



Programmable, Off-Line, PWM Controller

FEATURES

- All Control, Driving, Monitoring, and Protection Functions Included
- Low-Current Off Line Start Circuit
- Voltage Feed Forward or Current Mode Control
- High Current Totem Pole Output
- 50% Absolute Max Duty Cycle
- PWM Latch for Single Pulse Per Period
- Pulse-by-Pulse Current Limiting plus Shutdown for Over-Current Fault
- No Start-Up or Shutdown Transients
- Slow Turn-On Both Initially and After Fault Shutdown
- Shutdown Upon Over or Under Voltage Sensing
- Latch Off or Continuous Retry After Fault
- 1% Reference Accuracy
- 500kHz Operation
- 18 Pin DIL or 20 Pin PLCC Package

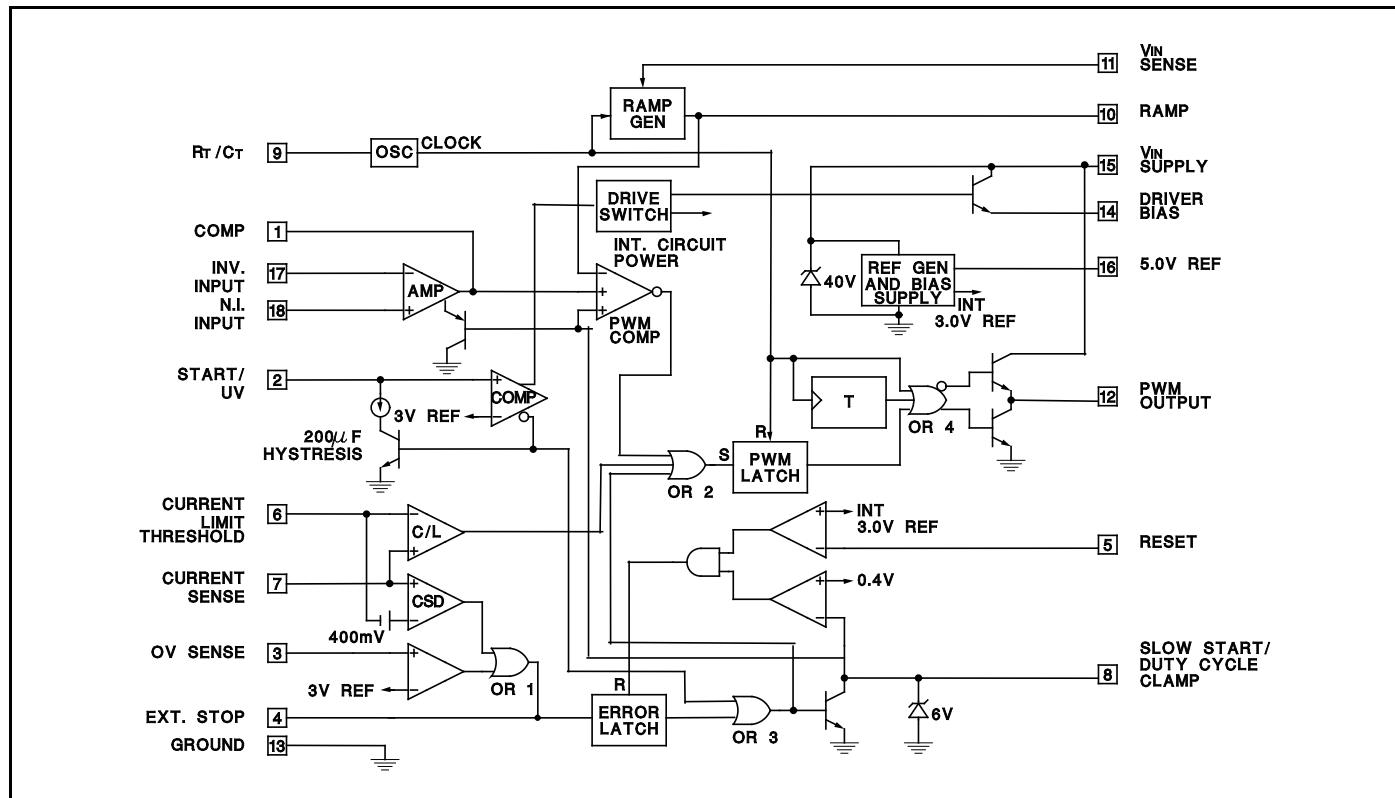
DESCRIPTION

The UC1851 family of PWM controllers are optimized for off-line primary side control. These devices include a high current totem pole output stage and a toggle flip-flop for absolute 50% duty cycle limiting. In all other respects this line of controllers is pin for pin compatible with the UC1841 series. Inclusion of all major housekeeping functions in these high performance controllers makes them ideal for use in cost sensitive applications.

Important features of these controllers include low current start-up, linear feed-forward for constant volt-second operation, and compatibility with both voltage or current mode control. In addition, these devices include a programmable start threshold, as well as programmable over-voltage, under-voltage, and over current fault thresholds. The fault latch on these devices can be configured for automatic restart, or latched off response to a fault.

These devices are packaged in 18-pin plastic or ceramic dual-in-line packages, or for surface mount applications, a 20 Pin PLCC. The UC1851 is characterized for -55°C to +125°C operation while the UC2851 and UC3851 are designed for -40°C to +85°C and 0°C to +70°C, respectively.

BLOCK DIAGRAM



ABSOLUTE MAXIMUM RATINGS (Note 1)

Supply Voltage, +VIN (Pin 15)

Voltage Driven	+32V
Current Driven, 100mA maximum	Self-limiting
PWM Output Voltage (Pin 12)	40V
PWM Output Current, Steady-State (Pin 12)	400mA
PWM Output Peak Energy Discharge	20μJoules
Driver Bias Current (Pin 14)	-200mA
Reference Output Current (Pin 16)	-50mA
Slow-Start Sink Current (Pin 8)	20mA
VIN Sense Current (Pin 11)	10mA
Current Limit Inputs (Pins 6 & 7)	-0.5 to +5.5V
Stop Input (Pin 4)	-0.3 to +5.5V

Comparator Inputs

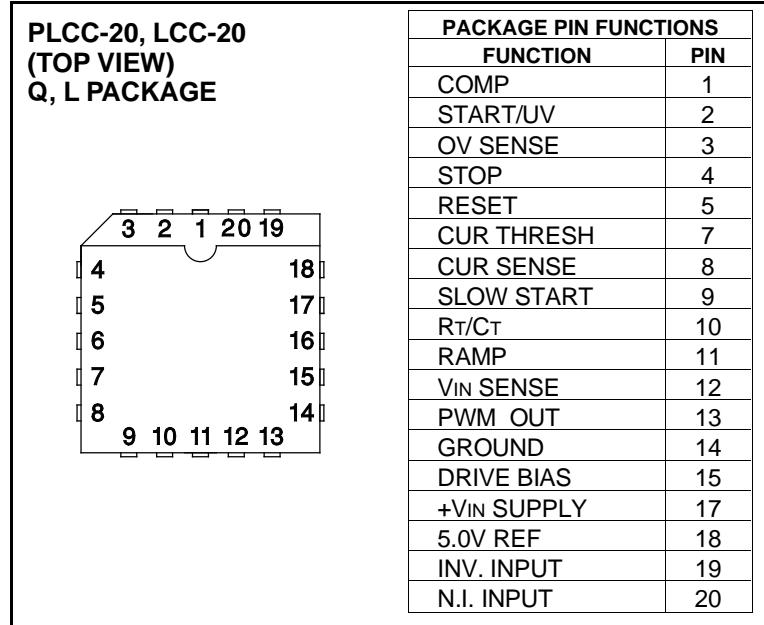
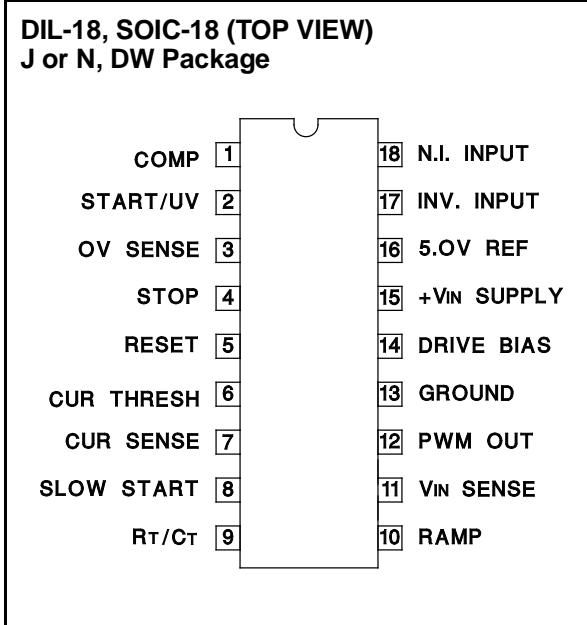
(Pins 1–7, 9–11, 16)	Internally clamped at 12V
Power Dissipation at $T_A = 25^\circ\text{C}$ (Note 3)	1000mW
Power Dissipation at $T_C = 25^\circ\text{C}$ (Note 3)	2000mW
Operating Junction Temperature	-55°C to +150°C
Storage Temperature Range	-65°C to +150°C
Lead Temperature (Soldering, 10 sec)	+300°C

Note 1: All voltages are with respect to ground, Pin 13.

Currents are positive-into, negative-out of the specified terminal

Note 2: All pin numbers are referenced to DIL-18 package.

Note 3: Consult Packaging Section of Databook for thermal limitations and considerations of package.

CONNECTION DIAGRAMS

ELECTRICAL CHARACTERISTICS: Unless otherwise stated, these specifications apply for $T_A = -55^\circ\text{C}$ to $+125^\circ\text{C}$ for the UC1851, -40°C to $+85^\circ\text{C}$ for the UC2851, and 0°C to 70°C for the UC3851; $VIN = 20V$, $RT = 20k\Omega$, $CT = .001 \text{ mfd}$, $RR = 10k\Omega$, $CR = .001 \text{ mfd}$. Current Limit Threshold = 200mV, $T_A = T_J$.

PARAMETER	TEST CONDITIONS	UC1851 / UC2851			UC3851			UNITS
		MIN	TYP	MAX	MIN	TYP	MAX	
Power Inputs								
Start-Up Current	$VIN = 30V$, Pin 2 = 2.5V		4.5	6		4.5	6	mA
Operating Current	$VIN = 30V$, Pin 2 = 3.5V		15	21		15	21	mA
Supply OV Clamp	$VIN = 20mA$	33	39	45	33	39	45	V
Reference Section								
Reference Voltage	$T_J = 25^\circ\text{C}$	4.95	5.0	5.05	4.9	5.0	5.1	V
Line Regulation	$VIN = 8$ to $30V$		10	15		10	20	mV
Load Regulation	$I_L = 0$ to $10mA$		10	20		10	30	mV
Total Ref Variation	Over Operating Temperature Range	4.9		5.1	4.85		5.15	V
Short Circuit Current	$V_{REF} = 0$, $T_J = 25^\circ\text{C}$		-80	-100		-80	-100	mA
Oscillator								
Nominal Frequency	$T_J = 25^\circ\text{C}$	47	50	53	45	50	55	kHz
Voltage Stability	$VIN = 8$ to $30V$		0.5	1		0.5	1	%
Total Ref Variation	Over Operating Temperature Range	45		55	43		57	kHz
Maximum Frequency	$RT = 2k\Omega$, $CT = 330\text{pF}$	500			500			kHz

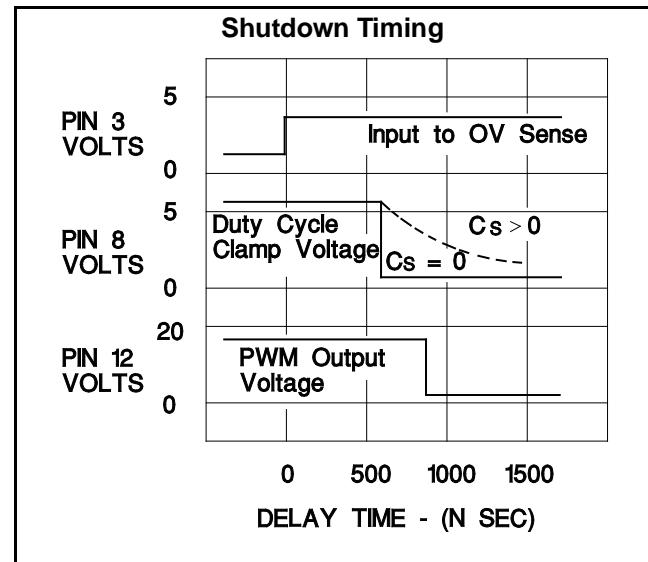
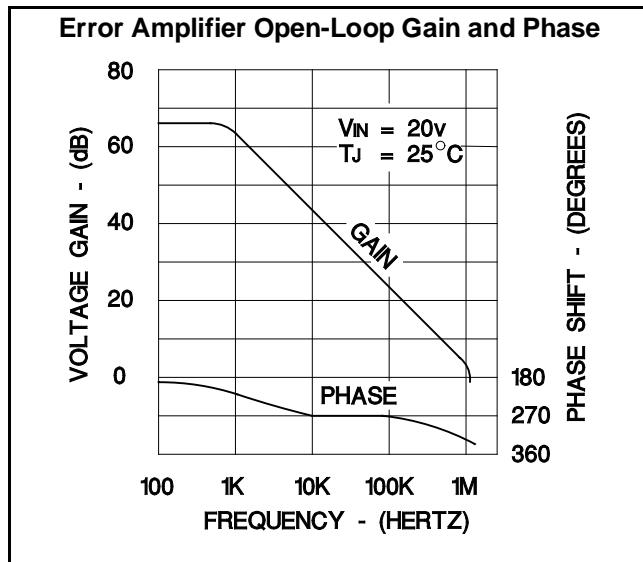
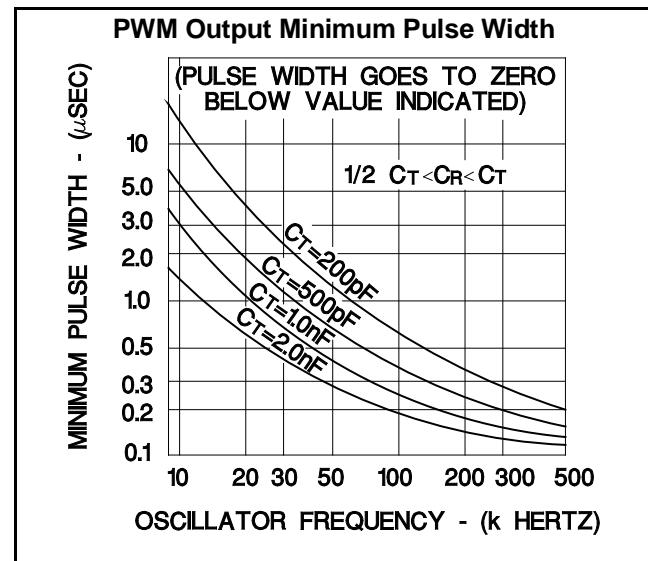
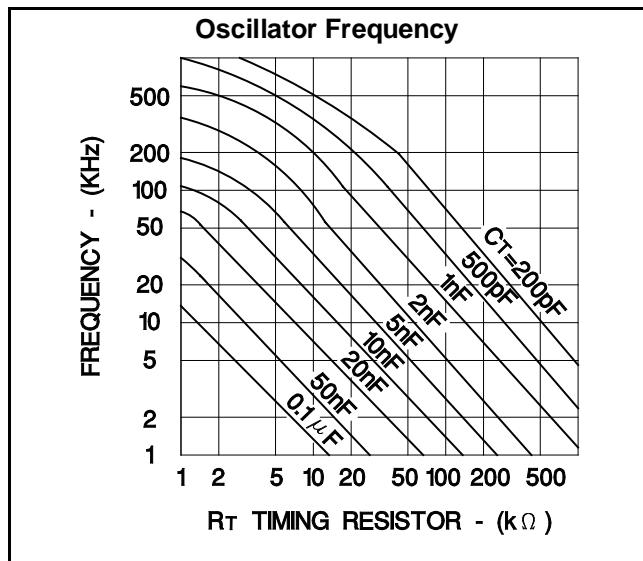
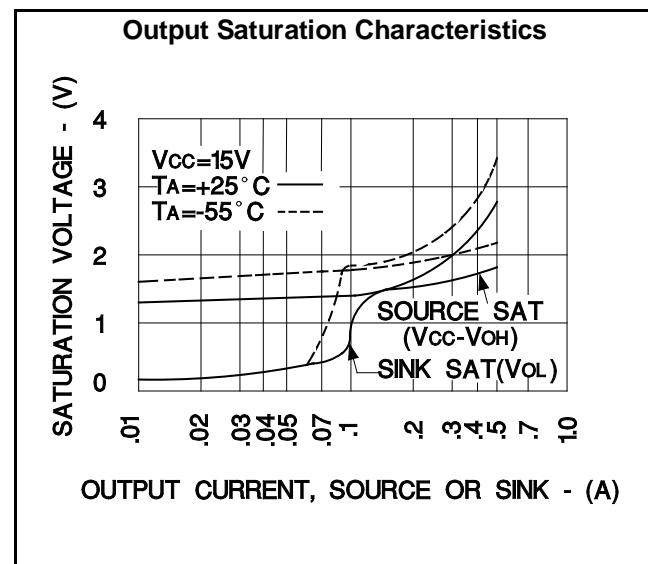
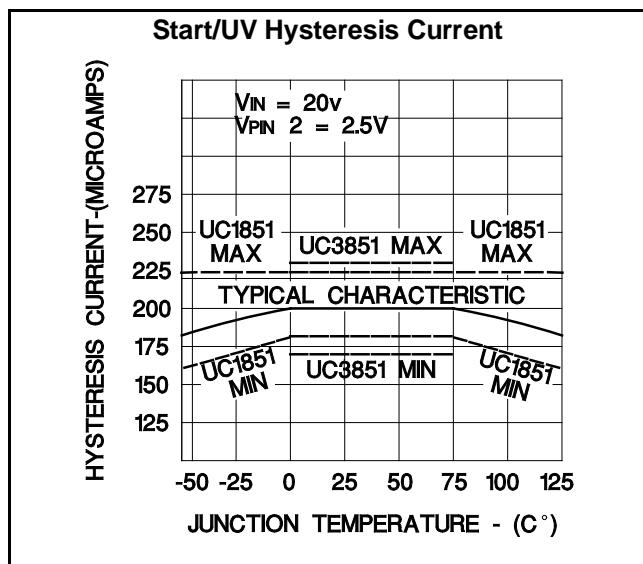
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PARAMETER	TEST CONDITIONS	UC1851 / UC2851			UC3851			UNITS
		MIN	TYP	MAX	MIN	TYP	MAX	
Ramp Generator								
Ramp Current, Minimum	$I_{SENSE} = -10\mu\text{A}$		-11	-14		-11	-14	μA
Ramp Current, Maximum	$I_{SENSE} = 1.0\text{mA}$	-0.9	-.95		-0.9	-.95		mA
Ramp Valley		0.3	0.4	0.6	0.3	0.4	0.6	V
Ramp Peak	Clamping Level	3.9	4.2	4.5	3.9	4.2	4.5	V
Error Amplifier								
Input Offset Voltage	$V_{CM} = 5.0\text{V}$		0.5	5		2	10	mV
Input Bias Current			0.5	2		1	5	μA
Input Offset Current				0.5			0.5	μA
Open Loop Gain	$\Delta V_O = 1$ to 3V	60	66		60	66		dB
Output Swing (Max Output \leq Ramp Peak - 100mV)	Minimum Total Range	0.3		3.5	0.3		3.5	V
CMRR	$V_{CM} = 1.5$ to 5.5V	70	80		70	80		dB
PSRR	$V_{IN} = 8$ to 30V	70	80		70	80		dB
Short Circuit Current	$V_{COMP} = 0\text{V}$		-4	-10		-4	-10	mA
Gain Bandwidth (Note 1)	$T_J = 25^\circ\text{C}$, $AVOL = 0\text{dB}$	1	2		1	2		MHz
Slew Rate (Note 1)	$T_J = 25^\circ\text{C}$, $AVCL = 0\text{dB}$		0.8			0.8		$\text{V}/\mu\text{s}$
PWM Section								
Continuous Duty Cycle Range (other than zero) (Note 1)	Minimum Total Continuous Range Ramp Peak $< 4.2\text{V}$	2		46	2		46	%
Output High Level	$I_{SOURCE} = 20\text{mA}$	18	18.5		18	18.5		V
	$I_{SOURCE} = 200\text{mA}$	17	18.5		17	18.5		V
Rise Time (Note 1)	$T_J = 25^\circ\text{C}$, $C_L = 1\text{nF}$		50	150		50	150	ns
Fall Time (Note 1)	$T_J = 25^\circ\text{C}$, $C_L = 1\text{nF}$		50	150		50	150	ns
Output Saturation	$I_{OUT} = 20\text{mA}$		0.2	0.4		0.2	0.4	V
	$I_{OUT} = 200\text{mA}$		1.7	2.2		1.7	2.2	V
Comparator Delay (Note 1)	Pin 8 to Pin 12, $T_J = 25^\circ\text{C}$, $R_L = 1\text{k}\Omega$		300	500		300	500	ns
Sequencing Functions								
Comparator Thresholds	Pins 2, 3, 5	2.8	3.0	3.2	2.8	3.0	3.2	V
Input Bias Current	Pins 3, 5 = 0V		-1.0	-4.0		-1.0	-4.0	μA
Input Leakage	Pins 3, 5 = 10V		0.1	2.0		0.1	2.0	μA
Start/UV Hysteresis Current	Pin 2 = 2.5V	170	200	220	170	200	230	μA
Ext. Stop Threshold	Pin 4	0.8	1.6	2.4	0.8	1.6	2.4	V
Error Latch Activate Current	Pin 4 = 0V , Pin 3 > 3V		-120	-200		-120	-200	μA
Driver Bias Saturation Voltage, $V_{IN}-V_{OH}$	$I_B = -50\text{mA}$		2	3		2	3	V
Driver Bias Leakage	$V_B = 0\text{V}$		-0.1	-10		-0.1	-10	μA
Slow-Start Saturation	$I_S = 10\text{mA}$		0.2	0.5		0.2	0.5	V
Slow-Start Leakage	$V_S = 4.5\text{V}$		0.1	2.0		0.1	2.0	μA
Current Control								
Current Limit Offset			0	5		0	10	mV
Current Shutdown Offset		370	400	430	360	400	440	mV
Input Bias Current	Pin 7 = 0V		-2	-5		-2	-5	μA
Common Mode Range (Note 1)		-0.4		3.0	-0.4		3.0	V
Current Limit Delay (Note 1)	$T_J = 25^\circ\text{C}$, Pin 7 to 12, $R_L = 1\text{k}$		200	400		200	400	ns

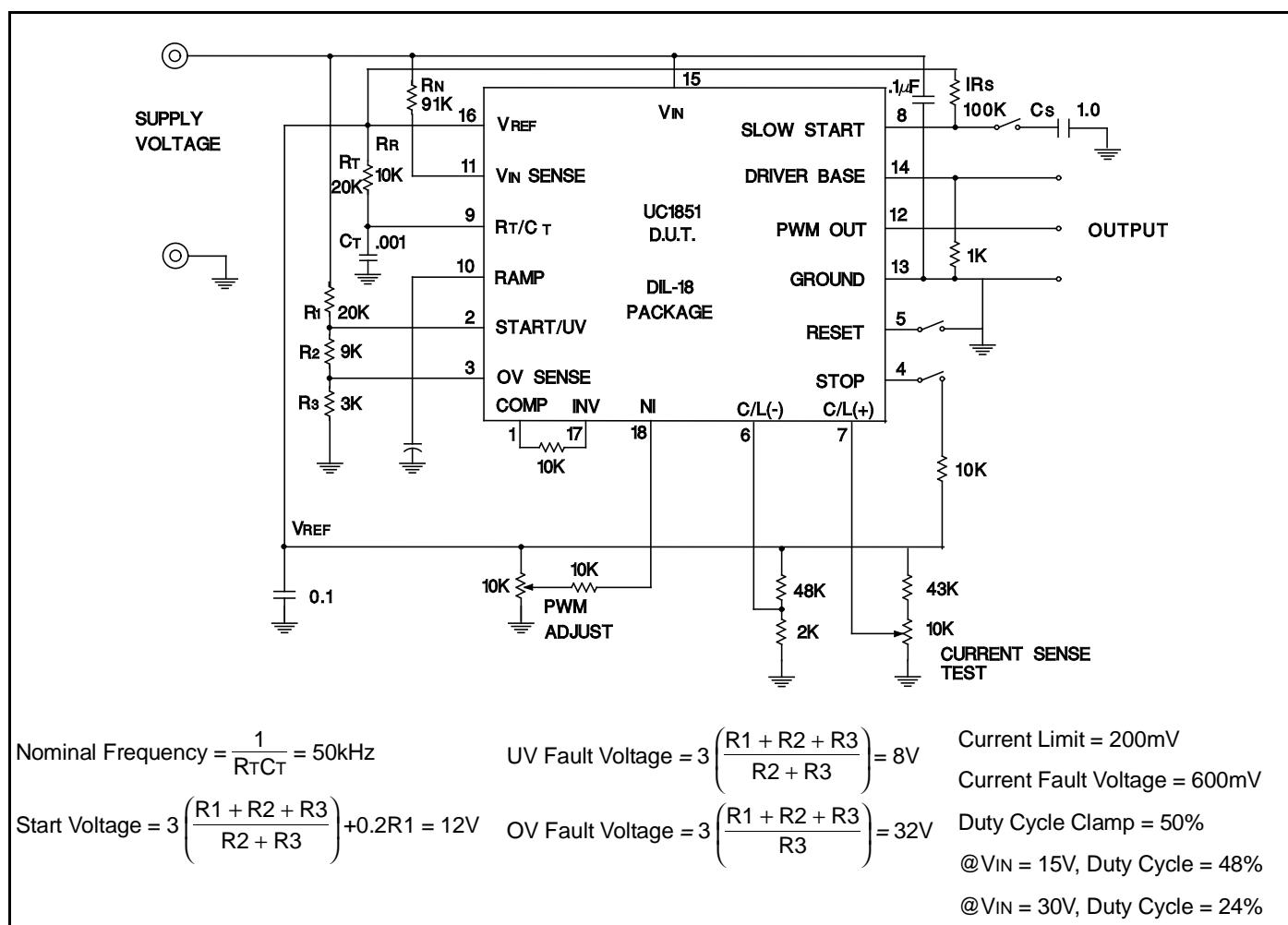
Note 1: Guaranteed by design. Not 100% tested in production.

FUNCTIONAL DESCRIPTION

PWM CONTROL	
1. Oscillator	Generates a fixed-frequency internal clock from an external R_T and C_T . Frequency = $\frac{K_C}{R_T C_T}$ where K_C is a first-order correction factor $\approx 0.3 \log (C_T \times 10^{12})$.
2. Ramp Generator:	Develops linear ramp with slope defined externally by $\frac{dV}{dt} = \frac{\text{sense voltage}}{R_R C_R}$. C_R is normally selected $\leq C_T$ and its value will have some effect upon valley duty cycle. Limiting the minimum value for I_{SENSE} into pin 11 will establish a maximum duty cycle clamp. C_R terminal can be used as an input port for current mode control.
3. Error Amplifier	Conventional operational amplifier for closed-loop gain and phase compensation. Low output impedance; unity-gain stable. The output is held low by the slow start voltage at turn on in order to minimize overshoot.
4. Reference Generator:	Precision 5.0V for internal and external usage to 50mA. Tracking 3.0V reference for internal usage only with nominal accuracy of $\pm 2\%$. 40V clamp zener for chip OV protection, 100mA maximum current.
5. PWM Comparator:	Generates output pulse which starts at termination of clock pulse and ends when the ramp input crosses the lowest of two positive inputs.
6. PWM Latch:	Terminates the PWM output pulse when set by inputs from either the PWM comparator, the pulse-by-pulse comparator, or the error latch. Resets with each internal clock pulse.
7. PWM Output Switch:	Totem pole output stage capable of sourcing and sinking 1 amp peak current. The active "on" state is high.
SEQUENCING FUNCTIONS	
1. Start/UV Sense:	With an increasing voltage, this comparator generates a turn-on signal and releases the slow start clamp at a start threshold. With a decreasing voltage, it generates a turn-off command at a lower level separated by a $200\mu A$ hysteresis current.
2. Drive Switch:	Disables most of the chip to hold internal current consumption low, and Driver Bias OFF, until input voltage reaches start threshold.
3. Driver Bias:	Supplies drive to external circuitry upon start-up.
4. Slow Start:	Clamps low to hold PWM OFF. Upon release, rises with rate controlled by $R_s C_s$ for slow increase of output pulse width. Can also be used as an alternate maximum duty cycle clamp with an external voltage divider.
PROTECTION FUNCTIONS	
1. Error Latch:	When set by momentary input, this latch insures immediate PWM shutdown and hold off until reset. Inputs to Error Latch are: a. OV $> 3.2V$ (Typically 3V) b. Stop $> 2.4V$ (Typically 1.6V) c. Current Sense 400mV over threshold. (Typical). Error Latch resets when slow start voltage falls to 0.4V if Reset Pin $< 2.8V$. With Pin 5 $> 3.2V$, Error Latch will remain set.
2. Current Limiting:	Differential input comparator terminates individual output pulses each time sense voltage rises above threshold. When sense voltage rises to 400mV (typical) above threshold, a shutdown signal is sent to Error Latch.
3. External Stop:	A voltage over 2.4 will set the Error Latch and hold the output off. A voltage less than 0.8V will defeat the error latch and prevent shutdown. A capacitor here will slow the action of the error latch for transient protection by providing a Typical Delay of 13ms/ μF .

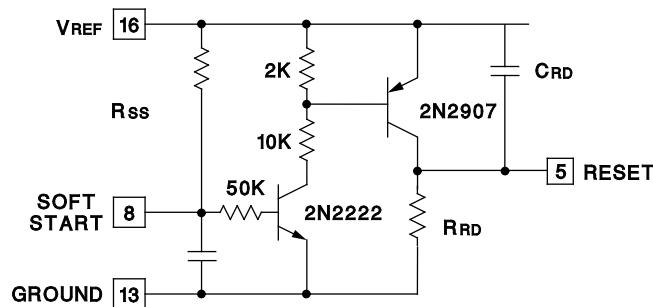


OPEN-LOOP CIRCUIT



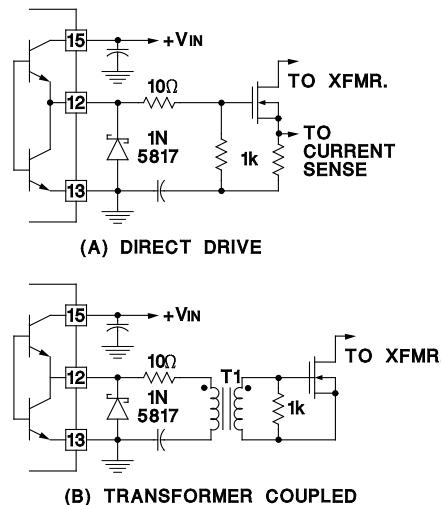
High Peak currents associated with capacitive loads necessitate careful grounding techniques. Timing and bypass capacitors should be connected close to pin 13 in a single ground point.

Programmable Soft Start and Restart Delay Circuit



For further application information see UC1840/UC1841
Data Sheets

UC1851 Power MOSFET Drive Interface



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