HRTL 3B Laser diffuse reflection light scanner with background suppression











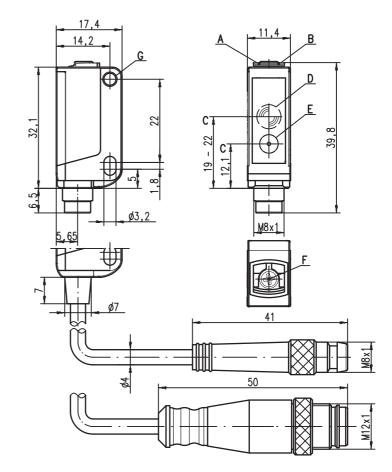






- Laser diffuse reflection light scanner with visible red light and adjustable background suppression
- Exact scanning range adjustment through 8-turn potentiometer
- Collimated light beam propagation with small beam diameter permits identical switching behavior within the specified scanning range
- Standard device in laser class 1 in accordance with EN 60825-1; extended scanning area with excellent black/white ratio in laser class 2
- High switching frequency and short response time for fast events and highprecision applications

Dimensioned drawing



- Green indicator diode Α
- В Yellow indicator diode
- С Optical axis
- D Receiver
- Transmitter Ε
- F 8-turn potentiometer for scanning range adjustment
- G Attachment sleeve

Electrical connection











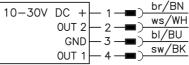




Accessories:

- (available separately)
- Mounting systems (BT 3...)
- Cable with M8 or M12 connector (K-D ...)

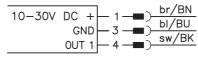
Plug connection, 4-pin 10-30V DC +



10-30V	DC T	br/BN
10-300		ws/WH
	CND	Ы/BU
	OUT 2 GND OUT 1	bl/BU sw/BK
	0011	

Cable, 4-wire

Plug connection, 3-pin



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Specifications

Optical data Typ. scanning range limit 1) Scanning range 2) Adjustment range of the switching point Black/white error < 10% up to Light beam diameter Light beam characteristic Squint angle Light source 3) Wavelength

Max. output power Pulse duration **Timing**

Switching frequency Response time Response jitter Decay time Delay before start-up **Electrical data**

Operating voltage U_B ⁴⁾ Residual ripple Open-circuit current Switching output

.../66 5)

Signal voltage high/low Output current Scanning range

Indicators Green LED Yellow LED

Mechanical data

Housing⁶⁾ Color Optics cover Fastening Weight

Connection type

Environmental data

Ambient temp. (operation/storage) Protective circuit 7) VDE safety class

Protection class Laser class

Standards applied Certifications

Laser class 1 10 ... 400mm

see tables 20 ... 400mm 170mm

approx. 1 mm, consistent collimated tvp. $\pm 2^{\circ}$ laser, pulsed

650nm (visible red light) ≤ 0.81 mW 7µs

2,000Hz 0.25ms typ. 65µs 0.25ms ≤ 300 ms

10 ... 30VDC (incl. residual ripple) $\leq 10\%$ of $U_B \leq 20\,mA$

2 push-pull switching outputs pin 2: PNP dark switching, NPN light switching pin 4: PNP light switching, NPN dark switching

pin 4: PNP light switching, NPN dark switching 1 push-pull switching output pin 4: PNP light switching, NPN dark switching ≥ (U_B-2V)/≤ 2V max. 100mA

adjustable via 8-turn potentiometer

ready

.../6 5)

object detected - reflection

plastic (PC-ABS); 1 attachment sleeve, nickel-plated steel red RAL 3000 plastic (PMMA)

Laser class 2

5 ... 500mm

20 ... 500mm

250mm

 $\stackrel{\leq}{3.3}mW\\7.6\mu s$

through holes for 2 x M3

with connector: 20g with 200mm cable and connector: 40g

with 2m cable: 50g 2m cable (cross section 4x0.20mm²), connector M8 metal,

0.2m cable with connector M8 or M12

-10 °C ... +55 °C /-30 °C ... +70 °C 1, 2, 3 II for cable $^{8)}\!,$

III for metal plug

IP 67

1 (in accordance with

EN 60825-1) IEC 60947-5-2 UL 508 4)

EN 60825-1)

2 (in accordance with

Typ. scan. range limit/adjustment range: max. achievable scanning range/adjustment range for light objects

Scanning range: recommended scanning range for objects with different diffuse reflection

Average life expectancy 50,000h at an ambient temperature of 25°C

For UL applications: for use in class 2 circuits according to NEC only

The push-pull switching outputs must not be connected in parallel Patent Pending Publ. No. US 7,476,848 B2

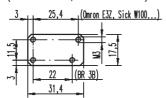
1=overload protection, 2=polarity reversal protection, 3=short circuit protection for all transistor outputs

Rating voltage 50V

Remarks

Adapter plate:

BT 3.2 (Part No. 501 03844) for alternate mounting on 25.4 mm hole spacing (Omron E3Z, Sick W100...)



Tables

Models of laser class 1:

1	15	400
2	15	250
3	15	170

Models of laser class 2:

Ī	1	15	!	500
Ī	2	15	400	
Ī	3	15	250	
_				

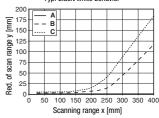
1	white 90%
2	grey 18%
3	black 6%

Scanning range [mm]

Diagrams

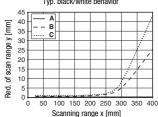
Models of laser class 1:

Typ. black/white behavior



Models of laser class 2:

Typ. black/white behavior



A white 90%

grey 18%

C black 6%



Remarks

Mounting system:



= BT 3

(Part no. 50060511)

 $= BT 3.1^{1}$ (Part no. 50105585)

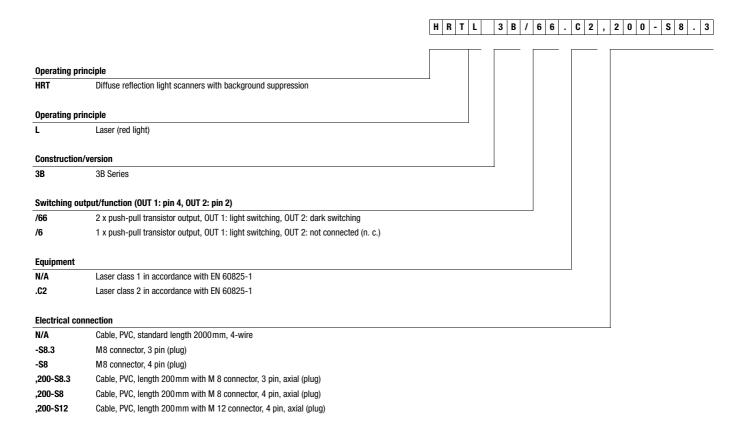
0+2+3 = BT 3B

(Part no. 50105546)

1) Packaging unit: PU = 10 pcs.

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Part number code



Order guide

The sensors listed here are preferred types; current information at www.leuze.com

Order code	Part No.
HRTL 3B/66	50114760
HRTL 3B/66-S8	50114581
HRTL 3B/66, 200-S8	50114761
HRTL 3B/66, 200-S12	50114762
HRTL 3B/66-C2	50114763
HRTL 3B/66-C2-S8	50114582
HRTL 3B/66-C2, 200-S8	50114764
HRTL 3B/66-C2, 200-S12	50114765

HRTL 3B

Application notes

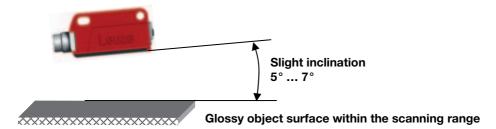


Approved purpose:

This product may only be used by qualified personnel and must only be used for the approved purpose. This sensor is not a safety sensor and is not to be used for the protection of persons..

• Detection of glossy surfaces within the scanning range:

When detecting glossy surfaces (e.g. metals), the light beam should not hit the object surface at a right angle. A slight inclination suffices to prevent undesirable direct reflections. The following rule of thumb applies: the smaller the scanning range, the larger the angle of the inclination (approx. 5° ... 7°).



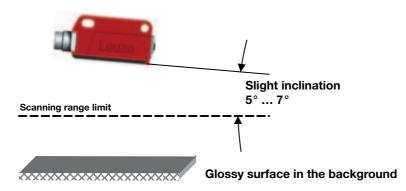
Avoiding interference from glossy surfaces in the background:

If a glossy surface is in the background (distance larger than scanning range limit), reflections may cause interfering signals. These may be avoided by mounting the device at a slight angle (see figure below).

Attention!



It is imperative to note the task and the associated inclination of the scanner of approx. 5° ... 7°.



- Objects should only be moved in laterally from the right or left. Moving in objects from the connection side or
 operating side is to be avoided.
- Outside of the scanning range, the sensor operates as an energetic diffuse reflection light scanner. Light objects can still be reliably detected up to the scanning range limit.
- The sensors are equipped with effective measures for the maximum avoidance of mutual interference should they
 be mounted opposite one another. Opposite mounting of multiple sensors of the same type should, however,
 absolutely be avoided.

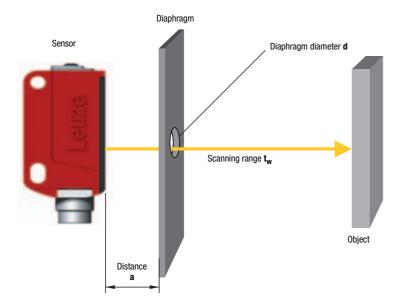
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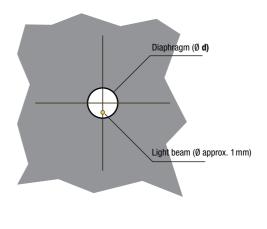
Object detection behind diaphragms

It is sometimes necessary to mount the sensor behind plant parts so that the light beam has to pass through an opening (diaphragm) that is as small as possible. Here, the detection depends, among other things, on set scanning range $\mathbf{t_w}$, distance \mathbf{a} between diaphragm and sensor, and diaphragm diameter \mathbf{d} . Here are some reference values ¹⁾:

Distance a [mm] between	Diaphragm diameter d [mm], dependent on scanning range t _w [mm] on a white object (90% diffuse reflection) set on the sensor		
sensor and diaphragm	t _w = 100	t _w = 200	t _w = 300
10	10	10	10
30	8	8	9
50	7	8	9
80	6	7	8
100	6	6	8
120		6	8
150		5	6
180		5	6
200		5	6

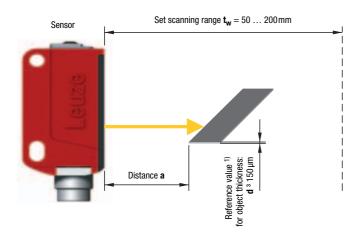






Detection of smallest objects

The laser scanner can also detect very thin parts (e.g., sheet metal plates or wire). Detection here depends, among other things, on set scanning range $\mathbf{t_w}$, distance \mathbf{a} to the object, and object size/thickness \mathbf{d} .





Reference values are not guaranteed properties. Due to the multitude of possible influencing factors, they must be confirmed in the application.

△ Leuze electronic

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