
ST-NXP Wireless

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As a result, the following changes are applicable to the attached document.

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ST-NXP Wireless



ISP1301

Universal Serial Bus On-The-Go transceiver

Rev. 03 — 21 February 2006

Product data sheet



1. General description

The ISP1301 is a Universal Serial Bus (USB) On-The-Go (OTG) transceiver device that is fully compliant with *Universal Serial Bus Specification Rev. 2.0* and *On-The-Go Supplement to the USB Specification Rev. 1.0a*. The ISP1301 can transmit and receive serial data at both full-speed (12 Mbit/s) and low-speed (1.5 Mbit/s) data rates.

It is ideal for use in portable electronics devices, such as mobile phones, digital still cameras, digital video cameras, Personal Digital Assistants (PDAs) and digital audio players. It allows USB Application Specific Integrated Circuits (ASICs), Programmable Logic Devices (PLDs) and any system chip set (with the USB host or device function built-in but without the USB physical layer) to interface to the physical layer of the USB.

The ISP1301 can interface to devices with digital I/O voltages in the range of 1.65 V to 3.6 V.

The ISP1301 is available in HVQFN24 package.

2. Features

- Fully complies with:
 - ◆ *Universal Serial Bus Specification Rev. 2.0*
 - ◆ *On-The-Go Supplement to the USB 2.0 Specification Rev. 1.0a*
 - ◆ *On-The-Go Transceiver Specification (CEA-2011) Rev. 1.0*
- Can transmit and receive serial data at both full-speed (12 Mbit/s) and low-speed (1.5 Mbit/s) data rates
- Ideal for system ASICs or chip sets with built-in USB OTG dual-role core
- Supports mini USB analog carkit interface
- Supports various serial data interface protocols; transparent general-purpose buffer mode allows you to control the direction of data transfer
- Supports data line and V_{BUS} pulsing session request
- Contains Host Negotiation Protocol (HNP) command and status registers
- Supports serial I²C-bus interface for OTG status and command controls
- 2.7 V to 4.5 V power supply input range for the ISP1301
- Built-in charge pump regulator outputs 5 V at current greater than 8 mA
- Supports external charge pump
- Supports wide range interfacing I/O voltage ($V_{CC(I/O)} = 1.65 \text{ V to } 3.6 \text{ V}$) for digital control logics

PHILIPS

- 8 kV built-in ElectroStatic Discharge (ESD) protection on the DP, DM, V_{BUS} and ID lines
- Full industrial grade operation from –40 °C to +85 °C
- Available in a small HVQFN24 (4 × 4 mm²) halogen-free and lead-free package

3. Applications

- Mobile phone
- Digital camera
- Personal digital assistant
- Digital video recorder

4. Ordering information

Table 1: Ordering information

| Type number | Package | | |
|-------------|---------|--|----------|
| | Name | Description | Version |
| ISP1301BS | HVQFN24 | plastic thermal enhanced very thin quad flat package; no leads; 24 terminals; body 4 × 4 × 0.85 mm | SOT616-1 |

5. Block diagram

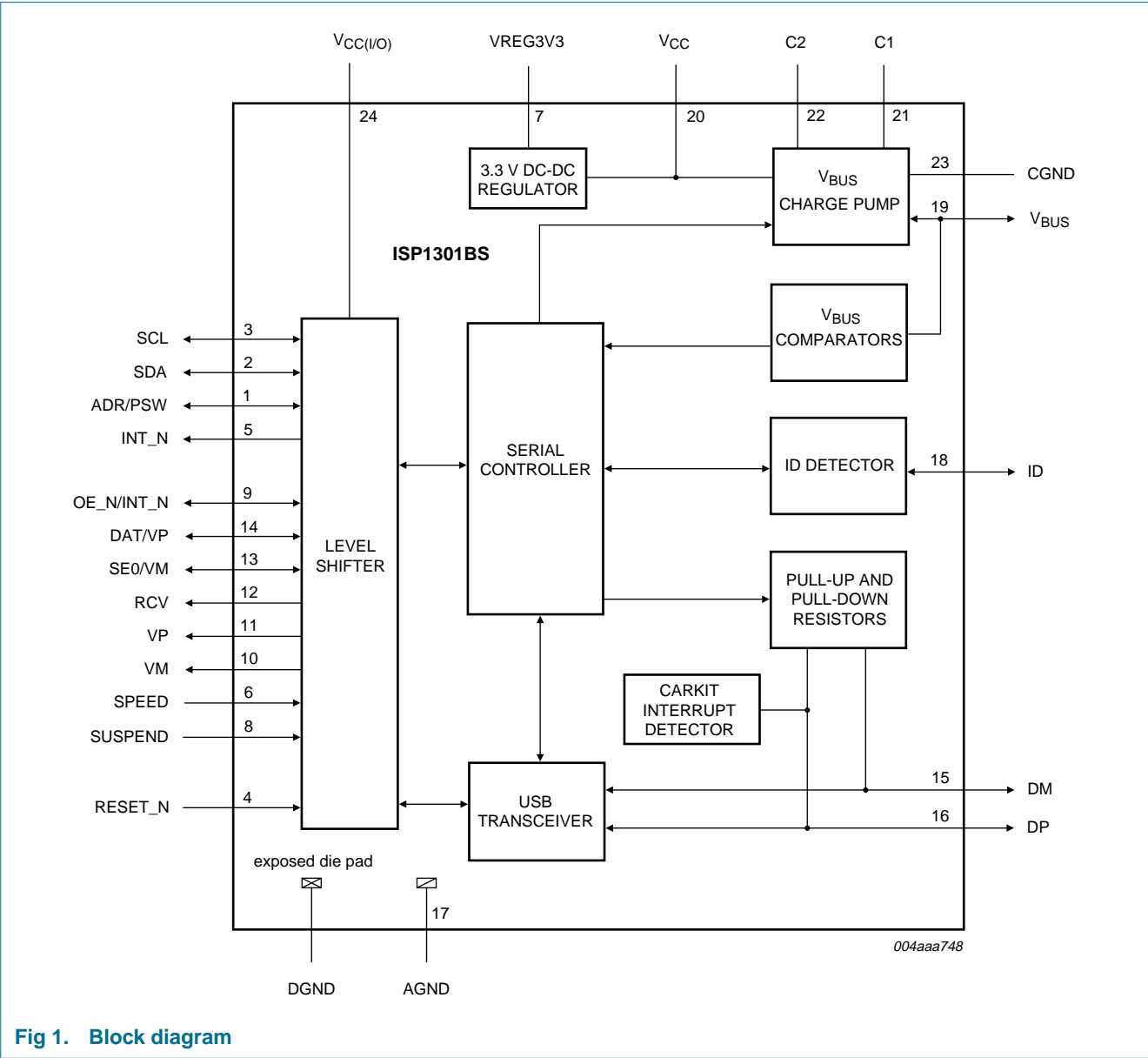


Fig 1. Block diagram

6. Pinning information

6.1 Pinning

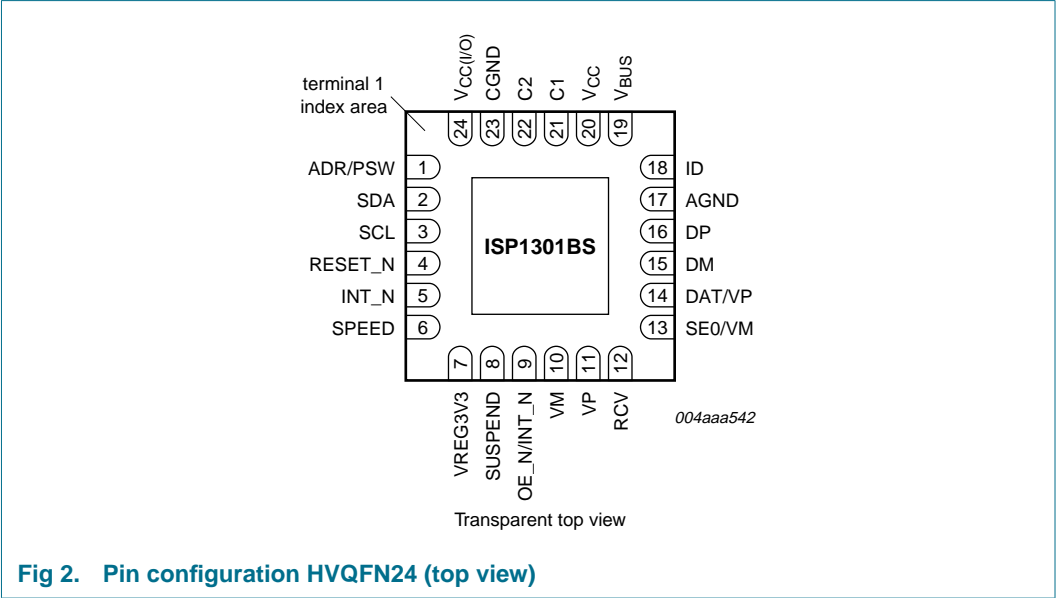


Fig 2. Pin configuration HVQFN24 (top view)

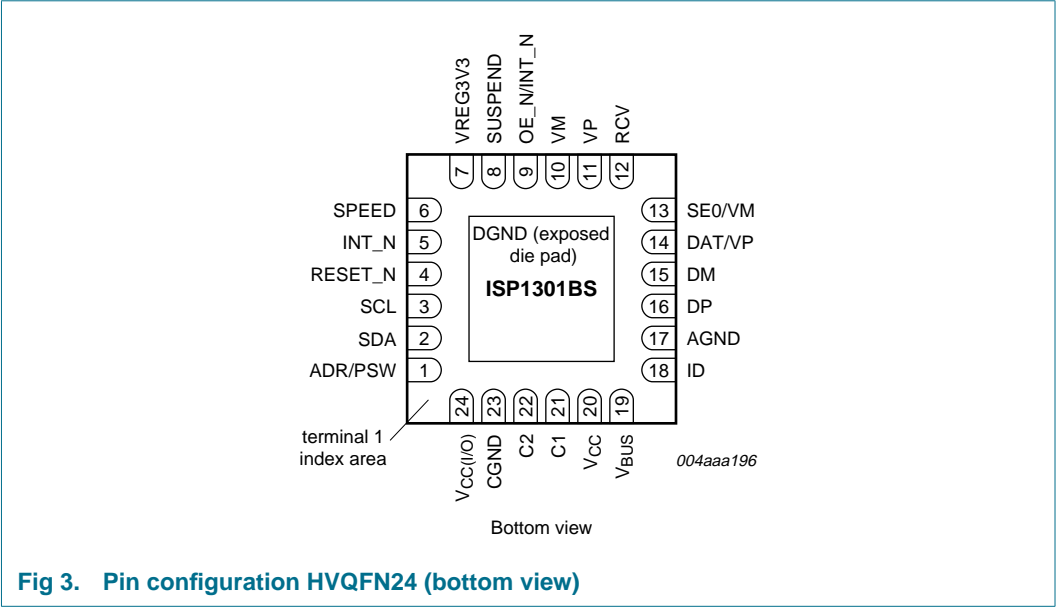


Fig 3. Pin configuration HVQFN24 (bottom view)

6.2 Pin description

Table 2: Pin description

| Symbol [1] | Pin | Type [2] | Reset state | Description [3] |
|----------------|-----|----------|-------------|---|
| ADR/PSW | 1 | I/O | high-Z | <p>ADR input — sets the least-significant I²C-bus address bit of the ISP1301; latched-on reset (including power-on reset)</p> <p>PSW output — enables or disables the external charge pump after reset</p> <p>bidirectional; push-pull input; 3-state output</p> |
| SDA | 2 | I/OD | high-Z | serial I ² C-bus data input and output bidirectional; push-pull input; open-drain output |
| SCL | 3 | I/OD | high-Z | serial I ² C-bus clock input and output bidirectional; push-pull input; open-drain output |
| RESET_N | 4 | I | - | asynchronous reset; active LOW push-pull input |
| INT_N | 5 | OD | high-Z | interrupt output; active LOW open-drain output |
| SPEED | 6 | I | - | <p>speed selection input for the ATX; effective when bit SPD_SUSP_CTRL = 0:</p> <ul style="list-style-type: none"> • LOW: low-speed • HIGH: full-speed <p>push-pull input</p> |
| VREG3V3 | 7 | P | - | output of the internal voltage regulator; an external decoupling capacitor of 0.1 µF is required |
| SUSPEND | 8 | I | - | <p>suspend selection input for the ATX; effective when bit SPD_SUSP_CTRL = 0:</p> <ul style="list-style-type: none"> • LOW: normal operating • HIGH: suspend <p>push-pull input</p> |
| OE_N/ INT_N | 9 | I/O | high-Z | <p>OE_N input — enables driving DP and DM when in USB mode</p> <p>INT_N output — interrupt (push pull) when suspended and bit OE_INT_EN = 1</p> <p>bidirectional; push-pull input; 3-state output</p> |
| VM | 10 | O | - | single-ended DM receiver output push-pull output |
| VP | 11 | O | - | single-ended DP receiver output push-pull output |
| RCV | 12 | O | 0 | differential receiver output; reflects the differential value of DP and DM push-pull output |
| SE0/VM | 13 | I/O | - [4] | <p>SE0 (input and output) — SE0 functions in DAT_SE0 USB mode</p> <p>VM (input and output) — VM functions in VP_VM USB mode</p> <p>bidirectional; push-pull input; 3-state output</p> |

Table 2: Pin description...continued

| Symbol [1] | Pin | Type [2] | Reset state | Description [3] |
|----------------------|-----------------|----------|-------------|--|
| DAT/VP | 14 | I/O | - [4] | DAT (input and output) — DAT functions in DAT_SE0 USB mode VP (input and output) — VP functions in VP_VM USB mode bidirectional; push-pull input; 3-state output |
| DM | 15 | AI/O | - | USB data minus pin (D–) |
| DP | 16 | AI/O | - | USB data plus pin (D+) |
| AGND | 17 | P | - | analog ground |
| ID | 18 | AI/O | - | identification detector input and output; connected to the ID pin of the USB mini receptacle |
| V _{BUS} | 19 | AI/O | - | V _{BUS} line input and output of the USB interface; place an external decoupling capacitor of 0.1 µF close to this pin |
| V _{CC} | 20 | P | - | supply voltage (2.7 V to 4.5 V) |
| C1 | 21 | AI/O | - | charge pump capacitor pin 1; typically use a 100 nF capacitor between pins C1 and C2 |
| C2 | 22 | AI/O | - | charge pump capacitor pin 2; typically use a 100 nF capacitor between pins C1 and C2 |
| CGND | 23 | P | - | ground for the charge pump |
| V _{CC(I/O)} | 24 | P | - | supply voltage for the interface logic signals (1.65 V to 3.6 V) |
| DGND | exposed die pad | P | - | digital ground |

[1] Symbol names ending with underscore N (for example, NAME_N) indicate active LOW signals.

[2] I = input; O = output; I/O = digital input/output; OD = open-drain output; AI/O = analog input/output; P = power or ground pin.

[3] A detailed description of these pins can be found in [Section 7.10](#).

[4] High-Z when pin OE_N/INT_N is LOW. Driven LOW when pin OE_N/INT_N is HIGH.



7. Functional description

7.1 Serial controller

The serial controller includes the following functions:

- I²C-bus slave interface
- Interrupt generator
- Mode Control registers
- OTG registers
- Interrupt related registers
- Device identification registers

The serial controller acts as an I²C-bus slave, and uses the SCL and SDA pins to communicate with the OTG Controller.

For details on serial controller, see [Section 10](#).

7.2 V_{BUS} charge pump

The charge pump supplies current to the V_{BUS} line. It can operate in any of the following modes:

- Output 5 V at current greater than 8 mA
- Pull-up V_{BUS} to 3.3 V through a resistor (R_{UP(VBUS)}) to initiate V_{BUS} pulsing SRP
- Pull-down V_{BUS} to ground through a resistor (R_{DN(VBUS)}) to discharge V_{BUS} before initiating SRP

7.3 V_{BUS} comparators

V_{BUS} comparators provide indications regarding the voltage level on V_{BUS}.

7.3.1 V_{BUS} valid comparator

This comparator is used by an A-device to determine whether the voltage on V_{BUS} is at a valid level for operation. The minimum threshold for the V_{BUS} valid comparator is 4.4 V. Any voltage on V_{BUS} below this threshold is considered to be a fault. During power-up, it is expected that the comparator output will be ignored.

7.3.2 Session valid comparator

The session valid comparator is a TTL-level input that determines when V_{BUS} is high enough for a session to start. Both the A-device and the B-device use this comparator to detect when a session is started. The A-device also uses this comparator to indicate when a session is completed. The session valid threshold of the ISP1301 is between 0.8 V and 2.0 V.

7.3.3 Session end comparator

The session end comparator determines when V_{BUS} is below the B-device session end threshold of 0.2 V to 0.8 V.

7.4 ID detector

In either active or suspended power mode, the ID detector senses the condition of the ID line and differentiates between the following three conditions:

- Pin ID is floating; bit ID_FLOAT = 1
- Pin ID is shorted to ground; bit ID_GND = 1
- Pin ID is connected to ground through resistor R_{ACC_ID}; bit ID_FLOAT = 0 and bit ID_GND = 0

The ID detector also has a switch that can be used to ground pin ID. This switch is controlled by bit ID_PULLDOWN in the serial controller.

7.5 Pull-up and pull-down resistors

The pull-up and pull-down resistors include the following switchable resistors:

- Pin DP pull-up
- Pin DP pull-down
- Pin DM pull-up
- Pin DM pull-down

The pull-up resistor is a context variable as described in the *ECN_27%_Resistor* document. The variable pull-up resistor hardware is implemented to meet the USB ECN_27% specification.

7.6 Analog USB Transceiver (ATX)

The behavior of the USB transceiver depends on operation mode of the ISP1301:

- In USB mode, the USB transceiver block performs USB full-speed or low-speed transceiver functions. This includes differential driver, differential receiver and single-ended receivers.
- In transparent general purpose buffer mode or UART mode, USB transceiver block functions as a level shifter between pins DAT/VP and SE0/VM and pins DP and DM.

7.7 3.3 V DC-DC regulator

The built-in 3.3 V DC-DC regulator conditions the supply voltage (V_{CC}) for use in the ISP1301:

- V_{CC} = 3.6 V to 4.5 V: the regulator will output 3.3 V ± 10 %
- V_{CC} < 3.6 V: the regulator will be bypassed

The output of the regulator can be monitored on the VREG3V3 pin.

7.8 Carkit interrupt detector

The carkit interrupt detector is a comparator that detects when the DP line is below the carkit interrupt threshold V_{PH_CR_INT} (0.4 V to 0.6 V). The carkit interrupt detector is enabled in audio mode only (bit AUDIO_EN = 1).

7.9 Power-On Reset (POR)

When V_{CC} is powered on, an internal POR is generated. The internal POR pulse width (t_{PORP}) will be typically 200 ns. The pulse is started when V_{CC} rises above $V_{POR(trip)}$.

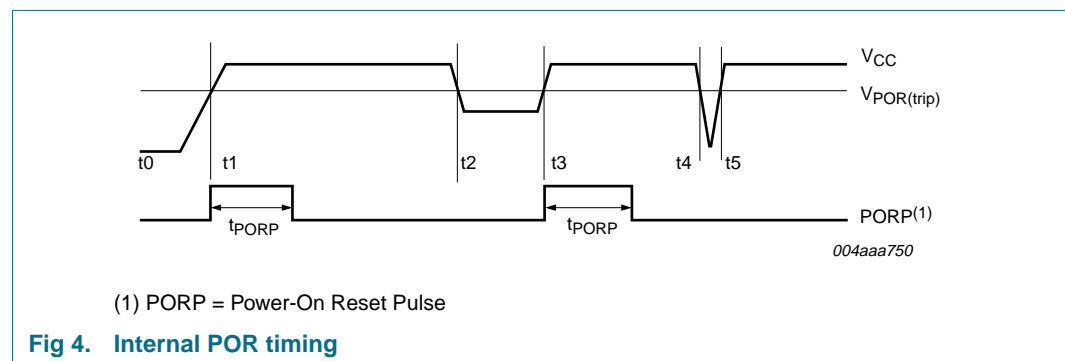
The POR function can be explained by viewing dips at t_2 to t_3 and t_4 to t_5 on the V_{CC} curve (Figure 4).

t0 — The internal POR starts with a LOW level.

t1 — The detector will see the passing of the trip level and a delay element will add another t_{PORP} before it drops to LOW.

t2-t3 — The internal POR pulse will be generated whenever V_{CC} drops below $V_{POR(trip)}$ for more than 11 μ s.

t4-t5 — The dip is too short ($< 11 \mu$ s) and the internal POR pulse will not react and will remain LOW.



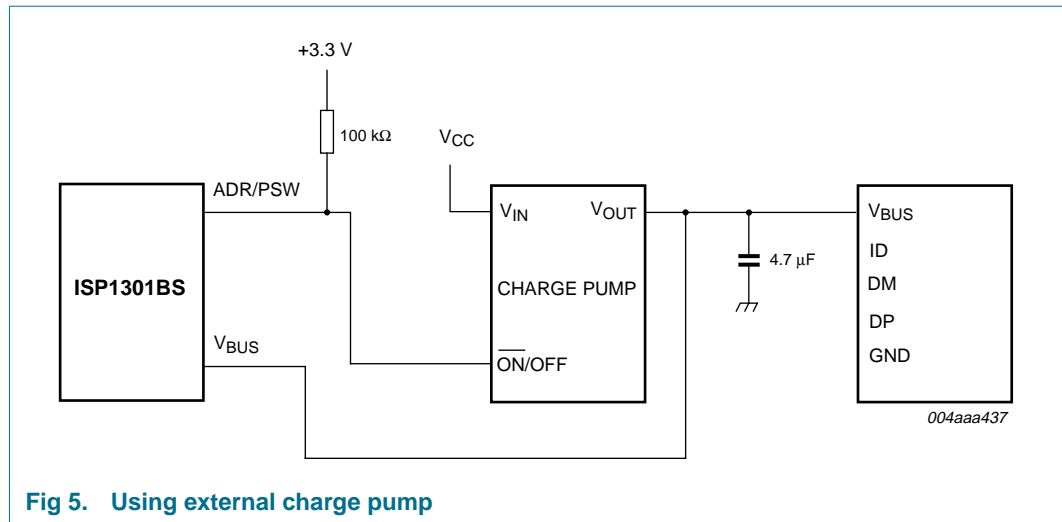
7.10 Detailed description of pins

7.10.1 ADR/PSW

The ADR/PSW pin has two functions. On reset (including power-on reset), the level on this pin is latched as ADR_REG, which represents the Least Significant Bit (LSB) of the I²C-bus address of the ISP1301. If bit ADR_REG = 0, the I²C-bus address for the ISP1301 is 010 1100 (2Ch); if bit ADR_REG = 1, the I²C-bus address for the ISP1301 is 010 1101 (2Dh).

After reset, the ADR/PSW pin can be programmed as an output. If in the Mode Control 2 register bit PSW_OE = 1, then the ADR/PSW output will be enabled. The logic level will be determined by bit ADR_REG. If bit ADR_REG = 0, then the ADR/PSW pin will be driven HIGH. If bit ADR_REG = 1, then the ADR/PSW pin will be driven LOW.

The ADR/PSW pin can be used to turn on or off the external charge pump. The ISP1301 built-in charge pump supports V_{BUS} current at 8 mA. If the application needs more current support (for example, 50 mA), an external charge pump may be needed. In this case, the ADR/PSW pin can act as a power switch for the external charge pump. Figure 5 shows an example of using external charge pump.



7.10.2 SCL and SDA

The SCL (serial clock) and SDA (serial data) signals implement a two-wire serial I²C-bus.

7.10.3 RESET_N

Active LOW asynchronous reset for all digital logic. Either connect this pin to $V_{CC(I/O)}$ for power-on reset or apply a minimum of 10 μ s LOW pulse for hardware reset.

7.10.4 INT_N

The INT_N (interrupt) pin is asserted while an interrupt condition exists. It is de-asserted when the Interrupt Latch register is cleared. The INT_N pin is open-drain, and, therefore, can be connected using a wired-AND with other interrupt signals.

7.10.5 OE_N/INT_N

Pin OE_N/INT_N is normally an input to the ISP1301.

When bit TRANSP_EN = 0 and bit UART_EN = 0, the OE_N/INT_N pin controls the direction of DAT/VP, SE0/VM, DP and DM as indicated in [Table 4](#).

When suspended (either pin SUSPEND = HIGH or bit SUSPEND_REG = 1) and bit OE_INT_EN = 1, pin OE_N/INT_N becomes a push-pull output (active LOW) to indicate the interrupt condition.

7.10.6 SE0/VM, DAT/VP, RCV, VM and VP

The ISP1301 transmits USB data on the USB line under the following conditions:

- Bit TRANSP_EN = 0
- Bit UART_EN = 0
- Pin OE_N/INT_N = LOW

[Table 10](#) shows the operation of the SE0/VM and DAT/VP pins during the transmit operation. The RCV pin is not used during transmit.

The ISP1301 receives USB data from the USB line under the following conditions:

- Bit TRANSP_EN = 0
- Bit UART_EN = 0
- Pin OE_N/INT_N = HIGH

Table 12 shows the operation of the SE0/VM, DAT/VP and RCV pins during the receive operation.

The VP and VM pins are single-ended receiver outputs of the DP and DM pins, respectively.

7.10.7 DP and DM

The DP (data plus) and DM (data minus) pins implement the USB data signals. When in transparent general-purpose buffer mode, the ISP1301 operates as a level shifter between the (DAT/VP, SE0/VM) and (DP, DM) pins.

7.10.8 ID

The ID (identification) pin is connected to the ID pin on the USB mini receptacle. An internal pull-up resistor (to VREG3V3) is connected to this pin. When bit ID_PULLDOWN is set, the ID pin will be shorted to ground.

7.10.9 V_{BUS}

This pin acts as an input to the V_{BUS} comparator or an output from the charge pump.

When the VBUS_DRV bit of the OTG Control register is asserted, the ISP1301 tries to drive V_{BUS} to a voltage of 4.4 V to 5.25 V, with an output current capability of at least 8 mA.

7.10.10 V_{CC}

This pin is an input and supplies power to the ISP1301. The ISP1301 operates when V_{CC} is between 2.7 V and 4.5 V.

7.10.11 C1 and C2

The C1 and C2 pins are to connect the flying capacitor of the charge pump. The output current capacity of the charge pump depends on the value of the capacitor. For maximum efficiency, place capacitors as close as possible to the pins.

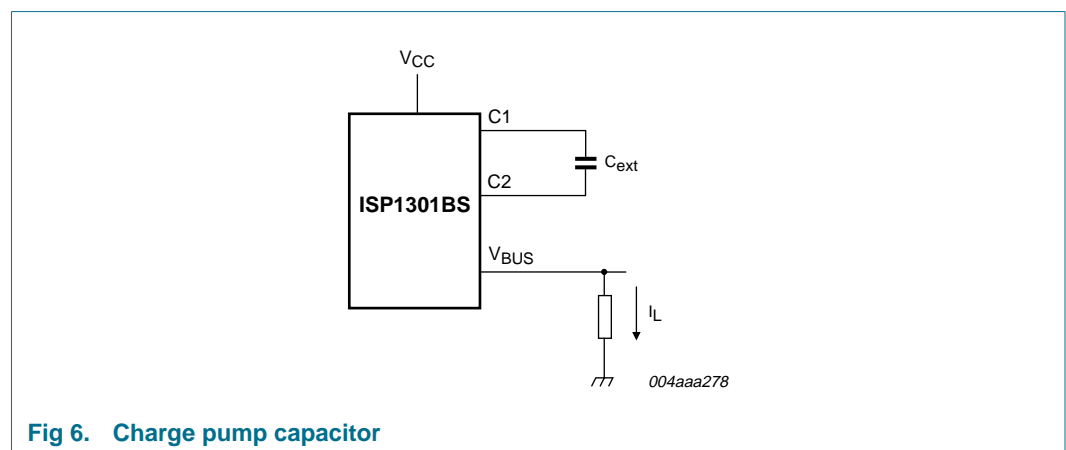


Table 3: Recommended charge pump capacitor value

| C_{ext} | V_{CC} | I_L (max) [1] |
|------------------|-----------------|---------------------------------|
| 47 nF | 2.7 V to 4.5 V | 8 mA |
| 100 nF | 2.7 V to 4.5 V | 8 mA |
| | 3.0 V to 4.5 V | 18 mA |

[1] For output voltage $V_{\text{BUS}} > 4.7$ V (bit $V_{\text{BUS_VLD}} = 1$).

7.10.12 $V_{\text{CC(VO)}}$

This pin is an input and sets logic thresholds. It also powers the pads of the following logic pins:

- ADR/PSW
- DAT/VP, SE0/VM and RCV
- VM and VP
- INT_N
- OE_N/INT_N
- RESET_N
- SPEED
- SUSPEND
- SCL and SDA

7.10.13 AGND, CGND and DGND

AGND, CGND and DGND are ground pins for analog, charge pump and digital circuits, respectively. These pins can be connected separately or together depending on the system performance requirements.

8. Modes of operation

There are four types of modes in the ISP1301:

- Power modes
- Direct I²C-bus mode
- USB modes
- Transparent modes

8.1 Power modes

Power modes of the ISP1301 are as follows:

- Active power mode: power is on.
- USB suspend mode: to reduce power consumption, the USB differential receiver is powered down.
- Global power-down mode: set bit $\text{GLOBAL_PWR_DN} = 1$ of the Mode Control 2 register; the differential transmitter and receiver, clock generator, charge pump, and all biasing circuits are turned off to reduce power consumption to the minimum possible; for details on waking up the clock, see [Section 11](#).

8.2 Direct I²C-bus mode

In direct I²C-bus mode, an external I²C-bus master (OTG Controller) directly communicates with the serial controller through the SCL and SDA lines. The serial controller has a built-in I²C-bus slave function.

In this mode, an external I²C-bus master can access the internal registers of the device (Status, Control, Interrupt, and so on) through the I²C-bus interface.

The supported I²C-bus bit rate is 100 kbit/s (maximum).

The ISP1301 is in direct I²C-bus mode when either bit TRANSP_EN bit = 0 or pin OE_N/INT_N is de-asserted.

8.3 USB modes

The four USB modes of the ISP1301 are:

- VP_VM unidirectional mode
- VP_VM bidirectional mode
- DAT_SE0 unidirectional mode
- DAT_SE0 bidirectional mode

In VP_VM USB mode, the DAT/VP pin is used for the VP function, the SE0/VM pin is used for the VM function, and the RCV pin is used for the RCV function.

In DAT_SE0 USB mode, the DAT/VP pin is used for the DAT function, the SE0/VM pin is used for the SE0 function, and the RCV pin is not used.

In unidirectional mode, the DAT/VP and SE0/VM pins are always inputs. In bidirectional mode, the direction of these signals depends on the OE_N/INT_N input.

[Table 6](#) specifies the functionality of the device during the four USB modes.

The ISP1301 is in USB mode when both the TRANSP_EN and UART_EN bits are cleared.

8.4 Transparent modes

8.4.1 Transparent general-purpose buffer mode

In transparent general-purpose buffer mode, the DAT/VP and SE0/VM pins are connected to the DP and DM pins, respectively. Using bits TRANSP_BDIR1 and TRANSP_BDIR0 of the Mode Control 2 register as specified in [Table 8](#), you can control the direction of data transfer. The ISP1301 is in transparent general-purpose buffer mode if bit TRANSP_EN = 1 and bit DAT_SE0 = 1.

8.4.2 Transparent UART mode

When in transparent UART mode, the ATX behaves as two logic level translator between the following pins:

- For the TxD signal: from SE0/VM ($V_{CC(I/O)}$ level) to DM (+3.3 V level).
- For the RxD signal: from DP (+3.3 V level) to DAT/VP ($V_{CC(I/O)}$ level).

In UART mode, the OTG Controller is allowed to connect a UART to the DAT/VP and SE0/VM pins of the ISP1301.

UART mode is entered by setting the UART_EN bit in the Mode Control 1 register. UART mode is equivalent to one of transparent general purpose buffer mode (bit TRANSP_BDIR1 = 1, bit TRANSP_BDIR0 = 0).

8.4.3 Summary tables

Table 4: Device operating modes

| Mode | USB suspend condition ^[1] | Bit DAT_SE0 | Pin OE_N/INT_N | Bit TRANSP_EN | Bit UART_EN | Description |
|---|--------------------------------------|-------------|----------------|---------------|-------------|--|
| Direct I²C-bus mode | | | | | | |
| Direct I ² C-bus mode | X | X | X | 0 | X | - |
| | X | X | HIGH | 1 | X | |
| | X | 1 | X | 1 | X | |
| USB modes | | | | | | |
| USB suspend mode | 1 | X | X | 0 | 0 | see Table 5 and Table 7 |
| USB functional mode | 0 | X | X | 0 | 0 | ATX is fully functional; see Table 6 |
| Transparent modes | | | | | | |
| Transparent general-purpose buffer mode | X | 1 | X | 1 | 0 | ATX is not functional; see Table 8 |
| Transparent UART mode | X | X | X | X | 1 | DAT/VP ← DP (RxD signal of UART) SE0/VM → DM (TxD signal of UART); ATX is not functional |

[1] Conditions:

- a) bit SPD_SUSP_CTRL = 0 and pin SUSPEND = HIGH, or
- b) bit SPD_SUSP_CTRL = 1 and bit SUSPEND_REG = 0.

Table 5: USB suspend mode: I/O

| Pin | Function |
|------------------|--|
| DP as output | can be driven if pin OE_N/INT_N is active LOW, otherwise high-Z ^[1] |
| DM as output | can be driven if pin OE_N/INT_N is active LOW, otherwise high-Z ^[1] |
| V _{BUS} | can be driven depending on bit VBUS_DRV |
| SCL | connected to SCL I/O of the I ² C-bus slave |
| SDA | connected to SDA I/O of the I ² C-bus slave |

- [1] In USB suspend mode, the ISP1301 can drive the DP and DM lines, if the OE_N/INT_N input (when the OE_INT_EN bit is not set) is LOW. In such a case, these outputs are driven as in USB functional modes, but with the full-speed characteristics, irrespective of the value of the SPEED input pin or the SPEED_REG bit.

Table 6: USB functional modes: I/O values

| USB mode ^[1] | | Bit | | Pin | | | | | |
|-------------------------|----------------|---------|-------|----------------|---------------------|---------------------|---------------------|---------------------|--------------------|
| | | DAT_SE0 | BI_DI | OE_N/ INT_N | DAT/VP | SE0/VM | VP | VM | RCV |
| VP_VM | unidirectional | 0 | 0 | X | TxD+ ^[2] | TxD– ^[2] | RxD+ ^[3] | RxD– ^[3] | RxD ^[6] |
| | bidirectional | 0 | 1 | LOW | TxD+ ^[2] | TxD– ^[2] | | | |
| | | 0 | 1 | HIGH | RxD+ ^[3] | RxD– ^[3] | | | |
| DAT_SE0 | unidirectional | 1 | 0 | X | TxD ^[4] | FSE0 ^[5] | | | |
| | bidirectional | 1 | 1 | LOW | TxD ^[4] | FSE0 ^[5] | | | |
| | | 1 | 1 | HIGH | RxD ^[6] | RSE0 ^[7] | | | |

[1] Some of the modes and signals are provided to achieve backward compatibility with IP cores.

[2] TxD+ and TxD– are single-ended inputs to drive the DP and DM outputs, respectively, in single-ended mode.

[3] RxD+ and RxD– are the outputs of the single-ended receivers connected to DP and DM, respectively.

[4] TxD is the input to drive DP and DM in DAT_SE0 mode.

[5] FSE0 is to force an SE0 on the DP and DM lines in DAT_SE0 mode.

[6] RxD is the output of the differential receiver.

[7] RSE0 is an output indicating that an SE0 has been received on the DP and DM lines.

Table 7: USB suspend mode: I/O values

| USB suspend mode | Input pin | | Output pin | | | | |
|------------------------------|-----------|------|------------|--------|------|------|-----|
| | DP | DM | DAT/VP | SE0/VM | VP | VM | RCV |
| DAT_SE0 (bit DAT_SE0 = 1) | LOW | LOW | LOW | HIGH | LOW | LOW | X |
| | HIGH | LOW | HIGH | LOW | HIGH | LOW | X |
| | LOW | HIGH | LOW | LOW | LOW | HIGH | X |
| | HIGH | HIGH | HIGH | LOW | HIGH | HIGH | X |
| VP_VM (bit DAT_SE0 = 0) | LOW | LOW | LOW | LOW | LOW | LOW | X |
| | HIGH | LOW | HIGH | LOW | HIGH | LOW | X |
| | LOW | HIGH | LOW | HIGH | LOW | HIGH | X |
| | HIGH | HIGH | HIGH | HIGH | HIGH | HIGH | X |

Table 8: Transparent general-purpose buffer mode

| Bit TRANSP_BDIR[1:0] | Direction of the data flow | |
|-------------------------|----------------------------|-------------|
| 00 | DAT/VP → DP | SE0/VM → DM |
| 01 | DAT/VP → DP | SE0/VM ← DM |
| 10 | DAT/VP ← DP | SE0/VM → DM |
| 11 | DAT/VP ← DP | SE0/VM ← DM |

9. USB transceiver

9.1 Differential driver

The operation of the driver is described in [Table 9](#). The register bits and the pins used in the column heading are described in [Section 10.1](#) and [Section 7.10](#), respectively.

Table 9: Transceiver driver operation setting

| Suspend [1] | Bit TRANSP_ EN | Pin OE_N/ INT_N | Bit DAT_SE0 | Differential driver |
|-------------|----------------------|-----------------------|----------------|---|
| 0 | 0 | LOW | 0 | output value from DAT/VP to DP and SE0/VM to DM |
| 0 | 0 | LOW | 1 | output value from DAT/VP to DP and DM if SE0/VM is 0; otherwise, drive both DP and DM LOW |
| 1 | 0 | LOW | X | output value from DAT/VP to DP and DM |
| X | X | HIGH | X | high-Z |
| X | 1 | X | X | high-Z |

[1] Can be controlled by using either the SUSPEND pin or the SUSPEND_REG bit.

Table 10: USB functional mode: transmit operation

| USB mode | Input pin | | Output pin | |
|----------|-----------|--------|------------|------|
| | DAT/VP | SE0/VM | DP | DM |
| DAT_SE0 | LOW | LOW | LOW | HIGH |
| | HIGH | LOW | HIGH | LOW |
| | LOW | HIGH | LOW | LOW |
| | HIGH | HIGH | LOW | LOW |
| VP_VM | LOW | LOW | LOW | LOW |
| | HIGH | LOW | HIGH | LOW |
| | LOW | HIGH | LOW | HIGH |
| | HIGH | HIGH | HIGH | HIGH |

9.2 Differential receiver

Table 11 describes the operation of the differential receiver. The register bits and the pins used in the column heading are described in Section 10.1 and Section 7.10, respectively.

The detailed behavior of the receive transceiver operation is given in Table 12.

Table 11: Differential receiver operation settings

| Suspend [1] | Bit TRANSP_EN | Pin OE_N/INT_N | Bit DAT_SE0 | Differential receiver |
|-------------|------------------|-------------------|----------------|--|
| 1 | X | X | X | X |
| X | X | LOW | X | 0 |
| X | 1 | X | X | 0 |
| 0 | 0 | HIGH | 1 | output differential value from DP and DM to DAT/VP and RCV |
| 0 | 0 | HIGH | 0 | output differential value from DP and DM to RCV |

[1] Can be controlled by using either the SUSPEND pin or the SUSPEND_REG bit.

Table 12: USB functional mode: receive operation

| USB mode | Suspend ^[1] | Input pin | | Output pin | | |
|----------|------------------------|-----------|------|------------|--------|-------------------|
| | | DP | DM | DAT/VP | SE0/VM | RCV |
| DAT_SE0 | 0 | LOW | LOW | RCV | HIGH | last value of RCV |
| DAT_SE0 | 0 | HIGH | LOW | HIGH | LOW | HIGH |
| DAT_SE0 | 0 | LOW | HIGH | LOW | LOW | LOW |
| DAT_SE0 | 0 | HIGH | HIGH | RCV | LOW | last value of RCV |
| DAT_SE0 | 1 | LOW | LOW | LOW | HIGH | X |
| DAT_SE0 | 1 | HIGH | LOW | HIGH | LOW | X |
| DAT_SE0 | 1 | LOW | HIGH | LOW | LOW | X |
| DAT_SE0 | 1 | HIGH | HIGH | HIGH | LOW | X |
| VP_VM | 0 | LOW | LOW | LOW | LOW | last value of RCV |
| VP_VM | 0 | HIGH | LOW | HIGH | LOW | HIGH |
| VP_VM | 0 | LOW | HIGH | LOW | HIGH | LOW |
| VP_VM | 0 | HIGH | HIGH | HIGH | HIGH | last value of RCV |
| VP_VM | 1 | LOW | LOW | LOW | LOW | X |
| VP_VM | 1 | HIGH | LOW | HIGH | LOW | X |
| VP_VM | 1 | LOW | HIGH | LOW | HIGH | X |
| VP_VM | 1 | HIGH | HIGH | HIGH | HIGH | X |

[1] Can be controlled by using either the SUSPEND pin or the SUSPEND_REG bit.

10. Serial controller

10.1 Register map

[Table 13](#) provides an overview of the serial controller registers.

Table 13: Serial controller registers

| Register | Width (bits) | Access ^[1] | Memory address | Functionality | Reference |
|-----------------------|--------------|-----------------------|--|---------------------------------|---|
| Vendor ID | 16 | R | 00h to 01h | device identification registers | Section 10.1.1 on page 18 |
| Product ID | 16 | R | 02h to 03h | | |
| Version ID | 16 | R | 14h to 15h | | |
| Mode Control 1 | 8 | R/S/C | Set — 04h Clear — 05h | mode control registers | Section 10.1.2 on page 19 |
| Mode Control 2 | 8 | R/S/C | Set — 12h Clear — 13h | | |
| OTG Control | 8 | R/S/C | Set — 06h Clear — 07h | OTG registers | Section 10.1.3 on page 20 |
| OTG Status | 8 | R | 10h | | |
| Interrupt Source | 8 | R | 08h | interrupt related registers | Section 10.1.4 on page 21 |
| Interrupt Latch | 8 | R/S/C | Set — 0Ah Clear — 0Bh | | |
| Interrupt Enable Low | 8 | R/S/C | Set — 0Ch Clear — 0Dh | | |
| Interrupt Enable High | 8 | R/S/C | Set — 0Eh Clear — 0Fh | | |

- [1] The R/S/C access type represents a field that can be read, set or cleared (set to 0). A register can be read from either of the indicated addresses: set or clear. Writing logic 1 to the set address causes the associated bit to be set. Writing logic 1 to the clear address causes the associated bit to be cleared. Writing logic 0 to an address has no effect.

10.1.1 Device identification registers

10.1.1.1 Vendor ID register (Read: 00h to 01h)

[Table 14](#) provides the bit description of the Vendor ID register.

Table 14: Vendor ID register: bit description

| Bit | Symbol | Access | Value | Description |
|---------|----------------|--------|-------|-----------------------------------|
| 15 to 0 | VENDORID[15:0] | R | 04CCh | Philips Semiconductors' Vendor ID |

10.1.1.2 Product ID register (Read: 02h to 03h)

The bit description of this register is given in [Table 15](#).

Table 15: Product ID register: bit description

| Bit | Symbol | Access | Value | Description |
|---------|-----------------|--------|-------|---------------------------|
| 15 to 0 | PRODUCTID[15:0] | R | 1301h | Product ID of the ISP1301 |

10.1.1.3 Version ID register (Read: 14h to 15h)

[Table 16](#) shows the bit description of this register.

Table 16: Version ID register: bit description

| Bit | Symbol | Access | Value | Description |
|---------|-----------------|--------|-------|-------------------------------|
| 15 to 0 | VERSIONID[15:0] | R | 0210h | Version number of the ISP1301 |

10.1.2 Mode control registers

10.1.2.1 Mode Control 1 register (Set/Clear: 04h/05h)

The bit allocation of the Mode Control 1 register is given in [Table 17](#).

Table 17: Mode Control 1 register: bit allocation

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|---------|-----------|--------------|-----------|---------|-------------|-----------|
| Symbol | - | UART_EN | OE_INT_EN | BDIS_ACON_EN | TRANSP_EN | DAT_SE0 | SUSPEND_REG | SPEED_REG |
| Reset | - | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Access | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C |

Table 18: Mode Control 1 register: bit description

| Bit | Symbol | Description |
|-----|--------------|--|
| 7 | - | reserved |
| 6 | UART_EN | When set, the ATX is in transparent UART mode. |
| 5 | OE_INT_EN | When set and when in suspend mode, pin OE_N/INT_N becomes an output and is asserted when an interrupt occurs. |
| 4 | BDIS_ACON_EN | Enables the A-device to connect if the B-device disconnect is detected; see Section 10.3 . |
| 3 | TRANSP_EN | When set, the ATX is in transparent mode. |
| 2 | DAT_SE0 | 0 — VP_VM mode 1 — DAT_SE0 mode; see Table 6 and Table 7 |
| 1 | SUSPEND_REG | Sets the ISP1301 in suspend mode, if bit SPD_SUSP_CTRL = 1. 0 — active-power mode 1 — USB suspend mode |
| 0 | SPEED_REG | Sets the rise time and the fall time of the transmit driver in USB modes, if bit SPD_SUSP_CTRL = 1. 0 — USB low-speed mode 1 — USB full-speed mode |

10.1.2.2 Mode Control 2 register (Set/Clear: 12h/13h)

For the bit allocation of this register, see [Table 19](#).

Table 19: Mode Control 2 register: bit allocation

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-------|--------|----------|--------------|--------------|-------|---------------|---------------|
| Symbol | EN2V7 | PSW_OE | AUDIO_EN | TRANSP_BDIR1 | TRANSP_BDIR0 | BI_DI | SPD_SUSP_CTRL | GLOBAL_PWR_DN |
| Reset | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 |
| Access | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C |

Table 20: Mode Control 2 register: bit description

| Bit | Symbol | Description |
|--------|------------------|---|
| 7 | EN2V7 | 0 — $V_{CC} = 3.0\text{ V}$ to 4.5 V 1 — $V_{CC} = 2.7\text{ V}$ to 4.5 V |
| 6 | PSW_OE | 0 — ADR/PSW pin acts as an input 1 — ADR/PSW pin is driven |
| 5 | AUDIO_EN | 0 — SE receiver is enabled; cr_int detector is disabled 1 — SE receiver is turned off (pin VP = LOW, pin VM = LOW); cr_int detector is enabled |
| 4 to 3 | TRANSP_BDIR[1:0] | controls the direction of data transfer in transparent general-purpose buffer mode; see Table 8 |
| 2 | BI_DI | 0 — direction of DAT/VP and SE0/VM are fixed (transmit only) 1 — direction of DAT/VP and SE0/VM are controlled by pin OE_N/INT_N; see Table 6 |
| 1 | SPD_SUSP_CTRL | control of speed and suspend in USB modes: 0 — controlled by pins SPEED and SUSPEND 1 — controlled by bit SPEED_REG and bit SUSPEND_REG of the Mode Control 1 register |
| 0 | GLOBAL_PWR_DN | 0 — normal operation 1 — sets the ISP1301 to Power-down mode Activities on the I ² C-bus or any OTG event can wake-up the chip; see Section 11 |

10.1.3 OTG registers

10.1.3.1 OTG Control register (Set/Clear: 06h/07h)

[Table 21](#) provides the bit allocation of the OTG Control register.

Table 21: OTG Control register: bit allocation

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|-----------|--------------|----------|-------------|-------------|-------------|-----------|-----------|
| Symbol | VBUS_CHRG | VBUS_DISCHRG | VBUS_DRV | ID_PULLDOWN | DM_PULLDOWN | DP_PULLDOWN | DM_PULLUP | DP_PULLUP |
| Reset | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 0 |
| Access | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C |

Table 22: OTG Control register: bit description

| Bit | Symbol | Description |
|-----|--------------|---|
| 7 | VBUS_CHRG | charge V_{BUS} through a resistor to 3.3 V |
| 6 | VBUS_DISCHRG | discharge V_{BUS} through a resistor to ground |
| 5 | VBUS_DRV | drive V_{BUS} to 5 V through the charge pump |
| 4 | ID_PULLDOWN | connect the ID pin to ground |
| 3 | DM_PULLDOWN | connect the DM pull-down resistor to ground |
| 2 | DP_PULLDOWN | connect the DP pull-down resistor to ground |
| 1 | DM_PULLUP | connect the DM pull-up resistor to 3.3 V |
| 0 | DP_PULLUP | connect the DP pull-up resistor to 3.3 V |

10.1.3.2 OTG Status register (Read: 10h)

[Table 23](#) shows the bit allocation of the OTG Status register.

Table 23: OTG Status register: bit allocation

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|------------|------------|----------|---|---|---|---|---|
| Symbol | B_SESS_VLD | B_SESS_END | reserved | | | | | |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Access | R | R | R | R | R | R | R | R |

Table 24: OTG Status register: bit description

| Bit | Symbol | Description |
|--------|------------|---|
| 7 | B_SESS_VLD | set when the V_{BUS} voltage is above the B-device session valid threshold (2.0 V to 4.0 V) |
| 6 | B_SESS_END | set when the V_{BUS} voltage is below the B-device session end threshold (0.2 V to 0.8 V) |
| 5 to 0 | - | reserved |

10.1.4 Interrupt related registers

10.1.4.1 Interrupt Source register (Read: 08h)

This register indicates the current state of the signals that can generate an interrupt. The bit allocation of the Interrupt Source register is given in [Table 25](#).

Table 25: Interrupt Source register: bit allocation

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|-----------|----------|-------|--------|-------|----------|----------|
| Symbol | CR_INT | BDIS_ACON | ID_FLOAT | DM_HI | ID_GND | DP_HI | SESS_VLD | VBUS_VLD |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Access | R | R | R | R | R | R | R | R |

Table 26: Interrupt Source register: bit description

| Bit | Symbol | Description |
|-----|-----------|---|
| 7 | CR_INT | DP pin is above the carkit interrupt threshold (0.4 V to 0.6 V) |
| 6 | BDIS_ACON | set when bit BDIS_ACON_EN is set, and the ISP1301 asserts bit DP_PULLUP after detecting the B-device disconnect |
| 5 | ID_FLOAT | ID pin is floating |
| 4 | DM_HI | DM pin is HIGH |
| 3 | ID_GND | ID pin is connected to ground |
| 2 | DP_HI | DP pin is HIGH |
| 1 | SESS_VLD | session valid comparator; threshold = 0.8 V to 2.0 V |
| 0 | VBUS_VLD | A-device V_{BUS} valid comparator; threshold > 4.4 V |

10.1.4.2 Interrupt Latch register (Set/Clear: 0Ah/0Bh)

This register indicates the source that generated the interrupt. The bit allocation of the Interrupt Latch register is given in [Table 27](#).

Table 27: Interrupt Latch register: bit allocation

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|-----------|----------|-------|--------|-------|----------|----------|
| Symbol | CR_INT | BDIS_ACON | ID_FLOAT | DM_HI | ID_GND | DP_HI | SESS_VLD | VBUS_VLD |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Access | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C |

Table 28: Interrupt Latch register: bit description

| Bit | Symbol | Description |
|-----|-----------|---------------------------------------|
| 7 | CR_INT | interrupt for CR_INT status change |
| 6 | BDIS_ACON | interrupt for BDIS_ACON status change |
| 5 | ID_FLOAT | interrupt for ID_FLOAT status change |
| 4 | DM_HI | interrupt for DM_HI status change |
| 3 | ID_GND | interrupt for ID_GND status change |
| 2 | DP_HI | interrupt for DP_HI status change |
| 1 | SESS_VLD | interrupt for SESS_VLD status change |
| 0 | VBUS_VLD | interrupt for VBUS_VLD status change |

10.1.4.3 Interrupt Enable Low register (Set/Clear: 0Ch/0Dh)

This register enables interrupts on transition from true to false. For the bit allocation of this register, see [Table 29](#).

Table 29: Interrupt Enable Low register: bit allocation

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|-----------|----------|-------|--------|-------|----------|----------|
| Symbol | CR_INT | BDIS_ACON | ID_FLOAT | DM_HI | ID_GND | DP_HI | SESS_VLD | VBUS_VLD |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Access | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C |

Table 30: Interrupt Enable Low register: bit description

| Bit | Symbol | Description |
|-----|-----------|--|
| 7 | CR_INT | interrupt enable for CR_INT status change from 1 to 0 |
| 6 | BDIS_ACON | interrupt enable for BDIS_ACON status change from 1 to 0 |
| 5 | ID_FLOAT | interrupt enable for ID_FLOAT status change from 1 to 0 |
| 4 | DM_HI | interrupt enable for DM_HI status change from 1 to 0 |
| 3 | ID_GND | interrupt enable for ID_GND status change from 1 to 0 |
| 2 | DP_HI | interrupt enable for DP_HI status change from 1 to 0 |
| 1 | SESS_VLD | interrupt enable for SESS_VLD status change from 1 to 0 |
| 0 | VBUS_VLD | interrupt enable for VBUS_VLD status change from 1 to 0 |

10.1.4.4 Interrupt Enable High register (Set/Clear: 0Eh/0Fh)

The Interrupt Enable High register enables interrupts on transition from FALSE to TRUE. [Table 31](#) provides the bit allocation of this register.

Table 31: Interrupt Enable High register: bit allocation

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|-----------|----------|-------|--------|-------|----------|----------|
| Symbol | CR_INT | BDIS_ACON | ID_FLOAT | DM_HI | ID_GND | DP_HI | SESS_VLD | VBUS_VLD |
| Reset | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Access | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C | R/S/C |

Table 32: Interrupt Enable High register: bit description

| Bit | Symbol | Description |
|-----|-----------|--|
| 7 | CR_INT | interrupt enable for CR_INT status change from 0 to 1 |
| 6 | BDIS_ACON | interrupt enable for BDIS_ACON status change from 0 to 1 |
| 5 | ID_FLOAT | interrupt enable for ID_FLOAT status change from 0 to 1 |
| 4 | DM_HI | interrupt enable for DM_HI status change from 0 to 1 |
| 3 | ID_GND | interrupt enable for ID_GND status change from 0 to 1 |
| 2 | DP_HI | interrupt enable for DP_HI status change from 0 to 1 |
| 1 | SESS_VLD | interrupt enable for SESS_VLD status change from 0 to 1 |
| 0 | VBUS_VLD | interrupt enable for VBUS_VLD status change from 0 to 1 |

10.2 Interrupts

[Table 26](#) indicates the signals that can generate interrupts. Any of the signals given in [Table 26](#) can generate an interrupt when the signal becomes either LOW or HIGH. After an interrupt has been generated, the OTG Controller should be able to read the status of each signal and the bit that indicates whether that signal generated the interrupt.

A bit in the Interrupt Latch register is set when any of these occurs:

- Writing logic 1 to its set address causes the corresponding bit to be set.
- The corresponding bit in the Interrupt Enable High register is set, and the associated signal changes from LOW to HIGH.
- The corresponding bit in the Interrupt Enable Low register is set, and the associated signal changes from HIGH to LOW.

The Interrupt Latch register bit is cleared by writing logic 1 to its clear address.

10.3 Auto-connect

The Host Negotiation Protocol (HNP) in the OTG supplement specifies the following sequence of events to transfer the role of the host from the A-device to the B-device:

1. The A-device puts the bus in the suspend state.
2. The B-device simulates a disconnect by de-asserting its DP pull-up.
3. The A-device detects SE0 on the bus, and asserts its DP pull-up.
4. The B-device detects that the DP line is HIGH, and takes the role of the host.

The OTG supplement specifies that the time between the B-device de-asserting its DP pull-up and the A-device asserting its pull-up must be less than 3 ms. For an A-device with a slow interrupt response time, 3 ms may not be enough time to write an I²C-bus

command to the ISP1301 to assert the DP pull-up. An alternative method is for the A-device transceiver to automatically assert the DP pull-up after detecting an SE0 from the B-device.

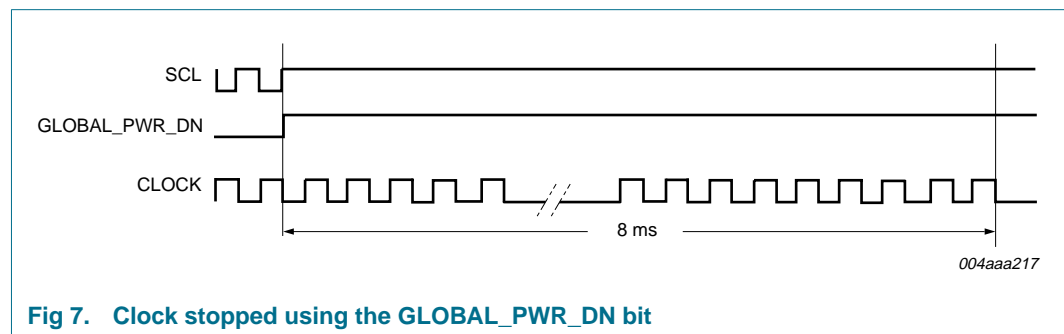
The sequence of events is: After finishing data transfers between the A-device and the B-device and before suspending the bus, the A-device sends SOFs. The B-device receives these SOFs, and does not transmit any packet back to the A-device. During this time, the A-device sets the BDIS_ACON_EN bit in the ISP1301. This enables the ISP1301 to look for SE0 whenever the A-device is not transmitting (that is, whenever the OE_N/INT_N pin of the ISP1301 is not asserted). After the BDIS_ACON_EN bit is set, the A-device stops transmitting SOFs and allows the bus to go to the idle state. If the B-device disconnects, the bus goes to SE0, and the ISP1301 logic automatically turns on the A-device pull-up.

11. Clock wake-up scheme

The following subsections explain the ISP1301 clock stop timing, events triggering the clock to wake up, and the timing of the clock wake-up.

11.1 Power-down event

The clock is stopped when the GLOBAL_PWR_DN bit is set. It takes approximately 8 ms for the clock to stop from the time the power-down condition is detected. The clock always stops at its falling edge. The waveform is given in [Figure 7](#).



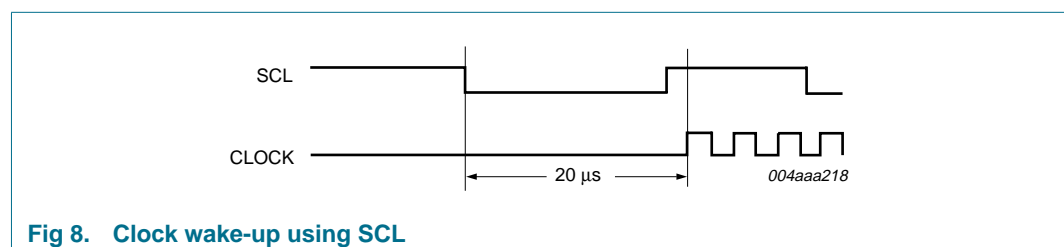
11.2 Clock wake-up events

The clock wakes up when any of the following events occur on the ISP1301 pins:

- SCL goes LOW.
- V_{BUS} goes above the session valid threshold (0.8 V to 2.0 V), provided the SESS_VLD bit in the Interrupt Enable High register is set.
- ID changes when mini-A plug is inserted, provided the ID_FLOAT bit in the Interrupt Enable Low register is set.
- ID changes when mini-A plug is removed, provided the ID_FLOAT bit in the Interrupt Enable High register is set.
- DP goes HIGH, provided the DP_HI bit in the Interrupt Enable High register is set.
- DM goes HIGH, provided the DM_HI bit in the Interrupt Enable High register is set.

The event triggers the clock to start and a stable clock is guaranteed after about six clock periods, which is approximately 8 μ s. The startup analog clock time is 10 μ s. Therefore, the total estimated start time after a triggered event is about 20 μ s. The clock will always start at its rising edge.

Waveforms of the clock wake-up because of different events are given in [Figure 8](#), [Figure 9](#), [Figure 10](#), [Figure 11](#) and [Figure 12](#).



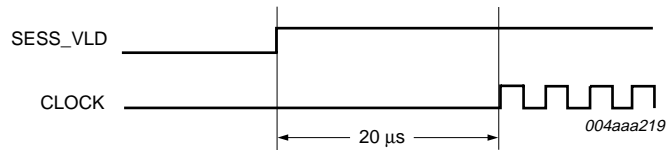


Fig 9. Clock wake-up by V_{BUS}

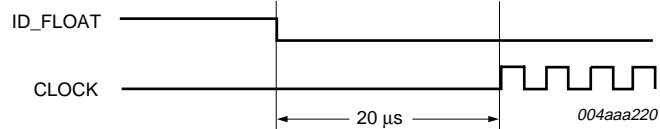


Fig 10. Clock wake-up by ID change (1)

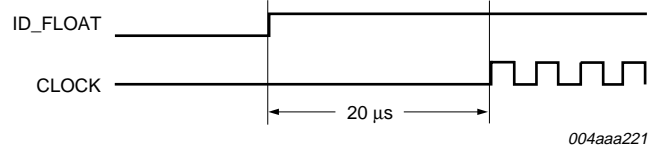


Fig 11. Clock wake-up by ID change (2)

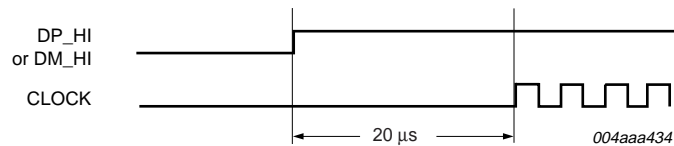


Fig 12. Clock wake-up by data line SRP

When an event is triggered and the clock is started, it will remain active for 8 ms. If the GLOBAL_PWR_DN bit is not cleared within this 8 ms period, the clock will stop. If the clock wakes up because of any event other than SCL going LOW, an interrupt will be generated once the clock is active.

12. I²C-bus protocol

For detailed information, refer to *The I²C-bus specification; version 2.1*.

12.1 I²C-bus byte transfer format

Table 33: I²C-bus byte transfer format

| S [1] | Byte 1 | A [2] | Byte 2 | A [2] | Byte 3 | A [2] | .. | A [2] | P [3] |
|-------|--------|-------|--------|-------|--------|-------|----|-------|-------|
| | 8 bits | | 8 bits | | 8 bits | | .. | | |

[1] S = Start.

[2] A = Acknowledge.

[3] P = Stop.

12.2 I²C-bus device address

Table 34: I²C-bus device address byte 1 bit allocation

| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|----|----|----|----|----|----|-----|-------|
| Symbol | A6 | A5 | A4 | A3 | A2 | A1 | A0 | R/W_N |
| Value | 0 | 1 | 0 | 1 | 1 | 0 | [1] | X |

[1] The value of A0 (LSB) is loaded from pin ADR/PSW during reset (including power-on reset). If pin ADR/PSW = HIGH, bit A0 = 1; otherwise bit A0 = 0.

Table 35: I²C-bus device address byte 1 bit description

| Bit | Symbol | Description |
|--------|--------|--|
| 7 to 1 | A[6:0] | Device address: The device address of the ISP1301 is: 01 0110 (A0). |
| 0 | R/W_N | Read or write command. 0 — write 1 — read |

12.3 Write format

A write operation can be performed as:

- One-byte write to the specified register address.
- Multi-byte write to N consecutive registers, starting from the specified start address. N defines the number of registers to write. If N = 1, only the start register is written.

12.3.1 One-byte write

Figure 13 illustrates the byte sequence.

Table 36: Transfer format description for one-byte write

| Byte | Description |
|--------------------|---|
| S | master starts with a START condition |
| Device select | master transmits device address and write command bit R/W = 0 |
| ACK | slave generates an acknowledgment |
| Register address K | master transmits address of register K |
| ACK | slave generates an acknowledgment |

Table 36: Transfer format description for one-byte write...continued

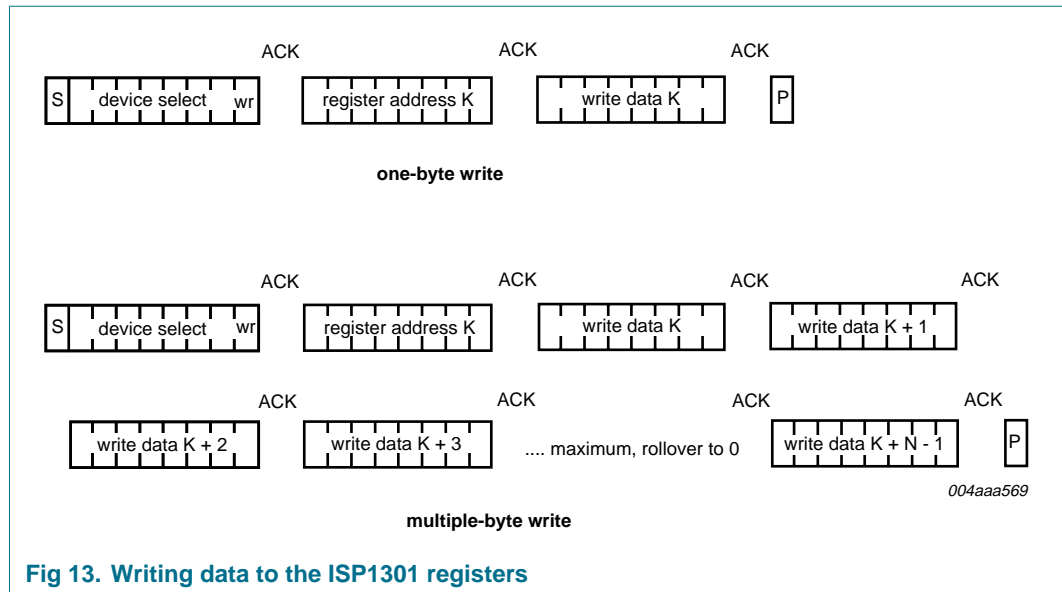
| Byte | Description |
|--------------|-----------------------------------|
| Write data K | master writes data to register K |
| ACK | slave generates an acknowledgment |
| P | master generates a STOP condition |

12.3.2 Multiple-byte write

Figure 13 illustrates the byte sequence.

Table 37: Transfer format description for multiple-byte write

| Byte | Description |
|----------------------|--|
| S | master starts with a START condition |
| Device select | master transmits device address and write command bit R/W = 0 |
| ACK | slave generates an acknowledgment |
| Register address K | master transmits address of register K. This is the start address for writing multiple data bytes to consecutive registers. After a byte is written, the register address is automatically incremented by 1. Remark: If the master writes to a non existent register, the slave must send a 'not ACK' and also must not increment the index address. |
| ACK | slave generates an acknowledgment |
| Write data K | master writes data to register K |
| ACK | slave generates an acknowledgment |
| Write data K + 1 | master writes data to register K + 1 |
| ACK | slave generates an acknowledgment |
| : | : |
| Write data K + N – 1 | master writes data to register K + N – 1. When the incremented address K + N – 1 becomes > 255, the register address rolls over to 0. Therefore, it is possible that some registers may be overwritten, if the transfer is not stopped before the rollover. |
| ACK | slave generates an acknowledgment |
| P | master generates a STOP condition |



12.4 Read format

A read operation can be performed in two ways:

- Current address read: to read the register at the current address.
 - Single register read
- Random address read: to read N registers starting at a specified address. N defines the number of registers to be read. If N = 1, only the start register is read.
 - Single register read
 - Multiple register read

12.4.1 Current address read

[Figure 14](#) illustrates the byte sequence.

Table 38: Transfer format description for current address read

| Byte | Description |
|---------------|---|
| S | master starts with a START condition |
| Device select | master transmits device address and read command bit R/W = 1 |
| ACK | slave generates an acknowledgment |
| Read data K | slave transmits and master reads data from register K. If the start address is not specified, the read operation starts from where the index register is pointing to because of a previous read or write operation. |
| No ACK | master terminates the read operation by generating a No Acknowledge |
| P | master generates a stop condition |

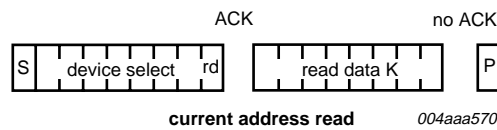


Fig 14. Current address read

12.4.2 Random address read

12.4.2.1 Single read

Figure 15 illustrates the byte sequence.

Table 39: Transfer format description for single-byte read

| SDA line | Description |
|--------------------|---|
| S | master starts with a START condition |
| Device select | master transmits device address and writes command bit R/W = 0 |
| ACK | slave generates an acknowledgment |
| Register address K | master transmits (start) address of register K to be read from |
| ACK | slave generates an acknowledgment |
| Device select | master transmits device address and read command bit R/W = 1 |
| ACK | slave generates an acknowledgment |
| S | master restarts with a START condition |
| Read data K | slave transmits and master reads data from register K |
| No ACK | master terminates the read operation by generating a No Acknowledge |
| P | master generates a STOP condition |

12.4.2.2 Multiple read

Figure 15 illustrates the byte sequence.

Table 40: Transfer format description for multiple-byte read

| SDA line | Description |
|--------------------|---|
| S | master starts with a START condition |
| Device select | master transmits device address and write command bit R/W = 0 |
| ACK | slave generates an acknowledgment |
| Register address K | master transmits (start) address of register K to be read from |
| ACK | slave generates an acknowledgment |
| S | master restarts with a START condition |
| Device select | master transmits device address and read command bit R/W = 1 |
| ACK | slave generates an acknowledgment |
| Read data K | slave transmits and master reads data from register K. After a byte is read, the address is automatically incremented by 1. |
| ACK | master generates an acknowledgment |
| Read data K + 1 | slave transmits and master reads data from register K + 1 |
| ACK | master generates an acknowledgment |
| : | : |

Table 40: Transfer format description for multiple-byte read...continued

| SDA line | Description |
|---------------------|--|
| Read data K + N – 1 | slave transmits and master reads data register K + N – 1. This is the last register to read. After incrementing, the address rolls over to 0. Here, N represents the number of addresses available in the slave. |
| No ACK | master terminates the read operation by generating a No Acknowledge |
| P | master generates a STOP condition |

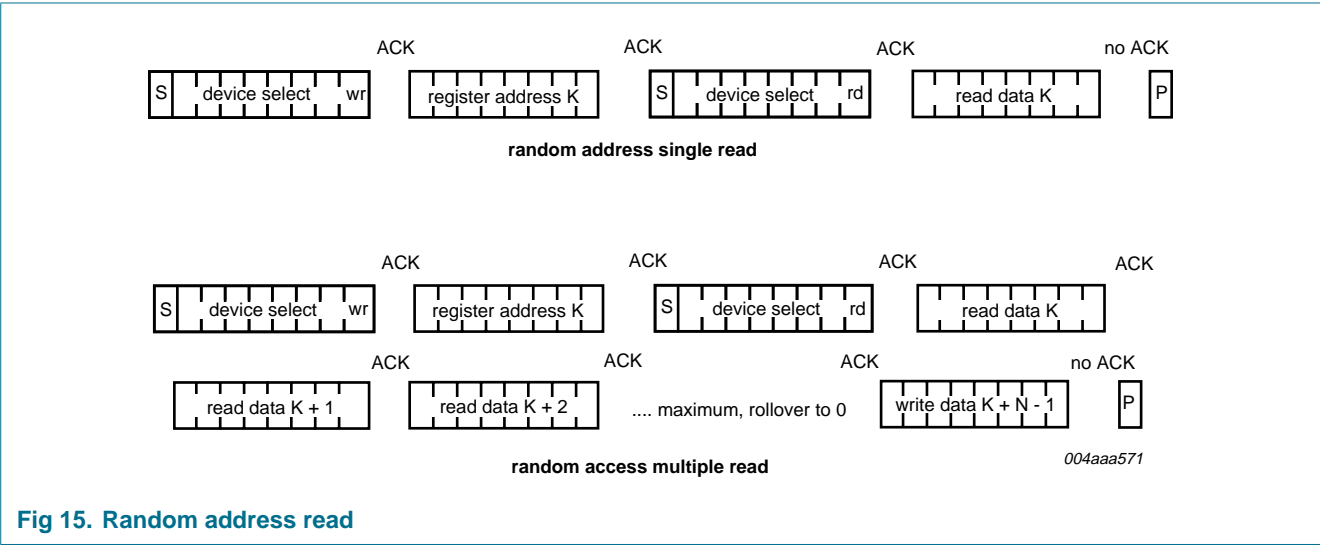


Fig 15. Random address read

13. Limiting values

Table 41: Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|---------------|---------------------------------|--|--------|-------------------------------|------|
| V_{CC} | supply voltage | | -0.5 | +4.6 | V |
| $V_{CC(I/O)}$ | input/output supply voltage | | -0.5 | +4.6 | V |
| V_I | input voltage | $V_I = -1.8 \text{ V to } +5.4 \text{ V}$ | -0.5 | $V_{CC(I/O)} + 0.5 \text{ V}$ | V |
| I_{lu} | latch-up current | | - | 100 | mA |
| V_{esd} | electrostatic discharge voltage | $I_{LI} < 1 \mu\text{A}$ | | | |
| | | pins DP, DM, ID, V_{BUS} , AGND, CGND and DGND | [1] -8 | +8 | kV |
| | | all other pins | -2 | +2 | kV |
| T_{stg} | storage temperature | | -60 | +125 | °C |

[1] Equivalent to discharging a 100 pF capacitor through a 1.5 kΩ resistor (Human Body Model). A 4.7 μF capacitor is needed from VREG3V3 and V_{BUS} to ground.

14. Recommended operating conditions

Table 42: Recommended operating conditions

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---------------|----------------------------------|------------|----------|-----|---------------|------|
| V_{CC} | supply voltage | | 2.7 | - | 3.6 | V |
| $V_{CC(I/O)}$ | input/output supply voltage | | [1] 1.65 | - | 3.6 | V |
| V_I | input voltage | | 0 | - | $V_{CC(I/O)}$ | V |
| $V_{IA(I/O)}$ | input voltage on analog I/O pins | | [2] 0 | - | 3.6 | V |
| $V_{(pu)OD}$ | open-drain pull-up voltage | | [3] 0 | - | 3.6 | V |
| T_{amb} | ambient temperature | | -40 | - | +85 | °C |

[1] $V_{CC(I/O)}$ should be less than or equal to V_{CC} .

[2] Input voltage on analog I/O pins DP and DM.

[3] Open-drain output pull-up voltage on pins SCL, SDA and INT_N.

15. Static characteristics

Table 43: Static characteristics: supply pins
 $V_{CC} = 2.7\text{ V to }4.5\text{ V}$; $V_{CC(I/O)} = 1.65\text{ V to }3.6\text{ V}$; $T_{amb} = -40\text{ }^{\circ}\text{C to }+85\text{ }^{\circ}\text{C}$; unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-----------------------------|--|--|---------|-----|-----|---------------|
| Charge pump disabled | | | | | | |
| $V_{O(REG3V3)}$ | output voltage from internal 3.3 V regulator | $V_{CC} = 3.0\text{ V to }4.5\text{ V}$ | [1] 3.0 | - | 3.6 | V |
| | | $V_{CC} = 2.7\text{ V to }3.0\text{ V}$ | 2.7 | - | 3.0 | V |
| $V_{POR(trip)}$ | power-on reset trip voltage | | 1.5 | - | 2.5 | V |
| I_{CC} | supply current | transmitting and receiving at 12 Mbit/s; $C_L = 50\text{ pF}$ on pins DP and DM | [2] - | 4 | 8 | mA |
| $I_{CC(I/O)}$ | supply current on pin $V_{CC(I/O)}$ | transmitting and receiving at 12 Mbit/s | [2] - | 1 | 2 | mA |
| $I_{CC(idle)}$ | idle and SE0 supply current | idle: $V_{DP} > 2.7\text{ V}$, $V_{DM} < 0.3\text{ V}$; SE0: $V_{DP} < 0.3\text{ V}$, $V_{DM} < 0.3\text{ V}$ | [3] - | - | 300 | μA |
| $I_{CC(I/O)(static)}$ | static supply current on pin $V_{CC(I/O)}$ | idle, SE0 or suspend | - | - | 20 | μA |
| $I_{CC(pd)}$ | Power-down mode supply current | bit GLOBAL_PWR_DN = 1 | [3] - | - | 20 | μA |
| Charge pump enabled | | | | | | |
| $I_{CC(cp)}$ | charge pump supply current | $I_{load} = 8\text{ mA}$; ATX is idle | - | - | 20 | mA |
| | | $I_{load} = 0\text{ mA}$; ATX is idle | - | - | 300 | μA |

[1] In suspend mode, the minimum voltage is 2.7 V.

[2] Maximum value characterized only, not tested in production.

[3] Excluding any load current to the 1.5 k Ω and 15 k Ω pull-up and pull-down resistors (200 μA typical).

Table 44: Static characteristics: digital pins
 $V_{CC} = 2.7\text{ V to }4.5\text{ V}$; $V_{CC(I/O)} = 1.65\text{ V to }3.6\text{ V}$; $T_{amb} = -40\text{ }^{\circ}\text{C to }+85\text{ }^{\circ}\text{C}$; unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---------------------------|---------------------------|-----------------------------------|----------------------------------|-----|------------------|---------------|
| Input levels | | | | | | |
| V_{IL} | LOW-level input voltage | | - | - | $0.3V_{CC(I/O)}$ | V |
| V_{IH} | HIGH-level input voltage | | $0.6V_{CC(I/O)}$ | - | - | V |
| Output levels | | | | | | |
| V_{OL} | LOW-level output voltage | $I_{OL} = 2\text{ mA}$ | - | - | 0.4 | V |
| | | $I_{OL} = 100\text{ }\mu\text{A}$ | - | - | 0.15 | V |
| V_{OH} | HIGH-level output voltage | $I_{OH} = 2\text{ mA}$ | [1] $V_{CC(I/O)} - 0.4\text{ V}$ | - | - | V |
| | | $I_{OH} = 100\text{ }\mu\text{A}$ | $V_{CC(I/O)} - 0.15\text{ V}$ | - | - | V |
| Leakage current | | | | | | |
| I_{LI} | input leakage current | | -1 | - | +1 | μA |
| Open-drain outputs | | | | | | |
| I_{OZ} | off-state output current | | -5 | - | +5 | μA |
| Capacitance | | | | | | |
| C_{in} | input capacitance | pin to GND | - | - | 10 | pF |

[1] Not applicable for open-drain outputs.

Table 45: Static characteristics: analog I/O pins DP and DM

$V_{CC} = 2.7\text{ V to }4.5\text{ V}$; $V_{CC(I/O)} = 1.65\text{ V to }3.6\text{ V}$; $T_{amb} = -40\text{ }^{\circ}\text{C to }+85\text{ }^{\circ}\text{C}$; unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|------------------------|--------------------------------|---|--------|-----|------|---------------|
| Input levels | | | | | | |
| V_{DI} | differential input sensitivity | $ V_{I(DP)} - V_{I(DM)} $ | 0.2 | - | - | V |
| V_{CM} | differential common-mode range | includes V_{DI} range | 0.8 | - | 2.5 | V |
| V_{IL} | LOW-level input voltage | | - | - | 0.8 | V |
| V_{IH} | HIGH-level input voltage | | 2.0 | - | - | V |
| Output levels | | | | | | |
| V_{OL} | LOW-level output voltage | R_L of 1.5 k Ω to +3.6 V | - | - | 0.3 | V |
| V_{OH} | HIGH-level output voltage | R_L of 15 k Ω to GND | | | | |
| | | $V_{CC} = 3.0\text{ V to }4.5\text{ V}$ | 2.8 | - | 3.6 | V |
| | | $V_{CC} = 2.7\text{ V to }3.0\text{ V}$ | 2.6 | - | 3.0 | V |
| Leakage current | | | | | | |
| I_{LZ} | off-state leakage current | | -1 | - | +1 | μA |
| Capacitance | | | | | | |
| C_{in} | input capacitance | pin to GND | - | - | 10 | pF |
| Resistance | | | | | | |
| $R_{DN(DP)}$ | pull-down resistance on pin DP | | 14.25 | - | 24.8 | k Ω |
| $R_{DN(DM)}$ | pull-down resistance on pin DM | | 14.25 | - | 24.8 | k Ω |
| $R_{UP(DP)}$ | pull-up resistance on pin DP | bus idle | 900 | - | 1575 | Ω |
| | | bus driven | 1425 | - | 3090 | Ω |
| $R_{UP(DM)}$ | pull-up resistance on pin DM | bus idle | 900 | - | 1575 | Ω |
| | | bus driven | 1425 | - | 3090 | Ω |
| Z_{DRV} | driver output impedance | steady-state drive | [1] 34 | - | 44 | Ω |
| Z_{INP} | input impedance | | 10 | - | - | M Ω |
| Termination | | | | | | |
| V_{TERM} | termination voltage | for the upstream port pull-up resistor (R_{PU}) | 3.0 | - | 3.6 | V |

[1] Includes external series resistors of $33\text{ }\Omega \pm 1\%$ each on DP and DM.

Table 46: Static characteristics: analog I/O pin ID

$V_{CC} = 2.7\text{ V to }4.5\text{ V}$; $V_{CC(I/O)} = 1.65\text{ V to }3.6\text{ V}$; $T_{amb} = -40\text{ }^{\circ}\text{C to }+85\text{ }^{\circ}\text{C}$; unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-------------------|--------------------------------------|-------------------------------------|-----|-----|-----|------------|
| Resistance | | | | | | |
| $R_{UP(ID)}$ | ID pull-up resistance | on pin ID to VREG3V3 | 77 | - | 130 | k Ω |
| $R_{DN(ID)}$ | pull-down resistance on pin ID | bit ID_PULLDOWN = 1 | - | - | 10 | Ω |
| R_{A_ID} | A-device ID impedance to GND | bit ID_GND = 1 | - | - | 1 | k Ω |
| R_{B_ID} | B-device ID impedance to GND | bit ID_FLOAT = 1 | 800 | - | - | k Ω |
| R_{ACC_ID} | accessory device ID impedance to GND | bit ID_GND = 0; bit ID_FLOAT = 0 | 20 | - | 200 | k Ω |

Table 47: Static characteristics: charge pump

$V_{CC} = 2.7\text{ V to }4.5\text{ V}$; $V_{CC(I/O)} = 1.65\text{ V to }3.6\text{ V}$; $T_{amb} = -40\text{ }^{\circ}\text{C to }+85\text{ }^{\circ}\text{C}$; unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-------------------------|---|--|------|-----|------|------------|
| Current | | | | | | |
| I_{load} | load current | $C_{ext} = 100\text{ nF}$; $V_{BUS} = 4.65\text{ V}$ | 8.0 | - | - | mA |
| Voltage | | | | | | |
| $V_{O(VBUS)}$ | output voltage on pin V_{BUS} | $I_{load} = 8\text{ mA}$; $C_{ext} = 100\text{ nF}$ | 4.65 | 5 | 5.25 | V |
| $V_{L(VBUS)}$ | leakage voltage on pin V_{BUS} | charge pump disabled | - | - | 0.2 | V |
| $V_{A_VBUS_VLD}$ | A-device V_{BUS} valid voltage | | 4.4 | - | 4.65 | V |
| $V_{B_SESS_END}$ | B-device session end voltage | | 0.2 | - | 0.8 | V |
| $V_{hys(B_SESS_END)}$ | B-device session end hysteresis voltage | | - | 150 | - | mV |
| $V_{A_SESS_VLD}$ | A-device session valid voltage | | 0.8 | - | 2.0 | V |
| $V_{hys(A_SESS_VLD)}$ | A-device session valid hysteresis voltage | | - | 200 | - | mV |
| $V_{B_SESS_VLD}$ | B-device session valid voltage | | 2.0 | - | 4.0 | V |
| $V_{hys(B_SESS_VLD)}$ | B-device session valid hysteresis voltage | | - | 200 | - | mV |
| η_{cp} | charge pump efficiency | $I_{load} = 8\text{ mA}$; $V_{CC} = 3\text{ V}$ | - | 75 | - | % |
| Resistance | | | | | | |
| $R_{UP(VBUS)}$ | pull-up resistance on pin V_{BUS} | connect to VREG3V3 when $VBUS_CHRG = 1$ | 460 | - | 1000 | Ω |
| $R_{DN(VBUS)}$ | pull-down resistance on pin V_{BUS} | connect to GND when $VBUS_DISCHRG = 1$ | 660 | - | 1200 | Ω |
| $R_{I(idle)(VBUS)(A)}$ | idle input resistance on pin V_{BUS} (A-device) | ID pin connected to GND | 40 | - | 100 | k Ω |

16. Dynamic characteristics

Table 48: Dynamic characteristics: reset and clock

$V_{CC} = 2.7\text{ V to }4.5\text{ V}$; $V_{CC(I/O)} = 1.65\text{ V to }3.6\text{ V}$; $T_{amb} = -40\text{ }^{\circ}\text{C to }+85\text{ }^{\circ}\text{C}$; unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--------------------------|------------------------------|-----------------------|-----|------|------|---------------|
| Reset | | | | | | |
| $t_{W(\text{RESET_N})}$ | external RESET_N pulse width | | 10 | - | - | μs |
| Internal clock | | | | | | |
| f_{clk} | clock frequency | bit GLOBAL_PWR_DN = 0 | 700 | 1000 | 1300 | kHz |

Table 49: Dynamic characteristics: digital I/O pins

$V_{CC} = 2.7\text{ V to }4.5\text{ V}$; $V_{CC(I/O)} = 1.65\text{ V to }3.6\text{ V}$; $C_L = 50\text{ pF}$; $R_{PU} = 1.5\text{ k}\Omega$ on DP to V_{TERM} ; $T_{amb} = -40\text{ }^{\circ}\text{C to }+85\text{ }^{\circ}\text{C}$; unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-----------|---------------------------|--|-----|-----|-----|------|
| t_{TOI} | bus turnaround time (O/I) | OE_N/INT_N to DAT/VP and SE0/VM; see Figure 20 | 0 | - | 5 | ns |
| t_{TIO} | bus turnaround time (I/O) | OE_N/INT_N to DAT/VP and SE0/VM; see Figure 20 | 0 | - | 5 | ns |

Table 50: Dynamic characteristics: analog I/O pins DP and DM

$V_{CC} = 2.7\text{ V to }4.5\text{ V}$; $V_{CC(I/O)} = 1.65\text{ V to }3.6\text{ V}$; $C_L = 50\text{ pF}$; $R_{PU} = 1.5\text{ k}\Omega$ on DP to V_{TERM} ; $T_{amb} = -40\text{ }^{\circ}\text{C to }+85\text{ }^{\circ}\text{C}$; unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-------------------------------|---|---|---------|-----|-------|------|
| Driver characteristics | | | | | | |
| t_{FR} | rise time | $C_L = 50\text{ pF to }125\text{ pF}$; 10 % to 90 % of $ V_{OH} - V_{OL} $; see Figure 16 | 4 | - | 20 | ns |
| t_{FF} | fall time | $C_L = 50\text{ pF to }125\text{ pF}$; 90 % to 10 % of $ V_{OH} - V_{OL} $; see Figure 16 | 4 | - | 20 | ns |
| FRFM | differential rise time/fall time matching | excluding the first transition from idle state | [1] 90 | - | 111.1 | % |
| V_{CRS} | output signal crossover voltage | excluding the first transition from idle state; see Figure 17 | [2] 1.3 | - | 2.0 | V |

Driver timing

| | | | | | | |
|-----------------------|--|---|---|---|----|----|
| $t_{PLH(\text{drv})}$ | driver propagation delay (LOW to HIGH) | DAT/VP, SE0/VM to DP, DM; see Figure 17 and Figure 21 | - | - | 18 | ns |
| $t_{PHL(\text{drv})}$ | driver propagation delay (HIGH to LOW) | DAT/VP, SE0/VM to DP, DM; see Figure 17 and Figure 21 | - | - | 18 | ns |
| t_{PHZ} | driver disable delay from HIGH level | OE_N/INT_N to DP, DM; see Figure 18 and Figure 22 | - | - | 15 | ns |
| t_{PLZ} | driver disable delay from LOW level | OE_N/INT_N to DP, DM; see Figure 18 and Figure 22 | - | - | 15 | ns |

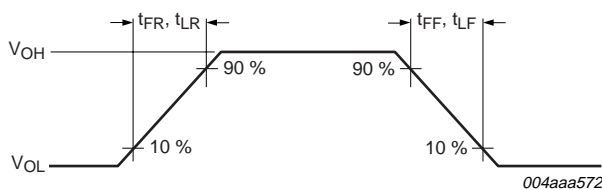
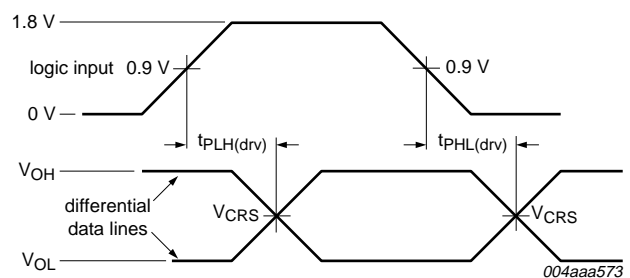
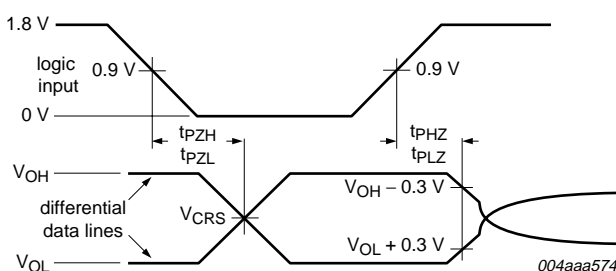
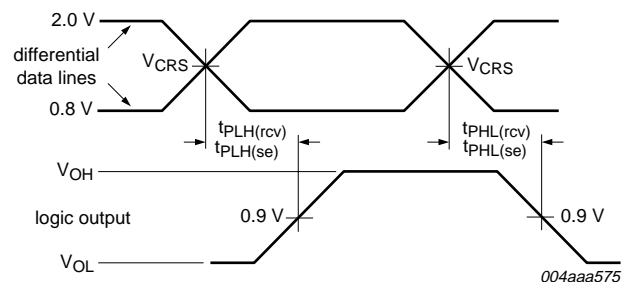
Table 50: Dynamic characteristics: analog I/O pins DP and DM...continued

$V_{CC} = 2.7\text{ V to }4.5\text{ V}$; $V_{CC(I/O)} = 1.65\text{ V to }3.6\text{ V}$; $C_L = 50\text{ pF}$; $R_{PU} = 1.5\text{ k}\Omega$ on DP to V_{TERM} ; $T_{amb} = -40\text{ }^{\circ}\text{C to }+85\text{ }^{\circ}\text{C}$; unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|------------------------------|--|---|-----|-----|-----|------|
| t_{PZH} | driver enable delay to HIGH level | OE_N/INT_N to DP, DM; see Figure 18 and Figure 22 | - | - | 15 | ns |
| t_{PZL} | driver enable delay to LOW level | OE_N/INT_N to DP, DM; see Figure 18 and Figure 22 | - | - | 15 | ns |
| Receiver timing | | | | | | |
| Differential receiver | | | | | | |
| $t_{PLH(rcv)}$ | receiver propagation delay (LOW to HIGH) | DP, DM to RCV; see Figure 19 and Figure 23 | - | - | 15 | ns |
| $t_{PHL(rcv)}$ | receiver propagation delay (HIGH to LOW) | DP, DM to RCV; see Figure 19 and Figure 23 | - | - | 15 | ns |
| Single-ended receiver | | | | | | |
| $t_{PLH(se)}$ | single-ended propagation delay (LOW to HIGH) | DP, DM to VP and DAT/VP, VM and SE0/VM; see Figure 19 and Figure 23 | - | - | 18 | ns |
| $t_{PHL(se)}$ | single-ended propagation delay (HIGH to LOW) | DP, DM to VP and DAT/VP, VM and SE0/VM; see Figure 19 and Figure 23 | - | - | 18 | ns |

[1] t_{FR} / t_{FF} .

[2] Characterized only; not tested. Limits guaranteed by design.

**Fig 16. Rise time and fall time****Fig 17. Timing of DAT/VP and SE0/VM to DP and DM****Fig 18. Timing of OE_N/INT_N to DP and DM****Fig 19. Timing of DP and DM to RCV, VP or DAT/VP and VM or SE0/VM**

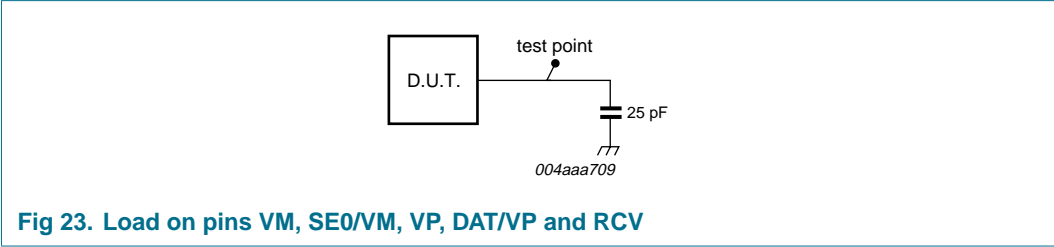
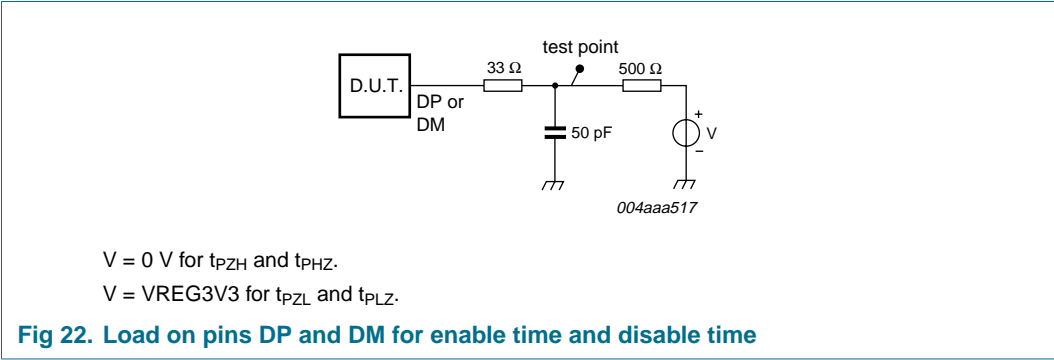
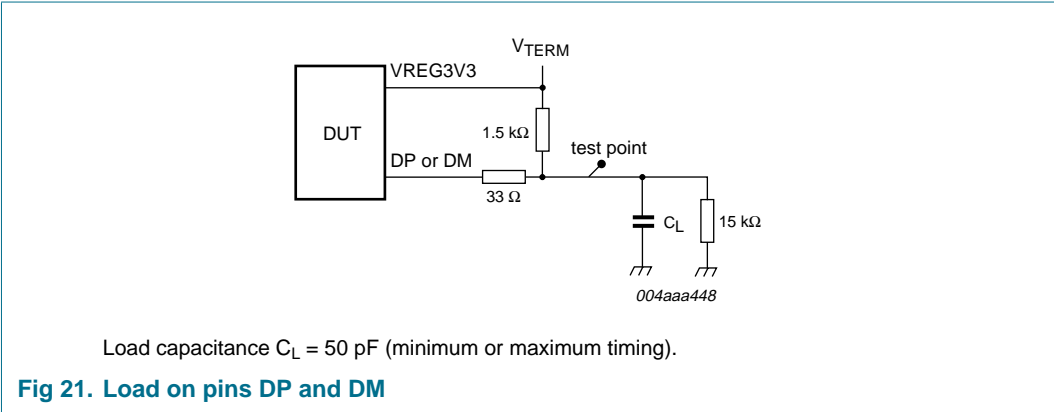
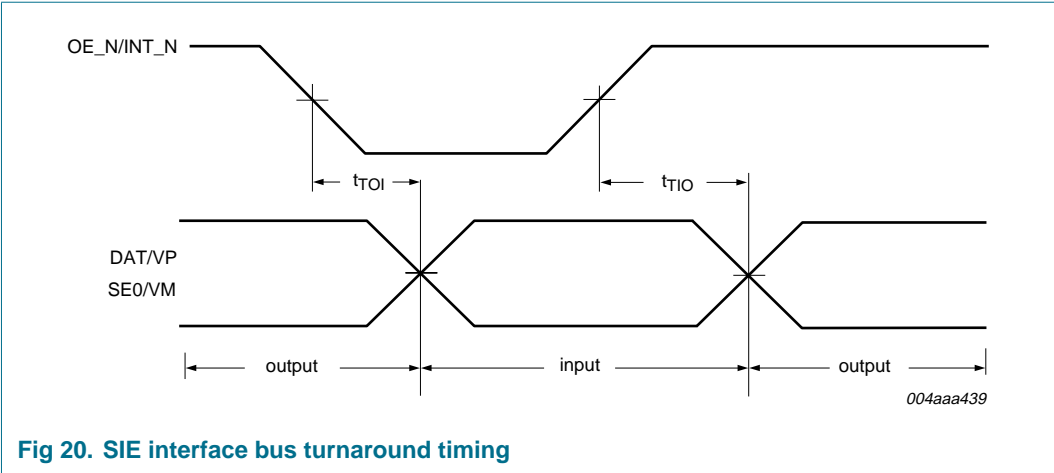
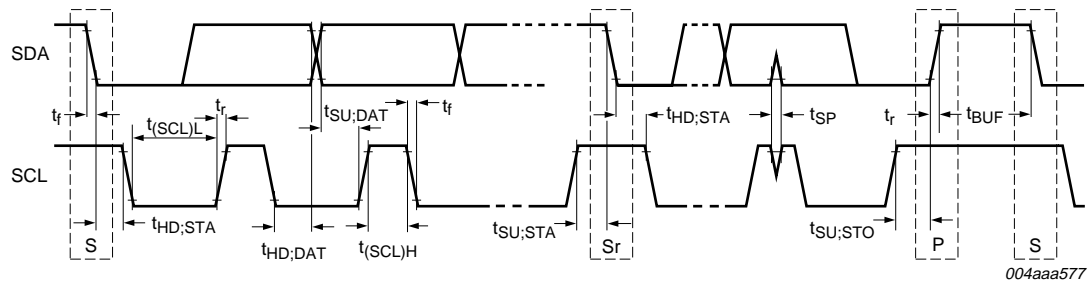


Table 51: Characteristics of I/O stages of I²C-bus lines (SDA, SCL)

| Symbol | Parameter | Conditions | Standard mode | | Unit |
|--------------|--|---------------------|---------------|------|---------|
| | | | Min | Max | |
| f_{SCL} | SCL clock frequency | | - | 100 | kHz |
| $t_{HD;STA}$ | hold time for the START condition | | 4.0 | - | μ s |
| $t_{(SCL)L}$ | LOW period of the SCL clock | | 4.7 | - | μ s |
| $t_{(SCL)H}$ | HIGH period of the SCL clock | | 4.0 | - | μ s |
| $t_{SU;STA}$ | setup time for the START condition | | 4.7 | - | μ s |
| $t_{SU;DAT}$ | data setup time | | 250 | - | ns |
| $t_{HD;DAT}$ | data hold time | | 0 | - | μ s |
| t_r | rise time | SDA and SCL signals | - | 1000 | ns |
| t_f | fall time | SDA and SCL signals | - | 300 | ns |
| $t_{SU;STO}$ | STOP condition setup time | | 4.0 | - | μ s |
| t_{BUF} | bus free time between a STOP and START condition | | 4.7 | - | μ s |

Fig 24. Definition of timing for standard-mode devices on the I²C-bus

17. Application information

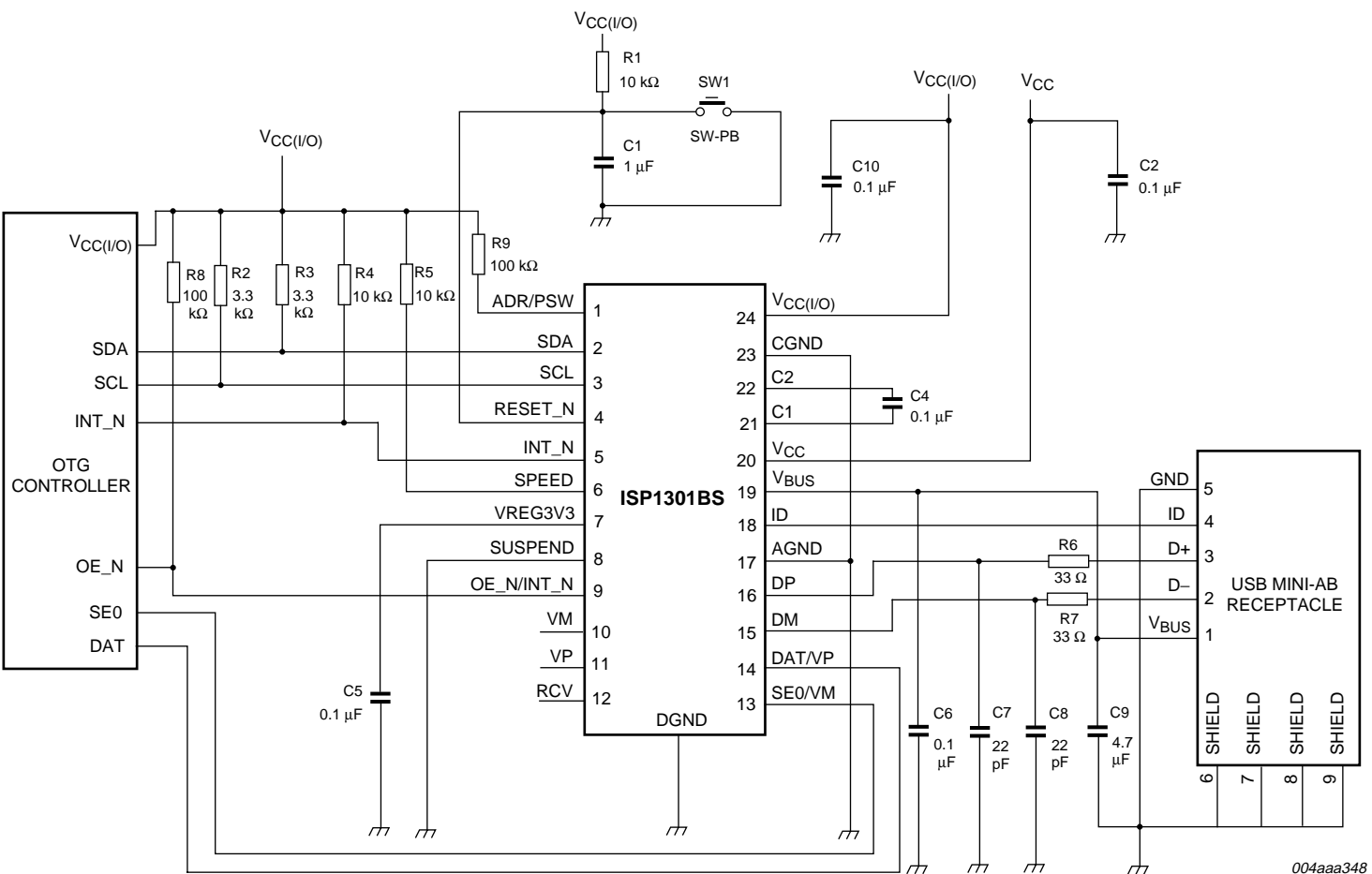


Fig 25. Application diagram for the OTG Controller with the DAT_SE0 SIE interface

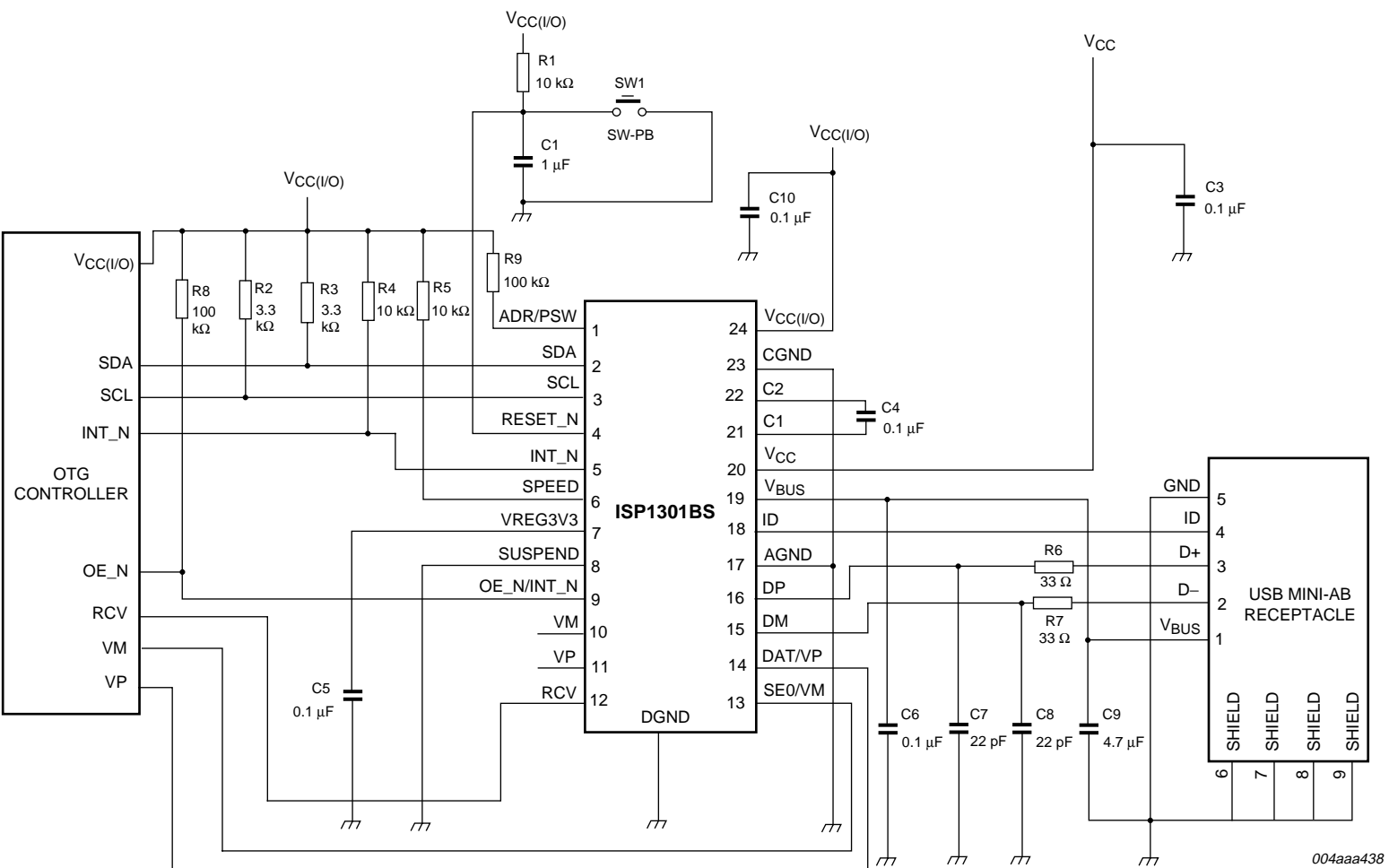


Fig 26. Application diagram for the OTG Controller with the VP_VM SIE interface

18. Package outline

HVQFN24: plastic thermal enhanced very thin quad flat package; no leads;
24 terminals; body 4 x 4 x 0.85 mm

SOT616-1

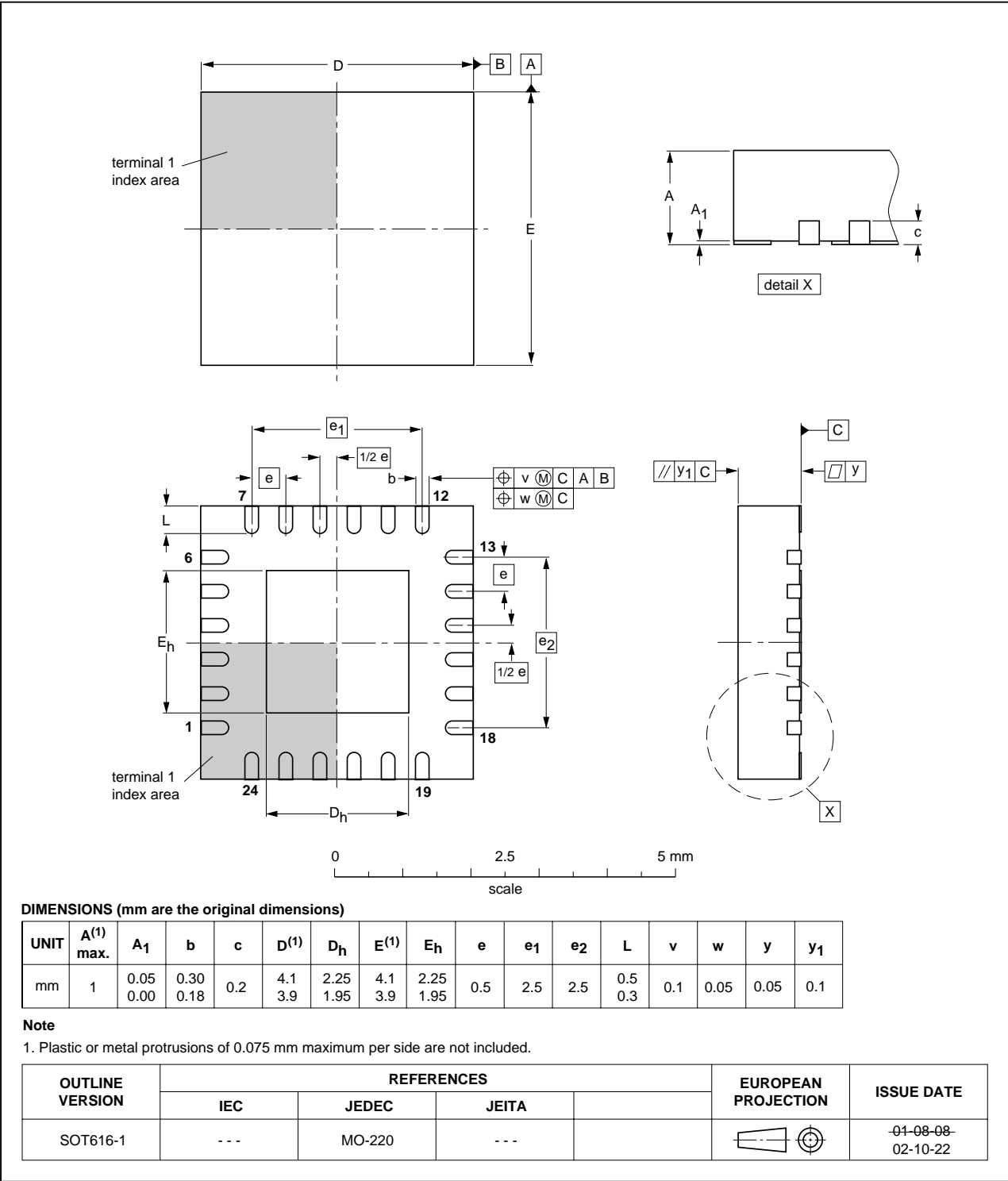


Fig 27. Package outline SOT616-1 (HVQFN24)

19. Soldering

19.1 Introduction to soldering surface mount packages

This text gives a very brief insight to a complex technology. A more in-depth account of soldering ICs can be found in our *Data Handbook IC26; Integrated Circuit Packages* (document order number 9398 652 90011).

There is no soldering method that is ideal for all surface mount IC packages. Wave soldering can still be used for certain surface mount ICs, but it is not suitable for fine pitch SMDs. In these situations reflow soldering is recommended.

19.2 Reflow soldering

Reflow soldering requires solder paste (a suspension of fine solder particles, flux and binding agent) to be applied to the printed-circuit board by screen printing, stencilling or pressure-syringe dispensing before package placement. Driven by legislation and environmental forces the worldwide use of lead-free solder pastes is increasing.

Several methods exist for reflowing; for example, convection or convection/infrared heating in a conveyor type oven. Throughput times (preheating, soldering and cooling) vary between 100 seconds and 200 seconds depending on heating method.

Typical reflow peak temperatures range from 215 °C to 270 °C depending on solder paste material. The top-surface temperature of the packages should preferably be kept:

- below 225 °C (SnPb process) or below 245 °C (Pb-free process)
 - for all BGA, HTSSON..T and SSOP..T packages
 - for packages with a thickness ≥ 2.5 mm
 - for packages with a thickness < 2.5 mm and a volume ≥ 350 mm³ so called thick/large packages.
- below 240 °C (SnPb process) or below 260 °C (Pb-free process) for packages with a thickness < 2.5 mm and a volume < 350 mm³ so called small/thin packages.

Moisture sensitivity precautions, as indicated on packing, must be respected at all times.

19.3 Wave soldering

Conventional single wave soldering is not recommended for surface mount devices (SMDs) or printed-circuit boards with a high component density, as solder bridging and non-wetting can present major problems.

To overcome these problems the double-wave soldering method was specifically developed.

If wave soldering is used the following conditions must be observed for optimal results:

- Use a double-wave soldering method comprising a turbulent wave with high upward pressure followed by a smooth laminar wave.
- For packages with leads on two sides and a pitch (e):
 - larger than or equal to 1.27 mm, the footprint longitudinal axis is **preferred** to be parallel to the transport direction of the printed-circuit board;

- smaller than 1.27 mm, the footprint longitudinal axis **must** be parallel to the transport direction of the printed-circuit board.

The footprint must incorporate solder thieves at the downstream end.

- For packages with leads on four sides, the footprint must be placed at a 45° angle to the transport direction of the printed-circuit board. The footprint must incorporate solder thieves downstream and at the side corners.

During placement and before soldering, the package must be fixed with a droplet of adhesive. The adhesive can be applied by screen printing, pin transfer or syringe dispensing. The package can be soldered after the adhesive is cured.

Typical dwell time of the leads in the wave ranges from 3 seconds to 4 seconds at 250 °C or 265 °C, depending on solder material applied, SnPb or Pb-free respectively.

A mildly-activated flux will eliminate the need for removal of corrosive residues in most applications.

19.4 Manual soldering

Fix the component by first soldering two diagonally-opposite end leads. Use a low voltage (24 V or less) soldering iron applied to the flat part of the lead. Contact time must be limited to 10 seconds at up to 300 °C.

When using a dedicated tool, all other leads can be soldered in one operation within 2 seconds to 5 seconds between 270 °C and 320 °C.

19.5 Package related soldering information

Table 52: Suitability of surface mount IC packages for wave and reflow soldering methods

| Package ^[1] | Soldering method | |
|--|---|-----------------------|
| | Wave | Reflow ^[2] |
| BGA, HTSSON..T ^[3] , LBGA, LFBGA, SQFP, SSOP..T ^[3] , TFBGA, VFBGA, XSON | not suitable | suitable |
| DHVQFN, HBCC, HBGA, HLQFP, HSO, HSOP, HSQFP, HSSON, HTQFP, HTSSOP, HVQFN, HVSON, SMS | not suitable ^[4] | suitable |
| PLCC ^[5] , SO, SOJ | suitable | suitable |
| LQFP, QFP, TQFP | not recommended ^[5] ^[6] | suitable |
| SSOP, TSSOP, VSO, VSSOP | not recommended ^[7] | suitable |
| CWQCCN..L ^[8] , PMFP ^[9] , WQCCN..L ^[8] | not suitable | not suitable |

[1] For more detailed information on the BGA packages refer to the *(LF)BGA Application Note* (AN01026); order a copy from your Philips Semiconductors sales office.

[2] All surface mount (SMD) packages are moisture sensitive. Depending upon the moisture content, the maximum temperature (with respect to time) and body size of the package, there is a risk that internal or external package cracks may occur due to vaporization of the moisture in them (the so called popcorn effect). For details, refer to the Drypack information in the *Data Handbook IC26; Integrated Circuit Packages; Section: Packing Methods*.

[3] These transparent plastic packages are extremely sensitive to reflow soldering conditions and must on no account be processed through more than one soldering cycle or subjected to infrared reflow soldering with peak temperature exceeding 217 °C ± 10 °C measured in the atmosphere of the reflow oven. The package body peak temperature must be kept as low as possible.

- [4] These packages are not suitable for wave soldering. On versions with the heatsink on the bottom side, the solder cannot penetrate between the printed-circuit board and the heatsink. On versions with the heatsink on the top side, the solder might be deposited on the heatsink surface.
- [5] If wave soldering is considered, then the package must be placed at a 45° angle to the solder wave direction. The package footprint must incorporate solder thieves downstream and at the side corners.
- [6] Wave soldering is suitable for LQFP, QFP and TQFP packages with a pitch (e) larger than 0.8 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.65 mm.
- [7] Wave soldering is suitable for SSOP, TSSOP, VSO and VSSOP packages with a pitch (e) equal to or larger than 0.65 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.5 mm.
- [8] Image sensor packages in principle should not be soldered. They are mounted in sockets or delivered pre-mounted on flex foil. However, the image sensor package can be mounted by the client on a flex foil by using a hot bar soldering process. The appropriate soldering profile can be provided on request.
- [9] Hot bar soldering or manual soldering is suitable for PMFP packages.

20. Abbreviations

Table 53: Abbreviations

| Acronym | Description |
|----------------------|---|
| ASIC | Application-Specific Integrated Circuit |
| ATX | Analog USB Transceiver |
| HNP | Host Negotiation Protocol |
| ESD | ElectroStatic Discharge |
| I ² C-bus | Inter IC-bus |
| IC | Integrated Circuit |
| LSB | Least Significant Bit |
| OTG | On-The-Go |
| PDA | Personal Digital Assistant |
| PLD | Programmable Logic Device |
| POR | Power-On Reset |
| PORP | Power-On Reset Pulse |
| SE0 | Single-Ended Zero |
| SOF | Start-Of-Frame |
| SRP | Session Request Protocol |
| USB | Universal Serial Bus |
| USB-IF | USB Implementers Forum |

21. References

- [1] ECN_27%_Resistor (Pull-up/pull-down Resistors ECN)
- [2] Universal Serial Bus Specification Rev. 2.0
- [3] On-The-Go Supplement to the USB Specification Rev. 1.0a
- [4] On-The-Go Transceiver Specification (CEA-2011) Rev. 1.0
- [5] The I2C-bus specification; version 2.1

22. Revision history

Table 54: Revision history

| Document ID | Release date | Data sheet status | Change notice | Doc. number | Supersedes |
|----------------|--|--------------------|---------------|----------------|------------|
| ISP1301_3 | 20060221 | Product data sheet | - | - | ISP1301-02 |
| Modifications: | <ul style="list-style-type: none">• The format of this data sheet has been redesigned to comply with the new presentation and information standard of Philips Semiconductors.• Updated symbols and pin names according to the latest Philips Semiconductors standards.• Table 41 "Limiting values": updated the maximum value of V_{CC}.• Table 42 "Recommended operating conditions": updated the maximum value of V_{CC}. | | | | |
| ISP1301-02 | 20050104 | Product data | - | 9397 750 14337 | ISP1301-01 |
| ISP1301-01 | 20040414 | Product data | - | 9397 750 11355 | - |

23. Data sheet status

| Level | Data sheet status ^[1] | Product status ^{[2] [3]} | Definition |
|-------|----------------------------------|-----------------------------------|--|
| I | Objective data | Development | This data sheet contains data from the objective specification for product development. Philips Semiconductors reserves the right to change the specification in any manner without notice. |
| II | Preliminary data | Qualification | This data sheet contains data from the preliminary specification. Supplementary data will be published at a later date. Philips Semiconductors reserves the right to change the specification without notice, in order to improve the design and supply the best possible product. |
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[2] The product status of the device(s) described in this data sheet may have changed since this data sheet was published. The latest information is available on the Internet at URL <http://www.semiconductors.philips.com>.

[3] For data sheets describing multiple type numbers, the highest-level product status determines the data sheet status.

24. Definitions

Short-form specification — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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Date of release: 21 February 2006
Document number: ISP1301_3

Published in The Netherlands

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