# RENESAS 2-Output 1.8V PCIe Gen1/2/3 Zero Delay / Fanout Buffer with Zo=100ohms

DATASHEET

### **Description**

The 9DBV0241 is a member of IDT's 1.8V Very-Low-Power (VLP) PCIe family. The device has 2 output enables for clock management.

### **Recommended Application**

1.8V PCIe Gen1/2/3 Zero-Delay/Fan-out Buffer (ZDB/FOB)

### **Output Features**

2 - 1-200MHz Low-Power (LP) HCSL DIF pairs w/Zo=100Ω

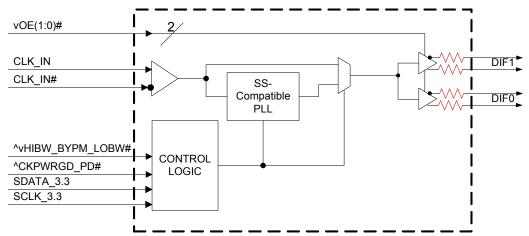
### **Key Specifications**

- DIF cycle-to-cycle jitter <50ps
- DIF output-to-output skew <50ps</li>
- DIF additive phase jitter is <100fs rms for PCle Gen3</li>
- DIF additive phase jitter <300fs rms (12k-20MHz)

#### Features/Benefits

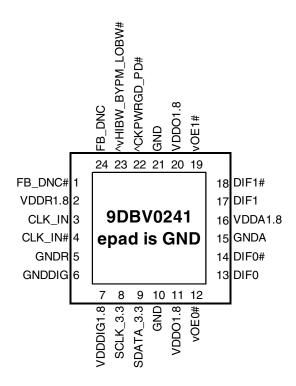
- LP-HCSL outputs with Zo=100Ω; saves 8 resistors compared to standard HCSL outputs
- 35mW typical power consumption in PLL mode; reduced thermal concerns
- Spread Spectrum (SS) compatible; allows use of SS for EMI reduction
- OE# pins; support DIF power management
- HCSL compatible differential input; can be driven by common clock sources
- SMBus-selectable features; optimize signal integrity to application
  - slew rate for each output
  - differential output amplitude
- Pin/software selectable PLL bandwidth and PLL Bypass; optimize PLL to application
- Outputs blocked until PLL is locked; clean system start-up
- · Device contains default configuration; SMBus interface not required for device control
- 3.3V tolerant SMBus interface; works with legacy controllers
- Space saving 24-pin 4x4mm VFQFPN; minimal board space

### **Block Diagram**





### **Pin Configuration**



#### 24-pin VFQFPN, 4x4 mm, 0.5mm pitch

^ prefix indicates internal 120KOhm pull up resistor ^v prefix indicates internal 120KOhm pull up AND pull down resistor (biased to VDD/2) v prefix indicates internal 120KOhm pull down resistor

#### **Power Management Table**

CKPWRGD PD#	CLK IN	SMBus	OEx# Pin	DIF	PLL	
CKFWKGD_FD#	CLK_III	OEx bit	OLX# FIII	True O/P	O/P Comp. O/P	
0	X	Х	X	Low	Low	Off
1	Running	0	Х	Low	Low	On <sup>1</sup>
1	Running	1	0	Running	Running	On <sup>1</sup>
1	Running	1	1	Low	Low	On <sup>1</sup>

<sup>1.</sup> If Bypass mode is selected, the PLL will be off, and outputs will be running.

#### **Power Connections**

Pin Numb	Pin Number					
VDD	GND	Description				
2	5	Input receiver analog				
7	6	Digital Power				
11,20	10,21	DIF outputs				
16	15	PLL Analog				

#### **Frequency Select Table**

FSEL	CLK_IN	DIFx
Byte3 [4:3]	(MHz)	(MHz)
00 (Default)	100.00	CLK_IN
01	50.00	CLK_IN
10	125.00	CLK_IN
11	Reserved	Reserved

#### **PLL Operating Mode**

		Byte1 [7:6]	Byte1 [4:3]
HiBW_BypM_LoBW#	MODE	Readback	Control
0	PLL Lo BW	00	00
M	Bypass	01	01
1	PLL Hi BW	11	11

#### **SMBus Address**

Address	+ Read/Write bit
1101101	Х



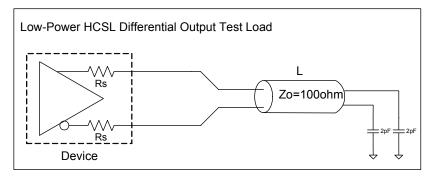
# **Pin Descriptions**

Pin#	Pin Name	Туре	Pin Description
1	FB_DNC#	DNC	Complement clock of differential feedback. The feedback output and feedback input are connected internally on this pin. Do not
2	VDDR1.8	PWR	connect anything to this pin.  1.8V power for differential input clock (receiver). This VDD should be treated as an Analog power rail and filtered appropriately.
3	CLK_IN	IN	True Input for differential reference clock.
4	CLK_IN#	IN	Complementary Input for differential reference clock.
5	GNDR	GND	Analog Ground pin for the differential input (receiver)
6	GNDDIG	GND	Ground pin for digital circuitry
7	VDDDIG1.8	PWR	1.8V digital power (dirty power)
8	SCLK_3.3	IN	Clock pin of SMBus circuitry, 3.3V tolerant.
9	SDATA 3.3	I/O	Data pin for SMBus circuitry, 3.3V tolerant.
10	GND	GND	Ground pin.
11	VDDO1.8	PWR	Power supply for outputs, nominally 1.8V.
			Active low input for enabling DIF pair 0. This pin has an internal pull-
12	vOE0#	IN	down.
			1 =disable outputs, 0 = enable outputs
13	DIF0	OUT	Differential true clock output
14	DIF0#	OUT	Differential Complementary clock output
15	GNDA	GND	Ground pin for the PLL core.
16	VDDA1.8	PWR	1.8V power for the PLL core.
17	DIF1	OUT	Differential true clock output
18	DIF1#	OUT	Differential Complementary clock output
19	vOE1#	IN	Active low input for enabling DIF pair 1. This pin has an internal pull-down.  1 =disable outputs, 0 = enable outputs
20	VDDO1.8	PWR	Power supply for outputs, nominally 1.8V.
21	GND	GND	Ground pin.
22	^CKPWRGD_PD#	IN	Input notifies device to sample latched inputs and start up on first high assertion. Low enters Power Down Mode, subsequent high assertions exit Power Down Mode. This pin has internal pull-up resistor.
23	^vHIBW_BYPM_LOBW#	LATCHED IN	Trilevel input to select High BW, Bypass or Low BW mode. This pin is biased to VDD/2 (Bypass mode) with internal pull up/pull down resistors. See PLL Operating Mode Table for Details.
24	FB_DNC	DNC	True clock of differential feedback. The feedback output and feedback input are connected internally on this pin. Do not connect anything to this pin.
25	epad	GND	GND

NOTE: DNC indicates Do Not Connect anything to this pin.



### **Test Loads**



L = 5 inches

### **Alternate Terminations**

The 9DBV family can easily drive LVPECL, LVDS, and CML logic. See <u>"AN-891 Driving LVPECL, LVDS, and CML Logic with IDT's "Universal" Low-Power HCSL Outputs"</u> for details.



### **Absolute Maximum Ratings**

Stresses above the ratings listed below can cause permanent damage to the 9DBV0241. These ratings, which are standard values for IDT commercially rated parts, are stress ratings only. Functional operation of the device at these or any other conditions above those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods can affect product reliability. Electrical parameters are guaranteed only over the recommended operating temperature range.

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
1.8V Supply Voltage	VDDxx	Applies to all VDD pins	-0.5		2.5	V	1,2
Input Voltage	$V_{IN}$		-0.5		$V_{DD} + 0.5V$	٧	1, 3
Input High Voltage, SMBus	$V_{IHSMB}$	SMBus clock and data pins			3.6V	V	1
Storage Temperature	Ts		-65		150	°C	1
Junction Temperature	Tj				125	°C	1
Input ESD protection	ESD prot	Human Body Model	2000			V	1

<sup>&</sup>lt;sup>1</sup>Guaranteed by design and characterization, not 100% tested in production.

### **Electrical Characteristics-Clock Input Parameters**

TA = T<sub>COM</sub> or T<sub>IND:</sub> Supply Voltage per VDD of normal operation conditions, See Test Loads for Loading Conditions

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PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Input Common Mode Voltage - DIF_IN	V <sub>COM</sub>	Common Mode Input Voltage	150		1000	mV	1
Input Swing - DIF_IN	V <sub>SWING</sub>	Differential value	300		1450	mV	1
Input Slew Rate - DIF_IN	dv/dt	Measured differentially	0.4		8	V/ns	1,2
Input Leakage Current	I <sub>IN</sub>	$V_{IN} = V_{DD}$ , $V_{IN} = GND$	-5		5	uA	
Input Duty Cycle	d <sub>tin</sub>	Measurement from differential wavefrom	45		55	%	1
Input Jitter - Cycle to Cycle	$J_{DIFIn}$	Differential Measurement	0		125	ps	1

<sup>&</sup>lt;sup>1</sup> Guaranteed by design and characterization, not 100% tested in production.

<sup>&</sup>lt;sup>2</sup> Operation under these conditions is neither implied nor guaranteed.

<sup>&</sup>lt;sup>3</sup> Not to exceed 2.5V.

<sup>&</sup>lt;sup>2</sup>Slew rate measured through +/-75mV window centered around differential zero



# Electrical Characteristics–Input/Supply/Common Parameters–Normal Operating Conditions

TA = T<sub>AMR</sub> Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

TA = TAMB, Supply Voltages	per normai c	pperation conditions, See Test Loads for Loading Con	uitions				
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Supply Voltage	VDDx	Supply voltage for core and analog	1.7	1.8	1.9	٧	
Ambient Operating	_	Commmercial range	0	25	70	°C	
Temperature	T <sub>AMB</sub>	Industrial range	-40	25	85	°C	
Input High Voltage	V <sub>IH</sub>	Single-ended inputs, except SMBus	0.75 V <sub>DD</sub>		$V_{DD} + 0.3$	V	
Input Mid Voltage	V <sub>IM</sub>	Single-ended tri-level inputs ('_tri' suffix)	0.4 V <sub>DD</sub>		0.6 V <sub>DD</sub>	V	
Input Low Voltage	$V_{IL}$	Single-ended inputs, except SMBus	-0.3		0.25 V <sub>DD</sub>	V	
	I <sub>IN</sub>	Single-ended inputs, $V_{IN} = GND$ , $V_{IN} = VDD$	-5		5	uA	
Input Current	I <sub>INP</sub>	Single-ended inputs $V_{IN} = 0 \text{ V}$ ; Inputs with internal pull-up resistors $V_{IN} = \text{VDD}$ ; Inputs with internal pull-down resistors	-200		200	uA	
	F <sub>ibyp</sub>	Bypass mode	1		200	MHz	2
land Formula	F <sub>ipll</sub>	100MHz PLL mode	60	100.00	140	MHz	2
Input Frequency	F <sub>ipII</sub>	125MHz PLL mode	75	125.00	175	MHz	2
	F <sub>ipll</sub>	50MHz PLL mode	30	50.00	65	MHz	2
	C <sub>IN</sub>	Logic Inputs, except DIF_IN	1.5		5	pF	1
Capacitance	C <sub>INDIF_IN</sub>	DIF_IN differential clock inputs	1.5		2.7	pF	1,5
	C <sub>OUT</sub>	Output pin capacitance			6	pF	1
Clk Stabilization	T <sub>STAB</sub>	From V <sub>DD</sub> Power-Up and after input clock stabilization or de-assertion of PD# to 1st clock			1	ms	1,2
Input SS Modulation Frequency PCIe	f <sub>MODINPCle</sub>	Allowable Frequency for PCIe Applications (Triangular Modulation)	30		33	kHz	
Input SS Modulation Frequency non-PCIe	f <sub>MODIN</sub>	Allowable Frequency for non-PCIe Applications (Triangular Modulation)	0		66	kHz	
OE# Latency	t <sub>LATOE#</sub>	DIF start after OE# assertion DIF stop after OE# deassertion	1		3	clocks	1,3
Tdrive_PD#	t <sub>DRVPD</sub>	DIF output enable after PD# de-assertion			300	us	1,3
Tfall	t <sub>F</sub>	Fall time of single-ended control inputs			5	ns	2
Trise	t <sub>R</sub>	Rise time of single-ended control inputs			5	ns	2
SMBus Input Low Voltage	V <sub>ILSMB</sub>	V <sub>DDSMB</sub> = 3.3V, see note 4 for V <sub>DDSMB</sub> < 3.3V			0.6	V	
SMBus Input High Voltage	V <sub>IHSMB</sub>	$V_{DDSMB} = 3.3V$ , see note 5 for $V_{DDSMB} < 3.3V$	2.1		3.6	V	4
SMBus Output Low Voltage	$V_{OLSMB}$	@ I <sub>PULLUP</sub>			0.4	V	
SMBus Sink Current	I <sub>PULLUP</sub>	@ V <sub>OL</sub>	4			mA	
Nominal Bus Voltage	$V_{\text{DDSMB}}$	Bus Voltage	1.7		3.6	V	
SCLK/SDATA Rise Time	t <sub>RSMB</sub>	(Max VIL - 0.15) to (Min VIH + 0.15)			1000	ns	1
SCLK/SDATA Fall Time	t <sub>FSMB</sub>	(Min VIH + 0.15) to (Max VIL - 0.15)			300	ns	1
SMBus Operating Frequency	f <sub>MAXSMB</sub>	Maximum SMBus operating frequency			400	kHz	6

<sup>&</sup>lt;sup>1</sup>Guaranteed by design and characterization, not 100% tested in production.

<sup>&</sup>lt;sup>2</sup>Control input must be monotonic from 20% to 80% of input swing.

<sup>&</sup>lt;sup>3</sup>Time from deassertion until outputs are >200 mV

 $<sup>^4</sup>$  For  $V_{\text{DDSMB}} < 3.3 V, \ V_{\text{IHSMB}} >= 0.8 x V_{\text{DDSMB}}$ 

<sup>&</sup>lt;sup>5</sup>DIF\_IN input

<sup>&</sup>lt;sup>6</sup>The differential input clock must be running for the SMBus to be active



### **Electrical Characteristics-DIF 0.7V Low Power HCSL Outputs**

TA = T<sub>AMR</sub> Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

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PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Slew rate	dV/dt	Scope averaging on, fast setting	1.6	2.8	4	V/ns	1,2,3
Siew late	dV/dt	Scope averaging on, slow setting	1.1	2.0	3	V/ns	1,2,3
Slew rate matching	8 dV/dt	Slew rate matching, Scope averaging on		7	20	%	1,2,4
Voltage High	$V_{HIGH}$	Statistical measurement on single-ended signal using oscilloscope math function. (Scope	660	736	850	mV	7
Voltage Low	$V_{LOW}$	using oscilloscope math function. (Scope averaging on)		32	150	""	7
Max Voltage	Vmax	Measurement on single ended signal using		769	1150	mV	7
Min Voltage	Vmin	absolute value. (Scope averaging off)	-300	21		1111	7
Crossing Voltage (abs)	Vcross_abs	Scope averaging off	250	391	550	mV	1,5
Crossing Voltage (var)	∆-Vcross	Scope averaging off		13	140	mV	1,6

<sup>&</sup>lt;sup>1</sup>Guaranteed by design and characterization, not 100% tested in production.

### **Electrical Characteristics-Current Consumption**

TA = T<sub>AMR</sub> Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

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PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES	
Operating Supply Current	I <sub>DDA</sub>	VDDA+VDDR, PLL Mode, @100MHz		4.4	6	mA	1	
Operating Supply Current	I <sub>DD</sub>	VDD, All outputs active @100MHz		14.2	18	mA	1	
Powerdown Current	I <sub>DDAPD</sub>	VDDA+VDDR, PLL Mode, @100MHz		0.01	1	mA	1, 2	
r owerdown Current	I <sub>DDPD</sub>	VDD, Outputs Low/Low		0.9	1.4	mA	1, 2	

<sup>&</sup>lt;sup>1</sup> Guaranteed by design and characterization, not 100% tested in production.

<sup>&</sup>lt;sup>2</sup> Measured from differential waveform

<sup>&</sup>lt;sup>3</sup> Slew rate is measured through the Vswing voltage range centered around differential 0V. This results in a +/-150mV window around differential 0V.

<sup>&</sup>lt;sup>4</sup> Matching applies to rising edge rate for Clock and falling edge rate for Clock#. It is measured using a +/-75mV window centered on the average cross point where Clock rising meets Clock# falling. The median cross point is used to calculate the voltage thresholds the oscilloscope is to use for the edge rate calculations.

<sup>&</sup>lt;sup>5</sup> Vcross is defined as voltage where Clock = Clock# measured on a component test board and only applies to the differential rising edge (i.e. Clock rising and Clock# falling).

<sup>&</sup>lt;sup>6</sup> The total variation of all Vcross measurements in any particular system. Note that this is a subset of Vcross\_min/max (Vcross absolute) allowed. The intent is to limit Vcross induced modulation by setting Δ-Vcross to be smaller than Vcross absolute.

<sup>&</sup>lt;sup>7</sup> At default SMBus settings.

<sup>&</sup>lt;sup>2</sup> Input clock stopped.



### Electrical Characteristics-Output Duty Cycle, Jitter, Skew and PLL Characteristics

TA = T<sub>AMB.</sub> Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

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PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
PLL Bandwidth	BW	-3dB point in High BW Mode	2	2.7	4	MHz	1,5
PLL Bandwidth	DVV	-3dB point in Low BW Mode	1	1.4	2	MHz	1,5
PLL Jitter Peaking	t <sub>JPEAK</sub>	Peak Pass band Gain		1.05	2	dB	1
Duty Cycle	t <sub>DC</sub>	Measured differentially, PLL Mode	45	50	55	%	1
Duty Cycle Distortion	t <sub>DCD</sub>	Measured differentially, Bypass Mode @100MHz	-1	-0.1	1	%	1,3
Ckow Input to Output	t <sub>pdBYP</sub>	Bypass Mode, V <sub>T</sub> = 50%	2800	3623	4500	ps	1
Skew, Input to Output	t <sub>pdPLL</sub>	PLL Mode V <sub>T</sub> = 50%	0	112	200	ps	1,4
Skew, Output to Output	t <sub>sk3</sub>	V <sub>T</sub> = 50%		33	50	ps	1,4
Jitter, Cycle to cycle	+.	PLL mode		13	50	ps	1,2
Jitter, Cycle to Cycle	t <sub>jcyc-cyc</sub>	Additive Jitter in Bypass Mode		0.1	5	ps	1,2

<sup>&</sup>lt;sup>1</sup> Guaranteed by design and characterization, not 100% tested in production.

### **Electrical Characteristics-Phase Jitter Parameters**

 $TA = T_{AMB}$ , Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

						INDUSTRY		
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	LIMIT	UNITS	Notes
	t <sub>jphPCleG1</sub>	PCIe Gen 1		32	52	86	ps (p-p)	1,2,3,5
	+	PCIe Gen 2 Lo Band 10kHz < f < 1.5MHz		0.8	1.4	3	ps (rms)	1,2,3,5
Phase Jitter, PLL Mode	t <sub>jphPCleG2</sub>	PCIe Gen 2 High Band 1.5MHz < f < Nyquist (50MHz)		2.4	2.5	3.1	ps (rms)	1,2,3,5
	t <sub>jphPCleG3</sub>	PCIe Gen 3 (PLL BW of 2-4 or 2-5MHz, CDR = 10MHz)		0.5	0.6	1	ps (rms)	1,2,3,5
	t <sub>jphSGMII</sub>	125MHz, 1.5MHz to 10MHz, -20dB/decade rollover < 1.5MHz, -40db/decade rolloff > 10MHz		1.9	2	NA	ps (rms)	1,6
	t <sub>jphPCleG1</sub>	PCIe Gen 1		0.1	5	N/A	ps (p-p)	1,2,3,5
		PCIe Gen 2 Lo Band 10kHz < f < 1.5MHz		0.2	0.3	N/A	ps (rms)	1,2,3,4, 5
	t <sub>jphPCleG2</sub>	PCIe Gen 2 High Band 1.5MHz < f < Nyquist (50MHz)		0.00	0.1	N/A	ps (rms)	1,2,3,4
Additive Phase Jitter, Bypass Mode	t <sub>jphPCleG3</sub>	PCIe Gen 3 (PLL BW of 2-4 or 2-5MHz, CDR = 10MHz)		0.00	0.1	N/A	ps (rms)	1,2,3,4
	t <sub>jphSGMII</sub>	125MHz, 1.5MHz to 10MHz, -20dB/decade rollover < 1.5MHz, -40db/decade rolloff > 10MHz		165	200	N/A	ps (rms)	1,6
	t <sub>jphSGMII</sub>	125MHz, 12kHz to 20MHz, -20dB/decade rollover < 1.5MHz, -40db/decade rolloff > 10MHz		251	300	N/A	ps (rms)	1,6

<sup>&</sup>lt;sup>1</sup>Guaranteed by design and characterization, not 100% tested in production.

<sup>&</sup>lt;sup>2</sup> Measured from differential waveform

<sup>&</sup>lt;sup>3</sup> Duty cycle distortion is the difference in duty cycle between the output and the input clock when the device is operated in bypass mode.

<sup>&</sup>lt;sup>4</sup> All outputs at default slew rate

<sup>&</sup>lt;sup>5</sup> The MIN/TYP/MAX values of each BW setting track each other, i.e., Low BW MAX will never occur with Hi BW MIN.

<sup>&</sup>lt;sup>2</sup> See http://www.pcisig.com for complete specs

<sup>&</sup>lt;sup>3</sup> Sample size of at least 100K cycles. This figures extrapolates to 108ps pk-pk @ 1M cycles for a BER of 1-12.

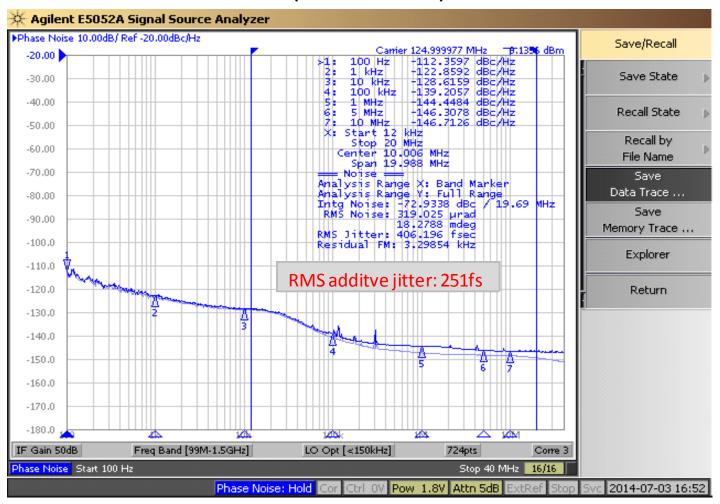
<sup>&</sup>lt;sup>4</sup> For RMS figures, additive jitter is calculated by solving the following equation: Additive jitter = SQRT[(total jitter)^2 - (input jitter)^2]

<sup>&</sup>lt;sup>5</sup> Driven by 9FG432 or equivalent

<sup>&</sup>lt;sup>6</sup> Rohde&Schartz SMA100



### Additive Phase Jitter Plot: 125M (12kHz to 20MHz)





#### **General SMBus Serial Interface Information**

#### **How to Write**

- Controller (host) sends a start bit
- Controller (host) sends the write address
- IDT clock will acknowledge
- Controller (host) sends the beginning byte location = N
- IDT clock will acknowledge
- Controller (host) sends the byte count = X
- IDT clock will acknowledge
- Controller (host) starts sending Byte N through Byte N+X-1
- IDT clock will acknowledge each byte one at a time
- Controller (host) sends a Stop bit

	Index Block Write Operation							
Controll	er (Host)		IDT (Slave/Receiver)					
Т	starT bit							
Slave A	Address							
WR	WRite							
			ACK					
Beginning	g Byte = N							
			ACK					
Data Byte	Count = X							
			ACK					
Beginnir	ng Byte N							
			ACK					
0		×						
0		X Byte	0					
0		æ	0					
			0					
Byte N	+ X - 1							
			ACK					
Р	stoP bit							

Note: SMBus Address is 1101101x, where x is the read/write bit.

#### How to Read

- Controller (host) will send a start bit
- Controller (host) sends the write address
- IDT clock will acknowledge
- Controller (host) sends the beginning byte location = N
- IDT clock will acknowledge
- Controller (host) will send a separate start bit
- Controller (host) sends the read address
- IDT clock will acknowledge
- IDT clock will send the data byte count = X
- IDT clock sends Byte N+X-1
- IDT clock sends Byte 0 through Byte X (if X<sub>(H)</sub> was written to Byte 8)
- Controller (host) will need to acknowledge each byte
- Controller (host) will send a not acknowledge bit
- · Controller (host) will send a stop bit

	Index Block R	Read C	<b>Operation</b>
Co	ntroller (Host)		IDT (Slave/Receiver)
Т	starT bit		
S	lave Address		
WR	WRite		
			ACK
Beg	inning Byte = N		
			ACK
RT	Repeat starT		
S	lave Address		
RD	ReaD		
			ACK
			Data Byte Count=X
	ACK		
			Beginning Byte N
	ACK		
		ē	0
	0	X Byte	0
	0	×	0
	0		
			Byte N + X - 1
N	Not acknowledge		
Р	stoP bit		



#### SMBus Table: Output Enable Register <sup>1</sup>

Byte 0	Name	Control Function	Туре	0	1	Default
Bit 7	Reserved					
Bit 6	Reserved					
Bit 5	DIF OE1 Output Enable RW Low/Low Enabled					
Bit 4	Reserved					
Bit 3	DIF OE0	Output Enable	RW	Low/Low	Enabled	1
Bit 2	Reserved					
Bit 1	Reserved					
Bit 0		Reserved				1

<sup>1.</sup> A low on these bits will overide the OE# pin and force the differential output Low/Low

#### SMBus Table: PLL Operating Mode and Output Amplitude Control Register

Byte 1	Name	Control Function	Туре	0 1		Default
Bit 7	PLLMODERB1	PLL Mode Readback Bit 1	R	See PLL Operating Mode Table		Latch
Bit 6	PLLMODERB0	PLL Mode Readback Bit 0	R	Oce i LL Opera	ling Mode Table	Latch
Bit 5	PLLMODE SWCNTRL	Enable SW control of PLL Mode	RW Values in B1[7:6] Values in B1[4:3]			0
				set PLL Mode	set PLL Mode	
Bit 4	PLLMODE1	PLL Mode Control Bit 1	RW <sup>1</sup>	See PLL Operat	ting Mode Table	0
Bit 3	PLLMODE0	PLL Mode Control Bit 0	RW <sup>1</sup>	See FLL Opera	iing wode rable	0
Bit 2		Reserved			1	
Bit 1	AMPLITUDE 1	Controls Output Amplitude	RW	00 = 0.6V	01 = 0.7V	1
Bit 0	AMPLITUDE 0	Controls Output Amplitude	RW	10= 0.8V	11 = 0.9V	0

<sup>1.</sup> B1[5] must be set to a 1 for these bits to have any effect on the part.

#### SMBus Table: DIF Slew Rate Control Register

Byte 2	Name	Control Function	Туре	0	1	Default
Bit 7		Reserved				1
Bit 6	Reserved					
Bit 5	SLEWRATESEL DIF1	Slew Rate Selection	RW	Slow setting	Fast setting	1
Bit 4	Reserved					
Bit 3	SLEWRATESEL DIF0	Slew Rate Selection	RW	Slow setting	Fast setting	1
Bit 2	Reserved					
Bit 1	Reserved					
Bit 0		Reserved				1

#### SMBus Table: Frequency Select Control Register

Byte 3	Name Control Function		Туре	0	1	Default
Bit 7	Reserved					
Bit 6		Reserved				1
Bit 5	FREQ_SEL_EN	Enable SW selection of frequency	RW	SW frequency change disabled	SW frequency change enabled	0
Bit 4	FSEL1	Freq. Select Bit 1	RW <sup>1</sup>	See Frequency	v Select Table	0
Bit 3	FSEL0	Freq. Select Bit 0	RW <sup>1</sup>	oce i requerio	y delect fable	0
Bit 2		Reserved				
Bit 1	Reserved					1
Bit 0	SLEWRATESEL FB	Adjust Slew Rate of FB	RW	Slow setting	Fast setting	1

<sup>1.</sup> B3[5] must be set to a 1 for these bits to have any effect on the part.

#### Byte 4 is Reserved and reads back 'hFF



#### SMBus Table: Revision and Vendor ID Register

Byte 5	Name	Control Function	Туре	0	1	Default
Bit 7	RID3		R	A rev = 0000		0
Bit 6	RID2	Revision ID	R			0
Bit 5	RID1	- Revision ib	R	A rev = 0000	0	
Bit 4	RID0		R			0
Bit 3	VID3		R			0
Bit 2	VID2	VENDOR ID	R 0001 = IDT	- IDT	0	
Bit 1	VID1	T VENDOR ID	R	0001 = 101		0
Bit 0	VID0		R			1

#### SMBus Table: Device Type/Device ID

Byte 6	Name	Control Function	Туре	0	1	Default
Bit 7	Device Type1	Device Type	R	00 = FGx,	01 = DBx,	0
Bit 6	Device Type0	Device Type	R	10 = DMx, 1	1= Reserved	1
Bit 5	Device ID5		R			0
Bit 4	Device ID4		R			0
Bit 3	Device ID3	Device ID	R	000100 bina	ny or 02 hay	0
Bit 2	Device ID2	Device ib	R	000100 binary or 02 hex		0
Bit 1	Device ID1		R			1
Bit 0	Device ID0		R			0

#### SMBus Table: Byte Count Register

Byte 7	Name	Control Function	Туре	0	1	Default
Bit 7		Reserved				0
Bit 6		Reserved				0
Bit 5		Reserved				0
Bit 4	BC4		RW			0
Bit 3	BC3		RW	Writing to this regist	er will configure how	1
Bit 2	BC2	Byte Count Programming	RW	many bytes will be r	ead back, default is	0
Bit 1	BC1		RW	= 8 b	ytes.	0
Bit 0	BC0		RW			0



## **Marking Diagrams**





#### Notes:

- 1. 'LOT' is the lot number.
- 2. 'YYWW' is the last two digits of the year and week that the part was assembled.
- 3. 'L' denotes RoHS compliant package.
- 4. 'l' denotes industrial temperature grade.

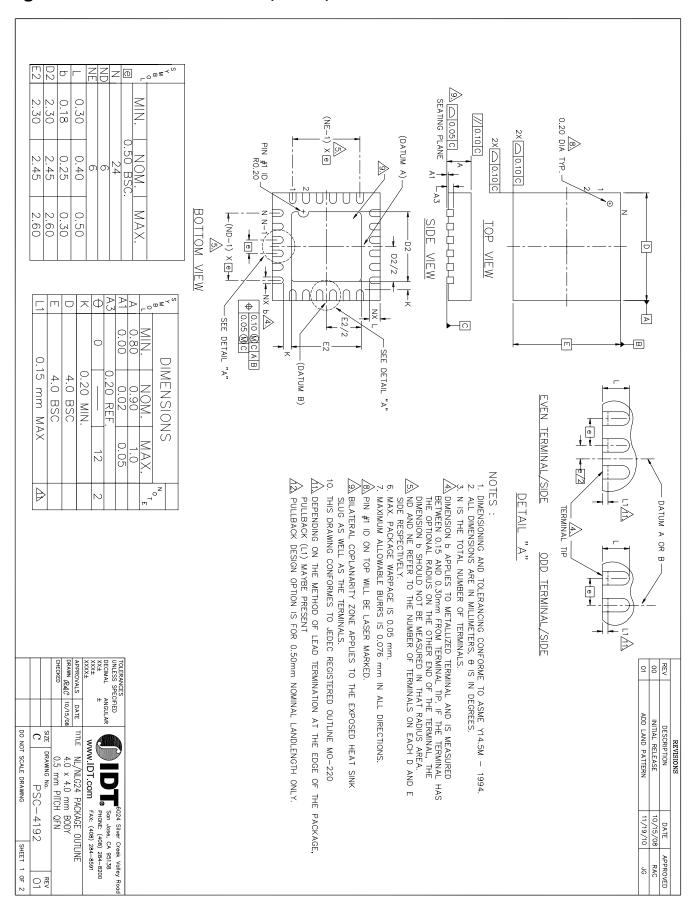
### **Thermal Characteristics**

PARAMETER	SYMBOL	CONDITIONS	PKG	TYP VALUE	UNITS	NOTES
	$\theta_{JC}$	Junction to Case		62	°C/W	1
	$\theta_{Jb}$	Junction to Base		5.4	°C/W	1
Thermal Resistance	$\theta_{JA0}$	Junction to Air, still air	NLG20	50	°C/W	1
Theimai nesistance	$\theta_{JA1}$	Junction to Air, 1 m/s air flow	NLG24	43	°C/W	1
	$\theta_{JA3}$	Junction to Air, 3 m/s air flow		39	°C/W	1
	$\theta_{JA5}$	Junction to Air, 5 m/s air flow		38	°C/W	1

<sup>&</sup>lt;sup>1</sup>ePad soldered to board

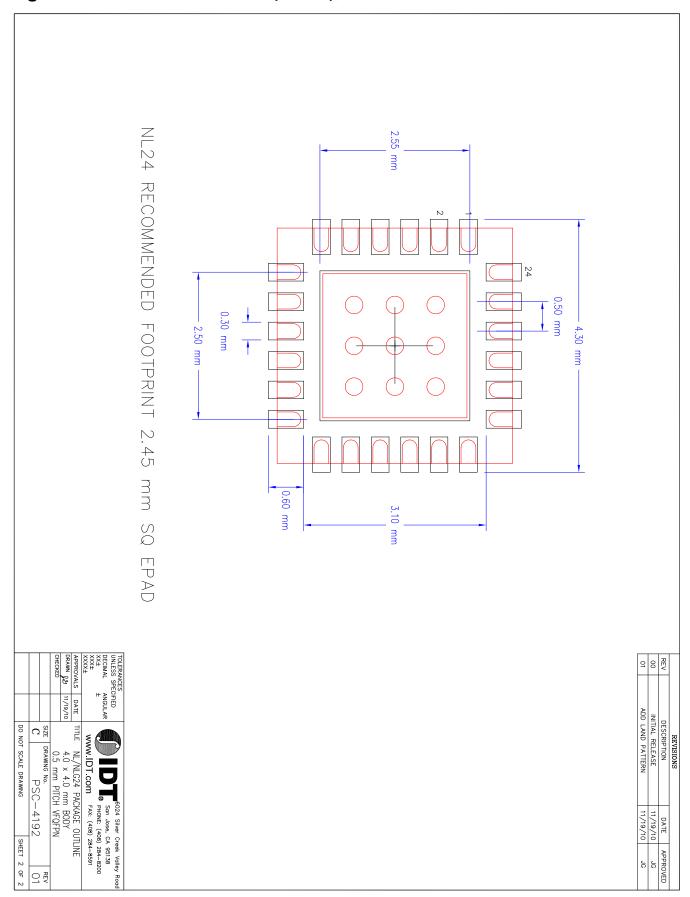


### Package Outline and Dimensions (NLG24)





# Package Outline and Dimensions (NLG24), cont.





# **Ordering Information**

Part / Order Number	Shipping Packaging	Package	Temperature
9DBV0241AKLF	Tubes	24-pin VFQFPN	0 to +70° C
9DBV0241AKLFT	Tape and Reel	24-pin VFQFPN	0 to +70° C
9DBV0241AKILF	Tubes	24-pin VFQFPN	-40 to +85° C
9DBV0241AKILFT	Tape and Reel	24-pin VFQFPN	-40 to +85° C

<sup>&</sup>quot;LF" suffix to the part number are the Pb-Free configuration and are RoHS compliant.

### **Revision History**

Rev.	Initiator	Issue Date	Description	Page #
Α	RDW	8/13/2012	Updated electrical characteristics tables.	5-8
	TIDVV	0/10/2012	2. Move to final.	30
В	RDW	9/6/2014	1. Changed VIH min. from 0.65*VDD to 0.75*VDD	Various
			2. Changed VIL max. from 0.35*VDD to 0.25*VDD	
			3. Added missing mid-level input voltage spec (VIM) of 0.4*VDD to	
			0.6*VDD.	
			4. Changed Shipping Packaging from "Trays" to Tubes".	
			5. Reformatted to new template	
С	RDW	8/10/2015	Updated front page text for family consistency	1,2,4,5, 6,7,8, 14
			Updated block diagram for family consistency	
			Updated pin configuration to indicate that paddle is ground	
			4. Added epad as pin 25 to pin descritptions	
			5. Replaced "Driving LVDS" with "Alternate Terminations", adding	
			reference to AN-891.	
			6. Updated "Clock Input Parameters Table" correcting inconsistency with	
			PCIe SIG specifications.	
			7. Widened allowable input frequency at each PLL mode frequency.	
			8. Updated phase jitter parameters with 12k-20M additive phase jitter and	
			added additive phase jitter graph.	
			9. Updated NLG24 package drawing with actual package info instead of	
_			generic drawing.	
D	RDW	9/11/2015	Corrected block diagram from clock generator to ZDB buffer	1
E	RDW	11/4/2015	Minor typographical corrections throughout the data sheet	Various, 4-8,11
			Updated test load diagram to generic diagram. Length of test load	
			listed outside the drawing.	
			3. Minor updates to electrical tables for formatting. Removed Schmitt	
			trigger info and output high/low voltage specifications for single-ended	
			outputs, since this part does not have any.	
			4. "Low-Power HCSL Outputs" table: corrected inversion of slew rate	
			setting with specifications. Changed reference from 2 V/ns and 3 V/ns to	
			slow setting and fast setting. Also change references in SMBus	
			Bytes[3:2]	
			5. "Low-Power HCSL Outputs" table: Removed Vswing parameter since	
			this is an input parameter and is covered in "Clock Input Parameters"	
			Table.	
			6. Reduced current consumption limits.	
			Minor updates to other electrical tables.     Updated max frequency of 100MHz PLL mode to 140MHz	
F	RDW	4/22/2046		_
	KDW	4/22/2016	2. Updated max frequency of 125MHz PLL mode to 175MHz	6
			3. Updated max frequency of 50MHz PLL mode to 65MHz	<u> </u>

<sup>&</sup>quot;A" is the device revision designator (will not correlate with the datasheet revision).



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