

# HI-3582, HI-3583

January 2005

### 3.3V ARINC 429 TERMINAL IC

### **GENERAL DESCRIPTION**

The HI-3582/HI-3583 from Holt Integrated Circuits are silicon gate CMOS devices for interfacing a 16-bit parallel data bus directly to the ARINC 429 serial bus. The HI-3582/HI-3583 design offers many enhancements to the industry standard HI-8282 architecture. The device provides two receivers each with label recognition, 32 by 32 FIFO, and analog line receiver. Up to 16 labels may be programmed for each receiver. The independent transmitter has a 32 X 32 FIFO and a built-in line driver. The status of all three FIFOs can be monitored using the external status pins, or by polling the HI-3582/HI-3583 status register. Other new features include a programmable option of data or parity in the 32nd bit, and the ability to unscramble the 32 bit word. Also, versions are available with different values of input resistance and output resistance to allow users to more easily add external lightning protection circuitry.

The 16-bit parallel data bus exchanges the 32-bit ARINC data word in two steps when either loading the transmitter or interrogating the receivers. The databus and all control signals are CMOS and TTL compatible.

The HI-3582/HI-3583 apply the ARINC protocol to the receivers and transmitter. Timing is based on a 1 Megahertz clock.

Although the line driver shares a common substrate with the receivers, the design of the physical isolation does not allow parasitic crosstalk, and thereby achieves the same isolation as common hybrid layouts.

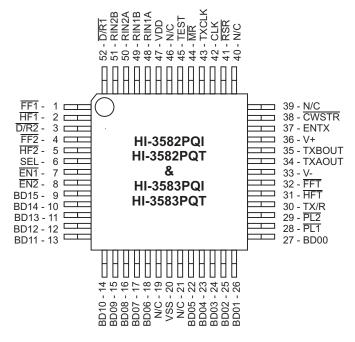
### **APPLICATIONS**

- Avionics data communication
- Serial to parallel conversion
- Parallel to serial conversion

### **FEATURES**

- ARINC specification 429 compatible
- 3.3V logic supply operation
- · Dual receiver and transmitter interface
- Analog line driver and receivers connect directly to ARINC bus
- Programmable label recognition
- On-chip 16 label memory for each receiver
- 32 x 32 FIFOs each receiver and transmitter
- Independent data rate selection for transmitter and each receiver
- · Status register
- Data scramble control
- 32nd transmit bit can be data or parity
- Self test mode
- Low power
- Industrial & full military temperature ranges

### PIN CONFIGURATION (Top View)



52 - Pin Plastic Quad Flat Pack (PQFP)

(See page 14 for additional pin configuration)

## PIN DESCRIPTIONS

SIGNAL	FUNCTION	DESCRIPTION
VDD	POWER	+3.3V power supply pin
RIN1A	INPUT	ARINC receiver 1 positive input
RIN1B	INPUT	ARINC receiver 1 negative input
RIN2A	INPUT	ARINC receiver 2 positive input
RIN2B	INPUT	ARINC receiver 2 negative input
D/R1	OUTPUT	Receiver 1 data ready flag
FF1	OUTPUT	FIFO full Receiver 1
HF1	OUTPUT	FIFO Half full, Receiver 1
D/R2	OUTPUT	Receiver 2 data ready flag
FF2	OUTPUT	FIFO full Receiver 2
HF2	OUTPUT	FIFO Half full, Receiver 2
SEL	INPUT	Receiver data byte selection (0 = BYTE 1) (1 = BYTE 2)
EN1	INPUT	Data Bus control, enables receiver 1 data to outputs
EN2	INPUT	Data Bus control, enables receiver 2 data to outputs if EN1 is high
BD15	1/0	Data Bus
BD14	I/O	Data Bus
BD13	I/O	Data Bus
BD12	I/O	Data Bus
BD11	I/O	Data Bus
BD10	I/O	Data Bus
BD09	I/O	Data Bus
BD08	I/O	Data Bus
BD07	I/O	Data Bus
BD06	I/O	Data Bus
GND	POWER	0 V
BD05	I/O	Data Bus
BD04	I/O	Data Bus
BD03	I/O	Data Bus
BD02	I/O	Data Bus
BD01	I/O	Data Bus
BD00	I/O	Data Bus
PL1	INPUT	Latch enable for byte 1 entered from data bus to transmitter FIFO.
PL2	INPUT	Latch enable for byte 2 entered from data bus to transmitter FIFO. Must follow PL1.
TX/R	OUTPUT	Transmitter ready flag. Goes low when ARINC word loaded into FIFO. Goes high after transmission and FIFO empty.
HFT	OUTPUT	Transmitter FIFO Half Full
FFT	OUTPUT	Transmitter FIFO Full
V-	POWER	-9.5V to -10.5V
TXAOUT	OUTPUT	Line driver output - A side
TXBOUT	OUTPUT	Line driver output - B side
V+	POWER	+9.5V to +10.5V
ENTX	INPUT	Enable Transmission
CWSTR	INPUT	Clock for control word register
RSR	INPUT	Read Status Register if SEL=0, read Control Register if SEL=1
CLK	INPUT	Master Clock input
TX CLK	OUTPUT	Transmitter Clock equal to Master Clock (CLK), divided by either 10 or 80.
MR	INPUT	Master Reset, active low
TEST	INPUT	Disable Transmitter output if high (pull-down)

### **FUNCTIONAL DESCRIPTION**

### **CONTROL WORD REGISTER**

The HI-3582/HI-3583 contain a 16-bit control register which is used to configure the device. The control register bits CR0 - CR15 are loaded from BD00 - BD15 when  $\overline{\text{CWSTR}}$  is pulsed low. The control register contents are output on the databus when SEL = 1 and  $\overline{\text{RSR}}$  is pulsed low. Each bit of the control register has the following function:

CR Bit	FUNCTION	STATE	DESCRIPTION
CR0	Receiver 1	0	Data rate = CLK/10
	Data clock Select	1	Data rate = CLK/80
CR1	Label Memory	0	Normal operation
	Read / Write	1	Load 16 labels using PL1 / PL2 Read 16 labels using EN1 / EN2
CR2	Enable Label	0	Disable label recognition
	Recognition (Receiver 1)	1	Enable label recognition
CR3	Enable Label	0	Disable Label Recognition
	Recognition (Receiver 2)	1	Enable Label recognition
CR4	Enable	0	Transmitter 32nd bit is data
	32nd bit as parity	1	Transmitter 32nd bit is parity
CR5	Self Test	0	The transmitter's digital outputs are internally connected to the receiver logic inputs
		1	Normal operation
CR6	Receiver 1	0	Receiver 1 decoder disabled
	decoder	1	ARINC bits 9 and 10 must match CR7 and CR8
CR7	-	-	If receiver 1 decoder is enabled, the ARINC bit 9 must match this bit
CR8	-	-	If receiver 1 decoder is enabled, the ARINC bit 10 must match this bit
CR9	Receiver 2	0	Receiver 2 decoder disabled
	Decoder	1	ARINC bits 9 and 10 must match CR10 and CR11
CR10	-	-	If receiver 2 decoder is enabled, the ARINC bit 9 must match this bit
CR11	-	-	If receiver 2 decoder is enabled, the ARINC bit 10 must match this bit
CR12	Invert	0	Transmitter 32nd bit is Odd parity
	Transmitter parity	1	Transmitter 32nd bit is Even parity
CR13	Transmitter	0	Data rate=CLK/10, O/P slope=1.5us
	data clock select	1	Data rate=CLK/80, O/P slope=10us
CR14	Receiver 2	0	Data rate=CLK/10
	select	1	Data rate=CLK/80
CR15	Data	0	Scramble ARINC data
	format	1	Unscramble ARINC data

### STATUS REGISTER

The HI-3582/HI-3583 contain a 9-bit status register which can be interrogated to determine the status of the ARINC receivers, data FIFOs and transmitter. The contents of the status register are output on BD00 - BD08 when the  $\overline{\text{RSR}}$  pin is taken low and SEL = 0. Unused bits are output as Zeros. The following table defines the status register bits.

SR Bit	FUNCTION	STATE	DESCRIPTION
SR0	Data ready (Receiver 1)	0	Receiver 1 FIFO empty
	(Receiver 1)	1	Receiver 1 FIFO contains valid data Resets to zero when all data has been read. D/R1 pin is the inverse of this bit
SR1	FIFO half full (Receiver 1)	0	Receiver 1 FIFO holds less than 16 words
		1	Receiver 1 FIFO holds at least 16 words. HF1 pin is the inverse of this bit.
SR2	FIFO full	0	Receiver 1 FIFO not full
	(Receiver 1)	1	Receiver 1 FIFO full. To avoid data loss, the FIFO must be read within one ARINC word period. FF1 pin is the inverse of this bit
SR3	Data ready	0	Receiver 2 FIFO empty
	(Receiver 2)	1	Receiver 2 FIFO contains valid data Resets to zero when all data has been read. D/R2 pin is the inverse of this bit
SR4	FIFO half full (Receiver 2)	0	Receiver 2 FIFO holds less than 16 words
		1	Receiver 2 FIFO holds at least 16 words. HF2 pin is the inverse of this bit.
SR5	FIFO full	0	Receiver 2 FIFO not full
	(Receiver 2)	1	Receiver 2 FIFO full. To avoid data loss, the FIFO must be read within one ARINC word period. FF2 pin is the inverse of this bit
SR6	Transmitter FIFO	0	Transmitter FIFO not empty
	empty	1	Transmitter FIFO empty.
SR7	Transmitter FIFO full	0	Transmitter FIFO not full
	iuli	1	Transmitter FIFO full. FFT pin is the inverse of this bit.
SR8	Transmitter FIFO half full	0	Transmitter FIFO contains less than 16 words
		1	Transmitter FIFO contains at least 16 words. HFT pin is the inverse of this bit.

#### **ARINC 429 DATA FORMAT**

Control register bit CR15 is used to control how individual bits in the received or transmitted ARINC word are mapped to the HI-3582/HI-3583 data bus during data read or write operations. The following table describes this mapping:

	BYTE 1															
DATA BUS	BD 15	BD 14	BD 13	BD 12	BD 11	BD 10	BD 09	BD 08	BD 07	BD 06	BD 05	BD 04	BD 03	BD 02	BD 01	BD 00
ARINC BIT CR15=0	13	12	11	10 IOS	SDI ©	31	30	Parity &	Label 1	Label N	Label ω	Label 4-	Label o	Label o	Label 4	Label ∞
ARINC BIT CR15=1	16	15	14	13	12	11	10 IOS	SDI ©	Label ∞	Label 4	Label o	Label o	Label 4	Label ω	Label N	Label 1

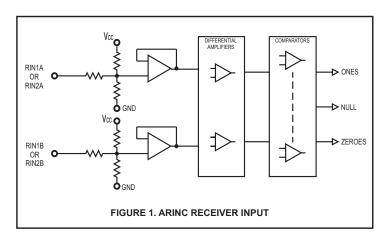
	BYTE 2															
DATA BUS	BD 15	BD 14	BD 13	BD 12	BD 11	BD 10	BD 09	BD 08	BD 07	BD 06	BD 05	BD 04	BD 03	BD 02	BD 01	BD 00
ARINC BIT CR15=0	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14
ARINC BIT CR15=1	Parity 55	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17

#### THE RECEIVERS

#### **ARINC BUS INTERFACE**

Figure 1 shows the input circuit for each receiver. The ARINC 429 specification requires the following detection levels:

TATE	DIFFERENTIAL VOLTAGE	
ONE	+6.5 Volts to +13 Volts	
NULL	+2.5 Volts to -2.5 Volts	
ZERO	-6.5 Volts to -13 Volts	
		-



The HI-3582/HI-3583 guarantee recognition of these levels with a common mode Voltage with respect to GND less than ±4V for the worst case condition (3.0V supply and 13V signal level).

The tolerances in the design guarantee detection of the above levels, so the actual acceptance ranges are slightly larger. If the ARINC signal is out of the actual acceptance ranges, including the nulls, the chip rejects the data.

#### RECEIVER LOGIC OPERATION

Figure 2 shows a block diagram of the logic section of each receiver.

#### **BIT TIMING**

The ARINC 429 specification contains the following timing specification for the received data:

	HIGH SPEED	LOW SPEED
BIT RATE	100K BPS ± 1%	12K -14.5K BPS
PULSE RISE TIME	$1.5 \pm 0.5  \mu sec$	$10 \pm 5 \mu sec$
PULSE FALL TIME	$1.5 \pm 0.5 \mu sec$	10 ± 5 µsec
<b>PULSE WIDTH</b>	5 µsec ± 5%	34.5 to 41.7 µsec

The HI-3582/HI-3583 accept signals that meet these specifications and rejects signals outside the tolerances. The way the logic operation achieves this is described below:

- 1. Key to the performance of the timing checking logic is an accurate 1MHz clock source. Less than 0.1% error is recommended.
- 2. The sampling shift registers are 10 bits long and must show three consecutive Ones, Zeros or Nulls to be considered valid data. Additionally, for data bits, the One or Zero in the upper bits of the sampling shift registers must be followed by a Null in the lower bits within the data bit time. For a Null in the word gap, three consecutive Nulls must be found in both the upper and lower bits of the sampling shift register. In this manner the minimum pulse width is guaranteed.
- 3. Each data bit must follow its predecessor by not less than 8 samples and no more than 12 samples. In this manner the bit rate is checked. With exactly 1MHz input clock frequency, the acceptable data bit rates are as follows:

	HIGH SPEED	<b>LOW SPEED</b>
DATA BIT RATE MIN	83K BPS	10.4K BPS
DATA BIT RATE MAX	125K BPS	15.6K BPS

4. The Word Gap timer samples the Null shift register every 10 input clocks (80 for low speed) after the last data bit of a valid reception. If the Null is present, the Word Gap counter is incremented. A count of 3 will enable the next reception.

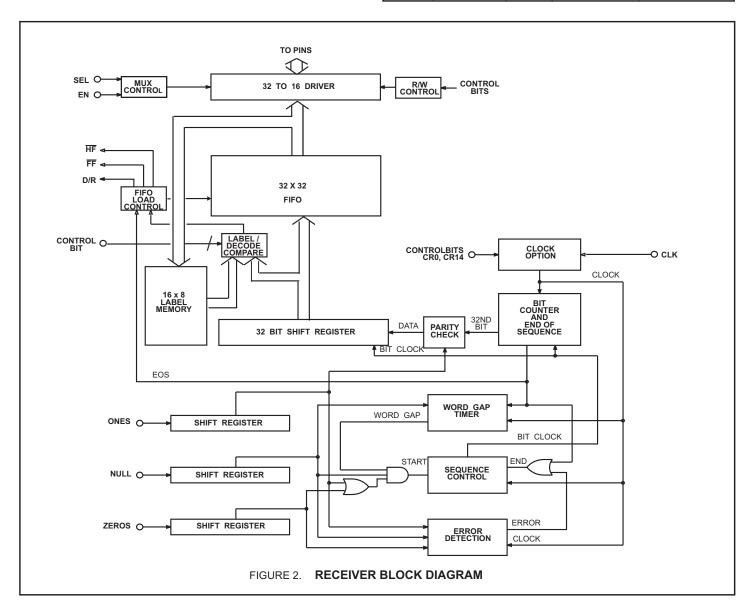
### **RECEIVER PARITY**

The receiver parity circuit counts Ones received, including the parity bit. If the result is odd, then a "0" will appear in the 32nd bit.

#### **RETRIEVING DATA**

Once 32 valid bits are recognized, the receiver logic generates an End of Sequence (EOS). Depending upon the state of control register bits CR2-CR11, the received ARINC 32-bit word is then checked for correct decoding and label matching before being loaded into the 32 x 32 receive FIFO. ARINC words which do not meet the necessary 9th and 10th ARINC bit or label matching are ignored and are not loaded into the receive FIFO. The following table describes this operation.

CR2(3)	ARINC word matches label	CR6(9)	ARINC word bits 9,10 match CR7,8 (10,11)	FIFO
0	Х	0	Х	Load FIFO
1	No	0	X	Ignore data
1	Yes	0	X	Load FIFO
0	X	1	No	Ignore data
0	X	1	Yes	Load FIFO
1	Yes	1	No	Ignore data
1	No	1	Yes	Ignore data
1	No	1	No	Ignore data
1	Yes	1	Yes	Load FIFO



Once a valid ARINC word is loaded into the FIFO, then EOS clocks the data ready flag flip flop to a "1",  $\overline{D/R1}$  or  $\overline{D/R2}$  (or both) will go low. The data flag for a receiver will remain low until both ARINC bytes from that receiver are retrieved and the FIFO is empty. This is accomplished by first activating  $\overline{EN}$  with SEL, the byte selector, low to retrieve the first byte and then activating  $\overline{EN}$  with SEL high to retrieve the second byte.  $\overline{EN1}$  retrieves data from receiver 1 and  $\overline{EN2}$  retrieves data from receiver 2.

Up to 32 ARINC words may be loaded into each receiver's FIFO. The FF1 (FF2) pin will go low when the receiver 1 (2) FIFO is full. Failure to retrieve data from a full FIFO will cause the next valid ARINC word received to overwrite the existing data in FIFO location 32. A FIFO half full flag HF1 (HF2) goes low if the FIFO contains 16 or more received ARINC words. The HF1 (HF2) pin is intended to act as an interrupt flag to the system's external microprocessor, allowing a 16 word data retrieval routine to be performed, without the user needing to continually poll the HI-8582/HI-8583 status register bits.

#### **LABEL RECOGNITION**

The chip compares the incoming label to the stored labels if label recognition is enabled. If a match is found, the data is processed. If a match is not found, no indicators of receiving ARINC data are presented. Note that 00(Hex) is treated in the same way as any other label value. Label bit significance is not changed by the status of control register bit CR15. Label bits BD00 - BD07 are always compared to received ARINC bits 1 - 8 respectively.

#### **LOADING LABELS**

After a write that takes CR1 from 0 to 1, the next 16 writes of data  $(\overline{PL})$  pulsed low) load label data into each location of the label memory from the BD00 - BD07 pins. The  $\overline{PL1}$  pin is used to write label data for receiver 1 and  $\overline{PL2}$  for receiver 2. Note that ARINC word reception is suspended during the label memory write sequence.

#### **READING LABELS**

After the write that changes CR1 from 0 to 1, the next 16 data reads of the selected receiver ( $\overline{\text{EN}}$  taken low) are labels.  $\overline{\text{EN1}}$  is used to read labels for receiver 1, and  $\overline{\text{EN2}}$  to read labels for receiver 2. Label data is presented on BD0-BD7.

When writing to, or reading from the label memory, SEL must be a one, all 16 locations should be accessed, and CR1 must be written to zero before returning to normal operation. Label recognition must be disabled (CR2/3=0) during the label read sequence.

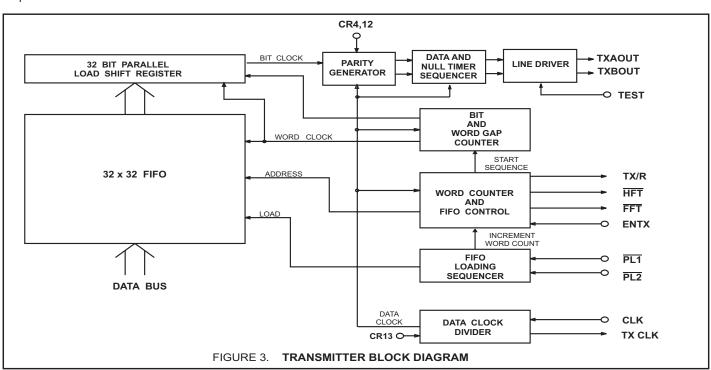
#### **TRANSMITTER**

#### **FIFO OPERATION**

The FIFO is loaded sequentially by first pulsing PL1 to load byte 1 and then PL2 to load byte 2. The control logic automatically loads the 31 bit word (or 32 bit word if CR4=0) in the next available position of the FIFO. If TX/R, the transmitter ready flag is high (FIFO empty), then up to 32 words, each 31 or 32 bits long, may be loaded. If TX/R is low, then only the available positions may be loaded. If all 32 positions are full, the FFT flag is asserted and the FIFO ignores further attempts to load data.

A transmitter FIFO half-full flag HFT is provided. When the transmit FIFO contains less than 16 words, HFT is high, indicating to the system microprocessor that a 16 ARINC word block write sequence can be initiated.

In normal operation (CR4=1), the 32nd bit transmitted is a parity bit. Odd or even parity is selected by programming control register bit CR12 to a zero or one. If CR4 is programmed to a 0, then all 32-bits of data loaded into the transmitter FIFO are treated as data and are transmitted.



#### **DATA TRANSMISSION**

When ENTX goes high, enabling transmission, the FIFO positions are incremented with the top register loading into the data transmission shift register. Within 2.5 data clocks the first data bit appears at TXAOUT and TXBOUT. The 31 or 32 bits in the data transmission shift register are presented sequentially to the outputs in the ARINC 429 format with the following timing:

	HIGH SPEED	LOW SPEEL
ARINC DATA BIT TIME	10 Clocks	80 Clocks
DATA BIT TIME	5 Clocks	40 Clocks
NULL BIT TIME	5 Clocks	40 Clocks
WORD GAP TIME	40 Clocks	320 Clocks

The word counter detects when all loaded positions have been transmitted and sets the transmitter ready flag, TX/R, high.

#### TRANSMITTER PARITY

The parity generator counts the Ones in the 31-bit word. If control register bit CR12 is set low, the 32nd bit transmitted will make parity odd. If the control bit is high, the parity is even. Setting CR4 to a Zero bypasses the parity generator, and allows 32 bits of data to be transmitted.

#### **SELF TEST**

If control register bit CR5 is set low, the transmitter serial output data are internally connected to each of the two receivers, bypassing the analog interface circuitry. Data is passed unmodified to receiver 1 and inverted to receiver 2. Taking TEST high forces TXAOUT and TXBOUT into the null state regardless of the state of CR5.

#### SYSTEM OPERATION

The two receivers are independent of the transmitter. Therefore, control of data exchanges is strictly at the option of the user. The only restrictions are:

- 1. The received data will be overwritten if the receiver FIFO is full and at least one location is not retrieved before the next complete ARINC word is received.
- 2. The transmitter FIFO can store 32 words maximum and ignores attempts to load additional data if full.

#### LINE DRIVER OPERATION

The line driver in the HI-8582/HI-8583 are designed to directly drive the ARINC 429 bus. The two ARINC outputs (TXAOUT and TXBOUT) provide a differential voltage to produce a +10 volt One, a -10 volt Zero, and a 0 volt Null. Control register bit CR13 controls both the transmitter data rate, and the slope of the differential output signal. No additional hardware is required to control the slope. Programming CR13 to Zero causes a 100 kbits/s data rate and a slope of 1.5  $\mu s$  on the ARINC outputs; a One on CR13 causes a 12.5 kbit/s data rate and a slope of 10  $\mu s$ . Timing is set by on-chip resistor and capacitor and tested to be within ARINC requirements.

The HI-3582 has 37.5 ohms in series with each line driver output. The HI-3583 has 10 ohms in series. The HI-3583 is for applications where external series resistance is needed, typically for lightning protection devices.

#### REPEATER OPERATION

Repeater mode of operation allows a data word that has been received by the HI-3582/HI-3583 to be placed directly into the transmitter FIFO. Repeater operation is similar to normal receiver operation. In normal operation, either byte of a received data word may be read from the receiver latches first by use of SEL input. During repeater operation however, the lower byte of the data word must be read first. This is necessary because, as the data is being read, it is also being loaded into transmitter FIFO which is always loaded with the lower byte of the data word first. Signal flow for repeater operation is shown in the Timing Diagrams section.

#### HI-3582-10 and HI-3583-10

The HI-3582-10/HI-3583-10 options are similar to the HI-3582/HI-3583 with the exception that they allow an external 10 Kohm resistor to be added in series with each ARINC input without affecting the ARINC input thresholds. This option is especially useful in applications where lightning protection circuitry is also required.

Each side of the ARINC bus must be connected through a 10 Kohm series resistor in order for the chip to detect the correct ARINC levels. The typical 10 volt differential signal is translated and input to a window comparator and latch. The comparator levels are set so that with the external 10 Kohm resistors, they are just below the standard 6.5 volt minimum ARINC data threshold and just above the standard 2.5 volt maximum ARINC null threshold.

Please refer to the Holt AN-300 Application Note for additional information and recommendations on lightning protection of Holt line drivers and line receivers.

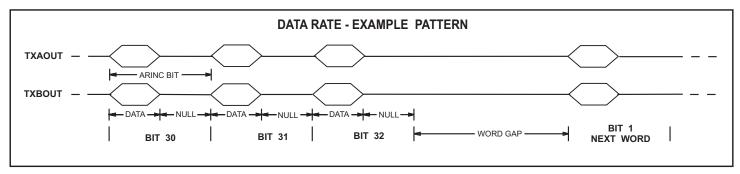
#### **HIGH SPEED OPERATION**

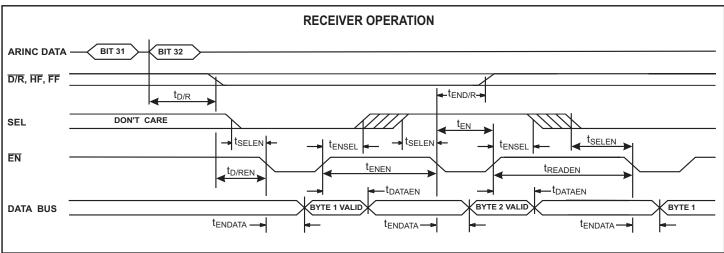
The HI-3582 and HI-3583 may be operated at clock frequencies beyond that required for ARINC compliant operation. For operation at Master Clock (CLK) frequencies up to 5MHz, please contact Holt applications engineering.

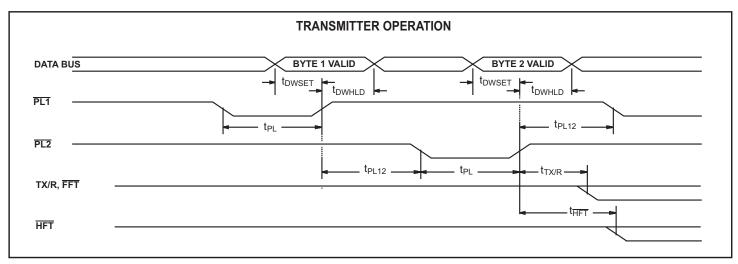
#### POWER SUPPLY SEQUENCING

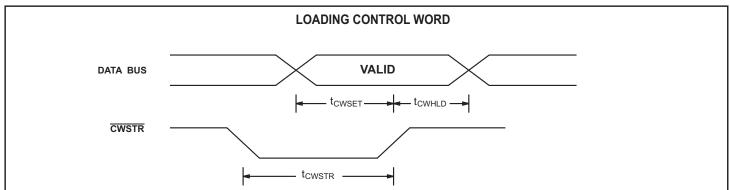
The power supplies should be controlled to prevent large currents during supply turn-on and turn-off. The recommended sequence is V+ followed by Vcc, always ensuring that V+ is the most positive supply. The V- supply is not critical and can be asserted at any time.

### **TIMING DIAGRAMS**

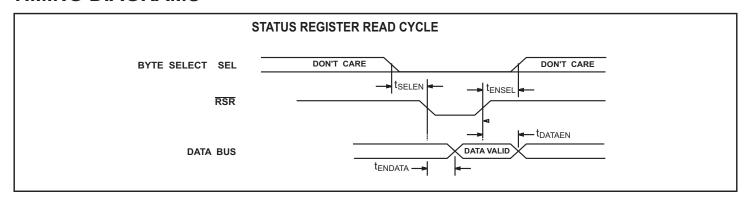


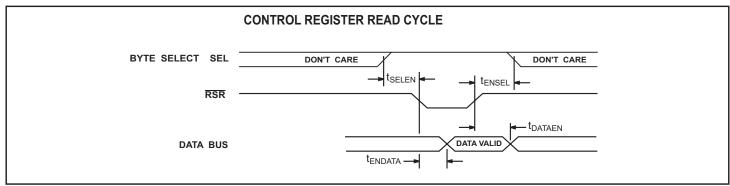


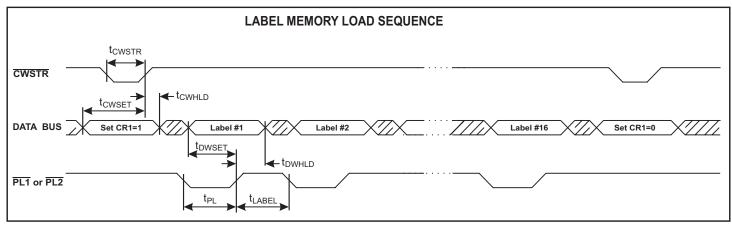


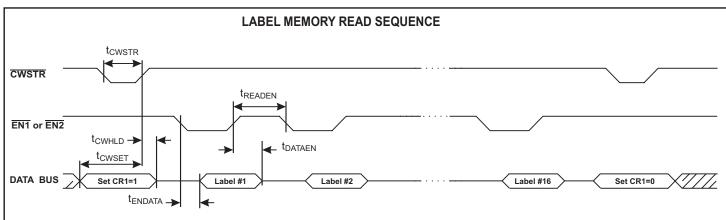


### **TIMING DIAGRAMS**

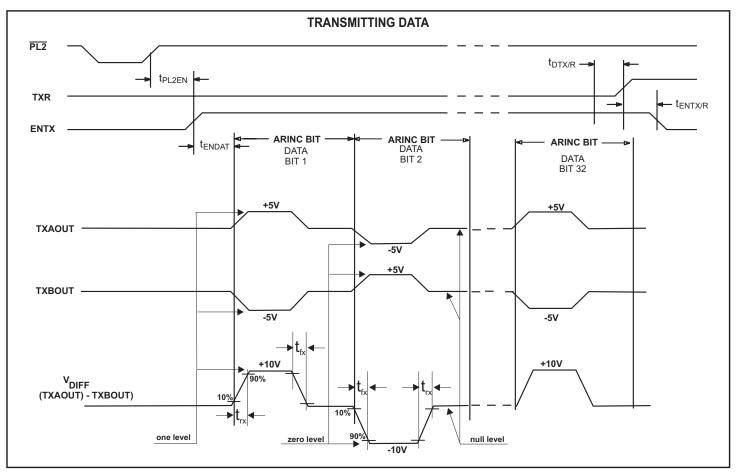


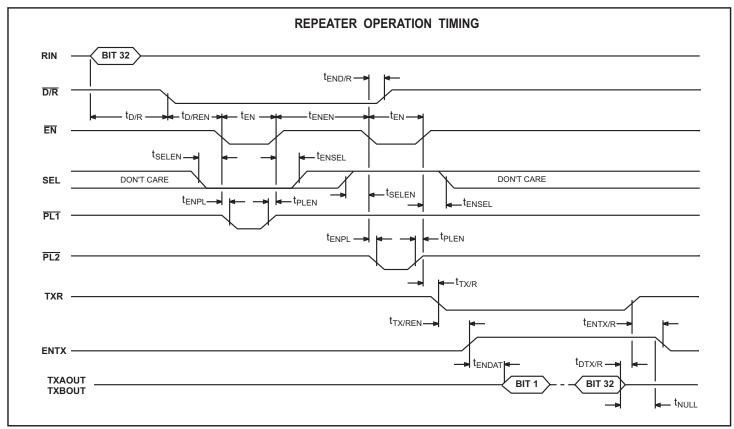






## **TIMING DIAGRAMS (cont.)**





### **ABSOLUTE MAXIMUM RATINGS**

Supply Voltages VDD0.3V to +4.0V V++11.0V V11.0V	Power Dissipation at 25°C Plastic Quad Flat Pack1.5 W, derate 10mW/°C Ceramic J-LEAD CERQUAD1.0 W, derate 7mW/°C
Voltage at pins RIN1A, RIN1B, RIN2A, RIN2B29V to +29V	DC Current Drain per pin ±10mA
Voltage at any other pin0.3V to VDD +0.3V	Storage Temperature Range65°C to +150°C
Solder temperature (Leads)	Operating Temperature Range (Industrial):40°C to +85°C (Military):55°C to +125°C

NOTE: Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only. Functional operation of the device at these or any other conditions above those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### DC ELECTRICAL CHARACTERISTICS

V<sub>DD</sub> = 3.3V , V+ = 10V, V- = -10V, GND = 0V, TA = Operating Temperature Range (unless otherwise specified).

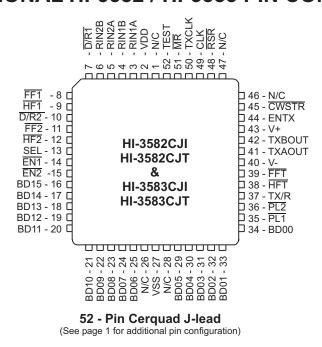
DIDAMETED	0)/115 01	OCH DITIONS				
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNIT
ARINC INPUTS - Pins RIN1A, RIN1B, RIN2A, RIN2B						
Differential Input Voltage: (RIN1A to RIN1B, RIN2A to RIN2B)  ZERO NULL	VIH VIL VNUL	Common mode voltages less than ±4V with respect to GND	6.5 -13.0 -2.5	10.0 -10.0 0	13.0 -6.5 2.5	V V V
Input Resistance:  Differential To GND To VDD	Rı Rg Rh		12 12 12	46 38 38		KΩ KΩ KΩ
Input Current: Input Sink Input Source	lih liL		-450		200	μA μA
Input Capacitance: Differential (Guaranteed but not tested) To GND To VDD	Cı Cg Ch	(RIN1A to RIN1B, RIN2A to RIN2B)			20 20 20	pF pF pF
BI-DIRECTIONAL INPUTS - Pins BD00 - BD15			•		'	
Input Voltage: Input Voltage HI Input Voltage LO	VIH VIL		70% VDD		30% VDD	V V
Input Current: Input Sink Input Source	lih lil		-1.5		1.5	μA μA
OTHER INPUTS						
Input Voltage: Input Voltage HI Input Voltage LO	VIH VIL		70% VDD		30% VDD	V V
Input Current: Input Sink Input Source Pull-down Current (TEST Pin)	lih lil lpd		-1.5 50		1.5 150	μΑ μΑ μΑ
ARINC OUTPUTS - Pins TXAOUT, TXBOUT		I				
ARINC output voltage (Ref. To GND)  One or zero Null	VDOUT VNOUT	No load and magnitude at pin, VDD = 3.3 V	4.50 -0.25	5.00	5.50 0.25	V V
ARINC output voltage (Differential)  One or zero Null	VDDIF VNDIF	No load and magnitude at pin, VDD = 3.3 V	9.0 -0.5	10.0	11.0 0.5	V
ARINC output current	Іоит		80			mA
OTHER OUTPUTS						
Output Voltage: Logic "1" Output Voltage Logic "0" Output Voltage	Voh Vol	Iон = -100μA IoL = 1.0mA	VDD - 0.2V		10% VDD	V
Output Current: Output Sink (All Outputs & Bi-directional Pins) Output Source	lol loн	Vout = 0.4V Vout = VDD - 0.4V	1.6		-1.0	mA mA
Output Capacitance:	Co			15		pF
Operating Voltage Range						
	VDD		3.15		3.45	V
	V+		9.5		10.5	V
	V-		-9.5		-10.5	V
Operating Supply Current						
VDD	IDD1			2.5	7	mA
V+	IDD2			4	10	mA
V-	IEE1			4	10	mA

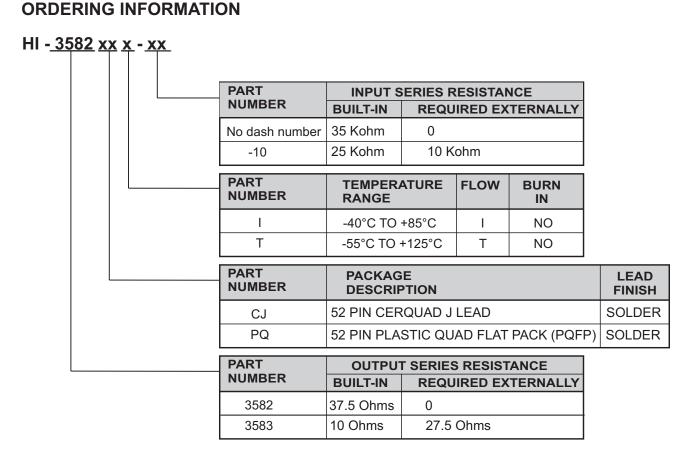
### **AC ELECTRICAL CHARACTERISTICS**

VDD = 3.3V, V+=10V, V-=-10V, GND = 0V, TA = Oper. Temp. Range and fclk=1MHz  $\pm 0.1\%$  with 60/40 duty cycle

PARAMETER	SYMBOL	LIMITS			UNITS
		MIN	TYP	MAX	UNITS
CONTROL WORD TIMING					
Pulse Width - CWSTR	tcwstr	90			ns
Setup - DATA BUS Valid to CWSTR HIGH Hold - CWSTR HIGH to DATA BUS Hi-Z	tcwset tcwhld	80			ns ns
RECEIVER FIFO AND LABEL READ TIMING		1 - 1		1	
Delay - Start ARINC 32nd Bit to D/R LOW: High Speed	tD/R			16	μs
Low Speed	tD/R	_		128	μs
Delay - D/R LOW to EN LOW Delay - EN LOW to D/R HIGH	tD/REN tEND/R	0	420	520	ns ns
Setup - SEL to <u>EN</u> LOW Hold - SEL to <u>EN</u> HIGH	tselen tensel	10 10			ns ns
Delay - EN LOW to DATA BUS Valid Delay - EN HIGH to DATA BUS Hi-Z	tendata tdataen		110 110	150 140	ns ns
Pulse Width - EN1 or EN2	ten	60			ns
Spacing - EN HIGH to next EN LOW (Same ARINC Word) Spacing -EN HIGH to next EN LOW (Next ARINC Word)	tenen treaden	65 200			ns ns
TRANSMITTER FIFO AND LABEL WRITE TIMING	IREADEN	200			115
Pulse Width - PL1 or PL2	tpL	90		Τ	ns
Setup - DATA BUS Valid to PL HIGH Hold - PL HIGH to DATA BUS Hi-Z	towset towhld	120 55			ns ns
Spacing - PL1 or PL2	tPL12	110			ns
Spacing between Label Write pulses  Delay - PL2 HIGH to TX/R LOW	tlabel ttx/r	150		240	ns ns
Delay - PL2 HIGH to HFT low	thet			560	ns
TRANSMISSION TIMING				1 000	110
Spacing - PL2 HIGH to ENTX HIGH	tPL2EN	0			ns
Delay - 32nd ARINC Bit to TX/R HIGH	tdtx/R			50	ns
Spacing - TX/R HIGH to ENTX LOW	tentx/R	0			ns
LINE DRIVER OUTPUT TIMING					
Delay - ENTX HIGH to TXAOUT or TXBOUT: High Speed Delay - ENTX HIGH to TXAOUT or TXBOUT: Low Speed	tendat tendat			25 200	μs μs
Line driver transition differential times:					, po
(High Speed, control register CR13 = Logic 0) high to low low to high	tfx trx	1.0 1.0	1.5 1.5	2.0 2.0	µs µs
REPEATER OPERATION TIMING					
Delay - EN LOW to PL LOW	tenpl	0			ns
Hold - PL HIGH to EN HIGH	tplen	0			ns
Delay - TX/R LOW to ENTX HIGH	tTX/REN	0			ns
MASTER RESET PULSE WIDTH	tmr	50			ns
ARINC DATA RATE AND BIT TIMING				± 1%	

### ADDITIONAL HI-3582 / HI-3583 PIN CONFIGURATIONS







### HI-3582 / HI-3583 PACKAGE DIMENSIONS

inches (millimeters)

