



**MS Long-Range
Handheld Transmitter
Master Development System
User's Guide**

Wireless made simple®

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Do not use this or any Linx product to trigger an action directly from the data line or RSSI lines without a protocol or encoder/decoder to validate the data. Without validation, any signal from another unrelated transmitter in the environment received by the module could inadvertently trigger the action.

All RF products are susceptible to RF interference that can prevent communication. RF products without frequency agility or hopping implemented are more subject to interference. This module does have a frequency hopping protocol built in, but the developer should still be aware of the risk of interference.

Do not use any Linx product over the limits in this data guide. Excessive voltage or extended operation at the maximum voltage could cause product failure. Exceeding the reflow temperature profile could cause product failure which is not immediately evident.

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MS Long-Range Handheld Transmitter Master Development System

Data Guide

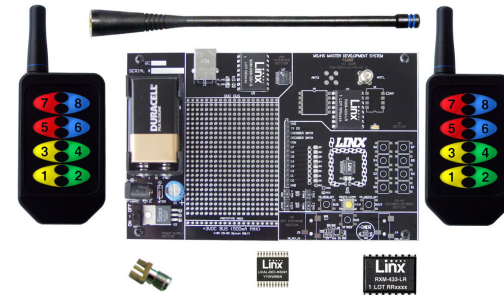


Figure 1: MS Long-Range Handheld Transmitter Master Development System

Introduction

The LinX MS Long-Range Handheld transmitter offers a simple, efficient and cost-effective method of adding remote control capabilities to any product. This Master Development System gives a designer all the tools necessary to incorporate the transmitter, LR Series receiver and MS Series decoder into a product. The Master Development System serves several important functions:

- **Rapid Evaluation:** It allows the performance and features of the transmitter, LR Series receiver and MS Series encoders and decoders to be evaluated quickly in a user's environment.
- **Range Testing:** The transmitter and receiver board form a full remote control system so that the range performance can be evaluated.
- **Design Benchmark:** The boards provide a known benchmark against which the performance of a custom design may be judged.
- **Application Development:** An onboard prototyping area allows for the development of custom circuits directly on the development board. All signal lines are available on a header for easy access.

The Master Development System includes 2 MS Long-Range Handheld transmitters, 2 LR Series receivers*, 2 MS Series decoders*, 1 receiver / decoder development board, 1 CW Series antenna, demonstration software CD and full documentation.

*One part is soldered to the board, one extra is for use on your first prototype board

Ordering Information

Ordering Information	
Part Number	Description
MDEV-***-HH-LR8-MS	MS Long-Range Transmitter Master Development System
*** = 315, 418 (Standard) or 433.92MHz	

Figure 2: Ordering Information

MS Series Decoder Development Board

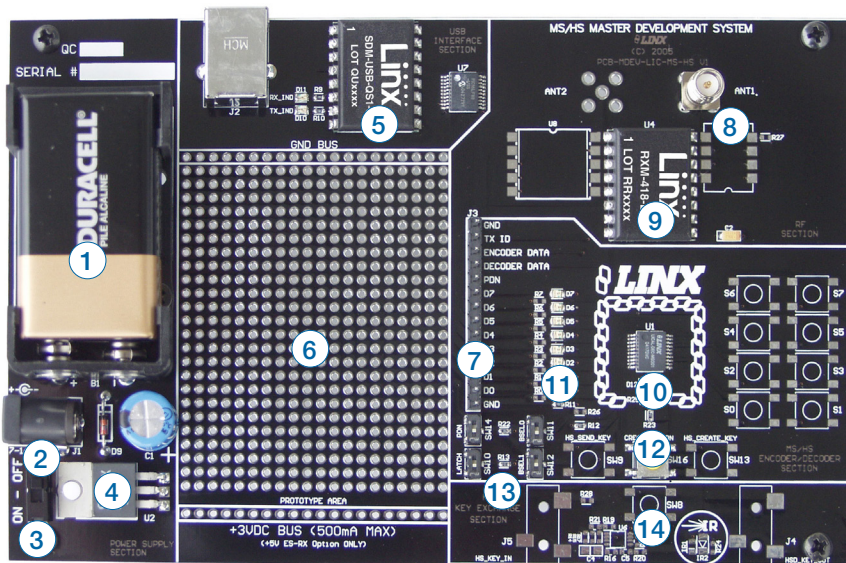


Figure 3: The MS Series Decoder Development Board

1. 9V Battery
2. Power Jack
3. On-Off Switch
4. Voltage Regulator
5. QS Series USB Module
6. Prototype Area
7. Break-Out Header
8. RP-SMA Antenna Connector
9. LR Series Receiver
10. MS Series Decoder
11. Data Line LEDs
12. Indicator LEDs
13. Function Switches
14. LEARN Button

Using the Master Development System

Using the Master Development System is straightforward. After unpacking the board, screw the antenna onto the connector, install the supplied 9V battery, and turn on the power switch. The encoder and decoder are configured from the factory and work straight out of the box. To create a new address (if desired), follow these easy steps:

1. Press and hold the CREATE button on the transmitter to create a new Code Word. This is done by sticking a paper clip through the hole on the back of the case and pressing the button inside. The Code Word is randomized for as long as the button is held down. Once comfortable that the number is sufficiently random, release the button.
2. Once the button is released, the MODE_IND LED begins flashing to indicate that it is ready to accept Control Permissions. Press all of the data line buttons that are to be recognized, then press the CREATE button again or let it time out after seventeen seconds.
3. Press the LEARN button on the decoder board and the MODE_IND LED starts flashing. Press any of the data line buttons on the transmitter and press the LEARN button again. The encoder's Code Word has now been learned by the decoder and they will operate together.

Troubleshooting

If the boards fail to work out of the box, then try the following:

- Check the battery to make sure it is not dead.
- Make sure the baud rate switches are set to 9,600bps on the decoder board.
- Make sure that the antenna is connected.
- Check to see if the PDN switch is on, placing the decoder into Power Down Mode. In most cases, the decoder PDN switch should be on.
- Make sure that the Control Permissions are set correctly. If the encoder has not been set to use a particular line, then when that button is pressed on the transmitter, the MODE_IND LED on the decoder board lights up, but the data line LED does not light up.

If all of these appear to be in order, then you can call +1 800 736 6677 or e-mail techsupport@linxtechnologies.com for technical support.

Setting the Transmitter Address

The MS Long-Range Handheld Transmitter allows the selection of one of 16,777,216 (2^{24}) unique addresses. All transmitters are supplied set to a unique address to avoid contention with other units; however, the address can be changed. This is accomplished by using a paper clip or probe to press the CREATE button on the board through the hole in the back of the case. Press the button and an LED lights up in the MODE_IND window,

MODE_IND Window



CREATE Button

Figure 4: CREATE Button Access

indicating that the address is being created. The address is randomized for as long as the button is held down. Release the button and the randomized address is saved and the LED begins flashing to indicate that the Control Permissions may now be set. Press the buttons that the transmitter should have the authority to access. Press the CREATE button with the paper clip again or wait 17 seconds for it to time out. The address and Control Permissions are now set. The decoder needs to learn the address before it will accept any transmissions. Please see the Typical Applications section of this data guide or the MS Series Decoder Data Guide for details.

OTX-***-HH-LR8-MS Button Assignments

Figure 5 illustrates the relationship between the button locations and encoder data lines.

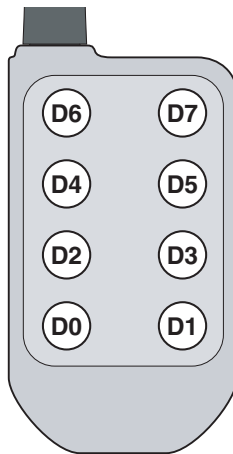


Figure 5: OTX-***-HH-LR8-MS Button Assignments

Contention Considerations

It is important to understand that only one transmitter at a time can be activated within a reception area. While the transmitted signal consists of encoded digital data, only one carrier of any particular frequency can occupy airspace without contention at any given time. If two transmitters are activated in the same area at the same time, then the signals will interfere with each other and the decoder will not see a valid transmission, so it will not take any action.

Battery Replacement

The remote unit utilizes a standard CR2032 lithium button cell. In normal use, it provides 1 to 2 years of operation. To replace the battery, remove the access cover by pressing firmly on the label area and sliding it off. Once the unit is open, remove the battery by sliding it from beneath the holder. Replace it with the same type of battery while observing the polarity shown in Figure 6.



Battery access

Figure 6: Battery Access

Assembly Diagram

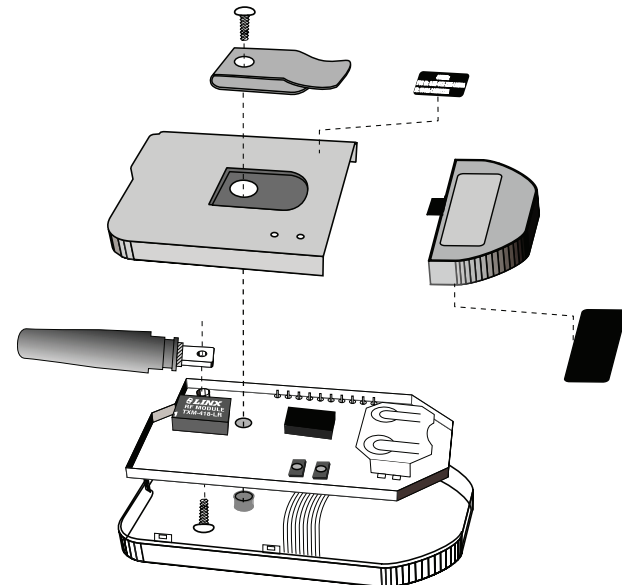


Figure 7: OTX-***-HH-LR8-MS Assembly

The Decoder Board

The decoder board included with the evaluation kit uses an LR Series receiver to receive the signal from the Handheld transmitter and then feeds it into an MS Series decoder. The board is designed to allow full access to the many features of the decoder and to speed development and integration of the LR and MS into a product. The following sections describe the features of this board in detail.

The Prototyping Area

The prototyping area on the decoder board contains a large section of plated through-holes so that external circuitry can be placed on the board. This circuitry can be interfaced with the MS Series decoder through the breakout header to the right of the holes. At the bottom of this area is a row connected to the 3V power supply and at the top is a row connected to ground.

All of the data lines are connected to a wire-wrap header to the right, allowing easy access from the prototyping area. The Decoder Data and TX ID lines are also available on the header as well as the PDN line from the RF module. This allows complete control of the entire system from the prototyping area, giving the designer a great deal of flexibility in using the board.

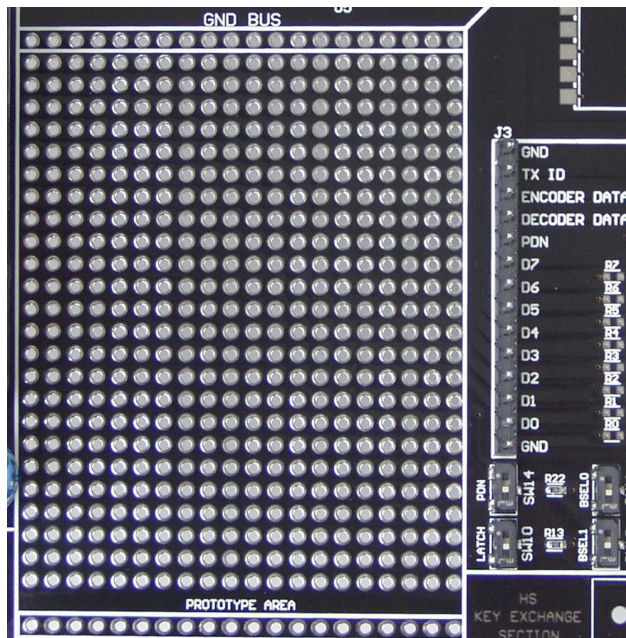


Figure 8: The Decoder Board Prototyping Area

The Power Supply

The power supply on the decoder board consists of a 9V battery and power jack connected to a 3.0V voltage regulator. It can provide approximately 500mA of current to the prototyping area, so if the added circuitry will need more than this, the designer must add an external supply. If the circuit consistently draws more than 100mA of current, it might be better to use the power jack rather than the battery, as the battery may run down fairly quickly, reducing testing and development time.

The jack accepts a standard 5.5mm plug with the tip ground and the outer shell 7 to 16VDC positive supply. While a reverse voltage protection diode has been included on the board to protect the circuitry in case the voltage on the plug is reversed, it is still a good idea to double-check the polarity.



Figure 9: The Decoder Board Power Supply Area

The RF Area

The Figure 10 shows the RF area of the development board. The board uses the LR Series receiver as shown. Attach the included antenna to the reverse polarity SMA connector before operation.

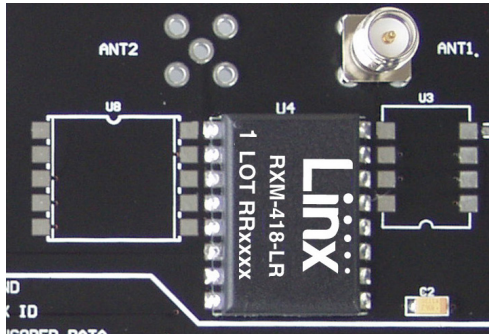


Figure 10: The Decoder Board RF Area

The Decoder Area

Figure 11 shows the decoder area of the development board.

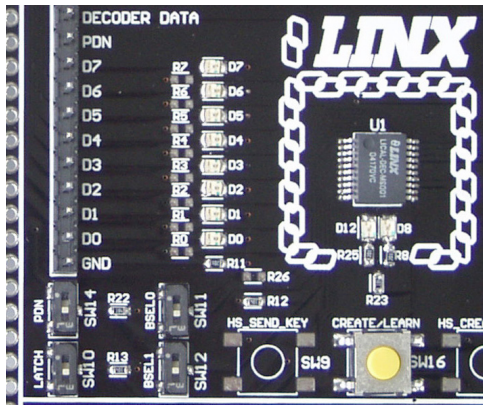


Figure 11: The Decoder Area

The decoder is in the center beneath the Linx logo. To the left are LEDs that are connected to the decoder data lines. These light up when the decoder receives a signal from the transmitter instructing it to take the data line high. LED D0 corresponds to data line D0 and so forth.

Beneath the decoder are two LEDs. D12 is connected to the MODE_IND line. D8 is connected to the RX_CNTL line and provides visual feedback by lighting up when the decoder activates the receiver when in RX Control Mode.

Under the LEDs is a button that is connected to the LEARN line. This button is used to learn the Code Word from the encoder as described in the MS Series Decoder Data Guide.

There are four switches to the left of the CREATE / LEARN button. BSEL0 and BSEL1 are used to set the baud rate of the decoder as shown in Figure 12. The Keyfob transmitter is set to 9,600bps, so BSEL0 should be on and BSEL1 should be off. If the switch is up, then the line is high (on); if down, then the line is low (off).

BSEL1	BSEL0	Baud Rate
0	0	2,400
0	1	9,600
1	0	19,200
1	1	28,800

Figure 12: Baud Rate Controls

Note: The decoder board must be set to the same baud rate as the transmitter in order for the signal to be received correctly.

The PDN switch connects the RX_CNTL line of the encoder to the PDN line of the receiver so that the RX Control Mode can be tested. This mode is described in the MS Series Decoder Data Guide.

The LATCH switch places the decoder into Latch Mode when on, so that the data lines go high when a valid signal is received and stay high until a second valid signal is received. If the switch is off, the data lines are momentary.

The USB Area

The decoder board has a Linx SDM-USB-QS-S USB module for use with the included development software. This module is powered by the USB bus, so it does not pull any current from the battery. Figure 13 shows this section.

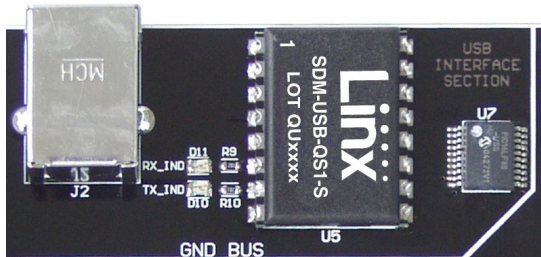


Figure 13: The Decoder Board USB Area

The microcontroller on the right monitors the data lines and generates commands that are sent to the development software on the PC via the QS Series USB module. The RX_IND LED to the left of the module flashes to indicate that data is being received from the PC, and the TX_IND line flashes to indicate that the module is sending data to the PC.

The QS Series USB module provides a simple serial link to a PC via a USB connection. It converts logic-level serial signals to USB-compliant signals and vice versa, so it can be connected to virtually any serial device, including microcontrollers, RS-232 / RS-485 level converters, or Linx RF modules. It is completely self-contained, requiring only a USB type B jack, and includes all necessary firmware and drivers.

Installing the Software and Drivers

The Master Development System uses the QS Series USB module to provide a simple serial interface to a PC via a USB connection. The module requires drivers to be installed on the PC before it can function properly. The QS Series Drivers are included on the CD with the software.

The first time the QS module is plugged into the computer, Windows displays the Found New Hardware Wizard, which guides the installation of the drivers. Application Note AN-00201 describes the installation of the drivers in detail. The drivers should be installed before running the Development Software.

The MS Master Development Software automatically starts when the CD is inserted and the player in Figure 14 appears.



Figure 14: Software Installer

Clicking the Install Software button starts the Installation Wizard, which guides the installation of the development software. The View Documentation button shows a list of the application notes and manuals related to the MS Series. Selecting one of these opens the file in Adobe Acrobat. The Play Movie button plays a short video about Linx on the Player Screen, which can be controlled with the Selection Keypad. Clicking the button on the bottom right of the player opens the Linx Technologies website in the computer's default browser.

The View Documentation list allows for the installation of Adobe Acrobat Reader so that the documents may be viewed. There is also the option of installing Flash, which may be required if the Linx video does not play correctly.

Master Development Software

This software is designed to give a complete understanding of how the MS Series encoders and decoders work together, as well as showing how they can be used in a system.

The Master Development software can be used in one of two modes. The default mode is a software simulation of the system and does not require any hardware. It simulates two handheld transmitters as well as two receiving devices. This is a good way of showing how the MS Series can work in a system by turning on lights and opening doors.

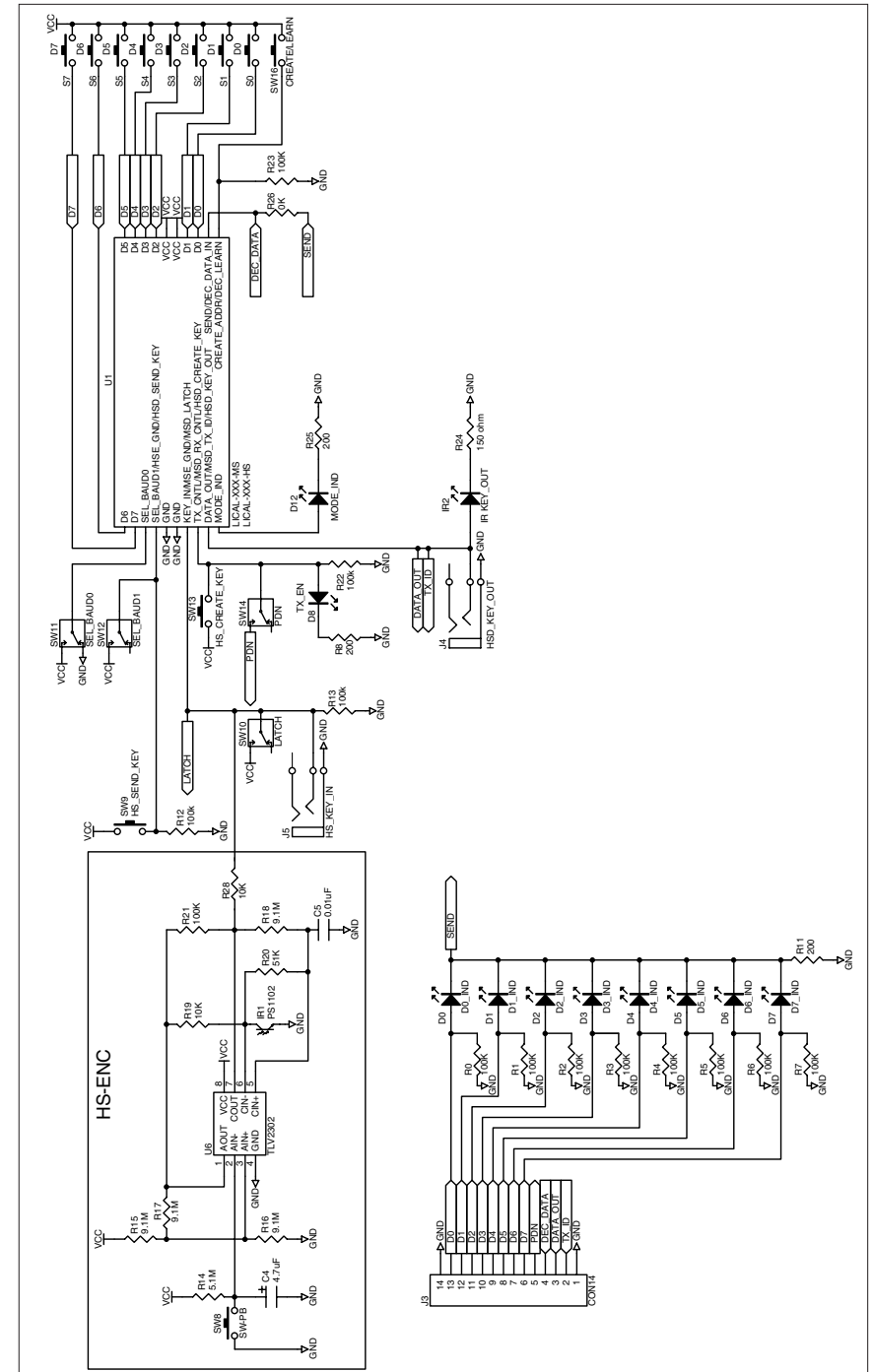
The second mode is for use with the Master Development System. When the decoder board is plugged into a USB port on the PC, the transmitter can be used to activate the features in the software. If the LEDs on the evaluation board turn on, then the LEDs in the program turn on and activate the corresponding data line function.

Figure 15 is a screen shot of the program set up in Software Operation Mode for simulating the operation of the system.



Figure 15: MS Encoder / Decoder Demonstration Software

The transmitters are on the right hand side and the receivers are at the bottom. Complete instructions for using the software can be found by clicking on the Help label at the top right of the window.





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