

S25FS-S Family

MirrorBit® Flash Non-Volatile Memory

1.8-Volt Single Supply with CMOS I/O

Serial Peripheral Interface with Multi-I/O

S25FS128S 128 Mbit (16 Mbyte)

S25FS256S 256 Mbit (32 Mbyte)

Data Sheet (Preliminary)



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Data Sheet (Preliminary)

Features

■ Density

- 128 Mbits (16 Mbytes)
- 256 Mbits (32 Mbytes)

■ Serial Peripheral Interface (SPI)

- SPI Clock polarity and phase modes 0 and 3
- Double Data Rate (DDR) option
- Extended Addressing: 24- or 32-bit address options
- Serial Command subset and footprint compatible with S25FL-A, S25FL-K, S25FL-P, and S25FL-S SPI families
- Multi I/O Command subset and footprint compatible with S25FL-P, and S25FL-S SPI families

■ Read

- Commands: Normal, Fast, Dual I/O, Quad I/O, DDR Quad I/O
- Modes: Burst Wrap, Continuous (XIP), QPI
- Serial Flash Discoverable Parameters (SFDP) and Common Flash Interface (CFI), for configuration information

■ Program

- 256- or 512-byte Page Programming buffer
- Program suspend and resume

■ Erase

- Hybrid sector option
 - Physical set of eight 4-kbyte sectors and one 32-kbyte sector at the top or bottom of address space with all remaining sectors of 64 kbytes
- Uniform sector option
 - Uniform 64-kbyte or 256-kbyte blocks for software compatibility with higher density and future devices
- Erase suspend and resume
- Erase status evaluation
- 100,000 Program-Erase Cycles on any sector, minimum
- 20 Year Data Retention, typical

■ Security Features

- One-Time Program (OTP) array of 1024 bytes
- Block Protection:
 - Status Register bits to control protection against program or erase of a contiguous range of sectors
 - Hardware and software control options
- Advanced Sector Protection (ASP)
 - Individual sector protection controlled by boot code or password
 - Option for password control of read access

■ Technology

- Spansion 65 nm MirrorBit Technology with Eclipse™ Architecture

■ Supply Voltage

- 1.7V to 2.0V

■ Temperature Range

- Industrial (0°C to +85°C)
- Automotive (–40°C to +105°C)

■ Packages (All Pb-Free)

- 8-lead SOIC 208 mil (SOC008) - FS128S only
- WSON 6x5 mm (WND008) - FS128S only
- WSON 6x8 mm (WNH008) - FS256S only
- 16-lead SOIC 300 mil (SO3016- FS256S only)
- BGA-24 6x8 mm
 - 5x5 ball (FAB024) footprint
 - 4x6 ball (FAC024) footprint
- Known Good Die, and Known Tested Die

1. Performance Summary

Table 1.1 Maximum Read Rates

Command	Clock Rate (MHz)	Mbytes / s
Read	50	6.25
Fast Read	133	16.5
Dual Read	133	33
Quad Read	133	66

Table 1.2 Maximum Read Rates DDR

Command	Clock Rate (MHz)	Mbytes / s
DDR Quad I/O Read	80	80

Table 1.3 Typical Program and Erase Rates

Operation	kbytes / s
Page Programming (256-bytes Page Buffer)	712
Page Programming (512-bytes Page Buffer)	1080
4-kbyte Physical Sector Erase (Hybrid Sector Option)	28
64-kbyte Physical Sector Erase (Hybrid Sector Option)	450
256-kbyte Sector Erase (Uniform Logical Sector Option)	450

Table 1.4 Typical Current Consumption (–40°C to +85°C)

Operation	Current (mA)
Serial Read 50 MHz	10
Serial Read 133 MHz	20
Quad Read 133 MHz	60
Quad DDR Read 80 MHz	70
Program	60
Erase	60
Standby	0.07

Table of Contents

Features

1. Performance Summary	4
2. Overview	12
2.1 General Description	12
2.2 Migration Notes	13
2.3 Glossary	16
2.4 Other Resources	17

Hardware Interface

3. Signal Descriptions	18
3.1 Input/Output Summary	18
3.2 Multiple Input / Output (MIO)	19
3.3 Serial Clock (SCK)	19
3.4 Chip Select (CS#)	19
3.5 Serial Input (SI) / IO0	19
3.6 Serial Output (SO) / IO1	19
3.7 Write Protect (WP#) / IO2	19
3.8 IO3 / RESET#	20
3.9 Voltage Supply (V_{DD})	20
3.10 Supply and Signal Ground (V_{SS})	20
3.11 Not Connected (NC)	20
3.12 Reserved for Future Use (RFU)	21
3.13 Do Not Use (DNU)	21
3.14 Block Diagrams	21
4. Signal Protocols	23
4.1 SPI Clock Modes	23
4.2 Command Protocol	24
4.3 Interface States	28
4.4 Configuration Register Effects on the Interface	31
4.5 Data Protection	32
5. Electrical Specifications	33
5.1 Absolute Maximum Ratings	33
5.2 Latch-Up Characteristics	33
5.3 Operating Ranges	33
5.4 Power-Up and Power-Down	34
5.5 DC Characteristics	36
6. Timing Specifications	37
6.1 Key to Switching Waveforms	37
6.2 AC Test Conditions	37
6.3 Reset	38
6.4 SDR AC Characteristics	40
6.5 DDR AC Characteristics	42
7. Physical Interface	44
7.1 SOIC 16-Lead Package	44
7.2 8-Connector Packages	46
7.3 FAB024 24-Ball BGA Package	50
7.4 FAC024 24-Ball BGA Package	52

Software Interface

8. Address Space Maps	54
8.1 Overview	54
8.2 Flash Memory Array	54
8.3 ID-CFI Address Space	57
8.4 JEDEC JESD216 Serial Flash Discoverable Parameters (SFDP) Space	57
8.5 OTP Address Space	58
8.6 Registers	59

9. Data Protection	76
9.1 Secure Silicon Region (OTP)	76
9.2 Write Enable Command	77
9.3 Block Protection	77
9.4 Advanced Sector Protection	78
9.5 Recommended Protection Process	84
10. Commands	85
10.1 Command Set Summary	87
10.2 Identification Commands	91
10.3 Register Access Commands	94
10.4 Read Memory Array Commands	104
10.5 Program Flash Array Commands	113
10.6 Erase Flash Array Commands	115
10.7 One-Time Program Array Commands	123
10.8 Advanced Sector Protection Commands	123
10.9 Reset Commands	132
11. Embedded Algorithm Performance Tables	134
12. Software Interface Reference	135
12.1 Command Summary by Instruction	135
12.2 Registers	136
12.3 Serial Flash Discoverable Parameters (SFDP) Address Map	142
12.4 Device ID and Common Flash Interface (ID-CFI) Address Map	143
12.5 Initial Delivery State	150
Ordering Information	
13. Ordering Part Number	151
14. Contacting Spansion	152
15. Revision History	153

Figures

Figure 3.1	Bus Master and Memory Devices on the SPI Bus - Single Bit Data Path	21
Figure 3.2	Bus Master and Memory Devices on the SPI Bus - Dual Bit Data Path	22
Figure 3.3	Bus Master and Memory Devices on the SPI Bus - Quad Bit Data Path	22
Figure 4.1	SPI SDR Modes Supported	23
Figure 4.2	SPI DDR Modes Supported	23
Figure 4.3	Stand Alone Instruction Command	25
Figure 4.4	Single Bit Wide Input Command	25
Figure 4.5	Single Bit Wide Output Command	26
Figure 4.6	Single Bit Wide I/O Command without Latency	26
Figure 4.7	Single Bit Wide I/O Command with Latency	26
Figure 4.8	Dual I/O Command	26
Figure 4.9	Quad I/O Command	26
Figure 4.10	Quad I/O Read Command in QPI Mode	27
Figure 4.11	DDR Quad I/O Read	27
Figure 4.12	DDR Quad I/O Read in QPI Mode	27
Figure 5.1	Maximum Negative Overshoot Waveform	34
Figure 5.2	Maximum Positive Overshoot Waveform	34
Figure 5.3	Power-Up	35
Figure 5.4	Power-Down and Voltage Drop	35
Figure 6.1	Waveform Element Meanings	37
Figure 6.2	Test Setup	37
Figure 6.3	Input, Output, and Timing Reference Levels	37
Figure 6.4	Reset Low at the End of POR	38
Figure 6.5	Reset High at the End of POR	38
Figure 6.6	POR Followed by hardware reset	38
Figure 6.7	Hardware Reset when Quad Mode is Not Enabled and IO3 / Reset# is Enabled	39
Figure 6.8	Hardware Reset when Quad Mode and IO3 / Reset# are Enabled	40
Figure 6.9	Clock Timing	41
Figure 6.10	SPI Single Bit Input Timing	41
Figure 6.11	SPI Single Bit Output Timing	41
Figure 6.12	SPI SDR MIO Timing	41
Figure 6.13	WP# Input Timing	42
Figure 6.14	SPI DDR Input Timing	42
Figure 6.15	SPI DDR Output Timing	43
Figure 6.16	SPI DDR Data Valid Window	43
Figure 7.1	16-Lead SOIC Package (SO3016), Top View	44
Figure 7.2	SOIC 16-Lead, 300-mil Body Width (SO3016)	45
Figure 7.3	8-Pin Plastic Small Outline Package (SOIC8)	46
Figure 7.4	8-Connector Package (WSON 6x5), Top View	46
Figure 7.5	SOIC 8-Lead, 208 mil Body Width (SOC008)	47
Figure 7.6	WSON 8-Contact 6x5 mm Leadless (WND008)	48
Figure 7.7	WSON 8-Contact 6x8 mm Leadless (WNH008)	49
Figure 7.8	24-Ball BGA, 5x5 Ball Footprint (FAB024), Top View	50
Figure 7.9	Ball Grid Array 24-Ball 6x8 mm (FAB024)	51
Figure 7.10	24-Ball BGA, 4x6 Ball Footprint (FAC024), Top View	52
Figure 7.11	Ball Grid Array 24-Ball 6 x 8 mm (FAC024)	53
Figure 8.1	OTP Address Space	58
Figure 9.1	Sector Protection Control	79
Figure 9.2	Advanced Sector Protection Overview	80
Figure 10.1	Read Identification (RDID) Command Sequence	92
Figure 10.2	Read Identification (RDID) QPI Mode Command	92
Figure 10.3	Read Quad Identification (RDQID) Command Sequence	92
Figure 10.4	RSFDP Command Sequence	93
Figure 10.5	RSFDP QPI Mode Command Sequence	93

Figure 10.6	Read Status Register 1 (RDSR1) Command Sequence	94
Figure 10.7	Read Status Register 1 (RDSR1) QPI Mode Command	94
Figure 10.8	Read Status Register 2 (RDSR2) Command.	94
Figure 10.9	Read Configuration Register (RDCR) Command Sequence	95
Figure 10.10	Write Registers (WRR) Command Sequence – 8-Data Bits	95
Figure 10.11	Write Registers (WRR) Command Sequence – 16-Data Bits	96
Figure 10.12	Write Registers (WRR) Command Sequence – 16-Data Bits QPI Mode.	96
Figure 10.13	Write Enable (WREN) Command Sequence	97
Figure 10.14	Write Enable (WREN) Command Sequence QPI Mode	97
Figure 10.15	Write Disable (WRDI) Command Sequence	98
Figure 10.16	Write Disable (WRDI) Command Sequence QPI Mode.	98
Figure 10.17	Clear Status Register (CLSR) Command Sequence	99
Figure 10.18	Clear Status Register (CLSR) Command Sequence QPI Mode	99
Figure 10.19	Program NVDLR (PNVDLR) Command Sequence	99
Figure 10.20	Write VDLR (WVDLR) Command Sequence.	100
Figure 10.21	DLP Read (DLPRD) Command Sequence	100
Figure 10.22	Enter 4-Byte Address Mode (4BAM B7h) Command Sequence	100
Figure 10.23	Read Any Register Read Command Sequence	102
Figure 10.24	Read Any Register, QPI Mode, CR2[7] = 0, Command Sequence	102
Figure 10.25	Read Any Register, QPI Mode, CR2[7] = 1 Command Sequence.	102
Figure 10.26	Set Burst Length Command Sequence	104
Figure 10.27	Read Command Sequence (3-Byte Address, 03h or 13h)	105
Figure 10.28	Fast Read (FAST_READ) Command Sequence (3-Byte Address, 0Bh [CR2V[7]=0])	106
Figure 10.29	Dual I/O Read Command Sequence (3-Byte Address, BBh [CR2V[7]=0])	107
Figure 10.30	Dual I/O Read Command Sequence (4-Byte Address, BBh [CR2V[7]=1])	107
Figure 10.31	Dual I/O Continuous Read Command Sequence (4-Byte Address [CR2V[7]=1])	108
Figure 10.32	Quad I/O Read Command Sequence (3-Byte Address, EBh [CR2V[7]=0]).	109
Figure 10.33	Quad I/O Read Command Sequence (3-Byte Address, EBh [CR2V[7]=0]) QPI Mode	109
Figure 10.34	Continuous Quad I/O Read Command Sequence (3-Byte Address).	109
Figure 10.35	Quad I/O Read Command Sequence (4-Byte Address, ECh or EBh [CR2V[7]=1])	110
Figure 10.36	Continuous Quad I/O Read Command Sequence (4-Byte Address).	110
Figure 10.37	Quad I/O Read Command Sequence (4-Byte Address, ECh or EBh [CR2V[7]=1]) QPI Mode	110
Figure 10.38	DDR Quad I/O Read Initial Access (3-Byte Address, EDh [CR2V[7]=0])	112
Figure 10.39	Continuous DDR Quad I/O Read Subsequent Access (3-Byte Address)	112
Figure 10.40	DDR Quad I/O Read Initial Access (4-Byte Address, EEh or EDh [CR2V[7]=1])	112
Figure 10.41	DDR Quad I/O Read Initial Access (4-Byte Address, EEh or EDh [CR2V[7]=1]) QPI Mode	113
Figure 10.42	Continuous DDR Quad I/O Read Subsequent Access (4-Byte Address)	113
Figure 10.43	Page Program (PP 02h or 4PP 12h) Command Sequence.	114
Figure 10.44	Page Program (PP 02h or 4PP 12h) QPI Mode Command Sequence	114
Figure 10.45	Parameter Sector Erase (P4E 20h or 4P4E 21h) Command Sequence	115
Figure 10.46	Parameter Sector Erase (P4E 20h or 4P4E 21h) QPI Mode Command Sequence	116
Figure 10.47	Sector Erase (SE D8h or 4SE DCh) Command Sequence	117
Figure 10.48	Sector Erase (SE D8h or 4SE DCh) QPI Mode Command Sequence	117
Figure 10.49	Bulk Erase Command Sequence.	118
Figure 10.50	Bulk Erase Command Sequence QPI Mode	118
Figure 10.51	EES Command Sequence.	119
Figure 10.52	EES QPI Mode Command Sequence	119
Figure 10.53	Program or Erase Suspend Command Sequence.	121
Figure 10.54	Program or Erase Suspend Command Sequence.	121
Figure 10.55	Program or Erase Suspend Command Sequence QPI Mode	122
Figure 10.56	Erase or Program Resume Command Sequence	122
Figure 10.57	Erase or Program Resume Command Sequence QPI Mode	122
Figure 10.58	ASPRD Command.	123

Figure 10.59	ASPP Command	124
Figure 10.60	DYBRD Command Sequence	125
Figure 10.61	DYBRD QPI Mode Command Sequence	125
Figure 10.62	DYBWR Command Sequence	126
Figure 10.63	DYBWR QPI Mode Command Sequence	126
Figure 10.64	PPBRD Command Sequence	127
Figure 10.65	PPBP Command Sequence	127
Figure 10.66	PPB Erase Command Sequence	128
Figure 10.67	PPB Lock Register Read Command Sequence	128
Figure 10.68	PPB Lock Bit Write Command Sequence	129
Figure 10.69	Password Read Command Sequence	129
Figure 10.70	Password Program Command Sequence	130
Figure 10.71	Password Unlock Command Sequence	131
Figure 10.72	Software Reset Command Sequence	132
Figure 10.73	Software Reset Command Sequence QPI Mode	132
Figure 10.74	Mode Bit Reset Command Sequence	133
Figure 10.75	Mode Bit Reset Command Sequence QPI Mode	133

Tables

Table 1.1	Maximum Read Rates	4
Table 1.2	Maximum Read Rates DDR	4
Table 1.3	Typical Program and Erase Rates	4
Table 1.4	Typical Current Consumption (–40°C to +85°C)	4
Table 2.1	Spansion SPI Families Comparison	13
Table 3.1	Signal List	18
Table 4.1	Interface States Summary	28
Table 5.1	Absolute Maximum Ratings	33
Table 5.2	Latch-Up Specification	33
Table 5.3	FS-S Power-Up / Power-Down Voltage and Timing	34
Table 5.4	FS-S DC Characteristics	36
Table 6.1	AC Measurement Conditions	37
Table 6.2	Capacitance	38
Table 6.3	Hardware Reset Parameters	39
Table 6.4	AC Characteristics	40
Table 6.5	AC Characteristics 80 MHz Operation	42
Table 8.1	S25FS256S Sector Address Map, Bottom 4-kB Sectors, 64-kB Physical Uniform Sectors	55
Table 8.2	S25FS256S Sector Address Map, Top 4-kB Sectors, 64-kB Physical Uniform Sectors	55
Table 8.3	S25FS256S Sector Address Map, Uniform 64-kB Physical Sectors	55
Table 8.4	S25FS256S Sector Address Map, Bottom 4-kB Sectors, 256-kB Logical Uniform Sectors	55
Table 8.6	S25FS256S Sector Address Map, Uniform 256-kB Logical Sectors	56
Table 8.7	S25FS128S Sector and Memory Address Map, Bottom 4-kB Sectors	56
Table 8.8	S25FS128S Sector and Memory Address Map, Top 4-kB Sectors	56
Table 8.9	S25FS128S Sector and Memory Address Map, Uniform 64-kB Blocks	56
Table 8.5	S25FS256S Sector Address Map, Top 4-kB Sectors, 256-kB Logical Uniform Sectors	56
Table 8.10	S25FS128S Sector Address Map, Bottom 4-kB Sectors, 256-kB Logical Uniform Sectors	57
Table 8.11	S25FS128S Sector Address Map, Top 4-kB Sectors, 256-kB Logical Uniform Sectors	57
Table 8.12	S25FS128S Sector and Memory Address Map, Uniform 256-kB Blocks	57
Table 8.13	OTP Address Map	59
Table 8.14	Status Register 1 Non-Volatile (SR1NV)	60
Table 8.15	Status Register 1 Volatile (SR1V)	61
Table 8.16	Status Register 2 Volatile (SR2V)	62
Table 8.17	Configuration Register 1 Non-Volatile (CR1NV)	63
Table 8.18	Configuration Register 1 Volatile (CR1V)	64
Table 8.19	Configuration Register 2 Non-Volatile (CR2NV)	66
Table 8.20	Latency Code (Cycles) Versus Frequency	67
Table 8.21	Configuration Register 2 Volatile (CR2V)	68
Table 8.22	Configuration Register 3 Non-Volatile (CR3NV)	69
Table 8.23	Configuration Register 3 Volatile (CR3V)	70
Table 8.24	Configuration Register 4 Non-Volatile (CR4NV)	71
Table 8.25	Output Impedance Control	71
Table 8.26	Configuration Register 4 Volatile (CR4V)	72
Table 8.27	ASP Register (ASPR)	73
Table 8.28	Password Register (PASS)	74
Table 8.29	PPB Lock Register (PPBL)	74
Table 8.30	PPB Access Register (PPBAR)	74
Table 8.31	DYB Access Register (DYBAR)	75
Table 8.32	Non-Volatile Data Learning Register (NVDLR)	75
Table 8.33	Volatile Data Learning Register (VDLR)	75
Table 9.1	Upper Array Start of Protection (TBPROT_O = 0)	77
Table 9.2	Lower Array Start of Protection (TBPROT_O = 1)	78
Table 9.3	Sector Protection States	83
Table 10.1	S25FS-S Family Command Set (sorted by function)	88
Table 10.2	Block Protection Modes	97

Table 10.3	Register Address Map	101
Table 10.4	Example Burst Wrap Sequences	104
Table 10.5	Commands Allowed During Program or Erase Suspend	120
Table 11.1	Program and Erase Performance	134
Table 11.2	Program or Erase Suspend AC Parameters	134
Table 12.1	S25FS-S Family Command Set (sorted by instruction)	135
Table 12.2	Status Register 1 Non-Volatile (SR1NV)	136
Table 12.3	Status Register 1 Volatile (SR1V)	137
Table 12.4	Status Register 2 Volatile (SR2V)	137
Table 12.5	Configuration Register 1 Non-Volatile (CR1NV)	138
Table 12.6	Configuration Register 1 Volatile (CR1V)	138
Table 12.7	Configuration Register 2 Non-Volatile (CR2NV)	138
Table 12.8	Configuration Register 2 Volatile (CR2V)	139
Table 12.9	Configuration Register 3 Non-Volatile (CR3NV)	139
Table 12.10	Configuration Register 3 Volatile (CR3V)	139
Table 12.11	Configuration Register 4 Non-Volatile (CR4NV)	140
Table 12.12	Configuration Register 4 Volatile (CR4V)	140
Table 12.13	ASP Register (ASPR)	140
Table 12.14	Password Register (PASS)	141
Table 12.15	PPB Lock Register (PPBL)	141
Table 12.16	PPB Access Register (PPBAR)	141
Table 12.17	DYB Access Register (DYBAR)	141
Table 12.18	Non-Volatile Data Learning Register (NVDLR)	141
Table 12.19	Volatile Data Learning Register (VDLR)	141
Table 12.20	SFDP Overview Map	142
Table 12.21	SFDP Header	142
Table 12.22	Manufacturer and Device ID	143
Table 12.23	CFI Query Identification String	143
Table 12.24	CFI System Interface String	144
Table 12.25	Device Geometry Definition for Bottom Boot Initial Delivery State	145
Table 12.26	CFI Primary Vendor-Specific Extended Query	146
Table 12.27	CFI Alternate Vendor-Specific Extended Query Header	147
Table 12.28	CFI Alternate Vendor-Specific Extended Query Parameter 0	147
Table 12.29	CFI Alternate Vendor-Specific Extended Query Parameter 80h Address Options	147
Table 12.30	CFI Alternate Vendor-Specific Extended Query Parameter 84h Suspend Commands	148
Table 12.31	CFI Alternate Vendor-Specific Extended Query Parameter 88h Data Protection	148
Table 12.32	CFI Alternate Vendor-Specific Extended Query Parameter 8Ch Reset Timing	148
Table 12.33	CFI Alternate Vendor-Specific Extended Query Parameter F0h RFU	149
Table 12.34	CFI Alternate Vendor-Specific Extended Query Parameter A5h, JEDEC SFDP	149

2. Overview

2.1 General Description

The Spansion S25FS-S family devices are flash non-volatile memory products using:

- MirrorBit technology - that stores two data bits in each memory array transistor
- Eclipse architecture - that dramatically improves program and erase performance
- 65 nm process lithography

The S25FS-S family connects to a host system via a Serial Peripheral Interface (SPI). Traditional SPI single bit serial input and output (Single I/O or SIO) is supported as well as optional 2-bit (Dual I/O or DIO) and 4-bit wide Quad I/O (QIO) or Quad Peripheral Interface (QPI) serial commands. This multiple width interface is called SPI Multi-I/O or MIO. In addition, there are Double Data Rate (DDR) read commands for QIO and QPI that transfer address and read data on both edges of the clock.

The FS-S Eclipse architecture features a Page Programming Buffer that allows up to 512 bytes to be programmed in one operation, resulting in faster effective programming and erase than prior generation SPI program or erase algorithms.

Executing code directly from flash memory is often called Execute-In-Place or XIP. By using S25FS-S family devices at the higher clock rates supported, with Quad or DDR Quad commands, the instruction read transfer rate can match or exceed traditional parallel interface, asynchronous, NOR flash memories, while reducing signal count dramatically.

The S25FS-S family products offer high densities coupled with the flexibility and fast performance required by a variety of mobile or embedded applications. They are an excellent solution for systems with limited space, signal connections, and power. They are ideal for code shadowing to RAM, executing code directly (XIP), and storing reprogrammable data.

2.2 Migration Notes

2.2.1 Features Comparison

The S25FS-S family is command subset and footprint compatible with prior generation FL-S, FL-K, and FL-P families. However, the power supply and interface voltages are nominal 1.8V.

Table 2.1 Spansion SPI Families Comparison

Parameter	FS-S	FL-S	FL-K	FL-P
Technology Node	65 nm	65 nm	90 nm	90 nm
Architecture	MirrorBit Eclipse	MirrorBit Eclipse	Floating Gate	MirrorBit
Density	128 Mb, 256 Mb	128 Mb, 256 Mb, 512 Mb, 1 Gb	4 Mb - 128 Mb	32 Mb - 256 Mb
Bus Width	x1, x2, x4	x1, x2, x4	x1, x2, x4	x1, x2, x4
Supply Voltage	1.7V - 2.0V	2.7V - 3.6V / 1.65V - 3.6V V_{IO}	2.7V - 3.6V	2.7V - 3.6V
Normal Read Speed (SDR)	6 MB/s (50 MHz)	6 MB/s (50 MHz)	6 MB/s (50 MHz)	6 MB/s (40 MHz)
Fast Read Speed (SDR)	16.5 MB/s (133 MHz)	17 MB/s (133 MHz)	13 MB/s (104 MHz)	13 MB/s (104 MHz)
Dual Read Speed (SDR)	33 MB/s (133 MHz)	26 MB/s (104 MHz)	26 MB/s (104 MHz)	20 MB/s (80 MHz)
Quad Read Speed (SDR)	66 MB/s (133 MHz)	52 MB/s (104 MHz)	52 MB/s (104 MHz)	40 MB/s (80 MHz)
Quad Read Speed (DDR)	80 MB/s (80 MHz)	80 MB/s (80 MHz)		
Program Buffer Size	256B / 512B	256B / 512B	256B	256B
Erase Sector Size	64 kB / 256 kB	64 kB / 256 kB	4 kB / 32 kB / 64 kB	64 kB / 256 kB
Parameter Sector Size	4 kB (option)	4 kB (option)	4 kB	4 kB
Sector Erase Rate (typ.)	500 kB/s	500 kB/s	136 kB/s (4 kB) 437 kB/s (64 kB)	130 kB/s
Page Programming Rate (typ.)	0.71 MB/s (256B) 1.08 MB/s (512B)	1.2 MB/s (256B) 1.5 MB/s (512B)	365 kB/s	170 kB/s
OTP	1024B	1024B	768B (3x256B)	506B
Advanced Sector Protection	Yes	Yes	No	No
Auto Boot Mode	No	Yes	No	No
Erase Suspend/Resume	Yes	Yes	Yes	No
Program Suspend/Resume	Yes	Yes	Yes	No
Operating Temperature	-40°C to +85°C / +105°C	-40°C to +85°C / +105°C	-40°C to +85°C°	-40°C to +85°C / +105°C

Notes:

1. The 256B program page option only for 128-Mb and 256-Mb density FL-S devices.
2. The FL-P column indicates FL129P MIO SPI device (for 128-Mb density), FL128P does not support MIO, OTP, or 4-kB sectors.
3. 64-kB Sector Erase option only for 128-Mb/256-Mb density FL-P, FL-S and FS-S devices.
4. The FL-K family devices can erase 4-kB sectors in groups of 32 kB or 64 kB.
5. 512-Mb/1-Gb FL-S devices support 256-kB sector only.
6. Only 128-Mb/256-Mb density FL-S devices have 4-kB parameter sector option.
7. Refer to individual data sheets for further details.

2.2.2 Known Differences from Prior Generations

2.2.2.1 Error Reporting

FL-K and FL-P memories either do not have error status bits or do not set them if program or erase is attempted on a protected sector. The FS-S and FL-S families do have error reporting status bits for program and erase operations. These can be set when there is an internal failure to program or erase, or when there is an attempt to program or erase a protected sector. In these cases the program or erase operation did not complete as requested by the command. The P_ERR or E_ERR bits and the WIP bit will be set to and remain 1 in SR1V. The clear Status Register command must be sent to clear the errors and return the device to standby state.

2.2.2.2 Secure Silicon Region (OTP)

The FS-S size and format (address map) of the One-Time Program area is different from FL-K and FL-P generations. The method for protecting each portion of the OTP area is different. For additional details see [Secure Silicon Region \(OTP\) on page 76](#).

2.2.2.3 Configuration Register Freeze Bit

The Configuration Register 1 Freeze bit CR1V[0], locks the state of the Block Protection bits (SR1NV[4:2] and SR1V[4:2]), TBPARM_O bit (CR1NV[2]), and TBPROT_O bit (CR1NV[5]), as in prior generations. In the FS-S and FL-S families the Freeze bit also locks the state of the Configuration Register 1 BPNV_O bit (CR1NV[3]), and the Secure Silicon Region (OTP) area.

2.2.2.4 Sector Erase Commands

The command for erasing a 4-kbyte sector is supported only for use on 4-kbyte parameter sectors at the top or bottom of the FS-S device address space.

The command for erasing an 8-kbyte area (two 4-kbyte sectors) is not supported.

The command for erasing a 32-kbyte area (eight 4-kbyte sectors) is not supported.

The Sector Erase command (SE) for FS-S 64-kbyte sectors is supported when the configuration option for uniform 64-kbyte sector is selected or, when the hybrid configuration option for 4-kbyte parameter sectors with 64-kbyte uniform sectors is used. When the hybrid option is in use, the 64-kbyte erase command may be used to erase the 32-kbyte of address space adjacent to the group of eight 4-kbyte sectors. The 64-kbyte erase command in this case is erasing the 64-kbyte sector that is partially overlaid by the group of eight 4-kbyte sectors without affecting the 4-kbyte sectors. This provides erase control over the 32 kbytes of address space without also forcing the erase of the 4-kbyte sectors. This is different behavior than implemented in the FL-S family. In the FL-S family, the 64-kbyte Sector Erase command can be applied to a 64-kbyte block of 4-kbyte sectors to erase the entire block of parameter sectors in a single operation. In the FS-S, the parameter sectors do not fill an entire 64-kbyte block so only the 4-kbyte Parameter Sector Erase (20h) is used to erase parameter sectors.

The erase command for a 256-kbyte sector replaces the 64-kbyte erase command when the configuration option for 256-kbyte uniform logical sectors is used.

2.2.2.5 Deep Power-Down

The Deep Power-Down (DPD) function is not supported in the FS-S and FL-S family devices.

2.2.2.6 WRR Single Register Write

In some legacy SPI devices, a Write Registers (WRR) command with only one data byte would update Status Register 1 and clear some bits in Configuration Register 1, including the Quad Mode bit. This could result in unintended exit from Quad Mode. The S25FS-S family only updates Status Register 1 when a single data byte is provided. The Configuration Register 1 is not modified in this case.

2.2.2.7 Other Legacy Commands Not Supported

- Autoboot Related Commands
- Bank Address Related Commands
- Dual Output Read
- Quad Output Read
- Quad Page Program (QPP) - replaced by Page Program in QPI Mode
- DDR Fast Read
- DDR Dual I/O Read

2.2.2.8 New Features

The FS-S family introduces new features to Spansion SPI category memories:

- Single 1.8V power supply for core and I/O voltage.
- Configurable initial read latency (number of dummy cycles) for faster initial access time or higher clock rate read commands
- Quad Peripheral Interface (QPI, 4-4-4) read mode in which all transfers are 4 bits wide, including instructions
- JEDEC JESD216 standard, Serial Flash Discoverable Parameters (SFDP) that provide device feature and configuration information.
- Evaluate Erase Status command to determine if the last erase operation on a sector completed successfully. This command can be used to detect incomplete erase due to power loss or other causes. This command can be helpful to Flash File System software in file system recovery after a power loss.
- Advanced Sector Protection (ASP) Permanent Protection. A bit is added to the ASP register to provide the option to make protection of the Persistent Protection Bits (PPB) permanent. Also, when one of the two ASP protection modes is selected, all OTP configuration bits in all registers are protected from further programming so that all OTP configuration settings are made permanent. The OTP address space is not protected by the selection of an ASP protection mode. The Freeze bit (CR1V[0]) may be used to protect the OTP Address Space.

2.3 Glossary

BCD (Binary Coded Decimal)	A value in which each 4-bit nibble represents a decimal numeral.
Command	All information transferred between the host system and memory during one period while CS# is low. This includes the instruction (sometimes called an operation code or opcode) and any required address, mode bits, latency cycles, or data.
DDP (Dual Die Package)	Two die stacked within the same package to increase the memory capacity of a single package. Often also referred to as a Multi-Chip Package (MCP).
DDR (Double Data Rate)	When input and output are latched on every edge of SCK.
Flash	The name for a type of Electrical Erase Programmable Read Only Memory (EEPROM) that erases large blocks of memory bits in parallel, making the erase operation much faster than early EEPROM.
High	A signal voltage level $\geq V_{IH}$ or a logic level representing a binary one (1).
Instruction	The 8-bit code indicating the function to be performed by a command (sometimes called an operation code or opcode). The instruction is always the first 8 bits transferred from host system to the memory in any command.
Low	A signal voltage level $\leq V_{IL}$ or a logic level representing a binary zero (0).
LSB (Least Significant Bit)	Generally the right most bit, with the lowest order of magnitude value, within a group of bits of a register or data value.
MSB (Most Significant Bit)	Generally the left most bit, with the highest order of magnitude value, within a group of bits of a register or data value.
N/A (Not Applicable)	A value is not relevant to situation described.
Non-Volatile	No power is needed to maintain data stored in the memory.
OPN	Ordering Part Number. The alphanumeric string specifying the memory device type, density, package, factory non-volatile configuration, etc. used to select the desired device.
Page	512-byte or 256-byte aligned and length group of data. The size assigned for a page depends on the Ordering Part Number.
PCB	Printed Circuit Board.
Register Bit References	Are in the format: Register_name[bit_number] or Register_name[bit_range_MSB:bit_range_LSB]
SDR (Single Data Rate)	When input is latched on the rising edge and output on the falling edge of SCK.
Sector	Erase unit size; depending on device model and sector location this may be 4 kbytes, 64 kbytes or 256 kbytes.
Write	An operation that changes data within volatile or non-volatile registers bits or non-volatile flash memory. When changing non-volatile data, an erase and reprogramming of any unchanged non-volatile data is done, as part of the operation, such that the non-volatile data is modified by the write operation, in the same way that volatile data is modified – as a single operation. The non-volatile data appears to the host system to be updated by the single write command, without the need for separate commands for erase and reprogram of adjacent, but unaffected data.

2.4 Other Resources

2.4.1 Links to software

<http://www.spansion.com/Support/Pages/Support.aspx>

2.4.2 Links to application notes

<http://www.spansion.com/Support/TechnicalDocuments/Pages/ApplicationNotes.aspx>

2.4.3 Specification Bulletins

Specification bulletins provide information on temporary differences in feature description or parametric variance since the publication of the last full data sheet. Contact your local sales office for details. Obtain the latest list of company locations and contact information at:

<http://www.spansion.com/About/Pages/Locations.aspx>

Hardware Interface

Serial Peripheral Interface with Multiple Input / Output (SPI-MIO)

Many memory devices connect to their host system with separate parallel control, address, and data signals that require a large number of signal connections and larger package size. The large number of connections increase power consumption due to so many signals switching and the larger package increases cost.

The S25FS-S family reduces the number of signals for connection to the host system by serially transferring all control, address, and data information over 4 to 6 signals. This reduces the cost of the memory package, reduces signal switching power, and either reduces the host connection count or frees host connectors for use in providing other features.

The S25FS-S family uses the industry standard single bit Serial Peripheral Interface (SPI) and also supports optional extension commands for 2-bit (Dual) and 4-bit (Quad) wide serial transfers. This multiple width interface is called SPI Multi-I/O or SPI-MIO.

3. Signal Descriptions

3.1 Input/Output Summary

Table 3.1 Signal List

Signal Name	Type	Description
SCK	Input	Serial Clock.
CS#	Input	Chip Select.
SI / IO0	I/O	Serial Input for single bit data commands or IO0 for Dual or Quad commands.
SO / IO1	I/O	Serial Output for single bit data commands. IO1 for Dual or Quad commands.
WP# / IO2	I/O	Write Protect when not in Quad Mode (CR1V[1] = 0 and SR1NV[7] = 1). IO2 when in Quad Mode (CR1V[1] = 1). The signal has an internal pull-up resistor and may be left unconnected in the host system if not used for Quad commands or write protection. If write protection is enabled by SR1NV[7] = 1 and CR1V[1] = 0, the host system is required to drive WP# high or low during a WRR or WRAR command.
IO3 / RESET#	I/O	IO3 in Quad-I/O mode, when Configuration Register 1 QUAD bit, CR1V[1] = 1, and CS# is low. RESET# when enabled by CR2V[5] = 1 and not in Quad-I/O mode, CR1V[1] = 0, or when enabled in Quad Mode, CR1V[1] = 1 and CS# is high. The signal has an internal pull-up resistor and may be left unconnected in the host system if not used for Quad commands or RESET#.
V _{DD}	Supply	Power Supply.
V _{SS}	Supply	Ground.
NC	Unused	Not Connected. No device internal signal is connected to the package connector nor is there any future plan to use the connector for a signal. The connection may safely be used for routing space for a signal on a Printed Circuit Board (PCB). However, any signal connected to an NC must not have voltage levels higher than V _{DD} .
RFU	Reserved	Reserved for Future Use. No device internal signal is currently connected to the package connector but there is potential future use of the connector for a signal. It is recommended to not use RFU connectors for PCB routing channels so that the PCB may take advantage of future enhanced features in compatible footprint devices.
DNU	Reserved	Do Not Use. A device internal signal may be connected to the package connector. The connection may be used by Spansion for test or other purposes and is not intended for connection to any host system signal. Any DNU signal related function will be inactive when the signal is at V _{IL} . The signal has an internal pull-down resistor and may be left unconnected in the host system or may be tied to V _{SS} . Do not use these connections for PCB signal routing channels. Do not connect any host system signal to this connection.

3.2 Multiple Input / Output (MIO)

Traditional SPI single bit wide commands (Single or SIO) send information from the host to the memory only on the Serial Input (SI) signal. Data may be sent back to the host serially on the Serial Output (SO) signal.

Dual or Quad Input / Output (I/O) commands send instructions to the memory only on the SI/IO0 signal. Address or data is sent from the host to the memory as bit pairs on IO0 and IO1 or four bit (nibble) groups on IO0, IO1, IO2, and IO3. Data is returned to the host similarly as bit pairs on IO0 and IO1 or four bit (nibble) groups on IO0, IO1, IO2, and IO3.

QPI Mode transfers all instructions, address, and data from the host to the memory as four bit (nibble) groups on IO0, IO1, IO2, and IO3. Data is returned to the host similarly as four bit (nibble) groups on IO0, IO1, IO2, and IO3.

3.3 Serial Clock (SCK)

This input signal provides the synchronization reference for the SPI interface. Instructions, addresses, or data input are latched on the rising edge of the SCK signal. Data output changes after the falling edge of SCK, in SDR commands, and after every edge in DDR commands.

3.4 Chip Select (CS#)

The Chip Select signal indicates when a command is transferring information to or from the device and the other signals are relevant for the memory device.

When the CS# signal is at the logic high state, the device is not selected and all input signals are ignored and all output signals are high impedance. The device will be in the Standby Power mode, unless an internal embedded operation is in progress. An embedded operation is indicated by the Status Register 1 Write-In-Progress bit (SR1V[1]) set to 1, until the operation is completed. Some example embedded operations are: Program, Erase, or Write Registers (WRR) operations.

Driving the CS# input to the logic low state enables the device, placing it in the Active Power mode. After power-up, a falling edge on CS# is required prior to the start of any command.

3.5 Serial Input (SI) / IO0

This input signal is used to transfer data serially into the device. It receives instructions, addresses, and data to be programmed. Values are latched on the rising edge of serial SCK clock signal.

SI becomes IO0 - an input and output during Dual and Quad commands for receiving instructions, addresses, and data to be programmed (values latched on rising edge of serial SCK clock signal) as well as shifting out data (on the falling edge of SCK, in SDR commands, and on every edge of SCK, in DDR commands).

3.6 Serial Output (SO) / IO1

This output signal is used to transfer data serially out of the device. Data is shifted out on the falling edge of the serial SCK clock signal.

SO becomes IO1 - an input and output during Dual and Quad commands for receiving addresses, and data to be programmed (values latched on rising edge of serial SCK clock signal) as well as shifting out data (on the falling edge of SCK, in SDR commands, and on every edge of SCK, in DDR commands).

3.7 Write Protect (WP#) / IO2

When WP# is driven Low (V_{IL}), during a WRR or WRAR command and while the Status Register Write Disable (SRWD_NV) bit of Status Register 1 (SR1NV[7]) is set to a 1, it is not possible to write to Status Register 1 or Configuration Register 1 related registers. In this situation, a WRR command is ignored, a WRAR command selecting SR1NV, SR1V, CR1NV, or CR1V is ignored, and no error is set.

This prevents any alteration of the Block Protection settings. As a consequence, all the data bytes in the memory area that are protected by the Block Protection feature are also hardware protected against data modification if WP# is Low during a WRR or WRAR command with SRWD_NV set to 1.

The WP# function is not available when the Quad Mode is enabled (CR1V[1]=1). The WP# function is replaced by IO2 for input and output during Quad Mode for receiving addresses, and data to be programmed (values are latched on rising edge of the SCK signal) as well as shifting out data (on the falling edge of SCK, in SDR commands, and on every edge of SCK, in DDR commands).

WP# has an internal pull-up resistance; when unconnected, WP# is at V_{IH} and may be left unconnected in the host system if not used for Quad Mode or protection.

3.8 IO3 / RESET#

IO3 is used for input and output during Quad Mode (CR1V[1]=1) for receiving addresses, and data to be programmed (values are latched on rising edge of the SCK signal) as well as shifting out data (on the falling edge of SCK, in SDR commands, and on every edge of SCK, in DDR commands).

The IO3 / RESET# signal may also be used to initiate the hardware reset function when the reset feature is enabled by writing Configuration Register 2 non-volatile bit 5 (CR2V[5]=1). The input is only treated as RESET# when the device is not in Quad-I/O mode, CR1V[1] = 0, or when CS# is high. When Quad I/O mode is in use, CR1V[1]=1, and the device is selected with CS# low, the IO3 / RESET# is used only as IO3 for information transfer. When CS# is high, the IO3 / RESET# is not in use for information transfer and is used as the RESET# input. By conditioning the reset operation on CS# high during Quad Mode, the reset function remains available during Quad Mode.

When the system enters a reset condition, the CS# signal must be driven high as part of the reset process and the IO3 / RESET# signal is driven low. When CS# goes high the IO3 / RESET# input transitions from being IO3 to being the RESET# input. The reset condition is then detected when CS# remains high and the IO3 / RESET# signal remains low for t_{RP} . If a reset is not intended, the system is required to actively drive IO3 / Reset# to high along with CS# being driven high at the end of a transfer of data to the memory. Following transfers of data to the host system, the memory will drive IO3 high during t_{CS} . This will ensure that IO3 / Reset is not left floating or being pulled slowly to high by the internal or an external passive pull-up. Thus, an unintended reset is not triggered by the IO3 / RESET# not being recognized as high before the end of t_{RP} .

The IO3 / RESET# signal is unused when the reset feature is disabled (CR2V[5]=0).

The IO3 / RESET# signal has an internal pull-up resistor and may be left unconnected in the host system if not used for Quad Mode or the reset function. The internal pull-up will hold IO3 / RESET high after the host system has actively driven the signal high and then stops driving the signal.

Note that IO3 / RESET# cannot be shared by more than one SPI-MIO memory if any of them are operating in Quad I/O mode as IO3 being driven to or from one selected memory may look like a reset signal to a second non-selected memory sharing the same IO3 / RESET# signal.

3.9 Voltage Supply (V_{DD})

V_{DD} is the voltage source for all device internal logic. It is the single voltage used for all device internal functions including read, program, and erase.

3.10 Supply and Signal Ground (V_{SS})

V_{SS} is the common voltage drain and ground reference for the device core, input signal receivers, and output drivers.

3.11 Not Connected (NC)

No device internal signal is connected to the package connector nor is there any future plan to use the connector for a signal. The connection may safely be used for routing space for a signal on a Printed Circuit Board (PCB).

3.12 Reserved for Future Use (RFU)

No device internal signal is currently connected to the package connector but there is potential future use of the connector. It is recommended to not use RFU connectors for PCB routing channels so that the PCB may take advantage of future enhanced features in compatible footprint devices.

3.13 Do Not Use (DNU)

A device internal signal may be connected to the package connector. The connection may be used by Spansion for test or other purposes and is not intended for connection to any host system signal. Any DNU signal related function will be inactive when the signal is at V_{IL} . The signal has an internal pull-down resistor and may be left unconnected in the host system or may be tied to V_{SS} . Do not use these connections for PCB signal routing channels. Do not connect any host system signal to these connections.

3.14 Block Diagrams

Figure 3.1 Bus Master and Memory Devices on the SPI Bus - Single Bit Data Path

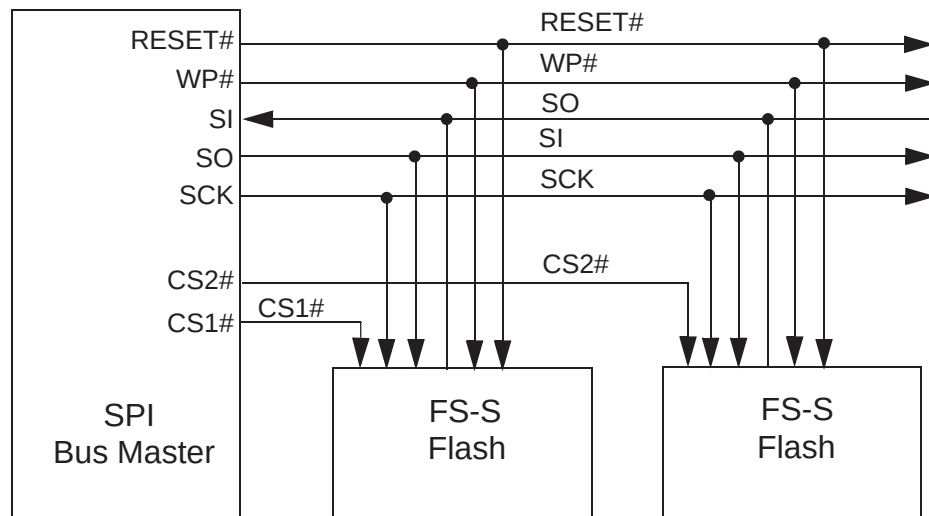


Figure 3.2 Bus Master and Memory Devices on the SPI Bus - Dual Bit Data Path

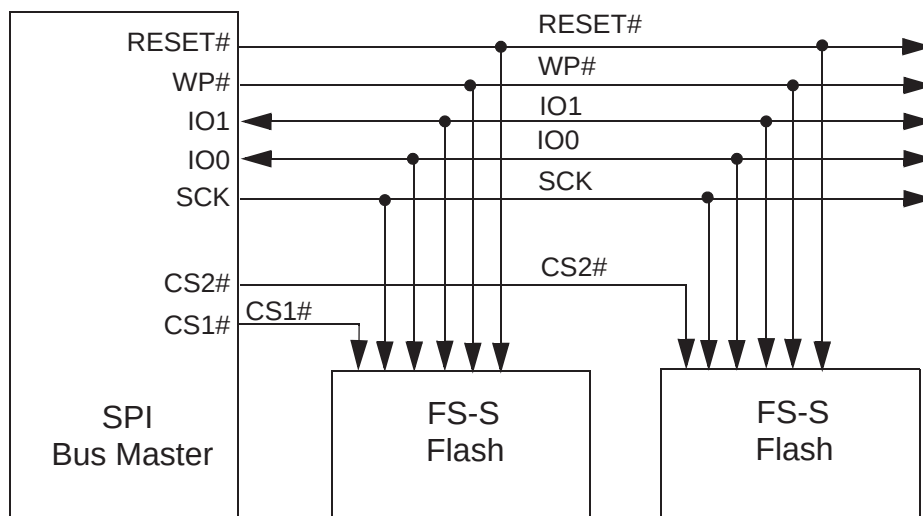
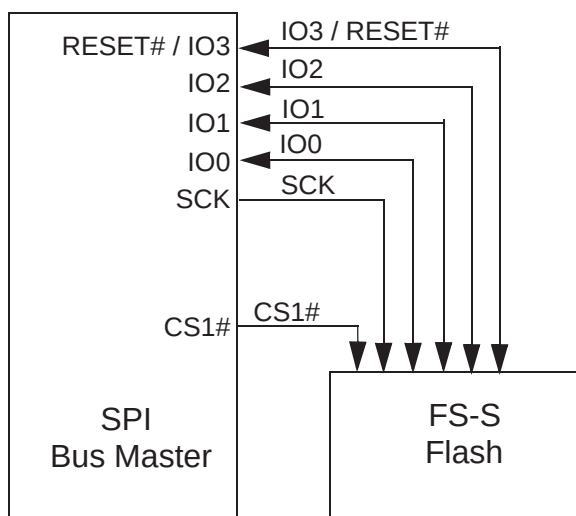


Figure 3.3 Bus Master and Memory Devices on the SPI Bus - Quad Bit Data Path



4. Signal Protocols

4.1 SPI Clock Modes

4.1.1 Single Data Rate (SDR)

The S25FS-S family can be driven by an embedded microcontroller (bus master) in either of the two following clocking modes.

- **Mode 0** with Clock Polarity (CPOL) = 0 and, Clock Phase (CPHA) = 0
- **Mode 3** with CPOL = 1 and, CPHA = 1

For these two modes, input data into the device is always latched in on the rising edge of the SCK signal and the output data is always available from the falling edge of the SCK clock signal.

The difference between the two modes is the clock polarity when the bus master is in standby mode and not transferring any data.

- SCK will stay at logic low state with CPOL = 0, CPHA = 0
- SCK will stay at logic high state with CPOL = 1, CPHA = 1

Figure 4.1 SPI SDR Modes Supported



Timing diagrams throughout the remainder of the document are generally shown as both Mode 0 and 3 by showing SCK as both high and low at the fall of CS#. In some cases a timing diagram may show only Mode 0 with SCK low at the fall of CS#. In such a case, Mode 0 timing simply means the clock is high at the fall of CS# so no SCK rising edge set up or hold time to the falling edge of CS# is needed for Mode 0.

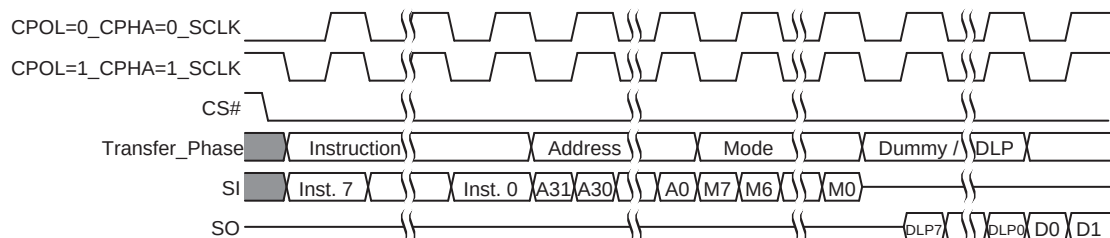
SCK cycles are measured (counted) from one falling edge of SCK to the next falling edge of SCK. In Mode 0 the beginning of the first SCK cycle in a command is measured from the falling edge of CS# to the first falling edge of SCK because SCK is already low at the beginning of a command.

4.1.2 Double Data Rate (DDR)

Mode 0 and Mode 3 are also supported for DDR commands. In DDR commands, the instruction bits are always latched on the rising edge of clock, the same as in SDR commands. However, the address and input data that follow the instruction are latched on both the rising and falling edges of SCK. The first address bit is latched on the first rising edge of SCK following the falling edge at the end of the last instruction bit. The first bit of output data is driven on the falling edge at the end of the last access latency (dummy) cycle.

SCK cycles are measured (counted) in the same way as in SDR commands, from one falling edge of SCK to the next falling edge of SCK. In Mode 0 the beginning of the first SCK cycle in a command is measured from the falling edge of CS# to the first falling edge of SCK because SCK is already low at the beginning of a command.

Figure 4.2 SPI DDR Modes Supported



4.2 Command Protocol

All communication between the host system and S25FS-S family memory devices is in the form of units called commands.

All commands begin with an 8-bit instruction that selects the type of information transfer or device operation to be performed. Commands may also have an address, instruction modifier, latency period, data transfer to the memory, or data transfer from the memory. All instruction, address, and data information is transferred sequentially between the host system and memory device.

Command protocols are also classified by a numerical nomenclature using three numbers to reference the transfer width of three command phases:

- instruction;
- address and instruction modifier (Continuous Read mode bits);
- data.

Single bit wide commands start with an instruction and may provide an address or data, all sent only on the SI signal. Data may be sent back to the host serially on the SO signal. This is referenced as a 1-1-1 command protocol for single bit width instruction, single bit width address and modifier, single bit data.

Dual or Quad Input / Output (I/O) commands provide an address sent from the host as bit pairs on IO0 and IO1 or, four bit (nibble) groups on IO0, IO1, IO2, and IO3. Data is returned to the host similarly as bit pairs on IO0 and IO1 or, four bit (nibble) groups on IO0, IO1, IO2, and IO3. This is referenced as 1-2-2 for Dual I/O and 1-4-4 for Quad I/O command protocols.

The S25FS-S family also supports a QPI Mode in which all information is transferred in 4-bit width, including the instruction, address, modifier, and data. This is referenced as a 4-4-4 command protocol.

Commands are structured as follows:

- Each command begins with CS# going low and ends with CS# returning high. The memory device is selected by the host driving the Chip Select (CS#) signal low throughout a command.
- The Serial Clock (SCK) marks the transfer of each bit or group of bits between the host and memory.
- Each command begins with an 8-bit (byte) instruction. The instruction selects the type of information transfer or device operation to be performed. The instruction transfers occur on SCK rising edges. However, some read commands are modified by a prior read command, such that the instruction is implied from the earlier command. This is called Continuous Read mode. When the device is in Continuous Read mode, the instruction bits are not transmitted at the beginning of the command because the instruction is the same as the read command that initiated the Continuous Read mode. In Continuous Read mode the command will begin with the read address. Thus, Continuous Read mode removes eight instruction bits from each read command in a series of same type read commands.
- The instruction may be stand alone or may be followed by address bits to select a location within one of several address spaces in the device. The instruction determines the address space used. The address may be either a 24-bit or a 32-bit, byte boundary, address. The address transfers occur on SCK rising edge, in SDR commands, or on every SCK edge, in DDR commands.
- In legacy SPI mode, the width of all transfers following the instruction are determined by the instruction sent. Following transfers may continue to be single bit serial on only the SI or Serial Output (SO) signals, they may be done in two bit groups per (dual) transfer on the IO0 and IO1 signals, or they may be done in 4-bit groups per (quad) transfer on the IO0-IO3 signals. Within the dual or quad groups the least significant bit is on IO0. More significant bits are placed in significance order on each higher numbered IO signal. Single bits or parallel bit groups are transferred in most to least significant bit order.
- In QPI Mode, the width of all transfers is a 4-bit wide (Quad) transfer on the IO0-IO3 signals.
- Dual and Quad I/O read instructions send an instruction modifier called Continuous Read mode bits, following the address, to indicate whether the next command will be of the same type with an implied, rather than an explicit, instruction. These mode bits initiate or end the Continuous Read mode. In Continuous Read mode, the next command thus does not provide an instruction byte, only a new address and mode bits. This reduces the time needed to send each command when the same command type is repeated in a sequence of commands. The mode bit transfers occur on SCK rising edge, in SDR commands, or on every SCK edge, in DDR commands.

- The address or mode bits may be followed by write data to be stored in the memory device or by a read latency period before read data is returned to the host.
- Write data bit transfers occur on SCK rising edge, in SDR commands, or on every SCK edge, in DDR commands.
- SCK continues to toggle during any read access latency period. The latency may be zero to several SCK cycles (also referred to as dummy cycles). At the end of the read latency cycles, the first read data bits are driven from the outputs on SCK falling edge at the end of the last read latency cycle. The first read data bits are considered transferred to the host on the following SCK rising edge. Each following transfer occurs on the next SCK rising edge, in SDR commands, or on every SCK edge, in DDR commands.
- If the command returns read data to the host, the device continues sending data transfers until the host takes the CS# signal high. The CS# signal can be driven high after any transfer in the read data sequence. This will terminate the command.
- At the end of a command that does not return data, the host drives the CS# input high. The CS# signal must go high after the eighth bit, of a stand alone instruction or, of the last write data byte that is transferred. That is, the CS# signal must be driven high when the number of bits after the CS# signal was driven low is an exact multiple of eight bits. If the CS# signal does not go high exactly at the eight bit boundary of the instruction or write data, the command is rejected and not executed.
- All instruction, address, and mode bits are shifted into the device with the Most Significant Bits (MSB) first. The data bits are shifted in and out of the device MSB first. All data is transferred in byte units with the lowest address byte sent first. The following bytes of data are sent in lowest to highest byte address order i.e. the byte address increments.
- All attempts to read the flash memory array during a program, erase, or a write cycle (embedded operations) are ignored. The embedded operation will continue to execute without any affect. A very limited set of commands are accepted during an embedded operation. These are discussed in the individual command descriptions.
- Depending on the command, the time for execution varies. A command to read status information from an executing command is available to determine when the command completes execution and whether the command was successful.

4.2.1 Command Sequence Examples

Figure 4.3 Stand Alone Instruction Command

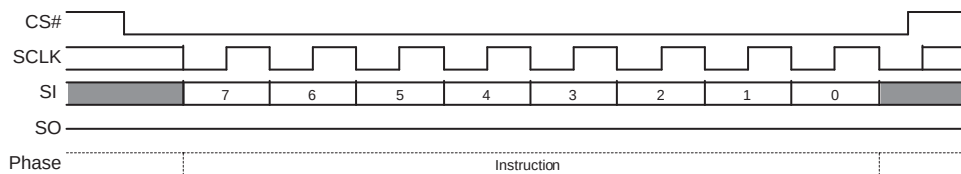


Figure 4.4 Single Bit Wide Input Command

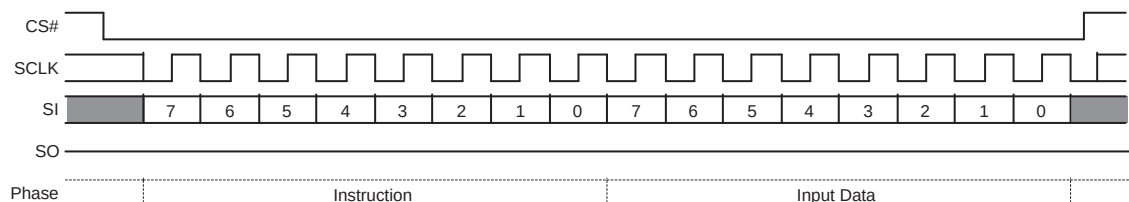


Figure 4.5 Single Bit Wide Output Command

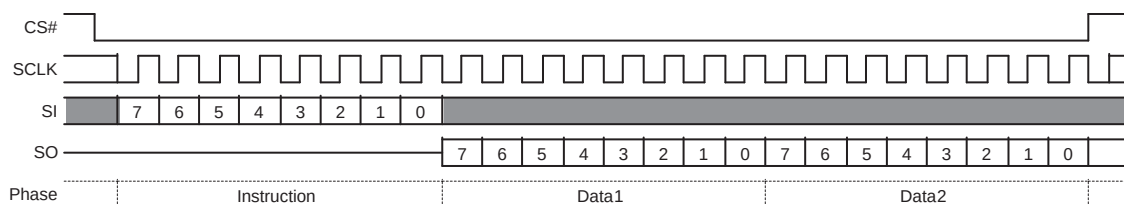


Figure 4.6 Single Bit Wide I/O Command without Latency

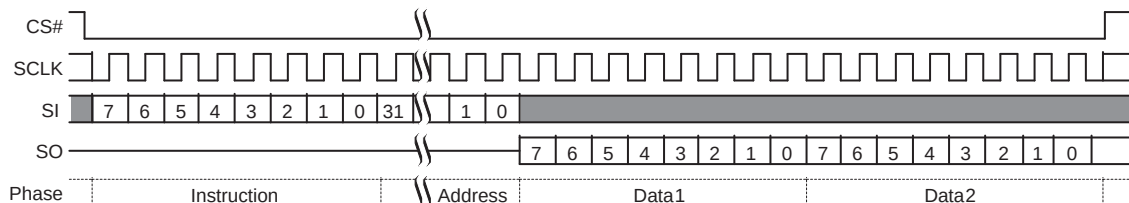


Figure 4.7 Single Bit Wide I/O Command with Latency

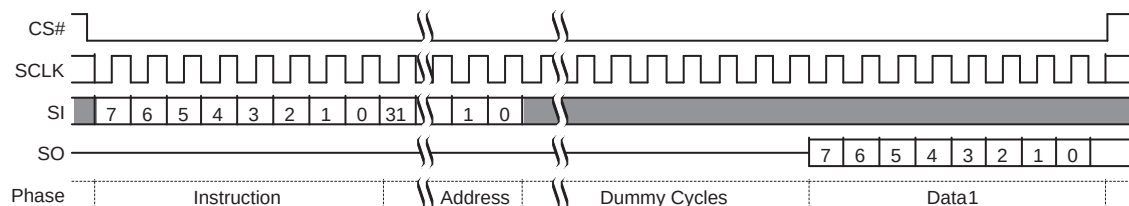


Figure 4.8 Dual I/O Command

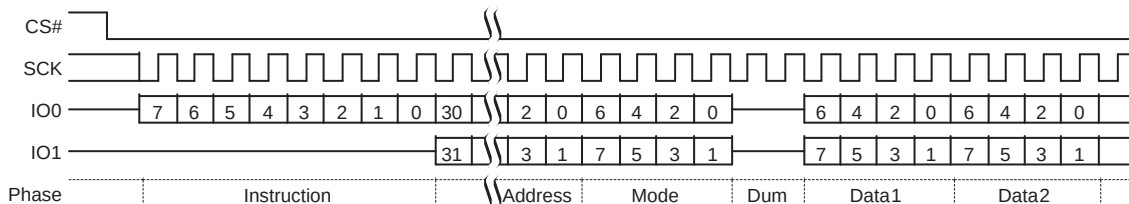


Figure 4.9 Quad I/O Command

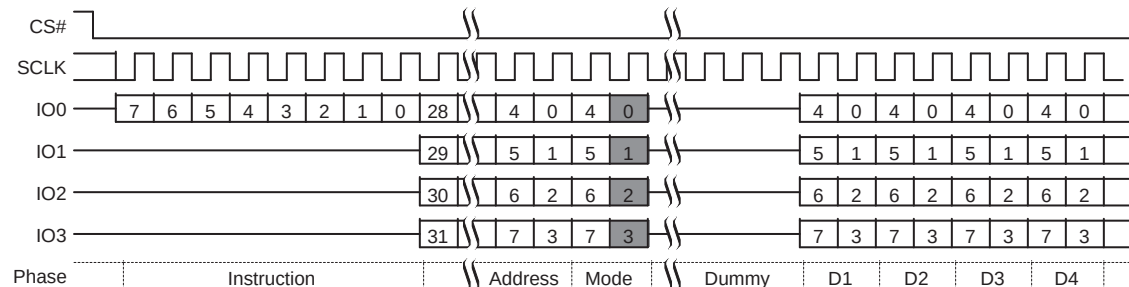
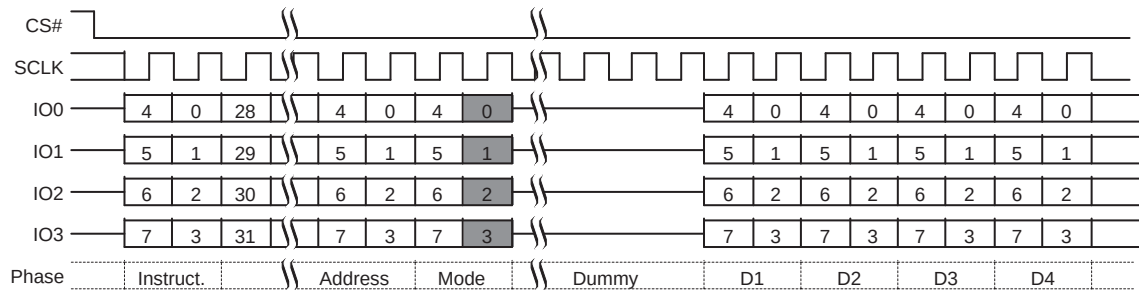
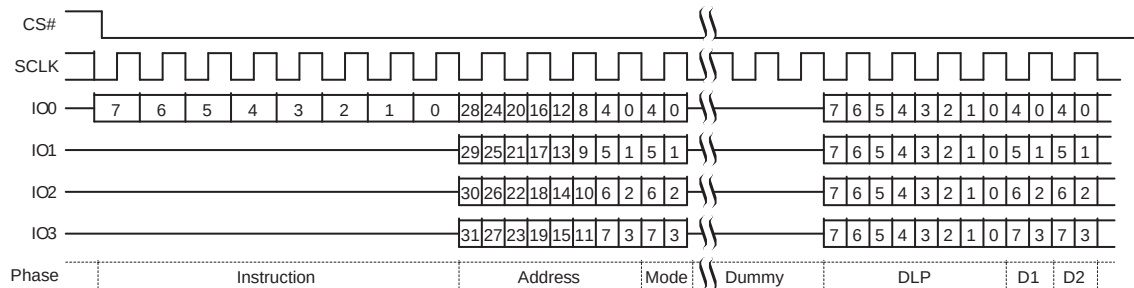
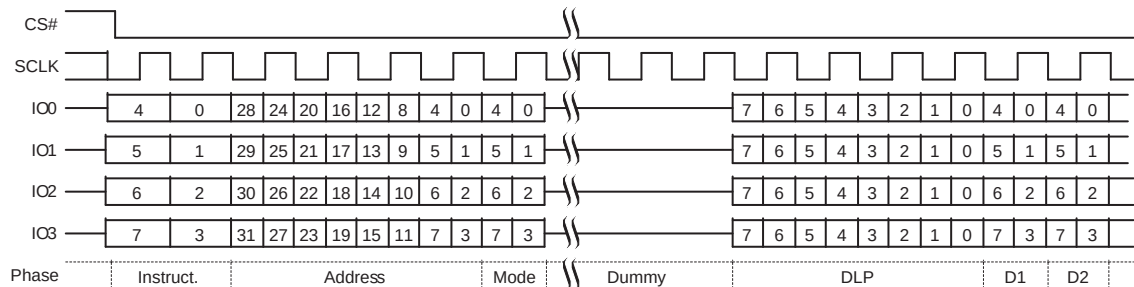


Figure 4.10 Quad I/O Read Command in QPI Mode**Figure 4.11** DDR Quad I/O Read**Figure 4.12** DDR Quad I/O Read in QPI Mode

Additional sequence diagrams, specific to each command, are provided in [Commands on page 85](#)

4.3 Interface States

This section describes the input and output signal levels as related to the SPI interface behavior.

Table 4.1 Interface States Summary

Interface State	V _{DD}	SCK	CS#	IO3 / RESET#	WP# / IO2	SO / IO1	SI / IO0
Power-Off	<V _{DD} (low)	X	X	X	X	Z	X
Low-Power Hardware Data Protection	<V _{DD} (cut-off)	X	X	X	X	Z	X
Power-On (Cold) Reset	≥V _{DD} (min)	X	HH	X	X	Z	X
Hardware (Warm) Reset Non-Quad Mode	≥V _{DD} (min)	X	X	HL	X	Z	X
Hardware (Warm) Reset Quad Mode	≥V _{DD} (min)	X	HH	HL	X	Z	X
Interface Standby	≥V _{DD} (min)	X	HH	X	X	Z	X
Instruction Cycle (Legacy SPI)	≥V _{DD} (min)	HT	HL	HH	HV	Z	HV
Single Input Cycle Host to Memory Transfer	≥V _{DD} (min)	HT	HL	HH	X	Z	HV
Single Latency (Dummy) Cycle	≥V _{DD} (min)	HT	HL	HH	X	Z	X
Single Output Cycle Memory to Host Transfer	≥V _{DD} (min)	HT	HL	HH	X	MV	X
Dual Input Cycle Host to Memory Transfer	≥V _{DD} (min)	HT	HL	HH	X	HV	HV
Dual Latency (Dummy) Cycle	≥V _{DD} (min)	HT	HL	HH	X	X	X
Dual Output Cycle Memory to Host Transfer	≥V _{DD} (min)	HT	HL	HH	X	MV	MV
Quad Input Cycle Host to Memory Transfer	≥V _{DD} (min)	HT	HL	HV	HV	HV	HV
Quad Latency (Dummy) Cycle	≥V _{DD} (min)	HT	HL	X	X	X	X
Quad Output Cycle Memory to Host Transfer	≥V _{DD} (min)	HT	HL	MV	MV	MV	MV
DDR Quad Input Cycle Host to Memory Transfer	≥V _{DD} (min)	HT	HL	HV	HV	HV	HV
DDR Latency (Dummy) Cycle	≥V _{DD} (min)	HT	HL	MV or Z	MV or Z	MV or Z	MV or Z
DDR Quad Output Cycle Memory to Host Transfer	≥V _{DD} (min)	HT	HL	MV	MV	MV	MV

Legend

Z = No driver - floating signal
 HL = Host driving V_{IL}
 HH = Host driving V_{IH}
 HV = Either HL or HH
 X = HL or HH or Z
 HT = Toggling between HL and HH
 ML = Memory driving V_{IL}
 MH = Memory driving V_{IH}
 MV = Either ML or MH

4.3.1 Power-Off

When the core supply voltage is at or below the V_{DD (Low)} voltage, the device is considered to be powered off. The device does not react to external signals, and is prevented from performing any program or erase operation.

4.3.2 Low-Power Hardware Data Protection

When V_{DD} is less than V_{DD (Cut-off)} the memory device will ignore commands to ensure that program and erase operations can not start when the core supply voltage is out of the operating range.

4.3.3 Power-On (Cold) Reset

When the core voltage supply remains at or below the $V_{DD(Low)}$ voltage for $\geq t_{PD}$ time, then rises to $\geq V_{DD(Minimum)}$ the device will begin its Power-On Reset (POR) process. POR continues until the end of t_{PU} . During t_{PU} the device does not react to external input signals nor drive any outputs. Following the end of t_{PU} the device transitions to the Interface Standby state and can accept commands. For additional information on POR see [Power-On \(Cold\) Reset on page 38](#)

4.3.4 Hardware (Warm) Reset

A configuration option is provided to allow IO3 to be used as a hardware reset input when the device is not in Quad Mode or when it is in Quad Mode and CS# is high. When IO3 / RESET# is driven low for t_{RP} time the device starts the hardware reset process. The process continues for t_{RPH} time. Following the end of both t_{RPH} and the reset hold time following the rise of RESET# (t_{RH}) the device transitions to the Interface Standby state and can accept commands. For additional information on hardware reset see [Reset on page 38](#)

4.3.5 Interface Standby

When CS# is high the SPI interface is in standby state. Inputs other than RESET# are ignored. The interface waits for the beginning of a new command. The next interface state is Instruction Cycle when CS# goes low to begin a new command.

While in interface standby state the memory device draws standby current (I_{SB}) if no embedded algorithm is in progress. If an embedded algorithm is in progress, the related current is drawn until the end of the algorithm when the entire device returns to standby current draw.

4.3.6 Instruction Cycle (Legacy SPI Mode)

When the host drives the MSB of an instruction and CS# goes low, on the next rising edge of SCK the device captures the MSB of the instruction that begins the new command. On each following rising edge of SCK the device captures the next lower significance bit of the 8-bit instruction. The host keeps CS# low, and drives the Write Protect (WP#) and IO3/RESET signals as needed for the instruction. However, WP# is only relevant during instruction cycles of a WRR or WRAR command and is otherwise ignored. IO3/RESET# is driven high when the device is not in Quad Mode ($CR1V[1]=0$) or QPI Mode ($CR2V[6]=0$) and hardware reset is not required.

Each instruction selects the address space that is operated on and the transfer format used during the remainder of the command. The transfer format may be Single, Dual I/O, Quad I/O, or DDR Quad I/O. The expected next interface state depends on the instruction received.

Some commands are stand alone, needing no address or data transfer to or from the memory. The host returns CS# high after the rising edge of SCK for the eighth bit of the instruction in such commands. The next interface state in this case is Interface Standby.

4.3.7 Instruction Cycle (QPI Mode)

In QPI Mode, when $CR2V[6]=1$, instructions are transferred 4 bits per cycle. In this mode, instruction cycles are the same as a Quad Input Cycle. See [Quad Input Cycle - Host to Memory Transfer on page 30](#).

4.3.8 Single Input Cycle - Host to Memory Transfer

Several commands transfer information after the instruction on the single Serial Input (SI) signal from host to the memory device. The host keeps RESET# high, CS# low, and drives SI as needed for the command. The memory does not drive the Serial Output (SO) signal.

The expected next interface state depends on the instruction. Some instructions continue sending address or data to the memory using additional Single Input Cycles. Others may transition to Single Latency, or directly to Single, Dual, or Quad Output Cycle states.

4.3.9 Single Latency (Dummy) Cycle

Read commands may have zero to several latency cycles during which read data is read from the main flash memory array before transfer to the host. The number of latency cycles are determined by the Latency Code in the Configuration Register (CR2V[3:0]). During the latency cycles, the host keeps RESET# high, CS# low. The Write Protect (WP#) signal is ignored. The host may drive the SI signal during these cycles or the host may leave SI floating. The memory does not use any data driven on SI / IO0 or other I/O signals during the latency cycles. The memory does not drive the Serial Output (SO) or I/O signals during the latency cycles.

The next interface state depends on the command structure i.e. the number of latency cycles, and whether the read is single, dual, or quad width.

4.3.10 Single Output Cycle - Memory to Host Transfer

Several commands transfer information back to the host on the single Serial Output (SO) signal. The host keeps RESET# high, CS# low. The Write Protect (WP#) signal is ignored. The memory ignores the Serial Input (SI) signal. The memory drives SO with data.

The next interface state continues to be Single Output Cycle until the host returns CS# to high ending the command.

4.3.11 Dual Input Cycle - Host to Memory Transfer

The Read Dual I/O command transfers two address or mode bits to the memory in each cycle. The host keeps RESET# high, CS# low. The Write Protect (WP#) signal is ignored. The host drives address on SI / IO0 and SO / IO1.

The next interface state following the delivery of address and mode bits is a Dual Latency Cycle if there are latency cycles needed or Dual Output Cycle if no latency is required.

4.3.12 Dual Latency (Dummy) Cycle

Read commands may have zero to several latency cycles during which read data is read from the main flash memory array before transfer to the host. The number of latency cycles are determined by the Latency Code in the Configuration Register (CR2V[3:0]). During the latency cycles, the host keeps RESET# high, CS# low. The Write Protect (WP#) signal is ignored. The host may drive the SI / IO0 and SO / IO1 signals during these cycles or the host may leave SI / IO0 and SO / IO1 floating. The memory does not use any data driven on SI / IO0 and SO / IO1 during the latency cycles. The host must stop driving SI / IO0 and SO / IO1 on the falling edge at the end of the last latency cycle. It is recommended that the host stop driving them during all latency cycles so that there is sufficient time for the host drivers to turn off before the memory begins to drive at the end of the latency cycles. This prevents driver conflict between host and memory when the signal direction changes. The memory does not drive the SI / IO0 and SO / IO1 signals during the latency cycles.

The next interface state following the last latency cycle is a Dual Output Cycle.

4.3.13 Dual Output Cycle - Memory to Host Transfer

The Read Dual Output and Read Dual I/O return data to the host two bits in each cycle. The host keeps RESET# high, CS# low. The Write Protect (WP#) signal is ignored. The memory drives data on the SI / IO0 and SO / IO1 signals during the Dual Output Cycles.

The next interface state continues to be Dual Output Cycle until the host returns CS# to high ending the command.

4.3.14 Quad Input Cycle - Host to Memory Transfer

The Quad I/O Read command transfers four address or mode bits to the memory in each cycle. In QPI Mode the Quad I/O Read and Page Program commands transfer four data bits to the memory in each cycle, including the instruction cycles. The host keeps CS# low, and drives the IO signals.

For Quad I/O Read the next interface state following the delivery of address and mode bits is a Quad Latency Cycle if there are latency cycles needed or Quad Output Cycle if no latency is required. For QPI Mode Page Program, the host returns CS# high following the delivery of data to be programmed and the interface returns to standby state.

4.3.15 Quad Latency (Dummy) Cycle

Read commands may have zero to several latency cycles during which read data is read from the main flash memory array before transfer to the host. The number of latency cycles are determined by the Latency Code in the Configuration Register (CR2V[3:0]). During the latency cycles, the host keeps CS# low. The host may drive the IO signals during these cycles or the host may leave the IO floating. The memory does not use any data driven on IO during the latency cycles. The host must stop driving the IO signals on the falling edge at the end of the last latency cycle. It is recommended that the host stop driving them during all latency cycles so that there is sufficient time for the host drivers to turn off before the memory begins to drive at the end of the latency cycles. This prevents driver conflict between host and memory when the signal direction changes. The memory does not drive the IO signals during the latency cycles.

The next interface state following the last latency cycle is a Quad Output Cycle.

4.3.16 Quad Output Cycle - Memory to Host Transfer

The Quad I/O Read returns data to the host four bits in each cycle. The host keeps CS# low. The memory drives data on IO0-IO3 signals during the Quad Output Cycles.

The next interface state continues to be Quad Output Cycle until the host returns CS# to high ending the command.

4.3.17 DDR Quad Input Cycle - Host to Memory Transfer

The DDR Quad I/O Read command sends address, and mode bits to the memory on all the IO signals. Four bits are transferred on the rising edge of SCK and four bits on the falling edge in each cycle. The host keeps CS# low.

The next interface state following the delivery of address and mode bits is a DDR Latency Cycle.

4.3.18 DDR Latency Cycle

DDR Read commands may have one to several latency cycles during which read data is read from the main flash memory array before transfer to the host. The number of latency cycles are determined by the Latency Code in the Configuration Register (CR2V[3:0]). During the latency cycles, the host keeps CS# low. The host may not drive the IO signals during these cycles. So that there is sufficient time for the host drivers to turn off before the memory begins to drive. This prevents driver conflict between host and memory when the signal direction changes. The memory has an option to drive all the IO signals with a Data Learning Pattern (DLP) during the last 4 latency cycles. The DLP option should not be enabled when there are fewer than five latency cycles so that there is at least one cycle of high impedance for turn around of the IO signals before the memory begins driving the DLP. When there are more than 4 cycles of latency the memory does not drive the IO signals until the last four cycles of latency.

The next interface state following the last latency cycle is a DDR Single, or Quad Output Cycle, depending on the instruction.

4.3.19 DDR Quad Output Cycle - Memory to Host Transfer

The DDR Quad I/O Read command returns bits to the host on all the IO signals. Four bits are transferred on the rising edge of SCK and four bits on the falling edge in each cycle. The host keeps CS# low.

The next interface state continues to be DDR Quad Output Cycle until the host returns CS# to high ending the command.

4.4 Configuration Register Effects on the Interface

The Configuration Register 2 volatile bits 3 to 0 (CR2V[3:0]) select the variable latency for all array read commands except Read and Read SDFP (RSFDP). Read always has zero latency cycles. RSFDP always has 8 latency cycles. The variable latency is also used in the OTPR, and RDAR commands.

The Configuration Register bit 1 (CR1V[1]) selects whether Quad Mode is enabled to switch WP# to IO2 function, RESET# to IO3 function, and thus allow Quad I/O Read and QPI Mode commands. Quad Mode must also be selected to allow DDR Quad I/O Read commands.

4.5 Data Protection

Some basic protection against unintended changes to stored data are provided and controlled purely by the hardware design. These are described below. Other software managed protection methods are discussed in the software section of this document.

4.5.1 Power-Up

When the core supply voltage is at or below the $V_{DD(Low)}$ voltage, the device is considered to be powered off. The device does not react to external signals, and is prevented from performing any program or erase operation. Program and erase operations continue to be prevented during the Power-On Reset (POR) because no command is accepted until the exit from POR to the Interface Standby state.

4.5.2 Low Power

When V_{DD} is less than $V_{DD(Cut-off)}$ the memory device will ignore commands to ensure that program and erase operations can not start when the core supply voltage is out of the operating range.

4.5.3 Clock Pulse Count

The device verifies that all non-volatile memory and register data modifying commands consist of a clock pulse count that is a multiple of eight bit transfers (byte boundary) before executing them. A command not ending on an 8-bit (byte) boundary is ignored and no error status is set for the command.

5. Electrical Specifications

5.1 Absolute Maximum Ratings

Table 5.1 Absolute Maximum Ratings

Storage Temperature Plastic Packages	–65°C to +150°C
Ambient Temperature with Power Applied	–65°C to +125°C
V_{DD}	–0.5 V to +2.5V
Input voltage with respect to Ground (V_{SS}) (Note 1)	–0.5 V to $V_{DD} + 0.5V$
Output Short Circuit Current (Note 2)	100 mA

Notes:

1. See [Section 5.3.3, Input Signal Overshoot on page 33](#) for allowed maximums during signal transition.
2. No more than one output may be shorted to ground at a time. Duration of the short circuit should not be greater than one second.
3. Stresses above those listed under [Absolute Maximum Ratings](#) may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational sections of this data sheet is not implied. Exposure of the device to absolute maximum rating conditions for extended periods may affect device reliability.

5.2 Latch-Up Characteristics

Table 5.2 Latch-Up Specification

Description	Min	Max	Unit
Input voltage with respect to V_{SS} on all input only connections	–1.0	$V_{DD} + 1.0$	V
Input voltage with respect to V_{SS} on all I/O connections	–1.0	$V_{DD} + 1.0$	V
V_{DD} Current	–100	+100	mA

Note:

1. Excludes power supply V_{DD} . Test conditions: $V_{DD} = 1.8$ V, one connection at a time tested, connections not being tested are at V_{SS} .

5.3 Operating Ranges

Operating ranges define those limits between which the functionality of the device is guaranteed.

5.3.1 Power Supply Voltages

V_{DD} 1.7V to 2.0V

5.3.2 Temperature Ranges

Industrial (I) Devices

Ambient Temperature (T_A)..... –40°C to +85°C

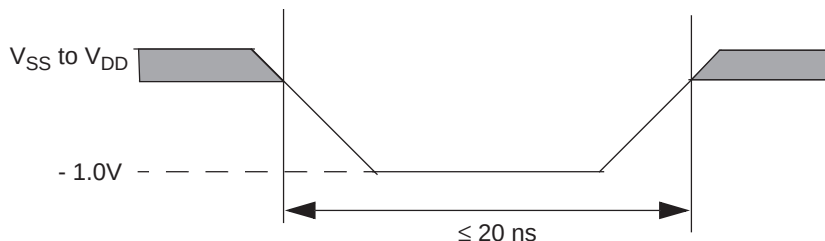
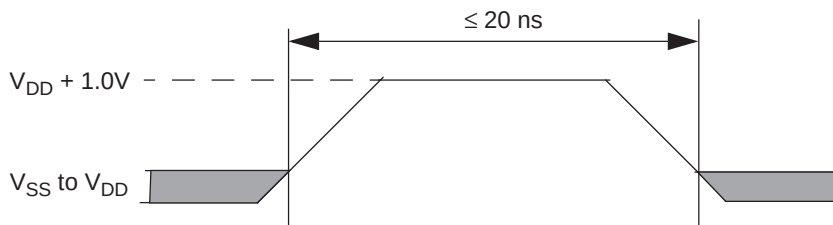
Automotive (A) Infotainment Devices

Ambient Temperature (T_A)..... –40°C to +105°C

Automotive operating and performance parameters will be determined by device characterization and may vary from standard industrial temperature range devices as currently shown in this specification.

5.3.3 Input Signal Overshoot

During DC conditions, input or I/O signals should remain equal to or between V_{SS} and V_{DD} . During voltage transitions, inputs or I/Os may overshoot V_{SS} to –1.0V or overshoot to $V_{DD} + 1.0V$, for periods up to 20 ns.

Figure 5.1 Maximum Negative Overshoot Waveform

Figure 5.2 Maximum Positive Overshoot Waveform


5.4 Power-Up and Power-Down

The device must not be selected at power-up or power-down (that is, CS# must follow the voltage applied on V_{DD}) until V_{DD} reaches the correct value as follows:

- V_{DD} (min) at power-up, and then for a further delay of t_{PU}
- V_{SS} at power-down

A simple pull-up resistor on Chip Select (CS#) can usually be used to insure safe and proper power-up and power-down.

The device ignores all instructions until a time delay of t_{PU} has elapsed after the moment that V_{DD} rises above the minimum V_{DD} threshold (see Figure 5.3). However, correct operation of the device is not guaranteed if V_{DD} returns below V_{DD} (min) during t_{PU}. No command should be sent to the device until the end of t_{PU}.

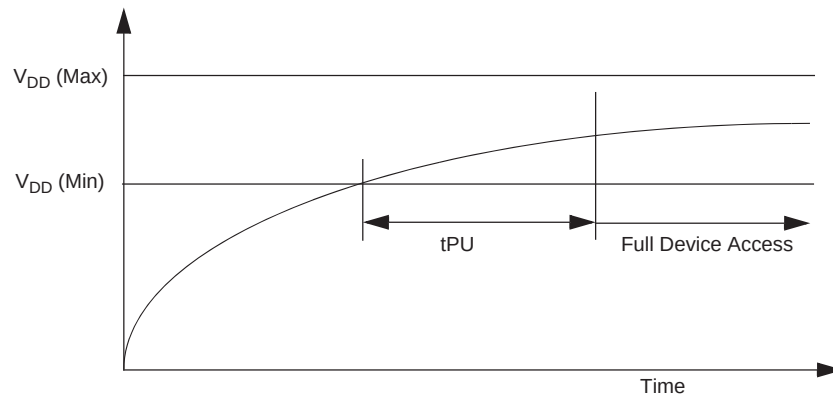
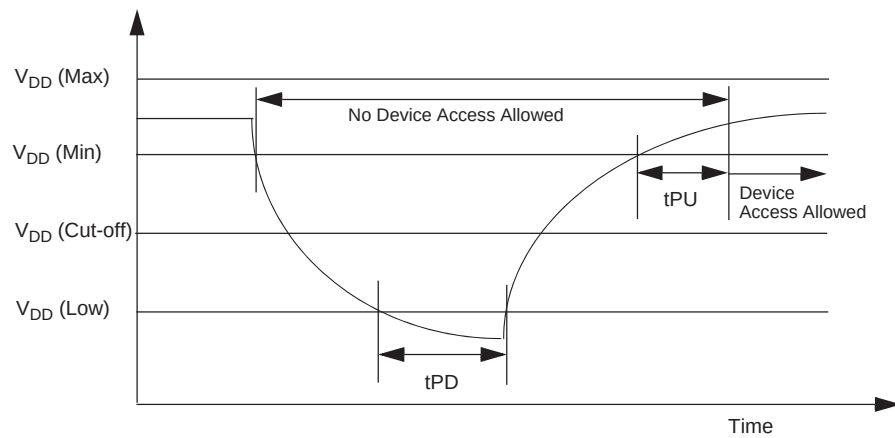
The device draws I_{POR} during t_{PU}. After power-up (t_{PU}), the device is in Standby mode, draws CMOS standby current (I_{SB}), and the WEL bit is reset.

During power-down or voltage drops below V_{DD}(cut-off), the voltage must drop below V_{DD}(low) for a period of t_{PD} for the part to initialize correctly on power-up. See Figure 5.4. If during a voltage drop the V_{DD} stays above V_{DD}(cut-off) the part will stay initialized and will work correctly when V_{DD} is again above V_{DD}(min). In the event Power-On Reset (POR) did not complete correctly after power-up, the assertion of the RESET# signal or receiving a software reset command (RESET) will restart the POR process.

Normal precautions must be taken for supply rail decoupling to stabilize the V_{DD} supply at the device. Each device in a system should have the V_{DD} rail decoupled by a suitable capacitor close to the package supply connection (this capacitor is generally of the order of 0.1 μf).

Table 5.3 FS-S Power-Up / Power-Down Voltage and Timing

Symbol	Parameter	Min	Max	Unit
V _{DD} (min)	V _{DD} (minimum operation voltage)	1.7		V
V _{DD} (cut-off)	V _{DD} (Cut Off where re-initialization is needed)	1.5		V
V _{DD} (low)	V _{DD} (low voltage for initialization to occur)	0.7		V
t _{PU}	V _{DD} (min) to Read operation		300	μs
t _{PD}	V _{DD} (low) time	10.0		μs

Figure 5.3 Power-Up**Figure 5.4 Power-Down and Voltage Drop**

5.5 DC Characteristics

Applicable within operating ranges.

Table 5.4 FS-S DC Characteristics

Symbol	Parameter	Test Conditions	Min	Typ (1)	Max	Unit
V_{IL}	Input Low Voltage		-0.5		$0.3 \times V_{DD}$	V
V_{IH}	Input High Voltage		$0.7 \times V_{DD}$		$V_{DD} + 0.4$	V
V_{OL}	Output Low Voltage	$I_{OL} = 0.1 \text{ mA}$			0.2	V
V_{OH}	Output High Voltage	$I_{OH} = -0.1 \text{ mA}$	$V_{DD} - 0.2$			V
I_{LI}	Input Leakage Current	$V_{DD} = V_{DD} \text{ Max}$, $V_{IN} = V_{IH}$ or V_{SS} , $CS\# = V_{IH}$			± 2	μA
I_{LO}	Output Leakage Current	$V_{DD} = V_{DD} \text{ Max}$, $V_{IN} = V_{IH}$ or V_{SS} , $CS\# = V_{IH}$			± 2	μA
I_{CC1}	Active Power Supply Current (READ) (2)	Serial SDR @ 50 MHz Serial SDR @ 133 MHz Quad SDR @ 133 MHz Quad DDR @ 80 MHz		10 20 60 70	18 30 65 90	mA
I_{CC2}	Active Power Supply Current (Page Program)	$CS\# = V_{DD}$		60	100	mA
I_{CC3}	Active Power Supply Current (WRR or WRAR)	$CS\# = V_{DD}$		60	100	mA
I_{CC4}	Active Power Supply Current (SE)	$CS\# = V_{DD}$		60	100	mA
I_{CC5}	Active Power Supply Current (BE)	$CS\# = V_{DD}$		60	100	mA
I_{SB} (Industrial)	Standby Current	IO3/RESET#, $CS\# = V_{DD}$; SI, SCK = V_{DD} or V_{SS} , Industrial Temp		70	100	μA
I_{SB} (Automotive)	Standby Current	IO3/RESET#, $CS\# = V_{DD}$; SI, SCK = V_{DD} or V_{SS} , Automotive Temp		70	300	μA
I_{POR}	Power-On Reset Current	IO3/RESET#, $CS\# = V_{DD}$; SI, SCK = V_{DD} or V_{SS}			80	mA

Notes:

1. Typical values are at $T_{AI} = 25^\circ\text{C}$ and $V_{DD} = 1.8\text{V}$.
2. Outputs unconnected during read data return. Output switching current is not included.

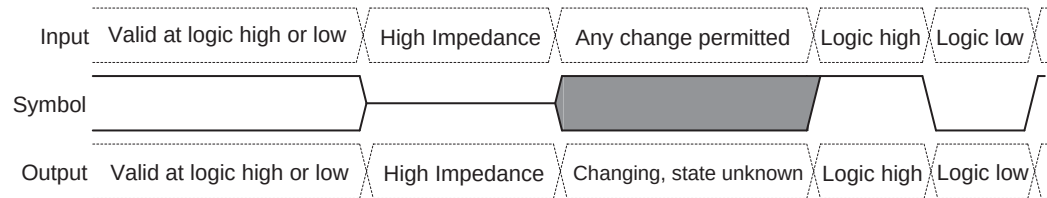
5.5.1 Active Power and Standby Power Modes

The device is enabled and in the Active Power mode when Chip Select ($CS\#$) is Low. When $CS\#$ is high, the device is disabled, but may still be in an Active Power mode until all program, erase, and write operations have completed. The device then goes into the Standby Power mode, and power consumption drops to I_{SB} .

6. Timing Specifications

6.1 Key to Switching Waveforms

Figure 6.1 Waveform Element Meanings



6.2 AC Test Conditions

Figure 6.2 Test Setup

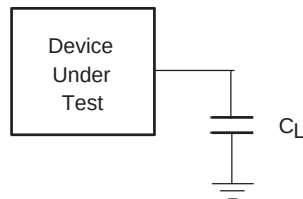


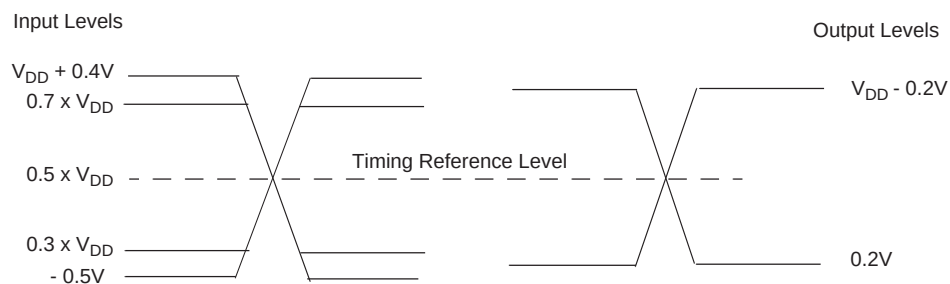
Table 6.1 AC Measurement Conditions

Symbol	Parameter	Min	Max	Unit
C_L	Load Capacitance		30	pF
	Input Pulse Voltage	$0.2 \times V_{DD}$	$0.8 \times V_{DD}$	V
	Input Slew Rate	0.23	1.25	V/ns
	Input Rise and Fall Times	0.9	5	ns
	Input Timing Ref Voltage	$0.5 \times V_{DD}$		V
	Output Timing Ref Voltage	$0.5 \times V_{DD}$		V

Notes:

- Input slew rate measured from input pulse min to max at V_{DD} max. Example: $(1.9V \times 0.8) - (1.9V \times 0.2) = 1.14V$; $1.14V/1.25V/ns = 0.9$ ns rise or fall time.
- AC characteristics tables assume clock and data signals have the same slew rate (slope).

Figure 6.3 Input, Output, and Timing Reference Levels



6.2.1 Capacitance Characteristics

Table 6.2 Capacitance

	Parameter	Test Conditions	Min	Max	Unit
C_{IN}	Input Capacitance (applies to SCK, CS#, IO3/RESET#)	1 MHz		8	pF
C_{OUT}	Output Capacitance (applies to All I/O)	1 MHz		8	pF

Note:

1. Parameter values are not 100% tested. For more details, please refer to the IBIS models.

6.3 Reset

6.3.1 Power-On (Cold) Reset

The device executes a Power-On Reset (POR) process until a time delay of t_{PU} has elapsed after the moment that V_{DD} rises above the minimum V_{DD} threshold. See [Figure 5.3 on page 35](#), [Table 5.3 on page 34](#). The device must not be selected (CS# to go high with V_{DD}) during power-up (t_{PU}), i.e. no commands may be sent to the device until the end of t_{PU} .

The IO3 / RESET# signal functions as the RESET# input when CS# is high for more than t_{CS} time or when Quad Mode is not enabled CR1V[1]=0.

RESET# is ignored during POR. If RESET# is low during POR and remains low through and beyond the end of t_{PU} , CS# must remain high until t_{RH} after RESET# returns high. RESET# must return high for greater than t_{RS} before returning low to initiate a hardware reset.

Figure 6.4 Reset Low at the End of POR

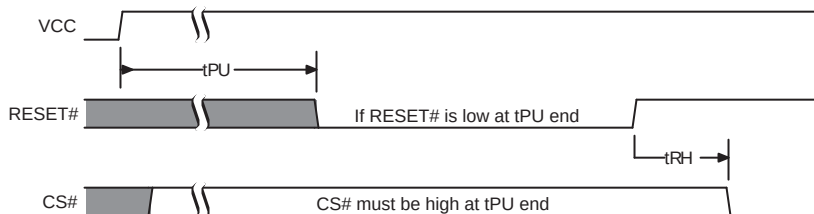


Figure 6.5 Reset High at the End of POR

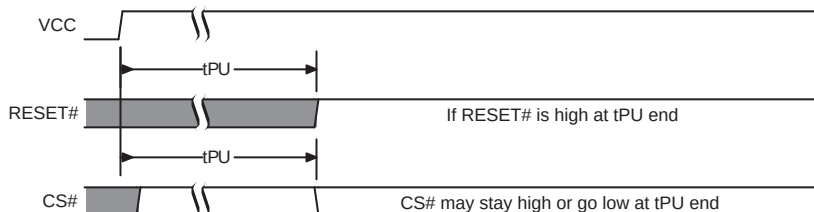
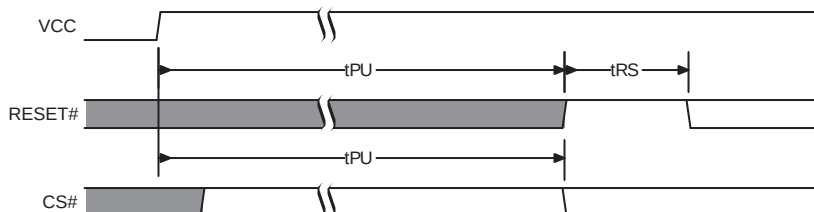


Figure 6.6 POR Followed by hardware reset



6.3.2 IO3 / RESET# Input Initiated Hardware (Warm) Reset

The IO3 / RESET# signal functions as the RESET# input when CS# is high for more than t_{CS} time or when Quad Mode is not enabled $CR1V[1]=0$. The IO3 / RESET# input has an internal pull-up to V_{DD} and may be left unconnected if Quad Mode is not used. The t_{CS} delay after CS# goes high gives the memory or host system time to drive IO3 high after its use as a Quad Mode I/O signal while CS# was low. The internal pull-up to V_{DD} will then hold IO3 / RESET# high until the host system begins driving IO3 / RESET#. The IO3 / RESET# input is ignored while CS# remains high during t_{CS} , to avoid an unintended Reset operation. If CS# is driven low to start a new command, IO3 / RESET# is used as IO3.

When the device is not in Quad Mode or, when CS# is high, and IO3 / RESET# transitions from V_{IH} to V_{IL} for $> t_{RP}$, following t_{CS} , the device will reset register states in the same manner as Power-On Reset but, does not go through the full reset process that is performed during POR. The hardware reset process requires a period of t_{RPH} to complete. If the POR process did not complete correctly for any reason during power-up (t_{PU}), RESET# going low will initiate the full POR process instead of the hardware reset process and will require t_{PU} to complete the POR process.

The RESET command is independent of the state of IO3 / RESET#. If IO3 / RESET# is high or unconnected, and the RESET instruction is issued, the device will perform software reset.

Additional IO3 RESET# Notes:

- IO3 / RESET# must be high for t_{RS} following t_{PU} or t_{RPH} , before going low again to initiate a hardware reset.
- When IO3 / RESET# is driven low for at least a minimum period of time (t_{RP}), following t_{CS} , the device terminates any operation in progress, makes all outputs high impedance, and ignores all read/write commands for the duration of t_{RPH} . The device resets the interface to standby state.
- If Quad Mode and the IO3 / RESET# feature are enabled, the host system should not drive IO3 low during t_{CS} , to avoid driver contention on IO3. Immediately following commands that transfer data to the host in Quad Mode, e.g. Quad I/O Read, the memory drives IO3 / Reset high during t_{CS} , to avoid an unintended Reset operation. Immediately following commands that transfer data to the memory in Quad Mode, e.g. Page Program, the host system should drive IO3 / Reset high during t_{CS} , to avoid an unintended Reset operation.
- If Quad Mode is not enabled, and if CS# is low at the time IO3 / RESET# is asserted low, CS# must return high during t_{RPH} before it can be asserted low again after t_{RH} .

Table 6.3 Hardware Reset Parameters

Parameter	Description	Limit	Time	Unit
t_{RS}	Reset Setup - Prior Reset end and RESET# high before RESET# low	Min	50	ns
t_{RPH}	Reset Pulse Hold - RESET# low to CS# low	Min	35	μ s
t_{RP}	RESET# Pulse Width	Min	200	ns
t_{RH}	Reset Hold - RESET# high before CS# low	Min	50	ns

Notes:

1. IO3 / RESET# Low is ignored during power-up (t_{PU}). If Reset# is asserted during the end of t_{PU} , the device will remain in the reset state and t_{RH} will determine when CS# may go Low.
2. If Quad Mode is enabled, IO3 / RESET# Low is ignored during t_{CS} .
3. Sum of t_{RP} and t_{RH} must be equal to or greater than t_{RPH} .

Figure 6.7 Hardware Reset when Quad Mode is Not Enabled and IO3 / Reset# is Enabled

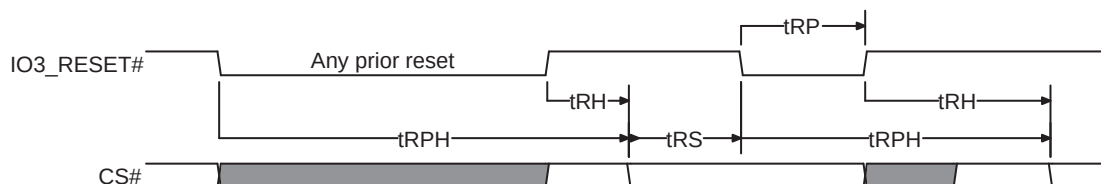
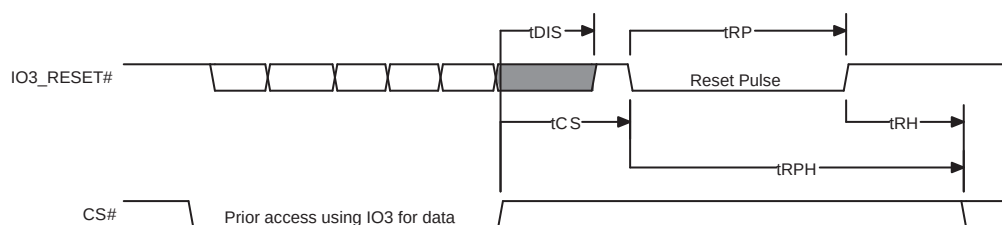


Figure 6.8 Hardware Reset when Quad Mode and IO3 / Reset# are Enabled


6.4 SDR AC Characteristics

Table 6.4 AC Characteristics

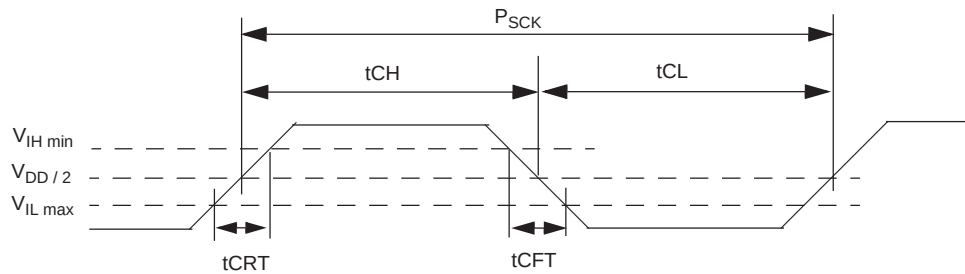
Symbol	Parameter	Min	Typ	Max	Unit
$F_{SCK, R}$	SCK Clock Frequency for READ and 4READ instructions	DC		50	MHz
$F_{SCK, C}$	SCK Clock Frequency for FAST_READ, 4FAST_READ, and the following Dual and Quad commands: QOR, 4QOR, DIOR, 4DIOR, QIOR, 4QIOR	DC		133	MHz
$F_{SCK, D}$	SCK Clock Frequency for the following DDR commands: QIOR, 4QIOR	DC		80	MHz
P_{SCK}	SCK Clock Period	$1/F_{SCK}$		∞	
t_{WH}, t_{CH}	Clock High Time	$50\% P_{SCK} - 5\%$		$50\% P_{SCK} + 5\%$	ns
t_{WL}, t_{CL}	Clock Low Time	$50\% P_{SCK} - 5\%$		$50\% P_{SCK} + 5\%$	ns
t_{CRT}, t_{CLCH}	Clock Rise Time (slew rate)	0.1			V/ns
t_{CFT}, t_{CHCL}	Clock Fall Time (slew rate)	0.1			V/ns
t_{CS}	CS# High Time (Read Instructions) CS# High Time (Read Instructions when Reset feature and Quad Mode are both enabled) CS# High Time (Program/Erase instructions)	10 20 (5) 50			ns
t_{CSS}	CS# Active Setup Time (relative to SCK)	2			ns
t_{CSH}	CS# Active Hold Time (relative to SCK)	3			ns
t_{SU}	Data in Setup Time	2			ns
t_{HD}	Data in Hold Time	3			ns
t_V	Clock Low to Output Valid			8 (2) 6 (3)	ns
t_{HO}	Output Hold Time	1			ns
t_{DIS}	Output Disable Time (4) Output Disable Time (when Reset feature and Quad Mode are both enabled)			8 20 (5)	ns
t_{WPS}	WP# Setup Time (1)	20			ns
t_{WPH}	WP# Hold Time (1)	100			ns

Notes:

- Only applicable as a constraint for WRR or WRAR instruction when SRWD is set to a 1.
- Full V_{DD} range and $CL=30$ pF.
- Full V_{DD} range and $CL=15$ pF.
- Output High-Z is defined as the point where data is no longer driven.
- t_{CS} and t_{DIS} require additional time when the Reset feature and Quad Mode are enabled ($CR2V[5]=1$ and $CR1V[1]=1$).

6.4.1 Clock Timing

Figure 6.9 Clock Timing



6.4.2 Input / Output Timing

Figure 6.10 SPI Single Bit Input Timing

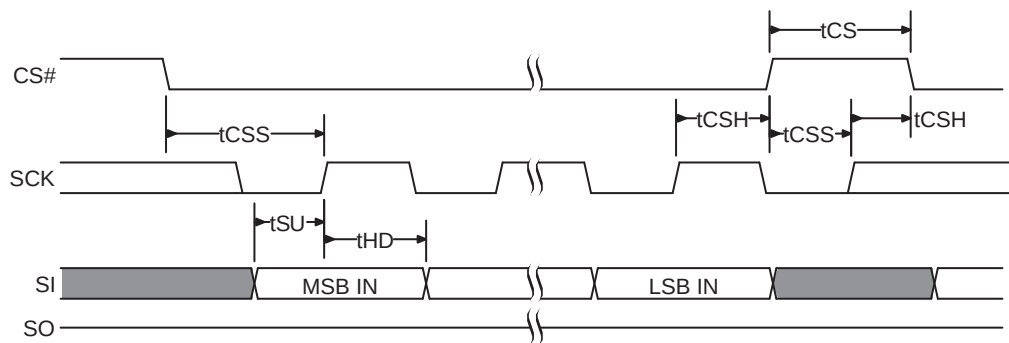


Figure 6.11 SPI Single Bit Output Timing

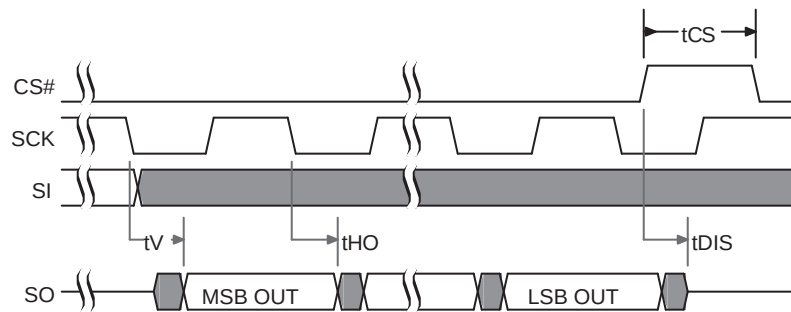


Figure 6.12 SPI SDR MIO Timing

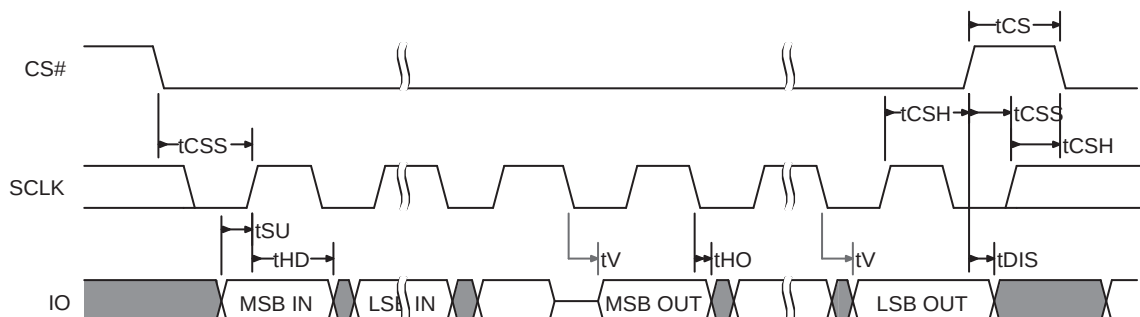
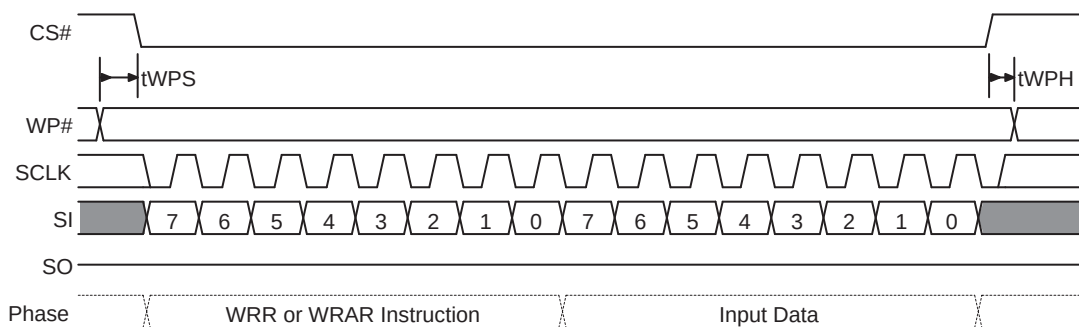


Figure 6.13 WP# Input Timing



6.5 DDR AC Characteristics

Table 6.5 AC Characteristics 80 MHz Operation

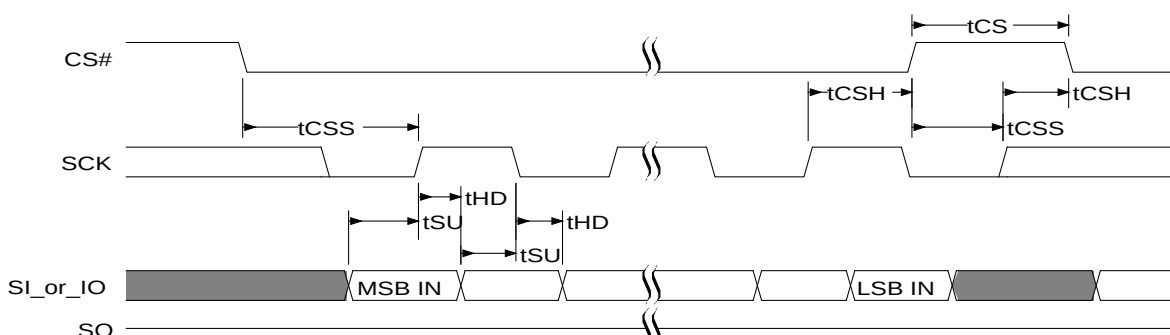
Symbol	Parameter	Min	Typ	Max	Unit
$F_{SCK, R}$	SCK Clock Frequency for DDR READ instruction	DC		80	MHz
$P_{SCK, R}$	SCK Clock Period for DDR READ instruction	12.5		∞	ns
t_{WH}, t_{CH}	Clock High Time	50% $P_{SCK} - 5\%$		50% $P_{SCK} + 5\%$	ns
t_{WL}, t_{CL}	Clock Low Time	50% $P_{SCK} - 5\%$		50% $P_{SCK} + 5\%$	ns
t_{CS}	CS# High Time (Read Instructions) CS# High Time (Read Instructions when Reset feature is enabled)	10 20			ns
t_{CSS}	CS# Active Setup Time (relative to SCK)	2			ns
t_{CSH}	CS# Active Hold Time (relative to SCK)	3			ns
t_{SU}	IO in Setup Time	1.5			ns
t_{HD}	IO in Hold Time	1.5			ns
t_V	Clock Low to Output Valid	1.5		6 (1)	ns
t_{HO}	Output Hold Time	1.5			ns
t_{DIS}	Output Disable Time Output Disable Time (when Reset feature is enabled)			8 20	ns
t_{O_SKEW}	First Output to last Output data valid time			400	ps

Note:

1. $CL=15\text{ pF}$

6.5.1 DDR Input Timing

Figure 6.14 SPI DDR Input Timing



6.5.2 DDR Output Timing

Figure 6.15 SPI DDR Output Timing

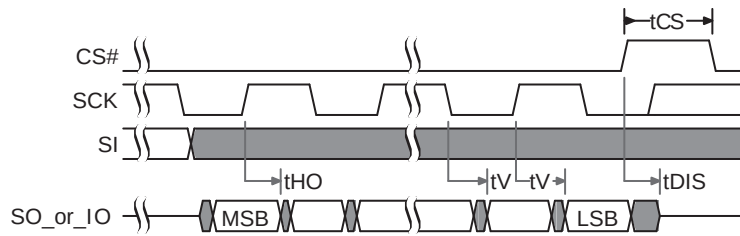
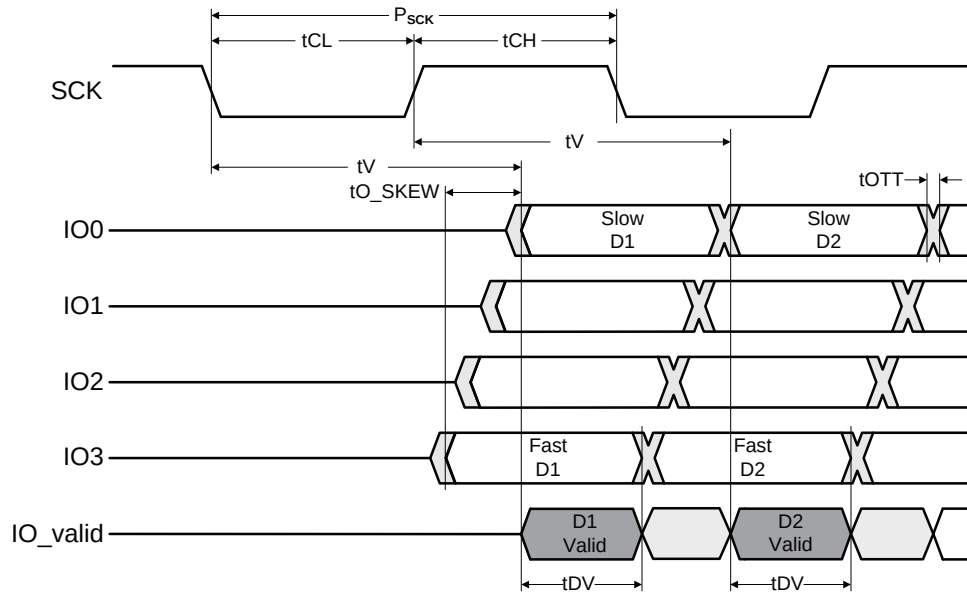


Figure 6.16 SPI DDR Data Valid Window



Notes:

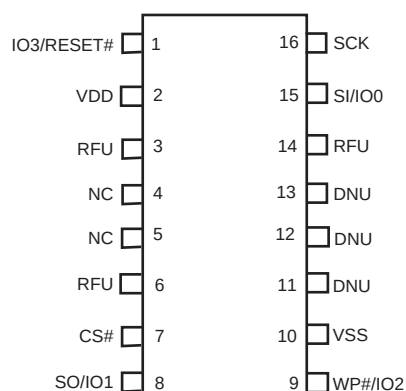
1. t_{CLH} is the shorter duration of t_{CL} or t_{CH} .
2. t_{O_SKEW} is the maximum difference (delta) between the minimum and maximum t_V (output valid) across all IO signals.
3. t_{OTT} is the maximum Output Transition Time from one valid data value to the next valid data value on each IO.
4. t_{OTT} is dependent on system level considerations including:
 - a. Memory device output impedance (drive strength)
 - b. System level parasitics on the IOs (primarily bus capacitance)
 - c. Host memory controller input V_{IH} and V_{IL} levels at which 0 to 1 and 1 to 0 transitions are recognized
 - d. As an example, assuming that the above considerations result a memory output slew rate of 2V/ns and a 1.8V transition (from 1 to 0 or 0 to 1) is required by the host, the t_{OTT} would be:
 - i. $t_{OTT} = 1.8V / (2V/ns) = 0.9\text{ ns}$
 - e. t_{OTT} is not a specification tested by Spansion, it is system dependent and must be derived by the system designer based on the above considerations.
5. The minimum data valid window (t_{DV}) can be calculated as follows:
 - a. As an example, assuming:
 - i. 80 MHz clock frequency = 12.5 ns clock period
 - ii. DDR operations are specified to have a duty cycle of 45% or higher
 - iii. $t_{CLH} = 0.45 \cdot P_{SCK} = 0.45 \cdot 12.5\text{ ns} = 5.625\text{ ns}$
 - iv. $t_{O_SKEW} = 400\text{ ps}$
 - v. $t_{OTT} = 0.9\text{ ns}$
 - b. $t_{DV} = t_{CLH} - t_{O_SKEW} - t_{OTT}$
 - c. $t_{DV} = 5.625\text{ ns} - 400\text{ ps} - 0.9\text{ ns} = 4.125\text{ ns}$

7. Physical Interface

7.1 SOIC 16-Lead Package

7.1.1 SOIC 16 Connection Diagram

Figure 7.1 16-Lead SOIC Package (SO3016), Top View

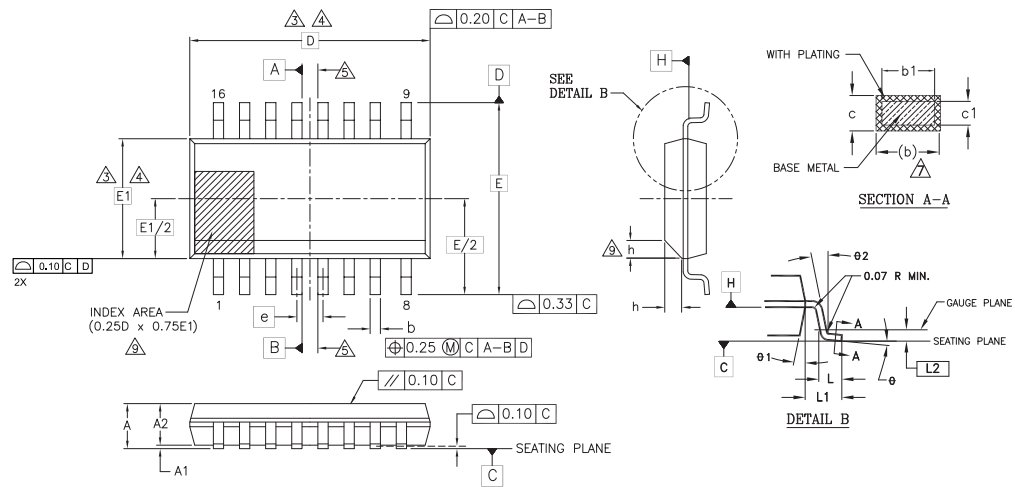


Note:

1. The RESET# input has an internal pull-up and may be left unconnected in the system if Quad Mode and hardware reset are not in use.

7.1.2 SOIC 16 Physical Diagram

Figure 7.2 SOIC 16-Lead, 300-mil Body Width (SO3016)



PACKAGE	SO3 016 (inches)		SO3 016 (mm)	
JEDEC	MS-013(E)AA		MS-013(E)AA	
SYMBOL	MIN	MAX	MIN	MAX
A	0.093	0.104	2.35	2.65
A1	0.004	0.012	0.10	0.30
A2	0.081	0.104	2.05	2.55
b	0.012	0.020	0.31	0.51
b1	0.011	0.019	0.27	0.48
c	0.008	0.013	0.20	0.33
c1	0.008	0.012	0.20	0.30
D	0.406 BSC		10.30 BSC	
E	0.406 BSC		10.30 BSC	
E1	0.295 BSC		7.50 BSC	
e	0.050 BSC		1.27 BSC	
L	0.016	0.050	0.40	1.27
L1	0.055 REF		1.40 REF	
L2	0.010 BSC		0.25 BSC	
N	16		16	
h	0.10	0.30	0.25	0.75
θ	0°	8°	0°	8°
θ1	5°	15°	5°	15°
θ2	0°	—	0°	—

NOTES:

- ALL DIMENSIONS ARE IN BOTH INCHES AND MILLIMETERS.
- DIMENSIONING AND TOLERANCING PER ASME Y14.5M - 1994.
- DIMENSION D DOES NOT INCLUDE MOLD FLASH, PROTRUSIONS OR GATE BURRS. MOLD FLASH, PROTRUSIONS OR GATE BURRS SHALL NOT EXCEED 0.15 mm PER END. DIMENSION E1 DOES NOT INCLUDE INTERLEAD FLASH OR PROTRUSION INTERLEAD FLASH OR PROTRUSION SHALL NOT EXCEED 0.25 mm PER SIDE. D AND E1 DIMENSIONS ARE DETERMINED AT DATUM H.
- THE PACKAGE TOP MAY BE SMALLER THAN THE PACKAGE BOTTOM. DIMENSIONS D AND E1 ARE DETERMINED AT THE OUTMOST EXTREMES OF THE PLASTIC BODY EXCLUSIVE OF MOLD FLASH, TIE BAR BURRS, GATE BURRS AND INTERLEAD FLASH, BUT INCLUDING ANY MISMATCH BETWEEN THE TOP AND BOTTOM OF THE PLASTIC BODY.
- DATUMS A AND B TO BE DETERMINED AT DATUM H.
- "N" IS THE MAXIMUM NUMBER OF TERMINAL POSITIONS FOR THE SPECIFIED PACKAGE LENGTH.
- THE DIMENSIONS APPLY TO THE FLAT SECTION OF THE LEAD BETWEEN 0.10 TO 0.25 mm FROM THE LEAD TIP.
- DIMENSION "b" DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.10 mm TOTAL IN EXCESS OF THE "b" DIMENSION AT MAXIMUM MATERIAL CONDITION. THE DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OF THE LEAD FOOT.
- THIS CHAMFER FEATURE IS OPTIONAL. IF IT IS NOT PRESENT, THEN A PIN 1 IDENTIFIER MUST BE LOCATED WITHIN THE INDEX AREA INDICATED.
- LEAD COPLANARITY SHALL BE WITHIN 0.10 mm AS MEASURED FROM THE SEATING PLANE.

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7.2 8-Connector Packages

7.2.1 8-Connector Diagrams

Figure 7.3 8-Pin Plastic Small Outline Package (SOIC8)

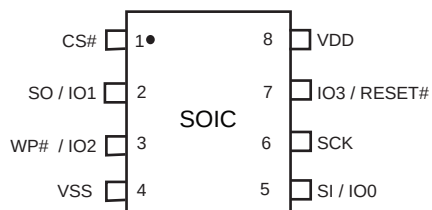
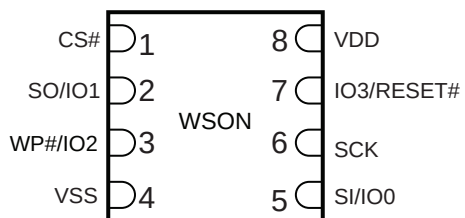


Figure 7.4 8-Connector Package (WSON 6x5), Top View

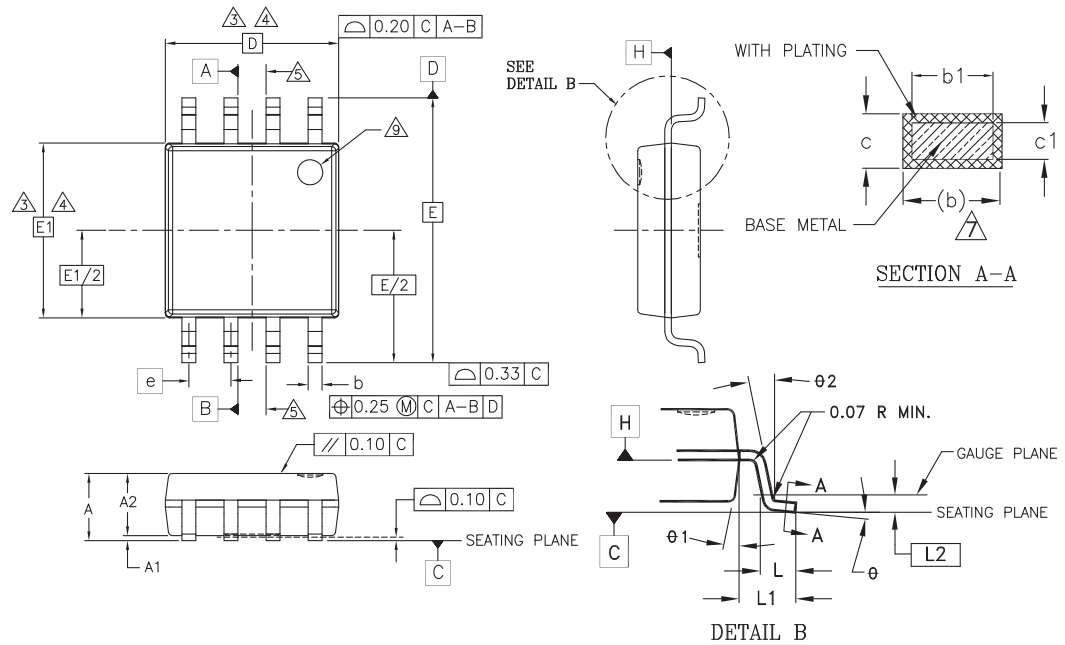


Note:

1. The RESET# input has an internal pull-up and may be left unconnected in the system if Quad Mode and hardware reset are not in use.

7.2.2 8-Connector Physical Diagrams

Figure 7.5 SOIC 8-Lead, 208 mil Body Width (SOC008)



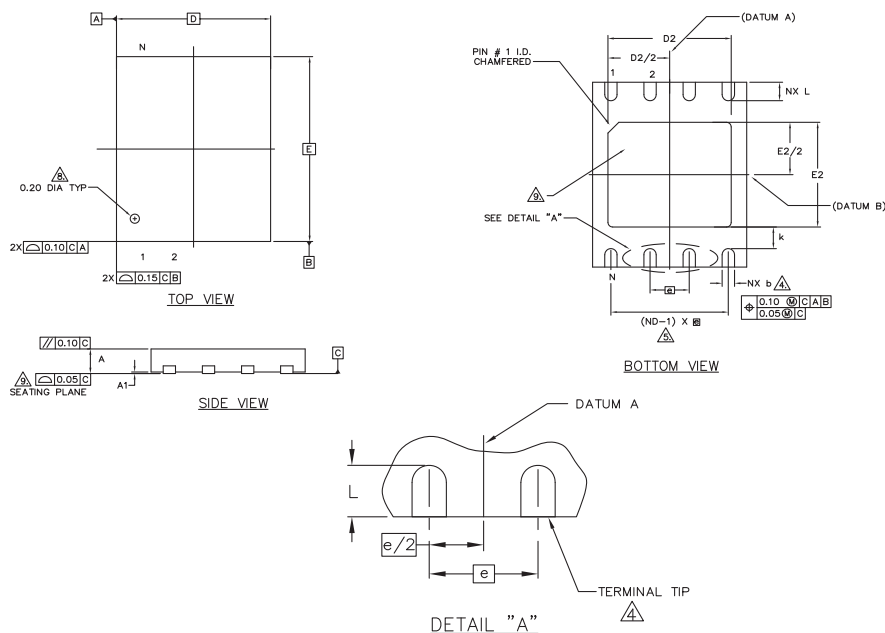
PACKAGE	SOC 008 (inches)		SOC 008 (mm)	
JEDEC				
SYMBOL	MIN	MAX	MIN	MAX
A	0.069	0.085	1.753	2.159
A1	0.002	0.0098	0.051	0.249
A2	0.067	0.075	1.70	1.91
b	0.014	0.019	0.356	0.483
b1	0.013	0.018	0.330	0.457
c	0.0075	0.0095	0.191	0.241
c1	0.006	0.008	0.152	0.203
D	0.208 BSC		5.283 BSC	
E	0.315 BSC		8.001 BSC	
E1	0.208 BSC		5.283 BSC	
e	.050 BSC		1.27 BSC	
L	0.020	0.030	0.508	0.762
L1	.049 REF		1.25 REF	
L2	.010 BSC		0.25 BSC	
N	8		8	
theta	0°	8°	0°	8°
theta1	5°	15°	5°	15°
theta2	0°		0°	

NOTES:

- ALL DIMENSIONS ARE IN BOTH INCHES AND MILLIMETERS.
- DIMENSIONING AND TOLERANCING PER ASME Y14.5M - 1994.
- DIMENSION D DOES NOT INCLUDE MOLD FLASH, PROTRUSIONS OR GATE BURRS. MOLD FLASH, PROTRUSIONS OR GATE BURRS SHALL NOT EXCEED 0.15 mm PER END. DIMENSION E1 DOES NOT INCLUDE INTERLEAD FLASH OR PROTRUSION INTERLEAD FLASH OR PROTRUSION SHALL NOT EXCEED 0.25 mm PER SIDE. D AND E1 DIMENSIONS ARE DETERMINED AT DATUM H.
- THE PACKAGE TOP MAY BE SMALLER THAN THE PACKAGE BOTTOM. DIMENSIONS D AND E1 ARE DETERMINED AT THE OUTMOST EXTREMES OF THE PLASTIC BODY EXCLUSIVE OF MOLD FLASH, TIE BAR BURRS, GATE BURRS AND INTERLEAD FLASH, BUT INCLUDING ANY MISMATCH BETWEEN THE TOP AND BOTTOM OF THE PLASTIC BODY.
- DATUMS A AND B TO BE DETERMINED AT DATUM H.
- "N" IS THE MAXIMUM NUMBER OF TERMINAL POSITIONS FOR THE SPECIFIED PACKAGE LENGTH.
- THE DIMENSIONS APPLY TO THE FLAT SECTION OF THE LEAD BETWEEN 0.10 TO 0.25 mm FROM THE LEAD TIP.
- DIMENSION "b" DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.10 mm TOTAL IN EXCESS OF THE "b" DIMENSION AT MAXIMUM MATERIAL CONDITION. THE DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OF THE LEAD FOOT.
- THIS CHAMFER FEATURE IS OPTIONAL. IF IT IS NOT PRESENT, THEN A PIN 1 IDENTIFIER MUST BE LOCATED WITHIN THE INDEX AREA INDICATED.
- LEAD COPLANARITY SHALL BE WITHIN 0.10 mm AS MEASURED FROM THE SEATING PLANE.

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Figure 7.6 WSON 8-Contact 6x5 mm Leadless (WND008)



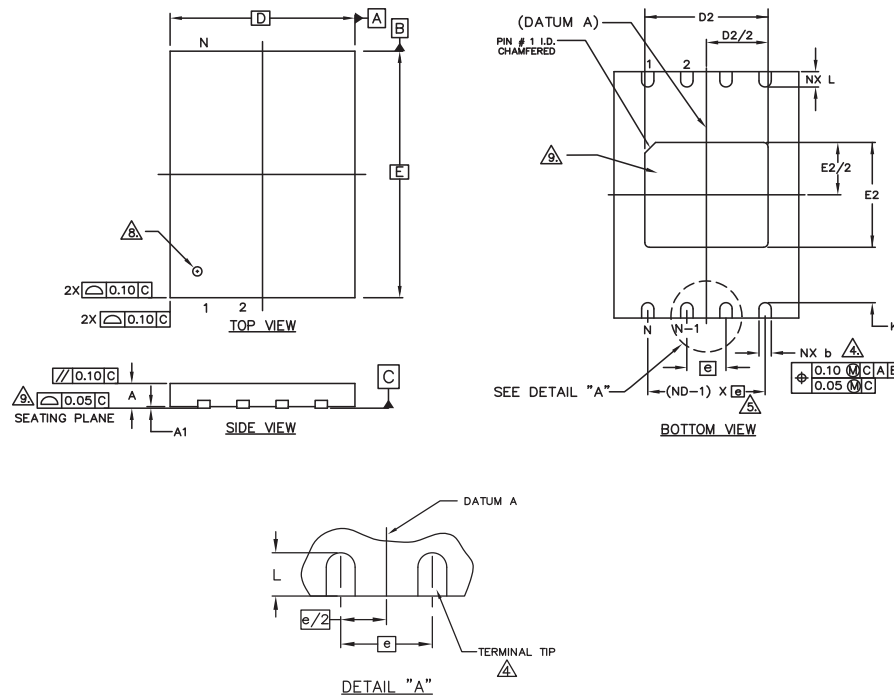
PACKAGE	WND008			
SYMBOL	MIN	NOM	MAX	NOTES
[e]	1.27 BSC.			
N	8			3
ND	4			5
L	0.55	0.60	0.65	
b	0.35	0.40	0.45	4
D2	3.90	4.00	4.10	
E2	3.30	3.40	3.50	
D	5.00 BSC			
E	6.00 BSC			
A	0.70	0.75	0.80	
A1	0.00	0.02	0.05	
K	0.20 MIN.			

NOTES:

1. DIMENSIONING AND TOLERANCING CONFORMS TO ASME Y14.5M - 1994.
2. ALL DIMENSIONS ARE IN MILLIMETERS.
3. N IS THE TOTAL NUMBER OF TERMINALS.
4. DIMENSION "b" APPLIES TO METALLIZED TERMINAL AND IS MEASURED BETWEEN 0.15 AND 0.30mm FROM TERMINAL TIP. IF THE TERMINAL HAS THE OPTIONAL RADIUS ON THE OTHER END OF THE TERMINAL, THE DIMENSION "b" SHOULD NOT BE MEASURED IN THAT RADIUS AREA.
5. ND REFERS TO THE NUMBER OF TERMINALS ON D SIDE.
6. MAX. PACKAGE WARPAGE IS 0.05mm.
7. MAXIMUM ALLOWABLE BURR IS 0.076mm IN ALL DIRECTIONS.
8. PIN #1 ID ON TOP WILL BE LASER MARKED.
9. BILATERAL COPLANARITY ZONE APPLIES TO THE EXPOSED HEAT SINK SLUG AS WELL AS THE TERMINALS.

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Figure 7.7 WSON 8-Contact 6x8 mm Leadless (WNH008)



PACKAGE	WNH008			
SYMBOL	MIN	NOM	MAX	NOTE
e	1.27 BSC.			
N	8			3
ND	4			5
L	0.45	0.50	0.55	
b	0.35	0.40	0.45	4
D2	3.90	4.00	4.10	
E2	3.30	3.40	3.50	
D	6.00 BSC			
E	8.00 BSC			
A	0.70	0.75	0.80	
A1	0.00	---	0.05	
K	0.20 MIN.			

NOTES:

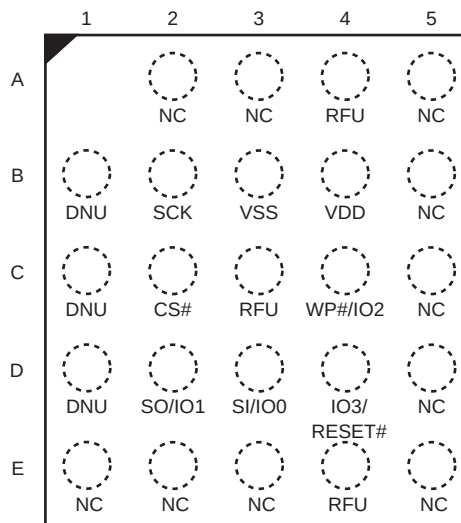
1. DIMENSIONING AND TOLERANCING CONFORMS TO ASME Y14.5M - 1994.
2. ALL DIMENSIONS ARE IN MILLIMETERS.
3. N IS THE TOTAL NUMBER OF TERMINALS.
4. DIMENSION "b" APPLIES TO METALLIZED TERMINAL AND IS MEASURED BETWEEN 0.15 AND 0.30mm FROM TERMINAL TIP. IF THE TERMINAL HAS THE OPTIONAL RADIUS ON THE OTHER END OF THE TERMINAL, THE DIMENSION "b" SHOULD NOT BE MEASURED IN THAT RADIUS AREA.
5. ND REFERS TO THE NUMBER OF TERMINALS ON D SIDE.
6. MAX. PACKAGE WARPAGE IS 0.05mm.
7. MAXIMUM ALLOWABLE BURRS IS 0.076mm IN ALL DIRECTIONS.
8. PIN #1 ID ON TOP WILL BE LASER MARKED.
9. BILATERAL COPLANARITY ZONE APPLIES TO THE EXPOSED HEAT SINK SLUG AS WELL AS THE TERMINALS.

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7.3 FAB024 24-Ball BGA Package

7.3.1 Connection Diagrams

Figure 7.8 24-Ball BGA, 5x5 Ball Footprint (FAB024), Top View

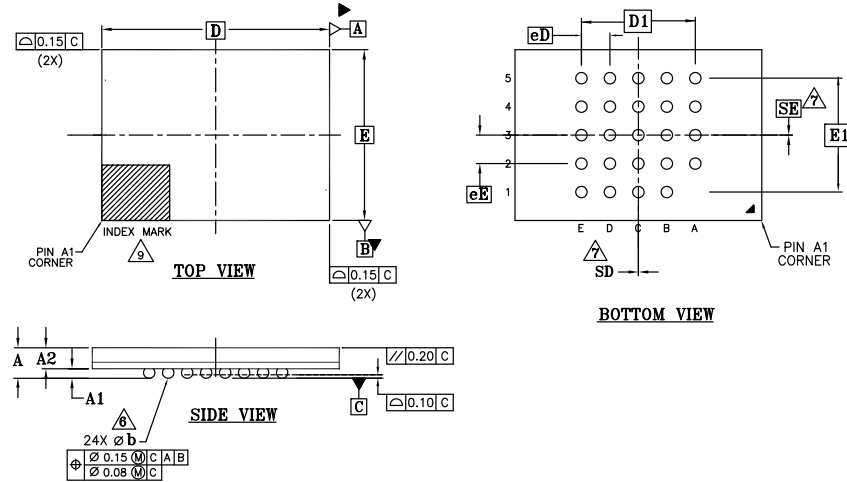


Notes:

1. Signal connections are in the same relative positions as FAC024 BGA, allowing a single PCB footprint to use either package.
2. The RESET# input has an internal pull-up and may be left unconnected in the system if Quad Mode and hardware reset are not in use.

7.3.2 Physical Diagram

Figure 7.9 Ball Grid Array 24-Ball 6x8 mm (FAB024)



PACKAGE	FAB024			
JEDEC	N/A			
	8.00mmx6.00mm NOM PACKAGE			
SYMBOL	MIN.	NOM.	MAX.	NOTE
A	—	—	1.20	OVERALL THICKNESS
A1	0.20	—	—	BALL HEIGHT
A2	0.70	—	0.90	BODY THICKNESS
D	8.00 BSC.			BODY SIZE
E	6.00 BSC.			BODY SIZE
D1	4.00 BSC.			BALL FOOTPRINT
E1	4.00 BSC.			BALL FOOTPRINT
MD	5			ROW MATRIX SIZE D DIRECTION
ME	5			ROW MATRIX SIZE E DIRECTION
N	24			TOTAL BALL COUNT
Øb	0.35	0.40	0.45	BALL DIAMETER
e	1.00 BSC.			BALL PITCH
SD/SE	0.00			SOLDER BALL PLACEMENT
	A1			DEPOPULATED SOLDER BALLS
	I			PACKAGE OUTLINE TYPE

NOTES:

- DIMENSIONING AND TOLERANCING METHODS PER ASME Y14.5M-1994.
- ALL DIMENSIONS ARE IN MILLIMETERS.
- BALL POSITION DESIGNATION PER JEP95, SECTION 4.3, SFP-010.
- [e] REPRESENTS THE SOLDER BALL GRID PITCH.
- SYMBOL "MD" IS THE BALL MATRIX SIZE IN THE "D" DIRECTION. SYMBOL "ME" IS THE BALL MATRIX SIZE IN THE "E" DIRECTION. n IS THE NUMBER OF POPULATED SOLDER BALL POSITIONS FOR MATRIX SIZE MD X ME.

- DIMENSION "b" IS MEASURED AT THE MAXIMUM BALL DIAMETER IN A PLANE PARALLEL TO DATUM C.
- SD AND SE ARE MEASURED WITH RESPECT TO DATUMS A AND B AND DEFINE THE POSITION OF THE CENTER SOLDER BALL IN THE OUTER ROW.

WHEN THERE IS AN ODD NUMBER OF SOLDER BALLS IN THE OUTER ROW SD OR SE = 0.000.

WHEN THERE IS AN EVEN NUMBER OF SOLDER BALLS IN THE OUTER ROW, SD OR SE = $e/2$

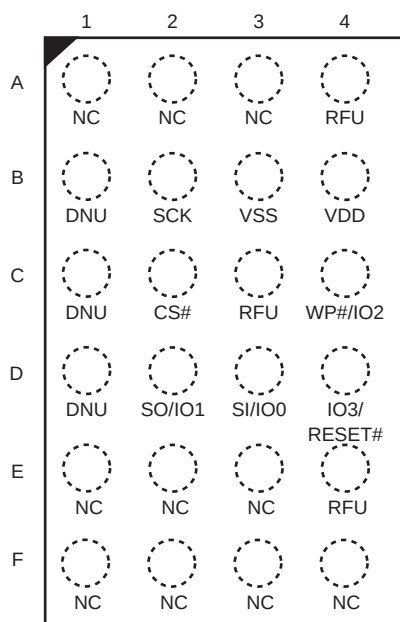
- "+" INDICATES THE THEORETICAL CENTER OF DEPOPULATED BALLS.
- A1 CORNER TO BE IDENTIFIED BY CHAMFER, LASER OR INK MARK, METALLIZED MARK INDENTATION OR OTHER MEANS.

4002/F16-038 Rev.A /6.04.09

7.4 FAC024 24-Ball BGA Package

7.4.1 Connection Diagram

Figure 7.10 24-Ball BGA, 4x6 Ball Footprint (FAC024), Top View

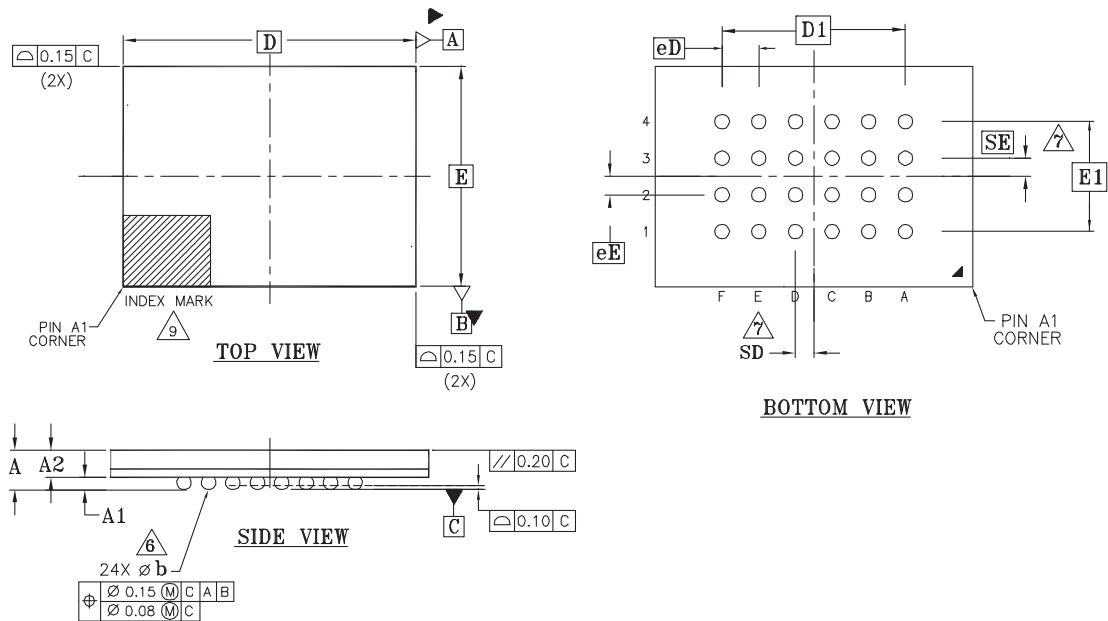


Notes:

1. Signal connections are in the same relative positions as FAB024 BGA, allowing a single PCB footprint to use either package.
2. The RESET# input has an internal pull-up and may be left unconnected in the system if Quad Mode and hardware reset are not in use.

7.4.2 Physical Diagram

Figure 7.11 Ball Grid Array 24-Ball 6 x 8 mm (FAC024)



PACKAGE	FAC024			
JEDEC	N/A			
D x E	8.00 mm x 6.00 mm NOM PACKAGE			
SYMBOL	MIN	NOM	MAX	NOTE
A	----	----	1.20	PROFILE
A1	0.25	----	----	BALL HEIGHT
A2	0.70	----	0.90	BODY THICKNESS
D	8.00 BSC.			BODY SIZE
E	6.00 BSC.			BODY SIZE
D1	5.00 BSC.			MATRIX FOOTPRINT
E1	3.00 BSC.			MATRIX FOOTPRINT
MD	6			MATRIX SIZE D DIRECTION
ME	4			MATRIX SIZE E DIRECTION
N	24			BALL COUNT
Øb	0.35	0.40	0.45	BALL DIAMETER
e	1.00 BSC.			BALL PITCH
SD/ SE	0.5/0.5			SOLDER BALL PLACEMENT
				DEPOPULATED SOLDER BALLS
	J			PACKAGE OUTLINE TYPE

NOTES:

- DIMENSIONING AND TOLERANCING METHODS PER ASME Y14.5M-1994.
- ALL DIMENSIONS ARE IN MILLIMETERS.
- BALL POSITION DESIGNATION PER JEP95, SECTION 4.3, SPP-010.
- [e] REPRESENTS THE SOLDER BALL GRID PITCH.
- SYMBOL "MD" IS THE BALL MATRIX SIZE IN THE "D" DIRECTION.
SYMBOL "ME" IS THE BALL MATRIX SIZE IN THE "E" DIRECTION.
n IS THE NUMBER OF POPULATED SOLDER BALL POSITIONS FOR MATRIX SIZE MD X ME.
- DIMENSION "b" IS MEASURED AT THE MAXIMUM BALL DIAMETER IN A PLANE PARALLEL TO DATUM C.
- DATUM C IS THE SEATING PLANE AND IS DEFINED BY THE CROWNS OF THE SOLDER BALLS.
- SD AND SE ARE MEASURED WITH RESPECT TO DATUMS A AND B AND DEFINE THE POSITION OF THE CENTER SOLDER BALL IN THE OUTER ROW.
- WHEN THERE IS AN ODD NUMBER OF SOLDER BALLS IN THE OUTER ROW SD OR SE = 0.000.
- WHEN THERE IS AN EVEN NUMBER OF SOLDER BALLS IN THE OUTER ROW, SD OR SE = e/2
- "+" INDICATES THE THEORETICAL CENTER OF DEPOPULATED BALLS.
- A1 CORNER TO BE IDENTIFIED BY CHAMFER, LASER OR INK MARK, METALLIZED MARK INDENTATION OR OTHER MEANS.
- OUTLINE AND DIMENSIONS PER CUSTOMER REQUIREMENT.

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7.4.3 Special Handling Instructions for FBGA Packages

Flash memory devices in BGA packages may be damaged if exposed to ultrasonic cleaning methods. The package and/or data integrity may be compromised if the package body is exposed to temperatures above 150°C for prolonged periods of time.

Software Interface

This section discusses the features and behaviors most relevant to host system software that interacts with S25FS-S family memory devices.

8. Address Space Maps

8.1 Overview

8.1.1 Extended Address

The S25FS-S family supports 32-bit (4-byte) addresses to enable higher density devices than allowed by previous generation (legacy) SPI devices that supported only 24-bit (3-byte) addresses. A 24-bit, byte resolution, address can access only 16-Mbytes (128-Mbits) maximum density. A 32-bit, byte resolution, address allows direct addressing of up to a 4-Gbytes (32-Gbits) address space.

Legacy commands continue to support 24-bit addresses for backward software compatibility. Extended 32-bit addresses are enabled in two ways:

- Extended address mode — a volatile Configuration Register bit that changes all legacy commands to expect 32 bits of address supplied from the host system.
- 4-byte address commands — that perform both legacy and new functions, which always expect 32-bit address.

The default condition for extended address mode, after power-up or reset, is controlled by a non-volatile configuration bit. The default extended address mode may be set for 24- or 32-bit addresses. This enables legacy software compatible access to the first 128 Mbits of a device or for the device to start directly in 32-bit address mode.

The 128-Mbit density member of the S25FS-S family supports the extended address features in the same way but in essence ignores bits 31 to 24 of any address because the main flash array only needs 24 bits of address. This enables simple migration from the 128-Mb density to higher density devices without changing the address handling aspects of software.

8.1.2 Multiple Address Spaces

Many commands operate on the main flash memory array. Some commands operate on address spaces separate from the main flash array. Each separate address space uses the full 24- or 32-bit address but may only define a small portion of the available address space.

8.2 Flash Memory Array

The main flash array is divided into erase units called physical sectors.

The FS-S family physical sectors may be configured as a hybrid combination of eight 4-kB parameter sectors at the top or bottom of the address space with all but one of the remaining sectors being uniform size. Because the group of eight 4-kB parameter sectors is in total smaller than a uniform sector, the group of 4-kB physical sectors respectively overlay (replace) the top or bottom 32 kB of the highest or lowest address uniform sector.

The Parameter Sector Erase commands (20h or 21h) must be used to erase the 4-kB sectors individually. The Sector (uniform block) Erase commands (D8h or DCh) must be used to erase any of the remaining sectors, including the portion of highest or lowest address sector that is not overlaid by the parameter sectors. The uniform block erase command has no effect on parameter sectors.

Configuration Register 1 non-volatile bit 2 (CR1NV[2]) equal to 0 overlays the parameter sectors at the bottom of the lowest address uniform sector. CR1NV[2] = 1 overlays the parameter sectors at the top of the highest address uniform sector. See [Section 8.6, Registers on page 59](#) for more information.

There is also a configuration option to remove the 4-kB parameter sectors from the address map so that all sectors are uniform size. Configuration Register 3 volatile bit 3 (CR3V[3]) equal to 0 selects the hybrid sector

architecture with 4-kB parameter sectors. CR3V[3]=1 selects the uniform sector architecture without parameter sectors. Uniform physical sectors are 64 kB in FS128S and FS256S.

Both devices also may be configured to use the Sector (uniform block) Erase commands to erase 256-kB logical blocks rather than individual 64-kB physical sectors. This configuration option (CR3V[1]=1) allows lower density devices to emulate the same Sector Erase behavior as higher density members of the family that use 256-kB physical sectors. This can simplify software migration to the higher density members of the family.

Table 8.1 S25FS256S Sector Address Map, Bottom 4-kB Sectors, 64-kB Physical Uniform Sectors

Sector Size (kbyte)	Sector Count	Sector Range	Address Range (Byte Address)	Notes
4	8	SA00	00000000h-0000FFFFh	Sector Starting Address — Sector Ending Address
		:	:	
		SA07	00007000h-00007FFFh	
32	1	SA08	00008000h-0000FFFFh	
64	511	SA09	00010000h-0001FFFFh	
		:	:	
		SA519	01FF0000h-01FFFFFFh	

Table 8.2 S25FS256S Sector Address Map, Top 4-kB Sectors, 64-kB Physical Uniform Sectors

Sector Size (kbyte)	Sector Count	Sector Range	Address Range (Byte Address)	Notes
64	511	SA00	0000000h-000FFFFh	Sector Starting Address — Sector Ending Address
		:	:	
		SA510	01FE0000h-01FEFFFFh	
32	1	SA511	01FF0000h-01FF7FFFh	
4	8	SA512	01FF8000h-01FF8FFFh	
		:	:	
		SA519	01FFF000h-01FFFFFFh	

Table 8.3 S25FS256S Sector Address Map, Uniform 64-kB Physical Sectors

Sector Size (kbyte)	Sector Count	Sector Range	Address Range (8-bit)	Notes
64	512	SA00	0000000h-000FFFFh	Sector Starting Address — Sector Ending Address
		:	:	
		SA511	1FF0000h-1FFFFFFh	

Table 8.4 S25FS256S Sector Address Map, Bottom 4-kB Sectors, 256-kB Logical Uniform Sectors

Sector Size (kbyte)	Sector Count	Sector Range	Address Range (Byte Address)	Notes
4	8	SA00	00000000h-0000FFFFh	Sector Starting Address — Sector Ending Address
		:	:	
		SA07	00007000h-00007FFFh	
224	1	SA08	00008000h-0003FFFFh	
256	127	SA09	00040000h-0007FFFFh	
		:	:	
		SA135	01FC0000h-01FFFFFFh	

Table 8.5 S25FS256S Sector Address Map, Top 4-kB Sectors, 256-kB Logical Uniform Sectors

Sector Size (kbyte)	Sector Count	Sector Range	Address Range (Byte Address)	Notes
256	127	SA00	0000000h-003FFFFh	Sector Starting Address — Sector Ending Address
		:	:	
		SA126	01F80000h-01FBFFFFh	
224	1	SA127	01FC0000h-01FC7FFFh	
4	8	SA128	01FF8000h-01FF8FFFh	
		:	:	
		SA135	01FFF000h-01FFFFFFh	

Table 8.6 S25FS256S Sector Address Map, Uniform 256-kB Logical Sectors

Sector Size (kbyte)	Sector Count	Sector Range	Address Range (8-bit)	Notes
256	128	SA00	00000000h-0003FFFFh	Sector Starting Address — Sector Ending Address
		:	:	
		SA127	01FC0000h-01FFFFFFh	

Table 8.7 S25FS128S Sector and Memory Address Map, Bottom 4-kB Sectors

Sector Size (kbyte)	Sector Count	Sector Range	Address Range (Byte Address)	Notes
4	8	SA00	00000000h-0000FFFFh	Sector Starting Address — Sector Ending Address
		:	:	
		SA07	00007000h-00007FFFh	
32	1	SA08	00008000h-0000FFFFh	
64	255	SA09	00010000h-0001FFFFh	
		:	:	
		SA263	00FF0000h-00FFFFFFh	

Table 8.8 S25FS128S Sector and Memory Address Map, Top 4-kB Sectors

Sector Size (kbyte)	Sector Count	Sector Range	Address Range (Byte Address)	Notes
64	255	SA00	0000000h-000FFFFh	Sector Starting Address — Sector Ending Address
		:	:	
		SA254	00FE0000h-00FEFFFFh	
32	1	SA255	00FF0000h - 00FF7FFFh	
4	8	SA256	00FF8000h - 00FF8FFFh	
		:	:	
		SA263	00FFF000h-00FFFFFFh	

Table 8.9 S25FS128S Sector and Memory Address Map, Uniform 64-kB Blocks

Sector Size (kbyte)	Sector Count	Sector Range	Address Range (Byte Address)	Notes
64	256	SA00	0000000h-0000FFFFh,	Sector Starting Address — Sector Ending Address
		:	:	
		SA255	00FF0000h-0FFFFFFh	

Table 8.10 S25FS128S Sector Address Map, Bottom 4-kB Sectors, 256-kB Logical Uniform Sectors

Sector Size (kbyte)	Sector Count	Sector Range	Address Range (Byte Address)	Notes
4	8	SA00	00000000h-00000FFFh	Sector Starting Address — Sector Ending Address
		:	:	
		SA07	00007000h-00007FFFh	
224	1	SA08	00008000h-0003FFFFh	
256	63	SA09	00040000h-0007FFFFh	
		:	:	
		SA71	00FC0000h-00FFFFFFh	

Table 8.11 S25FS128S Sector Address Map, Top 4-kB Sectors, 256-kB Logical Uniform Sectors

Sector Size (kbyte)	Sector Count	Sector Range	Address Range (Byte Address)	Notes
256	63	SA00	00000000h-0003FFFFh	Sector Starting Address — Sector Ending Address
		:	:	
		SA62	00F80000h-00FBFFFFh	
224	1	SA63	00FC0000h-00FF7FFFh	
4	8	SA64	00FF8000h-00FF8FFFh	
		:	:	
		SA71	00FFF000h-00FFFFFFh	

Table 8.12 S25FS128S Sector and Memory Address Map, Uniform 256-kB Blocks

Sector Size (kbyte)	Sector Count	Sector Range	Address Range (Byte Address)	Notes
256	64	SA00	00000000h-0003FFFFh	Sector Starting Address — Sector Ending Address
		:	:	
		SA63	00FC0000h-00FFFFFFh	

Note: These are condensed tables that use a couple of sectors as references. There are address ranges that are not explicitly listed. All 4-kB sectors have the pattern XXXX000h-XXXXFFFh. All 64-kB sectors have the pattern XXX0000h-XXXFFFFh. All 256-kB sectors have the pattern XX00000h-XX3FFFFh, XX40000h-XX7FFFFh, XX80000h-XXCFFFFh, or XXD0000h-XXFFFFFFh.

8.3 ID-CFI Address Space

The RDID command (9Fh) reads information from a separate flash memory address space for device identification (ID) and Common Flash Interface (CFI) information. See [Section 12.4, Device ID and Common Flash Interface \(ID-CFI\) Address Map on page 143](#) for the tables defining the contents of the ID-CFI address space. The ID-CFI address space is programmed by Spansion and read-only for the host system.

8.4 JEDEC JESD216 Serial Flash Discoverable Parameters (SFDP) Space.

The RSFDP command (5Ah) reads information from a separate flash memory address space for device identification, feature, and configuration information, in accord with the JEDEC JESD216 standard for Serial Flash Discoverable Parameters. The ID-CFI address space is incorporated as one of the SFDP parameters. See [Section 12.3, Serial Flash Discoverable Parameters \(SFDP\) Address Map on page 142](#) for the tables defining the contents of the SFDP address space. The SFDP address space is programmed by Spansion and read-only for the host system.

8.5 OTP Address Space

Each FS-S family memory device has a 1024-byte One-Time Program (OTP) address space that is separate from the main flash array. The OTP area is divided into 32, individually lockable, 32-byte aligned and length regions.

In the 32-byte region starting at address zero:

- The 16 lowest address bytes are programmed by Spansion with a 128-bit random number. Only Spansion is able to program zeros in these bytes. Programming ones in these byte locations is ignored and does not affect the value programmed by Spansion. Attempting to program any zero in these byte locations will fail and set P_ERR.
- The next 4 higher address bytes (OTP Lock Bytes) are used to provide one bit per OTP region to permanently protect each region from programming. The bytes are erased when shipped from Spansion. After an OTP region is programmed, it can be locked to prevent further programming, by programming the related protection bit in the OTP Lock Bytes.
- The next higher 12 bytes of the lowest address region are Reserved for Future Use (RFU). The bits in these RFU bytes may be programmed by the host system but it must be understood that a future device may use those bits for protection of a larger OTP space. The bytes are erased when shipped from Spansion.

The remaining regions are erased when shipped from Spansion, and are available for programming of additional permanent data.

Refer to [Figure 8.1, OTP Address Space on page 58](#) for a pictorial representation of the OTP memory space.

The OTP memory space is intended for increased system security. OTP values, such as the random number programmed by Spansion, can be used to “mate” a flash component with the system CPU/ASIC to prevent device substitution.

The Configuration Register FREEZE (CR1V[0]) bit protects the entire OTP memory space from programming when set to 1. This allows trusted boot code to control programming of OTP regions then set the FREEZE bit to prevent further OTP memory space programming during the remainder of normal power-on system operation.

Figure 8.1 OTP Address Space

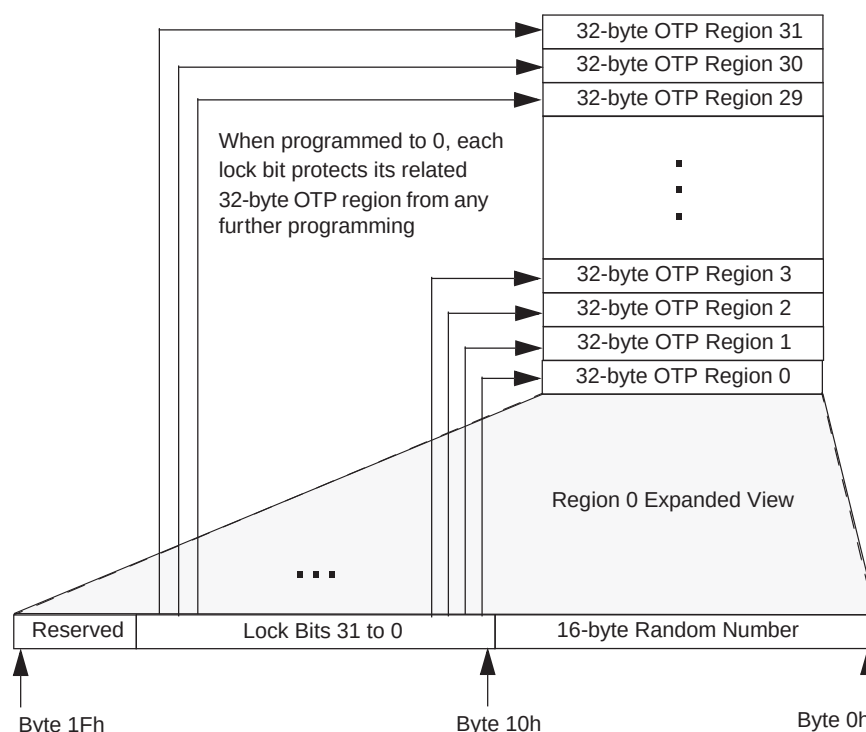


Table 8.13 OTP Address Map

Region	Byte Address Range (Hex)	Contents	Initial Delivery State (Hex)
Region 0	000	Least Significant Byte of Spansion Programmed Random Number	Spansion Programmed Random Number
	...	...	
	00F	Most Significant Byte of Spansion Programmed Random Number	
	010 to 013	Region Locking Bits Byte 10 [bit 0] locks region 0 from programming when = 0 ... Byte 13 [bit 7] locks region 31 from programming when = 0	All Bytes = FF
	014 to 01F	Reserved for Future Use (RFU)	All Bytes = FF
Region 1	020 to 03F	Available for User Programming	All Bytes = FF
Region 2	040 to 05F	Available for User Programming	All Bytes = FF
...	...	Available for User Programming	All Bytes = FF
Region 31	3E0 to 3FF	Available for User Programming	All Bytes = FF

8.6 Registers

Registers are small groups of memory cells used to configure how the S25FS-S family memory device operates or to report the status of device operations. The registers are accessed by specific commands. The commands (and hexadecimal instruction codes) used for each register are noted in each register description.

In legacy SPI memory devices the individual register bits could be a mixture of volatile, non-volatile, or One-Time Programmable (OTP) bits within the same register. In some configuration options the type of a register bit could change e.g. from non-volatile to volatile.

The S25FS-S family uses separate non-volatile or volatile memory cell groups (areas) to implement the different register bit types. However, the legacy registers and commands continue to appear and behave as they always have for legacy software compatibility. There is a non-volatile and a volatile version of each legacy register when that legacy register has volatile bits or when the command to read the legacy register has zero read latency. When such a register is read the volatile version of the register is delivered. During Power-On Reset (POR), hardware reset, or software reset, the non-volatile version of a register is copied to the volatile version to provide the default state of the volatile register. When non-volatile register bits are written the non-volatile version of the register is erased and programmed with the new bit values and the volatile version of the register is updated with the new contents of the non-volatile version. When OTP bits are programmed the non-volatile version of the register is programmed and the appropriate bits are updated in the volatile version of the register. When volatile register bits are written, only the volatile version of the register has the appropriate bits updated.

The type for each bit is noted in each register description. The default state shown for each bit refers to the state after Power-On Reset, hardware reset, or software reset if the bit is volatile. If the bit is non-volatile or OTP, the default state is the value of the bit when the device is shipped from Spansion. Non-Volatile bits have the same cycling (erase and program) endurance as the main flash array.

8.6.1 Status Register 1

8.6.1.1 Status Register 1 Non-Volatile (SR1NV)

Related Commands: Write Registers (WRR 01h), Read Any Register (RDAR 65h), Write Any Register (WRAR 71h)

Table 8.14 Status Register 1 Non-Volatile (SR1NV)

Bits	Field Name	Function	Type	Default State	Description
7	SRWD_NV	Status Register Write Disable Default	Non-Volatile	0	1 = Locks state of SRWD, BP, and Configuration Register 1 bits when WP# is low by not executing WRR or WRAR commands that would affect SR1NV, SR1V, CR1NV, or CR1V. 0 = No protection, even when WP# is low.
6	P_ERR_D	Programming Error Default	Non-Volatile Read Only	0	Provides the default state for the Programming Error Status. Not user programmable.
5	E_ERR_D	Erase Error Default	Non-Volatile Read Only	0	Provides the default state for the Erase Error Status. Not user programmable.
4	BP_NV2	Block Protection Non-Volatile	Non-Volatile	000b	Protects the selected range of sectors (Block) from Program or Erase when the BP bits are configured as non-volatile (CR1NV[3]=0). Programmed to 111b when BP bits are configured to volatile (CR1NV[3]=1).- after which these bits are no longer user programmable.
3	BP_NV1				
2	BP_NV0				
1	WEL_D	WEL Default	Non-Volatile Read Only	0	Provides the default state for the WEL Status. Not user programmable.
0	WIP_D	WIP Default	Non-Volatile Read Only	0	Provides the default state for the WIP Status. Not user programmable.

Status Register Write Non-Volatile (SRWD_NV) SR1NV[7]: Places the device in the Hardware Protected mode when this bit is set to 1 and the WP# input is driven low. In this mode, the Write Registers (WRR) and Write Any Register (WRAR) commands (that select Status Register 1 or Configuration Register 1) are ignored and not accepted for execution, effectively locking the state of the Status Register 1 and Configuration Register 1 (SR1NV, SR1V, CR1NV, or CR1V) bits, by making the registers read-only. If WP# is high, Status Register 1 and Configuration Register 1 may be changed by the WRR or WRAR commands. If SRWD_NV is 0, WP# has no effect and Status Register 1 and Configuration Register 1 may be changed by the WRR or WRAR commands. WP# has no effect on the writing of any other registers. The SRWD_NV bit has the same non-volatile endurance as the main flash array. The SRWD (SR1V[7]) bit serves only as a copy of the SRWD_NV bit to provide zero read latency.

Program Error Default (P_ERR_D) SR1NV[6]: Provides the default state for the Programming Error Status in SR1V[6]. This bit is not user programmable.

Erase Error (E_ERR) SR1V[5]: Provides the default state for the Erase Error Status in SR1V[5]. This bit is not user programmable.

Block Protection (BP_NV2, BP_NV1, BP_NV0) SR1NV[4:2]: These bits define the main flash array area to be software-protected against Program and Erase commands. The BP bits are selected as either volatile or non-volatile, depending on the state of the BP non-volatile bit (BPNV_O) in the Configuration Register CR1NV[3]. When CR1NV[3]=0 the non-volatile version of the BP bits (SR1NV[4:2]) are used to control Block Protection and the WRR command writes SR1NV[4:2] and updates SR1V[4:2] to the same value. When CR1NV[3]=1 the volatile version of the BP bits (SR1V[4:2]) are used to control Block Protection and the WRR command writes SR1V[4:2] and does not affect SR1NV[4:2]. When one or more of the BP bits is set to 1, the relevant memory area is protected against Program and Erase. The Bulk Erase (BE) command can be executed only when the BP bits are cleared to 0's. See [Section 9.3, Block Protection on page 77](#) for a description of how the BP bit values select the memory array area protected. The non-volatile version of the BP bits have the same non-volatile endurance as the main flash array.

Write Enable Latch Default (WEL_D) SR1NV[1]: Provides the default state for the WEL Status in SR1V[1]. This bit is programmed by Spansion and is not user programmable.

Write-In-Progress Default (WIP_D) SR1NV[0]: Provides the default state for the WIP Status in SR1V[0]. This bit is programmed by Spansion and is not user programmable.

8.6.1.2 Status Register 1 Volatile (SR1V)

Related Commands: Read Status Register (RDSR1 05h), Write Registers (WRR 01h), Write Enable (WREN 06h), Write Disable (WRDI 04h), Clear Status Register (CLSR 30h or 82h), Read Any Register (RDAR 65h), Write Any Register (WRAR 71h). This is the register displayed by the RDSR1 command.

Table 8.15 Status Register 1 Volatile (SR1V)

Bits	Field Name	Function	Type	Default State	Description
7	SRWD	Status Register Write Disable	Volatile Read Only	SR1NV	Volatile copy of SR1NV[7].
6	P_ERR	Programming Error Occurred	Volatile Read Only		1 = Error occurred. 0 = No Error.
5	E_ERR	Erase Error Occurred	Volatile Read Only		1= Error occurred. 0 = No Error.
4	BP2	Block Protection Volatile	Volatile		Protects selected range of sectors (Block) from Program or Erase when the BP bits are configured as volatile (CR1NV[3]=1). Volatile copy of SR1NV[4:2] when BP bits are configured as non-volatile. User writable when BP bits are configured as volatile.
3	BP1				
2	BP0				
1	WEL	Write Enable Latch	Volatile		1 = Device accepts Write Registers (WRR and WRAR), Program, or Erase commands. 0 = Device ignores Write Registers (WRR and WRAR), Program, or Erase commands. This bit is not affected by WRR or WRAR, only WREN and WRDI commands affect this bit.
0	WIP	Write-In-Progress	Volatile Read Only		1= Device Busy, an embedded operation is in progress such as Program or Erase. 0 = Ready Device is in Standby mode and can accept commands. This bit is not affected by WRR or WRAR, it only provides WIP status.

Status Register Write (SRWD) SR1V[7]: SRWD is a volatile copy of SR1NV[7]. This bit tracks any changes to the non-volatile version of this bit.

Program Error (P_ERR) SR1V[6]: The Program Error bit is used as a program operation success or failure indication. When the Program Error bit is set to a 1 it indicates that there was an error in the last program operation. This bit will also be set when the user attempts to program within a protected main memory sector, or program within a locked OTP region. When the Program Error bit is set to a 1 this bit can be cleared to 0 with the Clear Status Register (CLSR) command. This is a read-only bit and is not affected by the WRR or WRAR commands.

Erase Error (E_ERR) SR1V[5]: The Erase Error bit is used as an Erase operation success or failure indication. When the Erase Error bit is set to a 1 it indicates that there was an error in the last erase operation. This bit will also be set when the user attempts to erase an individual protected main memory sector. The Bulk Erase command will not set E_ERR if a protected sector is found during the command execution. When the Erase Error bit is set to a 1 this bit can be cleared to 0 with the Clear Status Register (CLSR) command. This is a read-only bit and is not affected by the WRR or WRAR commands.

Block Protection (BP2, BP1, BP0) SR1V[4:2]: These bits define the main flash array area to be software protected against program and Erase commands. The BP bits are selected as either volatile or non-volatile, depending on the state of the BP non-volatile bit (BPNV_O) in the Configuration Register CR1NV[3]. When CR1NV[3]=0 the non-volatile version of the BP bits (SR1NV[4:2]) are used to control Block Protection and the WRR command writes SR1NV[4:2] and updates SR1V[4:2] to the same value. When CR1NV[3]=1 the volatile version of the BP bits (SR1V[4:2]) are used to control Block Protection and the WRR command writes SR1V[4:2] and does not affect SR1NV[4:2]. When one or more of the BP bits is set to 1, the relevant memory area is protected against program and erase. The Bulk Erase (BE) command can be executed only when the BP bits are cleared to 0's. See [Section 9.3, Block Protection on page 77](#) for a description of how the BP bit values select the memory array area protected.

Write Enable Latch (WEL) SR1V[1]: The WEL bit must be set to 1 to enable program, write, or erase operations as a means to provide protection against inadvertent changes to memory or register values. The Write Enable (WREN) command execution sets the Write Enable Latch to a 1 to allow any program, erase, or write commands to execute afterwards. The Write Disable (WRDI) command can be used to set the Write Enable Latch to a 1 to prevent all program, erase, and write commands from execution. The WEL bit is cleared to 0 at the end of any successful program, write, or erase operation. Following a failed operation the WEL bit may remain set and should be cleared with a WRDI command following a CLSR command. After a power-down / power-up sequence, hardware reset, or software reset, the Write Enable Latch is set to a 0. The WRR or WRAR command does not affect this bit.

Write-In-Progress (WIP) SR1V[0]: Indicates whether the device is performing a program, write, erase operation, or any other operation, during which a new operation command will be ignored. When the bit is set to a 1 the device is busy performing an operation. While WIP is 1, only Read Status (RDSR1 or RDSR2), Read Any Register (RDAR), Erase Suspend (ERSP), Program Suspend (PGSP), Clear Status Register (CLSR), and software reset (RESET) commands are accepted. ERSP and PGSP will only be accepted if memory array erase or program operations are in progress. The Status Register E_ERR and P_ERR bits are updated while WIP = 1. When P_ERR or E_ERR bits are set to 1, the WIP bit will remain set to 1 indicating the device remains busy and unable to receive new operation commands. A Clear Status Register (CLSR) command must be received to return the device to standby mode. When the WIP bit is cleared to 0 no operation is in progress. This is a read-only bit.

8.6.2 Status Register 2 Volatile (SR2V)

Related Commands: Read Status Register 2 (RDSR2 07h), Read Any Register (RDAR 65h).

Status Register 2 does not have user programmable non-volatile bits, all defined bits are volatile read only status. The default state of these bits are set by hardware.

Table 8.16 Status Register 2 Volatile (SR2V)

Bits	Field Name	Function	Type	Default State	Description
7	RFU	Reserved		0	Reserved for Future Use.
6	RFU	Reserved		0	Reserved for Future Use.
5	RFU	Reserved		0	Reserved for Future Use.
4	RFU	Reserved		0	Reserved for Future Use.
3	RFU	Reserved		0	Reserved for Future Use.
2	ESTAT	Erase Status	Volatile Read Only	0	1 = Sector Erase Status command result = Erase Completed. 0 = Sector Erase Status command result = Erase Not Completed.
1	ES	Erase Suspend	Volatile Read Only	0	1 = In Erase Suspend mode. 0 = Not in Erase Suspend mode.
0	PS	Program Suspend	Volatile Read Only	0	1 = In Program Suspend mode. 0 = Not in Program Suspend mode.

Erase Status (ESTAT) SR2V[2]: The Erase Status bit indicates whether the sector, selected by an immediately preceding Erase Status command, completed the last Erase command on that sector. The Erase Status command must be issued immediately before reading SR2V to get valid Erase Status. Reading SR2V during a program or erase suspend does not provide valid Erase Status. The Erase Status bit can be used by system software to detect any sector that failed its last erase operation. This can be used to detect erase operations failed due to loss of power during the erase operation.

Erase Suspend (ES) SR2V[1]: The Erase Suspend bit is used to determine when the device is in Erase Suspend mode. This is a status bit that cannot be written by the user. When Erase Suspend bit is set to 1, the device is in Erase Suspend mode. When Erase Suspend bit is cleared to 0, the device is not in erase suspend mode. Refer to [Section 10.6.5, Program or Erase Suspend \(PES 85h, 75h, B0h\)](#) on page 120 for details about the Erase Suspend/Resume commands.

Program Suspend (PS) SR2V[0]: The Program Suspend bit is used to determine when the device is in Program Suspend mode. This is a status bit that cannot be written by the user. When Program Suspend bit is set to 1, the device is in Program Suspend mode. When the Program Suspend bit is cleared to 0, the device is not in Program Suspend mode. Refer to [Section 10.6.5, Program or Erase Suspend \(PES 85h, 75h, B0h\)](#) on page 120 for details.

8.6.3 Configuration Register 1

Configuration Register 1 controls certain interface and data protection functions. The register bits can be changed using the WRR command with sixteen input cycles or with the WRAR command.

8.6.3.1 Configuration Register 1 Non-Volatile (CR1NV)

Related Commands: Write Registers (WRR 01h), Read Any Register (RDAR 65h), Write Any Register (WRAR 71h).

Table 8.17 Configuration Register 1 Non-Volatile (CR1NV)

Bits	Field Name	Function	Type	Default State	Description
7	RFU	Reserved for Future Use	Non-Volatile	0	Reserved.
6	RFU			0	
5	TBPROT_O	Configures Start of Block Protection	OTP	0	1 = BP starts at bottom (Low address). 0 = BP starts at top (High address).
4	RFU	Reserved for Future Use	RFU	0	Reserved.
3	BPNV_O	Configures BP2-0 in Status Register	OTP	0	1 = Volatile. 0 = Non-Volatile.
2	TBPARAM_O	Configures Parameter Sectors location	OTP	0	1 = 4-kB physical sectors at top, (high address). 0 = 4-kB physical sectors at bottom (Low address). RFU in uniform sector configuration.
1	QUAD_NV	Quad Non-Volatile	Non-Volatile	0	Provides the default state for the QUAD bit.
0	FREEZE_D	FREEZE Default	Non-Volatile Read Only	0	Provides the default state for the Freeze bit. Not user programmable.

Top or Bottom Protection (TBPROT_O) CR1NV[5]: This bit defines the operation of the Block Protection bits BP2, BP1, and BP0 in the Status Register. As described in the Status Register section, the BP2-0 bits allow the user to optionally protect a portion of the array, ranging from 1/64, 1/4, 1/2, etc., up to the entire array. When TBPROT_O is set to a 0 the Block Protection is defined to start from the top (maximum address) of the array. When TBPROT_O is set to a 1 the Block Protection is defined to start from the bottom (zero address) of the array. The TBPROT_O bit is OTP and set to a 0 when shipped from Spansion. If TBPROT_O is programmed to 1, writing the bit with a 0 does not change the value or set the Program Error bit (P_ERR in SR1V[6]).

The desired state of TBPROT_O must be selected during the initial configuration of the device during system manufacture; before the first program or erase operation on the main flash array. TBPROT_O must not be programmed after programming or erasing is done in the main flash array.

CR1NV[4]: Reserved for Future Use.

Block Protection Non-Volatile (BPNV_O) CR1NV[3]: The BPNV_O bit defines whether the BP_NV 2-0 bits or the BP 2-0 bits in the Status Register are selected to control the Block Protection feature. The BPNV_O bit is OTP and cleared to a 0 with the BP_NV bits cleared to "000" when shipped from Spansion. When BPNV_O is set to a 0 the BP_NV 2-0 bits in the Status Register are selected to control the block protection and are written by the WRR command. The time required to write the BP_NV bits is t_{WV} . When BPNV is set to a 1 the BP2-0 bits in the Status Register are selected to control the block protection and the BP_NV 2-0 bits will be programmed to binary "111". This will cause the BP 2-0 bits to be set to binary 111 after POR, hardware reset, or command reset. When BPNV is set to a 1, the WRR command writes only the volatile version of the BP bits (SR1V[4:2]). The non-volatile version of the BP bits (SR1NV[4:2]) are no longer affected by the WRR command. This allows the BP bits to be written an unlimited number of times because they are volatile and the time to write the volatile BP bits is the much faster t_{CS} volatile register write time. If BPNV_O is programmed to 1, writing the bit with a 0 does not change the value or set the Program Error bit (P_ERR in SR1V[6]).

TBPARAM_O CR1NV[2]: TBPARAM_O defines the logical location of the parameter block. The parameter block consists of eight 4-kB parameter sectors, which replace a 32-kB portion of the highest or lowest address sector. When TBPARAM_O is set to a 1 the parameter block is in the top of the memory array address space. When TBPARAM_O is set to a 0 the parameter block is at the Bottom of the array. TBPARAM_O is OTP

and set to a 0 when it ships from Spansion. If TBPARM_O is programmed to 1, writing the bit with a 0 does not change the value or set the Program Error bit (P_ERR in SR1V[6]).

The desired state of TBPARM_O must be selected during the initial configuration of the device during system manufacture; before the first program or erase operation on the main flash array. TBPARM_O must not be programmed after programming or erasing is done in the main flash array.

TBPROT_O can be set or cleared independent of the TBPARM_O bit. Therefore, the user can elect to store parameter information from the bottom of the array and protect boot code starting at the top of the array, or vice versa. Or, the user can elect to store and protect the parameter information starting from the top or bottom together.

When the memory array is configured as uniform sectors, the TBPARM_O bit is Reserved for Future Use (RFU) and has no effect because all sectors are uniform size.

Quad Data Width Non-Volatile (QUAD_NV) CR1NV[1]: Provides the default state for the Quad bit in CR1V[1]. The WRR or WRAR command affects this bit. Non-Volatile selection of QPI Mode, by programming CR2NV[6] =1, will also program QUAD_NV =1 to change the non-volatile default to Quad data width mode. While QPI Mode is selected by CR2V[6]=1, the Quad_NV bit cannot be cleared to 0.

Freeze Protection Default (FREEZE) CR1NV[0]: Provides the default state for the FREEZE bit in CR1V[0]. This bit is not user programmable.

8.6.3.2 Configuration Register 1 Volatile (CR1V)

Related Commands: Read Configuration Register (RDCR 35h), Write Registers (WRR 01h), Read Any Register (RDAR 65h), Write Any Register (WRAR 71h). This is the register displayed by the RDCR command.

Table 8.18 Configuration Register 1 Volatile (CR1V)

Bits	Field Name	Function	Type	Default State	Description
7	RFU	Reserved for Future Use	Volatile	CR1NV	Reserved.
6	RFU				
5	TBPROT	Volatile copy of TBPROT_O	Volatile Read Only		Not user writable. See CR1NV[5] TBPROT_O.
4	RFU	Reserved for Future Use	RFU		Reserved.
3	BPNV	Volatile copy of BPNV_O	Volatile Read Only		Not user writable. See CR1NV[3] BPNV_O.
2	TBPARM	Volatile copy of TBPARM_O	Volatile Read Only		Not user writable. See CR1NV[2] TBPARM_O.
1	QUAD	Quad I/O Mode	Volatile		1 = Quad. 0 = Dual or Serial.
0	FREEZE	Lock-Down Block Protection until next power cycle	Volatile		Lock current state of Block Protection control bits, and OTP regions. 1 = Block Protection and OTP locked. 0 = Block Protection and OTP unlocked.

TBPROT, BPNV, and TBPARM CR1V[5,3,2]: These bits are volatile copies of the related non-volatile bits of CR1NV. These bits track any changes to the related non-volatile version of these bits.

Quad Data Width (QUAD) CR1V[1]: When set to 1, this bit switches the data width of the device to 4-bit Quad Mode. That is, WP# becomes IO2 and IO3 / RESET# becomes an active I/O signal when CS# is low or the RESET# input when CS# is high. The WP# input is not monitored for its normal function and is internally set to high (inactive). The commands for Serial, and Dual I/O Read still function normally but, there is no need to drive the WP# input for those commands when switching between commands using different data path widths. Similarly, there is no requirement to drive the IO3 / RESET# during those commands (while CS# is low). The QUAD bit must be set to 1 when using the Quad I/O Read, DDR Quad I/O Read, QPI Mode (CR2V[6] = 1), and Read Quad ID commands. While QPI Mode is selected by CR2V[6]=1, the Quad bit cannot be cleared to 0. The WRR command writes the non-volatile version of the Quad bit (CR1NV[1]), which also causes an update to the volatile version CR1V[1]. The WRR command can not write the volatile version CR1V[1] without first affecting the non-volatile version CR1NV[1]. The WRAR command must be used when it is desired to write the volatile Quad bit CR1V[1] without affecting the non-volatile version CR1NV[1].

Freeze Protection (FREEZE) CR1V[0]: The Freeze bit, when set to 1, locks the current state of the Block Protection control bits and OTP area:

- BPNV_2-0 bits in the non-volatile Status Register 1 (SR1NV[4:2])
- BP 2-0 bits in the volatile Status Register 1 (SR1V[4:2])
- TBPROT_O, TBPARM_O, and BPNV_O bits in the non-volatile Configuration Register (CR1NV[53, 2])
- TBPROT, TBPARM, and BPNV bits in the volatile Configuration Register (CR1V[5, 3, 2]) are indirectly protected in that they are shadows of the related CR1NV OTP bits and are read only
- the entire OTP memory space

Any attempt to change the above listed bits while FREEZE = 1 is prevented:

- The WRR command does not affect the listed bits and no error status is set.
- The WRAR command does not affect the listed bits and no error status is set.
- The OTPP command, with an address within the OTP area, fails and the P-ERR status is set.

As long as the FREEZE bit remains cleared to logic 0 the Block Protection control bits and FREEZE are writable, and the OTP address space is programmable.

Once the FREEZE bit has been written to a logic 1 it can only be cleared to a logic 0 by a power-off to power-on cycle or a hardware reset. Software reset will not affect the state of the FREEZE bit.

The CR1V[0] FREEZE bit is volatile and the default state of FREEZE after power-on comes from FREEZE_D in CR1NV[0]. The FREEZE bit can be set in parallel with updating other values in CR1V by a single WRR or WRAR command.

The FREEZE bit does not prevent the WRR or WRAR commands from changing the SRWD_NV (SR1NV[7]), Quad_NV (CR1NV[1]), or QUAD (CR1V[1]) bits.

8.6.4 Configuration Register 2

Configuration Register 2 controls certain interface functions. The register bits can be read and changed using the Read Any Register and Write Any Register commands. The non-volatile version of the register provides the ability to set the POR, hardware reset, or software reset state of the controls. These configuration bits are OTP and may only have their default state changed to the opposite value one time during system configuration. The volatile version of the register controls the feature behavior during normal operation.

8.6.4.1 Configuration Register 2 Non-Volatile (CR2NV)

Related Commands: Read Any Register (RDAR 65h), Write Any Register (WRAR 71h).

Table 8.19 Configuration Register 2 Non-Volatile (CR2NV)

Bits	Field Name	Function	Type	Default State	Description
7	AL_NV	Address Length	OTP	0	1 = 4-byte address. 0 = 3-byte address.
6	QA_NV	QPI		0	1 = Enabled - QPI (4-4-4) protocol in use. 0 = Disabled - Legacy SPI protocols in use, instruction is always serial on SI.
5	IO3R_NV	IO3 Reset		0	1 = Enabled - IO3 is used as RESET# input when CS# is high or Quad Mode is disabled CR1V[1]=1. 0 = Disabled - IO3 has no alternate function, hardware reset is disabled.
4	RFU	Reserved		0	Reserved For Future Use.
3	RL_NV	Read Latency		1	0 to 15 latency (dummy) cycles following read address or continuous mode bits. Note that bit 3 has a default value of 1 and may be programmed one time to 0 but cannot be returned to 1.
2				0	
1				0	
0				0	

Address Length Non-Volatile CR2NV[7]: This bit controls the POR, hardware reset, or software reset state of the expected address length for all commands that require address and are not fixed 3-byte only or 4-byte (32-bit) only address. Most commands that need an address are legacy SPI commands that traditionally used 3-byte (24-bit) address. For device densities greater than 128 Mbit a 4-byte address is required to access the entire memory array. The address length configuration bit is used to change most 3-byte address commands to expect 4-byte address. See [Table 10.1, S25FS-S Family Command Set \(sorted by function\) on page 88](#) for command address length. The use of 4-byte address length also applies to the 128-Mbit member of the S25FS-S family so that the same 4-byte address hardware and software interface may be used for all family members to simplify migration between densities. The 128-Mbit member of the S25FS-S family simply ignores the content of the fourth, high order, address byte. This non-volatile address length configuration bit enables the device to start immediately (boot) in 4-byte address mode rather than the legacy 3-byte address mode.

QPI Non-Volatile CR2NV[6]: This bit controls the POR, hardware reset, or software reset state of the expected instruction width for all commands. Legacy SPI commands always send the instruction one bit wide (serial I/O) on the SI (IO0) signal. The S25FS-S family also supports the QPI Mode in which all transfers between the host system and memory are 4-bits wide on IO0 to IO3, including all instructions. This non-volatile QPI configuration bit enables the device to start immediately (boot) in QPI Mode rather than the legacy serial instruction mode. When this bit is programmed to QPI Mode, the QUAD_NV bit is also programmed to Quad Mode (CR1NV[1]=1). The recommended procedure for moving to QPI Mode is to first use the WRAR command to set CR2V[6]=1, QPI Mode. The volatile register write for QPI Mode has a short and well defined time (t_{CS}) to switch the device interface into QPI Mode. Following commands can then be immediately sent in QPI protocol. The WRAR command can be used to program CR2NV[6]=1, followed by polling of SR1V[0] to know when the programming operation is completed. Similarly, to exit QPI Mode, the WRAR command is used to clear CR2V[6]=0. CR2NV[6] cannot be erased to 0 because it is OTP.

IO3 Reset Non-Volatile CR2NV[5]: This bit controls the POR, hardware reset, or software reset state of the IO3 signal behavior. Most legacy SPI devices do not have a hardware reset input signal due to the limited signal count and connections available in traditional SPI device packages. The S25FS-S family provides the option to use the IO3 signal as a hardware reset input when the IO3 signal is not in use for transferring information between the host system and the memory. This non-volatile IO3 Reset configuration bit enables the device to start immediately (boot) with IO3 enabled for use as a RESET# signal.

Read Latency Non-Volatile CR2NV[3:0]: This bit controls the POR, hardware reset, or software reset state of the Read Latency (dummy cycle) delay in all variable latency read commands. The following read commands have a variable latency period between the end of address or mode and the beginning of read data returning to the host:

- Fast Read
- Dual I/O Read
- Quad I/O Read
- DDR Quad I/O Read
- OTPR
- RDAR

This Non-Volatile Read Latency configuration bit sets the number of read latency (dummy cycles) in use so the device can start immediately (boot) with an appropriate read latency for the host system.

Table 8.20 Latency Code (Cycles) Versus Frequency

Latency Cycles	Read Command Maximum Frequency (MHz)			
	Fast Read (1-1-1) OTPR (1-1-1) RDAR (1-1-1) RDAR (4-4-4)	Dual I/O (1-2-2)	Quad I/O (1-4-4) QPI (4-4-4)	DDR Quad I/O (1-4-4) DDR QPI (4-4-4) (Note 4)
	Mode Cycles = 0	Mode Cycles = 4	Mode Cycles = 2	Mode Cycles = 1
0	50	80	40	N/A
1	66	92	53	22
2	80	104	66	34
3	92	116	80	45
4	104	129	92	57
5	116	133	104	68
6	129	133	116	80
7	133	133	129	80
8	133	133	133	80
9	133	133	133	80
10	133	133	133	80
11	133	133	133	80
12	133	133	133	80
13	133	133	133	80
14	133	133	133	80
15	133	133	133	80

Notes:

1. SCK frequency > 133 MHz SDR, or 80 MHz DDR is not supported by this family of devices.
2. The Dual I/O, Quad I/O, QPI, DDR Quad I/O, and DDR QPI, command protocols include Continuous Read mode bits following the address. The clock cycles for these bits are not counted as part of the latency cycles shown in the table. Example: the legacy Quad I/O command has 2 Continuous Read mode cycles following the address. Therefore, the legacy Quad I/O command without additional read latency is supported only up to the frequency shown in the table for a read latency of 0 cycles. By increasing the variable read latency the frequency of the Quad I/O command can be increased to allow operation up to the maximum supported 133 MHz frequency.
3. Other read commands have fixed latency, e.g. Read always has zero read latency. RSFDP always has eight cycles of latency.
4. DDR QPI is only supported for Latency Cycles 1 through 5 and for clock frequency of up to 68 MHz.

8.6.4.2 Configuration Register 2 Volatile (CR2V)

Related Commands: Read Any Register (RDAR 65h), Write Any Register (WRAR 71h), 4BAM.

Table 8.21 Configuration Register 2 Volatile (CR2V)

Bits	Field Name	Function	Type	Default State	Description
7	AL	Address Length	Volatile	CR2NV	1 = 4 byte address. 0 = 3 byte address.
6	QA	QPI			1 = Enabled - QPI (4-4-4) protocol in use. 0 = Disabled - Legacy SPI protocols in use, instruction is always serial on SI.
5	IO3R_S	IO3 Reset			1 = Enabled - IO3 is used as RESET# input when CS# is high or Quad Mode is disabled CR1V[1]=1. 0 = Disabled - IO3 has no alternate function, hardware reset is disabled.
4	RFU	Reserved			Reserved for Future Use.
3	RL	Read Latency			0 to 15 latency (dummy) cycles following read address or continuous mode bits.
2					
1					
0					

Address Length CR2V[7]: This bit controls the expected address length for all commands that require address and are not fixed 3-byte only or 4-byte (32-bit) only address. See [Table 10.1, S25FS-S Family Command Set \(sorted by function\) on page 88](#) for command address length. This volatile Address Length configuration bit enables the address length to be changed during normal operation. The 4-byte address mode (4BAM) command directly sets this bit into 4-byte address mode.

QPI CR2V[6]: This bit controls the expected instruction width for all commands. This volatile QPI configuration bit enables the device to enter and exit QPI Mode during normal operation. When this bit is set to QPI Mode, the Quad bit is also set to Quad Mode (CR1V[1]=1). When this bit is cleared to legacy SPI mode, the Quad bit is not affected.

IO3 Reset CR2V[5]: This bit controls the IO3 / RESET# signal behavior. This volatile IO3 Reset configuration bit enables the use of IO3 as a RESET# input during normal operation.

Read Latency CR2V[3:0]: This bit controls the read latency (dummy cycle) delay in variable latency read commands. These volatile configuration bits enable the user to adjust the read latency during normal operation to optimize the latency for different commands or, at different operating frequencies, as needed.

8.6.5 Configuration Register 3

Configuration Register 3 controls certain command behaviors. The register bits can be read and changed using the Read Any Register and Write Any Register commands. The non-volatile register provides the POR, hardware reset, or software reset state of the controls. These configuration bits are OTP and may be programmed to their opposite state one time during system configuration if needed. The volatile version of Configuration Register 3 allows the configuration to be changed during system operation or testing.

8.6.5.1 Configuration Register 3 Non-Volatile (CR3NV)

Related Commands: Read Any Register (RDAR 65h), Write Any Register (WRAR 71h).

Table 8.22 Configuration Register 3 Non-Volatile (CR3NV)

Bits	Field Name	Function	Type	Default State	Description
7	RFU	Reserved	OTP	0	Reserved for Future Use.
6	RFU	Reserved		0	Reserved for Future Use.
5	BC_NV	Blank Check		0	1 = Blank Check during erase enabled. 0 = Blank Check disabled.
4	02h_NV	Page Buffer Wrap		0	1 = Wrap at 512 bytes. 0 = Wrap at 256 bytes.
3	20h_NV	4-kB Erase		0	1 = 4-kB Erase disabled (Uniform Sector Architecture). 0 = 4-kB Erase enabled (Hybrid Sector Architecture).
2	30h_NV	Clear Status / Resume Select		0	1 = 30h is Erase or Program Resume command. 0 = 30h is clear status command.
1	D8h_NV	Block Erase Size		0	1 = 256-kB Erase. 0 = 64-kB Erase.
0	F0h_NV	Legacy Software Reset Enable		0	1 = F0h software reset is enabled. 0 = F0h software reset is disabled (ignored).

Blank Check Non-Volatile CR3NV[5]: This bit controls the POR, hardware reset, or software reset state of the blank check during erase feature.

02h Non-Volatile CR3NV[4]: This bit controls the POR, hardware reset, or software reset state of the Page Programming Buffer address wrap point.

20h Non-Volatile CR3NV[3]: This bit controls the POR, hardware reset, or software reset state of the availability of 4-kB parameter sectors in the main flash array address map.

30h Non-Volatile CR3NV[2]: This bit controls the POR, hardware reset, or software reset state of the 30h instruction code is used.

D8h Non-Volatile CR3NV[1]: This bit controls the POR, hardware reset, or software reset state of the configuration for the size of the area erased by the D8h or DCh instructions.

F0h Non-Volatile CR3NV[0]: This bit controls the POR, hardware reset, or software reset state of the availability of the Spansion legacy FL-S family software reset instruction.

8.6.5.2 Configuration Register 3 Volatile (CR3V)

Related Commands: Read Any Register (RDAR 65h), Write Any Register (WRAR 71h).

Table 8.23 Configuration Register 3 Volatile (CR3V)

Bits	Field Name	Function	Type	Default State	Description
7	RFU	Reserved	Volatile	CR3NV	Reserved for Future Use.
6	RFU	Reserved			Reserved for Future Use.
5	BC_V	Blank Check			1 = Blank Check during erase enabled. 0 = Blank Check disabled.
4	02h_V	Page Buffer Wrap			1 = Wrap at 512 bytes. 0 = Wrap at 256 bytes.
3	20h_V	4-kB Erase	Volatile, Read Only		1 = 4-kB Erase disabled (Uniform Sector Architecture). 0 = 4-kB Erase enabled (Hybrid Sector Architecture).
2	30h_V	Clear Status / Resume Select	Volatile		1 = 30h is Erase or Program Resume command. 0 = 30h is Clear Status command.
1	D8h_V	Block Erase Size			1 = 256-kB Erase. 0 = 64-kB Erase.
0	F0h_V	Legacy Software Reset Enable			1 = F0h software reset is enabled. 0 = F0h software reset is disabled (ignored).

Blank Check Volatile CR3V[5]: This bit controls the blank check during erase feature. When this feature is enabled an erase command first evaluates the Erase Status of the sector. If the sector is found to have not completed its last erase successfully, the sector is unconditionally erased. If the last erase was successful, the sector is read to determine if the sector is still erased (blank). The erase operation is started immediately after finding any programmed zero. If the sector is already blank (no programmed zero bit found) the remainder of the erase operation is skipped. This can dramatically reduce erase time when sectors being erased do not need the erase operation. When enabled the blank check feature is used within the parameter erase, Sector Erase, and Bulk Erase commands. When blank check is disabled an Erase command unconditionally starts the Erase operation.

02h Volatile CR3V[4]: This bit controls the Page Programming Buffer address wrap point. Legacy SPI devices generally have used a 256-byte Page Programming Buffer and defined that if data is loaded into the buffer beyond the 255-byte location, the address at which additional bytes are loaded would be wrapped to address zero of the buffer. The S25FS-S family provides a 512-byte Page Programming Buffer that can increase programming performance. For legacy software compatibility, this configuration bit provides the option to continue the wrapping behavior at the 256-byte boundary or to enable full use of the available 512-byte buffer by not wrapping the load address at the 256-byte boundary.

20h Volatile CR3V[3]: This bit controls the availability of 4-kB parameter sectors in the main flash array address map. The parameter sectors can overlay the highest or lowest 32-kB address range of the device or they can be removed from the address map so that all sectors are uniform size. This bit shall not be written to a value different than the value of CR3NV[3]. The value of CR3V[3] may only be changed by writing CR3NV[3].

30h Volatile CR3V[2]: This bit controls how the 30h instruction code is used. The instruction may be used as a Clear Status command or as an alternate Program / Erase Resume command. This allows software compatibility with either Spansion legacy SPI devices or alternate vendor devices.

D8h Volatile CR3V[1]: This bit controls the area erased by the D8h or DCh instructions. The instruction can be used to erase 64-kB physical sectors or 256-kB size and aligned blocks. The option to erase 256-kB blocks in the lower density family members allows for consistent software behavior across all densities that can ease migration between different densities.

F0h Volatile CR3V[0]: This bit controls the availability of the Spansion legacy FL-S family software reset instruction. The S25FS-S family supports the industry common 66h + 99h instruction sequence for software reset. This configuration bit allows the option to continue use of the legacy F0h single command for software reset.

8.6.6 Configuration Register 4

Configuration Register 4 controls the main Flash Array Read commands burst wrap behavior. The burst wrap configuration does not affect commands reading from areas other than the main flash array e.g. read commands for registers or OTP array. The non-volatile version of the register provides the ability to set the start up (boot) state of the controls as the contents are copied to the volatile version of the register during the POR, hardware reset, or software reset. The volatile version of the register controls the feature behavior during normal operation. The register bits can be read and changed using the Read Any Register and Write Any Register commands. The volatile version of the register can also be written by the Set Burst Length (C0h) command.

8.6.6.1 Configuration Register 4 Non-Volatile (CR4NV)

Related Commands: Read Any Register (RDAR 65h), Write Any Register (WRAR 71h).

Table 8.24 Configuration Register 4 Non-Volatile (CR4NV)

Bits	Field Name	Function	Type	Default State	Description
7	OI_O	Output Impedance	OTP	0	See Table 8.25, Output Impedance Control on page 71 .
6				0	
5				0	
4	WE_O	Wrap Enable		1	0 = Wrap Enabled. 1 = Wrap Disabled.
3	RFU	Reserved		0	Reserved for Future Use.
2	RFU	Reserved		0	Reserved for Future Use.
1	WL_O	Wrap Length		0	00 = 8-byte wrap. 01 = 16-byte wrap. 10 = 32-byte wrap. 11 = 64-byte wrap.
0				0	

Output Impedance Non-Volatile CR4NV[7:5]: These bits control the POR, hardware reset, or software reset state of the IO signal output impedance (drive strength). Multiple drive strength are available to help match the output impedance with the system printed circuit board environment to minimize overshoot and ringing. These non-volatile output impedance configuration bits enable the device to start immediately (boot) with the appropriate drive strength.

Table 8.25 Output Impedance Control

CR4NV[7:5] Impedance Selection	Typical Impedance to V _{SS} (Ohms)	Typical Impedance to V _{DD} (Ohms)	Notes
000	47	45	Factory Default
001	124	105	
010	71	64	
011	47	45	
100	34	35	
101	26	28	
110	22	24	
111	18	21	

Wrap Enable Non-Volatile CR4NV[4]: This bit controls the POR, hardware reset, or software reset state of the Wrap Enable. The commands affected by Wrap Enable are: Quad I/O Read, and DDR Quad I/O Read. This configuration bit enables the device to start immediately (boot) in wrapped burst read mode rather than the legacy sequential read mode.

Wrap Length Non-Volatile CR4NV[1:0]: These bits controls the POR, hardware reset, or software reset state of the wrapped read length and alignment. These non-volatile configuration bits enable the device to start immediately (boot) in wrapped burst read mode rather than the legacy sequential read mode.

8.6.6.2 Configuration Register 4 Volatile (CR4V)

Related Commands: Read Any Register (RDAR 65h), Write Any Register (WRAR 71h), Set Burst Length (SBL C0h).

Table 8.26 Configuration Register 4 Volatile (CR4V)

Bits	Field Name	Function	Type	Default State	Description
7	OI	Output Impedance	Volatile	CR4NV	See Table 8.25, Output Impedance Control on page 71 .
6					
5					
4	WE	Wrap Enable			0 = Wrap Enabled. 1 = Wrap Disabled.
3	RFU	Reserved			Reserved for Future Use.
2	RFU	Reserved			Reserved for Future Use.
1	WL	Wrap Length			00 = 8-byte wrap. 01 = 16-byte wrap. 10 = 32-byte wrap. 11 = 64-byte wrap.
0					

Output Impedance CR2V[7:5]: These bits control the IO signal output impedance (drive strength). This volatile output impedance configuration bit enables the user to adjust the drive strength during normal operation.

Wrap Enable CR4V[4]: This bit controls the burst wrap feature. This volatile configuration bit enables the device to enter and exit burst wrapped read mode during normal operation.

Wrap Length CR4V[1:0]: These bits controls the wrapped read length and alignment during normal operation. These volatile configuration bits enable the user to adjust the burst wrapped read length during normal operation.

8.6.7 ASP Register (ASPR)

Related Commands: ASP Read (ASPRD 2Bh) and ASP Program (ASPP 2Fh), Read Any Register (RDAR 65h), Write Any Register (WRAR 71h).

The ASP register is a 16-bit OTP memory location used to permanently configure the behavior of Advanced Sector Protection (ASP) features. ASPR does not have user programmable volatile bits, all defined bits are OTP.

The default state of the ASPR bits are programmed by Spansion.

Table 8.27 ASP Register (ASPR)

Bits	Field Name	Function	Type	Default State	Description
15 to 9	RFU	Reserved	OTP	1	Reserved for Future Use.
8	RFU	Reserved	OTP	1	Reserved for Future Use.
7	RFU	Reserved	OTP	1	Reserved for Future Use.
6	RFU	Reserved	OTP	1	Reserved for Future Use.
5	RFU	Reserved	OTP	1	Reserved for Future Use.
4	RFU	Reserved	RFU	1	Reserved for Future Use.
3	RFU	Reserved	RFU	1	Reserved for Future Use.
2	PWDMLB	Password Protection Mode Lock Bit	OTP	1	0 = Password Protection mode permanently enabled. 1 = Password Protection mode not permanently enabled.
1	PSTMLB	Persistent Protection Mode Lock Bit	OTP	1	0 = Persistent Protection mode permanently enabled. 1 = Persistent Protection mode not permanently enabled.
0	RFU	Reserved	RFU	1	Reserved for Future Use.

Password Protection Mode Lock Bit (PWDMLB) ASPR[2]: When programmed to 0, the Password Protection mode is permanently selected.

Persistent Protection Mode Lock Bit (PSTMLB) ASPR[1]: When programmed to 0, the Persistent Protection mode is permanently selected.

PWDMLB (ASPR[2]) and PSTMLB (ASPR[1]) are mutually exclusive, only one may be programmed to 0.

ASPR bits may only be programmed while ASPR[2:1] = 11b. Attempting to program ASPR bits when ASPR[2:1] is not = 11b will result in a programming error with P_ERR (SR1V[6]) set to 1. After the ASP protection mode is selected by programming ASPR[2:1] = 10b or 01b, the state of all ASPR bits are locked and permanently protected from further programming. Attempting to program ASPR[2:1] = 00b will result in a programming error with P_ERR (SR1V[6]) set to 1.

Similarly, OTP configuration bits listed in the ASP Register description ([ASP Register on page 81](#)), may only be programmed while ASPR[2:1] = 11b. The OTP configuration must be selected before selecting the ASP protection mode. The OTP configuration bits are permanently protected from further change when the ASP protection mode is selected. Attempting to program these OTP configuration bits when ASPR[2:1] is not = 11b will result in a programming error with P_ERR (SR1V[6]) set to 1.

The ASP protection mode should be selected during system configuration to ensure that a malicious program does not select an undesired protection mode at a later time. By locking all the protection configuration via the ASP mode selection, later alteration of the protection methods by malicious programs is prevented.

8.6.8 Password Register (PASS)

Related Commands: Password Read (PASSRD E7h) and Password Program (PASSP E8h), Read Any Register (RDAR 65h), Write Any Register (WRAR 71h). The PASS register is a 64-bit OTP memory location used to permanently define a password for the Advanced Sector Protection (ASP) feature. PASS does not have user programmable volatile bits, all defined bits are OTP. A volatile copy of PASS is used to satisfy read latency requirements but the volatile register is not user writable or further described.

Table 8.28 Password Register (PASS)

Bits	Field Name	Function	Type	Default State	Description
63 to 0	PWD	Hidden Password	OTP	FFFFFFFF-FFFFFFFFh	Non-Volatile OTP storage of 64-bit password. The password is no longer readable after the password protection mode is selected by programming ASP register bit 2 to 0.

8.6.9 PPB Lock Register (PPBL)

Related Commands: PPB Lock Read (PLBRD A7h, PLBWR A6h), Read Any Register (RDAR 65h).

PPBL does not have separate user programmable non-volatile bits, all defined bits are volatile read only status. The default state of the RFU bits is set by hardware. The default state of the PPBLOCK bit is defined by the ASP protection mode bits in ASPR[2:1]. There is no non-volatile version of the PPBL register.

The PPBLOCK bit is used to protect the PPB bits. When PPBL[0] = 0, the PPB bits can not be programmed.

Table 8.29 PPB Lock Register (PPBL)

Bits	Field Name	Function	Type	Default State	Description
7 to 1	RFU	Reserved	Volatile	00h	Reserved for Future Use
0	PPBLOCK	Protect PPB Array	Volatile Read Only	ASPR[2:1] = 1xb = Persistent Protection Mode = 1 ASPR[2:1] = 01b = Password Protection Mode = 0	0 = PPB array protected. 1 = PPB array may be programmed or erased.

8.6.10 PPB Access Register (PPBAR)

Related Commands: PPB Read (PPBRD FCh or 4PPBRD E2h), PPB Program (PPBP FDh or 4PPBP E3h), PPB Erase (PPBE E4h).

PPBAR does not have user writable volatile bits, all PPB array bits are non-volatile. The default state of the PPB array is erased to FFh by Spansion. There is no volatile version of the PPBAR register.

Table 8.30 PPB Access Register (PPBAR)

Bits	Field Name	Function	Type	Default State	Description
7 to 0	PPB	Read or Program per sector PPB	Non-Volatile	FFh	00h = PPB for the sector addressed by the PPBRD or PPBP command is programmed to 0, protecting that sector from program or erase operations. FFh = PPB for the sector addressed by the PPBRD command is 1, not protecting that sector from program or erase operations.

8.6.11 DYB Access Register (DYBAR)

Related Commands: DYB Read (DYBRD FAh or 4DYBRD E0h) and DYB Write (DYBWR FBh or 4DYBWR E1h).

DYBAR does not have user programmable non-volatile bits, all bits are a representation of the volatile bits in the DYB array. The default state of the DYB array bits is set by hardware. There is no non-volatile version of the DYBAR register.

Table 8.31 DYB Access Register (DYBAR)

Bits	Field Name	Function	Type	Default State	Description
7 to 0	DYB	Read or Write per sector DYB	Volatile	FFh	00h = DYB for the sector addressed by the DYBRD or DYBWR command is cleared to 0, protecting that sector from program or erase operations. FFh = DYB for the sector addressed by the DYBRD or DYBWR command is set to 1, not protecting that sector from program or erase operations.

8.6.12 SPI DDR Data Learning Registers

Related Commands: Program NVDLR (PNVDLR 43h), Write VDLR (WVDLR 4Ah), Data Learning Pattern Read (DLPRD 41h), Read Any Register (RDAR 65h), Write Any Register (WRAR 71h).

The Data Learning Pattern (DLP) resides in an 8-bit Non-Volatile Data Learning Register (NVDLR) as well as an 8-bit Volatile Data Learning Register (VDLR). When shipped from Spansion, the NVDLR value is 00h. Once programmed, the NVDLR cannot be reprogrammed or erased; a copy of the data pattern in the NVDLR will also be written to the VDLR. The VDLR can be written to at any time, but on reset or power cycles the data pattern will revert back to what is in the NVDLR. During the learning phase described in the SPI DDR modes, the DLP will come from the VDLR. Each IO will output the same DLP value for every clock edge. For example, if the DLP is 34h (or binary 00110100) then during the first clock edge all IO's will output 0; subsequently, the 2nd clock edge all I/O's will output 0, the 3rd will output 1, etc.

When the VDLR value is 00h, no preamble data pattern is presented during the dummy phase in the DDR commands.

Table 8.32 Non-Volatile Data Learning Register (NVDLR)

Bits	Field Name	Function	Type	Default State	Description
7 to 0	NVDLP	Non-Volatile Data Learning Pattern	OTP	00h	OTP value that may be transferred to the host during DDR read command latency (dummy) cycles to provide a training pattern to help the host more accurately center the data capture point in the received data bits.

Table 8.33 Volatile Data Learning Register (VDLR)

Bits	Field Name	Function	Type	Default State	Description
7 to 0	VDLP	Volatile Data Learning Pattern	Volatile	Takes the value of NVDLR during POR or Reset	Volatile copy of the NVDLP used to enable and deliver the Data Learning Pattern (DLP) to the outputs. The VDLP may be changed by the host during system operation.

9. Data Protection

9.1 Secure Silicon Region (OTP)

The device has a 1024 byte One-Time Program (OTP) address space that is separate from the main flash array. The OTP area is divided into 32, individually lockable, 32-byte aligned and length regions.

The OTP memory space is intended for increased system security. OTP values can “mate” a flash component with the system CPU/ASIC to prevent device substitution. See [OTP Address Space on page 58](#), [OTP Program \(OTPP 42h\) on page 123](#), and [OTP Read \(OTPR 4Bh\) on page 123](#).

9.1.1 Reading OTP Memory Space

The OTP Read command uses the same protocol as Fast Read. OTP Read operations outside the valid 1-kB OTP address range will yield indeterminate data.

9.1.2 Programming OTP Memory Space

The protocol of the OTP programming command is the same as Page Program. The OTP Program command can be issued multiple times to any given OTP address, but this address space can never be erased.

The valid address range for OTP Program is depicted in [Figure 8.1, OTP Address Space on page 58](#). OTP Program operations outside the valid OTP address range will be ignored, without P_ERR in SR1V set to 1. OTP Program operations within the valid OTP address range, while FREEZE = 1, will fail with P_ERR in SR1V set to 1. The OTP address space is not protected by the selection of an ASP Protection mode. The Freeze bit (CR1V[0]) may be used to protect the OTP Address Space.

9.1.3 Spansion Programmed Random Number

Spansion standard practice is to program the low order 16 bytes of the OTP memory space (locations 0x0 to 0xF) with a 128-bit random number using the Linear Congruential Random Number Method. The seed value for the algorithm is a random number concatenated with the day and time of tester insertion.

9.1.4 Lock Bytes

The LSB of each Lock byte protects the lowest address region related to the byte, the MSB protects the highest address region related to the byte. The next higher address byte similarly protects the next higher 8 regions. The LSB bit of the lowest address Lock Byte protects the higher address 16 bytes of the lowest address region. In other words, the LSB of location 0x10 protects all the Lock Bytes and RFU bytes in the lowest address region from further programming. See [OTP Address Space on page 58](#).

9.2 Write Enable Command

The Write Enable (WREN) command must be written prior to any command that modifies non-volatile data. The WREN command sets the Write Enable Latch (WEL) bit. The WEL bit is cleared to 0 (disables writes) during power-up, hardware reset, or after the device completes the following commands:

- Reset
- Page Program (PP or 4PP)
- Parameter 4-kB Erase (P4E or 4P4E)
- Sector Erase (SE or 4SE)
- Bulk Erase (BE)
- Write Disable (WRDI)
- Write Registers (WRR)
- Write Any Register (WRAR)
- OTP Byte Programming (OTPP)
- Advanced Sector Protection Register Program (ASPP)
- Persistent Protection Bit Program (PPBP)
- Persistent Protection Bit Erase (PPBE)
- Password Program (PASSP)
- Program Non-Volatile Data Learning Register (PNVDLR)

9.3 Block Protection

The Block Protect bits (Status Register bits BP2, BP1, BP0) in combination with the Configuration Register TBPROT_O bit can be used to protect an address range of the main flash array from program and erase operations. The size of the range is determined by the value of the BP bits and the upper or lower starting point of the range is selected by the TBPROT_O bit of the Configuration Register (CR1NV[5]).

Table 9.1 Upper Array Start of Protection (TBPROT_O = 0)

Status Register Content			Protected Fraction of Memory Array	Protected Memory (kbytes)	
BP2	BP1	BP0		FS128S 128 Mb	FS256S 256 Mb
0	0	0	None	0	0
0	0	1	Upper 64th	256	512
0	1	0	Upper 32nd	512	1024
0	1	1	Upper 16th	1024	2048
1	0	0	Upper 8th	2048	4096
1	0	1	Upper 4th	4096	8192
1	1	0	Upper Half	8192	16384
1	1	1	All Sectors	16384	32768

Table 9.2 Lower Array Start of Protection (TBPROT_O = 1)

Status Register Content			Protected Fraction of Memory Array	Protected Memory (kbytes)	
BP2	BP1	BP0		FS128S 128 Mb	FS256S 256 Mb
0	0	0	None	0	0
0	0	1	Lower 64th	256	512
0	1	0	Lower 32nd	512	1024
0	1	1	Lower 16th	1024	2048
1	0	0	Lower 8th	2048	4096
1	0	1	Lower 4th	4096	8192
1	1	0	Lower Half	8192	16384
1	1	1	All Sectors	16384	32768

When Block Protection is enabled (i.e., any BP2-0 are set to 1), Advanced Sector Protection (ASP) can still be used to protect sectors not protected by the Block Protection scheme. In the case that both ASP and Block Protection are used on the same sector the logical OR of ASP and Block Protection related to the sector is used.

9.3.1 Freeze Bit

Bit 0 of Configuration Register 1 (CR1V[0]) is the FREEZE bit. The Freeze bit, when set to 1, locks the current state of the Block Protection control bits and OTP area until the next power off-on cycle. Additional details in [Configuration Register 1 Volatile \(CR1V\) on page 64](#).

9.3.2 Write Protect Signal

The Write Protect (WP#) input in combination with the Status Register Write Disable (SRWD) bit (SR1NV[7]) provide hardware input signal controlled protection. When WP# is Low and SRWD is set to 1 Status Register 1 (SR1NV and SR1V) and Configuration Register 1 (CR1NV and CR1V) are protected from alteration. This prevents disabling or changing the protection defined by the Block Protect bits. See [Status Register 1 on page 60](#).

9.4 Advanced Sector Protection

Advanced Sector Protection (ASP) is the name used for a set of independent hardware and software methods used to disable or enable programming or erase operations, individually, in any or all sectors.

Every main flash array sector has a non-volatile Persistent Protection Bit (PPB) and a volatile Dynamic Protection Bit (DYB) associated with it. When either bit is 0, the sector is protected from program and erase operations. The PPB bits are protected from program and erase when the volatile PPB Lock bit is 0. There are two methods for managing the state of the PPB Lock bit: Password Protection and Persistent Protection. An overview of these methods is shown in [Figure 9.2, Advanced Sector Protection Overview on page 80](#).

Block Protection and ASP protection settings for each sector are logically ORed to define the protection for each sector i.e. if either mechanism is protecting a sector the sector cannot be programmed or erased. Refer to [Block Protection on page 77](#) for full details of the BP2-0 bits.

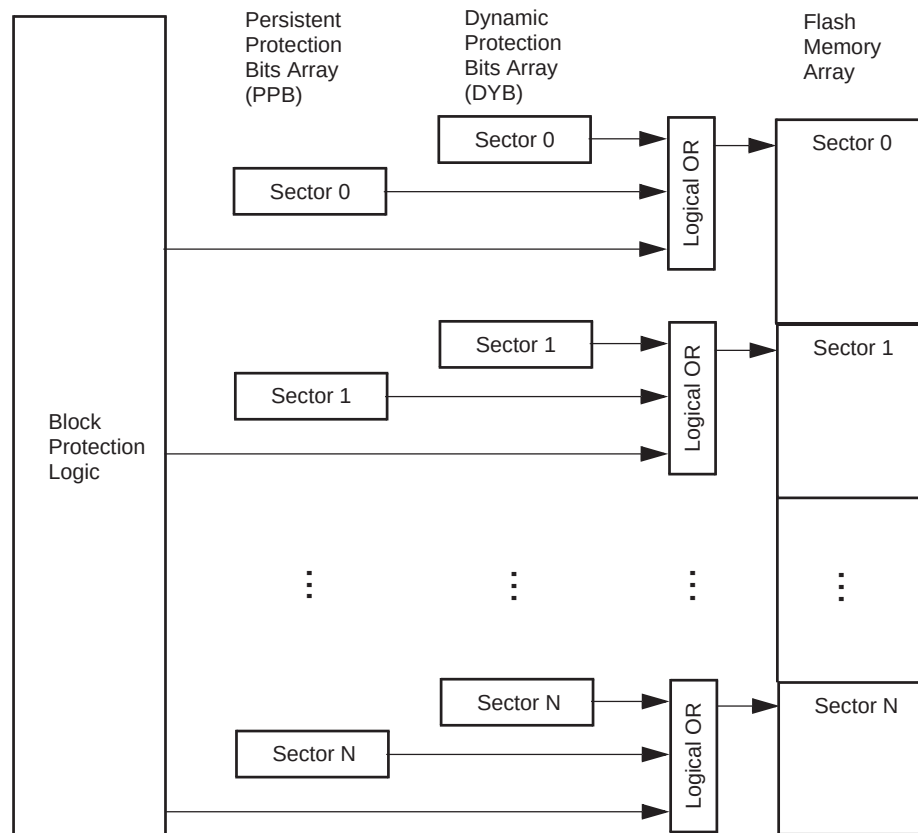
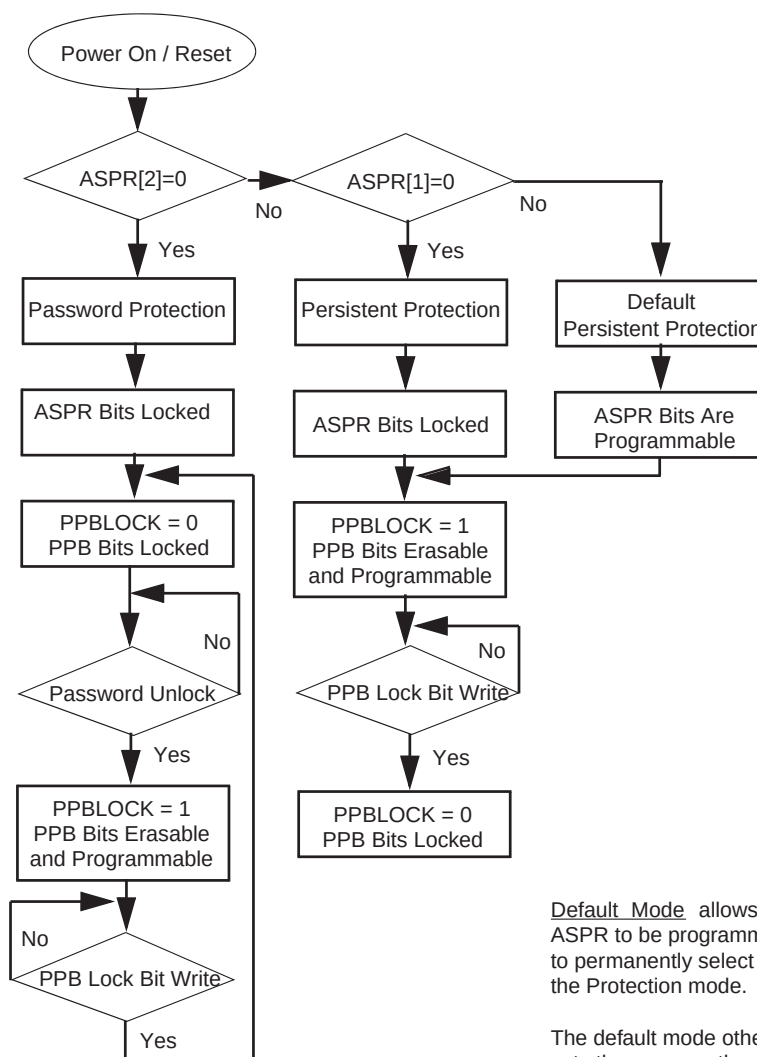
Figure 9.1 Sector Protection Control

Figure 9.2 Advanced Sector Protection Overview



Password Protection Mode protects the PPB after power up. A password unlock command will enable changes to PPB. A PPB Lock Bit write command turns protection back on.

Persistent Protection Mode does not protect the PPB after power up. The bits may be changed. A PPB Lock Bit write command protects the PPB bits until the next power-off or reset.

Default Mode allows ASPR to be programmed to permanently select the Protection mode.

The default mode otherwise acts the same as the Persistent Protection Mode.

After one of the protection modes is selected, ASPR is no longer programmable, making the selected protection mode permanent.

The Persistent Protection method sets the PPB Lock bit to 1 during POR, or hardware reset so that the PPB bits are unprotected by a device reset. There is a command to clear the PPB Lock bit to 0 to protect the PPB. There is no command in the Persistent Protection method to set the PPB Lock bit to 1, therefore the PPB Lock bit will remain at 0 until the next power-off or hardware reset. The Persistent Protection method allows boot code the option of changing sector protection by programming or erasing the PPB, then protecting the PPB from further change for the remainder of normal system operation by clearing the PPB Lock bit to 0. This is sometimes called Boot-code controlled sector protection.

The Password method clears the PPB Lock bit to 0 during POR, or hardware reset to protect the PPB. A 64-bit password may be permanently programmed and hidden for the password method. A command can be used to provide a password for comparison with the hidden password. If the password matches, the PPB Lock bit is set to 1 to unprotect the PPB. A command can be used to clear the PPB Lock bit to 0. This method requires use of a password to control PPB protection.

The selection of the PPB Lock bit management method is made by programming OTP bits in the ASP Register so as to permanently select the method used.

9.4.1 ASP Register

The ASP register is used to permanently configure the behavior of Advanced Sector Protection (ASP) features. See [Table 8.27, ASP Register \(ASPR\) on page 73](#).

As shipped from the factory, all devices default ASP to the Persistent Protection mode, with all sectors unprotected, when power is applied. The device programmer or host system must then choose which sector protection method to use. Programming either of the, one-time programmable, Protection Mode Lock bits, locks the part permanently in the selected mode:

- ASPR[2:1] = "11" = No ASP mode selected, Persistent Protection mode is the default.
- ASPR[2:1] = "10" = Persistent Protection mode permanently selected.
- ASPR[2:1] = "01" = Password Protection mode permanently selected.
- ASPR[2:1] = "00" is an Illegal condition, attempting to program more than one bit to zero results in a programming failure.

ASP register programming rules:

- If the password mode is chosen, the password must be programmed prior to setting the Protection Mode Lock bits.
- Once the Protection mode is selected, the following OTP Configuration Register bits are permanently protected from programming and no further changes to the OTP register bits is allowed:
 - CR1NV[5:2]
 - CR2NV
 - CR3NV
 - CR4NV
 - ASPR
 - PASS
 - NVDLR
- If an attempt to change any of the registers above, after the ASP mode is selected, the operation will fail and P_ERR (SR1V[6]) will be set to 1.

The programming time of the ASP register is the same as the typical page programming time. The system can determine the status of the ASP register programming operation by reading the WIP bit in the Status Register. See [Status Register 1 on page 60](#) for information on WIP.

See [Sector Protection States Summary on page 83](#).

9.4.2 Persistent Protection Bits

The Persistent Protection Bits (PPB) are located in a separate non-volatile flash array. One of the PPB bits is related to each sector. When a PPB is 0, its related sector is protected from program and erase operations. The PPB are programmed individually but must be erased as a group, similar to the way individual words may be programmed in the main array but an entire sector must be erased at the same time. The PPB have the same program and erase endurance as the main flash memory array. Preprogramming and verification prior to erasure are handled by the device.

Programming a PPB bit requires the typical page programming time. Erasing all the PPBs requires typical Sector Erase time. During PPB bit programming and PPB bit erasing, status is available by reading the Status Register. Reading of a PPB bit requires the initial access time of the device.

Notes:

1. Each PPB is individually programmed to 0 and all are erased to 1 in parallel.
2. If the PPB Lock bit is 0, the PPB Program or PPB Erase command does not execute and fails without programming or erasing the PPB.
3. The state of the PPB for a given sector can be verified by using the PPB Read command.

9.4.3 Dynamic Protection Bits

Dynamic Protection Bits are volatile and unique for each sector and can be individually modified. DYB only control the protection for sectors that have their PPB set to 1. By issuing the DYB Write command, a DYB is cleared to 0 or set to 1, thus placing each sector in the protected or unprotected state respectively. This feature allows software to easily protect sectors against inadvertent changes, yet does not prevent the easy removal of protection when changes are needed. The DYBs can be set or cleared as often as needed as they are volatile bits.

9.4.4 PPB Lock Bit (PPBL[0])

The PPB Lock Bit is a volatile bit for protecting all PPB bits. When cleared to 0, it locks all PPBs, when set to 1, it allows the PPBs to be changed. See [Section 8.6.9, PPB Lock Register \(PPBL\) on page 74](#) for more information.

The PLBWR command is used to clear the PPB Lock bit to 0. The PPB Lock Bit must be cleared to 0 only after all the PPBs are configured to the desired settings.

In Persistent Protection mode, the PPB Lock is set to 1 during POR or a hardware reset. When cleared to 0, no software command sequence can set the PPB Lock bit to 1, only another hardware reset or power-up can set the PPB Lock bit.

In the Password Protection mode, the PPB Lock bit is cleared to 0 during POR or a hardware reset. The PPB Lock bit can only be set to 1 by the Password Unlock command.

9.4.5 Sector Protection States Summary

Each sector can be in one of the following protection states:

- Unlocked — The sector is unprotected and protection can be changed by a simple command. The protection state defaults to unprotected when the device is shipped from Spansion.
- Dynamically Locked — A sector is protected and protection can be changed by a simple command. The protection state is not saved across a power cycle or reset.
- Persistently Locked — A sector is protected and protection can only be changed if the PPB Lock bit is set to 1. The protection state is non-volatile and saved across a power cycle or reset. Changing the protection state requires programming and or erase of the PPB bits.

Table 9.3 Sector Protection States

Protection Bit Values			Sector State
PPB Lock	PPB	DYB	
1	1	1	Unprotected – PPB and DYB are changeable.
1	1	0	Protected – PPB and DYB are changeable.
1	0	1	Protected – PPB and DYB are changeable.
1	0	0	Protected – PPB and DYB are changeable.
0	1	1	Unprotected – PPB not changeable, DYB is changeable.
0	1	0	Protected – PPB not changeable, DYB is changeable.
0	0	1	Protected – PPB not changeable, DYB is changeable.
0	0	0	Protected – PPB not changeable, DYB is changeable.

9.4.6 Persistent Protection Mode

The Persistent Protection method sets the PPB Lock bit to 1 during POR or hardware reset so that the PPB bits are unprotected by a device hardware reset. Software reset does not affect the PPB Lock bit. The PLBWR command can clear the PPB Lock bit to 0 to protect the PPB. There is no command to set the PPB Lock bit therefore the PPB Lock bit will remain at 0 until the next power-off or hardware reset.

9.4.7 Password Protection Mode

Password Protection mode allows an even higher level of security than the Persistent Sector Protection mode, by requiring a 64-bit password for unlocking the PPB Lock bit. In addition to this password requirement, after power-up and hardware reset, the PPB Lock bit is cleared to 0 to ensure protection at power-up. Successful execution of the Password Unlock command by entering the entire password sets the PPB Lock bit to 1, allowing for sector PPB modifications.

Password Protection Notes:

- Once the Password is programmed and verified, the Password mode (ASPR[2]=0) must be set in order to prevent reading the password.
- The Password Program Command is only capable of programming 0s. Programming a 1 after a cell is programmed as a 0 results in the cell left as a 0 with no programming error set.
- The password is all 1s when shipped from Spansion. It is located in its own memory space and is accessible through the use of the Password Program, Password Read, RDAR, and WRAR commands.
- All 64-bit password combinations are valid as a password.
- The Password mode, once programmed, prevents reading the 64-bit password and further password programming. All further program and read commands to the password region are disabled and these commands are ignored or return undefined data. There is no means to verify what the password is after the Password Mode Lock bit is selected. Password verification is only allowed before selecting the Password Protection mode.
- The Protection Mode Lock bits are not erasable.

- The exact password must be entered in order for the unlocking function to occur. If the password unlock command provided password does not match the hidden internal password, the unlock operation fails in the same manner as a programming operation on a protected sector. The P_ERR bit is set to 1, the WIP bit remains set, and the PPB Lock bit remains cleared to 0.
- The Password Unlock command cannot be accepted any faster than once every $100\ \mu\text{s} \pm 20\ \mu\text{s}$. This makes it take an unreasonably long time (58 million years) for a hacker to run through all the 64-bit combinations in an attempt to correctly match a password. The Read Status Register 1 command may be used to read the WIP bit to determine when the device has completed the password unlock command or is ready to accept a new password command. When a valid password is provided the password unlock command does not insert the $100\ \mu\text{s}$ delay before returning the WIP bit to 0.
- If the password is lost after selecting the Password mode, there is no way to set the PPB Lock bit.

9.5 Recommended Protection Process

During system manufacture, the flash device configuration should be defined by:

1. Programming the OTP configuration bits in CR1NV[5, 3:2], CR2NV, CR3NV, and CR4NV as desired.
2. Program the Secure Silicon Region (OTP area) as desired.
3. Program the PPB bits as desired via the PPBP command.
4. Program the Non-Volatile Data Learning Pattern (NVDLR) if it will be used in DDR read commands.
5. Program the Password register (PASS) if password protection will be used.
6. Program the ASP Register as desired, including the selection of the persistent or password ASP protection mode in ASPR[2:1]. It is very important to explicitly select a protection mode so that later accidental or malicious programming of the ASP register and OTP configuration is prevented. This is to ensure that only the intended OTP protection and configuration features are enabled.

During system power-up and boot code execution:

1. Trusted boot code can determine whether there is any need to program additional SSR (OTP area) information. If no SSR changes are needed the FREEZE bit (CR1V[0]) can be set to 1 to protect the SSR from changes during the remainder of normal system operation while power remains on.
2. If the Persistent Protection mode is in use, trusted boot code can determine whether there is any need to modify the persistent (PPB) sector protection via the PPBP or PPBE commands. If no PPB changes are needed the PPBLOCK bit can be cleared to 0 via the PPBL to protect the PPB bits from changes during the remainder of normal system operation while power remains on.
3. The Dynamic (DYB) Sector Protection bits can be written as desired via the DYBAR.

10. Commands

All communication between the host system and S25FS-S family memory devices is in the form of units called commands.

All commands begin with an instruction that selects the type of information transfer or device operation to be performed. Commands may also have an address, instruction modifier, latency period, data transfer to the memory, or data transfer from the memory. All instruction, address, and data information is transferred sequentially between the host system and memory device.

Command protocols are also classified by a numerical nomenclature using three numbers to reference the transfer width of three command phases:

- instruction;
- address and instruction modifier (mode);
- data.

Single bit wide commands start with an instruction and may provide an address or data, all sent only on the SI signal. Data may be sent back to the host serially on the SO signal. This is referenced as a 1-1-1 command protocol for single bit width instruction, single bit width address and modifier, single bit data.

Dual or Quad Input / Output (I/O) commands provide an address sent from the host as bit pairs on IO0 and IO1 or, four bit (nibble) groups on IO0, IO1, IO2, and IO3. Data is returned to the host similarly as bit pairs on IO0 and IO1 or, four bit (nibble) groups on IO0, IO1, IO2, and IO3. This is referenced as 1-2-2 for Dual I/O and 1-4-4 for Quad I/O command protocols.

The S25FS-S family also supports a QPI Mode in which all information is transferred in 4-bit width, including the instruction, address, modifier, and data. This is referenced as a 4-4-4 command protocol.

Commands are structured as follows:

- Each command begins with an eight bit (byte) instruction. However, some read commands are modified by a prior read command, such that the instruction is implied from the earlier command. This is called Continuous Read mode. When the device is in Continuous Read mode, the instruction bits are not transmitted at the beginning of the command because the instruction is the same as the read command that initiated the Continuous Read mode. In Continuous Read mode the command will begin with the read address. Thus, Continuous Read mode removes eight instruction bits from each read command in a series of same type read commands.
- The instruction may be stand alone or may be followed by address bits to select a location within one of several address spaces in the device. The address may be either a 24-bit or 32-bit, byte boundary, address.
- The Serial Peripheral Interface with Multiple IO provides the option for each transfer of address and data information to be done one, two, or four bits in parallel. This enables a trade off between the number of signal connections (IO bus width) and the speed of information transfer. If the host system can support a two or four bit wide IO bus the memory performance can be increased by using the instructions that provide parallel 2-bit (dual) or parallel 4-bit (quad) transfers.
- In legacy SPI Multiple IO mode, the width of all transfers following the instruction are determined by the instruction sent. Following transfers may continue to be single bit serial on only the SI or Serial Output (SO) signals, they may be done in two bit groups per (dual) transfer on the IO0 and IO1 signals, or they may be done in 4-bit groups per (quad) transfer on the IO0-IO3 signals. Within the dual or quad groups the least significant bit is on IO0. More significant bits are placed in significance order on each higher numbered IO signal. Single bits or parallel bit groups are transferred in most to least significant bit order.
- In QPI Mode, the width of all transfers, including instructions, is a 4-bit wide (quad) transfer on the IO0-IO3 signals.
- Dual I/O and Quad I/O read instructions send an instruction modifier called mode bits, following the address, to indicate that the next command will be of the same type with an implied, rather than an explicit, instruction. The next command thus does not provide an instruction byte, only a new address and mode bits. This reduces the time needed to send each command when the same command type is repeated in a sequence of commands.
- The address or mode bits may be followed by write data to be stored in the memory device or by a read latency period before read data is returned to the host.

- Read latency may be zero to several SCK cycles (also referred to as dummy cycles).
- All instruction, address, mode, and data information is transferred in byte granularity. Addresses are shifted into the device with the most significant byte first. All data is transferred with the lowest address byte sent first. Following bytes of data are sent in lowest to highest byte address order i.e. the byte address increments.
- All attempts to read the flash memory array during a program, erase, or a write cycle (embedded operations) are ignored. The embedded operation will continue to execute without any affect. A very limited set of commands are accepted during an embedded operation. These are discussed in the individual command descriptions. While a program, erase, or write operation is in progress, it is recommended to check that the Write-In Progress (WIP) bit is 0 before issuing most commands to the device, to ensure the new command can be accepted.
- Depending on the command, the time for execution varies. A command to read status information from an executing command is available to determine when the command completes execution and whether the command was successful.
- Although host software in some cases is used to directly control the SPI interface signals, the hardware interfaces of the host system and the memory device generally handle the details of signal relationships and timing. For this reason, signal relationships and timing are not covered in detail within this software interface focused section of the document. Instead, the focus is on the logical sequence of bits transferred in each command rather than the signal timing and relationships. Following are some general signal relationship descriptions to keep in mind. For additional information on the bit level format and signal timing relationships of commands, see [Command Protocol on page 24](#).
 - The host always controls the Chip Select (CS#), Serial Clock (SCK), and Serial Input (SI) - SI for single bit wide transfers. The memory drives Serial Output (SO) for single bit read transfers. The host and memory alternately drive the IO0-IO3 signals during Dual and Quad transfers.
 - All commands begin with the host selecting the memory by driving CS# low before the first rising edge of SCK. CS# is kept low throughout a command and when CS# is returned high the command ends. Generally, CS# remains low for eight bit transfer multiples to transfer byte granularity information. Some commands will not be accepted if CS# is returned high not at an 8-bit boundary.

10.1 Command Set Summary

10.1.1 Extended Addressing

To accommodate addressing above 128 Mb, there are two options:

1. Instructions that always require a 4-byte address, used to access up to 32 Gb of memory:

Command Name	Function	Instruction (Hex)
4READ	Read	13
4FAST_READ	Read Fast	0C
4DIOR	Dual I/O Read	BC
4QIOR	Quad I/O Read	EC
4DDRQIOR	DDR Quad I/O Read	EE
4PP	Page Program	12
4P4E	Parameter 4-kB Erase	21
4SE	Erase 64/256 kB	DC
4DYBRD	DYB Read	E0
4DYBWR	DYBWR	E1
4PPBRD	PPB Read	E2
4PPBP	PPB Program	E3

2. A 4-byte address mode for backward compatibility to the 3-byte address instructions. The standard 3-byte instructions can be used in conjunction with a 4-byte address mode controlled by the Address Length configuration bit (CR2V[7]). The default value of CR2V[7] is loaded from CR2NV[7] (following power-up, hardware reset, or software reset), to enable default 3-byte (24-bit) or 4-byte (32-bit) addressing. When the address length (CR2V[7]) set to 1, the legacy commands are changed to require 4-bytes (32-bits) for the address field. The following instructions can be used in conjunction with the 4-byte address mode configuration to switch from 3 bytes to 4 bytes of address field.

Command Name	Function	Instruction (Hex)
READ	Read	03
FAST_READ	Read Fast	0B
DIOR	Dual I/O Read	BB
QIOR	Quad I/O Read	EB
DDRQIOR	DDR Quad I/O Read)	ED
PP	Page Program	02
P4E	Parameter 4-kB Erase	20
SE	Erase 64 / 256 kB	D8
RDAR	Read Any Register	65
WRAR	Write Any Register	71
EES	Evaluate Erase Status	D0
OTPP	OTP Program	42
OTPR	OTP Read	4B
DYBRD	DYB Read	FA
DYBWR	DYBWR	FB
PPBRD	PPB Read	FC
PPBP	PPB Program	FD

10.1.2 Command Summary by Function

Table 10.1 S25FS-S Family Command Set (sorted by function) (Sheet 1 of 2)

Function	Command Name	Command Description	Instruction Value (Hex)	Maximum Frequency (MHz)	Address Length (Bytes)	QPI
Read Device ID	RDID	Read ID (JEDEC Manufacturer ID and JEDEC CFI)	9F	133	0	Yes
	RSFDP	Read JEDEC Serial Flash Discoverable Parameters	5A	50	3	Yes
	RDQID	Read Quad ID	AF	133	0	Yes
Register Access	RDSR1	Read Status Register 1	05	133	0	Yes
	RDSR2	Read Status Register 2	07	133	0	No
	RDCR	Read Configuration Register 1	35	133	0	No
	RDAR	Read Any Register	65	133	3 or 4	Yes
	WRR	Write Register (Status 1, Configuration 1)	01	133	0	Yes
	WRDI	Write Disable	04	133	0	Yes
	WREN	Write Enable	06	133	0	Yes
	WRAR	Write Any Register	71	133	3 or 4	Yes
	CLSR	Clear Status Register 1 - Erase/Prog. Fail Reset This command may be disabled and the instruction value instead used for a program / erase resume command - see Configuration Register 3 on page 69	30	133	0	Yes
	CLSR	Clear Status Register 1 (alternate instruction) - Erase/Prog. Fail Reset	82	133	0	Yes
	4BAM	Enter 4-byte Address Mode	B7	133	0	No
	SBL	Set Burst Length	C0	133	0	No
	EES	Evaluate Erase Status	D0	133	3 or 4	Yes
	DLPRD	Data Learning Pattern Read	41	133	0	No
	PNVDLR	Program NV Data Learning Register	43	133	0	No
	WVDLR	Write Volatile Data Learning Register	4A	133	0	No
Read Flash Array	READ	Read	03	50	3 or 4	No
	4READ	Read	13	50	4	No
	FAST_READ	Fast Read	0B	133	3 or 4	No
	4FAST_READ	Fast Read	0C	133	4	No
	DIOR	Dual I/O Read	BB	66	3 or 4	No
	4DIOR	Dual I/O Read	BC	66	4	No
	QIOR	Quad I/O Read	EB	133	3 or 4	Yes
	4QIOR	Quad I/O Read	EC	133	4	Yes
	DDRQIOR	DDR Quad I/O Read	ED	80	3 or 4	Yes
	4DDRQIOR	DDR Quad I/O Read	EE	80	4	Yes
Program Flash Array	PP	Page Program	02	133	3 or 4	Yes
	4PP	Page Program	12	133	4	Yes
Erase Flash Array	P4E	Parameter 4-kB Sector Erase	20	133	3 or 4	Yes
	4P4E	Parameter 4-kB Sector Erase	21	133	4	Yes
	SE	Erase 64 kB or 256 kB	D8	133	3 or 4	Yes
	4SE	Erase 64 kB or 256 kB	DC	133	4	Yes
	BE	Bulk Erase	60	133	0	Yes
	BE	Bulk Erase (alternate instruction)	C7	133	0	Yes

Table 10.1 S25FS-S Family Command Set (sorted by function) (Sheet 2 of 2)

Function	Command Name	Command Description	Instruction Value (Hex)	Maximum Frequency (MHz)	Address Length (Bytes)	QPI
Erase /Program Suspend /Resume	EPS	Erase / Program Suspend	75	133	0	Yes
	EPS	Erase / Program Suspend (alternate instruction)	85	133	0	Yes
	EPS	Erase / Program Suspend (alternate instruction)	B0	133	0	Yes
	EPR	Erase / Program Resume	7A	133	0	Yes
	EPR	Erase / Program Resume (alternate instruction)	8A	133	0	Yes
	EPR	Erase / Program Resume (alternate instruction) This command may be disabled and the instruction value instead used for a clear status command - see Configuration Register 3 on page 69	30	133	0	Yes
One-Time Program Array	OTPP	OTP Program	42	133	3 or 4	No
	OTPR	OTP Read	4B	133	3 or 4	No
Advanced Sector Protection	DYBRD	DYB Read	FA	133	3 or 4	Yes
	4DYBRD	DYB Read	E0	133	4	Yes
	DYBWR	DYB Write	FB	133	3 or 4	Yes
	4DYBWR	DYB Write	E1	133	4	Yes
	PPBRD	PPB Read	FC	133	3 or 4	No
	4PPBRD	PPB Read	E2	133	4	No
	PPBP	PPB Program	FD	133	3 or 4	No
	4PPBP	PPB Program	E3	133	4	No
	PPBE	PPB Erase	E4	133	0	No
	ASPRD	ASP Read	2B	133	0	No
	ASPP	ASP Program	2F	133	0	No
	PLBRD	PPB Lock Bit Read	A7	133	0	No
	PLBWR	PPB Lock Bit Write	A6	133	0	No
	PASSRD	Password Read	E7	133	0	No
	PASSP	Password Program	E8	133	0	No
	PASSU	Password Unlock	E9	133	0	No
Reset	RSTEN	Software Reset Enable	66	133	0	Yes
	RST	Software Reset	99	133	0	Yes
	RESET	Legacy Software Reset	F0	133	0	No
	MBR	Mode Bit Reset	FF	133	0	Yes

Note:

1. Commands not supported in QPI Mode have undefined behavior if sent when the device is in QPI Mode.

10.1.3 Read Device Identification

There are multiple commands to read information about the device manufacturer, device type, and device features. SPI memories from different vendors have used different commands and formats for reading information about the memories. The S25FS-S family supports the three device information commands.

10.1.4 Register Read or Write

There are multiple registers for reporting embedded operation status or controlling device configuration options. There are commands for reading or writing these registers. Registers contain both volatile and non-volatile bits. Non-Volatile bits in registers are automatically erased and programmed as a single (write) operation.

10.1.4.1 Monitoring Operation Status

The host system can determine when a write, program, erase, suspend or other embedded operation is complete by monitoring the Write-In-Progress (WIP) bit in the Status Register. The Read from Status Register 1 command or Read Any Register command provides the state of the WIP bit. The program error (P_ERR) and erase error (E_ERR) bits in the Status Register indicate whether the most recent program or erase command has not completed successfully. When P_ERR or E_ERR bits are set to 1, the WIP bit will remain set to one indicating the device remains busy and unable to receive most new operation commands. Only Status Read (RDSR1 05h), Read Any Register (RDAR 65h), Status Clear (CLSR 30h or 82h), and Software Reset (RSTEN 66h, RST 99h or RESET F0h) are valid commands when P_ERR or E_ERR is set to 1. A Clear Status Register (CLSR) followed by a Write Disable (WRDI) command must be sent to return the device to standby state. Clear Status Register clears the WIP, P_ERR, and E_ERR bits. WRDI clears the WEL bit. Alternatively, hardware reset, or software reset (RST or RESET) may be used to return the device to standby state.

10.1.4.2 Configuration

There are commands to read, write, and protect registers that control interface path width, interface timing, interface address length, and some aspects of data protection.

10.1.5 Read Flash Array

Data may be read from the memory starting at any byte boundary. Data bytes are sequentially read from incrementally higher byte addresses until the host ends the data transfer by driving CS# input High. If the byte address reaches the maximum address of the memory array, the read will continue at address zero of the array.

There are several different read commands to specify different access latency and data path widths. Double Data Rate (DDR) commands also define the address and data bit relationship to both SCK edges:

- The Read command provides a single address bit per SCK rising edge on the SI signal with read data returning a single bit per SCK falling edge on the SO signal. This command has zero latency between the address and the returning data but is limited to a maximum SCK rate of 50MHz.
- Other read commands have a latency period between the address and returning data but can operate at higher SCK frequencies. The latency depends on a Configuration Register read latency value.
- The Fast Read command provides a single address bit per SCK rising edge on the SI signal with read data returning a single bit per SCK falling edge on the SO signal.
- Dual or Quad I/O Read commands provide address two bits or four bits per SCK rising edge with read data returning two bits, or four bits of data per SCK falling edge on the IO0-IO3 signals.
- Quad Double Data Rate read commands provide address four bits per every SCK edge with read data returning four bits of data per every SCK edge on the IO0-IO3 signals.

10.1.6 Program Flash Array

Programming data requires two commands: Write Enable (WREN), and Page Program (PP). The Page Program command accepts from 1 byte up to 256 or 512 consecutive bytes of data (page) to be programmed in one operation. Programming means that bits can either be left at 1, or programmed from 1 to 0. Changing bits from 0 to 1 requires an erase operation.

10.1.7 Erase Flash Array

The Parameter Sector Erase, Sector Erase, or Bulk Erase commands set all the bits in a sector or the entire memory array to 1. A bit needs to be first erased to 1 before programming can change it to a 0. While bits can be individually programmed from a 1 to 0, erasing bits from 0 to 1 must be done on a sector-wide or array-wide (bulk) level. The Write Enable (WREN) command must precede an erase command.

10.1.8 OTP, Block Protection, and Advanced Sector Protection

There are commands to read and program a separate One-Time Programmable (OTP) array for permanent data such as a serial number. There are commands to control a contiguous group (block) of flash memory array sectors that are protected from program and erase operations. There are commands to control which individual flash memory array sectors are protected from program and erase operations.

10.1.9 Reset

There are commands to reset to the default conditions present after power-on to the device. However, the software reset commands do not affect the current state of the FREEZE or PPB Lock bits. In all other respects a software reset is the same as a hardware reset.

There is a command to reset (exit from) the Continuous Read mode.

10.1.10 Reserved

Some instructions are reserved for future use. In this generation of the S25FS-S family some of these command instructions may be unused and not affect device operation, some may have undefined results.

Some commands are reserved to ensure that a legacy or alternate source device command is allowed without effect. This allows legacy software to issue some commands that are not relevant for the current generation S25FS-S family with the assurance these commands do not cause some unexpected action.

Some commands are reserved for use in special versions of the FS-S not addressed by this document or for a future generation. This allows new host memory controller designs to plan the flexibility to issue these command instructions. The command format is defined if known at the time this document revision is published.

10.2 Identification Commands

10.2.1 Read Identification (RDID 9Fh)

The Read Identification (RDID) command provides read access to manufacturer identification, device identification, and Common Flash Interface (CFI) information. The manufacturer identification is assigned by JEDEC. The CFI structure is defined by JEDEC standard. The device identification and CFI values are assigned by Spansion.

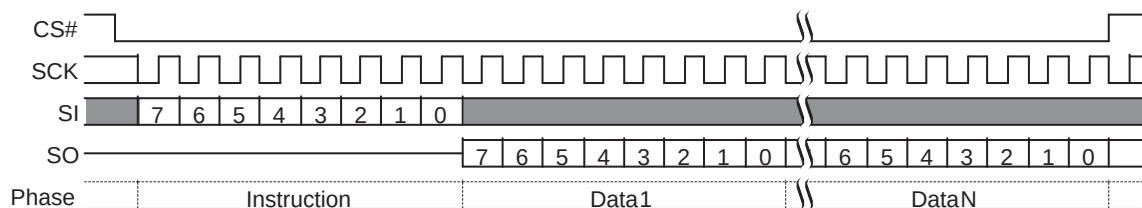
The JEDEC Common Flash Interface (CFI) specification defines a device information structure, which allows a vendor-specified software flash management program (driver) to be used for entire families of flash devices. Software support can then be device-independent, JEDEC manufacturer ID independent, forward and backward-compatible for the specified flash device families. System vendors can standardize their flash drivers for long-term software compatibility by using the CFI values to configure a family driver from the CFI information of the device in use.

Any RDID command issued while a program, erase, or write cycle is in progress is ignored and has no effect on execution of the program, erase, or write cycle that is in progress.

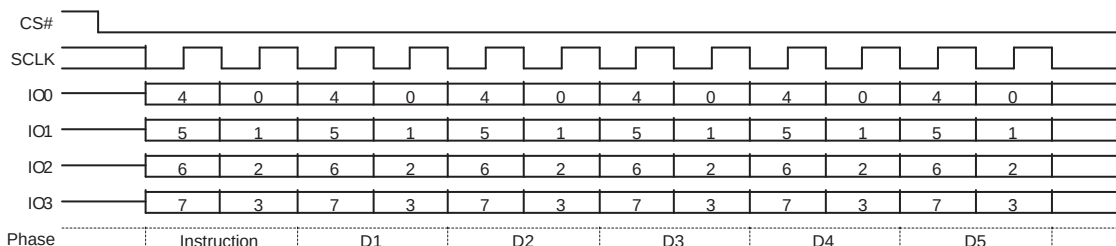
The RDID instruction is shifted on SI. After the last bit of the RDID instruction is shifted into the device, a byte of manufacturer identification, two bytes of device identification, extended device identification, and CFI information will be shifted sequentially out on SO. As a whole this information is referred to as ID-CFI. See [Device ID and Common Flash Interface \(ID-CFI\) Address Map on page 143](#) for the detail description of the ID-CFI contents.

Continued shifting of output beyond the end of the defined ID-CFI address space will provide undefined data. The RDID command sequence is terminated by driving CS# to the logic high state anytime during data output.

The maximum clock frequency for the RDID command is 133 MHz.

Figure 10.1 Read Identification (RDID) Command Sequence


This command is also supported in QPI Mode. In QPI Mode the instruction is shifted in on IO0-IO3 and the returning data is shifted out on IO0-IO3.

Figure 10.2 Read Identification (RDID) QPI Mode Command


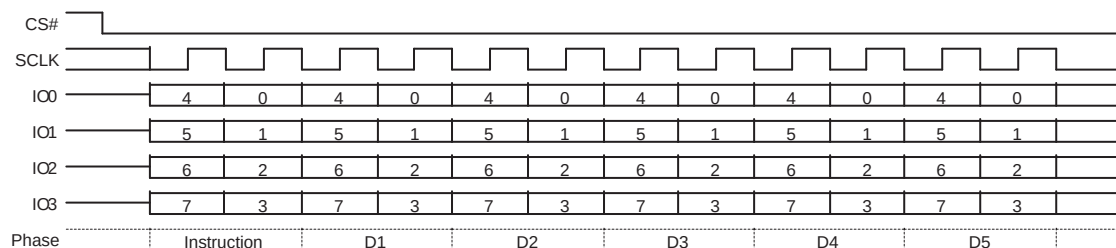
10.2.2 Read Quad Identification (RDQID AFh)

The Read Quad Identification (RDQID) command provides read access to manufacturer identification, device identification, and Common Flash Interface (CFI) information. This command is an alternate way of reading the same information provided by the RDID command while in QPI Mode. In all other respects the command behaves the same as the RDID command.

The command is recognized only when the device is in QPI Mode (CR2V[6]=1). The instruction is shifted in on IO0-IO3. After the last bit of the instruction is shifted into the device, a byte of manufacturer identification, two bytes of device identification, extended device identification, and CFI information will be shifted sequentially out on IO0-IO3. As a whole this information is referred to as ID-CFI. See [Device ID and Common Flash Interface \(ID-CFI\) Address Map on page 143](#) for the detail description of the ID-CFI contents.

Continued shifting of output beyond the end of the defined ID-CFI address space will provide undefined data. The command sequence is terminated by driving CS# to the logic high state anytime during data output.

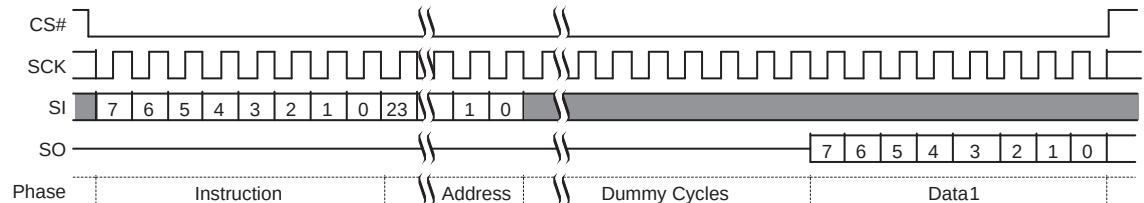
The maximum clock frequency for the command is 133 MHz.

Figure 10.3 Read Quad Identification (RDQID) Command Sequence


10.2.3 Read Serial Flash Discoverable Parameters (RSFDP 5Ah)

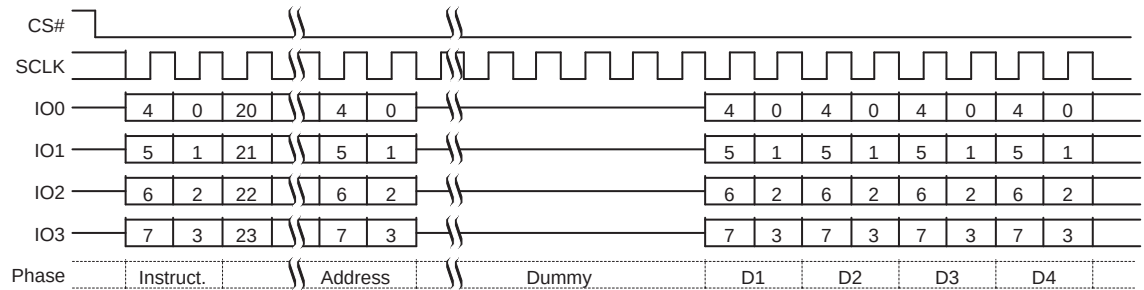
The command is initiated by shifting on SI the instruction code “5Ah”, followed by a 24-bit address of 000000h, followed by 8 dummy cycles. The SFDP bytes are then shifted out on SO starting at the falling edge of SCK after the dummy cycles. The SFDP bytes are always shifted out with the MSB first. If the 24-bit address is set to any other value, the selected location in the SFDP space is the starting point of the data read. This enables random access to any parameter in the SFDP space. The RSFDP command is supported up to 50 MHz.

Figure 10.4 RSFDP Command Sequence



This command is also supported in QPI Mode. In QPI Mode the instruction is shifted in on IO0-IO3 and the returning data is shifted out on IO0-IO3.

Figure 10.5 RSFDP QPI Mode Command Sequence

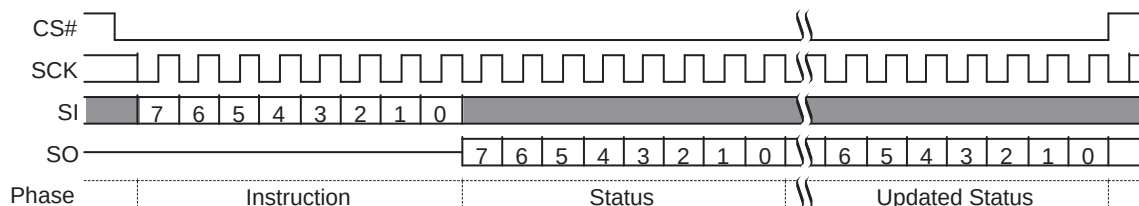


10.3 Register Access Commands

10.3.1 Read Status Register 1 (RDSR1 05h)

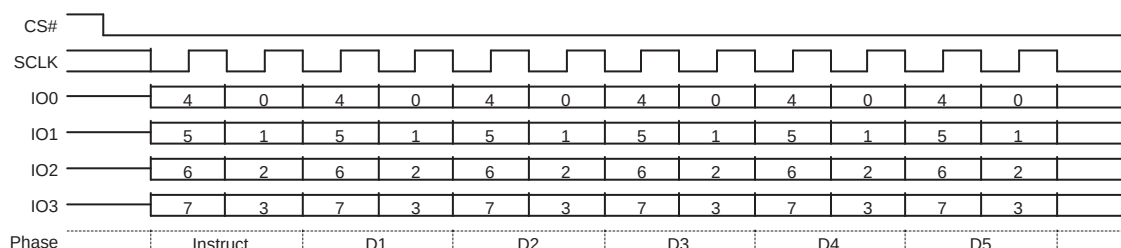
The Read Status Register 1 (RDSR1) command allows the Status Register 1 contents to be read from SO. The volatile version of Status Register 1 (SR1V) contents may be read at any time, even while a program, erase, or write operation is in progress. It is possible to read Status Register 1 continuously by providing multiples of eight clock cycles. The status is updated for each eight cycle read. The maximum clock frequency for the RDSR1 (05h) command is 133 MHz.

Figure 10.6 Read Status Register 1 (RDSR1) Command Sequence



This command is also supported in QPI Mode. In QPI Mode the instruction is shifted in on IO0-IO3 and the returning data is shifted out on IO0-IO3, two clock cycles per byte.

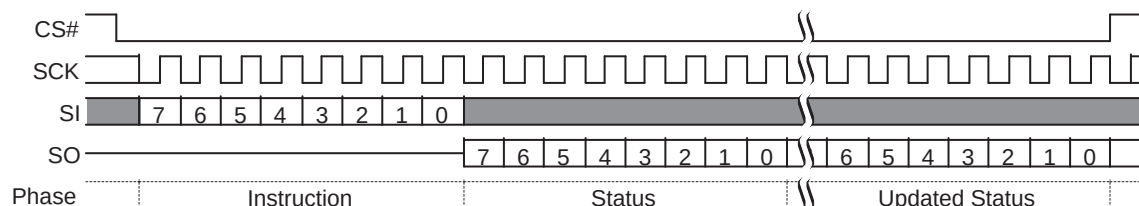
Figure 10.7 Read Status Register 1 (RDSR1) QPI Mode Command



10.3.2 Read Status Register 2 (RDSR2 07h)

The Read Status Register 2 (RDSR2) command allows the Status Register 2 contents to be read from SO. The Status Register 2 contents may be read at any time, even while a program, erase, or write operation is in progress. It is possible to read the Status Register 2 continuously by providing multiples of eight clock cycles. The status is updated for each eight cycle read. The maximum clock frequency for the RDSR2 command is 133 MHz.

Figure 10.8 Read Status Register 2 (RDSR2) Command

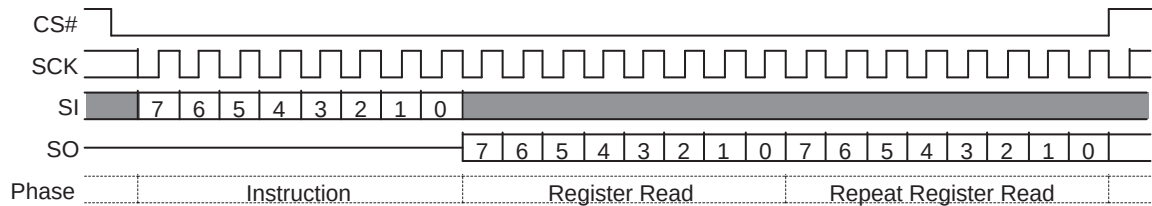


In QPI Mode, Status Register 2 may be read via the Read Any Register command, see [Read Any Register \(RDAR 65h\)](#) on page 101

10.3.3 Read Configuration Register (RDCR 35h)

The Read Configuration Register (RDCR) command allows the volatile Configuration Register (CR1V) contents to be read from SO. It is possible to read CR1V continuously by providing multiples of eight clock cycles. The Configuration Register contents may be read at any time, even while a program, erase, or write operation is in progress.

Figure 10.9 Read Configuration Register (RDCR) Command Sequence



In QPI Mode, Configuration Register 1 may be read via the Read Any Register command, see [Section 10.3.12, Read Any Register \(RDAR 65h\) on page 101](#)

10.3.4 Write Registers (WRR 01h)

The Write Registers (WRR) command allows new values to be written to both the Status Register 1 and Configuration Register 1. Before the Write Registers (WRR) command can be accepted by the device, a Write Enable (WREN) command must be received. After the Write Enable (WREN) command has been decoded successfully, the device will set the Write Enable Latch (WEL) in the Status Register to enable any write operations.

The Write Registers (WRR) command is entered by shifting the instruction and the data bytes on SI. The Status Register is one data byte in length.

The WRR operation first erases the register then programs the new value as a single operation. The Write Registers (WRR) command will set the P_ERR or E_ERR bits if there is a failure in the WRR operation. See [Status Register 1 Volatile \(SR1V\) on page 61](#) for a description of the error bits. Any Status or Configuration Register bit reserved for the future must be written as a 0.

CS# must be driven to the logic high state after the eighth or sixteenth bit of data has been latched. If not, the Write Registers (WRR) command is not executed. If CS# is driven high after the eighth cycle then only the Status Register 1 is written; otherwise, after the sixteenth cycle both the Status and Configuration Registers are written.

As soon as CS# is driven to the logic high state, the self-timed Write Registers (WRR) operation is initiated. While the Write Registers (WRR) operation is in progress, the Status Register may still be read to check the value of the Write-In Progress (WIP) bit. The Write-In Progress (WIP) bit is a 1 during the self-timed Write Registers (WRR) operation, and is a 0 when it is completed. When the Write Registers (WRR) operation is completed, the Write Enable Latch (WEL) is set to a 0. The maximum clock frequency for the WRR command is 133 MHz.

This command is also supported in QPI Mode. In QPI Mode the instruction and data is shifted in on IO0-IO3, two clock cycles per byte.

Figure 10.10 Write Registers (WRR) Command Sequence – 8-Data Bits

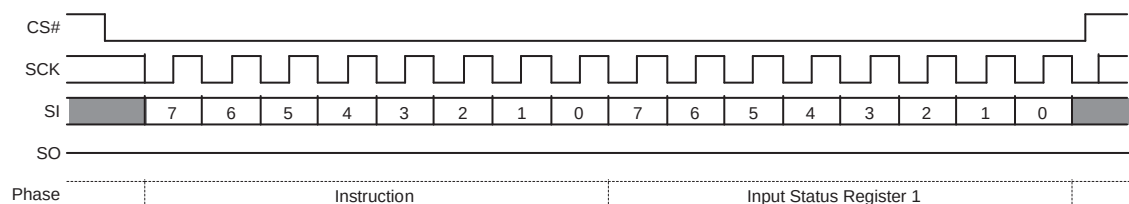
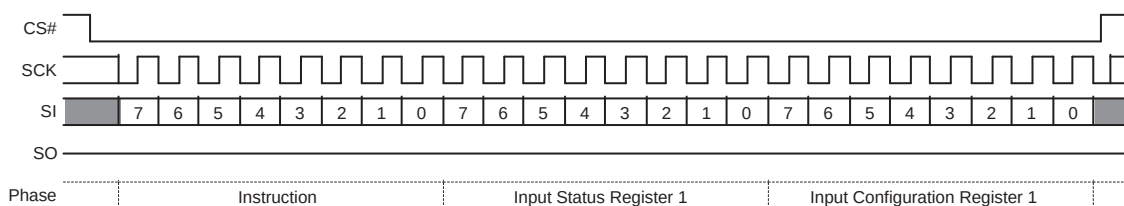
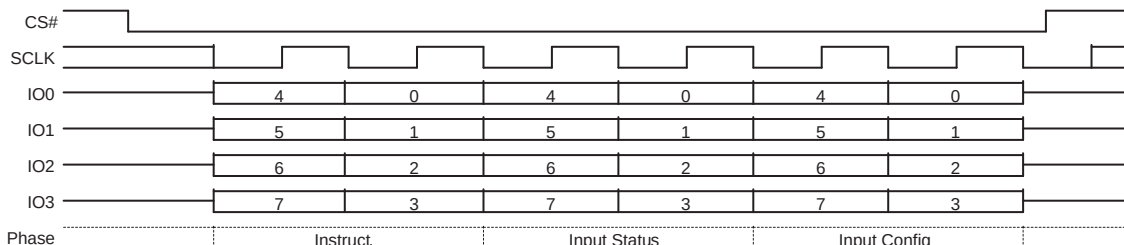


Figure 10.11 Write Registers (WRR) Command Sequence – 16-Data Bits

Figure 10.12 Write Registers (WRR) Command Sequence – 16-Data Bits QPI Mode


The Write Registers (WRR) command allows the user to change the values of the Block Protect (BP2, BP1, and BP0) bits in either the non-volatile Status Register 1 or in the volatile Status Register 1, to define the size of the area that is to be treated as read-only. The BPNV_O bit (CR1NV[3]) controls whether WRR writes the non-volatile or volatile version of Status Register 1. When CR1NV[3]=0 WRR writes SR1NV[4:2]. When CR1NV[3]=1 WRR writes SR1V[4:2].

The Write Registers (WRR) command also allows the user to set the Status Register Write Disable (SRWD) bit to a 1 or a 0. The Status Register Write Disable (SRWD) bit and Write Protect (WP#) signal allow the BP bits to be hardware protected.

When the Status Register Write Disable (SRWD) bit of the Status Register is a 0 (its initial delivery state), it is possible to write to the Status Register provided that the Write Enable Latch (WEL) bit has previously been set by a Write Enable (WREN) command, regardless of the whether Write Protect (WP#) signal is driven to the logic high or logic low state.

When the Status Register Write Disable (SRWD) bit of the Status Register is set to a 1, two cases need to be considered, depending on the state of Write Protect (WP#):

- If Write Protect (WP#) signal is driven to the logic high state, it is possible to write to the Status and Configuration Registers provided that the Write Enable Latch (WEL) bit has previously been set to a 1 by initiating a Write Enable (WREN) command.
- If Write Protect (WP#) signal is driven to the logic low state, it is not possible to write to the Status and Configuration Registers even if the Write Enable Latch (WEL) bit has previously been set to a 1 by a Write Enable (WREN) command. Attempts to write to the Status and Configuration Registers are rejected, not accepted for execution, and no error indication is provided. As a consequence, all the data bytes in the memory area that are protected by the Block Protect (BP2, BP1, BP0) bits of the Status Register, are also hardware protected by WP#.

The WP# hardware protection can be provided:

- by setting the Status Register Write Disable (SRWD) bit after driving Write Protect (WP#) signal to the logic low state;
- or by driving Write Protect (WP#) signal to the logic low state after setting the Status Register Write Disable (SRWD) bit to a 1.

The only way to release the hardware protection is to pull the Write Protect (WP#) signal to the logic high state. If WP# is permanently tied high, hardware protection of the BP bits can never be activated.

Table 10.2 Block Protection Modes

WP#	SRWD Bit	Mode	Write Protection of Registers	Memory Content	
				Protected Area	Unprotected Area
1	1	Software Protected	Status and Configuration Registers are Writable (if WREN command has set the WEL bit). The values in the SRWD, BP2, BP1, and BP0 bits and those in the Configuration Register can be changed.	Protected against Page Program, Sector Erase, and Bulk Erase.	Ready to accept Page Program, and Sector Erase commands.
1	0				
0	0				
0	1	Hardware Protected	Status and Configuration Registers are Hardware Write Protected. The values in the SRWD, BP2, BP1, and BP0 bits and those in the Configuration Register cannot be changed.	Protected against Page Program, Sector Erase, and Bulk Erase.	Ready to accept Page Program or Erase commands.

Notes:

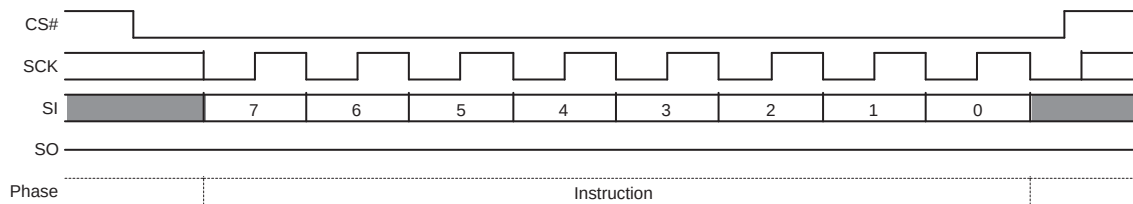
1. The Status Register originally shows 00h when the device is first shipped from Spansion to the customer.
2. Hardware protection is disabled when Quad Mode is enabled (CR1V[1] = 1). WP# becomes IO2; therefore, it cannot be utilized.

10.3.5 Write Enable (WREN 06h)

The Write Enable (WREN) command sets the Write Enable Latch (WEL) bit of the Status Register 1 (SR1V[1]) to a 0. The Write Enable Latch (WEL) bit must be set to a 1 by issuing the Write Enable (WREN) command to enable write, program and erase commands.

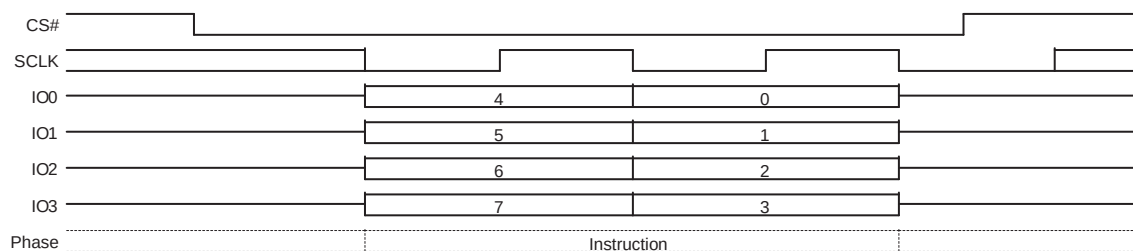
CS# must be driven into the logic high state after the eighth bit of the instruction byte has been latched in on SI. Without CS# being driven to the logic high state after the eighth bit of the instruction byte has been latched in on SI, the write enable operation will not be executed.

Figure 10.13 Write Enable (WREN) Command Sequence



This command is also supported in QPI Mode. In QPI Mode the instruction is shifted in on IO0-IO3, two clock cycles per byte.

Figure 10.14 Write Enable (WREN) Command Sequence QPI Mode



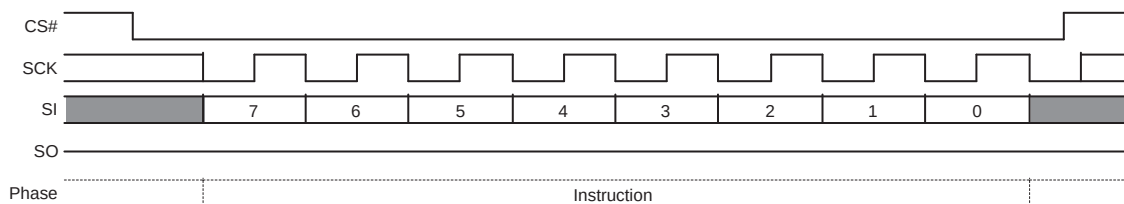
10.3.6 Write Disable (WRDI 04h)

The Write Disable (WRDI) command clears the Write Enable Latch (WEL) bit of the Status Register 1 (SR1V[1]) to a 1.

The Write Enable Latch (WEL) bit may be cleared to a 0 by issuing the Write Disable (WRDI) command to disable Page Program (PP), Sector Erase (SE), Bulk Erase (BE), Write Registers (WRR or WRAR), OTP Program (OTPP), and other commands, that require WEL be set to 1 for execution. The WRDI command can be used by the user to protect memory areas against inadvertent writes that can possibly corrupt the contents of the memory. The WRDI command is ignored during an embedded operation while WIP bit =1.

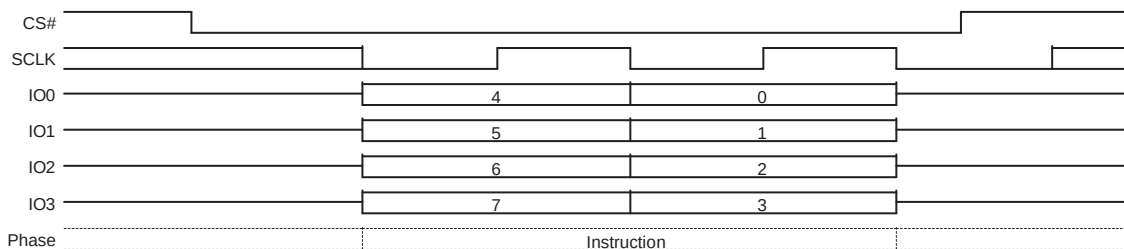
CS# must be driven into the logic high state after the eighth bit of the instruction byte has been latched in on SI. Without CS# being driven to the logic high state after the eighth bit of the instruction byte has been latched in on SI, the write disable operation will not be executed.

Figure 10.15 Write Disable (WRDI) Command Sequence



This command is also supported in QPI Mode. In QPI Mode the instruction is shifted in on IO0-IO3, two clock cycles per byte.

Figure 10.16 Write Disable (WRDI) Command Sequence QPI Mode

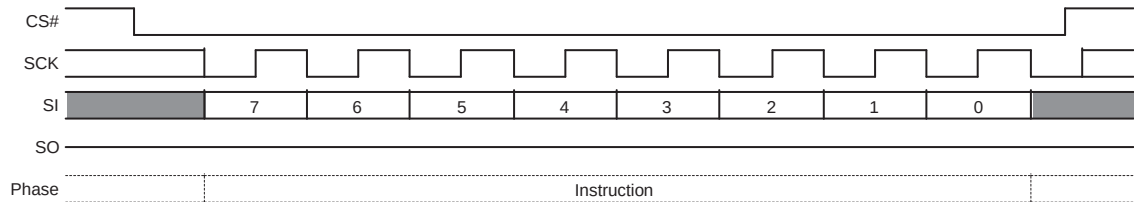


10.3.7 Clear Status Register (CLSR 30h or 82h)

The Clear Status Register command resets bit SR1V[5] (Erase Fail Flag) and bit SR1V[6] (Program Fail Flag). It is not necessary to set the WEL bit before a Clear Status Register command is executed. The Clear Status Register command will be accepted even when the device remains busy with WIP set to 1, as the device does remain busy when either error bit is set. The WEL bit will be unchanged after this command is executed.

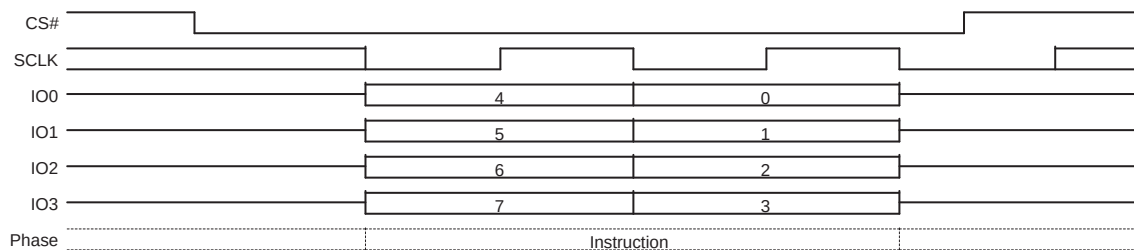
The legacy Clear Status Register (CLSR 30h) instruction may be disabled and the 30h instruction value instead used for a program / erase resume command - see [Configuration Register 3 on page 69](#). The Clear Status Register alternate instruction (CLSR 82h) is always available to clear the Status Register.

Figure 10.17 Clear Status Register (CLSR) Command Sequence



This command is also supported in QPI Mode. In QPI Mode the instruction is shifted in on IO0-IO3, two clock cycles per byte.

Figure 10.18 Clear Status Register (CLSR) Command Sequence QPI Mode



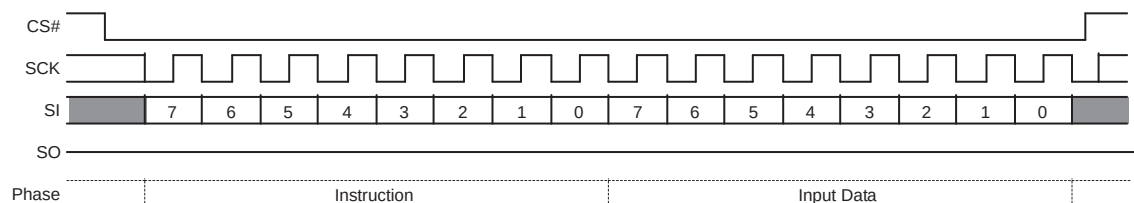
10.3.8 Program NVDLR (PNVDLR 43h)

Before the Program NVDLR (PNVDLR) command can be accepted by the device, a Write Enable (WREN) command must be issued and decoded by the device. After the Write Enable (WREN) command has been decoded successfully, the device will set the Write Enable Latch (WEL) to enable the PNVDLR operation.

The PNVDLR command is entered by shifting the instruction and the data byte on SI.

CS# must be driven to the logic high state after the eighth bit of data has been latched. If not, the PNVDLR command is not executed. As soon as CS# is driven to the logic high state, the self-timed PNVDLR operation is initiated. While the PNVDLR operation is in progress, the Status Register may be read to check the value of the Write-In Progress (WIP) bit. The Write-In Progress (WIP) bit is a 1 during the self-timed PNVDLR cycle, and is a 0 when it is completed. The PNVDLR operation can report a program error in the P_ERR bit of the Status Register. When the PNVDLR operation is completed, the Write Enable Latch (WEL) is set to a 0. The maximum clock frequency for the PNVDLR command is 133 MHz.

Figure 10.19 Program NVDLR (PNVDLR) Command Sequence



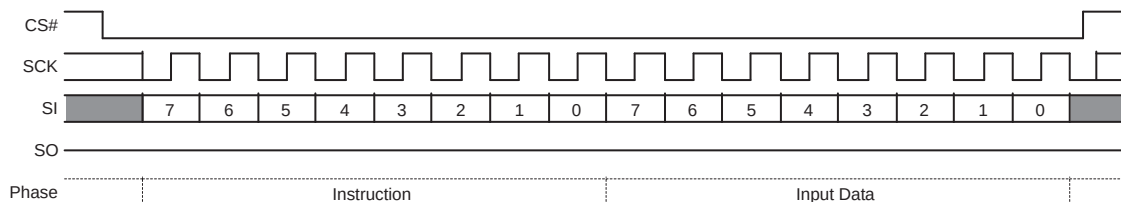
10.3.9 Write VDLR (WVDLR 4Ah)

Before the Write VDLR (WVDLR) command can be accepted by the device, a Write Enable (WREN) command must be issued and decoded by the device. After the Write Enable (WREN) command has been decoded successfully, the device will set the Write Enable Latch (WEL) to enable WVDLR operation.

The WVDLR command is entered by shifting the instruction and the data byte on SI.

CS# must be driven to the logic high state after the eighth bit of data has been latched. If not, the WVDLR command is not executed. As soon as CS# is driven to the logic high state, the WVDLR operation is initiated with no delays. The maximum clock frequency for the PNVDLR command is 133 MHz.

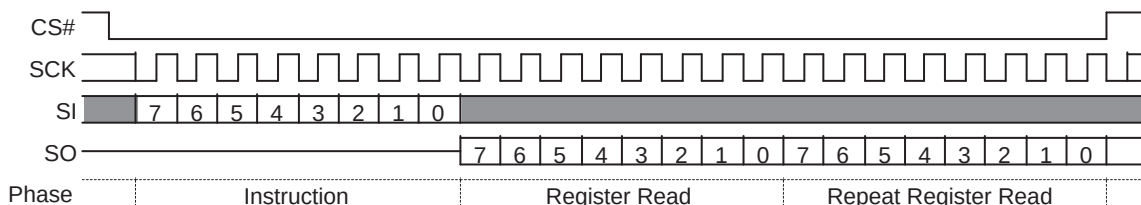
Figure 10.20 Write VDLR (WVDLR) Command Sequence



10.3.10 Data Learning Pattern Read (DLPRD 41h)

The instruction is shifted on SI, then the 8-bit DLP is shifted out on SO. It is possible to read the DLP continuously by providing multiples of eight clock cycles. The maximum operating clock frequency for the DLPRD command is 133 MHz.

Figure 10.21 DLP Read (DLPRD) Command Sequence

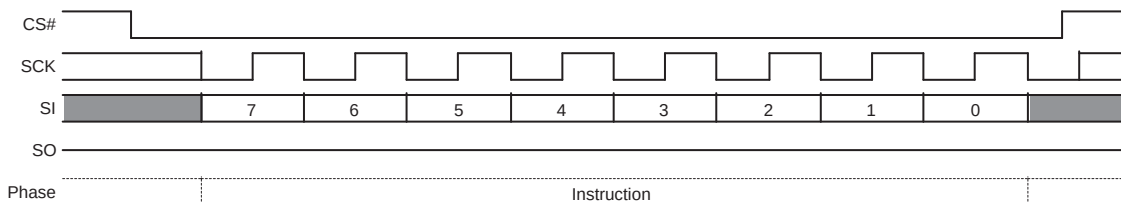


10.3.11 Enter 4-Byte Address Mode (4BAM B7h)

The enter 4-byte Address Mode (4BAM) command sets the volatile Address Length bit (CR2V[7]) to 1 to change most 3-byte address commands to require 4 bytes of address. The Read SFDP (RSFDP) command is the only 3-byte command that is not affected by the Address Length bit. RSFDP is required by the JEDEC JESD216 standard to always have only 3 bytes of address.

A hardware or software reset is required to exit the 4-byte address mode.

Figure 10.22 Enter 4-Byte Address Mode (4BAM B7h) Command Sequence



10.3.12 Read Any Register (RDAR 65h)

The Read Any Register (RDAR) command provides a way to read all device registers - non-volatile and volatile. The instruction is followed by a 3- or 4-byte address (depending on the address length configuration CR2V[7], followed by a number of latency (dummy) cycles set by CR2V[3:0]. Then the selected register contents are returned. If the read access is continued the same addressed register contents are returned until the command is terminated - only one register is read by each RDAR command.

Reading undefined locations provides undefined data.

The RDAR command may be used during embedded operations to read Status Register 1 (SR1V).

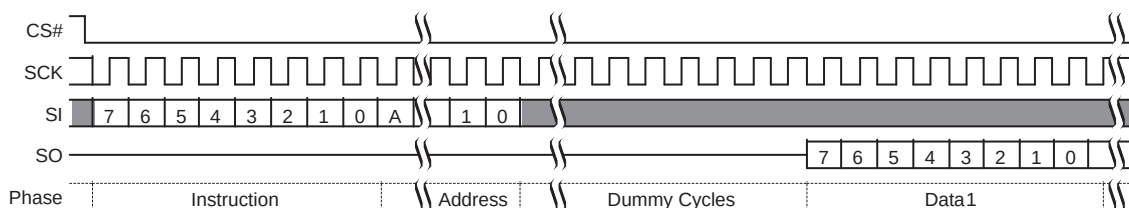
The RDAR command is not used for reading registers that act as a window into a larger array: PPBAR, and DYBAR. There are separate commands required to select and read the location in the array accessed.

The RDAR command will read invalid data from the PASS register locations if the ASP Password protection mode is selected by programming ASPR[2] to 0.

Table 10.3 Register Address Map

Byte Address (Hex)	Register Name	Description
00000000	SR1NV	Non-Volatile Status and Configuration Registers
00000001	N/A	
00000002	CR1NV	
00000003	CR2NV	
00000004	CR3NV	
00000005	CR4NV	
...	N/A	
00000010	NVDLR	Non-Volatile Data Learning Register
...	N/A	
00000020	PASS[7:0]	Non-Volatile Password Register
00000021	PASS[15:8]	
00000022	PASS[23:16]	
00000023	PASS[31:24]	
00000024	PASS[39:32]	
00000025	PASS[47:40]	
00000026	PASS[55:48]	
00000027	PASS[63:56]	
...	N/A	
00000030	ASPR[7:0]	Non-Volatile
00000031	ASPR[15:8]	
...	N/A	
00800000	SR1V	Volatile Status and Configuration Registers
00800001	SR2V	
00800002	CR1V	
00800003	CR2V	
00800004	CR3V	
00800005	CR4V	
...	N/A	
00800010	VDLR	Volatile Data Learning Register
...	N/A	
00800040	PPBL	Volatile PPB Lock Register
...	N/A	

Figure 10.23 Read Any Register Read Command Sequence



Note:

1. A = MSB of address = 23 for Address length CR2V[7] = 0, or 31 for CR2V[7]=1

This command is also supported in QPI Mode. In QPI Mode the instruction is shifted in on IO0-IO3, two clock cycles per byte.

Figure 10.24 Read Any Register, QPI Mode, CR2[7] = 0, Command Sequence

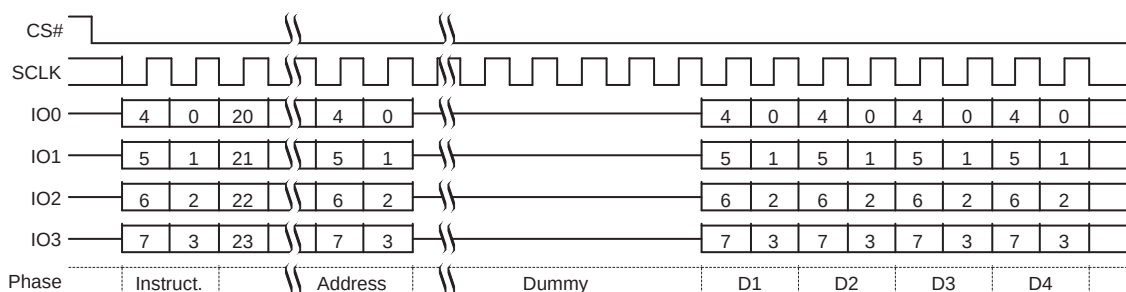
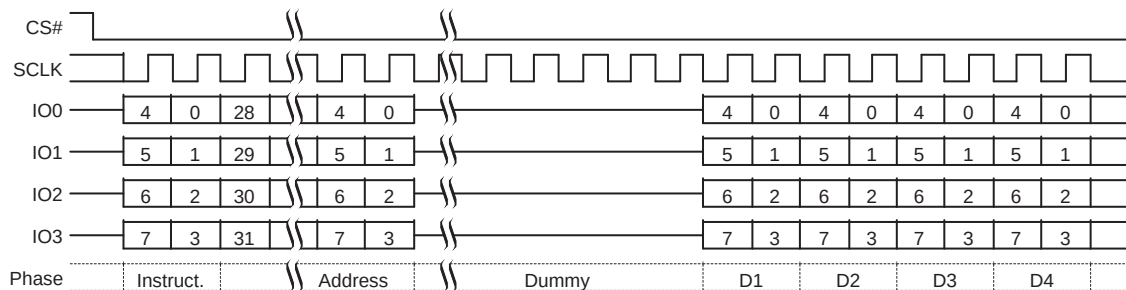


Figure 10.25 Read Any Register, QPI Mode, CR2[7] = 1 Command Sequence



10.3.13 Write Any Register (WRAR 71h)

The Write Any Register (WRAR) command provides a way to write any device register - non-volatile or volatile. The instruction is followed by a 3- or 4-byte address (depending on the address length configuration CR2V[7], followed by one byte of data to write in the address selected register.

Before the WRAR command can be accepted by the device, a Write Enable (WREN) command must be issued and decoded by the device, which sets the Write Enable Latch (WEL) in the Status Register to enable any write operations. The WIP bit in SR1V may be checked to determine when the operation is completed. The P_ERR and E_ERR bits in SR1V may be checked to determine if any error occurred during the operation.

Some registers have a mixture of bit types and individual rules controlling which bits may be modified. Some bits are read only, some are OTP.

Read only bits are never modified and the related bits in the WRAR command data byte are ignored without setting a program or erase error indication (P_ERR or E_ERR in SR1V). Hence, the value of these bits in the WRAR data byte do not matter.

OTP bits may only be programmed to the level opposite of their default state. Writing of OTP bits back to their default state is ignored and no error is set.

Non-Volatile bits which are changed by the WRAR data, require non-volatile register write time (t_{WV}) to be updated. The update process involves an erase and a program operation on the non-volatile register bits. If either the erase or program portion of the update fails the related error bit and WIP in SR1V will be set to 1.

Volatile bits which are changed by the WRAR data, require the volatile register write time (t_{CS}) to be updated.

Status Register 1 may be repeatedly read (polled) to monitor the Write-In-Progress (WIP) bit (SR1V[0]) and the error bits (SR1V[6,5]) to determine when the register write is completed or failed. If there is a write failure, the clear status command is used to clear the error status and enable the device to return to standby state.

However, the PPBL register can not be written by the WRAR command. Only the PPB Lock Bit Write (PLBWR) command can write the PPBL register.

The command sequence and behavior is the same as the PP or 4PP command with only a single byte of data provided. See [Section 10.5.2, Page Program \(PP 02h or 4PP 12h\) on page 114](#).

The address map of the registers is the same as shown for [Section 10.3.12, Read Any Register \(RDAR 65h\) on page 101](#).

10.3.14 Set Burst Length (SBL C0h)

The Set Burst Length (SBL) command is used to configure the Burst Wrap feature. Burst Wrap is used in conjunction with Quad I/O Read and DDR Quad I/O Read, in legacy SPI or QPI Mode, to access a fixed length and alignment of data. Certain applications can benefit from this feature by improving the overall system code execution performance. The Burst Wrap feature allows applications that use cache, to start filling a cache line with instruction or data from a critical address first, then fill the remainder of the cache line afterwards within a fixed length (8/16/32/64-bytes) of data, without issuing multiple read commands.

The Set Burst Length (SBL) command writes the CR4V register to enable or disable the wrapped read feature and set the wrap boundary. When enabled the wrapped read feature changes the related read commands from sequentially reading until the command ends, to reading sequentially wrapped within a group of bytes.

When CR4V[4]=1, the wrap mode is not enabled and unlimited length sequential read is performed.

When CR4V[4]=0, the wrap mode is enabled and a fixed length and aligned group of 8, 16, 32, or 64 bytes is read starting at the byte address provided by the read command and wrapping around at the group alignment boundary.

The group of bytes is of length and aligned on an 8-, 16-, 32-, or 64-byte boundary. CR4V[1:0] selects the boundary. See [Configuration Register 4 Volatile \(CR4V\) on page 72](#).

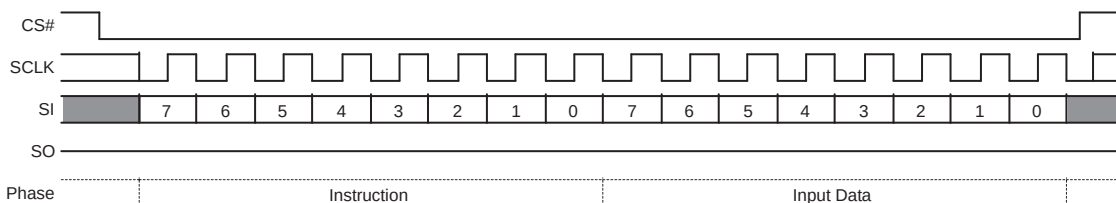
The starting address of the read command selects the group of bytes and the first data returned is the addressed byte. Bytes are then read sequentially until the end of the group boundary is reached. If the read continues the address wraps to the beginning of the group and continues to read sequentially. This wrapped read sequence continues until the command is ended by CS# returning high.

Table 10.4 Example Burst Wrap Sequences

CR4V[4,1:0] Value (Hex)	Wrap Boundary (Bytes)	Start Address (Hex)	Address Sequence (Hex)
1X	Sequential	XXXXXX03	03, 04, 05, 06, 07, 08, 09, 0A, 0B, 0C, 0D, 0E, 0F, 10, 11, 12, 13, 14, 15, 16, 17, 18, ...
00	8	XXXXXX00	00, 01, 02, 03, 04, 05, 06, 07, 00, 01, 02, ...
00	8	XXXXXX07	07, 00, 01, 02, 03, 04, 05, 06, 07, 00, 01, ...
01	16	XXXXXX02	02, 03, 04, 05, 06, 07, 08, 09, 0A, 0B, 0C, 0D, 0E, 0F, 00, 01, 02, 03, ...
01	16	XXXXXX0C	0C, 0D, 0E, 0F, 00, 01, 02, 03, 02, 03, 04, 05, 06, 07, 08, 09, 0A, 0B, 0C, 0D, 0E, ...
02	32	XXXXXX0A	0A, 0B, 0C, 0D, 0E, 0F, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 1A, 1B, 1C, 1D, 1E, 1F, 00, 01, 02, 03, 04, 05, 06, 07, 08, 09, 0A, 0B, 0C, 0D, 0E, 0F, ...
02	32	XXXXXX1E	1E, 1F, 00, 01, 02, 03, 04, 05, 06, 07, 08, 09, 0A, 0B, 0C, 0D, 0E, 0F, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 1A, 1B, 1C, 1D, 1E, 1F, 00, ...
03	64	XXXXXX03	03, 04, 05, 06, 07, 08, 09, 0A, 0B, 0C, 0D, 0E, 0F, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 1A, 1B, 1C, 1D, 1E, 1F, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 2A, 2B, 2C, 2D, 2E, 2F, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 3A, 3B, 3C, 3D, 3E, 3F, 00, 01, 02 ...
03	64	XXXXXX2E	2E, 2F, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 3A, 3B, 3C, 3D, 3E, 3F, 00, 01, 02, 03, 04, 05, 06, 07, 08, 09, 0A, 0B, 0C, 0D, 0E, 0F, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 1A, 1B, 1C, 1D, 1E, 1F, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 2A, 2B, 2C, 2D, 2E, 2F, ...

The Power-On Reset, hardware reset, or software reset default burst length can be changed by programming CR4NV with the desired value using the WRAR command.

Figure 10.26 Set Burst Length Command Sequence



10.4 Read Memory Array Commands

Read commands for the main flash array provide many options for prior generation SPI compatibility or enhanced performance SPI:

- Some commands transfer address or data on each rising edge of SCK. These are called Single Data Rate commands (SDR).
- Some SDR commands transfer address one bit per rising edge of SCK and return data 1bit of data per rising edge of SCK. These are called Single width commands.
- Some SDR commands transfer both address and data two or four bits per rising edge of SCK. These are called Dual I/O for two bits, Quad I/O, and QPI for four bits. QPI also transfers instruction four bits per rising edge.
- Some commands transfer address and data on both the rising edge and falling edge of SCK. These are called Double Data Rate (DDR) commands.
- There are DDR commands for 4 bits of address or data per SCK edge. These are called Quad I/O DDR and QPI DDR for four bit per edge transfer.

All of these commands, except QPI Read, begin with an instruction code that is transferred one bit per SCK rising edge. QPI Read transfers the instruction four bits per SCK rising edge. The instruction is followed by either a 3- or 4-byte address transferred at SDR or DDR. Commands transferring address or data 2 or 4 bits per clock edge are called Multiple I/O (MIO) commands. For S25FS-S family devices at 256-Mbits or higher density, the traditional SPI 3-byte addresses are unable to directly address all locations in the memory array. Separate 4-byte address read commands are provided for access to the entire address space. These devices may be configured to take a 4-byte address from the host system with the traditional 3-byte address commands. The 4-byte address mode for traditional commands is activated by setting the Address Length bit

in Configuration Register 2 to 0. In the FS128S, higher order address bits above A23 in the 4-byte address commands, or commands using 4-byte address mode are not relevant and are ignored because the flash array is only 128 Mbits in size.

The Quad I/O and QPI commands provide a performance improvement option controlled by mode bits that are sent following the address bits. The mode bits indicate whether the command following the end of the current read will be another read of the same type, without an instruction at the beginning of the read. These mode bits give the option to eliminate the instruction cycles when doing a series of Quad Read accesses.

Some commands require delay cycles following the address or mode bits to allow time to access the memory array - read latency. The delay or read latency cycles are traditionally called dummy cycles. The dummy cycles are ignored by the memory thus any data provided by the host during these cycles is "don't care" and the host may also leave the SI signal at high impedance during the dummy cycles. When MIO commands are used the host must stop driving the IO signals (outputs are high impedance) before the end of last dummy cycle. When DDR commands are used the host must not drive the I/O signals during any dummy cycle. The number of dummy cycles varies with the SCK frequency or performance option selected via the Configuration Register 2 (CR2V[3:0]) Latency Code. Dummy cycles are measured from SCK falling edge to next SCK falling edge. SPI outputs are traditionally driven to a new value on the falling edge of each SCK. Zero dummy cycles means the returning data is driven by the memory on the same falling edge of SCK that the host stops driving address or mode bits.

The DDR commands may optionally have an 8-edge Data Learning Pattern (DLP) driven by the memory, on all data outputs, in the dummy cycles immediately before the start of data. The DLP can help the host memory controller determine the phase shift from SCK to data edges so that the memory controller can capture data at the center of the data eye.

When using SDR I/O commands at higher SCK frequencies (>50 MHz), an LC that provides one or more dummy cycles should be selected to allow additional time for the host to stop driving before the memory starts driving data, to minimize I/O driver conflict. When using DDR I/O commands with the DLP enabled, an LC that provides five or more dummy cycles should be selected to allow one cycle of additional time for the host to stop driving before the memory starts driving the 4-cycle DLP.

Each read command ends when CS# is returned High at any point during data return. CS# must not be returned High during the mode or dummy cycles before data returns as this may cause mode bits to be captured incorrectly; making it indeterminate as to whether the device remains in Continuous Read mode.

10.4.1 Read (Read 03h or 4READ 13h)

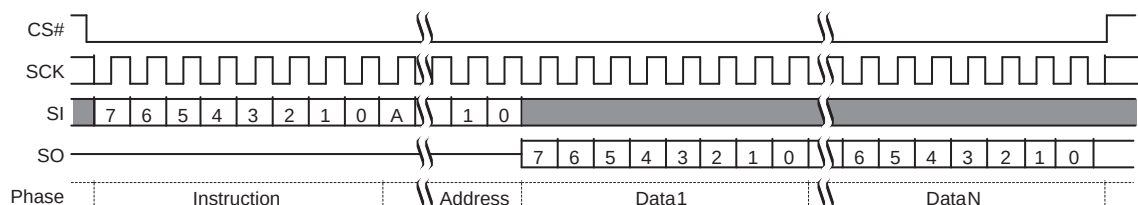
The instruction

- 03h (CR2V[7]=0) is followed by a 3-byte address (A23-A0) or
- 03h (CR2V[7]=1) is followed by a 4-byte address (A31-A0) or
- 13h is followed by a 4-byte address (A31-A0)

Then the memory contents, at the address given, are shifted out on SO. The maximum operating clock frequency for the Read command is 50 MHz.

The address can start at any byte location of the memory array. The address is automatically incremented to the next higher address in sequential order after each byte of data is shifted out. The entire memory can therefore be read out with one single read instruction and address 000000h provided. When the highest address is reached, the address counter will wrap around and roll back to 000000h, allowing the read sequence to be continued indefinitely.

Figure 10.27 Read Command Sequence (3-Byte Address, 03h or 13h)



Note:

1. A = MSB of address = 23 for CR2V[7]=0, or 31 for CR2V[7]=1 or command 13h.

10.4.2 Fast Read (FAST_READ 0Bh or 4FAST_READ 0Ch)

The instruction

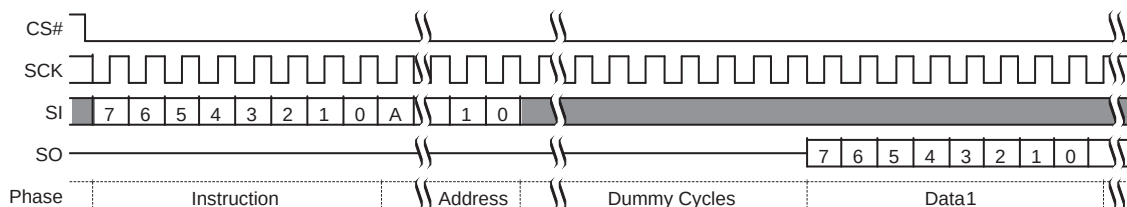
- 0Bh (CR2V[7]=0) is followed by a 3-byte address (A23-A0) or
- 0Bh (CR2V[7]=1) is followed by a 4-byte address (A31-A0) or
- 0Ch is followed by a 4-byte address (A31-A0)

The address is followed by dummy cycles depending on the latency code set in the Configuration Register CR2V[3:0]. The dummy cycles allow the device internal circuits additional time for accessing the initial address location. During the dummy cycles the data value on SO is “don’t care” and may be high impedance. Then the memory contents, at the address given, are shifted out on SO.

The maximum operating clock frequency for Fast Read command is 133 MHz.

The address can start at any byte location of the memory array. The address is automatically incremented to the next higher address in sequential order after each byte of data is shifted out. The entire memory can therefore be read out with one single read instruction and address 000000h provided. When the highest address is reached, the address counter will wrap around and roll back to 000000h, allowing the read sequence to be continued indefinitely.

Figure 10.28 Fast Read (FAST_READ) Command Sequence (3-Byte Address, 0Bh [CR2V[7]=0])



Note:

1. A = MSB of address = 23 for CR2V[7]=0, or 31 for CR2V[7]=1 or command 0Ch.

10.4.3 Dual I/O Read (DIOR BBh or 4DIOR BCh)

The instruction

- BBh (CR2V[7]=0) is followed by a 3-byte address (A23-A0) or
- BBh (CR2V[7]=1) is followed by a 4-byte address (A31-A0) or
- BCh is followed by a 4-byte address (A31-A0)

The Dual I/O Read commands improve throughput with two I/O signals — IO0 (SI) and IO1 (SO). This command takes input of the address and returns read data two bits per SCK rising edge. In some applications, the reduced address input and data output time might allow for code execution in place (XIP) i.e. directly from the memory device.

The maximum operating clock frequency for Dual I/O Read is 133 MHz.

The Dual I/O Read command has Continuous Read mode bits that follow the address so, a series of Dual I/O Read commands may eliminate the 8-bit instruction after the first Dual I/O Read command sends a mode bit pattern of Axh that indicates the following command will also be a Dual I/O Read command. The first Dual I/O Read command in a series starts with the 8-bit instruction, followed by address, followed by four cycles of mode bits, followed by an optional latency period. If the mode bit pattern is Axh the next command is assumed to be an additional Dual I/O Read command that does not provide instruction bits. That command starts with address, followed by mode bits, followed by optional latency.

Variable latency may be added after the mode bits are shifted into SI and SO before data begins shifting out of IO0 and IO1. This latency period (dummy cycles) allows the device internal circuitry enough time to access data at the initial address. During the dummy cycles, the data value on SI and SO are “don’t care” and may be high impedance. The number of dummy cycles is determined by the frequency of SCK. The latency is configured in CR2V[3:0].

The Continuous Read feature removes the need for the instruction bits in a sequence of read accesses and greatly improves code execution (XIP) performance. The upper nibble (bits 7-4) of the Mode bits control the

length of the next Dual I/O Read command through the inclusion or exclusion of the first byte instruction code. The lower nibble (bits 3-0) of the Mode bits are “don’t care” (“x”) and may be high impedance. If the Mode bits equal Axh, then the device remains in Dual I/O Continuous Read mode and the next address can be entered (after CS# is raised high and then asserted low) without the BBh or BCh instruction, as shown in [Figure 10.31 on page 108](#); thus, eliminating eight cycles of the command sequence. The following sequences will release the device from Dual I/O Continuous Read mode; after which, the device can accept standard SPI commands:

1. During the Dual I/O Continuous Read command sequence, if the Mode bits are any value other than Axh, then the next time CS# is raised high the device will be released from Dual I/O continuous read mode.
2. Send the Mode Reset command.

Note that the four mode bit cycles are part of the device's internal circuitry latency time to access the initial address after the last address cycle that is clocked into IO0 (SI) and IO1 (SO).

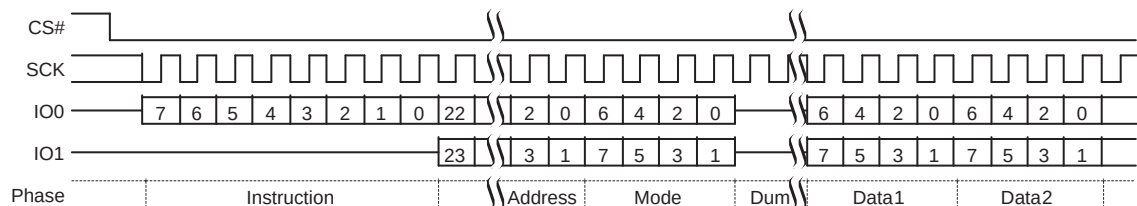
It is important that the I/O signals be set to high-impedance at or before the falling edge of the first data out clock. At higher clock speeds the time available to turn off the host outputs before the memory device begins to drive (bus turn around) is diminished. It is allowed and may be helpful in preventing I/O signal contention, for the host system to turn off the I/O signal outputs (make them high impedance) during the last two “don’t care” mode cycles or during any dummy cycles.

Following the latency period the memory content, at the address given, is shifted out two bits at a time through IO0 (SI) and IO1 (SO). Two bits are shifted out at the SCK frequency at the falling edge of SCK signal.

The address can start at any byte location of the memory array. The address is automatically incremented to the next higher address in sequential order after each byte of data is shifted out. The entire memory can therefore be read out with one single read instruction and address 000000h provided. When the highest address is reached, the address counter will wrap around and roll back to 000000h, allowing the read sequence to be continued indefinitely.

CS# should not be driven high during mode or dummy bits as this may make the mode bits indeterminate.

Figure 10.29 Dual I/O Read Command Sequence (3-Byte Address, BBh [CR2V[7]=0])



Note:

1. Least significant 4 bits of Mode are don't care and it is optional for the host to drive these bits. The host may turn off drive during these cycles to increase bus turn around time between Mode bits from host and returning data from the memory.

Figure 10.30 Dual I/O Read Command Sequence (4-Byte Address, BBh [CR2V[7]=1])

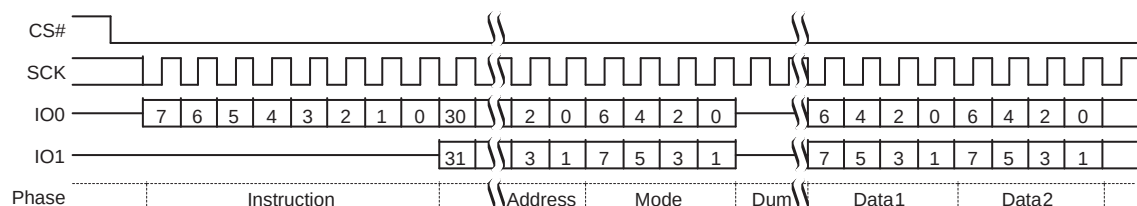
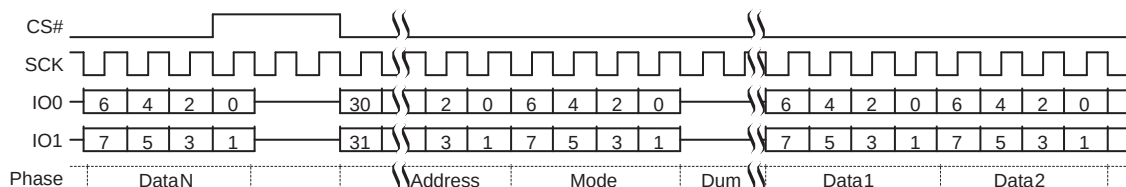


Figure 10.31 Dual I/O Continuous Read Command Sequence (4-Byte Address [CR2V[7]=1])


10.4.4 Quad I/O Read (QIOR EBh or 4QIOR ECh)

The instruction

- EBh (CR2V[7]=0) is followed by a 3-byte address (A23-A0) or
- EBh (CR2V[7]=1) is followed by a 4-byte address (A31-A0) or
- ECh is followed by a 4-byte address (A31-A0)

The Quad I/O Read command improves throughput with four I/O signals — IO0-IO3. It allows input of the address bits four bits per serial SCK clock. In some applications, the reduced instruction overhead might allow for code execution (XIP) directly from S25FS-S family devices. The Quad bit of the Configuration Register must be set (CR1V[1]=1) to enable the Quad capability of S25FS-S family devices.

The maximum operating clock frequency for Quad I/O Read is 133MHz.

For the Quad I/O Read command, there is a latency required after the mode bits (described below) before data begins shifting out of IO0-IO3. This latency period (i.e., dummy cycles) allows the device's internal circuitry enough time to access data at the initial address. During latency cycles, the data value on IO0-IO3 are "don't care" and may be high impedance. The number of dummy cycles is determined by the frequency of SCK. The latency is configured in CR2V[3:0].

Following the latency period, the memory contents at the address given, is shifted out four bits at a time through IO0-IO3. Each nibble (4 bits) is shifted out at the SCK frequency by the falling edge of the SCK signal.

The address can start at any byte location of the memory array. The address is automatically incremented to the next higher address in sequential order after each byte of data is shifted out. The entire memory can therefore be read out with one single read instruction and address 000000h provided. When the highest address is reached, the address counter will wrap around and roll back to 000000h, allowing the read sequence to be continued indefinitely.

Address jumps can be done without the need for additional Quad I/O Read instructions. This is controlled through the setting of the Mode bits (after the address sequence, as shown in [Figure 10.32 on page 109](#) or [Figure 10.35 on page 110](#)). This added feature removes the need for the instruction sequence and greatly improves code execution (XIP). The upper nibble (bits 7-4) of the Mode bits control the length of the next Quad I/O instruction through the inclusion or exclusion of the first byte instruction code. The lower nibble (bits 3-0) of the Mode bits are "don't care" ("x"). If the Mode bits equal Axxh, then the device remains in Quad I/O High Performance Read mode and the next address can be entered (after CS# is raised high and then asserted low) without requiring the EBh or ECh instruction, as shown in [Figure 10.34 on page 109](#) or [Figure 10.36 on page 110](#); thus, eliminating eight cycles for the command sequence. The following sequences will release the device from Quad I/O High Performance Read mode; after which, the device can accept standard SPI commands:

1. During the Quad I/O Read Command Sequence, if the Mode bits are any value other than Axxh, then the next time CS# is raised high the device will be released from Quad I/O High Performance Read mode.
2. Send the Mode Reset command.

Note that the two mode bit clock cycles and additional wait states (i.e., dummy cycles) allow the device's internal circuitry latency time to access the initial address after the last address cycle that is clocked into IO0-IO3.

It is important that the IO0-IO3 signals be set to high-impedance at or before the falling edge of the first data out clock. At higher clock speeds the time available to turn off the host outputs before the memory device begins to drive (bus turn around) is diminished. It is allowed and may be helpful in preventing IO0-IO3 signal

contention, for the host system to turn off the IO0-IO3 signal outputs (make them high impedance) during the last “don’t care” mode cycle or during any dummy cycles.

CS# should not be driven high during mode or dummy bits as this may make the mode bits indeterminate.

In QPI Mode (CR2V[6]=1) the Quad I/O instructions are sent 4 bits per SCK rising edge. The remainder of the command protocol is identical to the Quad I/O commands.

Figure 10.32 Quad I/O Read Command Sequence (3-Byte Address, EBh [CR2V[7]=0])

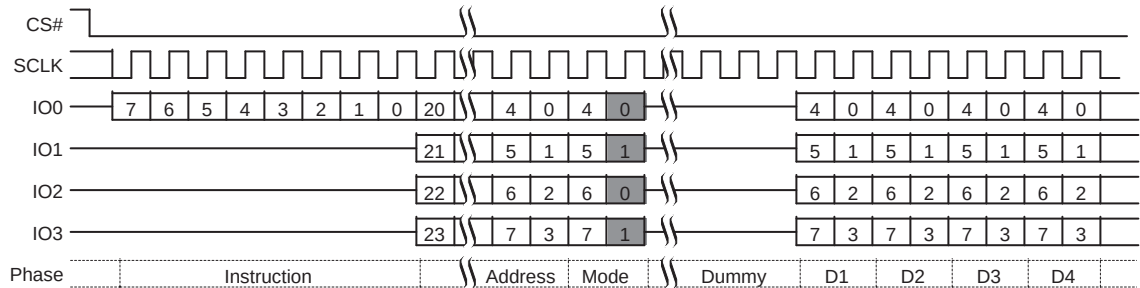


Figure 10.33 Quad I/O Read Command Sequence (3-Byte Address, EBh [CR2V[7]=0]) QPI Mode

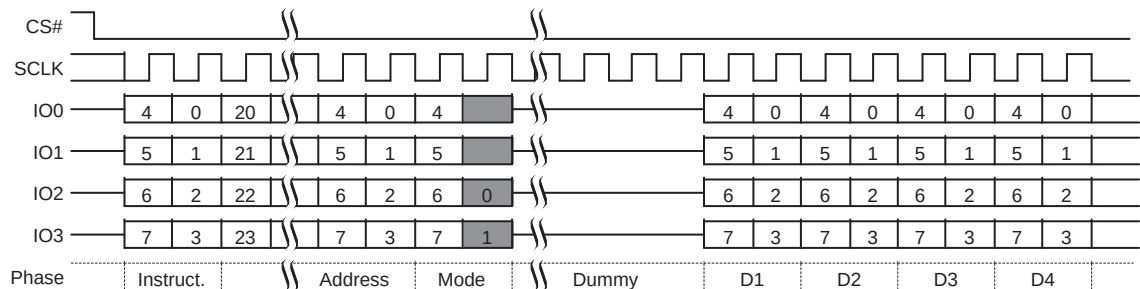


Figure 10.34 Continuous Quad I/O Read Command Sequence (3-Byte Address)

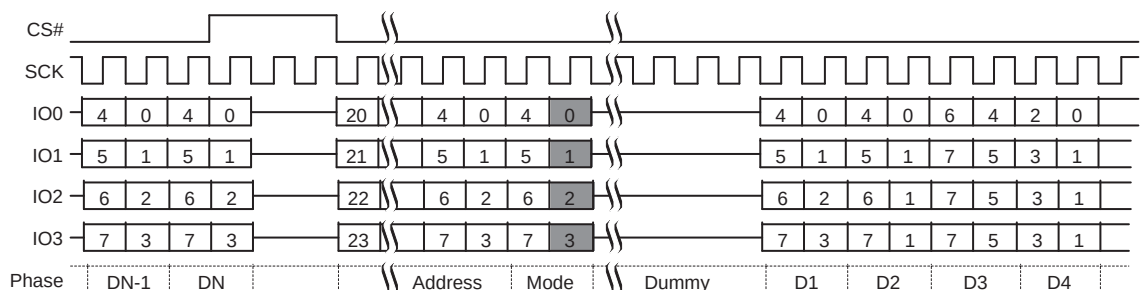
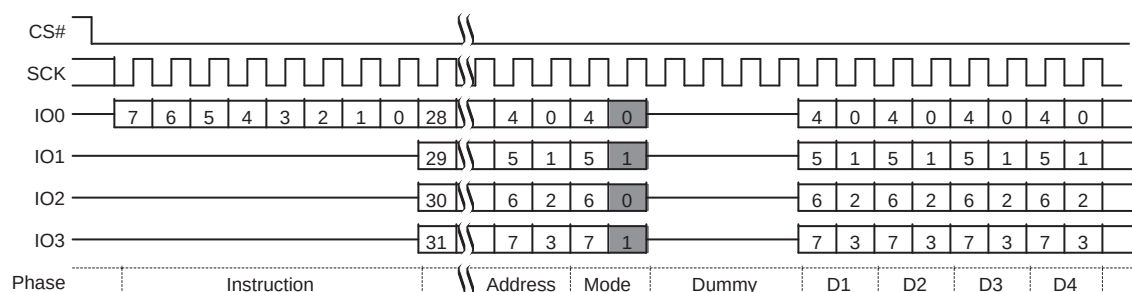
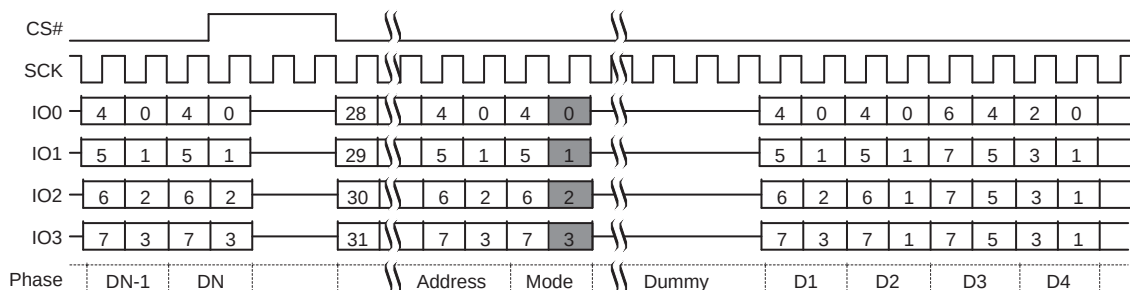
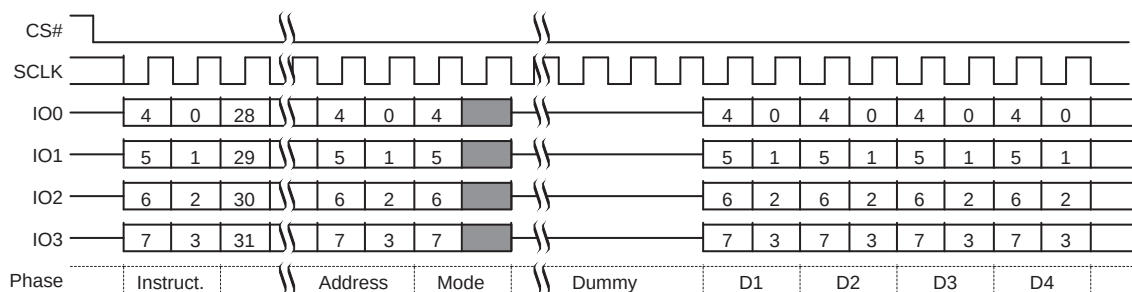


Figure 10.35 Quad I/O Read Command Sequence (4-Byte Address, ECh or EBh [CR2V[7]=1])

Figure 10.36 Continuous Quad I/O Read Command Sequence (4-Byte Address)

Note:

1. The same sequence is used in QPI Mode

Figure 10.37 Quad I/O Read Command Sequence (4-Byte Address, ECh or EBh [CR2V[7]=1]) QPI Mode


10.4.5 DDR Quad I/O Read (EDh, EEh)

The DDR Quad I/O Read command improves throughput with four I/O signals - IO0-IO3. It is similar to the Quad I/O Read command but allows input of the address four bits on every edge of the clock. In some applications, the reduced instruction overhead might allow for code execution (XIP) directly from S25FS-S family devices. The Quad bit of the Configuration Register must be set (CR1V[1]=1) to enable the Quad capability.

The instruction

- EDh (CR2V[7]=0) is followed by a 3-byte address (A23-A0) or
- EDh (CR2V[7]=1) is followed by a 4-byte address (A31-A0) or
- EEh is followed by a 4-byte address (A31-A0)

The address is followed by mode bits. Then the memory contents, at the address given, is shifted out, in a DDR fashion, with four bits at a time on each clock edge through IO0-IO3.

The maximum operating clock frequency for DDR Quad I/O Read command is 80 MHz.

For DDR Quad I/O Read, there is a latency required after the last address and mode bits are shifted into the IO0-IO3 signals before data begins shifting out of IO0-IO3. This latency period (dummy cycles) allows the device's internal circuitry enough time to access the initial address. During these latency cycles, the data value on IO0-IO3 are "don't care" and may be high impedance. When the Data Learning Pattern (DLP) is enabled the host system must not drive the IO signals during the dummy cycles. The IO signals must be left high impedance by the host so that the memory device can drive the DLP during the dummy cycles.

The number of dummy cycles is determined by the frequency of SCK. The latency is configured in CR2V[3:0].

Mode bits allow a series of Quad I/O DDR commands to eliminate the 8-bit instruction after the first command sends a complementary mode bit pattern, as shown in [Figure 10.38](#) and [Figure 10.40](#). This feature removes the need for the 8-bit SDR instruction sequence and dramatically reduces initial access times (improves XIP performance). The Mode bits control the length of the next DDR Quad I/O Read operation through the inclusion or exclusion of the first byte instruction code. If the upper nibble (IO[7:4]) and lower nibble (IO[3:0]) of the Mode bits are complementary (i.e. 5h and Ah) the device transitions to Continuous DDR Quad I/O Read mode and the next address can be entered (after CS# is raised high and then asserted low) without requiring the EDh or EEh instruction, as shown in [Figure 10.39 on page 112](#) and [Figure 10.42 on page 113](#) thus, eliminating eight cycles from the command sequence. The following sequences will release the device from Continuous DDR Quad I/O Read mode; after which, the device can accept standard SPI commands:

1. During the DDR Quad I/O Read Command Sequence, if the Mode bits are not complementary the next time CS# is raised high and then asserted low the device will be released from DDR Quad I/O Read mode.
2. Send the Mode Reset command.

The address can start at any byte location of the memory array. The address is automatically incremented to the next higher address in sequential order after each byte of data is shifted out. The entire memory can therefore be read out with one single read instruction and address 000000h provided. When the highest address is reached, the address counter will wrap around and roll back to 000000h, allowing the read sequence to be continued indefinitely.

CS# should not be driven high during mode or dummy bits as this may make the mode bits indeterminate. Note that the memory devices may drive the IOs with a preamble prior to the first data value. The preamble is a Data Learning Pattern (DLP) that is used by the host controller to optimize data capture at higher frequencies. The preamble drives the IO bus for the four clock cycles immediately before data is output. The host must be sure to stop driving the IO bus prior to the time that the memory starts outputting the preamble.

The preamble is intended to give the host controller an indication about the round trip time from when the host drives a clock edge to when the corresponding data value returns from the memory device. The host controller will skew the data capture point during the preamble period to optimize timing margins and then use the same skew time to capture the data during the rest of the read operation. The optimized capture point will be determined during the preamble period of every read operation. This optimization strategy is intended to compensate for both the PVT (process, voltage, temperature) of both the memory device and the host controller as well as any system level delays caused by flight time on the PCB.

Although the data learning pattern (DLP) is programmable, the following example shows example of the DLP of 34h. The DLP 34h (or 00110100) will be driven on each of the active outputs (i.e. all four SIOs). This

pattern was chosen to cover both “DC” and “AC” data transition scenarios. The two DC transition scenarios include data low for a long period of time (two half clocks) followed by a high going transition (001) and the complementary low going transition (110). The two AC transition scenarios include data low for a short period of time (one half clock) followed by a high going transition (101) and the complementary low going transition (010). The DC transitions will typically occur with a starting point closer to the supply rail than the AC transitions that may not have fully settled to their steady state (DC) levels. In many cases the DC transitions will bound the beginning of the data valid period and the AC transitions will bound the ending of the data valid period. These transitions will allow the host controller to identify the beginning and ending of the valid data eye. Once the data eye has been characterized the optimal data capture point can be chosen. See [SPI DDR Data Learning Registers on page 75](#) for more details.

In QPI Mode (CR2V[6]=1) the DDR Quad I/O instructions are sent 4 bits per SCK rising edge. The remainder of the command protocol is identical to the DDR Quad I/O commands.

Figure 10.38 DDR Quad I/O Read Initial Access (3-Byte Address, EDh [CR2V[7]=0])

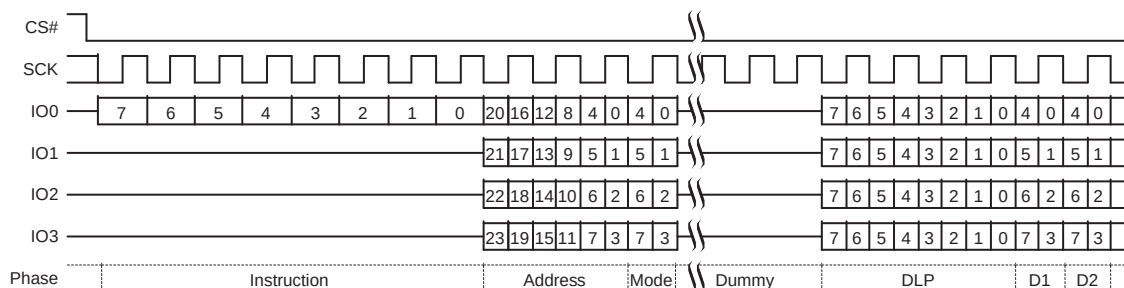


Figure 10.39 Continuous DDR Quad I/O Read Subsequent Access (3-Byte Address)

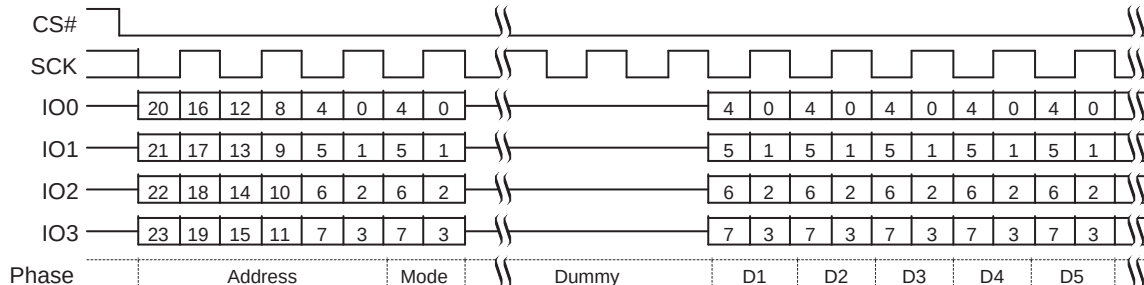
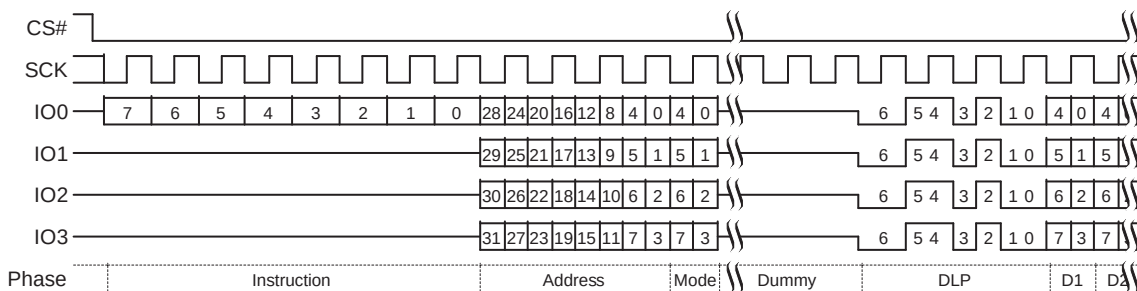


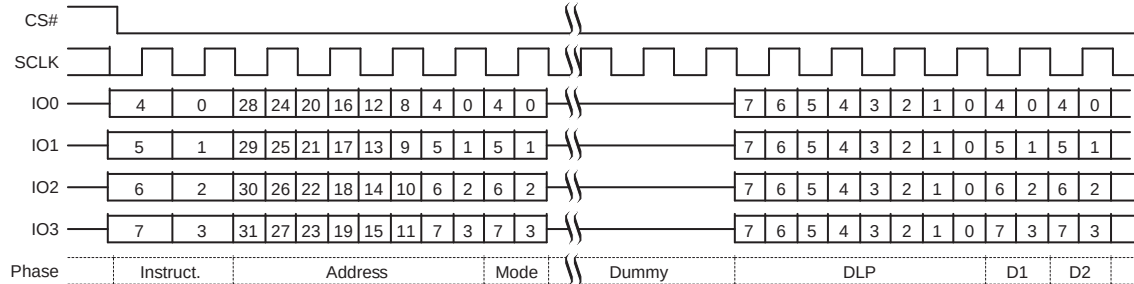
Figure 10.40 DDR Quad I/O Read Initial Access (4-Byte Address, EEh or EDh [CR2V[7]=1])



Note:

1. Example DLP of 34h (or 00110100).

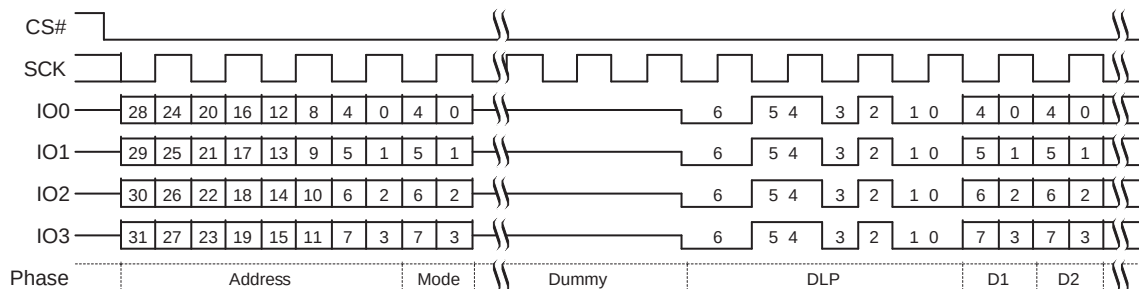
Figure 10.41 DDR Quad I/O Read Initial Access
(4-Byte Address, EEh or EDh [CR2V[7]=1]) QPI Mode



Note:

1. Example DLP of 34h (or 00110100).

Figure 10.42 Continuous DDR Quad I/O Read Subsequent Access (4-Byte Address)



Note:

1. Example DLP of 34h (or 00110100).

10.5 Program Flash Array Commands

10.5.1 Program Granularity

10.5.1.1 Page Programming

Page Programming is done by loading a Page Buffer with data to be programmed and issuing a programming command to move data from the buffer to the memory array. This sets an upper limit on the amount of data that can be programmed with a single programming command. Page Programming allows up to a page size (either 256 or 512 bytes) to be programmed in one operation. The page size is determined by the Configuration Register bit CR3V[4]. The page is aligned on the page size address boundary. It is possible to program from one bit up to a page size in each Page programming operation. It is recommended that a multiple of 16-byte length and aligned Program Blocks be written. For the very best performance, programming should be done in full pages of 512 bytes aligned on 512-byte boundaries with each Page being programmed only once.

10.5.1.2 Single Byte Programming

Single Byte Programming allows full backward compatibility to the legacy standard SPI Page Programming (PP) command by allowing a single byte to be programmed anywhere in the memory array.

10.5.2 Page Program (PP 02h or 4PP 12h)

The Page Program (PP) command allows bytes to be programmed in the memory (changing bits from 1 to 0). Before the Page Program (PP) commands can be accepted by the device, a Write Enable (WREN) command must be issued and decoded by the device. After the Write Enable (WREN) command has been decoded successfully, the device sets the Write Enable Latch (WEL) in the Status Register to enable any write operations.

The instruction

- 02h (CR2V[7]=0) is followed by a 3-byte address (A23-A0) or
- 02h (CR2V[7]=1) is followed by a 4-byte address (A31-A0) or
- 12h is followed by a 4-byte address (A31-A0)

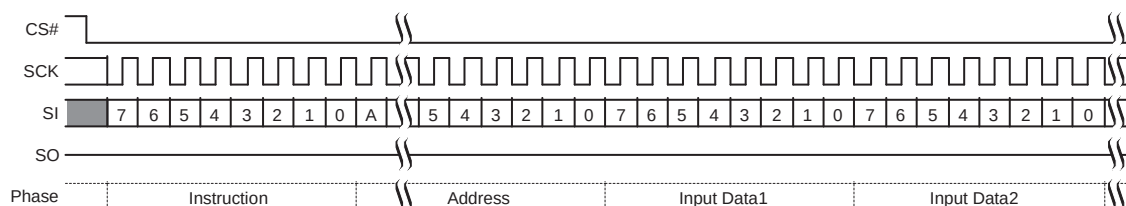
and at least one data byte on SI. Depending on CR3V[4], the page size can either be 256 or 512 bytes. Up to a page can be provided on SI after the 3-byte address with instruction 02h or 4-byte address with instruction 12h has been provided.

If more data is sent to the device than the space between the starting address and the page aligned end boundary, the data loading sequence will wrap from the last byte in the page to the zero byte location of the same page and begin overwriting any data previously loaded in the page. The last page worth of data is programmed in the page. This is a result of the device being equipped with a page program buffer that is only page size in length. If less than a page of data is sent to the device, these data bytes will be programmed in sequence, starting at the provided address within the page, without having any affect on the other bytes of the same page.

Using the Page Program (PP) command to load an entire page, within the page boundary, will save overall programming time versus loading less than a page into the program buffer.

The programming process is managed by the flash memory device internal control logic. After a programming command is issued, the programming operation status can be checked using the Read Status Register 1 command. The WIP bit (SR1V[0]) will indicate when the programming operation is completed. The P_ERR bit (SR1V[6]) will indicate if an error occurs in the programming operation that prevents successful completion of programming. This includes attempted programming of a protected area.

Figure 10.43 Page Program (PP 02h or 4PP 12h) Command Sequence

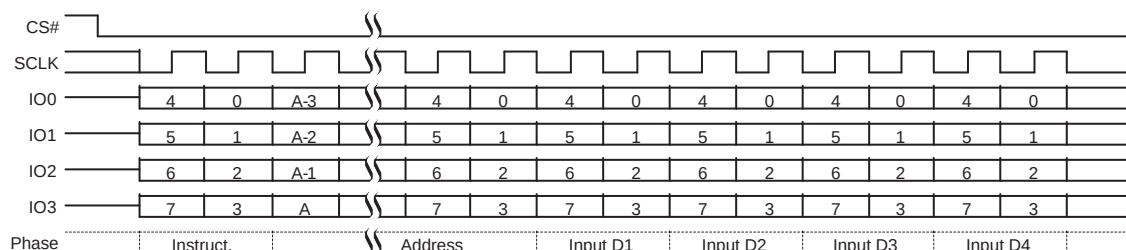


Note:

1. A = MSB of address = A23 for PP 02h, or A31 for 4PP 12h.

This command is also supported in QPI Mode. In QPI Mode the instruction is shifted in on IO0-IO3, two clock cycles per byte.

Figure 10.44 Page Program (PP 02h or 4PP 12h) QPI Mode Command Sequence



Note:

1. A = MSB of address = A23 for PP 02h, or A31 for 4PP 12h.

10.6 Erase Flash Array Commands

10.6.1 Parameter 4-kB Sector Erase (P4E 20h or 4P4E 21h)

The main flash array address map may be configured to overlay 4-kB parameter sectors over the lowest address portion of the lowest address uniform sector (bottom parameter sectors) or over the highest address portion of the highest address uniform sector (top parameter sectors). The main flash array address map may also be configured to have only uniform size sectors. The parameter sector configuration is controlled by the configuration bit CR3V[3]. The P4E and 4P4E commands are ignored when the device is configured for uniform sectors only (CR3V[3]=1).

The parameter 4-kB Sector Erase commands set all the bits of a 4-kB parameter sector to 1 (all bytes are FFh). Before the P4E or 4P4E command can be accepted by the device, a Write Enable (WREN) command must be issued and decoded by the device, which sets the Write Enable Latch (WEL) in the Status Register to enable any write operations.

The instruction

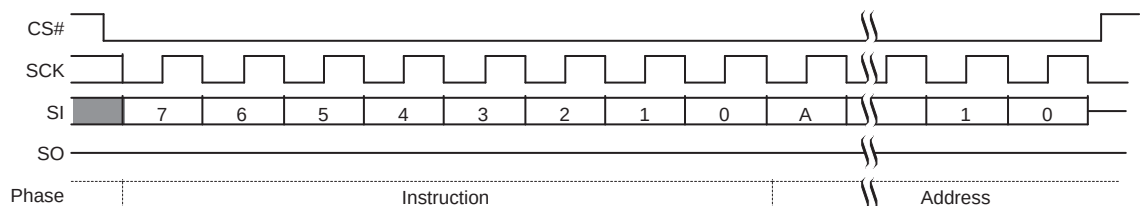
- 20h [CR2V[7]=0] is followed by a 3-byte address (A23-A0), or
- 20h [CR2V[7]=1] is followed by a 4-byte address (A31-A0), or
- 21h is followed by a 4-byte address (A31-A0)

CS# must be driven into the logic high state after the twenty-fourth or thirty-second bit of the address has been latched in on SI. This will initiate the beginning of internal erase cycle, which involves the pre-programming and erase of the chosen sector of the flash memory array. If CS# is not driven high after the last bit of address, the Sector Erase operation will not be executed.

As soon as CS# is driven high, the internal erase cycle will be initiated. With the internal erase cycle in progress, the user can read the value of the Write-In Progress (WIP) bit to determine when the operation has been completed. The WIP bit will indicate a 1 when the erase cycle is in progress and a 0 when the erase cycle has been completed.

A P4E or 4P4E command applied to a sector that has been write protected through the Block Protection bits or ASP, will not be executed and will set the E_ERR status. A P4E command applied to a sector that is larger than 4 kbytes will not be executed and will not set the E_ERR status.

Figure 10.45 Parameter Sector Erase (P4E 20h or 4P4E 21h) Command Sequence

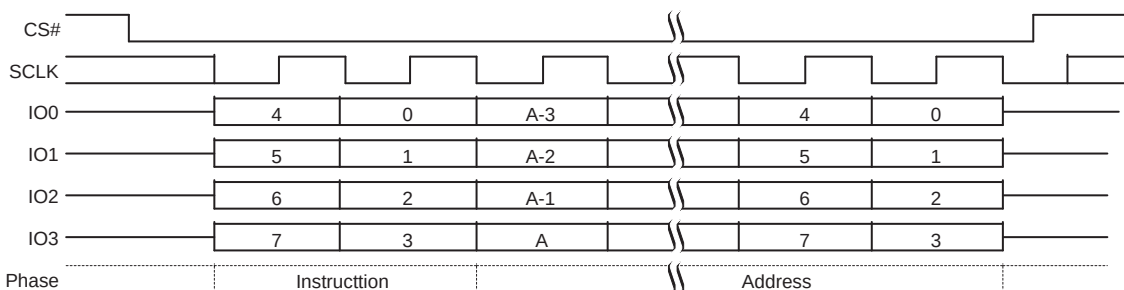


Note:

1. A = MSB of address = A23 for P4E 20h with CR2V[7]=0, or A31 for P4E 20h with CR2V[7]=1 or 4P4E 21h.

This command is also supported in QPI Mode. In QPI Mode the instruction is shifted in on IO0-IO3, two clock cycles per byte.

Figure 10.46 Parameter Sector Erase (P4E 20h or 4P4E 21h) QPI Mode Command Sequence



Note:

1. A = MSB of address = A23 for P4E 20h with CR2V[7]=0, or A31 for P4E 20h with CR2V[7]=1 or 4P4E 21h.

10.6.2 Sector Erase (SE D8h or 4SE DCh)

The Sector Erase (SE) command sets all bits in the addressed sector to 1 (all bytes are FFh). Before the Sector Erase (SE) command can be accepted by the device, a Write Enable (WREN) command must be issued and decoded by the device, which sets the Write Enable Latch (WEL) in the Status Register to enable any write operations.

The instruction

- D8h [CR2V[7]=0] is followed by a 3-byte address (A23-A0), or
- D8h [CR2V[7]=1] is followed by a 4-byte address (A31-A0), or
- DCh is followed by a 4-byte address (A31-A0)

CS# must be driven into the logic high state after the twenty-fourth or thirty-second bit of address has been latched in on SI. This will initiate the erase cycle, which involves the pre-programming and erase of the chosen sector. If CS# is not driven high after the last bit of address, the Sector Erase operation will not be executed.

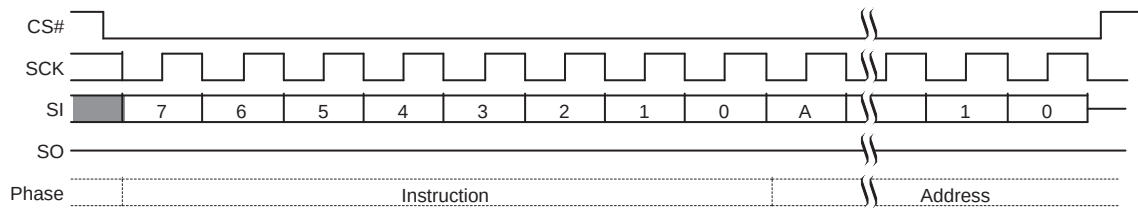
As soon as CS# is driven into the logic high state, the internal erase cycle will be initiated. With the internal erase cycle in progress, the user can read the value of the Write-In Progress (WIP) bit to check if the operation has been completed. The WIP bit will indicate a 1 when the erase cycle is in progress and a 0 when the erase cycle has been completed.

A Sector Erase (SE) command applied to a sector that has been Write Protected through the Block Protection bits or ASP, will not be executed and will set the E_ERR status.

A device configuration option (CR3V[1]) determines whether the SE command erases 64 kbytes or 256 kbytes. The option to use this command to always erase 256 kbytes provides for software compatibility with higher density and future S25FS family devices.

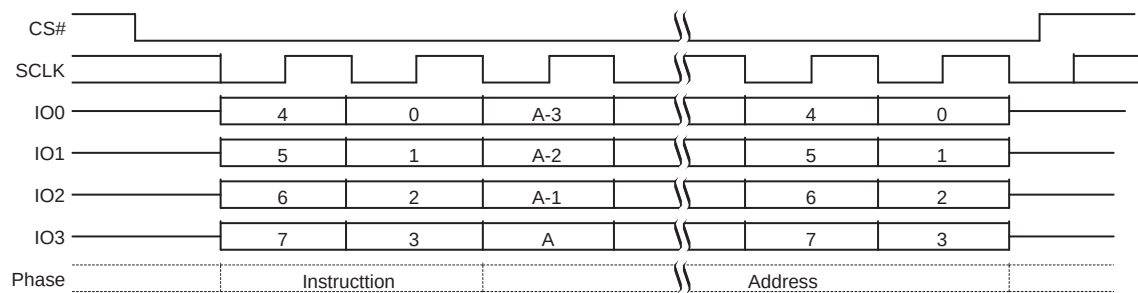
A device configuration option (CR3V[3]) determines whether 4-kB parameter sectors are in use. When CR3V[3] = 0, 4-kB parameter sectors overlay a portion of the highest or lowest address 32 kB of the device address space. If a Sector Erase command is applied to a 64-kB sector that is overlaid by 4-kB sectors, the overlaid 4-kB sectors are not affected by the erase. Only the visible (non-overlaid) portion of the 64-kB sector appears erased. Similarly if a Sector Erase command is applied to a 256-kB range that is overlaid by 4-kB sectors, the overlaid 4-kB sectors are not affected by the erase. When CR3V[3] = 1, there are no 4-kB parameter sectors in the device address space and the Sector Erase command always operates on fully visible 64-kB or 256-kB sectors.

ASP has a PPB and a DYB protection bit for each physical sector, including any 4-kB sectors. If a Sector Erase command is applied to a 256-kB range that includes a 64-kB protected physical sector, the erase will not be executed on the 256-kB range and will set the E_ERR status.

Figure 10.47 Sector Erase (SE D8h or 4SE DCh) Command Sequence**Note:**

1. A = MSB of address = A23 for SE D8h with CR2V[7]=0, or A31 for SE D8h with CR2V[7]=1 or 4P4E DCh.

This command is also supported in QPI Mode. In QPI Mode the instruction is shifted in on IO0-IO3, two clock cycles per byte.

Figure 10.48 Sector Erase (SE D8h or 4SE DCh) QPI Mode Command Sequence**Note:**

1. A = MSB of address = A23 for P4E 20h with CR2V[7]=0, or A31 for P4E 20h with CR2V[7]=1 or 4P4E 21h.

10.6.3 Bulk Erase (BE 60h or C7h)

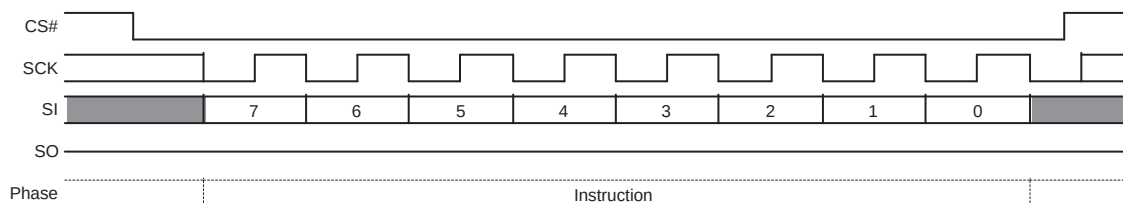
The Bulk Erase (BE) command sets all bits to 1 (all bytes are FFh) inside the entire flash memory array. Before the BE command can be accepted by the device, a Write Enable (WREN) command must be issued and decoded by the device, which sets the Write Enable Latch (WEL) in the Status Register to enable any write operations.

CS# must be driven into the logic high state after the eighth bit of the instruction byte has been latched in on SI. This will initiate the erase cycle, which involves the pre-programming and erase of the entire flash memory array. If CS# is not driven high after the last bit of instruction, the BE operation will not be executed.

As soon as CS# is driven into the logic high state, the erase cycle will be initiated. With the erase cycle in progress, the user can read the value of the Write-In Progress (WIP) bit to determine when the operation has been completed. The WIP bit will indicate a 1 when the erase cycle is in progress and a 0 when the erase cycle has been completed.

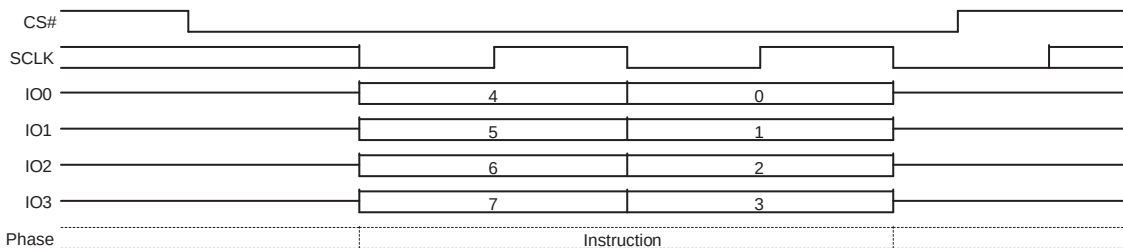
A BE command can be executed only when the Block Protection (BP2, BP1, BP0) bits are set to 0s. If the BP bits are not 0, the BE command is not executed and E_ERR is not set. The BE command will skip any sectors protected by the DYB or PPB and the E_ERR status will not be set.

Figure 10.49 Bulk Erase Command Sequence



This command is also supported in QPI Mode. In QPI Mode the instruction is shifted in on IO0-IO3, two clock cycles per byte.

Figure 10.50 Bulk Erase Command Sequence QPI Mode



10.6.4 Evaluate Erase Status (EES D0h)

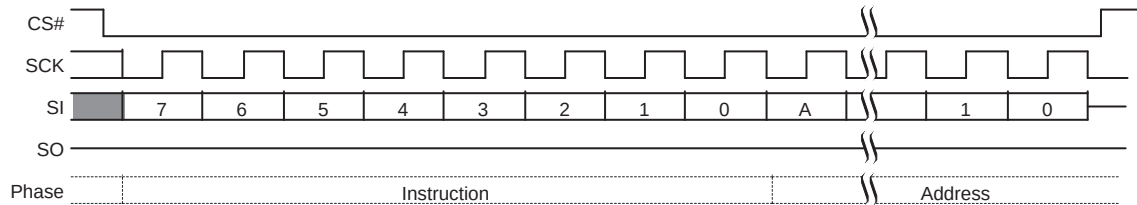
The Evaluate Erase Status (EES) command verifies that the last erase operation on the addressed sector was completed successfully. If the selected sector was successfully erased the Erase Status bit (SR2V[2]) is set to 1. If the selected sector was not completely erased SR2V[2] is 0.

The EES command can be used to detect erase operations failed due to loss of power, reset, or failure during the erase operation.

The EES instruction is followed by a 3- or 4-byte address, depending on the address length configuration (CR2V[7]). The EES command requires t_{EES} to complete and update the Erase Status in SR2V. The WIP bit (SR1V[0]) may be read using the RDSR1 (05h) command, to determine when the EES command is finished. Then the RDSR2 (07h) or the RDAR (65h) command can be used to read SR2V[2]. If a sector is found not erased with SR2V[2]=0, the sector must be erased again to ensure reliable storage of data in the sector.

The Write Enable command (to set the WEL bit) is not required before the EES command. However, the WEL bit is set by the device itself and cleared at the end of the operation, as visible in SR1V[1] when reading status.

Figure 10.51 EES Command Sequence

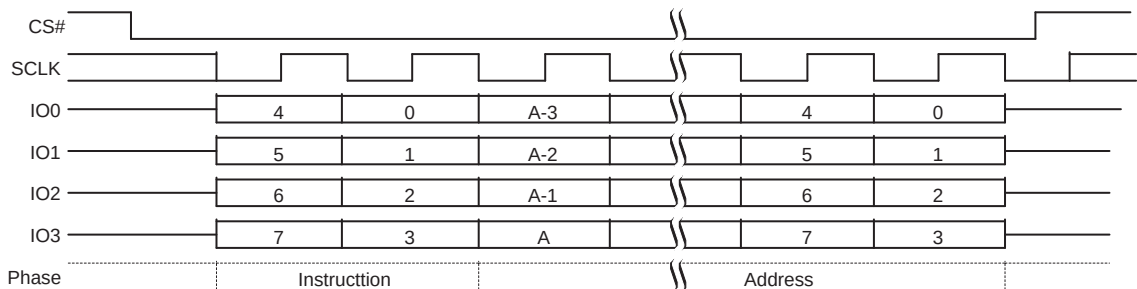


Note:

1. A = MSB of address = A23 for CR2V[7]=0, or A31 for CR2V[7]=1.

This command is also supported in QPI Mode. In QPI Mode the instruction is shifted in on IO0-IO3, two clock cycles per byte.

Figure 10.52 EES QPI Mode Command Sequence



Note:

1. A = MSB of address = A23 for CR2V[7]=0, or A31 for CR2V[7]=1.

10.6.5 Program or Erase Suspend (PES 85h, 75h, B0h)

There are three instruction codes for Program or Erase Suspend (PES) to enable legacy and alternate source software compatibility.

The PES command allows the system to interrupt a programming or erase operation and then read from any other non-erase-suspended sector or non-program-suspended-page. Program or Erase Suspend is valid only during a programming or Sector Erase operation. A Bulk Erase operation cannot be suspended.

The Write-In-Progress (WIP) bit in Status Register 1 (SR1V[0]) must be checked to know when the programming or erase operation has stopped. The Program Suspend Status bit in the Status Register 2 (SR2[0]) can be used to determine if a programming operation has been suspended or was completed at the time WIP changes to 0. The Erase Suspend Status bit in the Status Register 2 (SR2[1]) can be used to determine if an erase operation has been suspended or was completed at the time WIP changes to 0. The time required for the suspend operation to complete is t_{SL} , see [Table 11.2, Program or Erase Suspend AC Parameters on page 134](#).

An Erase can be suspended to allow a program operation or a read operation. During an erase suspend, the DYB array may be read to examine sector protection and written to remove or restore protection on a sector to be programmed.

A program operation may be suspended to allow a read operation.

A new erase operation is not allowed with an already suspended erase or program operation. An erase command is ignored in this situation.

Table 10.5 Commands Allowed During Program or Erase Suspend (Sheet 1 of 2)

Instruction Name	Instruction Code (Hex)	Allowed During Erase Suspend	Allowed During Program Suspend	Comment
PP	02	X		Required for array program during erase suspend. Only allowed if there is no other program suspended program operation (SR2V[0]=0). A program command will be ignored while there is a suspended program. If a program command is sent for a location within an erase suspended sector the program operation will fail with the P_ERR bit set.
READ	03	X	X	All array reads allowed in suspend.
RDSR1	05	X	X	Needed to read WIP to determine end of suspend process.
RDAR	65	X	X	Alternate way to read WIP to determine end of suspend process.
WREN	06	X		Required for program command within erase suspend.
RDSR2	07	X	X	Needed to read suspend status to determine whether the operation is suspended or complete.
4PP	12	X		Required for array program during erase suspend. Only allowed if there is no other program suspended program operation (SR2V[0]=0). A program command will be ignored while there is a suspended program. If a program command is sent for a location within an erase suspended sector the program operation will fail with the P_ERR bit set.
4READ	13	X	X	All array reads allowed in suspend.
CLSR	30	X		Clear status may be used if a program operation fails during erase suspend. Note the instruction is only valid if enabled for clear status by CR4NV[2=1].
CLSR	82	X		Clear status may be used if a program operation fails during erase suspend.
EPR	30	X	X	Required to resume from erase or program suspend. Note the command must be enabled for use as a resume command by CR4NV[2]=0.
EPR	7A	X	X	Required to resume from erase or program suspend.
EPR	8A	X	X	Required to resume from erase or program suspend.
RSTEN	66	X	X	Reset allowed anytime.
RST	99	X	X	Reset allowed anytime.
FAST_READ	0B	X	X	All array reads allowed in suspend.
4FAST_READ	0C	X	X	All array reads allowed in suspend.
EPR	7A	X		Required to resume from erase suspend.
EPR	8A	X		Required to resume from erase suspend.
DIOR	BB	X	X	All array reads allowed in suspend.

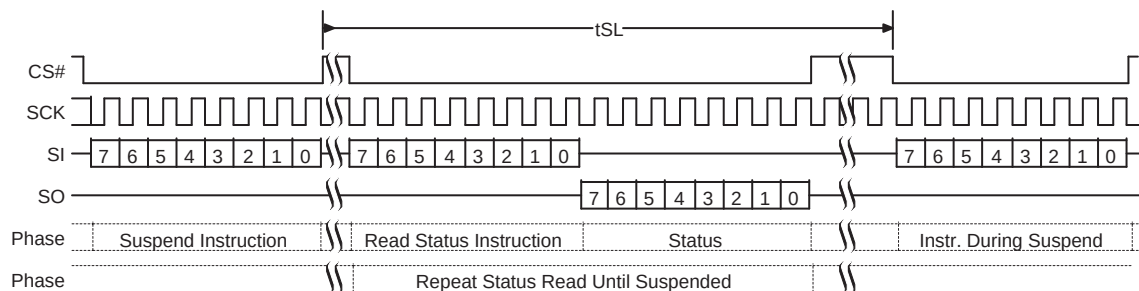
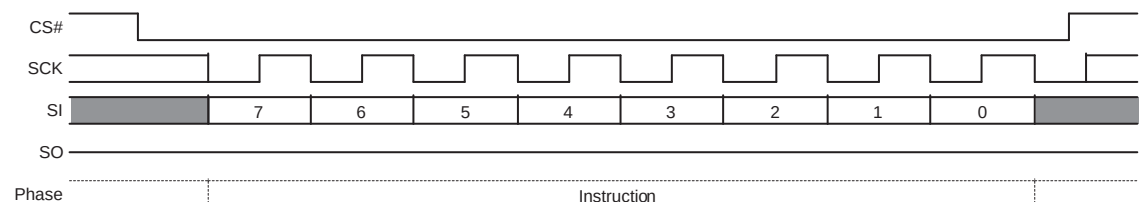
Table 10.5 Commands Allowed During Program or Erase Suspend (Sheet 2 of 2)

Instruction Name	Instruction Code (Hex)	Allowed During Erase Suspend	Allowed During Program Suspend	Comment
4DIOR	BC	X	X	All array reads allowed in suspend.
DYBRD	FA	X		It may be necessary to remove and restore dynamic protection during erase suspend to allow programming during erase suspend.
DYBWR	FB	X		It may be necessary to remove and restore dynamic protection during erase suspend to allow programming during erase suspend.
PPBRD	FC	X		Allowed for checking Persistent Protection before attempting a program command during erase suspend.
4DYBRD	E0	X		It may be necessary to remove and restore dynamic protection during erase suspend to allow programming during erase suspend.
4DYBWR	E1	X		It may be necessary to remove and restore dynamic protection during erase suspend to allow programming during erase suspend.
4PPBRD	E2	X		Allowed for checking Persistent Protection before attempting a program command during erase suspend.
QIOR	EB	X	X	All array reads allowed in suspend.
4QIOR	EC	X	X	All array reads allowed in suspend.
DDRQIOR	ED	X	X	All array reads allowed in suspend.
4DDRQIOR	EE	X	X	All array reads allowed in suspend.
RESET	F0	X	X	Reset allowed anytime.
MBR	FF	X	X	May need to reset a read operation during suspend.

Reading at any address within an erase-suspended sector or program-suspended page produces undetermined data.

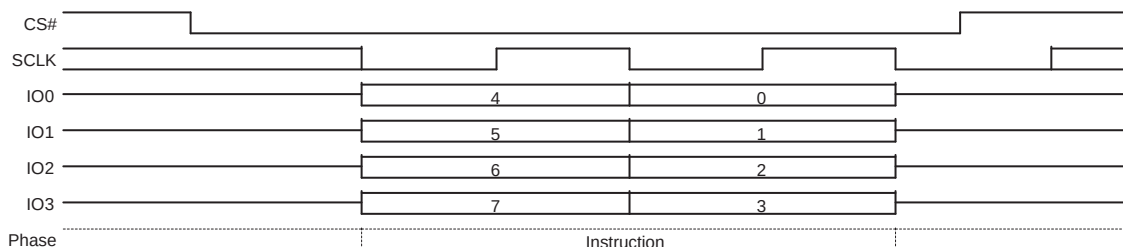
The WRR, WRAR, or PPB Erase commands are not allowed during Erase or Program Suspend, it is therefore not possible to alter the Block Protection or PPB bits during Erase Suspend. If there are sectors that may need programming during Erase suspend, these sectors should be protected only by DYB bits that can be turned off during Erase Suspend.

After an erase-suspended program operation is complete, the device returns to the erase-suspend mode. The system can determine the status of the program operation by reading the WIP bit in the Status Register, just as in the standard program operation.

Figure 10.53 Program or Erase Suspend Command Sequence**Figure 10.54** Program or Erase Suspend Command Sequence

This command is also supported in QPI Mode. In QPI Mode the instruction is shifted in on IO0-IO3, two clock cycles per byte.

Figure 10.55 Program or Erase Suspend Command Sequence QPI Mode



10.6.6 Erase or Program Resume (EPR 7Ah, 8Ah, 30h)

There are three instruction codes for Erase or Program Resume (EPR) to enable legacy and alternate source software compatibility.

After program or read operations are completed during a program or erase suspend the Erase or Program Resume command is sent to continue the suspended operation.

After an Erase or Program Resume command is issued, the WIP bit in the Status Register 1 will be set to a 1 and the programming operation will resume if one is suspended. If no program operation is suspended the suspended erase operation will resume. If there is no suspended program or erase operation the resume command is ignored.

Program or erase operations may be interrupted as often as necessary e.g. a program suspend command could immediately follow a program resume command but, in order for a program or erase operation to progress to completion there must be some periods of time between resume and the next suspend command greater than or equal to t_{RS} . See [Table 11.2, Program or Erase Suspend AC Parameters on page 134](#).

An Erase or Program Resume command must be written to resume a suspended operation.

Figure 10.56 Erase or Program Resume Command Sequence

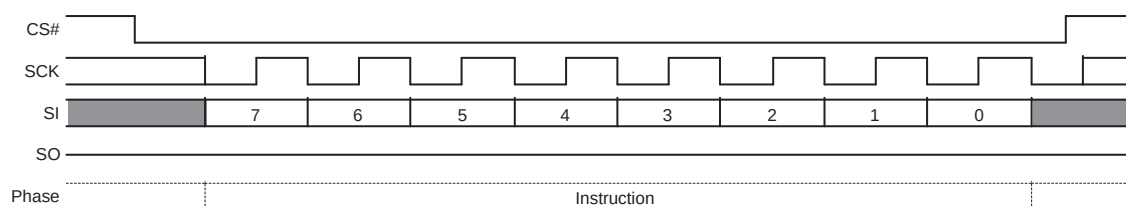
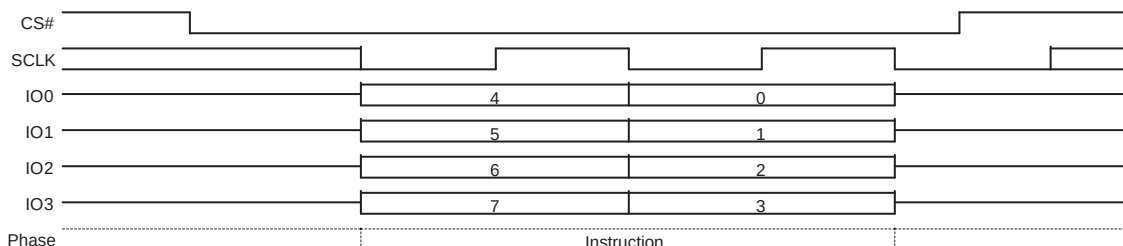


Figure 10.57 Erase or Program Resume Command Sequence QPI Mode



10.7 One-Time Program Array Commands

10.7.1 OTP Program (OTPP 42h)

The OTP Program command programs data in the One-Time Program region, which is in a different address space from the main array data. The OTP region is 1024 bytes so, the address bits from A31 to A10 must be 0 for this command. Refer to [OTP Address Space on page 58](#) for details on the OTP region.

Before the OTP Program command can be accepted by the device, a Write Enable (WREN) command must be issued and decoded by the device, which sets the Write Enable Latch (WEL) in the Status Register to enable any write operations. The WIP bit in SR1V may be checked to determine when the operation is completed. The P_ERR bit in SR1V may be checked to determine if any error occurred during the operation.

To program the OTP array in bit granularity, the rest of the bits within a data byte can be set to 1.

Each region in the OTP memory space can be programmed one or more times, provided that the region is not locked. Attempting to program 0s in a region that is locked will fail with the P_ERR bit in SR1V set to 1. Programming ones, even in a protected area does not cause an error and does not set P_ERR. Subsequent OTP programming can be performed only on the un-programmed bits (that is, 1 data).

The protocol of the OTP Program command is the same as the Page Program command. See [Page Program \(PP 02h or 4PP 12h\) on page 114](#) for the command sequence.

10.7.2 OTP Read (OTPR 4Bh)

The OTP Read command reads data from the OTP region. The OTP region is 1024 bytes so, the address bits from A31 to A10 must be zero for this command. Refer to [OTP Address Space on page 58](#) for details on the OTP region. The protocol of the OTP Read command is similar to the Fast Read command except that it will not wrap to the starting address after the OTP address is at its maximum; instead, the data beyond the maximum OTP address will be undefined. The OTP Read command read latency is set by the latency value in CR2V[3:0].

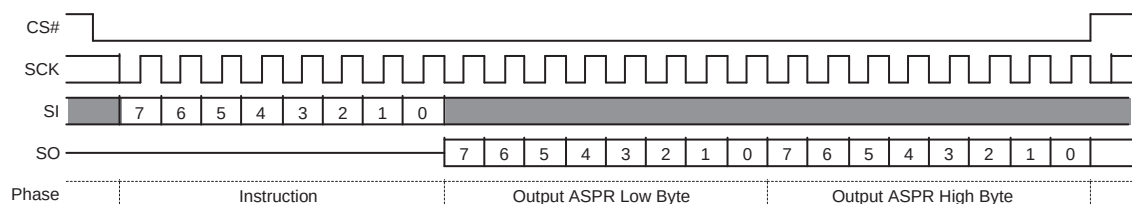
See [Fast Read \(FAST_READ 0Bh or 4FAST_READ 0Ch\) on page 106](#) for the command sequence.

10.8 Advanced Sector Protection Commands

10.8.1 ASP Read (ASPRD 2Bh)

The ASP Read instruction 2Bh is shifted into SI by the rising edge of the SCK signal. Then the 16-bit ASP register contents are shifted out on the serial output SO, least significant byte first. Each bit is shifted out at the SCK frequency by the falling edge of the SCK signal. It is possible to read the ASP register continuously by providing multiples of 16 clock cycles. The maximum operating clock frequency for the ASP Read (ASPRD) command is 133 MHz.

Figure 10.58 ASPRD Command



10.8.2 ASP Program (ASPP 2Fh)

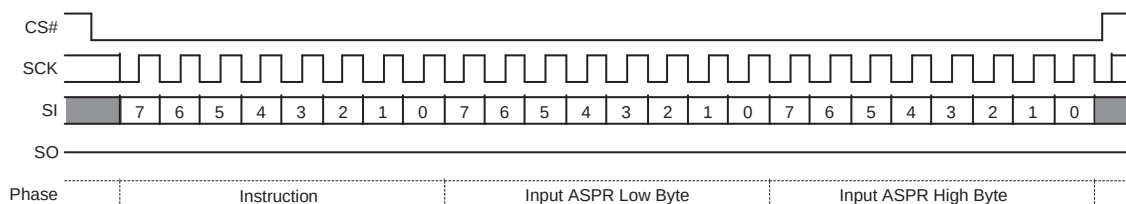
Before the ASP Program (ASPP) command can be accepted by the device, a Write Enable (WREN) command must be issued. After the Write Enable (WREN) command has been decoded, the device will set the Write Enable Latch (WEL) in the Status Register to enable any write operations.

The ASPP command is entered by driving CS# to the logic low state, followed by the instruction and two data bytes on SI, least significant byte first. The ASP Register is two data bytes in length.

The ASPP command affects the P_ERR and WIP bits of the Status and Configuration Registers in the same manner as any other programming operation.

CS# input must be driven to the logic high state after the sixteenth bit of data has been latched in. If not, the ASPP command is not executed. As soon as CS# is driven to the logic high state, the self-timed ASPP operation is initiated. While the ASPP operation is in progress, the Status Register may be read to check the value of the Write-In Progress (WIP) bit. The Write-In Progress (WIP) bit is a 1 during the self-timed ASPP operation, and is a 0 when it is completed. When the ASPP operation is completed, the Write Enable Latch (WEL) is set to a 0.

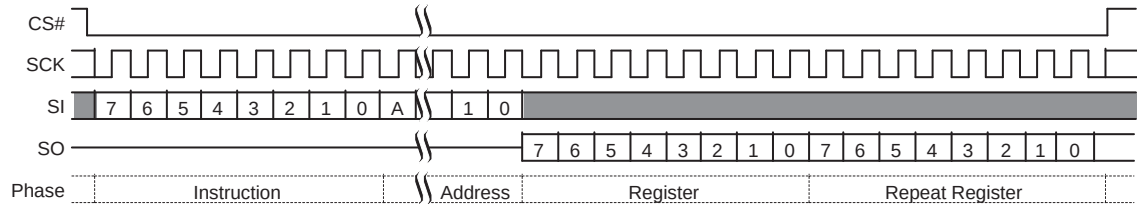
Figure 10.59 ASPP Command



10.8.3 DYB Read (DYBRD FAh or 4DYBRD E0h)

The instruction is latched into SI by the rising edge of the SCK signal. The instruction is followed by the 24 or 32-bit address, depending on the address length configuration CR2V[7], selecting location zero within the desired sector. Note, the high order address bits not used by a particular density device must be zero. Then the 8-bit DYB access register contents are shifted out on the serial output SO. Each bit is shifted out at the SCK frequency by the falling edge of the SCK signal. It is possible to read the same DYB access register continuously by providing multiples of eight clock cycles. The address of the DYB register does not increment so this is not a means to read the entire DYB array. Each location must be read with a separate DYB Read command. The maximum operating clock frequency for READ command is 133 MHz.

Figure 10.60 DYBRD Command Sequence

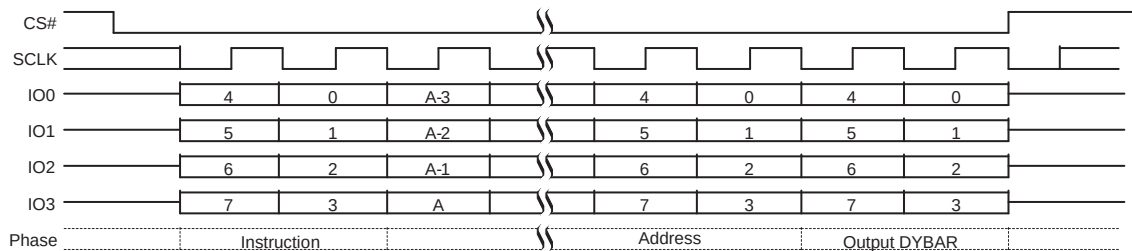


Notes:

1. A = MSB of address = 23 for Address length (CR2V[7] = 0, or 31 for CR2V[7]=1 with command FAh.
2. A = MSB of address = 31 with command E0h.

This command is also supported in QPI Mode. In QPI Mode the instruction and address is shifted in on IO0-IO3 and returning data is shifted out on IO0-IO3.

Figure 10.61 DYBRD QPI Mode Command Sequence



Notes:

1. A = MSB of address = 23 for Address length (CR2V[7] = 0, or 31 for CR2V[7]=1 with command FAh.
2. A = MSB of address = 31 with command E0h.

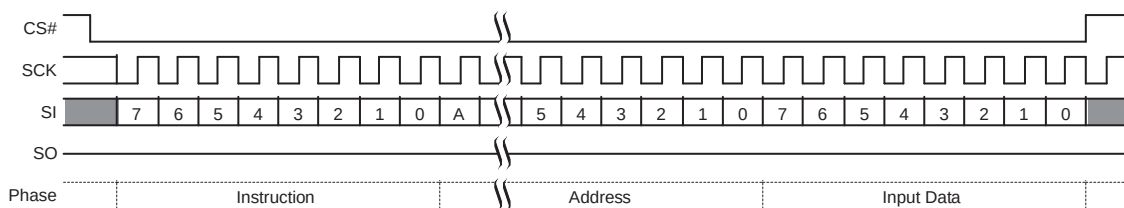
10.8.4 DYB Write (DYBWR FBh or 4DYBWR E1h)

Before the DYB Write (DYBWR) command can be accepted by the device, a Write Enable (WREN) command must be issued. After the Write Enable (WREN) command has been decoded, the device will set the Write Enable Latch (WEL) in the Status Register to enable any write operations.

The DYBWR command is entered by driving CS# to the logic low state, followed by the instruction, followed by the 24- or 32-bit address, depending on the address length configuration CR2V[7], selecting location zero within the desired sector (note, the high order address bits not used by a particular density device must be zero), then the data byte on SI. The DYB Access Register is one data byte in length. The data value must be 00h to protect or FFh to unprotect the selected sector.

The DYBWR command affects the P_ERR and WIP bits of the Status and Configuration Registers in the same manner as any other programming operation. CS# must be driven to the logic high state after the eighth bit of data has been latched in. As soon as CS# is driven to the logic high state, the self-timed DYBWR operation is initiated. While the DYBWR operation is in progress, the Status Register may be read to check the value of the Write-In Progress (WIP) bit. The Write-In Progress (WIP) bit is a 1 during the self-timed DYBWR operation, and is a 0 when it is completed. When the DYBWR operation is completed, the Write Enable Latch (WEL) is set to a 0.

Figure 10.62 DYBWR Command Sequence

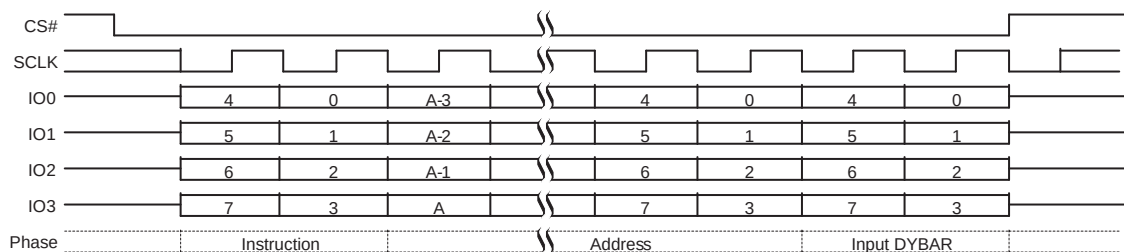


Notes:

1. A = MSB of address = 23 for Address length (CR2V[7] = 0, or 31 for CR2V[7]=1 with command FBh.
2. A = MSB of address = 31 with command E1h.

This command is also supported in QPI Mode. In QPI Mode the instruction is shifted in on IO0-IO3, two clock cycles per byte.

Figure 10.63 DYBWR QPI Mode Command Sequence



Notes:

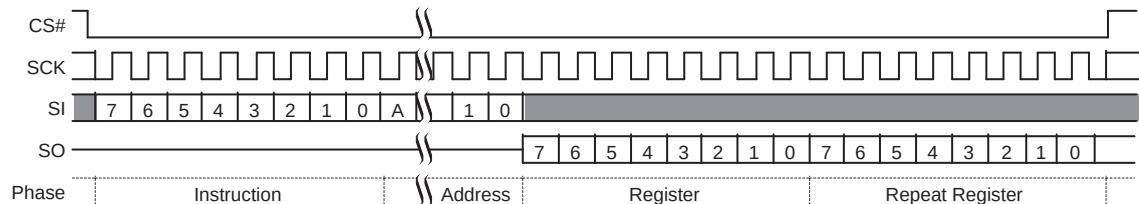
1. A = MSB of address = 23 for Address length (CR2V[7] = 0, or 31 for CR2V[7]=1 with command FBh.
2. A = MSB of address = 31 with command E1h

10.8.5 PPB Read (PPBRD FCh or 4PPBRD E2h)

The instruction E2h is shifted into SI by the rising edges of the SCK signal, followed by the 24- or 32-bit address, depending on the address length configuration CR2V[7], selecting location zero within the desired sector (note, the high order address bits not used by a particular density device must be zero). Then the 8-bit PPB access register contents are shifted out on SO.

It is possible to read the same PPB access register continuously by providing multiples of eight clock cycles. The address of the PPB register does not increment so this is not a means to read the entire PPB array. Each location must be read with a separate PPB Read command. The maximum operating clock frequency for the PPB Read command is 133 MHz.

Figure 10.64 PPBRD Command Sequence



Notes:

1. A = MSB of address = 23 for Address length (CR2V[7] = 0, or 31 for CR2V[7]=1 with command FCh.
2. A = MSB of address = 31 with command E2h.

10.8.6 PPB Program (PPBP FDh or 4PPBP E3h)

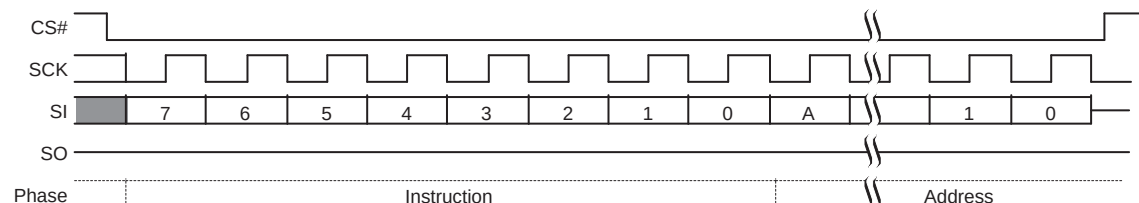
Before the PPB Program (PPBP) command can be accepted by the device, a Write Enable (WREN) command must be issued. After the Write Enable (WREN) command has been decoded, the device will set the Write Enable Latch (WEL) in the Status Register to enable any write operations.

The PPBP command is entered by driving CS# to the logic low state, followed by the instruction, followed by the 24- or 32-bit address, depending on the address length configuration CR2V[7], selecting location zero within the desired sector (note, the high order address bits not used by a particular density device must be zero).

The PPBP command affects the P_ERR and WIP bits of the Status and Configuration Registers in the same manner as any other programming operation.

CS# must be driven to the logic high state after the last bit of address has been latched in. If not, the PPBP command is not executed. As soon as CS# is driven to the logic high state, the self-timed PPBP operation is initiated. While the PPBP operation is in progress, the Status Register may be read to check the value of the Write-In Progress (WIP) bit. The WIP bit is a 1 during the self-timed PPBP operation, and is a 0 when it is completed. When the PPBP operation is completed, the Write Enable Latch (WEL) is set to a 0.

Figure 10.65 PPBP Command Sequence



Notes:

1. A = MSB of address = 23 for Address length (CR2V[7] = 0, or 31 for CR2V[7]=1 with command FDh.
2. A = MSB of address = 31 with command E3h.

10.8.7 PPB Erase (PPBE E4h)

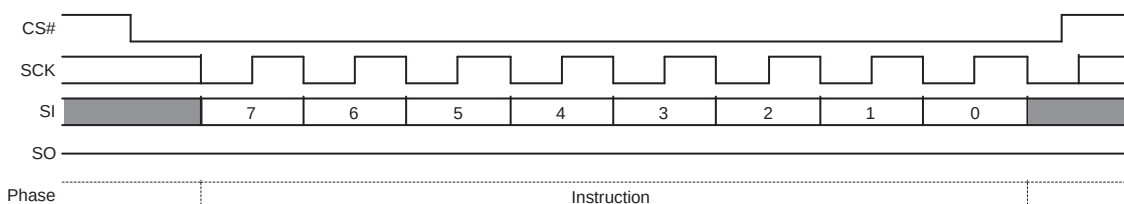
The PPB Erase (PPBE) command sets all PPB bits to 1. Before the PPB Erase command can be accepted by the device, a Write Enable (WREN) command must be issued and decoded by the device, which sets the Write Enable Latch (WEL) in the Status Register to enable any write operations.

The instruction E4h is shifted into SI by the rising edges of the SCK signal.

CS# must be driven into the logic high state after the eighth bit of the instruction byte has been latched in on SI. This will initiate the beginning of internal erase cycle, which involves the pre-programming and erase of the entire PPB memory array. Without CS# being driven to the logic high state after the eighth bit of the instruction, the PPB erase operation will not be executed.

With the internal erase cycle in progress, the user can read the value of the Write-In Progress (WIP) bit to check if the operation has been completed. The WIP bit will indicate a 1 when the erase cycle is in progress and a 0 when the erase cycle has been completed. Erase suspend is not allowed during PPB Erase.

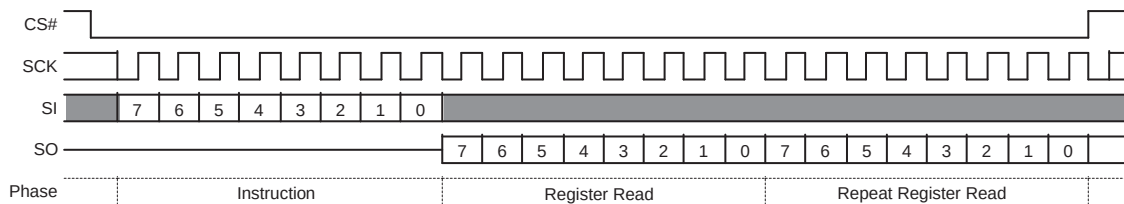
Figure 10.66 PPB Erase Command Sequence



10.8.8 PPB Lock Bit Read (PLBRD A7h)

The PPB Lock Bit Read (PLBRD) command allows the PPB Lock Register contents to be read out of SO. It is possible to read the PPB lock register continuously by providing multiples of eight clock cycles. The PPB Lock Register contents may only be read when the device is in standby state with no other operation in progress. It is recommended to check the Write-In Progress (WIP) bit of the Status Register before issuing a new command to the device.

Figure 10.67 PPB Lock Register Read Command Sequence



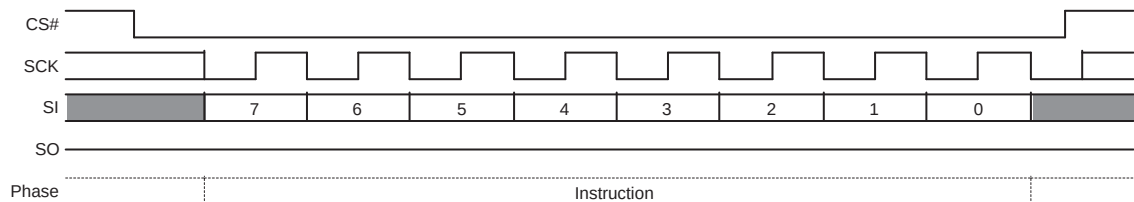
10.8.9 PPB Lock Bit Write (PLBWR A6h)

The PPB Lock Bit Write (PLBWR) command clears the PPB Lock Register to zero. Before the PLBWR command can be accepted by the device, a Write Enable (WREN) command must be issued and decoded by the device, which sets the Write Enable Latch (WEL) in the Status Register to enable any write operations.

The PLBWR command is entered by driving CS# to the logic low state, followed by the instruction.

CS# must be driven to the logic high state after the eighth bit of instruction has been latched in. If not, the PLBWR command is not executed. As soon as CS# is driven to the logic high state, the self-timed PLBWR operation is initiated. While the PLBWR operation is in progress, the Status Register may still be read to check the value of the Write-In Progress (WIP) bit. The Write-In Progress (WIP) bit is a 1 during the self-timed PLBWR operation, and is a 0 when it is completed. When the PLBWR operation is completed, the Write Enable Latch (WEL) is set to a 0. The maximum clock frequency for the PLBWR command is 133 MHz.

Figure 10.68 PPB Lock Bit Write Command Sequence

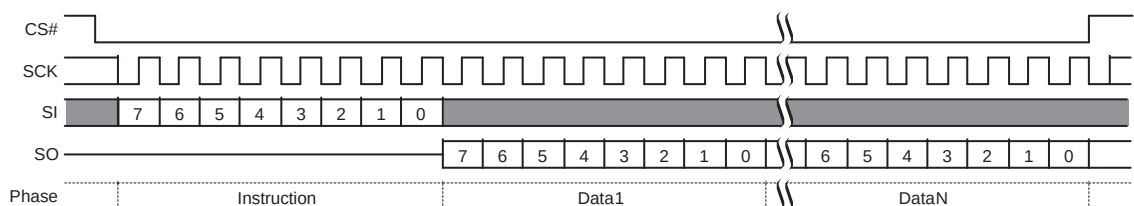


10.8.10 Password Read (PASSRD E7h)

The correct password value may be read only after it is programmed and before the Password mode has been selected by programming the Password Protection mode bit to 0 in the ASP Register (ASP[2]). After the Password Protection mode is selected the password is no longer readable, the PASSRD command will output undefined data.

The PASSRD command is shifted into SI. Then the 64-bit Password is shifted out on the serial output SO, least significant byte first, most significant bit of each byte first. Each bit is shifted out at the SCK frequency by the falling edge of the SCK signal. It is possible to read the Password continuously by providing multiples of 64 clock cycles. The maximum operating clock frequency for the PASSRD command is 133 MHz.

Figure 10.69 Password Read Command Sequence



10.8.11 Password Program (PASSP E8h)

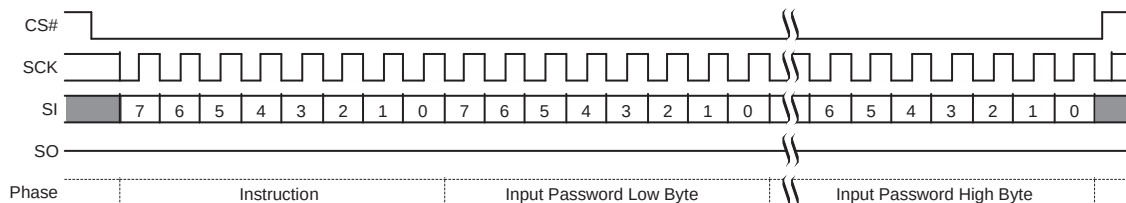
Before the Password Program (PASSP) command can be accepted by the device, a Write Enable (WREN) command must be issued and decoded by the device. After the Write Enable (WREN) command has been decoded, the device sets the Write Enable Latch (WEL) to enable the PASSP operation.

The password can only be programmed before the Password mode is selected by programming the Password Protection mode bit to 0 in the ASP Register (ASP[2]). After the Password Protection mode is selected the PASSP command is ignored.

The PASSP command is entered by driving CS# to the logic low state, followed by the instruction and the password data bytes on SI, least significant byte first, most significant bit of each byte first. The password is sixty-four (64) bits in length.

CS# must be driven to the logic high state after the sixty-fourth (64th) bit of data has been latched. If not, the PASSP command is not executed. As soon as CS# is driven to the logic high state, the self-timed PASSP operation is initiated. While the PASSP operation is in progress, the Status Register may be read to check the value of the Write-In Progress (WIP) bit. The Write-In Progress (WIP) bit is a 1 during the self-timed PASSP cycle, and is a 0 when it is completed. The PASSP command can report a program error in the P_ERR bit of the Status Register. When the PASSP operation is completed, the Write Enable Latch (WEL) is set to a 0. The maximum clock frequency for the PASSP command is 133 MHz.

Figure 10.70 Password Program Command Sequence



10.8.12 Password Unlock (PASSU E9h)

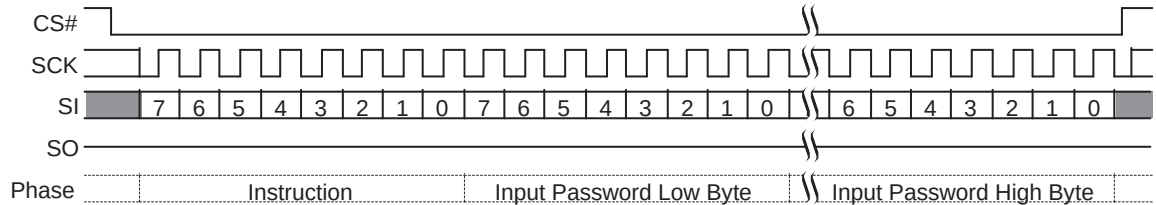
The PASSU command is entered by driving CS# to the logic low state, followed by the instruction and the password data bytes on SI, least significant byte first, most significant bit of each byte first. The password is sixty-four (64) bits in length.

CS# must be driven to the logic high state after the sixty-fourth (64th) bit of data has been latched. If not, the PASSU command is not executed. As soon as CS# is driven to the logic high state, the self-timed PASSU operation is initiated. While the PASSU operation is in progress, the Status Register may be read to check the value of the Write-In Progress (WIP) bit. The Write-In Progress (WIP) bit is a 1 during the self-timed PASSU cycle, and is a 0 when it is completed.

If the PASSU command supplied password does not match the hidden password in the Password Register, an error is reported by setting the P_ERR bit to 1. The WIP bit of the Status Register also remains set to 1. It is necessary to use the CLSR command to clear the Status Register, the RESET command to software reset the device, or drive the RESET# input low to initiate a hardware reset, in order to return the P_ERR and WIP bits to 0. This returns the device to standby state, ready for new commands such as a retry of the PASSU command.

If the password does match, the PPB Lock bit is set to 1. The maximum clock frequency for the PASSU command is 133 MHz.

Figure 10.71 Password Unlock Command Sequence



10.9 Reset Commands

Software controlled Reset commands restore the device to its initial power-up state, by reloading volatile registers from non-volatile default values. However, the volatile FREEZE bit in the Configuration Register CR1V[0] and the volatile PPB Lock bit in the PPB Lock Register are not changed by a software reset. The software reset cannot be used to circumvent the FREEZE or PPB Lock bit protection mechanisms for the other security configuration bits.

The Freeze bit and the PPB Lock bit will remain set at their last value prior to the software reset. To clear the FREEZE bit and set the PPB Lock bit to its protection mode selected power-on state, a full power-on-reset sequence or hardware reset must be done.

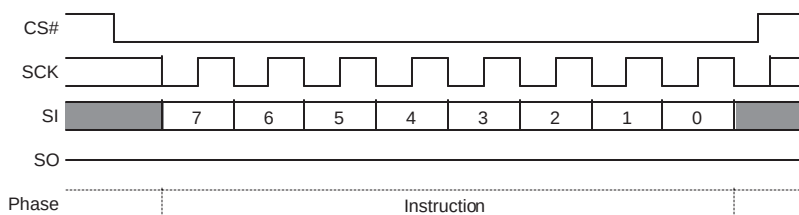
The non-volatile bits in the Configuration Register (CR1NV), TBPROT_O, TBPARM, and BPNV_O, retain their previous state after a software reset.

The Block Protection bits BP2, BP1, and BP0, in the Status Register (SR1V) will only be reset to their default value if FREEZE = 0.

A reset command (RST or RESET) is executed when CS# is brought high at the end of the instruction and requires t_{RPH} time to execute.

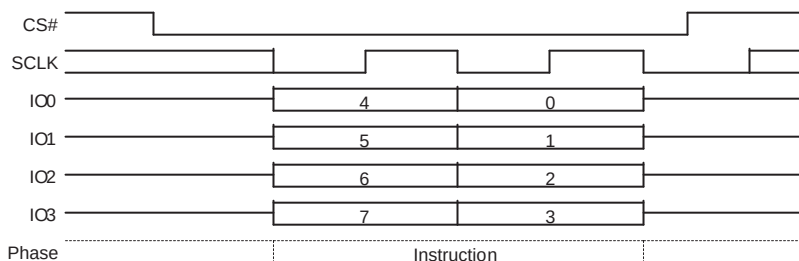
In the case of a previous Power-Up Reset (POR) failure to complete, a reset command triggers a full power-up sequence requiring t_{PU} to complete.

Figure 10.72 Software Reset Command Sequence



This command is also supported in QPI Mode. In QPI Mode the instruction is shifted in on IO0-IO3, two clock cycles per byte.

Figure 10.73 Software Reset Command Sequence QPI Mode



10.9.1 Software Reset Enable (RSTEN 66h)

The Reset Enable (RSTEN) command is required immediately before a Reset command (RST) such that a software reset is a sequence of the two commands. Any command other than RST following the RSTEN command, will clear the reset enable condition and prevent a later RST command from being recognized.

10.9.2 Software Reset (RST 99h)

The Reset (RST) command immediately following a RSTEN command, initiates the software reset process.

10.9.3 Legacy Software Reset (RESET F0h)

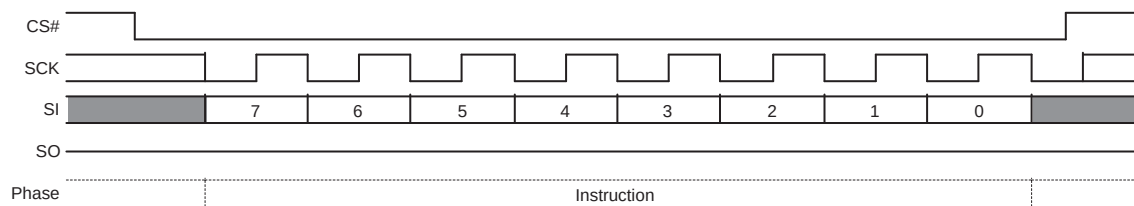
The Legacy Software Reset (RESET) is a single command that initiates the software reset process. This command is disabled by default but can be enabled by programming CR3V[0]=1, for software compatibility with Spansion legacy FL-S devices.

10.9.4 Mode Bit Reset (MBR FFh)

The Mode Bit Reset (MBR) command is used to return the device from continuous high performance read mode back to normal standby awaiting any new command. Because some device packages lack a hardware RESET# input and a device that is in a continuous high performance read mode may not recognize any normal SPI command, a system hardware reset or software reset command may not be recognized by the device. It is recommended to use the MBR command after a system reset when the RESET# signal is not available or, before sending a software reset, to ensure the device is released from continuous high performance read mode.

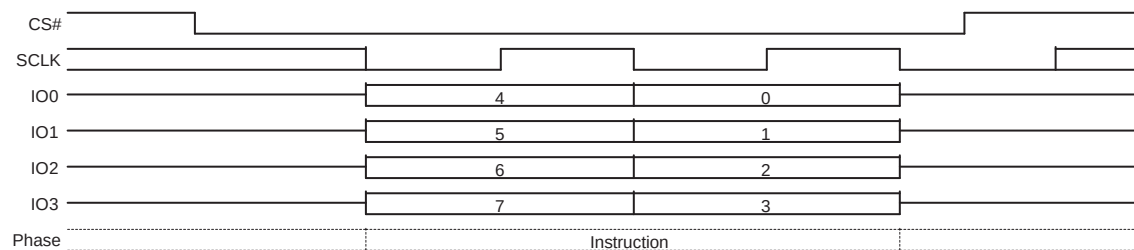
The MBR command sends 1s on SI or IO0 for 8 SCK cycles. IO1 to IO3 are “don’t care” during these cycles.

Figure 10.74 Mode Bit Reset Command Sequence



This command is also supported in QPI Mode. In QPI Mode the instruction is shifted in on IO0-IO3, two clock cycles per byte.

Figure 10.75 Mode Bit Reset Command Sequence QPI Mode



11. Embedded Algorithm Performance Tables

The Joint Electron Device Engineering Council (JEDEC) standard JESD22-A117 defines the procedural requirements for performing valid endurance and retention tests based on a qualification specification. This methodology is intended to determine the ability of a flash device to sustain repeated data changes without failure (program/erase endurance) and to retain data for the expected life (data retention). Endurance and retention qualification specifications are specified in JESD47 or may be developed using knowledge-based methods as in JESD94.

Table 11.1 Program and Erase Performance

Symbol	Parameter	Min	Typ (2)	Max	Unit
t_W	Non-Volatile Register Write Time		145	750	ms
t_{PP}	Page Programming (512 bytes) Page Programming (256 bytes)		475 360	1080 1080	μ s
t_{SE}	Sector Erase Time (64-kB or 4-kB physical sectors)		145	725	ms
	Sector Erase Time (256-kB logical sectors = 4x64K physical sectors)		580	2900	ms
$t_{BE} (1)$	Bulk Erase Time (S25FS128S)		36	180	sec
$t_{BE} (1)$	Bulk Erase Time (S25FS256S)		72	360	sec
t_{EES}	Evaluate Erase Status Time (64-kB or 4-kB physical sectors)		20	25	μ s
	Evaluate Erase Status Time (256-kB physical or logical sectors)		80	100	
	Erase per sector	100,000			cycles

Notes:

1. Not 100% tested.
2. Typical program and erase times assume the following conditions: 25°C, $V_{DD} = 1.8V$; random data pattern.
3. The programming time for any OTP programming command is the same as t_{PP} . This includes OTP 42h, PNVDLR 43h, ASPP 2Fh, and PASSP E8h.
4. The programming time for the PPBP E3h command is the same as t_{PP} . The erase time for PPBE E4h command is the same as t_{SE} .
5. Data retention of 20 years is based on 1k erase cycles or less.

Table 11.2 Program or Erase Suspend AC Parameters

Parameter	Typical	Max	Unit	Comments
Suspend Latency (t_{SL})		40	μ s	The time from Suspend command until the WIP bit is 0.
Resume to next Program Suspend (t_{RS})	100		μ s	Minimum is the time needed to issue the next Suspend command but $\geq$ typical periods are needed for Program or Erase to progress to completion.

12. Software Interface Reference

12.1 Command Summary by Instruction

Table 12.1 S25FS-S Family Command Set (sorted by instruction)

Command Name	Command Description	Instruction Value (Hex)	Maximum Frequency (MHz)	Address Length (Bytes)	QPI
WRR	Write Register (Status 1, Configuration 1)	01	133	0	Yes
PP	Page Program	02	133	3 or 4	Yes
READ	Read	03	50	3 or 4	No
WRDI	Write Disable	04	133	0	Yes
RDSR1	Read Status Register 1	05	133	0	Yes
WREN	Write Enable	06	133	0	Yes
RDSR2	Read Status Register 2	07	133	0	No
4PP	Page Program	12	133	4	Yes
4READ	Read	13	50	4	No
P4E	Parameter 4-kB Sector Erase	20	133	3 or 4	Yes
4P4E	Parameter 4-kB Sector Erase	21	133	4	Yes
CLSR	Clear Status Register 1 - Erase/Prog. Fail Reset This command may be disabled and the instruction value instead used for a program / erase resume command - see Configuration Register 3 on page 69	30	133	0	Yes
EPR	Erase / Program Resume (alternate instruction) This command may be disabled and the instruction value instead used for a clear status command - see Configuration Register 3 on page 69	30	133	0	Yes
RDCR	Read Configuration Register 1	35	133	0	No
DLPRD	Data Learning Pattern Read	41	133	0	No
OTPP	OTP Program	42	133	3 or 4	No
PNVDLR	Program NV Data Learning Register	43	133	0	No
BE	Bulk Erase	60	133	0	Yes
RDAR	Read Any Register	65	133	3 or 4	Yes
RSTEN	Software Reset Enable	66	133	0	Yes
WRAR	Write Any Register	71	133	3 or 4	Yes
EPS	Erase / Program Suspend	75	133	0	Yes
CLSR	Clear Status Register 1 (alternate instruction) - Erase/Prog. Fail Reset	82	133	0	Yes
EPS	Erase / Program Suspend (alternate instruction)	85	133	0	Yes
RST	Software Reset	99	133	0	Yes
FAST_READ	Fast Read	0B	133	3 or 4	No
4FAST_READ	Fast Read	0C	133	4	No
ASPRD	ASP Read	2B	133	0	No
ASPP	ASP Program	2F	133	0	No
WVDLR	Write Volatile Data Learning Register	4A	133	0	No
OTPR	OTP Read	4B	133	3 or 4	No
RSFDP	Read JEDEC Serial Flash Discoverable Parameters	5A	50	3	Yes
EPR	Erase / Program Resume	7A	133	0	Yes
EPR	Erase / Program Resume (alternate instruction)	8A	133	0	Yes
RDID	Read ID (JEDEC Manufacturer ID and JEDEC CFI)	9F	133	0	Yes
PLBWR	PPB Lock Bit Write	A6	133	0	No
PLBRD	PPB Lock Bit Read	A7	133	0	No
RDQID	Read Quad ID	AF	133	0	Yes
EPS	Erase / Program Suspend (alternate instruction)	B0	133	0	Yes

Table 12.1 S25FS-S Family Command Set (sorted by instruction)

Command Name	Command Description	Instruction Value (Hex)	Maximum Frequency (MHz)	Address Length (Bytes)	QPI
4BAM	Enter 4-byte Address Mode	B7	133	0	No
DIOR	Dual I/O Read	BB	66	3 or 4	No
4DIOR	Dual I/O Read	BC	66	4	No
SBL	Set Burst Length	C0	133	0	No
BE	Bulk Erase (alternate instruction)	C7	133	0	Yes
EES	Evaluate Erase Status	D0	133	3 or 4	Yes
SE	Erase 64 kB or 256 kB	D8	133	3 or 4	Yes
4SE	Erase 64 kB or 256 kB	DC	133	4	Yes
4DYBRD	DYB Read	E0	133	4	Yes
4DYBWR	DYB Write	E1	133	4	Yes
4PPBRD	PPB Read	E2	133	4	No
4PPBP	PPB Program	E3	133	4	No
PPBE	PPB Erase	E4	133	0	No
PASSRD	Password Read	E7	133	0	No
PASSP	Password Program	E8	133	0	No
PASSU	Password Unlock	E9	133	0	No
QIOR	Quad I/O Read	EB	133	3 or 4	Yes
4QIOR	Quad I/O Read	EC	133	4	Yes
DDRQIOR	DDR Quad I/O Read	ED	80	3 or 4	Yes
4DDRQIOR	DDR Quad I/O Read	EE	80	4	Yes
RESET	Legacy Software Reset	F0	133	0	No
DYBRD	DYB Read	FA	133	3 or 4	Yes
DYBWR	DYB Write	FB	133	3 or 4	Yes
PPBRD	PPB Read	FC	133	3 or 4	No
PPBP	PPB Program	FD	133	3 or 4	No
MBR	Mode Bit Reset	FF	133	0	Yes

12.2 Registers

The register maps are copied in this section as a quick reference. See [Registers on page 59](#) for the full description of the register contents.

Table 12.2 Status Register 1 Non-Volatile (SR1NV)

Bits	Field Name	Function	Type	Default State	Description
7	SRWD_NV	Status Register Write Disable Default	Non-Volatile	0	1 = Locks state of SRWD, BP, and Configuration Register 1 bits when WP# is low by not executing WRR or WRAR commands that would affect SR1NV, SR1V, CR1NV, or CR1V. 0 = No protection, even when WP# is low.
6	P_ERR_D	Programming Error Default	Non-Volatile Read Only	0	Provides the default state for the Programming Error Status. Not user programmable.
5	E_ERR_D	Erase Error Default	Non-Volatile Read Only	0	Provides the default state for the Erase Error Status. Not user programmable.
4	BP_NV2	Block Protection Non-Volatile	Non-Volatile	000b	Protects the selected range of sectors (Block) from Program or Erase when the BP bits are configured as non-volatile (CR1NV[3]=0). Programmed to 111b when BP bits are configured to volatile (CR1NV[3]=1).- after which these bits are no longer user programmable.
3	BP_NV1				
2	BP_NV0				
1	WEL_D	WEL Default	Non-Volatile Read Only	0	Provides the default state for the WEL Status. Not user programmable.
0	WIP_D	WIP Default	Non-Volatile Read Only	0	Provides the default state for the WIP Status. Not user programmable.

Table 12.3 Status Register 1 Volatile (SR1V)

Bits	Field Name	Function	Type	Default State	Description
7	SRWD	Status Register Write Disable	Volatile Read Only	SR1NV	Volatile copy of SR1NV[7].
6	P_ERR	Programming Error Occurred	Volatile Read Only		1 = Error occurred. 0 = No Error.
5	E_ERR	Erase Error Occurred	Volatile Read Only		1= Error occurred. 0 = No Error.
4	BP2	Block Protection Volatile	Volatile		Protects selected range of sectors (Block) from Program or Erase when the BP bits are configured as volatile (CR1NV[3]=1). Volatile copy of SR1NV[4:2] when BP bits are configured as non-volatile. User writable when BP bits are configured as volatile.
3	BP1				
2	BP0				
1	WEL	Write Enable Latch	Volatile		1 = Device accepts Write Registers (WRR and WRAR), Program, or Erase commands. 0 = Device ignores Write Registers (WRR and WRAR), Program, or Erase commands. This bit is not affected by WRR or WRAR, only WREN and WRDI commands affect this bit.
0	WIP	Write-In-Progress	Volatile Read Only		1= Device Busy, an embedded operation is in progress such as Program or Erase. 0 = Ready Device is in Standby mode and can accept commands. This bit is not affected by WRR or WRAR, it only provides WIP status.

Table 12.4 Status Register 2 Volatile (SR2V)

Bits	Field Name	Function	Type	Default State	Description
7	RFU	Reserved		0	Reserved for Future Use.
6	RFU	Reserved		0	Reserved for Future Use.
5	RFU	Reserved		0	Reserved for Future Use.
4	RFU	Reserved		0	Reserved for Future Use.
3	RFU	Reserved		0	Reserved for Future Use.
2	ESTAT	Erase Status	Volatile Read Only	0	1 = Sector Erase Status command result = Erase Completed. 0 = Sector Erase Status command result = Erase Not Completed.
1	ES	Erase Suspend	Volatile Read Only	0	1 = In Erase Suspend mode. 0 = Not in Erase Suspend mode.
0	PS	Program Suspend	Volatile Read Only	0	1 = In Program Suspend mode. 0 = Not in Program Suspend mode.

Table 12.5 Configuration Register 1 Non-Volatile (CR1NV)

Bits	Field Name	Function	Type	Default State	Description
7	RFU	Reserved for Future Use	Non-Volatile	0	Reserved.
6	RFU			0	
5	TBPROT_O	Configures Start of Block Protection	OTP	0	1 = BP starts at bottom (Low address). 0 = BP starts at top (High address).
4	RFU	Reserved for Future Use	RFU	0	Reserved.
3	BPNV_O	Configures BP2-0 in Status Register	OTP	0	1 = Volatile. 0 = Non-Volatile.
2	TBPARAM_O	Configures Parameter Sectors location	OTP	0	1 = 4-kB physical sectors at top, (high address). 0 = 4-kB physical sectors at bottom (Low address). RFU in uniform sector configuration.
1	QUAD_NV	Quad Non-Volatile	Non-Volatile	0	Provides the default state for the QUAD bit.
0	FREEZE_D	FREEZE Default	Non-Volatile Read Only	0	Provides the default state for the Freeze bit. Not user programmable.

Table 12.6 Configuration Register 1 Volatile (CR1V)

Bits	Field Name	Function	Type	Default State	Description
7	RFU	Reserved for Future Use	Volatile	CR1NV	Reserved.
6	RFU				Reserved.
5	TBPROT	Volatile copy of TBPROT_O	Volatile Read Only		Not user writable. See CR1NV[5] TBPROT_O.
4	RFU	Reserved for Future Use	RFU		Reserved.
3	BPNV	Volatile copy of BPNV_O	Volatile Read Only		Not user writable. See CR1NV[3] BPNV_O.
2	TBPARAM	Volatile copy of TBPARAM_O	Volatile Read Only		Not user writable. See CR1NV[2] TBPARAM_O.
1	QUAD	Quad I/O Mode	Volatile		1 = Quad. 0 = Dual or Serial.
0	FREEZE	Lock-Down Block Protection until next power cycle	Volatile		Lock current state of Block Protection control bits, and OTP regions. 1 = Block Protection and OTP locked. 0 = Block Protection and OTP unlocked.

Table 12.7 Configuration Register 2 Non-Volatile (CR2NV)

Bits	Field Name	Function	Type	Default State	Description
7	AL_NV	Address Length	OTP	0	1 = 4-byte address. 0 = 3-byte address.
6	QA_NV	QPI		0	1 = Enabled - QPI (4-4-4) protocol in use. 0 = Disabled - Legacy SPI protocols in use, instruction is always serial on SI.
5	IO3R_NV	IO3 Reset		0	1 = Enabled - IO3 is used as RESET# input when CS# is high or Quad Mode is disabled CR1V[1]=1. 0 = Disabled - IO3 has no alternate function, hardware reset is disabled.
4	RFU	Reserved		0	Reserved For Future Use.
3	RL_NV	Read Latency		1	0 to 15 latency (dummy) cycles following read address or continuous mode bits. Note that bit 3 has a default value of 1 and may be programmed one time to 0 but cannot be returned to 1.
2				0	
1				0	
0				0	

Table 12.8 Configuration Register 2 Volatile (CR2V)

Bits	Field Name	Function	Type	Default State	Description
7	AL	Address Length	Volatile	CR2NV	1 = 4 byte address. 0 = 3 byte address.
6	QA	QPI			1 = Enabled - QPI (4-4-4) protocol in use. 0 = Disabled - Legacy SPI protocols in use, instruction is always serial on SI.
5	IO3R_S	IO3 Reset			1 = Enabled - IO3 is used as RESET# input when CS# is high or Quad Mode is disabled CR1V[1]=1. 0 = Disabled - IO3 has no alternate function, hardware reset is disabled.
4	RFU	Reserved			Reserved for Future Use.
3	RL	Read Latency			0 to 15 latency (dummy) cycles following read address or continuous mode bits.
2					
1					
0					

Table 12.9 Configuration Register 3 Non-Volatile (CR3NV)

Bits	Field Name	Function	Type	Default State	Description
7	RFU	Reserved	OTP	0	Reserved for Future Use.
6	RFU	Reserved		0	Reserved for Future Use.
5	BC_NV	Blank Check		0	1 = Blank Check during erase enabled. 0 = Blank Check disabled.
4	02h_NV	Page Buffer Wrap		0	1 = Wrap at 512 bytes. 0 = Wrap at 256 bytes.
3	20h_NV	4-kB Erase		0	1 = 4-kB Erase disabled (Uniform Sector Architecture). 0 = 4-kB Erase enabled (Hybrid Sector Architecture).
2	30h_NV	Clear Status / Resume Select		0	1 = 30h is Erase or Program Resume command. 0 = 30h is clear status command.
1	D8h_NV	Block Erase Size		0	1 = 256-kB Erase. 0 = 64-kB Erase.
0	F0h_NV	Legacy Software Reset Enable		0	1 = F0h software reset is enabled. 0 = F0h software reset is disabled (ignored).

Table 12.10 Configuration Register 3 Volatile (CR3V)

Bits	Field Name	Function	Type	Default State	Description
7	RFU	Reserved	Volatile	CR3NV	Reserved for Future Use.
6	RFU	Reserved			Reserved for Future Use.
5	BC_V	Blank Check			1 = Blank Check during erase enabled. 0 = Blank Check disabled.
4	02h_V	Page Buffer Wrap			1 = Wrap at 512 bytes. 0 = Wrap at 256 bytes.
3	20h_V	4-kB Erase	Volatile, Read Only		1 = 4-kB Erase disabled (Uniform Sector Architecture). 0 = 4-kB Erase enabled (Hybrid Sector Architecture).
2	30h_V	Clear Status / Resume Select	Volatile		1 = 30h is Erase or Program Resume command. 0 = 30h is Clear Status command.
1	D8h_V	Block Erase Size			1 = 256-kB Erase. 0 = 64-kB Erase.
0	F0h_V	Legacy Software Reset Enable			1 = F0h software reset is enabled. 0 = F0h software reset is disabled (ignored).

Table 12.11 Configuration Register 4 Non-Volatile (CR4NV)

Bits	Field Name	Function	Type	Default State	Description
7	OI_O	Output Impedance	OTP	0	See Table 8.25, Output Impedance Control on page 71.
6				0	
5				0	
4	WE_O	Wrap Enable		1	0 = Wrap Enabled. 1 = Wrap Disabled.
3	RFU	Reserved		0	Reserved for Future Use.
2	RFU	Reserved		0	Reserved for Future Use.
1	WL_O	Wrap Length		0	00 = 8-byte wrap. 01 = 16-byte wrap. 10 = 32-byte wrap. 11 = 64-byte wrap.
0				0	

Table 12.12 Configuration Register 4 Volatile (CR4V)

Bits	Field Name	Function	Type	Default State	Description
7	OI	Output Impedance	Volatile	CR4NV	See Table 8.25, Output Impedance Control on page 71.
6					
5					
4	WE	Wrap Enable			0 = Wrap Enabled. 1 = Wrap Disabled.
3	RFU	Reserved			Reserved for Future Use.
2	RFU	Reserved			Reserved for Future Use.
1	WL	Wrap Length			00 = 8-byte wrap. 01 = 16-byte wrap. 10 = 32-byte wrap. 11 = 64-byte wrap.
0					

Table 12.13 ASP Register (ASPR)

Bits	Field Name	Function	Type	Default State	Description
15 to 9	RFU	Reserved	OTP	1	Reserved for Future Use.
8	RFU	Reserved	OTP	1	Reserved for Future Use.
7	RFU	Reserved	OTP	1	Reserved for Future Use.
6	RFU	Reserved	OTP	1	Reserved for Future Use.
5	RFU	Reserved	OTP	1	Reserved for Future Use.
4	RFU	Reserved	RFU	1	Reserved for Future Use.
3	RFU	Reserved	RFU	1	Reserved for Future Use.
2	PWDMLB	Password Protection Mode Lock Bit	OTP	1	0 = Password Protection mode permanently enabled. 1 = Password Protection mode not permanently enabled.
1	PSTMLB	Persistent Protection Mode Lock Bit	OTP	1	0 = Persistent Protection mode permanently enabled. 1 = Persistent Protection mode not permanently enabled.
0	RFU	Reserved	RFU	1	Reserved for Future Use.

Table 12.14 Password Register (PASS)

Bits	Field Name	Function	Type	Default State	Description
63 to 0	PWD	Hidden Password	OTP	FFFFFFFF-FFFFFFFFh	Non-Volatile OTP storage of 64-bit password. The password is no longer readable after the password protection mode is selected by programming ASP register bit 2 to 0.

Table 12.15 PPB Lock Register (PPBL)

Bits	Field Name	Function	Type	Default State	Description
7 to 1	RFU	Reserved	Volatile	00h	Reserved for Future Use
0	PPBLOCK	Protect PPB Array	Volatile Read Only	ASPR[2:1] = 1xb = Persistent Protection Mode = 1 ASPR[2:1] = 01b = Password Protection Mode = 0	0 = PPB array protected. 1 = PPB array may be programmed or erased.

Table 12.16 PPB Access Register (PPBAR)

Bits	Field Name	Function	Type	Default State	Description
7 to 0	PPB	Read or Program per sector PPB	Non-Volatile	FFh	00h = PPB for the sector addressed by the PPBRD or PPBP command is programmed to 0, protecting that sector from program or erase operations. FFh = PPB for the sector addressed by the PPBRD command is 1, not protecting that sector from program or erase operations.

Table 12.17 DYB Access Register (DYBAR)

Bits	Field Name	Function	Type	Default State	Description
7 to 0	DYB	Read or Write per sector DYB	Volatile	FFh	00h = DYB for the sector addressed by the DYBRD or DYBWR command is cleared to 0, protecting that sector from program or erase operations. FFh = DYB for the sector addressed by the DYBRD or DYBWR command is set to 1, not protecting that sector from program or erase operations.

Table 12.18 Non-Volatile Data Learning Register (NVDLR)

Bits	Field Name	Function	Type	Default State	Description
7 to 0	NVDLP	Non-Volatile Data Learning Pattern	OTP	00h	OTP value that may be transferred to the host during DDR read command latency (dummy) cycles to provide a training pattern to help the host more accurately center the data capture point in the received data bits.

Table 12.19 Volatile Data Learning Register (VDLR)

Bits	Field Name	Function	Type	Default State	Description
7 to 0	VDLP	Volatile Data Learning Pattern	Volatile	Takes the value of NVDLR during POR or Reset	Volatile copy of the NVDLP used to enable and deliver the Data Learning Pattern (DLP) to the outputs. The VDLP may be changed by the host during system operation.

12.3 Serial Flash Discoverable Parameters (SFDP) Address Map

The SFDP address space has a header starting at address zero that identifies the SFDP data structure and provides a pointer to each parameter. One parameter is mandated by the JEDEC JESD216 standard. Spansion provides an additional parameter by pointing to the ID-CFI address space i.e. the ID-CFI address space is a sub-set of the SFDP address space. The JEDEC parameter is located within the ID-CFI address space and is thus both a CFI parameter and an SFDP parameter. In this way both SFDP and ID-CFI information can be accessed by either the RSFDP or RDID commands.

Table 12.20 SFDP Overview Map

Relative Byte Address Offset	SFDP Dword Address	Description
0000h	00h	Location zero within SFDP space - start of SFDP header.
...	...	Remainder of SFDP header followed by undefined space.
1000h	400h	Location zero within ID-CFI space - start of ID-CFI.
...	...	ID-CFI parameters.
1120h	448h	Start of SFDP JEDEC parameter which is also part of a CFI parameter.
...	...	Remainder of SFDP JEDEC parameter followed by either more CFI parameters or undefined space.

12.3.1 Field Definitions

Table 12.21 SFDP Header

Relative Byte Address Offset	SFDP Dword Address	Data	Description
00h	00h	53h	This is the entry point for Read SFDP (5Ah) command i.e. location zero within SFDP space ASCII "S"
01h		46h	ASCII "F"
02h		44h	ASCII "D"
03h		50h	ASCII "P"
04h	01h	00h	SFDP Minor Revision
05h		01h	SFDP Major Revision
06h		01h	Number of Parameter Headers (zero based, 01h = 2 parameters)
07h		FFh	Unused
08h	02h	00h	Manufacturer ID (JEDEC SFDP Mandatory Parameter)
09h		00h	Parameter Minor Revision
0Ah		01h	Parameter Major Revision
0Bh		09h	Parameter Table Length (in double words = Dwords = 4 byte units)
0Ch	03h	48h	Parameter Table Pointer Byte 0 (Dword = 4-byte aligned) JEDEC parameter byte offset = 1120h = 448h Dword address
0Dh		04h	Parameter Table Pointer Byte 1
0Eh		00h	Parameter Table Pointer Byte 2
0Fh		FFh	Unused
10h	04h	01h	Manufacturer ID (Spansion)
11h		00h	Parameter Minor Revision
12h		01h	Parameter Major Revision
13h		51h	Parameter Table Length (in double words = Dwords = 4-byte units)
14h	05h	00h	Parameter Table Pointer Byte 0 (Dword = 4-byte aligned) Entry point for ID-CFI parameter is byte offset = 1000h relative to SFDP location zero. 1000h Bytes = 400h Dwords
15h		04h	Parameter Table Pointer Byte 1
16h		00h	Parameter Table Pointer Byte 2
17h		FFh	Unused

12.4 Device ID and Common Flash Interface (ID-CFI) Address Map

12.4.1 Field Definitions

Table 12.22 Manufacturer and Device ID

Byte Address	Data	Description
00h	01h	Manufacturer ID for Spansion
01h	20h (128 Mb) 02h (256 Mb)	Device ID Most Significant Byte - Memory Interface Type
02h	18h (128 Mb) 19h (256 Mb)	Device ID Least Significant Byte - Density
03h	4Dh	ID-CFI Length - number bytes following. Adding this value to the current location of 03h gives the address of the last valid location in the ID-CFI legacy address map. The legacy CFI address map ends with the Primary Vendor-Specific Extended Query. The original legacy length is maintained for backward software compatibility. However, the CFI Query Identification String also includes a pointer to the Alternate Vendor-Specific Extended Query that contains additional information related to the FS-S family.
04h	00h (Uniform 256-kB physical sectors) 01h (Uniform 64-kB physical sectors)	Physical Sector Architecture The S25FS-S family may be configured with or without 4-kB parameter sectors in addition to the uniform sectors.
05h	81h (S25FS-S Family)	Family ID
06h	xxh	ASCII characters for Model Refer to Ordering Information on page 151 for the model number definitions.
07h	xxh	
08h	xxh	Reserved
09h	xxh	Reserved
0Ah	xxh	Reserved
0Bh	xxh	Reserved
0Ch	xxh	Reserved
0Dh	xxh	Reserved
0Eh	xxh	Reserved
0Fh	xxh	Reserved

Table 12.23 CFI Query Identification String

Byte Address	Data	Description
10h 11h 12h	51h 52h 59h	Query Unique ASCII string "QRY"
13h 14h	02h 00h	Primary OEM Command Set FL-P backward compatible command set ID
15h 16h	40h 00h	Address for Primary Extended Table
17h 18h	53h 46h	Alternate OEM Command Set ASCII characters "FS" for SPI (F) interface, S Technology
19h 1Ah	51h 00h	Address for Alternate OEM Extended Table

Table 12.24 CFI System Interface String

Byte Address	Data	Description
1Bh	17h	V _{DD} Min. (erase/program): 100 millivolts BCD
1Ch	19h	V _{DD} Max. (erase/program): 100 millivolts BCD
1Dh	00h	V _{PP} Min. voltage (00h = no V _{PP} present)
1Eh	00h	V _{PP} Max. voltage (00h = no V _{PP} present)
1Fh	09h	Typical timeout per single byte program 2 ^N μs
20h	09h	Typical timeout for Min. size Page program 2 ^N μs (00h = not supported)
21h	08h (4 kB or 64 kB) 0Ah (256 kB)	Typical timeout per individual Sector Erase 2 ^N ms
22h	0Fh (128 Mb) 10h (256 Mb)	Typical timeout for full chip erase 2 ^N ms (00h = not supported)
23h	02h	Max. timeout for byte program 2 ^N times typical
24h	02h	Max. timeout for page program 2 ^N times typical
25h	03h	Max. timeout per individual Sector Erase 2 ^N times typical
26h	03h	Max. timeout for full chip erase 2 ^N times typical (00h = not supported)

Table 12.25 Device Geometry Definition for Bottom Boot Initial Delivery State

Byte Address	Data	Description
27h	18h (128 Mb) 19h (256 Mb)	Device Size = 2^N bytes;
28h	02h	Flash Device Interface Description; 0000h = x8 only 0001h = x16 only 0002h = x8/x16 capable 0003h = x32 only 0004h = Single I/O SPI, 3-byte address 0005h = Multi I/O SPI, 3-byte address 0102h = Multi I/O SPI, 3- or 4-byte address
29h	01h	
2Ah	08h	Max. number of bytes in multi-byte write = 2^N 0000 = not supported 0008h = 256B page
2Bh	00h	
2Ch	03h	Number of Erase Block Regions within device 1 = Uniform Device, >1 = Boot Device
2Dh	07h	Erase Block Region 1 Information (refer to JEDEC JEP137) 8 sectors = 8-1 = 0007h 4-kB sectors = 256 bytes x 0010h
2Eh	00h	
2Fh	10h	
30h	00h	
31h	00h	Erase Block Region 2 Information (refer to JEDEC JEP137) 128 Mb and 256 Mb: 1 sector = 1-1 = 0000h 32-kB sector = 256 bytes x 0080h
32h	00h	
33h	80h	
34h	00h (128 Mb) 00h (256 Mb)	
35h	FEh	Erase Block Region 3 Information 128 Mb and 256 Mb: 255 sectors = 255-1 = 00FEh (128 Mb) 511 sectors = 511-1 = 01FEh (256 Mb) 64-kB sectors = 0100h x 256 bytes
36h	00h (128 Mb) 01h (256 Mb)	
37h	00h	
38h	01h (128 Mb) 01h (256 Mb)	
39h thru 3Fh	FFh	RFU

Note:

- FS-S devices are user configurable to have either a hybrid sector architecture (with eight 4-kB sectors and all remaining sectors are uniform 64 kB or 256 kB) or a uniform sector architecture with all sectors uniform 64 kB or 256 kB. FS-S devices are also user configurable to have the 4-kB parameter sectors at the top of memory address space. The CFI geometry information of the above table is relevant only to the initial delivery state. All devices are initially shipped from Spansion with the hybrid sector architecture with the 4-kB sectors located at the bottom of the array address map. However, the device configuration TBPARM bit CR1NV[2] may be programmed to invert the sector map to place the 4-kB sectors at the top of the array address map. The 20h_NV bit (CR3NV[3]) may be programmed to remove the 4-kB sectors from the address map. The flash device driver software must examine the TBPARM and 20h_NV bits to determine if the sector map was inverted or hybrid sectors removed at a later time.

Table 12.26 CFI Primary Vendor-Specific Extended Query

Byte Address	Data	Description
40h	50h	Query-unique ASCII string "PRI"
41h	52h	
42h	49h	
43h	31h	Major version number = 1, ASCII
44h	33h	Minor version number = 3, ASCII
45h	21h	Address Sensitive Unlock (Bits 1-0) 00b = Required, 01b = Not Required Process Technology (Bits 5-2) 0000b = 0.23 μ m Floating Gate 0001b = 0.17 μ m Floating Gate 0010b = 0.23 μ m MirrorBit 0011b = 0.11 μ m Floating Gate 0100b = 0.11 μ m MirrorBit 0101b = 0.09 μ m MirrorBit 1000b = 0.065 μ m MirrorBit
46h	02h	Erase Suspend 0 = Not Supported 1 = Read Only 2 = Read and Program
47h	01h	Sector Protect 00 = Not Supported X = Number of sectors in group
48h	00h	Temporary Sector Unprotect 00 = Not Supported 01 = Supported
49h	08h	Sector Protect/Unprotect Scheme 04 = High Voltage Method 05 = Software Command Locking Method 08 = Advanced Sector Protection Method
4Ah	00h	Simultaneous Operation 00 = Not Supported X = Number of Sectors
4Bh	01h	Burst Mode (Synchronous sequential read) support 00 = Not Supported 01 = Supported
4Ch	03h	Page Mode Type, initial delivery configuration, user configurable for 512B page 00 = Not Supported 01 = 4 Word Read Page 02 = 8-Read Word Page 03 = 256-byte Program Page 04 = 512-byte Program Page
4Dh	00h	ACC (Acceleration) Supply Minimum 00 = Not Supported, 100 mV
4Eh	00h	ACC (Acceleration) Supply Maximum 00 = Not Supported, 100 mV
4Fh	07h	WP# Protection 01 = Whole Chip 04 = Uniform Device with Bottom WP Protect 05 = Uniform Device with Top WP Protect 07 = Uniform Device with Top or Bottom Write Protect (user configurable)
50h	01h	Program Suspend 00 = Not Supported 01 = Supported

The Alternate Vendor-Specific Extended Query provides information related to the expanded command set provided by the FS-S family. The alternate query parameters use a format in which each parameter begins with an identifier byte and a parameter length byte. Driver software can check each parameter ID and can use the length value to skip to the next parameter if the parameter is not needed or not recognized by the software.

Table 12.27 CFI Alternate Vendor-Specific Extended Query Header

Byte Address	Data	Description
51h	41h	Query-unique ASCII string "ALT"
52h	4Ch	
53h	54h	
54h	32h	Major version number = 2, ASCII
55h	30h	Minor version number = 0, ASCII

Table 12.28 CFI Alternate Vendor-Specific Extended Query Parameter 0

Parameter Relative Byte Address Offset	Data	Description
00h	00h	Parameter ID (Ordering Part Number)
01h	10h	Parameter Length (The number of following bytes in this parameter. Adding this value to the current location value +1 = the first byte of the next parameter)
02h	53h	ASCII "S" for manufacturer (Spansion)
03h	32h	ASCII "25" for Product Characters (Single Die SPI)
04h	35h	
05h	46h	
06h	53h	ASCII "FS" for Interface Characters (SPI 1.8 Volt)
07h	31h (128 Mb) 32h (256 Mb)	ASCII characters for density
08h	32h (128 Mb) 35h (256 Mb)	
09h	38h (128 Mb) 36h (256 Mb)	
0Ah	53h	ASCII "S" for Technology (65 nm MirrorBit)
0Bh	FFh	Reserved for Future Use
0Ch	FFh	
0Dh	FFh	
0Eh	FFh	Reserved for Future Use
0Fh	FFh	
10h	xxh	ASCII characters for Model
11h	xxh	Refer to Ordering Information on page 151 for the model number definitions.

Table 12.29 CFI Alternate Vendor-Specific Extended Query Parameter 80h Address Options

Parameter Relative Byte Address Offset	Data	Description
00h	80h	Parameter ID (Ordering Part Number)
01h	01h	Parameter Length (The number of following bytes in this parameter. Adding this value to the current location value +1 = the first byte of the next parameter)
02h	EBh	Bits 7:5 - Reserved = 111b Bit 4 - Address Length Bit in CR2V[7] - Yes= 0b Bit 3 - AutoBoot support - No = 1b Bit 2 - 4 byte address instructions supported - Yes= 0b Bit 1 - Bank address + 3-byte address instructions supported - No = 1b Bit 0 - 3-byte address instructions supported - No = 1b

Table 12.30 CFI Alternate Vendor-Specific Extended Query Parameter 84h Suspend Commands

Parameter Relative Byte Address Offset	Data	Description
00h	84h	Parameter ID (Suspend Commands)
01h	08h	Parameter Length (The number of following bytes in this parameter. Adding this value to the current location value +1 = the first byte of the next parameter)
02h	75h	Program suspend instruction code
03h	28h	Program suspend latency maximum (μ s)
04h	7Ah	Program resume instruction code
05h	64h	Program resume to next suspend typical (μ s)
06h	75h	Erase suspend instruction code
07h	28h	Erase suspend latency maximum (μ s)
08h	7Ah	Erase resume instruction code
09h	64h	Erase resume to next suspend typical (μ s)

Table 12.31 CFI Alternate Vendor-Specific Extended Query Parameter 88h Data Protection

Parameter Relative Byte Address Offset	Data	Description
00h	88h	Parameter ID (Data Protection)
01h	04h	Parameter Length (The number of following bytes in this parameter. Adding this value to the current location value +1 = the first byte of the next parameter)
02h	0Ah	OTP size 2^N bytes, FFh = not supported
03h	01h	OTP address map format, 01h = FL-S and FS-S format FFh = not supported
04h	xxh	Block Protect Type, model dependent 00h = FL-P, FL-S, FS-S FFh = not supported
05h	xxh	Advanced Sector Protection type, model dependent 01h = FL-S and FS-S ASP.

Table 12.32 CFI Alternate Vendor-Specific Extended Query Parameter 8Ch Reset Timing

Parameter Relative Byte Address Offset	Data	Description
00h	8Ch	Parameter ID (Reset Timing)
01h	06h	Parameter Length (The number of following bytes in this parameter. Adding this value to the current location value +1 = the first byte of the next parameter)
02h	96h	POR maximum value
03h	01h	POR maximum exponent 2^N μ s
04h	23h	Hardware Reset maximum value, FFh = not supported (the initial delivery state has hardware reset disabled but it may be enabled by the user at a later time)
05h	00h	Hardware Reset maximum exponent 2^N μ s
06h	23h	Software Reset maximum value, FFh = not supported
07h	00h	Software Reset maximum exponent 2^N μ s

Table 12.33 CFI Alternate Vendor-Specific Extended Query Parameter F0h RFU

Parameter Relative Byte Address Offset	Data	Description
00h	F0h	Parameter ID (RFU)
01h	0Fh	Parameter Length (The number of following bytes in this parameter. Adding this value to the current location value +1 = the first byte of the next parameter)
02h	FFh	RFU
...	FFh	RFU
10h	FFh	RFU

This parameter type (Parameter ID F0h) may appear multiple times and have a different length each time. The parameter is used to reserve space in the ID-CFI map or to force space (pad) to align a following parameter to a required boundary.

Table 12.34 CFI Alternate Vendor-Specific Extended Query Parameter A5h, JEDEC SFDP (Sheet 1 of 2)

Parameter Relative Byte Address Offset	SFDP Relative Dword Address Offset	Data	Description
00h	N/A	A5h	CFI Parameter ID (JEDEC SFDP)
01h	N/A	3Ch	Parameter Length (The number of following bytes in this parameter. Adding this value to the current location value +1 = the first byte of the next parameter).
02h	00h JEDEC SFDP Parameter Dword-1	FFh	Start of SFDP JEDEC parameter Bits 7:5 = unused = 111b Bit 4 = 06h is Status Register write instruction = 1 Bit 3 = 00h must be written to Status Register to enable program and erase = 1 Bit 2 = Program Buffer > 64 bytes = 1 Bits 1:0 = Uniform 4-kB erase unavailable = 11b
03h		FFh	Uniform 4-kB erase opcode = not supported = FFh
04h		B2h (FSxxxSAG) BAh (FSxxxSDS)	Bit 23 = Unused = 1b Bit 22 = Supports Quad Out (1-1-4) Read = No = 0b Bit 21 = Supports Quad I/O (1-4-4) Read = Yes = 1b Bit 20 = Supports Dual I/O (1-2-2) Read = Yes = 1b Bit 19 = Supports DDR 0 = No, 1 = Yes Bit 18:17 = Number of Address Bytes, 3 or 4 = 01b Bit 16 = Supports Dual Out (1-1-2) Read = No = 0b
05h		FFh	Bits 31:24 = Unused = FFh
06h	01h JEDEC SFDP Parameter Dword-2	FFh	Density in bits, zero based
07h		FFh	
08h		FFh	
09h		07h (128 Mb) 0Fh (256 Mb)	
0Ah	02h JEDEC SFDP Parameter Dword-3	48h	Bits 7:5 = number of Quad I/O (1-4-4) Mode cycles = 010b Bits 4:0 = number of Quad I/O Dummy cycles = 01000b (Initial Delivery State)
0Bh		EBh	Quad I/O instruction code
0Ch		FFh	Bits 23:21 = number of Quad Out (1-1-4) Mode cycles = 111b Bits 20:16 = number of Quad Out Dummy cycles = 11111b
0Dh		FFh	Quad Out instruction code
0Eh	03h JEDEC SFDP Parameter Dword-4	FFh	Bits 7:5 = number of Dual Out (1-1-2) Mode cycles = 111b Bits 4:0 = number of Dual Out Dummy cycles = 11111b
0Fh		FFh	Dual Out instruction code
10h		88h	Bits 23:21 = number of Dual I/O (1-2-2) Mode cycles = 100b Bits 20:16 = number of Dual I/O Dummy cycles = 01000b (Initial Delivery State)
11h		BBh	Dual I/O instruction code

Table 12.34 CFI Alternate Vendor-Specific Extended Query Parameter A5h, JEDEC SFDP (Sheet 2 of 2)

Parameter Relative Byte Address Offset	SFDP Relative Dword Address Offset	Data	Description
12h	04h JEDEC SFDP Parameter Dword-5	F6h	Bits 7:5 RFU = 111b Bit 4 = QPI supported = Yes = 1b Bits 3:1 RFU = 11b Bit 0 = Dual All not supported = 0b
13h		FFh	Bits 15:8 = RFU = FFh
14h		FFh	Bits 23:16 = RFU = FFh
15h		FFh	Bits 31:24 = RFU = FFh
16h	05h JEDEC SFDP Parameter Dword-6	FFh	Bits 7:0 = RFU = FFh
17h		FFh	Bits 15:8 = RFU = FFh
18h		FFh	Bits 23:21 = number of Dual All Mode cycles = 111b Bits 20:16 = number of Dual All Dummy cycles = 11111b
19h		FFh	Dual All instruction code
1Ah	06h JEDEC SFDP Parameter Dword-7	FFh	Bits 7:0 = RFU = FFh
1Bh		FFh	Bits 15:8 = RFU = FFh
1Ch		48h	Bits 23:21 = number of QPI Mode cycles = 010b Bits 20:16 = number of QPI Dummy cycles = 01000b
1Dh		EBh	QPI Mode (4-4-4) instruction code
1Eh	07h JEDEC SFDP Parameter Dword-8	0Ch	Sector type 1 size 2^N Bytes = 4-kB = 0Ch for Hybrid (Initial Delivery State)
1Fh		20h	Sector type 1 instruction
20h		10h (128 Mb) 10h (256 Mb)	Sector type 2 size 2^N Bytes = 64 kB = 10h for 128 Mb and 256 Mb
21h		D8	Sector type 2 instruction
22h	08h JEDEC SFDP Parameter Dword-9	00h	Sector type 3 size 2^N Bytes = not supported = 00h
23h		FFh	Sector type 3 instruction = not supported = FFh
24h		00h	Sector type 4 size 2^N Bytes = not supported = 00h
25h		FFh	Sector type 4 instruction = not supported = FFh

12.5 Initial Delivery State

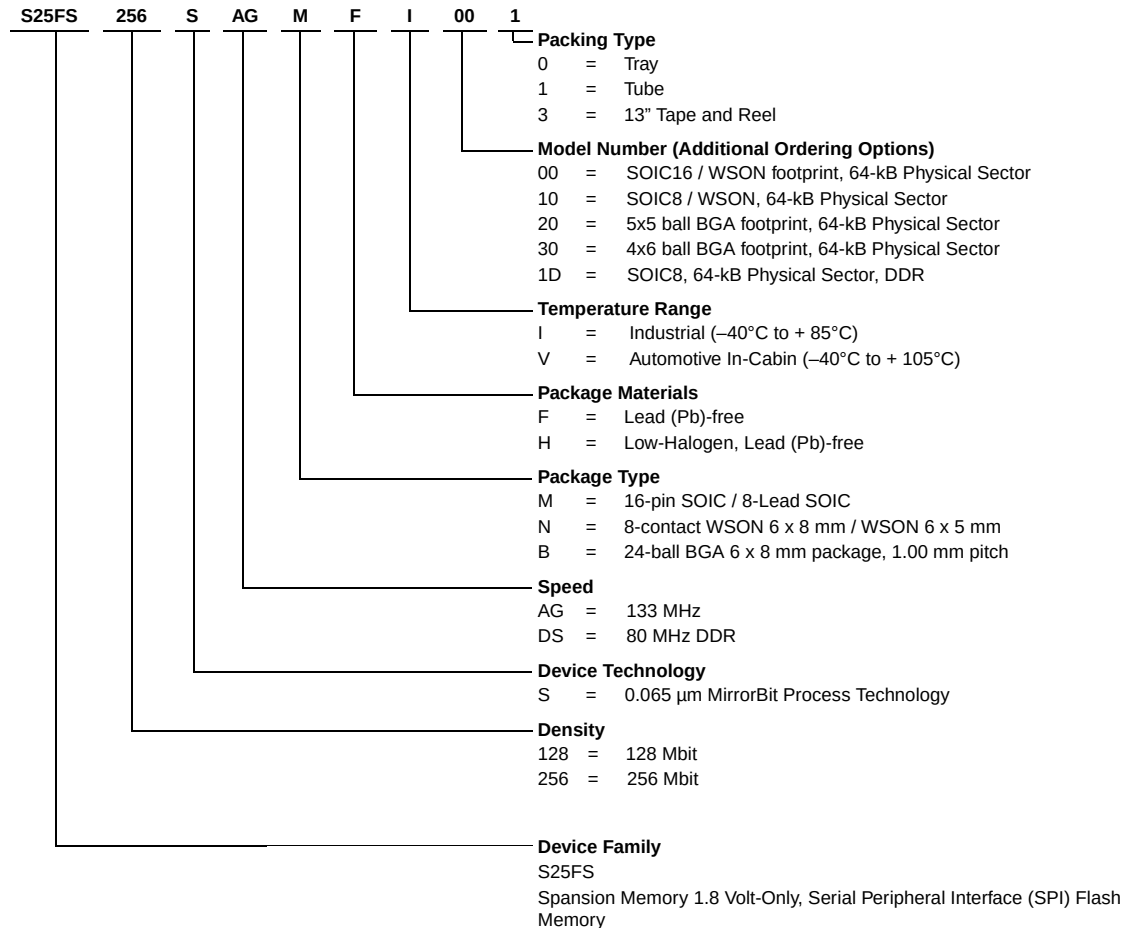
The device is shipped from Spansion with non-volatile bits set as follows:

- The entire memory array is erased: i.e. all bits are set to 1 (each byte contains FFh).
- The OTP address space has the first 16 bytes programmed to a random number. All other bytes are erased to FFh.
- The SFDP address space contains the values as defined in the description of the SFDP address space.
- The ID-CFI address space contains the values as defined in the description of the ID-CFI address space.
- The Status Register 1 Non-Volatile contains 00h (all SR1NV bits are cleared to 0's).
- The Configuration Register 1 Non-Volatile contains 00h.
- The Configuration Register 2 Non-Volatile contains 08h.
- The Configuration Register 3 Non-Volatile contains 00h.
- The Configuration Register 4 Non-Volatile contains 10h.
- The Password Register contains FFFFFFFF-FFFFFFFh
- All PPB bits are 1.
- The ASP Register bits are FFFFh

Ordering Information

13. Ordering Part Number

The ordering part number is formed by a valid combination of the following:



Valid Combinations

Valid Combinations list configurations planned to be supported in volume for this device. Consult your local sales office to confirm availability of specific valid combinations and to check on newly released combinations.

Valid Combinations					
Base Ordering Part Number	Speed Option	Package and Temperature	Model Number	Packing Type	Package Marking
S25FS128S	AG	MFI, MFV	10	0, 1, 3	FS128S + (Temp) + F + (Model Number)
	AG	NFI, NFV	10	0, 1, 3	FS128S + A + (Temp) + F + (Model Number)
	AG	BHI, BHV	20, 30	0, 3	FS128S + A + (Temp) + H + (Model Number)
	DS	MFI, MFV	1D	0, 1, 3	FS128S + (Temp) + F + (Model Number)
	DS	NFI, NFV	10	0, 1, 3	FS128S + D + (Temp) + F + (Model Number)
	DS	BHI, BHV	20, 30	0, 3	FS128S + D + (Temp) + H + (Model Number)
S25FS256S	AG	MFI, MFV	00	0, 1, 3	FS256S + A + (Temp) + F + (Model Number)
	AG	NFI, NFV	00	0, 1, 3	FS256S + A + (Temp) + F + (Model Number)
	AG	BHI, BHV	20, 30	0, 3	FS256S + A + (Temp) + H + (Model Number)
	DS	MFI, MFV	00	0, 1, 3	FS256S + D + (Temp) + F + (Model Number)
	DS	NFI, NFV	00	0, 1, 3	FS256S + D + (Temp) + F + (Model Number)
	DS	BHI, BHV	20, 30	0, 3	FS256S + D + (Temp) + H + (Model Number)

14. Contacting SpanSion

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15. Revision History

Section	Description
Revision 01 (April 5, 2013)	
	Initial release
Revision 02 (April 8, 2013)	
Initial Delivery State	Corrected information on <i>Configuration Register 2</i>
Revision 03 (August 22, 2013)	
Global	Replaced 'Quad All' with 'QPI'
Performance Summary	Typical Program and Erase Rates table: corrected kbytes / s
Migration Notes	Spansion SPI Families Comparison table: corrected Page Programming Rate (typ.) for FS-S
DC Characteristics	FS-S DC Characteristics table: added I_{SB} (Automotive)
SDR AC Characteristics	AC Characteristics table: updated Parameter for $F_{SCK, C}$
Registers	Latency Code (Cycles) Versus Frequency table: updated table added Note 4
Embedded Algorithm Performance Tables	Program and Erase Performance table: corrected Typ and Max values for t_{pp}
Ordering Information	Added 1D and 5D to Model Number Valid Combinations table: corrected Model Number for S25FS128S
Revision 04 (November 6, 2013)	
Global	Changed data sheet designation from "Advance Information" to "Preliminary" Changed USON to WSON
Physical Interface	Added figure: 8-Pin Plastic Small Outline Package (SOIC8) Updated figure: 8-Connector Package (WSON 6x5) Removed figure: VSOP Thin 8-Lead, 208 mil Body Width, (SOV008)
Configuration Register 4	Updated Output Impedance Control table
Ordering Information	Updated Model Numbers and Package Type
Revision 05 (December 20, 2013)	
Migration Notes	Changed Quad Read Speed (DDR) for FL-S
DDR AC Characteristics	Updated AC Characteristics 80 MHz Operation table
DDR Output Timing	SPI DDR Data Valid Window figure: updated figure and Notes

Colophon

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