



# Configurable, Single-/Dual-Output, Synchronous Buck Controller for High-Current Applications

MAX5066

## General Description

The MAX5066 is a two-phase, configurable single- or dual-output buck controller with an input voltage range of 4.75V to 5.5V or from 5V to 28V. Each phase of the MAX5066 is designed for 180° operation. A mode pin allows for a dual-output supply or connecting two phases together for a single-output, high-current supply. Each output channel of the MAX5066 drives n-channel MOSFETs and is capable of providing more than 25A of load current. The MAX5066 uses average current-mode control with a switching frequency up to 1MHz per phase where each phase is 180° out of phase with respect to the other. Out-of-phase operation results in significantly reduced input capacitor ripple current and output voltage ripple in dual-phase, single-output voltage applications. Each buck regulator output has its own high-performance current and voltage-error amplifier that can be compensated for optimum output filter L-C values and transient response.

The MAX5066 offers two enable inputs with accurate turn-on thresholds to allow for output voltage sequencing of the two outputs. The device's switching frequency can be programmed from 100kHz to 1MHz with an external resistor. The MAX5066 can be synchronized to an external clock. Each output voltage is adjustable from 0.61V to 5.5V. Additional features include thermal shutdown, "hiccup mode" short-circuit protection. Use the MAX5066 with adaptive voltage positioning for applications that require a fast transient response, or accurate output voltage regulation.

The MAX5066 is available in a thermally enhanced 28-pin TSSOP package capable of dissipating 1.9W. The device is rated for operation over the -40°C to +85°C extended, or -40°C to +125°C automotive temperature range.

## Applications

High-End Desktop Computers  
Graphics Cards  
Networking Systems  
Point-of-Load High-Current/High-Density  
Telecom DC-DC Regulators  
RAID Systems

## Features

- ◆ 4.75V to 5.5V or 5V to 28V Input
- ◆ Dual-Output Synchronous Buck Controller
- ◆ Configurable for Two Separate Outputs or One Single Output
- ◆ Each Output is Capable of Up to 25A Output Current
- ◆ Average Current-Mode Control Provides Accurate Current Limit
- ◆ 180° Interleaved Operation Reduces Size of Input Filter Capacitors
- ◆ Limits Reverse Current Sinking When Operated in Parallel Mode
- ◆ Each Output is Adjustable from 0.61V to 5.5V
- ◆ Independently Programmable Adaptive Voltage Positioning
- ◆ Independent Shutdown for Each Output
- ◆ 100kHz to 1MHz per Phase Programmable Switching Frequency
- ◆ Oscillator Frequency Synchronization from 200kHz to 2MHz
- ◆ Hiccup Mode Overcurrent Protection
- ◆ Overtemperature Shutdown
- ◆ Thermally Enhanced 28-Pin TSSOP Package Capable of Dissipating 1.9W
- ◆ Operates Over -40°C to +85°C or -40°C to +125°C Temperature Range

## Ordering Information

PART	TEMP RANGE	PIN-PACKAGE
MAX5066EUI	-40°C to +85°C	28 TSSOP-EP*
MAX5066AUI	-40°C to +125°C	28 TSSOP-EP*

\*Exposed Pad

# Configurable, Single-/Dual-Output, Synchronous Buck Controller for High-Current Applications

## ABSOLUTE MAXIMUM RATINGS

IN to AGND ..... -0.3V to +30V  
 BST\_ to AGND ..... -0.3V to +35V  
 DH\_ to LX\_ ..... -0.3V to (V<sub>BST\_</sub> - V<sub>LX\_</sub>) + 0.3V  
 DL\_ to PGND ..... -0.3V to (V<sub>DD</sub> + 0.3V)  
 BST\_ to LX\_ ..... -0.3V to +6V  
 V<sub>DD</sub> to PGND ..... -0.3V to +6V  
 AGND to PGND ..... -0.3V to +0.3V  
 REG, RT/CLKIN, CSP\_, CSN\_ to AGND ..... -0.3V to +6V  
 All Other Pins to AGND ..... -0.3V to (V<sub>REG</sub> + 0.3V)  
 REG Continuous Output Current  
 (Limited by Power Dissipation, No Thermal or Short-Circuit  
 Protection) ..... 67mA

REF Continuous Output Current ..... 200μA  
 Continuous Power Dissipation (T<sub>A</sub> = +70°C)  
 28-Pin TSSOP (derate 23.8mW/°C above +70°C) ..... 1904mW  
 Package Thermal Resistance (θ<sub>JC</sub>) ..... 2°C/W  
 Operating Temperature Ranges  
 MAX5066EUI ..... -40°C to +85°C  
 MAX5066AUI ..... -40°C to +125°C  
 Maximum Junction Temperature ..... +150°C  
 Storage Temperature Range ..... -60°C to +150°C  
 Lead Temperature (soldering, 10s) ..... +300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## ELECTRICAL CHARACTERISTICS

(V<sub>IN</sub> = V<sub>REG</sub> = V<sub>DD</sub> = V<sub>EN\_</sub> = +5V, T<sub>A</sub> = T<sub>J</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted, circuit of Figure 6. Typical values are at T<sub>A</sub> = +25°C.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>SYSTEM SPECIFICATIONS</b>						
Input Voltage Range	V <sub>IN</sub>		5		28	V
		IN and REG shorted together for +5V operation	4.75		5.5	
Quiescent Supply Current	I <sub>IN</sub>	f <sub>OSC</sub> = 500kHz, DH_, DL_ = open		4	20	mA
<b>STARTUP/INTERNAL REGULATOR OUTPUT (REG)</b>						
REG Undervoltage Lockout	UVLO	V <sub>REG</sub> rising	4.0	4.15	4.5	V
Hysteresis	V <sub>HYST</sub>			200		mV
REG Output Accuracy		V <sub>IN</sub> = 5.8V to 28V, I <sub>SOURCE</sub> = 0 to 65mA	4.75	5.10	5.30	V
REG Dropout		V <sub>IN</sub> < 5.8V, I <sub>SOURCE</sub> = 60mA			0.5	V
<b>INTERNAL REFERENCE</b>						
Internal Reference Voltage	V <sub>EAN_</sub>	EAN_ connected to EAOUT_ (Note 2)		0.6135		V
Internal Reference Voltage Accuracy	V <sub>EAN_</sub>	V <sub>IN</sub> = V <sub>REG</sub> = 4.75V to 5.5V or V <sub>IN</sub> = 5V to 28V, EAN_ connected to EAOUT_ (Note 2)	-0.9		+0.9	%
<b>EXTERNAL REFERENCE VOLTAGE OUTPUT (REF)</b>						
Accuracy	V <sub>REF</sub>	I <sub>REF</sub> = 100μA	3.23	3.3	3.37	V
Load Regulation		I <sub>REF</sub> = 0 to 200μA	3.2		3.4	V
<b>MOSFET DRIVERS</b>						
p-Channel Output Driver Impedance	R <sub>ON_P</sub>			1.35	4	Ω
n-Channel Output Driver Impedance	R <sub>ON_N</sub>			0.45	1.35	Ω
Output Driver Source Current	I <sub>DH_</sub> , I <sub>DL_</sub>			2.5		A
Output Driver Sink Current	I <sub>DH_</sub> , I <sub>DL_</sub>			8		A
Nonoverlap Time (Dead Time)	t <sub>NO</sub>	C <sub>DH_</sub> or C <sub>DL_</sub> = 5nF		30		ns

# Configurable, Single-/Dual-Output, Synchronous Buck Controller for High-Current Applications

## ELECTRICAL CHARACTERISTICS (continued)

( $V_{IN} = V_{REG} = V_{DD} = V_{EN\_} = +5V$ ,  $T_A = T_J = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted, circuit of Figure 6. Typical values are at  $T_A = +25^\circ C$ .) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>OSCILLATOR</b>						
Switching Frequency	f <sub>SW</sub>	1MHz (max) switching frequency per phase	R <sub>RT</sub> = 12.4k $\Omega$		1000	kHz
			R <sub>RT</sub> = 127k $\Omega$		100	
Switching Frequency Accuracy		f <sub>SW</sub> = 250kHz nominal, R <sub>RT</sub> = 50k $\Omega$	-7.5		+7.5	%
		f <sub>SW</sub> = 1MHz nominal, R <sub>RT</sub> = 12.4k $\Omega$	-10		+10	
RT/CLKIN Output Voltage	V <sub>RT/CLKIN</sub>			1.225		V
RT/CLKIN Current Sourcing Capability	I <sub>RT/CLKIN</sub>			0.5		mA
RT/CLKIN Logic-High Threshold	V <sub>RT/CLKIN_H</sub>		2.4			V
RT/CLKIN Logic-Low Threshold	V <sub>RT/CLKIN_L</sub>				0.8	V
RT/CLKIN High Pulse Width	t <sub>RT/CLKIN</sub>			30		ns
RT/CLKIN Synchronization Frequency Range	f <sub>RT/CLKIN</sub>		200		2000	kHz
<b>CURRENT LIMIT</b>						
Average Current-Limit Threshold	V <sub>CL_</sub>	V <sub>CSP_</sub> - V <sub>CSEN_</sub>	20.4	22.5	24.75	mV
Reverse Current-Limit Threshold	V <sub>RCL_</sub>	V <sub>CSP_</sub> - V <sub>CSEN_</sub>	-3.13	-1.63	-0.1	mV
Cycle-by-Cycle Current-Limit Threshold	V <sub>CLpk_</sub>	V <sub>CSP_</sub> - V <sub>CSEN_</sub>		52.5		mV
Cycle-by-Cycle Current-Limit Response Time	t <sub>R</sub>			260		ns
<b>DIGITAL FAULT INTEGRATION (DF_)</b>						
Number of Switching Cycles to Shutdown in Current-Limit	NSDF_			32,768		Clock cycles
Number of Switching Cycles to Recover from Shutdown	NRDF_			524,288		Clock cycles
<b>CURRENT-SENSE AMPLIFIER</b>						
CSP_ to CSN_ Input Resistance	R <sub>CS_</sub>			1.9835		k $\Omega$
Common-Mode Range	V <sub>CMR(CS)</sub>	V <sub>IN</sub> = V <sub>REG</sub> = 4.75V to 5.5V or V <sub>IN</sub> = 5V to 10V	-0.3		+3.6	V
		V <sub>IN</sub> = 7V to 28V	-0.3		+5.5	V
Input Offset Voltage	V <sub>OS(CS)</sub>			100		$\mu$ V
Amplifier Gain	A <sub>V(CS)</sub>			36		V/V
-3dB Bandwidth	f <sub>-3dB</sub>			4		MHz
CSP_ Input Bias Current	I <sub>CSA(IN)</sub>	V <sub>CSP_</sub> = 5.5V, sinking			120	$\mu$ A
		V <sub>CSP_</sub> = 0V, sourcing			30	

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## ELECTRICAL CHARACTERISTICS (continued)

( $V_{IN} = V_{REG} = V_{DD} = V_{EN\_} = +5V$ ,  $T_A = T_J = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted, circuit of Figure 6. Typical values are at  $T_A = +25^\circ C$ .) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>CURRENT-ERROR AMPLIFIER (CEA_)</b>						
Transconductance	$g_m$			550		$\mu S$
Open-Loop Gain	$A_{VOL}(CEA)$	No load		50		dB
<b>VOLTAGE ERROR AMPLIFIER (EAOUT_)</b>						
Open-Loop Gain	$A_{VOL}(EA)$			70		dB
Unity-Gain Bandwidth	$f_{UGEA}$			3		MHz
EAOUT_ Input Bias Current	$I_{BIAS}(EA)$	$V_{EAOUT\_} = 2.0V$		100		nA
Error Amplifier Output Clamping High Voltage	$V_{CLMP\_HI}(EA)$	With respect to $V_{CM}$		1.14		V
Error Amplifier Output Clamping Low Voltage	$V_{CLMP\_LO}(EA)$	With respect to $V_{CM}$		-0.234		V
<b>EN_ INPUTS</b>						
EN_ Input High Voltage	$V_{ENH}$	EN rising	1.204	1.222	1.240	V
EN_ Hysteresis				0.05		
EN_ Input Leakage Current	$I_{EN}$		-1		+1	$\mu A$
<b>MODE INPUT</b>						
MODE Logic-High Threshold	$V_{MODE\_H}$		2.4			V
MODE Logic-Low Threshold	$V_{MODE\_L}$				0.8	V
MODE Input Pulldown	$I_{PULLDWN}$			5		$\mu A$
<b>THERMAL SHUTDOWN</b>						
Thermal Shutdown	$T_{SHDN}$			160		$^\circ C$
Thermal Shutdown Hysteresis	$T_{HYST}$			10		

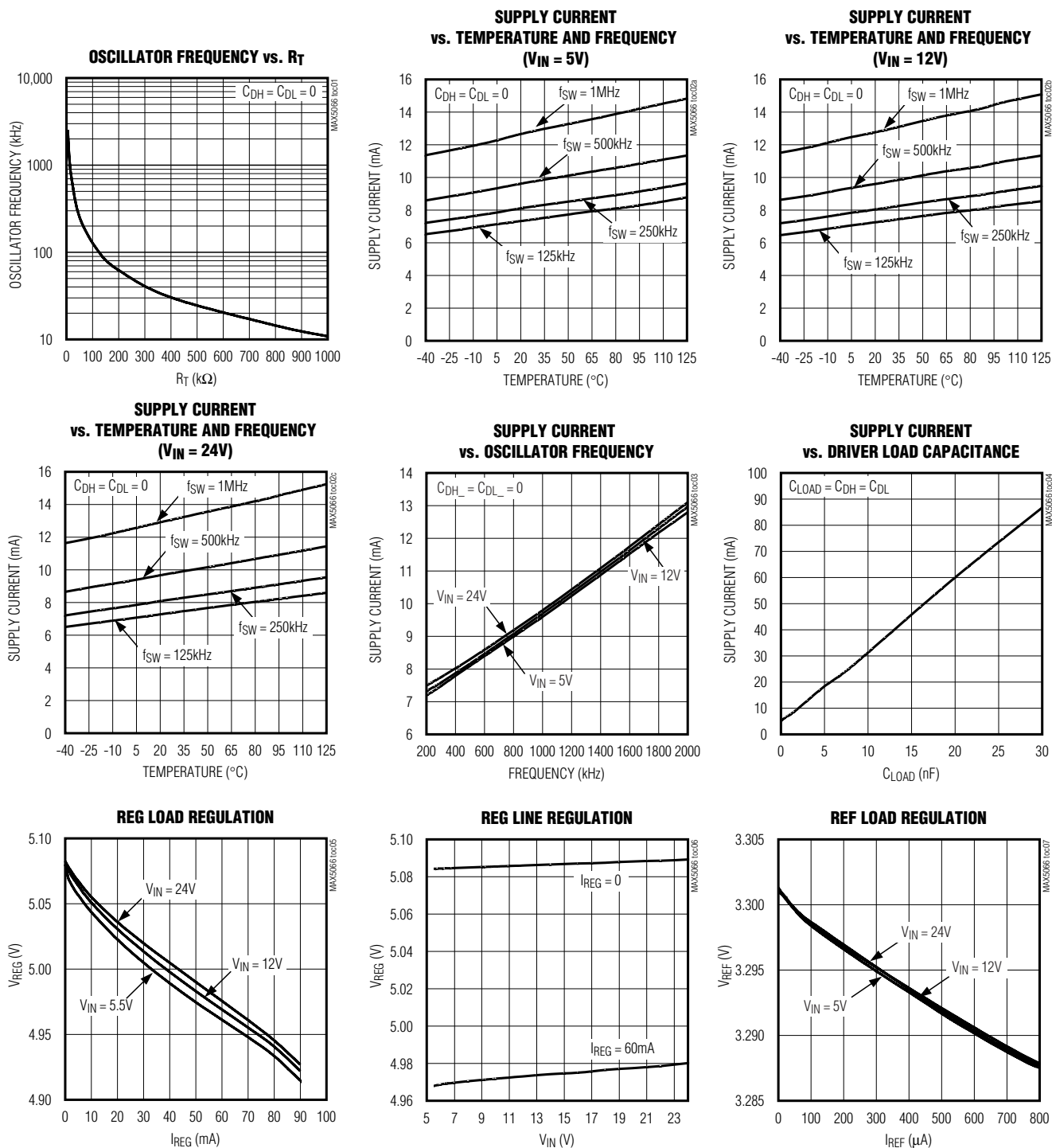
**Note 1:** The device is 100% production tested at  $T_A = +85^\circ C$  (MAX5066EUI) and  $T_A = T_J = +125^\circ C$  (MAX5066AUI). Limits at  $-40^\circ C$  and  $+25^\circ C$  are guaranteed by design.

**Note 2:** The internal reference voltage accuracy is measured at the negative input of the error amplifiers (EAOUT\_). Output voltage accuracy must include external resistor-divider tolerances.

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## Typical Operating Characteristics

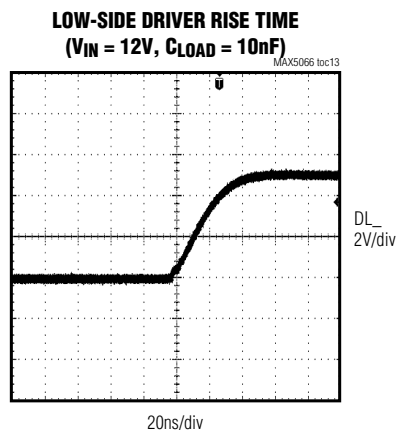
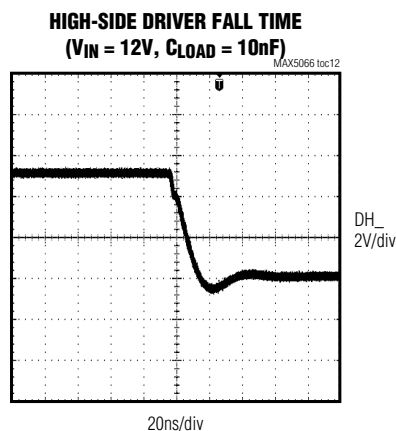
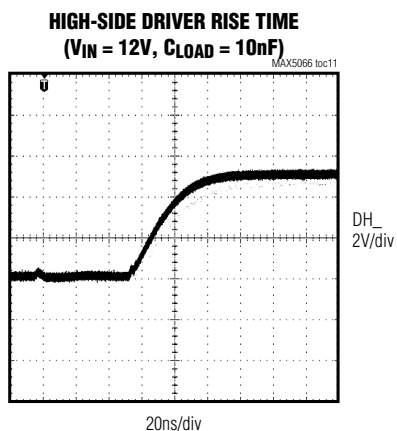
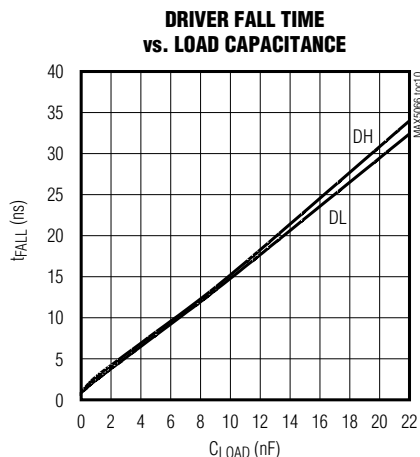
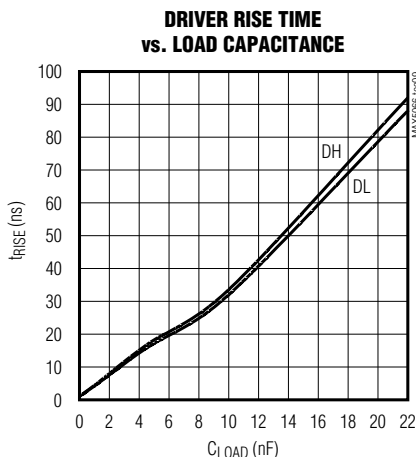
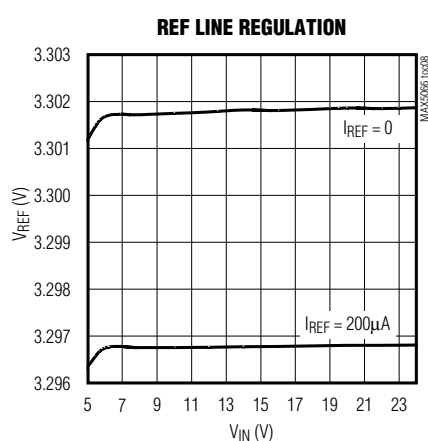
(Circuit of Figure 6,  $T_A = +25^\circ\text{C}$ , unless otherwise noted.  $V_{IN} = 12\text{V}$ ,  $V_{OUT1} = 0.8\text{V}$ ,  $V_{OUT2} = 1.3\text{V}$ ,  $f_{SW} = 500\text{kHz}$  per phase.)



# Configurable, Single-/Dual-Output, Synchronous Buck Controller for High-Current Applications

## Typical Operating Characteristics (continued)

(Circuit of Figure 6,  $T_A = +25^\circ\text{C}$ , unless otherwise noted.  $V_{IN} = 12\text{V}$ ,  $V_{OUT1} = 0.8\text{V}$ ,  $V_{OUT2} = 1.3\text{V}$ ,  $f_{SW} = 500\text{kHz}$  per phase.)

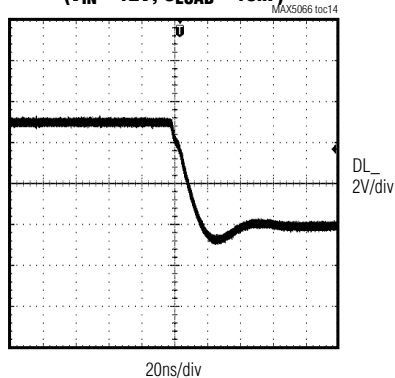


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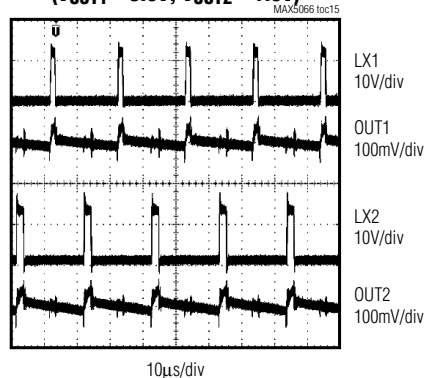
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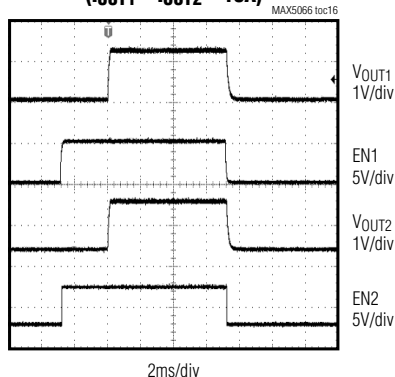
**LOW-SIDE DRIVER FALL TIME**  
( $V_{IN} = 12\text{V}$ ,  $C_{LOAD} = 10\text{nF}$ )



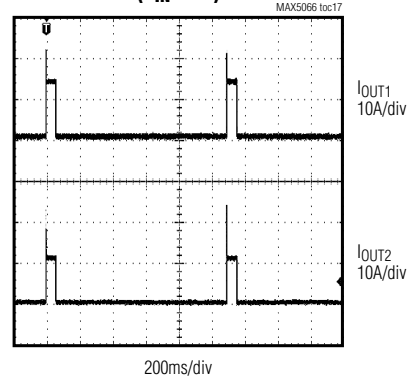
**OUT1/OUT2 OUT-OF-PHASE WAVEFORMS**  
( $V_{OUT1} = 0.8\text{V}$ ,  $V_{OUT2} = 1.3\text{V}$ )



**TURN-ON/-OFF WAVEFORMS**  
( $I_{OUT1} = I_{OUT2} = 10\text{A}$ )



**SHORT-CIRCUIT CURRENT WAVEFORMS**  
( $V_{IN} = 5\text{V}$ )



# Configurable, Single-/Dual-Output, Synchronous Buck Controller for High-Current Applications

## Pin Description

PIN	NAME	FUNCTION
1	CSN2	Current-Sense Differential Amplifier Negative Input for Output2. Connect CSN2 to the negative terminal of the sense resistor. The differential voltage between CSP2 and CSN2 is internally amplified by the current-sense amplifier ( $A_{V(CS)} = 36V/V$ ).
2	CSP2	Current-Sense Differential Amplifier Positive Input for Output2. Connect CSP2 to the positive terminal of the sense resistor. The differential voltage between CSP2 and CSN2 is internally amplified by the current-sense amplifier ( $A_{V(CS)} = 36V/V$ ).
3	EAOUT2	Voltage Error-Amplifier Output2. Connect to an external gain-setting feedback resistor. The error-amplifier gain determines the output voltage load regulation for adaptive voltage positioning. This output also serves as the compensation network connection from EAOUT2 to EAN2. A resistive network results in a drooped output voltage regulation characteristic. An integrator configuration results in very tight output voltage regulation (see the <i>Adaptive Voltage Positioning</i> section).
4	EAN2	Voltage Error-Amplifier Inverting Input for Output2. Connect a resistive divider from VOUT2 to EAN2 to AGND to set the output voltage. A compensation network connects from EAOUT2 to EAN2. A resistive network results in a drooped output-voltage-regulation characteristic. An integrator configuration results in very tight output-voltage regulation (see the <i>Adaptive Voltage Positioning</i> section).
5	CLP2	Current-Error Amplifier Output2. Compensate the current loop by connecting an R-C network from CLP2 to AGND.
6	REF	3.3V Reference Output. Bypass REF to AGND with a minimum 0.1 $\mu$ F ceramic capacitor. REF can source up to 200 $\mu$ A for external loads.
7	RT/CLKIN	External Clock Input or Internal Frequency-Setting Connection. Connect a resistor from RT/CLKIN to AGND to set the switching frequency. Connect an external clock at RT/CLKIN for external frequency synchronization.
8	AGND	Analog Ground
9	MODE	Mode Function Input. MODE selects between a single-output dual phase or a dual-output buck regulator. When MODE is grounded, VEA1 and VEA2 connect to CEA1 and CEA2, respectively (see Figure 1) and the device operates as a two-output, out-of-phase buck regulator. When MODE is connected to REG (logic high), VEA2 is disconnected and VEA1 is routed to both CEA1 and CEA2.
10	CLP1	Current-Error Amplifier Output1. Compensate the current loop by connecting an R-C network from CLP1 to AGND.
11	EAN1	Voltage Error Amplifier Inverting Input for Output1. Connect a resistive divider from VOUT1 to EAN1 to regulate the output voltage. A compensation network connects from EAOUT1 to EAN1. A resistive network results in a drooped output-voltage-regulation characteristic. An integrator configuration results in very tight output voltage regulation (see the <i>Adaptive Voltage Positioning</i> section).
12	EAOUT1	Voltage Error Amplifier Output1. Connect to an external gain-setting feedback resistor. The error amplifier gain determines the output-voltage-load regulation for adaptive voltage positioning. This output also serves as the compensation network connection from EAOUT1 to EAN1. A resistive network results in a drooped output-voltage-regulation characteristic. An integrator configuration results in very tight output-voltage regulation (see the <i>Adaptive Voltage Positioning</i> section).
13	CSP1	Current-Sense Differential Amplifier Positive Input for Output1. Connect CSP1 to the positive terminal of the sense resistor. The differential voltage between CSP1 and CSN1 is internally amplified by the current-sense amplifier ( $A_{V(CS)} = 36V/V$ ).

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## Pin Description (continued)

PIN	NAME	FUNCTION
14	CSN1	Current-Sense Differential Amplifier Negative Input for Output1. Connect CSN1 to the negative terminal of the sense resistor. The differential voltage between CSP1 and CSN1 is internally amplified by the current-sense amplifier ( $A_V(CS) = 36V/V$ ).
15	EN1	Output 1 Enable. A logic-low shuts down channel 1's MOSFET drivers. EN1 can be used for output sequencing.
16	BST1	Boost Flying Capacitor Connection. Reservoir capacitor connection for the high-side MOSFET driver supply. Connect a 0.47 $\mu$ F ceramic capacitor between BST1 and LX1.
17	DH1	High-Side Gate Driver Output1. DH1 drives the gate of the high-side MOSFET.
18	LX1	External inductor connection and source connection for the high-side MOSFET for Output1. LX1 also serves as the return terminal for the high-side MOSFET driver.
19	DL1	Low-Side Gate Driver Output1. Gate driver output for the synchronous MOSFET.
20	V <sub>DD</sub>	Supply Voltage for Low-Side Drivers. REG powers V <sub>DD</sub> . Connect a parallel combination of 0.1 $\mu$ F and 1 $\mu$ F ceramic capacitors from V <sub>DD</sub> to PGND and a 1 $\Omega$ resistor from V <sub>DD</sub> to REG to filter out the high-peak currents of the driver from the internal circuitry.
21	REG	Internal 5V Regulator Output. REG is derived internally from IN and is used to power the internal bias circuitry. Bypass REG to AGND with a 4.7 $\mu$ F ceramic capacitor.
22	IN	Supply Voltage Connection. Connect IN to a 5V to 28V input supply.
23	PGND	Power Ground. Source connection for the low-side MOSFET. Connect V <sub>DD</sub> 's bypass capacitor returns to PGND.
24	DL2	Low-Side Gate Driver Output2. Gate driver for the synchronous MOSFET.
25	LX2	External inductor connection and source connection for the high-side MOSFET for Output2. Also serves as the return terminal for the high-side MOSFET driver.
26	DH2	High-Side Gate Driver Output2. DH2 drives the gate of the high-side MOSFET.
27	BST2	Boost Flying Capacitor Connection. Reservoir capacitor connection for the high-side MOSFET driver supply. Connect a 0.47 $\mu$ F ceramic capacitor between BST2 and LX2.
28	EN2	Output 2 Enable. A logic-low shuts down channel 2's MOSFET drivers. EN2 can be used for output sequencing.
EP	EP	Exposed Pad. Connect exposed pad to ground plane.

## Detailed Description

The MAX5066 switching power-supply controller can be configured in two ways. With the MODE input high, it operates as a single-output, dual-phase, step-down switching regulator where each output is 180° out of phase. With the MODE pin connected low, the MAX5066 operates as a dual-output, step-down switching regulator. The average current-mode control topology of the MAX5066 offers high-noise immunity while having benefits similar to those of peak current-mode control. Average current-mode control has the intrinsic ability to accurately limit the average current sourced by the converter during a fault condition. When a fault condition occurs, the error amplifier output voltage

(EAOUT1 or EAOUT2) that connects to the positive input of the transconductance amplifier (CA1 or CA2) is clamped thus limiting the output current.

The MAX5066 contains all blocks necessary for two independently regulated average current-mode PWM regulators. It has two voltage error amplifiers (VEA1 and VEA2), two current-error amplifiers (CEA1 and CEA2), two current-sensing amplifiers (CA1 and CA2), two PWM comparators (CPWM1 and CPWM2), and drivers for both low- and high-side power MOSFETs (see Figure 1). Each PWM section is also equipped with a pulse-by-pulse, current-limit protection and a fault integration block for hiccup protection.

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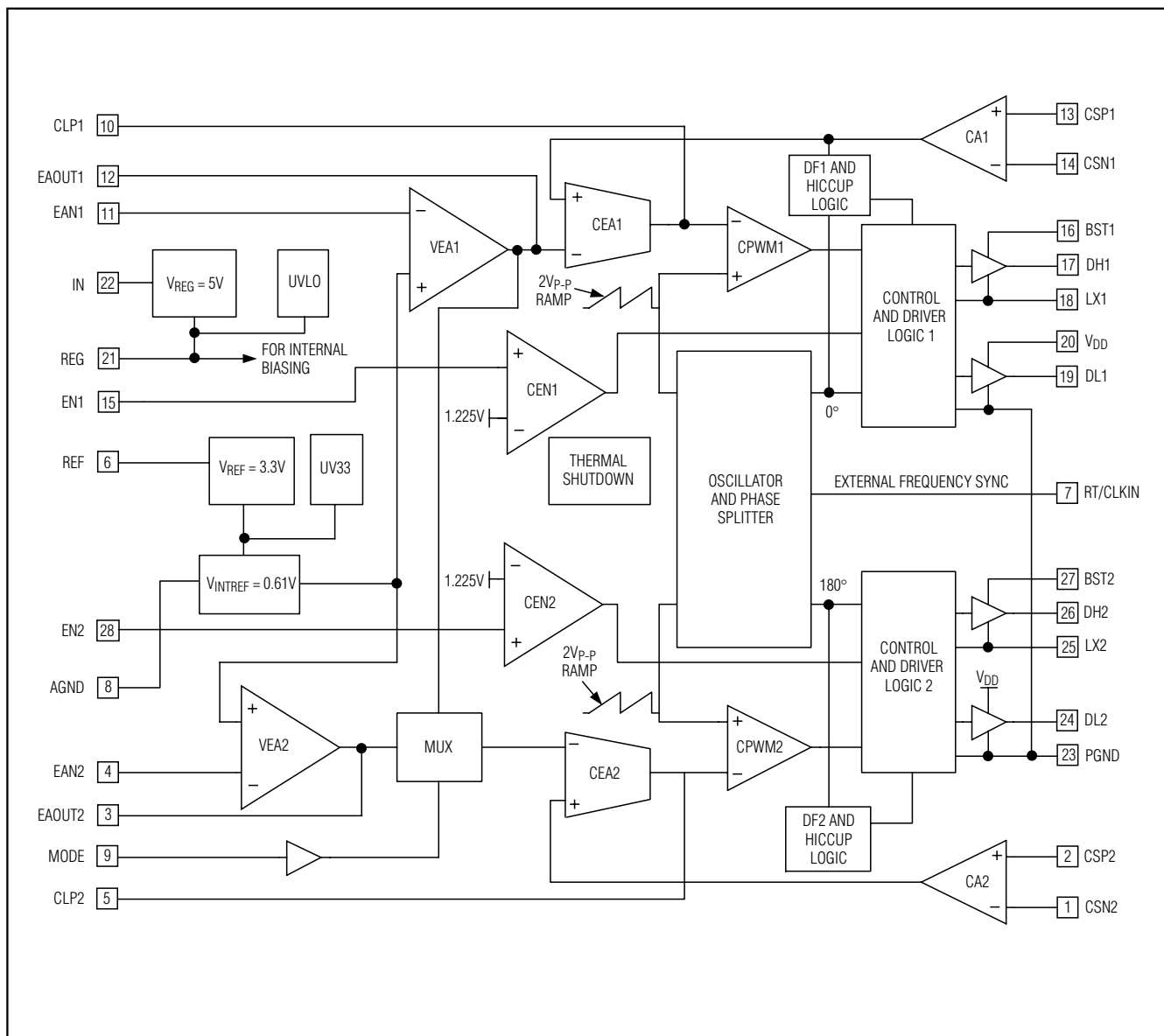


Figure 1. Block Diagram

Two enable comparators (CEN1 and CEN2) are available to control and sequence the two PWM sections through the enable (EN1 or EN2) inputs. An oscillator, with an externally programmable frequency generates two clock pulse trains and two ramps for both PWM sections. The two clocks and the two ramps are 180° out of phase with each other.

A linear regulator (REG) generates the 5V to supply the device. This regulator has the output-current capability

necessary to provide for the MAX5066's internal circuitry and the power for the external MOSFET's gate drivers. A low-current linear regulator (REF) provides a precise 3.3V reference output and is capable of driving loads of up to 200μA. Internal UVLO circuitry ensures that the MAX5066 starts up only when VREG and VREF are at the correct voltage levels to guarantee safe operation of the IC and of the power MOSFETs.

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Finally, a thermal-shutdown feature protects the device during thermal faults and shuts down the MAX5066 when the die temperature exceeds +160°C.

## Dual-Output/Dual-Phase Select (MODE)

The MAX5066 can operate as a dual-output independently regulated buck converter, or as a dual-phase, single-output buck converter. The MODE input selects between the two operating modes. When MODE is grounded (logic low), VEA1 and VEA2 connect to CEA1 and CEA2, respectively (see Figure 1) and the device operates as a two-output DC-DC converter. When MODE is connected to REG (logic high), VEA2 is disconnected and VEA1 is routed to both CEA1 and CEA2 and the device works as a dual-phase, single-output buck regulator with each output 180° out of phase with respect to each other.

## Supply Voltage Connections (VIN/VREG)

The MAX5066 accepts a wide input voltage range at IN of 5V to 28V. An internal linear regulator steps down VIN to 5.1V (typ) and provides power to the MAX5066. The output of this regulator is available at REG. For VIN = 4.75V to 5.5V, connect IN and REG together externally. REG can supply up to 65mA for external loads. Bypass REG to AGND with a 4.7µF ceramic capacitor for high-frequency noise rejection and stable operation.

REG supplies the current for both the MAX5066's internal circuitry and for the MOSFET gate drivers (when connected externally to VDD), and can source up to 65mA. Calculate the maximum bias current (IBIAS) for the MAX5066:

$$I_{BIAS} = I_{IN} + f_{SW} \times (Q_{GQ1} + Q_{GQ2} + Q_{GQ3} + Q_{GQ4})$$

where IIN is the quiescent supply current into IN (4mA, typ), QGQ1, QGQ2, QGQ3, QGQ4 are the total gate charges of MOSFETs Q1 through Q4 at VGS = 5V (see Figure 6), and fSW is the switching frequency of each individual phase.

## Low-Side MOSFET Driver Supply (VDD)

VDD is the power input for the low-side MOSFET drivers. Connect the regulator output REG externally to VDD through an R-C lowpass filter. Use a 1Ω resistor and a parallel combination of 1µF and 0.1µF ceramic capacitors to filter out the high peak currents of the MOSFET drivers from the sensitive internal circuitry.

## High-Side MOSFET Drive Supply (BST\_)

BST1 and BST2 supply the power for the high-side MOSFET drivers for output 1 and output 2, respectively. Connect BST1 and BST2 to VDD through rectifier

diodes D1 and D2 (see Figure 6). Connect a 0.1µF ceramic capacitor between BST\_ and LX\_.

Minimize the trace inductance from BST\_ and VDD to rectifier diodes, D1 and D2, and from BST\_ and LX\_ to the boost capacitors, C8 and C9 (see Figure 6). This is accomplished by using short, wide trace lengths.

## Undervoltage Lockout (UVLO)/Power-On Reset (POR)/Soft-Start

The MAX5066 includes an undervoltage lockout (UVLO) with hysteresis, and a power-on reset circuit for converter turn-on and monotonic rise of the output voltage. The UVLO threshold monitors VREG and is internally set between 4.0V and 4.5V with 200mV of hysteresis. Hysteresis eliminates "chattering" during startup. Most of the internal circuitry, including the oscillator, turns on when VREG reaches 4.5V. The MAX5066 draws up to 4mA (typ) of current before VREG reaches the UVLO threshold.

The compensation network at the current-error amplifiers (CLP1 and CLP2) provides an inherent soft-start of the output voltage. It includes (R14 and C10) in parallel with C11 at CLP1 and (R15 and C12) in parallel with C13 at CLP2 (see Figure 6). The voltage at the current-error amplifier output limits the maximum current available to charge the output capacitors. The capacitor at CLP\_ in conjunction with the finite output-drive current of the current-error amplifier yields a finite rise time for the output current and thus the output voltage.

## Setting the Switching Frequency (fsw)

An internal oscillator generates the 180° out-of-phase clock signals required for both PWM modulators. The oscillator also generates the 2Vp-p voltage ramps necessary for the PWM comparators. The oscillator frequency can be set from 200kHz to 2MHz by an external resistor (RT) connected from RT/CLKIN to AGND (see Figure 6). The equation below shows the relationship between RT and the switching frequency:

$$f_{OSC} = \frac{2.5 \times 10^{10}}{R_{RT}} \text{ Hz}$$

where RRT is in ohms and fSW(PER PHASE) = fOSC/2.

Use RT/CLKIN as a clock input to synchronize the MAX5066 to an external frequency (fRT/CLKIN). Applying an external clock to RT/CLKIN allows each PWM section to work at a frequency equal to fRT/CLKIN/2. An internal comparator with a 1.6V threshold detects fRT/CLKIN. If fRT/CLKIN is present, internal logic switches from the internal oscillator clock, to the clock present at RT/CLKIN.

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## Hiccup Fault Protection

The MAX5066 includes overload fault protection circuitry that prevents damage to the power MOSFETs. The fault protection consists of two digital fault integration blocks that enable “hiccuping” under overcurrent conditions. This circuit works as follows: for every clock cycle the current-limit threshold is exceeded, the fault integration counter increments by one count. Thus, if the current-limit condition persists, then the counter reaches its shutdown threshold in 32,768 counts and shuts down the external MOSFETs. When the MAX5066 shuts down due to a fault, the counter begins to count down, (since the current-limit condition has ended), once every 16 clock cycles. Thus, the device counts down for 524,288 clock cycles. At this point, switching resumes. This produces an effective duty cycle of 6.25% power-up and 93.75% power-down under fault conditions. With a switching frequency set to 250kHz, power-up and power-down times are approximately 131ms and 2.09s, respectively.

## Control Loop

The MAX5066 uses an average current-mode control topology to regulate the output voltage. The control

loop consists of an inner current loop and an outer voltage loop. The inner current loop controls the output current, while the outer voltage loop controls the output voltage. The inner current loop absorbs the inductor pole, reducing the order of the outer voltage loop to that of a single-pole system. Figure 2 is the block diagram of OUT1's control loop.

The current loop consists of a current-sense resistor,  $R_{SENSE}$ , a current-sense amplifier (CA1), a current-error amplifier (CEA1), an oscillator providing the carrier ramp, and a PWM comparator (CPWM1). The precision current-sense amplifier (CA1) amplifies the sense voltage across  $R_{SENSE}$  by a factor of 36. The inverting input to CEA1 senses the output of CA1. The output of CEA1 is the difference between the voltage-error amplifier output (EAOUT1) and the gained-up voltage from CA1. The RC compensation network connected to CLP1 provides external frequency compensation for the respective CEA1 (see the *Compensation* section). The start of every clock cycle enables the high-side driver and initiates a PWM on-cycle. Comparator CPWM1 compares the output voltage from CEA1 against a 0 to 2V ramp from the

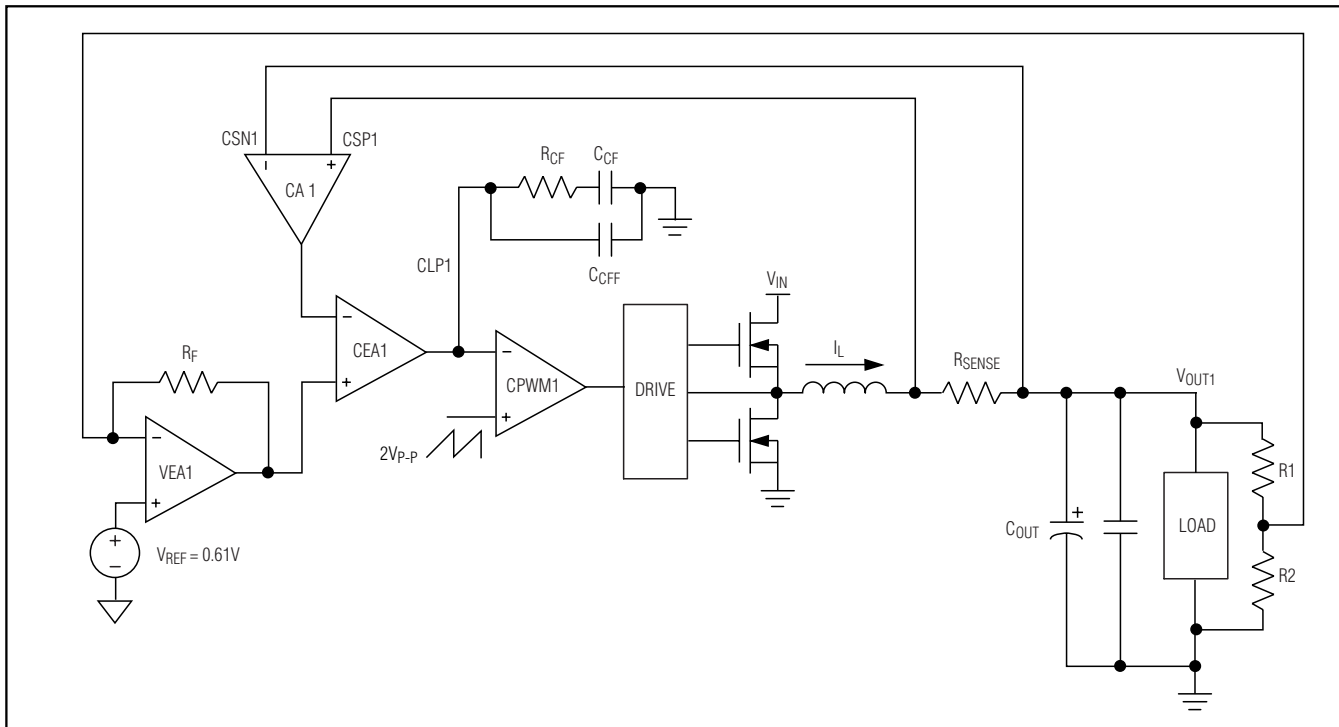


Figure 2. Current and Voltage Loops

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oscillator. The PWM on-cycle terminates when the ramp voltage exceeds the error voltage from the current-error amplifier (CEA1).

The outer voltage control loop consists of the voltage-error amplifier (VEA1). The noninverting input (EAN1) is externally connected to the midpoint of a resistive voltage-divider from OUT1 to EAN1 to AGND. The voltage loop gain is set by using an external resistor from the output of this amplifier (EAOUT1) to its inverting input (EAN1). The noninverting input of (VEA1) is connected to the 0.61V internal reference.

## Peak-Current Comparator

The peak-current comparator (see Figure 3) monitors the voltage across the current-sense resistor (R<sub>SENSE</sub>) and provides a fast cycle-by-cycle current limit with a threshold of 52.5mV. Note that the average current-limit threshold of 22.5mV still limits the output current during short-circuit conditions. To prevent inductor saturation, select an output inductor with a saturation current specification greater than the average current limit of 22.5mV/R<sub>SENSE</sub>. Proper inductor selection ensures that only extreme conditions trip the peak-current comparator, such as a damaged output inductor. The typical propagation delay of the peak current-limit comparator is 260ns.

## Current-Error Amplifier

The MAX5066 has two dedicated transconductance current-error amplifiers CEA1 and CEA2 with a typical g<sub>m</sub> of 550μS and 320μA output sink and source capability. The current-error amplifier outputs (CLP1 and CLP2) serve as the inverting input to the PWM comparators. CLP1 and CLP2 are externally accessible to provide frequency compensation for the inner current loops (see CCFF, CCF, and RCF in Figure 2). Compensate the current-error amplifier such that the inductor current down slope, which becomes the up slope at the inverting input of the PWM comparator, is less than the slope of the internally generated voltage ramp (see the *Compensation* section).

## PWM Comparator and R-S Flip-Flop

The PWM comparator (CPWM1 or CPWM2) sets the duty cycle for each cycle by comparing the current-error amplifier output to a 2V<sub>P-P</sub> ramp. At the start of each clock cycle an R-S flip-flop resets and the high-side drivers (DH1 and DH2) turn on. The comparator sets the flip-flop as soon as the ramp voltage exceeds the current-error amplifier output voltage, thus terminating the on cycle.

## Voltage Error Amplifier

The voltage-error amplifier (VEA<sub>1</sub>) sets the gain of the voltage control loop. Its output clamps to 1.14V and -0.234V relative to V<sub>CM</sub> = 0.61V. Set the MAX5066 output voltage by connecting a voltage-divider from the output to EAN<sub>1</sub> to GND (see Figure 4). At no load the output of the voltage error amplifier is zero.

Use the equation below to calculate the no load voltage:

$$V_{OUT(NL)} = 0.6135 \times \left(1 + \frac{R_1}{R_2}\right)$$

The voltage at full load is given by:

$$V_{OUT(FL)} = 0.6135 \times \left(1 + \frac{R_1}{R_2}\right) - \Delta V_{OUT}$$

where  $\Delta V_{OUT}$  is the voltage-positioning window described in the *Adaptive Voltage Positioning* section.

## Adaptive Voltage Positioning

Powering new-generation ICs requires new techniques to reduce cost, size, and power dissipation. Voltage positioning (Figure 5) reduces the total number of output capacitors to meet a given transient response requirement. Setting the no-load output voltage slightly higher than the output voltage during nominally loaded conditions allows a larger downward voltage excursion when the output current suddenly increases. Regulating at a lower output voltage under a heavy load allows a larger upward-voltage excursion when the output current suddenly decreases. A larger allowed voltage-step excursion reduces the required number of output capacitors and/or allows the use of higher ESR capacitors.

The internal 0.61V reference in the MAX5066 has a tolerance of ±0.9%. If we use 0.1% resistors for R<sub>1</sub> and R<sub>2</sub>, we still have another 4% available for the variation in the output voltage from nominal. This available voltage range allows us to reduce the total number of output capacitors to meet a given transient response requirement. This results in a voltage-positioning window as shown in Figure 5.

From the allowable voltage-positioning window we can calculate the value of R<sub>F</sub> from the equation below.

$$R_F = \frac{I_{OUT} \times R_{SENSE} \times 36 \times R_1}{\Delta V_{OUT}}$$

where  $\Delta V_{OUT}$  is the allowable voltage-positioning window, R<sub>SENSE</sub> is the sense resistor, 36 is the current-sense amplifier gain, and R<sub>1</sub> is as shown in Figure 4.

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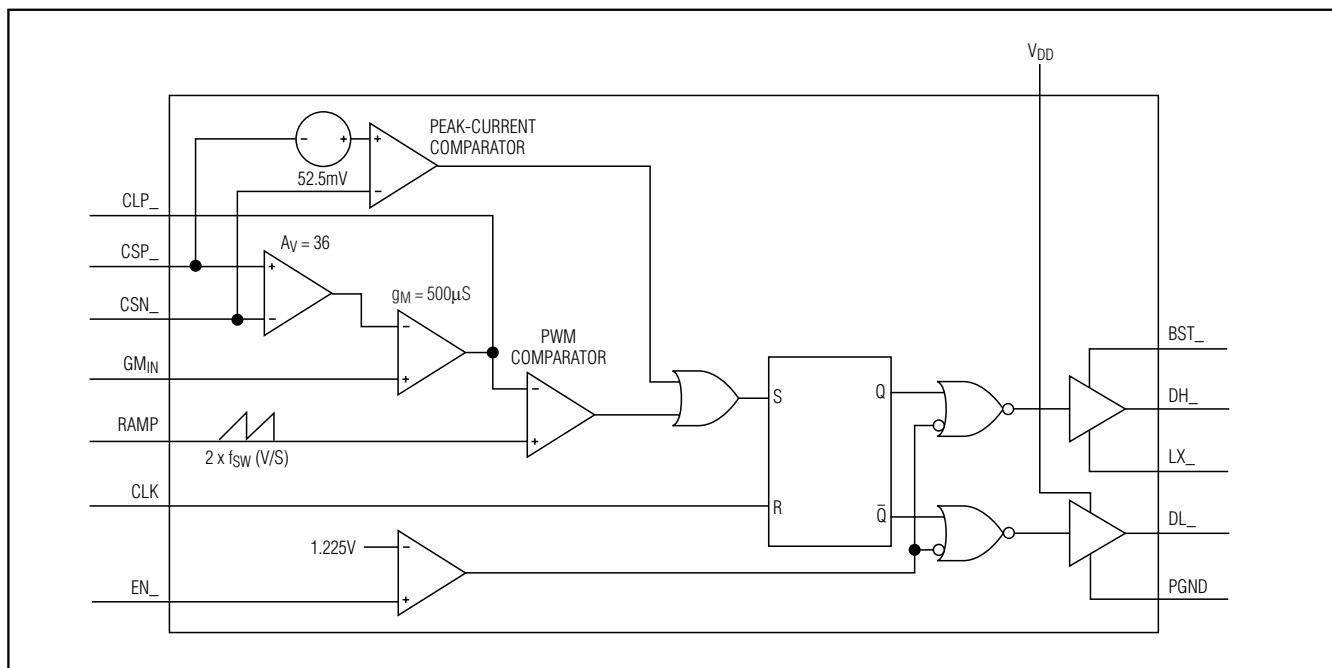


Figure 3. Current Comparator and MOSFET Driver Logic

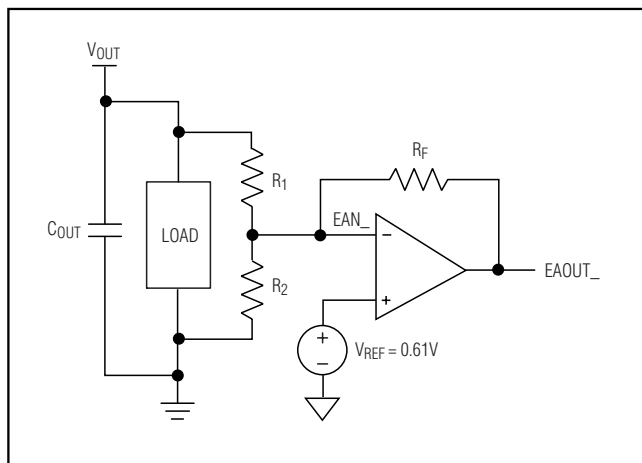


Figure 4. Voltage Error Amplifier

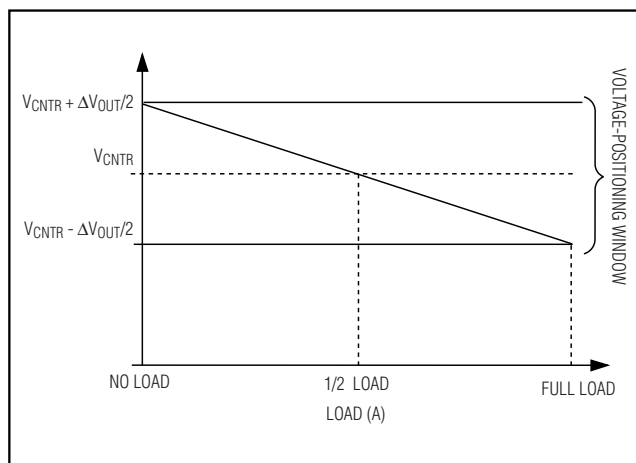


Figure 5. Defining the Voltage-Positioning Window

## MOSFET Gate Drivers (DH\_, DL\_)

The high-side drivers (DH1 and DH2) and low-side drivers (DL1 and DL2) drive the gates of external n-channel MOSFETs. The high-peak sink and source current capability of these drivers provides ample drive for the fast rise and fall times of the switching MOSFETs. Faster rise and fall times result in reduced switching losses. For low-

output, voltage-regulating applications where the duty cycle is less than 50%, choose high-side MOSFETs (Q2 and Q4, Figure 6) with a moderate  $R_{DS(ON)}$  and a very low gate charge. Choose low-side MOSFETs (Q1 and Q3, Figure 6) with very low  $R_{DS(ON)}$  and moderate gate charge. The driver block also includes a logic circuit that provides an adaptive nonoverlap time (30ns typical) to

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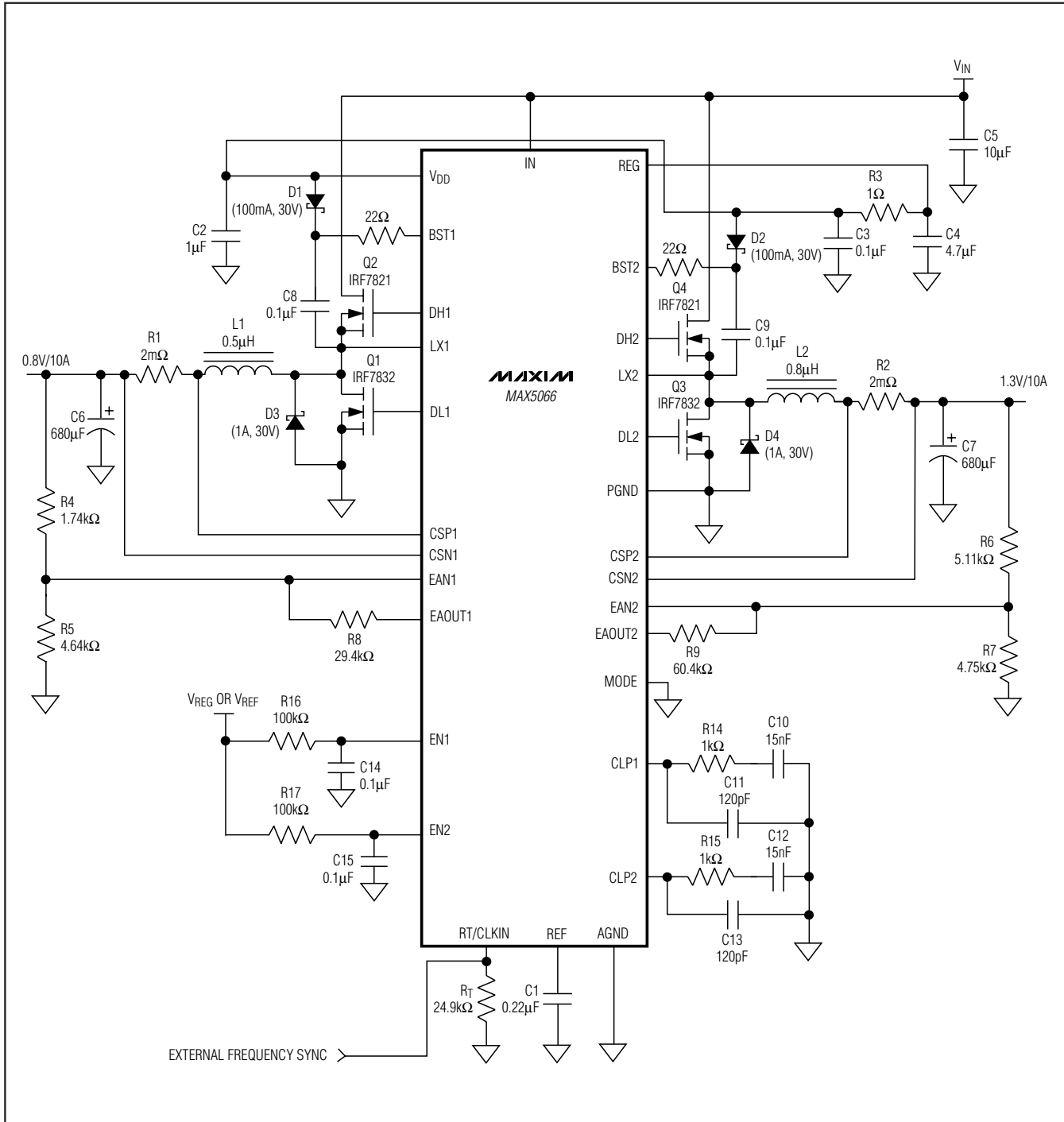


Figure 6. Dual-Output Buck Regulator

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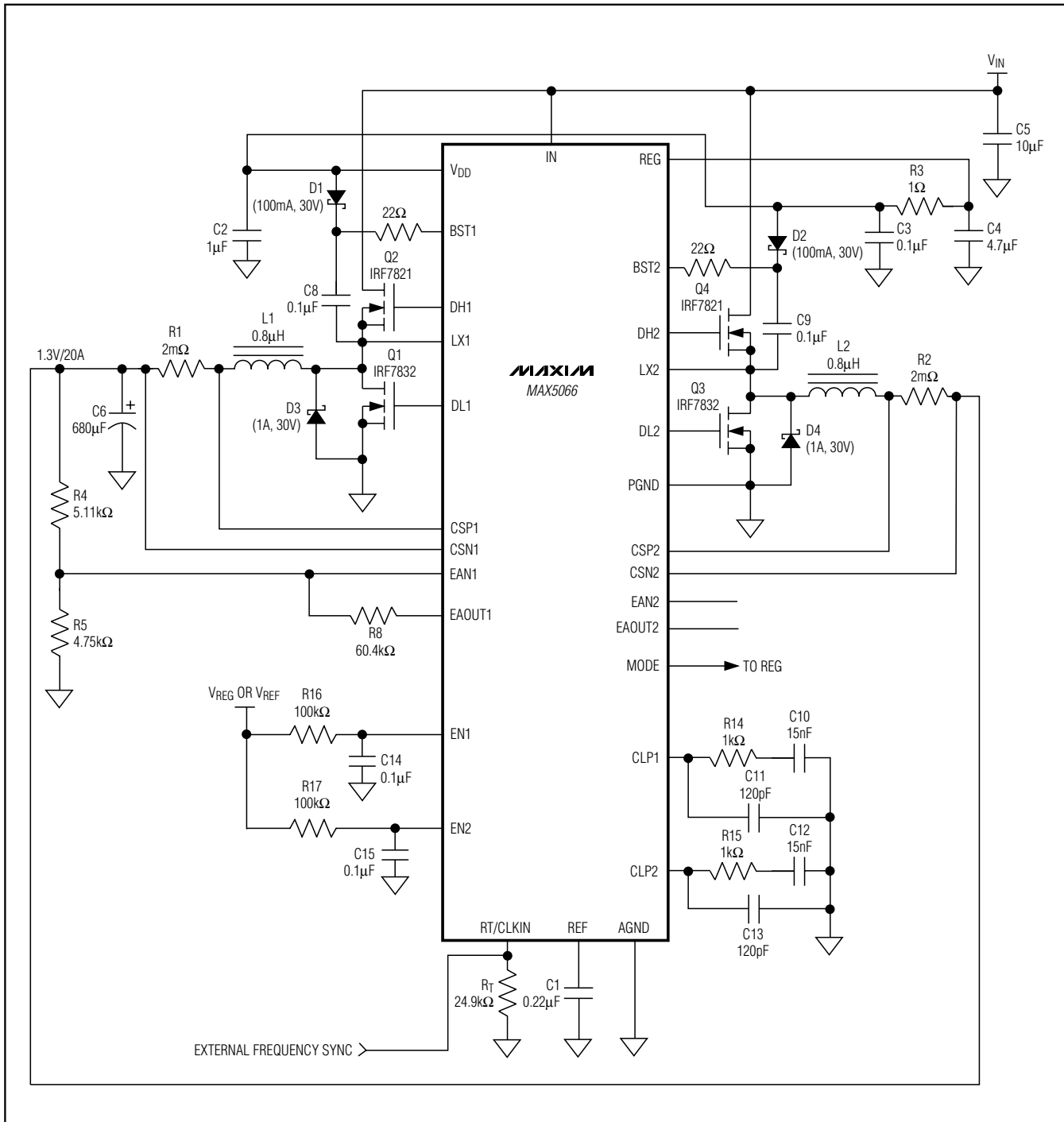


Figure 7. Dual-Phase, Single-Output Buck Regulator

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prevent shoot-through currents during transition. Figure 7 shows the dual-phase, single-output buck regulator.

## Design Procedures

### Inductor Selection

The switching frequency per phase, peak-to-peak ripple current in each phase, and allowable voltage ripple at the output, determine the inductance value. Selecting higher switching frequencies reduces the inductance requirement, but at the cost of lower efficiency due to the charge/discharge cycle of the gate and drain capacitances in the switching MOSFETs. The situation worsens at higher input voltages, since capacitive switching losses are proportional to the square of the input voltage. Lower switching frequencies on the other hand will increase the peak-to-peak inductor ripple current ( $\Delta I_L$ ) and therefore increase the MOSFET conduction losses (see the *Power MOSFET Selection* section for a detailed description of MOSFET power loss).

When using higher inductor ripple current, the ripple cancellation in the multiphase topology, reduces the input and output capacitor RMS ripple current. Use the following equation to determine the minimum inductance value:

$$L = \frac{V_{OUT}(V_{IN(MAX)} - V_{OUT})}{V_{IN} \times f_{SW} \times \Delta I_L}$$

Choose  $\Delta I_L$  to be equal to about 30% of the output current per channel. Since  $\Delta I_L$  affects the output-ripple voltage, the inductance value may need minor adjustment after choosing the output capacitors for full-rated efficiency. Choose inductors from the standard high-current, surface-mount inductor series available from various manufacturers. Particular applications may require custom-made inductors. Use high-frequency core material for custom inductors. High  $\Delta I_L$  causes large peak-to-peak flux excursion increasing the core losses at higher frequencies. The high-frequency operation coupled with high  $\Delta I_L$ , reduces the required minimum inductance and even makes the use of planar inductors possible. The advantages of using planar magnetics include low-profile design, excellent current sharing between phases due to the tight control of parasitics, and low cost. For example, the minimum inductance at  $V_{IN} = 12V$ ,  $V_{OUT} = 0.8V$ ,  $\Delta I_L = 3A$ , and  $f_{SW} = 500kHz$  is  $0.5\mu H$ .

The average current-mode control feature of the MAX5066 limits the maximum inductor current, which prevents the inductor from saturating. Choose an

inductor with a saturating current greater than the worst-case peak inductor current:

$$I_{L\_PEAK} = \frac{24.75 \times 10^{-3}}{R_{SENSE}} + \frac{\Delta I_L}{2}$$

where 24.75mV is the maximum average current-limit threshold for the current-sense amplifier and  $R_{SENSE}$  is the sense resistor.

### Power MOSFET Selection

When choosing the MOSFETs, consider the total gate charge,  $R_{DS(ON)}$ , power dissipation, the maximum drain-to-source voltage, and package thermal impedance. The product of the MOSFET gate charge and on-resistance is a figure of merit, with a lower number signifying better performance. Choose MOSFETs optimized for high-frequency switching applications. The average gate-drive current from the MAX5066's output is proportional to the total capacitance it drives at DH1, DH2, DL1, and DL2. The power dissipated in the MAX5066 is proportional to the input voltage and the average drive current. See the *Supply Voltage Connection* ( $V_{IN}/V_{REG}$ ) and the *Low-Side MOSFET Drives Supply* ( $V_{DD}$ ) sections to determine the maximum total gate charge allowed from all driver outputs together.

The losses may be broken into four categories: conduction loss, gate drive loss, switching loss and output loss. The following simplified power loss equation is true for both MOSFETs in the synchronous buck-converter:

$$P_{LOSS} = P_{CONDUCTION} + P_{GATEDRIVE} + P_{SWITCH} + P_{OUTPUT}$$

For the low-side MOSFET, the  $P_{SWITCH}$  term becomes virtually zero because the body diode of the MOSFET is conducting before the MOSFET is turned on.

Tables 1 and 2 describe the different losses and shows an approximation of the losses during that period.

### Input Capacitance

The discontinuous input-current waveform of the buck converter causes large ripple currents in the input capacitor. The switching frequency, peak inductor current, and the allowable peak-to-peak voltage ripple reflected back to the source, dictate the capacitance requirement. Increasing the number of phases increases the effective switching frequency and lowers the peak-to-average current ratio, yielding lower input capacitance requirement. It can be shown that the

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**Table 1. High-Side MOSFET Losses**

LOSS	DESCRIPTION	SEGMENT LOSS
Conduction Loss	Losses associated with MOSFET on-time and on-resistance. $I_{RMS}$ is a function of load current and duty cycle.	$P_{CONDUCTION} = I_{RMS}^2 \times R_{DS(ON)}$ where $I_{RMS} \approx \sqrt{\frac{V_{OUT}}{V_{IN}}} \times I_{LOAD}$
Gate Drive Loss	Losses associated with charging and discharging the gate capacitance of the MOSFET every cycle. Use the MOSFET's ( $Q_G$ ) specification.	$P_{GATEDRIVE} = V_{DD} \times Q_G \times f_{SW}$
Switching Loss	Losses during the drain voltage and drain current transitions for every switching cycle. Losses occur only during the $Q_{GS2}$ and $Q_{GD}$ time period and not during the initial $Q_{GS1}$ period. The initial $Q_{GS1}$ period is the rise in the gate voltage from zero to $V_{TH}$ . $R_{DH}$ is the high-side MOSFET driver's on-resistance and $R_{GATE}$ is the internal gate resistance of the high-side MOSFET ( $Q_{GD}$ and $Q_{GS2}$ are found in the MOSFET data sheet).	$P_{SWITCH} = V_{IN} \times I_{LOAD} \times f_{SW} \times \frac{(Q_{GS2} + Q_{GD})}{I_{GATE}}$ where $I_{GATE} = \frac{V_{DD}}{2 \times (R_{DH} + R_{GATE})}$
Output Loss	Losses associated with $Q_{OSS}$ of the MOSFET occur every cycle when the high-side MOSFET turns on. The losses are caused by both MOSFETs but are dissipated in the high-side MOSFET.	$P_{OUTPUT} = \frac{Q_{OSS(HS)} + Q_{OSS(LS)}}{2} \times V_{IN} \times f_{SW}$

worst-case RMS current occurs when only one controller section is operating. The controller section with the highest output power needs to be used in determining the maximum input RMS ripple current requirement. Increasing the output current drawn from the other out-of-phase controller section results in reducing the input ripple current. A low-ESR input capacitor that can handle the maximum input RMS ripple current of one channel must be used. The maximum RMS capacitor ripple current is given by:

$$I_{CIN(RMS)} \approx I_{MAX} \frac{\sqrt{V_{OUT}(V_{IN} - V_{OUT})}}{V_{IN}}$$

where  $I_{MAX}$  is the full load current of the regulator.  $V_{OUT}$  is the output voltage of the same regulator and  $C_{IN}$  is C5 in Figure 6. The ESR of the input capacitors wastes power from the input and heats up the capacitor. Reducing the ESR is important to maintain a high overall efficiency and in reducing the heating of the capacitors.

## Output Capacitors

The worst-case peak-to-peak inductor ripple current, the allowable peak-to-peak output ripple voltage, and the maximum deviation of the output voltage during step loads determine the capacitance and the ESR requirements for the output capacitors. The output ripple can be approximated as the inductor current ripple multiplied by the output capacitor's ESR ( $RESR_{OUT}$ ). The peak-to-peak inductor current ripple is given by:

$$\Delta I_L = \frac{V_{OUT}(1-D)}{L \times f_{SW}}$$

During a load step, the allowable deviation of the output voltage during the fast transient load dictates the output capacitance and ESR. The output capacitors supply the load step until the controller responds with a greater duty cycle. The response time ( $t_{RESPONSE}$ ) depends on the closed-loop bandwidth of the regulator. The resistive drop across the capacitor's ESR and capacitor discharge causes a voltage drop during a

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**Table 2. Low-Side MOSFET Losses**

LOSS	DESCRIPTION	SEGMENT LOSSES
Conduction Loss	Losses associated with MOSFET on-time, $I_{RMS}$ is a function of load current and duty cycle.	$P_{CONDUCTION} = I_{RMS}^2 \times R_{DS(ON)}$ where $I_{RMS} \approx \sqrt{\frac{V_{IN} - V_{OUT}}{V_{IN}}} \times I_{LOAD}$
Gate Drive Loss	Losses associated with charging and discharging the gate of the MOSFET every cycle. There is no $Q_{GD}$ charging involved in this MOSFET due to the zero-voltage turn-on. The charge involved is $(Q_G - Q_{GD})$ .	$P_{GATEDRIVE} = V_{DD} \times (Q_G - Q_{GD}) \times f_{SW}$

**Note:** The gate drive losses are distributed between the drivers and the MOSFETs in the ratio of the gate driver's resistance and the MOSFET's internal gate resistance.

load step. Use a combination of SP polymer and ceramic capacitors for better transient load and ripple/noise performance.

Keep the maximum output-voltage deviation less than or equal to the adaptive voltage-positioning window ( $\Delta V_{OUT}$ ). During a load step, assume a 50% contribution each from the output capacitance discharge and the voltage drop across the ESR ( $\Delta V_{OUT} = \Delta V_{ESR\_OUT} + \Delta V_{Q\_OUT}$ ). Use the following equations to calculate the required ESR and capacitance value:

$$R_{ESR\_OUT} = \frac{\Delta V_{ESR\_OUT}}{I_{LOAD\_STEP}}$$

$$C_{OUT} = \frac{I_{LOAD\_STEP} \times t_{RESPONSE}}{\Delta V_{Q\_OUT}}$$

where  $I_{LOAD\_STEP}$  is the step in load current and  $t_{RESPONSE}$  is the response time of the controller. Controller response time depends on the control-loop bandwidth.  $C_{OUT}$  is C6 and C7 in Figure 6.

## Current Limit

The average current-mode control technique of the MAX5066 accurately limits the maximum average output current per phase. The MAX5066 senses the voltage across the sense resistor and limits the maximum inductor current accordingly. Use the equations below to calculate the current-sense resistor values:

$$I_{LOAD(MAX)} = \frac{24.75 \times 10^{-3}}{R_{SENSE}}$$

Due to tolerances involved, the minimum average voltage at which the voltage across the current-sense resistor is clamped is 20.4mV. Therefore, the minimum average current limit is set at:

$$I_{LIMIT(MIN)} = \frac{20.4 \times 10^{-3}}{R_{SENSE}}$$

For example, the current-sense resistor:

$$R_{SENSE} = \frac{20.4mV}{10A} = 2.04m\Omega$$

for a maximum output current of 10A. The standard value is 2m $\Omega$ . Also, adjust the value of the current-sense resistor to compensate for parasitics associated with the PC board. Select a noninductive resistor with appropriate wattage rating.

The second type of current limit is the peak current limit as explained in the *Peak-Current Comparator* section.

The third current-protection circuit is the hiccup fault protection as explained in the *Hiccup Fault Protection* section. The average current during a short at the output is given by:

$$I_{AVG(SHORT)} = \frac{1.41 \times 10^{-3}}{R_{SENSE}}$$

## Reverse Current Limit

The MAX5066 limits the reverse current when the output capacitor voltage is higher than the preset output voltage. Calculate the maximum reverse current limit based on  $V_{CLAMP\_LO}$  and the current-sense resistor  $R_{SENSE}$ .

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$$I_{\text{REVERSE}} = \frac{1.63 \times 10^{-3}}{R_{\text{SENSE}}}$$

## Output-Voltage Setting

The output voltage is set by the combination of resistors R1, R2, and R<sub>F</sub> as described in the *Voltage Error Amplifier* section. First select a value for resistor R2. Then calculate the value of R1 from the following equation:

$$R1 = \frac{(V_{\text{OUT(NL)}} - 0.6135)}{0.6135} \times R2$$

where V<sub>OUT(NL)</sub> is the voltage at no load. Then find the value of R<sub>F</sub> from the following equation:

$$R_F = \frac{I_{\text{OUT}} \times R_{\text{SENSE}} \times 36 \times R1}{\Delta V_{\text{OUT}}}$$

where ΔV<sub>OUT</sub> is the allowable drop in voltage from no load to full load. R<sub>F</sub> is R8 and R9, R1 is R4 and R6, R2 is R5 and R7 in Figure 6.

## Compensation

The MAX5066 uses an average current-mode control scheme to regulate the output voltage (see Figure 2). The main control loop consists of an inner current loop and an outer voltage loop. The voltage error amplifier (VEA1 and VEA2) provides the controlling voltage for the current loop in each phase. The output inductor is “hidden” inside the inner current loop. This simplifies the design of the outer voltage control loop and also improves the power-supply dynamics. The objective of the inner current loop is to control the average inductor current. The gain-bandwidth characteristic of the current loop can be tailored for optimum performance by the compensation network at the output of the current-error amplifier (CEA1 or CEA2). Compared with peak current-mode control, the current-loop gain crossover frequency, f<sub>C</sub>, can be made approximately the same, but the gain at low frequencies is much higher. This results in the following advantages over peak current-mode control.

- 1) The average current tracks the programmed current with a high degree of accuracy.
- 2) Slope compensation is not required, but there is a limit to the loop gain at the switching frequency in order to achieve stability.
- 3) Noise immunity is excellent.
- 4) The average current-mode method can be used to sense and control the current in any circuit branch.

For stability of the current loop, the amplified inductor-current downslope at the negative input of the PWM comparator (CPWM1 and CPWM2) must not exceed the ramp slope at the comparator's positive input. This puts an upper limit on the current-error amplifier gain at the switching frequency. The inductor current downslope is given by V<sub>OUT</sub>/L where L is the value of the inductor (L1 and L2 in Figure 6) and V<sub>OUT</sub> is the output voltage. The amplified inductor current downslope at the negative input of the PWM comparator is given by:

$$\frac{\Delta V_L}{\Delta t} = \frac{V_{\text{OUT}}}{L} \times R_{\text{SENSE}} \times 36 \times g_M \times R_{\text{CF}}$$

where R<sub>SENSE</sub> is the current-sense resistor (R1 and R2 in Figure 6) and g<sub>M</sub> × R<sub>CF</sub> is the gain of the current-error amplifier (CEA<sub>1</sub>) at the switching frequency. The slope of the ramp at the positive input of the PWM comparator is 2V × f<sub>SW</sub>. Use the following equation to calculate the maximum value of R<sub>CF</sub> (R14 or R15 in Figure 6).

$$R_{\text{CF}} \leq \frac{2 \times f_{\text{SW}} \times L}{V_{\text{OUT}} \times R_{\text{SENSE}} \times 36 \times g_M} \quad (1)$$

The highest crossover frequency f<sub>C<sub>MAX</sub></sub> is given by:

$$f_{\text{C<sub>MAX</sub>}} = \frac{f_{\text{SW}} \times V_{\text{IN}}}{2\pi \times V_{\text{OUT}}}$$

or alternatively:

$$f_{\text{SW}} = \frac{f_{\text{C<sub>MAX</sub>}} \times 2\pi \times V_{\text{OUT}}}{V_{\text{IN}}}$$

Equation (1) can now be rewritten as:

$$R_{\text{CF}} = \frac{\pi \times f_{\text{C}} \times L}{V_{\text{IN}} \times R_{\text{S}} \times 9 \times g_M} \quad (2)$$

In practical applications, pick the crossover frequency (f<sub>C</sub>) in the range of:

$$\frac{f_{\text{SW}}}{10} < f_{\text{C}} < \frac{f_{\text{SW}}}{2}$$

First calculate R<sub>CF</sub> in equation 2 above. Calculate C<sub>CF</sub> such that:

$$C_{\text{CF}} = \frac{10}{2 \times \pi \times f_{\text{C}} \times R_{\text{CF}}}$$

where C<sub>CF</sub> is C10 and C12 in Figure 6.

# Configurable, Single-/Dual-Output, Synchronous Buck Controller for High-Current Applications

Calculate  $C_{\text{CFF}}$  such that:

$$C_{\text{CFF}} = \frac{1}{2 \times \pi \times f_{\text{C}} \times 10 \times R_{\text{CF}}}$$

where  $C_{\text{CFF}}$  is C11 and C13 in Figure 6.

## Applications Information

### Independent Turn-On and Off

The MAX5066 can be used to regulate two outputs from one controller. Each of the two outputs can be turned on and off independently of one another by controlling the enable input of each phase (EN1 and EN2). A logic-low on each enable pin shuts down the MOSFET drivers for that phase. When the voltage on the enable pin exceeds 1.2V, the drivers are turned on and the output can come up to regulation. This method of turning on the outputs allows the MAX5066 to be used for power sequencing.

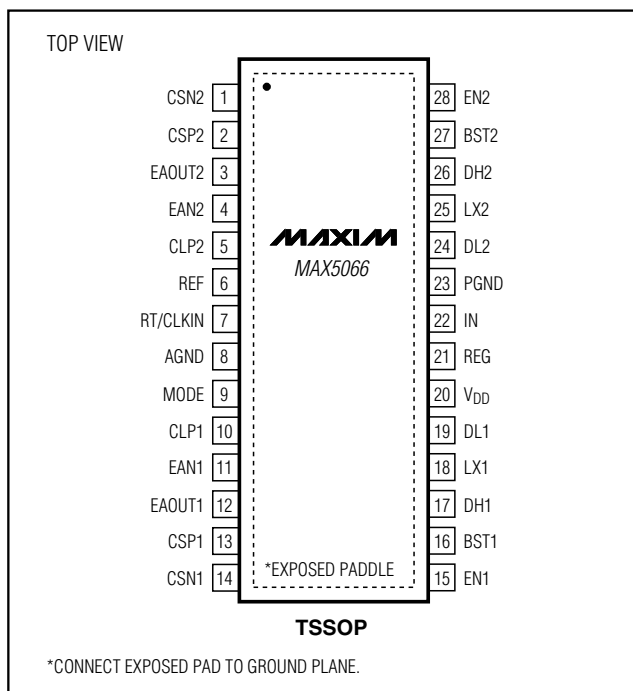
### PC Board Layout Guidelines

Careful PC board layout is critical to achieve low losses, low output noise, and clean and stable operation. This is especially true for dual-phase converters where one channel can affect the other. Use the following guidelines for PC board layout:

- 1) Place the  $V_{\text{DD}}$ , REG, and the BST1 and BST2 bypass capacitors close to the MAX5066.
- 2) Minimize all high-current switching loops.
- 3) Keep the power traces and load connections short. This practice is essential for high efficiency. Use thick copper PC boards (2oz or higher) to enhance efficiency and minimize trace inductance and resistance.
- 4) Run the current-sense lines CSP\_ and CSN\_ very close to each other to minimize loop areas. Do not cross these critical signal lines through power circuitry. Sense the current right at the pads of the current-sense resistors.
- 5) Place the bank of output capacitors close to the load.
- 6) Isolate the power components on the top side from the analog components on the bottom side with a ground plane in between.
- 7) Provide enough copper area around the switching MOSFETs, inductors, and sense resistors to aid in thermal dissipation and reducing resistance.

- 8) Distribute the power components evenly across the top side for proper heat dissipation.
- 9) Keep AGND and PGND isolated and connect them at one single point close to the IC. Do not connect them together anywhere else.
- 10) Place all input bypass capacitors for each input as close to each other as is practical.

## Pin Configuration



## Chip Information

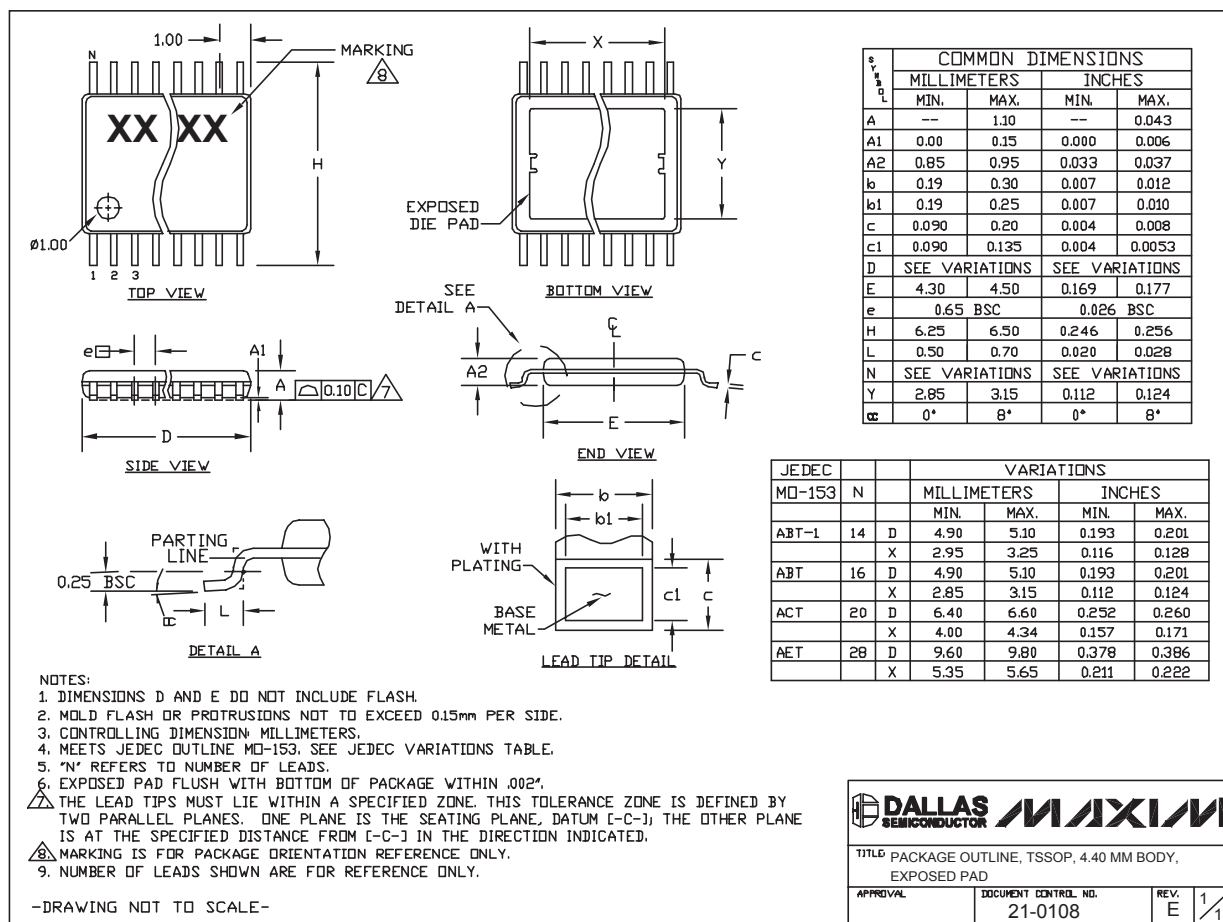
TRANSISTOR COUNT: 6252

PROCESS: BiCMOS

# Configurable, Single-/Dual-Output, Synchronous Buck Controller for High-Current Applications

## Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to [www.maxim-ic.com/packages](http://www.maxim-ic.com/packages).)



TSSOP 4.4mm BODY EPS

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