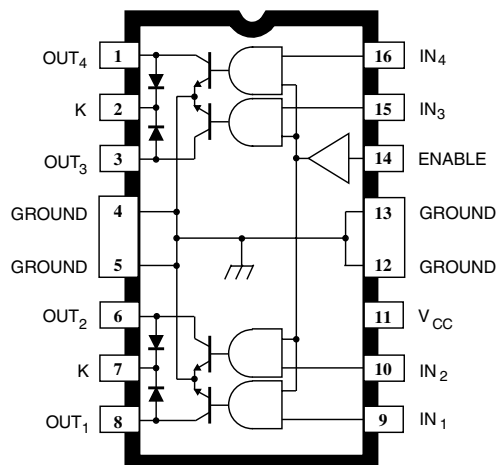


## PROTECTED QUAD POWER DRIVER

UDx2549B



Dwg. PP-017-1

### ABSOLUTE MAXIMUM RATINGS at $T_A = 25^\circ\text{C}$

|                                                           |                 |
|-----------------------------------------------------------|-----------------|
| Output Voltage, $V_{OUT}$ .....                           | 60 V            |
| Over-Current Protected Output Voltage,<br>$V_{OUT}$ ..... | 25 V            |
| Output Current, $I_{OUT}$ .....                           | 1.0 A*          |
| Supply Voltage, $V_{CC}$ .....                            | 7.0 V           |
| Input Voltage, $V_{IN}$ or $V_{EN}$ .....                 | 7.0 V           |
| Package Power Dissipation,<br>$P_D$ .....                 | See Graph       |
| Operating Temperature Range, $T_A$                        |                 |
| Prefix 'UDK' .....                                        | -40°C to +125°C |
| Prefix 'UDN' .....                                        | -20°C to +85°C  |
| Prefix 'UDQ' .....                                        | -40°C to +85°C  |
| Storage Temperature Range,<br>$T_S$ .....                 | -55°C to +150°C |

\*Outputs are peak current limited at approximately 1.0 A per driver. See Circuit Description and Applications for further information.

Providing improved output current limiting, the UDK/UDN/UDQ2549B and UDK/UDN/UDQ2549EB quad power drivers combine AND logic gates and high-current bipolar outputs with complete output protection. Each of the four outputs will sink 600 mA in the on state. The outputs have a minimum breakdown voltage (load dump) of 60 V and a sustaining voltage of 40 V. The inputs are compatible with TTL and 5 V CMOS logic systems.

Over-current protection for each channel has been designed into these devices and is activated at approximately 1 A. It protects each output from short circuits with supply voltages up to 25 V. When an output current trip point is reached, that output stage is driven linearly resulting in a reduced output current level. If an over-current or short circuit condition continues, the thermal limiting circuits will first sense the rise in junction temperature and then the rise in chip temperature, further decreasing the output current. Under worst-case conditions, the six devices in this family will tolerate short-circuits on all outputs, simultaneously.

These devices can be used to drive various loads including incandescent lamps (without warming or limiting resistors) or inductive loads such as relays, solenoids, or dc stepping motors.

The suffix 'B' devices are 16-pin power DIPs while the suffix 'EB' devices are 28-lead power PLCCs for surface-mount applications. Both packages are of batwing construction to provide for maximum package power dissipation.

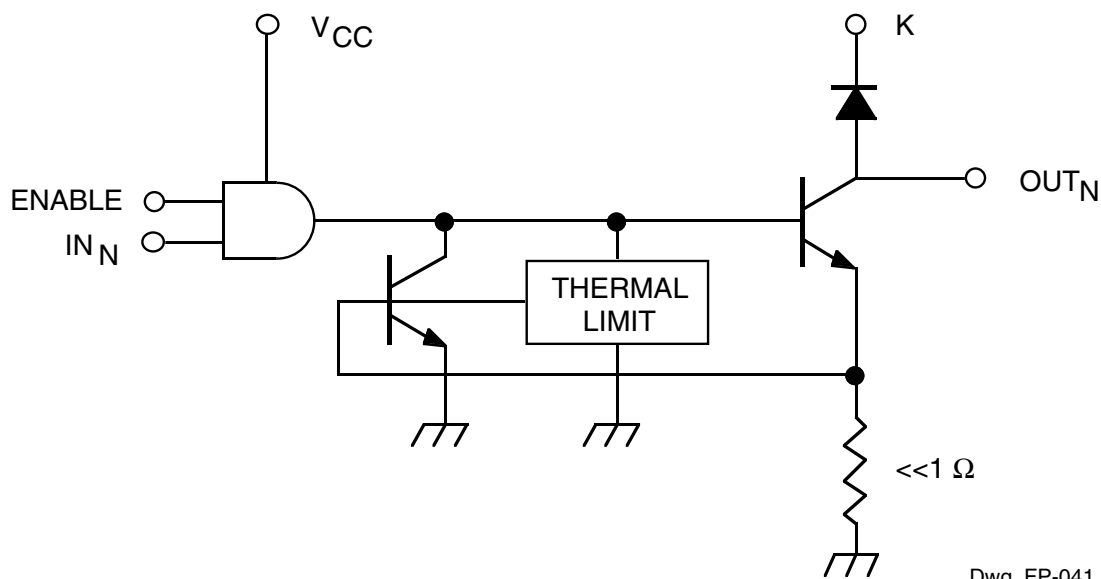
### FEATURES

- 600 mA Output Current per Channel
- Independent Over-Current Protection for Each Driver
- Thermal Protection for Device and Each Driver
- Low Output-Saturation Voltage
- Integral Output Flyback Diodes
- TTL and 5 V CMOS Compatible Inputs
- Pin-Compatible With UDN2543B/EB

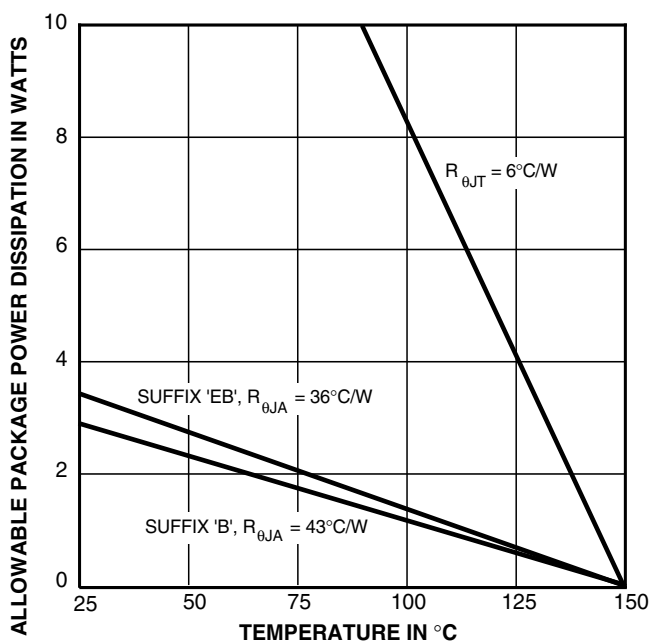
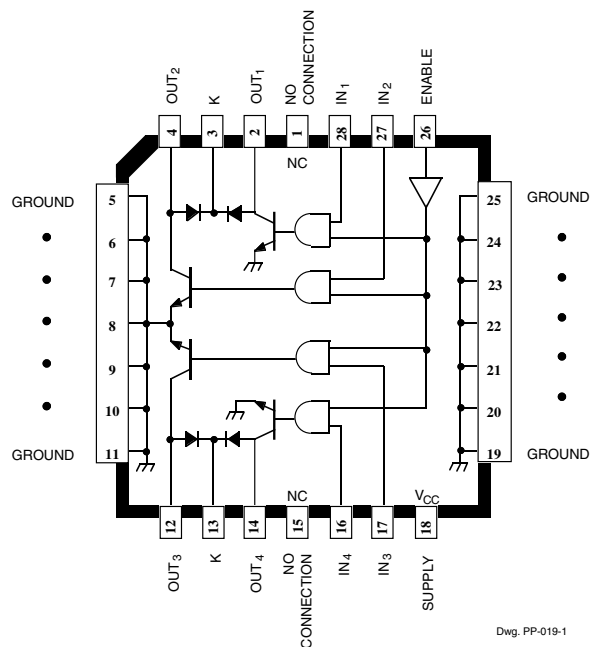
Always order by complete part number: a prefix to indicate operating temperature range + the basic four-digit part number + a suffix to indicate package style, e.g., **UDK2549EB**.

## 2549 PROTECTED QUAD POWER DRIVER

### FUNCTIONAL BLOCK DIAGRAM



UDx2549EB



# 2549 PROTECTED QUAD POWER DRIVER

**ELECTRICAL CHARACTERISTICS** at  $T_A = +25^\circ\text{C}$  (prefix 'UDN') or over operating temperature range (prefix 'UDK' or 'UDQ'),  $V_{CC} = 4.75\text{ V to }5.25\text{ V}$

| Characteristic              | Symbol         | Test Conditions                                                       | Limits |      |      |                  |
|-----------------------------|----------------|-----------------------------------------------------------------------|--------|------|------|------------------|
|                             |                |                                                                       | Min.   | Typ. | Max. | Units            |
| Output Leakage Current      | $I_{CEX}$      | $V_{OUT} = 60\text{ V}, V_{IN} = 0.8\text{ V}, V_{EN} = 2.0\text{ V}$ | —      | <1.0 | 100  | $\mu\text{A}$    |
|                             |                | $V_{OUT} = 60\text{ V}, V_{IN} = 2.0\text{ V}, V_{EN} = 0.8\text{ V}$ | —      | <1.0 | 100  | $\mu\text{A}$    |
| Output Sustaining Voltage   | $V_{OUT(SUS)}$ | $I_{OUT} = 100\text{ mA}, V_{IN} = V_{EN} = 0.8\text{ V}$             | 40     | —    | —    | V                |
| Output Saturation Voltage   | $V_{OUT(SAT)}$ | $I_{OUT} = 100\text{ mA}$                                             | —      | —    | 200  | mV               |
|                             |                | $I_{OUT} = 400\text{ mA}$                                             | —      | —    | 400  | mV               |
|                             |                | $I_{OUT} = 600\text{ mA}$                                             | —      | —    | 600  | mV               |
| Over-Current Trip           | $I_{TRIP}$     |                                                                       | —      | 1.0  | —    | A                |
| Input Voltage               | Logic 1        | $V_{IN(1)} \text{ or } V_{EN(1)}$                                     | 2.0    | —    | —    | V                |
|                             | Logic 0        | $V_{IN(0)} \text{ or } V_{EN(0)}$                                     | —      | —    | 0.8  | V                |
| Input Current               | Logic 1        | $V_{IN(1)} \text{ or } V_{EN(1)} = 2.0\text{ V}$                      | —      | —    | 10   | $\mu\text{A}$    |
|                             | Logic 0        | $V_{IN(0)} \text{ or } V_{EN(0)} = 0.8\text{ V}$                      | —      | —    | -10  | $\mu\text{A}$    |
| Total Supply Current        | $I_{CC}$       | $I_{OUT} = 600\text{ mA}, V_{IN}^* = V_{EN} = 2.0\text{ V}$           | —      | —    | 65   | mA               |
|                             |                | All Outputs OFF                                                       | —      | —    | 15   | mA               |
| Clamp Diode Forward Voltage | $V_F$          | $I_F = 1.0\text{ A}$                                                  | —      | —    | 1.7  | V                |
| Clamp Diode Leakage Current | $I_R$          | $V_R = 60\text{ V}, D_1 + D_2 \text{ or } D_3 + D_4$                  | —      | —    | 50   | $\mu\text{A}$    |
| Thermal Limit               | $T_J$          |                                                                       | —      | 165  | —    | $^\circ\text{C}$ |

Typical Data is for design information only.

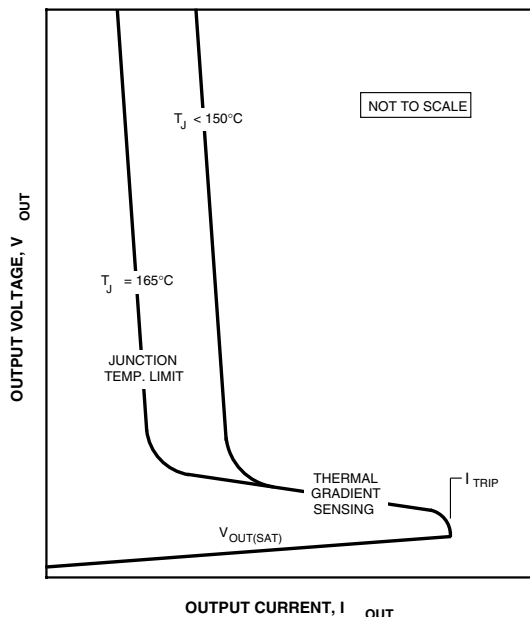
Negative current is defined as coming out of (sourcing) the specified terminal.

As used here, -100 is defined as greater than +10 (absolute magnitude convention) and the minimum is implicitly zero.

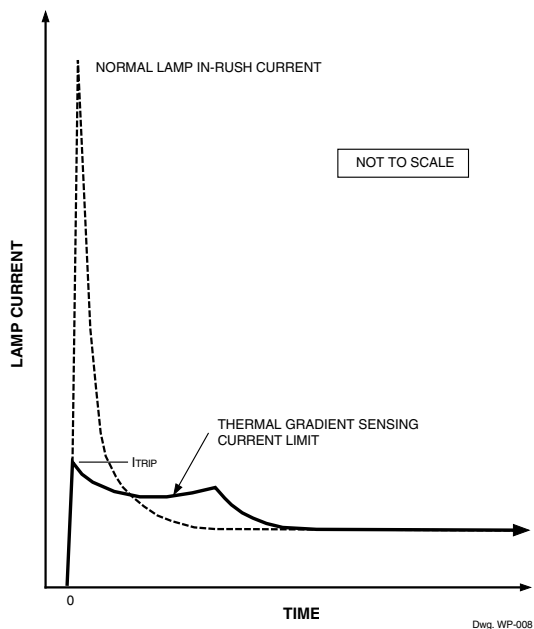
\* All inputs simultaneously, all other tests are performed with each input tested separately.

# 2549 PROTECTED QUAD POWER DRIVER

## TYPICAL OUTPUT CHARACTERISTIC



## TYPICAL OUTPUT BEHAVIOR



## CIRCUIT DESCRIPTION AND APPLICATION

### INCANDESCENT LAMP DRIVER

High incandescent lamp turn-ON/in-rush currents can contribute to poor lamp reliability and destroy semiconductor lamp drivers. Warming or current-limiting resistors protect both driver and lamp but use significant power either when the lamp is OFF or when the lamp is ON, respectively. Lamps with steady-state current ratings up to 600 mA can be driven by these devices without the need for warming (parallel) or current-limiting (series) resistors.

When an incandescent lamp is initially turned ON, the cold filament is at minimum resistance and would normally allow a 10x to 12x in-rush current. With these drivers, during turn-ON, the high in-rush current is sensed by the internal low-value sense resistor. Drive current to the output stage is then diverted by the shunting transistor, and the load current is momentarily limited to approximately 1.0 A. During this short transition period, the output current is reduced to a value dependent on supply voltage and filament resistance. During lamp warmup, the filament resistance increases to its maximum value, the output stage goes into saturation and applies maximum rated voltage to the lamp.

### INDUCTIVE LOAD DRIVER

Bifilar (unipolar) stepper motors, relays, or solenoids can be driven directly. The internal flyback diodes prevent damage to the output transistors by suppressing the high-voltage spikes which occur when turning OFF an inductive load. For rapid current decay (fast turn-OFF speeds), the use of Zener diodes will raise the flyback voltage and improve performance. However, the peak voltage must not exceed the specified minimum sustaining voltage ( $V_{SUPPLY} + V_Z + V_F \leq V_{OUT(SUS)}$ ).

### FAULT CONDITIONS

In the event of a shorted load, the load current will attempt to increase. As described above, the drive current to the affected output stage is reduced, causing the output stage to go linear, limiting the peak output current to approximately 1 A. As the power dissipation of that output stage increases, a thermal gradient sensing circuit will become operational, further decreasing the drive current to the affected output stage and reducing the output current to a value dependent on supply voltage and load resistance.

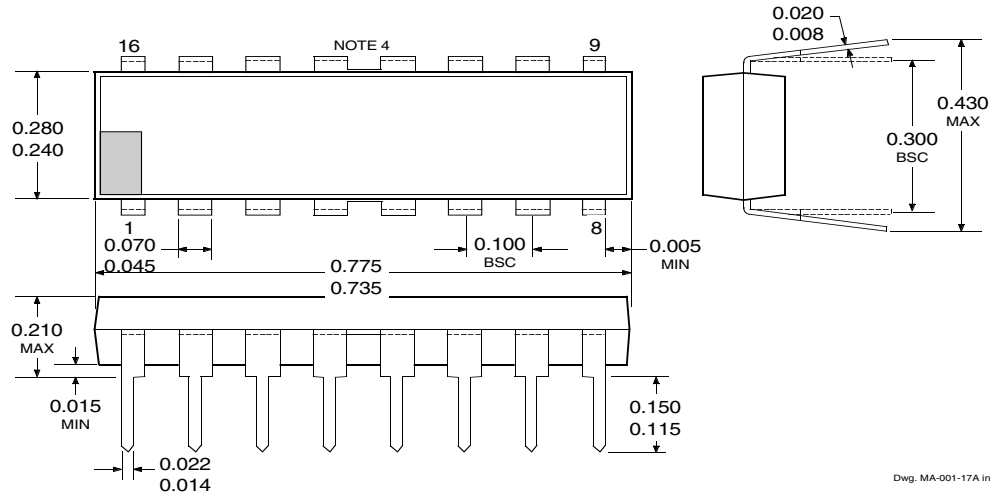
Continuous or multiple overload conditions causing the chip temperature to reach approximately  $165^\circ\text{C}$  will result in an additional reduction in output current to maintain a safe level.

If the fault condition is corrected, the output stage will return to its normal saturated condition.

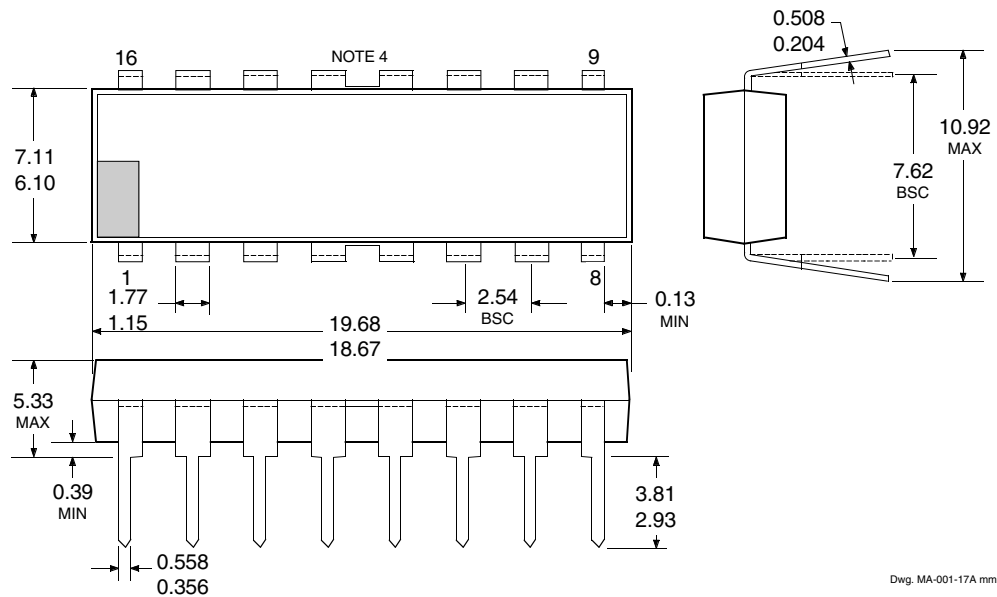
# 2549 PROTECTED QUAD POWER DRIVER

## UDN2549B and UDQ2549B

Dimensions in Inches  
(controlling dimensions)



Dimensions in Millimeters  
(for reference only)

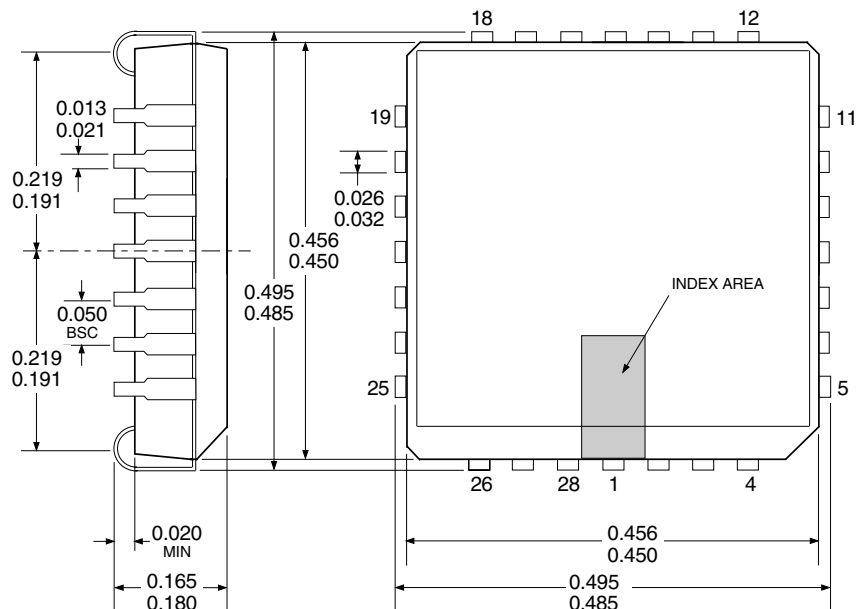


- NOTES: 1. Exact body and lead configuration at vendor's option within limits shown.  
2. Lead spacing tolerance is non-cumulative  
3. Lead thickness is measured at seating plane or below.  
4. Webbed lead frame. Leads 4, 5, 12, and 13 are internally one piece.

# 2549 PROTECTED QUAD POWER DRIVER

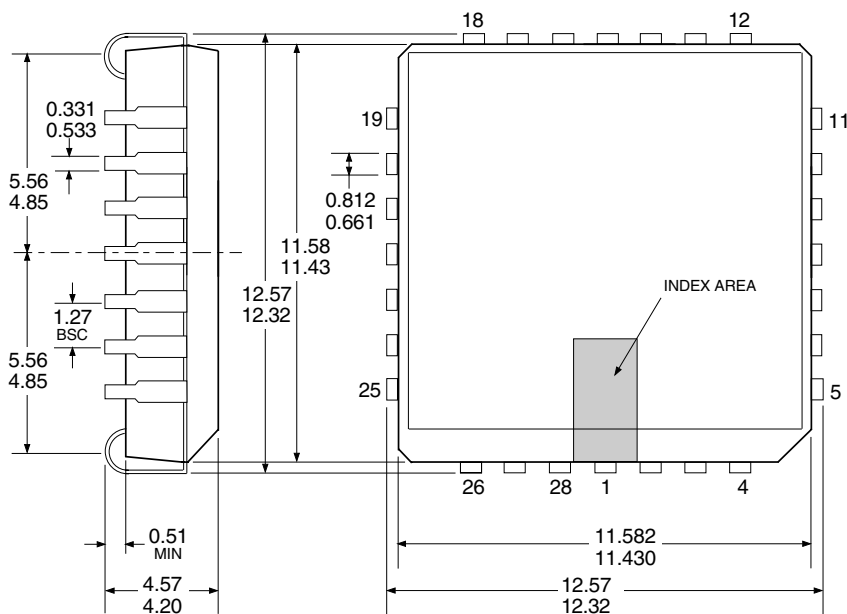
## UDN2549EB and UDQ2549EB

Dimensions in Inches  
(controlling dimensions)



Dwg. MA-005-28A in

Dimensions in Millimeters  
(for reference only)



Dwg. MA-005-28A mm

- NOTES: 1. Exact body and lead configuration at vendor's option within limits shown.  
2. Lead spacing tolerance is non-cumulative  
3. Webbed lead frame. Leads 5 through 11 and 19 through 25 are internally one piece.

**2549**  
***PROTECTED***  
***QUAD POWER DRIVER***

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# 2549 PROTECTED QUAD POWER DRIVER

## POWER SINK DRIVERS

IN ORDER OF 1) OUTPUT CURRENT, 2) OUTPUT VOLTAGE, 3) NUMBER OF DRIVERS

| Output Ratings * |     |    | Features                          |                    |             |                  |                     | Part Number <sup>†</sup> |
|------------------|-----|----|-----------------------------------|--------------------|-------------|------------------|---------------------|--------------------------|
| mA               | V   | #  | Serial Input                      | Latched Drivers    | Diode Clamp | Outputs          | Internal Protection |                          |
| 75               | 17  | 8  | X                                 | X                  | —           | constant current | —                   | 6275                     |
|                  | 17  | 16 | X                                 | X                  | —           | constant current | —                   | 6276                     |
| 100              | 20  | 8  | —                                 | —                  | —           | saturated        | —                   | 2595                     |
|                  | 30  | 32 | X                                 | X                  | —           | —                | —                   | 5833                     |
|                  | 40  | 32 | X                                 | X                  | —           | saturated        | —                   | 5832                     |
|                  | 50  | 8  | addressable decoder/driver        |                    |             | DMOS             | —                   | 6B259                    |
|                  | 50  | 8  | —                                 | X                  | —           | DMOS             | —                   | 6B273                    |
|                  | 50  | 8  | X                                 | X                  | —           | DMOS             | —                   | 6B595                    |
| 250              | 50  | 8  | addressable decoder/driver        |                    |             | DMOS             | —                   | 6259                     |
|                  | 50  | 8  | —                                 | X                  | —           | DMOS             | —                   | 6273                     |
|                  | 50  | 8  | X                                 | X                  | —           | DMOS             | —                   | 6595                     |
|                  | 135 | 7  | —                                 | —                  | X           | —                | —                   | 7003                     |
| 300              | 45  | 1  | —                                 | Hall sensor/driver | X           | —                | X                   | 5140                     |
|                  | 50  | 7  | —                                 | —                  | X           | —                | —                   | 2003                     |
|                  | 50  | 8  | —                                 | —                  | X           | —                | —                   | 2803                     |
|                  | 50  | 8  | —                                 | —                  | X           | saturated        | —                   | 2596                     |
|                  | 60  | 4  | —                                 | —                  | X           | saturated        | X                   | 2557                     |
|                  | 95  | 7  | —                                 | —                  | X           | —                | —                   | 2023                     |
|                  | 95  | 8  | —                                 | —                  | X           | —                | —                   | 2823                     |
| 350              | 50  | 4  | —                                 | X                  | X           | —                | —                   | 5800                     |
|                  | 50  | 7  | —                                 | —                  | X           | —                | —                   | 2004                     |
|                  | 50  | 8  | —                                 | —                  | X           | —                | —                   | 2804                     |
|                  | 50  | 8  | —                                 | X                  | X           | —                | —                   | 5801                     |
|                  | 50  | 8  | X                                 | X                  | —           | —                | —                   | 5821                     |
|                  | 50  | 8  | X                                 | X                  | X           | —                | —                   | 5841                     |
|                  | 50  | 8  | addressable decoder/driver        |                    |             | DMOS             | —                   | 6A259                    |
|                  | 50  | 8  | X                                 | X                  | —           | DMOS             | —                   | 6A595                    |
|                  | 80  | 8  | X                                 | X                  | —           | —                | —                   | 5822                     |
|                  | 80  | 8  | X                                 | X                  | X           | —                | —                   | 5842                     |
|                  | 95  | 7  | —                                 | —                  | X           | —                | —                   | 2024                     |
|                  | 95  | 8  | —                                 | —                  | X           | —                | —                   | 2824                     |
| 450              | 30  | 28 | dual 4- to 14-line decoder/driver |                    |             | —                | —                   | 6817                     |
| 600              | 60  | 4  | —                                 | —                  | —           | saturated        | X                   | 2547                     |
|                  | 60  | 4  | —                                 | —                  | X           | saturated        | X                   | 2549                     |
| 700              | 60  | 4  | —                                 | —                  | X           | saturated        | X                   | 2543 and 2559            |
| 750              | 50  | 8  | —                                 | —                  | X           | saturated        | —                   | 2597                     |
| 900              | 14  | 2  | —                                 | Hall sensor/driver | X           | saturated        | X                   | 3625                     |
|                  | 26  | 2  | —                                 | Hall sensor/driver | X           | saturated        | X                   | 3626                     |
| 1000             | 46  | 4  | stepper motor controller/driver   |                    |             | MOS              | —                   | 7024 and 7029            |
| 1200             | 46  | 4  | microstepping controller/driver   |                    |             | MOS              | —                   | 7042                     |
| 1250             | 50  | 4  | stepper motor translator/driver   |                    |             | —                | X                   | 5804                     |
|                  | 50  | 4  | —                                 | —                  | X           | —                | —                   | 2064 and 2068            |
| 1500             | 80  | 4  | —                                 | —                  | X           | —                | —                   | 2065 and 2069            |
| 1800             | 50  | 4  | —                                 | —                  | X           | —                | —                   | 2544                     |
|                  | 50  | 4  | —                                 | —                  | X           | —                | —                   | 2540                     |
| 3000             | 46  | 4  | stepper motor controller/driver   |                    |             | MOS              | —                   | 7026                     |
|                  | 46  | 4  | microstepping controller/driver   |                    |             | MOS              | —                   | 7044                     |
| 4000             | 50  | 4  | —                                 | —                  | X           | —                | —                   | 2878                     |
|                  | 80  | 4  | —                                 | —                  | X           | —                | —                   | 2879                     |

\* Current is maximum specified test condition, voltage is maximum rating. See specification for sustaining voltage limits or over-current protection voltage limits.

† Complete part number includes additional characters to indicate operating temperature range and package style.



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