

#### **General Description**

The MAX4820/MAX4821 8-channel relay drivers offer built-in kickback protection and drive +3.3V/+5V nonlatching or dual-coil-latching relays. These devices are especially useful when driving +3V relays. Each independent open-drain output features a  $2\Omega$  on-resistance and is guaranteed to sink 70mA (min) of load current. Both devices consume less than 50µA (max) guiescent current and have 1µA output off-leakage current.

The MAX4820 features an SPITM-/QSPITM-/MICROWIRETMcompatible serial interface. Input data is shifted into an 8bit shift register and latched to the outputs when  $\overline{\text{CS}}$ transitions from low to high. Each data bit in the shift register corresponds to a specific output, allowing independent control of all outputs.

The MAX4821 features a 4-bit (A0, A1, A2, LVL) parallel-input interface. The first three bits (A0, A1, A2) determine the output address, and the fourth bit (LVL) determines whether the selected output is switched on or off. Data is latched to the outputs when  $\overline{\text{CS}}$  transitions from low to high.

Both devices feature separate set and reset functions that allow the user to turn on or turn off all outputs simultaneously with a single control line. Built-in hysteresis (Schmidt trigger) on all digital inputs allows this device to be used with slow rising and falling signals, such as those from optocouplers or RC power-up initialization circuits. The MAX4820/MAX4821 are available in 20-pin TSSOP and space-saving 20-pin Thin QFN packages.

#### **Applications**

Central Office

ATF

DSL, ADSL Line Cards

Industrial Equipment

E1/T1 Redundancy

Pin Configurations continued at end of data sheet.

Typical Application Circuits and Functional Diagrams appear at end of data sheet.

SPI and QSPI are trademarks of Motorola, Inc. MICROWIRE is a trademark of National Semiconductor Corp.

### **Features**

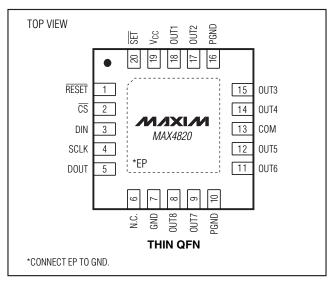
- **♦ 8 Independent Output Channels**
- **♦ Built-In Inductive Kickback Protection**
- ◆ Drive +3V and +5V Relays
- ♦ Guaranteed 70mA (min) Coil Drive Current
- **♦ SET Function to Turn On All Outputs** Simultaneously
- **♦ RESET Function to Turn Off All Outputs** Simultaneously
- **♦** SPI-/QSPI-/MICROWIRE-Compatible Serial Interface (MAX4820)
- ♦ Serial Digital Output for Daisy Chaining (MAX4820)
- **♦** Parallel Interface (MAX4821)
- ♦ Low 50µA (max) Quiescent Supply Current
- ♦ Space-Saving 20-Pin Thin QFN Package

#### **Ordering Information**

PART	TEMP RANGE	PIN-PACKAGE
MAX4820ETP	-40°C to +85°C	20 Thin QFN-EP*
MAX4820EUP	-40°C to +85°C	20 TSSOP
MAX4821ETP	-40°C to +85°C	20 Thin QFN-EP*
MAX4821EUP	-40°C to +85°C	20 TSSOP

<sup>\*</sup>EP = Exposed pad.

### **Pin Configurations**



#### **ABSOLUTE MAXIMUM RATINGS**

(All voltages referenced to GND.)
V <sub>CC</sub> , COM0.3V to +6.0V
OUT0.3V to (V <sub>COM</sub> + 0.3V)
CS, SCLK, DIN, SET, RESET, A0, A1, A2, LVL0.3V to +6.0V
DOUT0.3V to (V <sub>CC</sub> + 0.3V)
Continuous OUT_ Current (all outputs turned on)150mA
Continuous OUT_ Current (single output turned on)300mA

Continuous Power Dissipation (T <sub>A</sub> = +70° 20-Lead Thin QFN	C)
(derate 16.9mW/°C above +70°C)	1350mW
θJA (Note 1)	59.3°C/W
20-Pin TSSOP	
(derate 21.7mW/°C above +70°C)	1739mW
θJA (Note 1)	46°C/W
Operating Temperature Range	40°C to +85°C
Junction Temperature	+150°C
Storage Temperature Range	65°C to +150°C
Soldering Temperature (10s)	+300°C

**Note 1:** Package thermal resistances were obtained using the method described in JEDEC specifications. For detailed information on package thermal considerations, refer to <a href="https://www.maxim-ic.com/thermal-tutorial">www.maxim-ic.com/thermal-tutorial</a>.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### **ELECTRICAL CHARACTERISTICS**

 $(V_{CC} = +3V \text{ to } +5.5V, V_{COM} = V_{CC}, T_A = -40^{\circ}\text{C} \text{ to } +85^{\circ}\text{C}, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}\text{C.})$  (Note 2)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS	
Operating Voltage	Vcc			2.3		5.5	V	
Quiescent Current	lo	I <sub>OUT</sub> _ = 0,	$V_{CC} = 3.6V$		15	50		
Quiescent Current	IQ	logic inputs = $0V$ or $V_{CC}$	$V_{CC} = 5.5V$		20	70	μΑ	
Thermal Shutdown					160		°C	
Power-On Reset				0.8	1.5	2.2	V	
Power-On Reset Hysteresis					140		mV	
DIGITAL INPUTS (SCLK, DIN, CS	, LVL, A0, A1	I, A2, RESET, SET)						
Input Logic-High Voltage	VIH	$V_{CC} = 3.3V$		2.0			V	
input Logic-High Voltage	VIH	$V_{CC} = 5V$	2.4			v		
Input Logic-Low Voltage	\ /	V <sub>CC</sub> = 3.3V				0.6	V	
input Logic-Low voitage	VIL	V <sub>CC</sub> = 5V				0.8	V	
Input Logic Hysteresis	V <sub>HYST</sub>				150		mV	
Input Leakage Currents	ILEAK	Input voltages = 0V or 5.5	5V	-1.0	0.01	+1.0	μΑ	
C <sub>IN</sub> Input Capacitance	CIN				5		рF	
DIGITAL OUTPUT (DOUT)								
DOUT Low Voltage	V <sub>OL</sub>	I <sub>SINK</sub> = 6mA				0.4	V	
DOUT High Voltage	VoH	ISOURCE = 0.5mA		V <sub>C</sub> C - 0.	5		V	
RELAY OUTPUT DRIVERS (OUT	1–OUT8)							
OUT_ Drive Current		V <sub>CC</sub> = 2.7V		70			m ^	
OO1_ Drive Current		V <sub>CC</sub> = 4.5V		70			mA	
OUT_ On-Resistance	Ron	V <sub>CC</sub> = 2.7V			2	6	Ω	
OUT_ Voltage	V <sub>OUT</sub> _	V <sub>CC</sub> = 3.0V, I <sub>OUT</sub> = 70m	A			0.4	V	
I <sub>OUT</sub> Off-Leakage Current	ILEAK	V <sub>OUT</sub> = V <sub>CC</sub> , all outputs	-1		+1	μΑ		
Kickback Diode Forward Voltage	VFORW	I <sub>OUT</sub> = 150mA (Note 3)			1.5	V		

#### **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{CC} = +3V \text{ to } +5.5V, V_{COM} = V_{CC}, T_A = -40^{\circ}\text{C} \text{ to } +85^{\circ}\text{C}, \text{ unless otherwise noted.}$  Typical values are at  $T_A = +25^{\circ}\text{C}$ .) (Note 2)

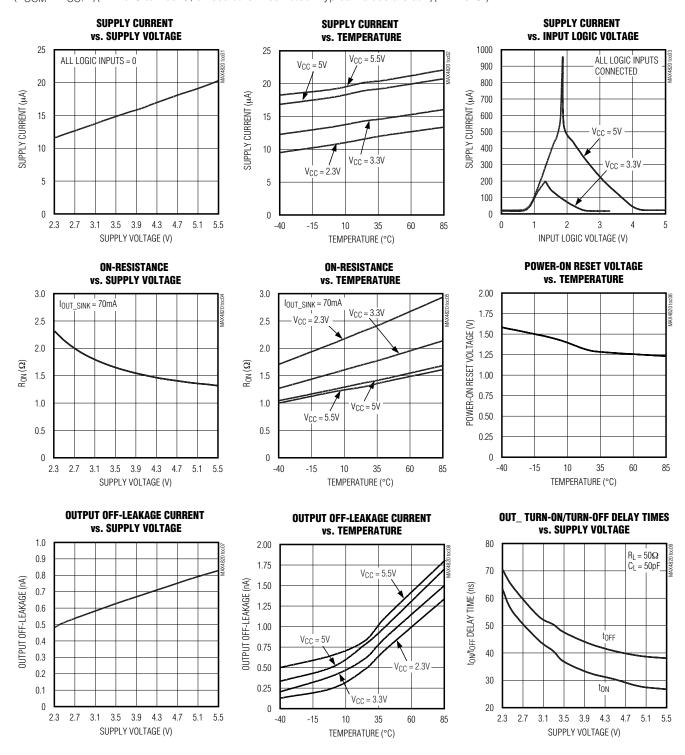
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SPI TIMING (MAX4820)						
Turn-On Time (OUT_)	ton	From rising edge of $\overline{\text{CS}}$ , $R_L = 50\Omega$ , $C_L = 50\text{pF}$			1.0	μs
Turn-Off Time (OUT_)	toff	From rising edge of $\overline{\text{CS}}$ , $R_L = 50\Omega$ , $C_L = 50\text{pF}$			1.0	μs
SCLK Frequency	fsclk		0		2.1	MHz
Cycle Time	tch + tcl		480			ns
CS Fall to SCLK Rise Setup	tcss		240			ns
CS Rise to SCLK Hold	tcsh		240			ns
SCLK High Time	tch		190			ns
SCLK Low Time	tcL		190			ns
Data Setup Time	tDS		100			ns
Data Hold Time	tDH		0			ns
SCLK Fall to DOUT Valid	t <sub>DO</sub>	50% of SCLK to 10% of DOUT, C <sub>L</sub> = 50pF		85	120	ns
Rise Time (DIN, SCLK, $\overline{\text{CS}}$ , $\overline{\text{SET}}$ , $\overline{\text{RESET}}$ )	tscr	20% of V <sub>CC</sub> to 70% of V <sub>CC</sub> , C <sub>L</sub> = 50pF			2	μs
Fall Time (DIN, SCLK, $\overline{\text{CS}}$ , RESET, SET)	tscf	20% of V <sub>CC</sub> to 70% of V <sub>CC</sub> , C <sub>L</sub> = 50pF			2	μs
RESET Min Pulse Width	t <sub>RW</sub>		70			ns
SET Min Pulse Width	tsw		70			ns
PARALLEL TIMING (MAX4821)			·			
Turn-On Time	ton	From rising edge of $\overline{\text{CS}}$ , $R_L = 50\Omega$ , $C_L = 50\text{pF}$			1	μs
Turn-Off Time	toff	From rising edge of $\overline{\text{CS}}$ , $\text{R}_{\text{L}} = 50\Omega$ , $\text{C}_{\text{L}} = 50\text{pF}$			1	μs
LVL Setup Time	tLS		100			ns
LVL Hold Time	tLH		0			ns
Address to CS Setup Time	tah		100			ns
Address to CS Hold Time	tas		0			ns
Rise Time (A2, A1, A0, LVL)	tscr	20% of V <sub>CC</sub> to 70% of V <sub>CC</sub> , C <sub>L</sub> = 50pF			2	μs
Fall Time (A2, A1, A0, LVL)	tscf	20% of V <sub>CC</sub> to 70% of V <sub>CC</sub> , C <sub>L</sub> = 50pF			2	μs
RESET Pulse Width	t <sub>RW</sub>		70			ns
SET Pulse Width	tsw		70			ns

Note 2: Specifications at -40°C are guaranteed by design and not production tested.

**Note 3:** After relay turn-off, inductive kickback may momentarily cause the voltage at OUT\_ to exceed V<sub>COM</sub>. This is considered part of normal operation and will not damage the device.

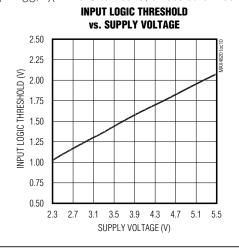
#### Typical Operating Characteristics

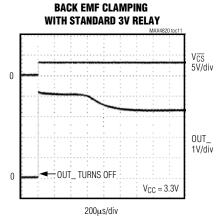
 $(V_{COM} = V_{CC}, T_A = -40^{\circ}C \text{ to } +85^{\circ}C, \text{ unless otherwise noted.}$  Typical values are at  $T_A = +25^{\circ}C.$ )



#### Typical Operating Characteristics (continued)

 $(V_{COM} = V_{CC}, T_A = -40^{\circ}C \text{ to } +85^{\circ}C, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}C.)$ 





#### **Pin Description**

	PI	IN				
MAX	4820	MAX4821		NAME	FUNCTION	
THIN QFN	TSSOP	THIN QFN	TSSOP	NAME	FUNCTION	
1	3	1	3	RESET	Reset Input. Drive RESET low to clear all latches and registers (all outputs are turned off). RESET overrides all other inputs. If RESET and SET are pulled low at the same time, then RESET takes precedence.	
2	4	2	4	<del>CS</del>	Chip-Select Input.  MAX4820: Drive $\overline{CS}$ low to select the device. When $\overline{CS}$ is low, data at DII clocked into the 8-bit shift register on SCLK's rising edge. Drive $\overline{CS}$ from to high to latch the data to the registers and activate the appropriate relative max4821: Drive $\overline{CS}$ low to select the device and set level on LVL. Drive $\overline{CS}$ from low to high to latch the address and level data to the output.	
3	5	_	_	DIN	DIN Serial-Data Input	
4	6	_	_	SCLK	Serial-Clock Input	
5	7	_	_	DOUT	Serial-Data Output. DOUT is the output of the 8-bit shift register. This output can be used to daisy chain multiple MAX4820s. The data at DOUT appears synchronous to SCLK's falling edge.	
6	8	_	_	N.C.	No Connection	
7	9	7	9	GND	Ground	
8	10	8	10	OUT8	Open-Drain Output 8. Connect OUT8 to the low side of a relay coil. This output is pulled to PGND when activated, but otherwise is high impedance.	
9	11	9	11	OUT7 Open-Drain Output 7. Connect OUT7 to the low side of a relay coil. This output is pulled to PGND when activated, but otherwise is high impedance.		
10, 16	12, 18	10, 16	12, 18	PGND Power Ground. PGND is a return for the output sinks. Connect PGND pins together and to GND.		
11	13	11	13	OUT6	Open-Drain Output 6. Connect OUT6 to the low side of a relay coil. This output is pulled to PGND when activated, but otherwise is high impedance.	

#### Pin Description (continued)

	P	IN				
MAX	(4820	MAX	(4821	NAME	FUNCTION	
THIN QFN	TSSOP	THIN QFN	TSSOP	NAME	FUNCTION	
12	14	12	14	OUT5	Open-Drain Output 5. Connect OUT5 to the low side of a relay coil. This output is pulled to PGND when activated, but otherwise is high impedance.	
13	15	13	15	COM	Common Free-Wheeling Diodes. Connect COM to $V_{CC}$ . COM can also be connected to a separate supply that is higher than $V_{CC}$ . In that case, bypass $V_{CC}$ to GND with a 0.1µF capacitor.	
14	16	14	16	OUT4	Open-Drain Output 4. Connect OUT4 to the low side of a relay coil. This output is pulled to PGND when activated, but otherwise is high impedance.	
15	17	15	17	OUT3 Open-Drain Output 3. Connect OUT3 to the low side of a relay coil. The output is pulled to PGND when activated, but otherwise is high imped		
17	19	17	19	OUT2 Open-Drain Output 2. Connect OUT2 to the low side of a relay coil. This output is pulled to PGND when activated, but otherwise is high impedal		
18	20	18	20	OUT1	Open-Drain Output 1. Connect OUT1 to the low side of a relay coil. This output is pulled to PGND when activated, but otherwise is high impedance.	
19	1	19	1	Vcc	Input Supply Voltage. Bypass VCC to GND with a 0.1µF capacitor.	
20	2	20	2	SET	Set Input. Drive SET low to set all latches and registers high (all outputs are turned on). SET overrides all parallel and serial control inputs. RESET overrides SET under all conditions.	
_	_	3	5	LVL	Level Input. LVL determines whether the selected address is switched on off. A logic high on LVL switches on the addressed output. A logic low on LVL switches off the addressed output.	
		4	6	A0	A0 Digital Address "0" Input. (See Table 2 for address mapping.)	
		5	7	A1	Digital Address "1" Input. (See Table 2 for address mapping.)	
_	_	6	8	A2	Digital Address "2" Input. (See Table 2 for address mapping.)	
_	_	_	_	EP	Exposed Pad (Thin QFN Only). Connect exposed pad to GND.	

#### **Detailed Description**

The MAX4820/MAX4821 8-channel relay drivers offer built-in kickback protection and drive +3.3V/+5V non-latching or dual-coil-latching relays. These devices are especially useful when driving +3V relays. Each independent open-drain output features a  $2\Omega$  on-resistance and is guaranteed to sink 70mA (min) load current. Both devices consume less than 50µA (max) quiescent current and feature 1µA (min) output off-leakage current.

The MAX4820 features an SPI/QSPI/MICROWIRE-compatible serial interface. Input data is shifted into an 8-bit shift register and latched to the outputs when  $\overline{\text{CS}}$  transitions from low to high. Each data bit in the shift register corresponds to a specific output, allowing independent control of all outputs.

The MAX4821 features a 4-bit (A0, A1, A2, LVL) parallel input interface. The three bits (A0, A1, A2) determine the output address, and LVL determines whether the selected output is switched on or off. Data is latched to the outputs when  $\overline{\text{CS}}$  transitions from low to high.

Both devices feature separate set and reset functions that allow the user to turn on or turn off all outputs simultaneously with a single control line. Built-in hysteresis (Schmidt trigger) on all digital inputs allows this device to be used with slow rising and falling signals, such as those from optocouplers or RC power-up initialization circuits. The MAX4820/MAX4821 are available in 20-pin TSSOP and space-saving 20-pin Thin QFN packages.

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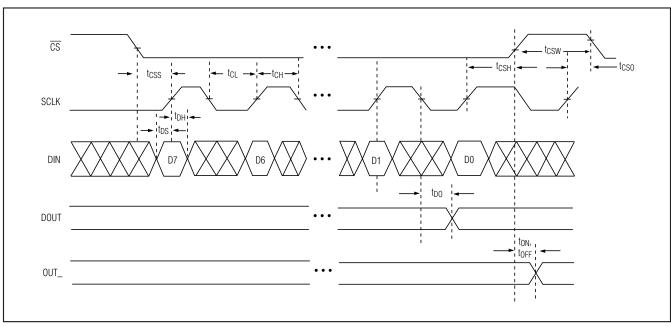


Figure 1. 3-Wire Serial-Interface Timing Diagram (MAX4820 only)

#### Table 1. Serial Input Address Map (MAX4820 Only)

DIN	D0	D1	D2	D3	D4	D5	D6	D7
OUT_	OUT1	OUT2	OUT3	OUT4	OUT5	OUT6	OUT7	OUT8

#### **Digital Interface** Serial Interface (MAX4820)

The serial interface consists of an 8-bit shift register and parallel latch controlled by SCLK and  $\overline{CS}$ . The input to the shift register is an 8-bit word. Each data bit controls one of the eight outputs, with the most significant bit (D7) corresponding to OUT8 and the least significant bit (D0) corresponding to OUT1 (see Table 1). When  $\overline{CS}$  is low (device is selected), data at DIN is clocked into the shift register synchronously with SCLK's rising edge. Driving  $\overline{CS}$  from low to high latches the data in the shift register to the parallel latch.

DOUT is the output of the shift register. Data appears on DOUT synchronously with SCLK's falling edge and is identical to the data at DIN delayed by eight clock cycles. When shifting the input data, D7 is the first bit in and out of the shift register.

While  $\overline{\text{CS}}$  is low, the switches always remain in their previous state. Drive  $\overline{\text{CS}}$  high after 8 bits of data have been shifted in to update the output state and inhibit further data from entering the shift register. When  $\overline{\text{CS}}$  is high, transitions at DIN and SCLK have no effect on the out-

put, and the first input bit (D7) is present at DOUT.

If the number of data bits entered while  $\overline{\text{CS}}$  is low is greater or less than 8, the shift register contains only the last 8 data bits, regardless of when they were entered.

The 3-wire serial interface is compatible with SPI, QSPI, and MICROWIRE standards. The latch that drives the analog switch is updated on the rising edge of  $\overline{\text{CS}}$ , regardless of SCLK's state.

#### Parallel Interface (MAX4821)

The parallel interface consists of three address bits (A0, A1, A2) and one level selector bit (LVL). The address bits determine which output is updated, and the level bit determines whether the addressed output is switched on (LVL = high) or off (LVL = low). When  $\overline{\text{CS}}$  is high, the address and level bits have no effect on the state of the outputs. Driving  $\overline{\text{CS}}$  from low to high latches the address and level data to the parallel register and updates the state of the outputs. Address data entered after  $\overline{\text{CS}}$  is pulled low is not reflected in the state of the outputs following the next low-to-high transition on  $\overline{\text{CS}}$  (Figure 2).

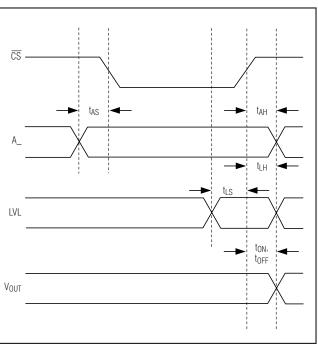


Figure 2. Parallel Interface Timing Diagram (MAX4821 only)

Table 2. Parallel Interface Address Map (MAX4821 Only)

A2	A1	Α0	OUTPUT
Low	Low	Low	OUT1
Low	Low	High	OUT2
Low	High	Low	OUT3
Low	High	High	OUT4
High	Low	Low	OUT5
High	Low	High	OUT6
High	High	Low	OUT7
High	High	High	OUT8

#### **SET/RESET** Functions

The MAX4820/MAX4821 feature set and reset inputs that allow the user to simultaneously turn all outputs on or off using a single control line. Drive SET low to set all latches and registers to 1 and turn all outputs on. SET overrides all serial/parallel control inputs. Drive RESET low to clear all latches and registers and turn all outputs off. RESET overrides all other inputs, including SET.

### \_Applications Information

#### **Daisy Chaining**

The MAX4820 features a digital output, DOUT, that provides a simple way to daisy chain multiple devices. This feature allows the user to drive large banks of relays using only a single serial interface. To daisy chain multiple devices, connect all  $\overline{\text{CS}}$  pins together, and connect the DOUT of one device to the DIN of another device (see Figure 3). During operation, a stream of serial data

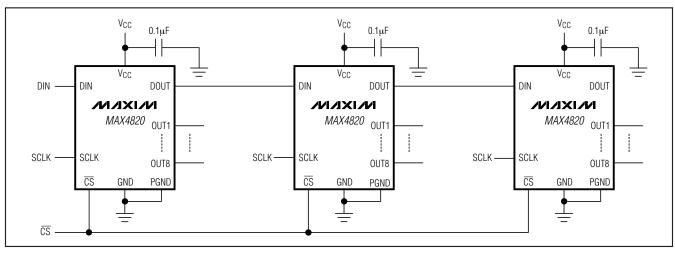


Figure 3. Daisy-Chain Configuration

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is shifted through all the MAX4820s in series. When  $\overline{\text{CS}}$  goes high, all outputs update simultaneously.

The MAX4820 can also be used in a slave configuration that allows the user to address individual devices. Connect all the DIN pins together, and use the  $\overline{\text{CS}}$  input

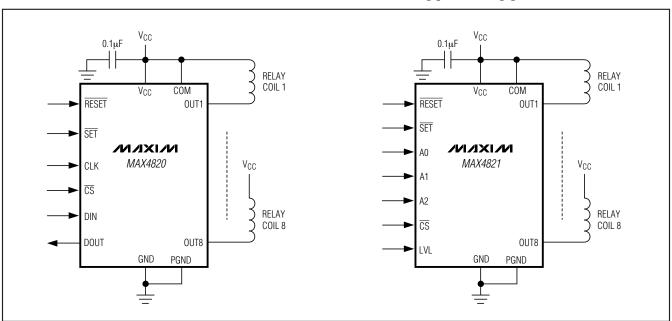
to address one device at a time. Drive  $\overline{\text{CS}}$  low to select a slave and input the data into the shift register. Drive  $\overline{\text{CS}}$  high to latch the data and turn on the appropriate outputs. Typically, in this configuration only one slave is addressed at a time.

#### **Relay Manufacturers**

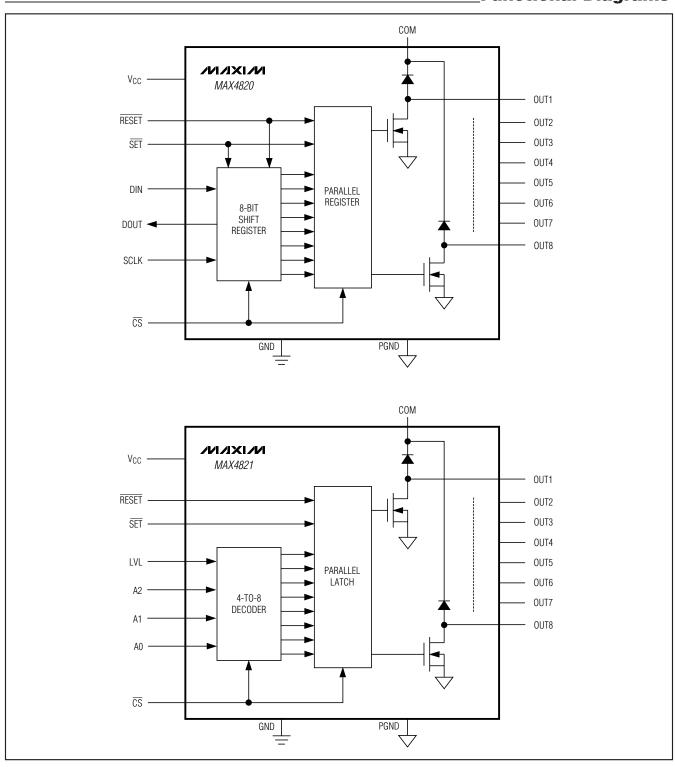
COMPANY	PHONE	WEBSITE
Aromat Corp.	310-524-9862	www.aromat.com
CP Clare Corp.	978-524-6700	www.crouzet.com
Coto Techonology	401-943-2686	www.cotorelay.com
Deustch Relays, Inc.	516-499-6000	www.deutschrelays.com
Fujitsu Takamisawa	408-745-4900	www.fujitsufta.com
Hella KG Hueck	734-414-0970	www.hella.com

COMPANY	PHONE	WEBSITE
NEC Electronics, Inc.	800-366-9782	www.nec-global.com
Omron Electronics, Inc.	847-843-7900	www.oeiweb.omron.com
Rockwell/Allen- Bradley	414-382-2000	www.ab.com
Siemens Electromechanical Component, Inc.	770-371-3000	www.sec.siemens.com
Teledyne Relays	213-777-0077	www.teledynerelays.com

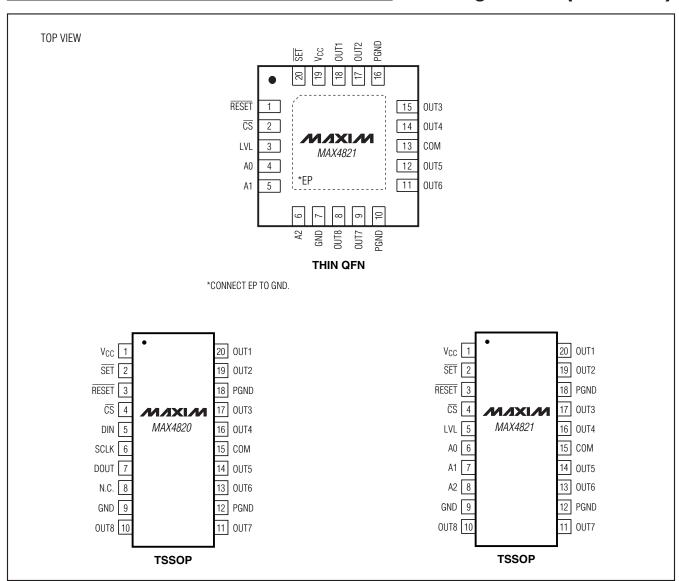
### **Typical Application Circuits**



#### **Functional Diagrams**



#### Pin Configurations (continued)



#### **Chip Information**

### \_\_\_Package Information

PROCESS: BiCMOS

For the latest package outline information and land patterns, go to **www.maxim-ic.com/packages**.

PACKAGE TYPE	PACKAGE CODE	DOCUMENT NO.
20 TQFN-EP	T2044-3	<u>21-0139</u>
20 TSSOP	U20E-1	21-0108

#### **Revision History**

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	1/03	Initial release	_
1	4/09	Correct error in Electrical Characteristics table, style edits	1, 2, 3, 5, 11, 12, 13

Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time.