# **SMC** Information

**SMC Corporation** 

Akihabara UDX 15F, 4-14-1, Sotokanda, Chiyoda-ku, Tokvo 101-0021, JAPAN

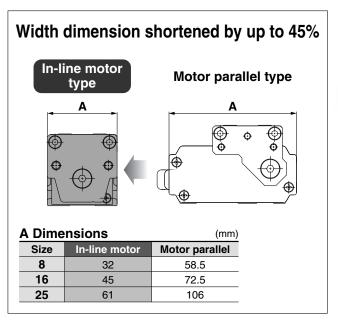
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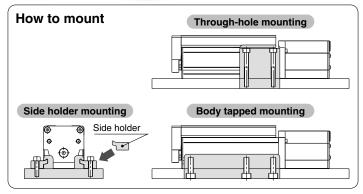
D-DN Printing OW 12450KS

# **Electric Slide Table/In-line Motor Type** Series **LESH** □ **D**

(RoHS

In-line motor type newly added to electric slide table!





#### Reduced cycle time

Max. acceleration and deceleration: 5,000 mm/s<sup>2</sup>

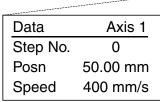
Max. speed: 400 mm/s

●Positioning repeatability: ±0.05 mm

Maximum pushing force: 180 N

●Speed control/Positioning: Max. 64 points





Teaching box screen



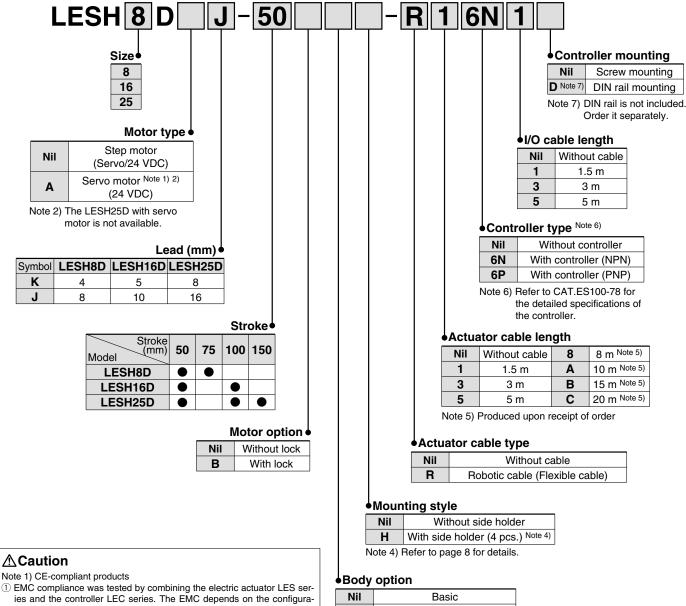
#### Series Variations

		Work load (kg)				Max. speed	Screw lead	Positioning
Model	Stroke (mm)	Step	Step motor		motor	(mm/s)	(mm)	repeatability
		Horizontal	Vertical	Horizontal	Vertical	(11111/0)	(11111)	(mm)
LESH8D	50, 75	2	0.5	2	0.5	200	4	
LESHOD		1	0.25	1	0.25	400	8	
LESH16D	50, 100	6	2	5	2	200	5	10.05
LESHIOD		4	1	2.5	1	400	10	±0.05
LESH25D	50, 100, 150	9	4	_	_	150	8	
		6	2	_	_	400	16	

# **Electric Slide Table/In-line Motor Type** Series LESH **\_ESH8D/16D/25D**

Refer to the LES series catalog (CAT.ES100-78) for more details about model selection

**How to Order** 



- ${f \odot}$  EMC compliance was tested by combining the electric actuator LES sertion of the customer's control panel and the relationship with other electrical equipment and wiring. Therefore conformity to the EMC directive cannot be certified for SMC components incorporated into the customer's equipment under actual operating conditions. As a result it is necessary for the customer to verify conformity to the EMC directive for the machinery and equipment as a whole.
- ② For the servo motor (24 VDC) specification, EMC compliance was tested by installing a noise filter set (LEC-NFA). Refer to CAT.ES100-78 for the noise filter set. Refer to the LECA Operation Manual for installation.

Nil	Basic
S	Dustproof specification Note 3)

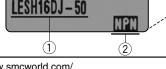
Note 3) A scraper is mounted on the rod.

The actuator and controller are sold as a package. (Controller → Refer to the LES series catalog (CAT.ES100-78)

Confirm that the combination of the controller and the actuator is compatible.

#### <Be sure to check the following before use.>

- 1 Check that actuator label for model number. This matches the controller.
- 2 Check Parallel I/O configuration matches (NPN or PNP).





<sup>\*</sup> Refer to the operation manual for using the products. Please download it via our website. http://www.smcworld.com/





Note 1) Pushing force accuracy is ±20% (F.S.). Note 2) Pushing operation speed is from the minimum speed to 20 mm/s.

Note 3) Vibration resistance: No malfunction occurred in a test ranging between 45 to 2000 Hz. Test was performed in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the slide table in the initial state.)
Impact resistance: No malfunction occurred when the slide table was tested with a drop tester in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the slide table in the initial state.)

Note 4) Power consumption (including the controller) is for when the actuator is operating.

Note 5) Standby power consumption when operating (including the controller) is for when the actuator is stopped in the set position during operation, except during pushing operation.

Note 6) Momentary max. power consumption (including the controller) is for when the actuator is operating. This value can be used for the selection of the power supply.

Note 7) With lock only

Note 8) For an actuator with lock, add the power consumption for the lock.

Note 1) Pushing force range for LESH8DA is between 50 and 75%. Pushing force accuracy is ±20% (F.S.).

Note 2) Pushing operation speed is from the minimum speed to 20 mm/s.

Note 3) Vibration resistance: No malfunction occurred in a test ranging between 45 to 2000 Hz. Test was performed in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the slide table in the initial state.)
Impact resistance: No malfunction occurred when the slide table was tested with a drop tester in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the slide table in the initial state.)

Note 4) Power consumption (including the controller) is for when the actuator is operating.

Note 5) Standby power consumption when operating (including the controller) is for when the actuator is stopped in the set position during operation, except during pushing operation.

Note 6) Momentary max. power consumption (including the controller) is for when the actuator is operating. This value can be used for the selection of the power supply.

Note 7) With lock only

Note 8) For an actuator with lock, add the power consumption for the lock.

#### **Specifications**

#### Step Motor (Servo/24 VDC)

Model		LESH8D		LESH16D		LESH25D		
	Stroke (mm)		50,	75	50, 100		50, 100, 150	
	Work load (kg)	Horizontal	2	1	6	4	9	6
S	Work load (kg)	Vertical	0.5	0.25	2	1	4	2
Ö	Pushing force (N) 3	0% to 70% Note 1)	6 to 15	4 to 10	23.5 to 55	15 to 35	77 to 180	43 to 100
cat	Speed (mm/s)		10 to 200	20 to 400	10 to 200	20 to 400	10 to 150	20 to 400
틍	Pushing speed	(mm/s) Note 2)	10 to 20	20	10 to 20	20	10 to 20	20
be	Positioning repe	atability (mm)		•	±0	.05		
S	Screw lead (mm)		4	8	5	10	8	16
Actuator specifications	Impact/Vibration resist	ance (m/sec <sup>2</sup> ) Note 3)			50,	/20		
믉	Actuation type				Slide	screw		
Ă	Guide type		Linear guide (Circulating type)					
	Operating temp	5 to 40 (No condensation and freezing)						
	Operating humic	lity range (%)	35 to 85 (No condensation and freezing)					
ns	Motor size		□20 □28 □42				42	
읉	Motor type		Step motor (Servo 24 VDC)					
<u>:</u>	Encoder		Incremental A/B phase (800 pulse/rotation)					
specifications	Rated voltage (		24 VDC ±10%					
	Power consump			0	4	3	6	7
Electric	Standby power consumption v			7	1	5	1	3
Sc	Momentary max. power c	onsumption (W) Note 6)	3	5	6	0	7	4
	Controller weig	ht (kg)	0.15	(Screw m	nounting),	0.17 (DIN	rail mount	ing)
t Sus	Туре		Non-energizing operation type					
Lock unit specifications	Holding force (N		24	2.5	300	48	500	77
Sciff	Power consumption	1 (W) Note 8)	4	4	3.6		5	
- sp	Rated voltage (	<b>V</b> )			24 VD0	C ±10%		

#### Servo Motor (24 VDC)

36	Servo Motor (24 VDC)								
	Model		LESH	18DA	LESH16DA				
	Stroke (mm)		50,	75	50, 100				
	Work load (kg)	Horizontal	2	1	5	2.5			
SC	Work load (kg)	Vertical	0.5	0.25	2	1			
ē	Pushing force (N) 50	% to 100% Note 1)	7.5 to 11	5 to 7.5	17.5 to 35	10 to 20			
Actuator specifications	Speed (mm/s)		10 to 200	20 to 400	10 to 200	20 to 400			
i iii	Pushing speed	(mm/s) Note 2)	10 to 20	20	10 to 20	20			
be	Positioning repe	atability (mm)		±0.	05				
2 8	Screw lead (mm		4	8	5	10			
atc	Impact/Vibration resist	ance (m/sec²) Note 3)	50/20						
댫	Actuation type			Slide	screw				
Ă	Guide type		Linear guide (Circulating type)						
	Operating temp	. range (°C)	5 to 40 (No condensation and freezing)						
	Operating humic	lity range (%)	35 to	85 (No conder	sation and free	zing)			
S	Motor size			20	□28				
ö	Motor output (W	/)	10 30						
cat	Motor type		Servo motor (24 VDC)						
ij	Encoder		Incremental A/B phase (800 pulse/rotation)/Z phase						
ğ	Rated voltage (			24 VD0	£10%				
S	Power consump		5	8	8	4			
Ë	Standby power consumption v		4 (Horizonta	l)/7 (Vertical)	2 (Horizontal)	/15 (Vertical)			
Electric specifications	Momentary max. power c	onsumption (W) Note 6)	8	4	124				
	Controller weig	ht (kg)	0.15 (Screw mounting), 0.17 (DIN rail mounting)						
it ons	Туре		Non-energizing operation type						
catio	Holding force (N		24	2.5	300	48			
Lock unit specifications	Power consumption	1 (W) Note 8)		1	3	.6			
- ds	Rated voltage (			24 VD0	£10%				

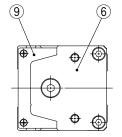
#### Weight

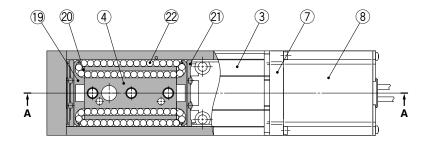
Model		LESH	8D(A)	LESH16D(A)		LESH25D		D
Stroke (mm)		50	75	50	100	50	100	150
Weight (kg)	Without lock	0.57	0.70	1.25	1.70	2.52	3.27	3.60
	With lock	0.66	0.79	1.36	1.81	2.82	3.57	3.90

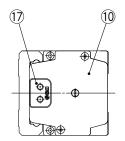


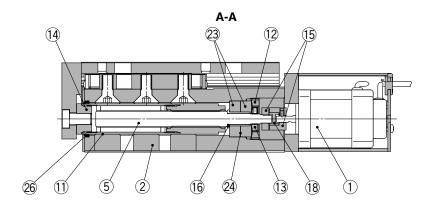
# Series **LESH**□**D**

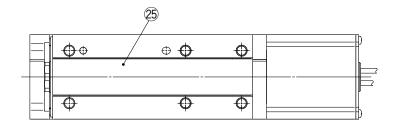
#### Construction













#### **Component Parts**

No.	Description	Material	Note
1	Motor	_	_
2	Body	Aluminum alloy	Anodized
3	Table	Stainless steel	Heat treatment+ Electroless nickel plated
4	Guide block	Stainless steel	Heat treatment
5	Ball screw	Stainless steel	Heat treatment + Specially treated
6	End plate	Aluminum alloy	Anodized
7	Motor flange	Aluminum alloy	Anodized
8	Motor cover	Aluminum alloy	Anodized
9	End cover	Aluminum alloy	Anodized
10	Motor end cover	Aluminum alloy	Anodized
11	Rod	Stainless steel	_
12	Bearing holder	Steel	Electroless nickel plated
13	Lock nut	Steel	Chromate treated
14	Socket	Steel	Electroless nickel plated
15	Hub	Aluminum alloy	_
16	Spacer	Stainless steel	LESH25D□ only
17	Grommet	NBR	_
18	Spider	NBR	_
19	Cover	Synthetic resin	_
20	Return guide	Synthetic resin	_
21	Scraper	Stainless steel + NBR	Linear guide

No.	Description	Material	Note
22	Steel ball	Special steel	_
23	Bearing	_	_
24	Sim ring	Steel	_
25	Masking tape	_	_
26	Scraper	NBR	Only for dustproof specification/Rod
27	Side holder	Aluminum alloy	Anodized

#### **Replacement Parts/Grease Pack**

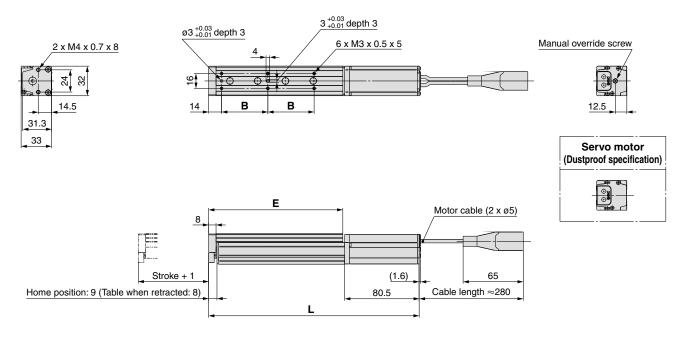
Applied portion	Kit no.
Guide unit	GR-S-010 (10 g) GR-S-020 (20 g)

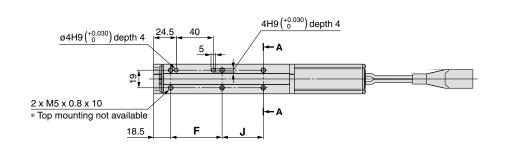


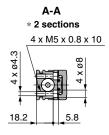
# Electric Slide Table/In-line Motor Type $\,$ Series $LESH\Box D$

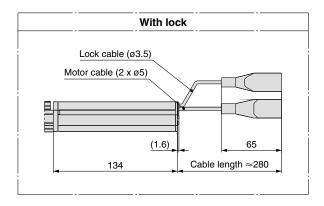
#### **Dimensions**

#### LESH8D









Cable							
Step motor	Servo motor						
20	24						
07	15						
	Step motor						

					(mm)
Model	L	В	E	F	J
LESH8D	201.5	46	119	54.5	10.5
LESH8D 50B	255	46	119	54.5	19.5
LESH8D -75	227.5	50	115	EE E	44.5
LESH8D -75B	281	50	145	55.5	44.5

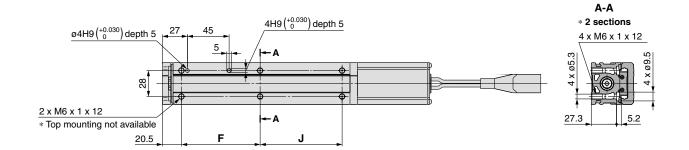
<sup>\*</sup> L is the home position value.

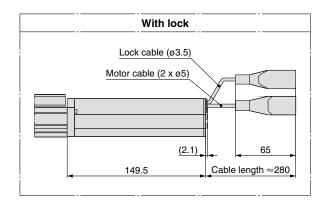


## Series **LESH**□**D**

#### **Dimensions**

#### LESH16D $Ø5^{+0.03}_{+0.01}$ depth 5 **D** x M5 x 0.8 x 6.5 2 x M5 x 0.8 x 9 Manual override screw 8 17 (**D**/2-1) x **B** 37.3 46 Servo motor (Dustproof specification) Ε Motor cable (2 x ø5) \_----(2.1) Stroke + 1 Home position: 10 (Table when retracted: 9) 86 Cable length ≈280





	Cable	
	Step motor	Servo motor
Motor cable	20	24
Lock cable	07	15

						(mm)
Model	L	В	D	E	F	J
LESH16D -50	219.5	40	6	125.5	0.5	20.5
LESH16D -50B	283	40	0	125.5	65	39.5
LESH16D -100	288.5	44	0	000 5	0.5	00.5
LESH16D 100B	352	44	8	200.5	85	88.5

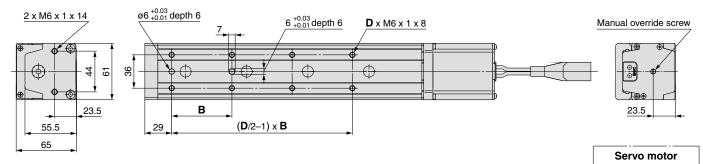
 $<sup>\</sup>ast$  L is the home position value.

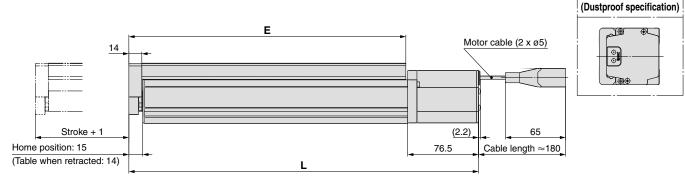


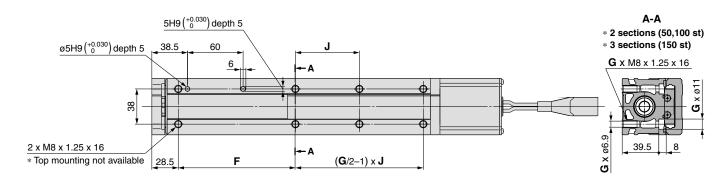
# Electric Slide Table/In-line Motor Type $\,$ Series $LESH\Box D$

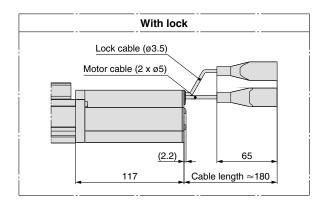
#### **Dimensions**

#### LESH25D









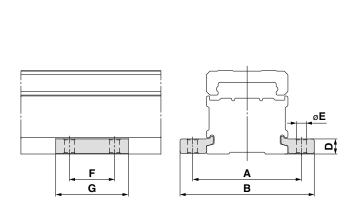
	Cable	
	Step motor	Servo motor
Motor cable	20	24
Lock cable	02	15

							(mm)
Model	L	В	D	E	F	G	J
LESH25D -50	237.5	75	4	157	0.4		40.5
LESH25D -50B	278	75	4	157	84		40.5
LESH25D -100	299.5	40		001	00.5	4	00
LESH25D -100B	340	48	8	221	98.5		88
LESH25D -150	377.5			299	126.5	6	69
LESH25D -150B	418	65					

 $<sup>\</sup>ast$  L is the home position value.

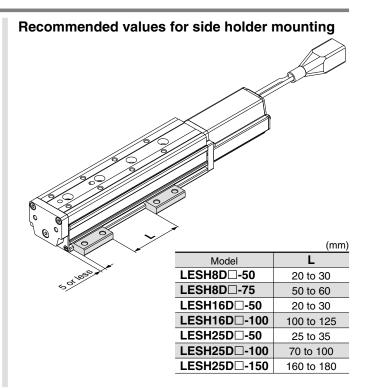
### Series LESH□D

#### **Side Holder**



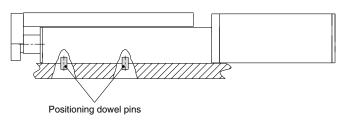
							(mm)
Model number Note)	Α	В	D	Е	F	G	Applicable model
LE-D-3-1	45	57.6	6.4	4.5	20	33	LESH8D
LE-D-3-2	60	74	8.3	5.5	25	40	LESH16D
LE-D-3-3	81	99	12	6.6	30	49	LESH25D

Note) Model numbers for 1 side holder.



### **⚠** Caution

1 Please mount using positioning dowel pins.



② When mounting the body with through holes in the mounting orientations below, please make sure to use two side holders as shown in the figures.

