E3T

CSM_E3T_DS_E_14_1

Photoelectric Sensor with Built-in Amplifier Contributes to Equipment Downsizing

- Ultracompact and Thin Photoelectric Sensor with Built-in Amplifier
- ullet Easy optical axis adjustment with emitter fluctuation of $\pm 2\%$ max. for Through-beam Models.
- Product lineup includes Coaxial Retro-reflective Models that support positioning applications.
- Product lineup includes BGS* Reflective Models unaffected by background (E3T-FL1 -/-FL2 -).
- Product lineup of models with a variety of connection specifications.
 - (e.g., robot cable and Smartclick pre-wired connectors)
- * BGS (Background Suppression) technology prevents detecting background objects.





Be sure to read *Safety Precautions* on page 14.

Features

E3T-SR4 : Retro-reflective Sensor with Enhanced Compactness and High Performance

• Perform detection from a small hole.

With a coaxial optical system, the lens diameter is only 2 mm.

Sufficient incident light is obtained even through a small hole.

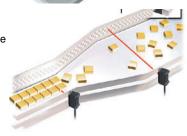
The Coaxial Retro-reflective Sensor can be used for reliable application with positioning.



• Improved Stability of Short-distance Detection

A detection distance as short as 10 mm can be used with a Tape Reflector.

Detection is stable through a hole whether the distance is 10 mm or 100 mm (except in combination with the E39-R4).

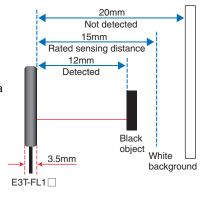


E3T-FL1□/-FL2□: The Slimmest BGS (Background Suppression) Reflective Photoelectric Sensors in the World

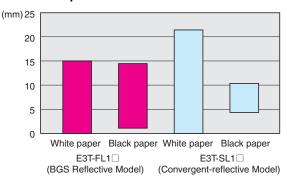
Ultra slim at 3.5 mm and black/white error of only 15%.

For example, the E3T-FL1 can stably detect a black object at 12 mm without being affected by a white background at 20 mm.

OMRON provides BGS performance sharper than the previous Convergent-reflective Sensors.



Dramatic Improvement in Black/White Error



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Ordering Information

Sensors (Refer to Dimensions on page 15.)

Red light

Sensing	Appea	rance	Connection	Sensing	Operation	Mod	del
method	Appea	irance	method	distance	mode	NPN output	PNP output
				1 m	Light-ON	E3T-ST11 2M *2 Emitter E3T-ST11-L 2M Receiver E3T-ST11-D 2M	E3T-ST13 2M *2 Emitter E3T-ST13-L 2M Receiver E3T-ST13-D 2M
		Side-view		(Sensitivity Adjustment Unit can be used.)	Dark-ON	E3T-ST12 2M *2 Emitter E3T-ST12-L 2M Receiver E3T-ST12-D 2M	E3T-ST14 2M *2 Emitter E3T-ST14-L 2M Receiver E3T-ST14-D 2M
	TT				Light-ON	E3T-ST21 2M *2 Emitter E3T-ST21-L 2M Receiver E3T-ST21-D 2M	E3T-ST23 2M *2 Emitter E3T-ST23-L 2M Receiver E3T-ST23-D 2M
Through-beam (Emitter +				300 mm	Dark-ON	E3T-ST22 2M *2 Emitter E3T-ST22-L 2M Receiver E3T-ST22-D 2M	E3T-ST24 2M *2 Emitter E3T-ST24-L 2M Receiver E3T-ST24-D 2M
Receiver) *1	in the second			500	Light-ON	E3T-FT11 2M Emitter E3T-FT11-L 2M Receiver E3T-FT11-D 2M	E3T-FT13 2M Emitter E3T-FT13-L 2M Receiver E3T-FT13-D 2M
		Flat		500 mm	Dark-ON	E3T-FT12 2M Emitter E3T-FT12-L 2M Receiver E3T-FT12-D 2M	E3T-FT14 2M Emitter E3T-FT14-L 2M Receiver E3T-FT14-D 2M
					Light-ON	E3T-FT21 2M Emitter E3T-FT21-L 2M Receiver E3T-FT21-D 2M	E3T-FT23 2M Emitter E3T-FT23-L 2M Receiver E3T-FT23-D 2M
				300 mm	Dark-ON	E3T-FT22 2M Emitter E3T-FT22-L 2M Receiver E3T-FT22-D 2M	E3T-FT24 2M Emitter E3T-FT24-L 2M Receiver E3T-FT24-D 2M
Retro-	2	Side-view	Pre-wired (2 m)	Using the E39-R4 Reflector provided 200 mm [30 mm] *4	Light-ON	E3T-SR41 2M *5	E3T-SR43 2M *5
reflective *3				Using the E39-R37-CA 100 mm [10 mm] *4	Dark-ON	E3T-SR42 2M *5	E3T-SR44 2M *5
Diffuse-	In the last	Flat			Light-ON	E3T-FD11 2M *2	E3T-FD13 2M *2
reflective				5 to 30 mm	Dark-ON	E3T-FD12 2M *2	E3T-FD14 2M *2
		Side-view		_	Light-ON	E3T-SL11 2M *2	E3T-SL13 2M *2
Convergent-	0			5 to 15 mm	Dark-ON	E3T-SL12 2M *2	E3T-SL14 2M *2
reflective					Light-ON	E3T-SL21 2M *2	E3T-SL23 2M *2
	T	Ĭ		5 to 30 mm	Dark-ON	E3T-SL22 2M *2	E3T-SL24 2M *2
		Flat			Light-ON	E3T-FL11 2M	E3T-FL13 2M
BGS				1 to 15 mm	Dark-ON	E3T-FL12 2M	E3T-FL14 2M
reflective					Light-ON	E3T-FL21 2M	E3T-FL23 2M
	T	П		1 to 30 mm	Dark-ON	E3T-FL22 2M	E3T-FL24 2M

^{*1.} Through-beam Sensors are normally sold in sets that include both the Emitter and Receiver.

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Orders or individual Emitters and Receivers are accepted. (Modifications are required for some models. Ask your OMRON representative for details.)

Orders for individual Emitters and Receivers are accepted. (Modifications are required for some models. As *2. M3 mounting models are also available. These models have the M-suffix. Example: E3T-ST11M 2M Contact your OMRON representative for detail.

*3. Ask your OMRON representative about the previous Retro-reflective Sensors: E3T-SR2□ and E3T-SR3□.

*4. Values in parentheses indicate the minimum required distance between the Sensor and Reflector.

*5. Models are available either with or without the E39-R37-CA Reflector included. Model with E39-R37-CA Reflector: E3T-SR4□-S Model without Reflector: E3T-SR4□-C

Variety of Connection Specifications

The models with the connection specifications marked with a black circle in the table are available. The model number indication is a combination of the basic model and the connection specification.

Example: E3T-ST11-M1TJ 0.3M

Connection Basic model number specification

NPN Output

	Model		Model number example	E3T-ST11-M1TJ 0.3M	E3T-ST11 5M	E3T-ST11R 2M	E3T-ST11-ECON 0.3M	E3T-ST11-ECON 2M
Sensing method	Sensing distance	Operation mode	Connection specification	M12 pre-wired Smartclick Con- nector (cable length: 0.3 m)	Pre-wired (cable length: 5 m)	Pre-wired robot (cable length: 2 m)	e-CON pre-wired connector (cable length: 0.3 m)	e-CON pre-wired connector (cable length: 2 m)
memod	uistance	illoue	Basic model number	-M1TJ 0.3M	5M	R 2M	-ECON 0.3M	-ECON 2M
	1 m Light-ON E3T-ST11		•	•	•	•	•	
Through- beam (side-	1 111	Dark-ON	E3T-ST12	•	•	•	•	•
view)	300 mm	Light-ON	E3T-ST21	•	•		•	•
	300 mm	Dark-ON	E3T-ST22	•	•		•	•
	500 mm	Light-ON	E3T-FT11	•	•	•	•	•
Through-	300 11111	Dark-ON	E3T-FT12	•	•	•	•	•
beam (flat)	300 mm	Light-ON	E3T-FT21	•			•	•
	300 11111	Dark-ON	E3T-FT22	•			•	•
Retro-	200 mm	Light-ON	E3T-SR41	•	•	•	•	•
reflective	(100 mm)	Dark-ON	E3T-SR42	•	•	•	•	•
Diffuse-	5 to	Light-ON	E3T-FD11	•	•	•	•	•
reflective	30 mm	Dark-ON	ON E3T-SR41	•	•	•	•	
	5 to	Light-ON	E3T-SL11	•	•	•	•	•
Convergent-	15 mm	Dark-ON	E3T-SL12	•	•	•	•	•
reflective	5 to	Light-ON	E3T-SL21	•	•	•	•	•
	30 mm	Dark-ON	E3T-SL22	•	•	•	•	•
	1 to	Light-ON	E3T-FL11	•		•		
BGS reflec-	15 mm	Dark-ON	E3T-FL12	•		•		
tive	1 to	Light-ON	E3T-FL21	•		•	•	
	30 mm	Dark-ON	E3T-FL22	•		•		

^{*} The sensing distance depends on the Reflector that is used. The sensing distance is 200 mm if an E39-R4 is used and 100 mm if an E39-R37-CA is used.

PNP Output

	Model		Model number example	E3T-ST13-M1TJ 0.3M	E3T-ST13 5M	E3T-ST13R 2M
Sensing method	Sensing distance	Operation mode	Connection specification	M12 pre-wired Smartclick Con- nector (cable length: 0.3 m)	Pre-wired (cable length: 5 m)	Pre-wired robot (cable length: 2 m)
	distance	mode	Basic model number	-M1TJ 0.3M 5M		R 2M
	1 m	Light-ON	E3T-ST13	•	•	•
Through-	1 111	Dark-ON	E3T-ST14	•	•	•
beam (side- view)	300 mm	Light-ON	E3T-ST23	•		
	300 mm	Dark-ON	E3T-ST24	•		
	F00	Light-ON	E3T-FT13	•	•	•
Through-	500 mm	Dark-ON	E3T-FT14	•	•	•
beam (flat)	000	Light-ON	E3T-FT23	•		
	300 mm	Dark-ON	E3T-FT24	•	•	

	Model		Model number example	E3T-ST13-M1TJ 0.3M	E3T-ST13 5M	E3T-ST13R 2M
Sensing method	Sensing distance	Operation mode	Connection specification	M12 pre-wired Smartclick Con- nector (cable length: 0.3 m)	Pre-wired (cable length: 5 m)	Pre-wired robot (cable length: 2 m)
metriod	distance	illoue	Basic model number	-M1TJ 0.3M	5M	R 2M
Retro- 200 mm		Light-ON	E3T-SR43	•	•	•
reflective	(100 mm)	Dark-ON	E3T-SR44	•	•	•
Diffuse-	5 to	Light-ON	E3T-FD13	•	•	•
reflective	30 mm	Dark-ON	E3T-FD14	•	•	•
	5 to	Light-ON	E3T-SL13	•	•	•
Convergent-	15 mm	Dark-ON	E3T-SL14	•	•	•
reflective	5 to	Light-ON	E3T-SL23	•	•	•
	30 mm	Dark-ON	E3T-SL24	•	•	•
	1 to	Light-ON	E3T-FL13	•		•
BGS reflec-	15 mm	Dark-ON	E3T-FL14	•		•
tive	1 to	Light-ON	E3T-FL23	•		•
	30 mm	Dark-ON	E3T-FL24	•		•

^{*} The sensing distance depends on the Reflector that is used. The sensing distance is 200 mm if an E39-R4 is used and 100 mm if an E39-R37-CA is used.

Accessories (Order Separately)

Slits (A Slit is not provided with the Sensor for through-beam. Order a Slit separately if required.) (Refer to Dimensions on page 18.)

Slit width	Sensing distance (typical) (Sensor model)	Minimum detectable object (typical)	Model	Quantity	Remarks	
0.5-mm dia.	100 mm (E3T-ST1□)	0.5-mm dia.				
0.5-mm dia.	30 mm (E3T-ST2□)	0.5-min dia.	E39-S63		Plug-in type round slits Can be used with E3T-ST	
1-mm dia.	300 mm (E3T-ST1□)	1-mm dia.	E39-303	One each for Emitter and	Through-beam Models.	
	100 mm (E3T-ST2□)	1-IIIII ula.		Receiver; common with Slit		
0.5-mm dia.	50 mm (E3T-FT1□)	0.5-mm dia.		widths of 1 dia. and 0.5 dia. (total of 2)	Division type yound elite	
0.0 mm dia.	30 mm (E3T-FT2□)	o.o min dia.	E39-S64	(total of 2)	Plug-in type round slits Can be used with E3T-FT Through-beam Models.	
1-mm dia.	100 mm (E3T-FT1□)	1-mm dia.	200 001			
i-iiiii ula.	50 mm (E3T-FT2□)	i-iiiii ula.				

Reflectors

(Requirement for retro-reflective: A Retroreflector is provided depending on the model number. Check the model number in remarks column.) (For Compact Reflectors, refer to *Dimensions* on page 17. For Tape Reflectors, refer to *E39-L/F39-L/E39-S.*)

Name	Recommended Sensor	Sensing distance	Minimum detectable object	Model	Quantity	Remarks	
Small	E3T-SR4□	200 mm (30 mm) *1	→ .	E39-R4		Provided with the E3T-SR4□	
Reflectors Tape Reflectors	E3T-SR4□-S	100 mm (10 mm) *1		E39-R37-CA *2	1	Provided with the E3T-SR4□-S	
			2-mm dia.	E39-RS1-CA *2		Use Tape Reflectors in combina-	
	E3T-SR4□-C	100 mm (10 mm) *1		E39-RS2-CA *2		tion with the E3T-SR4□-C, which	
Tichectors				E39-RS3-CA *2		does not come with a Reflector.	

^{*1.} Values in parentheses indicate the minimum required distance between the Sensor and Reflector.

Sensitivity Adjustment Unit

(A Unit is not provided with the Sensor (for the E3T-ST1□). Order a Unit separately if required.

(Refer to Dimensions on page 18.)

Appearance	Sensing distance (typical)	Model	Quantity	Remarks
	300 to 800 mm	E39-E10	1	Can be used with the E3T-ST1□ Through-beam Models.

Mounting Brackets

A Mounting Bracket is not provided with the Sensor. Order a Mounting Bracket separately if required. (Refer to *Dimensions* on page 18.)

Appearance	Model	Quantity	Remarks
	E39-L116		Can be used with the
	E39-L117		E3T-S Side-view Models. (A securing nut plate is provided with the
	E39-L118	1	Mounting Bracket.)
	E39-L119		Can be used with the
6	E39-L120		E3T-F

Note: When using Through-beam models, order one bracket for the Receiver and one for the Emitter.

Set of Mounting Screws A Set is provided with the Sensor.

Applicable sensors	Model	Description	Material	Quantity	Remarks
Side-view models E3T-S□□□	E39-L164	Phillips screws (M2 × 14) Hexagonal nuts (M2) Spring washers (M2) Flat washers (M2)	Iron, zinc plating Iron, zinc plating Iron, nickel plating Iron, zinc plating	2 for each	Provided with the side-view models E3T-S□□□.
Flat models E3T-F□□□	E39-L165	Phillips screws (M2 × 8) Hexagonal nuts (M2) Spring washers (M2) Flat washers (M2)	Iron, zinc plating Iron, zinc plating Iron, nickel plating Iron, zinc plating	2 101 GaUI	Provided with the flat models E3T-F□□□.

Note: If a Through-beam Model is used, order two sets of Mounting Screws, one for the Emitter and one for the Receiver.

Used for mounting sensors. Order the set separately if it becomes lost or damaged.

These screws are not used for mounting brackets to the equipment.

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^{*2.} The E3T-SR4□ cannot be used with the E39-R37 or E39-RS1/2/3 (without CA) Tape Reflectors. The E39-□-CA Reflector is for use only with the E3T-SR4□. It cannot be used with other Sensors.

Sensor I/O Connectors

(Models with Pre-wired Connectors: A Connector is not provided with the Sensor. Be sure to order a Connector separately.) (For M12, refer to XS5. For e-CON, contact your OMRON representative.)

Size	Cable	Appearance	Cable t	type	Model	
M12 (For-M1TJ	Standard	Straight	2 m	4-wire	XS5F-D421-D80-A	
models)	Standard	on alignment of the control of the c	5 m	4-WIIC	XS5F-D421-G80-A	
	Connector on one end	2 m		E39-ECON2M		
			5 m		E39-ECON5M	
e-CON	Standard cable	Connector on both ends	0.5 to 1 m	4-wire	E39-ECONW□M	
			1.1 to 1.5 m		Replace with the cable length in	
		287	1.6 to 2 m		0.1-m increments.	

Note: When using Through-beam models, order one connector for the Receiver and one for the Emitter.

Ratings and Specifications

			Throug	jh-beam		Retro-reflective func			
		Side	-view	F	lat	Functions Side-NPN	view		
Sensing me	ethod	NPN	PNP	NPN	PNP	NPN	PNP		
_		E3T-ST11 E3T-ST12 E3T-ST21 E3T-ST22	E3T-ST13 E3T-ST14 E3T-ST23 E3T-ST24	E3T-FT11 E3T-FT12 E3T-FT21 E3T-FT22	E3T-FT13 E3T-FT14 E3T-FT23 E3T-FT24		E3T-SR43 E3T-SR44		
Sensing di	stance	E3T-ST1□ E3T-ST2□	1 m 300 mm	E3T-FT1□ E3T-FT2□	500 mm 300 mm	200 mm (30 mm) (Using the E39-R4) ing the E39-R37-CA)		
Standard s	ensing object	Opaque, 2-mm dia	ı. min.	Opaque, 1.3-mm	dia. min.	Opaque, 27-mm di	a. min.		
Minimum d		2-mm dia opaque	object	1.3-mm dia opaqı	ue object		of 100 mm)		
Hysteresis	(white paper)			1		1	P-mm dia. sensing distance of 100 mm) To to 20° To mA max. The max and the max are the		
Black/white	e error								
Directional	angle	Emitter: 2° to 20°,	Receiver: 2° to 70°	Emitter: 3° to 25°	, Receiver: 3° min.	2° to 20°			
Light sourc	e (wavelength)	Red LED ("Pin-poi	nt" LED) λ = 650 nr	n		1			
Power supp	ly voltage	12 to 24 VDC ±109	%, ripple (p-p) 10%	max.					
Current con	sumption	30 mA max. (Emitt	er 10 mA max., Re	ceiver 20 mA max.)	l .	20 mA max.			
Control out	tput	Load current: 50 mA Open-collector out		e: 2 V max. for load cu	urrent of 10 to 50 mA, 1 3T-□□□2 and E3T-		nt of less than 10 mA)		
Protection	circuits	Power supply and Output short-circui	control output reve t protection	rse polarity protecti	on	verse polarity prote Output short-circuit	ection protection, Mutual		
Response	time	Operate or reset: 1	l ms max.						
Ambient illu	umination	Incandescent lamp	o: 5,000 lx max.,	Sunlight: 10,000) lx max.				
Ambient ten	nperature range	Operating: -25 to	55°C	Storage: -40 to	70°C (with no icing	or condensation)			
Ambient hu	umidity range	Operating: 35% to	85%	Storage: 35% to	95% (with no cond	lensation)			
Insulation r	esistance	20 MΩ min. at 500	VDC						
Dielectric s	strength	1,000 VAC, 50/60	Hz for 1 min						
Vibration re	esistance	Destruction: 10 to	2,000 Hz, 1.5-mm	double amplitude or	300 m/s ² for 0.5 hrs	s each in X, Y, and Z	directions		
Shock resi	stance	Destruction: 1,000	m/s² 3 times each	in X, Y, and Z direc	tions				
Degree of p	rotection	IP67 (IEC60529)							
Connection	n method	Pre-wired (standar	d length: 2 m)						
Weight		Approx. 40 g				Approx. 20 g			
	Case	PBT (polybutylene	terephthalate)						
Materials	Display window	Denatured polyary	late						
	Lens	Denatured polyary				Methacrylic resin			
Accessorie	es				/ Models: M2 × 14, F 37-CA (E3T-SR4⊟-	Flat Models: M2 × 8), S only)	, Nuts, Spring		

^{*}Values in parentheses indicate the minimum required distance between the Sensor and Reflector.

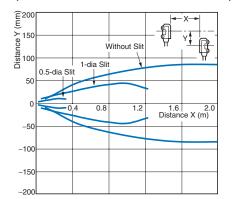
		Diffuse-r	eflective		Converger	t-reflective			BGS re	flective	
		FI	at		Side	-view			FI	at	
C	اد حاله د	NPN	PNP	NPN	PNP	NPN	PNP	NPN	PNP	NPN	PNP
Minimum de object (typic object (typic object (typic object (typic object objec	etnoa	E3T-FD11 E3T-FD12	E3T-FD13 E3T-FD14	E3T-SL11 E3T-SL12	E3T-SL13 E3T-SL14	E3T-SL21 E3T-SL22	E3T-SL23 E3T-SL24	E3T-FL11 E3T-FL12	E3T-FL13 E3T-FL14	E3T-FL21 E3T-FL22	E3T-FL23 E3T-FL24
Sensing di	stance	5 to 30 mm 5 to 15 r (50 × 50 mm white paper) (50 × 50 paper)			mm white $(50 \times 50 \text{ mm white})$ (50			1 to 15mm (50 × 50 m paper)		1 to 30mm (50 × 50 m paper)	
Standard s	ensing object										
		0.15-mm d	15-mm dia. (sensing distance of 10 mm) 0.15-mm dia non-glossy object (sensing distance of 10 mm)								
Hysteresis	(white paper)	6 mm max	-	2 mm max		6 mm max		0.5 mm ma	ax.	2 mm max	-
Black/white	e error					•		15% max.			
Directional	angle										
Light source	e (wavelength)	Red LED ("Pin-point" L	.ED) λ = 65	0 nm						
Power supp	ly voltage	12 to 24 VI	DC ±10%, ri	pple (p-p) 1	0% max.						
Current con	sumption	20 mA max	Κ.								
Control ou	tput	Load curren Open-colle	er supply vol t: 50 mA max ector output E3T-□□□1	. (residual vo	ltage: 2 V ma	x. for load cu Dark ON: E3		,	ax. for load c	urrent of less	than 10 mA)
Protection	circuits		ply and conf ort-circuit pro								
Response	time	Operate or	reset: 1 ms	max.							
Ambient ille	umination	Incandesce	ent lamp: 5,0	000 lx max.	Sunli	ght: 10,000	lx max.				
Ambient ten	nperature range	Operating:	–25 to 55°)	Stora	ige: -40 to	70°C (with r	no icing or c	ondensation	1)	
Ambient h	umidity range	Operating:	35% to 85%	6	Stora	ige: 35% to	95% (with I	no condens	ation)		
Insulation r	esistance	20 MΩ min	. at 500 VD	С							
Dielectric s	strength	1,000 VAC	, 50/60 Hz f	or 1 min							
Vibration re	esistance	Destruction	n: 10 to 2,00	0 Hz, 1.5-m	ım double a	mplitude or	300 m/s ² fo	r 0.5 hrs eac	ch in X, Y, a	nd Z direction	ons
Shock resi	stance	Destruction	n: 1,000 m/s	² 3 times ea	ach in X, Y,	and Z direct	ions				
Degree of p	rotection	IP67 (IEC6	60529)								
Connection	n method	Pre-wired (standard le	ngth: 2 m)							
Weight	_	Approx. 20	prox. 20 g								
	Case	PBT (polyb	outylene tere	phthalate)							
Materials	Display window	Denatured	polyarylate								
	Lens	Denatured	polyarylate								
Accessorie	es		manual, Ins lat washers	tallation Ph	illips screws	(Side-view	Models: M2	2×14 , Flat I	Models: M2	× 8), Nuts, S	Spring

Engineering Data (Typical)

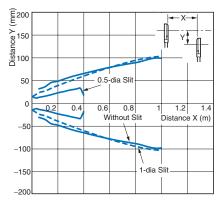
Parallel Operating Range

Through-beam

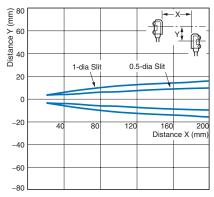
E3T-ST1□ + E39-S63 Slit (Order Separately) (A Slit is mounted to the Emitter and Receiver.)



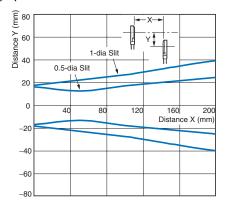
E3T-FT1 → + E39-S64 Slit (Order Separately) (A Slit is mounted to the Emitter and Receiver.)



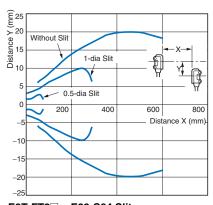
E3T-ST1 + E39-S63 Slit (Order Separately) (Enlarged graph) (A Slit is mounted to the Emitter and Receiver.)



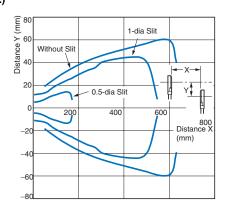
E3T-FT1□ + E39-S64 Slit (Order Separately) (Enlarged graph) (A Slit is mounted to the Emitter and Receiver.)



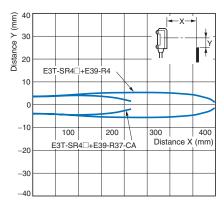
E3T-ST2□ + E39-S63 Slit (A Slit is mounted to the Emitter and Receiver.)



E3T-FT2 \square + E39-S64 Slit (A Slit is mounted to the Emitter and Receiver.)



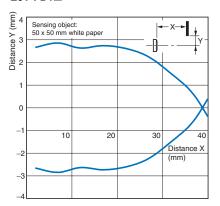
Retro-reflective E3T-SR4□



Operating Range

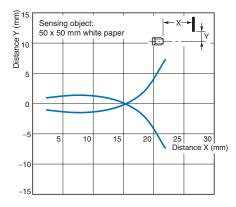
Diffuse-reflective

E3T-FD1□

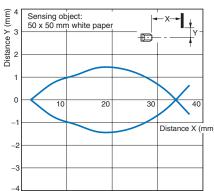


Convergent-reflective

E3T-SL1□

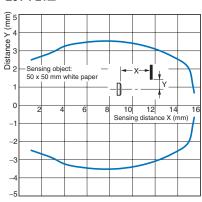


E3T-SL2□

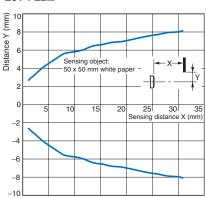


BGS Reflective

E3T-FL1□



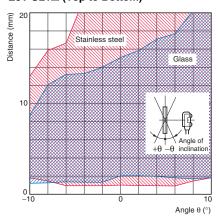
E3T-FL2



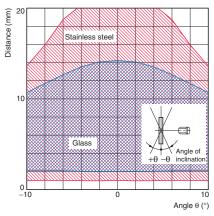
Inclination Detection Area Characteristic

Convergent-reflective

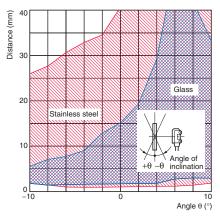
E3T-SL1□ (Top to Bottom)



E3T-SL1□ (Right to Left)



E3T-SL2□ (Top to Bottom)



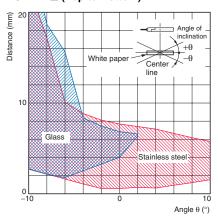
E3T-SL2□ (Right to Left)

Distance (mm) 00 00 Stainless steel Angle of $+\theta - \theta$ inclination Glass

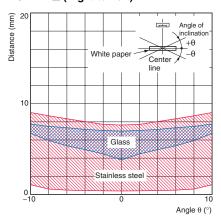
Angle θ (°)

BGS Reflective

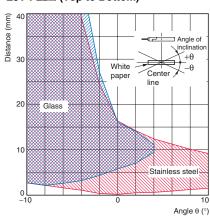
E3T-FL1□ (Top to Bottom)



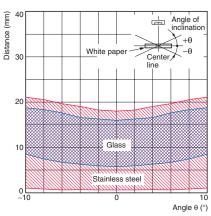
E3T-FL1□ (Right to Left)



E3T-FL2□ (Top to Bottom)

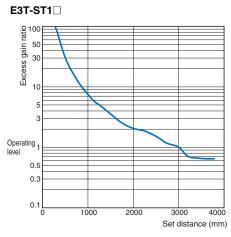


E3T-FL2□ (Right to Left)

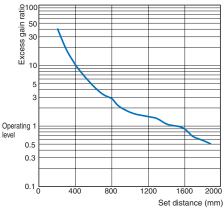


Excess Gain vs. Set Distance

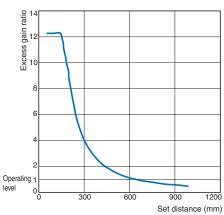
Through-beam

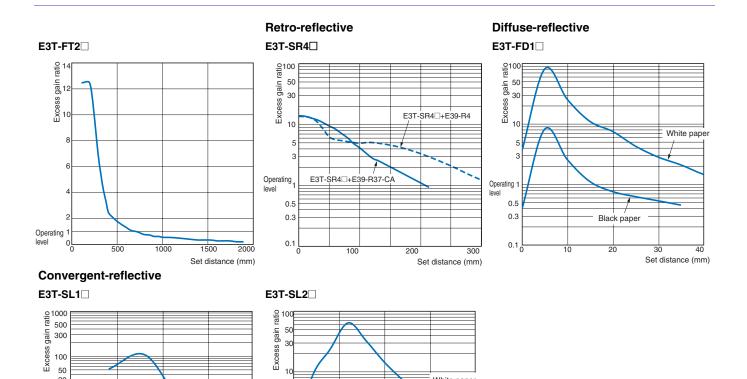






E3T-ST2□





Set distance (mm) **Sensing Object Size vs. Sensing Distance**

Black paper

10

White paper

Operating 1

0.5

0.3

0.1 L

Convergent-reflective

E3T-SL1□

30

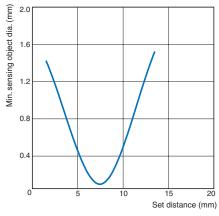
10

Operating 1 level

0.5

0.3

0.1



Diffuse-reflective, Convergent-reflective

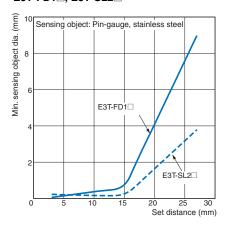
Black pape

White paper

Set distance (mm)

E3T-FD1 \square , E3T-SL2 \square

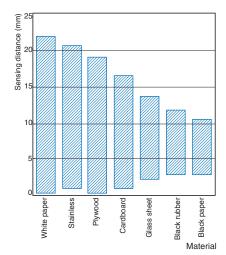
10



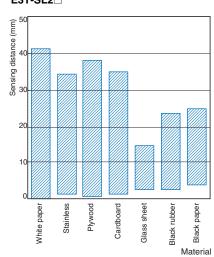
Sensing Distance vs. Material

Convergent-reflective

E3T-SL1□

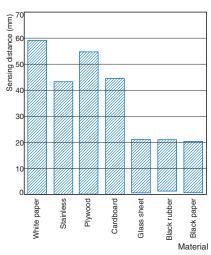


E3T-SL2□



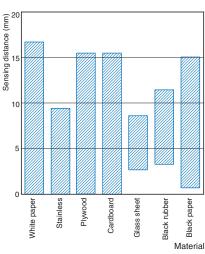
Diffuse-reflective

E3T-FD1□

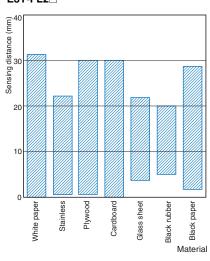


BGS Reflective

E3T-FL1□

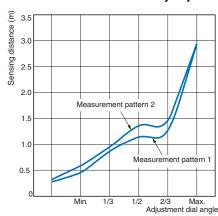


E3T-FL2□



Sensing Distance Characteristics of Sensitivity Adjustment Unit (when Completing Optical Axis Adjustment)

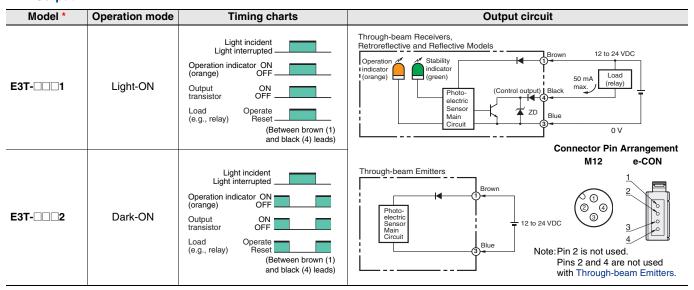
E3T-ST1□ + E39-E10 Sensitivity Adjustment Unit (Order Separately) for Emitter



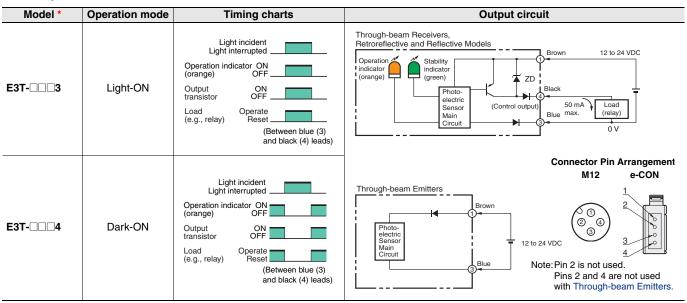
12

I/O Circuit Diagrams

NPN Output



PNP Output

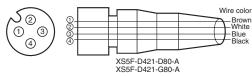


^{*} Models numbers for Through-beam Sensors (E3T- \Box T \Box) are for sets that include both the Emitter and Receiver.

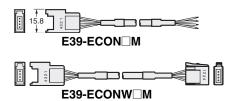
The model number of the Emitter is expressed by adding "-L" to the set model number (example: E3T-ST11-L 2M), the model number of the Receiver, by adding "-D" (example: E3T-ST11-D 2M.) Refer to *Ordering Information* to confirm model numbers for Emitter and Receivers.

Plugs (Sensor I/O Connectors)

M12 Connector



e-CON connector



Pin arrangement

Classification	Wire color	Connector pin No.	Application
DC	Brown	1	Power supply (+V)
	White	2	
	Blue	3	Power supply (0 V)
	Black	4	Output

Note: Pin 2 is not used.

13

Safety Precautions

Refer to Warranty and Limitations of Liability.



This product is not designed or rated for ensuring safety of persons. Do not use it for such purpose.



Do not apply AC power to the E3T, otherwise the E3T may rupture.



Precautions for Correct Use

Do not use the product in atmospheres or environments that exceed product ratings.

Wiring

The maximum power supply voltage is 24 VDC +10%. Before turning the power ON, make sure that the power supply voltage is not more than maximum voltage.

Load short-circuit protection

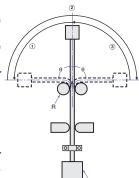
The E3T incorporates a load short-circuit protection function. If the load short-circuits, the output of the E3T will be turned OFF. Then, recheck the wiring and turn on the E3T again to reset the load short-circuit protection function. The load short-circuit protection function will work if there is a current flow that is 1.5 times larger than the rated load current. When using a capacitance load, be sure that the inrush current will not exceed 1.5 times larger than the rated current.

Mounting

When mounting the Sensor, never strike it with a heavy object, such as a hammer. Doing so may reduce its watertight properties. Use M2 screws and flat or spring washers to secure the Sensor. (Tightening torque: 0.15 N·m max.)

Mounting the Sensor on Moving Parts

Consider models that use break resistant cables (e.g., Robotics Cables) if the Sensor will be mounted on a moving part, such as a robot hand. The flexing resistance of Robotics Cable at approximately 400 thousand times is far superior to that of standard cable at approximately 14 thousand times.



Cable Bending Rupture Test (Tough Cable Breaking Test)

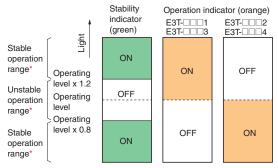
The cable is repeatedly bent with power supplied to check the number of bends until the current is turned OFF.

Test	Specimen	Standard cable 2.4-mm dia. (7/0.127-mm dia.), 3 conductors	Robotics cable 2.4-mm dia. (20/0.08-mm dia.), 3 conductors	
	Bending angle (θ)	90° each to the left	and right	
Contents/conditions	Bending speed	50 times/min		
	Load	200 g		
	Operation per bend	Once in 1 to 3 in the diagram		
	Curvature radius of support point (R)	5 mm		
Result		Approx. 14,000 times	Approx. 400,000 times	

Adjusting

Indicators

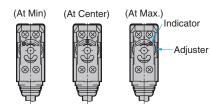
- The following graphs indicate the status of each operating level.
- Be sure to use the E3T within the stable operating range.



*If the E3T fs operating level is set to the stable operation range, the E3T will be in most reliable operation without being influenced by temperature change, voltage fluctuation, dust, or setting change. If the operating level cannot be set to the stable operation range, pay attention to environmental changes while operating the E3T.

Use of E39-E10 Sensitivity Adjustment Unit

(Dark-ON: E3T-ST12)



- 1. Mount the Unit on the Receiver.
- 2. Set the adjuster of the Sensitivity Adjustment Unit to Max. (Before shipping: Max.)
- After mounting on the Sensor, adjust the optical axis and secure the Sensor.
- 4. Place a workpiece between the Emitter and Receiver and gradually turn the adjuster counterclockwise toward the Min. side. Stop turning the adjuster when the operation indicator and stability indicator (green) turn ON.
- Remove the workpiece and confirm that the operation indicator is OFF and the stability indicator (green) is ON. This completes the adjustment.

Note: If the light attenuation rate due to a workpiece is 40% or less, the stability indicator will not turn ON whether or not light is received. When the variation of light is small such as when sensing semi-transparent workpieces, carefully perform preliminary testing.

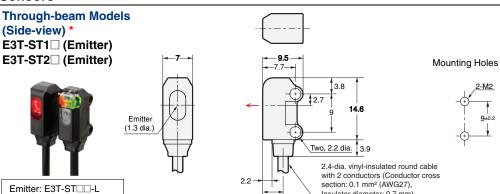
Others

Do not install the E3T in the following locations.

- Locations subject to excessive dust or dirt
- Locations subject to direct sunlight
- Locations subject to corrosive gas
- Locations subject to contact with organic solvents
- Locations subject to vibration and shock
- Locations subject to contact with water, oil, or chemicals
- Locations subject to high humidities that might result in condensation

Dimensions





E3T-ST1 (Receiver) E3T-ST2□ (Receiver)

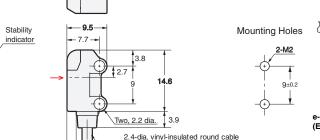
> Operation Indicator

> > (1.3 dia.)

Receiver: E3T-ST□□-D

ction: 0.1 mm² (AWG27) Insulator diameter: 0.7 mm), Standard length: 2 m

M12 Smartclick Pre-wired Connector Model (E3T-ST□□-M1TJ)

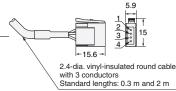


Standard length: 2 m

with 3 conductors (Conductor cross section: 0.1 mm² (AWG27), Insulator diameter: 0.7 mm),

2.4-dia. vinyl-insulated round cable with 2 or 3 conductors Standard length: 0.3 m

e-CON Pre-wired Connector Model (E3T-ST□□-ECON)

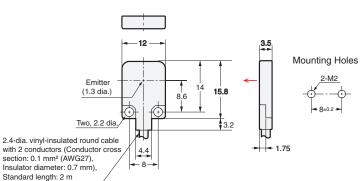


Through-beam Models (Flat) *

E3T-FT1 (Emitter) E3T-FT2□ (Emitter)



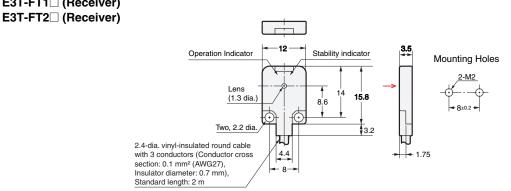
Receiver: E3T-FT□□-D E3T-FT1 (Receiver)



4.8

Termi- nal No.	Specifica- tions	
1	+V	
2		
3	0 V	
4	Output (receiver only)	

Refer to Mounting the Sensor on Moving Parts on page 14 for details on Robotics Cable models.



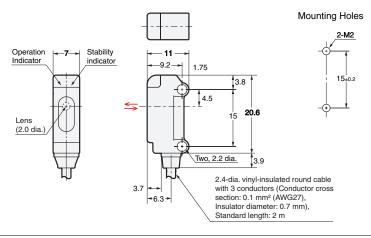
^{*} Models numbers for Through-beam Sensors (E3T-\(\pi \) are for sets that include both the Emitter and Receiver.

The model number of the Emitter is expressed by adding "-L" to the set model number (example: E3T-ST11-L 2M), the model number of the Receiver, by adding "-D" (example: E3T-ST11-D 2M.) Refer to Ordering Information to confirm model numbers for Emitter and Receivers.

Retro-reflective Models (Side-view)







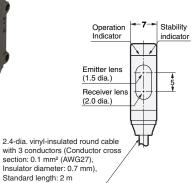
M12 Smartclick Pre-wired Connector Model (E3T-SR -- M1TJ/E3T-SL -- M1TJ/ E3T-FD -- M1TJ)

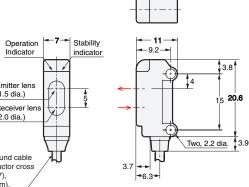


Convergent-reflective Models (Side-view)

E3T-SL1 E3T-SL2□

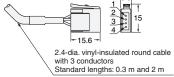






Mounting Holes

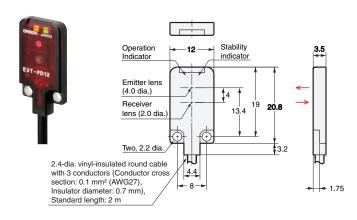




Terminal No.	Specifi- cations
1	+V
2	
3	0 V
4	Output

Diffuse-reflective Models (Flat)

E3T-FD1□



* Refer to Mounting the Sensor on Moving Parts on page 14 for details on

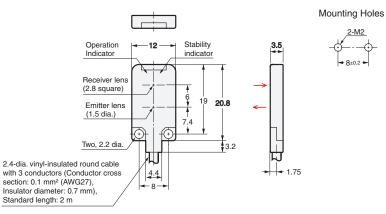
Mounting Holes

Robotics Cable models.

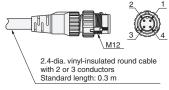
BGS Models (Flat)

E3T-FL1□ E3T-FL2

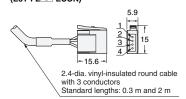




M12 Smartclick Pre-wired Connector Model (E3T-FL□□-M1TJ)



e-CON Pre-wired Connector (E3T-FL□□-ECON)



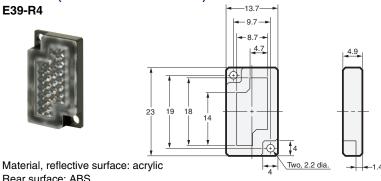
Termi- nal No.	Specifi- cations
1	+V
2	
3	0 V
4	Output

^{*} Refer to Mounting the Sensor on Moving Parts on page 14 for details on Robotics Cable models.

Accessories

Reflector (Provided with E3T-SR4□)

E39-R4

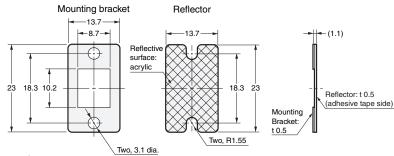


Rear surface: ABS

Reflector (Provided with E3T-SR4□-S)

E39-R37-CA





Material: Mounting plate: stainless steel

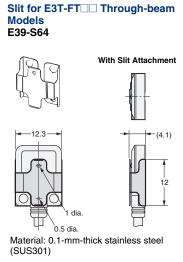
(SUS301)

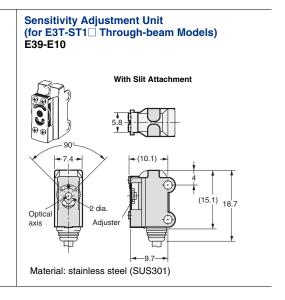
Reflective surface: acrylic

Note: The reflective plate and mounting plate (1) come as a set.

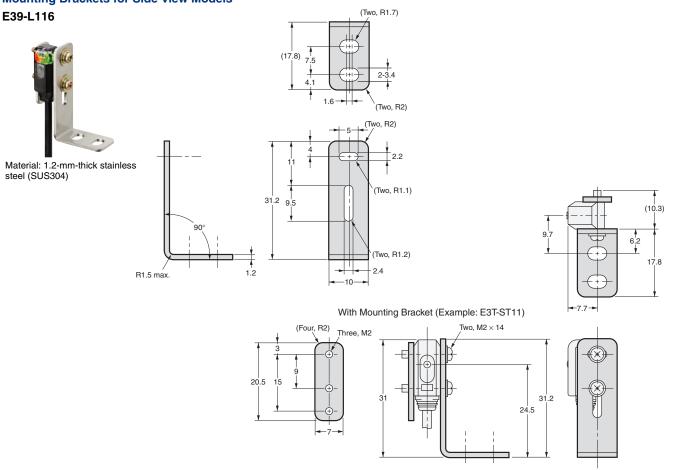
Accessories (Order Separately)

Slit for E3T-ST Through-beam Models E39-S63 With Slit Attachment With Slit Attachment O.5±0.05 dia. Note: Align the notch direction of the Slit when installing on the Emitter and Receiver.





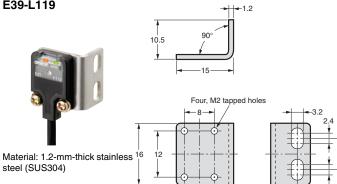
Mounting Brackets for Side-view Models

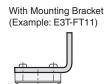


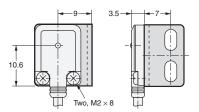
Mounting Brackets for Side-view Models E39-L117 R1 max (Two, R1.7) (Two, R2) Material: 1.2-mm-thick stainless steel (SUS304) (23) (10.3) (Two, R1.7) **-**5**-**(Two, R1.1) -10-**←** (11.2) **→** 7.7 - 6.2 With Mounting Bracket (Example: E3T-ST11) Two, M2 × 14 (Four, R2) —11.2 — Three, M2 **Mounting Brackets for Side-view Models** E39-L118 22.7 (Two, R1.7) Material: 1.2-mm-thick stainless steel (SUS304) 2-2.2 **45**► (Two, R1.1) (Four, R2) With Mounting Bracket (Example: E3T-ST11) (Four, R2) Two, M2 × 14 Three, M2 20.5

Mounting Brackets for Flat Models

E39-L119

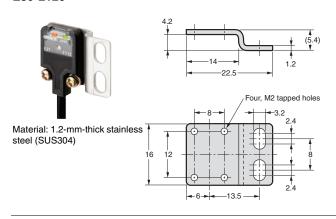






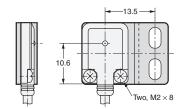
Mounting Brackets for Flat Models

E39-L120



With Mounting Bracket (Example: E3T-FT11)





Read and Understand This Catalog

Please read and understand this catalog before purchasing the products. Please consult your OMRON representative if you have any questions or comments.

Warranty and Limitations of Liability

WARRANTY

OMRON's exclusive warranty is that the products are free from defects in materials and workmanship for a period of one year (or other period if specified) from date of sale by OMRON.

OMRON MAKES NO WARRANTY OR REPRESENTATION, EXPRESS OR IMPLIED, REGARDING NON-INFRINGEMENT, MERCHANTABILITY, OR FITNESS FOR PARTICULAR PURPOSE OF THE PRODUCTS. ANY BUYER OR USER ACKNOWLEDGES THAT THE BUYER OR USER ALONE HAS DETERMINED THAT THE PRODUCTS WILL SUITABLY MEET THE REQUIREMENTS OF THEIR INTENDED USE. OMRON DISCLAIMS ALL OTHER WARRANTIES, EXPRESS OR IMPLIED.

LIMITATIONS OF LIABILITY

OMRON SHALL NOT BE RESPONSIBLE FOR SPECIAL, INDIRECT, OR CONSEQUENTIAL DAMAGES, LOSS OF PROFITS OR COMMERCIAL LOSS IN ANY WAY CONNECTED WITH THE PRODUCTS, WHETHER SUCH CLAIM IS BASED ON CONTRACT, WARRANTY, NEGLIGENCE, OR STRICT

In no event shall the responsibility of OMRON for any act exceed the individual price of the product on which liability is asserted.

IN NO EVENT SHALL OMRON BE RESPONSIBLE FOR WARRANTY, REPAIR, OR OTHER CLAIMS REGARDING THE PRODUCTS UNLESS OMRON'S ANALYSIS CONFIRMS THAT THE PRODUCTS WERE PROPERLY HANDLED, STORED, INSTALLED, AND MAINTAINED AND NOT SUBJECT TO CONTAMINATION, ABUSE, MISUSE, OR INAPPROPRIATE MODIFICATION OR REPAIR.

Application Considerations

SUITABILITY FOR USE

OMRON shall not be responsible for conformity with any standards, codes, or regulations that apply to the combination of products in the customer's application or use of the products.

At the customer's request, OMRON will provide applicable third party certification documents identifying ratings and limitations of use that apply to the products. This information by itself is not sufficient for a complete determination of the suitability of the products in combination with the end product, machine, system, or other application or use.

The following are some examples of applications for which particular attention must be given. This is not intended to be an exhaustive list of all possible uses of the products, nor is it intended to imply that the uses listed may be suitable for the products:

- Outdoor use, uses involving potential chemical contamination or electrical interference, or conditions or uses not described in this catalog.
- Nuclear energy control systems, combustion systems, railroad systems, aviation systems, medical equipment, amusement machines, vehicles, safety equipment, and installations subject to separate industry or government regulations.
- Systems, machines, and equipment that could present a risk to life or property.

Please know and observe all prohibitions of use applicable to the products.

NEVER USE THE PRODUCTS FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCTS ARE PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

PROGRAMMABLE PRODUCTS

OMRON shall not be responsible for the user's programming of a programmable product, or any consequence thereof.

Disclaimers

CHANGE IN SPECIFICATIONS

Product specifications and accessories may be changed at any time based on improvements and other reasons.

It is our practice to change model numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the products may be changed without any notice. When in doubt, special model numbers may be assigned to fix or establish key specifications for your application on your request. Please consult with your OMRON representative at any time to confirm actual specifications of purchased products.

DIMENSIONS AND WEIGHTS

Dimensions and weights are nominal and are not to be used for manufacturing purposes, even when tolerances are shown.

PERFORMANCE DATA

Performance data given in this catalog is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of OMRON's test conditions, and the users must correlate it to actual application requirements. Actual performance is subject to the OMRON Warranty and Limitations of Liability.

ERRORS AND OMISSIONS

The information in this document has been carefully checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical, or proofreading errors, or omissions.

2010.11

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