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Data Sheet

Micro RWD MF (Mifare) Low Power Version
(with auxiliary data outputs)

The MicroRWD MF LP (Low Power) module is a complete read and write solution for 13.56 MHz Mifare (1k, 4k and Ultralight versions) and supports "Mifare" contactless operations to dual-interface cards such as DESFire, Mifare ProX, Smart MX and other types. The solution is entirely housed within a 24-pin DIL package and only needs an antenna connected and a 5v DC supply to be a fully featured ISO14443A Mifare read/write system. The MicroRWD MF LP version behaves in the same manner as the standard reader except that it has an **active, average current consumption of less than 100μA (micro Amps**) with 1 second (default) polling rate. As on other RWD modules, all commands and data response are via a simple TTL level RS232 interface. In addition, the RWD MF LP version has **auxiliary data outputs on the OP0 / OP1 pins** that can be programmed to automatically output UID (serial number) or other block data as **asynchronous 9600 baud** serial or **Wiegand protocol Data High / Data Low signals**. All these features can be configured and turned ON/OFF by setting RWD EEPROM parameters. The diagram below shows the pin out configuration for the MicroRWD MF LP module.

Micro RWD MF LP module connections
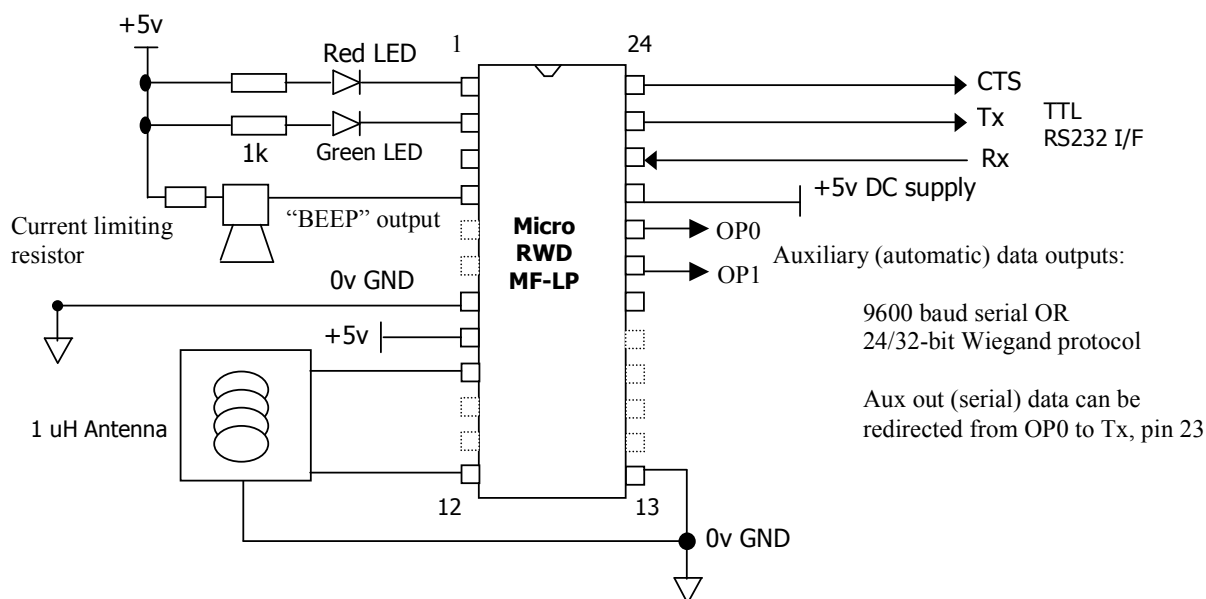
With the ultra-low-power current consumption and the additional auxiliary data output features, this one of the most compact and flexible reader systems available.

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Auxiliary Data Output

The Micro RWD MF LP version uses the 4-byte UID (serial number) or the least significant (first) 4 bytes of data from a Mifare card memory block to create a 32-bit data frame. The data frame can then be output as asynchronous 9600 baud serial data on OP0 pin or as 24 / 32 bit Wiegand protocol with parity bits attached (making 26 or 34 bits of data) on OP0 / OP1 pins.

An RWD EEPROM parameter can redirect the serial auxiliary output on OP0 to the main TX output (pin 23). This is to allow both bi-directional command/data communication and the uni-directional auxiliary serial data output with the same 3-wire RS232 interface. Note that when the auxiliary serial output has been redirected to TX pin, there will be NO acknowledgement or data response to commands.

For normal command and data response using the Windows application, the serial auxiliary output MUST be directed to the OP0 pin.

The auxiliary data outputs on OP0 / OP1 are **AUTOMATIC** and if enabled, occur when a card enters the RF field for the first time. The "beep" output signal delay, the data source and byte order for the auxiliary output and the various Wiegand protocol options are all controlled by programmable RWD EEPROM parameters (see page 8). A zero data length parameter effectively turns the auxiliary outputs OFF (factory default set to asynchronous serial output of UID-serial number from OP0 with NO "beep" output).

In this manner the MicroRWD MF LP can be used in a battery powered application (<100µA average current consumption) and automatically output simple blocks of data (such as the UID) WITHOUT any commands having to be sent to the module. In addition, the "Green" LED output or the BEEP output can be used as a control signal to "interrupt" the host computer or microcontroller just before the automatic data is transmitted.

NOTE that the "BEEP" output (RWD pin 4) idles in a high state and is an open drain output so it "sinks" current. External loads can be connected between the supply rail and pin 4 with a series resistor to ensure "sink" current does not exceed 25ma.

MicroRWD MF (Mifare) operation

The Mifare transponder cards have significantly more memory than most other cards and the 13.56 MHz carrier frequency provides fast transaction times of 106 kbaud. The cards are available with 64 bytes (Mifare Ultralight), 1024 bytes (Mifare 1k) and 4096 bytes (Mifare 4k) of memory. For the 1k and 4k cards the memory is organised as 16 and 40 Sectors respectively, each Sector has 64 bytes arranged as 4 Blocks of memory (3 of which are available for general Read/Write use). Each Sector can be separately locked/unlocked for access using security keys. Initial communication with the cards can only proceed after mutual authentication between the RWD and the card has succeeded (as defined by ISO 14443A standard). Combined with the "Security Key" access control for the memory sectors and encrypted data streams, the Mifare cards are ideally suited to Electronic-Purse applications such as ticketing and vending applications where each sector can hold entirely separate data for different applications.

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The MicroRWD MF LP is a proximity system and a Read/Write range of up to 10cm can be achieved under ideal conditions using the appropriate antenna. For evaluation purposes the RWD is available on a base board with PCB antenna, LEDs, power-regulation, 9-pin RS232 and optional USB interfaces. When power is first applied to the board the red and green LEDs flash once to indicate successful power-up (both LEDs stay on if initialisation fails). The RWD can also check for antenna faults and internal error conditions, these problems are indicated by the red LED or both LEDs flashing continuously until the fault has been rectified.

The RWD will normally have the red LED lit until a valid card is brought into the RF field. If the tag is accepted as valid then the green LED is turned ON (and red LED OFF). If the auxiliary output features are enabled then the UID (serial number) is acquired, or block data is internally read and transmitted as serial data or Wiegand protocol data on OP0/OP1 pins.
If the Beep delay is set then the "BEEP" output (pin 4) is pulsed ON/OFF. With auxiliary output features turned OFF, the RWD responds to host commands on the TTL serial interface at 9600 baud, 8 bits, 1 stop, no parity, as usual.

Note: Some ISO14443A compliant cards have a SINGLE (4 byte) UID and others have a DOUBLE (7 byte) UID. These serial numbers are acquired as part of the initial anticollision/select procedure when a card is brought into the field. This UID information can be reported using the CARD UID command. For Mifare Classic 1k and 4k cards the SINGLE UID is acquired and can be reported BUT subsequent block read/write operations will not function if the Security KEY is incorrect for the particular sector and the authentication fails.

For many applications where only the UID (serial number) is required, the Security KEY information is therefore NOT required.

MicroRWD MF modes of operation

The Micro RWD has two basic modes of operation:-
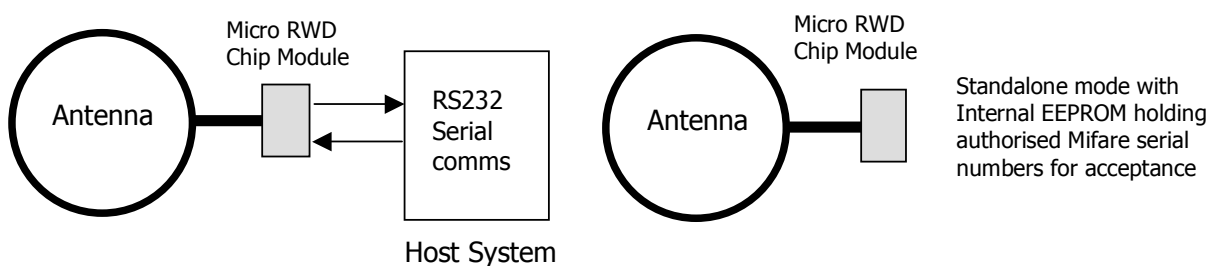
Remote mode (connected to a host computer or microcontroller) and Standalone mode.

1) Remote mode involves connecting to a host serial interface. This is where the stored list of authorised identity codes (serial numbers) can be empty, effectively authorising any Mifare card for subsequent read/write operations (depending on correct Security Key. A simple serial protocol allows a host system to communicate with the Micro RWD in order to program new authorised identity codes, change parameters, load Security Keys and perform Read/Write operations to the card itself.

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2) Standalone mode is where the Mifare card identity codes (serial numbers) are checked against a stored list of authorised codes. If an identity code is matched, the output drives and Green LED are enabled. Effectively standalone mode occurs when there is no host system communicating with the Micro RWD. Up to 60 serial numbers can be stored in the authorisation list so this mode of operation can be used to create a "mini access control" system.

The automatic auxiliary outputs can also be used to send serial number or other card memory block data to a controller with no command interaction required.

Supported transponder types

The MicroRWD MF is designed to communicate with the following passive RF transponder types. Note that Mifare cards and transponder devices are fabricated by several companies under licence from Philips/NXP Semiconductors. They are all fully Mifare compliant and only differ in having different default Security Keys loaded in the factory:-

1) Mifare standard 1k card (MF1 IC S50 transponder) and Infineon equivalent.

2) Mifare standard 4k card (MF1 IC S70 transponder)

3) Mifare Ultralight card (MF0 IC U1 transponder)

4) DESFire, Mifare ProX, Smart MX dual-interface card types are supported to allow single or double UID to be acquired and "Mifare" operations performed across the contactless interface.

5) Any ISO 14443A compliant contactless card can be accessed for Serial Number. Full Read/Write access will only be possible if card fully supports Philips/NXP Semiconductors CRYPTO1 algorithm and encrypted data protocols.

The operation of the Micro RWD MF and the Mifare transponders is described in more detail at the end of this document.

The identification codes described in this text are regarded as the four-byte Mifare SINGLE UID (Unique Identifier/serial number) or the least significant four bytes of the seven-byte Ultralight DOUBLE UID.

Serial Interface

This is a basic implementation of RS232. The Micro RWD does not support buffered interrupt driven input so it must control a BUSY (CTS) line to inhibit communications from the host when it is fully occupied with card communication. It is assumed that the host (such as a PC) can buffer received data. This CTS signal must be connected to the host computer communication port to allow "hardware handshaking" or the host driver software must check the CTS signal and only send commands/data when it is in a LOW state. The CTS signal is pulsed LOW for a 6ms period each polling cycle. The host computer must wait for this LOW signal and then send the command and data.

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The CTS line remains in a LOW state while the command and data bytes are being received. After the last byte of data the CTS signal "times out" for 6ms and returns HIGH.

This 6ms "window" every polling cycle allows the host computer to send a single command and associated data to the RWD. Please note that only one command and it's corresponding data bytes can be sent during a CTS LOW period, the command and data bytes must be sent with no gaps between, if there is a pause of more than 6ms between bytes then "time out" occurs, the CTS line returns high and the command fails (flagged as RS232 error). The CTS signal idles in this HIGH state (to inhibit host communication) until the next polling cycle begins.

The communication baud rate is 9600 baud, 8 bits, 1 stop, no parity. The RWD Tx, Rx and CTS signals are all TTL level and can be converted to +/-10v RS232 levels using a level converter device such as the MAX202 (note the inversion of the TTL levels).

The Micro RWD MF LP (low-power) version has been specifically designed to operate with very low average power consumption but still remain responsive to cards entering and leaving the field and be able to read large amounts of data as quickly as possible.

THE RWD HAS THREE POLLING STATES:

1) **NO card present and NO host commands received.**

   Polling cycle rate (time between subsequent CTS low periods) is determined by the "polling rate" parameter stored in the RWD EEPROM memory. This is typically set to a long period (4ms to 8 seconds, default setting 1 second) and is the primary means to reduce average power consumption. This is because most of the polling cycle period is spent in a power-down/sleep mode.
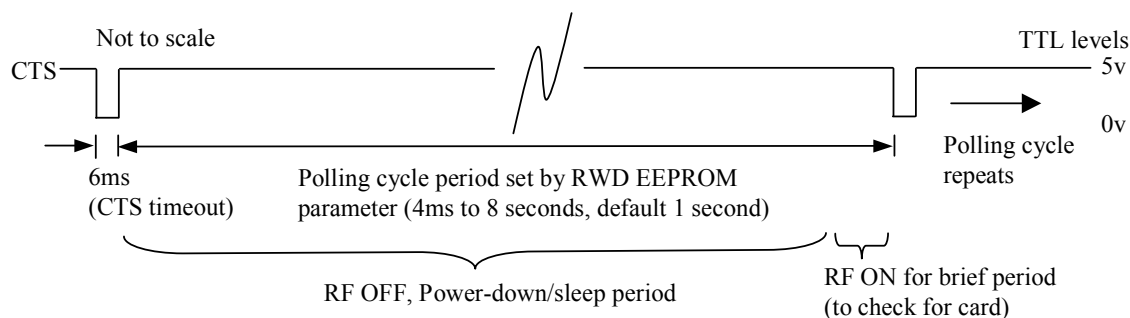
2) **Mifare card in field, NO host commands received**.

   When a card is detected in the field the polling rate changes to approximately 100ms (between CTS low periods). This is to ensure that the RWD can respond quickly to the card leaving the field and a new card being presented.

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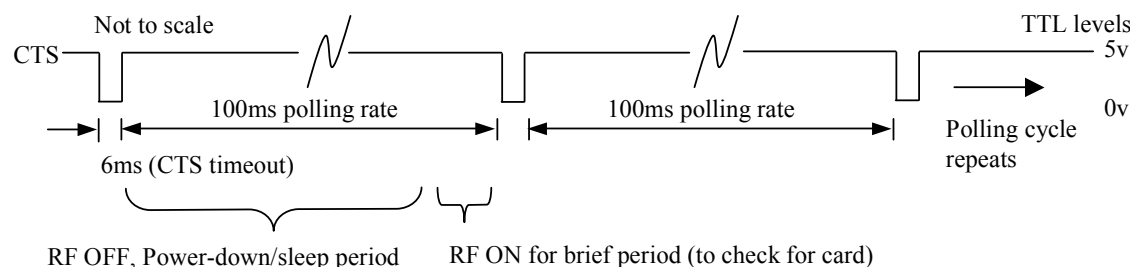
3) **Host commands received and processed.**

When the RWD receives commands from the host computer, the polling rate increases to allow a quick response to the command. This means that commands such as READ or WRITE BLOCK can be repeated quickly and the large amounts of data read from, or written to the card as fast as possible.

The polling cycle delay in this case is effectively the minimum, so the RWD responds to the host command immediately after the RF communication is complete.

Example a) NO card present, single CARD UID (0x55) command received.

Note: at 9600 baud serial communication rate, a single byte is received or transmitted in approximately 1mS (104μS per bit). If no commands follow then the polling rate reverts back to the stored parameter value as in (1).
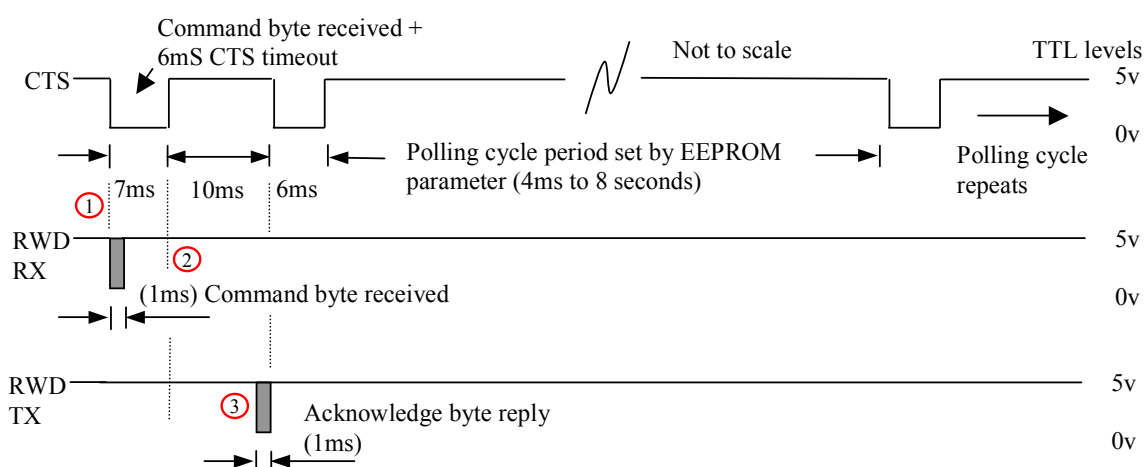
① Host waits for CTS falling edge then sends command byte.
② RWD processes command, RF turned ON for brief period to check if card present.
③ RWD then replies with acknowledge byte (+ data).

Example b) Mifare card in field, single CARD UID (0x55) command received.

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**Example c) Mifare card in field, valid READ BLOCK command received
(Read cmd (0x52) + Keycode number + Block number)**

Command + parameters
received + 6mS CTS

Not to scale   TTL levels

CTS

5v

0v

9ms   37ms   6ms   100 ms polling delay   Polling cycle
(card still present)   repeats

①

RWD
RX   5v

②

(3ms) Command byte + parameters received   0v

RWD   5v
TX

③   Acknowledge byte + 16 byte block data reply

0v

20ms   17ms

Auxiliary output and BEEP delay timing (if options are enabled)

Mifare card in field for first time, Auxiliary output enabled and BEEP delay set. Green LED
signal can be used as an interrupt signal to the host to indicate that auxiliary data will follow.

TTL levels

GREEN   5v
LED

0v

Not to scale

AUX   5v
OUT

0v

Representation of Auxiliary (serial/Wiegand) data output on OP0 / OP1 pins

2mS after Green LED signal

CTS   5v

BEEP delay after Aux output   CTS goes LOW after Aux out/BEEP delay
(if enabled)   0v

Summary of Polling rates and command timing

Three polling rates:
1) NO card and NO commands: Polling rate determined by Polling rate parameter in
   RWD EEPROM (4mS to 8 seconds, default setting 1 second)
2) Card present but NO commands: 100ms polling delay between CTS pulses.
3) Command (and parameters) received: 10ms polling delay to next CTS pulse.

For lowest power consumption, the Polling rate parameter in EEPROM is typically set to a
long period (> 1 second). Auxiliary output (if enabled) occurs after Green LED signal and
before CTS.
Host communication software must be able to handle the three polling rates.

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Note that Auxiliary outputs (and "BEEP" output) should be turned OFF if standard RS232 command interface is being used to ensure minimum power consumption and no additional delays occur in the polling loop.

Transmitted or Received data byte, 9600 baud, 8 bit, 1 stop, No parity (104 µS per bit)

```
              b0    b1    b2    b3    b4    b5    b6    b7    b8    b9
   5v  ───────┐                                                  ┌──────────
              │ 1  │                                             │ 0      TTL levels
   0v         └────┘                                             └──────────
        idle  START                  8 bit data                 STOP  idle
```
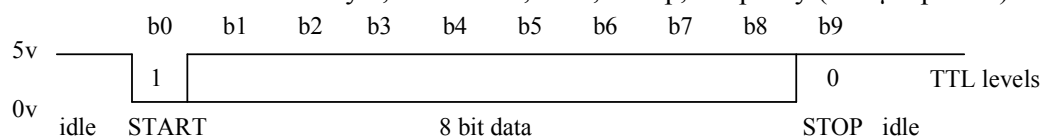
Host Driver software

Communication with the MicroRWD module is via the TTL level RS232 interface (9600 baud, 8 bit, 1 stop bit, no parity) and uses the CTS line for hardware handshaking. The Windows applications (supplied with the Evaluation kit) can be used to communicate with the module or the user can write their own application on a PC or a microcontroller. Please note that the host software must be able to handle the three distinct polling rates (different periods between CTS pulses). The following basic communication algorithm can be used:-

Typical host computer "pseudo" driver code

```
if (Green LED ON (pin 2 = 0))                // Optional check for valid tag in field
{
   if (CTS = 0)          // Wait for CTS = 0 (RWD ready to receive command / data)
   {
           // CTS times out after 6ms so command and all parameters must be sent with no-
           // gaps otherwise CTS times out and goes HIGH.
           // For example, send READ BLOCK 1 using KEY 0 as KEYA (0x52 0x01 0x00)

           SEND_CMD( );            // Sent command + parameters to RWD

           // RWD sets CTS = 1 after last parameter received. RWD module processes
           // command, turns on RF for short period, then sends reply.

           GET_REPLY( );           // Get Acknowledge byte + data
           // Response to READ command is 0x80 (no tag) or 0x86 + sixteen bytes of DATA.
   }
}
```

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Command Protocol

The following commands are supported. The corresponding acknowledge code should be read back by the host and decoded to confirm that the command was received and handled correctly. The serial bit protocol is 9600 baud, 8 bits, 1 stop, no parity (lsb transmitted first).

The status flags returned in the Acknowledge byte are as follows:

```
b7  b6  b5  b4  b3  b2  b1  b0
 1   1   1   1   1   1   1   1
 |   |   |   |   |   |   |   |   EEPROM error (Internal EEPROM write error)
 |   |   |   |   |   |   |   Card OK (Card serial number matched to identity code list)
 |   |   |   |   |   |   Rx OK  (Card  communication and acknowledgement OK)
 |   |   |   |   |   RS232  error (Host serial communication error)
 |   |   |   |   MF type (0 = MF 1k byte card, 1 = MF 4k byte card)
 |   |   |   UL type (0 = MF standard 1k/4k card, SINGLE UID), 1 = MF Ultralight card, DOUBLE UID)
 |   |   MFRC error (Internal or antenna fault)
```

Note that bit 7 is fixed so that using a Mifare 1k card, the RWD acknowledge response to a valid host command would generally be 86 (Hex), indicating that a matched (or authorised) MF 1k card is present. The MF Ultralight card has a different memory structure to the standard 1k/4k MF cards so bits 4 and 5 have to be checked to determine which card type is present. Note also that only the relevant flags are set after each command as indicated in the following specification.

Card UID

Command to return card status and UID (Unique Identifier or Serial number).
The acknowledge byte flags indicate general Mifare card status.

```
              B7                B0
Command:    0  1  0  1  0  1  0  1        (Ascii "U",  0x55)

Acknowledge:  1  F  F  F  F  F  F  X      (F = Status flags)
```

Data only follows if card was selected OK with no errors detected.

```
Reply1:       D D D D D D D D     (D = LS Byte of UID/Serial number from card)
Reply2:       D D D D D D D D
Reply3:       D D D D D D D D
Reply4:       D D D D D D D D

Reply5:       D D D D D D D D  ⎫
Reply6:       D D D D D D D D  ⎬  Dummy bytes (0x00) for Mifare 1k/4k card types
Reply7:       D D D D D D D D  ⎭
```

Note that Mifare 1k and 4k cards have a four-byte serial number but Mifare Ultralight cards have a seven-byte serial number. To accommodate all card types, the Card UID command returns a seven-byte field with the last three bytes padded out with 0x00 dummy bytes in the case of Mifare 1k/4k cards.

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Card STATUS

Command to return card status.
The acknowledge byte flags indicate general Mifare card status.

```
            B7              B0
Command:    0  1  0  1  0  0  1  1        (Ascii "S",  0x53)

Acknowledge:  1  F  F  F  F  F  F  X      (F = Status flags)
```

Program EEPROM

The Micro RWD has some internal EEPROM for storing system parameters such as polling rate and authorised identity codes (serial numbers). This command sequence allows individual bytes of the EEPROM to be programmed with new data. The data is internally read back after programming to verify successful operation. Note that due to the fundamental nature of these system parameters, incorrect data may render the system temporarily inoperable.

```
            B7              B0
Command:    0  1  0  1  0  0  0  0        (Ascii "P",  0x50)
Argument1:  N  N  N  N  N  N  N  N        (N = EEPROM  memory location 0 - 255)
Argument2:  D  D  D  D  D  D  D  D        (D = data to write to EEPROM)

Acknowledge:  1  X  X  X  F  X  X  F      (F = Status flags)
```

Internal EEPROM memory map

Polling delay parameter values (EEPROM location 0):

Parameter 0 value	Polling Delay SLEEP Period
0x00	4 mS
0x10	8 mS
0x20	16 mS
0x30	32 mS
0x40	65 mS
0x50	132 mS
0x60	262 mS
0x70	524 mS
0x80	**1 second**
0x90	2 seconds
0xA0	4 seconds
0xB0	8 seconds

Polling delay can be set from 4mS to 8 seconds to give complete control over current consumption and battery life.

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Byte 0:   Polling Delay (SLEEP / Power down) period (Default = 0x80 = approx 1 second)

Byte 1:   Aux data output: 0x00 = OFF (NO output from OP0 / OP1),
        0x01 = 24 (26) bit, Wiegand on OP0 / OP1. (default)
        0x02 = 32 (34) bit, Wiegand on OP0 / OP1.
        0x03 = 9600 baud serial from OP0

Byte 2:   Reserved (Checksum)

Byte 3:   Wiegand parity option, 0x00 = no parity
        0x01 = Even / Odd parity attached (default)

Byte 4:   Aux data byte order plain or reversed, 0x00 = plain data as read (default)
        0x01 = byte order reversed

Byte 5:   Aux block address on card (Mifare card block address 0 – 255), default 0x01, block 1
        (only used if parameter byte 8 is set to 0x01 for internal Block Read)

Byte 6:   Key number / type used for internal Block Read of Aux data:
        (TxxKKKKK), (T = Key type, 0 = KeyA, 1 = KeyB)
        (K = Key code number, 0 - 31), default = key 0x00 used as typeA

        (only used if parameter byte 8 is set to 0x01 for internal Block Read)

Byte 7:   "Beep" delay parameter (x 40 mS) Default = 0x00 (OFF)

Byte 8:   Aux output source data selection.
        0x00 = use UID / serial number (default)
        0x01 = perform Block Read

Byte 9:   Aux out (serial data) redirection (OP0 - pin 20 or Tx – pin 23)
        0x00 = Serial aux output from OP0 pin (default)
        0x01 = Serial aux output from main Tx pin

Byte 10: Reserved
Byte 11: Reserved

Start of authorised card codes. List is terminated with FF FF FF FF sequence.
List is regarded as empty (all identity codes valid) if first code sequence in list is (FF FF FF FF).
List can hold up to 60 identity codes (serial numbers)

Byte 12: 0xFF   Empty list
Byte 13: 0xFF
Byte 14: 0xFF
Byte 15: 0xFF

Byte 16: (MSB) Tag identity code
Byte 17:
Byte 18:
Byte 19: (LSB)
-
-
-
-
Byte 255:   Last Internal EEPROM location

Note that the default RWD EEPROM setting above are different to the standard version. In particular the polling delay parameter must be valid value (as shown in the table above), other values will give undefined results.

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Default RWD EEPROM parameter settings:

Byte 0:	0x80,	1-second Polling delay / SLEEP period
Byte 1:	0x03,	Aux data output as 9600 baud serial on OP0
Byte 2:	Reserved	
Byte 3:	0x00	(Wiegand NO parity option, only used if Byte 1 = 0x01 / 02)
Byte 4:	0x01	(Aux data byte order reversed, only used if Byte 1 = 0x01 / 02)
Byte 5:	0x01	(Aux block address on card, only used if Byte 8 = 0x01)
Byte 6:	0x00	(Key number / type used for internal Block Read of Aux data)
		(Use Key Code 0 as Key Type A, only used if Byte 8 = 0x01)
Byte 7:	0x00	"Beep" output delay OFF
Byte 8:	0x00	Aux output source data is UID (serial number).
Byte 9:	0x00	Aux output (serial data) directed to OP0 pin.

Store Keys

The Micro RWD has additional internal storage for 32 Security KEYs. Six byte Key codes are required to access individual card sectors for any Read or Write operations. This command sequence allows 6 byte Key codes to be stored at any one of the 32 key code locations. Factory defaults are Infineon/Philips specified transport key code pairs (Hex FF FF FF FF FF FF / Hex FF FF FF FF FF FF)) and (Hex A0 A1 A2 A3 A4 A5 / Hex B0 B1 B2 B3 B4 B5) and these are stored in the RWD non-volatile memory during manufacture. Note that due to the fundamental nature of these Key codes, incorrect values may render the system inoperable. Only one or two Security key codes are required to unlock a card sector so the provision of 32 storage locations allows for many possible applications and card uses.
IT IS STRONGLY ADVISED THAT THE KEY CODES IN THE RWD AND STORED ON THE MIFARE CARD ARE NOT CHANGED UNTIL THE OPERATION OF THE MIFARE CARD SECURITY IS FULLY UNDERSTOOD.

	B7 B0	
Command:	0 1 0 0 1 0 1 1	(Ascii "K", 0x4B)
Argument1:	x x x K K K K K	(K = Key code number, 0 - 31)
Argument2:	D D D D D D D D	(D = data to write to EEPROM, LS byte)
Argument3:	D D D D D D D D	
Argument4:	D D D D D D D D	
Argument5:	D D D D D D D D	
Argument6:	D D D D D D D D	
Argument7:	D D D D D D D D	(D = data to write to EEPROM, MS byte)
Acknowledge:	1 X X X F X X F	(F = Status flags)

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Internal Key Storage memory map (default settings)

Location 0 (0x00):   Key code 0 (Default 0xFF FF FF FF FF FF)
Location 1 (0x01):   Key code 1 (Default 0xFF FF FF FF FF FF)

Location 2 (0x02):   Key code 2 (Default 0xA0 A1 A2 A3 A4 A5)
Location 3 (0x03):   Key code 3 (Default 0xB0 B1 B2 B3 B4 B5)
-
-
-
Location 28 (0x1C):   Key code 28 (Default 0xFF FF FF FF FF FF)
Location 29 (0x1D):   Key code 29 (Default 0xFF FF FF FF FF FF)

Location 30 (0x1E):   Key code 30 (Default 0xA0 A1 A2 A3 A4 A5)
Location 31 (0x1F):   Key code 31 (Default 0xB0 B1 B2 B3 B4 B5)

Note that Mifare cards manufactured by Infineon have default transport key codes of (0xFF FF FF FF FF FF) and Philips cards have (0xA0 A1 A2 A3 A4 A5 / 0xB0 B1 B2 B3 B4 B5) default transport keys. The MicroRWD MF has both pairs stored as default settings to allow ease of use when the system is first used. (More information on the Mifare card memory maps, Security Keys and the KeyA and KeyB types can be found at the end of this document).

Write Card Block

Command to write 16 bytes of data to specified Mifare block. A Block is made up of 16 bytes and there are four blocks in each card sector (sixteen blocks per sector in upper half of Mifare 4k card). Note that blocks 3, 7, 11, 15 etc are sector trailer blocks that contain Security Key data and Access bits. Writing incorrect information to these blocks can permanently disable the sector concerned. The first argument is the block number to write data to, the second argument specifies which key code (0 - 31 from the internal storage area) to use for sector authentication/unlocking and if the Security Key is to be used as a KeyA or KeyB type code. If the write was unsuccessful (invalid card, authentication failed or card out of field) then Status flags in acknowledge byte indicate error.

```
            B7                    B0
Command:    0  1  0  1  0  1  1  1     (Ascii "W",  0x57)
Argument1:  N  N  N  N  N  N  N  N     (N = MF Card Block Address 0 – 255)
Argument2:  T  x  x  K  K  K  K  K     (T = Key Type, 0 = KeyA, 1= KeyB)
                                       (K = Key code number, 0 – 31)
Argument3:  D  D  D  D  D  D  D  D     (D = LS Byte of data to write to card)
Argument4:  D  D  D  D  D  D  D  D
Argument5:  D  D  D  D  D  D  D  D
Argument6:  D  D  D  D  D  D  D  D


                                       16 Bytes of data

Argument15: D  D  D  D  D  D  D  D
Argument16: D  D  D  D  D  D  D  D
Argument17: D  D  D  D  D  D  D  D
Argument18: D  D  D  D  D  D  D  D     (D = MS Byte of data to write to card)

Acknowledge: 1 F  F  F  F  F  F  X     (F = Status flags)
```

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Note that Mifare Ultralight cards DO NOT USE Security Keys or CRYPTO Authentication and the memory is organised differently as groups of 4 bytes (Pages). Only one Page of 4 bytes can be written at a time so to maintain compatibility and a simple RWD host command set, the same command as above is used to write data to Ultralight cards. The command and arguments have the same structure but different meanings. The "Block" address is treated as a "Page Address" and the KeyType/Key number parameter is a dummy 0x00 byte. In addition the 4 bytes of data are padded out to 16 bytes with dummy 0x00 bytes.

```
                  B7              B0
Command:     0  1  0  1  0  1  1  1        (Ascii "W",  0x57)
Argument1:   x  x  x  x  N  N  N  N        (N = UL Card Page Address 0 – 15)
Argument2:   0  0  0  0  0  0  0  0        (Dummy byte, 0x00)

Argument3:   D  D  D  D  D  D  D  D        (D = LS Byte of data to write to UL card)
Argument4:   D  D  D  D  D  D  D  D
Argument5:   D  D  D  D  D  D  D  D
Argument6:   D  D  D  D  D  D  D  D        (D = MS Byte of data to write to UL card)

Argument7 – Argument18
             0  0  0  0  0  0  0  0        12 Dummy padding bytes, 0x00

Acknowledge: 1  F  F  F  F  F  F  X        (F = Status flags)
```

Read Card Block

Command to read 16 bytes of data from specified Mifare block. The first argument is the block number to read data from, the second argument specifies which key code (0 - 31 from the internal storage area) to use for sector authentication/unlocking and if the Security Key is to be used as a KeyA or KeyB type code. If the read was successful, indicated by acknowledge status flags then sixteen bytes of block data follow.

```
                  B7              B0
Command:     0  1  0  1  0  0  1  0        (Ascii "R",  0x52)
Argument1:   N  N  N  N  N  N  N  N        (N = MF Card Block Address 0 – 255)
Argument2:   T  x  x  K  K  K  K  K        (T = Key Type, 0 = KeyA, 1= KeyB)
                                           (K = Key code number, 0 – 31)
Acknowledge: 1  F  F  F  F  F  F  X        (F = Status flags)
```

Data only follows if Read was successful

```
Reply1:      D  D  D  D  D  D  D  D        (D = LS Byte of data Read from card)
Reply2:      D  D  D  D  D  D  D  D
Reply3:      D  D  D  D  D  D  D  D
Reply4:      D  D  D  D  D  D  D  D

                                           16 Bytes of data

Reply13:     D  D  D  D  D  D  D  D
Reply14:     D  D  D  D  D  D  D  D
Reply15:     D  D  D  D  D  D  D  D
Reply16:     D  D  D  D  D  D  D  D        (D = MS Byte of data Read from card)
```

Note that as mentioned for the WRITE command, Mifare Ultralight cards DO NOT USE Security Keys or Authentication and the memory is organised differently as groups of 4 bytes (Pages). However, unlike the Write command, 16 bytes (4 pages) can be read in a single operation The same Read command as above is used except the "Block" address is treated as a "Page Address" and the KeyType/Key number parameter is a dummy 0x00 byte. For page numbers greater than 12, the card data wraps around to page 0 etc.

```
            B7                  B0
Command:    0  1  0  1  0  0  1  0     (Ascii "R",  0x52)
Argument1:  x  x  x  x  N  N  N  N     (N = UL Card Page Address 0 – 15)
Argument2:  0  0  0  0  0  0  0  0     (Dummy byte, 0x00)

Acknowledge:  1  F  F  F  F  F  F  X   (F = Status flags)
```

Data only follows if Read was successful

```
Reply1:     D  D  D  D  D  D  D  D     (D = LS Byte of data Read from UL card)
Reply2:     D  D  D  D  D  D  D  D
Reply3:     D  D  D  D  D  D  D  D
Reply4:     D  D  D  D  D  D  D  D

                                       16 Bytes of data

Reply13:    D  D  D  D  D  D  D  D
Reply14:    D  D  D  D  D  D  D  D
Reply15:    D  D  D  D  D  D  D  D
Reply16:    D  D  D  D  D  D  D  D     (D = MS Byte of data Read from UL card)
```

Inc Value (only operates on Value Data Structure)

Command to increment integer within a Value Data Structure. The command loads the value from the specified block address, adds the integer parameter and stores the result at the same or another block address. Note that the source block must have been formatted as a Value Block beforehand according to the data structure below, using the WRITE command. The INC Value command only operates on a "Value Block Structure" and will fail if the block configuration or the specified key type is incorrect.

Value Block Structure

Example format for value = 100 decimal (0x64), at block address 0.
(Value data stored LS byte first, ADR = block address, $\overline{ADR}$ = inverted block address)

```
    0x64  00  00  00  9B  FF  FF  FF  64  00  00  00  00  FF  00  FF

Byte:  0   1   2   3   4   5   6   7   8   9  10  11  12  13  14  15
       <----------->   <----------->   <----------->  ADR | ADR |
          Value         Inverted Value     Value       ADR    ADR
```

The first argument is the source block address to load data from, the second argument specifies which key code and type to use for sector authentication (0-31 and if it is KeyA or KeyB type).

The third argument specifies the destination block address where the incremented data is stored. Note that source and destination blocks must be within same authenticated sector. The four byte positive integer to add follows (least significant byte first).

```
                  B7                 B0
Command:      0  1  0  0  1  0  0  1      (Ascii "I",  0x49)
Argument1:    N  N  N  N  N  N  N  N      (N = MF source block address 0 – 255)
Argument2:    T  x  x  K  K  K  K  K      (T = Key Type, 0 = KeyA, 1= KeyB)
                                          (K = Key code number, 0 – 31)
Argument3:    N  N  N  N  N  N  N  N      (N = MF destination block address 0 – 255)

Argument4:    D  D  D  D  D  D  D  D   ⌐  (D = LS byte of integer to add)
Argument5:    D  D  D  D  D  D  D  D          4 byte integer
Argument6:    D  D  D  D  D  D  D  D
Argument7:    D  D  D  D  D  D  D  D   ⌐  (D = MS byte of integer to add)

Acknowledge:  1  F  F  F  F  F  F  X      (F = Status flags)
```

Dec Value (only operates on Value Data Structure)

Command to decrement integer within a Value Data Structure. The DEC Value command operates as the INC command except the integer parameter is subtracted from the loaded value. The first argument is the source block address to load data from, the second argument specifies which key code and type to use for sector authentication (0-31 and if it is KeyA or KeyB type). The third argument specifies the destination block address where the decremented data is stored. Note that source and destination blocks must be within same authenticated sector. The four byte positive integer to subtract follows (least significant byte first).

```
                  B7                 B0
Command:      0  1  0  0  0  1  0  0      (Ascii "D",  0x44)
Argument1:    N  N  N  N  N  N  N  N      (N = MF source block address 0 – 255)
Argument2:    T  x  x  K  K  K  K  K      (T = Key Type, 0 = KeyA, 1= KeyB)
                                          (K = Key code number, 0 – 31)
Argument3:    N  N  N  N  N  N  N  N      (N = MF destination block address 0 – 255)

Argument4:    D  D  D  D  D  D  D  D   ⌐  (D = LS byte of integer to subtract)
Argument5:    D  D  D  D  D  D  D  D          4 byte integer
Argument6:    D  D  D  D  D  D  D  D
Argument7:    D  D  D  D  D  D  D  D   ⌐  (D = MS byte of integer to subtract)

Acknowledge:  1  F  F  F  F  F  F  X      (F = Status flags)
```

Transfer Value (only operates on Value Data Structure)

Command to transfer (copy) Value Data Structure. The command loads the value from the specified block address and then stores the result at the same or another block address. As with INC and DEC commands the source block must have been formatted as a Value Block beforehand and the block addresses must be within same authenticated sector.

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The first argument is the source block address to load data from, the second argument specifies which key code to use for sector authentication (0-31) and if it is a KeyA or KeyB code. The third argument specifies where the data is stored.

```
            B7              B0
Command:    0 1 0 1 0 1 0 0      (Ascii "T",  0x54)
Argument1:  N N N N N N N N      (N = MF source block address 0 – 255)
Argument2:  T x  x  K K K K K    (T = Key Type, 0 = KeyA, 1= KeyB)
                                 (K = Key code number, 0 – 31)
Argument3:  N N N N N N N N      (N = MF destination block address 0 – 255)

Acknowledge: 1 F  F  F  F  F  F  X   (F = Status flags)
```

If the Inc, Dec or Transfer function was unsuccessful (invalid card, card out of field, authentication failed or data structures are incorrect) then Status flags in acknowledge byte indicate error. Note that the value manipulation commands operate internally on the Mifare card and no data is transferred back to the MicroRWD. Note also that Ultralight cards do not support Value Data Structures or the Inc, Dec, Transfer commands.

Type Identification

Command to return the **ATQA** (Answer to Request, Type A) two-byte codes and the **SAK** (Select Acknowledge) single-byte code after the complete UID has been acquired. As part of the initial communication with the Mifare card (as defined by ISO 14443A specification), the Mifare transponder responds to REQA (Request Command, Type A) with ATQA. The two-byte ATQA contains information that allows particular transponder types to be indentified. Following on from this the Mifare transponder responds to the SELECT (Select Command, Type A) with SAK (Select Acknowledge, Type A). The SAK code is a single byte value that contains further information about the type of transponder and the length of the UID. The SAK value reported is the final value after all "cascade levels" and the complete UID has been acquired.

NOTE THAT THIS COMMAND IS INCLUDED FOR DIAGNOSTIC PURPOSES TO ALLOW THE USER TO DETERMINE THE EXACT TYPE OF MIFARE CARD PRESENT IN THE FIELD, IF REQUIRED.

```
            B7              B0
Command:    0 1 1 1 1 0 0 0      (Ascii "x",  0x78)

Acknowledge: 1 F  F  F  F  F  F  X   (F = Status flags)
```

Data only follows if card was selected OK with no errors detected.

```
Reply1:     D D D D D D D D      ATQA - MSB
Reply2:     D D D D D D D D      ATQA - LSB
Reply3:     D D D D D D D D      SAK
```

	MF UL	MF 1K	MF 4K	MF DESFire	MF Prox	MF Prox	MF Prox	MF Prox	MF Prox	MF Prox
ATQA - MSB	0x00	0x00	0x00	0x03	0xXX	0xXX	0xXX	0xXX	0xXX	0xXX
ATQA - LSB	0x44	0x04	0x02	0x44	0x08	0x04	0x02	0x48	0x44	0x42

	Smart MX	Smart MX	Smart MX	Smart MX	Smart MX	Smart MX
ATQA - MSB	0xXX	0xXX	0xXX	0xXX	0xXX	0xXX
ATQA - LSB	0x08	0x04	0x02	0x48	0x44	0x42

	MF UL	MF 1K	INFINEON 1K	MF 4K	MF DESFire	MF ProX	MF ProX	MF ProX	MF ProX	MF ProX	MF ProX
SAK	0x00	0x08	0x88	0x18	0x20	0x20	0x08	0x28	0x00	0x20	0x08

	MF ProX	MF ProX	MF ProX	Smart MX	Smart MX	Smart MX	Smart MX	Smart MX	Smart MX
SAK	0x28	0x18	0x38	0x00	0x20	0x08	0x28	0x18	0x38

Note that many of the "extended" Mifare types are complex dual interface cards with embedded 8051 microcontrollers running operating systems. Depending on the card type the memory map and protocol of the "extended" Mifare card may be different to the standard card types. In these cases the MicroRWD MF will report the UID using the Card UID command but read/write operation MAY NOT be fully supported.

Message

Command to return product and firmware identifier string to host.

```
           B7                B0
Command:   0  1  1  1  1  0  1  0        (Ascii "z",  0x7A)
```

Reply: "m IDE RWD Mifare AS/WD (SECMF_CWAX_LP V1.xx DD/MM/YY) IB Technology
              Ltd accepts no liability for the use of this product in any end application" 0x00

Returned string identifies product descriptor, project name, firmware version no. and date of last software change together with IB Technology disclaimer message. Note that the string is always NULL terminated. The string begins with a unique lower case character that can be used to identify a particular version of Micro RWD.

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Addition Notes for Commands

NOTE also that for the "Read Card Block" or "Card UID" command, if an error flag has been set in the Acknowledge code then there will be NO following data.

NOTE that the serial communication uses hardware handshaking to inhibit the host from sending the Micro RWD commands while Card communication is in progress. The serial communication system and protocol allows for a 6ms 'window' every Card polling cycle indicated by the CTS/BUSY line being low. During this 'window' the host must assert the first start bit and start transmitting data. The CTS/BUSY goes high again 6ms after the last stop bit is received. NOTE that only one command sequence is handled at a time. The period between the CTS pulses (polling delay) can have three rates depending on whether a card is present or not and if commands are being received by the RWD

NOTE that the commands and parameters must be sent to the RWD with no gaps otherwise communication timeout occurs and the RWD enters the polling delay period (the command string would then be incomplete and an RS232 error is flagged).

NOTE that the MicroRWD MF LP version performs fast polling cycles as long as there are commands to be processed. As soon as the commands stop being sent or the gap between sending commands is too long then timeout occurs and the polling delay increases to 100ms (if the card is still present) or the typically longer period (as set by EEPROM parameter) if there is no card. This is to allow repeated commands to be handled quickly such as for a "complete card read" where repeated Read Block commands are sent to the RWD.

Commands sent infrequently will have the full polling delay between each CTS/BUSY period.

Basic RWD Communication

For basic operation of the MicroRWD connected to a host computer, the RWD can either be polled or communication can be triggered by an interrupt signal (Green LED output). In either case the user would initially send the "STORE KEYS" command to load a custom security key into the RWD memory or simply use the pre-loaded default key values.

For a polling technique, the host computer would then keep sending the "STATUS" or "CARD UID" command and would monitor the acknowledgement code until a valid Mifare card was detected.

For the interrupt technique, the Green LED output can be used as an interrupt signal connected to the host computer. The Green LED output is normally high and goes low only when a valid card has been detected. This falling-edge signal can trigger a host interrupt to then send the "STATUS" or "CARD UID" command to determine the card type and serial number.

In both cases once a valid card has been detected a "READ BLOCK" or "WRITE BLOCK" command can be sent and the acknowledge code monitored to establish that the operation was successful.

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Method of Operation

The system works on a polling principle whereby the RF field is turned on for a short period to check if a card is present. Authentication and Read/Write operations can then be performed before the RF field is turned off again and the process repeats. The polling principle where the RF is off most of the time allows for low average power consumption.
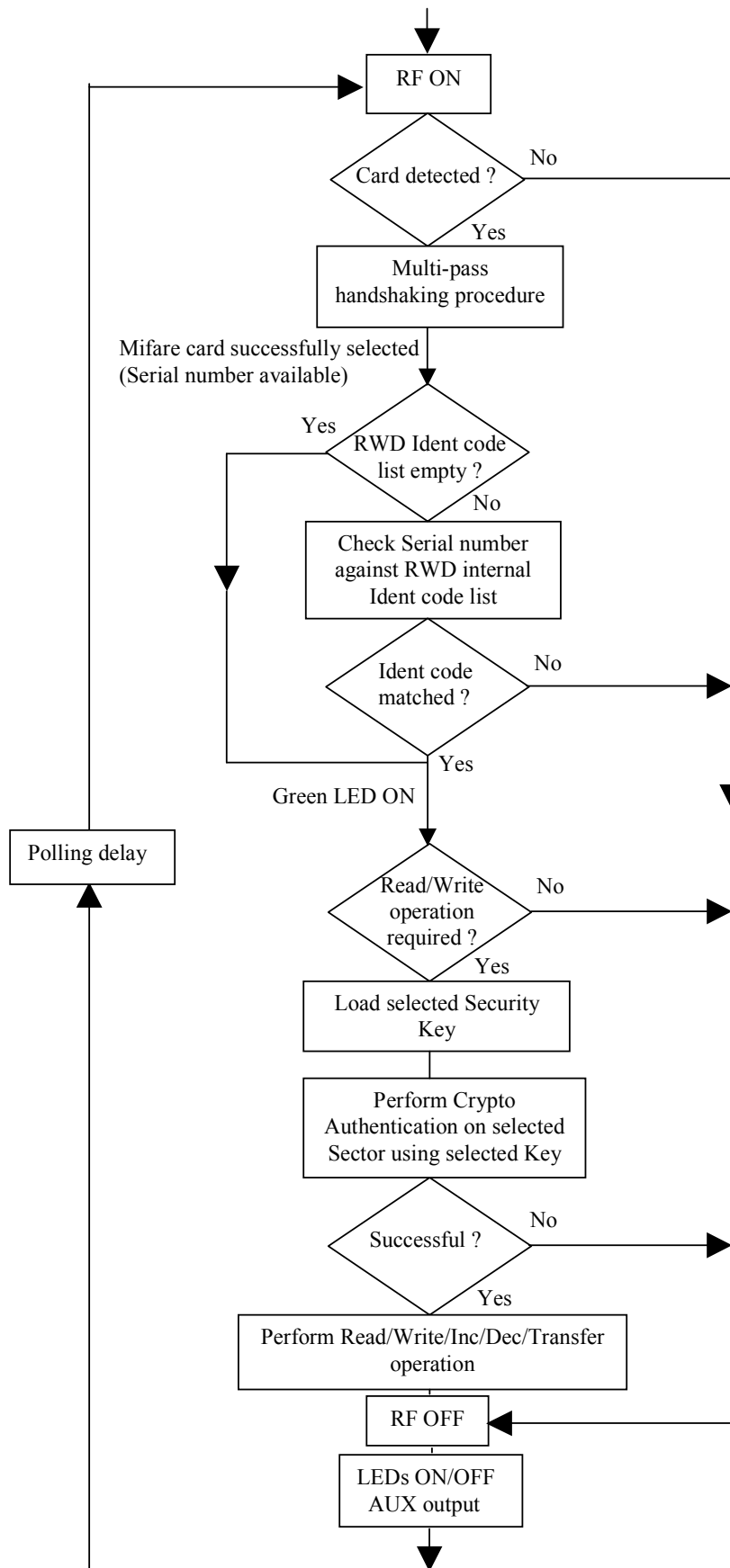
When a Mifare card is detected in the field a multi-pass handshaking procedure takes place where card information and serial number data is exchanged and checked for integrity. Once this procedure has completed successfully an individual card has been selected and is available for other operations.

The RWD itself has the additional feature of then checking the four byte Mifare UID/serial number (or least significant four bytes of Ultralight UID) against an internal authorisation list. The RWD internal EEPROM contains a list of four byte Identity codes (up to 60 of them) located from byte 12 onwards. If the list has FF FF FF FF (hex) stored at the first location (EEPROM bytes 12 - 15) then the list is treated as empty so the Identity code check is skipped.
Otherwise the card serial number is checked against all the entries in the list (until the FF FF FF FF termination code is reached) and if matched then the RWD allows the card to be accessed for other operations. If not the Red LED remains on and the card is blocked for further access. This is an additional level of security that can be used as a "mini access control" system for simple applications that only involve the serial number or where the Security Keys are not known.

Once the RWD has selected the card and has matched the serial number against it's internal list (or the list is empty) then the Read/Write (or Inc/Dec/Transfer) operations can be performed. These require an internal high-security Authentication Crypto algorithm to take place that use the supplied Security Keys to gain access to a particular sector. If the Key selected does not match the Key stored in the Mifare card sector then the operation fails and the Red LED is turned on again.

So in summary, a card can be successfully selected but can be blocked by the RWD authorisation list and fail Read/Write operations because the Keys are incorrect. Even if the Security Key is incorrect the Serial number can still be read using the "Card UID" command.

RF ON

Card detected ? — No

Yes

Multi-pass handshaking procedure

Mifare card successfully selected
(Serial number available)

Yes

RWD Ident code list empty ?

No

Check Serial number against RWD internal Ident code list

Ident code matched ? — No

Yes

Green LED ON

Polling delay

Read/Write operation required ? — No

Yes

Load selected Security Key

Perform Crypto Authentication on selected Sector using selected Key

Successful ? — No

Yes

Perform Read/Write/Inc/Dec/Transfer operation

RF OFF

LEDs ON/OFF AUX output

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Auxiliary Asynchronous Serial output

If selected, data can be automatically output from the **OP0 or main TX** pin as 4-bytes of data transmitted asynchronously at 9600 baud, 8-bits, 1 stop-bit, no parity. The data source can be selected as the 4-byte UID (serial number), the least significant 4-bytes of a double UID or the least significant (first) 4-bytes of a card memory block.

Data bytes transmitted at 9600 baud, 8-bits, 1-stop bit, No parity (104 µS per bit)

```
         b0    b1    b2    b3    b4    b5    b6    b7    b8    b9
5v  _____                                          _____
            | 1 |                                      | 0 |         TTL levels
0v          |___|_____|
    idle  START              8 bit data                STOP  idle
```
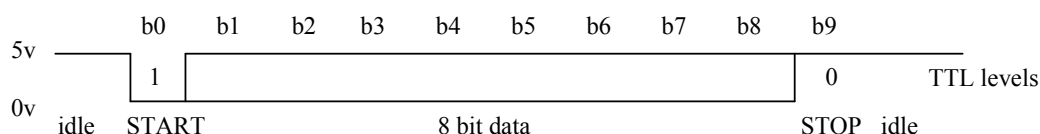
Auxiliary Wiegand Output Protocol

If selected, data can be automatically output from the **OP0 / OP1** pins as Data HIGH and Data LOW signals according to the Wiegand protocol.
The Wiegand protocol (24 bit data length) can be made up of a leading even parity bit (for b0 - b11), 24 bits of data (from transponder data) and a trailing odd parity bit (for b12- b23) creating a 26 bit output stream. The 32-bit mode has the same format except least significant four bytes of block data are used to form the data sequence. The parity bits are included or omitted and the byte order is reversed according to the EEPROM parameter settings.

For Example:-

Mifare block data (least significant 4 bytes):   0x04 60 22 12

(reversed byte option would use 0x12 22 60 04 as base data)

Wiegand 26 bit sequence:-   E   (b0 --------- b11) (b12 -------- b23) O

                                       E   (0   4   6   0   2   2) O

                                       1   0000 0100 0110   0000 0010 0010   1

Where E is EVEN parity bit for bit 0 to 11 and O is ODD parity bit for bits 12 to 23

The base data for the Wiegand output can be the UID (least significant 4-bytes of serial number) acquired during the initial ISO14443A communication or the least significant 4-bytes of data from a block of card memory (acquired by an internal Block Read operation). Selection is by means of an RWD EEPROM parameter.
For the internal Block Read operation, the block number, key code number and type (KeyA or KeyB) are programmable EEPROM parameters. In addition, parameters control whether the base data byte order is reversed or if parity bits are added before output.

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In this manner the user can select to use the UID (serial number) or user programmed information within a memory block as the base data for the Wiegand output. The complete data frame is output whenever the tag is within the RWD's antenna field and the tag has been validated. This output is independent of the normal TTL serial interface which responds to received commands and replies with the data as requested.

The physical Wiegand protocol is asynchronously transmitted as low going 50 µS pulses on the appropriate DATA low or DATA high pins. These pulses are separated by 2mS periods. The Wiegand sequence is output a single time whenever a valid tag enters the RF field for the first time. The data frame is then followed by a one second delay before normal operation continues (NO Wiegand output if AUX OUTPUT parameter is ZERO/OFF).

Wiegand Protocol Timing Diagram

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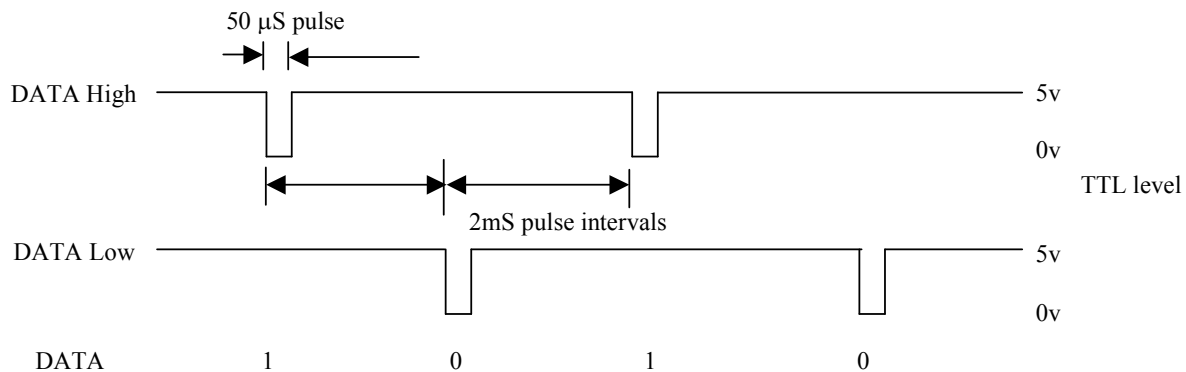
Mifare 1k (1024 byte) Memory Map

16 byte Block

Byte 0   Byte 15

Serial number + Manufacturer Information	Block 0 (0x00)

Sector 0

KeyA, Access bits, KeyB	Block 3 (0x03)
	Block 4 (0x04)

Sector 1

KeyA, Access bits, KeyB	Block 7 (0x07)

16 separate Sectors with individual Authentication and access control.

	Block 56 (0x38)

Sector 14

KeyA, Access bits, KeyB	Block 59 (0x3B)
	Block 60 (0x3C)

Sector 15

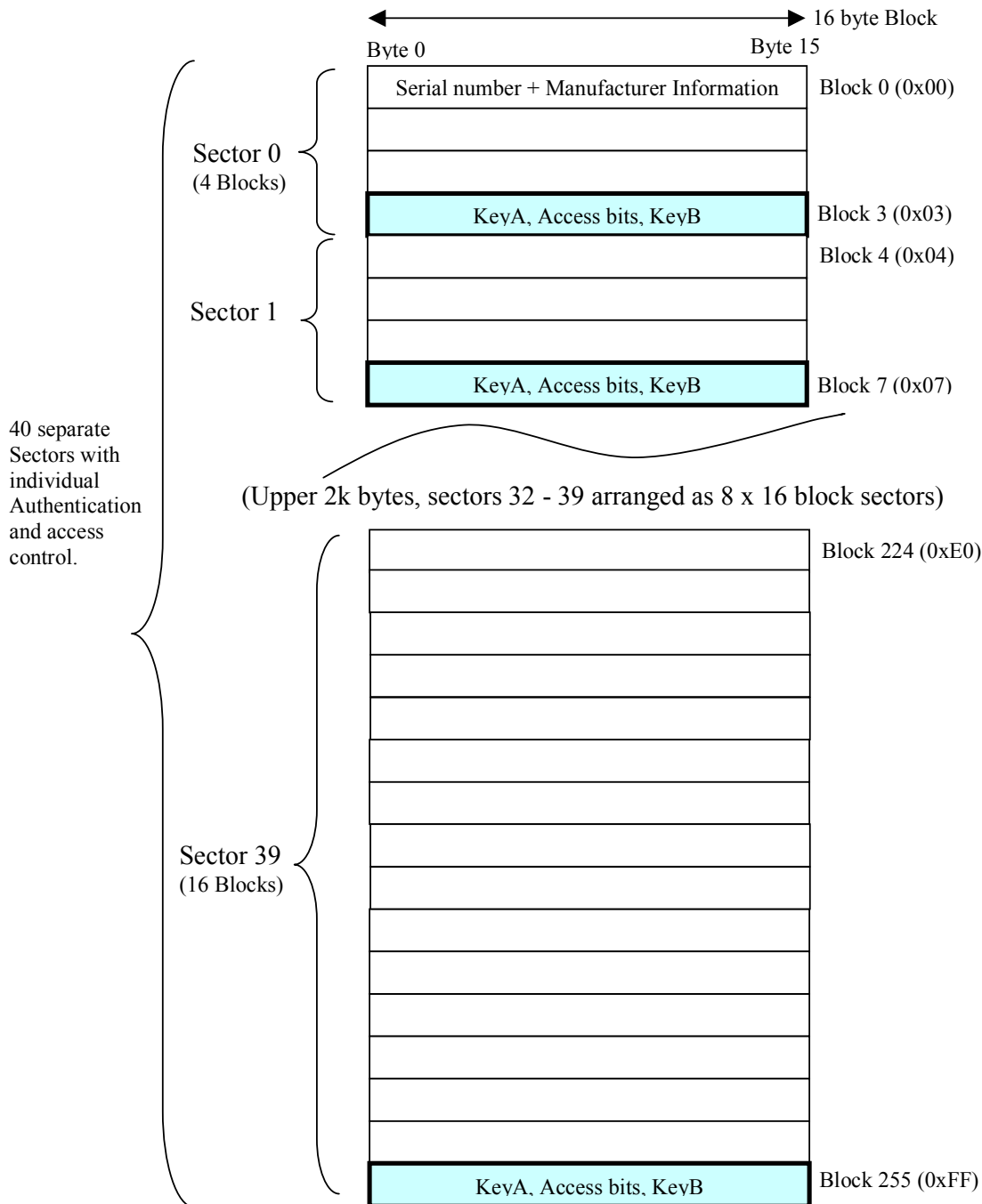|	
KeyA, Access bits, KeyB	Block 63 (0x3F)

1024 byte memory is organised as sixteen sectors, each of which is made up of four blocks and each block is 16 bytes long. The first block in the memory (Block 0) is read-only and is set in the factory to contain the four-byte serial number (UID), check bytes and manufacturers data.

The last block of each sector (Blocks 3, 7, 11, 15……59, 63) is the Sector Trailer Block which contains the two security Key codes (KeyA and KeyB) and the Access bits that define how the sector can be accessed

Taking into account the Serial Number/Manufacturers Block and the Sector Trailer Blocks then there are 752 bytes of free memory for user storage. For all Read and Write operations the Mifare card memory is addressed by Block number (in hexadecimal format).
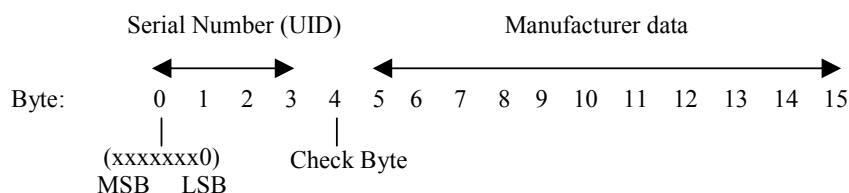
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Mifare 4k (4096 byte) Memory Map

(Lower 2k bytes, sectors 0-31 arranged as 32 x 4 block sectors)

16 byte Block

Byte 0   Byte 15

Serial number + Manufacturer Information	Block 0 (0x00)

Sector 0 (4 Blocks)

KeyA, Access bits, KeyB — Block 3 (0x03)

Block 4 (0x04)

Sector 1

KeyA, Access bits, KeyB — Block 7 (0x07)

40 separate Sectors with individual Authentication and access control.

(Upper 2k bytes, sectors 32 - 39 arranged as 8 x 16 block sectors)

Block 224 (0xE0)

Sector 39 (16 Blocks)

KeyA, Access bits, KeyB — Block 255 (0xFF)

The lower 2048 bytes of the 4k card (sectors 0 – 31) are organised in the same way as the 1k card. However the upper 2048 bytes are organised as eight large sectors of 16 blocks each (sectors 32 – 39). Taking into account the Serial Number/Manufacturers Block and the Sector Trailer Blocks then there are 3440 bytes of free memory for user storage.
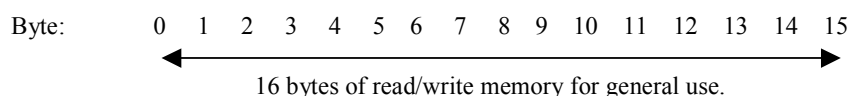
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Manufacturer Block

The Manufacturer block is the first data block in Sector 0 and it contains the read-only serial number (UID – Unique Identifier) and the IC manufacture information.

```
          Serial Number (UID)              Manufacturer data
          |<------------->|         |<------------------------------------>|
Byte:     0   1   2   3   4   5   6   7   8   9   10  11  12  13  14  15
              |               |
          (xxxxxxx0)       Check Byte
          MSB    LSB
```

Data Blocks

Mifare sectors contain 3 blocks (1k card) or 15 blocks (upper half of 4k card) of 16 data bytes (except Sector 0 that has Manufacturer Block and 2 data blocks). Data blocks can be configured as standard read/write memory or "Value Blocks" for special electronic-purse operations. "Value Blocks" can use additional commands such as Increment and Decrement for direct control of the data field, they have a fixed data format which permits error detection/correction and backup management. "VALUE" is a signed four byte integer (2's complement format) and is stored three times, twice non-inverted and once inverted. "ADR" signifies a one byte address that can be used to store the block number. "ADR" is stored four times, twice inverted and twice non-inverted.
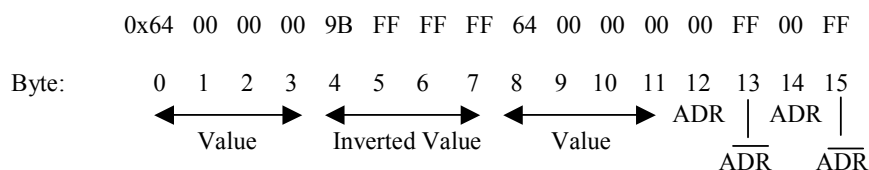
Data Block

```
Byte:     0   1   2   3   4   5   6   7   8   9   10  11  12  13  14  15
          |<--------------------------------------------------------->|
               16 bytes of read/write memory for general use.
```

Value Block
Example format for value = 100 decimal (0x64), at block address 0.
(Value data stored LS byte first, ADR = block address, $\overline{ADR}$ = inverted block address)

```
          0x64  00  00  00  9B  FF  FF  FF  64  00  00  00  00  FF  00  FF

Byte:     0   1   2   3   4   5   6   7   8   9   10  11  12   13   14   15
          |<------->|   |<------->|   |<------->|  ADR  |  ADR  |
             Value      Inverted Value    Value       ___       ___
             ____                                     ADR       ADR
```

Note that the ADR and inverted ADR block address is part of the required format for the Value Data Structure BUT it is not changed by the Inc, Dec or Transfer commands and exists to allow optional storage of block numbers. For general use, the 0x00 address and 0xFF inverted address can be used to satisfy the structure format. The Inc, Dec and Transfer commands first check the structure format before beginning the operations and the commands fail if the format is not correct.

Value Data Structures must first be formatted as above using a WRITE Block command before INC, DEC or TRANSFER commands can be used.

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Sector Trailer Block

The last block of each sector (Blocks 3, 7, 11, 15……59, 63 etc) is the Sector Trailer Block which contains the two security Key codes (KeyA and KeyB) and the Access bits that define how the data blocks can be accessed (Read/Write, Read or Write only, as data or Value blocks and using which key). If KeyB is not used then the last 6 bytes of the Sector Trailer Block can be used for general data storage. Byte 9 (last byte of Access bits) is not used and can also be used for general storage. Note that the KeyA (and KeyB) value read back as logical 0's to ensure system security.

IT IS STRONGLY RECOMMENDED THAT THE KEY CODES AND THE ACCESS BITS STORED ON THE MIFARE CARD ARE NOT CHANGED UNTIL THEIR OPERATION IS FULLY UNDERSTOOD.

Sector Trailer Block

Byte: 0 1 2 3 4 5   6 7 8 9   10 11 12 13 14 15

                KeyA (6 bytes)   Access Bits   KeyB (optional)
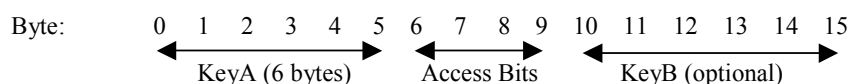
KeyA and KeyB

The security Key codes are each six bytes long and for successful authentication and read/write communication the RWD device would have to have one or both keys stored in its internal memory as well (depending on Access Bit settings). To allow "out-of-the-box" operation with new Mifare transponders and RWD devices, Transport Key values are pre-loaded into the transponder memory and also into the RWD memory.

Transport Key values as defined by Infineon are:
KeyA: 0xFF FF FF FF FF FF   **KeyB:**   0xFF FF FF FF FF FF

Transport Key values as defined by Philips Semiconductors are:
KeyA: 0xA0 A1 A2 A3 A4 A5   **KeyB**:   0xB0 B1 B2 B3 B4 B5

These KeyA and KeyB values are stored as repeated pairs in the MicroRWD MF device as a factory default.

If the user intends using other Mifare cards then they may have different transport keys loaded so the user would have to use the STORE KEY command to load the particular Key codes into the RWD memory first. Once correct communication is established then Keys and Access bits can be changed on the card and RWD to suit the users final system requirements.

Access Bits

The access conditions for every data block and sector trailer are defined by three bits (C1, C2, C3), which are stored in a specific non-inverted and inverted pattern in the sector trailer of the particular sector. The access bits control the memory access rights using the secret KeyA and KeyB codes. The access bits can be changed provided the relevant Key(s) is known and the current access conditions allow this operation.

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Note that with each memory access the internal logic of the Mifare transponder verifies the format of the access conditions. If it detects a format error then the entire sector is irreversibly locked. Since the access bits themselves can be blocked for read/write operations, care must be taken when cards are being personalised for a particular application or service provider.
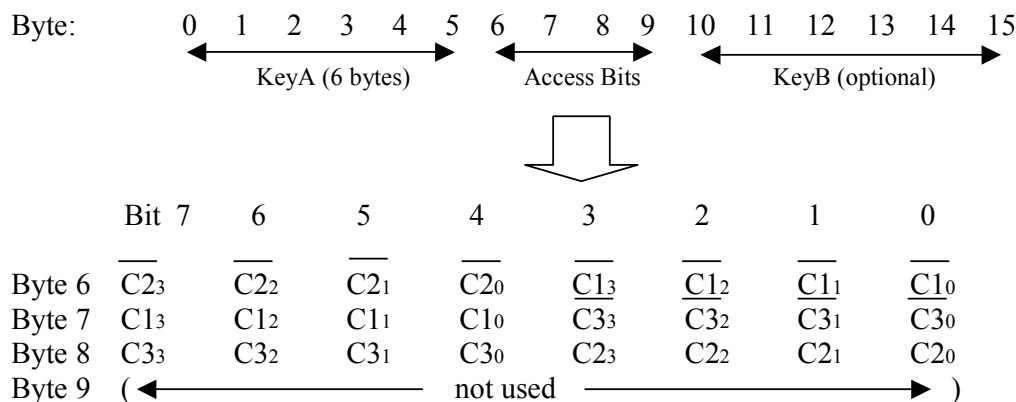
Access Bits	**Block Affected within a sector**	
	(1k card and lower half of 4k card)	(Upper half of 4k card)
$C1_0$ $C2_0$ $C3_0$	Block 0 (Data Block)	Blocks 0-4 (Data Blocks)
$C1_1$ $C2_1$ $C3_1$	Block 1 (Data Block)	Blocks 5-9 (Data Blocks)
$C1_2$ $C2_2$ $C3_2$	Block 2 (Data Block)	Blocks 10-14 (Data Blocks)
$C1_3$ $C2_3$ $C3_3$	Block 3 (Sector Trailer)	Block 15 (Sector Trailer)

Note that the Access Conditions for individual blocks can be set on 1k cards and for lower half of 4k card memory. However for the upper half of 4k cards the Access conditions are set for groups of five blocks (except for Sector Trailer Block which is still individually set).

Access Conditions
The C1, C2, C3 access bits are stored in a specific non-inverted and inverted pattern in the sector trailer of the particular sector. These bits control the Access Conditions for every data block and sector trailer block.

Sector Trailer Block

Byte: 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15

KeyA (6 bytes)   Access Bits   KeyB (optional)

	Bit 7	6	5	4	3	2	1	0
Byte 6	$\overline{C2_3}$	$\overline{C2_2}$	$\overline{C2_1}$	$\overline{C2_0}$	$\overline{C1_3}$	$\overline{C1_2}$	$\overline{C1_1}$	$\overline{C1_0}$
Byte 7	$C1_3$	$C1_2$	$C1_1$	$C1_0$	$\overline{C3_3}$	$\overline{C3_2}$	$\overline{C3_1}$	$\overline{C3_0}$
Byte 8	$C3_3$	$C3_2$	$C3_1$	$C3_0$	$C2_3$	$C2_2$	$C2_1$	$C2_0$
Byte 9	(←			not used			→	)

$\overline{Cxy}$ = Inverted bit

Transport settings (factory defaults)

Byte 6	(1	1	1	1	1	1	1	1)	= 0xFF
Byte 7	0	0	0	0	0	1	1	1)	= 0x07
Byte 8	1	0	0	0	0	0	0	0)	= 0x80
Byte 9	(←			not used			→	)	

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Access Condition for Sector Trailer Block

The read/write access to the Keys and the Access Bits themselves is controlled by the access conditions for the Sector Trailer Block. The read/write access is specified as "Never", "KeyA", KeyB" or Key A|B (KeyA OR KeyB).

Access Bits			Access condition for:						
			KEY A		ACCESS BITS		KEY B		
C1	C2	C3	Read	Write	Read	Write	Read	Write	
0	0	0	never	keyA	keyA	never	keyA	keyA	(KeyB can be read)
0	0	1	never	keyA	keyA	keyA	keyA	keyA	**(Transport setting)**
0	1	0	never	never	keyA	never	keyA	never	(KeyB can be read)
0	1	1	never	keyB	keyA|B	keyB	never	keyB	
1	0	0	never	keyB	keyA|B	never	never	keyB	
1	0	1	never	never	keyA|B	keyB	never	never	
1	1	0	never	never	keyA|B	never	never	never	
1	1	1	never	never	keyA|B	never	never	never	

The new Mifare cards have the access conditions predefined as transport configuration:

C1 C2 C3 = (0 0 1) which means Sector Trailer Block can only be read or written to using KeyA and KeyA itself can never be read.

Because the Access Bits themselves can be locked great care must be taken when any of these settings are changed because they may be irreversible making the card unusable.

Access Condition for data areas

The read/write access to the data areas is also controlled by the access conditions defined in the Sector Trailer Block. The read/write access is specified as "Never", "KeyA", KeyB" or Key A|B (KeyA OR KeyB).

A data block can be a "read/write block" or a "value block". For a "read/write" block the basic read and write operations are allowed. For the "value block" the additional increment, decrement, transfer and restore operations can apply. In one case (001) only read and decrement are possible for a "non-rechargeable" card application and in another case (110) recharging is only possible using keyB.
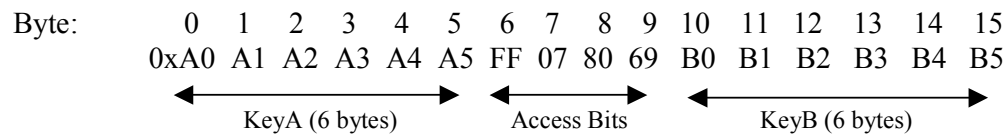
The default transport configuration specifies that the data areas can only be accessed using KeyA|B, however the operation of the Mifare cards define that "IF KEYB CAN BE READ IN THE CORRESPONDING SECTOR TRAILER THEN IT CANNOT SERVE FOR AUTHENTICATION". This means that for the transport configuration (and 001 and 010 cases), KeyA must be used for access.

Note also that the read-only status of the Manufacturer Block is not affected by the access bits setting.

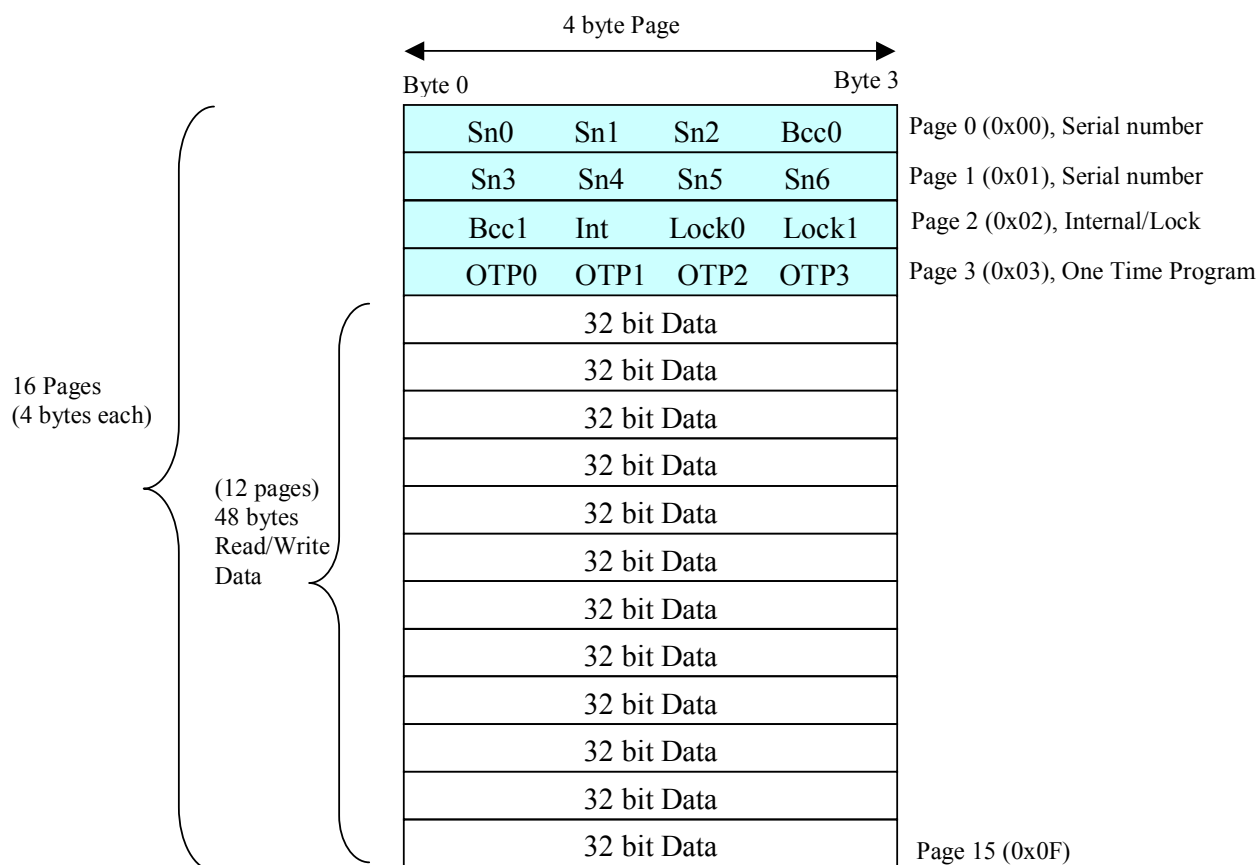| Access Bits	Access condition for:				Application
C1 C2 C3	Read	Write	Increment	Decrement, Transfer, Restore	
0 0 0	keyA|B	keyA|B	keyA|B	keyA|B	(Transport setting)
0 0 1	keyA|B	never	never	keyA|B	(value block)
0 1 0	keyA|B	never	never	never	(read/write block)
0 1 1	keyB	keyB	never	never	(read/write block)
1 0 0	keyA|B	keyB	never	never	(read/write block)
1 0 1	keyB	never	never	never	(read/write block)
1 1 0	keyA|B	keyB	keyB	keyA|B	(value block)
1 1 1	never	never	never	never	(read/write block)

Combining the transport (default) access conditions for the data areas and the sector trailer block, the typical setting is:

Sector Trailer Block

Byte:	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
	0xA0	A1	A2	A3	A4	A5	FF	07	80	69	B0	B1	B2	B3	B4	B5

KeyA (6 bytes)   Access Bits   KeyB (6 bytes)

The default access bits (0xFF 07 80 69) define that KeyA must used for all operations and KeyA can never be read, so in the previous example bytes 0 – 5 (keyA) would always read as zeros.

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<u>Mifare Ultralight (64 byte) Memory Map</u>

4 byte Page

Byte 0   Byte 3

Sn0	Sn1	Sn2	Bcc0	Page 0 (0x00), Serial number
Sn3	Sn4	Sn5	Sn6	Page 1 (0x01), Serial number
Bcc1	Int	Lock0	Lock1	Page 2 (0x02), Internal/Lock
OTP0	OTP1	OTP2	OTP3	Page 3 (0x03), One Time Program
32 bit Data				
32 bit Data				
32 bit Data				
32 bit Data				
32 bit Data				
32 bit Data				
32 bit Data				
32 bit Data				
32 bit Data				
32 bit Data				
32 bit Data				
32 bit Data				Page 15 (0x0F)

16 Pages
(4 bytes each)

(12 pages)
48 bytes
Read/Write
Data

Note: Ultralight card has 7 byte serial number (+ 2 check bytes)
Bcc0 = CT xor Sn0 xor Sn1 xor SN2 (CT = Cascade Tag = 0x88)
Bcc1 = Sn3 xor Sn4 xor Sn5 xor Sn6

The Mifare Ultralight transponder has a different structure to the standard 1k and 4k byte Mifare transponders. The 64 byte memory is organised as sixteen pages of four bytes each. The first two pages (and byte 0 of page 3) contain a seven byte serial number (UID) together with two check bytes. The other "system" bytes are used for locking card features and providing a number of OTP (One Time Programmable) data bytes. The remaining 12 pages (48 bytes) can be used for general read/write storage.

Despite having a different memory structure, the Ultralight uses the same Mifare communication protocol except that a cascaded selection procedure is used and the **Authentication procedure is not used for read/write operations**. The security Keys are therefore NOT required for any operations to an Ultralight card. Because of it's smaller memory, more basic operation and lower cost, the Ultralight card is typically used for low-value single applications.

The MicroRWD MF reader module fully supports the Ultralight cards and the read and write commands have the same format as for the standard cards except that dummy data bytes (0x00 values) are used for the Key number etc. In addition the "block number" argument becomes a "page number" parameter.

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Mifare Applications and Security

The Mifare "classic" family is the pioneer and market leader in contactless smart card technology operating in the 13.56 MHz frequency range with read/write capability. The Mifare technology was originally designed for Electronic-Purse applications for public transport systems and was a benchmark for the ISO 14443A standard. The cards have up to 40 separate memory sectors or "purses" (on Mifare 4k card) that can be individually locked and unlocked for access. In addition, the high speed communication of the 13.56 MHz interface allows for quick increment/decrement operations that are required for rapid ticketing or e-purse applications. Typical transaction time is less than 100ms for read/modify/write operations. The multiple memory sectors allow for different service providers to use the same Mifare card with complete independence and security, the Ultralight card has only one sector and is designed for single use or disposable applications due to it's low cost.

Because Mifare was designed originally for Electronic-Purse applications, a very high level of security was essential to prevent fraud. Each transaction is started with a mutual three pass authentication procedure according to the ISO 9798-2 standard. RF communication is protected from replay attack and data communication between RWD and card is encrypted according to the Philips triple-DES CRYPTO1 algorithm. Separate sets of two security keys for each memory sector (or application) ensure that service providers have complete security control over their individual sector. The high level of data integrity for the 106 kbaud RF communication is achieved by combining a special patented modulation technique, 16 bit CRC, parity bit coding, bit counting, channel monitoring and an anticollision algorithm.

Finally, the RWD device itself stores up to 32 security keys that the service provider can change and use for their applications. These keys are non-volatile and cannot be read back further ensuring system security.

Even though the Mifare technology is ideally suited to e-purse uses, each card has a unique serial number at the beginning of it's memory that makes the technology suitable for almost any application requiring large and secure read/write memory areas. Typical applications could include:-

Access Control, Automatic Fare Collection, Bus/Train/Airline ticketing, Electronic Purse, Vending, Loyalty / Membership Schemes, ID cards, Time and Attendance, Asset Tracking, Gambling, Electronic Keys, Logistics, Road Tolling, Payphones, Park and Ride Schemes, pre-paid metering.

IB Technology's design philosophy has created the "Universal RFID Socket" so that different technologies such as the 125 kHz MicroRWD (Hitag and EM Marin) modules, QT (Quad Tag) module and the 13.56 MHz MicroRWD Mifare and I.CODE modules are the same physical size, have the same pinout and share common serial commands. This concept allows users to select and migrate between different RFID technologies according to the specific features they require with the minimum of design changes.

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Micro RWD MF (Mifare) LP (low-power) specification

The MicroRWD MF (Mifare) LOW-POWER version is a complete read/write system for 13.56 MHz Mifare 1k, 4k and Ultralight cards. The module is pin-compatible and virtually identical in operation and features to the "standard" version (NOTE differences in EEPROM parameters and the three polling rates).

However the LOW-POWER version uses a different specification microcontroller offering lower voltage operation and is designed to be powered from four alkaline battery cells. During the Polling Delay period the microcontroller enters SLEEP mode with the RF device in hard power-down mode to reduce the current consumption to a very low level.
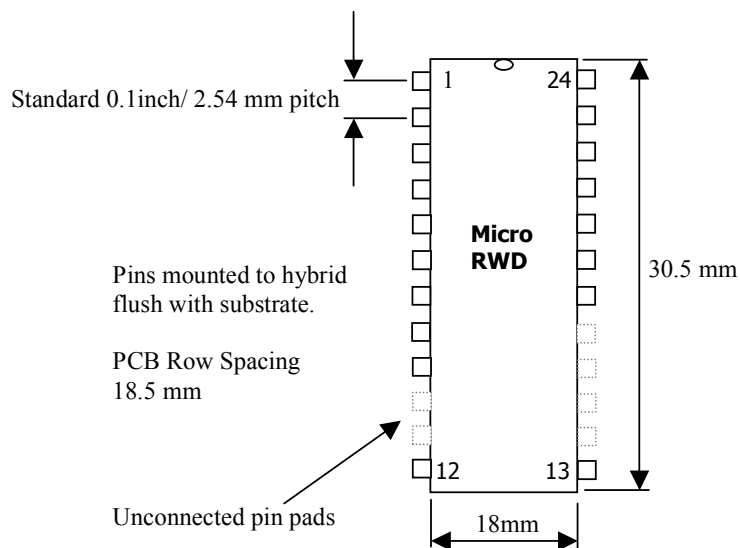
The module wakes up after the polling delay period and the process repeats. The RWD-MIFARE "low-power" Windows applications can be used to configure the parameters and read/write data.

Parameter	Typical Value
Supply Voltage (performance optimised for 5 volt operation)	4 – 6 volts DC (operation from 4 x alkaline cells)
Operating temperature	-40 deg C to + 85 deg C
AVERAGE current consumption. (1 second polling)	**Less than 100 μA**
Active period for RF AND host communication (each polling cycle).	Up to 20 mS
Peak antenna voltage (optimum tuning)	30 volts peak-to-peak
Peak antenna current (optimum tuning) for short period each polling cycle (up to 10 mS burst)	150 mA
Polling Delay (SLEEP / Power-down mode)	4 mS to 8 seconds
Current consumption during Polling delay / SLEEP	Less than 20 μA
Current consumption during RF ON each polling cycle	Less than 20mA
Maximum data rate (between card and RWD)	106k baud
Range (dependent on antenna dimensions and tuning)	25-50 mm
Auxiliary output drives	Up to 25mA
Serial Interface	TTL level RS232
Serial Communication Parameters	9600 baud, 8 data bits, no parity, 1 stop bit protocol with CTS handshake

Basic electrical specification with LEDs pins and auxiliary outputs NOT connected.
Note that the MicroRWD MF (Mifare) LOW-POWER version is designed for optimum performance and range at 5-volt operation. Performance will be reduced at maximum and minimum operating voltage.

During the "Polling Delay" SLEEP/Power-down period the logic levels on the RWD pins remain active and so for minimum current consumption, the LEDs and the auxiliary output drives must be disconnected (and the Beep output delay set to zero).

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Micro RWD MIFARE module dimensions and pinout

Standard 0.1inch/ 2.54 mm pitch

Pins mounted to hybrid flush with substrate.

PCB Row Spacing 18.5 mm

Unconnected pin pads

30.5 mm

18mm

PINOUT DESCRIPTION

Pin Name	DIP No.	I/O Type	Buffer Type	Description
LED1	1	O	TTL	Red LED connection. 25ma max sink current
LED2	2	O	TTL	Green LED connection. 25ma max sink current
RESET	3	I	ST	Reset pin internally pulled high. Active low. Normally not connected
BEEP	4	O	TTL	BEEP output pin (active LOW), 25ma max sink current
-	5	-	-	Not connected
-	6	-	-	Not connected
GND	7	P	-	Ground reference for logic and analogue pins
VCC	8	P	-	+5v Positive supply
AN1	9	P	AN	Antenna connection. 1 (connected to Mifare antenna board)
-	10	-	-	Not connected
-	11	-	-	Not connected
AN2	12	P	AN	Antenna connection 2 (connected to Mifare antenna board)
GND	13	P	-	Ground reference for logic and analogue pins.
-	14	-	-	Not connected
-	15	-	-	Not connected
-	16	-	-	Not connected
-	17	-	-	Not connected
-	18	-	-	Not connected
OP1	19	O	TTL	Auxiliary output drive. 25ma max sink current.
OP0	20	O	TTL	Auxiliary output drive. 25ma max sink current.
VCC	21	P	-	+5v Positive supply
RX	22	I	TTL	Serial communication Receive line. 9600 baud, 8 bit, 1 stop, no parity
TX	23	O	TTL	Serial communication Transmit line
CTS	24	O	TTL	Serial communication CTS handshake. RX enabled when CTS low and disabled when high.

(I/O = Input/Output, AN = Antenna output, P = Power, ST = Schmitt Trigger input, TTL = TTL logic I/O)

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No responsibility is taken for the method of integration or final use of Micro RWD

More information on the Micro RWD and other products can be found at the Internet web site:

http://www.ibtechnology.co.uk

Or alternatively contact IB Technology by email at:

sales@ibtechnology.co.uk