High Voltage 1.5A, 200kHz Step-Down Switching Regulator with 100µA Quiescent Current

### FEATURES

Wide Input Range: 3.3V to 60V 1.5A Peak Switch Current

Burst Mode® Operation: 100µA Quiescent Current\*\*

**Low Shutdown Current:**  $I_0 < 1 \mu A$ 

Power Good Flag with Programmable Threshold

■ Load Dump Protection

200kHz Switching Frequency Saturating Switch Design:  $0.2\Omega$ 

Peak Switch Current Maintained Over Full Duty Cycle Range

■ 1.25V Feedback Reference Voltage

■ Easily Synchronizable

Soft-Start Capability

Small 16-Pin Thermally Enhanced TSSOP Package

### **APPLICATIONS**

- High Voltage Power Conversion
- 14V and 42V Automotive Systems
- Industrial Power Systems
- Distributed Power Systems

### DESCRIPTION

**April 2003** 

The LT®1976 is a 200kHz monolithic buck switching regulator that accepts input voltages up to 60V. A high efficiency 1.5A,  $0.2\Omega$  switch is included on the die along with all the necessary oscillator, control and logic circuitry. Current mode topology is used for fast transient response and good loop stability.

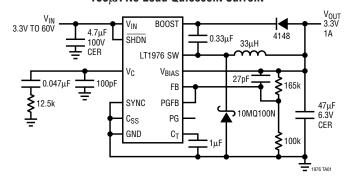
Innovative design techniques along with a new high voltage process achieve high efficiency over a wide input range. Efficiency is maintained over a wide output current range by employing Burst Mode operation at low currents, utilizing the output to bias the internal circuitry, and by using a supply boost capacitor to fully saturate the power switch. Patented circuitry maintains peak switch current over the full duty cycle range\*. Shutdown reduces input supply current to less than 1µA. External synchronization can be implemented by driving the SYNC pin with logic-level inputs. A single capacitor from the C<sub>SS</sub> pin to the output voltage provides a controlled output voltage ramp (softstart). The device also has a power good flag with a programmable threshold and time-out and thermal shutdown protection.

The LT1976 is available in a 16-pin TSSOP package with exposed leadframe for low thermal resistance.

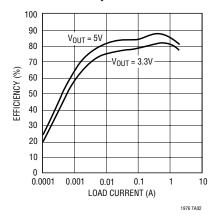
LTC and LT are registered trademarks of Linear Technology Corporation. Burst Mode is a registered trademark of Linear Technology Corporation \*U.S. Patent 6,498,466 \*\*See Burst Mode Operation section for conditions

### TYPICAL APPLICATION

#### 14V to 3.3V Step-Down Converter with 100µA No Load Quiescent Current



#### **Efficiency vs Load Current**



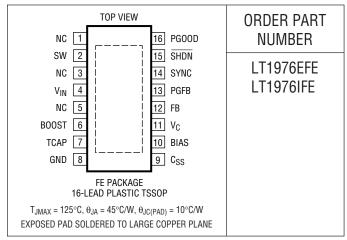
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### **ABSOLUTE MAXIMUM RATINGS**

| (Note 1)                                  |
|---|
| V <sub>IN</sub> , SHDN, BIAS 60\          |
| BOOST Pin Above SW                        |
| BOOST Pin Voltage 68\                     |
| SYNC, C <sub>SS</sub> , PGFB, FB          |
| Operating JunctionTemperature Range       |
| LT1976EFE (Note 2)40°C to 125°C           |
| LT1976IFE (Note 2)40°C to 125°C           |
| Storage Temperature Range65°C to 150°C    |
| Lead Temperature (Soldering, 10 sec)300°C |
|   |

### PACKAGE/ORDER INFORMATION



Consult LTC Marketing for parts specified with wider operating temperature ranges.

**ELECTRICAL CHARACTERISTICS** The  $\bullet$  denotes the specifications which apply over the full operating temperature range, otherwise specifications are at  $T_J = 25^{\circ}C$ .  $V_{IN} = 12V$ ,  $\overline{SHDN} = 12V$ ,  $\overline{BOOST} = 15.3V$ ,  $\overline{BIAS} = 5V$ ,  $\overline{FB/PGFB} = 1.25V$ ,  $\overline{C_{SS}/SYNC} = 0V$  unless otherwise noted.

| SYMBOL             | PARAMETER                             | CONDITIONS  |   | MIN T | ΥP         | MAX | UNITS    |
|--------------------|---------------------------------------|---|---|-------|------------|-----|----------|
|                    | SHDN Threshold                        |   | • | 1     | .3         |     | V        |
| I <sub>SHDN</sub>  | SHDN Input Current                    | SHDN = 12V  | • |       | 3          |     | μΑ       |
|                    | Minimum Input Voltage (Note 3)        |   | • | 2     | 2.4        |     | V        |
| I <sub>VINS</sub>  | Supply Shutdown Current               | SHDN = 0V, BOOST = 0V, FB/PGFB = 0V   | • |       | 1          |     | μΑ       |
|                    | Supply Sleep Current (Note 4)         | BIAS = 0V, FB = 1.35V<br>FB = 1.35V   | • |       | 70<br>15   |     | μA<br>μA |
| I <sub>VIN</sub>   | Supply Quiescent Current              | BIAS = 0V, FB = 1.15V, V <sub>C</sub> = 0.8V<br>FB = 1.15V, V <sub>C</sub> = 0.8V | • |       | 3.2<br>2.6 |     | mA<br>mA |
|                    | Minimum BIAS Voltage (Note 5)         |   | • | 2     | 2.7        |     | V        |
| I <sub>BIASS</sub> | BIAS Sleep Current (Note 4)           |   | • | 1     | 00         |     | μΑ       |
| I <sub>BIAS</sub>  | BIAS Quiescent Current                | SYNC = 3.3V   | • | 6     | 00         |     | μΑ       |
|                    | Minimum Boost Voltage (Note 6)        | I <sub>SW</sub> = 1.5A  |   | 1     | .8         |     | V        |
|                    | Input Boost Current (Note 7)          | I <sub>SW</sub> = 0.5A<br>I <sub>SW</sub> = 1.5A                                  |   |       | 10<br>10   |     | mA<br>mA |
| V <sub>REF</sub>   | Reference Voltage (V <sub>REF</sub> ) | 3.3V < V <sub>VIN</sub> < 60V   | • | 1     | .25        |     | V        |
| I <sub>FB</sub>    | FB Input Bias Current                 |   |   | -     | 75         |     | nA       |
|                    | EA Voltage Gain (Note 8)              |   |   | 6     | 00         |     | V/V      |
|                    | EA Voltage g <sub>m</sub>             | $dI(V_C)=\pm 10\mu A$   |   | 6     | 00         |     | μMho     |
|                    | EA Source Current                     | FB = 1.15V  |   | 4     | 40         |     | μΑ       |
|                    | EA Sink Current                       | FB = 1.35V  |   | (     | 30         |     | μΑ       |
|                    | V <sub>C</sub> to SW g <sub>m</sub>   |   |   |       | 3          |     | V        |
|                    | V <sub>C</sub> High Clamp             |   |   | 2     | 2.2        |     | V        |
|                    | SW Current Limit                      |   | • |       | 2          |     | А        |



**ELECTRICAL CHARACTERISTICS** The ullet denotes the specifications which apply over the full operating temperature range, otherwise specifications are at  $T_J = 25^{\circ}C$ .  $V_{IN} = 12V$ ,  $\overline{S}HDN = 12V$ , BOOST = 15.3V, BIAS = 5V, FB/PGFB = 1.25V,  $C_{SS}/SYNC = 0V$  unless otherwise noted.

| SYMBOL            | PARAMETER                                   | CONDITIONS            |   | MIN TYP | MAX | UNITS |
|-------------------|---|-----------------------|---|---------|-----|-------|
|                   | Switch On Resistance (Note 9)               |                       | • | 0.2     |     | Ω     |
|                   | Switching Frequency                         |                       | • | 200     |     | kHz   |
|                   | Maximum Duty Cycle                          |                       |   | 90      |     | %     |
|                   | Minimum SYNC Amplitude                      |                       |   | 1.5     |     | V     |
|                   | SYNC Frequency Range                        |                       |   | 700     |     | kHz   |
|                   | SYNC Input Impedance                        |                       |   | 100     |     | kΩ    |
| I <sub>CSS</sub>  | C <sub>SS</sub> Current Threshold (Note 10) |                       |   | 10      |     | μΑ    |
| I <sub>PGFB</sub> | PGFB Input Current                          |                       |   | 100     |     | nA    |
| V <sub>PGFB</sub> | PGFB Voltage Threshold (Note 11)            |                       | • | 90      |     | %     |
| I <sub>CT</sub>   | C <sub>T</sub> Source Current (Note 11)     |                       | • | 3.5     |     | μΑ    |
|                   | C <sub>T</sub> Sink Current (Note 11)       |                       |   | 1.5     |     | mA    |
| V <sub>CT</sub>   | C <sub>T</sub> Voltage Threshold (Note 11)  |                       |   | 1.2     |     | V     |
|                   | PG Leakage (Note 11)                        |                       |   | 100     |     | nA    |
|                   | PG Sink Current (Note 11)                   | PGFB = 1V, PG = 400mV |   | 200     |     | μΑ    |

**Note 1:** Absolute Maximum Ratings are those values beyond which the life of a device may be impaired.

**Note 2:** The LT1976EFE is guaranteed to meet performance specifications from 0°C to 125°C junction temperature. Specifications over the -40°C to 125°C operating junction temperature range are assured by design, characterization and correlation with statistical process controls. The LT1976IFE is guaranteed and tested over the full -40°C to 125°C operating junction temperature range.

**Note 3:** Minimum input voltage is defined as the voltage where switching starts. Actual minimum input voltage to maintain a regulated output will depend upon output voltage and load current. See Applications Information.

**Note 4:** Supply input current is the quiescent current drawn by the input pin. Its typical value depends on the voltage on the BIAS pin and operating state of the LT1976. With the BIAS pin at 0V, all of the quiescent current required to operate the LT1976 will be provided by the  $V_{\rm IN}$  pin. With the BIAS voltage above its minimum input voltage, a portion of the total quiescent current will be supplied by the BIAS pin. Supply sleep current is defined as the quiescent current during the "sleep" portion of Burst Mode operation. See Applications Information for determining application supply currents.

Note 5: Minimum BIAS voltage is the voltage on the BIAS pin when  $I_{\mbox{\footnotesize{BIAS}}}$  is sourced into the pin.

**Note 6:** This is the minimum voltage across the boost capacitor needed to guarantee full saturation of the internal power switch.

**Note 7:** Boost current is the current flowing into the BOOST pin with the pin held 3.3V above input voltage. It flows only during switch on time.

**Note 8:** Gain is measured with a  $V_C$  swing from 1.15V to 750mV.

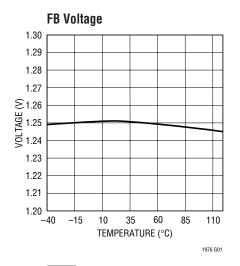
**Note 9:** Switch on resistance is calculated by dividing  $V_{\text{IN}}$  to SW voltage by the forced current (1.5A). See Typical Performance Characteristics for the graph of switch voltage at other currents.

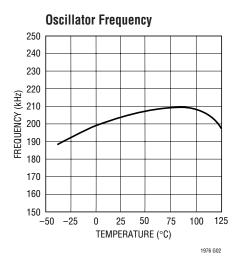
**Note 10:** The  $C_{SS}$  threshold is defined as the value of current sourced into the  $C_{SS}$  pin which results in an increase in sink current from the  $V_C$  pin. See the Soft-Start section in Applications Information.

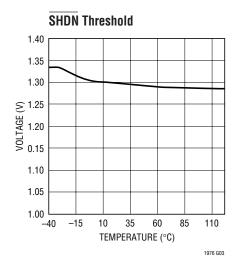
**Note 11:** The PGFB threshold is defined as the percentage of  $V_{REF}$  voltage which causes the current source output of the  $C_T$  pin to change from sinking (below threshold) to sourcing current (above threshold). When sourcing current, the voltage on the  $C_T$  pin rises until it is clamped internally. When the clamp is activated, the output of the PG pin will be set to a high impedance state. When the  $C_T$  clamp is inactive the PG pin will be set active low with a current sink capability of  $200\mu A$ .

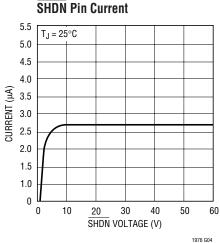


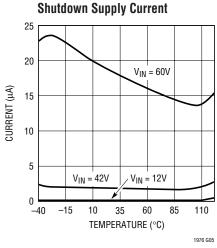
### TYPICAL PERFORMANCE CHARACTERISTICS

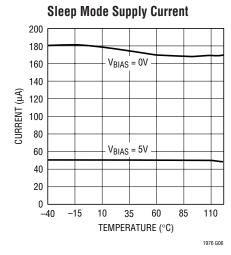


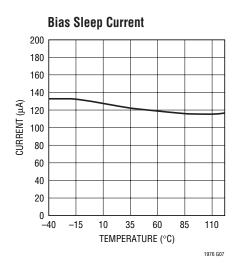


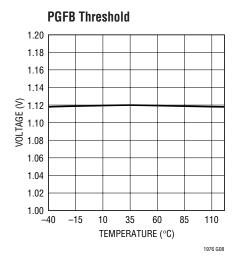


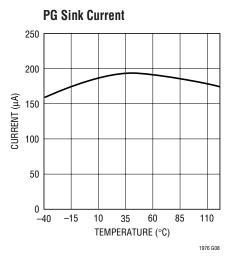






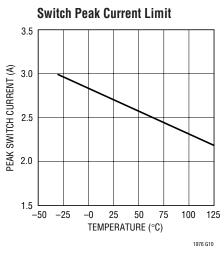


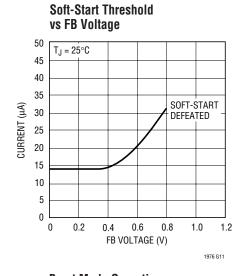


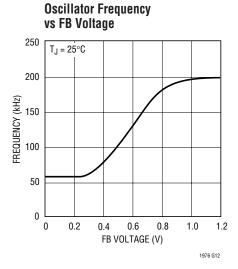


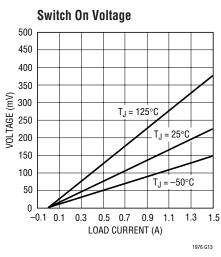
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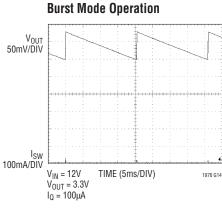
### TYPICAL PERFORMANCE CHARACTERISTICS

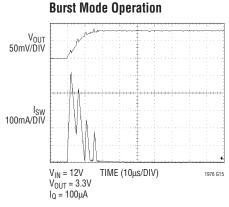




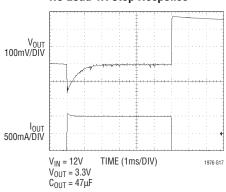




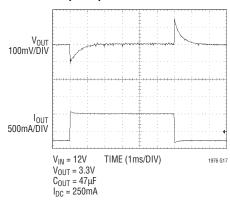




### No Load 1A Step Response









### PIN FUNCTIONS

NC (Pins 1, 3, 5): No Connection.

**SW** (Pin 2): The SW pin is the emitter of the on-chip power NPN switch. This pin is driven up to the input pin voltage during switch on time. Inductor current drives the SW pin negative during switch off time. Negative voltage is clamped with the external catch diode. Maximum negative switch voltage allowed is -0.8V.

 $V_{IN}$  (Pin 4): This is the collector of the on-chip power NPN switch.  $V_{IN}$  powers the internal control circuitry when a voltage on the BIAS pin is not present. High dI/dt edges occur on this pin during switch turn on and off. Keep the path short from the  $V_{IN}$  pin through the input bypass capacitor, through the catch diode back to SW. All trace inductance on this path will create a voltage spike at switch off, adding to the  $V_{CF}$  voltage across the internal NPN.

**BOOST (Pin 6):** The BOOST pin is used to provide a drive voltage, higher than the input voltage, to the internal bipolar NPN power switch. Without this added voltage, the typical switch voltage loss would be about 1.5V. The additional BOOST voltage allows the switch to saturate and its voltage loss approximates that of a  $0.2\Omega$  FET structure, but with much smaller die area.

 $C_T$  (Pin 7): A capacitor on the  $C_T$  pin determines the amount of delay time between the PGFB pin exceeding its threshold ( $V_{PGFB}$ ) and the PG pin set to a high impedance state. When the PGFB pin rises above  $V_{PGFB}$ , current is sourced from the  $C_T$  pin into the external capacitor. When the voltage on the external capacitor reaches an internal clamp ( $V_{CT}$ ), the PG pin becomes a high impedance node. The resultant PG delay time is given by  $t = C_{CT} \cdot V_{CT}/I_{CT}$ . If the voltage on the PGFB pin drops below  $V_{PGFB}$ ,  $C_{CT}$  will be discharged rapidly to 0V and PG will be active low with a 200 $\mu$ A sink capability. See the Power Good section in Applications Information for details.

**GND (Pin 8):** The GND pin connection acts as the reference for the regulated output, so load regulation will suffer if the "ground" end of the load is not at the same voltage as the GND pin of the IC. This condition will occur when load current or other currents flow through metal paths between the GND pin and the load ground. Keep the

path between the GND pin and the load ground short and use a ground plane when possible. The GND pin also acts as a heat sink and should be soldered (along with the exposed leadframe) to the copper plane to reduce thermal resistance (see Applications Information).

 $C_{SS}$  (Pin 9): A capacitor from the  $C_{SS}$  pin to the regulated output voltage determines the output voltage ramp rate during start-up. When the current through the  $C_{SS}$  capacitor exceeds the  $C_{SS}$  threshold ( $I_{CSS}$ ), the voltage ramp of the output is limited. The  $C_{SS}$  threshold is proportional to the FB voltage (see Typical Performance Characteristics) and is defeated for FB voltage greater than 0.9V (typical). See Soft-Start section in Applications Information for details.

**BIAS (Pin 10):** The BIAS pin is used to improve efficiency when operating at higher input voltages and light load current. Connecting this pin to the regulated output voltage forces most of the internal circuitry to draw its operating current from the output voltage rather than the input supply. This architecture increases efficiency especially when the input voltage is much higher than the output. Minimum output voltage setting for this mode of operation is 3V.

 $V_C$  (Pin 11): The  $V_C$  pin is the output of the error amplifier and the input of the peak switch current comparator. It is normally used for frequency compensation, but can also serve as a current clamp or control loop override.  $V_C$  sits at about 0.45V for light loads and 2.2V at maximum load. During the sleep portion of Burst Mode operation, the  $V_C$  pin is held at a voltage slightly below the burst threshold for better transient response. Driving the  $V_C$  pin to ground will disable switching and place the IC into sleep mode.

**FB** (**Pin 12**): The feedback pin is used to determine the output voltage using an external voltage divider from the output that generates 1.25V at the FB pin . When the FB pin drops below 0.9V, switching frequency is reduced, the SYNC function is disabled and output ramp rate control is enabled via the  $C_{SS}$  pin. See the Feedback section in Applications Information for details.

LINEAR

### PIN FUNCTIONS

**PGFB (PIN 13):** The PGFB pin is the positive input to a comparator whose negative input is set at  $V_{PGFB}$ . When PGFB is taken above  $V_{PGFB}$ , current ( $I_{CSS}$ ) is sourced into the  $C_T$  pin starting the PG delay period. When the voltage on the PGFB pin drops below  $V_{PGFB}$ , the  $C_T$  pin is rapidly discharged resetting the PG delay period. The PGFB voltage is typically generated by a resistive divider from the regulated output or input supply. See Power Good section in Applications Information for details.

**SYNC (Pin 14):** The SYNC pin is used to synchronize the internal oscillator to an external signal. It is directly logic compatible and can be driven with any signal between 20% and 80% duty cycle. The synchronizing range is equal to initial operating frequency up to 700kHz. When

the voltage on the FB pin is below 0.9V the SYNC function is disabled. See the Synchronizing section in Applications Information for details.

**SHDN** (Pin 15): The SHDN pin is used to turn off the regulator and to reduce input current to less than  $1\mu A$ . The SHDN pin requires a voltage above 1.2V with a typical source current of  $3\mu A$  to take the IC out of the shutdown state.

**PG (Pin 16):** The PG pin is active low when the internal clamp on the  $C_T$  pin is below its clamp level and high impedance when the clamp is active. The PG pin has a typical sink capability of  $200\mu A$ . See the Power Good section in Applications Information for details.



### **BLOCK DIAGRAM**

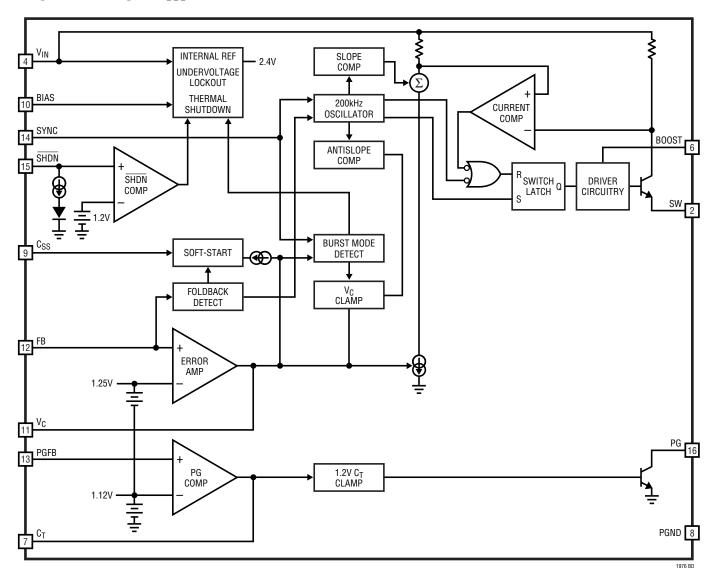


Figure 1. LT1976 Block Diagram

The LT1976 is a constant frequency, current mode buck converter. This means that there is an internal clock and two feedback loops that control the duty cycle of the power switch. In addition to the normal error amplifier, there is a current sense amplifier that monitors switch current on a cycle-by-cycle basis. A switch cycle starts with an oscillator pulse which sets the RS latch to turn the switch on. When switch current reaches a level set by the current comparator the latch is reset and the switch turns off. Output voltage control is obtained by using the output of the error amplifier to set the switch current trip point. This technique means that the error amplifier commands current to be

delivered to the output rather than voltage. A voltage fed system will have low phase shift up to the resonant frequency of the inductor and output capacitor, then an abrupt 180° shift will occur. The current fed system will have 90° phase shift at a much lower frequency, but will not have the additional 90° shift until well beyond the LC resonant frequency. This makes it much easier to frequency compensate the feedback loop and also gives much quicker transient response.

Most of the circuitry of the LT1976 operates from an internal 2.4V bias line. The bias regulator normally draws

TINEAR TECHNOLOGY

### **BLOCK DIAGRAM**

power from the  $V_{\text{IN}}$  pin, but if the BIAS pin is connected to an external voltage higher than 3V bias power will be drawn from the external source (typically the regulated output voltage). This improves efficiency.

High switch efficiency is attained by using the BOOST pin to provide a voltage to the switch driver which is higher than the input voltage, allowing switch to be saturated. This boosted voltage is generated with an external capacitor and diode.

To further optimize efficiency, the LT1976 automatically switches to Burst Mode operation in light load situations. In Burst Mode operation, all circuitry associated with controlling the output switch is shut down reducing the input supply current to 45µA.

The LT1976 contains a power good flag with a program-mable threshold and delay time. A logic-level low on the  $\overline{SHDN}$  pin disables the IC and reduces input suppy current to less than 1 $\mu$ A.

### APPLICATIONS INFORMATION

#### FEEDBACK PIN FUNCTIONS

The feedback (FB) pin on the LT1976 is used to set output voltage and provide several overload protection features. The first part of this section deals with selecting resistors to set output voltage and the remaining part talks about frequency foldback and soft-start features. Please read both parts before committing to a final design.

Referring to Figure 2, the output voltage is determined by a voltage divider from  $V_{OUT}$  to ground which generates 1.25V at the FB pin. Since the output divider is a load on the output care must be taken when choosing the resistor divider values. For light load applications the resistor values should be as large as possible to achieve peak efficiency in Burst Mode operation. Extremely large values for resistor R1 will cause an output voltage error due to the 50nA FB pin input current. The suggested value for the output divider resistor (see Figure 2) from FB to ground (R2) is 100k or less. A formula for R1 is shown below. A table of standard 1% values is shown in Table 1 for common output voltages.

$$R1 = R2 \cdot \frac{V_{OUT} - 1.25}{1.25 + R2 \cdot 50nA}$$

### More Than Just Voltage Feedback

The FB pin is used for more than just output voltage sensing. It also reduces switching frequency and controls the soft-start voltage ramp rate when output voltage is below the regulated level (see the Frequency Foldback

Table 1

| OUTPUT<br>Voltage<br>(V) | <b>R2</b> (kΩ) | R1<br>NEAREST (1%)<br>(kΩ) | OUTPUT<br>ERROR<br>(%) |
|--------------------------|----------------|----------------------------|------------------------|
| 2.5                      | 100            | 100                        | 0                      |
| 3                        | 100            | 140                        | 0                      |
| 3.3                      | 100            | 165                        | 0.38                   |
| 5                        | 100            | 300                        | 0                      |
| 6                        | 100            | 383                        | 0.63                   |
| 8                        | 100            | 536                        | -0.63                  |
| 10                       | 100            | 698                        | -0.25                  |
| 12                       | 100            | 866                        | 0.63                   |

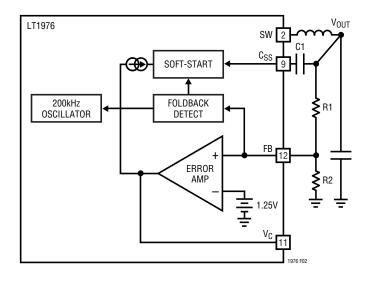


Figure 2. Feedback Network



and Soft-Start Current graphs in Typical Performance Characteristics).

Frequency foldback is done to control power dissipation in both the IC and in the external diode and inductor during short-circuit conditions. A shorted output requires the switching regulator to operate at very low duty cycles. As a result the average current through the diode and inductor is equal to the short-circuit current limit of the switch (typically 2A for the LT1976). Minimum switch on time limitations would prevent the switcher from attaining a sufficiently low duty cycle if switching frequency were maintained at 200kHz, so frequency is reduced by about 4:1 when the FB pin voltage drops below 0.4V (see Frequency Foldback graph). In addition, if the current in the switch exceeds 1.5 times the current specified by the  $V_C$  pin, due to minimum switch on time, the LT1976 will skip the next switch cycle. As the feedback voltage rises, the switching frequency increases to 200kHz with 0.95V on the FB pin. During frequency foldback, external syncronization is disabled to prevent interference with foldback operation. Frequency foldback does not affect operation during normal load conditions.

In addition to lowering switching frequency the soft-start ramp rate is also affected by the feedback voltage. Large capacitive loads or high input voltages can cause a high input current surge during start-up. The soft-start function reduces input current surge by regulating switch current via the V<sub>C</sub> pin to maintain a constant voltage ramp rate (dV/dt) at the output. A capacitor (C1 in Figure 2) from the C<sub>SS</sub> pin to the output determines the maximum output dV/dt. When the feedback voltage is below 0.4V, the  $V_C$  pin will rise, resulting in an increase in switch current and output voltage. If the dV/dt of the output causes the current through the  $C_{SS}$  capacitor to exceed  $I_{CSS}$  the  $V_C$  voltage is reduced resulting in a constant dV/dt at the output. As the feedback voltage increases I<sub>CSS</sub> increases, resulting in an increased dV/dt until the soft-start function is defeated with 0.9V present at the FB pin. The soft-start function does not affect operation during normal load conditions. However, if a momentary short (brown out condition) is present at the output which causes the FB voltage to drop below 0.9V, the soft-start circuitry will become active.

#### **INPUT CAPACITOR**

Step-down regulators draw current from the input supply in pulses. The rise and fall times of these pulses are very fast. The input capacitor is required to reduce the voltage ripple this causes at the input of LT1976 and force the switching current into a tight local loop, thereby minimizing EMI. The RMS ripple current can be calculated from:

$$I_{RIPPLE(RMS)} = I_{OUT} \left( \frac{V_{OUT} (V_{IN} - V_{OUT})}{V_{IN}^2} \right)^{0.5}$$

Ceramic capacitors are ideal for input bypassing. At 200kHz switching frequency input capacitor values in the range of  $4.7\mu F$  to  $20\mu F$  are suitable for most applications. If operation is required close to the minimum input required by the LT1976 a larger value may be required. This is to prevent excessive ripple causing dips below the minimum operating voltage resulting in erratic operation.

You need to check for input voltage transients during power up.

Input voltage transients caused by input voltage steps or by connecting the LT1976 to a pre powered source such as a wall adapter can exceed maximum  $V_{\text{IN}}$  ratings. The sudden application of input voltage will cause a large surge of current in the input leads that will store energy in the parasitic inductance of the leads. This energy will cause the input voltage to swing above the DC level of input power source and it may exceed the maximum voltage rating of the input capacitor and LT1976.

The easiest way to suppress input voltage transients is to add a small aluminum electrolytic capacitor in parallel with the low ESR input capacitor. The selected capacitor needs to have the right amount of ESR to critically damp the resonant circuit formed by the input lead inductance and the input capacitor. The typical values of ESR will fall in the range of  $0.5\Omega$  to  $2\Omega$  and capacitance will fall in the range of  $5\mu F$  to  $50\mu F$ .

If tantalum capacitors are used, values in the  $22\mu F$  to  $470\mu F$  range are generally needed to minimize ESR and meet ripple current and surge ratings. Care should be

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taken to ensure the ripple and surge ratings are not exceeded. The AVX TPS and Kemet T495 series are surge rated AVX recommends derating capacitor operating voltage by 2:1 for high surge applications.

#### **OUTPUT CAPACITOR**

The output capacitor is normally chosen by its effective series resistance (ESR) because this is what determines output ripple voltage. To get low ESR takes volume, so physically smaller capacitors have higher ESR. The ESR range for typical LT1976 applications is  $0.05\Omega$  to  $0.2\Omega$ . A typical output capacitor is an AVX type TPS, 100µF at 10V, with a guaranteed ESR less than  $0.1\Omega$ . This is a "D" size surface mount solid tantalum capacitor. TPS capacitors are specially constructed and tested for low ESR, so they give the lowest ESR for a given volume. The value in microfarads is not particularly critical and values from 22µF to greater than 500µF work well, but you cannot cheat Mother Nature on ESR. If you find a tiny 22µF solid tantalum capacitor, it will have high ESR and output ripple voltage could be unacceptable. Table 2 shows some typical solid tantalum surface mount capacitors.

Table 2. Surface Mount Solid Tantalum Capacitor ESR and Ripple Current

| ESR MAX (Ω)   | RIPPLE CURRENT (A)                     |
|---------------|--|
| 0.1 to 0.3    | 0.7 to 1.1                             |
| 0.7 to 0.9    | 0.4                                    |
|               |  |
| 0.1 to 0.3    | 0.7 to 1.1                             |
|               |  |
| X TPS 0.2 0.5 |  |
|               | 0.1 to 0.3<br>0.7 to 0.9<br>0.1 to 0.3 |

Many engineers have heard that solid tantalum capacitors are prone to failure if they undergo high surge currents. This is historically true and type TPS capacitors are specially tested for surge capability but surge ruggedness is not a critical issue with the output capacitor. Solid tantalum capacitors fail during very high turn-on surges which do not occur at the output of regulators. High discharge surges, such as when the regulator output is dead shorted, do not harm the capacitors.

Unlike the input capacitor RMS ripple current in the output capacitor is normally low enough that ripple current rating is not an issue. The current waveform is triangular with a typical value of  $200 \text{mA}_{RMS}$ . The formula to calculate this is:

Output capacitor ripple current (RMS)

$$I_{RIPPLE(RMS)} = \frac{0.29 \big(V_{OUT}\big) \big(V_{IN} - V_{OUT}\big)}{\big(L\big) \big(f\big) \big(V_{IN}\big)}$$

#### **CERAMIC CAPACITORS**

Higher value, lower cost ceramic capacitors are now becoming available. They are generally chosen for their good high frequency operation, small size and very low ESR (effective series resistance). Low ESR reduces output ripple voltage but also removes a useful zero in the loop frequency response, common to tantalum capacitors. To compensate for this a resistor R<sub>C</sub> can be placed in series with the  $V_C$  compensation capacitor  $C_C$  (Figure 10). Care must be taken however since this resistor sets the high frequency gain of the error amplifier including the gain at the switching frequency. If the gain of the error amplifier is high enough at the switching frequency output ripple voltage (although smaller for a ceramic output capacitor) may still affect the proper operation of the regulator. A filter capacitor  $C_F$  in parallel with the  $R_C/C_C$  network, along with a small feedforward capacitor CFB, is suggested to control possible ripple at the V<sub>C</sub> pin. The LT1976 can be stabilized using a 47µF ceramic output capacitor and V<sub>C</sub> component values of  $C_C = 0.047 \mu F$ ,  $R_C = 12.5 k$ ,  $C_F = 100 pF$ and  $C_{FR} = 27pF$ .

#### **OUTPUT RIPPLE VOLTAGE**

Figure 3 shows a typical output ripple voltage waveform for the LT1976. Ripple voltage is determined by the impedance of the output capacitor and ripple current through the inductor. Peak-to-peak ripple current through the inductor into the output capacitor is:

$$I_{P-P} = \frac{V_{OUT}(V_{IN} - V_{OUT})}{(V_{IN})(L)(f)}$$



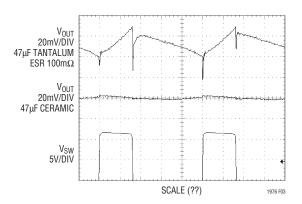


Figure 3. LT1976 Ripple Voltage Waveform

For high frequency switchers, the sum of ripple current slew rates may also be relevant and can be calculated from:

$$\frac{\sum di}{dt} = \frac{V_{IN}}{L}$$

Peak-to-peak output ripple voltage is the sum of a triwave created by peak-to-peak ripple current times ESR and a square wave created by parasitic inductance (ESL) and ripple current slew rate. Capacitive reactance is assumed to be small compared to ESR or ESL.

$$V_{RIPPLE} = (I_{P-P})(ESR) + (ESL)\frac{\sum di}{dt}$$

Example: with  $V_{IN}$  = 12V,  $V_{OUT}$  = 3.3V, L = 33 $\mu$ H, ESR = 0.08 $\Omega$ , ESL = 10nH:

$$I_{P-P} = \frac{(3.3)(12 - 3.3)}{(12)(33e - 6)(200e3)} = 0.362A$$

$$\frac{\sum di}{dt} = \frac{12}{33e - 6} = 363e3$$

$$V_{RIPPLE} = (0.362A)(0.08) + (10e - 9)(363e3)$$
  
= 0.0289 + 0.003 = 32mV<sub>P-P</sub>

#### **MAXIMUM OUTPUT LOAD CURRENT**

Maximum load current for a buck converter is limited by the maximum switch current rating ( $I_{PK}$ ). The current rating for the LT1976 is 1.5A. Unlike most current mode

converters, the LT1976 maximum switch current limit does not fall off at high duty cycles. Most current mode converters suffer a drop off of peak switch current for duty cycles above 50%. This is due to the effects of slope compensation required to prevent subharmonic oscillations in current mode converters. (For detailed analysis, see Application Note 19.)

The LT1976 is able to maintain peak switch current limit over the full duty cycle range by using patented circuitry to cancel the effects of slope compensation on peak switch current without affecting the frequency compensation it provides.

Maximum load current would be equal to maximum switch current for an infinitely large inductor, but with finite inductor size, maximum load current is reduced by one-half peak-to-peak inductor current. The following formula assumes continuous mode operation, implying that the term on the right is less than one-half of  $I_{PK}$ .

$$I_{OUT(MAX)} = \frac{I_{PK} - \left(V_{OUT}\right)\!\left(V_{IN} - V_{OUT}\right)}{2(L)(f)(V_{IN})}$$

Discontinuous operation occurs when:

$$I_{OUT(DIS)} = \frac{V_{OUT}}{2(L)(f)}$$

For  $V_{OUT} = 5V$ ,  $V_{IN} = 8V$  and  $L = 20\mu H$ :

$$I_{OUT(MAX)} = \frac{1.5 - (5)(8 - 5)}{2(20e - 6)(200e3)(8)}$$
$$= 1.5 - 0.24 = 1.26A$$

Note that there is less load current available at the higher input voltage because inductor ripple current increases. At  $V_{IN} = 15V$ , duty cycle is 33% and for the same set of conditions:

$$I_{OUT(MAX)} = \frac{1.5 - (5)(15 - 5)}{2(20e - 6)(200e3)(15)}$$
$$= 1.5 - 0.42 = 1.08A$$

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To calculate actual peak switch current with a given set of conditions, use:

$$I_{SW(PK)} = \frac{I_{OUT} + V_{OUT}(V_{IN} - V_{OUT})}{2(L)(f)(V_{IN})}$$

For lighter loads where discontinuous operation can be used, maximum load current is equal to:

$$I_{OUT(MAX)} = \frac{{I_{PK}}^2 2(f)(L)(V_{IN})}{2(V_{OUT})(V_{IN} - V_{OUT})}$$

#### CHOOSING THE INDUCTOR

For most applications the output inductor will fall in the range of  $15\mu H$  to  $100\mu H$ . Lower values are chosen to reduce physical size of the inductor. Higher values allow more output current because they reduce peak current seen by the LT1976 switch, which has a 1.5A limit. Higher values also reduce output ripple voltage and reduce core loss.

When choosing an inductor you might have to consider maximum load current, core and copper losses, allowable component height, output voltage ripple, EMI, fault current in the inductor, saturation and of course cost. The following procedure is suggested as a way of handling these somewhat complicated and conflicting requirements.

 Choose a value in microhenries from the graph of maximum load current. Choosing a small inductor with lighter loads may result in discontinuous mode of operation, but the LT1976 is designed to work well in either mode.

Assume that the average inductor current is equal to load current and decide whether or not the inductor must withstand continuous fault conditions. If maximum load current is 0.5A, for instance, a 0.5A inductor may not survive a continuous 2A overload condition.

2. Calculate peak inductor current at full load current to ensure that the inductor will not saturate. Peak current can be significantly higher than output current, especially with smaller inductors and lighter loads, so don't omit

Table 3. Inductor Selection Criteria

|             |   | 1       |   |  |  |  |  |  |
|-------------|---|---------|---|--|--|--|--|--|
| VALUE (μH)  | I <sub>RMS</sub> (A)  | DCR (Ω) | HEIGHT (mm)   |  |  |  |  |  |
| Coiltronics |   |         |   |  |  |  |  |  |
| 15          | 1.4   | 0.087   | 4.2   |  |  |  |  |  |
| 15          | 1.1   | 0.08    | 4.2   |  |  |  |  |  |
| 33          | 1.3   | 0.126   | 6   |  |  |  |  |  |
| 33          | 1.4   | 0.106   | 6   |  |  |  |  |  |
| 33          | 2.4   | 0.099   | 5.9   |  |  |  |  |  |
| 100         | 0.9   | 0.146   | 5.9   |  |  |  |  |  |
| 100         | 1.7   | 0.19    | 5.9   |  |  |  |  |  |
| 100         | 1.4   | 0.277   | 5.9   |  |  |  |  |  |
|             |   |         |   |  |  |  |  |  |
| 15          | 1.4   | 0.076   | 4   |  |  |  |  |  |
| 15          | 1.6   | 0.062   | 4   |  |  |  |  |  |
| 33          | 0.97  | 0.122   | 3   |  |  |  |  |  |
| 33          | 2.1   | 0.069   | 3.8   |  |  |  |  |  |
| 33          | 2.1   | 0.044   | 6   |  |  |  |  |  |
| 47          | 2.1   | 0.095   | 3.8   |  |  |  |  |  |
| 47          | 1.8   | 0.058   | 6   |  |  |  |  |  |
| 68          | 0.75  | 0.173   | 4   |  |  |  |  |  |
| 68          | 1.5   | 0.158   | 3.8   |  |  |  |  |  |
| 68          | 1.5   | 0.093   | 6   |  |  |  |  |  |
| 100         | 1.35  | 0.225   | 3.8   |  |  |  |  |  |
| 100         | 1.5   | 0.120   | 6   |  |  |  |  |  |
|             |   |         |   |  |  |  |  |  |
| 15          | 1.8   | 0.06    | 5   |  |  |  |  |  |
| 33          | 1.3   | 0.09    | 5   |  |  |  |  |  |
| 47          | 1   | 0.11    | 5   |  |  |  |  |  |
|             | 15<br>15<br>33<br>33<br>33<br>100<br>100<br>100<br>15<br>15<br>33<br>33<br>47<br>47<br>47<br>68<br>68<br>68<br>100<br>100 | 15      | 15         1.4         0.087           15         1.1         0.08           33         1.3         0.126           33         1.4         0.106           33         2.4         0.099           100         0.9         0.146           100         1.7         0.19           100         1.4         0.277           15         1.4         0.076           15         1.6         0.062           33         2.1         0.069           33         2.1         0.044           47         2.1         0.095           47         1.8         0.058           68         0.75         0.173           68         1.5         0.158           68         1.5         0.093           100         1.35         0.225           100         1.5         0.120 |  |  |  |  |  |

this step. Powdered iron cores are forgiving because they saturate softly, whereas ferrite cores saturate abruptly. Other core materials fall somewhere in between. The following formula assumes continuous mode of operation, but it errs only slightly on the high side for discontinuous mode, so it can be used for all conditions.

$$I_{PEAK} = I_{OUT} + \frac{V_{OUT}(V_{IN} - V_{OUT})}{2(f)(L)(V_{IN})}$$

 $V_{\text{IN}}$  = maximum input voltage

f = switching frequency, 200kHz



- 3. Decide if the design can tolerate an "open" core geometry like a rod or barrel, which have high magnetic field radiation, or whether it needs a closed core like a toroid to prevent EMI problems. This is a tough decision because the rods or barrels are temptingly cheap and small and there are no helpful guidelines to calculate when the magnetic field radiation will be a problem.
- 4. After making an initial choice, consider the secondary things like output voltage ripple, second sourcing, etc. Use the experts in the Linear Technology's applications department if you feel uncertain about the final choice. They have experience with a wide range of inductor types and can tell you about the latest developments in low profile, surface mounting, etc.

#### **Short-Circuit Considerations**

The LT1976 is a current mode controller. It uses the  $V_C$  node voltage as an input to a current comparator which turns off the output switch on a cycle-by-cycle basis as this peak current is reached. The internal clamp on the  $V_C$  node, nominally 2.2V, then acts as an output switch peak current limit. This action becomes the switch current limit specification. The maximum available output power is then determined by the switch current limit.

A potential controllability problem could occur under short-circuit conditions. If the power supply output is short circuited, the feedback amplifier responds to the low output voltage by raising the control voltage,  $V_C$ , to its peak current limit value. Ideally, the output switch would be turned on, and then turned off as its current exceeded the value indicated by  $V_C$ . However, there is finite response time involved in both the current comparator and turn-off of the output switch. These result in a minimum on time  $t_{ON(MIN)}$ . When combined with the large ratio of  $V_{IN}$  to  $(V_F + I \bullet R)$ , the diode forward voltage plus inductor  $I \bullet R$  voltage drop, the potential exists for a loss of control. Expressed mathematically the requirement to maintain control is:

$$f \bullet t_{ON} \le \frac{V_F + I \bullet R}{V_{IN}}$$

where:

f = switching frequency

 $t_{ON}$  = switch on time

 $V_F$  = diode forward voltage

V<sub>IN</sub> = Input voltage

I • R = inductor I • R voltage drop

If this condition is not observed, the current will not be limited at  $I_{PK}$  but will cycle-by-cycle ratchet up to some higher value. Using the nominal LT1976 clock frequency of 200kHz, a  $V_{IN}$  of 40V and a  $(V_F + I - R)$  of say 0.7V, the maximum  $t_{ON}$  to maintain control would be approximately 90ns, an unacceptably short time.

The solution to this dilemma is to slow down the oscillator to allow the current in the inductor to drop to a sufficiently low value such that the current doesn't continue to ratchet higher. When the FB pin voltage is abnormally low thereby indicating some sort of short-circuit condition, the oscillator frequency will be reduced. Oscillator frequency is reduced by a factor of 4 when the FB pin voltage is below 0.4V and increases linearly to its typical value of 200kHz at a FB voltage of 0.95V (see Typical Performance Characteristics). In addition, if the current in the switch exceeds 1.5 
•  $I_{PK}$  current demanded by the  $V_C$  pin, the LT1976 will skip the next on cycle effectively reducing the oscillator frequency by a factor of 2. These oscillator frequency reductions during short-circuit conditions allow the LT1976 to maintain current control.

#### **SOFT-START**

For applications where  $[V_{IN}/(V_{OUT} + V_F)]$  ratios > 10 or large input surge currents can't be tolerated, the LT1976 soft-start feature should be used to control the output capacitor charge rate during start-up, or during recovery from an output short circuit thereby adding additional control over peak inductor current. The soft-start function limits the switch current via the  $V_C$  pin to maintain a constant voltage ramp rate (dV/dt) at the output capacitor. A capacitor (C1 in Figure 2) from the  $C_{SS}$  pin to the regulated output voltage determines the output voltage ramp rate. When the current through the  $C_{SS}$  capacitor

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exceeds the  $C_{SS}$  threshold ( $I_{CSS}$ ), the voltage ramp of the output capacitor is limited by reducing the  $V_C$  pin voltage. The  $C_{SS}$  threshold is proportional to the FB voltage (see Typical Performance Characteristics) and is defeated for FB voltages greater than 0.9V (typical). The output dV/dt can be approximated by:

$$\frac{dV}{dt} = \frac{C_{SS}}{I_{CSS}}$$

but actual values will vary due to start-up load conditions, compensation values and output capacitor selection.

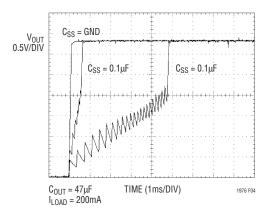


Figure 4. V<sub>OUT</sub> dV/dt

#### **Burst Mode OPERATION**

To enhance efficiency at light loads, the LT1976 automatically switches to Burst Mode operation which keeps the output capacitor charged to the proper voltage while minimizing the input quiescent current. During Burst Mode operation, the LT1976 delivers short bursts of current to the output capacitor followed by sleep periods where the output power is delivered to the load by the output capacitor. In addition,  $V_{IN}$  and BIAS quiescent currents are reduced to typically 45 $\mu$ A and 125 $\mu$ A respectively during the sleep time. As the load current decreases towards a no load condition, the percentage of time that the LT1976 operates in sleep mode increases and the average input current is greatly reduced resulting in higher efficiency.

The minimum average input current depends on the  $V_{IN}$  to  $V_{OUT}$  ratio,  $V_{C}$  frequency compensation, feedback divider

network and Schottky diode leakage. It can be approximated by the following equation:

$$I_{IN(AVG)} = I_{VINS} + I_{SHDN} + \left(\frac{V_{OUT}}{V_{IN}}\right) \frac{\left(I_{BIASS} + I_{FB} + I_{S}\right)}{\left(\eta\right)}$$

where

I<sub>VINS</sub> = input pin current in sleep mode

 $V_{OUT}$  = output voltage

V<sub>IN</sub> = input voltage

I<sub>BIASS</sub> = BIAS pin current in sleep mode

I<sub>FB</sub> = feedback network current

 $I_S$  = catch diode reverse leakage at  $V_{OUT}$ 

 $\eta$  = low current efficiency (non Burst Mode operation)

Example: For  $V_{OUT} = 3.3V$ ,  $V_{IN} = 12V$ 

$$\begin{split} I_{IN(AVG)} &= 45\mu A + 5\mu A + \left(\frac{3.3}{12}\right) \frac{\left(125\mu A + 12.5\mu A + 0.5\mu A\right)}{\left(0.8\right)} \\ &= 45\mu A + 5\mu A + 44\mu A = 99\mu A \end{split}$$

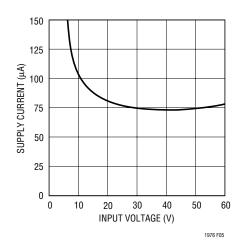


Figure 5. Io vs VIN

During the sleep portion of the Burst Mode cycle, the  $V_{C}$  pin voltage is held just below the level needed for normal operation to improve transient response. See the Typical Performance Characteristics section for burst and transient response waveforms.

If a no load condition can be anticipated, the supply current can be further reduced by cycling the SHDN pin at a rate higher than the natural no load burst frequency. Figure 6



shows Burst Mode operation with the  $\overline{SHDN}$  pin.  $V_{OUT}$  burst ripple is maintained while the average supply current drops to 15µA.

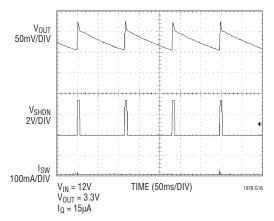


Figure 6. Burst Mode with Shutdown Pin

#### **CATCH DIODE**

The catch diode carries load current during the SW off time. The average diode current is therefore dependent on the switch duty cycle. At high input to output voltage ratios the diode conducts most of the time. As the ratio approaches unity the diode conducts only a small fraction of the time. The most stressful condition for the diode is when the output is short circuited. Under this condition the diode must safely handle  $I_{PEAK}$  at maximum duty cycle.

To maximize high and low load current efficiency a fast switching diode with low forward drop and low reverse leakage should be used. Low reverse leakage is critical to maximize low current efficiency since its value over temperature can potentially exceed the magnitude of the LT1976 supply current. Low forward drop is critical for high current efficiency since the loss is proportional to forward drop.

These requirements result in the use of a Schottky type diode. DC switching losses are minimized due to its low forward voltage drop and AC behavior is benign due to its lack of a significant reverse recovery time. Schottky diodes are generally available with reverse voltage ratings of 60V and even 100V and are price competitive with other types.

The effect of reverse leakage and forward drop on efficiency for various Schottky diodes is shown in Table 4. As can be seen these are conflicting parameters and the user

**Table 4. Catch Diode Selection Criteria** 

|            | LEAKAGE<br>V <sub>OUT</sub> = 3.3V |        | V <sub>F</sub> AT 1A |       | EFFICIENCY |                     |
|------------|------------------------------------|--------|----------------------|-------|------------|---------------------|
| DIODE      | 25°C                               | 125°C  | 25°C                 | 125°C | $I_L = 0A$ | I <sub>L</sub> = 1A |
| MBR0540    | 0.25μΑ                             | 0.25μΑ | 0.50V                | 0.50V | TBD        | TBD                 |
| UPS5817    | 2.8μΑ                              | 2.8μΑ  | 0.41V                | 0.41V | TBD        | TBD                 |
| MBR0520    | 3.7μΑ                              | 3.7μΑ  | 0.36V                | 0.36V | TBD        | TBD                 |
| MBRS120T3  | 4.4μΑ                              | 4.4μΑ  | 0.43V                | 0.43V | TBD        | TBD                 |
| MBRM120LT3 | 8.3μΑ                              | 8.3µA  | 0.32V                | 0.32V | TBD        | TBD                 |
| MBRS320    | 19.7μΑ                             | 19.7μΑ | 0.29V                | 0.29V | TBD        | TBD                 |

must weigh the importance of each specification in choosing the best diode for the application.

The use of so-called "ultrafast" recovery diodes is generally not recommended. When operating in continuous mode, the reverse recovery time exhibited by "ultrafast" diodes will result in a slingshot type effect. The power internal switch will ramp up  $V_{IN}$  current into the diode in an attempt to get it to recover. Then, when the diode has finally turned off, some tens of nanoseconds later, the  $V_{SW}$  node voltage ramps up at an extremely high dV/dt, perhaps 5V to even 10V/ns! With real world lead inductances the  $V_{SW}$  node can easily overshoot the  $V_{IN}$  rail. This can result in poor RFI behavior and, if the overshoot is severe enough, damage the IC itself.

#### **BOOST PIN**

For most applications the boost components are a 0.33µF capacitor and a MMSD914 diode. The anode is typically connected to the regulated output voltage to generate a voltage approximately  $V_{OUT}$  above  $V_{IN}$  to drive the output stage. However, the output stage discharges the boost capacitor during the on time of the switch. The output driver requires at least xV of headroom throughout this period to keep the switch fully saturated. If the output voltage is less than 3.3V it is recommended that an alternate boost supply is used. The boost diode can be connected to the input but care must be taken to prevent the boost voltage (V<sub>BOOST</sub> = V<sub>IN</sub> • 2) from exceeding the BOOST pin absolute maximum rating. The additional voltage across the switch driver also increases power loss and reduces efficiency. If available, an independent supply can be used with a local bypass capacitor.

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A  $0.33\mu F$  boost capacitor is recommended for most applications. Almost any type of film or ceramic capacitor is suitable but the ESR should be  $<1\Omega$  to ensure it can be fully recharged during the off time of the switch. The capacitor value is derived from worst-case conditions of 4700ns on time, 42mA boost current and 0.7V discharge ripple. The boost capacitor value could be reduced under less demanding conditions but this will not improve circuit operation or efficiency. Under low input voltage and low load conditions a higher value capacitor will reduce discharge ripple and improve start-up operation.

# SHUTDOWN FUNCTION AND UNDERVOLTAGE LOCKOUT

The SHDN pin on the LT1976 controls the operation of the IC. When the voltage on the SHDN pin is below the 1.2V shutdown threshold the LT1976 is placed in a "zero" supply current state. Driving the SHDN pin above the shutdown threshold enables normal operation. The SHDN pin has an internal sink current of 3µA.

In addition to the shutdown feature, the LT1976 has an undervoltage lockout function. When the input voltage is below 2.4V, switching will be disabled. The undervoltage lockout threshold doesn't have any hysteresis and is mainly used to insure that all internal voltages are at the correct level before switching is enabled. If an undervoltage lockout function is needed to limit input current at low  $V_{\mbox{\scriptsize IN}}$  to  $V_{\mbox{\scriptsize OUT}}$  ratios refer to Figure 7 and the following:

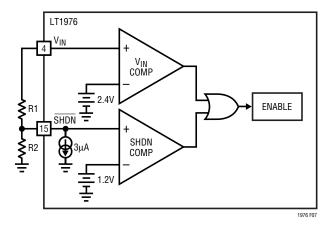


Figure 7. Undervoltage Lockout

$$V_{UVLO} = \frac{1.3V(R1+R2) + (3\mu A)(R1)(R2)}{R2}$$

See the Typical Performance Characteristics section for graphs of SHDN and  $V_{\text{IN}}$  currents verses input voltage.

#### **SYNCHRONIZING**

Oscillator synchronization to an external input is achieved by connecting a TTL logic-compatible square wave with a duty cycle between 20% and 80% to the LT1976 SYNC pin. The synchronizing range is equal to initial operating frequency up to 700kHz. This means that minimum practical sync frequency is equal to the worst-case high selfoscillating frequency (2xxkHz), not the typical operating frequency of 200kHz. Caution should be used when synchronizing above 2xxkHz because at higher sync frequencies the amplitude of the internal slope compensation used to prevent subharmonic switching is reduced. This type of subharmonic switching only occurs at input voltages less than twice output voltage. Higher inductor values will tend to eliminate this problem. See Frequency Compensation section for a discussion of an entirely different cause of subharmonic switching before assuming that the cause is insufficient slope compensation. Application Note 19 has more details on the theory of slope compensation.

If the FB pin voltage is below 0.9XV (power-up or output short-circuit conditions) the sync function is disabled. This allows the frequency foldback to operate to avoid and hazardous conditions for the SW pin.

If no synchronization is required this pin should be connected to ground.

#### **POWER GOOD**

The LT1976 contains a power good block which consists of a comparator, delay timer and active low flag that allows the user to generate a delayed signal after the power good threshold is exceeded.

Referring to Figure 2, the PGFB pin is the positive input to a comparator whose negative input is set at  $V_{PGFB}$ . When PGFB is taken above  $V_{PGFB}$ , current ( $I_{CSS}$ ) is sourced into the  $C_T$  pin starting the delay period. When the voltage on



the PGFB pin drops below  $V_{PGFB}$  the  $C_{T}$  pin is rapidly discharged resetting the delay period. The PGFB voltage is typically generated by a resistive divider from the regulated output or input supply.

The capacitor on the  $C_T$  pin determines the amount of delay time between the PGFB pin exceeding its threshold  $(V_{PGFB})$  and the PG pin set to a high impedance state. When the PGFB pin rises above  $V_{PGFB}$  current is sourced  $(I_{CT})$  from the  $C_T$  pin into the external capacitor. When the voltage on the external capacitor reaches an internal clamp  $(V_{CT})$ , the PG pin becomes a high impedance node. The resultant PG delay time is given by  $t = C_{CT} \cdot (V_{CT})/(I_{CT})$ . If the voltage on the PGFB pin drops below its  $V_{PGFB}$ ,  $C_{CT}$  will be discharged rapidly and PG will be active low with a  $200\mu A$  sink capability. Figure 8 shows the power good operation with PGFB connected to FB and the capacitance on  $C_T = 0.1\mu F$ .

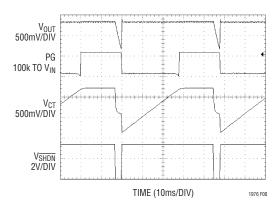


Figure 8. Power Good

#### LAYOUT CONSIDERATIONS

As with all high frequency switchers, when considering layout, care must be taken in order to achieve optimal electrical, thermal and noise performance. For maximum efficiency switch rise and fall times are typically in the nanosecond range. To prevent noise both radiated and conducted the high speed switching current path, shown in Figure 9, must be kept as short as possible. This is implemented in the suggested layout of Figure 10. Shortening this path will also reduce the parasitic trace inductance of approximately 25nH/inch. At switch off, this parasitic inductance produces a flyback spike across the LT1976 switch. When operating at higher currents and

input voltages, with poor layout, this spike can generate voltages across the LT1976 that may exceed its absolute maximum rating. A ground plane should always be used under the switcher circuitry to prevent interplane coupling and overall noise.

The  $V_{\text{C}}$  and FB components should be kept as far away as possible from the switch and boost nodes. The LT1976 pinout has been designed to aid in this. The ground for these components should be separated from the switch current path. Failure to do so will result in poor stability or subharmonic like oscillation.

Board layout also has a significant effect on thermal resistance. Pin 8 and the exposed die pad are a continuous copper plate that runs under the LT1976 die. This is the best thermal path for heat out of the package. Reducing the thermal resistance from Pin 8 and exposed pad onto the

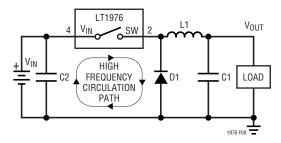


Figure 9. High Speed Switching Path

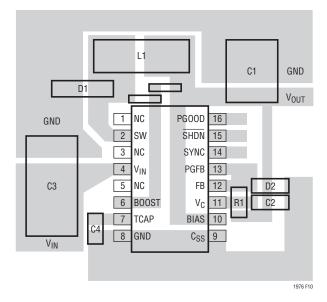


Figure 10. Suggested Layout (Topside Only Shown)

LINEAR TECHNOLOGY

board will reduce die temperature and increase the power capability of the LT1976. This is achieved by providing as much copper area as possible around the exposed pad. Adding multiple solder filled feedthroughs under and around this pad to an internal ground plane will also help. Similar treatment to the catch diode and coil terminations will reduce any additional heating effects.

#### THERMAL CALCULATIONS

Power dissipation in the LT1976 chip comes from four sources: switch DC loss, switch AC loss, boost circuit current, and input quiescent current. The following formulas show how to calculate each of these losses. These formulas assume continuous mode operation, so they should not be used for calculating efficiency at light load currents.

Switch loss:

$$P_{SW} = \frac{R_{SW} \big(I_{OUT}\big)^2 \big(V_{OUT}\big)}{V_{IN} + t_{EFF} \big(1/2\big) \big(I_{OUT}\big) \big(V_{IN}\big) (f)}$$

Boost current loss:

$$P_{BOOST} = \frac{\left(V_{OUT}\right)^2 \left(I_{OUT}/36\right)}{V_{IN}}$$

Quiescent current loss:

$$P_0 = V_{IN} (0.0015) + V_{OUT} (0.003)$$

 $R_{SW}$  = switch resistance ( $\approx 0.3$  when hot )

t<sub>EFF</sub> = effective switch current/voltage overlap time

$$\left(t_r + t_f + t_{IR} + t_{IF}\right)$$

$$t_r = (V_{IN}/1.2) ns$$

$$t_f = (V_{IN}/1.7)ns$$

$$t_{IR} = t_{IF} = (I_{OUT}/0.05)ns$$

f = switch frequency

Example: with  $V_{IN} = 40V$ ,  $V_{OUT} = 5V$  and  $I_{OUT} = 1A$ :

$$P_{SW} = \frac{(0.3)(1)^2(5)}{40} + (97e - 9)(1/2)(1)(40)(200e3)$$

$$0.04 + 0.388 = 0.43W$$

$$P_{BOOST} = \frac{(5)^2 (1/36)}{40} = 0.02W$$

$$P_Q = 40(0.0015) + 5(0.003) = 0.08W$$

Total power dissipation is:

$$P_{TOT} = 0.43 + 0.02 + 0.08 = 0.53W$$

Thermal resistance for the LT1976 package is influenced by the presence of internal or backside planes. With a full plane under the FE16 package, thermal resistance will be about 45°C/W. No plane will increase resistance to about 150°C/W. To calculate die temperature, use the proper thermal resistance number for the desired package and add in worst-case ambient temperature:

$$T_J = T_A + Q_{JA} (P_{TOT})$$

With the FE16 package ( $Q_{JA} = 45^{\circ}C/W$ ) at an ambient temperature of  $70^{\circ}C$ :

$$T_{J} = 70 + 45(0.53) = 94^{\circ}C$$

### Input Voltage vs Operating Frequency Considerations

The absolute maximum input supply voltage for the LT1976 is specified at 60V. This is based solely on internal semi-conductor junction breakdown effects. Due to internal power dissipation the actual maximum  $V_{\text{IN}}$  achievable in a particular application may be less than this.

A detailed theoretical basis for estimating internal power loss is given in the section Thermal Considerations. Note that AC switching loss is proportional to both operating frequency and output current. The majority of AC switching loss is also proportional to the square of input voltage.



For example, while the combination of  $V_{IN} = 40V$ ,  $V_{OUT} = 5V$  at 1A and  $f_{OSC} = 200k$ Hz may be easily achievable, simultaneously raising  $V_{IN}$  to 60V and  $f_{OSC}$  to 700kHz is not possible. Nevertheless, input voltage transients up to 60V can usually be accommodated, assuming the resulting increase in internal dissipation is of insufficient time duration to raise die temperature significantly.

A second consideration is controllability. A potential limitation occurs with a high step-down ratio of  $V_{IN}$  to  $V_{OUT}$ , as this requires a correspondingly narrow minimum switch on time. An approximate expression for this (assuming continuous mode operation) is given as follows:

 $t_{ON(MIN)} = V_{OUT} + V_F/V_{IN}(f_{OSC})$ 

where:

V<sub>IN</sub> = input voltage

 $V_{OLIT}$  = output voltage

V<sub>F</sub> = Schottky diode forward drop

 $f_{OSC}$  = switching frequency

A potential controllability problem arises if the LT1976 is called upon to produce an on time shorter than it is able to produce. Feedback loop action will lower then reduce the  $V_{C}$  control voltage to the point where some sort of cycleskipping or Burst Mode behavior is exhibited.

In summary:

- Be aware that the simultaneous requirements of high V<sub>IN</sub>, high I<sub>OUT</sub> and high f<sub>OSC</sub> may not be achievable in practice due to internal dissipation. The Thermal Considerations section offers a basis to estimate internal power. In questionable cases a prototype supply should be built and exercised to verify acceptable operation.
- 2. The simultaneous requirements of high  $V_{IN}$ , low  $V_{OUT}$  and high  $f_{OSC}$  can result in an unacceptably short minimum switch on time. Cycle skipping and/or Burst Mode behavior will result although correct output voltage is usually maintained.

#### FREQUENCY COMPENSATION

Before starting on the theoretical analysis of frequency response the following should be remembered—the worse the board layout, the more difficult the circuit will be to stabilize. This is true of almost all high frequency analog circuits. Read the Layout Considerations section first. Common layout errors that appear as stability problems are distant placement of input decoupling capacitor and/or catch diode and connecting the  $V_{\rm C}$  compensation to a ground track carrying significant switch current. In addition the theoretical analysis considers only first order non-ideal component behavior. For these reasons, it is important that a final stability check is made with production layout and components.

The LT1976 uses current mode control. This alleviates many of the phase shift problems associated with the inductor. The basic regulator loop is shown in Figure 10. The LT1976 can be considered as two  $g_m$  blocks, the error amplifier and the power stage.

Figure 11 shows the overall loop response with a 300pF  $V_C$  capacitor and a typical 100 $\mu$ F tantalum output capacitor. The response is set by the following terms:

Error amplifier: DC gain is set by g<sub>m</sub> and R<sub>0</sub>:

EA Gain = 600μ℧ • TBD = TBD

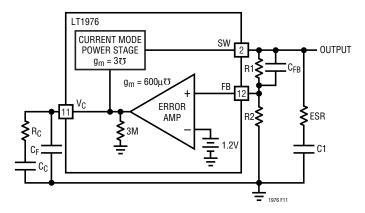


Figure 11. Model for Loop Response



The pole set by  $C_C$  and  $R_O$ :

EA Pole =  $1/(2\pi \bullet TBD \bullet TBD) = TBD$ 

Unity gain frequency is set by  $C_C$  and  $g_m$ :

EA Unity Gain Frequency = TBD/ $(2\pi \cdot C_C)$  = TBD

Powerstage: DC gain is set by  $g_m$  and  $R_L$  (assume  $10\Omega$ ):

PS DC Gain = TBD • 10 = TBD

Pole set by C<sub>OUT</sub> and R<sub>L</sub>:

PS Pole =  $1/(2\pi \bullet TBD \bullet 10) = TBD$ 

Unity gain set by  $C_{OUT}$  and  $g_m$ :

PS Unity Gain Freq = TBD/ $(2\pi \cdot TBD)$  TBD.

Tantalum output capacitor zero is set by  $C_{OUT}$  and  $C_{OUT}$  FSR

Output Capacitor Zero =  $1/(2\pi \bullet TBD \bullet 0.1) = TBD$ 

The zero produced by the ESR of the tantalum output capacitor is very useful in maintaining stability. If better transient response is required, a zero can be added to the loop using a resistor ( $R_{\text{C}}$ ) in series with the compensation capacitor. As the value of  $R_{\text{C}}$  is increased, transient response will generally improve but two effects limit its value. First, the combination of output capacitor ESR and a large  $R_{\text{C}}$  may stop loop gain rolling off altogether. Second, if the loop gain is not rolled off sufficiently at the switching frequency output ripple will perturb the  $V_{\text{C}}$  pin

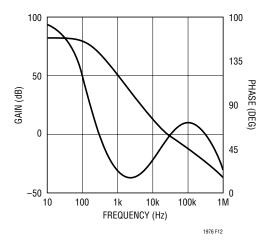


Figure 12. Overall Loop Response

enough to cause unstable duty cycle switching similar to subharmonic oscillation. This may not be apparent at the output. Small-signal analysis will not show this since a continuous time system is assumed. If needed, an additional capacitor ( $C_F$ ) can be added to form a pole at typically one-fifth the switching frequency (if  $R_C = \approx TBD$ ,  $C_F = \approx TBD$ )

When checking loop stability the circuit should be operated over the application's full voltage, current and temperature range. Any transient loads should be applied and the output voltage monitored for a well-damped behavior.

#### CONVERTER WITH BACKUP OUTPUT REGULATOR

In systems with a primary and backup supply, for example a battery-powered device with a wall adapter input, the output of the LT1976 can be held up by the backup supply with the LT1976 input disconnected. In this condition the SW pin will source current into the  $V_{IN}$  pin. If the SHDN pin is held at ground or floating, only the shutdown current of  $1\mu A$  will be pulled via the SW pin from the second supply. With the SHDN pin tied to  $V_{IN}$ , the LT1976 will consume its quiescent operating current of 1.xmA. The  $V_{IN}$  pin will also source current to any other components connected to the input line. If this load is greater than 10mA or the input could be shorted to ground, a series Schottky diode must be added as shown in Figure 13. With these safeguards the output can be held at voltages up to the  $V_{IN}$  absolute maximum rating.

#### **DUAL OUTPUT SEPIC CONVERTER**

The circuit in Figure 14 generates both positive and negative 5V outputs with a single piece of magnetics. The two inductors shown are actually just two windings on a standard Coiltronics inductor. The topology for the 5V output is a standard buck converter. The -5V topology would be a simple flyback winding coupled to the buck converter if C4 were not present. C4 creates a SEPIC (single-ended primary inductance converter) topology which improves regulation and reduces ripple current in L1. Without C4, the voltage swing on L1B compared to L1A would vary due to relative loading and coupling



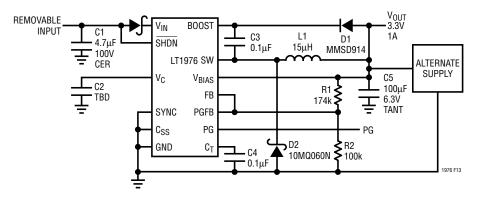


Figure 13. Dual Source Supply

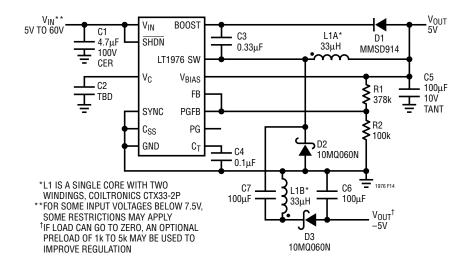


Figure 14. Dual Output Sepic Converter

losses. C4 provides a low impedance path to maintain an equal voltage swing in L1B, improving regulation. In a flyback converter, during switch on time, all the converter's energy is stored in L1A only, since no current flows in L1B. At switch off, energy is transferred by magnetic coupling into L1B, powering the -5V rail. C4 pulls L1B positive

during switch on time, causing current to flow and energy to build in L1B and C4. At switch off, the energy stored in both L1B and C4 supply the -5V rail. This reduces the current in L1A and changes L1B current waveform from square to triangular. For details on this circuit, including maximum output currents, see Design Note 100.

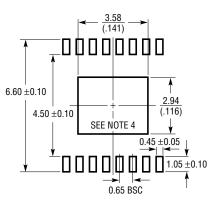
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### PACKAGE DESCRIPTION

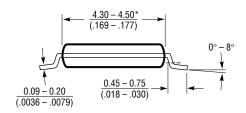
#### **FE Package** 16-Lead Plastic TSSOP (4.4mm)

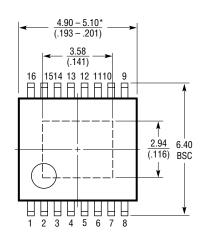
(Reference LTC DWG # 05-08-1663)

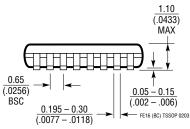
#### **Exposed Pad Variation BC**



RECOMMENDED SOLDER PAD LAYOUT







- 2. DIMENSIONS ARE IN MILLIMETERS (INCHES)
- 3. DRAWING NOT TO SCALE
- NOTE: (.0077 .0110)

  1. CONTROLLING DIMENSION: MILLIMETERS 4. RECOMMENDED MINIMUM PCB METAL SIZE FOR EXPOSED PAD ATTACHMENT
  - \*DIMENSIONS DO NOT INCLUDE MOLD FLASH. MOLD FLASH SHALL NOT EXCEED 0.150mm (.006") PER SIDE



## **RELATED PARTS**

| PART NUMBER       | DESCRIPTION  | COMMENTS  |
|-------------------|--|---|
| LT1074/LT1074HV   | 4.4A (I <sub>OUT</sub> ), 100kHz, High Efficiency Step-Down DC/DC Converter          | V <sub>IN</sub> : 7.3V to 45V/64V, V <sub>OUT(MIN)</sub> : 2.21V, I <sub>Q</sub> : 8.5mA, I <sub>SD</sub> : 10μA, DD5/7, T0220-5/7          |
| LT1076/LT1076HV   | 1.6A (I <sub>OUT</sub> ), 100kHz, High Efficiency Step-Down DC/DC Converter          | V <sub>IN</sub> : 7.3V to 45V/64V, V <sub>OUT(MIN)</sub> : 2.21V, I <sub>Q</sub> : 8.5mA, I <sub>SD</sub> : 10μA, DD5/7, T0220-5/7          |
| LT1676            | 60V, 440mA (I <sub>OUT</sub> ), 100kHz, High Efficiency Step-Down DC/DC<br>Converter | $V_{IN}$ : 7.4V to 60V, $V_{OUT(MIN)}$ : 1.24V, $I_Q$ : 3.2mA, $I_{SD}$ : 2.5 $\mu$ A, S8   |
| LT1765            | 25V, 2.75A (I <sub>OUT</sub> ), 1.25MHz, High Efficiency Step-Down DC/DC Converter   | $V_{\text{IN}}$ : 3V to 25V, $V_{\text{OUT}(\text{MIN})}$ : 1.20V, $I_{\text{Q}}$ : 1mA, $I_{\text{SD}}$ : 15 $\mu\text{A},$ S0-8, TSS0P16E |
| LT1766            | 60V, 1.2A (I <sub>OUT</sub> ), 200kHz, High Efficiency Step-Down DC/DC<br>Converter  | $V_{\text{IN}}$ : 5.5V to 60V, $V_{\text{OUT(MIN)}}$ : 1.20V, $I_{\text{Q}}$ : 2.5mA, $I_{\text{SD}}$ : 25µA, TSSOP16/E                     |
| LT1767            | 25V, 1.2A (I <sub>OUT</sub> ), 1.25MHz, High Efficiency Step-Down DC/DC Converter    | $V_{\text{IN}}$ : 3V to 25V, $V_{\text{OUT}(\text{MIN})}$ : 1.20V, $I_{\text{Q}}$ : 1mA, $I_{\text{SD}}$ : 6µA, MS8/E                       |
| LT1776            | 40V, 550mA (I <sub>OUT</sub> ), 200kHz, High Efficiency Step-Down DC/DC Converter    | $V_{IN}$ : 7.4V to 40V, $V_{OUT(MIN)}$ : 1.24V, $I_Q$ : 3.2mA, $I_{SD}$ : 30 $\mu A$ , N8, S8   |
| LTC®1875          | 1.5A (I <sub>OUT</sub> ), 550kHz, Synchronous Step-Down DC/DC Converter              | $V_{IN}$ : 2.7V to 6V, $V_{OUT(MIN)}$ : 0.8V, $I_Q$ : 15 $\mu$ A, $I_{SD}$ : <1 $\mu$ A, TSSOP16  |
| LT1956            | 60V, 1.2A (I <sub>OUT</sub> ), 500kHz, High Efficiency Step-Down DC/DC<br>Converter  | $V_{\text{IN}}$ : 5.5V to 60V, $V_{\text{OUT(MIN)}}$ : 1.20V, $I_{\text{Q}}$ : 2.5mA, $I_{\text{SD}}$ : 25µA, TSSOP16/E                     |
| LT3010            | 80V, 50mA, Low Noise Linear Regulator  | $V_{IN}$ : 1.5V to 80V, $V_{OUT(MIN)}$ : 1.28V, IQ: 30 $\mu$ A, ISD: <1 $\mu$ A, MS8E   |
| LTC3412           | 2.5A (I <sub>OUT</sub> ), 4MHz, Synchronous Step-Down DC/DC Converter                | $V_{IN}$ : 2.5V to 5.5V, $V_{OUT(MIN)}$ : 0.8V, $I_{Q}$ : 60 $\mu$ A, $I_{SD}$ : <1 $\mu$ A, TSSOP16E                                       |
| LT3430            | 60V, 2.75A (I <sub>OUT</sub> ), 200kHz, High Efficiency Step-Down DC/DC Converter    | $V_{\text{IN}}$ : 5.5V to 60V, $V_{\text{OUT(MIN)}}$ : 1.20V, Iq: 2.5mA, IsD: 30 $\mu\text{A}$ , TSSOP16E                                   |
| LT3431            | 60V, 2.75A (I <sub>OUT</sub> ), 500kHz, High Efficiency Step-Down DC/DC Converter    | $V_{\text{IN}}$ : 5.5V to 60V, $V_{\text{OUT(MIN)}}$ : 1.20V, Iq: 2.5mA, IsD: 30µA, TSSOP16E  |
| LTC3727/LTC3727-1 | 36V, 500kHz, High Efficiency Step-Down DC/DC Converter                               | V <sub>IN</sub> : 4V to 36V, V <sub>OUT(MIN)</sub> : 0.8V, I <sub>Q</sub> : 670μA, I <sub>SD</sub> : 20μA, QFN-32, SSOP-28                  |