

ECN3053F

ECN3053 is a single chip driver IC which has 6 MOS-Gated devices for its output. It is suitable for controlling 3-phase DC brushless motors and 3-phase induction motors.

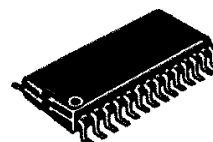
Functions

- Lower arm Over current (OC) Protection
- Under voltage Protection
- Fault Output function

Features

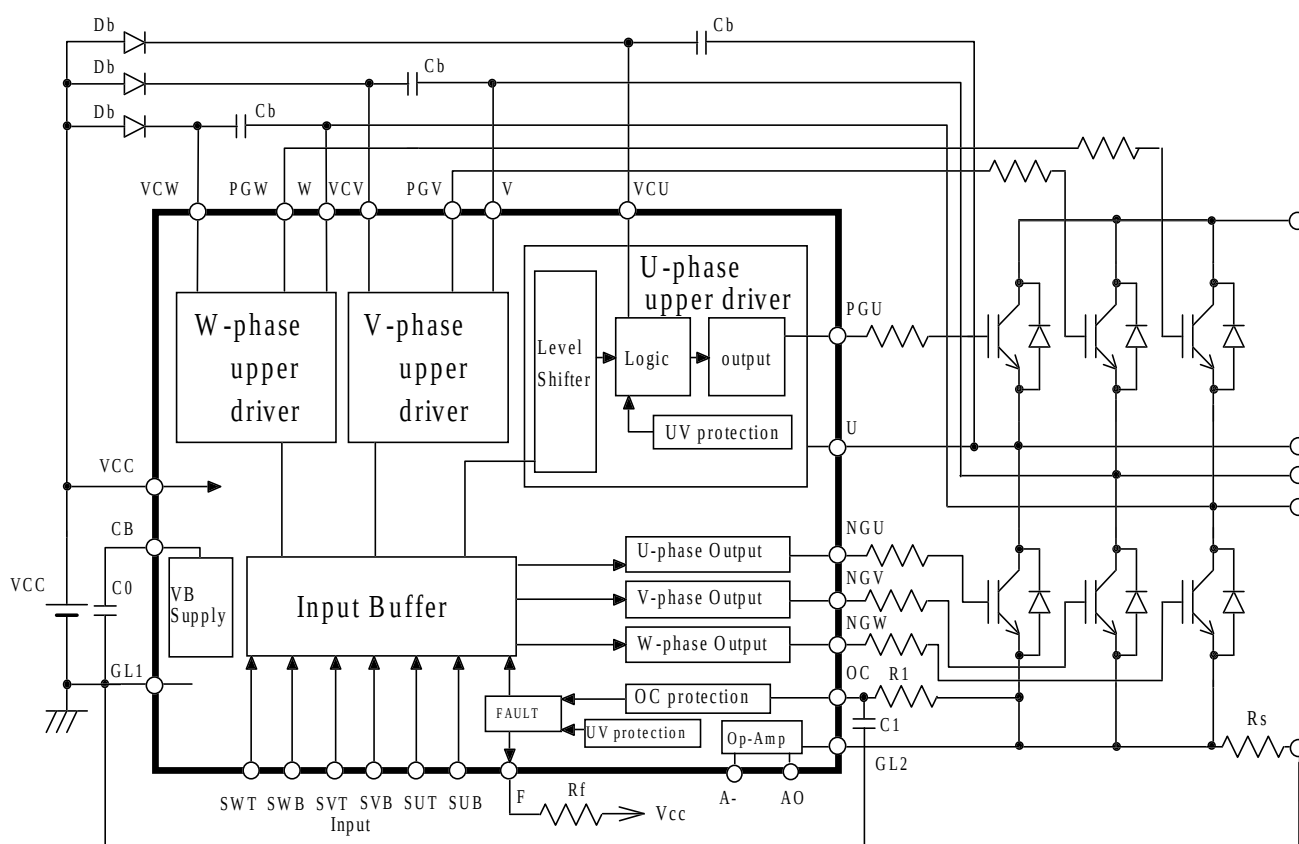
- It can be controlled by PWM with 6 inputs from an external microprocessor.
- 6 logic inputs are compatible with 5V CMOS and LSTTL outputs.

Package



SOP-28

Block Diagram



ECN3053F

1. General

This specification shall be applied to the following semiconductor integrated circuits.

- 1) Type : ECN3053F
- 2) Application : 3-phase Brushless Motor, 3-phase Induction Motor
- 3) Structure : Monolithic IC
- 4) Package : SOP28

2. Maximum Allowable Ratings (Ta=25°C)

No.	ITEMS	SYMBOLS	UNIT	VALUES	CONDITIONS
1	Output Device Breakdown voltage	V _{bv}	V	620	Between V _{cu,v,w} & GL1
2	GL2 terminal voltage	V _{gl2}	V	-5~V _{cc}	V _{cc} =18V _{max} at GL2=-5V
3	U,V,W terminal Voltage	V _{u,v,w}	V	-5~600	
4	Supply voltage	V _{cc}	V	20	
5	Input voltage	V _{in}	V	-0.5~V _{cc} +0.5	
6	Operating Junction Temperature	T _{jop}	°C	-20~125	
7	Storage Temperature	T _{stg}	°C	-40~150	

Note 1 : Thermal resistance R_{ja}

PACKAGE	SOP28	Unit
Single	121	°C/W
Mounted	84	°C/W
PCB size,Density *	120x21x1.6 (30%)	mm

* This figure varies depending on the mounting condition.

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3. Electrical Characteristics

Unless otherwise noted, $T_a=25\text{ }^{\circ}\text{C}$, $V_{u,v,w}$ to $GL1=374\text{V}$, $V_{cc}=15\text{V}$. (suffix T=top, B=bottom arm)

No	ITEMS	SYMBOLS	UNIT	MIN.	TYP.	MAX.	CONDITIONS
1	Stand-by current	Is1	mA	-	6.5	10	$V_{in}=H$ or L , Between V_{cc} -GL1
		Is2	μA	-	15	30	Between V_{cu} -U, V_{cv} -V, V_{cw} -W 15V, $V_{in}=H$ or L
2	Input Voltage (Output is L)	VIH	V	3.5	-	-	Input=H or L
	Input Voltage (Output is H)	VIL	V	-	-	1.5	
3	Output Source Current	Io+	A	0.2	0.25	-	V_{cu} -PGU, V_{cv} -PGV, V_{cw} -PGW =15V, V_{cc} -NGU, V, W =15V $PW<10\mu\text{s}$
4	Output Sink Current	Io-	A	0.4	0.5	-	PGU-U, PGV-V, PGW-W =15V, NGU, V, W -GL2=15V $PW<10\mu\text{s}$
5	High level Output Voltage	VOH	mV	-	-	100	$V_{cu,v,w}$ -PGU, V, W & V_{cc} -NGU, V, W $V_{in}=0$, $I_o=0$
6	Low level Output Voltage	VOL	mV	-	-	100	PGU, V, W -U, V, W & NGU, V, W -GL2 $V_{in}=5\text{V}$, $I_o=0$
7	Leakage Current at HV terminal	IL	μA	-	-	50	$V_{cu,v,w}=U, V, W=600\text{V}$
8	Input Current	IIL	μA	-200	-	-	$V_{in}=0\text{V}$ Internal Pull up $R=200\text{k}\Omega$
9	Input Current	IIH	μA	-120	-	-	$V_{in}=5\text{V}$ Internal Pull up $R=200\text{k}\Omega$
10	Vcc Under voltage	Negative Going	Vuwb	9.5	10.5	11.6	
		Reset Hysteresis	Vrhb	0.1	0.4	0.9	
11	Vcu,v,w Under Voltage	Negative Going	Vuvt	8.9	10.5	12.1	
		Reset Hysteresis	Vrht	0.1	0.4	0.9	
12	OC Input Positive Going threshold	Voc	V	0.44	0.49	0.54	
13	Fault Output On Resistance	Ronf	Ω	-	300	400	F-GL1=0.5V
14	Turn On Delay Time	ton	μs	-	0.8	1.5	CL=1000pF RL=0
15	Turn Off Delay Time	toff	μs	-	0.5	1.2	CL=1000pF RL=0
16	OC Output to Output Shutdown Delay	toc	μs	-	0.7	1.7	CL=1000pF RL=0
17	OC to Fault Delay	tflt	μs	-	0.6	1.6	CL=1000pF RL=0
18	Fault Reset Delay Time	tflrs	μs	6.5	10	20	CL=1000pF RL=0
19	Fault Output terminal Voltage	Vflt	V	-0.5	-	$V_{cc}+0.5$	
20	Fault Output Sink Current	Iflt	mA	4	-	-	$V(F\&GL)=2\text{V}$
21	VB Output Voltage	VB	V	6.8	7.5	8.2	
22	VB Output Current	IB	mA	25	-	-	Delta Vload=0.1V
23	Op-Amp Input Offset Voltage	Vos	mV	-	-	30	GL2=A-=0.2V
24	Op-Amp High Level Output Voltage	VOHa	V	5.0	7.5	-	A-=0V GL2=1V
25	Op-Amp Low Level Output Voltage	VOLa	mV	-	-	20	A-=1V GL2=0V
26	Op-Amp Output Source Current	Isrca	mA	1.0	-	-	A-=0V GL2=1V AO=4V
27	Op-Amp Output Sink Current	Isnka	mA	1.0	-	-	A-=1V GL2=0V AO=2V

Note 1: Vuwb, Vrhb, Vuvt and Vrht are defined and shown in Fig. 1.

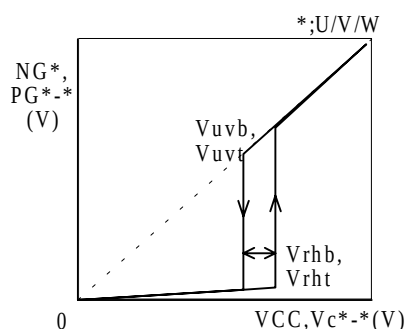


Fig 1. Negative going and reset voltage and hysteresis for the top and bottom arm under voltage circuit

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4. Truth Table

INPUT		OC Input	U phase		V phase		W phase	
			Top arm	Bot.arm	Top arm	Bot.arm	Top arm	Bot.arm
SUT	L	L	ON	-	-	-	-	-
	H		OFF	-	-	-	-	-
SUB	L		-	ON	-	-	-	-
	H		-	OFF	-	-	-	-
SVT	L		-	-	ON	-	-	-
	H		-	-	OFF	-	-	-
SVB	L		-	-	-	ON	-	-
	H		-	-	-	OFF	-	-
SWT	L		-	-	-	-	ON	-
	H		-	-	-	-	OFF	-
SWB	L		-	-	-	-	-	ON
	H		-	-	-	-	-	OFF
-	-	H	OFF	OFF	OFF	OFF	OFF	OFF
SUT,SUB	L	-	OFF	OFF	-	-	-	-
SVT,SVB	L	-	-	-	OFF	OFF	-	-
SWT,SWB	L	-	-	-	-	-	OFF	OFF

Note 1: Fault output level is referenced Low when over current or under voltage for Vcc is detected.

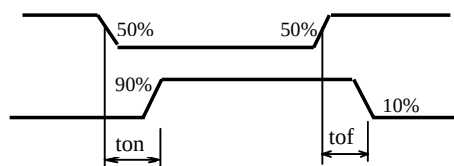
Note 2: Over current protection works when the voltage drop of the external sensing resistor exceeds the threshold voltage Voc(typical 0.49V). In this case all six outputs are turned off and Fault output level becomes low.

Reset after detection is done by feeding high signal to all six inputs or re-supplying Vcc voltage.

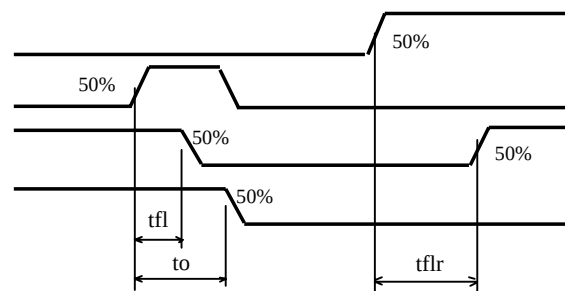
Note 3: The output signal for Fault is reset by feeding high signal to all six inputs.

5. Definition of switching delay

Input
(SUB,T, SVB,T, SWB,T)
Output
(PGU,V,W, NGU,V,W)



Input
OC
F
Output
(PGU,V,W NGU,V,W)



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6. Recommended Operating Conditions

No.	ITEMS	SYMBOLS	UNIT	VALUES TOL.	CONDITIONS
1	Power Supply Voltage	Vcc	V	13.5~16.5	
2	PWM Frequency	fpwm	kHz	1~20	
3	VB Smoothing Capacitor	Co	μF	> 0.22	Stress voltage:VB
4	Boot Strap Capacitor	Cb	μF	3.3	Stress voltage:Vcc
5	Boot Strap Diodes	Db	Hitachi DFG1C6 DFM1F6 or equivalent		600V/1.0A $\leq 0.1\mu s$
6	Sensing Resistor	Rs	Ω	Note 1	
7	OC Filtering Resistor	R1	Ω	Note 2	
8	OC Filtering Capacitor	C1	μF	Note 2	
9	Load resistor for F terminal	Rf	kΩ	≥ 5.6	

Note 1. Over-current detection level is determined by the following equation

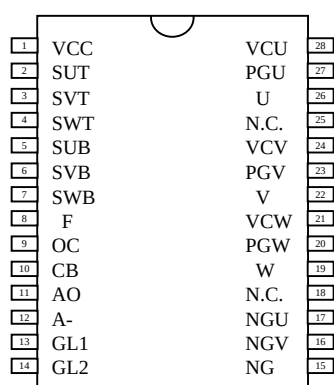
$$I_{oc} = V_{oc} / R_s$$

Note.2 This IC has filters of 0.4us for noise reduction.

But appropriate R1, C1 should be added when noise can not be removed.

7. Pin Assignment

<SOP28>



8. Outline Drawing

< SOP28 >

