



LMC6001 Ultra, Ultra-Low Input Current Amplifier

1 Features

- (Maximum Limit, 25°C Unless Otherwise Noted)
- Input Current (100% Tested): 25 fA
- Input Current Over Temperature: 2 pA
- Low Power: 750 μ W
- Low V_{OS} : 350 μ V
- Low Noise: 22 nV/ $\sqrt{\text{Hz}}$ at 1 kHz Typical

2 Applications

- Electrometer Amplifiers
- Photodiode Preamplifiers
- Ion Detectors
- A.T.E. Leakage Testing

3 Description

Featuring 100% tested input currents of 25 fA maximum, low operating power, and ESD protection of 2000 V, the LMC6001 device achieves a new industry benchmark for low input current operational amplifiers. By tightly controlling the molding compound, Texas Instruments is able to offer this ultra-low input current in a lower cost molded package.

To avoid long turnon settling times common in other low input current op amps, the LMC6001A is tested three times in the first minute of operation. Even units that meet the 25-fA limit are rejected if they drift.

Because of the ultra-low input current noise of 0.13 fA/ $\sqrt{\text{Hz}}$, the LMC6001 can provide almost noiseless amplification of high resistance signal sources. Adding only 1 dB at 100 k Ω , 0.1 dB at 1 M Ω and 0.01 dB or less from 10 M Ω to 2,000 M Ω , the LMC6001 is an almost noiseless amplifier.

The LMC6001 is ideally suited for electrometer applications requiring ultra-low input leakage such as sensitive photodetection transimpedance amplifiers and sensor amplifiers. Because input referred noise is only 22 nV/ $\sqrt{\text{Hz}}$, the LMC6001 can achieve higher signal to noise ratio than JFET input type electrometer amplifiers. Other applications of the LMC6001 include long interval integrators, ultra-high input impedance instrumentation amplifiers, and sensitive electrical-field measurement circuits.

Device Information⁽¹⁾

PART NUMBER	PACKAGE	BODY SIZE (NOM)
LMC6001	PDIP (8)	9.81 mm \times 6.35 mm
	TO-99 (8)	9.08 mm \times 9.08 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

Simplified Schematic

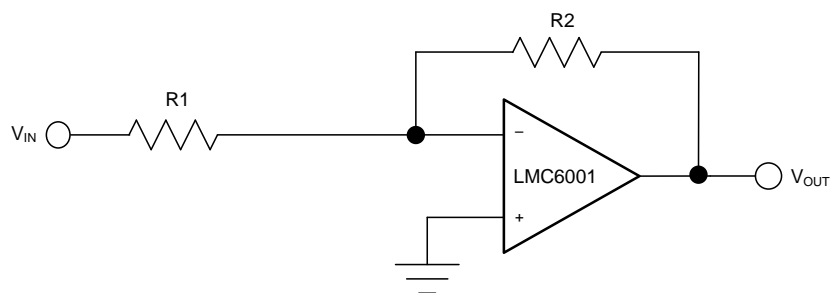


Table of Contents

1 Features	1	7.2 Functional Block Diagram	14
2 Applications	1	7.3 Feature Description	14
3 Description	1	7.4 Device Functional Modes	14
4 Revision History	2	8 Applications and Implementation	15
5 Pin Configuration and Functions	3	8.1 Application Information	15
6 Specifications	3	8.2 Typical Application	16
6.1 Absolute Maximum Ratings	3	8.3 System Example	18
6.2 ESD Ratings	4	9 Power Supply Recommendations	19
6.3 Recommended Operating Conditions	4	10 Layout	19
6.4 Thermal Information	4	10.1 Layout Guidelines	19
6.5 DC Electrical Characteristics for LMC6001AI	4	10.2 Layout Example	20
6.6 DC Electrical Characteristics for LMC6001BI	6	11 Device and Documentation Support	21
6.7 DC Electrical Characteristics for LMC6001CI	7	11.1 Documentation Support	21
6.8 AC Electrical Characteristics for LMC6001AIC	9	11.2 Related Links	21
6.9 AC Electrical Characteristics for LMC6001BI	9	11.3 Community Resources	21
6.10 AC Electrical Characteristics for LMC6001CI	10	11.4 Trademarks	21
6.11 Dissipation Ratings	10	11.5 Electrostatic Discharge Caution	21
6.12 Typical Characteristics	11	11.6 Glossary	21
7 Detailed Description	14	12 Mechanical, Packaging, and Orderable Information	21
7.1 Overview	14		

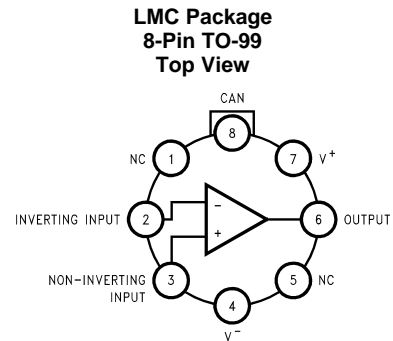
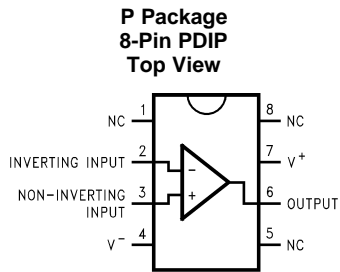
4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision H (March 2013) to Revision I	Page
<ul style="list-style-type: none"> Added <i>Pin Functions</i> table, <i>ESD Ratings</i> table, <i>Recommended Operating Conditions</i> table, <i>Thermal Information</i> table, <i>Timing Requirements</i> table, <i>Switching Characteristics</i> table, <i>Feature Description</i> section, <i>Device Functional Modes</i>, <i>Parameter Measurement Information</i> section, <i>Detailed Description</i> section, <i>Register Maps</i> section, <i>Application and Implementation</i> section, <i>Power Supply Recommendations</i> section, <i>Layout</i> section, <i>Device and Documentation Support</i> section, and <i>Mechanical, Packaging, and Orderable Information</i> section. 	1

Changes from Revision F (March 2013) to Revision H	Page
<ul style="list-style-type: none"> Changed layout of National Data Sheet to TI format 	18

5 Pin Configuration and Functions



Pin Functions

PIN			I/O	DESCRIPTION
NAME	PDIP NO.	TO-99 NO.		
CAN	—	8	—	No internal connection; connected to the external casing.
+IN	3	3	I	Noninverting Input
–IN	2	2	I	Inverting Input
NC	1, 5, 8	1, 5	—	No connection
OUTPUT	6	6	O	Output
V+	7	7	—	Positive (higher) power supply
V–	4	4	—	Negative (lower) power supply

6 Specifications

6.1 Absolute Maximum Ratings

Over operating free-air temperature range (unless otherwise noted)⁽¹⁾⁽²⁾

	MIN	MAX	Unit
Differential Input Voltage	\pm Supply Voltage		
Voltage at Input/Output Pin	$(V^+) + 0.3$	$(V^-) - 0.3$	V
Supply Voltage ($V^+ - V^-$)	-0.3	+16	V
Output Short Circuit to V^+	See ⁽³⁾⁽⁴⁾		
Output Short Circuit to V^-	See ⁽³⁾		
Lead Temperature (Soldering, 10 Sec.)	260		°C
Junction Temperature	150		°C
Current at Input Pin	± 10		mA
Current at Output Pin	± 30		mA
Current at Power Supply Pin	40		mA
Storage Temperature, T_{stg}	-65	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.
- (3) Applies to both single supply and split supply operation. Continuous short circuit operation at elevated ambient temperature can result in exceeding the maximum allowed junction temperature of 150°C. Output currents in excess of ± 30 mA over long term may adversely affect reliability.
- (4) Do not connect the output to V^+ , when V^+ is greater than 13 V or reliability will be adversely affected.

LMC6001

SNOS694I – MARCH 1995 – REVISED SEPTEMBER 2015

www.ti.com

6.2 ESD Ratings

			VALUE	UNIT
V_{ESD}	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾⁽²⁾	±2000	V

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) Human body model, 1.5 kΩ in series with 100 pF.

6.3 Recommended Operating Conditions

Over operating free-air temperature range (unless otherwise noted).

		MIN	MAX	UNIT
V_{SS}	Supply input voltage	4.5	15.5	V
T_{J}	Operating junction temperature	−40	85	°C

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾		LMC6001		UNIT
		P (PDIP)	LMC (TO-99)	
		8 PINS	8 PINS	
$R_{\theta\text{JA}}$	Junction-to-ambient thermal resistance	100	145	°C/W
$R_{\theta\text{JC(top)}}$	Junction-to-case (top) thermal resistance	—	45	°C/W

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, [SPRA953](#).

6.5 DC Electrical Characteristics for LMC6001AI

Limits are ensured for $T_{\text{J}} = 25^{\circ}\text{C}$ unless otherwise specified. Unless otherwise specified, $V^{+} = 5\text{ V}$, $V^{-} = 0\text{ V}$, $V_{\text{CM}} = 1.5\text{ V}$, and $R_{\text{L}} > 1\text{ M}\Omega$.

PARAMETER		TEST CONDITIONS		LMC6001AI			UNIT
				MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽¹⁾	
I_{B}	Input Current	Either Input, $V_{\text{CM}} = 0\text{ V}$, $V_{\text{S}} = \pm 5\text{ V}$		10	25		fA
			At the temperature extremes			2000	
I_{OS}	Input Offset Current			5			mV
		At the temperature extremes				1000	
V_{OS}	Input Offset Voltage					0.7	mV
		At the temperature extremes				1	
		$V_{\text{S}} = \pm 5\text{ V}$, $V_{\text{CM}} = 0\text{ V}$				10	
			At the temperature extremes			1.35	
TCV_{OS}	Input Offset Voltage Drift			2.5			μV/°C
R_{IN}	Input Resistance			>1			TΩ
CMRR	Common Mode	$0\text{ V} \leq V_{\text{CM}} \leq 7.5\text{ V}$		75	83		dB
	Rejection Ratio	$V^{+} = 10\text{ V}$	At the temperature extremes	72			
+PSRR	Positive Power Supply Rejection Ratio	$5\text{ V} \leq V^{+} \leq 15\text{ V}$		73	83		
			At the temperature extremes	70			
−PSRR	Negative Power Supply Rejection Ratio	$0\text{ V} \geq V^{-} \geq -10\text{ V}$		80	94		
			At the temperature extremes	77			
A_{V}	Large Signal Voltage Gain	Sourcing, $R_{\text{L}} = 2\text{ k}\Omega$ ⁽³⁾		400	1400		V/mV
				300			
		Sinking, $R_{\text{L}} = 2\text{ k}\Omega$ ⁽³⁾		180	350		
			At the temperature extremes	100			

(1) All limits are specified by testing or statistical analysis.

(2) Typical values represent the most likely parametric norm.

(3) $V^{+} = 15\text{ V}$, $V_{\text{CM}} = 7.5\text{ V}$ and R_{L} connected to 7.5 V . For Sourcing tests, $7.5\text{ V} \leq V_{\text{O}} \leq 11.5\text{ V}$. For Sinking tests, $2.5\text{ V} \leq V_{\text{O}} \leq 7.5\text{ V}$.

DC Electrical Characteristics for LMC6001AI (continued)

Limits are ensured for $T_J = 25^\circ\text{C}$ unless otherwise specified. Unless otherwise specified, $V^+ = 5\text{ V}$, $V^- = 0\text{ V}$, $V_{CM} = 1.5\text{ V}$, and $R_L > 1\text{ M}\Omega$.

PARAMETER	TEST CONDITIONS		LMC6001AI			UNIT
			MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽¹⁾	
V_{CM} Input Common-Mode Voltage	$V^+ = 5\text{ V}$ and 15 V For CMRR $\geq 60\text{ dB}$	V_{CM} Low			–0.4	V
				At the temperature extremes	–0.1	
		V_{CM} High			0	
			$V^+ - 2.3$	$V^+ - 1.9$		
V_O Output Swing	$V^+ = 15\text{ V}$, $R_L = 2\text{ k}\Omega$ to 2.5 V	V_O Low			$V^+ - 2.5$	V
				At the temperature extremes		
		V_O High			0.1	
				At the temperature extremes	0.14	
	$V^+ = 15\text{ V}$, $R_L = 2\text{ k}\Omega$ to 7.5 V	V_O Low	4.8	4.87		
				At the temperature extremes	0.17	
		V_O High	4.73			
				At the temperature extremes		
I_O Output Current	Sourcing, $V^+ = 5\text{ V}$, $V_O = 0\text{ V}$				0.26	mA
				At the temperature extremes	0.35	
	Sinking, $V^+ = 5\text{ V}$, $V_O = 5\text{ V}$		14.5	14.63		
				At the temperature extremes	14.34	
	Sourcing, $V^+ = 15\text{ V}$, $V_O = 0\text{ V}$		16	22		
				At the temperature extremes	10	
	Sinking, $V^+ = 15\text{ V}$, $V_O = 13\text{ V}^{(4)}$		16	21		
				At the temperature extremes	13	
I_S Supply Current	$V^+ = 5\text{ V}$, $V_O = 1.5\text{ V}$		28	30		μA
				At the temperature extremes	22	
	$V^+ = 15\text{ V}$, $V_O = 7.5\text{ V}$		28	34		
				At the temperature extremes	22	
I_S Supply Current	$V^+ = 5\text{ V}$, $V_O = 1.5\text{ V}$				450	μA
				At the temperature extremes	750	
	$V^+ = 15\text{ V}$, $V_O = 7.5\text{ V}$				900	
				At the temperature extremes	950	

(4) Do not connect the output to V^+ , when V^+ is greater than 13 V or reliability will be adversely affected.

LMC6001

SNOS694I –MARCH 1995–REVISED SEPTEMBER 2015

www.ti.com
6.6 DC Electrical Characteristics for LMC6001BI

 Limits are ensured for $T_J = 25^\circ\text{C}$ unless otherwise specified. Unless otherwise specified, $V^+ = 5\text{ V}$, $V^- = 0\text{ V}$, $V_{CM} = 1.5\text{ V}$, and $R_L > 1\text{ M}\Omega$.

PARAMETER		TEST CONDITIONS		LMC6001BI			UNIT
				MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽¹⁾	
I_B	Input Current	Either Input, $V_{CM} = 0\text{ V}$, $V_S = \pm 5\text{ V}$				100	fA
			At the temperature extremes			4000	
I_{OS}	Input Offset Current	At the temperature extremes				2000	
V_{OS}	Input Offset Voltage					1.35	mV
		At the temperature extremes				1.7	
		$V_S = \pm 5\text{ V}$, $V_{CM} = 0\text{ V}$				10	
			At the temperature extremes			2	
TCV_{OS}	Input Offset Voltage Drift						$\mu\text{V}/^\circ\text{C}$
R_{IN}	Input Resistance						T Ω
CMRR	Common Mode	$0\text{ V} \leq V_{CM} \leq 7.5\text{ V}$		72			dB
	Rejection Ratio	$V^+ = 10\text{ V}$	At the temperature extremes	68			
+PSRR	Positive Power Supply Rejection Ratio	$5\text{ V} \leq V^+ \leq 15\text{ V}$		66	83		
			At the temperature extremes	63			
-PSRR	Negative Power Supply Rejection Ratio	$0\text{ V} \geq V^- \geq -10\text{ V}$		74	94		
			At the temperature extremes	71			
A_V	Large Signal Voltage Gain	Sourcing, $R_L = 2\text{ k}\Omega$ ⁽³⁾		300	1400		V/mV
				200			
		Sinking, $R_L = 2\text{ k}\Omega$ ⁽³⁾		90	350		
				60			
V_{CM}	Input Common-Mode Voltage	$V^+ = 5\text{ V}$ and 15 V For CMRR $\geq 60\text{ dB}$	V_{CM} Low			-0.4 -0.1	V
			At the temperature extremes			0	
			V_{CM} High	$V^+ - 2.3$	$V^+ - 1.9$		
			At the temperature extremes	$V^+ - 2.5$			
V_O	Output Swing	$V^+ = 15\text{ V}$, $R_L = 2\text{ k}\Omega$ to 2.5 V	V_O Low			0.1 0.2	V
			At the temperature extremes			0.24	
			V_O High	4.75	4.87		
			At the temperature extremes	4.67			
		$V^+ = 15\text{ V}$, $R_L = 2\text{ k}\Omega$ to 7.5 V	V_O Low			0.26 0.44	
			At the temperature extremes			0.56	
			V_O High	14.37	14.63		
			At the temperature extremes	14.25			

(1) All limits are specified by testing or statistical analysis.

(2) Typical values represent the most likely parametric norm.

 (3) $V^+ = 15\text{ V}$, $V_{CM} = 7.5\text{ V}$ and R_L connected to 7.5 V . For Sourcing tests, $7.5\text{ V} \leq V_O \leq 11.5\text{ V}$. For Sinking tests, $2.5\text{ V} \leq V_O \leq 7.5\text{ V}$.

DC Electrical Characteristics for LMC6001BI (continued)

Limits are ensured for $T_J = 25^\circ\text{C}$ unless otherwise specified. Unless otherwise specified, $V^+ = 5\text{ V}$, $V^- = 0\text{ V}$, $V_{CM} = 1.5\text{ V}$, and $R_L > 1\text{ M}\Omega$.

PARAMETER	TEST CONDITIONS		LMC6001BI			UNIT
			MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽¹⁾	
I_O Output Current	Sourcing, $V^+ = 5\text{ V}$, $V_O = 0\text{ V}$		13	22		mA
		At the temperature extremes	8			
	Sinking, $V^+ = 5\text{ V}$, $V_O = 5\text{ V}$		13	21		
		At the temperature extremes	10			
	Sourcing, $V^+ = 15\text{ V}$, $V_O = 0\text{ V}$		23	30		
		At the temperature extremes	18			
I_S Supply Current	$V^+ = 5\text{ V}$, $V_O = 1.5\text{ V}$			450	750	μA
		At the temperature extremes			900	
	$V^+ = 15\text{ V}$, $V_O = 7.5\text{ V}$			550	850	
		At the temperature extremes			950	

(4) Do not connect the output to V^+ , when V^+ is greater than 13 V or reliability will be adversely affected.

6.7 DC Electrical Characteristics for LMC6001CI

Limits are ensured for $T_J = 25^\circ\text{C}$ unless otherwise specified. Unless otherwise specified, $V^+ = 5\text{ V}$, $V^- = 0\text{ V}$, $V_{CM} = 1.5\text{ V}$, and $R_L > 1\text{ M}\Omega$.

PARAMETER	TEST CONDITIONS		LMC6001CI			UNIT
			MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽¹⁾	
I_B Input Current	Either Input, $V_{CM} = 0\text{ V}$, $V_S = \pm 5\text{ V}$				1000	fA
		At the temperature extremes			4000	
I_{OS} Input Offset Current	At the temperature extremes				2000	
V_{OS} Input Offset Voltage	$V_S = \pm 5\text{ V}$, $V_{CM} = 0\text{ V}$				1	mV
					1.35	
TCV_{OS} Input Offset Voltage Drift						$\mu\text{V}/^\circ\text{C}$
R_{IN} Input Resistance						$\text{T}\Omega$
CMRR	Common Mode	$0\text{ V} \leq V_{CM} \leq 7.5\text{ V}$		66		dB
	Rejection Ratio	$V^+ = 10\text{ V}$		63		
+PSRR	Positive Power Supply Rejection Ratio	$5\text{ V} \leq V^+ \leq 15\text{ V}$		66	83	
				63		
-PSRR	Negative Power Supply Rejection Ratio	$0\text{ V} \geq V^- \geq -10\text{ V}$		74	94	
				71		

(1) All limits are specified by testing or statistical analysis.

(2) Typical values represent the most likely parametric norm.

LMC6001

SNOS694I –MARCH 1995–REVISED SEPTEMBER 2015

www.ti.com
DC Electrical Characteristics for LMC6001CI (continued)

 Limits are ensured for $T_J = 25^\circ\text{C}$ unless otherwise specified. Unless otherwise specified, $V^+ = 5\text{ V}$, $V^- = 0\text{ V}$, $V_{CM} = 1.5\text{ V}$, and $R_L > 1\text{ M}\Omega$.

PARAMETER	TEST CONDITIONS		LMC6001CI			UNIT
			MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽¹⁾	
A_V Large Signal Voltage Gain	Sourcing, $R_L = 2\text{ k}\Omega$ ⁽³⁾		300	1400		V/mV
			200			
	Sinking, $R_L = 2\text{ k}\Omega$ ⁽³⁾	At the temperature extremes	90	350		
			60			
V_{CM} Input Common-Mode Voltage	$V^+ = 5\text{ V}$ and 15 V For $CMRR \geq 60\text{ dB}$	V_{CM} Low			–0.4 –0.1	V
					0	
		V_{CM} High		$V^+ - 2.3$ $V^+ - 1.9$		
				$V^+ - 2.5$		
V_O Output Swing	$V^+ = 15\text{ V}$, $R_L = 2\text{ k}\Omega$ to 2.5 V	V_O Low			0.1 0.2	V
					0.24	
		V_O High		4.75 4.87		
				4.67		
	$V^+ = 15\text{ V}$, $R_L = 2\text{ k}\Omega$ to 7.5 V	V_O Low			0.26 0.44	
					0.56	
		V_O High		14.37 14.63		
				14.25		
I_O Output Current	Sourcing, $V^+ = 5\text{ V}$, $V_O = 0\text{ V}$		13	22		mA
		At the temperature extremes	8			
	Sinking, $V^+ = 5\text{ V}$, $V_O = 5\text{ V}$		13	21		
		At the temperature extremes	10			
	Sourcing, $V^+ = 15\text{ V}$, $V_O = 0\text{ V}$		23	30		
		At the temperature extremes	18			
	Sinking, $V^+ = 15\text{ V}$, $V_O = 13\text{ V}$ ⁽⁴⁾		23	34		
		At the temperature extremes	18			
I_S Supply Current	$V^+ = 5\text{ V}$, $V_O = 1.5\text{ V}$			450	750	μA
		At the temperature extremes			900	
	$V^+ = 15\text{ V}$, $V_O = 7.5\text{ V}$			550	850	
		At the temperature extremes			950	

 (3) $V^+ = 15\text{ V}$, $V_{CM} = 7.5\text{ V}$ and R_L connected to 7.5 V . For Sourcing tests, $7.5\text{ V} \leq V_O \leq 11.5\text{ V}$. For Sinking tests, $2.5\text{ V} \leq V_O \leq 7.5\text{ V}$.

 (4) Do not connect the output to V^+ , when V^+ is greater than 13 V or reliability will be adversely affected.

6.8 AC Electrical Characteristics for LMC6001AIC

Limits in standard typeface ensured for $T_J = 25^\circ\text{C}$ unless otherwise specified. Unless otherwise specified, $V^+ = 5\text{ V}$, $V^- = 0\text{ V}$, $V_{CM} = 1.5\text{ V}$ and $R_L > 1\text{ M}\Omega$.

PARAMETER		TEST CONDITIONS		LMC6001AIC			UNIT
				MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽¹⁾	
SR	Slew Rate	See ⁽³⁾		0.8	1.5		V/ μs
			At the temperature extremes	0.6			
GBW	Gain-Bandwidth Product				1.3		MHz
ϕ_{f_m}	Phase Margin				50		Deg
G_M	Gain Margin				17		dB
e_n	Input-Referred Voltage Noise	$F = 1\text{ kHz}$			22		nV/ $\sqrt{\text{Hz}}$
i_n	Input-Referred Current Noise	$F = 1\text{ kHz}$			0.13		fA/ $\sqrt{\text{Hz}}$
THD	Total Harmonic Distortion	$F = 10\text{ kHz}$, $A_V = -10$, $R_L = 100\text{ k}\Omega$, $V_O = 8\text{ V}_{PP}$			0.01%		

(1) All limits are specified by testing or statistical analysis.

(2) Typical values represent the most likely parametric norm.

(3) $V^+ = 15\text{ V}$. Connected as Voltage Follower with 10-V step input. Limit specified is the lower of the positive and negative slew rates.

6.9 AC Electrical Characteristics for LM6001BI

Limits in standard typeface ensured for $T_J = 25^\circ\text{C}$ unless otherwise specified. Unless otherwise specified, $V^+ = 5\text{ V}$, $V^- = 0\text{ V}$, $V_{CM} = 1.5\text{ V}$ and $R_L > 1\text{ M}\Omega$.

PARAMETER		TEST CONDITIONS		LM6001BI			UNIT
				MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽¹⁾	
SR	Slew Rate	See ⁽³⁾		0.8	1.5		V/ μs
			At the temperature extremes	0.6			
GBW	Gain-Bandwidth Product				1.3		MHz
ϕ_{f_m}	Phase Margin				50		Deg
G_M	Gain Margin				17		dB
e_n	Input-Referred Voltage Noise	$F = 1\text{ kHz}$			22		nV/ $\sqrt{\text{Hz}}$
i_n	Input-Referred Current Noise	$F = 1\text{ kHz}$			0.13		fA/ $\sqrt{\text{Hz}}$
THD	Total Harmonic Distortion	$F = 10\text{ kHz}$, $A_V = -10$, $R_L = 100\text{ k}\Omega$, $V_O = 8\text{ V}_{PP}$			0.01%		

(1) All limits are specified by testing or statistical analysis.

(2) Typical values represent the most likely parametric norm.

(3) $V^+ = 15\text{ V}$. Connected as Voltage Follower with 10-V step input. Limit specified is the lower of the positive and negative slew rates.

LMC6001

SNOS694I – MARCH 1995 – REVISED SEPTEMBER 2015

www.ti.com
6.10 AC Electrical Characteristics for LMC6001CI

Limits in standard typeface ensured for $T_J = 25^\circ\text{C}$ unless otherwise specified. Unless otherwise specified, $V^+ = 5\text{ V}$, $V^- = 0\text{ V}$, $V_{CM} = 1.5\text{ V}$ and $R_L > 1\text{ M}\Omega$.

PARAMETER		TEST CONDITIONS	LMC6001CI			UNIT
			MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽³⁾	
SR	Slew Rate	See ⁽⁴⁾	0.8	1.5		V/ μs
		At the temperature extremes	0.6			
GBW	Gain-Bandwidth Product			1.3		MHz
ϕ_{f_m}	Phase Margin			50		Deg
G_M	Gain Margin			17		dB
e_n	Input-Referred Voltage Noise	$F = 1\text{ kHz}$		22		nV/ $\sqrt{\text{Hz}}$
i_n	Input-Referred Current Noise	$F = 1\text{ kHz}$		0.13		fA/ $\sqrt{\text{Hz}}$
THD	Total Harmonic Distortion	$F = 10\text{ kHz}$, $A_V = -10$, $R_L = 100\text{ k}\Omega$, $V_O = 8\text{ V}_{PP}$		0.01%		

(1) All limits are specified by testing or statistical analysis.

(2) Typical values represent the most likely parametric norm.

(3) All limits are specified by testing or statistical analysis.

(4) $V^+ = 15\text{ V}$. Connected as Voltage Follower with 10-V step input. Limit specified is the lower of the positive and negative slew rates.

6.11 Dissipation Ratings

	MIN	MAX	UNIT
Power Dissipation	See ⁽¹⁾		

(1) For operating at elevated temperatures the device must be derated based on the thermal resistance θ_{JA} with $P_D = (T_J - T_A)/\theta_{JA}$.

6.12 Typical Characteristics

$V_S = \pm 7.5\text{ V}$, $T_A = 25^\circ\text{C}$, unless otherwise specified

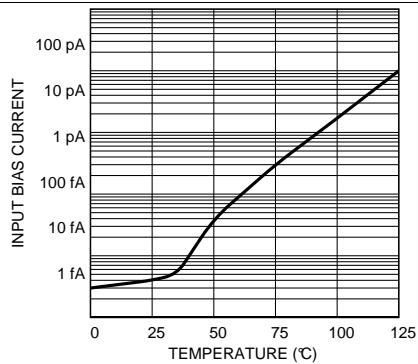
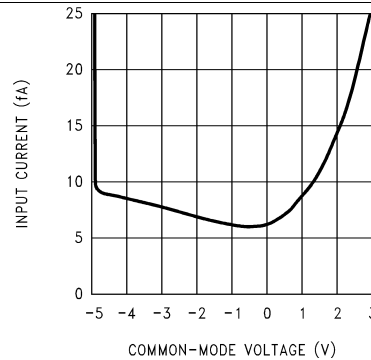


Figure 1. Input Current vs. Temperature



$V_S = \pm 5\text{ V}$

Figure 2. Input Current vs. V_{CM}

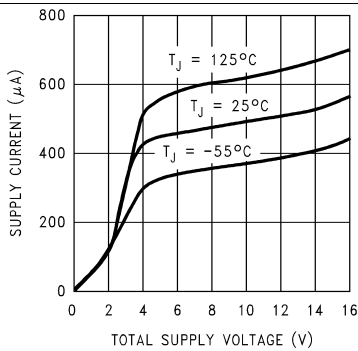


Figure 3. Supply Current vs. Supply Voltage

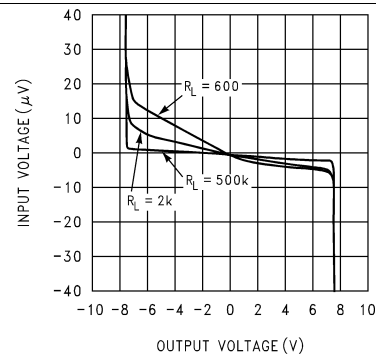


Figure 4. Input Voltage vs. Output Voltage

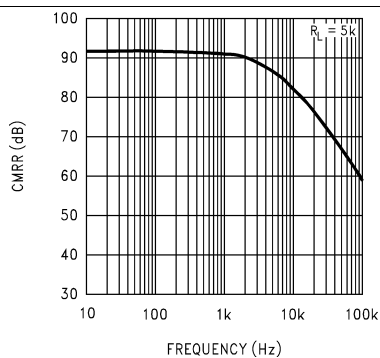


Figure 5. Common-Mode Rejection Ratio vs. Frequency

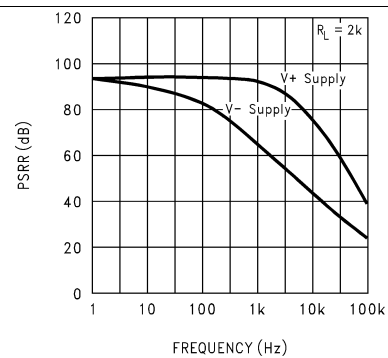


Figure 6. Power Supply Rejection Ratio vs. Frequency

Typical Characteristics (continued)

$V_S = \pm 7.5\text{ V}$, $T_A = 25^\circ\text{C}$, unless otherwise specified

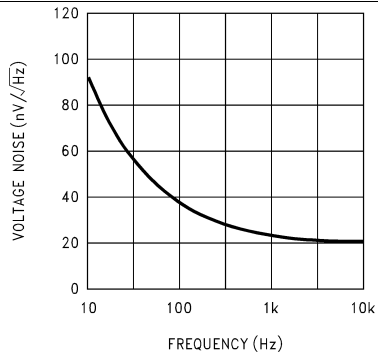


Figure 7. Input Voltage Noise vs. Frequency

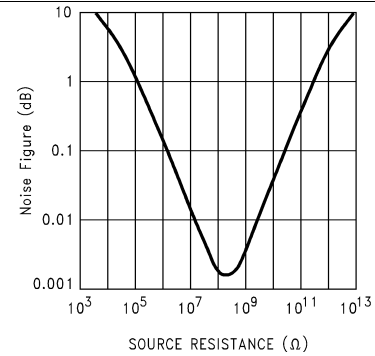


Figure 8. Noise Figure vs. Source Resistance

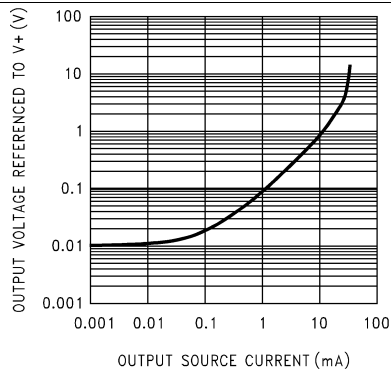


Figure 9. Output Characteristics Sourcing Current

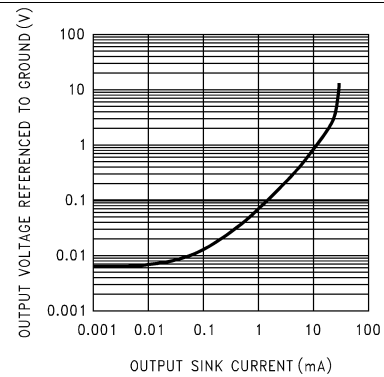


Figure 10. Output Characteristics Sinking Current

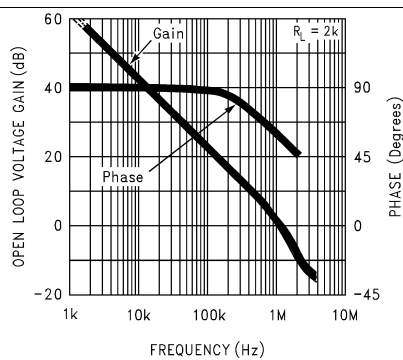
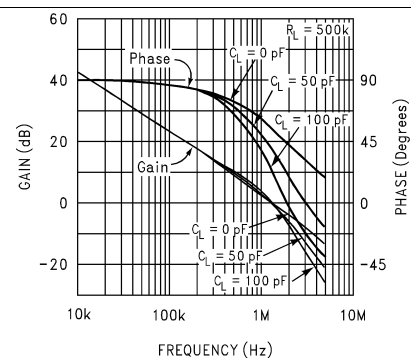


Figure 11. Gain and Phase Response vs. Temperature
(-55°C to $+125^\circ\text{C}$)



$R_L = 500\text{ k}\Omega$

Figure 12. Gain and Phase Response vs. Capacitive Load

Typical Characteristics (continued)

$V_S = \pm 7.5\text{ V}$, $T_A = 25^\circ\text{C}$, unless otherwise specified

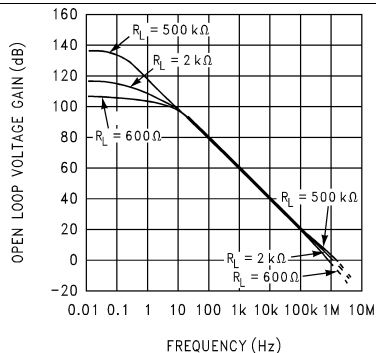


Figure 13. Open-Loop Frequency Response

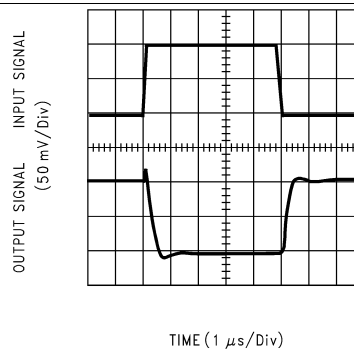


Figure 14. Inverting Small Signal Pulse Response

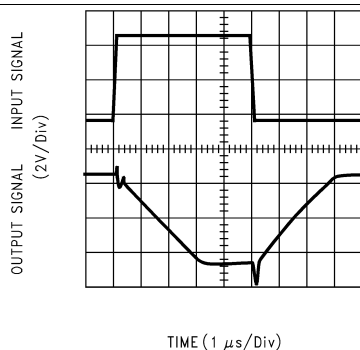


Figure 15. Inverting Large Signal Pulse Response

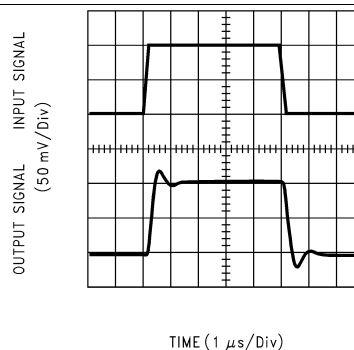


Figure 16. Noninverting Small Signal Pulse Response

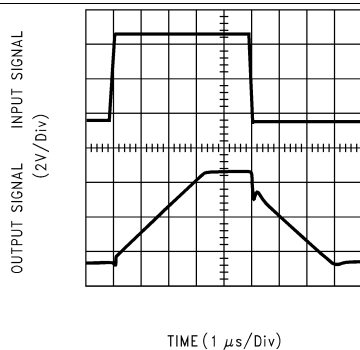


Figure 17. Noninverting Large Signal Pulse Response

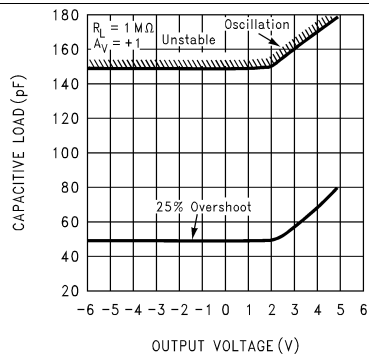


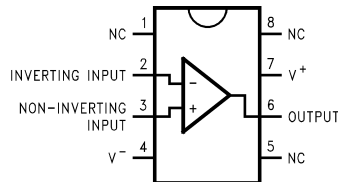
Figure 18. Stability vs. Capacitive Load

7 Detailed Description

7.1 Overview

LMC6001 has an extremely low input current of 25 fA. In addition, its ultra-low input current noise of $0.13 \text{ fA}/\sqrt{\text{Hz}}$ allows almost noiseless amplification of high-resistance signal sources. LMC6001 is ideally suited for electrometer applications requiring ultra-low input leakage current such as sensitive photodetection transimpedance amplifiers and sensor amplifiers.

7.2 Functional Block Diagram



7.3 Feature Description

7.3.1 Amplifier Topology

The LMC6001 incorporates a novel op amp design topology that enables it to maintain rail-to-rail output swing even when driving a large load. Instead of relying on a push-pull unity gain output buffer stage, the output stage is taken directly from the internal integrator, which provides both low output impedance and large gain. Special feed-forward compensation design techniques are incorporated to maintain stability over a wider range of operating conditions than traditional op amps. These features make the LMC6001 both easier to design with, and provide higher speed than products typically found in this low-power class.

7.3.2 Latch-Up Prevention

CMOS devices tend to be susceptible to latch-up due to their internal parasitic SCR effects. The (I/O) input and output pins look similar to the gate of the SCR. There is a minimum current required to trigger the SCR gate lead. The LMC6001 is designed to withstand 100-mA surge current on the I/O pins. Some resistive method should be used to isolate any capacitance from supplying excess current to the I/O pins. In addition, like an SCR, there is a minimum holding current for any latch-up mode. Limiting current to the supply pins will also inhibit latch-up susceptibility.

7.4 Device Functional Modes

The LMC6001 has a single functional mode and operates according to the conditions listed in [Recommended Operating Conditions](#).

8 Applications and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

8.1.1 Compensating For Input Capacitance

It is quite common to use large values of feedback resistance for amplifiers with ultra-low input current, like the LMC6001.

Although the LMC6001 is highly stable over a wide range of operating conditions, certain precautions must be met to achieve the desired pulse response when a large feedback resistor is used. Large feedback resistors with even small values of input capacitance, due to transducers, photodiodes, and printed-circuit-board parasitics, reduce phase margins.

When high input impedances are demanded, TI suggests guarding the LMC6001. Guarding input lines will not only reduce leakage, but lowers stray input capacitance as well. See [Printed-Circuit-Board Layout For High-Impedance Work](#).

The effect of input capacitance can be compensated for by adding a capacitor, C_f , around the feedback resistors (as in [Figure 19](#)) such that:

$$\frac{1}{2\pi R_1 C_{IN}} \geq \frac{1}{2\pi R_2 C_f} \quad (1)$$

or

$$R_1 C_{IN} \leq R_2 C_f \quad (2)$$

Because it is often difficult to know the exact value of C_{IN} , C_f can be experimentally adjusted so that the desired pulse response is achieved. Refer to the LMC660 ([SNOSBZ3](#)) and LMC662 ([SNOSC51](#)) for a more detailed discussion on compensating for input capacitance.

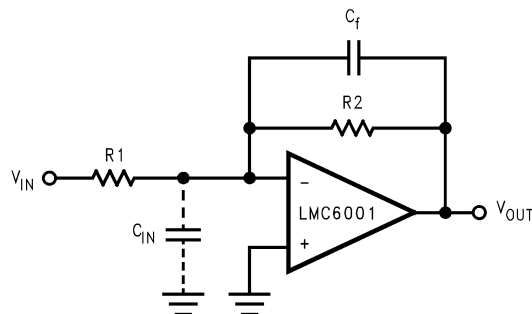


Figure 19. Cancelling the Effect of Input Capacitance

8.1.2 Capacitive Load Tolerance

All rail-to-rail output swing operational amplifiers have voltage gain in the output stage. A compensation capacitor is normally included in this integrator stage. The frequency location of the dominant pole is affected by the resistive load on the amplifier. Capacitive load driving capability can be optimized by using an appropriate resistive load in parallel with the capacitive load. See [Typical Characteristics](#).

Direct capacitive loading will reduce the phase margin of many op amps. A pole in the feedback loop is created by the combination of the output impedance of the op amp and the capacitive load. This pole induces phase lag at the unity-gain crossover frequency of the amplifier resulting in either an oscillatory or underdamped pulse response. With a few external components, op amps can easily indirectly drive capacitive loads, as shown in [Figure 20](#).

Application Information (continued)

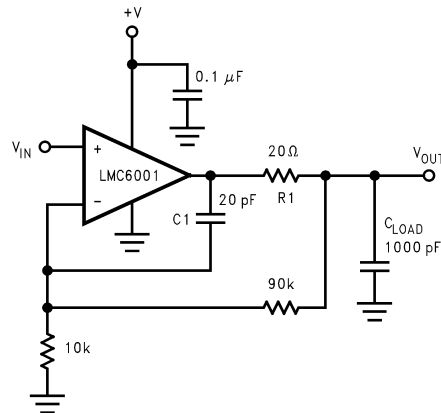


Figure 20. LMC6001 Noninverting Gain of 10 Amplifier, Compensated to Handle Capacitive Loads

In the circuit of [Figure 20](#), R1 and C1 serve to counteract the loss of phase margin by feeding the high frequency component of the output signal back to the inverting input of the amplifier, thereby preserving phase margin in the overall feedback loop.

Capacitive load driving capability is enhanced by using a pullup resistor to V^+ ([Figure 21](#)). Typically a pullup resistor conducting 500 μ A or more will significantly improve capacitive load responses. The value of the pullup resistor must be determined based on the current sinking capability of the amplifier with respect to the desired output swing. Open-loop gain of the amplifier can also be affected by the pullup resistor. See [DC Electrical Characteristics for LMC6001AI](#).

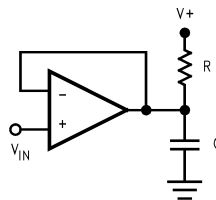


Figure 21. Compensating for Large Capacitive Loads With a Pullup Resistor

8.2 Typical Application

The extremely high input resistance, and low power consumption, of the LMC6001 make it ideal for applications that require battery-powered instrumentation amplifiers. Examples of these types of applications are hand-held pH probes, analytic medical instruments, electrostatic field detectors and gas chromatographs.

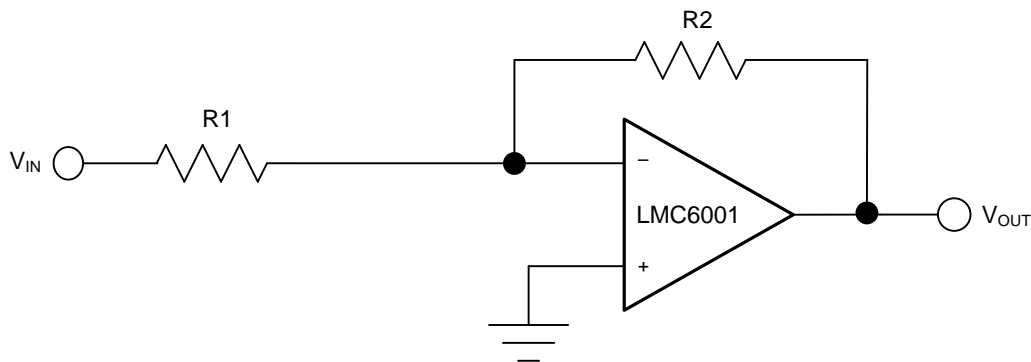


Figure 22. Typical Application Schematic, LMC6001

Typical Application (continued)

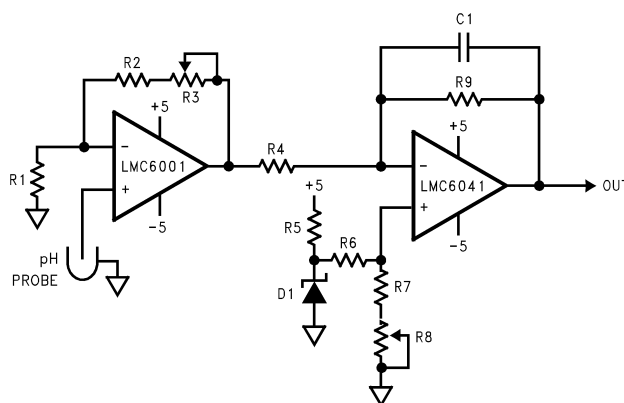
8.2.1 Two Op Amp, Temperature Compensated Ph Probe Amplifier

The signal from a pH probe has a typical resistance between 10 M Ω and 1000 M Ω . Because of this high value, it is very important that the amplifier input currents be as small as possible. The LMC6001 with less than 25-fA input current is an ideal choice for this application.

The LMC6001 amplifies the probe output providing a scaled voltage of ± 100 mV/pH from a pH of 7. The second op amp, a micropower LMC6041 provides phase inversion and offset so that the output is directly proportional to pH, over the full range of the probe. The pH reading can now be directly displayed on a low-cost, low-power digital panel meter. Total current consumption will be about 1 mA for the whole system.

The micropower dual-operational amplifier, LMC6042, would optimize power consumption but not offer these advantages:

1. The LMC6001A ensures a 25-fA limit on input current at 25°C.
2. The input ESD protection diodes in the LMC6042 are only rated at 500 V while the LMC6001 has much more robust protection that is rated at 2000 V.



(1)

R1 100 k + 3500 ppm/°C

R2 68.1 k

R3, 8 5 k

R4, 9 100 k

R5 36.5 k

R6 619 k

R7 97.6 k

D1 LM4040D1Z-2.5

C1 2.2 μ F

(2) $\mu\Omega$ style 137 or similar

Figure 23. Ph Probe Amplifier

8.2.1.1 Design Requirements

The theoretical output of the standard Ag/AgCl pH probe is 59.16 mV/pH at 25°C with 0 V out at a pH of 7.00. This output is proportional to absolute temperature. To compensate for this, a temperature-compensating resistor, R1, is placed in the feedback loop. This cancels the temperature dependence of the probe. This resistor must be mounted where it will be at the same temperature as the liquid being measured.

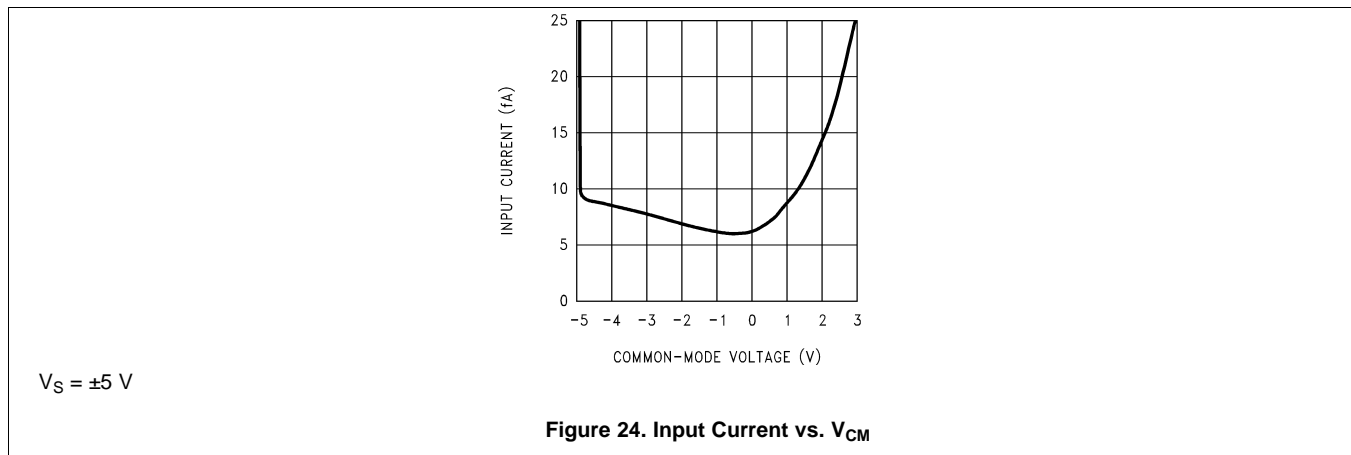
8.2.1.2 Detailed Design Procedure

The set-up and calibration is simple with no interactions to cause problems.

Typical Application (continued)

1. Disconnect the pH probe and with R3 set to about mid-range and the noninverting input of the LMC6001 grounded, adjust R8 until the output is 700 mV.
2. Apply -414.1 mV to the noninverting input of the LMC6001. Adjust R3 for an output of 1400 mV. This completes the calibration. As real pH probes may not perform exactly to theory, minor gain and offset adjustments should be made by trimming while measuring a precision buffer solution.

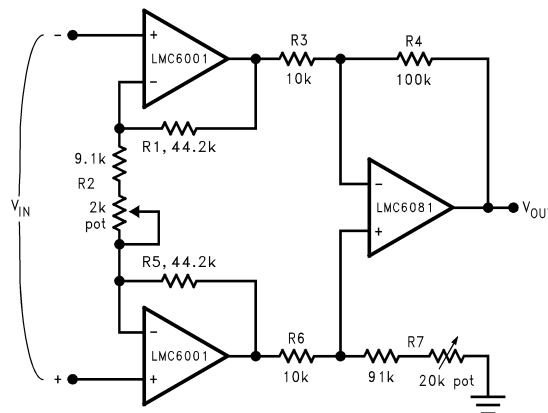
8.2.1.3 Application Curve



8.3 System Example

8.3.1 Ultra-Low Input Current Instrumentation Amplifier

Figure 25 shows an instrumentation amplifier that features high-differential and common-mode input resistance ($>10^{14}\Omega$), 0.01% gain accuracy at $A_V = 1000$, excellent CMRR with 1-M Ω imbalance in source resistance. Input current is less than 20 fA and offset drift is less than 2.5 $\mu\text{V}/^\circ\text{C}$. R_2 provides a simple means of adjusting gain over a wide range without degrading CMRR. R_7 is an initial trim used to maximize CMRR without using super precision matched resistors. For good CMRR over temperature, low-drift resistors should be used.



If $R_1 = R_5$, $R_3 = R_6$, and $R_4 = R_7$; then

$$\frac{V_{OUT}}{V_{IN}} = \frac{R_2 + 2R_1}{R_2} \times \frac{R_4}{R_3}$$

$\therefore A_V \approx 100$ for circuit shown ($R_2 = 9.85\text{k}$).

Figure 25. Instrumentation Amplifier

9 Power Supply Recommendations

See the [Recommended Operating Conditions](#) for the minimum and maximum values for the supply input voltage and operating junction temperature.

10 Layout

10.1 Layout Guidelines

10.1.1 Printed-Circuit-Board Layout For High-Impedance Work

It is generally recognized that any circuit which must operate with less than 1000 pA of leakage current requires special layout of the PCB. When one wishes to take advantage of the ultra-low bias current of the LMC6001, typically less than 10 fA, it is essential to have an excellent layout. Fortunately, the techniques of obtaining low leakages are quite simple. First, the user must not ignore the surface leakage of the PCB, even though it may sometimes appear acceptably low, because under conditions of high humidity or dust or contamination, the surface leakage will be appreciable.

To minimize the effect of any surface leakage, lay out a ring of foil completely surrounding the inputs of the LMC6001 and the terminals of capacitors, diodes, conductors, resistors, relay terminals, and so forth, connected to the inputs of the op amp, as in [Figure 30](#). To have a significant effect, guard rings must be placed on both the top and bottom of the PCB. This PC foil must then be connected to a voltage which is at the same voltage as the amplifier inputs, because no leakage current can flow between two points at the same potential. For example, a PCB trace-to-pad resistance of 10 TΩ, which is normally considered a very large resistance, could leak 5 pA if the trace were a 5-V bus adjacent to the pad of the input.

This would cause a 500 times degradation from the LMC6001's actual performance. If a guard ring is used and held within 1 mV of the inputs, then the same resistance of 10 TΩ will only cause 10 fA of leakage current. Even this small amount of leakage will degrade the extremely low input current performance of the LMC6001. See [Figure 28](#) for typical connections of guard rings for standard op amp configurations.

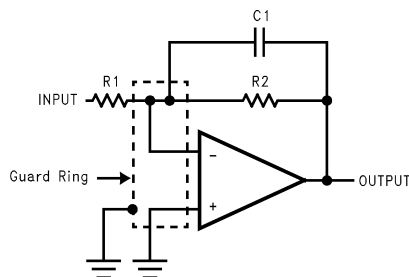


Figure 26. Inverting Amplifier

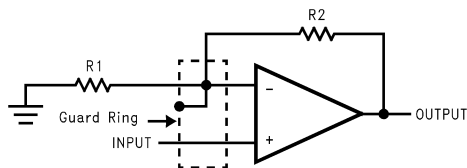


Figure 27. Noninverting Amplifier

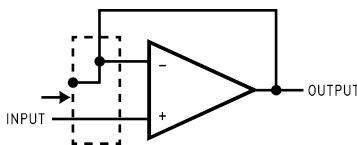
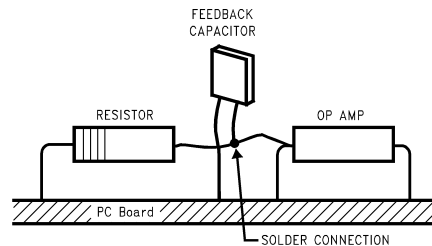


Figure 28. Typical Connections Of Guard Rings

Layout Guidelines (continued)

The designer should be aware that when it is inappropriate to lay out a PCB for the sake of just a few circuits, there is another technique which is even better than a guard ring on a PCB: Do not insert the input pin of the amplifier into the board at all, but bend it up in the air and use only air as an insulator. Air is an excellent insulator. In this case you may have to forego some of the advantages of PCB construction, but the advantages are sometimes well worth the effort of using point-to-point up-in-the-air wiring. See [Figure 29](#).



(Input pins are lifted out of PCB and soldered directly to components. All other pins connected to PCB).

Figure 29. Air Wiring

Another potential source of leakage that might be overlooked is the device package. When the LMC6001 is manufactured, the device is always handled with conductive finger cots. This is to assure that salts and skin oils do not cause leakage paths on the surface of the package. We recommend that these same precautions be adhered to, during all phases of inspection, test and assembly.

10.2 Layout Example

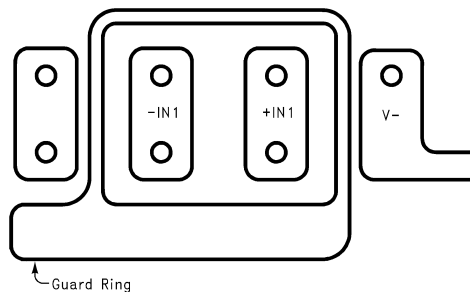


Figure 30. Examples Of Guard Ring In PCB Layout

11 Device and Documentation Support

11.1 Documentation Support

11.1.1 Related Documentation

For related documentation, see the following:

- *LMC660 CMOS Quad Operational Amplifier*, [SNOSBZ3](#)
- *LMC662 CMOS Dual Operational Amplifier*, [SNOSC51](#)

11.2 Related Links

[Table 1](#) lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.

Table 1. Related Links

PARTS	PRODUCT FOLDER	SAMPLE & BUY	TECHNICAL DOCUMENTS	TOOLS & SOFTWARE	SUPPORT & COMMUNITY
LMC6001	Click here	Click here	Click here	Click here	Click here

11.3 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

TI E2E™ Online Community *TI's Engineer-to-Engineer (E2E) Community*. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

11.4 Trademarks

E2E is a trademark of Texas Instruments.

All other trademarks are the property of their respective owners.

11.5 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

11.6 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical packaging and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
LMC6001AIN/NOPB	Active	Production	PDIP (P) 8	40 TUBE	Yes	NIPDAU	Level-1-NA-UNLIM	-40 to 85	LMC6001 AIN
LMC6001AIN/NOPB.A	Active	Production	PDIP (P) 8	40 TUBE	Yes	NIPDAU	Level-1-NA-UNLIM	-40 to 85	LMC6001 AIN
LMC6001AIN/NOPB.B	Active	Production	PDIP (P) 8	40 TUBE	Yes	NIPDAU	Level-1-NA-UNLIM	-40 to 85	LMC6001 AIN
LMC6001BIN/NOPB	Active	Production	PDIP (P) 8	40 TUBE	Yes	NIPDAU	Level-1-NA-UNLIM	-40 to 85	LMC6001 BIN
LMC6001BIN/NOPB.A	Active	Production	PDIP (P) 8	40 TUBE	Yes	NIPDAU	Level-1-NA-UNLIM	-40 to 85	LMC6001 BIN
LMC6001BIN/NOPB.B	Active	Production	PDIP (P) 8	40 TUBE	Yes	NIPDAU	Level-1-NA-UNLIM	-40 to 85	LMC6001 BIN

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

TUBE



*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (μm)	B (mm)
LMC6001AIN/NOPB	P	PDIP	8	40	502	14	11938	4.32
LMC6001AIN/NOPB.A	P	PDIP	8	40	502	14	11938	4.32
LMC6001AIN/NOPB.B	P	PDIP	8	40	502	14	11938	4.32
LMC6001BIN/NOPB	P	PDIP	8	40	502	14	11938	4.32
LMC6001BIN/NOPB.A	P	PDIP	8	40	502	14	11938	4.32
LMC6001BIN/NOPB.B	P	PDIP	8	40	502	14	11938	4.32

P (R-PDIP-T8)

PLASTIC DUAL-IN-LINE PACKAGE



- NOTES:
- A. All linear dimensions are in inches (millimeters).
 - B. This drawing is subject to change without notice.
 - C. Falls within JEDEC MS-001 variation BA.

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to [TI's Terms of Sale](#) or other applicable terms available either on [ti.com](https://www.ti.com) or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2025, Texas Instruments Incorporated