

## LM3280 Adjustable Step-Down DC-DC Converter and 3 LDOs for RF Power Management

Check for Samples: [LM3280](#)

### FEATURES

- 2MHz (typ.) PWM Switching Frequency
- Operates from a Single Li-Ion Cell (2.7V to 5.5V)
- Adjustable Output Voltage (0.8V to 3.6V) DC-DC
- High-Efficiency Synchronous Buck Converter
- 300mA Maximum Load Capability (PWM Mode)
- 500mA Maximum Load Capability (Bypass mode)
- PWM, Forced and Automatic Bypass Mode
- 3 Low-Dropout and Fast Transient Response LDOs
- 16-pin DSBGA Package
- Current Overload Protection
- Thermal Overload Protection

### APPLICATIONS

- Cellular Phones
- Hand-Held Radios
- Battery Powered RF Devices

### Typical Application

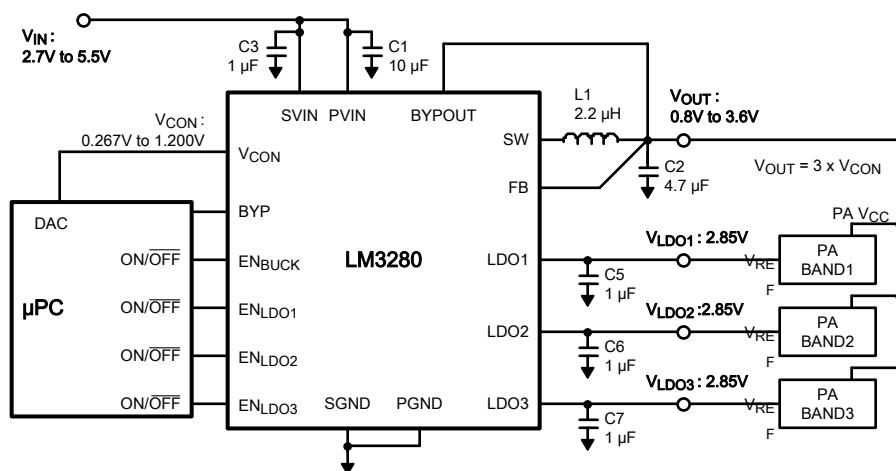


Figure 1. LM3280 Typical Application

### DESCRIPTION

The LM3280 is a multi-functional Power Management Unit, optimized for low-power handheld applications such as Cellular Phones.

The LM3280 incorporates three low-dropout LDO voltage regulators and one step down PWM DC-DC converter with an internal Bypass FET. The step down converter's output voltage can be set using an analog input ( $V_{CON}$ ) for optimizing efficiency of the RF PA at various power levels. The LDO operates a nominal output voltage of 2.85V and maximum load current capability of 20mA for a reference voltage required by linear RF power amplifiers. The LM3280 additionally features a separate enable pin for each output.

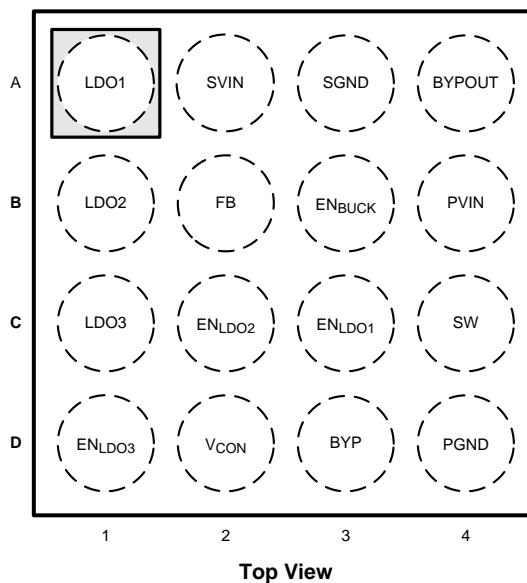
The LM3280 is available in a 16-pin lead free DSBGA package.



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## Connection Diagrams



**Figure 2. 16-Bump DSBGA Package, Large Bump**  
See Package Number YZR0016QQA

### Pin Descriptions

Pin #	Name	Description
A1	LDO1	LDO1 Output.
B1	LDO2	LDO2 Output.
C1	LDO3	LDO3 Output.
D1	EN <sub>LDO3</sub>	LDO3 Enable Input. Set this digital input high to turn on LDO3. (EN <sub>BUCK</sub> pin must be also set high.) For turning LDO3 off, set low.
A2	SVIN	Analog, Signal, and LDO Supply Input.
B2	FB	Buck Converter Feedback Analog Input. Connect to the output at the output filter capacitor.
C2	EN <sub>LDO2</sub>	LDO2 Enable Input. Set this digital input high to turn on LDO2. (EN <sub>BUCK</sub> pin must be also set high.) For turning LDO2 off, set low.
D2	V <sub>CON</sub>	Buck Converter Voltage Control Analog Input. This pin controls V <sub>OUT</sub> in PWM mode. Set: V <sub>OUT</sub> = 3 x V <sub>CON</sub> . Do not leave floating.
A3	SGND	Analog, Signal, and LDO Ground.
B3	EN <sub>BUCK</sub>	Buck Converter Enable Input. Set this digital input high after Vin >2.7V for normal operation. For shutdown, set low.
C3	EN <sub>LDO1</sub>	LDO1 Enable Input. Set this digital input high to turn on LDO1. (EN <sub>BUCK</sub> pin must be also set high.) For turning LDO1 off, set low.
D3	BYP	Forced Bypass Input. Use this digital input to command operation in Bypass mode. Set BYP low (<0.4V) for normal operation.
A4	BYPOUT	Bypass FET Drain. Connect to the output capacitor. Do not leave floating.
B4	PVIN	Buck Converter Power Supply Voltage Input to the internal PFET switch and Bypass FET.
C4	SW	Buck Converter Switch Node connection to the internal PFET switch and NFET synchronous rectifier. Connect to an inductor with a saturation current rating that exceeds the maximum Switch Peak Current Limit of the PWM Buck Converter.
D4	PGND	Buck Converter Power Ground.



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

## Absolute Maximum Ratings<sup>(1)(2)</sup>

SVIN, PVIN to SGND	-0.2V to +6.0V
PGND to SGND	-0.2V to +0.2V
ENs, FB, BYP, V <sub>CON</sub>	(SGND -0.2V) to (SVIN +0.2V) w/6.0V max
SW, BYPOUT	(PGND -0.2V) to (PVIN +0.2V) w/6.0V max
PVIN to SVIN	-0.2V to +0.2V
Continuous Power Dissipation <sup>(3)</sup>	Internally Limited
Junction Temperature (T <sub>J-MAX</sub> )	+150°C
Storage Temperature Range	-65°C to +150°C
Maximum Lead Temperature (Soldering, 10 sec.)	+260°C
ESD Rating <sup>(4)</sup> Human Body Model Machine Model	2k V 200 V

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the component may occur. Operating Ratings are conditions under which operation of the device is guaranteed. Operating Ratings do not imply guaranteed performance limits. For guaranteed performance limits and associated test conditions, see the Electrical Characteristics tables.
- (2) All voltages are with respect to the potential at the GND pins.
- (3) Internal thermal shutdown circuitry protects the device from permanent damage. Thermal shutdown engages at T<sub>J</sub> = 150°C (typ.) and disengages at T<sub>J</sub> = 125°C (typ.).
- (4) The Human body model is a 100pF capacitor discharged through a 1.5kΩ resistor into each pin. (MIL-STD-883 3015.7) The machine model is a 200pF capacitor discharged directly into each pin. National Semiconductor recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper ESD handling techniques can result in damage.

## Operating Ratings<sup>(1)(2)</sup>

Input Voltage Range	2.7V to 5.5V
Recommended Load Current	
PWM Mode:	0mA to 300mA
Bypass Mode:	0mA to 500mA
LDO:	0mA to 20mA
Junction Temperature (T <sub>J</sub> ) Range	-30°C to +125°C
Ambient Temperature (T <sub>A</sub> ) Range <sup>(3)</sup>	-30°C to +85°C

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the component may occur. Operating Ratings are conditions under which operation of the device is guaranteed. Operating Ratings do not imply guaranteed performance limits. For guaranteed performance limits and associated test conditions, see the Electrical Characteristics tables.
- (2) Shutdown current includes leakage current of PFET and Bypass FET.
- (3) In applications where high power dissipation and/or poor package thermal resistance is present, the maximum ambient temperature may have to be de-rated. Maximum ambient temperature (T<sub>A-MAX</sub>) is dependent on the maximum operating junction temperature (T<sub>J-MAX-OP</sub> = 125°C), the maximum power dissipation of the device in the application (P<sub>D-MAX</sub>), and the junction-to ambient thermal resistance of the part/package in the application (θ<sub>JA</sub>), as given by the following equation: T<sub>A-MAX</sub> = T<sub>J-MAX-OP</sub> - (θ<sub>JA</sub> × P<sub>D-MAX</sub>).

## Thermal Properties

Junction-to-Ambient Thermal Resistance (θ <sub>JA</sub> ), DSBGA Package <sup>(1)</sup>	48 °C/W
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- (1) Junction-to-ambient thermal resistance (θ<sub>JA</sub>) is taken from thermal measurements, performed under the conditions and guidelines set forth in the JEDEC standard JESD51-7. A 1" x 1", 4 layer, 1.5oz. Cu board was used for the measurements. The θ<sub>JA</sub>, which is performed under the 4 layer cellphone board condition, is 86°C/W.

## General Electrical Characteristics<sup>(1)(2)(3)</sup>

Limits in standard typeface are for  $T_A = T_J = 25^\circ\text{C}$ . Limits in **boldface** type apply over the full operating ambient temperature range ( $-30^\circ\text{C} \leq T_A = T_J \leq +85^\circ\text{C}$ ). Unless otherwise noted, specifications apply to the LM3280 with:  $V_{IN} = (SVIN = PVIN =) 3.6\text{V}$ ,  $EN_{BUCK} = 3.6\text{V}$ ,  $EN_{LDO1} = EN_{LDO2} = EN_{LDO3} = BYP = 0\text{V}$ ,  $FB = 2\text{V}$ ,  $V_{CON} = 0.267\text{V}$ .

Symbol	Parameter	Conditions	Min.	Typ.	Max	Units
$I_Q$	Shutdown Supply Current	$EN_{BUCK} = 0\text{V}$ , $FB = SW = V_{CON} = 0\text{V}$ , $BYPOUT = 0\text{V}$		0.1	<b>3</b>	$\mu\text{A}$
	No Load Supply Current	$EN_{BUCK} = 3.6\text{V}$ , $BYPOUT = 0\text{V}$		720	<b>800</b>	$\mu\text{A}$
		$EN_{BUCK} = 3.6\text{V}$ , $BYPOUT = 0\text{V}$ , $EN_{LDO1} = 3.6\text{V}$		920	<b>1300</b>	$\mu\text{A}$
		$EN_{BUCK} = BYP = 3.6\text{V}$		720	<b>800</b>	$\mu\text{A}$
		$EN_{BUCK} = BYP = 3.6\text{V}$ , $EN_{LDO1} = 3.6\text{V}$		920	<b>1300</b>	$\mu\text{A}$
$V_{IH}$	Logic High Input Threshold Voltage for ENx, BYP	$FB = 0\text{V}$	<b>1.2</b>			V
$V_{IL}$	Logic Low Input Threshold Voltage for ENx, BYP	$FB = 0\text{V}$			<b>0.4</b>	V
$I_{PDWN}$	Logic Input Pull Down Current for ENx, BYP	$ENx, BYP = 3.6\text{V}$		5	<b>10</b>	$\mu\text{A}$
THSD	Thermal Shutdown Temperature	(2)		150		$^\circ\text{C}$
	Hysteresis Temperature	(2)		25		$^\circ\text{C}$

- (1) All voltages are with respect to the potential at the GND pins.
- (2) Min and Max limits are guaranteed by design, test, or statistical analysis. Typical numbers are not guaranteed, but do represent the most likely norm.
- (3) The LM3280 is designed for mobile phone applications where turn-on after power-up is controlled by the system controller and where requirements for a small package size overrule increased die size for internal Under Voltage Lock-Out (UVLO) circuitry. Thus, it should be kept in shutdown by holding the EN pin low until the input voltage exceeds 2.7V.

## Buck Electrical Characteristics<sup>(1)(2)(3)</sup>

Limits in standard typeface are for  $T_A = T_J = 25^\circ\text{C}$ . Limits in **boldface** type apply over the full operating ambient temperature range ( $-30^\circ\text{C} \leq T_A = T_J \leq +85^\circ\text{C}$ ). Unless otherwise noted, specifications apply to the LM3280 with:  $V_{IN} = (SVIN = PVIN =) 3.6\text{V}$ ,  $EN_{BUCK} = 3.6\text{V}$ ,  $EN_{LDO1} = EN_{LDO2} = EN_{LDO3} = BYP = 0\text{V}$ ,  $FB = 2\text{V}$ ,  $V_{CON} = 0.267\text{V}$ .

Symbol	Parameter	Conditions	Min.	Typ.	Max	Units
$V_{FB\_MIN}$	Feedback Voltage at Minimum Setting	$V_{CON} = 0.267\text{V}$	<b>0.75</b>	0.800	<b>0.85</b>	V
$V_{FB\_MAX}$	Feedback Voltage at Maximum Setting	$V_{CON} = 1.20\text{V}$ , $V_{IN} = 4.2\text{V}$	<b>3.528</b>	3.600	<b>3.672</b>	V
OVP	Over-Voltage Protection Threshold	(4)		330	400	mV
$V_{BYPASS-}$	Auto Bypass Detection Negative Threshold	(5)	160	250	320	mV
$V_{BYPASS+}$	Auto Bypass Detection Positive Threshold	(5)	350	450	540	mV
$R_{DSON (P)}$	Pin-Pin Resistance for PFET	$I_{SW} = 500\text{mA}$ , $FB = 0\text{V}$		320	<b>450</b>	$\text{m}\Omega$
$R_{DSON (N)}$	Pin-Pin Resistance for N-FET	$I_{SW} = -200\text{mA}$		310	<b>450</b>	$\text{m}\Omega$
$R_{DSON (BYP)}$	Pin-Pin Resistance for Bypass FET	$I_{BYPOUT} = 500\text{mA}$		85	<b>120</b>	$\text{m}\Omega$

- (1) All voltages are with respect to the potential at the GND pins.
- (2) Min and Max limits are guaranteed by design, test, or statistical analysis. Typical numbers are not guaranteed, but do represent the most likely norm.
- (3) Shutdown current includes leakage current of PFET and Bypass FET.
- (4) Over-Voltage protection (OVP) threshold is the voltage above the nominal  $V_{OUT}$  where the OVP comparator turns off the PFET switch while in PWM mode.
- (5)  $SVIN$  is compared to the programmed output voltage ( $V_{OUT}$ ). When  $SVIN - V_{OUT}$  falls below  $V_{BYPASS-}$  for longer than  $T_{BYP}$  the Bypass FET turns on and the switching FETs turn off. This is called the Bypass mode. The device comes out of Bypass mode when  $SVIN - V_{OUT}$  exceeds  $V_{BYPASS+}$  for longer than  $T_{BYP}$ , and PWM mode returns. The hysteresis for the bypass detection threshold  $V_{BYPASS+} - V_{BYPASS-}$  will always be positive and will be approximately 200mV (typ.).

## Buck Electrical Characteristics<sup>(1)(2)(3)</sup> (continued)

Limits in standard typeface are for  $T_A = T_J = 25^\circ\text{C}$ . Limits in **boldface** type apply over the full operating ambient temperature range ( $-30^\circ\text{C} \leq T_A = T_J \leq +85^\circ\text{C}$ ). Unless otherwise noted, specifications apply to the LM3280 with:  $V_{IN} = (SVIN = PVIN =) 3.6\text{V}$ ,  $EN_{BUCK} = 3.6\text{V}$ ,  $EN_{LDO1} = EN_{LDO2} = EN_{LDO3} = BYP = 0\text{V}$ ,  $FB = 2\text{V}$ ,  $V_{CON} = 0.267\text{V}$ .

Symbol	Parameter	Conditions	Min.	Typ.	Max	Units
$I_{LIM-PWM}$	Switch Current Limit	$FB = 0\text{V}$ <sup>(6)</sup>	<b>700</b>	820	<b>940</b>	mA
$I_{LIM-BYP}$	Bypass FET Current Limit	<sup>(7)</sup>	<b>800</b>	1000	<b>1200</b>	mA
$F_{OSC}$	Internal Oscillator Frequency		<b>1.8</b>	2	<b>2.2</b>	MHz
Gain	$V_{CON}$ to $V_{OUT}$ Gain	$0.267\text{V} \leq V_{CON} \leq 1.20\text{V}$ , $V_{IN} = 4.2\text{V}$		3		V/V
$I_{CON}$	$V_{CON}$ Input Leakage Current	$V_{CON} = 1.2\text{V}$		10		nA

(6) Electrical Characteristic table reflects open loop data ( $FB = 0\text{V}$  and current drawn from SW pin ramped up until cycle by cycle current limit is activated). Refer to datasheet curves for closed loop data and its variation with regards to supply voltage and temperature. Closed loop current limit is the peak inductor current measured in the application circuit by increasing output current until output voltage drops by 10%.

(7) The current is defined as the load current at which the BYPOUT voltage is 1V lower than PVIN.

## Buck System Characteristics<sup>(1)(2)</sup>

The following spec table entries are guaranteed by design if the component values in the typical application circuit are used. **These parameters are not guaranteed by production testing.**

Symbol	Parameter	Conditions	Min	Typ	Max	Units
$T_{RESPONSE}$	Time for $V_{OUT}$ to Rise from 0.8V to 3.4V in PWM Mode	$V_{IN} = 4.2\text{V}$ , $C_{OUT} = 4.7\mu\text{F}$ , $R_{LOAD} = 15\Omega$ $L = 2.2\mu\text{H}$ ( $I_{SAT} > 0.94\text{A}$ )		25		μs
$T_{STARTUP}$	Time for $V_{OUT}$ to rise to 3.4V in PWM Mode <sup>(3)</sup>	$V_{IN} = 4.2\text{V}$ , $C_{OUT} = 4.7\mu\text{F}$ , $R_{LOAD} = 15\Omega$ $L = 2.2\mu\text{H}$ ( $I_{SAT} = 0.94\text{A}$ ) $EN = \text{Low to High}$		36		μs
$C_{CON}$	$V_{CON}$ Input Capacitance	$V_{IN} = 3.6\text{V}$ , $V_{CON} = 1\text{V}$ , Test Freq. = 100kHz			15	pF
$T_{ON\_BYP}$	Bypass FET Turn On Time In Bypass Mode	$V_{IN} = 3.6\text{V}$ , $V_{CON} = 0.267\text{V}$ , $C_{OUT} = 4.7\mu\text{F}$ , $R_{LOAD} = 15\Omega$ $BYP = \text{Low to High}$			30	μs
$T_{BYP}$	Auto Bypass Detect Delay Time	<sup>(4)</sup>	10	15	20	μs

(1) All voltages are with respect to the potential at the GND pins.  
 (2) Shutdown current includes leakage current of PFET and Bypass FET.  
 (3) The startup time is the time to reach 90% of 3.4V nominal output voltage from the  $EN_{BUCK}$  being low to high.  
 (4)  $SVIN$  is compared to the programmed output voltage ( $V_{OUT}$ ). When  $SVIN - V_{OUT}$  falls below  $V_{BYPASS-}$  for longer than  $T_{BYP}$  the Bypass FET turns on and the switching FETs turn off. This is called the Bypass mode. The device comes out of Bypass mode when  $SVIN - V_{OUT}$  exceeds  $V_{BYPASS+}$  for longer than  $T_{BYP}$ , and PWM mode returns. The hysteresis for the bypass detection threshold  $V_{BYPASS+} - V_{BYPASS-}$  will always be positive and will be approximately 200mV (typ.).

## LDO1, 2, and 3 Electrical Characteristics<sup>(1)(2)</sup>

Limits in standard typeface are for  $T_A = T_J = 25^\circ\text{C}$ . Limits in **boldface** type apply over the full operating ambient temperature range ( $-30^\circ\text{C} \leq T_A = T_J \leq +85^\circ\text{C}$ ). Unless otherwise noted, specifications apply to the LM3280 with:  $V_{IN} = 3.6\text{V}$ ,  $EN_{BUCK} = 3.6\text{V}$ ,  $BYP = 0\text{V}$ ,  $FB = 2\text{V}$ ,  $V_{CON} = 0.267\text{V}$ ,  $EN_{LDOx} = 3.6\text{V}$  <sup>(3)</sup>.

Symbol	Parameter	Conditions	Min	Typ	Max	Units
$V_{LDO}$	LDO Output Voltage Accuracy	$V_{LDO} = 2.85\text{V}$ , $I_{OUT} = 1\text{mA}$	-1 -2		+1 +2	% %
$\Delta V_{LDO}$	Line Regulation	$V_{IN} = V_{LDO(nom)} + 0.5\text{V}$ to $5.5\text{V}$ , $I_{OUT} = 1\text{mA}$		0.1		%/V
	Load Regulation	$I_{OUT} = 1\text{mA}$ to $20\text{mA}$		0.01	<b>0.04</b>	%/mA

(1) All voltages are with respect to the potential at the GND pins.  
 (2) Min and Max limits are guaranteed by design, test, or statistical analysis. Typical numbers are not guaranteed, but do represent the most likely norm.  
 (3) The  $EN_{LDOx}$  means that the one of  $EN_{LDO1}$ ,  $EN_{LDO2}$ , and  $EN_{LDO3}$  is set high ( $> 1.2\text{V}$ ) and the others are set 0V.

## LDO1, 2, and 3 Electrical Characteristics<sup>(1)(2)</sup> (continued)

Limits in standard typeface are for  $T_A = T_J = 25^\circ\text{C}$ . Limits in **boldface** type apply over the full operating ambient temperature range ( $-30^\circ\text{C} \leq T_A = T_J \leq +85^\circ\text{C}$ ). Unless otherwise noted, specifications apply to the LM3280 with:  $V_{IN} = 3.6\text{V}$ ,  $EN_{BUCK} = 3.6\text{V}$ ,  $BYP = 0\text{V}$ ,  $FB = 2\text{V}$ ,  $V_{CON} = 0.267\text{V}$ ,  $EN_{LDOx} = 3.6\text{V}$ <sup>(3)</sup>.

Symbol	Parameter	Conditions	Min	Typ	Max	Units
$I_{LIM\_LDO}$	LDO Current Limit	(4)	<b>30</b>	40	<b>55</b>	mA
$I_{PU}$	Pull-Up Current	(4)	<b>40</b>	60	<b>80</b>	mA
$R_{PD}$	Pull-Down Resistance	$I_{OUT} = -50\text{mA}$ , $EN_{BUCK} = \text{all } EN_{LDO} = 0\text{V}$	<b>10</b>	13.5	<b>17</b>	$\Omega$
$V_{DROP}$	Dropout Voltage	$I_{OUT} = 20\text{mA}$ <sup>(5)</sup>		70	<b>115</b>	mV

(4) The current is defined as the load current at which the LDOx voltage is 1.0V lower than the nominal output voltage.

(5) Dropout voltage is the voltage difference between the input and the output at which the output voltage drops to 100mV below the nominal voltage.

## LDO1, 2, and 3 System Characteristics<sup>(1)</sup>

The following spec table entries are guaranteed by design if the component values in the typical application circuit are used. Unless otherwise noted, specifications apply to the LM3280 with:  $V_{IN} = 3.6\text{V}$ . **These parameters are not guaranteed by production testing.**

Symbol	Parameter	Conditions	Min	Typ	Max	Units
PSRR	Power Supply Ripple Rejection Ratio	Test Freq. = 1KHz, $V_{RIPPLE} = 0.5\text{Vpp}$ $C_{OUT} = 1\mu\text{F}$ , $I_{OUT} = 1\text{mA}$ , $BYP = V_{IN}$		55		dB
$T_{LDO\_ON}$	Time to reach 90% of $V_{LDO(\text{nom})}$ after $EN_{LDO}$ signal goes high.	$V_{IN} = EN_{BUCK} = 3\text{V}$ , $C_{OUT} = 1\mu\text{F}$ , $EN_{LDOx} = \text{Low to High}$ , $R_{LOAD} = 270\Omega$		50	100	$\mu\text{s}$
		$V_{IN} = 3\text{V}$ , $C_{OUT} = 1\mu\text{F}$ , $EN_{BUCK} = EN_{LDO} = \text{Low to High}$ , $R_{LOAD} = 270\Omega$		80	130	$\mu\text{s}$
$T_{LDO\_OFF}$	Time to reach 0.1V of $V_{LDO}$ after $EN_{LDO}$ signal goes low.	$V_{IN} = 3\text{V}$ , $C_{OUT} = 1\mu\text{F}$ , $EN_{LDOx} = \text{High to Low}$ , $I_{OUT} = 0\text{mA}$		50	200	$\mu\text{s}$

(1) All voltages are with respect to the potential at the GND pins.

### Typical Performance Characteristics

( $V_{IN} = EN_{BUCK} = 3.6V$ ,  $EN_{LDOx} = BYP = 0V$ ,  $T_A = 25^\circ C$ , unless otherwise noted)

**Quiescent Current vs Supply Voltage**  
( $V_{CON} = 0.267V$ ,  $FB = 2V$ , No Switching, LDO Disabled)

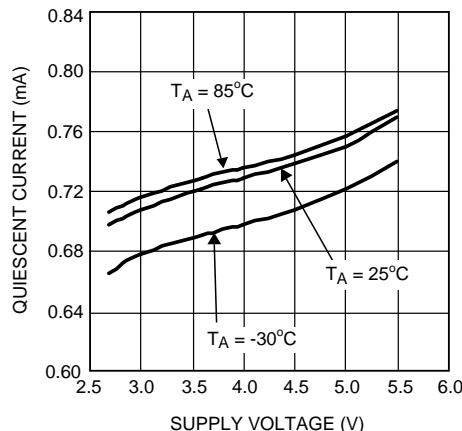


Figure 3.

**Quiescent Current vs Supply Voltage**  
( $V_{CON} = 0.267V$ ,  $FB = 2V$ , No Switching, LDO Enabled)

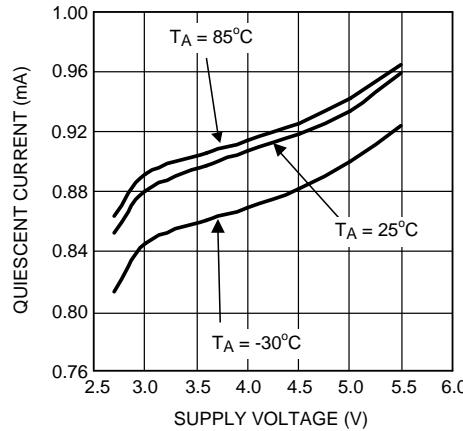


Figure 4.

**Shutdown Current vs Temperature**  
(all  $EN = BYPOUT = V_{CON} = SW = FB = 0V$ )

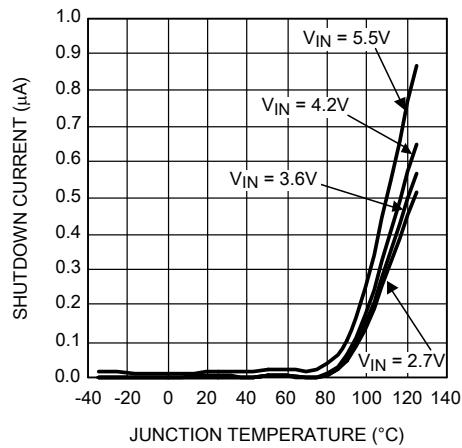


Figure 5.

**LDO Line Transient Response**  
( $R_{LOAD} = 270\Omega$ ,  $C_{OUT} = 1\mu F$ )

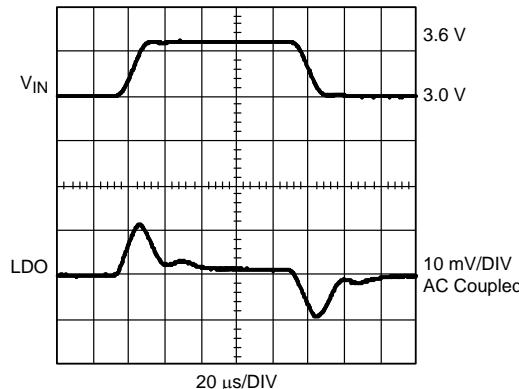


Figure 6.

**LDO Turn ON**  
( $EN_{LDO} = \text{Low to High}$ )

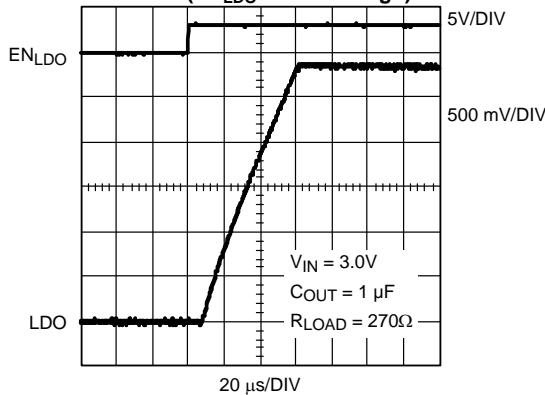


Figure 7.

**LDO Turn ON**  
( $EN_{BUCK} = EN_{LDO} = \text{Low to High}$ )

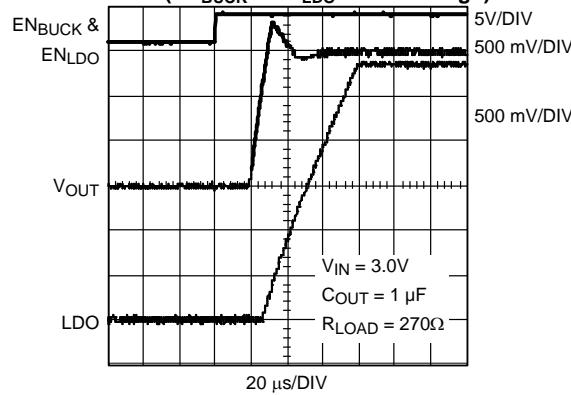


Figure 8.

### Typical Performance Characteristics (continued)

( $V_{IN} = EN_{BUCK} = 3.6V$ ,  $EN_{LDOx} = BYP = 0V$ ,  $T_A = 25^\circ C$ , unless otherwise noted)

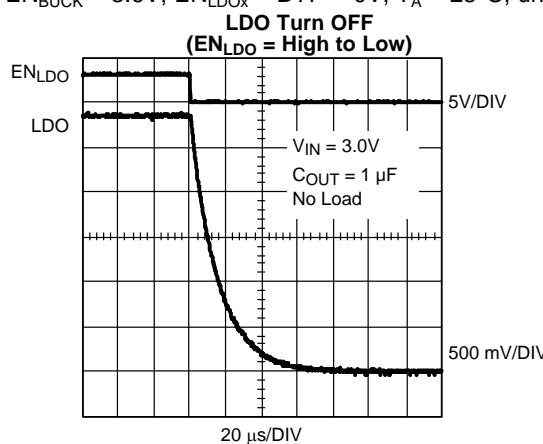


Figure 9.

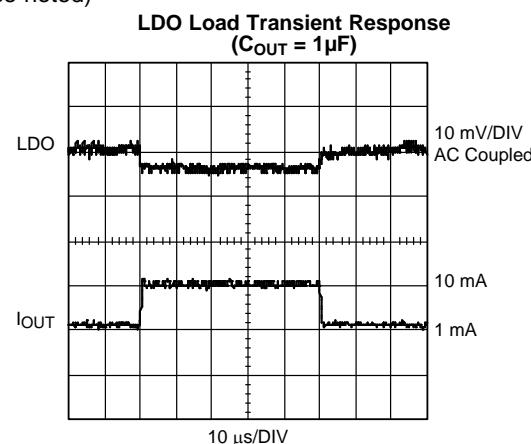


Figure 10.

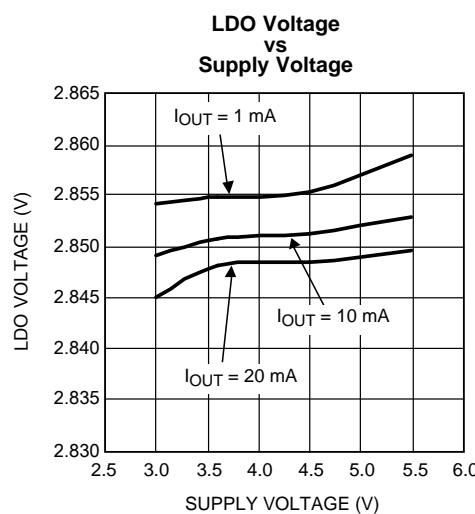


Figure 11.

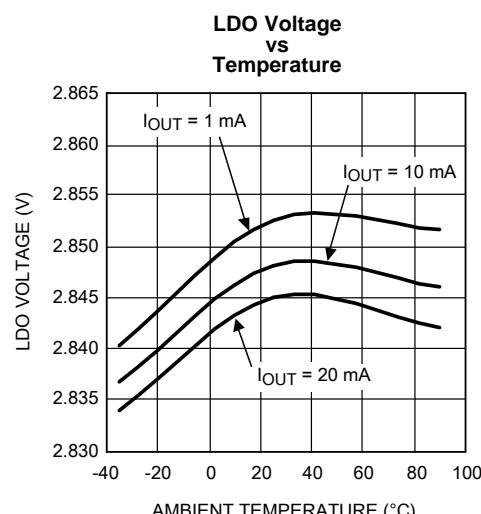


Figure 12.

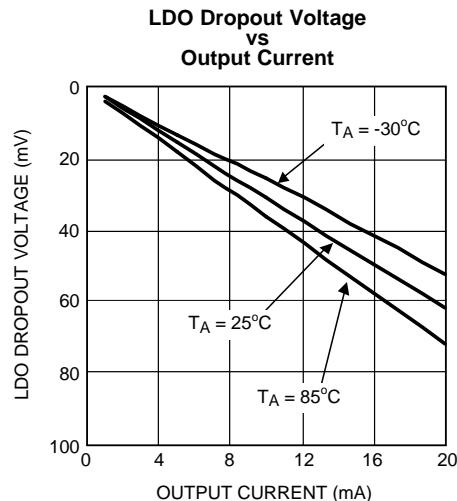


Figure 13.

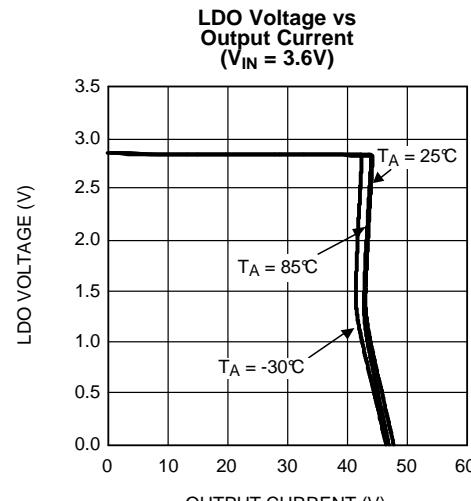


Figure 14.

### Typical Performance Characteristics (continued)

( $V_{IN} = EN_{BUCK} = 3.6V$ ,  $EN_{LDOX} = BYP = 0V$ ,  $T_A = 25^\circ C$ , unless otherwise noted)

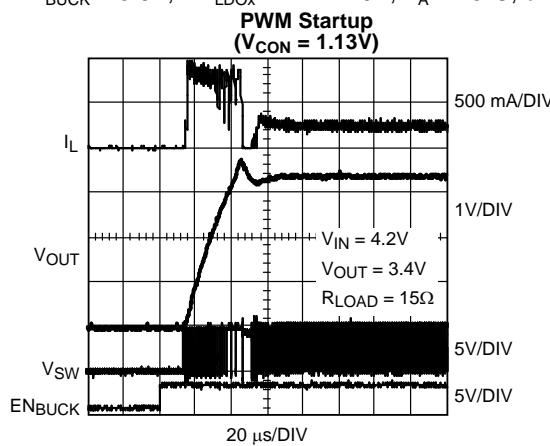


Figure 15.

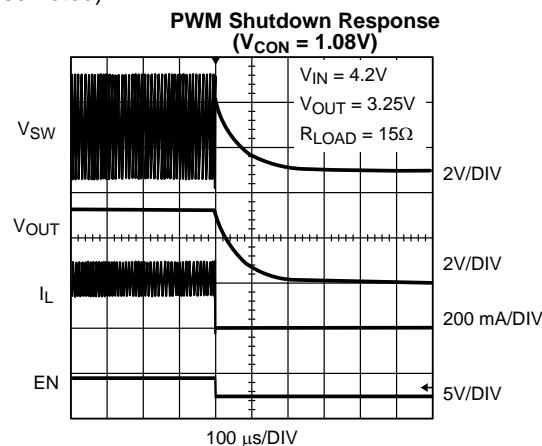


Figure 16.

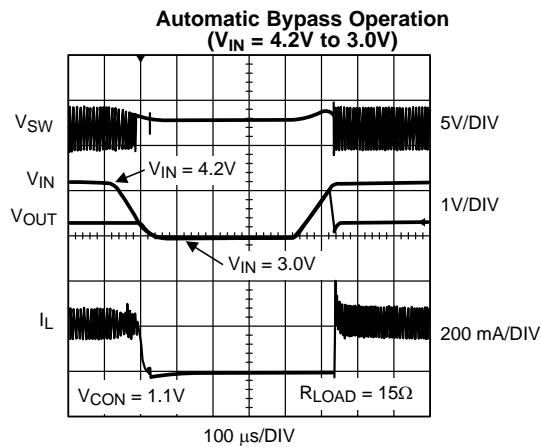


Figure 17.

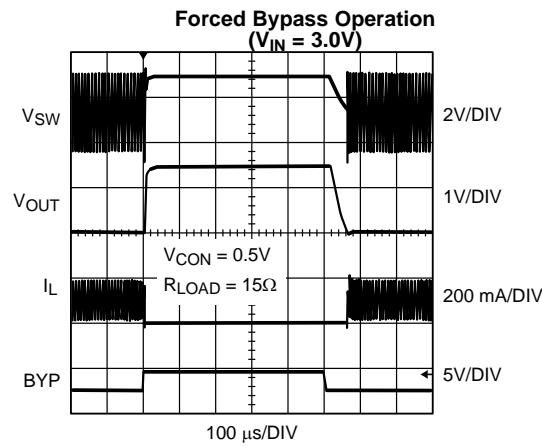


Figure 18.

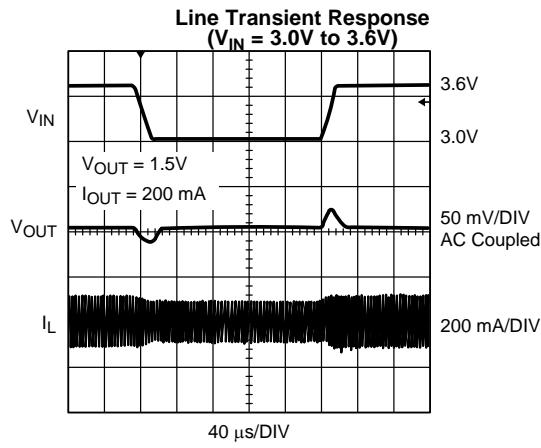


Figure 19.

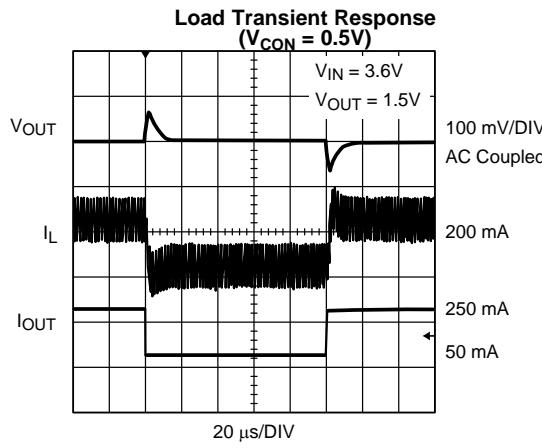


Figure 20.

### Typical Performance Characteristics (continued)

( $V_{IN} = EN_{BUCK} = 3.6V$ ,  $EN_{LDOX} = BYP = 0V$ ,  $T_A = 25^\circ C$ , unless otherwise noted)

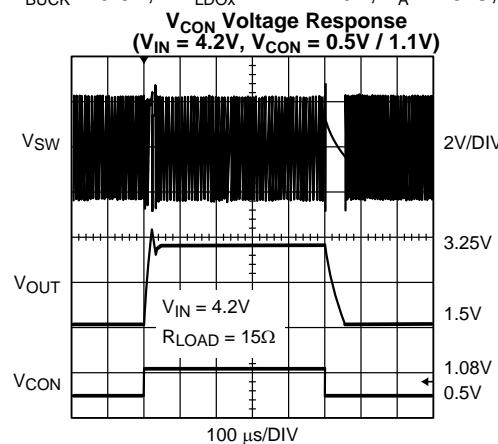


Figure 21.

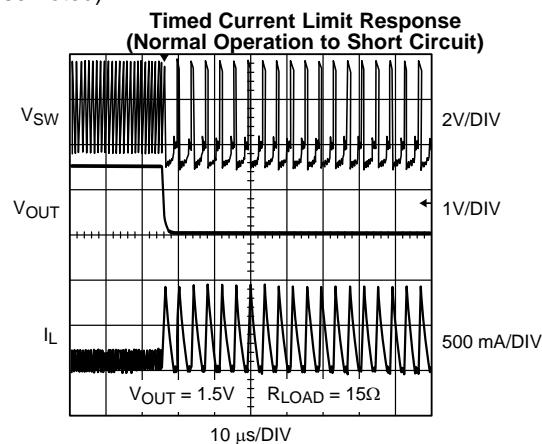


Figure 22.

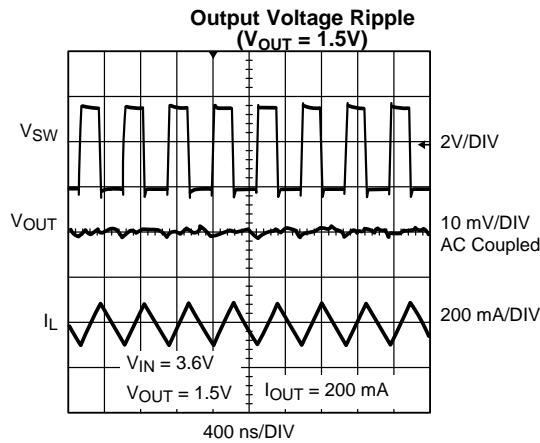


Figure 23.

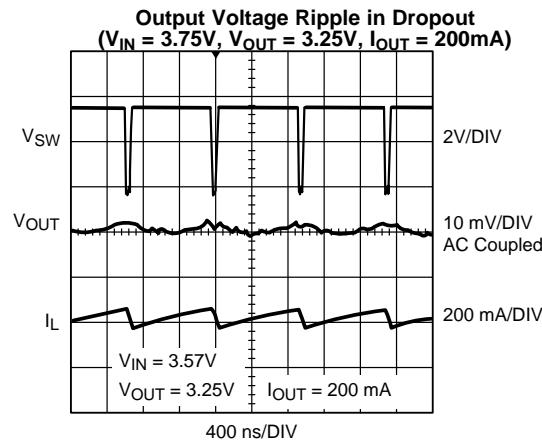


Figure 24.

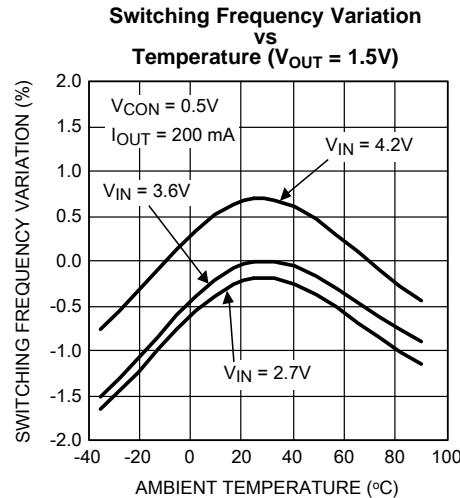


Figure 25.

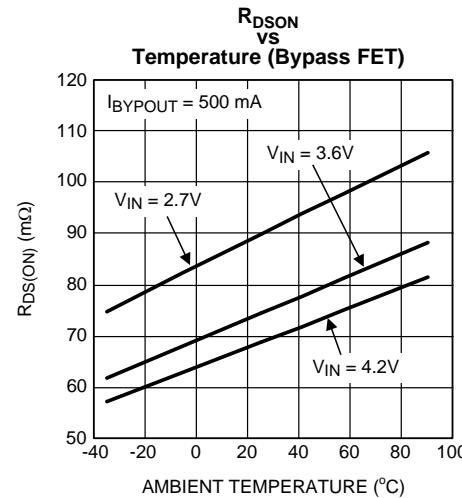


Figure 26.

### Typical Performance Characteristics (continued)

( $V_{IN} = EN_{BUCK} = 3.6V$ ,  $EN_{LDOX} = BYP = 0V$ ,  $T_A = 25^\circ C$ , unless otherwise noted)

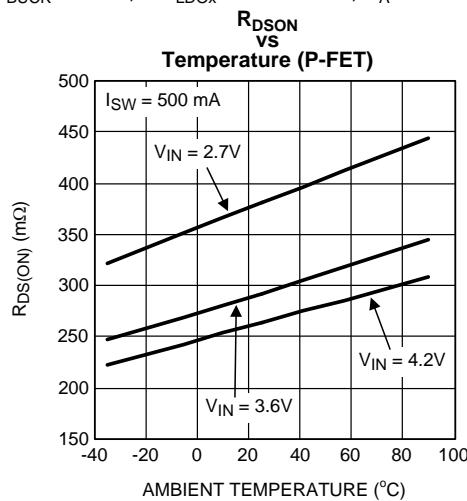


Figure 27.

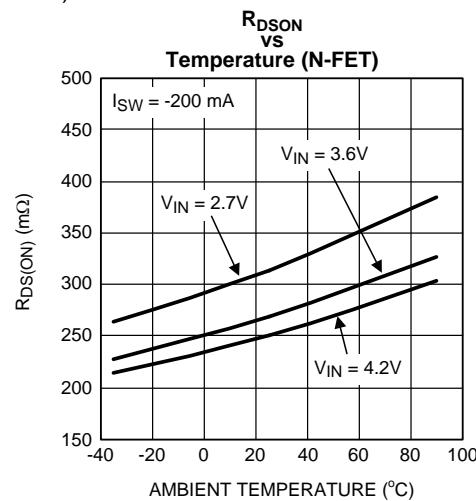


Figure 28.

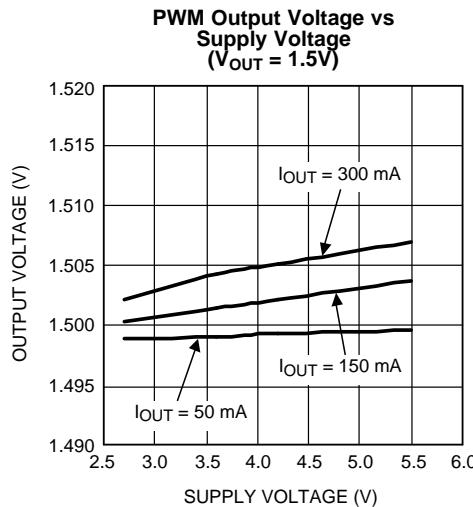


Figure 29.

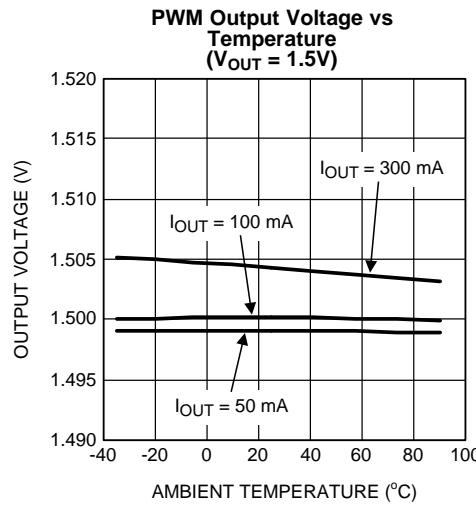


Figure 30.

### Typical Performance Characteristics (continued)

( $V_{IN} = EN_{BUCK} = 3.6V$ ,  $EN_{LDOx} = BYP = 0V$ ,  $T_A = 25^\circ C$ , unless otherwise noted)

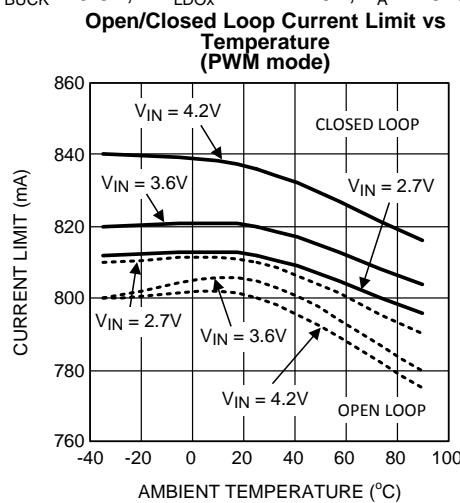


Figure 31.

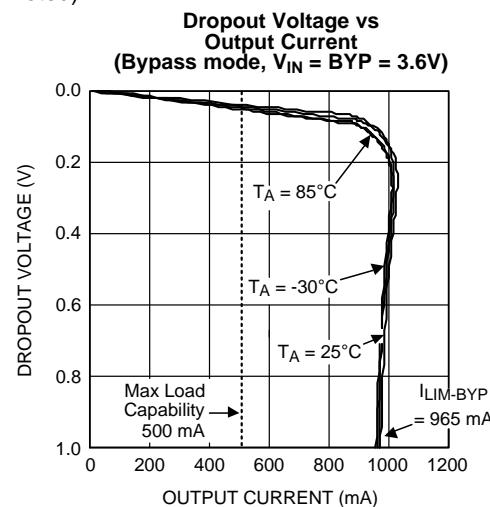


Figure 32.

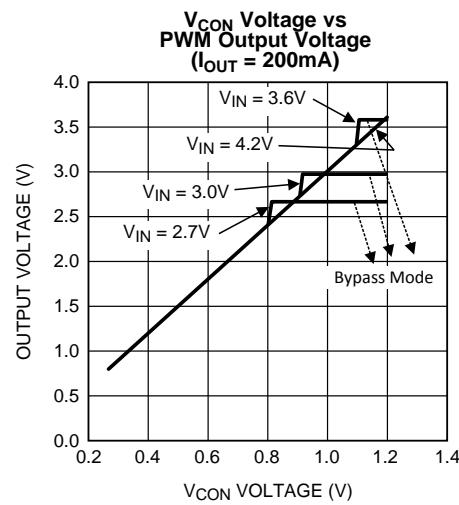


Figure 33.

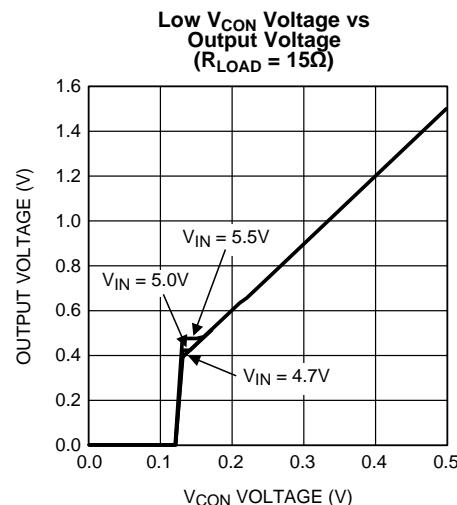


Figure 34.

### Typical Performance Characteristics (continued)

( $V_{IN} = EN_{BUCK} = 3.6V$ ,  $EN_{LDOX} = BYP = 0V$ ,  $T_A = 25^\circ C$ , unless otherwise noted)

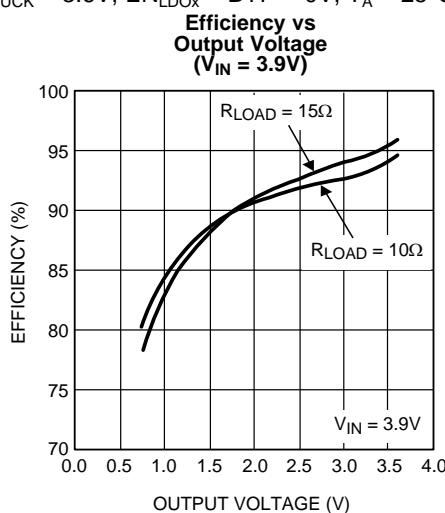


Figure 35.

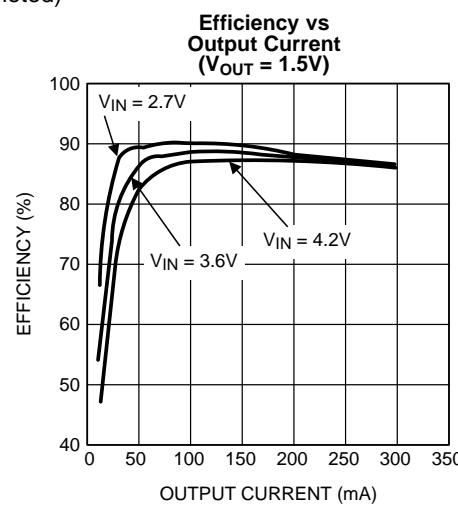


Figure 36.

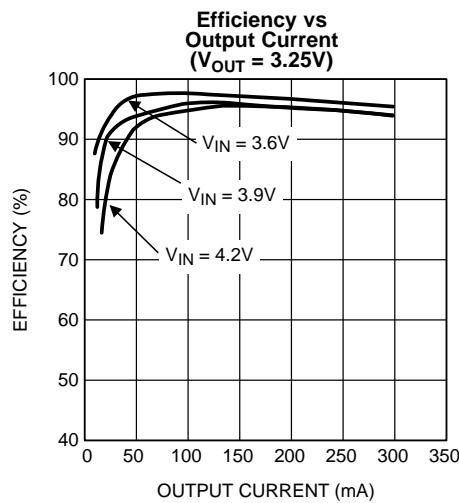


Figure 37.

## BLOCK DIAGRAM

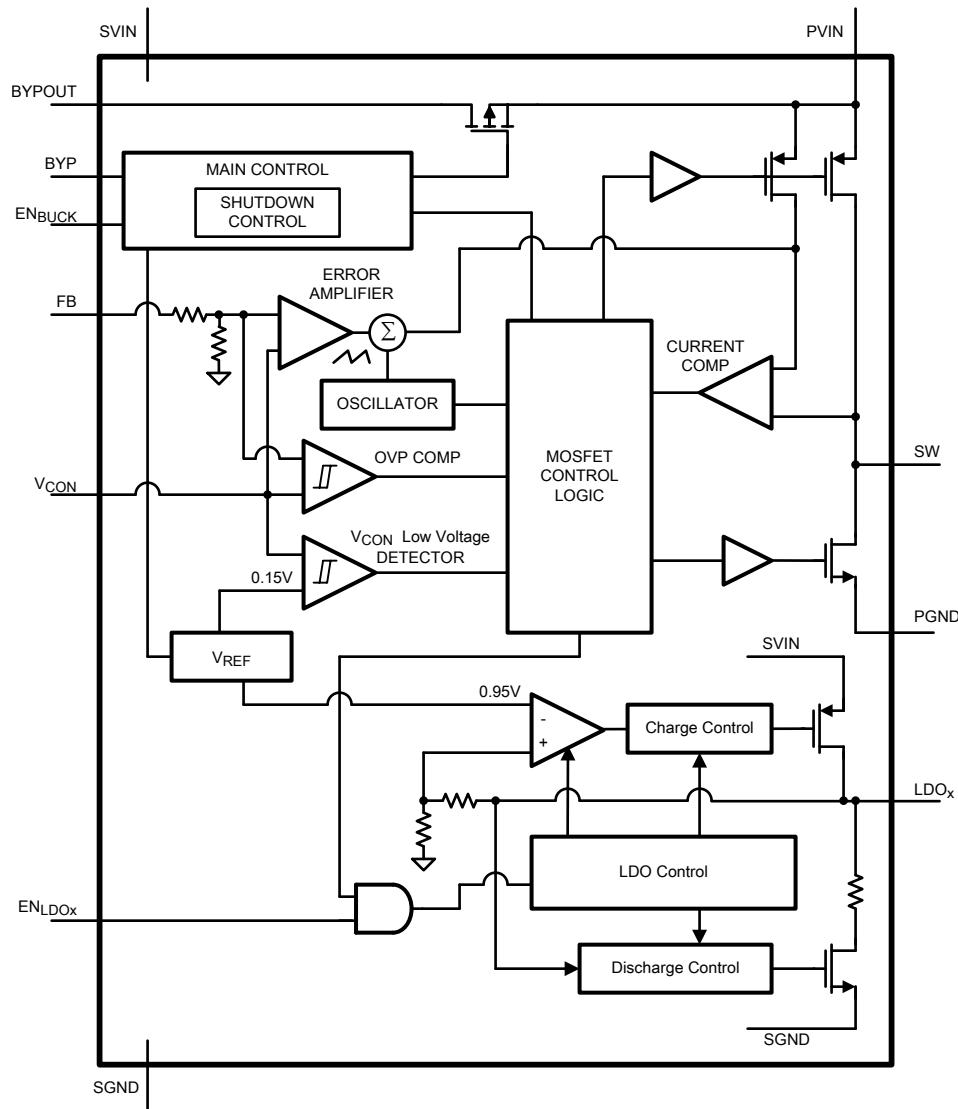


Figure 38. Functional Block Diagram

## DEVICE INFORMATION

The LM3280 is a multi-functional Power Management Unit, optimized for low-power handheld applications such as Cellular Phones. It incorporates one adjustable voltage PWM DC-DC converter with an internal Bypass FET and three LDOs. It also provides a separate enable pin for each output. The buck converter output voltage can be programmed from 0.8V to 3.6V in PWM mode. The buck converter is designed for a maximum load capability of 300mA in PWM mode and 500mA in Bypass mode. Maximum load range may vary from this depending on input voltage, output voltage and the inductor chosen. The LDO operates a nominal output voltage of 2.85V and maximum load current capability of 20mA.

The buck converter is designed to allow the RF PA (Power Amplifier) to operate at maximum efficiency over a wide range of power levels from a single Li-Ion battery cell. It is based on current-mode buck architecture, with synchronous rectification for high efficiency. It has three of pin-selectable operating modes. Fixed-frequency PWM operation offers regulated output at high efficiency while minimizing interference with sensitive IF and data acquisition circuits. Bypass mode (Forced or Automatic) turns on an internal FET bypass switch to power the PA directly from the battery. This helps the RF PA maintain its operating power during low battery conditions by reducing the dropout voltage across the buck converter. Shutdown mode turns the device off and reduces battery consumption to 0.1µA (typ.).

DC PWM mode output voltage precision is +/-2% for 3.6V<sub>OUT</sub>. Efficiency is typically around 96% for a 120mA load with 3.2V output, 3.6V input. PWM mode quiescent current is 0.72mA typ. The output voltage is dynamically programmable from 0.8V to 3.6V by adjusting the voltage on the control pin (V<sub>CON</sub>) without the need for external feedback resistors.

An LDO is used to provide a regulated 2.85V reference voltage supply to each RF PA. Since each LDO has its own enable pin, it can be used to enable or disable its respective PA. The LDO can be enabled only after the buck converter is activated. The LDO will automatically be disabled whenever the EN<sub>BUCK</sub> or EN<sub>LDOx</sub> is disabled. Single LDO must be turned on at the same time. Each LDO provides an active charge circuit. The LDO output is pulled to ground potential via an internal resistor when the EN<sub>BUCK</sub> or EN<sub>LDOx</sub> pin is low.

Additional features include current overload protection and thermal shutdown. The buck converter also provides over voltage protection.

The LM3280 is constructed using a chip-scale 16-pin DSBGA package. This package offers the smallest possible size, for space-critical applications such as cell phones, where board area is an important design consideration. Use of a DSBGA package requires special design considerations for implementation. (See [DSBGA PACKAGE ASSEMBLY AND USE](#).) Its fine bump-pitch requires careful board design and precision assembly equipment. Use of this package is best suited for opaque-case applications, where its edges are not subject to high-intensity ambient red or infrared light. Also, the system controller should set EN<sub>BUCK</sub> low during power-up and other low supply voltage conditions. (See [Shutdown Mode](#).)

### Buck Converter

### CIRCUIT OPERATION

Referring to [Figure 1](#) and [Figure 38](#), the buck converter operates as follows. During the first part of each switching cycle, the control block in the buck converter turns on the internal PFET (P-channel MOSFET) switch. This allows current to flow from the input through the inductor to the output filter capacitor and load. The inductor limits the current to a ramp with a slope of around  $(V_{IN} - V_{OUT}) / L$ , by storing energy in a magnetic field. During the second part of each cycle, the controller turns the PFET switch off, blocking current flow from the input, and then turns the NFET (N-channel MOSFET) synchronous rectifier on. In response, the inductor's magnetic field collapses, generating a voltage that forces current from ground through the synchronous rectifier to the output filter capacitor and load. As the stored energy is transferred back into the circuit and depleted, the inductor current ramps down with a slope around  $V_{OUT} / L$ . The output filter capacitor stores charge when the inductor current is going high, and releases it when inductor current is going low, smoothing the voltage across the load.

The output voltage is regulated by modulating the PFET switch on time to control the average current sent to the load. The effect is identical to sending a duty-cycle modulated rectangular wave formed by the switch and synchronous rectifier at SW to a low-pass filter formed by the inductor and output filter capacitor. The output voltage is equal to the average voltage at the SW pin.

## PWM MODE

While in PWM (Pulse Width Modulation) mode, the output voltage is regulated by switching at a constant frequency (2MHz typ.) and then modulating the energy per cycle to control power to the load. Energy per cycle is set by modulating the PFET switch on-time pulse width to control the peak inductor current. This is done by comparing the PFET drain current to a slope-compensated reference current generated by the error amplifier. At the beginning of each cycle, the clock turns on the PFET switch, causing the inductor current to ramp up. When the current sense signal ramps past the error amplifier signal, the PWM comparator turns off the PFET switch and turns on the NFET synchronous rectifier, ending the first part of the cycle. If an increase in load pulls the output down, the error amplifier output increases, which allows the inductor current to ramp higher before the comparator turns off the PFET. This increases the average current sent to the output and adjusts for the increase in the load. The minimum on-time of PFET in PWM mode is 50ns (typ.).

## BYPASS MODE

The buck converter contains an internal PFET switch for bypassing the PWM DC-DC converter during Bypass mode. In Bypass mode, this PFET is turned on to power the PA directly from the battery for maximum RF output power. Bypass mode is more efficient than operating in PWM mode at 100% duty cycle because the resistance of the bypass PFET is less than the series resistance of the PWM PFET and inductor. This translates into higher voltage available on the output in Bypass mode, for a given battery voltage. The part can be placed in bypass mode by sending BYP pin high. This is called Forced Bypass Mode and it remains in bypass mode until BYP pin goes low.

Alternatively the part can go into Bypass mode automatically. This is called Auto-bypass mode or Automatic Bypass mode. The bypass switch turns on when the difference between the input voltage and programmed output voltage is less than 250mV (typ.) for more than the bypass delay time of 15 $\mu$ s (typ.). The bypass switch turns off when the input voltage is higher than the programmed output voltage by 450mV (typ.) for longer than the bypass delay time. The bypass delay time is provided to prevent false triggering into Automatic Bypass mode by either spikes or dips in  $V_{IN}$ . This method is very system resource friendly in that the Bypass PFET is turned on automatically when the input voltage gets close to the output voltage, typical scenario of a discharging battery. It is also turned off automatically when the input voltage rises, typical scenario of a charger connected. Another scenario could be changes made to  $V_{CON}$  voltage causing Bypass PFET to turn on and off automatically. It is recommended to connect BYPOUT pin directly to the output capacitor with a separate trace and not to the FB pin.

## OPERATING MODE SELECTION CONTROL

The BYP digital input pin is used to select between PWM/Auto-bypass and Bypass operating mode. Setting BYP pin high (>1.2V) places the device in Forced Bypass mode. Setting BYP pin low (<0.4V) or leaving it floating places the device in PWM/Auto-bypass mode.

Bypass and PWM operation overlap during the transition between the two modes. This transition time is approximately 31 $\mu$ s when changing from PWM to Bypass mode, and 15 $\mu$ s when changing from Bypass to PWM mode. This helps prevent under or overshoots during the transition period between PWM and Bypass modes.

## DYNAMICALLY ADJUSTABLE OUTPUT VOLTAGE

The LM3280 buck converter features dynamically adjustable output voltage to eliminate the need for external feedback resistors. The output can be set from 0.8V to 3.6V by changing the voltage on the analog  $V_{CON}$  pin. This feature is useful in PA applications where peak power is needed only when the handset is far away from the base station or when data is being transmitted. In other instances, the transmitting power can be reduced. Hence the supply voltage to the PA can be reduced, promoting longer battery life. See [BUCK CONVERTER SETTING THE OUTPUT VOLTAGE](#) for further details.

## OVER VOLTAGE PROTECTION

The buck converter has an over voltage comparator that prevents the output voltage from rising too high, when the device is left in PWM mode under light-load conditions, during output voltage steps, or during startup. When the output voltage rises to 330mV over its target, the OVP comparator inhibits PWM operation to skip pulses until the output voltage returns to the target. During the over voltage protection mode, both the PWM PFET and the NFET synchronous rectifier are off. When the part comes out of the over voltage protection mode, the NFET synchronous rectifier remains off for approximately 3.5 $\mu$ s to avoid inductor current going negative.

## INTERNAL SYNCHRONOUS RECTIFICATION

While in PWM mode, the buck converter uses an internal NFET as a synchronous rectifier to reduce rectifier forward voltage drop and associated power loss. Synchronous rectification provides a significant improvement in efficiency whenever the output voltage is relatively low compared to the voltage drop across an ordinary rectifier diode.

With medium and heavy loads, the internal NFET synchronous rectifier is turned on during the inductor current down slope in the second part of each cycle. The synchronous rectifier is turned off prior to the next cycle. There is no zero cross detect, which means that the NFET can conduct current in both directions and inductor current is always continuous. The advantage of this method is that the part remains in PWM mode at light loads or no load conditions. The NFET has a current limit. The NFET is designed to conduct through its intrinsic body diode during transient intervals before it turns on, eliminating the need for an external diode.

## CURRENT LIMITING

A current limit feature allows the buck converter to protect itself and external components during overload conditions. In PWM mode, a 940mA (max.) cycle-by-cycle current limit is normally used. If an excessive load pulls the output voltage down to below approximately 0.375V, indicating a possible short to ground, then the device switches to a timed current limit mode. In timed current limit mode, the internal PFET switch is turned off after the current comparator trips, and the beginning of the next cycle is inhibited for 3.5 $\mu$ s to force the instantaneous inductor current to ramp down to a safe value. After the 3.5 $\mu$ s interval, the internal PFET is turned on again. This cycle is repeated until the load is reduced and the output voltage exceeds approximately 0.375V. Therefore, the device may not startup if an excessive load is connected to the output when the device is enabled. The synchronous rectifier is off in the timed current limit mode. Timed current limit prevents the loss of current control seen in some products when the output voltage is pulled low in serious overload conditions.

A current limit is also provided for the NFET. This is approximately -500mA. Both the NFET and the PFET are turned off in negative current limit until the PFET is turned on again at the beginning of the next cycle. The negative current limit inhibits buildup of excessive negative inductor current.

In the Bypass mode, the bypass current limit is 1000mA (typ.). The output voltage drops when the bypass current limit kicks in.

## LDO

### LDO OPERATION

The LDO provides a nominal output voltage of 2.85V. Each LDO can be enabled when the respective enable pin is set high (>1.2V) after the buck converter has been enabled. The LDO will automatically be disabled whenever the EN<sub>BUCK</sub> or EN<sub>LDOx</sub> is disabled. Only one LDO may be enabled on at a time. A 2 $\mu$ s period of time needs to occur between disabled one LDO and enabling another. Otherwise, all LDOs are disabled.

### CHARGE AND DISCHARGE

Each LDO includes an active charge circuit. 7.5 $\mu$ s (typ.) after the LDO is enabled, the current limit of the LDO is set to 60mA. A 1 $\mu$ F load capacitor will be charged to 90% of the nominal output voltage in approximately 50 $\mu$ s (typ.). (Note: This number is based on the assumption that the PWM loop has been enabled and given time to stabilize before the LDO is enabled.) The current limit is then reduced to 40mA.

An internal pull-down resistor is also included in each LDO. The LDO discharges the output capacitor through the pull-down resistor when LDO is disabled.

### Shutdown Mode

Setting the EN<sub>BUCK</sub> digital pin low (<0.4V) places the LM3280 in a 0.1 $\mu$ A (typ.) Shutdown mode. During shutdown, the PFET switch, NFET synchronous rectifier, reference voltage source, control and bias circuitry of the LM3280 are turned off. Setting EN<sub>BUCK</sub> high (>1.2V) enables normal operation.

$EN_{BUCK}$  should be set low to turn off the LM3280 during power-up and under voltage conditions when the power supply is less than the 2.7V minimum operating voltage. The LM3280 is designed for compact portable applications, such as cellular phones. In such applications, the system controller determines power supply sequencing and requirements for small package size outweigh the benefit of including UVLO (Under Voltage Lock-Out) circuitry.

## Thermal Overload Protection

The LM3280 has a thermal overload protection function to protect the device from short-term misuse and overload conditions. When the junction temperature exceeds around 150°C, the device inhibits operation. Both the PFET and the NFET are turned off in PWM mode, and the Bypass PFET is turned off in Bypass mode. The LDO is also turned off. When the temperature drops below 125°C, normal operation resumes. Prolonged operation in thermal overload conditions may damage the device.

## APPLICATION INFORMATION

### BUCK CONVERTER SETTING THE OUTPUT VOLTAGE

The buck converter features a pin-controlled variable output voltage to eliminate the need for external feedback resistors. It can be programmed for an output voltage from 0.8V to 3.6V by setting the voltage on the  $V_{CON}$  pin, as in the following formula:

$$V_{OUT} = 3 \times V_{CON} \quad (1)$$

When  $V_{CON}$  is between 0.267V and 1.20V, the output voltage will follow proportionally by 3 times of  $V_{CON}$ .

If  $V_{CON}$  is over 1.20V ( $V_{OUT} = 3.6V$ ), sub-harmonic oscillation may occur because of insufficient slope compensation.

If  $V_{CON}$  voltage is less than 0.267V ( $V_{OUT} = 0.8V$ ), the output voltage may not be regulated due to the required on-time being less than the minimum on-time (50ns). The output voltage can go lower than 0.8V providing a limited  $V_{IN}$  range is used. Refer to the [Typical Performance Characteristics](#) (Low  $V_{CON}$  Voltage vs. Output Voltage) for details. This curve is for a typical part and there could be part to part variation for output voltages less than 0.8V over the limited  $V_{IN}$  range. In addition, if the  $V_{CON}$  is less than approximately 0.15V, the PWM mode output is turned off, but the internal bias circuits are still active.

### INDUCTOR SELECTION

A 2.2μH inductor with saturation current rating over 940mA is recommended for almost all applications. The inductor resistance should be less than 0.2Ω for better efficiency. [Table 1](#) lists suggested inductors and suppliers.

**Table 1. Suggested Inductors and Their Suppliers**

Model	Size (WxLxH) [mm]	Vendor
DO3314-222MX	3.3 x 3.3 x 1.4	Coilcraft
LPS3010-222MLC	3.1 x 3.1 x 1.0	Coilcraft
LPS3008-222MLC	3.1 x 3.1 x 0.8	Coilcraft
MIPSA2520D2R2**	2.5 x 2.0 x 1.2	FDK
KSLI252010AG2R2*	2.5 x 2.0 x 1.0	Hitachi-Metal
VLF3010AT-2R2M1R0	2.6 x 2.8 x 1.0	TDK
NR3010T2R2M	3.0 x 3.0 x 1.0	Taiyo-Yuden
NR3012T2R2M	3.0 x 3.0 x 1.2	Taiyo-Yuden
1117AS-2R2M(DE2810C)	2.8 x 3.0 x 1.0	Toko

If a higher value inductor is used the LM3280 may become unstable and exhibit large under or over shoot during line, load and  $V_{CON}$  transients. If smaller inductance value is used, slope compensation maybe insufficient causing sub-harmonic oscillations. The device has been tested with inductor values in the range 1.55 $\mu$ H to 3.1 $\mu$ H to account for inductor tolerances.

For low-cost applications, an un-shielded bobbin inductor can be used. For noise-critical applications, an un-shielded or shielded-bobbin inductor should be used. A good practice is to layout the board with footprints accommodating both types for design flexibility. This allows substitution of an un-shielded inductor, in the event that noise from low-cost bobbin models is unacceptable. Saturation occurs when the magnetic flux density from current through the windings of the inductor exceeds what the inductor's core material can support with a corresponding magnetic field. This can cause poor efficiency, regulation errors or stress to a DC-DC converter like the LM3280.

## CAPACITOR SELECTION

The LM3280 is designed to be used with ceramic capacitors. Use a 10 $\mu$ F ceramic capacitor for the power input, a 4.7 $\mu$ F ceramic capacitor for the buck converter output, and a 1 $\mu$ F ceramic capacitor for the LDO and the signal input. Ceramic capacitors such as X5R, X7R and B are recommended for both filters. These provide an optimal balance between small size, cost, reliability and performance for cell phones and similar applications. [Table 2](#) lists suggested capacitors and suppliers.

**Table 2. Suggested Capacitors and Their Suppliers**

Model	Size (EIA)	Vendor
C1608X5R0J475M	1608 (0603)	TDK
C2012X5R0J106M	2012 (0805)	TDK
GRM188B10J105KA01	1608 (0603)	Murata
LMK107BJ105KA	1608 (0603)	Taiyo-Yuden
C1608JB1C105K	1608 (0603)	TDK

The DC bias characteristics of the capacitor must be considered when making the selection. If smaller case size such as 1608 (0603) is selected, the DC bias could reduce the cap value by as much as 40%, in addition to the 20% tolerances and 15% temperature coefficients. Request DC bias curves from manufacturer when making selection. The buck converter has been designed to be stable with output capacitors as low as 3 $\mu$ F to account for capacitor tolerances. The LDO has been done with output capacitors as low as 0.5 $\mu$ F. These values include DC bias reduction, manufacturing tolerances and temp coefficients.

The input filter capacitor supplies AC current drawn by the PFET switch of the LM3280 in the first part of each cycle and reduces the voltage ripple imposed on the input power source. A 1 $\mu$ F capacitor is also recommended close to SVIN pin. The output filter capacitor absorbs the AC inductor current, helps maintain a steady output voltage during transient load changes and reduces output voltage ripple. These capacitors must be selected with sufficient capacitance and sufficiently low ESR (Equivalent Series Resistance) to perform these functions. The ESR of the filter capacitors is generally a major factor in voltage ripple.

## DSBGA PACKAGE ASSEMBLY AND USE

Use of the DSBGA package requires specialized board layout, precision mounting and careful re-flow techniques, as detailed in National Semiconductor Application Note 1112. Refer to the section, *Surface Mount Technology (SMD) Assembly Considerations*. For best results in assembly, alignment ordinals on the PC board should be used to facilitate placement of the device. The pad style used with DSBGA package must be the NSMD (non-solder mask defined) type. This means that the solder-mask opening is larger than the pad size. This prevents a lip that otherwise forms if the solder-mask and pad overlap, from holding the device off the surface of the board and interfering with mounting. See Application Note 1112 for specific instructions how to do this. The 16-Bump package used for the LM3280 has 300 micron solder balls and requires 10.82 mil pads for mounting on the circuit board. The trace to each pad should enter the pad with a 90° entry angle to prevent debris from being caught in deep corners. Initially, the trace to each pad should be 6-7 mil wide, for a section approximately 6 mil long or longer, as a thermal relief. Then each trace should neck up or down to its optimal width. The important criterion is symmetry. This ensures the solder bumps on the LM3280 re-flow evenly and that the device solders level to the board. In particular, special attention must be paid to the pads for bumps B4, C4 and D4. Because PVIN and PGND are typically connected to large copper planes, inadequate thermal relief can result in inadequate re-flow of these bumps.

The DSBGA package is optimized for the smallest possible size in applications with red or infrared opaque cases. Because the DSBGA package lacks the plastic encapsulation characteristic of larger devices, it is vulnerable to light. Backside metallization and/or epoxy coating, along with front-side shading by the printed circuit board, reduce this sensitivity. However, the package has exposed die edges. In particular, Thin Micro DSBGA devices are sensitive to light, in the red and infrared range, shining on the package's exposed die edges.

Do not use or power-up the LM3280 while subjecting it to high intensity red or infrared light; otherwise degraded, unpredictable or erratic operation may result. Examples of light sources with high red or infrared content include the sun and halogen lamps. Place the device in a case opaque to red or infrared light.

## BOARD LAYOUT CONSIDERATIONS

PC board layout is an important part of DC-DC converter design. Poor board layout can disrupt the performance of a DC-DC converter and surrounding circuitry by contributing to EMI, ground bounce, and resistive voltage loss in the traces. These can send erroneous signals to the DC-DC converter, resulting in poor regulation or instability. Poor layout can also result in re-flow problems leading to poor solder joints between the DSBGA package and board pads. Poor solder joints can result in erratic or degraded performance. Good layout for the LM3280 can be implemented by following a few simple design rules.

1. Place the LM3280 on 10.82 mil pads. As a thermal relief, connect to each pad with a 7 mil wide, approximately 7 mil long traces, and when incrementally increase each trace to its optimal width. The important criterion is symmetry to ensure the solder bumps on the LM3280 re-flow evenly (see [DSBGA PACKAGE ASSEMBLY AND USE](#)).
2. Place the LM3280, inductor and filter capacitors close together and make the trace short. The traces between these components carry relatively high switching currents and act as antennas. Following this rule reduces radiated noise. Place the capacitors and inductor close to the LM3280. The input capacitor should be placed right next to the device between PVIN and PGND pin.
3. Arrange the components so that the switching current loops curl in the same direction. During the first half of each cycle, current flows from the input filter capacitor, through the LM3280 and inductor to the output filter capacitor and back through ground, forming a current loop. In the second half of each cycle, current is pulled up from ground, through the LM3280 by the inductor, to the output filter capacitor and then back through ground, forming a second current loop. Routing these loops so the current curls in the same direction, prevents magnetic field reversal between the two half-cycles and reduces radiated noise.
4. Connect the ground pins of the LM3280, and filter capacitors together using generous component side copper fill as a pseudo-ground plane. Then connect this to the ground-plane (if one is used) with several vias. This reduces ground plane noise by preventing the switching currents from circulating through the ground plane. It also reduces ground bounce at the LM3280 by giving it a low impedance ground connection.
5. Use wide traces between the power components and for power connections to the DC-DC converter circuit. This reduces voltage errors caused by resistive losses across the traces.
6. Route noise sensitive traces, such as the voltage feedback trace, away from noisy traces and components. The voltage feedback trace must remain close to the LM3280 circuit and should be routed directly from FB pin to  $V_{OUT}$  at the output capacitor. A good approach is to route the feedback trace on another layer and to have a ground plane between the top layer and the layer on which the feedback trace is routed. This reduces EMI radiation on to the DC-DC converter's own voltage feedback trace.
7. It is recommended to connect BYPOUT pin to  $V_{OUT}$  at the output capacitor using a separate trace, instead of connecting it directly to the FB pin for better noise immunity.

## REVISION HISTORY

<b>Changes from Revision A (February 2013) to Revision B</b>	<b>Page</b>
• Changed layout of National Data Sheet to TI format .....	20

**PACKAGING INFORMATION**

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
LM3280TL-275/NOPB	Active	Production	DSBGA (YZR)   16	250   SMALL T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-30 to 85	V002
LM3280TL-275/NOPB.A	Active	Production	DSBGA (YZR)   16	250   SMALL T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-30 to 85	V002

<sup>(1)</sup> **Status:** For more details on status, see our [product life cycle](#).

<sup>(2)</sup> **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

<sup>(4)</sup> **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

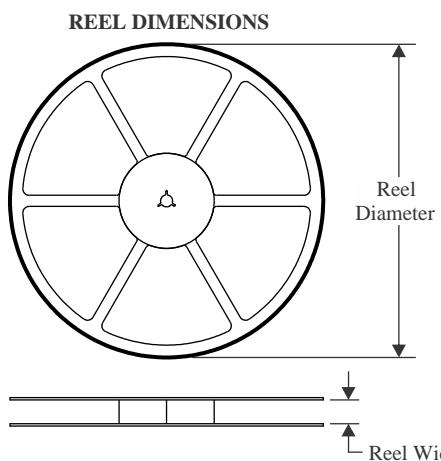
<sup>(5)</sup> **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

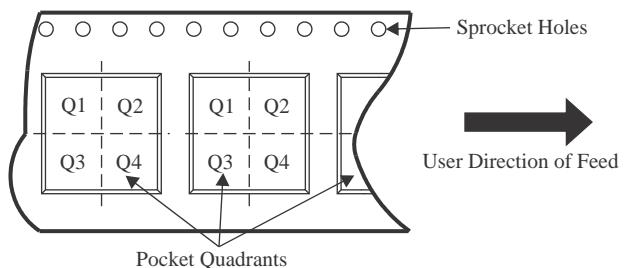
Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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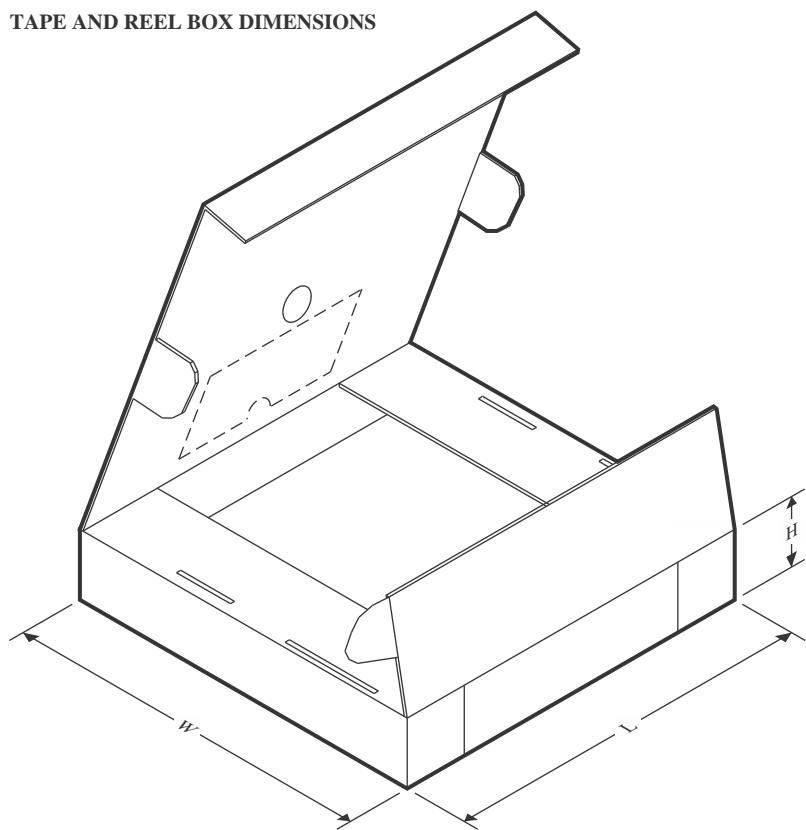
**TAPE AND REEL INFORMATION**


A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**


\*All dimensions are nominal

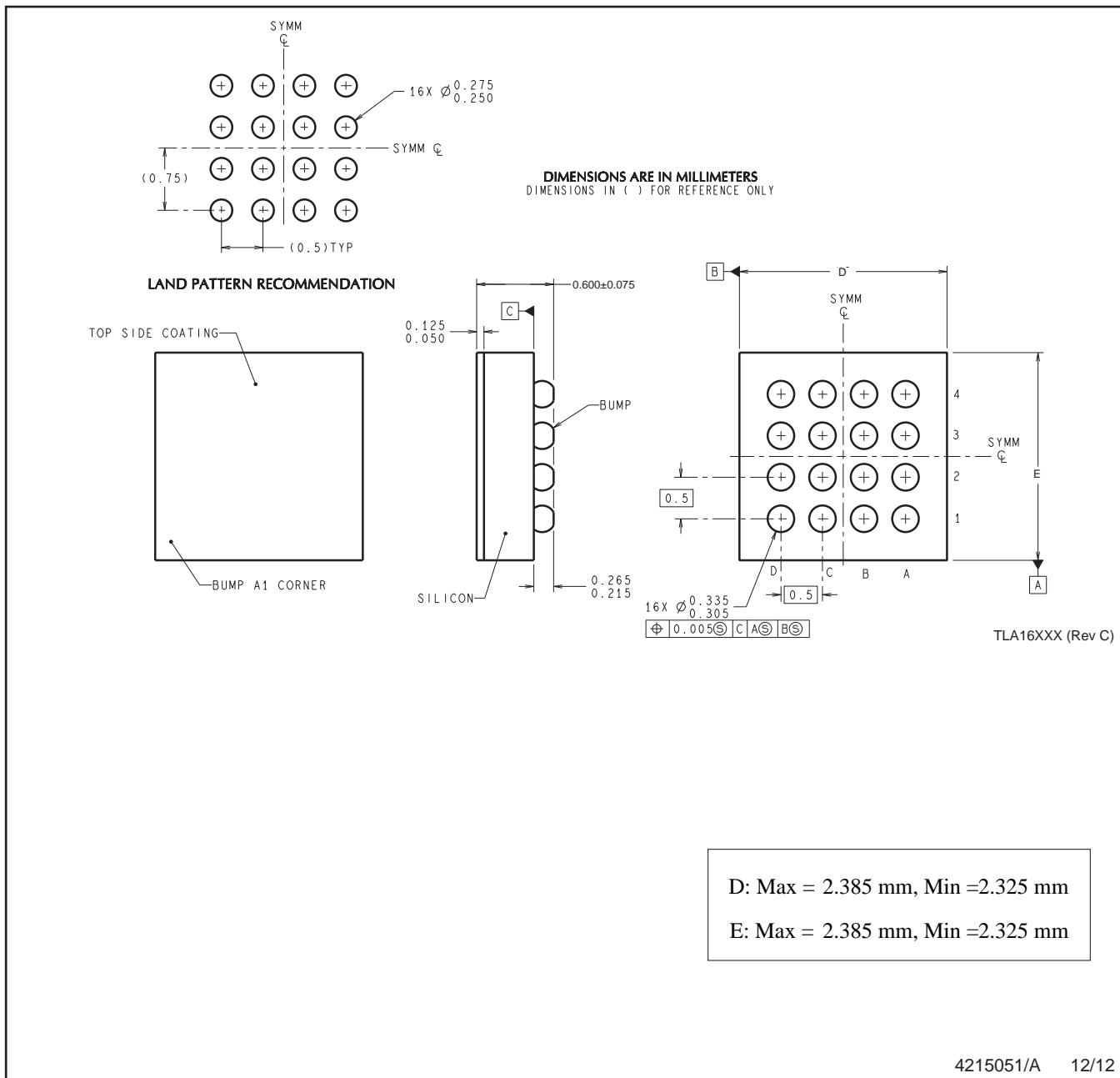
Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LM3280TL-275/NOPB	DSBGA	YZR	16	250	178.0	8.4	2.69	2.69	0.76	4.0	8.0	Q1

**TAPE AND REEL BOX DIMENSIONS**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LM3280TL-275/NOPB	DSBGA	YZR	16	250	208.0	191.0	35.0

YZR0016



NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.  
B. This drawing is subject to change without notice.

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