

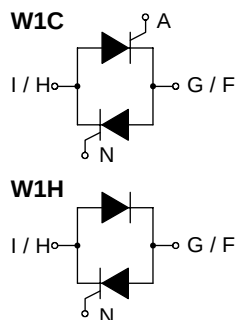
# AC Controller Modules

$$I_{RMS} = 140 \text{ A}$$

$$V_{RRM} = 800-1600 \text{ V}$$

## Preliminary Data

| $V_{RSM}$<br>$V_{DSM}$<br>V | $V_{RRM}$<br>$V_{DRM}$<br>V | Type          |               |
|-----------------------------|-----------------------------|---------------|---------------|
| 800                         | 800                         | MMO 140-08io7 | MLO 140-08io7 |
| 1200                        | 1200                        | MMO 140-12io7 | MLO 140-12io7 |
| 1600                        | 1600                        | MMO 140-16io7 | MLO 140-16io7 |



| Symbol         | Conditions                                                                                                                                                                       | Maximum Ratings                    |                       |
|----------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------|-----------------------|
| $I_{RMS}$      | $T_C = 85^\circ\text{C}$ , 50 - 400 Hz, (per single controller)                                                                                                                  | 130                                | A                     |
| $I_{TRMS}$     |                                                                                                                                                                                  | 90                                 | A                     |
| $I_{TAVM}$     | $T_C = 85^\circ\text{C}$ ; 180° sine, per Thyristor                                                                                                                              | 58                                 | A                     |
| $I_{TSM}$      | $T_{VJ} = 45^\circ\text{C}$<br>$V_R = 0$                                                                                                                                         | $t = 10 \text{ ms}$ (50 Hz), sine  | 1150 A                |
|                |                                                                                                                                                                                  | $t = 8.3 \text{ ms}$ (60 Hz), sine | 1230 A                |
|                | $T_{VJ} = 125^\circ\text{C}$<br>$V_R = 0$                                                                                                                                        | $t = 10 \text{ ms}$ (50 Hz), sine  | 1000 A                |
|                |                                                                                                                                                                                  | $t = 8.3 \text{ ms}$ (60 Hz), sine | 1070 A                |
| $I^2t$         | $T_{VJ} = 45^\circ\text{C}$<br>$V_R = 0$                                                                                                                                         | $t = 10 \text{ ms}$ (50 Hz), sine  | 6600 A <sup>2</sup> s |
|                |                                                                                                                                                                                  | $t = 8.3 \text{ ms}$ (60 Hz), sine | 6280 A <sup>2</sup> s |
|                | $T_{VJ} = 125^\circ\text{C}$<br>$V_R = 0$                                                                                                                                        | $t = 10 \text{ ms}$ (50 Hz), sine  | 5000 A <sup>2</sup> s |
|                |                                                                                                                                                                                  | $t = 8.3 \text{ ms}$ (60 Hz), sine | 4750 A <sup>2</sup> s |
| $(di/dt)_{cr}$ | $T_{VJ} = 125^\circ\text{C}$<br>$f = 50 \text{ Hz}$ , $t_p = 200 \mu\text{s}$<br>$V_D = \frac{2}{3} V_{DRM}$<br>$I_G = 0.45 \text{ A}$<br>$di_G/dt = 0.45 \text{ A}/\mu\text{s}$ | repetitive, $I_T = 60 \text{ A}$   | 150 A/ $\mu\text{s}$  |
|                |                                                                                                                                                                                  | non repetitive, $I_T = I_{TAVM}$   | 500 A/ $\mu\text{s}$  |
| $(dv/dt)_{cr}$ | $T_{VJ} = 125^\circ\text{C}$ ; $V_{DR} = \frac{2}{3} V_{DRM}$<br>$R_{GK} = \infty$ ; method 1 (linear voltage rise)                                                              |                                    | 1000 V/ $\mu\text{s}$ |
| $P_{GM}$       | $T_{VJ} = 125^\circ\text{C}$<br>$I_T = I_{TAVM}$                                                                                                                                 | $t_p = 30 \mu\text{s}$             | 10 W                  |
|                |                                                                                                                                                                                  | $t_p = 300 \mu\text{s}$            | 5 W                   |
| $P_{GAVM}$     |                                                                                                                                                                                  |                                    | 0.5 W                 |
| $V_{RGM}$      |                                                                                                                                                                                  |                                    | 10 V                  |
| $T_{VJ}$       |                                                                                                                                                                                  | -40...+150                         | °C                    |
| $T_{VJM}$      |                                                                                                                                                                                  | 150                                | °C                    |
| $T_{stg}$      |                                                                                                                                                                                  | -40...+125                         | °C                    |
| $V_{ISOL}$     | 50/60 Hz, RMS<br>$I_{ISOL} \leq 1 \text{ mA}$                                                                                                                                    | $t = 1 \text{ min}$                | 2500 V~               |
|                |                                                                                                                                                                                  | $t = 1 \text{ s}$                  | 3000 V~               |
| $M_d$          | Mounting torque (M4)                                                                                                                                                             | 1.5...2.0/14...18                  | Nm/lb.in.             |
| Weight         | typ.                                                                                                                                                                             | 18                                 | g                     |

## Features

- Thyristor controller for AC (circuit W1C acc. to IEC) for mains frequency
- Isolation voltage 3000 V~
- Planar glass passivated chips
- Low forward voltage drop
- Lead suitable for PC board solering

## Applications

- Switching and control of single and three phase AC circuits
- Light and temperature control
- Softstart AC motor controller
- Solid state switches

## Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling
- High power density
- Small and light weight

Data according to IEC 60747 and to a single thyristor/diode unless otherwise stated.  
 IXYS reserves the right to change limits, test conditions and dimensions.

| Symbol     | Conditions                                                                                                  | Characteristic Values  |
|------------|-------------------------------------------------------------------------------------------------------------|------------------------|
| $I_D, I_R$ | $T_{VJ} = 125^\circ\text{C}; V_R = V_{RRM}; V_D = V_{DRM}$                                                  | $\leq 5$ mA            |
| $V_T$      | $I_T = 200$ A; $T_{VJ} = 25^\circ\text{C}$                                                                  | $\leq 1.75$ V          |
| $V_{T0}$   | For power-loss calculations only                                                                            | 0.85 V                 |
| $r_T$      |                                                                                                             | 5.2 m $\Omega$         |
| $V_{GT}$   | $V_D = 6$ V $T_{VJ} = 25^\circ\text{C}$                                                                     | $\leq 1.5$ V           |
|            | $T_{VJ} = -40^\circ\text{C}$                                                                                | $\leq 1.6$ V           |
| $I_{GT}$   | $V_D = 6$ V $T_{VJ} = 25^\circ\text{C}$                                                                     | $\leq 100$ mA          |
|            | $T_{VJ} = -40^\circ\text{C}$                                                                                | $\leq 200$ mA          |
| $V_{GD}$   | $T_{VJ} = 125^\circ\text{C}; V_D = \frac{2}{3} V_{DRM}$                                                     | $\leq 0.2$ V           |
| $I_{GD}$   |                                                                                                             | $\leq 10$ mA           |
| $I_L$      | $T_{VJ} = 25^\circ\text{C}; t_p = 10$ $\mu\text{s}$<br>$I_G = 0.45$ A; $di_G/dt = 0.45$ A/ $\mu\text{s}$    | $\leq 450$ mA          |
| $I_H$      | $T_{VJ} = 25^\circ\text{C}; V_D = 6$ V; $R_{GK} = \infty$                                                   | $\leq 200$ mA          |
| $t_{gd}$   | $T_{VJ} = 25^\circ\text{C}; V_D = \frac{1}{2} V_{DRM}$<br>$I_G = 0.45$ A; $di_G/dt = 0.45$ A/ $\mu\text{s}$ | $\leq 2$ $\mu\text{s}$ |
| $R_{thJC}$ | per thyristor; DC                                                                                           | 0.7 K/W                |
|            | per module                                                                                                  | 0.35 K/W               |
| $R_{thCH}$ | per thyristor; sine 180° el                                                                                 | typ. 0.12 K/W          |
|            | per module                                                                                                  | typ. 0.06 K/W          |
| $d_s$      | Creeping distance on surface                                                                                | 11.2 mm                |
| $d_A$      | Creepage distance in air                                                                                    | 17.0 mm                |
| $a$        | Max. allowable acceleration                                                                                 | 50 m/s <sup>2</sup>    |

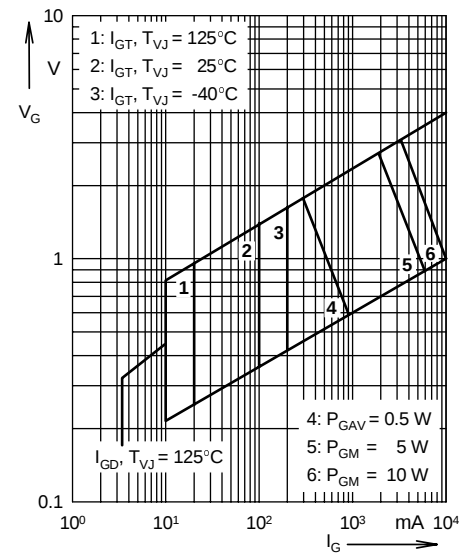


Fig. 1 Gate trigger characteristics

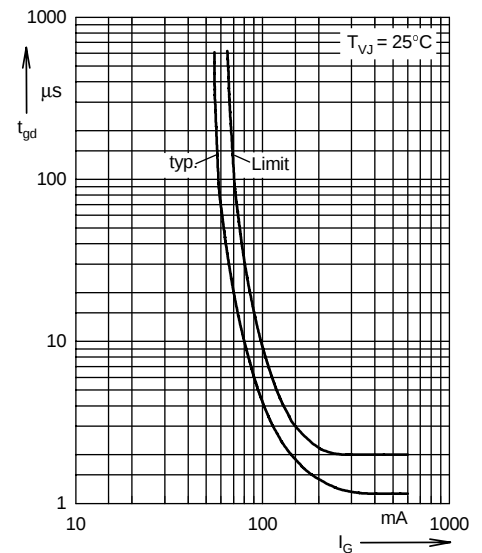


Fig. 2 Gate trigger delay time

## Dimensions in mm (1 mm = 0.0394")

