

273 MHz 6 Output Buffer for DDR400 DIMMS

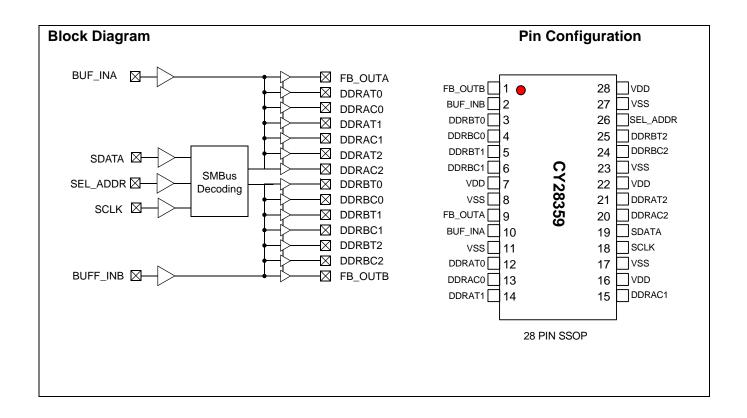
Features

- Dual 1- to 3-output buffer/driver
- Supports up to 2 DDR DIMMs
- · Outputs are individually enabled/disabled
- Low-skew outputs (< 100 ps)
- Supports 266 MHz, 333 MHz and 400 MHz DDR SDRAM
- SMBus Read and Write support
- · Space-saving 28-pin SSOP package

Functional Description

The CY28359 is a 2.5V buffer designed to distribute high-speed clocks in PC applications. The part has 6 differential outputs. Designers can configure these outputs to support up to two DDR DIMMs. The CY28359 can be used in conjunction with the CY28326 or similar clock synthesizer for the VIA P4X600 chipset.

The CY28359 also includes an SMBus interface which can enable or disable each output clock. On power-up, all output clocks are enabled.



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Pin Description

Pin	Name	PWR	I/O	Description
10 2	BUF_INA, BUF_INB	VDD2.5	I	Reference input from chipset. 2.5V input.
13,15,20 4,6,24	DDRA[0:2]C DDRB[0:2]C	VDD2.5	0	Clock outputs. These outputs provide complementary copies of BUF_INA & BUF_INB, respectively.
12,14,21 3,5,25	DDRA[0:2]T DDRB[0:2]T	VDD2.5	0	Clock outputs. These outputs provide copies of BUF_INA & BUF_INB, respectively.
9	FB_OUTA FB_OUTB	VDD2.5	0	Feedback clock for chipset
18	SCLK	VDD2.5	I	SMBus clock input. Has pull-up resistor
19	SDATA	VDD2.5	I/O	SMBus data input. Has pull-up resistor
26	SEL_ADDR		I	Address Select Pin. Has pull-down resistor
7,16,22,28	VDD2.5			2.5V voltage supply
8,11,17,23,27	VSS			Ground

Serial Data Interface

To enhance the flexibility and function of the clock synthesizer, a two-signal serial interface is provided. Through the Serial Data Interface, various device functions, such as individual clock output buffers, can be individually enabled or disabled. The registers associated with the Serial Data Interface initializes to their default setting upon power-up, and therefore use of this interface is optional. The interface can also be accessed during power down operation.

Data Protocol

The clock driver serial protocol accepts Byte Write, Byte Read, Block Write and Block Read operation from any external $\rm I^2C$

controller. For Block Write/Read operation, the bytes must be accessed in sequential order from lowest to highest byte (most significant bit first) with the ability to stop after any complete byte has been transferred. For Byte Write and Byte Read operations, the system controller can access individual indexed bytes. The offset of the indexed byte is encoded in the command code, as described in *Table 1*.

The Block Write and Block Read protocol is outlined in *Table 2* while *Table 3* outlines the corresponding Byte Write and Byte Read protocol. The slave receiver address is 11010010 (D2h) or 11011100 (DCh) depending on state of ADDRSEL.

Table 1. Command Code Definition

Bit	Description
7	0 = Block Read or Block Write operation 1 = Byte Read or Byte Write operation
(6:5)	01
(4:0)	Byte offset for Byte Read or Byte Write operation. For Block Read or Block Write operations, these bits should be '00000'



Table 2. Block Read and Block Write Protocol

	Block Write Protocol	Block Read Protocol		
Bit	Description	Bit	Description	
1	Start	1	Start	
2:8	Slave address – 7 bits	2:8	Slave address – 7 bits	
9	Write = 0	9	Write = 0	
10	Acknowledge from slave	10	Acknowledge from slave	
11:18	Command Code – 8 bits '00000000' stands for block operation	11:18	Command Code – 8 bits '00000000' stands for block operation	
19	Acknowledge from slave	19	Acknowledge from slave	
20:27	Byte Count – 8 bits	20	Repeat start	
28	Acknowledge from slave	21:27	Slave address – 7 bits	
29:36	Data byte 1 – 8 bits	28	Read = 1	
37	Acknowledge from slave	29	Acknowledge from slave	
38:45	Data byte 2 – 8 bits	30:37	Byte count from slave – 8 bits	
46	Acknowledge from slave	38	Acknowledge from master	
		39:46	Data byte from slave – 8 bits	
	Data Byte (N–1) – 8 bits	47	Acknowledge from master	
	Acknowledge from slave	48:55	Data byte from slave – 8 bits	
	Data Byte N – 8 bits	56	Acknowledge from master	
	Acknowledge from slave		Data byte N from slave – 8 bits	
	Stop		Acknowledge from master	
			Stop	

Table 3. Byte Read and Byte Write Protocol

	Byte Write Protocol		Byte Read Protocol
Bit	Description	Bit	Description
1	Start	1	Start
2:8	Slave address – 7 bits	2:8	Slave address – 7 bits
9	Write = 0	9	Write = 0
10	Acknowledge from slave	10	Acknowledge from slave
11:18	Command Code – 8 bits '1XXxxxxx' stands for byte operation,bit[6:5] for Device selection bits for multiple device selection, bits[4:0] of the command code represents the offset of the byte to be accessed	11:18	Command Code – 8 bits '1XXxxxxx' stands for byte operation,bit[6:5] for Device selection bits for multiple device selection, bits[4:0] of the command code represents the offset of the byte to be accessed
19	Acknowledge from slave	19	Acknowledge from slave
20:27	Data byte from master – 8 bits	20	Repeat start
28	Acknowledge from slave	21:27	Slave address – 7 bits
29	Stop	28	Read = 1
		29	Acknowledge from slave
		30:37	Data byte from slave – 8 bits
		38	Acknowledge from master
		40	Stop



Serial Configuration Map

 The Serial bits will be read by the clock driver in the following order:

Byte 0 - Bits 7, 6, 5, 4, 3, 2, 1, 0 Byte 1 - Bits 7, 6, 5, 4, 3, 2, 1, 0 .

Byte N - Bits 7, 6, 5, 4, 3, 2, 1, 0

• Reserved and unused bits should be programmed to "0".

SMBus Address for the CY28359 when SEL_ADDR=1:

A6	A5	A4	A3	A2	A1	A0	R/W
1	1	0	1	0	0	1	

SMBus Address for the CY28359 when SEL_ADDR=0:

A6	A5	A4	А3	A2	A1	A0	R/W
1	1	0	1	1	1	0	

Byte 22: Outputs Active/Inactive Register (1 = Active, 0 = Three-state), Default = Active

Bit	Pin #	Description	Default
Bit 7		Input Threshold Control00: Normal (1.25V)	0
Bit 6		01: 1.20V 10: 1.15V 11: 1.35V	0
Bit 5	9	FBOUTA 0 = Enable, 1 = Disable	0
Bit 4	1	FBOUTB 0 = Enable, 1 = Disable	0
Bit 3		Reserved, drive to 0	1
Bit 2		Reserved, drive to 0	1
Bit 1	24, 25	DDRBT2, DDRBC2	1
Bit 0		Reserved, drive to 0	1

Byte 23: Outputs Active/Inactive Register(1 = Active, 0 = Three-state), Default = Active

Bit	Pin #	Description	Default
Bit 7	5,6	DDRBT1, DDRBC1	1
Bit 6	3,4	DDRBT0, DDRBC0	1
Bit 5	21,20	DDRAT2, DDRAC2	1
Bit 4		Reserved, drive to 0	1
Bit 3	14,15	DDRAT1, DDRAC1	1
Bit 2	12,13	DDRAT0, DDRAC0	1
Bit 1		Reserved, drive to 0	1
Bit 0		Reserved, drive to 0	1



Absolute Maximum Conditions

Supply Voltage to Ground Potential.....-0.5 to +4.0V DC Input Voltage (except BUF_IN).....-0.5V to V_{DD}+0.5 Storage Temperature-65°C to +150°C

Static Discharge Voltage>2000V (per MIL-STD-883, Method 3015)

Operating Conditions

Parameter	Description	Min.	Тур.	Max.	Unit
V _{DD2.5}	Supply Voltage	2.375	_	2.625	V
T _A	Operating Temperature (Ambient Temperature)	-40	_	85	°C
C _{OUT}	Output Capacitance		6	_	pF
C _{IN}	Input Capacitance	_	5	_	pF

Electrical Characteristics Over the Operating Range

Parameter	Description	Test Conditions	Min.	Тур.	Max.	Unit
V_{IL}	Input LOW Voltage	For all pins except SMBus	-	_	0.8	V
V _{IH}	Input HIGH Voltage		2.0	_	_	V
I _{IL}	Input LOW Current	$V_{IN} = 0V$	-	_	5	μА
I _{IH}	Input HIGH Current	$V_{IN} = V_{DD}$	-	_	5	μА
I _{OH}	Output HIGH Current	V _{DD} = 2.375V V _{OUT} = 1V	-18	-32	-	mA
I _{OL}	Output LOW Current	$V_{DD} = 2.375V$ $V_{OUT} = 1.2V$	26	35	-	mA
V _{OL}	Output LOW Voltage	$I_{OL} = 12 \text{ mA}, V_{DD} = 2.375 \text{V}$	-	_	0.6	V
V _{OH}	Output HIGH Voltage	$I_{OH} = -12 \text{ mA}, V_{DD} = 2.375 \text{V}$	1.7	_	_	V
I _{DD}	Supply Current	Unloaded outputs, 273 MHz	-	_	250	mA
I _{DD}	Supply Current	Loaded outputs, 273 MHz	-	_	300	mA
V _{OUT}	Output Voltage Swing	See Test Circuitry (Refer to Figure 1)	0.7	_	V _{DD} + 0.6	V
V _{oc}	Output Crossing Voltage		$(V_{DD}/2) - 0.2$	V _{DD} /2	$(V_{DD}/2) + 0.2$	V
IN _{DC}	Input Clock Duty Cycle		48		52	%

Switching Characteristics^[1]

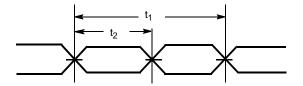
Parameter	Name	Test Conditions	Min.	Тур.	Max.	Unit
F _O	Operating Frequency		66	_	273	MHz
T _{DC}	Duty Cycle = $t_2 \div t_1$	Measured at V _{DD/} 2 for 2.5V outputs.	IN _{DC} - 2%	_	IN _{DC} + 2%	%
t ₃	DDR Rising/Falling Edge Rate ^[2]	Measured between 20% to 80% of output (Refer to <i>Figure 1</i>)	1	_	3	V/ns
t ₄	Output to Output Skew ^[2]	All outputs equally loaded	_	_	100	ps

Parameter is guaranteed by design and characterization. Not 100% tested in production
 All parameters specified with loaded outputs.



Switching Waveforms

Duty Cycle Timing



Output-Output Skew

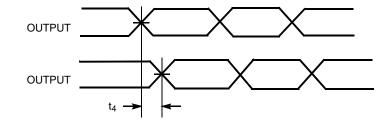


Figure 1 shows the differential clock directly terminated by a 120Ω resistor.

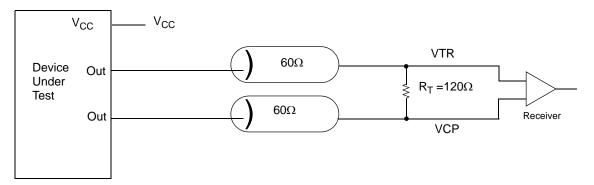


Figure 1. Differential Signal Using Direct Termination Resistor

Ordering Information

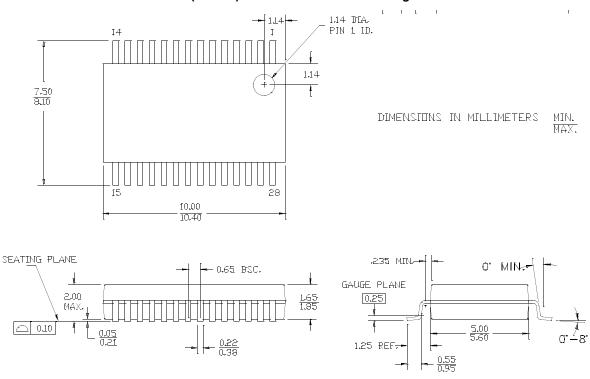
Ordering Code	Package Type	Operating Range
CY28359OC	28-pin SSOP	Commercial, 0°C to 70 °C
CY28359OCT	28-pin SSOP (Tape & Reel)	Commercial, 0°C to 70 °C
CY28359OI	28-pin SSOP	Industrial, -40°C to 85 °C
CY28359OIT	28-pin SSOP (Tape & Reel)	Industrial, –40°C to 85 °C

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Package Drawing and Dimensions

28-Lead (5.3 mm) Shrunk Small Outline Package O28



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