# CMOS 16-Bit Microcontrollers TMP95PS54F

### Outline and Features

TMP95PS54 is an LSI for TMP95CS54 system evaluation. TMP95PS54 incorporates a 64 Kbyte one-time PROM. With an adapter socket, the user can write/verify data in the TMP95PS54's PROM using a general-purpose EPROM writer.

TMP95PS54 is pin-compatible with TMP95CS54, which incorporates a mask ROM. To achieve the same operations as TMP95CS54, write program data to the internal PROM.

Product Name ROM		RAM	Package	Adapter Socket	
TMP95PS54F	OTP 64 Kbyte	2 Kbyte	P-LQFP100-1414-0.50D	BM11129	

#### **RESTRICTIONS ON PRODUCT USE**

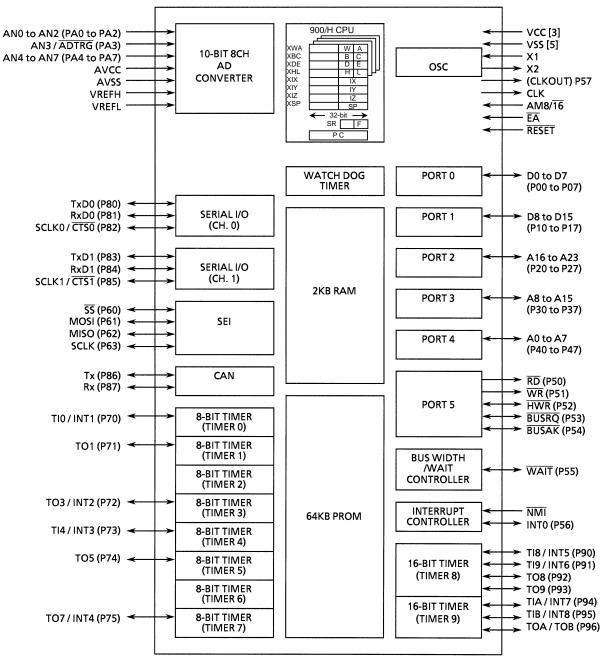
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95PS54-1 2005-05-10



Note: After reset, functions in parentheses () are selected for the shared pins.

Figure 1.1 TMP95PS54 Block Diagram

# 2. Pin Assignment and Pin Functions

This section shows the TMP95PS54 pin assignment, and the names and an outline of the functions of the input/output pins.

### 2.1 Pin Assignment Diagram

Figure 2.1.1 is a pin assignment diagram for TMP95PS54.

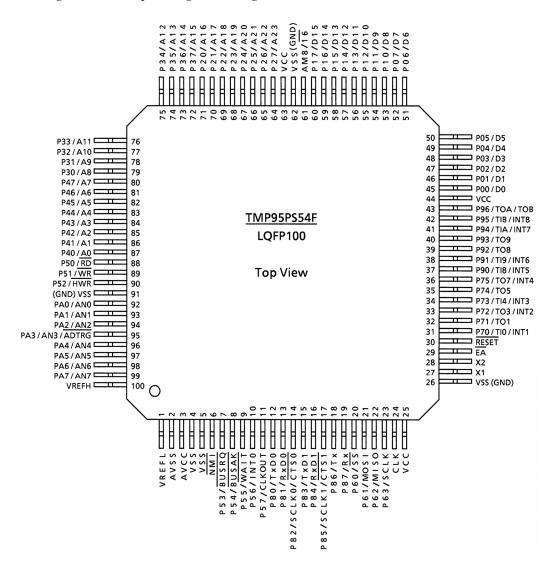


Figure 2.1.1 Pin Allocation Diagram (100-Pin LQFP)

95PS54-3 2005-05-10

### 2.2 Pin Names and Functions

TMP95PS54 has an MCU mode and a PROM mode.

### (1) Pin Names and Functions in MCU Mode

Table 2.2.1 lists the names and functions of the input/output pins.

Table 2.2.1 Pin Names and Functions (1/4)

Pin Name	Number of Pins	Input/Output	Function
P00 to P07	8	Input/output	Port 0: I/O port. Input or output specifiable in units of bits
/ D0 to D7		Input/output	Data: Data bus 0 to 7
P10 to P17	8	Input/output	Port 1: I/O port. Input or output specifiable in units of bits
/ D8 to D15		Input/output	Data: Data bus 8 to 15
P20 to P27	8	Input/output	Port 2: I/O port. Input or output specifiable in units of bits
/ A16 to A23		Output	Address: Address bus 16 to 23
P30 to P37	8	Input/output	Port 3: I/O port. Input or output specifiable in units of bits
/ A8 to A15		Output	Address: Address bus 8 to 15
P40 to P47	8	Input/output	Port 4: I/O port. Input or output specifiable in units of bits
/ A0 to A7		Output	Address: Address bus 0 to 7
P50	1	Output	Port 50: Output-only port
/RD		Output	Read: Outputs strobe signal to read external memory (setting P5
			<P50> = 0 and P5FC $<$ P50F> = 1 outputs strobe signal at all read
			timings)
P51	1	Output	Port 51: Output-only port.
/WR		Output	Write: Outputs strobe signal to write data on pins D0 to D7
P52	1	Input/output	Port 52: I/O port (with built-in pull-up resistor)
/ HWR		Output	Upper write: Outputs strobe signal to write data on pins D8 to D15
P53	1	Input/output	Port 53: I/O port (with built-in pull-up resistor)
/ BUSRQ		Input	Bus request: Input pin to request external bus release
P54	1	Input/output	Port 54: I/O port (with built-in pull-up resistor)
/BUSAK		Output	Bus acknowledge: Output pin to acknowledge that CPU received
			BUSRQ and released external bus.
P55	1	Input/output	Port 55: I/O port (with built-in pull up resistor)
/WAIT		Input	Wait: BuswaitrequestpinforCPU (Effective when 1 WAIT + N mode,
			or 0 + NWAIT mode. Set using bus width/wait control register.)
P56	1	Input/output	Port 56: I/O port (with built-in pull-up resistor)
/INTO		Input	Interrupt request pin 0: Interrupt request pin with programmable
			level/rising edge.

Table 2.2.1 Pin Names and Functions (2/4)

Pin Name	Number of Pins	Input/Output	Function
P57	1	Output	Port 57: Output-only port (with built-in pull-up resistor)
/ CLKOUT		Output	CLKOUT output: Outputs external clock divided by 6.
			Pulled up during reset.
P60	1	Input/output	Port 60: I/O port
/ <del>SS</del>		Input	SEI slave select input
P61	1	Input/output	Port 61: I/O port
/ MOSI		Input/output	SEI master output, slave input
P62	1	Input/output	Port 62: I/O port
/ MISO		Input/output	SEI master input, slave output
P63	1	Input/output	Port 63: I/O port
/ SCLK		Input/output	SEI clock input/output
P70	1	Input/output	Port 70: I/O port
/TI0		Input	Timer input 0: Input pin for timer 0
/INT1		Input	Interrupt request pin 1: Rising-edge interrupt request pin
P71	1	Input/output	Port 71: I/O port.
/TO1		Output	Timer output 1: Output pin for timer 0 or 1
P72	1	Input/output	Port 72: I/O port
/TO3		Output	Timer output 3: Output pin for timer 2 or 3
/INT2		Input	Interrupt request pin 2: Rising-edge interrupt request pin
P73	1	Input/output	Port 73: I/O port
/TI4		Input	Timer input 4: Input pin for timer 4
/INT3		Input	Interrupt request pin 3: Rising-edge interrupt request pin
P74	1	Input/output	Port 74: I/O port
/TO5		Output	Timer output 5: Output pin for timer 4 or 5
P75	1	Input/output	Port 75: I/O port
/TO7		Output	Timer output 7: Output pin for timer 6 or 7
/INT4		Input	Interrupt request pin 4: Rising-edge interrupt request pin
P80	1	Input/output	Port 80: I/O port (with built-in pull-up resistor)
/TxD0		Output	Serial transmission data 0
P81	1	Input/output	Port 81: I/O port (with built-in pull-up resistor)
/RxD0		Input	Serial receive data 0
P82	1	Input/output	Port 82: I/O port (with built-in pull-up resistor)
/ SCLK0		Input/output	Serial clock input/output 0
/ CTSO		Input	Serial data ready to send 0 (Clear-to-send)

Table 2.2.1 Pin Names and Functions (3/4)

Pin Name	Number of Pins	Input/Output	Function
P83	1	Input/output	Port 83: I/O port (with built-in pull-up resistor)
/TxD1		Output	Serial transmission data 1
P84	1	Input/output	Port 84: I/O port (with built-in pull-up resistor)
/RxD1		Input	Serial receive data 1
P85	1	Input/output	Port 85: I/O port (with built-in pull-up resistor)
/SCLK1		Input/output	Serial clock input/output 1
/ CTS1		Input	Serial data ready to send 1 (Clear-to-send)
P86	1	Input/output	Port 86: I/O port (with built-in pull-up resistor)
/Tx		Output	CAN transmission data
P87	1	Input/output	Port 87: I/O port (with built-in pull-up resistor)
/Rx		Input	CAN receive data
P90	1	Input/output	Port 90: I/O port
/TI8		Input	Timer input 8: Input pin for timer 8
/ INT5		Input	Interrupt request pin 5: Interrupt request pin with programmable
			rising/falling edge
P91	1	Input/output	Port 91: I/O port
/TI9		Input	Timer input 9: Input pin for timer 8
/INT6		Input	Interrupt request pin 6: Rising edge interrupt request pin
P92	1	Input/output	Port 92: I/O port
/TO8		Output	Timer output 8: Output pin for timer 8
P93	1	Input/output	Port 93: I/O port
/TO9		Output	Timer output 9: Output pin for timer 8
P94	1	Input/output	Port 94: I/O port
/TIA		Input	Timer input A: Input pin for timer 9
/ INT7		Input	Interrupt request pin 7: Interrupt request pin with programmable rising/falling edge
P95	1	Input/output	Port 95: I/O port
/TIB		Input	Timer input B: Input pin for timer 9
/INT8		Input	Interrupt request pin 8: Rising edge interrupt request pin
P96	1	Input/output	Port 96: I/O port
/TOA		Output	Timer output A: Output pin for timer 9
/TOB		Output	Timer output B: Output pin for timer 9
PA0 to PA2	3	Input	Port A0 to A2: Input-only port
/ AN0 to AN2		Input	Analog input 0 to 2: AD converter input pins
PA3	1	Input	Port A3: Input-only port
/AN3		Input	Analog input 3: AD converter input pin
/ADTRG		Input	External start trigger

Table 2.2.1 Pin Names and Functions (4/4)

Pin Name	Number of Pins	Input/Output	Function
PA4 to PA7	4	Input	Port A4 to A7: Input-only port
/ AN4 to AN7		Input	Analog input 4 to 7: AD converter input pins
NMI	1	Input	Non-maskable interrupt request pin: Interrupt request pin with
			programmable falling edge or both falling and rising edge
CLK	1	Output	Clock output: Outputs external clock divided by 4.
			Pulled up during reset.
ĒĀ	1	Input	External access: Connect to VCC.
AM8/ <del>16</del>	1	Input	Address mode: External data bus width select pin
			Connect this pin to VCC. Data bus width at external access can be
			set by bus width / wait control register.
RESET	1	Input	Reset: Initializes TMP95PS54 (with built-in pull-up resistor)
VREFH	1	Input	Reference voltage input pin for AD converter (high)
VREFL	1	Input	Reference voltage input pin for AD converter (low)
AVCC	1		Power supply pin for AD converter: Connect to power supply
AVSS	1		GND pin for AD converter: Connect to GND
X1/X2	2	Input/output	Oscillator connecting pin
VCC	3		Power supply pin: Connect all VCC pins to power supply
VSS	5		GND pin: Connect all VSS pins to GND (0 V)

Note: Software can be used to turn off the resistance of pull-up pins with resistors (except for the  $\overline{RESET}$  pin).

P57 and CLK pin are pulled-up only during reset.

### (2) PROM Mode Pin Functions and Pin Processing

Tables 2.2.2 and 2.2.3 show the names and functions of the input/output pins, and the pin processing.

Table 2.2.2 Pin Names and Functions

Pin Function Name	Number of Pins	Input/ Output	Function	Pin Name (In MCU Mode)		
A7 to A0	8		P20 to P27			
A15 to A8	8	Input	Program memory address input	P17 to P10		
A16	1			P34		
D7 to D0	8	Input/output	Program memory data input/output	P07 to P00		
CE	1	Input	Chip enable input	P35		
ŌĒ	1	Input	Output control input	P37		
PGM	1	Input	Program control input	P36		
VPP	1	Power supply	12.75 V / 5 V (program power supply)	ĒĀ		
vcc	4	Power supply	6.25 V / 5 V	VCC, AVCC		
VSS	6	Power supply	0 V	VSS, AVSS		

Table 2.2.3 Pin Names and Pin Processing

Pin Name	Number of Pins	Input/ Output	Pin Processing
P33	1	Input	Fixed to low level (SECURITY pin)
RESET	1	Input	Fixed to low level (set to PROM mode)
CLK	1	Input	Fixed to low level (set to PROM Mode)
X1	1	Input	Connect oscillator and set to self-oscillation
X2	1	Output	Connect oscillator and set to self-oscillation
P32 to P30 P47 to P40 P56 to P52 P63 to P60 P75 to P70 P87 to P80 P96 to P90 PA7 to PA0 AM8/16 NMI	51	Input	Fixed to high level
P57, P51, P50	3	Output	
VREFH	1		Open
VREFL	1	Input	

# 3. Operation

The following describes the structure and operation of the TMP95PS54 hardware.

In TMP95PS54, the internal ROM of TMP95CS54 is replaced by an internal PROM. Otherwise, TMP95PS54 is structurally and operationally identical to TMP95CS54. Accordingly, for functions not described here, see the TMP95CS54 section of the manual. TMP95PS54 supports MCU operating mode and PROM operating mode.

#### 3.1 MCU Mode

#### (1) Setting and function

Opening the CLK pin (setting to output) sets MCU mode. In MCU mode, TMP95PS54 operates the same as TMP95CS54.

### (2) Memory map

Figure 3.1.1 shows the memory map in MCU mode and the CPU access area in each addressing mode.

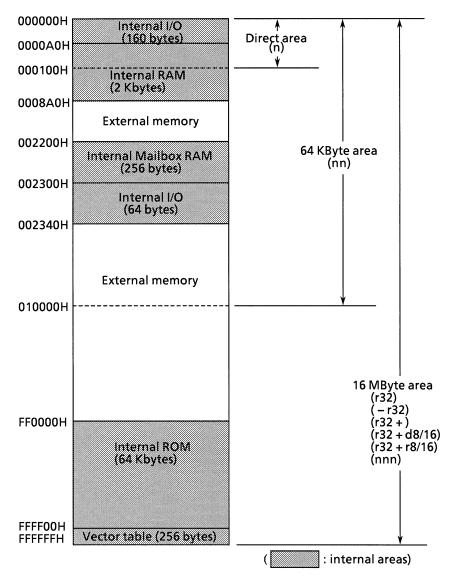


Figure 3.1.1 TMP95PS54 Memory Map

### 3.2 PROM Mode

#### (1) Setting and functions

To set PROM mode, set the  $\overline{RESET}$  and CLK pins to low level.

After PROM mode is set, applying  $V_{CC}$  = 6.25 V and  $V_{PP}$  = 12.75 V enters program mode. PROM can be verified by setting  $V_{CC}$  =  $V_{PP}$  = 5.0 V.

Programs can be written and verified using a general-purpose PROM writer and an adapter socket. Set the ROM type in the general-purpose PROM writer according to the following conditions. (Set the ROM type as equivalent to TC571000D).

• Size : 1 Mbit (128 K × 8 bits)

VPP : 12.75 VTPW : 0.1 ms

• Electric signature function : No

Figure 3.2.1 shows the pin settings in PROM mode.

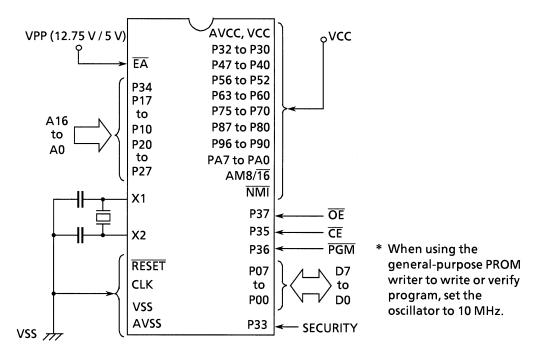


Figure 3.2.1 PROM Mode Pin Settings

#### **Electric Signature Cautions**

TMP95PS54 does not support electric signature mode (hereafter called a signature). When a signature is used by a PROM writer, TMP95PS54 is damaged because 12 V (±0.5 V) is applied to address pin 9 (A9). Therefore, use with the signature mode set off.

### (2) Memory map

The internal PROM addresses in PROM mode are 00000H to 0FFFFH. These correspond to MCU mode addresses FF0000H to FFFFFFH.

Figure 3.2.2 shows a comparison of the MCU and PROM mode memory maps.

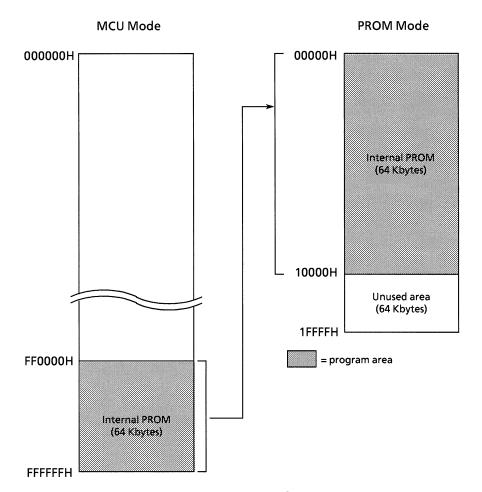


Figure 3.2.2 Memory Map Comparison

#### (3) Program mode

When TMP95PS54 is delivered, all bits are set to 1 (erased). Accordingly, program operations write 0 to the necessary bits. To enable writing, apply  $V_{PP} = 12.75 \text{ V}$ ,  $\overline{OE} = V_{IH}$ ,  $\overline{CE} = V_{II}$ .

The internal one-time PROM can be written to in any order, or may be written only at specified addresses.

#### (4) Adaptor socket (BM11129)

BM11129 is an adapter socket used to write data to the internal one-time PROM in TMP95PS54 using a general-purpose PROM writer.

(5) Settings for writing program using general-purpose PROM writer

Use a PROM writer equivalent to the TC571000D PROM writer.

- 1. Set BM11129 (hereafter called the adapter) switch (SW1) to the program side (NOR). (Note 1)
- 2. Set TMP95PS54 to the adapter socket. (Note 2)
- 3. Set the adapter socket to the PROM writer. (Note 2)
- 4. Set the PROM writer PROM type to TC571000D.
- 5. Set the PROM write start address to 0000H and the end address to FFFFH. (Note 3)
- 6. Write to the internal one-time PROM and verify according to the PROM writer operating procedure.
- Note 1: Writing data to the internal one-time PROM without setting the adapter switch (SW1) to the program side damages the device.
- Note 2: Adaptor socket pin 1 should be aligned with PROM writer socket pin 1. Setting the two the wrong way round will damage the MCU or PROM writer.
- Note 3: If data are written to addresses exceeding end address FFFFH, the data may be written to the 0000H to FFFFH addresses and program content may be damaged.

#### (6) High-speed programming method

To enter program mode, apply  $V_{PP}$  = 12.75 V of program voltage with  $V_{CC}$  = 6.25 V and the  $\overline{RESET}$  and CLK pins at low level input.

Input valid address and input data, and set  $\overline{\text{CE}}$  to low level input. Data can be written by applying a 0.1 ms program (single) pulse to the  $\overline{\text{PGM}}$  input. Verify that data are written to each address. If data are not correctly written, again apply a 0.1 ms program pulse, repeating this procedure (up to 25 times) until the data are correctly written. After that, write data in the same way, simply changing the addresses and the input data. When all writing is complete, set VCC = VPP = 5 V and verify all addresses.

Figure 3.2.3 shows a writing flow chart.

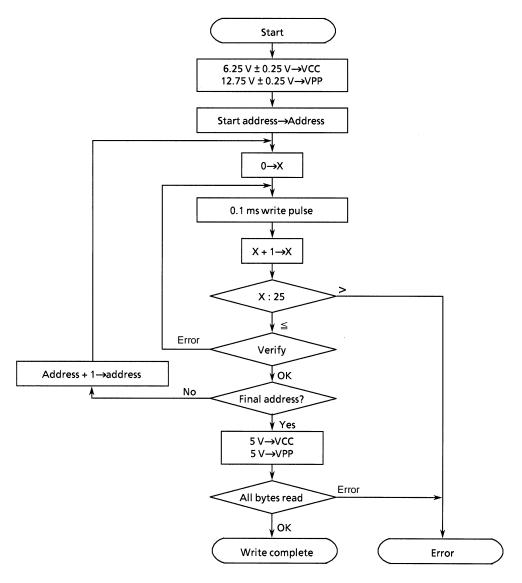


Figure 3.2.3 Writing Flow Chart (High-Speed Programming Method)

#### (7) SECURITY bit

The TMP95PS54 PROM cell contains a built-in security bit (one bit). Writing 0 to this security bit prevents the internal PROM data from being read in PROM mode.

#### Programming security bit

In PROM mode, set the security pin (P33) to 1 and write FEH to address 00000H. Set the PROM write start address to 00000H, the end address to 00000H, and the data on address 00000H to FEH. Then write FEH to address 00000H according to the PROM writer operating procedure. This sets the internal PROM security bit.

#### (8) Cautions

- 1. When turning the VPP power supply (12.75 V) off and on, the VCC must be on.
- 2. Do not plug in or unplug the device with the VPP power on.
- 3. When executing the program, the voltage applied to the VPP pin should not exceed the maximum rating (14 V).

## 4. Electrical Characteristics

### 4.1 Absolute Maximum Ratings

Parameter	Symbol	Rating		Unit
Power Supply Voltage	V cc	- 0.5 1	-0.5 to +6.5	
Input Voltage	V <sub>IN</sub>	except for EA pin	- 0.5 to Vcc + 0.5	V
input voitage	VIN	EA pin	- 0.5 to 14.0	<b>V</b>
Output current (total)	$\Sigma$ lol	+ 120		mA
Output current (total)	$\Sigma$ loh	- 120		mA
Power Dissipation ( $Ta = +85^{\circ}C$ )	P <sub>D</sub>	6	600	
Soldering Temperature (10 s)	T SOLDER	+ 260		°C
Storage Temperature	T <sub>STG</sub>	- 65 to + 150		°C
Operating Temperature	T OPR	<b>- 40</b> 1	to +85	°C

Note: The absolute maximum ratings are rated values which must not be exceeded during operation, even for an instant. Any one of the ratings must not be exceeded. If any absolute maximum rating is exceeded, a device may break down or its performance may be degraded, causing it to catch fire or explode resulting in injury to the user. Thus, when designing products which include this device, ensure that no absolute maximum rating value will ever be exceeded.

### 4.2 DC Electrical Characteristics

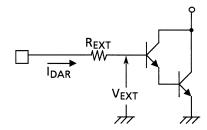
 $Vcc = 4.7 \text{ to } 5.3 \text{ V}, Ta = -40 \text{ to } + 85^{\circ}\text{C} \text{ (fc } = 8 \text{ to } 24 \text{ MHz)}$ 

(Typical values are for Ta = +25°C, VCC = +5 V.)

Parameter	Symbol	Test Condition	Min	Max	Unit
Input Low Voltage (D0 to 15) Port 2 to A (except P56, P70, P72, P73, P75)	V IL V IL1		-0.3 -0.3	0.8 0.3 Vcc	V
RESET, NMI, INTO to 4 EA, AM8/16 X1	V IL2 V IL3 V IL4		-0.3 -0.3 -0.3	0.25 Vcc 0.3 0.2Vcc	V V V
Input High Voltage (D0 to 15) Port 2 to A (except P56, P70, P72, P73, P75)	V <sub>IH</sub> V <sub>IH1</sub>		2.2 0.7 Vcc	Vcc + 0.3 Vcc + 0.3	V
RESET, NMI, INTO to 4 EA, AM8/16 X1	V 1H2 V 1H3 V 1H4		0.75 Vcc Vcc – 0.3 0.8Vcc	Vcc + 0.3 Vcc + 0.3 Vcc + 0.3	V V V
Output Low Voltage	V OL	I <sub>OL</sub> = 1.6 mA		0.45	V
Output High Voltage	V OH V OH1 V OH2	I <sub>OH</sub> = - 400 μA I <sub>OH</sub> = - 100 μA I <sub>OH</sub> = - 20 μA	2.4 0.75 Vcc 0.9 Vcc		> > >
Darlington Drive Current (8 Output Pins max.)	IDAR	$V_{EXT} = 1.5 V$ R <sub>EXT</sub> = 1.1 kΩ	<b>– 1.0</b>	- 3.5	mA
Input Leakage Current Output Leakage Current	I <sub>LI</sub> I LO	0.0≦ Vin≦ Vcc 0.2≦ Vin≦ Vcc – 0.2	0.02 (Typ) 0.05 (Typ)	±5 ±10	μ <b>Α</b> μ <b>Α</b>
Operating Current (NORMAL) RUN IDLE2 IDLE1	l cc	fc = 24 MHz	69 (Typ) 35 (Typ) 27 (Typ) 5 (Typ)	85 50 40 10	mA mA mA mA
STOP (Ta = -40 to +85 °C) (Ta = -20 to +70 °C)		0.2≦ Vin≦ Vcc – 0.2	0.5 (Typ)	100 50	μ <b>Α</b> μ <b>Α</b>
Power Down Voltage (@STOP, RAM Back up)	V STOP	V <sub>IL2</sub> = 0.2 Vcc, V <sub>IH2</sub> = 0.8 Vcc	2.0	6.0	V
Pull Up Registance	R <sub>RP</sub>		45	160	<b>k</b> Ω
Pin Capacitance	C 10	fc = 1 MHz		10	рF
Schmitt Width RESET, NMI, INTO to 4	V <sub>TH</sub>		0.4	1.0 (Typ)	٧

Note: IDAR guarantees up to eight pins from any output port.

Refer: I<sub>DAR</sub> definition diagram.



### 4.3 AC Electrical Characteristics

 $Vcc = 4.7 \text{ to } 5.3 \text{ V}, Ta = -40 \text{ to } + 85^{\circ}\text{C}$ 

(fc = 8 MHz to 24 MHz)

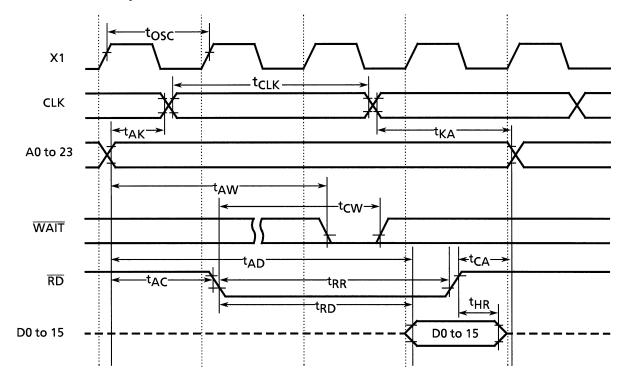
No.	Parameter	Cumahal	Vari	able	24 N	/lHz	Unit
NO.	Parameter	Symbol	Min	Max	Min	Max	Onit
1	Oscillation cycle ( = x)	tosc	42	125	42		ns
2	Clock pulse width	t <sub>CLK</sub>	2.0x - 40		44		ns
3	A0 to 23 valid → Clock hold	t <sub>AK</sub>	0.5x - 20		1		ns
4	Clock valid → A0 to 23 hold	t <sub>KA</sub>	1.5x - 60		3		ns
5	A0 to 23 valid $\rightarrow \overline{RD}/\overline{WR}$ fall	t <sub>AC</sub>	1.0x - 20		22		ns
6	$\overline{RD}/\overline{WR}$ rise $\rightarrow$ A0 to 23 hold	tcA	0.5x - 20		1		ns
7	A0 to 23 valid $\rightarrow$ D0 to 15 input	t <sub>AD</sub>		3.5x – 40		107	ns
8	$\overline{\text{RD}}$ fall $\rightarrow$ D0 to 15 input	t <sub>RD</sub>		2.5x - 45		60	ns
9	RD low pulse width	t <sub>RR</sub>	2.5x - 40		65		ns
10	$\overline{\text{RD}}$ rise $\rightarrow$ D0 to 15 hold	t <sub>HR</sub>	0		0		ns
11	WR low pulse width	t <sub>WW</sub>	2.5x - 40		65		ns
12	D0 to 15 valid $\rightarrow \overline{WR}$ rise	t <sub>DW</sub>	2.0x - 40		44		ns
13	WR rise →D0 to 15 hold	t <sub>WD</sub>	0.5x - 10		11		ns
14	A0 to 23 valid $\rightarrow \overline{\text{WAIT}}$ input $\binom{1 \text{ WAIT}}{+ \text{ n mode}}$	t <sub>AW</sub>		3.5x - 90		57	ns
	A0 to 23 valid $\rightarrow \overline{\text{WAIT}}$ input $\begin{pmatrix} 0 + \eta \text{ WAIT} \\ \text{mode} \end{pmatrix}$	t <sub>AW</sub>		1.5x – 40		23	ns
15	$\overline{\text{RD/WR}} \text{ fall} \rightarrow \overline{\text{WAIT}} \text{ hold} \qquad \begin{pmatrix} 1 \text{ WAIT} \\ + \text{ n mode} \end{pmatrix}$	t <sub>CW</sub>	2.5x + 0		105		ns
	$\overline{\text{RD/WR}} \text{ fall} \rightarrow \overline{\text{WAIT}} \text{ hold} \qquad \begin{pmatrix} 0 + \eta \text{ WAIT} \\ \text{mode} \end{pmatrix}$	t <sub>CW</sub>	0.5x + 0		21		ns
16	WR rise→ PORT valid	t <sub>CP</sub>		200		200	ns

### AC measuring conditions

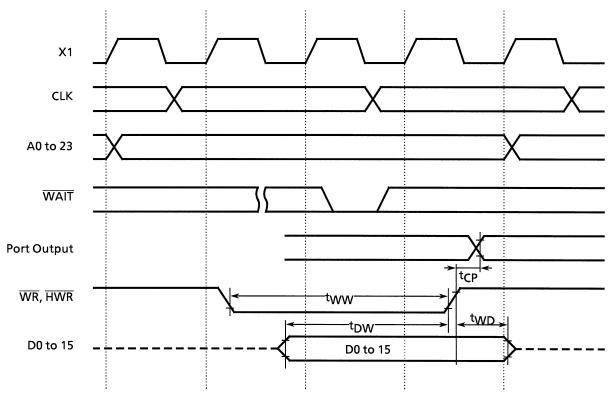
Output level : High 2.2 V / Low 0.8 V, CL = 50 pF
 Input level : High 2.4 V / Low 0.45 V (D0 to D15)

High 0.8xVcc / Lowx0.2Vcc (except for D0 to D15)

# (1) Read cycle



# (2) Write cycle



## 4.4 Serial Channel Timing

### (1) I/O interface mode

### [1] SCLK input mode

 $Vcc = 4.7 \text{ to } 5.3 \text{ V}, Ta = -40 \text{ to } +85^{\circ}\text{C} \text{ (fc} = 8 \text{ to } 24 \text{ MHz)}$ 

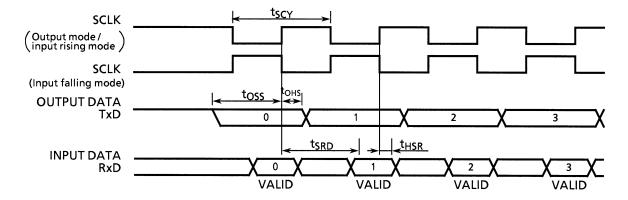
Dorometer	Cumph of	Varia	24 N	llmit		
Parameter	Symbol	Min	Max	Min	Max	Unit
SCLK cycle	t <sub>SCY</sub>	16x		0.667		μS
Output Data → SCLK rise/fall*	toss	$t_{SCY}/2 - 5x - 50$		75		ns
SCLK rise/fall*→Output Data hold	tons	5x – 100		108		ns
SCLK rise/fall* → input data hold	t <sub>HSR</sub>	0		0		ns
SCLK rise/fall*→valid data input	t <sub>SRD</sub>		t <sub>SCY</sub> – 5x – 100		358	ns

<sup>\*)</sup> SCLK rise/fall: In SCLK rising edge mode, SCLK rising edge timing; in SCLK falling edge mode, SCLK falling edge timing

## [2] SCLK output mode

 $Vcc = 4.7 \text{ to } 5.3 \text{ V}, Ta = -40 \text{ to } +85^{\circ}\text{C} \text{ (fc} = 8 \text{ to } 24 \text{ MHz)}$ 

				- (		,
Parameter	C. mala al	Varia	24 N	11		
Parameter	Symbol	Min	Max	Min	MHz Max 341.3	Unit
SCLK cycle (programmable)	t <sub>SCY</sub>	16x	8192x	0.667	341.3	μS
Output Data $\rightarrow$ SCLK rising edge	toss	t <sub>SCY</sub> – 2x – 150		433		ns
SCLK rising edge $\rightarrow$ Output Data hold	t <sub>OHS</sub>	2x – 80		3		ns
SCLK rising edge → Input Data hold	t <sub>HSR</sub>	0		0		ns
SCLK rising edge → valid data input	t <sub>SRD</sub>		t <sub>SCY</sub> – 2x – 150		433	ns



### (2) UART mode (SCLK0 to 1 External Input)

 $Vcc = 4.7 \text{ to } 5.3V, Ta = -40 \text{ to } +85 ^{\circ}C \text{ (fc} = 8 \text{ to } 24 \text{ MHz)}$ 

		,		(			
Parameter	Symphol	Variable			24 MHz		
	Symbol	Min	Max	Min	Max	Unit	
SCLK cycle	t <sub>SCY</sub>	4x + 20		187		ns	
Low-level SCLK pulse width	t <sub>SCYL</sub>	2x + 5		88		ns	
High-level SCLK pulse width	t <sub>SCYH</sub>	2x + 5		88		ns	

### 4.5 AD Conversion Characteristics

 $Vcc = 4.7 \text{ to } 5.3 \text{ V}, Ta = -40 \text{ to } +85 ^{\circ}\text{C} \text{ (fc} = 8 \text{ to } 24 \text{ MHz)}$ 

Parameter		Symbol	Test Conditions	Min	Тур.	Max	Unit
AD analog reference supply voltage (+)		$V_{REFH}$		Vcc – 0.2		Vcc	
AD analog reference supply voltage ( – )		V <sub>REFL</sub>		Vss		Vss + 0.2	
Analog reference voltage		AV <sub>CC</sub>		Vcc – 0.2		Vcc	V
Analog reference voltage		AVSS		Vss		Vss + 0.2	
Analog input voltage		V <sub>AIN</sub>		$V_{REFL}$		V <sub>REFH</sub>	
Analog reference	<vrefon> = 1</vrefon>	I <sub>REF</sub>	Vcc = 4.7 to 5.3 V			3.7	mA
voltage supply current	<vrefon>=0</vrefon>		Vcc = 4.7 to 5.3 V		0.02	5.0	μΑ
Total tolerance (excludes quantization error)		E <sub>T</sub>	Vcc = 4.7 to 5.3 V		± 1	±3	LSB

Note 1:1LSB=(VREFH-VREFL)/2<sup>10</sup>[V]

 $Note\ 2: Power\ supply\ current\ ICC\ from\ the\ VCC\ pin\ includes\ the\ power\ supply\ current\ from\ the\ AVCC\ pin.$ 

## 4.6 Event Counter (External Input Clocks: TI0, TI4, TI8, TI9, TIA, TIB)

 $Vcc = 4.7 \text{ to } 5.3 \text{ V}, Ta = -40 \text{ to } +85 ^{\circ}\text{C} \text{ (fc} = 8 \text{ to } 24 \text{ MHz)}$ 

Parameter	Symbol	Vari	241	Unit			
Parameter	Symbol	Min	Max	Min	Max	Unit	
External input clock cycle	t <sub>VCK</sub>	8x + 100		433		ns	
External low-level input clock pulse width	t <sub>VCKL</sub>	4x + 40		207		ns	
External high-level input clock pulse width	t <sub>VCKH</sub>	4x + 40		207		ns	

## 4.7 Interrupt Operation

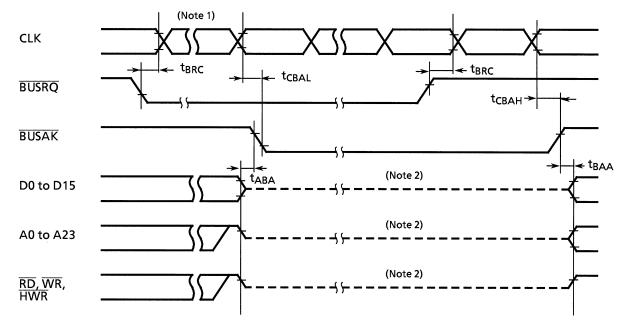
 $Vcc = 4.7 \text{ to } 5.3 \text{ V}, Ta = -40 \text{ to } +85 ^{\circ}\text{C} \text{ (fc} = 8 \text{ to } 24 \text{ MHz)}$ 

Davameter	Cumbal	Vari	24 [	Unit		
Parameter	Symbol	Min	Max	Min	Max	Unit
NMI, INTO to 4 low-level pulse width	t <sub>INTAL</sub>	4x		167		ns
NMI, INTO to 4 high-level pulse width	t <sub>INTAH</sub>	4x		167		ns
INT5 to INT8 low-level pulse width	t <sub>INTBL</sub>	8x + 100		433		ns
INT5 to INT8 high-level pulse width	t <sub>INTBH</sub>	8x + 100		433		ns

### 4.8 Bus Request/Bus Acknowledge Timing

Vcc-	17to	5 2\/	Ta	_ 40 to	+ 85 °C	(fc - 8 tc	24 MHz)
V C.C. =	4.7 LO	1 J.JV.	. 1 a =	- 40 10	+00 61	IIC = O IC	) Z4 IVI [[Z]

Parameter		\	/ariable	24 N	Unit	
		Min	Max	Min	Max	Unit
BUSRQ setup time for CLK	t <sub>BRC</sub>	120		120		ns
CLK→BUSAK fall	t <sub>CBAL</sub>		2.0x + 120		203	ns
CLK→BUSAK rise	t <sub>CBAH</sub>		0.5x + 40		61	ns
Time from output buffer off until BUSAK falling edge	t <sub>ABA</sub>	0	80	0	80	ns
Time from BUSAK rising edge until output buffer on	t <sub>BAA</sub>	0	80	0	80	ns



Note 1: When  $\overline{\mathsf{BUSRQ}}$  goes to low level to request bus release, if the current bus cycle is yet complete due to a wait, the bus is not released until the wait completes.

Note 2: The dotted line indicates only that the output buffer is off, not that the signal is at middle level. Immediately after bus release, the signal level prior to the bus release is held dynamically by the external load capacitance. Therefore, designs should allow for the fact that when using an external resistor or similar to fix the signal level while the bus is released, after bus release a delay occurs before the signal goes to its fixed level (due to the CR time constant). The internal programmable pull-up resistor continues to function in accordance with the internal signal level.

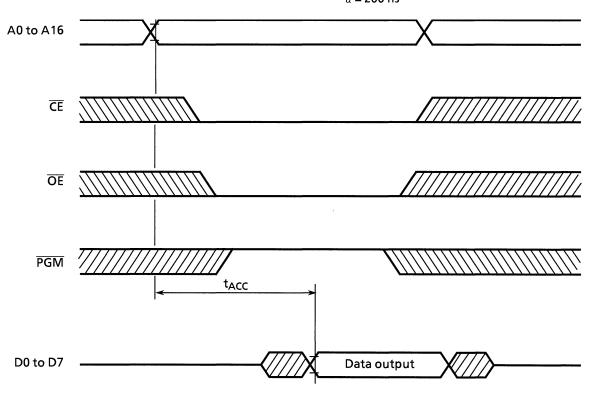
# 4.9 Read Operations in PROM Mode

DC/AC Electrical Specifications

 $Ta = 25 \pm 5$  °C,  $Vcc = 5 V \pm 10 \%$ 

Parameter	Symbol	Test Condition	Min	Max	Unit
V <sub>PP</sub> Read Voltage Input High Voltage (A0 to A16, CE, OE, PGM) Input Low Voltage (A0 to A16, CE, OE, PGM)	V <sub>PP</sub> V <sub>IH</sub>		4.5 2.2 -0.3	5.5 V <sub>CC</sub> + 0.3 0.8	V V V
Address to Output Delay	t <sub>ACC</sub>	C <sub>L</sub> = 50 <sub>P</sub> F	_	2.25TCYC + α	ns

TCYC = 400 ns (10 MHz Clock)  $\alpha$  = 200 ns

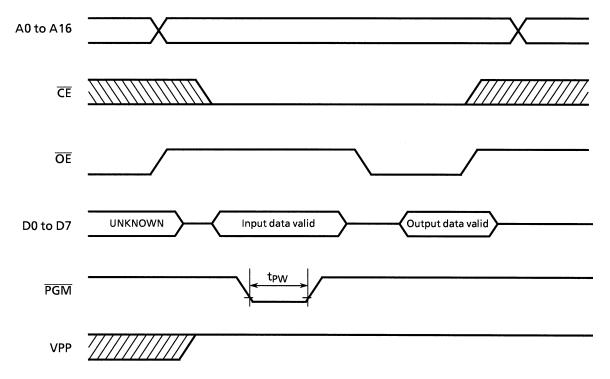


## 4.10 Program Operations in PROM Mode

DC/AC Electrical Specifications

 $Ta = 25 \pm 5$ °C,  $Vcc = 6.25 V \pm 0.25 V$ 

Parameter	Symbol	Test Condition	Min	Тур.	Max	Unit
Programing Supply Voltage	V <sub>PP</sub>		12.50	12.75	13.00	٧
Input High Voltage	V <sub>IH</sub>		2.6		$V_{CC} + 0.3$	V
(D0 to D7, A0 to A16, CE, OE, PGM)						
Input Low Voltage	V <sub>IL</sub>		- 0.3		0.8	V
(D0 to D7, A0 to A16, CE, OE, PGM)						
V <sub>CC</sub> Supply Current	lcc	fc = 10 MHz	_		50	mA
V <sub>PP</sub> Supply Current	Ірр	$V_{PP} = 13.00 \text{ V}$	ı		50	mA
PGM Program Pulse Width	t <sub>PW</sub>	C <sub>L</sub> = 50 <sub>P</sub> F	0.095	0.1	0.105	ms



- Note 1: When turning the  $V_{PP}$  (12.75 V) power supply off and on, ensure that  $V_{CC}$  is on.
- Note 2: Do not plug in or unplug the device when the VPP power (12.75 V) is on. (This can damage the device.)
- Note 3: The V<sub>PP</sub> pin maximum rating is 14 V. When the program is executed, the voltage applied, including overshoot, should not exceed 14 V.