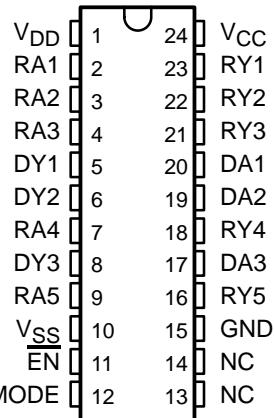


SN75LPE185
LOW-POWER MULTIPLE RS-232 DRIVERS/RECEIVERS
WITH ENABLE

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- Single-Chip RS-232 Interface for IBM™ PC-Compatible Serial Port
- Designed to Transmit and Receive 4- μ s Pulses (Equivalent to 256 kbit/s)
- Standby Power Is Less Than 750 μ W Maximum
- Wide Supply-Voltage Range . . . 4.75 V to 15 V
- Driver Output Slew Rates Are Internally Controlled to 30 V/ μ s Maximum
- RS-232 Bus-Pin ESD Protection Exceeds:
 - 15 kV, Human-Body Model
- Receiver Input Hysteresis . . . 1000 mV Typical
- Three Drivers and Five Receivers Meet or Exceed the Requirements of TIA/EIA-232-F and ITU v.28 Standards
- Complements the SN75LP196
- One Receiver Remains Active During WAKE-UP Mode (100 μ A Maximum)
- Matches Flow-Through Pinout of Industry-Standard SN75185, SN75C185, and SN75LP185, With Additional Control Pins
- Package Options Include Plastic Shrink Small-Outline (DB), Small-Outline (DW), and Thin Shrink Small-Outline (PW) Packages, and Standard Plastic (NT) DIPs

DB, DW, NT, OR PW PACKAGE
(TOP VIEW)



NC – No internal connection

description

The SN75LPE185 is a low-power bipolar device containing three drivers and five receivers, with 15-kV ESD protection on the bus pins, with respect to each other. Bus pins are defined as those pins that tie directly to the serial-port connector, including GND. The pinout matches the flow-through design of the industry-standard SN75185, SN75C185, and SN75LP185, with the addition of four pins for control signals. The flow-through pinout of the device allows easy interconnection of the universal asynchronous receiver/transmitter (UART) and serial-port connector of the IBM™ PC compatibles. The SN75LPE185 provides a rugged, low-cost solution for this function, with the combination of bipolar processing and 15-kV ESD protection.

The SN75LPE185 has an internal slew-rate control to provide a maximum rate of change in the output signal of 30 V/ μ s. The driver output swing is clamped at \pm 6 V to enable the higher data rates associated with this device and to reduce EMI emissions. Although the driver outputs are clamped, the outputs can handle voltages up to \pm 15 V without damage.



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**TEXAS
INSTRUMENTS**

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description (continued)

The device has flexible control options for power management when the serial port is inactive. A common disable for all of the drivers and receivers is provided with the active-low enable (EN) input. The mode-control (MODE) input selects between the STANDBY and WAKE-UP modes. With a low-level input on MODE and a high-level input on \bar{EN} , one receiver remains active, while the remaining drivers and receivers are disabled to implement the WAKE-UP mode. With a high-level input on both MODE and \bar{EN} , all drivers and receivers are disabled to implement the STANDBY mode. The outputs of the drivers are in the high-impedance state when the device is powered off. To ensure the outputs of the receivers are in a known output level (as listed in the *Application Information* section of this data sheet) when the device is powered off, in STANDBY mode, or in WAKE-UP mode, external pullup/pulldown circuitry must be provided. All the logic inputs accept 3.3-V or 5-V input signals.

The SN75LPE185 complies with the requirements of TIA/EIA-232-F and ITU v.28 standards. These standards are for data interchange between a host computer and peripheral at signaling rates up to 20 kbit/s. The switching speeds of the SN75LPE185 support rates up to 256 kbit/s.

The SN75LPE185 is characterized for operation from 0°C to 70°C.

AVAILABLE OPTIONS

TA	PACKAGED DEVICES			
	PLASTIC SHRINK SMALL OUTLINE (DB)	PLASTIC SMALL OUTLINE (DW)	PLASTIC THIN SHRINK SMALL OUTLINE (PW)	PLASTIC DIP (NT)
0°C to 70°C	SN75LPE185DBR	SN75LPE185DW	SN75LPE185PWR	SN75LPE185NT

The DB and PW packages are only available taped and reeled. The DW package is also available taped and reeled. Add the suffix R to device type (e.g., SN75LPE185DWR).

Function Tables

DRIVERS

INPUT DA	ENABLE EN	OUTPUT DY
X	H	Z
H	L	L
L	L	H
Open	L	L
H	Open	L
L	Open	H

H = high level, L = low level,
X = irrelevant, Z = high impedance (off)

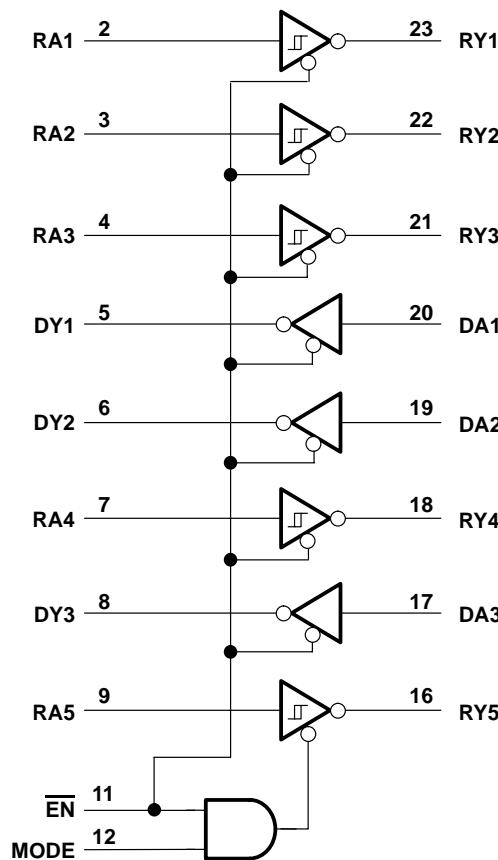
Function Tables (Continued)

RECEIVERS

INPUTS		ENABLE INPUTS		OUTPUTS	
RA1–RA4	RA5	EN	MODE	RY1–RY4	RY5
H	H	L	X	L	L
L	L	L	X	H	H
X	H	H	L	Z	L
X	L	H	L	Z	H
X	X	H	H	Z	Z
Open	Open	L	X	H	H
H	H	L	Open	L	L
L	L	L	Open	H	H
X	H	H	Open	Z	L
X	L	H	Open	Z	H
H	H	Open	X	L	L
L	L	Open	X	H	H

H = high level, L = low level, X = irrelevant, Z = high impedance (off)

functional logic diagram (positive logic)



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absolute maximum ratings over operating free-air temperature range (unless otherwise noted)

† Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTES: 1. All voltage values are with respect to network ground terminal unless otherwise noted.

2. Per MIL-STD-883 Method 3015.7
3. The package thermal impedance is calculated in accordance with JESD 51-7.
4. The package thermal impedance is calculated in accordance with JESD 51-3.

recommended operating conditions

			MIN	NOM	MAX	UNIT
V _{CC}	Supply voltage (see Note 5)		4.75	5	5.25	V
V _{DD}	Supply voltage		9	12	15	V
V _{SS}	Supply voltage		-9	-12	-15	V
V _{IH}	High-level input voltage	DA, \overline{EN} , MODE	2			V
V _{IL}	Low-level input voltage	DA, \overline{EN} , MODE			0.8	V
V _I	Receiver input voltage range	RA	-25		25	V
I _{OH}	High-level output current	RY			-1	mA
I _{OL}	Low-level output current	RY			2	mA
T _A	Operating free-air temperature		0		70	°C

NOTE 5: V_{CC} cannot be greater than V_{DD} .



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supply currents over the recommended operating conditions (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
I _{CC}	Supply current for V _{CC}	No load, All inputs at minimum V _{OH} or maximum V _{OL}	V _{DD} = 9 V, V _{SS} = -9 V, EN at GND, See Note 6		1000	
			V _{DD} = 12 V, V _{SS} = -12 V, EN at GND		1000	
			EN, MODE at V _{CC}		650	
			EN at V _{CC} , MODE at GND		700	
I _{DD}	Supply current for V _{DD}	No load, All inputs at minimum V _{OH} or maximum V _{OL}	V _{DD} = 9 V, V _{SS} = -9 V, EN at GND, See Note 6		800	
			V _{DD} = 12 V, V _{SS} = -12 V, EN at GND		800	
			EN, MODE at V _{CC}		20	
			EN at V _{CC} , MODE at GND		20	
I _{SS}	Supply current for V _{SS}	No load, All inputs at minimum V _{OH} or maximum V _{OL}	V _{DD} = 9 V, V _{SS} = -9 V, EN at GND, See Note 6		-625	
			V _{DD} = 12 V, V _{SS} = -12 V, EN at GND		-625	
			EN, MODE at V _{CC}		-50	
			EN at V _{CC} , MODE at GND		-50	

NOTE 6: Minimum RS-232 driver output voltages are not attained with ± 5 -V supplies.

driver electrical characteristics over the recommended operating conditions (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V _{OH}	High-level output voltage	V _I = 0.8 V, R _L = 3 k Ω , See Figure 1	V _{DD} = 9 V, V _{SS} = -9 V, EN at GND, See Note 6	5	5.8	6.6
			V _{DD} = 12 V, V _{SS} = -12 V, EN at GND, See Note 7	5	5.8	6.6
V _{OL}	Low-level output voltage	V _I = 2 V, R _L = 3 K, See Figure 1	V _{DD} = 9 V, V _{SS} = -9 V, EN at GND, See Note 6	-5	-5.8	-6.9
			V _{DD} = 12 V, V _{SS} = -12 V, EN at GND, See Note 7	-5	-5.8	-6.9
I _{IH}	High-level input current	V _I at V _{CC}			1	μ A
I _{IL}	Low-level input current	V _I at GND			-1	μ A
I _{OZ}	High-impedance output current	V _{CC} = 5 V, V _{DD} = 12 V, V _{SS} = -12 V, -5 V \leq V _O \leq 5 V			± 100	μ A
I _{OS(H)}	Short-circuit high-level output current	V _O = GND or V _{SS} , See Figure 2 and Note 8			-30	mA
I _{OS(L)}	Short-circuit low-level output current	V _O = GND or V _{SS} , See Figure 2 and Note 8			30	mA
r _o	Output resistance	V _{DD} = V _{SS} = V _{CC} = 0, V _O = 2 V			300	Ω

NOTES: 6. Minimum RS-232 driver output voltages are not attained with ± 5 -V supplies.

7. Maximum output swing is limited to ± 5.5 V to enable the higher data rates associated with this device and to reduce EMI emissions.
8. Not more than one output should be shorted at one time.

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driver switching characteristics over operating free-air temperature range (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
t_{PHL}	Propagation delay time, high- to low-level output $R_L = 3 \text{ k}\Omega$ to $7 \text{ k}\Omega$, $C_L = 15 \text{ pF}$, See Figure 1	300	800	1600	ns	
t_{PLH}	Propagation delay time, low- to high-level output $R_L = 3 \text{ k}\Omega$ to $7 \text{ k}\Omega$, $C_L = 15 \text{ pF}$, See Figure 1	300	800	1600	ns	
t_{PZL}	Driver output-enable time to low-level output $R_L = 3 \text{ k}\Omega$ to $7 \text{ k}\Omega$, $C_L = 15 \text{ pF}$	STANDBY or WAKE-UP modes, See Figures 1 and 6 and Note 7	50	100	μs	
t_{PZH}	Driver output-enable time to high-level output $R_L = 3 \text{ k}\Omega$ to $7 \text{ k}\Omega$, $C_L = 15 \text{ pF}$	STANDBY or WAKE-UP modes, See Figures 1 and 6 and Note 7	50	100	μs	
t_{PLZ}	Driver output-disable time from low-level output $R_L = 3 \text{ k}\Omega$ to $7 \text{ k}\Omega$, $C_L = 15 \text{ pF}$	STANDBY or WAKE-UP modes, See Figures 1 and 6 and Note 7	50	100	μs	
t_{PHZ}	Driver output-disable time from high-level output $R_L = 3 \text{ k}\Omega$ to $7 \text{ k}\Omega$, $C_L = 15 \text{ pF}$	STANDBY or WAKE-UP modes, See Figures 1 and 6 and Note 7	50	100	μs	
t_{TLH} Transition time, low- to high-level output	$V_{CC} = 5 \text{ V}$, $V_{DD} = 12 \text{ V}$, $V_{SS} = -12 \text{ V}$, $R_L = 3 \text{ k}\Omega$ to $7 \text{ k}\Omega$, See Figure 1 and Note 7	Using 10%-to-90% transition region, Driver speed = 250 kbit/s, $C_L = 15 \text{ pF}$	375	2240	ns	
		Using $\pm 3\text{-V}$ transition region, Driver speed = 250 kbit/s, $C_L = 15 \text{ pF}$	200	1500		
		Using $\pm 2\text{-V}$ transition region, Driver speed = 250 kbit/s, $C_L = 15 \text{ pF}$	133	1000		
		Using $\pm 3\text{-V}$ transition region, Driver speed = 125 kbit/s, $C_L = 2500 \text{ pF}$		2750		
t_{THL} Transition time, high- to low-level output	$V_{CC} = 5 \text{ V}$, $V_{DD} = 12 \text{ V}$, $V_{SS} = -12 \text{ V}$, $R_L = 3 \text{ k}\Omega$ to $7 \text{ k}\Omega$, See Figure 1 and Note 7	Using 10%-to-90% transition region, Driver speed = 250 kbit/s, $C_L = 15 \text{ pF}$	375	2240	ns	
		Using $\pm 3\text{-V}$ transition region, Driver speed = 250 kbit/s, $C_L = 15 \text{ pF}$	200	1500		
		Using $\pm 2\text{-V}$ transition region, Driver speed = 250 kbit/s, $C_L = 15 \text{ pF}$	133	1000		
		Using $\pm 3\text{-V}$ transition region, Driver speed = 125 kbit/s, $C_L = 2500 \text{ pF}$		2750		
SR	Output slew rate $V_{CC} = 5 \text{ V}$, $V_{DD} = 12 \text{ V}$, $V_{SS} = -12 \text{ V}$, $R_L = 3 \text{ k}\Omega$ to $7 \text{ k}\Omega$, $C_L = 15 \text{ pF}$, See Note 7	Using $\pm 3\text{-V}$ transition region, Driver speed = 0 to 250 kbit/s	4	20	30	$\text{V}/\mu\text{s}$

NOTE 7: Maximum output swing is limited to $\pm 5.5 \text{ V}$ to enable the higher data rates associated with this device and to reduce EMI emissions.

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receiver electrical characteristics over recommended operating free-air temperature range (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V_{IT+}	Positive-going input threshold voltage	See Figure 3	1.6	2	2.55
V_{IT-}	Negative-going input threshold voltage	See Figure 3	0.6	1	1.45
V_{HYS}	Input hysteresis, $V_{IT+} - V_{IT-}$	See Figure 3	600	1100	mV
V_{OH}	High-level output voltage	$I_{OH} = -1$ mA	2.5	3.9	V
V_{OL}	Low-level output voltage	$I_{OL} = 2$ mA	0.33	0.5	V
I_{IH}	$V_I = 3$ V	0.43	0.6	1	mA
	$V_I = 25$ V	3.6	5.1	8.3	
I_{IL}	$V_I = -3$ V	-0.43	-0.6	-1	mA
	$V_I = -25$ V	-3.6	-5.1	-8.3	
$I_{OS(H)}$	$V_O = 0$, See Figure 5 and Note 8			-20	mA
$I_{OS(L)}$	$V_O = V_{CC}$, See Figure 5 and Note 8			20	mA
I_{OZ}	$V_{CC} = 0$ or 5 V, 0.3 V $\leq V_O \leq V_{CC}$			± 100	μ A
R_{IN}	$V_I = \pm 3$ V to ± 25 V	3	5	7	k Ω

NOTE 8: Not more than one output should be shorted at one time.

receiver switching characteristics over recommended operating free-air temperature range (unless otherwise noted)

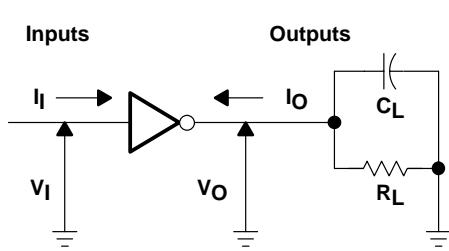
PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t_{PHL}	STANDBY mode $C_L = 50$ pF, See Figures 4 and 7	400	900	ns	
t_{PLH}		400	900	ns	
t_{TLH}		200	500	ns	
t_{THL}		200	400	ns	
$t_{SK(P)}$		200	425	ns	
t_{PZL}		50	100	μ s	
t_{PZH}		50	100	μ s	
t_{PLZ}		50	100	μ s	
t_{PHZ}		50	100	μ s	
t_{PHL}		500	1500	ns	
t_{PLH}		500	1500	ns	

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PARAMETER MEASUREMENT INFORMATION



NOTES: A. The pulse generator has the following characteristics:
 For $C_L < 1000 \text{ pF}$: $t_W = 4 \mu\text{s}$, PRR = 250 kbit/s, $Z_O = 50 \Omega$, $t_r = t_f < 50 \text{ ns}$.
 For $C_L = 2500 \text{ pF}$: $t_W = 8 \mu\text{s}$, PRR = 125 kbit/s, $Z_O = 50 \Omega$, $t_r = t_f < 50 \text{ ns}$.
 B. C_L includes probe and jig capacitance.

Figure 1. Driver Parameter Test Circuit and Waveform

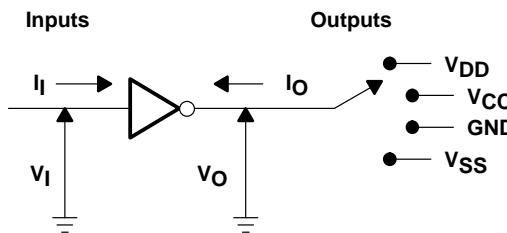


Figure 2. Driver I_{O_S} Test

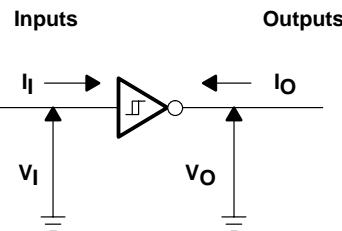
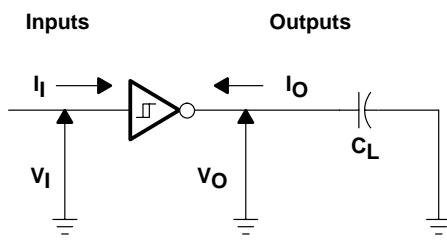


Figure 3. Receiver V_{IT} Test



NOTES: A. The pulse generator has the following characteristics: $t_W = 4 \mu\text{s}$, PRR = 250 kbit/s, $Z_O = 50 \Omega$, $t_r = t_f < 50 \text{ ns}$.
 B. C_L includes probe and jig capacitance.

Figure 4. Receiver Parameter Test Circuit and Waveform

PARAMETER MEASUREMENT INFORMATION

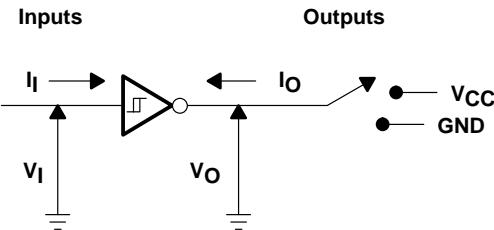
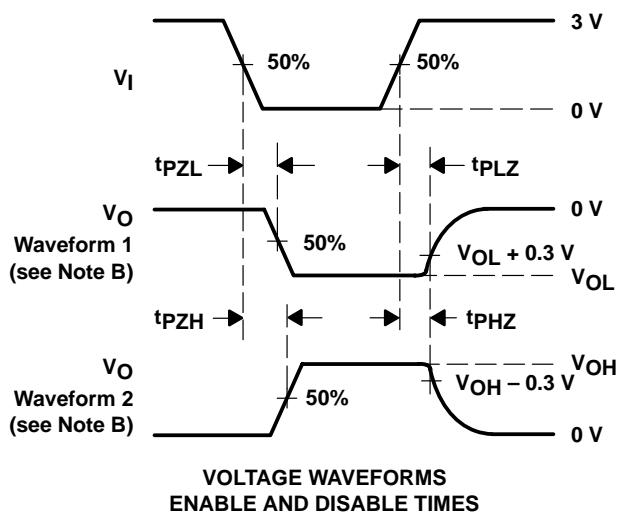
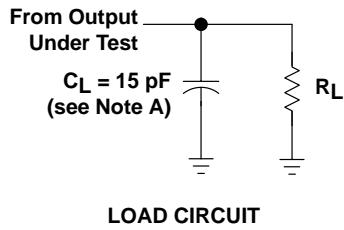


Figure 5. Receiver I_{OS} Test



NOTES:

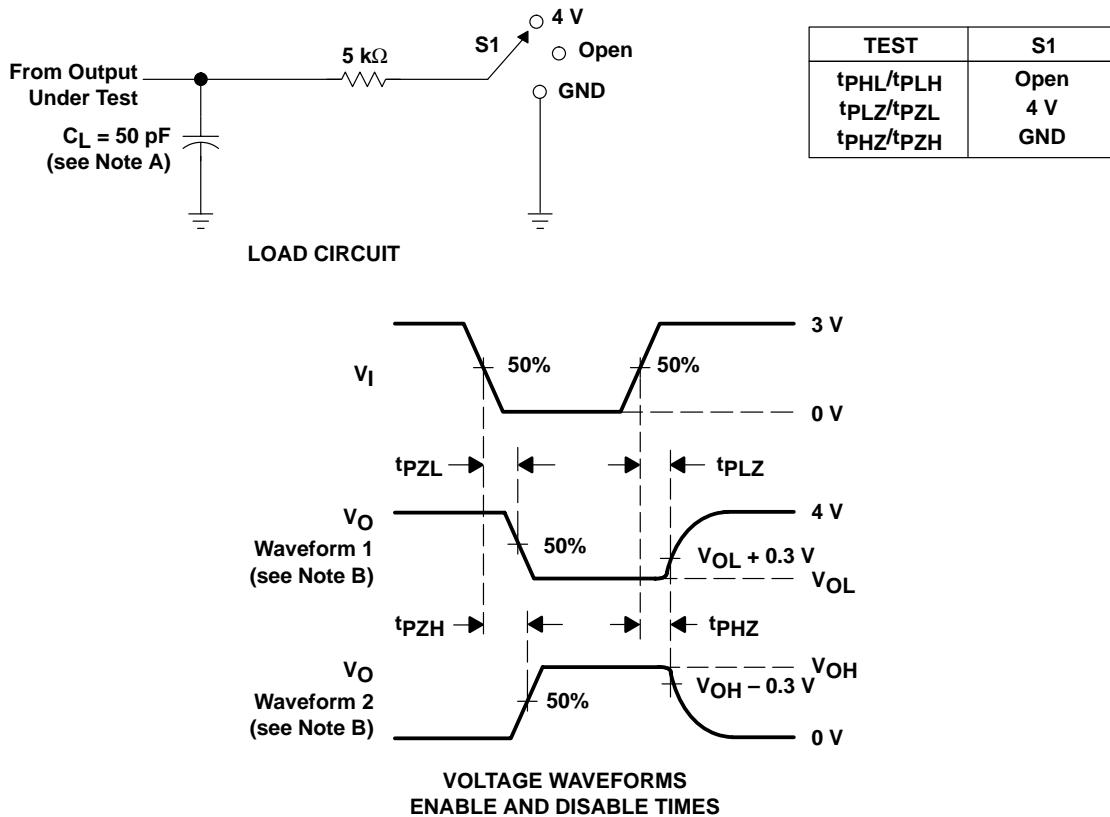
- A. C_L includes probe and jig capacitance.
- B. Waveform 1 is for an output with internal conditions such that the output is low except when disabled by the output control. Waveform 2 is for an output with internal conditions such that the output is high except when disabled by the output control.
- C. All input pulses are supplied by generators having the following characteristics: PRR = 250 kbit/s, $Z_O = 50 \Omega$, $t_r = t_f < 50$ ns.
- D. The outputs are measured one at a time with one transition per measurement.

Figure 6. Driver 3-State Parameter Load Circuit and Voltage Waveforms

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PARAMETER MEASUREMENT INFORMATION



NOTES: A. C_L includes probe and jig capacitance.
 B. Waveform 1 is for an output with internal conditions such that the output is low except when disabled by the output control.
 C. All input pulses are supplied by generators having the following characteristics: $PRR = 250\text{ kbit/s}$, $Z_O = 50\text{ }\Omega$, $t_r = t_f < 50\text{ ns}$.
 D. The outputs are measured one at a time with one transition per measurement.

Figure 7. Receiver 3-State Parameter Load Circuit and Voltage Waveforms

APPLICATION INFORMATION

receiver output states

RECEIVER KNOWN OUTPUT STATES DURING POWER-DOWN, STANDBY, OR WAKE-UP MODES		
RECEIVER NUMBER	SIGNAL NAME	RECEIVER OUTPUT
RY1	\overline{DCD}	High
RY2	\overline{DSR}	High
RY3	RX	Low
RY4	\overline{CTS}	High
RY5	\overline{RI}	High

fault protection during power down

Diodes placed in series with the V_{DD} and V_{SS} leads protect the SN75LPE185 in the fault condition, in which the device outputs are shorted to ± 15 V and the power supplies are at low voltage and provide low-impedance paths to ground.

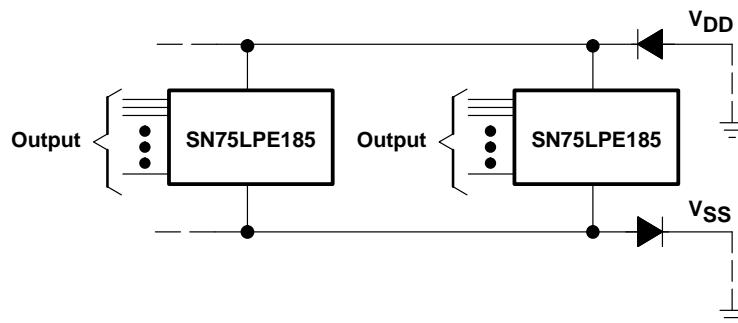


Figure 8. Power-Supply Protection to Meet Power-Off Fault Conditions of TIA/EIA-232-F

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APPLICATION INFORMATION

WAKE-UP mode

While in the WAKE-UP mode, all the drivers and receivers of the SN75LPE185 device are in the high-impedance state, except for receiver 5, which can be used as a ring indicator function. In this mode, the current drawn from the power supplies is low, to conserve power.

In today's PCs, board designers are becoming more concerned about power consumption. The flexibility of the SN75LPE185 during WAKE-UP mode allows the designer to operate the device at auxiliary power-supply voltages below specified levels. The SN75LPE185 functions properly during WAKE-UP mode, using the following power-supply conditions:

- (a) $V_{CC} = 4.75$ V, $V_{DD} = 9$ V, and $V_{SS} = -9$ V (data-sheet specifications)
- (b) $V_{CC} = 5$ V, $V_{DD} = 5$ V, and $V_{SS} = -5$ V
- (c) $V_{CC} = 5$ V, V_{DD} = open, and V_{SS} = open
- (d) $V_{CC} = 5$ V, $V_{DD} = 5$ V, and V_{SS} is shorted to the most negative supply.

Condition (a) describes the minimum supply voltages necessary for the device to comply fully to specifications.

Conditions (b) and (d) describe the condition where a -5-V supply is not available during auxiliary power. In this case, V_{SS} must be shorted to the most negative supply (i.e., GND or a voltage source close to, but below GND).

Condition (c) states V_{DD} and V_{SS} power supplies can be shut off.

In all cases, GND is understood to be 0 V, and the power-supply voltages should never exceed the absolute maximum ratings.



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