

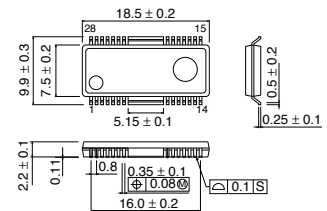
Current feedback actuator driver

BA5954FP/FM

●Description

BA5954FP/FM is an actuator driver IC for CD-ROM and DVD players. This actuator driver adopts current feedback system. This IC incorporates 2 channel actuator drivers and 2 channel motor drivers. Current phase lag influenced load inductance is little, because this type is current feedback.

●Dimension (Units : mm)



HSOP28 / HSOP-M28

●Features

- 1) Wide dynamic range
 $V_{OM}4.0V(\text{typ.})$ at $\text{Pre}V_{CC}=12V, \text{PV}_{CC}=5V, R_L=8\Omega$
- 2) Level shift circuit built in.
- 3) Thermal-shut-down circuit built in.
- 4) Stand-by mode built in.

●Applications

CD/CD-ROM

●Absolute Maximum Ratings ($T_a=25^\circ\text{C}$)

Parameter	Symbol	Limits		Unit
Supply voltage	$V_{CC}, \text{PV}_{CC1/2}$	18		V
Power dissipation	P_d	(BA5954FP) *1 1.7	(BA5954FM) *2 2.2	W
Operating temperature range	T_{opr}	$-35 \sim +85$		$^\circ\text{C}$
Storage temperature range	T_{stg}	$-55 \sim +150$		$^\circ\text{C}$

* PCB (70mmx70mm, $t=1.6\text{mm}$) glass epoxy mounting.

*1 Derating : $13.6\text{mW}/^\circ\text{C}$ for operation above $T_a=25^\circ\text{C}$

*2 Derating : $17.6\text{mW}/^\circ\text{C}$ for operation above $T_a=25^\circ\text{C}$

●Recommended Operating Conditions ($T_a=25^\circ\text{C}$)

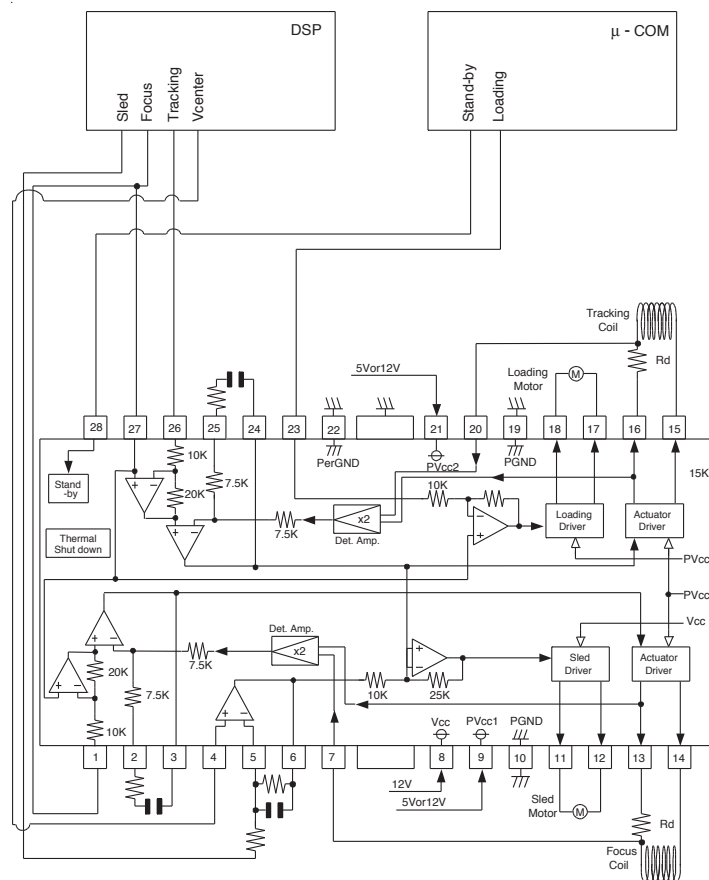
Parameter	Symbol	Limits		Unit
Power supply voltage	V_{CC}	4.3	\sim 13.2	V
	PV_{CC1}	4.3	\sim V_{CC}	V
	PV_{CC2}	4.3	\sim V_{CC}	V

● **Electrical characteristics** (Unless otherwise noted; Ta=25°C, Vcc=12V, PVcc1=PVcc2=5V, BIAS=2.5V, RL=8Ω, Rd=0.5Ω, C=100pF)

Parameter	Symbol	Min.	Typ.	Max.	Unit	Conditions
Quiescent current	I _{CC}	—	18	27	mA	
Stand-by quiescent current	I _{ST}	—	—	0.5	mA	
Voltage for stand-by ON	V _{STON}	—	—	0.5	V	
Voltage for stand-by OFF	V _{STOFF}	2.0	—	—	V	
<Actuator driver>						
Output offset voltage	I _{OO}	—6	—	6	mV	
Maximum output amplitude	V _{OM}	3.6	4.0	—	V	
Trans conductance	g _m	1.3	1.5	1.7	A/V	V _{IN} =BIAS±0.2V
<Sled motor driver/Pre OP-amp>						
Common mode input range	V _{ICM}	—0.3	—	11.0	V	
Input bias current	I _{BOP}	—	30	300	nA	
Low level output voltage	V _{OLOP}	—	0.1	0.3	V	
Output source current	I _{SO}	0.3	0.5	—	mA	
Output sink current	I _{ST}	1	—	—	mA	
<Sled motor driver>						
Output offset voltage	V _{OOFSL}	—100	0	100	mV	
Maximum output voltage	V _{OMLD}	7.5	9.0	—	V	
Closed loop voltage gain	G _{VSL}	18.0	20.0	22.0	dB	V _{IN} =±0.2V
<Loading motor driver>						
Output offset voltage	V _{OOFLD}	—50	0	50	mV	
Maximum output voltage	V _{OMLD}	3.6	4.0	—	V	
Closed loop voltage gain	G _{VLD}	13.5	15.5	17.5	dB	V _{IN} =BIAS±0.2V
Gain error by polarity	ΔG _{VLD}	0	1	2	dB	V _{IN} =BIAS±0.2V

This product is not designed for protection against radioactive rays.

- Application Circuit



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