

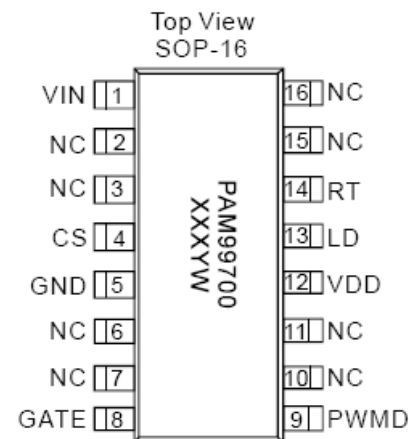
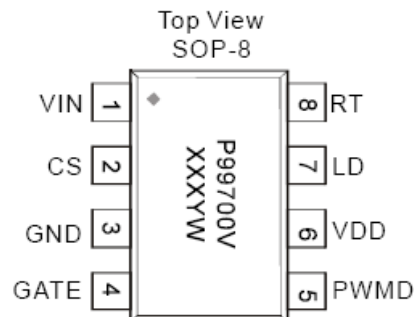
**UNIVERSAL HIGH BRIGHTNESS LED DRIVER**
**Description**

The PAM99700 is an open loop current mode control LED driver IC. The PAM99700 can be programmed to operate in either a constant frequency or constant off-time mode. It includes a 12 - 500V regulator which allows it to work from a wide range of input voltages without the need for an external low voltage supply. The PAM99700 includes a PWM dimming input that can accept an external control signal with a duty ratio of 0 - 100% and a frequency of up to a few kilohertz. It also includes a 0 - 250mV linear dimming input which can be used for linear dimming of the LED current.

The PAM99700 is ideally suited for buck LED drivers. Since the PAM99700 operates in open loop current mode control, the controller achieves good output current regulation without the need for any loop compensation. PWM dimming response is limited only by the rate of rise and fall of the inductor current, enabling very fast rise and fall times. The PAM99700 requires only three external components (apart from the power stage) to produce a controlled LED current making it an ideal solution for low cost LED drivers.

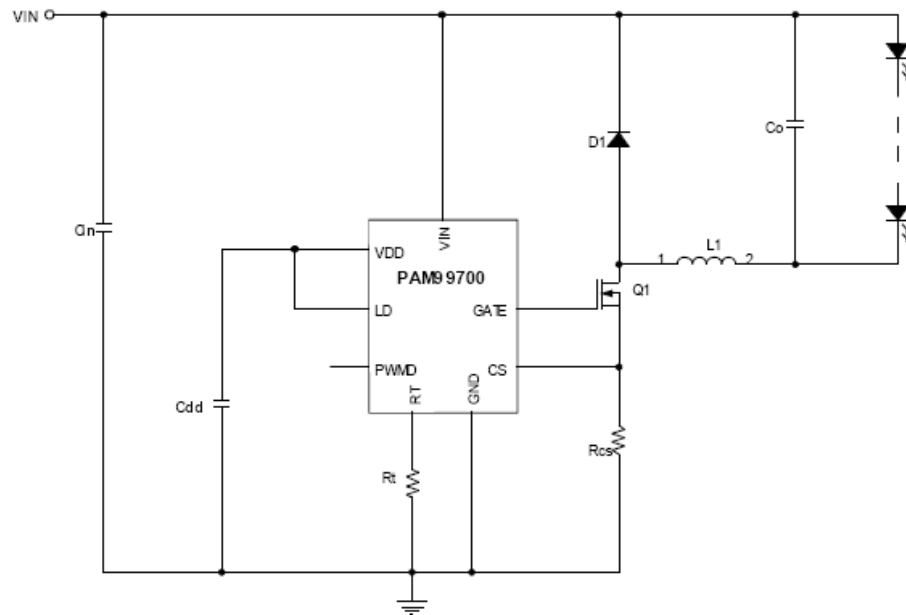
**Features**

- Switch Mode Controller for Single Switch LED Drivers
- Open Loop Peak Current Controller
- Constant Frequency or Constant Off-Time Operation
- Linear and PWM Dimming Capability
- Requires Few External Components for Operation
- Application From a Few mA to More than 1A Output

**Pin Assignments**

**Applications**

- DC/DC or AC/DC LED Driver Applications
- RGB Backlighting LED Driver
- Back Lighting of Flat Panel Displays
- General Purpose Constant Current Source
- Signage and Decorative LED Lighting

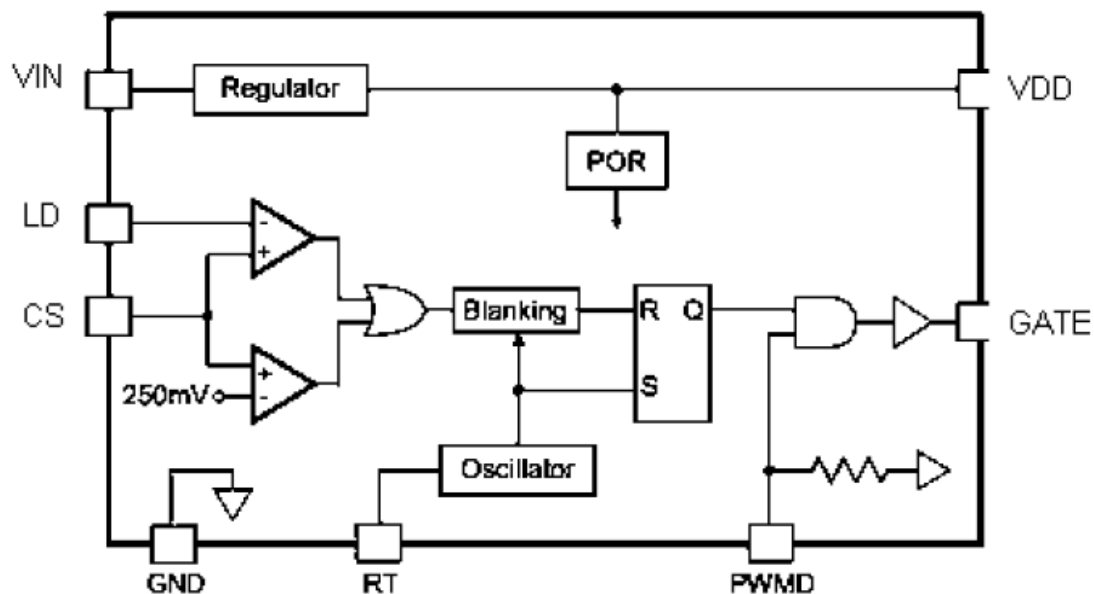
## Typical Applications Circuit



## Pin Descriptions

Pin Name	Pin Number		Function
	SOP-8	SOP-16	
VIN	1	1	This pin is the input of a 12V-500V regulator.
CS	2	4	This pin is the current sense pin used to sense the FET current by means of an external sense resistor. When this pin exceeds the lower of either the internal 250mV or the voltage at the LD pin, the gate output goes low.
GND	3	5	Ground return for all internal circuitry. This pin must be electrically connected to the ground of the power train.
GATE	4	8	This pin is the output gate driver for an external N-Channel power MOSFET.
PWMD	5	9	This is the PWM dimming input of the IC. When this pin is pulled to GND, the gate driver is turned off. When the pin is pulled high, the gate driver operates normally.
VDD	6	12	This is the power supply pin for all internal circuits. It must be bypassed with a low ESR capacitor to GND (~ 10μF).
LD	7	13	This pin is the linear dimming input and sets the current sense threshold as long as the voltage at the pin is less than 250mV (typ).
RT	8	14	This pin sets the oscillator frequency. When a resistor is connected between RT and GND, the PAM99700 operates in constant frequency mode. When the resistor is connected between RT and GATE, the IC operates in constant off-time mode.
NC	—	2, 3, 6, 7, 10, 11, 15, 16	Not connected.

## Functional Block Diagram



## Absolute Maximum Ratings (@T<sub>A</sub> = +25°C, unless otherwise specified.)

These are stress ratings only and functional operation is not implied. Exposure to absolute maximum ratings for prolonged time periods may affect device reliability. All voltages are with respect to ground.

Parameter	Rating	Unit
Maximum Junction Temperature	150	°C
Storage Temperature	-65 to +150	
Soldering Temperature	300, 5sec	

## Recommended Operating Conditions (@T<sub>A</sub> = +25°C, unless otherwise specified.)

Parameter	Rating	Unit
Supply Voltage	12 to 500	V
Ambient Temperature Range	-40 to +85	°C
Junction Temperature Range	-40 to +125	°C

## Thermal Information

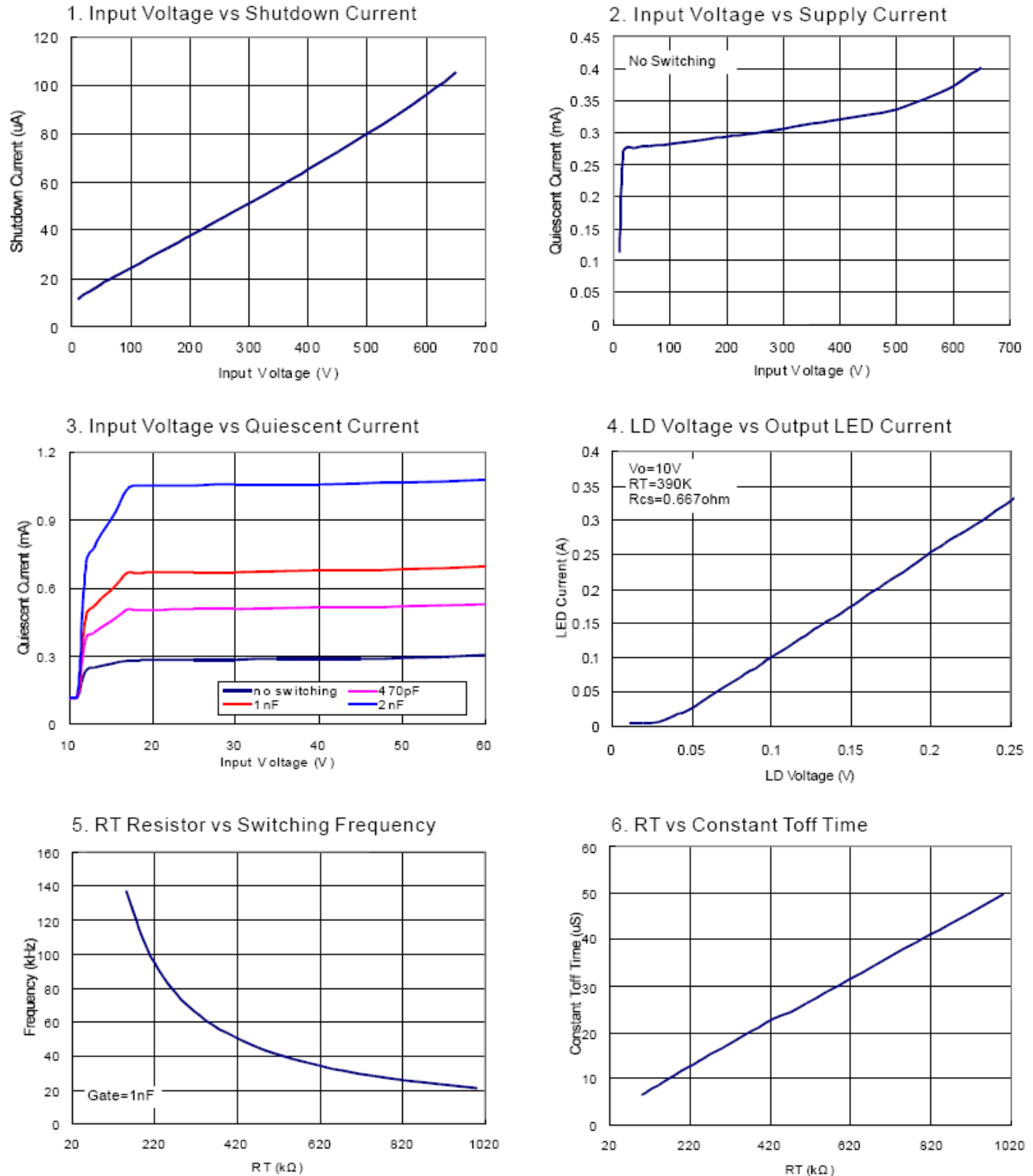
Parameter	Package	Symbol	Max	Unit
Thermal Resistance (Junction to Ambient)	SOP-8	$\theta_{JA}$	115	°C/W
	SOP-16		110	

## Electrical Characteristics (@T<sub>A</sub> = +25°C, unless otherwise specified.)

Parameter	Symbol	Test Conditions	Min	Typ	Max	Units
Input Voltage Range	V <sub>INDC</sub>	DC Input Voltage	12		500	V
Shutdown Mode Supply Current	I <sub>NSD</sub>	Pin PWM to GND		0.1		mA
Internally Regulated Voltage	V <sub>DD</sub>	V <sub>IN</sub> > 20V	6	10		V
Current Sense Pul-In Threshold Voltage	V <sub>CS,TH</sub>			250		mV
Current Sense Blanking Interval	T <sub>BLANK</sub>			250		Ns
Gate Sourcing Current	I <sub>SOURCE</sub>	V <sub>GATE</sub> = 0V	0.2			A
Gate Sinking Current	I <sub>SINK</sub>	V <sub>GATE</sub> = V <sub>DD</sub>	0.2			A
Gate Output Rise Time	t <sub>RISE</sub>	C <sub>GATE</sub> = 1nF		30	50	ns
Gate Output Fall Time	t <sub>FALL</sub>	C <sub>GATE</sub> = 1nF		30	50	ns
Oscillator Frequency	f <sub>OSC</sub>	R <sub>T</sub> = 510kΩ	37	41	49	kHz
		R <sub>T</sub> = 226kΩ	74	92	110	
EN Threshold High	V <sub>EH</sub>	V <sub>IN</sub> = 12V to 500V	2.4			V
EN Threshold Low	V <sub>EL</sub>	V <sub>IN</sub> = 12V to 500V			1.0	V
Over Temperature Protection	OTP			160		°C
OTP Hysteresis	OTH			50		°C

## Typical Performance Characteristics

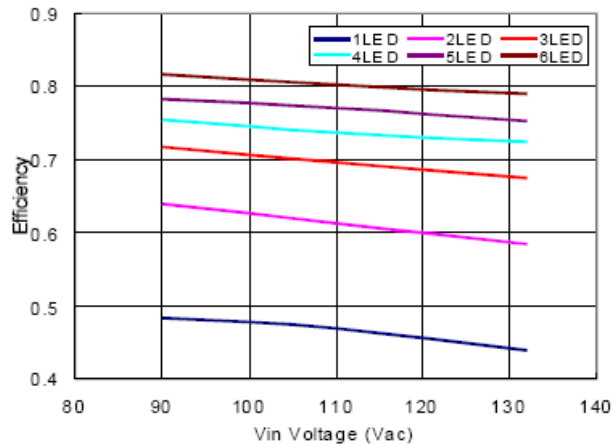
(@ $T_A = +25^\circ\text{C}$ ,  $V_{IN} = 60\text{V}$ ,  $1\text{WLED}$ ,  $R_T = 510\text{K}\Omega$ ,  $L = 5.2\text{mH}$ , unless otherwise specified.)



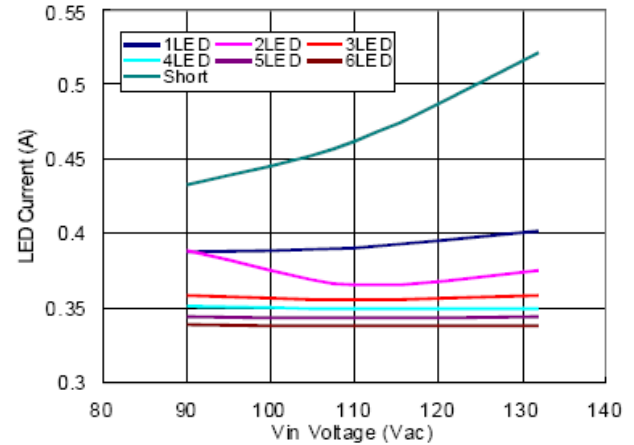
## Typical Performance Characteristics (cont.)

(@ $T_A = +25^\circ\text{C}$ ,  $V_{IN} = 110\text{VAC}$ , 1WLED,  $R_T = 510\text{K}\Omega$ ,  $L = 5.2\text{mH}$ ,  $R_{CS} = 0.68\Omega$ , unless otherwise specified.)

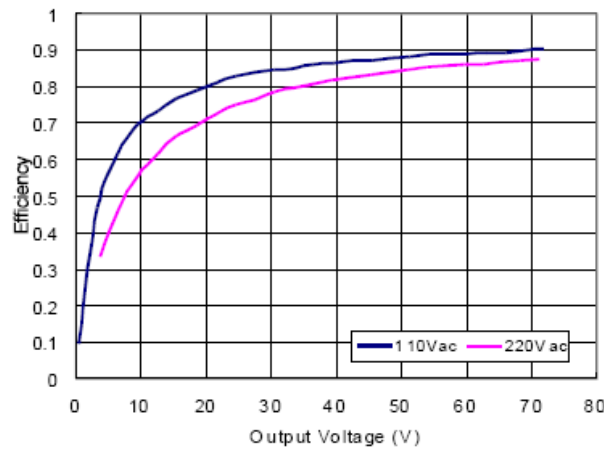
7. Input Voltage vs Efficiency



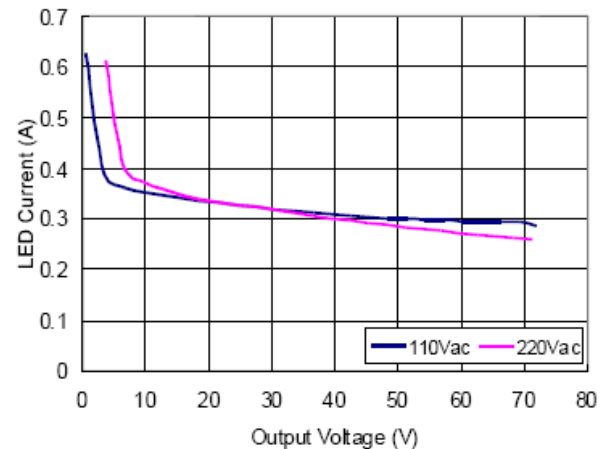
8. Input Voltage vs LED Current



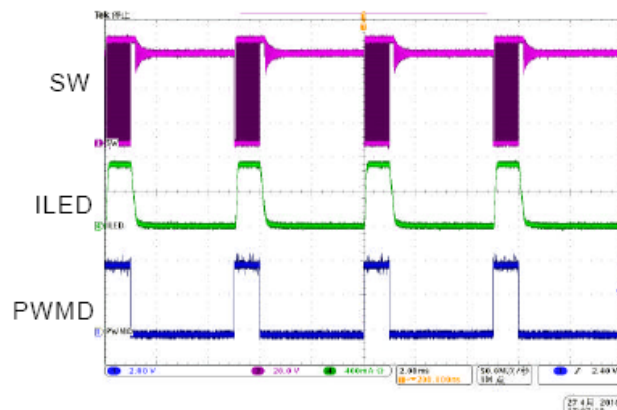
9. Output Voltage vs Efficiency



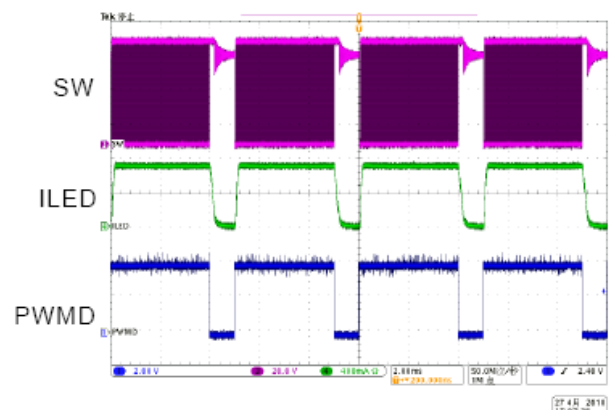
10. Output Voltage vs LED Current



11. PWM Dimming use PWM\_D pin



12. PWM Dimming use PWM\_D pin



## Application Information

The PAM99700 is optimized to drive buck LED drivers using open-loop peak current mode control. This method of control enables fairly accurate LED current control without the need for high side current sensing or the design of any closed loop controllers. The IC uses very few external components and enables both Linear and PWM dimming of the LED current.

A resistor connected to the RT pin programs the frequency of operation (or the off-time). The oscillator produces pulses at regular intervals. These pulses set the SR flip-flop in the PAM99700 which causes the gate driver to turn on. The same pulses also start the blanking timer which inhibits the reset input of the SR flip-flop and prevent false turn-offs due to the turn-on spike. When the FET turns on, the current through the inductor starts ramping up. This current flows through the external sense resistor  $R_{CS}$  and produces a ramp voltage at the CS pin. The comparators are constantly comparing the CS pin voltage to both the voltage at the LD pin and the internal 250mV. Once the blanking timer is complete, the output of these comparators is allowed to reset the flip-flop. When the output of either one of the two comparators goes high, the flip-flop is reset and the gate output goes low. The gate goes low until the SR flip-flop is set by the oscillator. Assuming a 30% ripple in the inductor, the current sense resistor  $R_{CS}$  can be set using:

$$R_{CS} = 0.25V \text{ (or } V_{LD}) / 1.15 \cdot I_{LED}(A)$$

Constant frequency peak current mode control has an inherent disadvantage - at duty cycles greater than 0.5, the control scheme goes into subharmonic oscillations. To prevent this, an artificial slope is typically added to the current sense waveform. This slope compensation scheme will affect the accuracy of the LED current in the present form. However, a constant off-time peak current control scheme does not have this problem and can easily operate at duty cycles greater than 0.5 and also gives inherent input voltage rejection making the LED current almost insensitive to input voltage variations. But, it leads to variable frequency operation and the frequency range depends greatly on the input and output voltage variation. PAM99700 makes it easy to switch between the two modes of operation by changing one connection (see oscillator section).

### Input Voltage Regulator

The PAM99700 can be powered directly from its VIN pin and can work from 12 - 500V DC at its VIN pin. When a voltage is applied at the VIN pin, the PAM99700 maintains a constant 12V at the VDD pin. This voltage is used to power the IC and any external resistor dividers needed to control the IC. The VDD pin must be bypassed by a low ESR capacitor to provide a low impedance path for the high frequency current of the output gate driver.

The PAM99700 can also be operated by supplying a voltage at the VDD pin greater than the internally regulated voltage. This will turn off the internal linear regulator of the IC and the PAM99700 will operate directly off the voltage supplied at the VDD pin. Please note that this external voltage at the VDD pin should not exceed 15V.

Although the VIN pin of the PAM99700 is rated up to 500V, the actual maximum voltage that can be applied is limited by the power dissipation in the IC. For example, if an 8-pin (junction to ambient thermal resistance  $R_{\theta JA} = 115^{\circ}C/W$ ) PAM99700 draws about  $I_{IN} = 2mA$  from the VIN pin, and has a maximum allowable temperature rise of the junction temperature limited to about  $\Delta T = 100^{\circ}C$ , the maximum voltage at the VIN pin would be:

$$\begin{aligned} V_{IN(MAX)} &= \frac{\Delta T}{R_{\theta JA}} \cdot \frac{1}{I_{IN}} \\ &= \frac{100^{\circ}C}{115^{\circ}C/W} \cdot \frac{1}{2mA} \\ &= 435V \end{aligned}$$

In these cases, to operate the PAM99700 from higher input voltages, a Zener diode can be added in series with the VIN pin to divert some of the power loss from the PAM99700 to the Zener diode. In the above example, using a 100V zener diode will allow the circuit to easily work up to 500V.

The input current drawn from the VIN pin is a sum of the 1.0mA current drawn by the internal circuit and the current drawn by the gate driver (which in turn depends on the switching frequency and the gate charge of the external FET).

$$I_{IN} \approx 350\mu A + Q_G \cdot f_S$$

In the above equation,  $f_S$  is the switching frequency and  $Q_G$  is the gate charge of the external FET (which can be obtained from the datasheet of the FET).

## Application Information (cont.)

### Current Sense

The current sense input of the PAM99700 goes to the non-inverting inputs of two comparators. The inverting terminal of one comparator is tied to an internal 250mV reference whereas the inverting terminal of the other comparator is connected to the LD pin. The outputs of both these comparators are fed into an OR gate and the output of the OR gate is fed into the reset pin of the flip-flop. Thus, the comparator which has the lowest voltage at the inverting terminal determines when the GATE output is turned off.

The outputs of the comparators also include a 150-280ns blanking time which prevents spurious turn-offs of the external FET due to the turn-on spike normally present in peak current mode control. In rare cases, this internal blanking might not be enough to filter out the turn-on spike. In these cases, an external RC filter needs to be added between the external sense resistor ( $R_{CS}$ ) and the CS pin.

Please note that the comparators are fast (with a typical 80ns response time). Hence these comparators are more susceptible to be triggered by noise than the comparators of the PAM99700. A proper layout minimizing external inductances will prevent false triggering of these comparators.

### Oscillator

The oscillator in the PAM99700 is controlled by a single resistor connected at the RT pin. The equation governing the oscillator frequency is given by:

$$F = \frac{21380}{RT(k\Omega) + 5.5} (\text{kHz})$$

If the resistor is connected between RT and GND, PAM99700 operates in a constant frequency mode and the above equation determines the time-period. If the resistor is connected between RT and GATE, the PAM99700 operates in a constant off-time mode and the below equation determines the off-time.

$$T_{OFF} = \frac{RT(k\Omega) + 44.1}{21.1} (\mu\text{s})$$

### GATE Output

The gate output of the PAM99700 is used to drive an external FET. It is recommended that the gate charge of the external FET be less than 25nC for switching frequencies 100kHz and less than 15nC for switching frequencies >100kHz.

### Linear Dimming

The Linear Dimming pin is used to control the LED current. There are two cases when it may be necessary to use the Linear Dimming pin. In some cases, it may not be possible to find the exact  $R_{CS}$  value required to obtain the LED current when the internal 250mV is used. In these cases, an external voltage divider from the  $V_{DD}$  pin can be connected to the LD pin to obtain a voltage (less than 250mV) corresponding to the desired voltage across  $R_{CS}$ .

Linear dimming may be desired to adjust the current level to reduce the intensity of the LEDs. In these cases, an external 0-250mV voltage can be connected to the LD pin to adjust the LED current during operation.

To use the internal 250mV, the LD pin can be connected to  $V_{DD}$ .

Note: Although the LD pin can be pulled to GND, the output current will not go to zero. This is due to the presence of a minimum on-time (which is equal to the sum of the blanking time and the delay to output time) which is about 450ns. This will cause the FET to be on for a minimum of 450ns and thus the LED current when LD = GND will not be zero. This current is also dependent on the input voltage, inductance value, forward voltage of the LEDs and circuit parasitics. To get zero LED current, the PWM pin has to be used.

### PWM Dimming

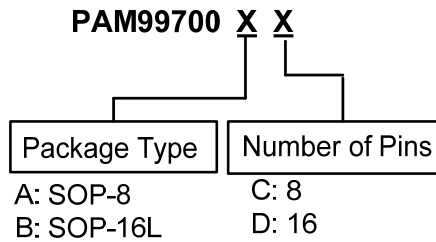
PWM Dimming can be achieved by driving the PWM pin with a low frequency square wave signal. When the PWM signal is zero, the gate driver is turned off and when the PWM signal is high, the gate driver is enabled. Since the PWM signal does not turn off the other parts of the IC, the response of the PAM99700 to the PWM signal is almost instantaneous. The rate of rise and fall of the LED current is thus determined solely by the rise and fall times of the inductor current. To disable PWM dimming and enable the PAM99700 permanently, connect the PWM pin to  $V_{DD}$ .

### Thermal Protection

When the die temperature exceeds +160°C, a reset occurs and the reset remains until the temperature decreases to +110°C, at which time the circuit can be restarted. When the die temperature exceeds +160°C, a reset occurs and the reset remains until the temperature decreases to +110°C, at which time the circuit can be restarted.

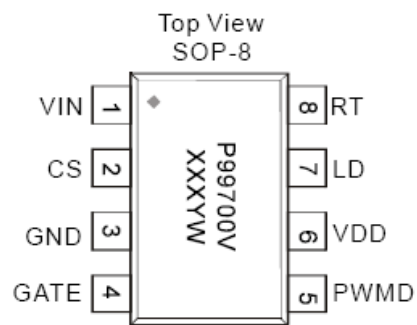


## Ordering Information

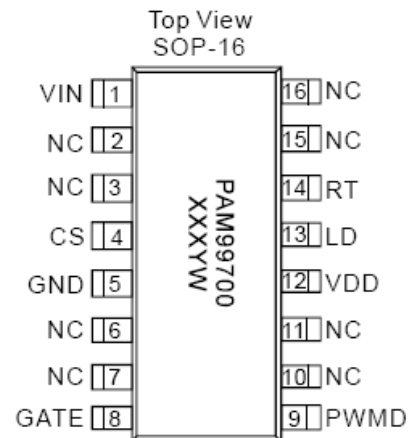


Part Number	Package Type	Standard Package
PAM99700AC	SOP-8L	2500 Units/Tape&Reel
PAM99100BD	SOP-16L	2500 Units/Tape&Reel

## Marking Information

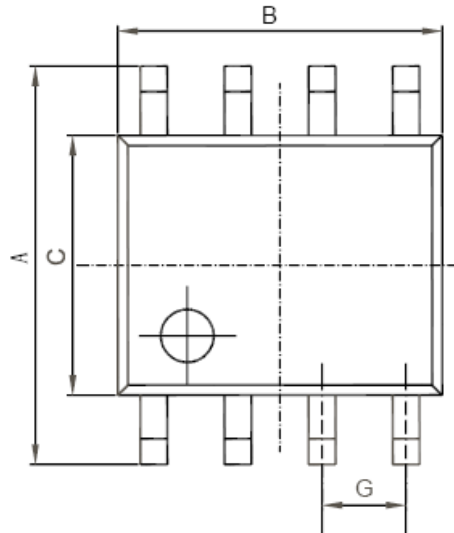


V: Output Voltage  
Y: Year  
W: Week  
X: Internal Code

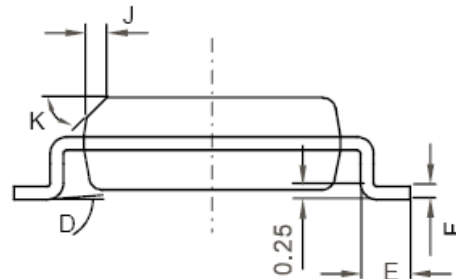
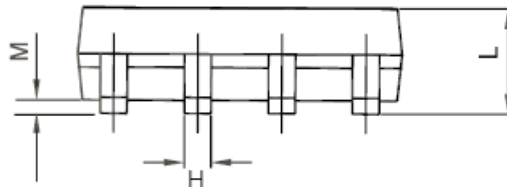


## Package Outline Dimensions (All dimensions in mm.)

SOP-8

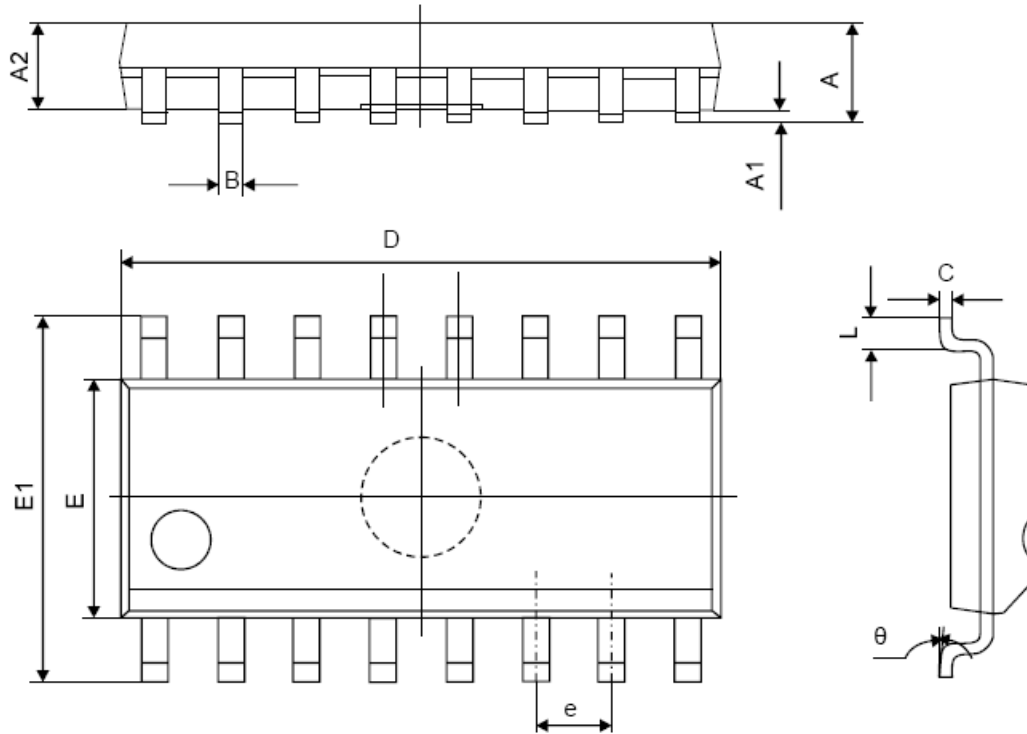


REF	DIMENSIONS	
	Millimeters	
	Min	Max
A	5.80	6.20
B	4.80	5.00
C	3.80	4.00
D	0°	8°
E	0.40	0.90
F	0.19	0.25
M	0.10	0.25
H	0.35	0.49
L	1.35	1.75
J	0.375 REF	
K	45°	
G	1.27 TYP	



**Package Outline Dimensions** (cont.) (All dimensions in mm.)

SOP-16



Symbol	Dimensions Millimeters	
	Min	Max
A	1.350	1.750
A1	0.100	0.250
A2	1.350	1.550
B	0.330	0.510
C	0.190	0.250
D	9.800	10.000
E	3.800	4.000
E1	5.800	6.300
e	1.270(TYP)	
L	0.400	1.270
θ	0°	8°

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