64 k SRAM (8-kword \times 8-bit)

HITACHI

ADE-203-454B (Z) Rev. 2.0 Nov. 1997

Description

The Hitachi HM6264B is 64k-bit static RAM organized 8-kword \times 8-bit. It realizes higher performance and low power consumption by 1.5 μ m CMOS process technology. The device, packaged in 450 mil SOP (foot print pitch width), 600 mil plastic DIP, 300 mil plastic DIP, is available for high density mounting.

Features

• High speed

Fast access time: 85/100 ns (max)

• Low power

Standby: 10 µW (typ)

Operation: 15 mW (typ) (f = 1 MHz)

- Single 5 V supply
- Completely static memory

No clock or timing strobe required

- Equal access and cycle times
- Common data input and output

Three state output

• Directly TTL compatible

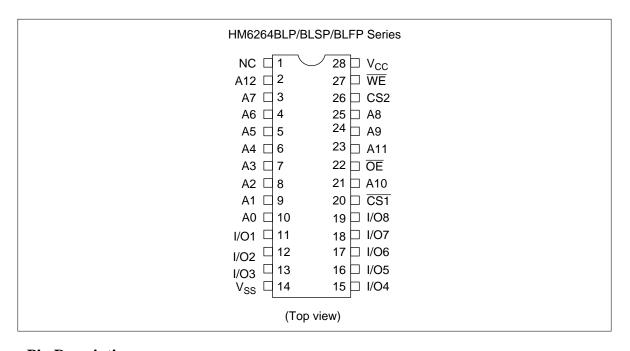
All inputs and outputs

Battery backup operation capability

Ordering Information

Type No.	Access time	Package
HM6264BLP-8L HM6264BLP-10L	85 ns 100 ns	600-mil, 28-pin plastic DIP (DP-28)
HM6264BLSP-8L HM6264BLSP-10L	85 ns 100 ns	300-mil, 28-pin plastic DIP(DP-28N)
HM6264BLFP-8LT HM6264BLFP-10LT	85 ns 100 ns	450-mil, 28-pin plastic SOP(FP-28DA)

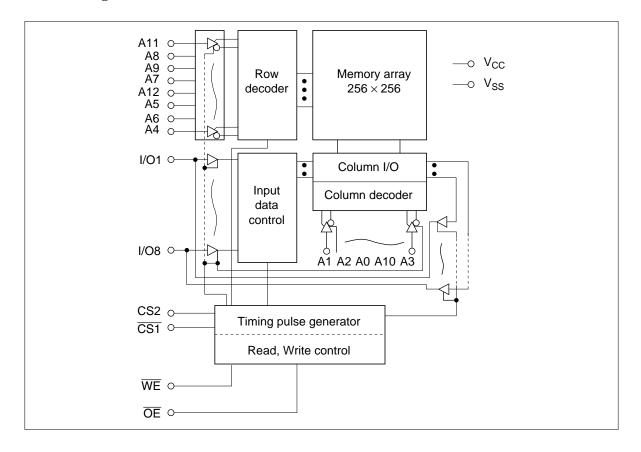
Pin Arrangement



Pin Description

Function	Pin name	Function	
Address input	WE	Write enable	
Data input/output	ŌĒ	Output enable	
Chip select 1	NC	No connection	
Chip select 2	V _{cc}	Power supply	
	V _{ss}	Ground	
	Address input Data input/output Chip select 1	Address input WE Data input/output OE Chip select 1 NC Chip select 2 V _{cc}	Address input WE Write enable

Block Diagram



Function Table

WE	CS1	CS2	OE	Mode	V _{cc} current	I/O pin	Ref. cycle
×	Н	×	×	Not selected (power down)	I_{SB}, I_{SB1}	High-Z	_
×	×	L	×	Not selected (power down)	I_{SB}, I_{SB1}	High-Z	_
Н	L	Н	Н	Output disable	I _{cc}	High-Z	_
Н	L	Н	L	Read	I _{cc}	Dout	Read cycle (1)–(3)
L	L	Н	Н	Write	I _{cc}	Din	Write cycle (1)
L	L	Н	L	Write	I _{cc}	Din	Write cycle (2)

Note: x: H or L

Absolute Maximum Ratings

Parameter	Symbol	Value	Unit
Power supply voltage ⁻¹	V _{cc}	-0.5 to +7.0	V
Terminal voltage ^{*1}	V _T	-0.5^{*2} to $V_{CC} + 0.3^{*3}$	V
Power dissipation	P _T	1.0	W
Operating temperature	Topr	0 to + 70	°C
Storage temperature	Tstg	-55 to +125	°C
Storage temperature under bias	Tbias	-10 to +85	°C

Notes: 1. Relative to V_{ss}

2. V_T min: -3.0 V for pulse half-width ≤ 50 ns

3. Maximum voltage is 7.0 V

Recommended DC Operating Conditions (Ta = 0 to +70°C)

Parameter	Symbol	Min	Тур	Max	Unit
Supply voltage	V _{cc}	4.5	5.0	5.5	V
	V _{SS}	0	0	0	V
Input high voltage	V_{IH}	2.2	_	$V_{cc} + 0.3$	V
Input low voltage	V _{IL}	-0.3 ^{*1}		0.8	V

Note: 1. V_{IL} min: -3.0 V for pulse half-width ≤ 50 ns

DC Characteristics (Ta = 0 to +70°C, V_{CC} = 5 V ±10%, V_{SS} = 0 V)

Parameter	Symbol	Min	Typ ^{⁺¹}	Max	Unit	Test conditions
Input leakage current	I _⊔	_	_	2	μΑ	$Vin = V_{SS}$ to V_{CC}
Output leakage current	I _{LO}	_	_	2	μΑ	$\overline{\text{CS1}} = \text{V}_{\text{IH}} \text{ or } \text{CS2} = \text{V}_{\text{IL}} \text{ or } \overline{\text{OE}} = \text{V}_{\text{IH}} \text{ or } \overline{\text{WE}} = \text{V}_{\text{IL}}, \text{V}_{\text{I/O}} = \text{V}_{\text{SS}} \text{ to } \text{V}_{\text{CC}}$
Operating power supply current	I _{CCDC}	_	7	15	mA	$\overline{\text{CS1}} = \text{V}_{\text{IL}}, \text{CS2} = \text{V}_{\text{IH}}, \text{I}_{\text{I/O}} = 0 \text{ mA}$ others = $\text{V}_{\text{IH}}/\text{V}_{\text{IL}}$
Average operating power supply current	I _{CC1}	_	30	45	mA	$\frac{\text{Min cycle, duty} = 100\%,}{\text{CS1}} = \text{V}_{\text{IL}}, \text{CS2} = \text{V}_{\text{IH}}, \text{I}_{\text{I/O}} = 0 \text{ mA}} \\ \text{others} = \text{V}_{\text{IH}}/\text{V}_{\text{IL}}$
	I _{CC2}	_	3	5	mA	$\begin{split} & \frac{\text{Cycle time}}{\text{CS1}} \leq 0.2 \text{ V, CS2} \geq V_{\text{CC}} - 0.2 \text{ V,} \\ & V_{\text{IH}} \geq V_{\text{CC}} - 0.2 \text{ V,} \\ \end{split}$
Standby power supply current	I _{SB}	_	1	3	mA	$\overline{\text{CS1}} = \text{V}_{\text{IH}}, \text{CS2} = \text{V}_{\text{IL}}$
	I _{SB1}	_	2	50	μΑ	
Output low voltage	V _{OL}	_		0.4	V	I _{OL} = 2.1 mA
Output high voltage	V _{OH}	2.4	_	_	V	I _{OH} = -1.0 mA

Notes: 1. Typical values are at $V_{cc} = 5.0 \text{ V}$, $Ta = +25^{\circ}\text{C}$ and not guaranteed.

Capacitance (Ta = 25°C, f = 1.0 MHz)

Parameter	Symbol	Min	Тур	Max	Unit	Test conditions
Input capacitance ¹	Cin	_	_	5	pF	Vin = 0 V
Input/output capacitance*1	C _{I/O}	_	_	7	pF	$V_{I/O} = 0 V$

Note: 1. This parameter is sampled and not 100% tested.

AC Characteristics (Ta = 0 to +70°C, V_{CC} = 5 V \pm 10%, unless otherwise noted.)

Test Conditions

• Input pulse levels: 0.8 V to 2.4 V

• Input and output timing reference level: 1.5 V

• Input rise and fall time: 10 ns

• Output load: 1 TTL Gate + C_L (100 pF) (Including scope & jig)

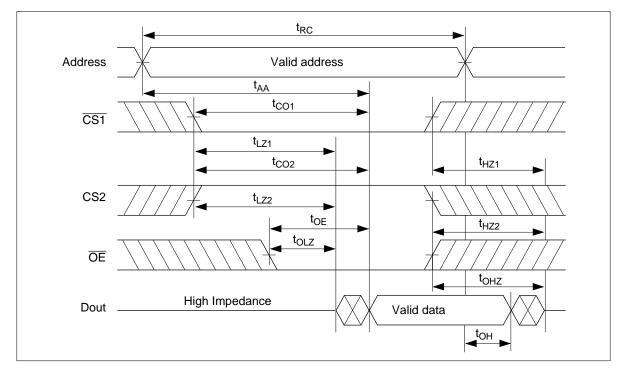
Read Cycle

			HM6264B-8L		HM6264B-10L			
Parameter		Symbol	Min	Max	Min	Max	Unit	Notes
Read cycle time		t _{RC}	85	_	100	_	ns	
Address access time		t _{AA}	_	85	_	100	ns	
Chip select access time	CS1	t _{CO1}	_	85	_	100	ns	
	CS2	t _{CO2}	_	85	_	100	ns	
Output enable to output valid		t _{oe}	_	45	_	50	ns	
Chip selection to output in low-Z	CS1	t _{LZ1}	10	_	10	_	ns	2
	CS2	t _{LZ2}	10		10	_	ns	2
Output enable to output in low-Z		t _{OLZ}	5	_	5	_	ns	2
Chip deselection in to output in high-Z	CS1	t _{HZ1}	0	30	0	35	ns	1, 2
	CS2	t _{HZ2}	0	30	0	35	ns	1, 2
Output disable to output in high-Z		t _{OHZ}	0	30	0	35	ns	1, 2
Output hold from address change		t _{oh}	10	_	10	_	ns	

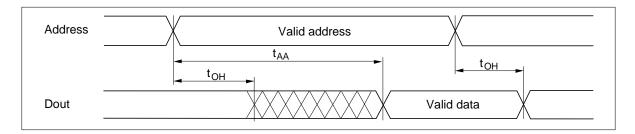
Notes: 1. t_{HZ} is defined as the time at which the outputs achieve the open circuit conditions and are not referred to output voltage levels.

^{2.} At any given temperature and voltage condition, t_{HZ} maximum is less than t_{LZ} minimum both for a given device and from device to device.

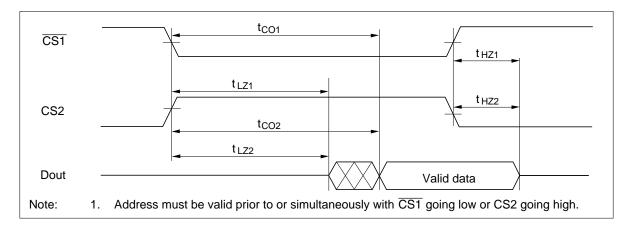
Read Timing Waveform (1) $(\overline{WE}=V_{IH})$



Read Timing Waveform (2) $(\overline{WE}=V_{IH},\,\overline{OE}=V_{IL})$



Read Timing Waveform (3) $(\overline{WE}=V_{IH},\,\overline{OE}=V_{IL})^{*1}$



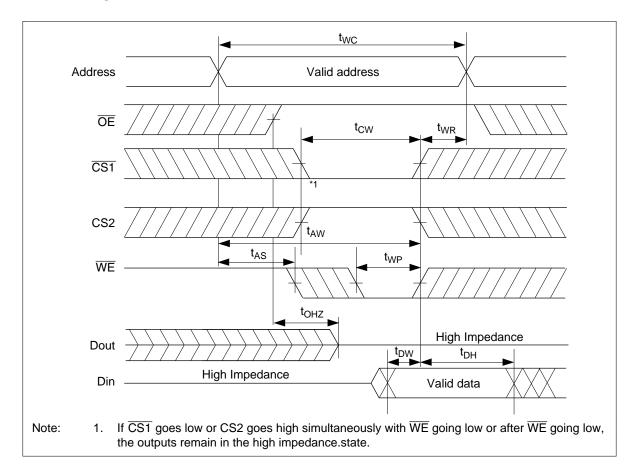
Write Cycle

		HM6264B-8L		HM6264B-10L			
Parameter	Symbol	Min	Max	Min	Max	Unit	Notes
Write cycle time	t _{wc}	85	_	100	_	ns	
Chip selection to end of write	t _{cw}	75	_	80	_	ns	2
Address setup time	t _{AS}	0		0	_	ns	3
Address valid to end of write	t _{AW}	75	_	80	_	ns	
Write pulse width	t _{WP}	55		60	_	ns	1, 6
Write recovery time	t _{WR}	0		0	_	ns	4
WE to output in high-Z	t _{wHZ}	0	30	0	35	ns	5
Data to write time overlap	t _{DW}	40		40	_	ns	
Data hold from write time	t _{DH}	0		0	_	ns	
Output active from end of write	t _{ow}	5		5	_	ns	
Output disable to output in high-Z	t _{OHZ}	0	30	0	35	ns	5

- Notes: 1. A write occurs during the overlap of a low $\overline{CS1}$, and high CS2, and a high \overline{WE} . A write begins at the latest transition among $\overline{CS1}$ going low,CS2 going high and \overline{WE} going low. A write ends at the earliest transition among $\overline{CS1}$ going high CS2 going low and \overline{WE} going high. Time t_{WP} is measured from the beginning of write to the end of write.
 - 2. t_{CW} is measured from the later of $\overline{CS1}$ going low or CS2 going high to the end of write.
 - 3. t_{AS} is measured from the address valid to the beginning of write.
 - 4. t_{WR} is measured from the earliest of $\overline{CS1}$ or \overline{WE} going high or CS2 going low to the end of write cycle.
 - 5. During this period, I/O pins are in the output state, therefore the input signals of the opposite phase to the outputs must not be applied.
 - 6. In the write cycle with $\overline{\text{OE}}$ low fixed, t_{WP} must satisfy the following equation to avoid a problem of data bus contention

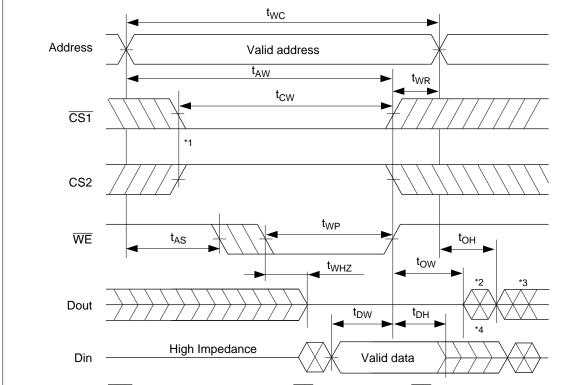
 $t_{WP} \ge t_{WHZ} \max + t_{DW} \min$.

Write Timing Waveform (1) (OE Clock)



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Write Timing Waveform (2) (\overline{OE} Low Fixed) (\overline{OE} = V_{IL})



Notes:

- 1. If $\overline{\text{CS1}}$ goes low simultaneously with $\overline{\text{WE}}$ going low or after $\overline{\text{WE}}$ goes low, the outputs remain in high impedance state.
- 2. Dout is the same phase of the written data in this write cycle.
- 3. Dout is the read data of the next address.
- 4. If $\overline{\text{CS1}}$ is low and CS2 is high during this period, I/O pins are in the output state. Input signals of opposite phase to the outputs must not be applied to I/O pins.

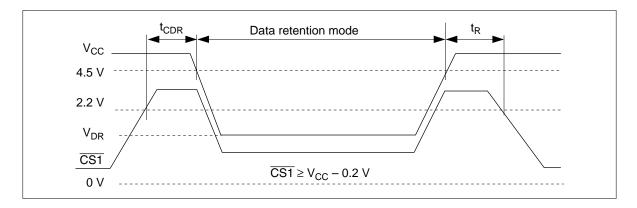
Low V_{CC} **Data Retention Characteristics** (Ta = 0 to +70°C)

Parameter	Symbol	Min	Typ ^{*1}	Max	Unit	Test conditions ^{'4}
V _{cc} for data retention	V_{DR}	2.0	_	_	V	
Data retention current	I _{CCDR}	_	1 ^{*1}	25 ^{*2}	μА	$\begin{array}{c} V_{\text{CC}} = 3.0 \text{ V}, \ 0 \text{ V} \leq \text{Vin} \leq \text{V}_{\text{CC}} \\ \hline \hline \text{CS1} \geq \text{V}_{\text{CC}} - 0.2 \text{ V}, \ \text{CS2} \geq \text{V}_{\text{CC}} - 0.2 \text{ V} \\ \text{or } 0 \text{ V} \leq \text{CS2} \leq 0.2 \text{ V} \end{array}$
Chip deselect to data retention time	t _{CDR}	0	_	_	ns	See retention waveform
Operation recovery time	t _R	t _{RC} *3	_	_	ns	_

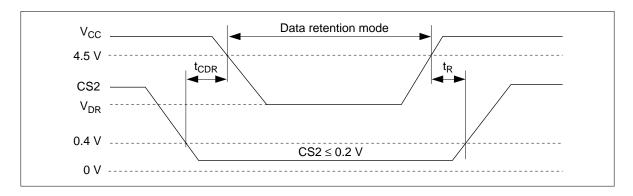
Notes: 1. Reference data at $Ta = 25^{\circ}C$.

- 2. $10 \mu A \text{ max at Ta} = 0 \text{ to} + 40 ^{\circ} \text{C}.$
- 3. t_{RC} = read cycle time.
- 4. CS2 controls address buffer, \overline{WE} buffer, $\overline{CS1}$ buffer, \overline{OE} buffer, and Din buffer. If CS2 controls data retention mode, Vin levels (address, \overline{WE} , \overline{OE} , $\overline{CS1}$, I/O) can be in the high impedance state. If $\overline{CS1}$ controls data retention mode, CS2 must be $CS2 \ge V_{CC} 0.2 \text{ V}$ or $0 \text{ V} \le CS2 \le 0.2 \text{ V}$. The other input levels (address, \overline{WE} , \overline{OE} , I/O) can be in the high impedance state.

Low V_{CC} **Data Retention Timing Waveform (1)** ($\overline{CS1}$ Controlled)

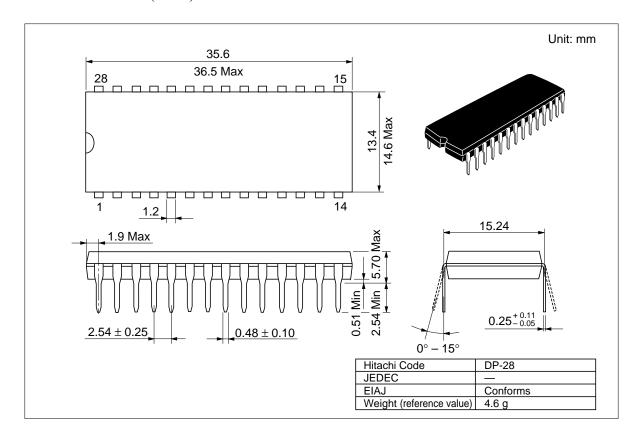


$Low~V_{CC}~Data~Retention~Timing~Waveform~(2)~(\mbox{CS2}~Controlled)$



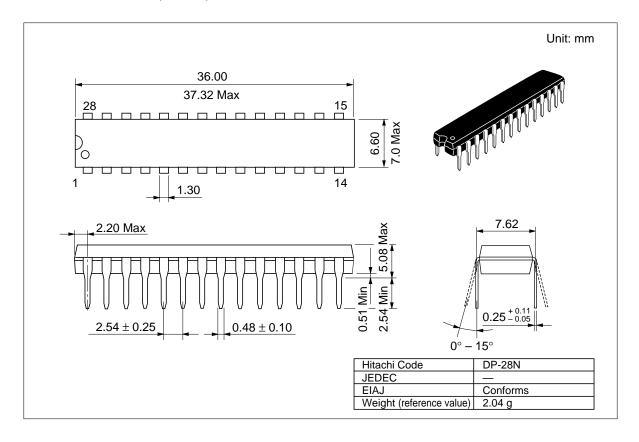
Package Dimensions

HM6264BLP Series (DP-28)



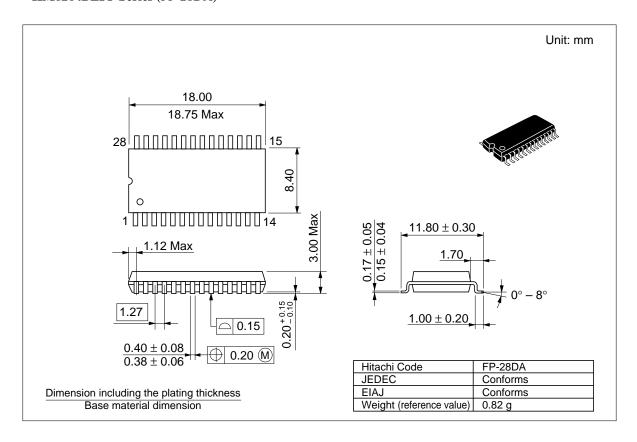
Package Dimensions (cont)

HM6264BLSP Series (DP-28N)



Package Dimensions (cont)

HM6264BLFP Series (FP-28DA)



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0.0	Sep. 5, 1995	Initial issue	I. Ogiwara	K. Yoshizaki
1.0	Dec. 6, 1995	Deletion of Preliminary	I. Ogiwara	K. Yoshizaki
2.0	Nov. 1997	Change of Subtitle Change of FP-28DA		