MOTOROLA

MC34151
MC33151

High Speed Dual MOSFET Drivers

The MC34151/MC33151 are dual inverting high speed drivers specifically designed for applications that require low current digital circuitry to drive large capacitive loads with high slew rates. These devices feature low input current making them CMOS and LSTTL logic compatible, input hysteresis for fast output switching that is independent of input transition time, and two high current totem pole outputs ideally suited for driving power MOSFETs. Also included is an undervoltage lockout with hysteresis to prevent erratic system operation at low supply voltages.
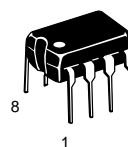
Typical applications include switching power supplies, dc to dc converters, capacitor charge pump voltage doublers/inverters, and motor controllers.

These devices are available in dual–in–line and surface mount packages.

- Two Independent Channels with 1.5 A Totem Pole Output
- Output Rise and Fall Times of 15 ns with 1000 pF Load
- CMOS/LSTTL Compatible Inputs with Hysteresis
- Undervoltage Lockout with Hysteresis
- Low Standby Current
- Efficient High Frequency Operation
- Enhanced System Performance with Common Switching Regulator Control ICs
- Pin Out Equivalent to DS0026 and MMH0026

HIGH SPEED DUAL MOSFET DRIVERS
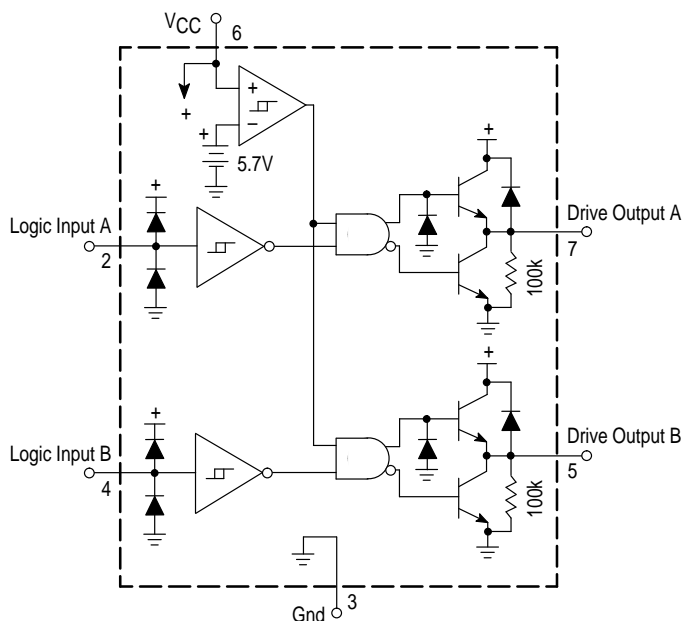
SEMICONDUCTOR TECHNICAL DATA
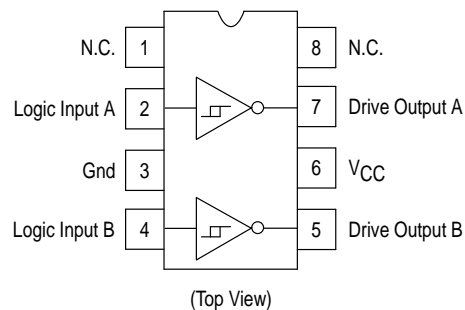
P SUFFIX
PLASTIC PACKAGE
CASE 626

D SUFFIX
PLASTIC PACKAGE
CASE 751
(SO–8)

PIN CONNECTIONS

N.C.	1		8	N.C.
Logic Input A	2		7	Drive Output A
Gnd	3		6	V_{CC}
Logic Input B	4		5	Drive Output B

(Top View)

Representative Block Diagram

V_{CC} 6

5.7V

Logic Input A 2

Drive Output A 7

100k

Logic Input B 4

Drive Output B 5

100k

Gnd 3

ORDERING INFORMATION

Device	Operating Temperature Range	Package
MC34151D	$T_A = 0°$ to $+70°C$	SO–8
MC34151P		Plastic DIP
MC33151D	$T_A = -40°$ to $+85°C$	SO–8
MC33151P		Plastic DIP

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Rev 0

MAXIMUM RATINGS

Rating	Symbol	Value	Unit
Power Supply Voltage	V_{CC}	20	V
Logic Inputs (Note 1)	V_{in}	−0.3 to V_{CC}	V

Drive Outputs (Note 2)
    Totem Pole Sink or Source Current
    Diode Clamp Current (Drive Output to V_{CC})
	I_O
	$I_{O(clamp)}$
		1.5
		1.0
			A

Power Dissipation and Thermal Characteristics
  D Suffix SO–8 Package Case 751
    Maximum Power Dissipation @ T_A = 50°C
    Thermal Resistance, Junction–to–Air
  P Suffix 8–Pin Package Case 626
    Maximum Power Dissipation @ T_A = 50°C
    Thermal Resistance, Junction–to–Air
	
	P_D
	$R_{\theta JA}$
	
	P_D
	$R_{\theta JA}$
		
		0.56
		180
		
		1.0
		100
			
			W
			°C/W
			
			W
			°C/W

Operating Junction Temperature	T_J	+150	°C

Operating Ambient Temperature
  MC34151
  MC33151
	T_A	
		0 to +70
		−40 to +85
			°C

Storage Temperature Range	T_{stg}	−65 to +150	°C

ELECTRICAL CHARACTERISTICS (V_{CC} = 12 V, for typical values T_A = 25°C, for min/max values T_A is the only operating ambient temperature range that applies [Note 3], unless otherwise noted.)

Characteristics	Symbol	Min	Typ	Max	Unit
LOGIC INPUTS					
Input Threshold Voltage – High State Logic 1 – Low State Logic 0	V_{IH} V_{IL}	2.6 –	1.75 1.58	– 0.8	V
Input Current – High State (V_{IH} = 2.6 V) – Low State (V_{IL} = 0.8 V)	I_{IH} I_{IL}	– –	200 20	500 100	µA
DRIVE OUTPUT					

Output Voltage – Low State (I_{Sink} = 10 mA)
                 (I_{Sink} = 50 mA)
                 (I_{Sink} = 400 mA)
        – High State (I_{Source} = 10 mA)
                 (I_{Source} = 50 mA)
                 (I_{Source} = 400 mA)
	V_{OL}
	
	V_{OH}
		–
		–
		–
		10.5
		10.4
		9.5
			0.8
			1.1
			1.7
			11.2
			11.1
			10.9
				1.2
				1.5
				2.5
				–
				–
				–
					V

Output Pull–Down Resistor	R_{PD}	–	100	–	kΩ
SWITCHING CHARACTERISTICS (T_A = 25°C)					

Propagation Delay (10% Input to 10% Output, C_L = 1.0 nF)
  Logic Input to Drive Output Rise
  Logic Input to Drive Output Fall
	
	$t_{PLH(in/out)}$
	$t_{PHL(in/out)}$
		
		–
		–
			
			35
			36
				
				100
				100
					ns

Drive Output Rise Time (10% to 90%) C_L = 1.0 nF C_L = 2.5 nF	t_r	– –	14 31	30 –	ns
Drive Output Fall Time (90% to 10%) C_L = 1.0 nF C_L = 2.5 nF	t_f	– –	16 32	30 –	ns
TOTAL DEVICE					

Power Supply Current
  Standby (Logic Inputs Grounded)
  Operating (C_L = 1.0 nF Drive Outputs 1 and 2, f = 100 kHz)
	I_{CC}	
		–
		–
			
			6.0
			10.5
				
				10
				15
					mA

Operating Voltage	V_{CC}	6.5	–	18	V

NOTES: 1. For optimum switching speed, the maximum input voltage should be limited to 10 V or V_{CC}, whichever is less.
      2. Maximum package power dissipation limits must be observed.
      3. T_{low} =   0°C for MC34151 T_{high} = +70°C for MC34151
                −40°C for MC33151   +85°C for MC33151

Figure 1. Switching Characteristics Test Circuit
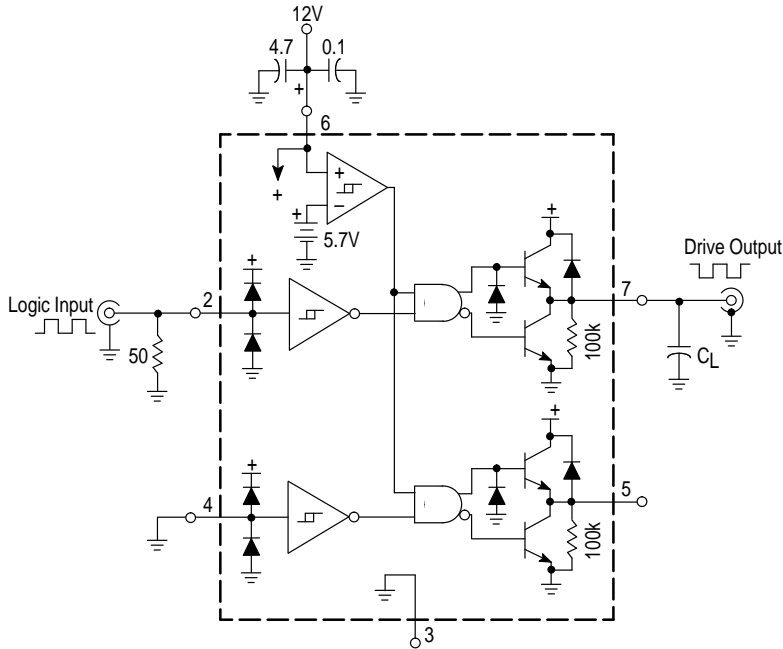

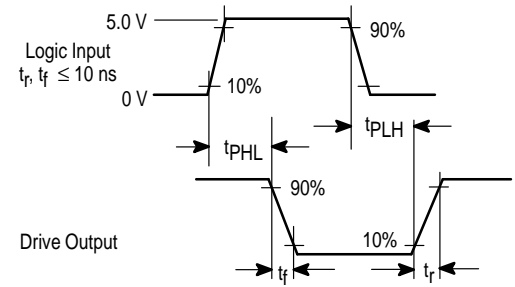## Figure 2. Switching Waveform Definitions

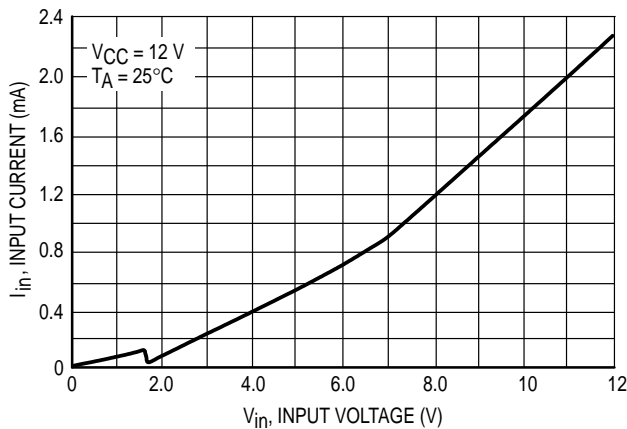## Figure 3. Logic Input Current versus Input Voltage

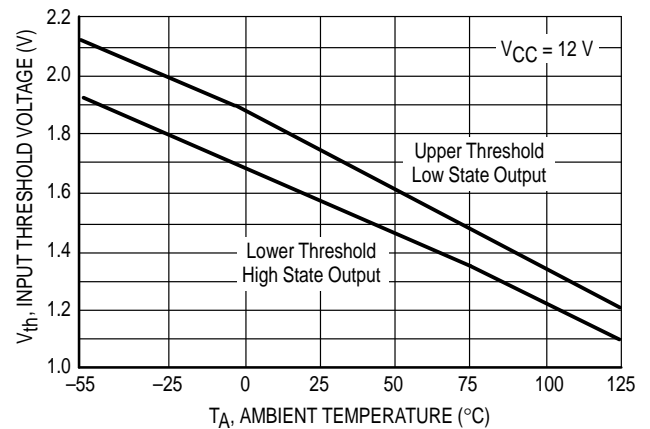## Figure 4. Logic Input Threshold Voltage versus Temperature

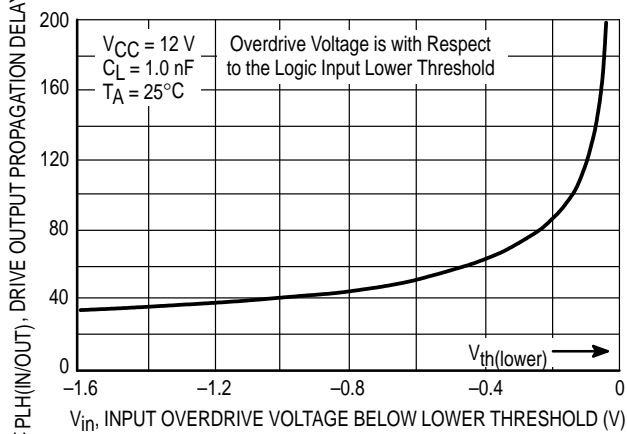## Figure 5. Drive Output Low–to–High Propagation Delay versus Logic Overdrive Voltage

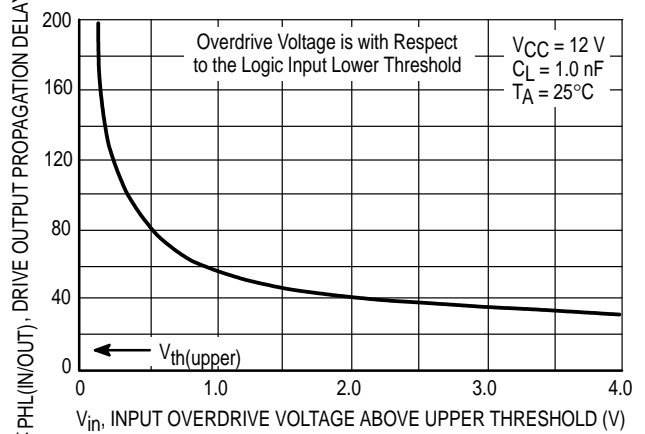## Figure 6. Drive Output High–to–Low Propagation Delay versus Logic Input Overdrive Voltage
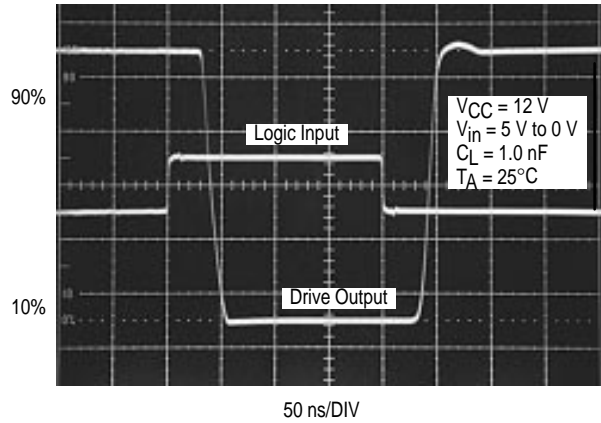
Figure 7. Propagation Delay

Logic Input

Drive Output

$V_{CC} = 12\ V$
$V_{in} = 5\ V\ to\ 0\ V$
$C_L = 1.0\ nF$
$T_A = 25°C$

90%

10%

50 ns/DIV

**Figure 8. Drive Output Clamp Voltage
versus Clamp Current**

High State Clamp
(Drive Output Driven Above V_{CC})

$V_{CC} = 12\ V$
80 μs Pulsed Load
120 Hz Rate
$T_A = 25°C$

V_{CC}

Gnd

Low State Clamp
(Drive Output Driven Below Ground)

V_{clamp}, OUTPUT CLAMP VOLTAGE (V)

I_O, OUTPUT LOAD CURRENT (A)
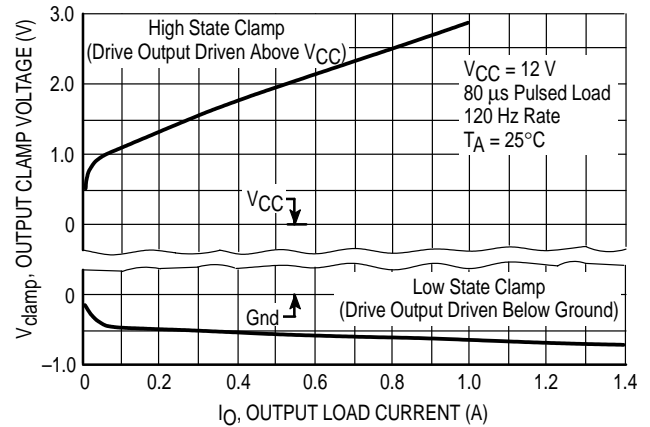
**Figure 9. Drive Output Saturation Voltage
versus Load Current**

Source Saturation
(Load to Ground)

V_{CC}

$V_{CC} = 12\ V$
80 μs Pulsed Load
120 Hz Rate
$T_A = 25°C$

Sink Saturation
(Load to V_{CC})

Gnd

V_{sat}, OUTPUT SATURATION VOLTAGE(V)

I_O, OUTPUT LOAD CURRENT (A)
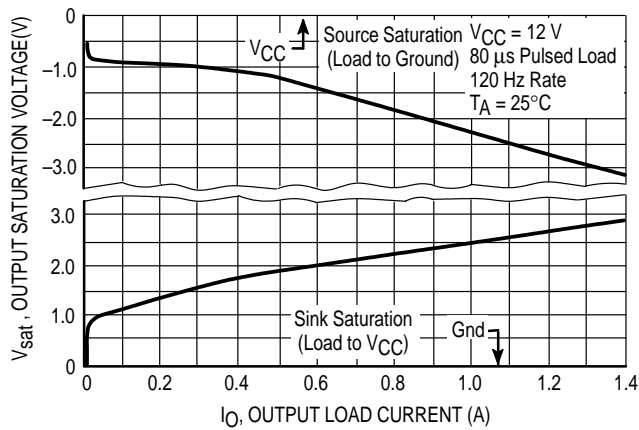
**Figure 10. Drive Output Saturation Voltage
versus Temperature**

Source Saturation
(Load to Ground)

V_{CC}

$V_{CC} = 12\ V$
$I_{source} = 10\ mA$
$I_{source} = 400\ mA$
$I_{sink} = 400\ mA$
$I_{sink} = 10\ mA$

Sink Saturation
(Load to V_{CC})

Gnd

V_{sat}, OUTPUT SATURATION VOLTAGE(V)

T_A, AMBIENT TEMPERATURE (°C)
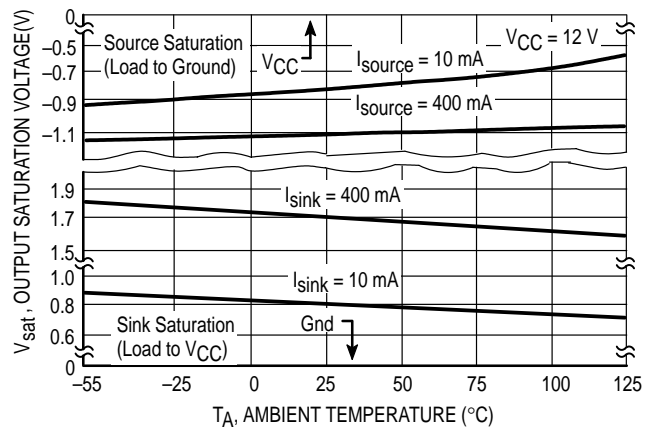
Figure 11. Drive Output Rise Time

$V_{CC} = 12\ V$
$V_{in} = 5\ V\ to\ 0\ V$
$C_L = 1.0\ nF$
$T_A = 25°C$

90%

10%

10 ns/DIV

Figure 12. Drive Output Fall Time

$V_{CC} = 12\ V$
$V_{in} = 5\ V\ to\ 0\ V$
$C_L = 1.0\ nF$
$T_A = 25°C$

90%

10%

10 ns/DIV
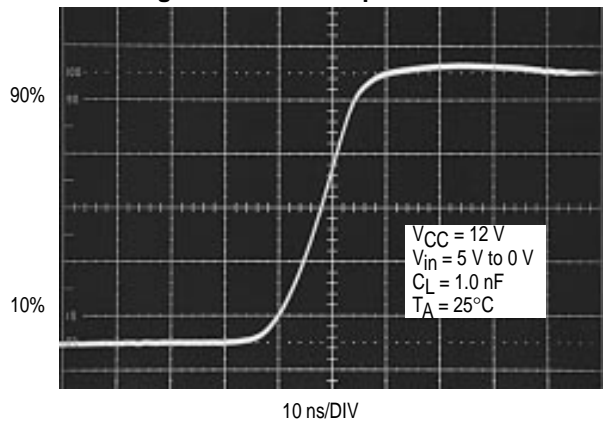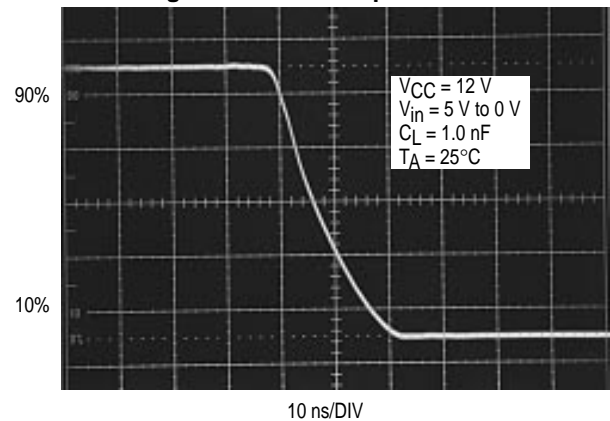
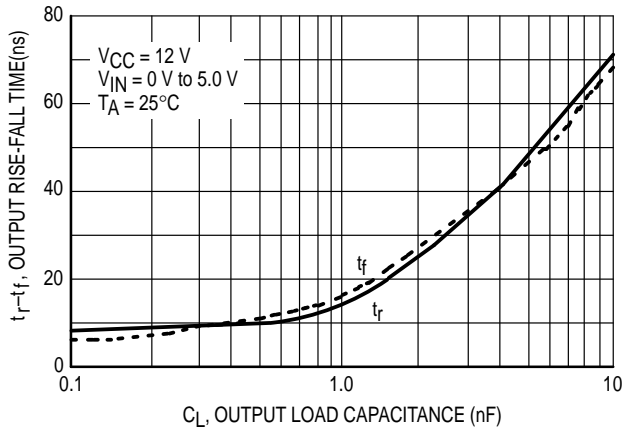**Figure 13. Drive Output Rise and Fall Time versus Load Capacitance**

Figure 14. Supply Current versus Drive Output Load Capacitance

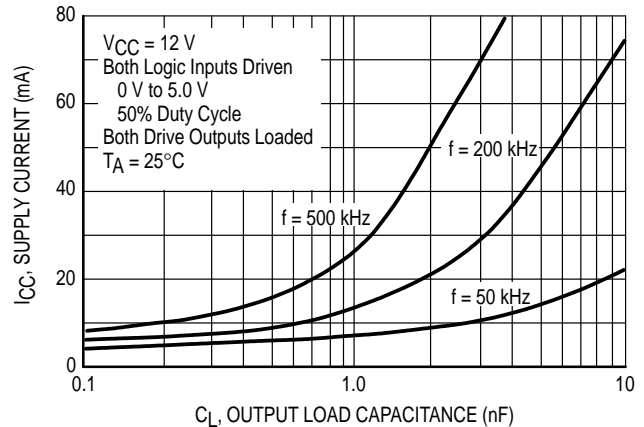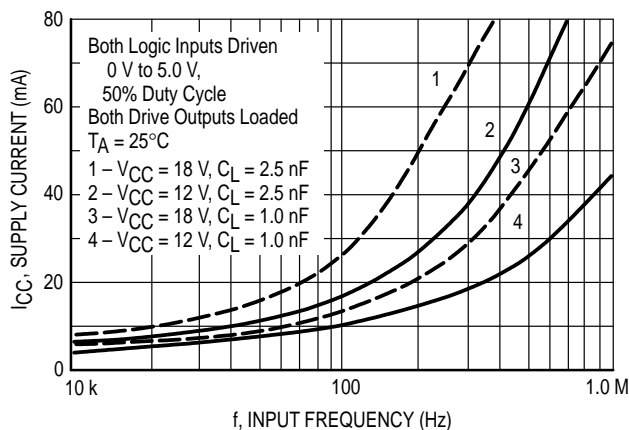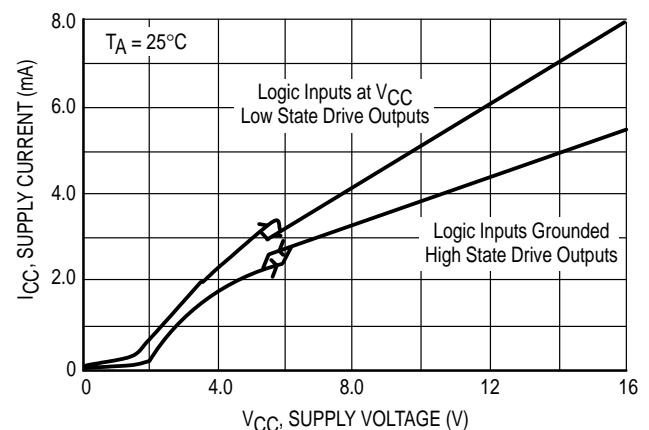**Figure 15. Supply Current versus Input Frequency**

Figure 16. Supply Current versus Supply Voltage

APPLICATIONS INFORMATION

Description

The MC34151 is a dual inverting high speed driver specifically designed to interface low current digital circuitry with power MOSFETs. This device is constructed with Schottky clamped Bipolar Analog technology which offers a high degree of performance and ruggedness in hostile industrial environments.

Input Stage

The Logic Inputs have 170 mV of hysteresis with the input threshold centered at 1.67 V. The input thresholds are insensitive to V_{CC} making this device directly compatible with CMOS and LSTTL logic families over its entire operating voltage range. Input hysteresis provides fast output switching that is independent of the input signal transition time, preventing output oscillations as the input thresholds are crossed. The inputs are designed to accept a signal amplitude ranging from ground to V_{CC}. This allows the output of one channel to directly drive the input of a second channel for master–slave operation. Each input has a 30 kΩ pull–down resistor so that an unconnected open input will cause the associated Drive Output to be in a known high state.

Output Stage

Each totem pole Drive Output is capable of sourcing and sinking up to 1.5 A with a typical 'on' resistance of 2.4 Ω at

1.0 A. The low 'on' resistance allows high output currents to be attained at a lower V_{CC} than with comparative CMOS drivers. Each output has a 100 kΩ pull–down resistor to keep the MOSFET gate low when V_{CC} is less than 1.4 V. No over current or thermal protection has been designed into the device, so output shorting to V_{CC} or ground must be avoided.

Parasitic inductance in series with the load will cause the driver outputs to ring above V_{CC} during the turn–on transition, and below ground during the turn–off transition. With CMOS drivers, this mode of operation can cause a destructive output latch–up condition. The MC34151 is immune to output latch–up. The Drive Outputs contain an internal diode to V_{CC} for clamping positive voltage transients. When operating with V_{CC} at 18 V, proper power supply bypassing must be observed to prevent the output ringing from exceeding the maximum 20 V device rating. Negative output transients are clamped by the internal NPN pull–up transistor. Since full supply voltage is applied across the NPN pull–up during the negative output transient, power dissipation at high frequencies can become excessive. Figures 19, 20, and 21 show a method of using external Schottky diode clamps to reduce driver power dissipation.

Undervoltage Lockout

An undervoltage lockout with hysteresis prevents erratic system operation at low supply voltages. The UVLO forces the Drive Outputs into a low state as V_{CC} rises from 1.4 V to

the 5.8 V upper threshold. The lower UVLO threshold is 5.3 V, yielding about 500 mV of hysteresis.

Power Dissipation

Circuit performance and long term reliability are enhanced with reduced die temperature. Die temperature increase is directly related to the power that the integrated circuit must dissipate and the total thermal resistance from the junction to ambient. The formula for calculating the junction temperature with the package in free air is:

$$T_J = T_A + P_D (R_{\theta JA})$$

where: T_J = Junction Temperature
T_A = Ambient Temperature
P_D = Power Dissipation
$R_{\theta JA}$ = Thermal Resistance Junction to Ambient

There are three basic components that make up total power to be dissipated when driving a capacitive load with respect to ground. They are:

$$P_D = P_Q + P_C + P_T$$

where: P_Q = Quiescent Power Dissipation
P_C = Capacitive Load Power Dissipation
P_T = Transition Power Dissipation

The quiescent power supply current depends on the supply voltage and duty cycle as shown in Figure 16. The device's quiescent power dissipation is:

$$P_Q = V_{CC} \left(I_{CCL} (1-D) + I_{CCH} (D) \right)$$

where: I_{CCL} = Supply Current with Low State Drive Outputs
I_{CCH} = Supply Current with High State Drive Outputs
D = Output Duty Cycle

The capacitive load power dissipation is directly related to the load capacitance value, frequency, and Drive Output voltage swing. The capacitive load power dissipation per driver is:

$$P_C = V_{CC} (V_{OH} - V_{OL}) C_L f$$

where: V_{OH} = High State Drive Output Voltage
V_{OL} = Low State Drive Output Voltage
C_L = Load Capacitance
f = frequency

When driving a MOSFET, the calculation of capacitive load power P_C is somewhat complicated by the changing gate to source capacitance C_{GS} as the device switches. To aid in this calculation, power MOSFET manufacturers provide gate charge information on their data sheets. Figure 17 shows a curve of gate voltage versus gate charge for the Motorola MTM15N50. Note that there are three distinct slopes to the curve representing different input capacitance values. To completely switch the MOSFET 'on', the gate must be brought to 10 V with respect to the source. The graph shows that a gate charge Q_g of 110 nC is required when operating the MOSFET with a drain to source voltage V_{DS} of 400 V.

Figure 17. Gate–To–Source Voltage versus Gate Charge
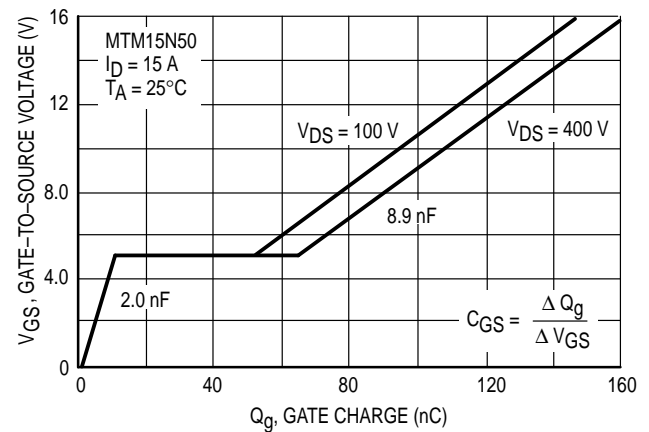
The capacitive load power dissipation is directly related to the required gate charge, and operating frequency. The capacitive load power dissipation per driver is:

$$P_{C(MOSFET)} = V_C Q_g f$$

The flat region from 10 nC to 55 nC is caused by the drain–to–gate Miller capacitance, occuring while the MOSFET is in the linear region dissipating substantial amounts of power. The high output current capability of the MC34151 is able to quickly deliver the required gate charge for fast power efficient MOSFET switching. By operating the MC34151 at a higher V_{CC}, additional charge can be provided to bring the gate above 10 V. This will reduce the 'on' resistance of the MOSFET at the expense of higher driver dissipation at a given operating frequency.

The transition power dissipation is due to extremely short simultaneous conduction of internal circuit nodes when the Drive Outputs change state. The transition power dissipation per driver is approximately:

$$P_T \approx V_{CC} (1.08 \, V_{CC} \, C_L \, f - 8 \times 10^{-4})$$
P_T must be greater than zero.

Switching time characterization of the MC34151 is performed with fixed capacitive loads. Figure 13 shows that for small capacitance loads, the switching speed is limited by transistor turn–on/off time and the slew rate of the internal nodes. For large capacitance loads, the switching speed is limited by the maximum output current capability of the integrated circuit.

LAYOUT CONSIDERATIONS

High frequency printed circuit layout techniques are imperative to prevent excessive output ringing and overshoot. **Do not attempt to construct the driver circuit on wire–wrap or plug–in prototype boards.** When driving large capacitive loads, the printed circuit board must contain a low inductance ground plane to minimize the voltage spikes induced by the high ground ripple currents. All high current loops should be kept as short as possible using heavy copper runs to provide a low impedance high frequency path. For optimum drive performance, it is recommended that the initial circuit design contains dual power supply bypass capacitors connected with short leads as close to the V_{CC} pin and ground as the layout will permit. Suggested capacitors are a low inductance 0.1 μF ceramic in parallel with a 4.7 μF tantalum. Additional bypass capacitors may be required depending upon Drive Output loading and circuit layout.

Proper printed circuit board layout is extremely critical and cannot be over emphasized.

Figure 18. Enhanced System Performance with Common Switching Regulators
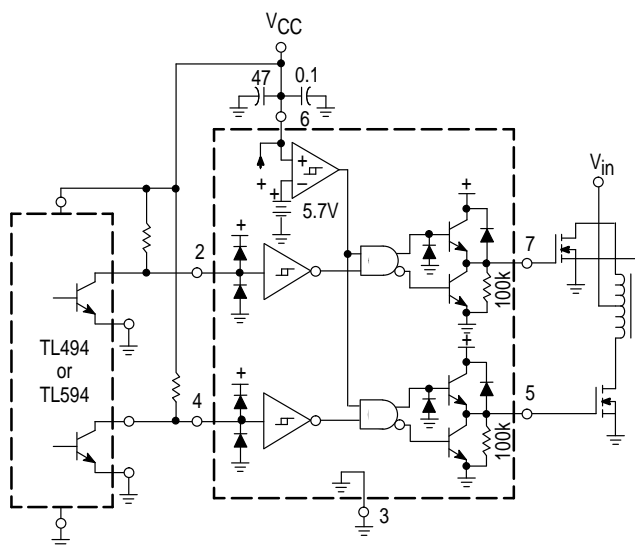
The MC34151 greatly enhances the drive capabilities of common switching regulators and CMOS/TTL logic devices.

Figure 19. MOSFET Parasitic Oscillations
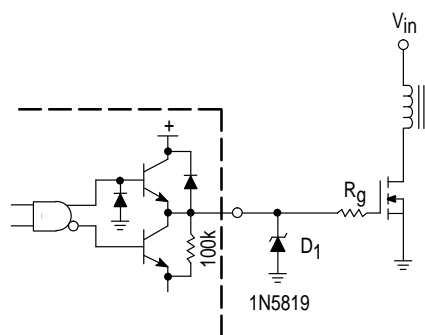
Series gate resistor R_g may be needed to damp high frequency parasitic oscillations caused by the MOSFET input capacitance and any series wiring inductance in the gate–source circuit. R_g will decrease the MOSFET switching speed. Schottky diode D_1 can reduce the driver's power dissipation due to excessive ringing, by preventing the output pin from being driven below ground.

Figure 20. Direct Transformer Drive
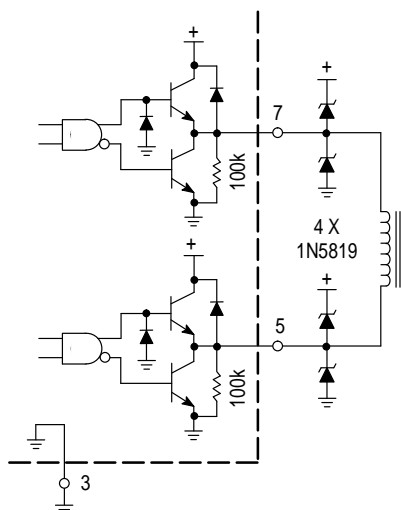
Output Schottky diodes are recommended when driving inductive loads at high frequencies. The diodes reduce the driver's power dissipation by preventing the output pins from being driven above V_{CC} and below ground.
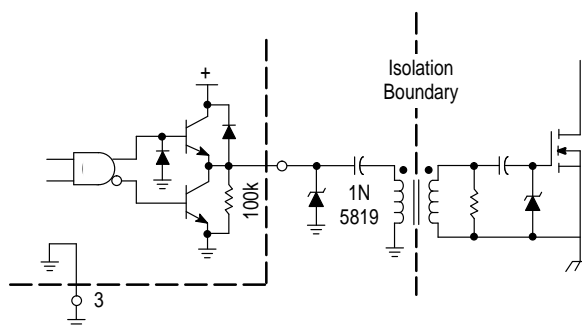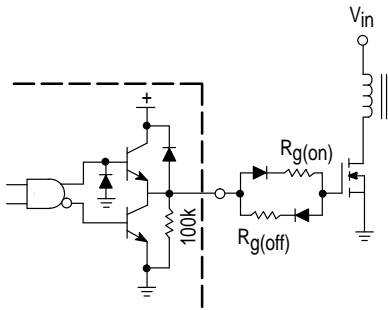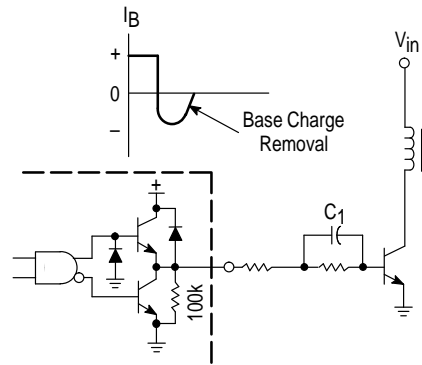
Figure 21. Isolated MOSFET Drive

Figure 22. Controlled MOSFET Drive

In noise sensitive applications, both conducted and radiated EMI can be reduced significantly by controlling the MOSFET's turn–on and turn–off times.

Figure 23. Bipolar Transistor Drive

The totem–pole outputs can furnish negative base current for enhanced transistor turn–off, with the addition of capacitor C_1.
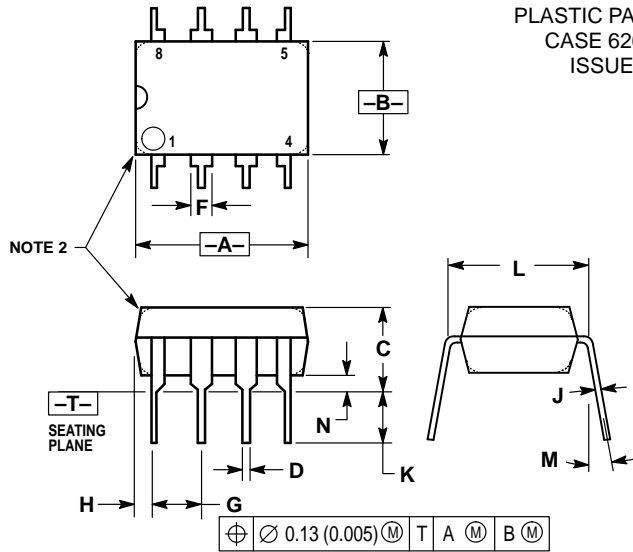
Figure 24. Dual Charge Pump Converter
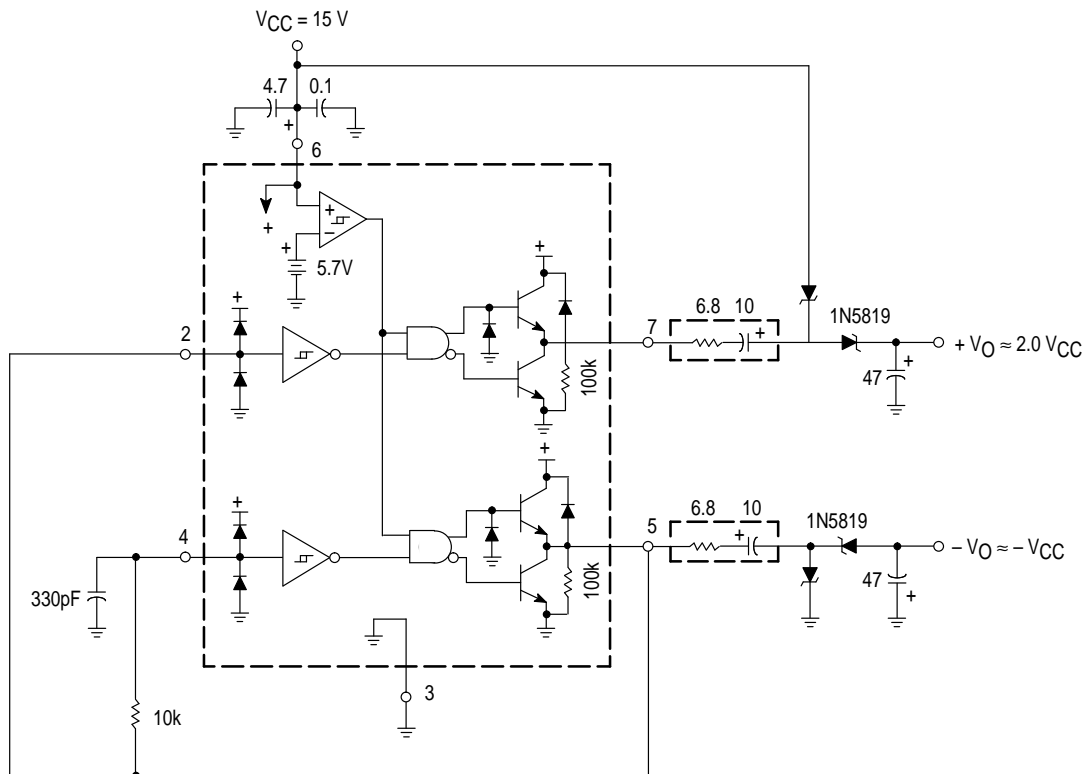
The capacitor's equivalent series resistance limits the Drive Output Current to 1.5 A. An additional series resistor may be required when using tantalum or other low ESR capacitors.

Output Load Regulation		
I_O (mA)	+V_O (V)	−V_O (V)
0	27.7	−13.3
1.0	27.4	−12.9
10	26.4	−11.9
20	25.5	−11.2
30	24.6	−10.5
50	22.6	−9.4

P SUFFIX
PLASTIC PACKAGE
CASE 626–05
ISSUE K

NOTE 2

NOTES:
1. DIMENSION L TO CENTER OF LEAD WHEN FORMED PARALLEL.
2. PACKAGE CONTOUR OPTIONAL (ROUND OR SQUARE CORNERS).
3. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	9.40	10.16	0.370	0.400
B	6.10	6.60	0.240	0.260
C	3.94	4.45	0.155	0.175
D	0.38	0.51	0.015	0.020
F	1.02	1.78	0.040	0.070
G	2.54 BSC		0.100 BSC	
H	0.76	1.27	0.030	0.050
J	0.20	0.30	0.008	0.012
K	2.92	3.43	0.115	0.135
L	7.62 BSC		0.300 BSC	
M	—	10 °	—	10 °
N	0.76	1.01	0.030	0.040

⊕ ⌀ 0.13 (0.005) Ⓜ T A Ⓜ B Ⓜ

D SUFFIX
PLASTIC PACKAGE
CASE 751–05
(SO–8)
ISSUE N
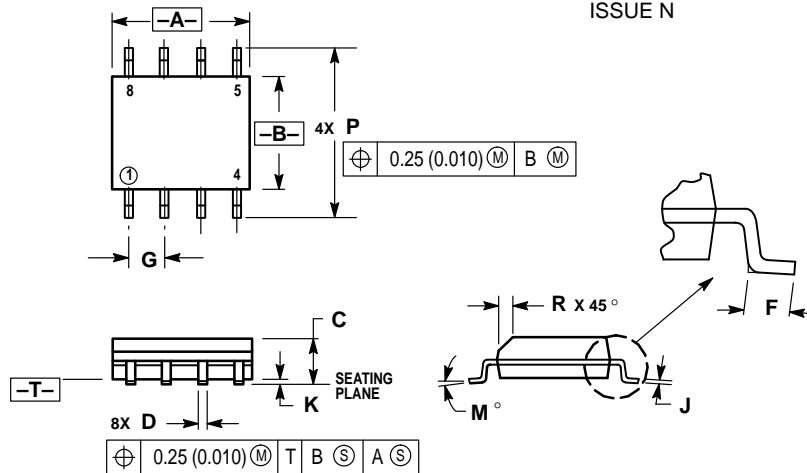
NOTES:
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: MILLIMETER.
3. DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION.
4. MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.
5. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.

4X P ⊕ 0.25 (0.010) Ⓜ B Ⓜ

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	4.80	5.00	0.189	0.196
B	3.80	4.00	0.150	0.157
C	1.35	1.75	0.054	0.068
D	0.35	0.49	0.014	0.019
F	0.40	1.25	0.016	0.049
G	1.27 BSC		0.050 BSC	
J	0.18	0.25	0.007	0.009
K	0.10	0.25	0.004	0.009
M	0 °	7 °	0 °	7 °
P	5.80	6.20	0.229	0.244
R	0.25	0.50	0.010	0.019

⊕ 0.25 (0.010) Ⓜ T B Ⓢ A Ⓢ

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INTERNET: http://Design–NET.com

JAPAN: Nippon Motorola Ltd.; Tatsumi–SPD–JLDC, 6F Seibu–Butsuryu–Center, 3–14–2 Tatsumi Koto–Ku, Tokyo 135, Japan. 03–81–3521–8315

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