

Dear customers,

About the change in the name such as "Oki Electric Industry Co. Ltd." and "OKI" in documents to OKI Semiconductor Co., Ltd.

The semiconductor business of Oki Electric Industry Co., Ltd. was succeeded to OKI Semiconductor Co., Ltd. on October 1, 2008. Therefore, please accept that although the terms and marks of "Oki Electric Industry Co., Ltd.", "Oki Electric", and "OKI" remain in the documents, they all have been changed to "OKI Semiconductor Co., Ltd.". It is a change of the company name, the company trademark, and the logo, etc., and NOT a content change in documents.

October 1, 2008 OKI Semiconductor Co., Ltd.

# OKI SEMICONDUCTOR CO., LTD.

550-1 Higashiasakawa-cho, Hachioji-shi, Tokyo 193-8550, Japan http://www.okisemi.com/en/

# **Preliminary**

This version: Dec. 2001

Dual FIFO (262,214 Words  $\times$  8 Bits)  $\times$  2

#### **GENERAL DESCRIPTION**

The MS8104166 is a single-chip 4Mb FIFO functionally composed of two Oki's 2Mb FIFO (First-In First-Out) memories which were designed for  $256k \times 8$ -bit high-speed asynchronous read/write operation.

The read clock of each of the 2Mb FIFO memories is connected in common, and the clocks are provided independently of each of the FIFO memories. The MS8104166 functionally compatible with Oki's 2Mb FIFO memory (MSM518222A), can be used as a  $\times 16$  configuration FIFO.

The MS8104166 is a field memory for wide or low end use in general commodity TVs and VTRs exclusively and is not designed for high end use in professional graphics systems, which require long term picture storage, data storage, medical use and other storage systems.

The MS8104166 provides independent control clocks to support asynchronous read and write operations. Different clock rates are also supported, which allow alternate data rates between write and read data streams.

The MS8104166 provides high speed FIFO (First-in First-out) operation without external refreshing: MS8104166 refreshes its DRAM storage cells automatically, so that it appears fully static to the users.

Moreover, fully static type memory cells and decoders for serial access enable the refresh free serial access operation, so that serial read and/or write control clock can be halted high or low for any duration as long as the power is on. Internal conflicts of memory access and refreshing operations are prevented by special arbitration logic.

The MS8104166's function is simple, and similar to a digital delay device whose delay-bit-length is easily set by reset timing. The delay length and the number of read delay clocks between write and read, is determined by externally controlled write and read reset timings.

Additional SRAM serial registers, or line buffers for the initial access of  $256 \times 16$ -bit enable high speed first-bit-access with no clock delay just after the write or read reset timings.

The MS8104166, which is provided with two sets of the serial write clocks, allows the split-screen processing to be implemented easily.

Additionally, the MS8104166 has a write mask function or input enable function (IE), and read-data skipping function or output enable function (OE). The differences between write enable (WE) and input enable (IE), and between read enable (RE) and output enable (OE) are that WE and RE can stop serial write/read address increments, but IE and OE cannot stop the increment, when write/read clocking is continuously applied to the MS8104166. The input enable (IE) function allows the user to write into selected locations of the memory only, leaving the rest of the memory contents unchanged. This facilitates data processing to display a "picture in picture" on a TV screen.

# **FEATURES**

•  $512 \text{ rows} \times 512 \text{ columns} \times 8 \text{ bits} \times 2$ 

• Fast FIFO (First-In First-Out) Operation: 25 ns cycle time

• Self refresh (No refresh control is required)

• High speed asynchronous serial access

Read/Write Cycle Time 20 ns/25 ns/30 ns Access Time 20 ns/25 ns/30 ns 18 ns/22 ns/25 ns

• Variable length delay bit (600 to 262215)

• Write mask function (Output enable control)

• Cascading capability by mode setting

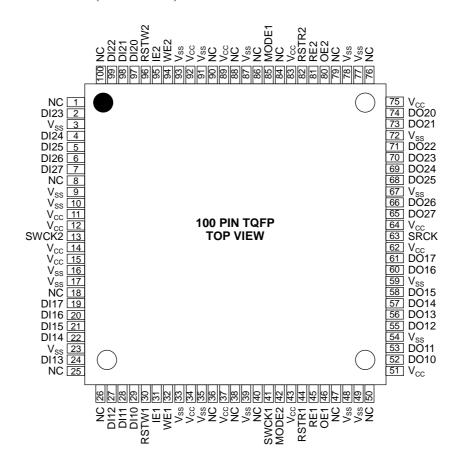
• Single power supply: 5.0 V ±10%

• Package:

100-Pin plastic TQFP (TQFP 100-P-1414-0.50-k) (Product: MS8104166-xxTB) xx indicates speed rank.

Parameter	Cumbal	MS8104166-xxTB			
- Farameter	Symbol	-20	-25	-30	
Access Time	t <sub>AC</sub>	18 ns	22 ns	25 ns	
Read/Write	t <sub>swc</sub>	20 ns	25 ns	20 50	
Cycle Time	t <sub>SRC</sub>	20 115	25 115	30 ns	
Operation current	I <sub>CC1</sub>	170 mA	150 mA	120 mA	
Standby current	I <sub>CC2</sub>	5 mA	5 mA	5 mA	

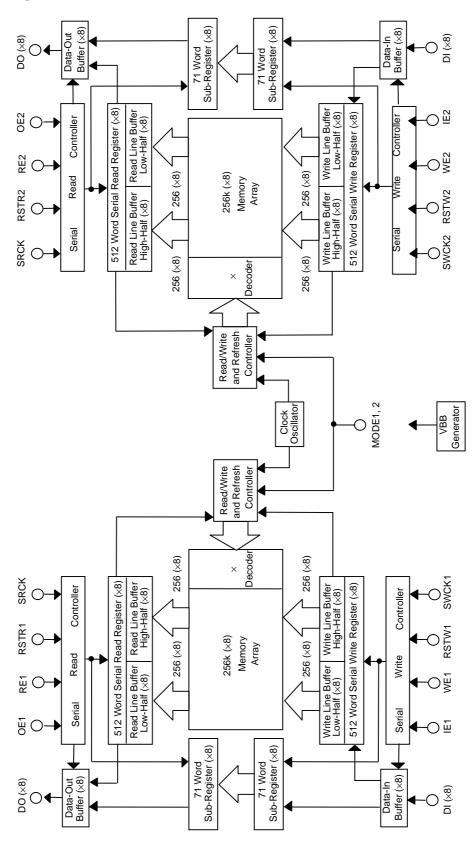
# PIN CONFIGURATION (TOP VIEW)



Pin Name	Function	Pin Name	Function
SWCK1	Port1 Serial Write clock	SRCK	Serial Read Clock
SWCK2	Port2 Serial Write clock	WE2	Port2 Write Enable
WE1	Port1 Write Enable	RE2	Port2 Read Enable
RE1	Port1 Read Enable	IE2	Port2 Input Enable
IE1	Port1 Input Enable	OE2	Port2 Output Enable
OE1	Port1 Output Enable	RSTW2	Port2 Reset Write
RSTW1	Port1 Reset Write	RSTR2	Port2 Reset Read
RSTR1	Port1 Reset Read	DI20 to 27	Port2 Data Input
DI10 to 17	Port1 Data Input	DO20 to 27	Port2 Data Output
DO10 to 17	Port1 Data Output	NC	No Connection
MODE1, 2	Mode Input	$V_{ss}$	Ground (0 V)
V <sub>cc</sub>	Power Supply (5.0 V)		

Note: The same power supply voltage must be provided to every  $V_{\text{CC}}$  pin, and the same GND voltage level must be provided to every  $V_{\text{SS}}$  pin.

# **BLOCK DIAGRAM**



#### PIN DESCRIPTION

# Data Inputs: (DIN10 to 17)

These pins are used for serial data inputs.

#### Write Reset: RSTW1

The first positive transition of SWCK after RSTW becomes high resets the write address pointers to zero. RSTW1 setup and hold times are referenced to the rising edge of SWCK. Because the write reset function is solely controlled by the SWCK rising edge after the high level of RSTW, the states of WE1 and IE1 are ignored in the write reset cycle. Before RSTW1 may be brought high again for a further reset operation, it must be low for at least two SWCK cycles.

#### Write Enable: WE1

WE1 is used for data write enable/disable control. WE1 high level enables the input, and WE1 low level disables the input and holds the internal write address pointer. There are no WE1 disable time (low) and WE1 enable time (high) restrictions, because the MS8104166 is in fully static operation as long as the power is on. Note that WE1 setup and hold times are referenced to the rising edge of SWCK.

## **Input Enable: IE1**

IE1 is used to enable/disable writing into memory. IE1 high level enables writing. The internal write address pointer is always incremented by cycling SWCK regardless of the IE1 level. Note that IE1 setup and hold times are referenced to the rising edge of SWCK.

# Data Out: (DOUT0 to 11)

These pins are used for serial data outputs.

# Read Reset: RSTR1

The first positive transition of SRCK after RSTR1 becomes high resets the read address pointers to zero. RSTR1 setup and hold times are referenced to the rising edge of SRCK. Because the read reset function is solely controlled by the SRCK rising edge after the high level of RSTR, the states of RE1 and OE1 are ignored in the read reset cycle. Before RSTR may be brought high again for a further reset operation, it must be low for at least \*two SRCK cycles.

#### Read Enable: RE1

The function of RE1 is to gate of the SRCK clock for incrementing the read pointer. When RE1 is high before the rising edge of SRCK, the read pointer is incremented. When RE1 is low, the read pointer is not incremented. RE1 setup times ( $t_{RENS}$  and  $t_{RDSS}$ ) and RE1 hold times ( $t_{RENH}$  and  $t_{RDSH}$ ) are referenced to the rising edge of the SRCK clock.

#### **Output Enable: OE1**

OE1 is used to enable/disable the outputs. OE1 high level enables the outputs. The internal read address pointer is always incremented by cycling SRCK regardless of the OE1 level. Note that OE1 setup and hold times are referenced to the rising edge of SRCK.

# Serial Write: Clock SWCK1

The SWCK1 latches the input data on chip when WE1 and IE1 are high, and also increments the internal write address pointer when WE1 is high. Data-in setup time  $t_{DS}$ , and hold time  $t_{DH}$  are referenced to the rising edge of SWCK1.

## Serial Write Clock: SWCK2

The SWCK2 latches the input data on chip when WE2 and IE2 are high, and also increments the internal write address pointer when WE2 is high, Data-in setup time  $t_{DS}$  and hold time  $t_{DH}$  are referenced to the rising edge of SWCK2.

#### Serial Read Clock: SRCK

Data is shifted out of the data registers. It is triggered by the rising edge of SRCK when RE1, 2 is high during a read operation. The SRCK input increments the internal read address pointer when RE1, 2 is high.

The three-state output buffer provides direct TTL compatibility (no pullup resistor required). Data out is the same polarity as data in. The output becomes valid after the access time interval  $t_{AC}$  that begins with the rising edge of SRCK. \*There are no output valid time restriction on MS8104166.

# Data Input: (DIN20 to 27)

These pins are used for serial data inputs.

#### Write Reset: RSTW2

The first positive transition of SWCK after RSTW becomes high resets the write address pointers to zero. RSTW2 setup and hold times are referenced to the rising edge of SWCK. Because the write reset function is solely controlled by the SWCK rising edge after the high level of RSTW2, the states of WE2 and IE2 are ignored in the write reset cycle. Before RSTW2 may be brought high again for a further reset operation, it must be low for at least two SWCK cycles.

#### Write Enable: WE2

WE is used for data write enable/disable control. WE2 high level enables the input, and WE2 low level disables the input and holds the internal write address pointer. There are no WE2 disable time (low) and WE2 enable time (high) restrictions, because the MS8104166 is in fully static operation as long as the power is on. Note that WE2 setup and hold times are referenced to the rising edge of SWCK.

#### **Input Enable: IE2**

IE2 is used to enable/disable writing into memory. IE2 high level enables writing. The internal write address pointer is always incremented by cycling SWCK regardless of the IE2 level. Note that IE2 setup and hold times are referenced to the rising edge of SWCK.

#### Data Out: (DOUT20 to 27)

These pins are used for serial data outputs.

# Read Reset: RSTR2

The first positive transition of SRCK after RSTR2 becomes high resets the read address pointers to zero. RSTR2 setup and hold times are referenced to the rising edge of SRCK. Because the read reset function is solely controlled by the SRCK rising edge after the high level of RSTR2, the states of RE2 and OE2 are ignored in the read reset cycle. Before RSTR2 may be brought high again for a further reset operation, it must be low for at least \*two SRCK cycles.

## **Output Enable: OE2**

OE2 is used to enable/disable the outputs. OE2 high level enables the outputs. The internal read address pointer is always incremented by cycling SRCK regardless of the OE2 level. Note that OE2 setup and hold times are referenced to the rising edge of SRCK.

# **Mode Setting: MODE1**

The Cascade/Non cascade select pin. Setting the MODE1 pin to the  $V_{\text{CC}}$  level configures this memory device as cascade type and setting the pin to the  $V_{\text{SS}}$  level configures this memory device as non cascade. During memory operation, the pin must be permanently connected to  $V_{\text{CC}}$  or  $V_{\text{SS}}$ . If a MODE1 level is changed during memory operation, memory data is not guaranteed.

# Note: Cascade/Non cascade

When MODE1 is set to the  $V_{SS}$  level, memory accessing starts in the cycle in which the control signals are input (Non cascade type). When MODE1 is set to the  $V_{CC}$  level, memory accessing starts in the cycle subsequent to the cycle in which the control signals are input (Cascade type). This type is used for consecutive memory accessing.

# **MODE Setting: MODE2**

The boost control pin for data-out Buffer. For the MS8104166, the MODE2 pin should be permanently connected to the  $V_{SS}$  level. For the MS8104166, the MODE2 pin should be permanently connected to the  $V_{CC}$  level.

# **ELECTRICAL CHARACTERISTICS**

# **Absolute Maximum Ratings**

Parameter	Symbol	Condition	Rating	Unit
Input Output Voltage	$V_{T}$	at Ta = 25°C, V <sub>SS</sub>	-1.0 to +7.0	V
Output Current	I <sub>os</sub>	Ta = 25°C	50	mA
Power Dissipation	$P_{D}$	Ta = 25°C	1	W
Operating Temperature	T <sub>OPR</sub>	_	0 to 70	°C
Storage Temperature	T <sub>STG</sub>	_	-55 to +150	°C

# **Recommended Operating Conditions**

Parameter	Symbol	Min.	Тур.	Max.	Unit
Power Supply Voltage	V <sub>cc</sub>	4.5	5.0	5.5	V
Power Supply Voltage	V <sub>ss</sub>	0	0	0	V
Input High Voltage	V <sub>IH</sub>	2.4	V <sub>cc</sub>	V <sub>cc</sub> + 1.0	V
Input Low Voltage	V <sub>IL</sub>	-0.3	0	0.8	V

# **DC** Characteristics

Parameter	Symbol	Condition	Min.	Max.	Unit
Input Leakage Current	I <sub>LI</sub>	$0 < V_I < V_{CC}$ , Other input pins at $V = 0 V$	-10	10	μΑ
Output Leakage Current	I <sub>LO</sub>	0 <v<sub>o<v<sub>cc</v<sub></v<sub>	-10	10	μΑ
Output "H" Level Voltage	V <sub>OH</sub>	$I_{OH} = -1 \text{ mA}$	2.4	_	V
Output "L" Level Voltage	V <sub>OL</sub>	I <sub>OL</sub> = 2 mA	_	0.4	V
Operating Current	I <sub>CC1</sub>	Minimum Cycle Time, Output Open	_	170	mA
Standby Current	I <sub>CC2</sub>	Input Pin = V <sub>IH</sub> /V <sub>IL</sub>	_	5	mA

# Capacitance

 $(Ta = 25^{\circ}C, f = 1 MHz)$ 

Parameter	Symbol	Max.	Unit
Input Capacitance (D <sub>I</sub> , SWCK, SRCK, RSTW, RSTR, WE, RE, IE, OE)	Cı	7	рF
Output Capacitance (D <sub>O</sub> )	Co	7	pF

# **AC Characteristics**

 $(V_{CC} = 5.0 \pm 0.5 \text{ V}, \text{Ta} = 0 \text{ to } 70^{\circ}\text{C})$ 

		MS8104	166-20	MS810	4166-25		4166-30	T 0 0,
Parameter	Symbol	Min.	Max.	Min.	Max.	Min.	Max.	Unit
Access Time from SRCK	t <sub>AC</sub>		18		22		25	ns
D <sub>OUT</sub> Hold Time from SRCK	t <sub>DDCK</sub>	6		6		6		ns
D <sub>OUT</sub> Enable Time from SRCK		6	18	6	22	6	25	ns
SWCK "H" Pulse Width	t <sub>DECK</sub>	10	—	12	_	15	_	ns
SWCK "L" Pulse Width	t <sub>WSWH</sub>	10		12		15	_	ns
Input Data Setup Time	t <sub>WSWL</sub>	3		3		5	_	ns
Input Data Hold Time	t <sub>DS</sub>	5		5		5		ns
WE Enable Setup Time		5	_	5	_	5	_	ns
WE Enable Hold Time	t <sub>WENS</sub>	5		5		5		ns
WE Disable Setup Time	t <sub>WENH</sub>	5		5		5		ns
WE Disable Setup Time WE Disable Hold Time	t <sub>WDSS</sub>	5		5		5		ns
IE Enable Setup Time	t <sub>WDSH</sub>	5		5		5		+
IE Enable Hold Time	t <sub>IENS</sub>	5	_	5		5	_	ns
•	t <sub>IENH</sub>	5				_	_	ns
IE Disable Setup Time IE Disable Hold Time	t <sub>IDSS</sub>	5	_	5		5	_	ns
	t <sub>IDSH</sub>		_	5	_	5	_	ns
WE "H" Pulse Width	t <sub>wweh</sub>	5	_	5	_	10	_	ns
WE "L" Pulse Width	t <sub>wwel</sub>	5	_	5	_	10	_	ns
IE "H" Pulse Width	t <sub>WIEH</sub>	5		5		10		ns
IE "L" Pulse Width	t <sub>WIEL</sub>	5		5		10	_	ns
RSTW Setup Time	t <sub>RSTWS</sub>	3	_	3	_	3	_	ns
RSTW Hold Time	t <sub>RSTWH</sub>	5	_	10	_	10	_	ns
SRCK "H" Pulse Width	t <sub>WSRH</sub>	10	_	12		15		ns
SRCK "L" Pulse Width	t <sub>WSRL</sub>	10	_	12		15		ns
RE Enable Setup Time	t <sub>RENS</sub>	5	_	5	_	5	_	ns
RE Enable Hold Time	t <sub>RENH</sub>	5	_	5	_	5	_	ns
RE Disable Setup Time	t <sub>RDSS</sub>	5	_	5	_	5	_	ns
RE Disable Hold Time	t <sub>RDSH</sub>	5		5	_	5	_	ns
OE Enable Setup Time	t <sub>OENS</sub>	5		5	_	5	_	ns
OE Enable Hold Time	t <sub>OENH</sub>	5	_	5		5	_	ns
OE Disable Setup Time	t <sub>ODSS</sub>	5	_	5	_	5	_	ns
OE Disable Hold Time	t <sub>odsh</sub>	5	_	5	_	5	_	ns
RE "H" Pulse Width	t <sub>WREH</sub>	5	_	5	_	10	_	ns
RE "L" Pulse Width	t <sub>WREL</sub>	5	_	5	_	10	_	ns
OE "H" Pulse Width	t <sub>WOEH</sub>	5	_	5	_	10	_	ns
OE "L" Pulse Width	t <sub>WOEL</sub>	5	_	5	_	10		ns
RSTR Setup Time	t <sub>RSTRS</sub>	3	_	3	_	3	_	ns
RSTR Hold Time	t <sub>RSTRH</sub>	5		10		10		ns
SWCK Cycle Time	t <sub>swc</sub>	20	_	25	_	30	_	ns
SRCK Cycle Time	t <sub>SRC</sub>	20	_	25	_	30	_	ns
Transition Time (Rise and Fall)	t <sub>T</sub>	3	30	3	30	3	30	ns

- 1. Input signal reference levels for the parameter measurement are  $V_{IH} = 3.0 \text{ V}$  and  $V_{IL} = 0 \text{ V}$ . The transition time  $t_T$  is defined to be a transition time that signal transfers between  $V_{IH} = 3.0 \text{ V}$  and  $V_{IL} = 0 \text{ V}$ .
- 2. AC measurements assume  $t_T = 3$  ns.
- 3. Read address must have more than a 600 address delay than write address in every cycle when asynchronous read/write is performed.
- 4. Read must have more than a 600 address delay than write in order to read the data written in a current series of write cycles which has been started at last write reset cycle: this is called "new data read". When read has less than a 70 address delay than write, the read data are the data written in a previous series of write cycles which had been written before at last write reset cycle: this is called "old data read".
- 5. When the read address delay is between more than 71 and less than 599 or more than 262,214, read data will be undetermined. However, normal write is achieved in this address condition.
- 6. Outputs are measured with a load equivalent to 1 TTL load and 30 pF. Output reference levels are  $V_{OH} = 1.5 \text{ V}$  and  $V_{OL} = 1.5 \text{ V}$ .

#### **OPERATION MODE**

# Write Operation Cycle (MODE2 = $V_{SS}$ )

The write operation is controlled by seven control signals, SWCK1, RSTW1, RSTW2, WE1, WE2 and IE1, IE2. Port1 write operation is accomplished by cycling SWCK1, and holding WE1 high after the write address pointer reset operation or RSTW1. RSTW1 must be preformed for internal circuit initialization before Write operation. Each write operation, which begins after RSTW1, must contain at least 80 active write cycles, i.e. SWCK1 cycles while WE1 and IE1 are high. To transfer the last data to the DRAM array, which at that time is stored in the serial data registers attached to the DRAM array, an RSTW1 operation is required after the last SWCK1 cycle.

Note that every write timing of the MS8104166 is delayed by one clock compared with read timings for easy cascading without any interface delay devices.

Setting MODE1 to the V<sub>ss</sub> level starts write data accessing in the cycle in which RSTW1, WE1, and IE1 control signals are input.

Setting MODE1 to the  $V_{CC}$  level starts write data accessing in the cycle subsequent to the cycle in which RSTW1, WE1, and IE1 control signals are input.

These operation are the same for Port1 and Port2.

Settings of WE1, 2 and IE1, 2 to the operation mode of Write address pointer and Data input.

WE1, 2	IE1, 2	Internal Write address pointer	Data input
Н	Н	Incremented	Input
Н	L	Incremented	Not innet
L	Х	Halted	Not input

X indicates "don't care"

## **Read Operation Cycle**

The read operation is controlled by seven control signals, SRCK, RSTR1, RSTR2, RE1, RE2, and OE1, OE2. Port1 read operation is accomplished by cycling SRCK, and holding both RE1 and OE1 high after the read address pointer reset operation or RSTR1.

Each read operation, which begins after RSTR1, must contain at least 80 active read cycles, i.e. SRCK cycles while RE1 and OE1 are high.

These operations are the same for Port1 and Port2.

Settings of RE1, 2 and OE1, 2 to the operation mode of read address pointer and Data output.

WE1, 2	IE1, 2	Internal Write address pointer	Data output
Н	Н	In a way a material	Output
Н	L	Incremented	High impedance
L	Х	Halted	Output
L	L	папес	High impedance

#### **Power-up and Initialization**

On power-up, the device is designed to begin proper operation after at least  $100~\mu s$  after  $V_{CC}$  has stabilized to a value within the range of recommended operating conditions. After this  $100~\mu s$  stabilization interval, the following initialization sequence must be performed.

Because the read and write address pointers are undefined after power-up, a minimum of 80 dummy write operations (SWCK cycles) and read operations (SRCK cycles) must be performed, followed by an RSTW1, 2 operation and an RSTR1, 2 operation, to properly initialize the write and the read address pointer. Dummy write cycles/RSTW1, 2 and dummy read cycles/RSTR1, 2 may occur simultaneously.

If these dummy read and write operations start while  $V_{CC}$  and/or the substrate voltage has not stabilized, it is necessary to perform an RSTR1, 2 operation plus a minimum of 80 SRCK cycles plus another RSTR1, 2 operation, and an RSTW1, 2 operation plus a minimum of 80 SWCK cycles plus another RSTW1, 2 operation to properly initialize read and write address pointers.

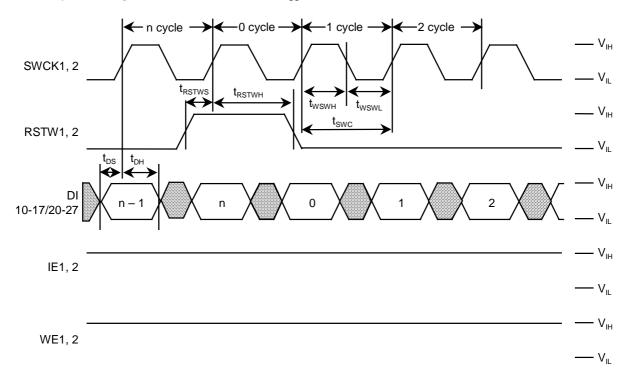
#### **Old/New Data Access**

There must be a minimum delay of 600 SWCK cycles between writing into memory and reading out from memory. If reading from the first field starts with an RSTR1, 2 operation, before the start of writing the second field (before the next RSTW1, 2 operation), then the data just written will be read out.

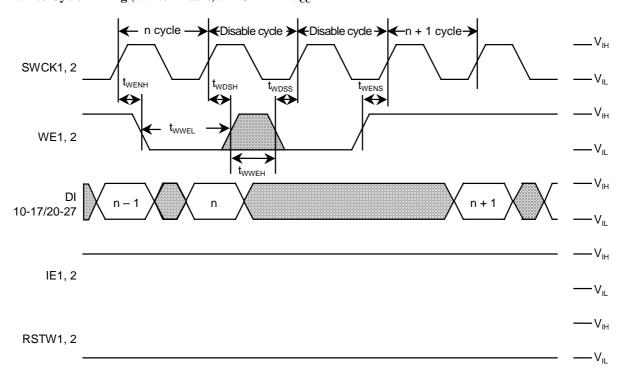
The start of reading out the first field of data may be delayed past the beginning of writing in the second field of data for as many as 70 SWCK cycles. If the RSTR1, 2 operation for the first field read-out occurs less than 70 SWCK cycles after the RSTW1, 2 operation for the second field write-in, then the internal buffering of the device assures that the first field will still be read out. The first field of data that is read out while the second field of data is written is called "old data". In order to read out "new data", i.e., the second field written in, the delay between an RSTW1, 2 operation and an RSTR1, 2 operation must be at least 600 SRCK cycles. If the delay between RSTW1, 2 and RSTR1, 2 operations is more than 71 but less than 600 cycles, then the data read out will be undetermined. It may be "old data" or "new data", or a combination of old and new data. Such a timing should be avoided.

# TIMING WAVEFORM

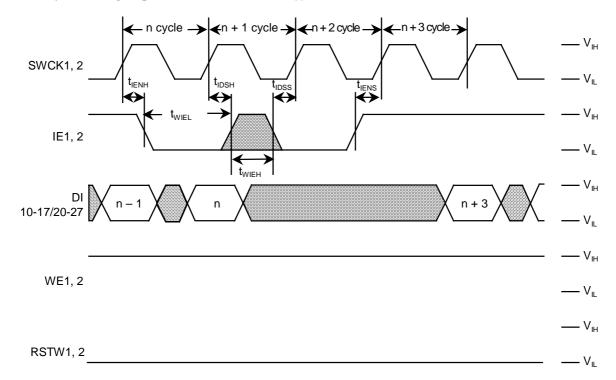
# Write Cycle Timing (Write Reset): MODE1 = $V_{CC}$



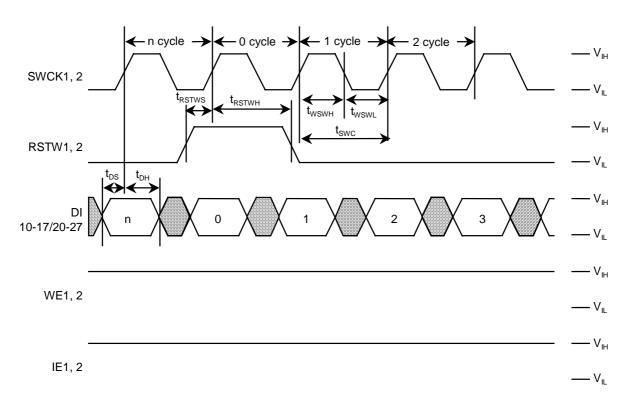
# Write Cycle Timing (Write Enable): $MODE1 = V_{CC}$



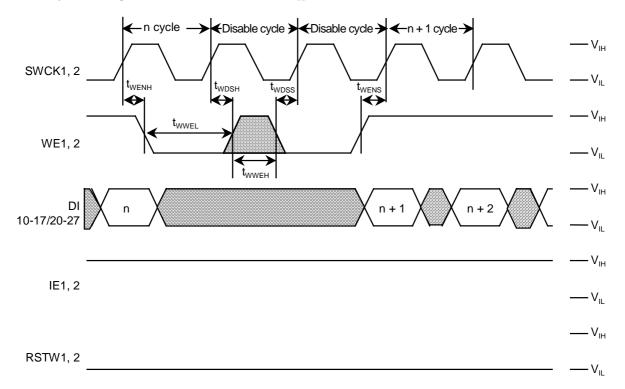
# Write Cycle Timing (Input Enable): $MODE1 = V_{CC}$



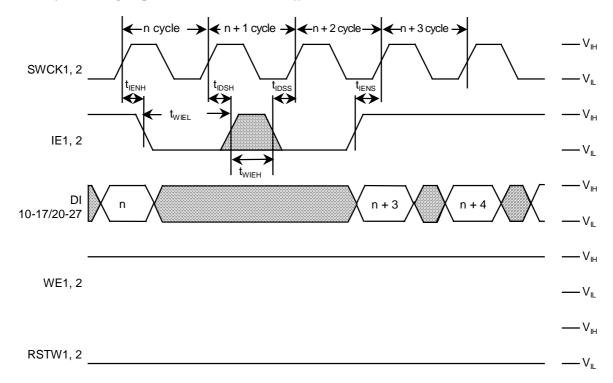
# Write Cycle Timing (Write Reset): $MODE1 = V_{SS}$



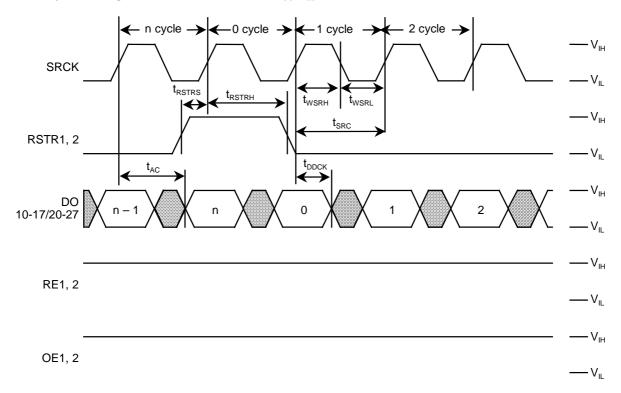
# Write Cycle Timing (Write Enable): $MODE1 = V_{SS}$



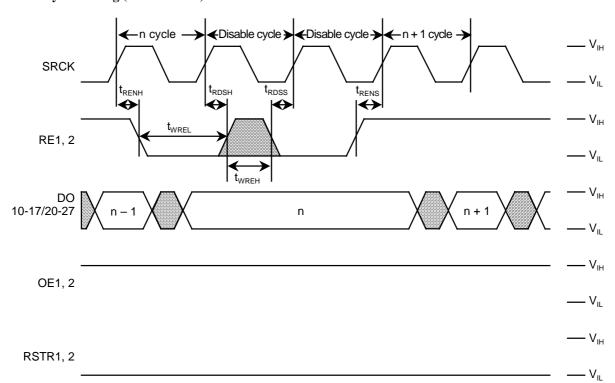
# Write Cycle Timing (Input Enable): $MODE1 = V_{SS}$



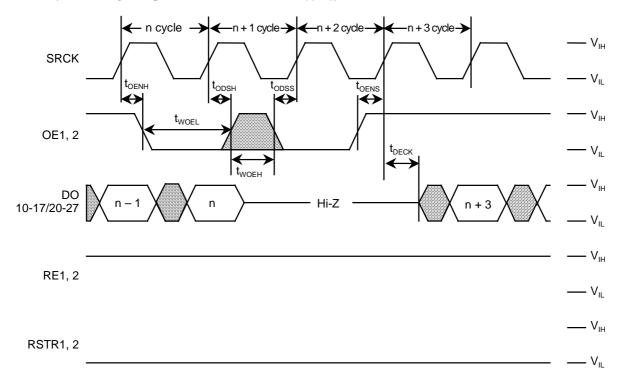
# Read Cycle Timing (Read Reset): MODE1 = $V_{CC}/V_{SS}$



# **Read Cycle Timing (Read Enable): MODE1 = Vcc/Vss**

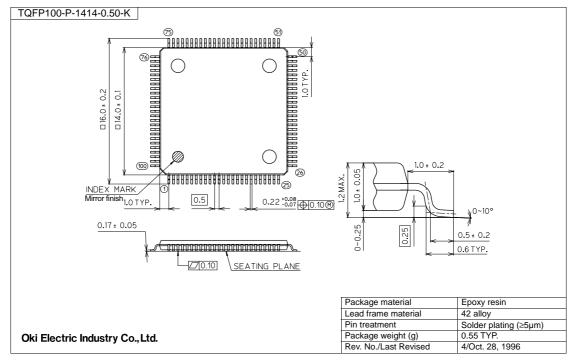


# Read Cycle Timing (Output Enable): MODE1 = $V_{CC}/V_{SS}$



#### PACKAGE DIMENSIONS

(Unit: mm)



Notes for Mounting the Surface Mount Type Package

The surface mount type packages are very susceptible to heat in reflow mounting and humidity absorbed in storage.

Therefore, before you perform reflow mounting, contact Oki's responsible sales person for the product name, package name, pin number, package code and desired mounting conditions (reflow method, temperature and times).

#### **NOTICE**

- 1. The information contained herein can change without notice owing to product and/or technical improvements. Before using the product, please make sure that the information being referred to is up-to-date.
- 2. The outline of action and examples for application circuits described herein have been chosen as an explanation for the standard action and performance of the product. When planning to use the product, please ensure that the external conditions are reflected in the actual circuit, assembly, and program designs.
- 3. When designing your product, please use our product below the specified maximum ratings and within the specified operating ranges including, but not limited to, operating voltage, power dissipation, and operating temperature.
- 4. Oki assumes no responsibility or liability whatsoever for any failure or unusual or unexpected operation resulting from misuse, neglect, improper installation, repair, alteration or accident, improper handling, or unusual physical or electrical stress including, but not limited to, exposure to parameters beyond the specified maximum ratings or operation outside the specified operating range.
- 5. Neither indemnity against nor license of a third party's industrial and intellectual property right, etc. is granted by us in connection with the use of the product and/or the information and drawings contained herein. No responsibility is assumed by us for any infringement of a third party's right which may result from the use thereof.
- 6. The products listed in this document are intended for use in general electronics equipment for commercial applications (e.g., office automation, communication equipment, measurement equipment, consumer electronics, etc.). These products are not authorized for use in any system or application that requires special or enhanced quality and reliability characteristics nor in any system or application where the failure of such system or application may result in the loss or damage of property, or death or injury to humans. Such applications include, but are not limited to, traffic and automotive equipment, safety devices, aerospace equipment, nuclear power control, medical equipment, and life-support systems.
- 7. Certain products in this document may need government approval before they can be exported to particular countries. The purchaser assumes the responsibility of determining the legality of export of these products and will take appropriate and necessary steps at their own expense for these.
- 8. No part of the contents contained herein may be reprinted or reproduced without our prior permission.

Copyright 2001 Oki Electric Industry Co., Ltd.