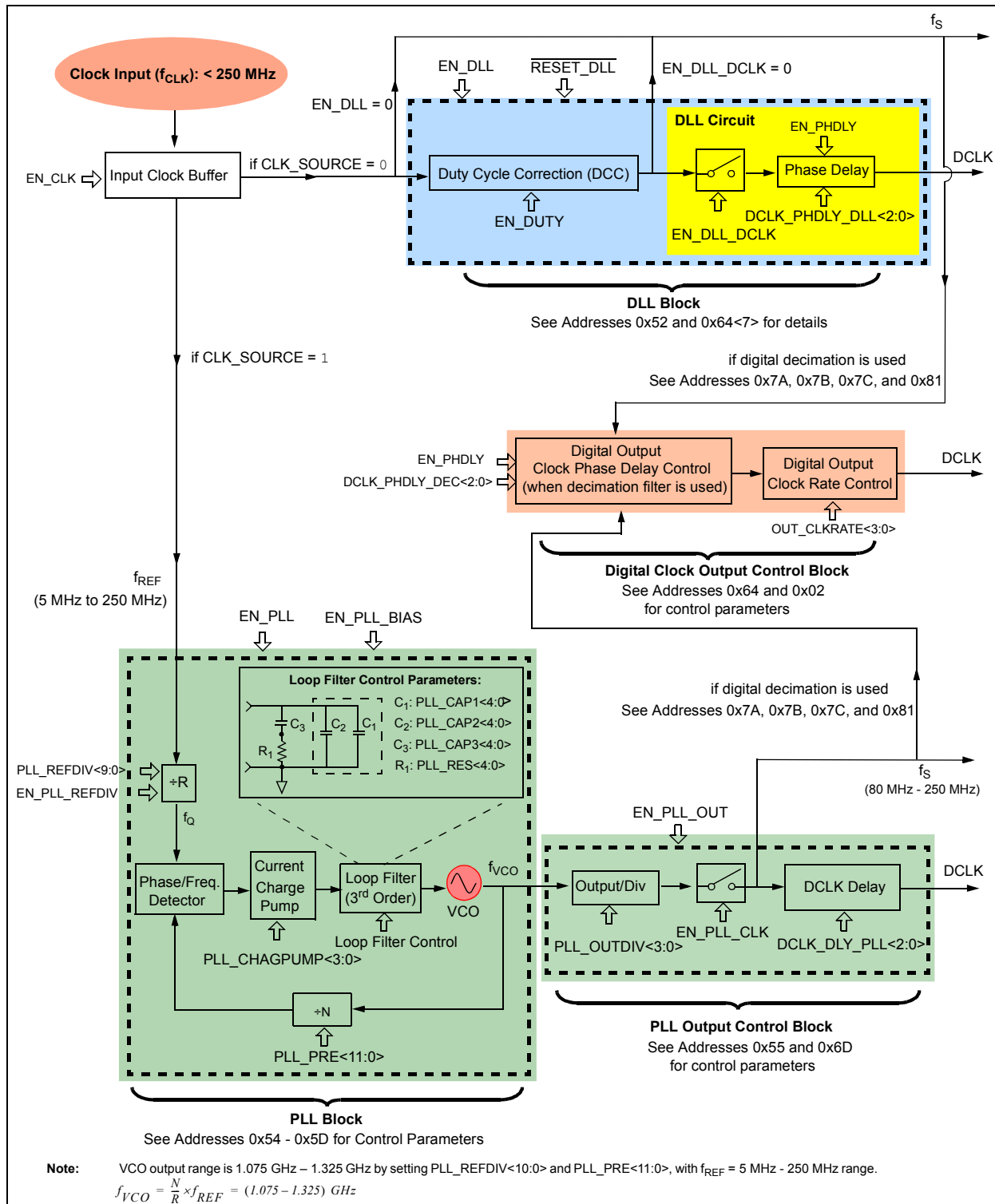
When the device is first powered-up, the external clock input (CLK+/-) is directly used for the ADC timing as default. After this point, the user can enable the DLL or PLL circuit by setting the register bits. [Figure 4-11](#) shows the clock control blocks. [Table 4-3](#) shows an example of how to select the ADC clock depending on the operating conditions.

**TABLE 4-3: ADC CLOCK SELECTION (EXAMPLE)**

Operating Conditions	Control Bit Settings <sup>(1)</sup>	Features	
		Input Clock Duty Cycle Correction	DCLK Output Phase Delay Control
CLK_SOURCE = 0 (Default) <sup>(2)</sup>			
<ul style="list-style-type: none"><li>DLL output is not used</li><li>Decimation is not used (Default)<sup>(3)</sup></li></ul>	EN_DLL = 0 EN_DLL_DCLK = 0 EN_PHDLY = 0	Not Available	Not Available
	EN_DLL = 1 EN_DLL_DCLK = 0 EN_PHDLY = 0	Available	
<ul style="list-style-type: none"><li>DLL output is used</li><li>Decimation is not used</li></ul>	EN_DLL = 1 EN_DLL_DCLK = 1 EN_PHDLY = 1	Available	Available
<ul style="list-style-type: none"><li>DLL output is not used</li><li>Decimation is used<sup>(4)</sup></li></ul>	EN_DLL = 0 EN_DLL_DCLK = X EN_PHDLY = 1	Not Available	
	EN_DLL = 1 EN_DLL_DCLK = 0 EN_PHDLY = 1	Available	
CLK_SOURCE = 1 <sup>(5)</sup>			
<ul style="list-style-type: none"><li>Decimation is not used</li></ul>	EN_DLL = X EN_DLL_DCLK = X EN_PHDLY = 0	Not Available	Available
<ul style="list-style-type: none"><li>Decimation is used<sup>(4)</sup></li></ul>	EN_DLL = X EN_DLL_DCLK = X EN_PHDLY = 1		

- Note**
- 1: See Addresses 0x52, 0x53, and 0x64 for bit settings.
  - 2: The sampling frequency ( $f_s$ ) of the ADC core comes directly from the input clock buffer
  - 3: Output data is synchronized with the output data clock (DCLK), which comes directly from the input clock buffer.
  - 4: While using decimation, output clock rate and phase delay are controlled by the digital clock output control block
  - 5: The sampling frequency ( $f_s$ ) is generated by the PLL circuit. The external clock input is used as the reference input clock for the PLL block.

# MCP37220-200 AND MCP37D20-200



**FIGURE 4-11:** Timing Clock Control Blocks.

# MCP37220-200 AND MCP37D20-200

## 4.5.1 USING DLL MODE

Using the DLL block is the best option when output clock phase control is needed while the clock multiplication and the digital decimation are not required. When the DLL block is enabled, the user can control the input clock Duty Cycle Correction (DCC) and the output clock phase delay.

See the DLL block in [Figure 4-11](#) for details. [Table 4-4](#) summarizes the DLL control register bits. See also [Table 4-15](#) for the output clock phase control.

**TABLE 4-4: DLL CONTROL REGISTER BITS**

Control Parameter	Register	Descriptions
CLK_SOURCE	0x53	CLK_SOURCE = 0: External clock input becomes input of the DLL block
EN_DLL	0x52	EN_DLL = 1: Enable DLL block
EN_DUTY	0x52	Input clock duty cycle correction control bit <sup>(1)</sup>
EN_DLL_DCLK	0x52	DLL output clock enable bit
EN_PHDLY	0x64	Enable digital output clock phase delay control.
DCLK_PHDLY_DLL<2:0>	0x52	Phase Delay control bits of digital output clock (DCLK) when DLL is used <sup>(2)</sup>
RESET_DLL	0x52	Reset control bit for the DLL block

**Note 1:** Duty cycle correction is not recommended when a high-quality external clock is used.

**2:** If decimation is used, the output clock phase delay is controlled using DCLK\_PHDLY\_DEC<2:0> in Address 0x64.

### 4.5.1.1 Input Clock Duty Cycle Correction

The ADC performance is sensitive to the clock duty cycle. The ADC achieves optimum performance with 50% duty cycle, and all performance characteristics are ensured when the duty cycle is 50% with  $\pm 1\%$  tolerance.

When CLK\_SOURCE = 0, the external clock is used as the sampling frequency ( $f_S$ ) of the ADC core. When the external input clock is not high-quality (for example, duty cycle is not 50%), the user can enable the internal clock duty cycle correction circuit by setting the EN\_DUTY bit in Address 0x52 ([Register 5-7](#)). When duty cycle correction is enabled (EN\_DUTY = 1), only the falling edge of the clock signal is modified (rising edge is unaffected).

The duty cycle correction process adds additional jitter noise to the clock signal. Therefore, using this option is only recommended when an asymmetrical input clock source causes significant performance degradation or when the input clock source is not stable.

**Note:** The clock duty cycle correction is only applicable when the DLL block is enabled (EN\_DLL = 1). It is not applicable for the PLL output.

### 4.5.1.2 DLL Block Reset Event

The DLL must be reset if the clock is removed or the clock frequency is changed. The DLL reset is controlled by using the RESET\_DLL bit in Address 0x52 ([Register 5-7](#)). The DLL has an automatic reset with the following events:

- During power-up: Stay in reset until the RESET\_DLL bit is cleared.
- When the SOFT\_RESET command is issued while the DLL is enabled: the RESET\_DLL bit is automatically cleared after reset.

## 4.5.2 USING PLL MODE

The PLL block is mainly used when clock multiplication is needed. When CLK\_SOURCE = 1, the sampling frequency ( $f_S$ ) of the ADC core is coming from the internal PLL block.

The recommended PLL output clock range is from 80 MHz to 250 MHz. The external clock input is used as the PLL reference frequency. The range of the clock input frequency is from 5 MHz to 250 MHz.

**Note:** The PLL mode is only supported for sampling frequencies between 80 MHz and 250 MHz.



# MCP37220-200 AND MCP37D20-200

## 4.5.2.1 PLL Output Frequency and Output Control Parameters

The internal PLL can provide a stable timing output ranging from 80 MHz to 250 MHz. [Figure 4-11](#) shows the PLL block using a charge-pump-based integer N PLL and the PLL output control block. The PLL block includes various user control parameters for the desired output frequency. [Table 4-5](#) summarizes the PLL control register bits and [Table 4-6](#) shows an example of register bit settings for the PLL charge pump and loop filter.

The PLL block consists of:

- Reference Frequency Divider (R)
- Prescaler – which is a feedback divider (N)
- Phase/Frequency Detector (PFD)
- Current Charge Pump
- Loop Filter – a 3<sup>rd</sup> order RC low-pass filter
- Voltage-Controlled Oscillator (VCO)

The external clock at the CLK+ and CLK- pins is the input frequency to the PLL. The range of input frequency ( $f_{REF}$ ) is from 5 MHz to 250 MHz. This input frequency is divided by the reference frequency divider (R) which is controlled by the 10-bit-wide PLL\_REFDIV<9:0> setting. In the feedback loop, the VCO frequency is divided by the prescaler (N) using PLL\_PRE<11:0>.

The ADC core sampling frequency ( $f_S$ ), ranging from 80 MHz to 250 MHz, is obtained after the output frequency divider (PLL\_OUTDIV<3:0>). For stable operation, the user needs to configure the PLL with the following limits:

- Input clock frequency ( $f_{REF}$ ) = 5 MHz to 250 MHz
- Charge pump input frequency = 4 MHz to 50 MHz (after PLL reference divider)
- VCO output frequency = 1.075 to 1.325 GHz
- PLL output frequency after output divider = 80 MHz to 250 MHz

The charge pump is controlled by the PFD and forces sink (DOWN) or source (UP) current pulses onto the loop filter. The charge pump bias current is controlled by the PLL\_CHAGPUMP<3:0> bits, approximately 25  $\mu$ A per step. The loop filter consists of a 3<sup>rd</sup> order passive RC filter. [Table 4-6](#) shows the recommended settings of the charge pump and loop filter parameters, depending on the charge pump input frequency range (output of the reference frequency divider).

When the PLL is locked, it tracks the input frequency ( $f_{REF}$ ) with the ratio of dividers (N/R). The PLL operating status is monitored by the PLL status indication bits: <PLL\_VCOL\_STAT> and <PLL\_VCOH\_STAT> in Address 0xD1 ([Register 5-68](#)).

[Equation 4-2](#) shows the VCO output frequency ( $f_{VCO}$ ) as a function of the two dividers and reference frequency:

## EQUATION 4-2: VCO OUTPUT FREQUENCY

$$f_{VCO} = \left(\frac{N}{R}\right)f_{REF} = 1.075 \text{ (GHz) to } 1.325 \text{ (GHz)}$$

Where:

N = 1 to 4095 controlled by PLL\_PRE<11:0>

R = 1 to 1023 controlled by PLL\_REFDIV<9:0>

See Addresses 0x54 to 0x57 ([Registers 5-9 to 5-12](#)) for these bits settings.

The tuning range of the VCO is 1.075 GHz to 1.325 GHz. N and R values must be chosen such that the VCO is within this range. In general, lower values of the VCO frequency ( $f_{VCO}$ ) and higher values of the charge pump frequency ( $f_Q$ ) should be chosen to optimize the clock jitter. Once the VCO output frequency is determined to be within this range, the user needs to set the final ADC sampling frequency ( $f_S$ ) with the PLL output divider using PLL\_OUTDIV<3:0>. [Equation 4-3](#) shows how to obtain the ADC core sampling frequency:

## EQUATION 4-3: SAMPLING FREQUENCY

$$f_S = \left(\frac{f_{VCO}}{PLL\_OUTDIV}\right) = 80 \text{ MHz to } 250 \text{ MHz}$$

[Table 4-7](#) shows an example of generating  $f_S = 200$  MHz output using the PLL control parameters.

## 4.5.2.2 PLL Calibration

The PLL should be recalibrated following a change in the clock input frequency or in the PLL configuration register bit settings (Addresses 0x54 - 0x57; [Registers 5-9 – 5-12](#)).

The PLL can be calibrated by toggling the PLL\_CAL\_TRIG bit in Address 0x6B ([Register 5-27](#)) or by sending a SOFT\_RESET command (See Address 0x00, [Register 5-1](#)). The PLL calibration status is observed by the PLL\_CAL\_STAT bit in Address 0xD1 ([Register 5-68](#)).

## 4.5.2.3 Monitoring of PLL Drifts

The PLL drifts can be monitored using the status monitoring bits in Address 0xD1 ([Register 5-68](#)). Under normal operation, the PLL maintains lock across all temperature ranges. It is not necessary to actively monitor the PLL, unless extreme variations in the supply voltage are expected or if the input reference clock frequency has been changed.



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**TABLE 4-5: PLL CONTROL REGISTER BITS**

Control Parameter	Register	Descriptions
<b>PLL Calibration and Status Indication Bits</b>		
<b>PLL Global Control Bits</b>		
EN_PLL	0x59	Master enable bit for the PLL circuit
EN_PLL_OUT	0x5F	Master enable bit for the PLL output
EN_PLL_BIAS	0x5F	Master enable bit for the PLL bias
EN_PLL_REFDIV	0x59	Master enable bit for the PLL reference divider
<b>PLL Block Setting Bits</b>		
PLL_REFDIV<9:0>	0x54-0x55	PLL reference divider (R) (See <a href="#">Table 4-7</a> )
PLL_PRE<11:0>	0x56-0x57	PLL prescaler (N) (See <a href="#">Table 4-7</a> )
PLL_CHAGPUMP<3:0>	0x58	PLL charge pump bias current control: from 25 $\mu$ A to 375 $\mu$ A, 25 $\mu$ A per step
PLL_RES<4:0>	0x5A	PLL loop filter resistor value selection (See <a href="#">Table 4-6</a> )
PLL_CAP3<4:0>	0x5B	PLL loop filter capacitor 3 value selection (See <a href="#">Table 4-6</a> )
PLL_CAP2<4:0>	0x5D	PLL loop filter capacitor 2 value selection (See <a href="#">Table 4-6</a> )
PLL_CAP1<4:0>	0x5C	PLL loop filter capacitor 1 value selection (See <a href="#">Table 4-6</a> )
<b>PLL Output Control Bits</b>		
PLL_OUTDIV<3:0>	0x55	PLL output divider (See <a href="#">Table 4-7</a> )
DCLK_DLY_PLL<2:0>	0x6D	Delay DCLK output up to 15 cycles of VCO clocks
EN_PLL_CLK	0x6D	EN_PLL_CLK = 1 enable PLL output clock to the ADC circuits
<b>PLL Drift Monitoring Bits</b>		
PLL_VCOL_STAT	0xD1	PLL drift status monitoring bit
PLL_VCOH_STAT	0xD1	PLL drift status monitoring bit
<b>PLL Block Calibration Bits</b>		
PLL_CAL_TRIG	0x6B	Forcing recalibration of the PLL
SOFT_RESET	0x00	PLL is calibrated when exiting soft reset mode
PLL_CAL_STAT	0xD1	PLL auto-calibration status indication

# MCP37220-200 AND MCP37D20-200

**TABLE 4-6: RECOMMENDED PLL CHARGE PUMP AND LOOP FILTER BIT SETTINGS**

PLL Charge Pump and Loop Filter Parameter	$f_Q = f_{REF}/PLL\_REFDIV$		
	$f_Q < 5 \text{ MHz}$	$5 \text{ MHz} \leq f_Q < 25 \text{ MHz}$	$f_Q \geq 25 \text{ MHz}$
PLL_CHAGPUMP<3:0>	0x04	0x04	0x04
PLL_RES<4:0>	0x1F	0x1F	0x07
PLL_CAP3<4:0>	0x07	0x02	0x07
PLL_CAP2<4:0>	0x07	0x01	0x08
PLL_CAP1<4:0>	0x07	0x01	0x08

**TABLE 4-7: EXAMPLE OF PLL CONTROL BIT SETTINGS FOR  $f_S = 200 \text{ MHz}$  WITH  $f_{REF} = 100 \text{ MHz}$**

PLL Control Parameter	Value	Descriptions
$f_{REF}$	100 MHz	$f_{REF}$ is coming from the external clock input
Target $f_S$ <sup>(1)</sup>	200 MHz	ADC sampling frequency
Target $f_{VCO}$ <sup>(2)</sup>	1.2 GHz	Range of $f_{VCO} = 1.0375 \text{ GHz} - 1.325 \text{ GHz}$
Target $f_Q$ <sup>(3)</sup>	10 MHz	$f_Q = f_{REF}/PLL\_REFDIV$ (See <a href="#">Table 4-6</a> )
PLL Reference Divider (R)	10	$PLL\_REFDIV<9:0> = 0x0A$
PLL Prescaler (N)	120	$PLL\_PRE<11:0> = 0x78$
PLL Output Divider	6	$PLL\_OUTDIV<3:0> = 0x06$

- Note 1:**  $f_S = f_{VCO}/PLL\_OUTDIV = 1.2 \text{ GHz}/6 = 200 \text{ MHz}$   
**Note 2:**  $f_{VCO} = (N/R) \times f_{REF} = (12) \times 100 \text{ MHz} = 1.2 \text{ GHz}$   
**Note 3:**  $f_Q$  should be maximized for the best noise performance.

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## 4.6 Digital Signal Post-Processing (DSPP) Options

While the device converts the analog input signals to digital output codes, the user can enable various digital signal post-processing (DSPP) options for special applications. These options are individually enabled or disabled by setting the configuration bits. [Table 4-8](#) summarizes the DSPP options that are available for each device.

**TABLE 4-8: DIGITAL SIGNAL POST-PROCESSING (DSPP) OPTIONS**

Digital Signal Post-Processing Option	Offering Device
FIR Decimation Filters	MCP37220-200
Digital Gain and Offset correction	MCP37D20-200
Digital Down-Conversion (DDC)	MCP37D20-200

### 4.6.1 DECIMATION FILTERS

[Figure 4-12](#) shows a simplified decimation filter block diagram and [Table 4-10](#) summarizes the related control parameters for using decimation filters.

- **MCP37220-200:** Decimation rate is controlled by  $FIR\_A<8:0>$  in Addresses 0x7A and 0x7B ([Registers 5-34 – 5-35](#)). The  $FIR\_A<8:0>$  provides a maximum programmable decimation rate up to 512x using nine cascaded decimation stages.
- **MCP37D20-200:** (a) When DDC mode is not required, only FIR A is used. (b) When digital down-conversion (DDC) is used for I and Q data filtering, both FIR A and FIR B filters are used (see [Figure 4-12](#)). In this case, both are set to the same decimation rate. Note that stage 1A in FIR A is unused: the user must clear  $FIR\_A<0>$  in Address 0x7A ([Register 5-34](#)).

The overall SNR performance can be improved with higher decimation rate. In theory, 3 dB improvement is expected with each successive stage of decimation (2x per stage), but the actual improvement is approximately 2.5 dB per stage due to finite attenuation in the FIR filters.

#### 4.6.1.1 Output Data Rate and Clock Phase Control when Decimation is Used

When decimation is used, it also reduces the output clock rate and output bandwidth by a factor equal to the decimation rate applied: the output clock rate is therefore no longer equal to the ADC sampling clock. The user needs to adjust the output clock and data rates in Address 0x02 ([Register 5-3](#)) based on the decimation applied. This allows the output data to be synchronized to the output data clock.

Phase shifts in the output clock can be achieved using  $DCLK\_PHDLY\_DEC<2:0>$  in Address 0x64 ([Register 5-22](#)). Only four output sampling phases are

available when decimation of 2x is used, while all eight clock phases are available for other decimation rates. See [Section 4.9.8 “Output Data And Clock Rates”](#) for more details.

#### 4.6.1.2 Using Decimation with Digital Down-Conversion (MCP37D20-200)

In the MCP37D20, the decimation feature can be used in conjunction with DDC. When DDC is enabled, the I and Q outputs can be decimated using I and Q channels. Since the half-band filter already includes a 2x decimation, the maximum possible decimation rate is 256x for each I and Q data using FIR A and FIR B filters (128x each from FIR A and B).

**Note:** Digital Gain/Offset adjustment and DDC for I/Q data options occur prior to the decimation filters if they are enabled.

**TABLE 4-9: DECIMATION RATE VS. SNR PERFORMANCE**

Decimation Rate	SNR (dBFS)
1x	67.8
2x	68.9
4x	71.8
8x	74.3
16x	76.8
32x	79
64x	81
128x	82.1
256x	82.7
512x	83.9

**Note:** The above data is valid with  $f_S = 200$  Msps,  $f_{IN} = 1$  MHz,  $A_{IN} = -1$ dBFS. The data may vary in other conditions.

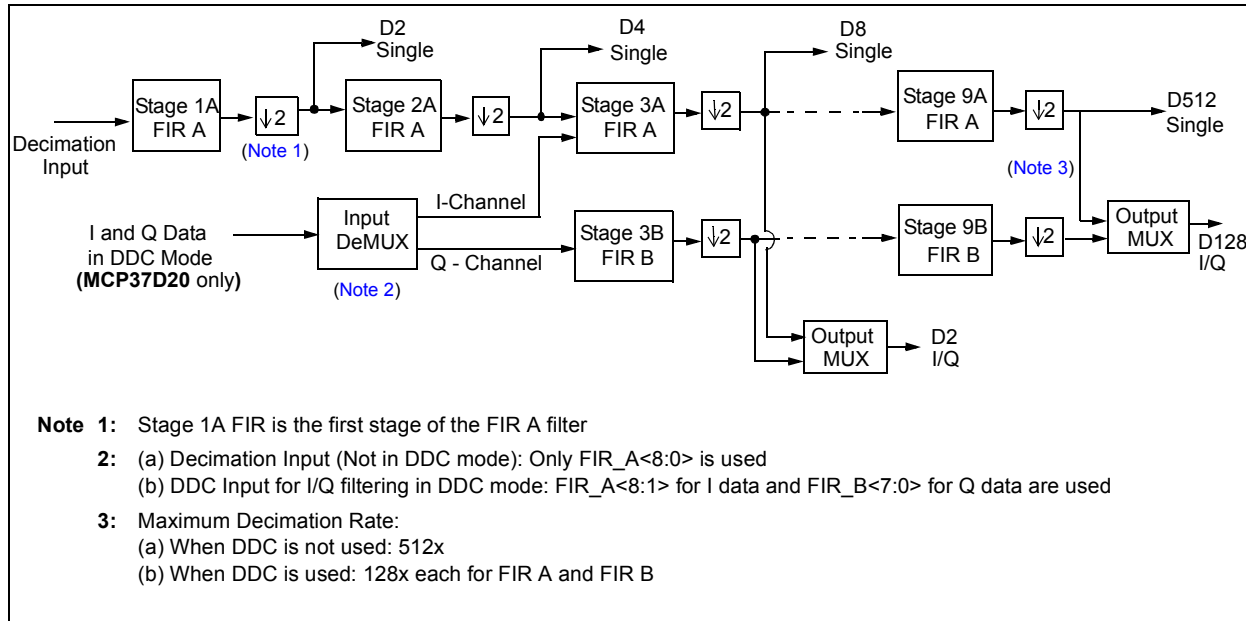
# MCP37220-200 AND MCP37D20-200

**TABLE 4-10: REGISTER CONTROL PARAMETERS FOR USING DECIMATION FILTERS**

Control Parameter	Register	Descriptions
<b>Decimation Filter Settings</b>		
FIR_A<8:0>	0x7A, 0x7B	FIR A configuration
FIR_B<7:0>	0x7C	FIR B configuration for Q-channel
<b>Output Data Rate and Clock Rate Settings<sup>(1)</sup></b>		
OUT_DATARATE<3:0>	0x02	Output data rate: Equal to decimation rate
OUT_CLKRATE<3:0>	0x02	Output clock rate: Equal to decimation rate
<b>Output Clock Phase Control Settings<sup>(2)</sup></b>		
EN_PHDLY	0x64	Enable digital output phase delay when decimation filter is used
DCLK_PHDLY_DEC<2:0>	0x64	Digital output clock phase delay control

**Note 1:** The output data and clock rates must be updated when decimation rates are changed.

**Note 2:** Output clock (DCLK) phase control is used when the output clock is divided by OUT\_CLKRATE<3:0> bit settings.



**FIGURE 4-12:** Simplified Block Diagram of Decimation Filters.

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#### 4.6.2 DIGITAL DOWN-CONVERSION (MCP37D20-200 ONLY)

The Digital Down-Conversion (DDC) feature is available in MCP37D20-200. This feature can be optionally combined with the decimation filter and used to:

- translate the input frequency spectrum to lower frequency band
- remove the unwanted out-of-band portion
- output the resulting signal as either I/Q data or a real signal centered at 1/4 of the output data rate.

Figure 4-13 shows the DDC configuration. The DDC includes a 32-bit complex numerically controlled oscillator (NCO), a selectable (high/low) half-band filter, optional decimation and two output modes (I/Q or  $f_s/8$ ).

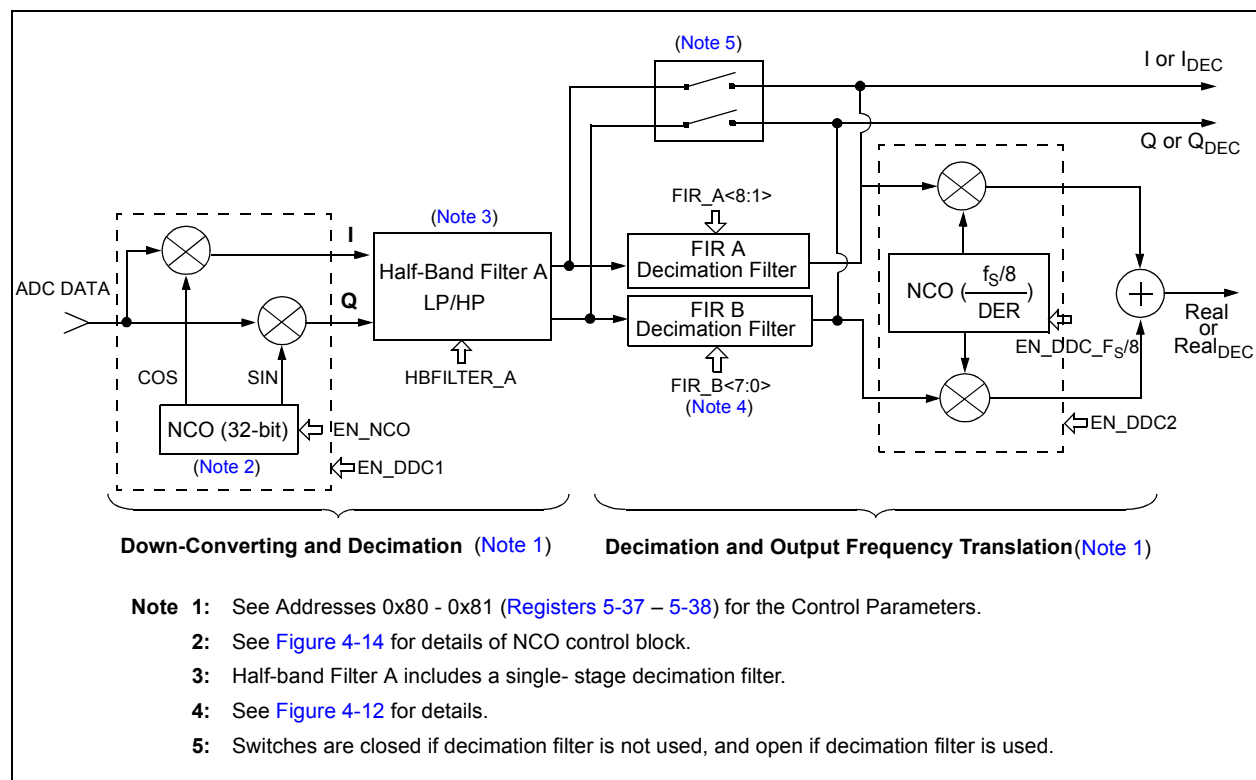
Frequency translation is accomplished with the NCO. The NCO frequency is programmable from 0 Hz to  $f_s$ . Phase and amplitude dither can be enabled to improve spurious performance of the NCO.

Each of the processing sub-blocks are individually controlled. Examples of setting registers for selected output type are shown in [Tables 4-11](#) and [4-12](#) in [Section 4.6.3 “Examples of Register Settings for DDC and Decimation”](#).

This DDC feature can be used in a variety of high-speed signal-processing applications, including digital radio, wireless base stations, radar, cable modems, digital video, MRI imaging, etc.

**Example:**

If the ADC is sampling an input at 200 Msps but the user is only interested in a 5 MHz span centered at 67 MHz, the digital down-conversion may be used to mix the sampled ADC data with 67 MHz to convert it to DC. The resulting signal can then be decimated by 16x such that the bandwidth of the ADC output is 6.25 MHz (200 Msps/16x decimation gives 12.5 Msps with 6.25 MHz Nyquist bandwidth). If  $f_s/8$  mode is selected, then a single 25 Msps channel is output, where 6.25 MHz in the output data corresponds to 67 MHz at the ADC input. If I/Q mode is selected, then two 12.5 Msps channels are output, where DC corresponds to 67 MHz and the channels represents In-Phase (I) and Quadrature (Q) components of the down-conversion.



**FIGURE 4-13:** Simplified DDC Block Diagram. See [Tables 4-11](#) and [4-12](#) for using this DDC Block.

# MCP37220-200 AND MCP37D20-200

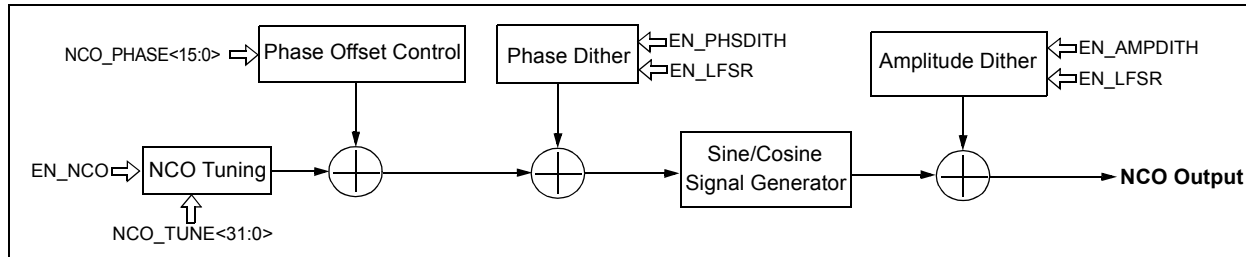
## 4.6.2.1 Numerically Controlled Oscillator (NCO)

The on-board Numerically Controlled Oscillator (NCO) provides the frequency reference for the In-Phase and Quadrature mixers in the digital down-converter (DDC).

The NCO serves as a quadrature local oscillator capable of producing an NCO frequency of between 0 Hz and  $f_S$  with a resolution of  $f_S/2^{32}$ , where  $f_S$  is the ADC core sampling frequency.

Figure 4-14 shows the control signals associated with the NCO.

**Note:** The NCO is only used for DDC. It should be disabled when not in use.



**FIGURE 4-14:** NCO Block Diagram.

### • NCO Frequency Control:

The NCO frequency is programmed from 0 Hz to  $f_S$ , using the 32-bit wide unsigned register variable `NCO_TUNE<31:0>` in Addresses 0x82 – 0x85 (Registers 5-39 – 5-42).

The following equation is used to set the `NCO_TUNE<31:0>` register:

### EQUATION 4-4: NCO FREQUENCY

$$NCO\_TUNE<31:0> = \text{round}\left(2^{32} \times \frac{\text{Mod}(f_{NCO}, f_S)}{f_S}\right)$$

Where:

- $f_S$  = sampling frequency (Hz)
- $f_{NCO}$  = desired NCO frequency (Hz)
- $\text{Mod}(f_{NCO}, f_S)$  = gives the remainder of  $f_{NCO}/f_S$

$\text{Mod}()$  is a remainder function. For example,  $\text{Mod}(5, 2) = 1$  and  $\text{Mod}(1.999, 2) = 1.999$ .

#### Example 1:

If  $f_{NCO}$  is 100 MHz and  $f_S$  is 200 MHz:

$$\begin{aligned} \text{Mod}(f_{NCO}, f_S) &= \text{Mod}(100, 200) = 100 \\ NCO\_TUNE<31:0> &= \text{round}\left(2^{32} \times \frac{\text{Mod}(100, 200)}{200}\right) \\ &= 0x8000\ 0000 \end{aligned}$$

#### Example 2:

If  $f_{NCO}$  is 199.9999994 MHz and  $f_S$  is 200 MHz:

$$\begin{aligned} \text{Mod}(f_{NCO}, f_S) &= \text{Mod}(199.9999994, 200) = 199.9999994 \\ NCO\_TUNE<31:0> &= \text{round}\left(2^{32} \times \frac{\text{Mod}(199.9999994, 200)}{200}\right) \\ &= 0xFFFF\ FFFF \end{aligned}$$

## 4.6.2.2 NCO Amplitude and Phase Dither

The `EN_AMPDITH` and `EN_PHSDITH` parameters in Address 0x80 (Register 5-37) can be used for amplitude and phase dithering, respectively. In principle, these will dither the quantization error created by the use of digital circuits in the mixer and local oscillator, thus reducing spurs at the expense of noise. In practice, the DDC circuitry has been designed with sufficient noise and spurious performance for most applications. In the worst case scenario, the NCO has an SFDR of greater than 116 dB when the amplitude dither is enabled and 112 dB when disabled. Although the SNR ( $\approx 93$  dB) of the DDC is not significantly affected by the dithering option, using the NCO with dithering options enabled is always recommended for the best performance.

## 4.6.2.3 NCO for $f_S/8$ and $f_S/(8 \times \text{DER})$

The output of the first down-conversion block (DDC1) is a complex signal (comprising I and Q data) which can then be optionally decimated further up to 128x to provide both a lower output data rate and input channel filtering. If  $f_S/8$  mode is enabled, a second mixer stage (DDC2) will convert the I/Q signals from the DDC1 to a real signal centered at half of the current Nyquist frequency; i.e., if the current output data rate for I and Q is 25 Msps each (12.5 MHz Nyquist), then in  $f_S/8$  mode the output data rate would be 50 Msps (25 Msps x2 for I and Q) and the resulting real signal after combining the two would be re-centered around 12.5 MHz. This second frequency translation by DDC2 is accomplished after the decimation filters (if used) as shown in Figure 4-13.

When decimation is enabled, the I/Q outputs are up-converted by  $f_S/(8 \times \text{DER})$ , where DER is the additional decimation rate added by the FIR decimation filters. This provides a decimated output signal centered at  $f_S/8$  or  $f_S/(8 \times \text{DER})$  in the frequency domain.

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## 4.6.2.4 NCO Phase Offset Control

The user can add phase offset to the NCO frequency using the NCO phase offset control registers (Addresses 0x86 to 0x87 – [Registers 5-43 – 5-44](#)). NCO\_PHASE<15:0> is the 16-bit-wide NCO phase offset control parameter. The phase offset can be controlled from 0° to 359.995° with 0.005° per step. The following equation is used to program the NCO phase offset register:

### EQUATION 4-5: NCO PHASE OFFSET

$$NCO\_PHASE<15:0> = 2^{16} \times \frac{\text{Offset Value } (\phi)}{360}$$

where:

Offset Value ( $\phi$ ) = desired phase offset value in degrees

A decimal number is used for the binary contents of the NCO\_PHASE<15:0>.

## 4.6.2.5 In-Phase and Quadrature Signals

When the first down-conversion is enabled, it produces In-phase (I) and Quadrature (Q) components given by:

### EQUATION 4-6: I AND Q SIGNALS

$$I = ADC \times \cos(2\pi f_{NCO}t + \phi)$$

$$Q = ADC \times \sin(2\pi f_{NCO}t + \phi)$$

where:

$$\begin{aligned} \phi &= 360 \times \frac{NCO\_PHASE<15:0>}{2^{16}} \\ &= 0.005493164^\circ \times NCO\_PHASE<15:0> \end{aligned}$$

where:

ADC = output of the ADC block

$\phi$  = NCO phase offset defined by NCO\_PHASE<15:0> in Address 0x86

t = k/f<sub>S</sub>, with k = 1, 2, 3, ..., n

f<sub>NCO</sub> = NCO frequency

I and Q data are output in an interleaved fashion where I data is output on the rising edge of the WCK.

## 4.6.2.6 Half-Band Filter

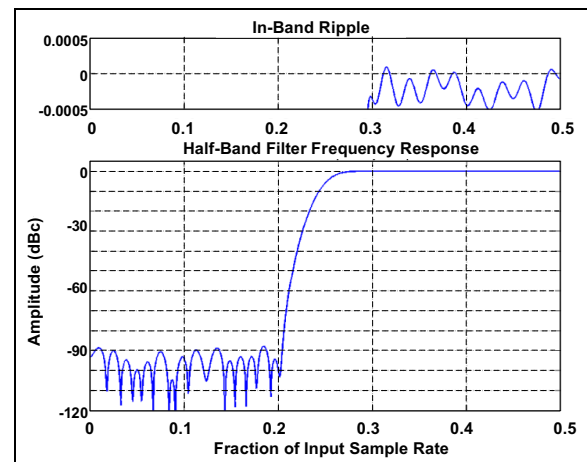
The frequency translation is followed by a half-band digital filter, which is used to reduce the sample rate by a factor of two while rejecting aliases that fall into the band of interest.

The user can select a high- or low-pass half-band filter using the HBFILTER\_A bit in Address 0x80 ([Register 5-37](#)). [Figures 4-15 and 4-16](#) show the transfer functions of the filters. These filters provide greater than 90 dB of attenuation in the attenuation band, and less than 1 mdB (10<sup>-3</sup> dB) of ripple in the passband region of 20% of the input sampling rate.

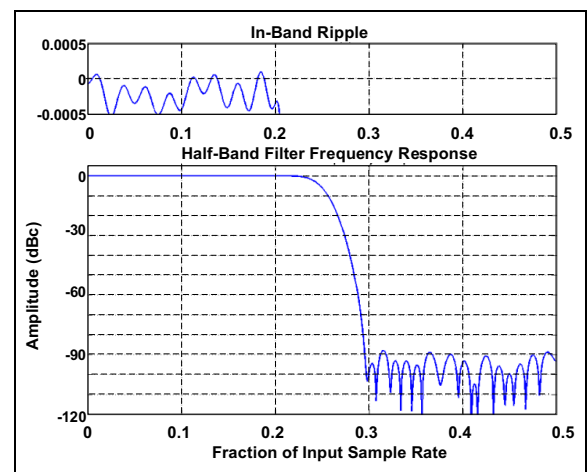
For example, for an ADC sample rate of 200 Msps, these filters provide less than 1 mdB of ripple over a bandwidth of 40 MHz.

The filter responses shown in [Figures 4-15 and 4-16](#) indicate a ripple of 0.5 mdB and an alias rejection of 90 dB. The output of the half-band filter is a DC-centered complex signal (I and Q). This I and Q signal is then carried to the next down-conversion stage (DDC2) for frequency translation (up-conversion), if the DDC is enabled.

**Note:** The half-band filter delays the data output by 80 clock cycles: 2 (due to decimation) x 40 cycles (due to filter group delay)



**FIGURE 4-15:** High-Pass (HP) Response of Half-Band Filter.



**FIGURE 4-16:** Low-Pass (LP) Response of Half-Band Filter.



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## 4.6.3 EXAMPLES OF REGISTER SETTINGS FOR DDC AND DECIMATION

The following tables show examples of setting registers for using digital down-conversion (DDC) with decimation depending on the output type selection. This feature is available in the MCP37D20-200 device only.

**TABLE 4-11: REGISTER SETTINGS FOR DDC AND DECIMATION OPTIONS – EXAMPLE**

Decimation Rate (by FIR A and FIR B) <sup>(1)</sup>	DDC Mode	Address 0x02 <sup>(2)</sup>	FIR A Filter		FIR B Filter	DDC1	DDC2	Output
			0x7A<6> (FIR_A<0>)	0x7B (FIR_A<8:1>)	0x7C (FIR_B<7:0>)	0x80<5,1,0> <sup>(3)</sup>	0x81<6> <sup>(4)</sup>	
0	Disabled	0x00	0	0x00	0x00	0,0,0	0	ADC
8	Disabled	0x33	1	0x03	0x00	0,0,0	0	ADC with decimation (+8)
512	Disabled	0x99	1	0xFF	0x00	0,0,0	0	ADC with decimation (+512)
0	I/Q	0x00 <sup>(5)</sup>	0	0x00	0x00	1,0,1	0	I/Q Data
8	I/Q	0x33	0	0x07	0x07	1,0,1	0	Decimated I/Q (+8)
0	$f_S/8$	0x11 <sup>(6)</sup>	0	0x00	0x00	1,1,1	0	Real without additional decimation
8	$f_S/8$	0x44	0	0x07	0x07	1,0,1	1	Real with decimation (+16)

- Note 1:** When DDC is used, the actual total decimation is 2x larger since 2x is included from the DDC Half-Band Filter.  
Example: Decimation = 8x with DDC-IQ option actually has 16x decimation with 8x provided by the decimation filter and 2x from the DDC Half-Band Filter.
- 2:** Output data and clock rate control register.
- 3:** 0x80<5,1,0> = <EN\_NCO, EN\_DDC\_FS/8, EN\_DDC1>.
- 4:** 0x81<6> = <EN\_DDC2>.
- 5:** Each of I/Q has 1/2 of  $f_S$  bandwidth. The combined bandwidth is the same as the  $f_S$  bandwidth. Therefore, the data rate adjustment is not needed.
- 6:** The Half-Band Filter A includes decimation of 2.



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**TABLE 4-12: OUTPUT TYPE VS. CONTROL PARAMETERS FOR DDC – EXAMPLE**

Output Type	Control Parameter	Register	Descriptions
Complex: I and Q	EN_DDC1 = 1	0x80	Enable DDC1 block
	EN_NCO = 1	0x80	Enable 32-bit NCO
	HBFILTER_A = 1	0x80	Enable Half-Band Filter A, includes 2x decimation
	EN_DDC_FS/8 = 0	0x80	NCO ( $f_S/8/DER$ ) is disabled
	EN_DDC2 = 0	0x81	DDC2 is disabled
	FIR_A<8:1> = 0x00	0x7B	FIR A decimation filter is disabled
	FIR_B<7:0> = 0x00	0x7C	FIR B decimation filter is disabled
	OUT_CLKRATE<3:0>	0x02	Output clock rate is not affected (no need to change)
Decimated I and Q: I <sub>DEC</sub> , Q <sub>DEC</sub>	EN_DDC1 = 1	0x80	Enable DDC1 block
	EN_NCO = 1	0x80	Enable 32-bit NCO
	HBFILTER_A = 1	0x80	Enable Half-Band Filter A, includes 2x decimation
	EN_DDC_FS/8 = 0	0x80	NCO ( $f_S/8/DER$ ) is disabled
	EN_DDC2 = 0	0x81	DDC2 is disabled
	FIR_A<8:1>	0x7B	Program FIR A filter for extra decimation <sup>(1)</sup>
	FIR_B<7:0>	0x7C	Program FIR B filter for extra decimation <sup>(1)</sup>
	OUT_CLKRATE<3:0>	0x02	Adjust the output clock rate to the decimation rate
Real: Real <sub>A</sub> after DDC( $f_S/8/DER$ ) without using Decimation Filter	EN_DDC1 = 1	0x80	Enable DDC1 block
	EN_NCO = 1	0x80	Enable 32-bit NCO
	HBFILTER_A = 1	0x80	Enable Half-Band Filter A, includes 2x decimation
	EN_DDC_FS/8 = 1	0x80	NCO ( $f_S/8/DER$ ) is enabled. This translates the input signal from DC to $f_S/8$ <sup>(2)</sup>
	EN_DDC2 = 1	0x81	DDC2 is enabled
	FIR_A<8:1> = 0x00	0x7B	Decimation filter FIR A is disabled
	FIR_B<7:0> = 0x00	0x7C	Decimation filter FIR B is disabled
	OUT_CLKRATE<3:0> = 0001	0x02	Adjust the output clock rate to divided by 2 <sup>(3)</sup>
Decimated Real: Real <sub>A_DEC</sub> after Decimation Filter and DDC( $f_S/8/DER$ )	EN_DDC1 = 1	0x80	Enable DDC1 block
	EN_NCO = 1	0x80	Enable 32-bit NCO
	HBFILTER_A = 1	0x80	Enable Half-Band Filter A, includes 2x decimation
	EN_DDC_FS/8 = 1	0x80	NCO ( $f_S/8/DER$ ) is enabled. This translates the input signal from DC to $f_S/8/DER$ <sup>(2)</sup>
	EN_DDC2 = 1	0x81	DDC2 is enabled
	FIR_A<8:1>	0x7B	Program FIR B filter for extra decimation <sup>(4)</sup>
	FIR_B<7:0>	0x7C	Program FIR B filter for extra decimation <sup>(4)</sup>
	OUT_CLKRATE<3:0>	0x02	Adjust the output clock rate to the total decimation rate including the 2x decimation by the Half-Band Filter A

**Note 1:** For I/Q decimation, the maximum decimation rate for the FIR A and FIR B filters is 128x each since the input is already decimated by 2x in the Half-Band Filter. See [Figure 4-12](#) for details.

**2:** DER is the decimation rate setting of the FIR A and FIR B filters.

**3:** The Half-Band Filter A includes decimation of 2.

**4:** When this filter is used, the up-conversion frequency is reduced by the extra decimation rates (DER).

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## 4.7 Digital Offset and Digital Gain Settings

Figure 4-17 shows a simplified block diagram of the digital offset and gain settings. Offset is applied prior to the gain. Offset and gain adjustments occur prior to DDC or decimation when these features are used.

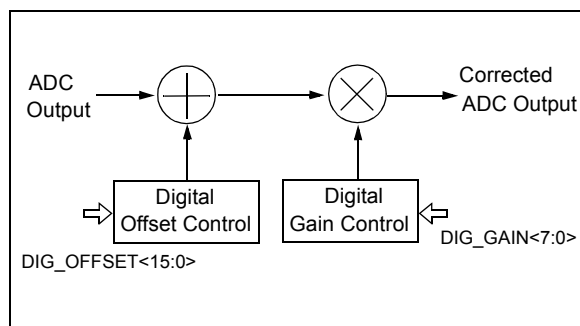
### 4.7.1 DIGITAL OFFSET SETTINGS

The ADC digital offset can be controlled using two combined digital offset correction registers: DIG\_OFFSET<15:0> in Addresses 0x66 - 0x67.

### 4.7.2 DIGITAL GAIN SETTINGS

The ADC digital gain can be controlled using DIG\_GAIN<7:0> in Addresses 0x96 - 0x9D. All DIG\_GAIN<7:0> in Addresses 0x96 - 0x9D must be programmed with the same value.

When the device is first powered-up or has hardware reset, DIG\_GAIN<7:0> is set with a default setting ('0011-1100'). The user may program the DIG\_GAIN<7:0> to '0011-1000' for optimum SNR performance (0.7 dB higher than the default setting).



**FIGURE 4-17:** Simplified Block Diagram for Digital Offset and Gain Settings.

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## 4.8 Output Data Format

The device can output the ADC data in offset binary or two's complement. The data format is selected by the DATA\_FORMAT bit in Address 0x62 ([Register 5-20](#)).

[Table 4-13](#) shows the relationship between the analog input voltage, the digital data output bits and the overrange bit. By default, the output data format is two's complement.

**TABLE 4-13: ADC OUTPUT CODE VS. INPUT VOLTAGE**

Input Range	Offset Binary <sup>(1)</sup>	Two's Complement <sup>(1)</sup>	Overrange (OVR)
$A_{IN} > A_{FS}$	11-1111-1111-1111	01-1111-1111-1111	1
$A_{IN} = A_{FS}$	11-1111-1111-1111	01-1111-1111-1111	0
$A_{IN} = A_{FS} - 1 \text{ LSB}$	11-1111-1111-1110	01-1111-1111-1110	0
$A_{IN} = A_{FS} - 2 \text{ LSB}$	11-1111-1111-1100	01-1111-1111-1100	0
	•		
	•		
	•		
$A_{IN} = A_{FS}/2$	11-0000-0000-0000	01-0000-0000-0000	0
$A_{IN} = 0$	10-0000-0000-0000	00-0000-0000-0000	0
$A_{IN} = -A_{FS}/2$	00-1111-1111-1111	10-1111-1111-1111	0
	•		
	•		
	•		
$A_{IN} = -A_{FS} + 2 \text{ LSB}$	00-0000-0000-0010	10-0000-0000-0010	0
$A_{IN} = -A_{FS} + 1 \text{ LSB}$	00-0000-0000-0001	10-0000-0000-0001	0
$A_{IN} = -A_{FS}$	00-0000-0000-0000	10-0000-0000-0000	0
$A_{IN} < -A_{FS}$	00-0000-0000-0000	10-0000-0000-0000	1

**Note 1:** MSb is sign bit.

## 4.9 Digital Output

The MCP37220-200 and MCP37D20-200 can operate in one of the following two digital output modes:

- Full-Rate CMOS
- Double-Data-Rate (DDR) LVDS

The outputs are powered by  $DV_{DD18}$  and GND. LVDS mode is recommended for data rates above 80 Msp. The digital output mode is selected by the OUTPUT\_MODE<1:0> bits in Address 0x62 ([Register 5-20](#)). [Figures 2-1](#) – [2-2](#) show the timing diagrams of the digital output.

### 4.9.1 FULL-RATE CMOS MODE

In full-rate CMOS mode, the data outputs (Q13 to Q0), overrange indicator (OVR), word clock (WCK) and the data output clock (DCLK+, DCLK-) have CMOS output levels. The WCK is disabled, except for the I/Q data output mode in the MCP37D20. The digital output should drive minimal capacitive loads. If the load capacitance is larger than 10 pF, a digital buffer should be used.

### 4.9.2 DOUBLE-DATA-RATE LVDS MODE

The double-data-rate (DDR) LVDS mode is a parallel data stream which changes on each edge of the output clock. See [Figure 2-2](#) for details.

In I/Q data output mode in the MCP37D20-200, I and Q data are clocked out sequentially with the WCK that is synchronized to I data. OVR and WCK are an LVDS pair.

The device outputs the following LVDS output pairs:

- Output data: Q6+/Q6- through Q0+/Q0-
- Output clock: DCLK+/DCLK-
- OVR/WCK

Note that WCK is logic '0' except in I/Q mode.

A 100Ω differential termination resistor is required for each LVDS output pin pair. The termination resistor should be located as close as possible to the LVDS receiver. By default, the outputs are standard LVDS levels: 3.5 mA output current with a 1.15V output common-mode voltage on 100Ω differential load. See Address 0x63 ([Register 5-21](#)) for more details of the LVDS mode control.

**Note:** LVDS output polarity can be controlled independently for each LVDS pair. See POL\_LVDS<6:0> setting in Address 0x65 ([Register 5-23](#))

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## 4.9.3 OVERRANGE BIT (OVR)

The input overrange status bit is asserted (logic high) when the analog input has exceeded the full-scale range of the ADC in either the positive or negative direction. The OVR bit has the same pipeline latency as the ADC data bits. See Address 0x68 ([Register 5-26](#)) for OVR control options.

If DSPP option is enabled, OVR pipeline latency will be unaffected; however, the data will incur additional delay. This has the effect of allowing the OVR indicator to precede the affected data.

### 4.9.3.1 OVR Bit in LVDS DDR Output Mode

#### (a) Normal ADC Output Mode:

The device outputs the OVR bit on the falling edge of the data output clock.

#### (b) I and Q Output Mode in MCP37D20-200:

The OVR bit is multiplexed with the word clock (WCK) output bit, such that OVR is output on the falling edge of the data output clock and WCK on the rising edge.

## 4.9.4 WORD CLOCK (WCK)

- MCP37220-200: WCK is disabled.
- MCP37D20-200: WCK is available in I/Q data output mode only. WCK is asserted coincidentally with the I data. See Address 0x68 ([Register 5-26](#)) for OVR and WCK control options.

## 4.9.5 LVDS OUTPUT POLARITY CONTROL

In LVDS mode, the output polarity can be controlled independently for each LVDS pair. [Table 4-14](#) summarizes the LVDS output polarity control register bits.

**TABLE 4-14: LVDS OUTPUT POLARITY CONTROL**

Control Parameter	Register	Descriptions
POL_LVDS<6:0>	0x65	Control polarity of LVDS data pairs
POL_OVR_WCK	0x68	Control polarity of OVR and WCK bit pair

## 4.9.6 PROGRAMMABLE LVDS OUTPUT CURRENT

In LVDS mode, the default output driver current is 3.5 mA. This current can be adjusted by using the LVDS\_IMODE<2:0> bit setting in Address 0x63 ([Register 5-21](#)). Available output drive currents are 1.8 mA, 3.5 mA, 5.4 mA, and 7.2 mA.

## 4.9.7 OPTIONAL LVDS DRIVER INTERNAL TERMINATION

In most cases, using an external 100Ω termination resistor will give excellent LVDS signal integrity. In addition, an optional internal 100Ω termination resistor can be enabled by setting the LVDS\_LOAD bit in Address 0x63 ([Register 5-21](#)). The internal termination helps absorb any reflections caused by imperfect impedance termination at the receiver.

## 4.9.8 OUTPUT DATA AND CLOCK RATES

The user can reduce output data and output clock rates using Address 0x02 ([Register 5-3](#)). When decimation or digital down-conversion (DDC) is used, the output data rate has to be reduced to synchronize with the reduced output clock rate.

## 4.9.9 PHASE SHIFTING OF OUTPUT CLOCK (DCLK)

In full-rate CMOS mode, the data output bit transition occurs at the rising edge of DCLK+, so the falling edge of DCLK+ can be used to latch the output data.

In double-data-rate LVDS mode, the data transition occurs at both the rising and falling edges of DCLK+. For adequate setup and hold time when latching the data into the external host device, the user can shift the phase of the digital clock output (DCLK+/DCLK-), relative to the data output bits.

The output phase shift (delay) is controlled by each unique register, depending on which timing source is used or if decimation is used. [Table 4-15](#) shows the output clock phase control registers for each configuration mode: (a) when DLL is used, (b) when decimation is used and (c) when PLL is used.

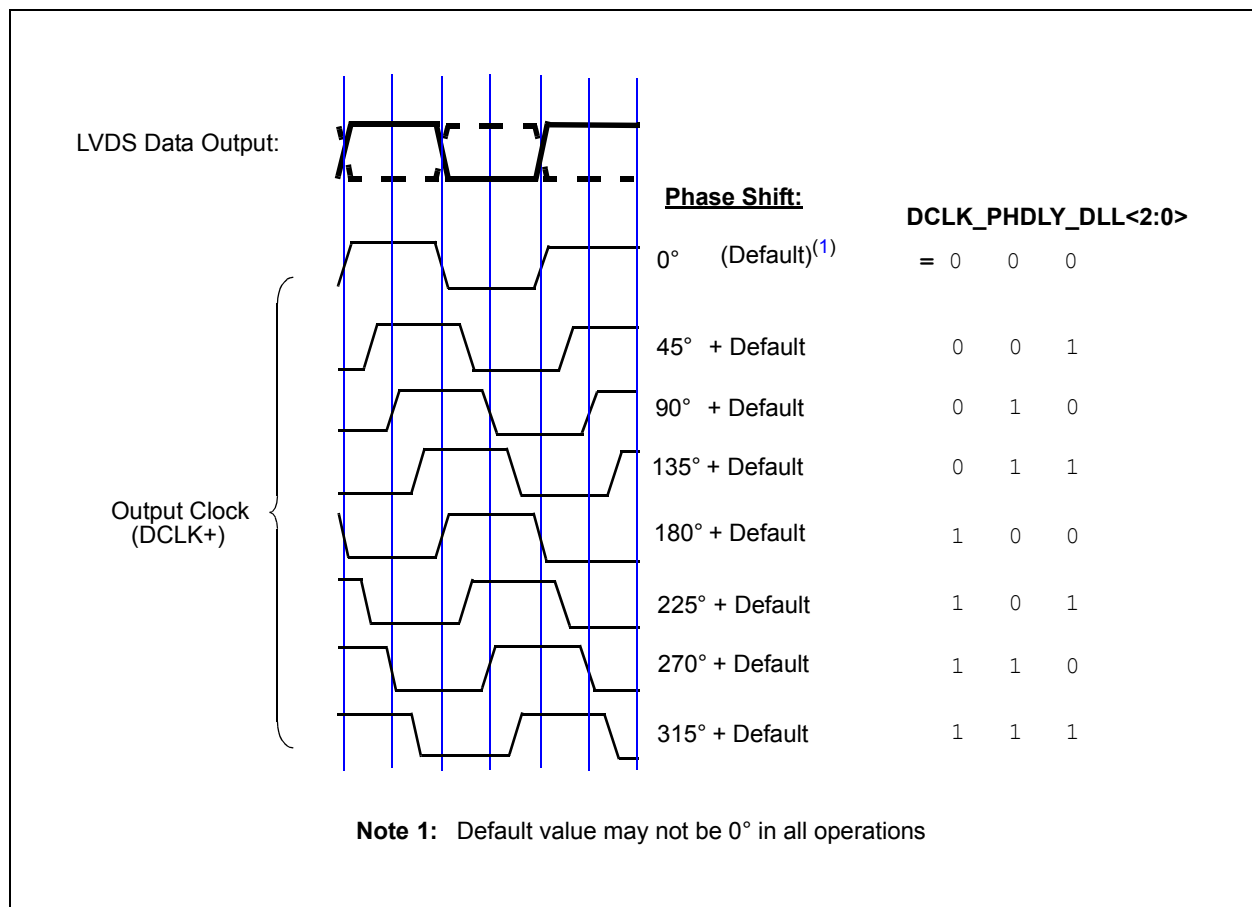
[Figure 4-18](#) shows an example of the output clock phase delay control using DCLK\_PHDLY\_DLL<2:0> when DLL is used.

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**TABLE 4-15: OUTPUT CLOCK (DCLK) PHASE CONTROL PARAMETERS**

Control Parameter	Register	Operating Condition <sup>(1)</sup>
When DLL is used:		
EN_PHDLY	0x64	EN_PHDLY = 1: Enable output clock phase delay control
DCLK_PHDLY_DLL<2:0>	0x52	DCLK phase delay control when DLL is used. Decimation is not used.
When decimation is used:		
EN_PHDLY	0x64	EN_PHDLY = 1: Enable output clock phase delay control
DCLK_PHDLY_DEC<2:0>		DCLK phase delay control when decimation filter is used. The phase delay is controlled in digital clock output control block.
When PLL is used:		
DCLK_DLY_PLL<2:0>	0x6D	DCLK delay control when PLL is used.

**Note 1:** See Figure 4-11 for details.



**FIGURE 4-18:** Example of Phase Shifting of Digital Output Clock (DCLK+) when DLL is used.

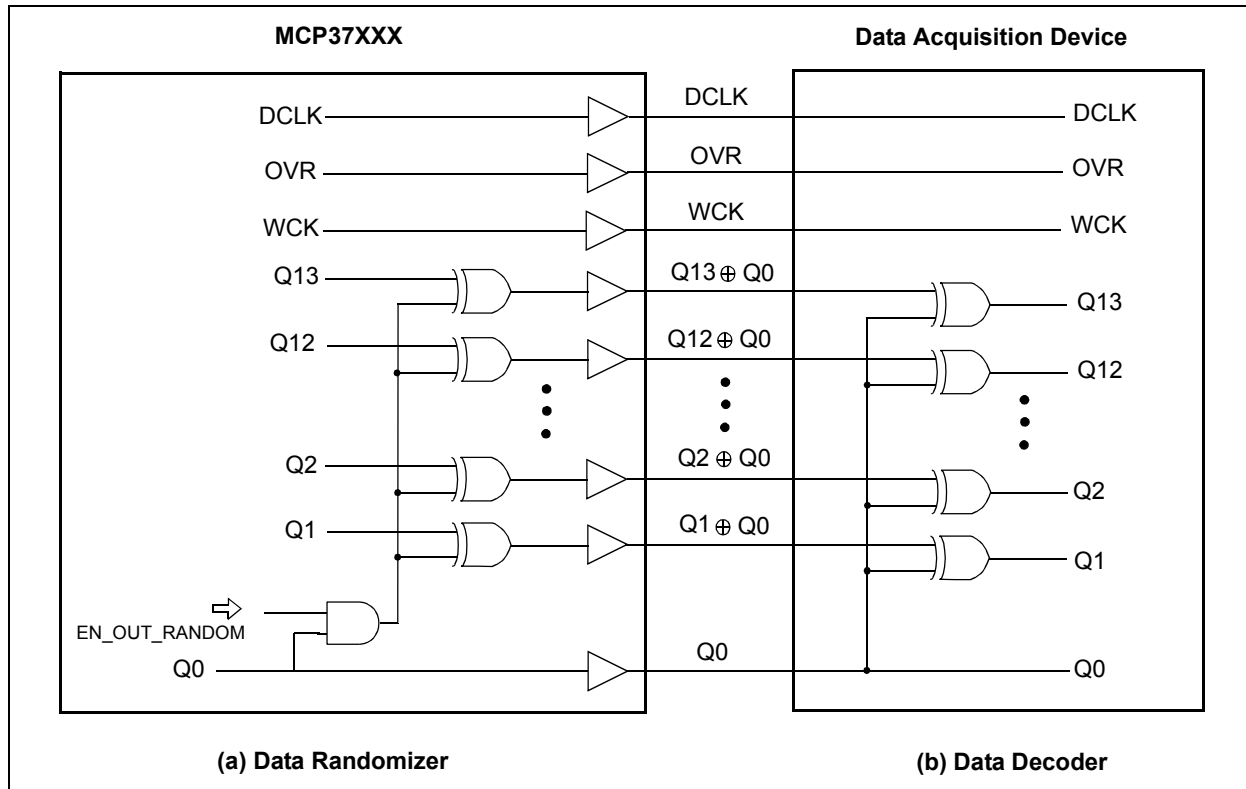
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## 4.9.10 DIGITAL OUTPUT RANDOMIZER

Depending on PCB layout considerations and power supply coupling, SFDR may be improved by decorrelating the ADC input from the ADC digital output data. The device includes an output data randomizer option. When this option is enabled, the digital output is randomized by applying an exclusive-OR logic operation between the LSb (D0) and all other data output bits.

To decode the randomized data, the reverse operation is applied: an exclusive-OR operation is applied between the LSb (D0) and all other bits. The DCLK, OVR, WCK and LSb (D0) outputs are not affected.

Figure 4-19 shows the block diagram of the data randomizer and decoder logic. The output randomizer is enabled by setting the EN\_OUT\_RANDOM bit in Address 0x07 (Register 5-5).



**FIGURE 4-19:** Logic Diagram for Digital Output Randomizer and Decoder.

## 4.9.11 OUTPUT DISABLE

The digital output can be disabled by setting OUTPUT\_MODE<1:0> = 00 in Address 0x62 (Register 5-20). All digital outputs are disabled, including OVR, DCLK, etc.

## 4.9.12 OUTPUT TEST PATTERNS

To facilitate testing of the I/O interface, the device can produce various predefined or user-defined patterns on the digital outputs. See TEST\_PATTERNS<2:0> in Address 0x62 (Register 5-20) for the predefined test patterns. For the user-defined test patterns, Addresses 0x74 – 0x77 (Registers 5-29 – 5-32) can be used. When an output test mode is enabled, the ADC's analog section can still be operational, but does not drive the digital outputs. The outputs are driven only with the selected test pattern.

Since the output test pins (TP, TP1 and TP2) can toggle during this test, always leave these test pins floating (not connected) to avoid contention and excess current draws.

## 4.9.12.1 Pseudo-Random Number (PN) Sequence Output

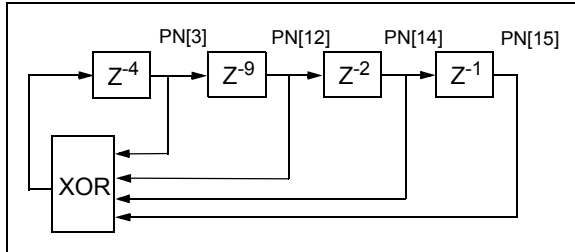
When TEST\_PATTERNS<2:0> = 111, the device outputs a pseudo-random number (PN) sequence which is defined by the polynomial of degree 16, as shown in Equation 4-7. Figure 4-20 shows the block diagram of a 16-bit Linear Feedback Shift Register (LFSR) for the PN sequence.

### EQUATION 4-7: POLYNOMIAL FOR PN

$$P(x) = 1 + x^4 + x^{13} + x^{15} + x^{16}$$

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The output PN[15:2] is directly applied to the output pins Qn[13:0]. In addition to the output at the Qn[13:0] pins, PN[15] is copied to the OVR pin and PN[14] is copied to the WCK pin. In CMOS output mode, the pattern is always applied to all CMOS I/O pins, regardless whether or not they are enabled. In LVDS output mode, the pattern is only applied to the LVDS pairs that are enabled.



**FIGURE 4-20:** Block Diagram of 16-bit LFSR for Pseudo-Random Number (PN) Sequence for Output Test Pattern.

## 4.10 System Calibration

The built-in system calibration algorithm includes:

- Harmonic Distortion Correction (HDC)
- DAC Noise Cancellation (DNC)
- Dynamic Element Matching (DEM)

HDC and DNC correct the nonlinearity in the residue amplifier and DAC, respectively. The system calibration is performed by:

- Power-up calibration, which takes place during the Power-on Reset sequence (requires  $3 \times 2^{26}$  clock cycles)
- Background calibration, which takes place during normal operation (per  $2^{30}$  clock cycles).

Background calibration time is invisible to the user and primarily affects the ADC's ability to track variations in ambient temperature.

The calibration status is monitored by the CAL pin or the ADC\_CAL\_STAT bit in Address 0xC0 (Register 5-67). See also Address 0x07 (Register 5-5) and 0x1E (Register 5-6) for time delay control of the auto-calibration. Table 4-16 shows the calibration time for various ADC core sample rates.

**TABLE 4-16: CALIBRATION TIME VS. ADC CORE SAMPLE RATE**

$f_s$ (Mps)	200	150	100	70	50
Power-Up Calibration Time (s)	1.01	1.34	2.01	2.88	4.03
Background Calibration Time (s)	5.37	7.16	10.73	15.34	21.48

## 4.10.1 RESET COMMAND

Although the background calibration will track changes in temperature or supply voltage, changes in clock frequency or register configuration should be followed by a recalibration of the ADC. This can be accomplished via either the Hard or the Soft Reset command. The recalibration time is the same as the power-up calibration time. Resetting the device is highly recommended when exiting from Shutdown or Standby mode after an extended amount of time. During the reset, the device has the following state:

- No ADC output
- No change in power-on condition of internal reference
- Most of the internal clocks are not distributed
- Contents of internal user registers:
  - Not affected by Soft Reset
  - Reset to default values by Hardware Reset
- Current consumption of the digital section is negligible, but no change in the analog section.

### 4.10.1.1 Hardware Reset

A hard reset is triggered by toggling the  $\overline{\text{RESET}}$  pin. On the rising edge, all internal calibration registers and user registers are initialized to their default states and recalibration of the ADC begins. The recalibration time is the same as the power-up calibration time. See Figure 2-6 for the timing details of the hardware RESET pin.

### 4.10.1.2 Soft Reset

The user can issue a Soft Reset command for a fast recalibration of the ADC by setting the  $\overline{\text{SOFT\_RESET}}$  bit to '0' in Address 0x00 (Register 5-1). During Soft Reset, all internal calibration registers are initialized to their initial default states. User registers are unaffected. When exiting the Soft Reset (changing from '0' to '1'), an automatic device calibration takes place.

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## 4.11 Power Dissipation and Power Savings

The power dissipation of the ADC core is proportional to the sample rate ( $f_S$ ). The digital power dissipation of the CMOS outputs are determined primarily by the strength of the digital drivers and the load condition on each output pin. The maximum digital load current ( $I_{LOAD}$ ) can be calculated as:

### EQUATION 4-8: CMOS OUTPUT LOAD CURRENT

$$I_{LOAD} = DV_{DD1.8} \times f_{DCLK} \times N \times C_{LOAD}$$

Where:

N = Number of bits

$C_{LOAD}$  = Capacitive load of output pin

The capacitive load presented at the output pins needs to be minimized to minimize digital power consumption. The output load current of the LVDS output is constant, since it is set by LVDS\_IMODE<2:0> in Address 0x63 ([Register 5-21](#)).

### 4.11.1 POWER-SAVING MODES

This device has two power-saving modes:

- Shutdown
- Standby

They are set by the SHUTDOWN and STANDBY bits in Address 0x00 ([Register 5-1](#)).

In Shutdown mode, most of the internal circuitry, including the reference and clock, are turned off with the exception of the SPI interface. During Shutdown mode, the device consumes 25 mA (typical), primarily due to digital leakage. When exiting from Shutdown mode, issuing a Soft Reset at the same time is highly recommended. This will perform a fast recalibration of the ADC. The contents of the internal registers are not affected by the Soft Reset.

In Standby mode, most of the internal circuitry is disabled, except for the reference, clock and SPI interface. If the device has been in standby for an extended period of time, the current calibration value may not be accurate. Therefore, when exiting from Standby mode, executing the device Soft Reset at the same time is highly recommended.



# MCP37220-200 AND MCP37D20-200

## 5.0 SERIAL PERIPHERAL INTERFACE (SPI)

The user can configure the ADC for specific functions or optimized performance by setting the device's internal registers through the Serial Peripheral Interface (SPI). The SPI communication uses three pins:  $\overline{\text{CS}}$ , SCLK and SDIO. Table 5-1 summarizes the SPI pin functions. The SCLK is used as serial timing clock and can be used up to 50 MHz.

SDIO (Serial Data Input/Output) is a dual-purpose pin that allows data to be sent or read from the internal registers. The Chip Select ( $\overline{\text{CS}}$ ) pin enables the SPI communication when active-low. The falling edge of  $\overline{\text{CS}}$  followed by a rising edge of SCLK determines the start of the SPI communication. When  $\overline{\text{CS}}$  is tied to high, the SPI communication is disabled and SPI pins are placed in high-impedance mode. The internal registers are accessible by their address.

Figures 5-1 and 5-2 show the SPI data communication protocols for this device with MSb-first and LSb-first option, respectively. It consists of:

- 16-bit wide instruction header + Data byte 1 + Data byte 2 + . . . + Data Byte N

Table 5-2 summarizes the bit functions. The  $\overline{\text{R/W}}$  bit of the instruction header indicates whether the command is a read ('1') or a write ('0'):

- If the  $\overline{\text{R/W}}$  bit is '1', the SDIO pin changes direction from an input (SDI) to an output (SDO) after the 16-bit wide instruction header.

By selecting the  $\overline{\text{R/W}}$  bit, the user can write the register or read back the register contents. The W1 and W2 bits in the instruction header indicate the number of data bytes to transmit or receive in the following data frame.

A2 – A0 bits are the SPI device address bits. These bits are used when multiple devices are used in the same SPI bus. A2 is internally hard-coded to '0'. A1 and A0 bits correspond to the logic level of ADR1 and ADR0 pins, respectively.

**Note:** In VTLA-124 package, ADR1 is internally bonded to ground (logic '0').

The R9 – R0 bits represent the starting address of the configuration register to write or read. The data bytes following the instruction header are the register data. All register data is eight bits wide. Data can be sent in MSb-first mode (default) or in LSb-first mode, which is determined by the <LSB\_FIRST> bit setting in Address 0x00 (Register 5-1). In Write mode, the data is clocked in at the rising edge of the SCLK. In Read mode, the data is clocked out at the falling edge of the SCLK.

TABLE 5-1: SPI PIN FUNCTIONS

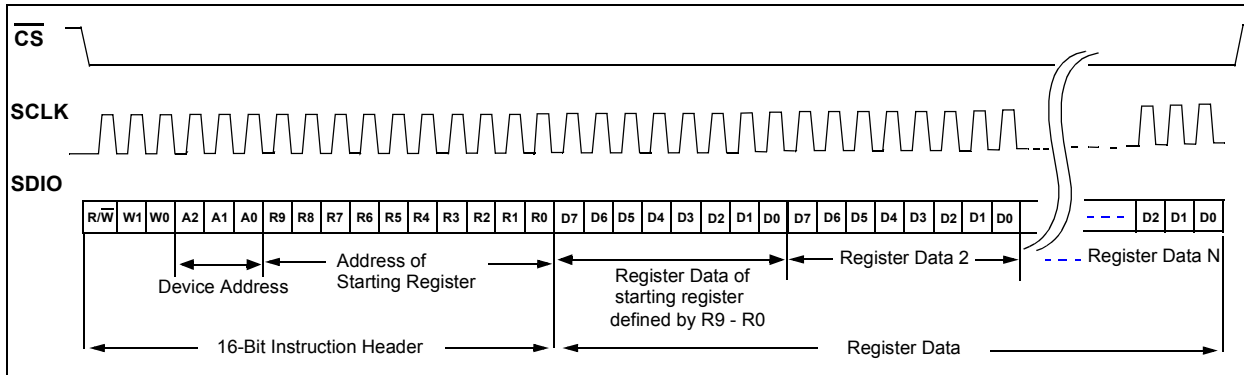
Pin Name	Descriptions
$\overline{\text{CS}}$	Chip Select pin. SPI mode is initiated at the falling edge. It needs to maintain active-low for the entire period of the SPI communication. The device exits the SPI communication at the rising edge.
SCLK	Serial clock input pin. <ul style="list-style-type: none"><li>• Writing to the device: Data is latched at the rising edge of SCLK</li><li>• Reading from the device: Data is latched at the falling edge of SCLK</li></ul>
SDIO	Serial data input/output pin. This pin is initially input pin (SDI) during the first 16-bit instruction header. After the instruction header, it's I/O status can be changed depending on R/W bit: <ul style="list-style-type: none"><li>• if <math>\overline{\text{R/W}} = 0</math>: Data input pin (SDI) for writing</li><li>• if <math>\overline{\text{R/W}} = 1</math>: Data output pin (SDO) for reading</li></ul>

TABLE 5-2: SPI DATA PROTOCOL BIT FUNCTIONS

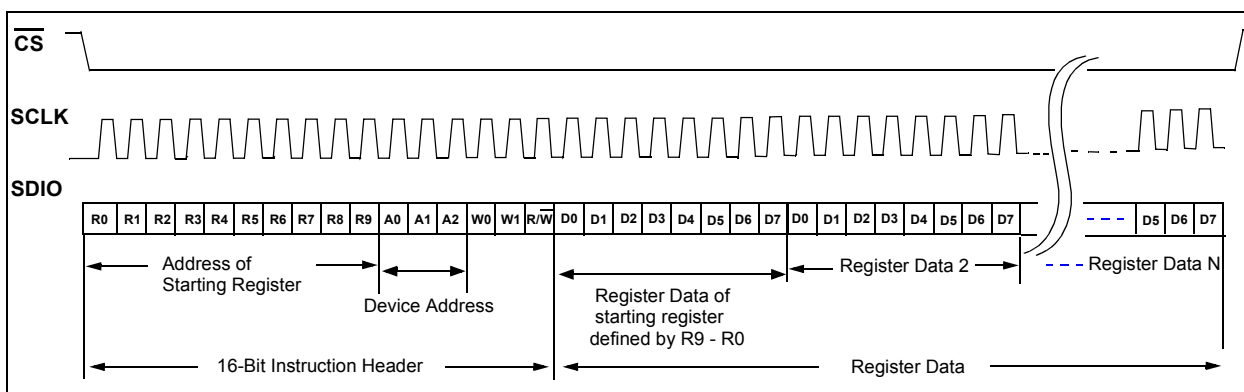
Bit Name	Descriptions
$\overline{\text{R/W}}$	1 = Read Mode 0 = Write Mode
W1, W0 (Data Length)	00 = Data for one register (1 byte) 01 = Data for two registers (2 bytes) 10 = Data for three registers (3 bytes) 11 = Continuous reading or writing by clocking SCLK <sup>(1)</sup>
A2 - A0	Device SPI Address for multiple devices in SPI bus. A2: Internally hard-coded to '0' A1: Logic level of ADR1 pin A0: Logic level of ADR0 pin
R9 - R0	Address of starting register.
D7 - D0	Register data. MSb or LSb first, depending on the LSB_FIRST bit setting in 0x00.

**Note 1:** The register address counter is incremented by one per step. The counter does not automatically reset to 0x00 after reaching the last address (0x15D). Be aware that the user-registers are not sequentially allocated.

# MCP37220-200 AND MCP37D20-200



**FIGURE 5-1:** SPI Serial Data Communication Protocol with MSb-first. See [Figures 2-5](#) and [2-6](#) for Timing Specifications.



**FIGURE 5-2:** SPI Serial Data Communication Protocol with LSb-First. See [Figures 2-5](#) and [2-6](#) for Timing Specifications.

## 5.1 Register Initialization

The internal configuration registers are initialized to their default values by two different ways:

- After  $2^{20}$  clock cycles of delay from the Power-on Reset (POR).
- Reset by the hardware reset pin ( $\overline{\text{RESET}}$ ).

[Figures 2-5](#) and [2-6](#) show the timing details.

All user configuration registers are read/write, except for the last four registers, which are read-only. Each register is made of an 8-bit-wide volatile memory and their default values are loaded during the power-up sequence or by using the hardware RESET pin. All registers are accessible by the SPI command using the register address. [Table 5-3](#) shows the user-configuration memory map and [Registers 5-1](#) to [5-70](#) show the details of the register bit functions.

## 5.2 Configuration Registers

The internal registers are mapped from address 0x00 to 0x15D. These user registers are not sequentially located.

Some user configuration registers include factory-controlled bits. The factory-controlled register bits should not be overwritten by the user.

**Note 1:** All address and bit locations that are not included in the following Register map table should not be written or modified by the user.

**2:** Some registers include factory-controlled bits (FCB). Do not overwrite these bits.

**TABLE 5-3: REGISTER MAP TABLE**

Addr.	Register Name	Bits								Default Value
		b7	b6	b5	b4	b3	b2	b1	b0	
0x00	SPI Bit Ordering and ADC Mode Selection	SHUTDOWN 1 = Shutdown	LSb-First 1 = LSb first 0 = MSb first	SOFT_RESET 0 = Soft Reset	STANDBY 1 = Standby	STANDBY 1 = Standby	SOFT_RESET 0 = Soft Reset	LSb-First 1 = LSb first 0 = MSb first	SHUTDOWN 1 = Shutdown	0x24
0x01	Independency Control of Output Data and Clock Divider	EN_DATCLK_IND	FCB<6:0> = 000 1111							0x0F
0x02	Output Data and Clock Rate Control	OUT_DATARATE<3:0>				OUT_CLKRATE<3:0>				0x00
0x04	SPI SDO Timing Control	SDO_TIME	FCB<6:0> = 00111111							0x9F
0x07	Output Randomizer and WCK Polarity Control	POL_WCK	EN_AUTOCAL_TIMEDLY	FCB<4:0> = 10001					EN_OUT_RANDOM	0x62
0x1E	Auto-Calibration Time Delay Control	AUTOCAL_TIMEDLY<7:0>								0x80
0x52	DLL Control	EN_DUTY	DCLK_PHDLY_DLL<2:0>			EN_DLL_DCLK	EN_DLL	EN_CLK	RESET_DLL	0x0A
0x53	Clock Source Selection	FCB<6:4>= 010			CLK_SOURCE	FCB<3:0>= 0101				0x45
0x54	PLL Reference Divider	PLL_REFDIV<7:0>								0x00
0x55	PLL Output and Reference Divider	PLL_OUTDIV<3:0>				FCB<1:0> = 10		PLL_REFDIV<9:8>		0x48
0x56	PLL Prescaler (LSB)	PLL_PRE (LSB)<7:0>								0x78
0x57	PLL Prescaler (MSB)	FCB<3:0> = 0100				PLL_PRE (MSB)<11:8>				0x40
0x58	PLL Charge-Pump	FCB<2:0> = 000			PLL_BIAS	PLL_CHAGPUMP<3:0>				0x12
0x59	PLL Enable Control 1	U	FCB<4:3> = 10		EN_PLL_REFDIV	FCB<2:1> = 00		EN_PLL	FCB<0> = 1	0x41
0x5A	PLL Loop Filter Resistor	U	FCB<1:0> = 01		PLL_RES<4:0>					0x2F
0x5B	PLL Loop Filter Cap3	U	FCB<1:0> = 01		PLL_CAP3<4:0>					0x27
0x5C	PLL Loop Filter Cap1	U	FCB<1:0> = 01		PLL_CAP1<4:0>					0x27
0x5D	PLL Loop Filter Cap2	U	FCB<1:0> = 01		PLL_CAP2<4:0>					0x27
0x5F	PLL Enable Control 2	FCB<5:2> = 1111				EN_PLL_OUT	EN_PLL_BIAS	FCB<1:0> = 01		0xF1
0x62	Output Data Format and Output Test Pattern	U	FCB<0> = 0	DATA_FORMAT	OUTPUT_MODE<1:0>		TEST_PATTERNS<2:0>			0x10
0x63	LVDS Output Load and Driver Current Control	FCB<3:0> = 0000				LVDS_LOAD	LVDS_IMODE<2:0>			0x01
0x64	Output Clock Phase Control when Decimation Filter is used	EN_PHDLY	DCLK_PHDLY_DEC<2:0>			FCB<3:0> = 0011				0x03
0x65	LVDS Output Polarity Control	POL_LVDS<6:0>							NO-EFFECT	0x00
0x66	Digital Offset Correction - Lower Byte	DIG_OFFSET<7:0>								0x00

**Legend:** U = Unimplemented bit, read as '0' FCB = Factory-Controlled bits. Do not program 1 = bit is set 0 = bit is cleared x = bit is unknown

**Note 1:** Read-only register. Preprogrammed at the factory for internal use.

**TABLE 5-3: REGISTER MAP TABLE (CONTINUED)**

Addr.	Register Name	Bits								Default Value
		b7	b6	b5	b4	b3	b2	b1	b0	
0x67	Digital Offset Correction - Upper Byte	DIG_OFFSET<15:8>								0x00
0x68	OVR and WCK Bit Control	FCB<5:2> = 0010				POL_OVR_WCK	EN_OVR_WCK	FCB<1:0> = 00		0x24
0x6B	PLL Calibration	FCB<6:2> = 00001				PLL_CAL_TRIG		FCB<1:0> = 00		0x08
0x6D	PLL Output and Output Clock Phase	U<1:0>	EN_PLL_CLK		FCB<1> = 0		DCLK_DLY_PLL<2:0>		FCB<0> = 0	0x00
0x74	User-Defined Output Pattern A - Lower Byte	PATTERN A<5:0>					Do not use (Leave these bits as '00')			0x00
0x75	User-Defined Output Pattern A - Upper Byte	PATTERN A<13:6>								0x00
0x76	User-Defined Output Pattern B - Lower Byte	PATTERN B<5:0>					Do not use (Leave these bits as '00')			0x00
0x77	User-Defined Output Pattern B - Upper Byte	PATTERN B<13:6>								0x00
0x79	I/Q-Channel DSPP Control	EN_DSPP_I/Q	FCB<6:0> = 000 0000							0x00
0x7A	FIR_A0 Bit Control	FCB<6> = 0	FIR_A<0>	FCB<5:0> = 00 0000						0x00
0x7B	FIR A Filter	FIR_A<8:1>								0x00
0x7C	FIR B Filter	FIR_B<7:0>								0x00
0x80	Digital Down-Converter Control 1	FCB<0> = 0	HBFILTER_A	EN_NCO	EN_AMPDITH	EN_PHSDITH	EN_LFSR	EN_DDC_FS/8	EN_DDC1	0x00
0x81	Digital Down-Converter Control 2	FCB<5> = 0	EN_DDC2	GAIN_HBF_DDC	FCB<4:0> = 0 0000					0x00
0x82	Numerically Controlled Oscillator (NCO) Tuning - Lower Byte	NCO_TUNE<7:0>								0x00
0x83	Numerically Controlled Oscillator (NCO) Tuning - Middle Lower Byte	NCO_TUNE<15:8>								0x00
0x84	Numerically Controlled Oscillator (NCO) Tuning - Middle Upper Byte	NCO_TUNE<23:16>								0x00
0x85	Numerically Controlled Oscillator (NCO) Tuning - Upper Byte	NCO_TUNE<31:24>								0x00
0x86	NCO Phase Offset in DDC Mode - Lower Byte	NCO_PHASE<7:0>								0x00
0x87	NCO Phase Offset in DDC Mode - Upper Byte	NCO_PHASE<15:8>								0x00
0x88	NCO Phase Offset in DDC Mode - Lower Byte	NCO_PHASE<7:0> - Repeat of Address 0x86								0x00

**Legend:** U = Unimplemented bit, read as '0' FCB = Factory-Controlled bits. Do not program 1 = bit is set 0 = bit is cleared x = bit is unknown

**Note 1:** Read-only register. Preprogrammed at the factory for internal use.

**TABLE 5-3: REGISTER MAP TABLE (CONTINUED)**

Addr.	Register Name	Bits								Default Value
		b7	b6	b5	b4	b3	b2	b1	b0	
0x89	NCO Phase Offset in DDC Mode - Upper Byte	NCO_PHASE<15:8> - Repeat of Address 0x87								0x00
0x8A	NCO Phase Offset in DDC Mode - Lower Byte	NCO_PHASE<7:0> - Repeat of Address 0x86								0x00
0x8B	NCO Phase Offset in DDC Mode - Upper Byte	NCO_PHASE<15:8> - Repeat of Address 0x87								0x00
0x8C	NCO Phase Offset in DDC Mode - Lower Byte	NCO_PHASE<7:0> - Repeat of Address 0x86								0x00
0x8D	NCO Phase Offset in DDC Mode - Upper Byte	NCO_PHASE<15:8> - Repeat of Address 0x87								0x00
0x8E	NCO Phase Offset in DDC Mode - Lower Byte	NCO_PHASE<7:0> - Repeat of Address 0x86								0x00
0x8F	NCO Phase Offset in DDC Mode - Upper Byte	NCO_PHASE<15:8> - Repeat of Address 0x87								0x00
0x90	NCO Phase Offset in DDC Mode - Lower Byte	NCO_PHASE<7:0> - Repeat of Address 0x86								0x00
0x91	NCO Phase Offset in DDC Mode - Upper Byte	NCO_PHASE<15:8> - Repeat of Address 0x87								0x00
0x92	NCO Phase Offset in DDC Mode - Lower Byte	NCO_PHASE<7:0> - Repeat of Address 0x86								0x00
0x93	NCO Phase Offset in DDC Mode - Upper Byte	NCO_PHASE<15:8> - Repeat of Address 0x87								0x00
0x94	NCO Phase Offset in DDC Mode - Lower Byte	NCO_PHASE<7:0> - Repeat of Address 0x86								0x00
0x95	NCO Phase Offset in DDC Mode - Upper Byte	NCO_PHASE<15:8> - Repeat of Address 0x87								0x00
0x96	Digital Gain Control	DIG_GAIN<7:0>								0x3C
0x97		DIG_GAIN<7:0> - Repeat of Address 0x96								0x3C
0x98		DIG_GAIN<7:0> - Repeat of Address 0x96								0x3C
0x99		DIG_GAIN<7:0> - Repeat of Address 0x96								0x3C
0x9A		DIG_GAIN<7:0> - Repeat of Address 0x96								0x3C
0x9B		DIG_GAIN<7:0> - Repeat of Address 0x96								0x3C
0x9C		DIG_GAIN<7:0> - Repeat of Address 0x96								0x3C
0x9D		DIG_GAIN<7:0> - Repeat of Address 0x96								0x3C

**Legend:** U = Unimplemented bit, read as '0' FCB = Factory-Controlled bits. Do not program 1 = bit is set 0 = bit is cleared x = bit is unknown  
**Note 1:** Read-only register. Preprogrammed at the factory for internal use.

TABLE 5-3: REGISTER MAP TABLE (CONTINUED)

Addr.	Register Name	Bits								Default Value
		b7	b6	b5	b4	b3	b2	b1	b0	
0xC0	Calibration Status Indication (Read only)	ADC_CAL_STAT	FCB<6:0> = 000-0000							—
0xD1	PLL Calibration Status and PLL Drift Status Indication (Read only)	FCB<4:3> = xx		PLL_CAL_STAT	FCB<2:1> = xx		PLL_VCOL_STAT	PLL_VCOH_STAT	FCB<0> = x	—
0x15C	CHIP ID - Lower Byte <sup>(1)</sup> (Read only)	CHIP_ID<7:0>								—
0x15D	CHIP ID - Upper Byte <sup>(1)</sup> (Read only)	CHIP_ID<15:8>								—

**Legend:** U = Unimplemented bit, read as '0' FCB = Factory-Controlled bits. Do not program 1 = bit is set 0 = bit is cleared x = bit is unknown

**Note 1:** Read-only register. Preprogrammed at the factory for internal use.

# MCP37220-200 AND MCP37D20-200

## REGISTER 5-1: ADDRESS 0X00 – SPI BIT ORDERING AND ADC MODE SELECTION<sup>(1)</sup>

R/W-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-1	R/W-0	R/W-0
SHUTDOWN	LSB_FIRST	SOFT_RESET	STANDBY	STANDBY	SOFT_RESET	LSB_FIRST	SHUTDOWN
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **SHUTDOWN:** Shutdown mode setting for power saving<sup>(2)</sup>

1 = ADC in Shutdown mode

0 = Not in Shutdown mode (**Default**)

bit 6 **LSB\_FIRST:** Select SPI communication bit order

1 = Start SPI communication with LSb first

0 = Start SPI communication with MSb first (**Default**)

bit 5 **SOFT\_RESET:** Soft Reset control bit<sup>(3)</sup>

1 = Not in Soft Reset mode (**Default**)

0 = ADC in Soft Reset

bit 4 **STANDBY:** Send the device into a power-saving Standby mode<sup>(4)</sup>

1 = ADC in Standby mode

0 = Not in Standby mode (**Default**)

bit 3 **STANDBY:** Send the device into a power-saving Standby mode<sup>(4)</sup>

1 = ADC in Standby mode

0 = Not in Standby mode (**Default**)

bit 2 **SOFT\_RESET:** Soft Reset control bit<sup>(3)</sup>

1 = Not in Soft Reset mode (**Default**)

0 = ADC in Soft Reset

bit 1 **LSB\_FIRST:** Select SPI communication bit order

1 = Start SPI communication with LSb first

0 = Start SPI communication with MSb first (**Default**)

bit 0 **SHUTDOWN:** Shutdown mode setting for power-saving<sup>(2)</sup>

1 = ADC in Shutdown mode

0 = Not in Shutdown mode (**Default**)

- Note**
- 1: Upper and lower nibble are mirrored, which makes the MSb- or LSb-first mode interchangeable. The lower nibble (bit <3:0>) has a higher priority when the mirrored bits have different values.
  - 2: During Shutdown mode, most of the internal circuits, including the reference and clock, are turned-off, except for the SPI interface. When exiting from Shutdown (changing from '1' to '0'), executing the device Soft Reset simultaneously is highly recommended for a fast recalibration of the ADC. The internal user registers are not affected.
  - 3: This bit forces the device into Soft Reset mode, which initializes the internal calibration registers to their initial default states. The user-registers are not affected. When exiting Soft Reset mode (changing from '0' to '1'), the device performs an automatic device calibration including PLL calibration if PLL is enabled. DLL is reset if enabled. During Soft Reset, the device has the following states:
    - no ADC output
    - no change in power-on condition of internal reference
    - most of the internal clocks are not distributed
    - power consumption: (a) digital section - negligible, (b) analog section - no change.
  - 4: During Standby mode, most of the internal circuits are turned off, except for the reference, clock and SPI interface. When exiting from Standby mode (changing from '1' to '0') after an extended amount of time, executing Soft Reset simultaneously is highly recommended. The internal user registers are not affected.

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## REGISTER 5-2: ADDRESS 0X01 – INDEPENDENCY CONTROL OF OUTPUT DATA AND CLOCK DIVIDER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1
EN_DATCLK_IND	FCB<6:0>						
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7

**EN\_DATCLK\_IND:** Enable data and clock divider independently<sup>(1)</sup>

1 = Enabled

0 = Disabled (**Default**)

bit 6-0

**FCB<6:0>:** Factory-Controlled bits. This is not for the user. Do not change default settings.

**Note 1:** EN\_DATCLK\_IND = 1 enables OUT\_CLKRATE<3:0> settings in Address 0x02 ([Register 5-3](#)).



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## REGISTER 5-3: ADDRESS 0X02 – OUTPUT DATA AND CLOCK RATE CONTROL<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
OUT_DATARATE<3:0>				OUT_CLKRATE<3:0>			
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-4

**OUT\_DATARATE<3:0>**: Output data rate control bits

1111 = Output data is all 0's  
 1110 = Output data is all 0's  
 1101 = Output data is all 0's  
 1100 = Internal test only<sup>(2)</sup>  
 1011 = Internal test only<sup>(2)</sup>  
 1010 = Internal test only<sup>(2)</sup>  
 1001 = Full speed divided by 512  
 1000 = Full speed divided by 256  
 0111 = Full speed divided by 128  
 0110 = Full speed divided by 64  
 0101 = Full speed divided by 32  
 0100 = Full speed divided by 16  
 0011 = Full speed divided by 8  
 0010 = Full speed divided by 4  
 0001 = Full speed divided by 2  
 0000 = Full speed rate (**Default**)

bit 3-0

**OUT\_CLKRATE<3:0>**: Output clock rate control bits<sup>(3,4)</sup>

1111 = Full speed rate  
 1110 = No clock output  
 1101 = No clock output  
 1100 = No clock output  
 1011 = No clock output  
 1010 = No clock output  
 1001 = Full speed divided by 512  
 1000 = Full speed divided by 256  
 0111 = Full speed divided by 128  
 0110 = Full speed divided by 64  
 0101 = Full speed divided by 32  
 0100 = Full speed divided by 16  
 0011 = Full speed divided by 8  
 0010 = Full speed divided by 4  
 0001 = Full speed divided by 2  
 0000 = No clock output (**Default**)

- Note 1:** This register should be used when the decimation filter selection option (see Addresses 0x7B and 0x7C - [Registers 5-35](#) and [5-36](#)) or digital down-conversion (DDC) option (see Address 0x80 - [Register 5-37](#)) is used.
- Note 2:** 1100 – 1010: Do not reprogram. These settings are used for the internal test only. If these bits are reprogrammed with different settings, the outputs will be in an undefined state.
- Note 3:** Bits <3:0> become active if EN\_DATCLK\_IND = 1 in Address 0x01 ([Register 5-2](#)).
- Note 4:** When no clock output is selected (Bits 1110 – 1010): clock output is not available at the DCLK+/DCLK- pins.

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## REGISTER 5-4: ADDRESS 0X04 – SPI SDO OUTPUT TIMING CONTROL

R/W-1	R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
SDO_TIME	FCB<6:0>						
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7                      **SDO\_TIME**: SPI SDO output timing control bit  
                                  1 = SDO output at the falling edge of clock (**Default**)  
                                  0 = SDO output at the rising edge of clock  
 bit 6-0                      **FCB<6:0>**: Factory-Controlled bits. This is not for the user. Do not change default settings.

## REGISTER 5-5: ADDRESS 0X07 – OUTPUT RANDOMIZER AND WCK POLARITY CONTROL

R/W-0	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0	R/W-1	R/W-0
POL_WCK	EN_AUTOCAL_TIMEDLY	FCB<4:0>					EN_OUT_RANDOM
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7                      **POL\_WCK**: WCK polarity control bit in DDC mode<sup>(1)</sup>  
                                  1 = Inverted  
                                  0 = Not inverted (**Default**)  
 bit 6                      **EN\_AUTOCAL\_TIMEDLY**: Auto-calibration starter time delay counter control bit<sup>(2)</sup>  
                                  1 = Enabled (**Default**)  
                                  0 = Disabled  
 bit 5-1                      **FCB<4:0>**: Factory-Controlled bits. This is not for the user. Do not change default settings.  
 bit 0                      **EN\_OUT\_RANDOM**: Output randomizer control bit  
                                  1 = Enabled: ADC data output is randomized  
                                  0 = Disabled (**Default**)

**Note** 1: Applicable in the MCP37D20-200 only. See Address 0x68 ([Register 5-26](#)) for OVR/WCK pair control.  
 2: This bit enables the AUTOCAL\_TIMEDLY<7:0> settings. See Address 0x1E ([Register 5-6](#)).

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## REGISTER 5-6: ADDRESS 0X1E – AUTOCAL TIME DELAY CONTROL<sup>(1)</sup>

R/W-1	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
AUTOCAL_TIMEDLY<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7-0                      **AUTOCAL\_TIMEDLY<7:0>**: Auto-calibration start time delay control bits  
                                  1111-1111 = Maximum value  
                                  ...  
                                  1000-0000 = **(Default)**  
                                  ...  
                                  0000-0000 = Minimum value

**Note 1:** EN\_AUTOCAL\_TIMEDLY in Address 0x07 ([Register 5-5](#)) enables this register setting. This register controls the time delay before the auto-calibration starts. The value increases linearly with the bit settings, from minimum to maximum values.

## REGISTER 5-7: ADDRESS 0X52 – DLL CONTROL

R/W-0	R/W-0	R/W-0	R/W-0	R/W-1	R/W-0	R/W-1	R/W-0
EN_DUTY	DCLK_PHDLY_DLL<2:0>		EN_DLL_DCLK	EN_DLL	EN_CLK	RESET_DLL	
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7                      **EN\_DUTY**: Enable DLL circuit for duty cycle correction (DCC) of input clock<sup>(1)</sup>  
                                  1 = Correction is ON  
                                  0 = Correction is OFF **(Default)**

bit 6-4                      **DCLK\_PHDLY\_DLL<2:0>**: Select the phase delay of the digital clock output when using DLL<sup>(2)</sup>  
                                  111 = +315° phase-shifted from default  
                                  110 = +270° phase-shifted from default  
                                  ...  
                                  010 = +90° phase-shifted from default  
                                  001 = +45° phase-shifted from default  
                                  000 = **(Default)**

bit 3                      **EN\_DLL\_DCLK**: Enable DLL digital clock output  
                                  1 = Enabled **(Default)**  
                                  0 = Disabled: DLL digital clock is turned off. ADC output is not available when using DLL

bit 2                      **EN\_DLL**: Enable DLL circuitry to provide a selectable phase clock to digital output clock  
                                  1 = Enabled  
                                  0 = Disabled. DLL block is disabled **(Default)**

bit 1                      **EN\_CLK**: Enable clock input buffer  
                                  1 = Enabled **(Default)**  
                                  0 = Disabled. No clock is available to the internal circuits, ADC output is not available

bit 0                      **RESET\_DLL**: DLL circuit reset control<sup>(3)</sup>  
                                  1 = DLL is active  
                                  0 = DLL circuit is held in reset **(Default)**

**Note 1:** Enable the DLL circuitry for the duty cycle correction.  
**2:** These bits have an effect only if EN\_PHDLY = 1 and decimation is not used.  
**3:** DLL reset control procedure: Set this bit to '0' (reset) and then to '1'.

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## REGISTER 5-8: ADDRESS 0X53 – CLOCK SOURCE SELECTION

R/W-0	R/W-1	R/W-0	R/W-0	R/W-0	R/W-1	R/W-0	R/W-1
FCB<6:4>			CLK_SOURCE	FCB<3:0>			
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-5 **FCB<6:4>**: Factory-Controlled bits. This is not for the user. Do not change default settings.

bit 4 **CLK\_SOURCE**: Select internal timing source

1 = PLL output is selected as timing source

0 = External clock input is selected as timing source (**Default**)

bit 3-0 **FCB<3:0>**: Factory-Controlled bits. This is not for the user. Do not change default settings.

## REGISTER 5-9: ADDRESS 0X54 – PLL REFERENCE DIVIDER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PLL_REFDIV<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **PLL\_REFDIV<7:0>**: PLL Reference clock divider control bits<sup>(1)</sup>

1111-1111 = PLL reference divided by 255 (if PLL\_REFDIV<9:8> = 00)

1111-1110 = PLL reference divided by 254 (if PLL\_REFDIV<9:8> = 00)

...

0000-0011 = PLL reference divided by 3 (if PLL\_REFDIV<9:8> = 00)

0000-0010 = **Do not use (No effect)**

0000-0001 = PLL reference divided by 1 (if PLL\_REFDIV<9:8> = 00)

0000-0000 = PLL reference not divided (if PLL\_REFDIV<9:8> = 00) (**Default**)

**Note 1:** PLL\_REFDIV is a 10-bit-wide setting. See Address 0x55 ([Register 5-10](#)) for the upper two bits and [Table 4-5](#) for PLL\_REFDIV<9:0> bit settings. This setting controls the clock division ratio of the PLL reference clock (external clock input at the clock input pin) before the PLL phase-frequency detector circuitry. Note that the divider value of 2 is not supported. EN\_PLL\_REFDIV in Address 0x59 ([Register 5-14](#)) must be set.

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## REGISTER 5-10: ADDRESS 0X55 – PLL OUTPUT AND REFERENCE DIVIDER

R/W-0	R/W-1	R/W-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-0
PLL_OUTDIV<3:0>				FCB<1:0>		PLL_REFDIV<9:8>	
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-4 **PLL\_OUTDIV<3:0>**: PLL output divider control bits<sup>(1)</sup>

1111 = PLL output divided by 15

1110 = PLL output divided by 14

...

0100 = PLL output divided by 4 (**Default**)

0011 = PLL output divided by 3

0010 = PLL output divided by 2

0001 = PLL output divided by 1

0000 = PLL output not divided

bit 3-2 **FCB<1:0>**: Factory-Controlled bits. This is not for the user. Do not change default settings.

bit 1-0 **PLL\_REFDIV<9:8>**: Upper two MSb bits of PLL\_REFDIV<9:0><sup>(2)</sup>

00 = see [Table 5-4](#). (**Default**)

**Note 1:** PLL\_OUTDIV<3:0> controls the PLL output clock divider: VCO output is divided by the PLL\_OUTDIV<3:0> setting.

**Note 2:** See Address 0x54 ([Register 5-9](#)) and [Table 5-4](#) for PLL\_REFDIV<9:0> bit settings. EN\_PLL\_REFDIV in Address 0x59 ([Register 5-14](#)) must be set.

**TABLE 5-4: Example – PLL Reference Divider Bit Settings Vs. PLL Reference Input Frequency**

PLL_REFDIV<9:0>	PLL Reference Frequency
11-1111-1111	Reference frequency divided by 1023
11-1111-1110	Reference frequency divided by 1022
—	—
00-0000-0011	Reference frequency divided by 3
00-0000-0010	Do not use (Not supported)
00-0000-0001	Reference frequency divided by 1
00-0000-0000	Reference frequency divided by 1

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**REGISTER 5-11: ADDRESS 0X56 – PLL PRESCALER (LSB)**

R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0
PLL_PRE<7:0>							
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7-0                      **PLL\_PRE<7:0>**: PLL prescaler selection<sup>(1)</sup>  
                                  1111-1111 = VCO clock divided by 255 (if PLL\_PRE<11:8> = 0000)  
                                  ...  
                                  0111-1000 = VCO clock divided by 120 (if PLL\_PRE<11:8> = 0000) **(Default)**  
                                  ...  
                                  0000-0010 = VCO clock divided by 2 (if PLL\_PRE<11:8> = 0000)  
                                  0000-0001 = VCO clock divided by 1 (if PLL\_PRE<11:8> = 0000)  
                                  0000-0000 = VCO clock not divided (if PLL\_PRE<11:8> = 0000)

**Note 1:** PLL\_PRE is a 12-bit-wide setting. The upper four bits (PLL\_PRE<11:8>) are defined in Address 0x57. See [Table 4-5](#) for the PLL\_PRE<11:0> bit settings. The PLL Prescaler is used to divide down the VCO output clock in the PLL phase-frequency detector loop circuit.

**REGISTER 5-12: ADDRESS 0X57 – PLL PRESCALER (MSB)**

R/W-0	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FCB<3:0>				PLL_PRE<11:8>			
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7-4                      **FCB<3:0>**: Factory-Controlled bits. This is not for the user. Do not change default settings.  
 bit 3-0                      **PLL\_PRE<11:8>**: PLL prescaler selection<sup>(1)</sup>  
                                  1111 =  $2^{12} - 1$  (max), if PLL\_PRE<7:0> = 0xFF  
                                  ...  
                                  0000 = **(Default)**

**Note 1:** PLL\_PRE is a 12-bit-wide setting. See the lower eight bit settings (PLL\_PRE<7:0>) in Address 0x56 ([Register 5-11](#)). See [Table 5-5](#) for the PLL\_PRE<11:0> bit settings for PLL feedback frequency.

**TABLE 5-5: Example: PLL Prescaler Bit Settings and PLL Feedback Frequency**

PLL_PRE<11:0>	PLL Feedback Frequency
1111-1111-1111	VCO clock divided by 4095 ( $2^{12} - 1$ )
1111-1111-1110	VCO clock divided by 4094 ( $2^{12} - 2$ )
—	—
0000-0000-0011	VCO clock divided by 3
0000-0000-0010	VCO clock divided by 2
0000-0000-0001	VCO clock divided by 1
0000-0000-0000	VCO clock divided by 1

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## REGISTER 5-13: ADDRESS 0X58 – PLL CHARGE PUMP

R/W-0	R/W-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-1	R/W-0
FCB<2:0>			PLL_BIAS	PLL_CHAGPUMP<3:0>			
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-5 **FCB<2:0>**: Factory-Controlled bits. This is not for the user. Do not change default settings.

bit 4 **PLL\_BIAS**: PLL charge pump bias source selection bit

1 = Self-biasing coming from AV<sub>DD</sub> (**Default**)

0 = Bandgap voltage from the reference generator (1.2V)

bit 3-0 **PLL\_CHAGPUMP<3:0>**: PLL charge-pump bias current control bits<sup>(1)</sup>

1111 = Maximum current

...

0010 = (**Default**)

...

0000 = Minimum current

**Note 1:** PLL\_CHAGPUMP<3:0> bits should be set based on the phase detector comparison frequency. The bias current amplitude increases linearly with increasing the bit setting values. The increase is from approximately 25  $\mu$ A to 375  $\mu$ A, 25  $\mu$ A per step. See [Section 4.5.2.1 "PLL Output Frequency and Output Control Parameters"](#) for more details of the PLL block.

## REGISTER 5-14: ADDRESS 0X59 – PLL ENABLE CONTROL 1

U-0	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-1
—	FCB<4:3>		EN_PLL_REFDIV	FCB<2:1>		EN_PLL	FCB<0>
bit 7			bit 0				

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **Unimplemented**: Not used.

bit 6-5 **FCB<4:3>**: Factory-Controlled bits. This is not for the user. Do not change default settings.

bit 4 **EN\_PLL\_REFDIV**: Enable PLL Reference Divider (PLL\_REFDIV<9:0>).

1 = Enable PLL\_REFDIV<9:0> register

0 = Reference divider is bypassed (**Default**)

bit 3-2 **FCB<2:1>**: Factory-Controlled bits. This is not for the user. Do not change default settings.

bit 1 **EN\_PLL**: Master enable bit for PLL circuit.

1 = Enable PLL circuit

0 = Disable PLL circuit (**Default**)

bit 0 **FCB<0>**: Factory-Controlled bit. This is not for the user. Do not change default setting.

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## REGISTER 5-15: ADDRESS 0X5A – PLL LOOP FILTER RESISTOR

U-0	R/W-0	R/W-1	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1
—	FCB<1:0>		PLL_RES<4:0>				
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7      **Unimplemented:** Not used.

bit 6-5      **FCB<1:0>:** Factory-Controlled bits. This is not for the user. Do not change default settings.

bit 4-0      **PLL\_RES<4:0>:** Resistor value selection bits for PLL loop filter<sup>(1)</sup>

11111 = Maximum value

...

01111 = **(Default)**

...

00000 = Minimum value

**Note 1:** PLL\_RES<4:0> bits should be set based on the phase detector comparison frequency. The resistor value increases linearly with the bit settings, from minimum to maximum values. See the PLL loop filter section in [Section 4.5.2.1 “PLL Output Frequency and Output Control Parameters”](#).

## REGISTER 5-16: ADDRESS 0X5B – PLL LOOP FILTER CAP3

U-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-1	R/W-1	R/W-1
—	FCB<1:0>		PLL_CAP3<4:0>				
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7      **Unimplemented:** Not used.

bit 6-5      **FCB<1:0>:** Factory-Controlled bits. This is not for the user. Do not change default settings.

bit 4-0      **PLL\_CAP3<4:0>:** Capacitor 3 value selection bits for PLL loop filter<sup>(1)</sup>

11111 = Maximum value

...

00111 = **(Default)**

...

00000 = Minimum value

**Note 1:** This capacitor is in series with the shunt resistor, which is set by PLL\_RES<4:0> bits. The capacitor value increases linearly with the bit settings, from minimum to maximum values. This setting should be set based on the phase detector comparison frequency.



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## REGISTER 5-17: ADDRESS 0X5C – PLL LOOP FILTER CAP1

U-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-1	R/W-1	R/W-1
—	FCB<1:0>		PLL_CAP1<4:0>				
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **Unimplemented:** Not used.

bit 6-5 **FCB<1:0>:** Factory-Controlled bits. This is not for the user. Do not change default settings.

bit 4-0 **PLL\_CAP1<4:0>:** Capacitor 1 value selection bits for PLL loop filter<sup>(1)</sup>

11111 = Maximum value

...

00111 = (Default)

...

00000 = Minimum value

**Note 1:** This capacitor is located between the charge pump output and ground, and in parallel with the shunt resistor which is defined by the PLL\_RES<4:0>. The capacitor value increases linearly with the bit settings, from minimum to maximum values. This setting should be set based on the phase detector comparison frequency.

## REGISTER 5-18: ADDRESS 0X5D – PLL LOOP FILTER CAP2

U-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-1	R/W-1	R/W-1
—	FCB<1:0>		PLL_CAP2<4:0>				
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **Unimplemented:** Not used.

bit 6-5 **FCB<1:0>:** Factory-Controlled bits. This is not for the user. Do not change default settings.

bit 4-0 **PLL\_CAP2<4:0>:** Capacitor 2 value selection bits for PLL loop filter<sup>(1)</sup>

11111 = Maximum value

...

00111 = (Default)

...

00000 = Minimum value

**Note 1:** This capacitor is located between the charge pump output and ground, and in parallel with CAP1 which is defined by the PLL\_CAP1<4:0>. The capacitor value increases linearly with the bit settings, from minimum to maximum values. This setting should be set based on the phase detector comparison frequency.

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## REGISTER 5-19: ADDRESS 0X5F – PLL ENABLE CONTROL 2<sup>(1)</sup>

R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0	R/W-1
FCB<5:2>				EN_PLL_OUT	EN_PLL_BIAS	FCB<1:0>	
bit 7						bit 0	

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-4      **FCB<5:2>**: Factory-Controlled bits. This is not for the user. Do not change default settings.

bit 3      **EN\_PLL\_OUT**: Enable PLL output.

1 = Enabled

0 = Disabled (**Default**)

bit 2      **EN\_PLL\_BIAS**: Enable PLL bias

1 = Enabled

0 = Disabled (**Default**)

bit 1-0      **FCB<1:0>**: Factory-Controlled bits. This is not for the user. Do not change default settings.

**Note 1:** To enable PLL output, EN\_PLL\_OUT, EN\_PLL\_BIAS and EN\_PLL in Address 0x59 ([Register 5-14](#)) must be set.

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## REGISTER 5-20: ADDRESS 0X62 – OUTPUT DATA FORMAT AND OUTPUT TEST PATTERN

U-0	R/W-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0
—	FCB<0>	DATA_FORMAT	OUTPUT_MODE<1:0>			TEST_PATTERNS<2:0>	
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **Unimplemented:** Not used

bit 6 **FCB<0>**: Factory-Controlled bit. This is not for the user. Do not change default setting.

bit 5 **DATA\_FORMAT**: Output data format selection

1 = Offset binary (unsigned)

0 = Two's complement (**Default**)

bit 4-3 **OUTPUT\_MODE<1:0>**: Output mode selection<sup>(1)</sup>

11 = Do not use. Output is undefined.

10 = DDR LVDS output mode with even bit first<sup>(2)</sup> (**Default**)

01 = CMOS output mode

00 = Output disabled

bit 2-0 **TEST\_PATTERNS<2:0>**: Test output data pattern selection<sup>(3)</sup>

111 = Output data is pseudo-random number (PN) sequence<sup>(4)</sup>

110 = Sync Pattern for LVDS output: '11111111 000000'

101 = Alternating Sequence for LVDS mode: '01010101 101010'

100 = Alternating Sequence for CMOS mode: '11111111 111111' alternating with '00000000 000000'

011 = Alternating Sequence for CMOS mode: '01010101 010101' alternating with '10101010 101010'

010 = Ramp Pattern. Output (Q0) is incremented by 1 LSb per 16 clock cycles

001 = Double Custom Patterns.

Output: Alternating custom pattern A (see Addresses 0X74 – 0X75 - [Registers 5-29 – 5-30](#)) and custom pattern B (see Address 0X76 - 0X77 - [Registers 5-31 – 5-32](#))<sup>(5)</sup>

000 = Normal Operation. Output: ADC data (**Default**)

**Note 1:** See [Figures 2-1 – 2-2](#) for the timing diagram.

**2:** Rising edge: Q12, Q10...Q0.

Falling edge: Q13, Q11...Q1.

**3:** See [Section 4.9.12 “Output Test Patterns”](#) for more details.

(a) In LVDS mode: only the active pins (per register settings) are active. Inactive output pins are in High Z state.

(b) In CMOS mode: all data output pins (Q13-Q0), output test pins (TP, TP1, TP2), OVR and WCK pins are active, even if they are disabled by register settings. Since the output test pins (TP, TP1, TP2) can toggle during this test, the output test pins can draw extra current if they are connected to the supply pin or ground. To avoid the extra current draws, always leave the test pins floating (not connected).

**4:** Pseudo-random number (PN) code is generated by the linear feedback shift register (LFSR).

See [Section 4.9.12.1 “Pseudo-Random Number \(PN\) Sequence Output”](#) for more details.

**5:** Pattern A<13:0> and B<13:0> are applied to Q<13:0>. Q13 = OVR, Q12 = WCK.

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## REGISTER 5-21: ADDRESS 0X63 – LVDS OUTPUT LOAD AND DRIVER CURRENT CONTROL

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-1
FCB<3:0>				LVDS_LOAD	LVDS_IMODE<2:0>		
bit 7					bit 0		

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-4 **FCB<3:0>**: Factory-controlled bits. This is not for the user. Do not change default settings.

bit 3 **LVDS\_LOAD**: Enable internal LVDS load termination

1 = Enabled

0 = Disabled (**Default**)

bit 2-0 **LVDS\_IMODE<2:0>**: LVDS driver current control bits

111 = 7.2 mA

011 = 5.4 mA

001 = 3.5 mA (**Default**)

000 = 1.8 mA

Do not use the following settings<sup>(1)</sup>:

110, 101, 100, 010

**Note 1:** These settings can result in unknown outputs currents.

## REGISTER 5-22: ADDRESS 0X64 – OUTPUT CLOCK PHASE CONTROL WHEN DECIMATION FILTER IS USED

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-1	R/W-1
EN_PHDLY	DCLK_PHDLY_DEC<2:0>			FCB<3:0>			
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **EN\_PHDLY**: Enable digital output clock phase delay control when DLL or decimation filter is used.

1 = Enabled

0 = Disabled (**Default**)

bit 6-4 **DCLK\_PHDLY\_DEC<2:0>**: Digital output clock phase delay control when decimation filter is used<sup>(1)</sup>

111 = +315° phase-shifted from default<sup>(2)</sup>

110 = +270° phase-shifted from default

101 = +225° phase-shifted from default<sup>(2)</sup>

100 = +180° phase-shifted from default

011 = +135° phase-shifted from default<sup>(2)</sup>

010 = +90° phase-shifted from default

001 = +45° phase-shifted from default<sup>(2)</sup>

000 = **Default**<sup>(3)</sup>

bit 3-0 **FCB<3:0>**: Factory-Controlled bits. This is not for the user. Do not change default settings.

**Note 1:** These bits have an effect only if EN\_PHDLY = 1. See Address 0x52 ([Register 5-7](#)) for the same feature when DLL is used.

**Note 2:** Only available when the decimation filter setting is greater than 2. When FIR\_A/B <8:1> = 0's (default) and FIR\_A<6> = 0, only 4-phase shifts are available (+45°, +135°, +225°, +315°) from default. See Addresses 0x7A, 0x7B and 0x7C ([Registers 5-34 – 5-36](#)). See address 0x6D and 0x52 for DCLK ([Registers 5-28 and 5-7](#)) phase shift for other modes.

**Note 3:** The phase delay for all other settings is referenced to this default phase.

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## REGISTER 5-23: ADDRESS 0X65 – LVDS OUTPUT POLARITY CONTROL

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
POL_LVDS<6:0>							NO-EFFECT<0>
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7-1                      **POL\_LVDS<6:0>**: Control polarity of LVDS data pairs  
111-1111 = Invert all LVDS pairs  
111-1110 = Invert all LVDS pairs except the LSb pair  
...  
100-0000 = Invert MSb LVDS pair  
...  
000-0001 = Invert LSb LVDS pair  
000-0000 = No inversion of LVDS bit pairs (**Default**)

bit 6-0                      **NO EFFECT<0>**: No effect bit.

## REGISTER 5-24: ADDRESS 0X66 – DIGITAL OFFSET CORRECTION (LOWER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DIG_OFFSET <7:0>							
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7-0                      **DIG\_OFFSET <7:0>**: Lower byte of DIG\_OFFSET<15:0><sup>(1)</sup>  
0000-0000 = **Default**

**Note 1:** Offset is added to the ADC output. Setting is two's complement using two combined registers (16 bits wide).  
- 0 LSb if DIG\_OFFSET<15:0> = 0x0000  
- Step size: 0.25 LSb per each bit setting  
- Setting Range:  $(-2^{15} \text{ to } 2^{15} - 1) \times 0.25 \text{ LSb}$  or  $(-32768 \text{ to } +32767) \times 0.25 \text{ LSb}$

## REGISTER 5-25: ADDRESS 0X67 – DIGITAL OFFSET CORRECTION (UPPER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DIG_OFFSET<15:8>							
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7-0                      **DIG\_OFFSET <15:8>**: Upper byte of DIG\_OFFSET<15:0><sup>(1)</sup>  
0000-0000 = **Default**

**Note 1:** See [Note 1](#) in Address 0x66 ([Register 5-24](#)).

# MCP37220-200 AND MCP37D20-200

## REGISTER 5-26: ADDRESS 0X68 – OVR AND WCK BIT CONTROL

R/W-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-1	R/W-0	R/W-0
FCB<5:2>			POL_OVR_WCK	EN_OVR_WCK	FCB<1:0>		
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-4      **FCB<5:2>**: Factory-Controlled bits. This is not for the user. Do not change default settings.

bit 3      **POL\_OVR\_WCK**: Polarity control for OVR and WCK bit pair in LVDS mode

1 = Inverted

0 = Not inverted (**Default**)

bit 2      **EN\_OVR\_WCK**: Enable OVR and WCK output bit pair

1 = Enabled (**Default**)

0 = Disabled

bit 1-0      **FCB<1:0>**: Factory-Controlled bits. This is not for the user. Do not change default settings.

## REGISTER 5-27: ADDRESS 0X6B – PLL CALIBRATION

R/W-0	R/W-0	R/W-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-0
FCB<6:2>				PLL_CAL_TRIG	FCB<1:0>		
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-3      **FCB<6:2>**: Factory-Controlled bits. This is not for the user. Do not change default settings.

bit 2      **PLL\_CAL\_TRIG**: Manually force recalibration of the PLL at the state of bit transition<sup>(1)</sup>

Toggle from '1' to '0', or '0' to '1' = Start PLL calibration

bit 1-0      **FCB<1:0>**: Factory-Controlled bits. This is not for the user. Do not change default settings.

**Note 1:** See PLL\_CAL\_STAT in Address 0xD1 ([Register 5-68](#)) for calibration status indication.

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## REGISTER 5-28: ADDRESS 0X6D – PLL OUTPUT AND OUTPUT CLOCK PHASE<sup>(1)</sup>

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	EN_PLL_CLK	FCB<1>	DCLK_DLY_PLL<2:0>			FCB<0>	
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-6 **Unimplemented:** Not used

bit 5 **EN\_PLL\_CLK:** Enable PLL output clock  
 1 = PLL output clock is enabled to the ADC core  
 0 = PLL clock output is disabled (**Default**)

bit 4 **FCB<1>:** Factory-Controlled bit. This is not for the user. Do not change default setting.

bit 3-1 **DCLK\_DLY\_PLL<2:0>:** Output clock is delayed by the number of VCO clock cycles from the nominal PLL output<sup>(2)</sup>  
 111 = Delay of 15 cycles  
 110 = Delay of 14 cycles  
 ...  
 001 = Delay of one cycle  
 000 = No delay (**Default**)

bit 0 **FCB<0>:** Factory-Controlled bit. This is not for the user. Do not change default setting.

- Note 1:** This register has effect only when the PLL clock is selected by CLK\_SOURCE bit in Address 0x53 ([Register 5-8](#)) and PLL circuit is enabled by EN\_PLL bit in Address 0x59 ([Register 5-14](#)).
- Note 2:** This bit setting enables the output clock phase delay. This phase delay control option is applicable when PLL is used as the clock source and the decimation is not used.

## REGISTER 5-29: ADDRESS 0X74 – USER-DEFINED OUTPUT PATTERN A (LOWER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PATTERN_A<5:0>						Do not use (leave as '00')	
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-2 **PATTERN\_A<5:0>:** Lower bit portion of PATTERN\_A<13:0><sup>(1)</sup>

bit 1-0 **Do not use:** Leave these bits to default settings ('00')<sup>(2)</sup>

- Note 1:** See PATTERN\_A<13:6> in Address 0x75 ([Register 5-30](#)) and TEST\_PATTERNS<2:0> in Address 0x62 ([Register 5-20](#)).
- Note 2:** The output from these bit settings is on "Unused Output Pattern Test Pins", which are recommended to not be connected to the host device. Therefore, the effect of these bit settings is not monitored. Leave these bits as default settings ('00') all the time.

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## REGISTER 5-30: ADDRESS 0X75 – USER-DEFINED OUTPUT PATTERN A (UPPER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PATTERN_A<13:6>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **PATTERN\_A<13:6>**: Upper byte of PATTERN\_A<15:0><sup>(1)</sup>

**Note 1:** See PATTERN\_A<5:0> in Address 0x74 ([Register 5-29](#)) and TEST\_PATTERNS<2:0> in Address 0x62 ([Register 5-20](#)).

## REGISTER 5-31: ADDRESS 0X76 – USER-DEFINED OUTPUT PATTERN B (LOWER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PATTERN_B<5:0>						Do not use (Leave as '00')	
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-2 **PATTERN\_B<5:0>**: Lower bit portion of PATTERN\_B<13:0><sup>(1)</sup>

bit 1-0 **Do not use:** Leave these bits to default settings ('00')

**Note 1:** See PATTERN\_B<13:6> in Address 0x77 ([Register 5-32](#)) and TEST\_PATTERNS<2:0> in Address 0x62 ([Register 5-20](#)).  
**2:** The output from these bit settings is on "Unused Output Pattern Test Pins", which are recommended to not be connected to the host device. Therefore, the effect of these bit settings is not monitored. Leave these bits as default settings ('00') all the time.

## REGISTER 5-32: ADDRESS 0X77 – USER-DEFINED OUTPUT PATTERN B (UPPER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PATTERN_B<13:6>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **PATTERN\_B<13:6>**: Upper byte of PATTERN\_B<13:0><sup>(1)</sup>

**Note 1:** See PATTERN\_B<5:0> in Address 0x76 ([Register 5-31](#)) and TEST\_PATTERNS<2:0> in Address 0x62 ([Register 5-20](#)).



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## REGISTER 5-33: ADDRESS 0X79 – I/Q CHANNEL DIGITAL SIGNAL POST-PROCESSING CONTROL

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
EN_DSPP_I/Q	FCB<6:0>						
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7                      **EN\_DSPP\_I/Q**: Enable all digital signal post-processing functions for I/Q-channel operation.  
1 = Enabled  
0 = Disabled (**Default**)

bit 6-0                      **FCB<6:0>**: Factory-Controlled bits. This is not for the user. Do not change default settings.

## REGISTER 5-34: ADDRESS 0X7A – FIR\_A0 BIT CONTROL

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FCB<6>	FIR_A<0>	FCB<5:0>					
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7                      **FCB<6>**: Factory-Controlled bit. This is not for the user. Do not change default setting.

bit 6                      **FIR\_A<0>**: Enable the first 2x decimation (Stage 1A in FIR A)<sup>(1)</sup>  
1 = Enabled  
0 = Disabled (**Default**)

bit 5-0                      **FCB<5:0>**: Factory-Controlled bits. This is not for the user. Do not change default settings.

**Note 1:** Set FIR\_A<0> = 0 for I and Q channels in DDC mode (MCP37D20-200). See Address 0x7B ([Register 5-35](#)) for FIR\_A<8:1>.

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## REGISTER 5-35: ADDRESS 0X7B – FIR A FILTER<sup>(1,4)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FIR_A<8:1>							
bit 7						bit 0	

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **FIR\_A<8:1>: Decimation Filter FIR A settings<sup>(2)</sup>**

#### **Normal Decimation Operation:**

##### **FIR\_A<8:0> =**

1-1111-1111 = Enabled stage 1 - 9 filters (decimation rate: 512)  
 0-1111-1111 = Enabled stage 1 - 8 filters  
 0-0111-1111 = Enabled stage 1 - 7 filters  
 0-0011-1111 = Enabled stage 1 - 6 filters  
 0-0001-1111 = Enabled stage 1 - 5 filters  
 0-0000-1111 = Enabled stage 1 - 4 filters  
 0-0000-0111 = Enabled stage 1 - 3 filters (decimation rate = 8)  
 0-0000-0011 = Enabled stage 1 - 2 filters (decimation rate = 4)  
 0-0000-0001 = Enabled stage 1 filter (decimation rate = 2)  
 0-0000-0000 = Disabled all FIR A filters. **(Default)**

#### **In-Phase (I) Data Channel in DDC Mode (MCP37D20-200):<sup>(3)</sup>**

##### **FIR\_A<8:0> =**

1-1111-1100 = Enabled stage 3 - 9 filters (decimation rate: 128)  
 0-1111-1100 = Enabled stage 3 - 8 filters  
 0-0111-1100 = Enabled stage 3 - 7 filters  
 0-0011-1100 = Enabled stage 3 - 6 filters  
 0-0001-1100 = Enabled stage 3 - 5 filters  
 0-0000-1100 = Enabled stage 3 - 4 filters  
 0-0000-0100 = Enabled stage 3 filter (decimation rate = 2)  
 0-0000-0000 = Disabled all FIR A filters. **(Default)**

- Note** 1: The register values are thermometer encoded.  
 2: FIR\_A<0> is placed in Address 0x7A ([Register 5-34](#)).  
 3: In I and Q channel operation, it starts with the 3<sup>rd</sup> stage filter.  
 4: SNR is improved by approximately 2.5 dB per each filter stage, but output data rate is reduced by a factor of 2 per stage. The data and clock rates in Address 0X02 ([Register 5-3](#)) need to be updated accordingly when this register is updated. Address 0x64 ([Register 5-22](#)) setting is also affected. The maximum decimation factor is 512, and 128 for the I and Q channel operation in DDC mode (MCP37D20).

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## REGISTER 5-36: ADDRESS 0X7C – FIR B FILTER<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FIR_B<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **FIR\_B<7:0>**:Decimation Filter FIR B settings for Quadrature (Q) data channel

1111-1111 = Enabled stage 3 - 9 filters (decimation rate: 128)

0111-1111 = Enabled stage 3 - 8 filters

0011-1111 = Enabled stage 3 - 7 filters

0001-1111 = Enabled stage 3 - 6 filters

0000-1111 = Enabled stage 3 - 5 filters

0000-0111 = Enabled stage 3 - 4 filters

0000-0011 = Enabled stage 3 filter (decimation rate = 2)

0000-0001 = No effect

0000-0000 = Disabled all FIR B filters. **(Default)**

**Note 1:** This register is used only for Q data channel in DDC mode (MCP37D20-200). The register values are thermometer encoded.

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## REGISTER 5-37: ADDRESS 0X80 – DIGITAL DOWN-CONVERTER CONTROL 1

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FCB<0>	HBFILTER_A	EN_NCO	EN_AMPDITH	EN_PHSDITH	EN_LFSR	EN_DDC_FS/8	EN_DDC1
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 7                      **FCB<0>**: Factory-Controlled bit. This is not for the user. Do not change default setting.
- bit 6                      **HBFILTER\_A**: Select half-bandwidth filter at DDC output of channel A<sup>(1)</sup>  
                                 1 = Select High-Pass filter at DDC output  
                                 0 = Select Low-Pass filter at DDC output (**Default**)
- bit 5                      **EN\_NCO**: Enable NCO of DDC1  
                                 1 = Enabled  
                                 0 = Disabled (**Default**)
- bit 4                      **EN\_AMPDITH**: Enable amplitude dithering for NCO<sup>(2, 3)</sup>  
                                 1 = Enabled  
                                 0 = Disabled (**Default**)
- bit 3                      **EN\_PHSDITH**: Enable phase dithering for NCO<sup>(2, 3)</sup>  
                                 1 = Enabled  
                                 0 = Disabled (**Default**)
- bit 2                      **EN\_LFSR**: Enable linear feedback shift register (LFSR) for amplitude and phase dithering for NCO  
                                 1 = Enabled  
                                 0 = Disabled (**Default**)
- bit 1                      **EN\_DDC\_FS/8**: Enable NCO for the DDC2 to center the DDC output signal to be around  $f_s/8/DER$ <sup>(4)</sup>  
                                 1 = Enabled  
                                 0 = Disabled (**Default**)
- bit 0                      **EN\_DDC1**: Enable digital down converter 1 (DDC1)  
                                 1 = Enabled<sup>(5)</sup>  
                                 0 = Disabled (**Default**)

- Note** 1: This filter includes a decimation of 2.  
 2: This requires the LFSR to be enabled: <EN\_LFSR> = 1  
 3: EN\_AMPDITH = 1 and EN\_PHSDITH = 1 are recommended for the best performance.  
 4: DER is the decimation rate defined by FIR A or FIR B filter. If up-converter is not enabled (disabled), output is I/Q data.  
 5: DDC and NCO are enabled. For DDC function, bits 0, 2 and 5 need to be enabled all together.

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## REGISTER 5-38: ADDRESS 0X81 – DIGITAL DOWN-CONVERTER CONTROL 2

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FCB<5>	EN_DDC2	GAIN_HBF_DDC	FCB<4:0>				
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **FCB<5>**: Factory-Controlled bit. This is not for the user. Do not change default setting.

bit 6 **EN\_DDC2**: Enable DDC2 after the digital half-band filter (HBF) in DDC

1 = Enabled

0 = Disabled (**Default**)

bit 5 **GAIN\_HBF\_DDC**: Gain select for the output of the digital half-band filter (HBF) in DDC

1 = x2

0 = x1 (**Default**)

bit 4-0 **FCB<4:0>**: Factory-Controlled bits. This is not for the user. Do not change default settings.

## REGISTER 5-39: ADDRESS 0X82 – NUMERICALLY CONTROLLED OSCILLATOR (NCO) TUNING (LOWER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_TUNE<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **NCO\_TUNE <7:0>**: Lower byte of NCO\_TUNE<31:0><sup>(1)</sup>

0000-0000 = DC (0 Hz) when NCO\_TUNE<31:0> = 0x00000000 (**Default**)

**Note 1:** See [Note 1](#) and [Note 2](#) in Address 0x85 ([Register 5-42](#)).

## REGISTER 5-40: ADDRESS 0X83 – NUMERICALLY CONTROLLED OSCILLATOR (NCO) TUNING (MIDDLE LOWER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_TUNE<15:8>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0 **NCO\_TUNE<15:8>**: Middle lower byte of NCO\_TUNE<31:0><sup>(1)</sup>

0000-0000 = **Default**

**Note 1:** See [Note 1](#) and [Note 2](#) in Address 0x85 ([Register 5-42](#)).

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## REGISTER 5-41: ADDRESS 0X84 – NUMERICALLY CONTROLLED OSCILLATOR (NCO) TUNING (MIDDLE UPPER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_TUNE<23:16>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **NCO\_TUNE<23:16>**: Middle-upper byte of NCO\_TUNE<31:0><sup>(1)</sup>  
 0000-0000 = **Default**

**Note 1:** See [Note 1](#) and [Note 2](#) in Address 0x85 ([Register 5-42](#)).

## REGISTER 5-42: ADDRESS 0X85 – NUMERICALLY CONTROLLED OSCILLATOR (NCO) TUNING (UPPER BYTE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_TUNE<31:24>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **NCO\_TUNE<31:24>**: Upper byte of NCO\_TUNE<31:0><sup>(2)</sup>  
 1111-1111 =  $f_S$  if NCO\_TUNE<31:0> = 0xFFFF FFFF  
 ...  
 0000-0000 = **Default**

- Note 1:** This Register is used only when DDC is enabled: EN\_DDC1 = 1 in Address 0x80 ([Register 5-37](#)). See [Section 4.6.2.1 "Numerically Controlled Oscillator \(NCO\)"](#) for the details of NCO.
- Note 2:** NCO frequency =  $(\text{NCO\_TUNE<31:0>} / 2^{32}) \times f_S$ , where  $f_S$  is the ADC core sampling frequency.

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## REGISTER 5-43: ADDRESS 0X86 – NCO PHASE OFFSET IN DDC MODE (LOWER BYTE)<sup>(1,3)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_PHASE<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **NCO\_PHASE<7:0>**: Lower byte of NCO\_PHASE<15:0><sup>(2)</sup>  
1111-1111 = 1.4° when NCO\_PHASE<15:0> = 0x00FF  
•  
0000-0000 = 0° when NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** This register has effect only when DDC mode is used in MCP37D20-200.

**2:**  $NCO\_PHASE\_OFFSET<15:0> = 2^{16} \times \text{Phase Offset Value}/360$ .

**3:** When this register is used, the same setting must be repeated in Addresses 0x88, 0x8A, 0x8C, 0x8E, 0x90, 0x92 and 0x94.

## REGISTER 5-44: ADDRESS 0X87 – NCO PHASE OFFSET IN DDC MODE (UPPER BYTE)<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_PHASE<15:8>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **NCO\_PHASE<15:8>**: Upper byte of NCO\_PHASE<15:0><sup>(2)</sup>  
1111-1111 = 359.995° when NCO\_PHASE<15:0> = 0xFFFF  
• • •  
0000-0000 = 0° when NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1](#) and [Note 2](#) in [Register 5-43](#).

**2:** When this register is used, the same setting must be repeated in Addresses 0x89, 0x8B, 0x8D, 0x8F, 0x91, 0x93 and 0x95.

# MCP37220-200 AND MCP37D20-200

## REGISTER 5-45: ADDRESS 0X88 – NCO PHASE OFFSET (REPEAT) IN DDC MODE (LOWER BYTE)<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_PHASE<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **NCO\_PHASE<7:0>**: Lower byte of NCO\_PHASE<15:0><sup>(1)</sup>  
0000-0000 = 0° when NCO\_PHASE<15:0> = 0x0000 (Default)

**Note 1:** See [Note 1](#) in [Register 5-43](#). Keep this register setting the same as in Address 0x86.

## REGISTER 5-46: ADDRESS 0X89 – NCO PHASE OFFSET (REPEAT) IN DDC MODE (UPPER BYTE)<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_PHASE<15:8>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **NCO\_PHASE<15:8>**: Upper byte of NCO\_PHASE<15:0><sup>(1)</sup>  
0000-0000 = 0° when NCO\_PHASE<15:0> = 0x0000 (Default)

**Note 1:** See [Note 1](#) in [Register 5-43](#). Keep this register setting the same as in Address 0x87.

## REGISTER 5-47: ADDRESS 0X8A – NCO PHASE OFFSET (REPEAT) IN DDC MODE (LOWER BYTE)<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_PHASE<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **NCO\_PHASE<7:0>**: Lower byte of NCO\_PHASE<15:0><sup>(1)</sup>  
0000-0000 = 0° when NCO\_PHASE<15:0> = 0x0000 (Default)

**Note 1:** See [Note 1](#) in [Register 5-43](#). Keep this register setting the same as in Address 0x86.



# MCP37220-200 AND MCP37D20-200

## REGISTER 5-48: ADDRESS 0X8B – NCO PHASE OFFSET (REPEAT) IN DDC MODE (UPPER BYTE)<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_PHASE<15:8>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **NCO\_PHASE<15:8>**: Upper byte of NCO\_PHASE<15:0><sup>(1)</sup>  
0000-0000 = 0° when NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1](#) in [Register 5-43](#). Keep this register setting the same as in Address 0x87.

## REGISTER 5-49: ADDRESS 0X8C – NCO PHASE OFFSET (REPEAT) IN DDC MODE (LOWER BYTE)<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_PHASE<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **NCO\_PHASE<7:0>**: Lower byte of NCO\_PHASE<15:0><sup>(1)</sup>  
0000-0000 = 0° when NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1](#) in [Register 5-43](#). Keep this register setting the same as in Address 0x86.

## REGISTER 5-50: ADDRESS 0X8D – NCO PHASE OFFSET (REPEAT) IN DDC MODE (UPPER BYTE)<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_PHASE<15:8>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **NCO\_PHASE<15:8>**: Upper byte of NCO\_PHASE<15:0><sup>(1)</sup>  
0000-0000 = 0° when NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1](#) in [Register 5-43](#). Keep this register setting the same as in Address 0x87.

# MCP37220-200 AND MCP37D20-200

## REGISTER 5-51: ADDRESS 0X8E – NCO PHASE OFFSET (REPEAT) IN DDC MODE (LOWER BYTE)<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_PHASE<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **NCO\_PHASE<7:0>**: Lower byte of NCO\_PHASE<15:0><sup>(1)</sup>  
0000-0000 = 0° when NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1](#) in [Register 5-43](#). Keep this register setting the same as in Address 0x86.

## REGISTER 5-52: ADDRESS 0X8F – NCO PHASE OFFSET (REPEAT) IN DDC MODE (UPPER BYTE)<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_PHASE<15:8>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **NCO\_PHASE<15:8>**: Upper byte of NCO\_PHASE<15:0><sup>(1)</sup>  
0000-0000 = 0° when NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1](#) in [Register 5-43](#). Keep this register setting the same as in Address 0x87.

## REGISTER 5-53: ADDRESS 0X90 – NCO PHASE OFFSET (REPEAT) IN DDC MODE (LOWER BYTE)<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_PHASE<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **NCO\_PHASE<7:0>**: Lower byte of NCO\_PHASE<15:0><sup>(1)</sup>  
0000-0000 = 0° when NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1](#) in [Register 5-43](#). Keep this register setting the same as in Address 0x86.

# MCP37220-200 AND MCP37D20-200

## REGISTER 5-54: ADDRESS 0X91 – NCO PHASE OFFSET (REPEAT) IN DDC MODE (UPPER BYTE)<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_PHASE<15:8>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **NCO\_PHASE<15:8>**: Upper byte of NCO\_PHASE<15:0><sup>(1)</sup>  
 0000-0000 = 0° when NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1](#) in [Register 5-43](#). Keep this register setting the same as in Address 0x87.

## REGISTER 5-55: ADDRESS 0X92 – NCO PHASE OFFSET (REPEAT) IN DDC MODE (LOWER BYTE)<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_PHASE<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **NCO\_PHASE<7:0>**: Lower byte of NCO\_PHASE<15:0><sup>(1)</sup>  
 0000-0000 = 0° when NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1](#) in [Register 5-43](#). Keep this register setting the same as in Address 0x86.

## REGISTER 5-56: ADDRESS 0X93 – NCO PHASE OFFSET (REPEAT) IN DDC MODE (UPPER BYTE)<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_PHASE<15:8>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **NCO\_PHASE<15:8>**: Upper byte of NCO\_PHASE<15:0><sup>(1)</sup>  
 0000-0000 = 0° when NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1](#) in [Register 5-43](#). Keep this register setting the same as in Address 0x87.

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## REGISTER 5-57: ADDRESS 0X94 – NCO PHASE OFFSET (REPEAT) IN DDC MODE (LOWER BYTE)<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_PHASE<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **NCO\_PHASE<7:0>**: Lower byte of NCO\_PHASE<15:0><sup>(1)</sup>  
0000-0000 = 0° when NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1](#) in [Register 5-43](#). Keep this register setting the same as in Address 0x86.

## REGISTER 5-58: ADDRESS 0X95 – NCO PHASE OFFSET (REPEAT) IN DDC MODE (UPPER BYTE)<sup>(1)</sup>

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NCO_PHASE<15:8>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **NCO\_PHASE<15:8>**: Upper byte of NCO\_PHASE<15:0><sup>(1)</sup>  
0000-0000 = 0° when NCO\_PHASE<15:0> = 0x0000 (**Default**)

**Note 1:** See [Note 1](#) in [Register 5-43](#). Keep this register setting the same as in Address 0x87.

# MCP37220-200 AND MCP37D20-200

## REGISTER 5-59: ADDRESS 0X96 – DIGITAL GAIN CONTROL<sup>(1,2)</sup>

R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0
DIG_GAIN<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **DIG\_GAIN<7:0>:** Digital gain setting<sup>(3)</sup>

1111-1111 = -0.03125

1111-1110 = -0.0625

1111-1101 = -0.09375

1111-1100 = -0.125

...

1000-0011 = -3.90625

1000-0010 = -3.9375

1000-0001 = -3.96875

1000-0000 = -4

0111-1111 = 3.96875 (MAX)

0111-1110 = 3.9375

0111-1101 = 3.90625

0111-1100 = 3.875

...

0011-1100 = 1.875 (Default)

0011-1011 = 1.84375

0011-1010 = 1.8125

0011-1001 = 1.78125

0011-1000 = 1.75 (Optimum)<sup>(3)</sup>

...

0000-0011 = 0.09375

0000-0010 = 0.0625

0000-0001 = 0.03125

0000-0000 = 0.0

**Note 1:** When this setting is updated, the same setting must be repeated in Addresses 0x97 - 0x9D.

**Note 2:** Max = 0x7F (3.96875), Min = 0x80 (-4), Step size = 0x01 (0.03125). Bit range from 0x81 - 0xFF is two's complementary of 0x00 - 0x80. Negative gain setting inverts output.

**Note 3:** This setting improves SNR by 0.7 dB from the default setting. This setting is recommended for optimum SNR performance.

# MCP37220-200 AND MCP37D20-200

## REGISTER 5-60: ADDRESS 0X97 – DIGITAL GAIN CONTROL (REPEAT)<sup>(1)</sup>

R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0
DIG_GAIN<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **DIG\_GAIN<7:0>**: Digital gain setting<sup>(1)</sup>  
0011-1100 = 1.875 (Default)

**Note 1:** Keep this register setting the same as in Address 0x96. See [Notes 1-3](#) in [Register 5-59](#)

## REGISTER 5-61: ADDRESS 0X98 – DIGITAL GAIN CONTROL (REPEAT)<sup>(1)</sup>

R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0
DIG_GAIN<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **DIG\_GAIN<7:0>**: Digital gain setting<sup>(1)</sup>  
0011-1100 = 1.875 (Default)

**Note 1:** Keep this register setting the same as in Address 0x96. See [Notes 1-3](#) in [Register 5-59](#)

## REGISTER 5-62: ADDRESS 0X99 – DIGITAL GAIN CONTROL (REPEAT)<sup>(1)</sup>

R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0
DIG_GAIN<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **DIG\_GAIN<7:0>**: Digital gain setting<sup>(1)</sup>  
0011-1100 = 1.875 (Default)

**Note 1:** Keep this register setting the same as in Address 0x96. See [Notes 1-3](#) in [Register 5-59](#)

## REGISTER 5-63: ADDRESS 0X9A – DIGITAL GAIN CONTROL (REPEAT)<sup>(1)</sup>

R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0
DIG_GAIN<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 7-0      **DIG\_GAIN<7:0>**: Digital gain setting<sup>(1)</sup>  
0011-1100 = 1.875 (Default)

**Note 1:** Keep this register setting the same as in Address 0x96. See [Notes 1-3](#) in [Register 5-59](#)

# MCP37220-200 AND MCP37D20-200

## REGISTER 5-64: ADDRESS 0X9B – DIGITAL GAIN CONTROL (REPEAT)<sup>(1)</sup>

R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0
DIG_GAIN<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **DIG\_GAIN<7:0>**: Digital gain setting<sup>(1)</sup>  
0011-1100 = 1.875 (**Default**)

**Note 1:** Keep this register setting the same as in Address 0x96. See [Notes 1-3](#) in [Register 5-59](#)

## REGISTER 5-65: ADDRESS 0X9C – DIGITAL GAIN CONTROL (REPEAT)<sup>(1)</sup>

R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0
DIG_GAIN<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **DIG\_GAIN<7:0>**: Digital gain setting<sup>(1)</sup>  
0011-1100 = 1.875 (**Default**)

**Note 1:** Keep this register setting the same as in Address 0x96. See [Notes 1-3](#) in [Register 5-59](#)

## REGISTER 5-66: ADDRESS 0X9D – DIGITAL GAIN CONTROL (REPEAT)<sup>(1)</sup>

R/W-0	R/W-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0
DIG_GAIN<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **DIG\_GAIN<7:0>**: Digital gain setting<sup>(1)</sup>  
0011-1100 = 1.875 (**Default**)

**Note 1:** Keep this register setting the same as in Address 0x96. See [Notes 1-3](#) in [Register 5-59](#)

# MCP37220-200 AND MCP37D20-200

## REGISTER 5-67: ADDRESS 0XC0 – CALIBRATION STATUS INDICATION

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
ADC_CAL_STAT	FCB<6:0>						
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7 **ADC\_CAL\_STAT:** Power-Up auto-calibration status indication flag bit

1 = Device power-up calibration is completed

0 = Device power-up calibration is not completed

bit 6-0 **FCB<6:0>:** Factory-Controlled bits. These bits are read only and have no meaning for the user.

## REGISTER 5-68: ADDRESS 0XD1 – PLL CALIBRATION STATUS AND PLL DRIFT STATUS INDICATION

R-x	R-x	R-x	R-x	R-x	R-x	R-x	R-x
FCB<4:3>	PLL_CAL_STAT	FCB<2:1>	PLL_VCOL_STAT	PLL_VCOH_STAT	FCB<0>		
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-6 **FCB<4:3>:** Factory-Controlled bits. These bits are read only and have no meaning for the user.

bit 5 **PLL\_CAL\_STAT:** PLL auto-calibration status indication flag bit<sup>(1)</sup>

1 = Complete: PLL auto-calibration is completed

0 = Incomplete: PLL auto-calibration is not completed

bit 4-3 **FCB<2:1>:** Factory-Controlled bits. These bits are read only and have no meaning for the user.

bit 2 **PLL\_VCOL\_STAT:** PLL drift status indication bit

1 = PLL drifts out of lock with low VCO frequency

0 = PLL operates as normal

bit 1 **PLL\_VCOH\_STAT:** PLL drift status indication bit

1 = PLL drifts out of lock with high VCO frequency

0 = PLL operates as normal

bit 0 **FCB<0>:** Factory-Controlled bit. This bit is read only and have no meaning for the user.

**Note 1:** See PLL\_CAL\_TRIG bit setting in Address 0x6B ([Register 5-27](#)).



# MCP37220-200 AND MCP37D20-200

## REGISTER 5-69: ADDRESS 0X15C – CHIP ID (LOWER BYTE)<sup>(1)</sup>

R-x	R-x	R-x	R-x	R-x	R-x	R-x	R-x
CHIP_ID<7:0>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **CHIP\_ID<7:0>**: Chip ID of the device: Lower byte of the CHIP\_ID<15:0>

**Note 1:** Read-only register. Preprogrammed at the factory for internal use.

**Example:** MCP37220-200: '0001000001010000'

MCP37D20-200: '0001001001010000'

## REGISTER 5-70: ADDRESS 0X15D – CHIP ID (UPPER BYTE)<sup>(1)</sup>

R-x	R-x	R-x	R-x	R-x	R-x	R-x	R-x
CHIP_ID<15:8>							
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0      **CHIP\_ID<15:8>**: Chip ID of the device: Upper byte of the CHIP\_ID<15:0>

**Note 1:** Read-only register. Preprogrammed at the factory for internal use.

**Example:** MCP37220-200: '0001000001010000'

MCP37D20-200: '0001001001010000'

# MCP37220-200 AND MCP37D20-200

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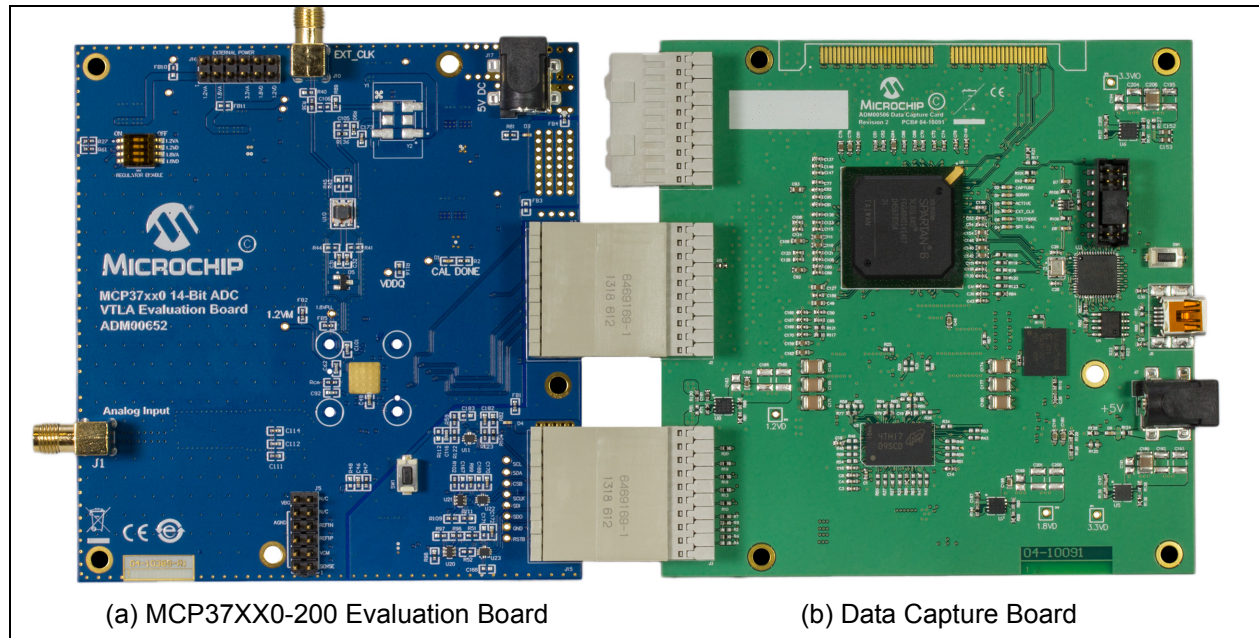
NOTES:

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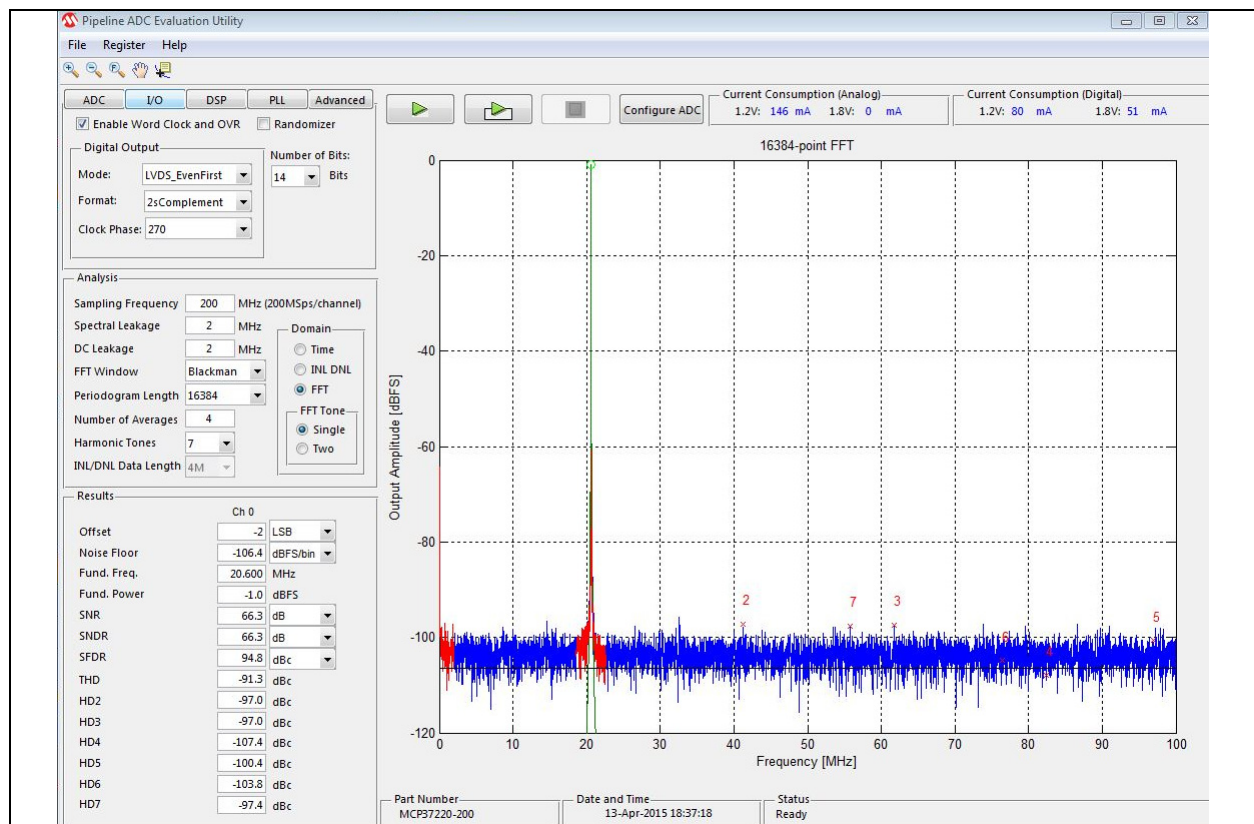
## 6.0 DEVELOPMENT SUPPORT

Microchip offers a high-speed ADC evaluation platform which can be used to evaluate Microchip's high-speed ADC products. The platform consists of an MCP37XXX-200 evaluation board, an FPGA-based data capture card board and PC-based Graphical User Interface (GUI) software for ADC configuration and evaluation.

Figure 6-1 and Figure 6-2 show this evaluation tool. This evaluation platform allows users to quickly evaluate the ADC's performance for their specific application requirements. More information is available at <http://www.microchip.com>.



**FIGURE 6-1:** MCP37XX0 Evaluation Kit.



**FIGURE 6-2:** PC-Based Graphical User Interface Software.

# MCP37220-200 AND MCP37D20-200

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NOTES:

# MCP37220-200 AND MCP37D20-200

## 7.0 TERMINOLOGY

### Analog Input Bandwidth (Full-Power Bandwidth)

The analog input frequency at which the spectral power of the fundamental frequency (as determined by FFT analysis) is reduced by 3 dB.

### Aperture Delay or Sampling Delay

The time delay between the rising edge of the input sampling clock and the actual time at which the sampling occurs.

### Aperture Uncertainty

The sample-to-sample variation in aperture delay.

### Aperture Delay Jitter

The variation in the aperture delay time from conversion to conversion. This random variation will result in noise when sampling an AC input. The signal-to-noise ratio due to the jitter alone will be:

#### EQUATION 7-1:

$$SNR_{JITTER} = -20\log(2\pi \times f_{IN} \times t_{JITTER})$$

### Calibration Algorithms

This device utilizes two patented analog and digital calibration algorithms, Harmonic Distortion Correction (HDC) and DAC Noise Cancellation (DNC), to improve the ADC performance. The algorithms compensate various sources of linear impairments such as capacitance mismatch, charge injection error and finite gain of operational amplifiers. These algorithms execute in both power-up sequence (foreground) and background mode:

- Power-Up Calibration: The calibration is conducted within the first  $3 \times 2^{26}$  clock cycles after power-up. The user needs to wait this Power-Up Calibration period after the device is powered-up for an accurate ADC performance.
- Background Calibration: This calibration is conducted in background while the ADC is performing conversions. The update rate is about once every  $2^{30}$  clock cycles.

### Pipeline Delay (LATENCY)

LATENCY is the number of clock cycles between the initiation of conversion and when that data is presented to the output driver stage. Data for any given sample is available after the pipeline delay plus the output delay after that sample is taken. New data is available at every clock cycle, but the data lags the conversion by the pipeline delay plus the output delay.

### Clock Pulse Width and Duty Cycle

The clock duty cycle is the ratio of the time the clock signal remains at a logic high (clock pulse width) to one clock period. Duty cycle is typically expressed as a percentage. A perfect differential sine-wave clock results in a 50% duty cycle.

### Differential Nonlinearity (DNL, No Missing Codes)

An ideal ADC exhibits code transitions that are exactly 1 LSB apart. DNL is the deviation from this ideal value. No missing codes to 12-bit resolution indicates that all 4096 codes must be present over all the operating conditions.

### Integral Nonlinearity (INL)

INL is the maximum deviation of each individual code from an ideal straight line drawn from negative full scale through positive full scale.

### Signal-to-Noise Ratio (SNR)

SNR is the ratio of the power of the fundamental ( $P_S$ ) to the noise floor power ( $P_N$ ), below the Nyquist frequency and excluding the power at DC and the first nine harmonics.

#### EQUATION 7-2:

$$SNR = 10\log\left(\frac{P_S}{P_N}\right)$$

SNR is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full-scale) when the power of the fundamental is extrapolated to the converter full-scale range.

### Signal-to-Noise and Distortion (SINAD)

SINAD is the ratio of the power of the fundamental ( $P_S$ ) to the power of all the other spectral components including noise ( $P_N$ ) and distortion ( $P_D$ ) below the Nyquist frequency, but excluding DC:

#### EQUATION 7-3:

$$\begin{aligned} SINAD &= 10\log\left(\frac{P_S}{P_D + P_N}\right) \\ &= -10\log\left[10^{\frac{-SNR}{10}} - 10^{\frac{-THD}{10}}\right] \end{aligned}$$

SINAD is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full-scale) when the power of the fundamental is extrapolated to the converter full-scale range.

# MCP37220-200 AND MCP37D20-200

## Effective Number of Bits (ENOB)

The effective number of bits for a sine wave input at a given input frequency can be calculated directly from its measured SINAD using the following formula:

### EQUATION 7-4:

$$ENOB = \frac{SINAD - 1.76}{6.02}$$

## Gain Error

Gain error is the deviation of the ADC's actual input full-scale range from its ideal value. The gain error is given as a percentage of the ideal input full-scale range.

Gain error is usually expressed in LSb or as a percentage of full-scale range (%FSR).

## Gain-Error Drift

Gain-error drift is the variation in gain error due to a change in ambient temperature, typically expressed in ppm/°C.

## Offset Error

The major carry transition should occur for an analog value of  $\frac{1}{2}$  LSb below  $A_{IN+} = A_{IN-}$ . Offset error is defined as the deviation of the actual transition from that point.

## Temperature Drift

The temperature drift for offset error and gain error specifies the maximum change from the initial (+25°C) value to the value across the  $T_{MIN}$  to  $T_{MAX}$  range.

## Maximum Conversion Rate

The maximum clock rate at which parametric testing is performed.

## Minimum Conversion Rate

The minimum clock rate at which parametric testing is performed.

## Spurious-Free Dynamic Range (SFDR)

SFDR is the ratio of the power of the fundamental to the highest other spectral component (either spur or harmonic). SFDR is typically given in units of dBc (dB to carrier) or dBFS.

## Total Harmonic Distortion (THD)

THD is the ratio of the power of the fundamental ( $P_S$ ) to the summed power of the first 13 harmonics ( $P_D$ ).

### EQUATION 7-5:

$$THD = 10 \log \left( \frac{P_S}{P_D} \right)$$

THD is typically given in units of dBc (dB to carrier). THD is also shown by:

### EQUATION 7-6:

$$THD = -20 \log \frac{\sqrt{V_2^2 + V_3^2 + V_4^2 + \dots + V_n^2}}{V_1^2}$$

Where:

$V_1$  = RMS amplitude of the fundamental frequency

$V_1$  through  $V_n$  = Amplitudes of the second through  $n^{\text{th}}$  harmonics

## Two-Tone Intermodulation Distortion (Two-Tone IMD, IMD3)

Two-tone IMD is the ratio of the power of the fundamental (at frequencies  $f_{IN1}$  and  $f_{IN2}$ ) to the power of the worst spectral component at either frequency  $2f_{IN1} - f_{IN2}$  or  $2f_{IN2} - f_{IN1}$ . Two-tone IMD is a function of the input amplitudes and frequencies ( $f_{IN1}$  and  $f_{IN2}$ ). It is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full-scale) when the power of the fundamental is extrapolated to the ADC full-scale range.

## Common-Mode Rejection Ratio (CMRR)

Common-mode rejection is the ability of a device to reject a signal that is common to both sides of a differential input pair. The common-mode signal can be an AC or DC signal or a combination of the two. CMRR is measured using the ratio of the differential signal gain to the common-mode signal gain and expressed in dB with the following equation:

### EQUATION 7-7:

$$CMRR = 20 \log \left( \frac{A_{DIFF}}{A_{CM}} \right)$$

Where:

$A_{DIFF}$  =  $\Delta$ Output Code/ $\Delta$ Differential Voltage

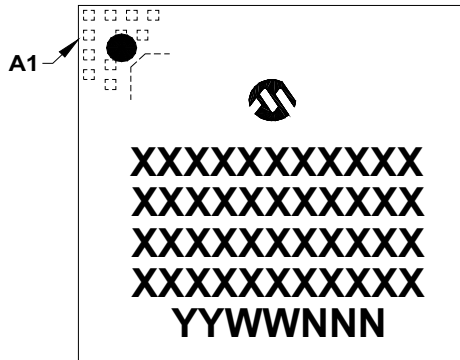
$A_{DIFF}$  =  $\Delta$ Output Code/ $\Delta$ Common Mode Voltage

# MCP37220-200 AND MCP37D20-200

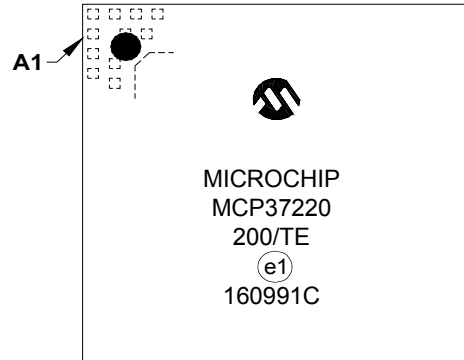
## 8.0 PACKAGING INFORMATION

### 8.1 Package Marking Information

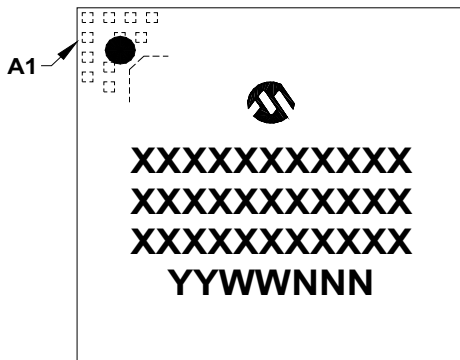
121-Lead TFBGA (8x8 mm)



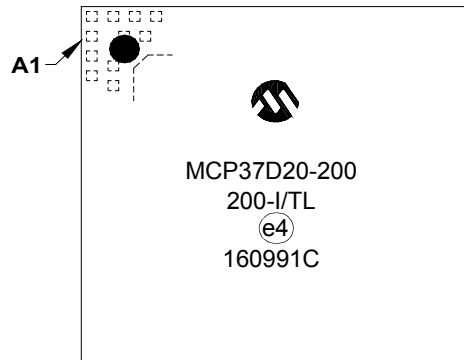
Example



124-Lead VTLA (9x9x0.9 mm)



Example



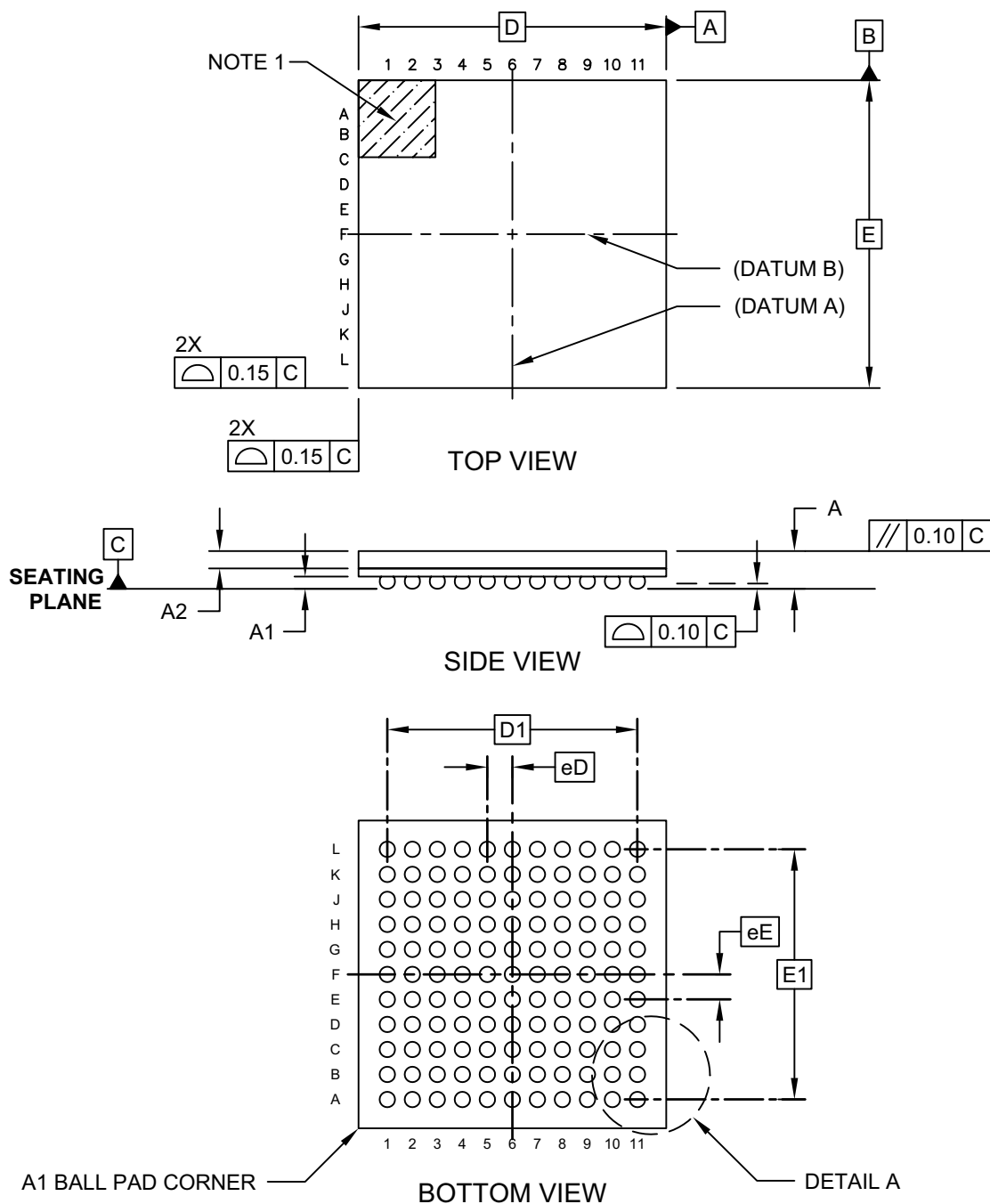
<b>Legend:</b>	XX...X	Customer-specific information
	Y	Year code (last digit of calendar year)
	YY	Year code (last 2 digits of calendar year)
	WW	Week code (week of January 1 is week '01')
	NNN	Alphanumeric traceability code
	e1	Pb-free JEDEC® designator for SnAgCu
	e4	Pb-free JEDEC® designator for NiPdAu
	*	This package is Pb-free. The Pb-free JEDEC designator (e1 or e4) can be found on the outer packaging for this package.

**Note:** In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information.

# MCP37220-200 AND MCP37D20-200

## 121-Ball Thin Fine Pitch Ball Grid Array (TE) - 8x8 mm Body [TFBGA] System In Package

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



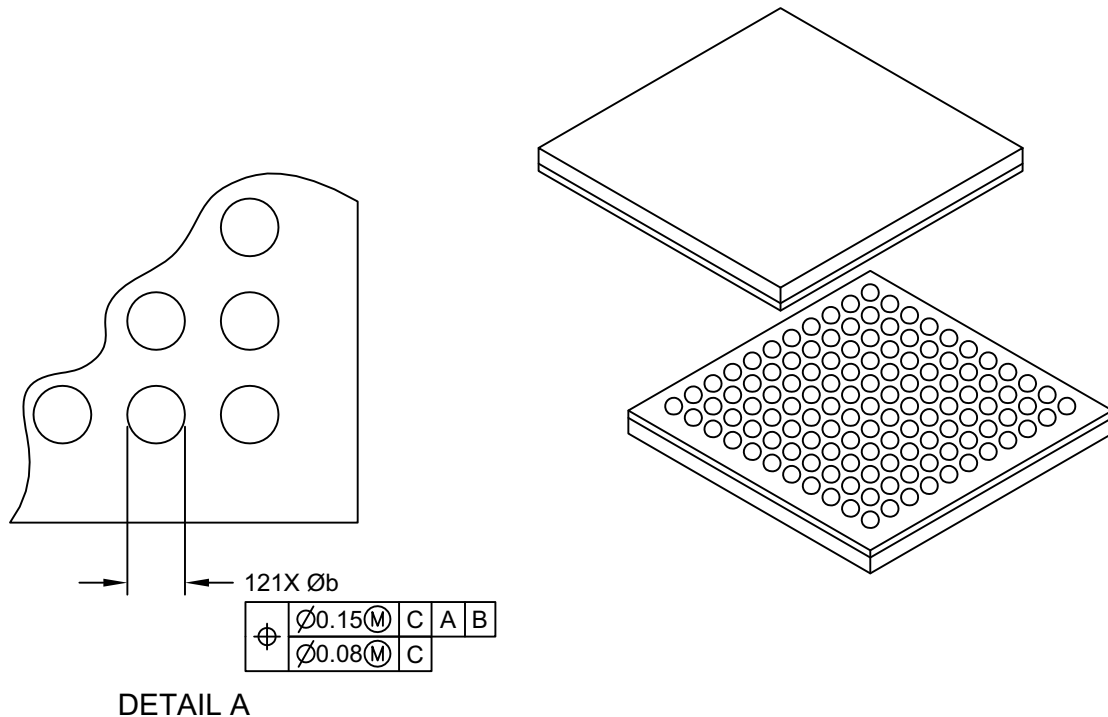
Microchip Technology Drawing C04-212A Sheet 1 of 2



# MCP37220-200 AND MCP37D20-200

## 121-Ball Thin Fine Pitch Ball Grid Array (TE) - 8x8 mm Body [TFBGA] System In Package

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Terminals	N	121		
Pitch	eE	0.65 BSC		
Pitch	eD	0.65 BSC		
Overall Height	A	-	-	1.08
Standoff	A1	0.21	0.32	-
Cap Thickness	A2	0.40	0.45	0.50
Overall Width	E	8.00 BSC		
Overall Pitch	E1	6.50 BSC		
Overall Length	D	8.00 BSC		
Overall Pitch	D1	6.50 BSC		
Terminal Diameter	b	.035	0.40	0.45

### Notes:

1. Terminal A1 visual index feature may vary, but must be located within the hatched area.
2. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

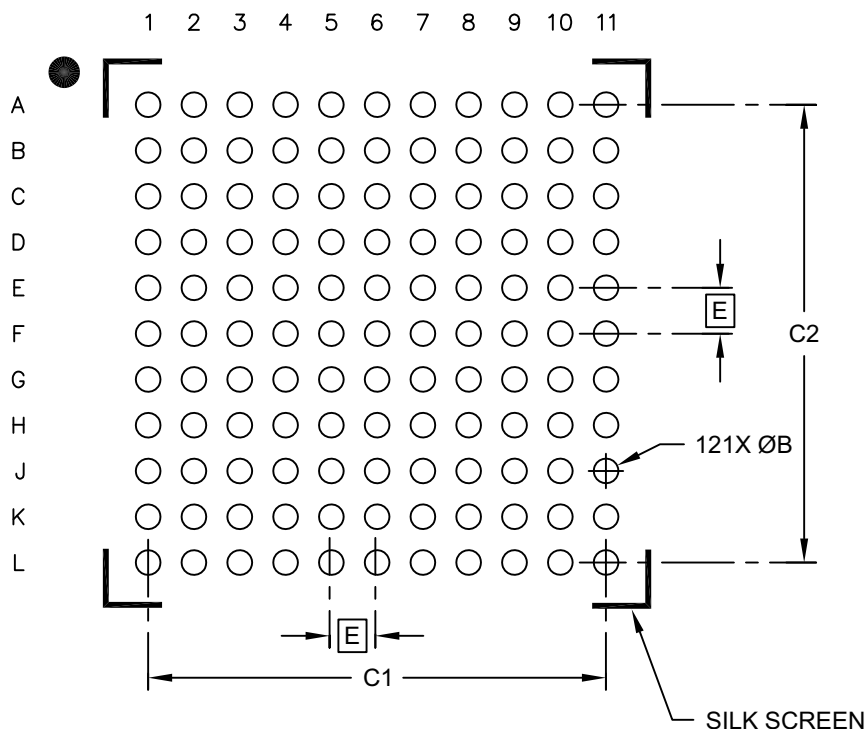
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-212A Sheet 2 of 2

# MCP37220-200 AND MCP37D20-200

## 121-Ball Thin Fine Pitch Ball Grid Array (TE) - 8x8 mm Body [TFBGA] System In Package

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E	0.65 BSC		
Contact Pad Spacing	C1		6.50	
Contact Pad Spacing	C2		6.50	
Contact Pad Diameter (X121)	B		0.35	

**Notes:**

1. Dimensioning and tolerancing per ASME Y14.5M

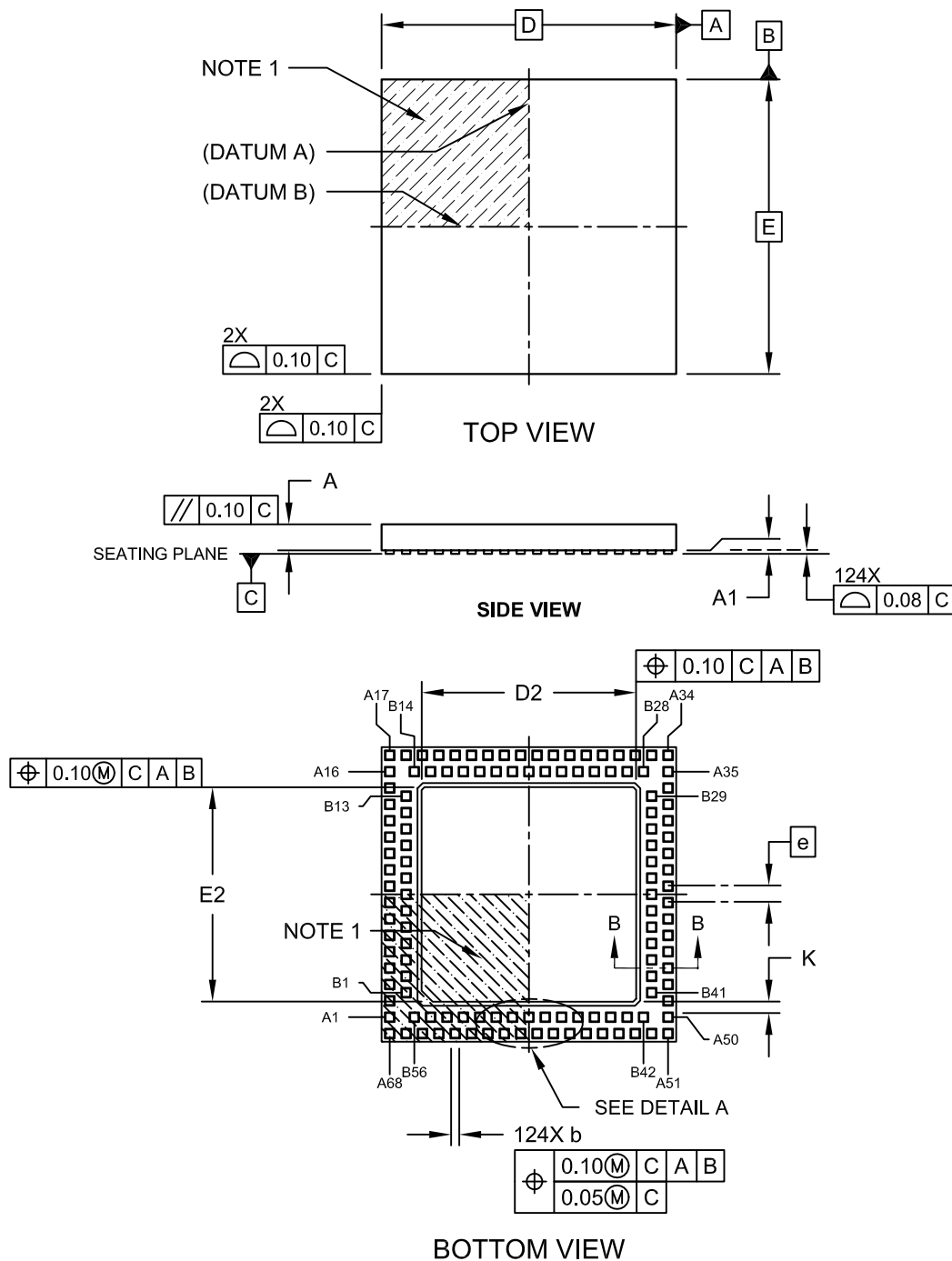
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2212B-TE

# MCP37220-200 AND MCP37D20-200

## 124-Terminal Very Thin Leadless Array Package (TL) – 9x9x0.9 mm Body [VTLA]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>

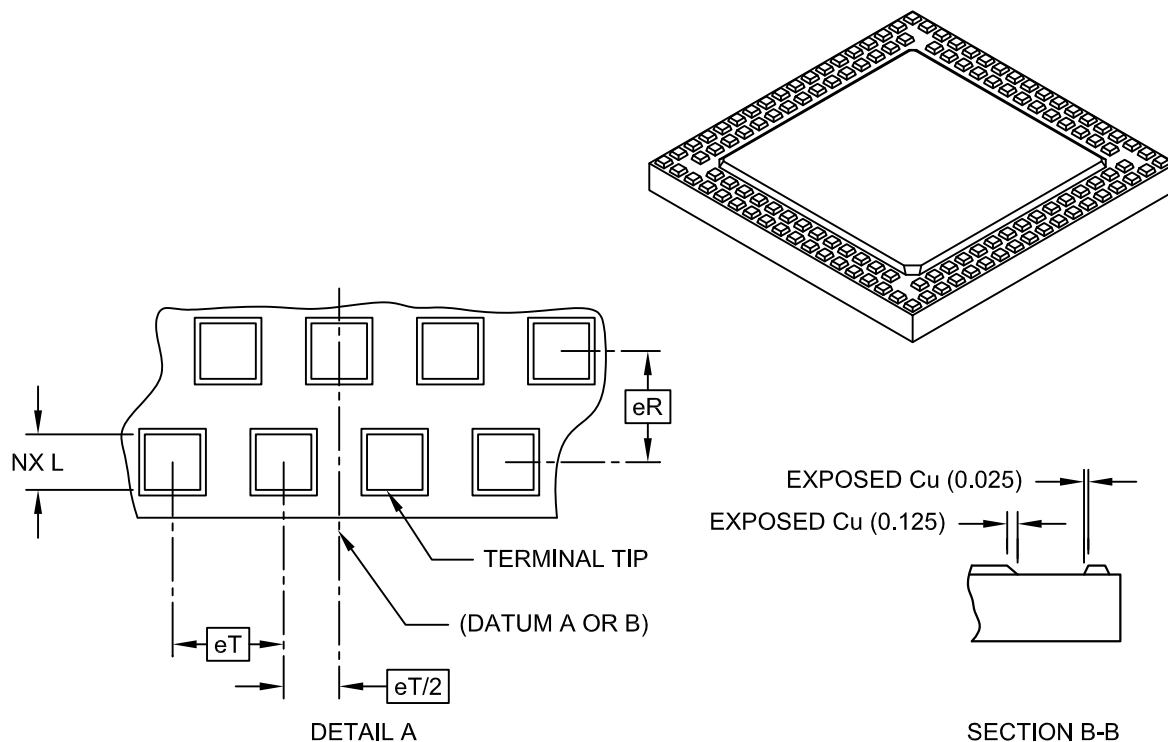


Microchip Technology Drawing C04-193A Sheet 1 of 2

# MCP37220-200 AND MCP37D20-200

## 124-Terminal Very Thin Leadless Array Package (TL) – 9x9x0.9 mm Body [VTLA]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Pins	N	124		
Pitch	eT	0.50 BSC		
Pitch (Inner to outer terminal ring)	eR	0.50 BSC		
Overall Height	A	0.80	0.85	0.90
Standoff	A1	0.00	-	0.05
Overall Width	E	9.00 BSC		
Exposed Pad Width	E2	6.40	6.55	6.70
Overall Length	D	9.00 BSC		
Exposed Pad Length	D2	6.40	6.55	6.70
Contact Width	b	0.20	0.25	0.30
Contact Length	L	0.20	0.25	0.30
Contact-to-Exposed Pad	K	0.20	-	-

### Notes:

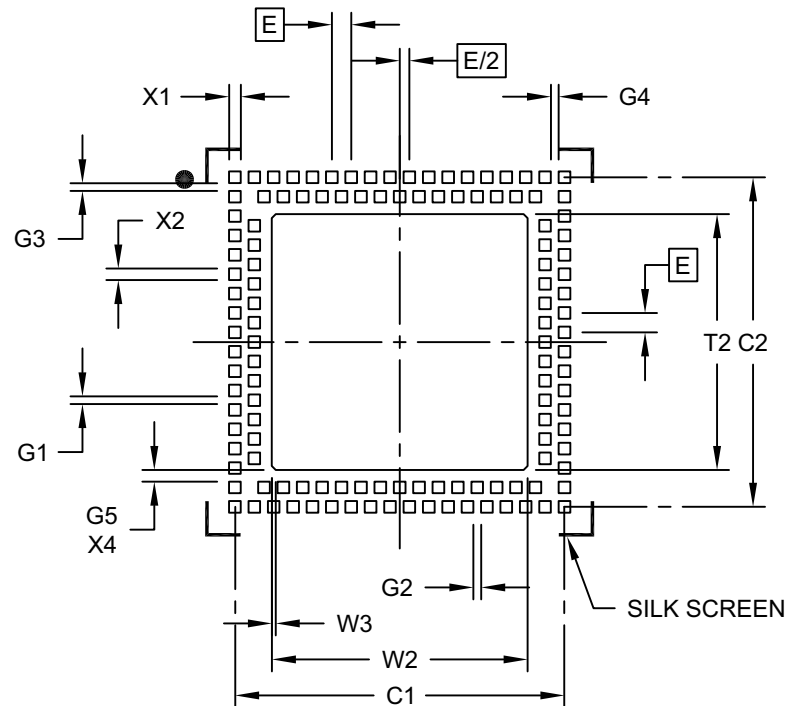
- Pin 1 visual index feature may vary, but must be located within the hatched area.
- Package is saw singulated.
- Dimensioning and tolerancing per ASME Y14.5M.  
BSC: Basic Dimension. Theoretically exact value shown without tolerances.  
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-193A Sheet 2 of 2

# MCP37220-200 AND MCP37D20-200

## 124-Very Thin Leadless Array Package (TL) – 9x9x0.9 mm Body [VTLA]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Dimension Limits	Units	MILLIMETERS		
		MIN	NOM	MAX
Contact Pitch	E	0.50 BSC		
Pad Clearance	G1	0.20		
Pad Clearance	G2	0.20		
Pad Clearance	G3	0.20		
Pad Clearance	G4	0.20		
Contact to Center Pad Clearance (X4)	G5	0.30		
Optional Center Pad Width	T2			6.60
Optional Center Pad Length	W2			6.60
Optional Center Pad Chamfer (X4)	W3		0.10	
Contact Pad Spacing	C1		8.50	
Contact Pad Spacing	C2		8.50	
Contact Pad Width (X124)	X1			0.30
Contact Pad Length (X124)	X2			0.30

**Notes:**

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2193A

# MCP37220-200 AND MCP37D20-200

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NOTES:

## APPENDIX A: REVISION HISTORY

### Revision B (April 2016)

- Modified package types and device offers to reflect the availability of the TFBGA package.
- Updated input leakage current at CLK input pin in [Table 2-1](#).
- Minor typographical changes.

### Revision A (April 2015)

- Original Release of this Document.

# MCP37220-200 AND MCP37D20-200

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NOTES:



# MCP37220-200 AND MCP37D20-200

## PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

<u>PART NO.</u>	<u>/X<sup>(1)</sup></u>	<u>-XXX</u>	<u>X</u>	<u>/XX</u>	<b>Examples:</b>
Device	Tape and Reel Option	Sample Rate	Temperature Range	Package	
<b>Device:</b> MCP37220-200: 14-Bit Low-Power Single-Channel ADC MCP37D20-200: 14-Bit Low-Power Single-Channel ADC with digital down-converter option					a) MCP37220-200I/TL: Industrial temperature, 124LD VTLA, 200 Msps b) MCP37220T-200I/TL: Tape and Reel, Industrial temperature, 124LD VTLA, 200 Msps c) MCP37220-200I/TE: Industrial temperature, 121LD TFBGA, 200 Msps
<b>Tape and Reel Option:</b> Blank = Standard packaging (tube or tray) T = Tape and Reel <sup>(1)</sup>					a) MCP37D20-200I/TL: Industrial temperature, 124LD VTLA, 200 Msps b) MCP37D20T-200I/TL: Tape and Reel, Industrial temperature, 124LD VTLA, 200 Msps c) MCP37D20-200I/TE: Industrial temperature, 121LD TFBGA, 200 Msps
<b>Sample Rate</b> 200 = 200 Msps					<b>Note 1:</b> Tape and Reel identifier only appears in the catalog part number description. This identifier is used for ordering purposes and is not printed on the device package. Check with your Microchip Sales Office for package availability with the Tape and Reel option.
<b>Temperature Range:</b> I = -40°C to +85°C (Industrial)					
<b>Package:</b> TL = Terminal Very Thin Leadless Array Package - 9x9x0.9 mm Body (VTLA), 124-Lead TE = Ball Plastic Thin Profile Fine Pitch Ball Grid Array - 8x8 mm Body (TFBGA), 121-Lead					

# MCP37220-200 AND MCP37D20-200

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NOTES:

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**Note the following details of the code protection feature on Microchip devices:**

- Microchip products meet the specification contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is one of the most secure families of its kind on the market today, when used in the intended manner and under normal conditions.
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