

Dual, 550kHz, 2-Phase Synchronous Regulator

FEATURES

- Dual, 180° Phased Controllers Reduce Required Input Capacitance and Power Supply Induced Noise
- OPTI-LOOP® Compensation Minimizes C_{OUT}
- $\pm 1.5\%$ Output Voltage Accuracy
- Power Good Output Voltage Indicator
- Phase-Lockable Fixed Frequency 250kHz to 550kHz
- Over Current Latchoff Disabled
- Wide V_{IN} Range: 4.5V to 28V (35V for LTC3728LI-1) Operation
- Very Low Dropout Operation: 99% Duty Cycle
- Adjustable Soft-Start Current Ramping
- Foldback Output Current Limiting
- Output Overvoltage Protection
- Low Shutdown I_Q : 20 μ A
- 5V and 3.3V Standby Regulators
- 3 Selectable Operating Modes: Constant Frequency, Burst Mode® Operation and PWM
- 5mm $\times$ 5mm QFN and 28-Lead Narrow SSOP Packages

APPLICATIONS

- Notebook and Palmtop Computers
- Telecom Systems
- Portable Instruments
- Battery-Operated Digital Devices
- DC Power Distribution Systems

DESCRIPTION

The LTC®3728L-1 is a dual high performance step-down switching regulator controller that drives all N-channel synchronous power MOSFET stages. A constant frequency current mode architecture allows phase-lockable frequency of up to 550kHz. Power loss and noise due to the ESR of the input capacitors are minimized by operating the two controller output stages out of phase. The LTC3728L-1 is identical to the LTC3728L except that the LTC3728L-1 lacks the over current latchoff feature.

OPTI-LOOP compensation allows the transient response to be optimized over a wide range of output capacitance and ESR values. The precision 0.8V reference and power good output indicator are compatible with future microprocessor generations, and a wide 4.5V to 28V (30V maximum/35V for LTC3728LI-1) input supply range encompasses all battery chemistries.

A RUN/SS pin for each controller provides soft-start. Current foldback limits MOSFET dissipation during short-circuit conditions. The FCB mode pin can select among Burst Mode operation, constant frequency mode and continuous inductor current mode or regulate a secondary winding. The LTC3728L-1 includes a power good output pin that indicates when both outputs are within 7.5% of their designed set point.

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TYPICAL APPLICATION

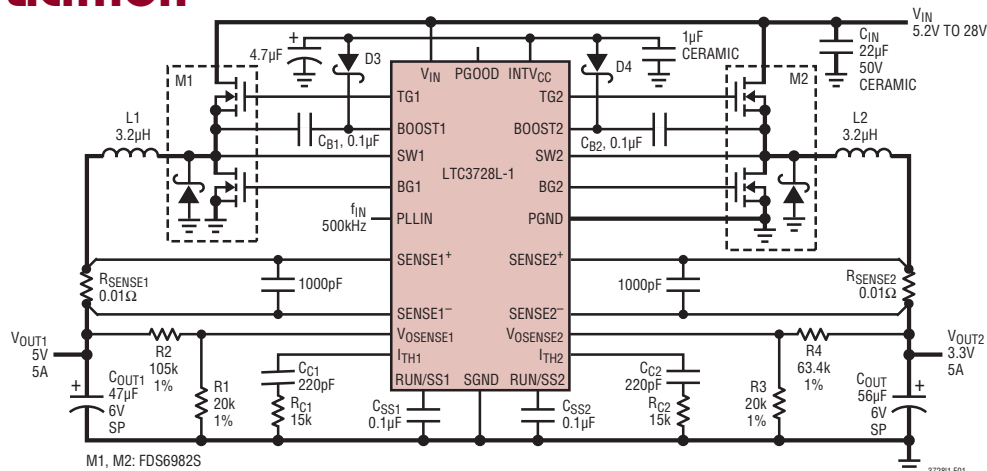


Figure 1. High Efficiency Dual 5V/3.3V Step-Down Converter

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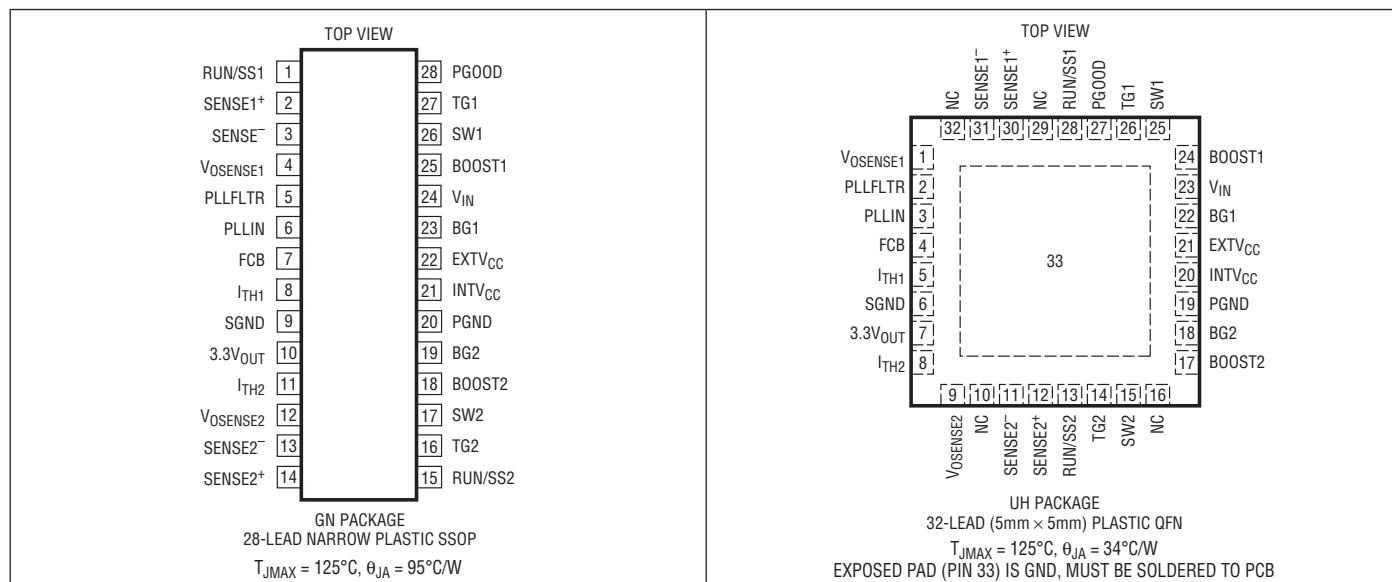
LTC3728L-1

ABSOLUTE MAXIMUM RATINGS (Note 1)

Input Supply Voltage (V_{IN}) 30V to $-0.3V$
 Input Supply Voltage (V_{IN}) LTC3728LI-1 35V to $-0.3V$
 Top Side Driver Voltages
 (BOOST1, BOOST2) 36V to $-0.3V$
 (BOOST1, BOOST2) LTC3728LI-1 38V to $-0.3V$
 Switch Voltage (SW1, SW2) 30V to $-5V$
 Switch Voltage (SW1, SW2) LTC3728LI-1 ... 35V to $-0.3V$
 $INTV_{CC}$, $EXTV_{CC}$, RUN/SS1, RUN/SS2, (BOOST1-SW1),
 (BOOST2-SW2), PGOOD 7V to $-0.3V$
 $INTV_{CC}$, $EXTV_{CC}$ LTC3728LI-1 8V to $-0.3V$
 $SENSE1^+$, $SENSE2^+$, $SENSE1^-$,
 $SENSE2^-$ Voltages (1.1) $INTV_{CC}$ to $-0.3V$

PLLIN, PLLFLTR, FCB, Voltage $INTV_{CC}$ to $-0.3V$
 I_{TH1} , I_{TH2} , $VOSENSE1$, $VOSENSE2$ Voltages 2.7V to $-0.3V$
 Peak Output Current $<10\mu s$ (TG1, TG2, BG1, BG2) 3A
 $INTV_{CC}$ Peak Output Current 40mA
 Operating Temperature Range (Note 7) $-40^{\circ}C$ to $85^{\circ}C$
 Junction Temperature (Note 2) $125^{\circ}C$
 Storage Temperature Range $-65^{\circ}C$ to $125^{\circ}C$
 Reflow Peak Body Temperature (UH Package) $260^{\circ}C$
 Lead Temperature (Soldering, 10 sec)
 GN Package $300^{\circ}C$

PIN CONFIGURATION



ORDER INFORMATION

LEAD FREE FINISH	TAPE AND REEL	PART MARKING	PACKAGE DESCRIPTION	TEMPERATURE RANGE
LTC3728LEGN-1#PBF	LTC3728LEGN-1#TRPBF	LTC3728LEGN-1	28-Lead Narrow Plastic SSOP	$-40^{\circ}C$ to $85^{\circ}C$
LTC3728LIGN-1#PBF	LTC3728LIGN-1#TRPBF	LTC3728LIGN-1	28-Lead Narrow Plastic SSOP	$-40^{\circ}C$ to $85^{\circ}C$
LTC3728LEUH-1#PBF	LTC3728LEUH-1#TRPBF	728LE1	32-Lead (5mm $\times$ 5mm) Plastic DFN	$-40^{\circ}C$ to $85^{\circ}C$
LTC3728LIUH-1#PBF	LTC3728LIUH-1#TRPBF	3728L1	32-Lead (5mm $\times$ 5mm) Plastic DFN	$-40^{\circ}C$ to $85^{\circ}C$
LEAD BASED FINISH	TAPE AND REEL	PART MARKING	PACKAGE DESCRIPTION	TEMPERATURE RANGE
LTC3728LEGN-1	LTC3728LEGN-1#TR	LTC3728LEGN-1	28-Lead Narrow Plastic SSOP	$-40^{\circ}C$ to $85^{\circ}C$
LTC3728LIGN-1	LTC3728LIGN-1#TR	LTC3728LIGN-1	28-Lead Narrow Plastic SSOP	$-40^{\circ}C$ to $85^{\circ}C$
LTC3728LEUH-1	LTC3728LEUH-1#TR	728LE1	32-Lead (5mm $\times$ 5mm) Plastic DFN	$-40^{\circ}C$ to $85^{\circ}C$
LTC3728LIUH-1	LTC3728LIUH-1#TR	3728L1	32-Lead (5mm $\times$ 5mm) Plastic DFN	$-40^{\circ}C$ to $85^{\circ}C$

Consult LTC Marketing for parts specified with wider operating temperature ranges.

For more information on lead free part marking, go to: <http://www.linear.com/leadfree/>

For more information on tape and reel specifications, go to: <http://www.linear.com/tapeandreel/>

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ELECTRICAL CHARACTERISTICS

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25^\circ\text{C}$. $V_{IN} = 15\text{V}$, $V_{RUN/SS1, 2} = 5\text{V}$ unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
Main Control Loops							
V _{OSENSE1, 2}	Regulated Feedback Voltage	(Note 3); I _{TH1, 2} Voltage = 1.2V	●	0.788	0.800	0.812	V
I _{VOSENSE1, 2}	Feedback Current	(Note 3)			−5	−50	nA
V _{REFLNREG}	Reference Voltage Line Regulation	V _{IN} = 3.6V to 30V (Note 3)			0.002	0.02	%/V
V _{LOADREG}	Output Voltage Load Regulation	(Note 3) Measured in Servo Loop; ΔI _{TH} Voltage = 1.2V to 0.7V Measured in Servo Loop; ΔI _{TH} Voltage = 1.2V to 2.0V	● ●		0.1 −0.1	0.5 −0.5	% %
g _{m1, 2}	Transconductance Amplifier g _m	I _{TH1, 2} = 1.2V; Sink/Source 5μA; (Note 3)			1.3		mmho
g _{mGBW1, 2}	Transconductance Amplifier GBW	I _{TH1, 2} = 1.2V; (Note 3)			3		MHz
I _Q	Input DC Supply Current Normal Mode Shutdown	(Note 4) V _{IN} = 15V; EXTV _{CC} Tied to V _{OUT1} ; V _{OUT1} = 5V V _{RUN/SS1, 2} = 0V			450 20	35	μA μA
V _{FCB}	Forced Continuous Threshold		●	0.76	0.800	0.84	V
I _{FCB}	Forced Continuous Pin Current	V _{FCB} = 0.85V		−0.50	−0.18	−0.1	μA
V _{BINHIBIT}	Burst Inhibit (Constant Frequency) Threshold	Measured at FCB pin			4.3	4.8	V
UVLO	Undervoltage Lockout	V _{IN} Ramping Down	●		3.5	4	V
V _{OVL}	Feedback Overvoltage Lockout	Measured at V _{OSENSE1, 2}	●	0.84	0.86	0.88	V
I _{SENSE}	Sense Pins Total Source Current	(Each Channel); V _{SENSE1−, 2−} = V _{SENSE1+, 2+} = 0V		−90	−60		μA
DF _{MAX}	Maximum Duty Factor	In Dropout		98	99.4		%
I _{RUN/SS1, 2}	Soft-Start Charge Current	V _{RUN/SS1, 2} = 1.9V		0.5	1.2		μA
V _{RUN/SS1, 2 ON}	RUN/SS Pin ON Threshold	V _{RUN/SS1} , V _{RUN/SS2} Rising		1.0	1.5	2.0	V
V _{SENSE(MAX)}	Maximum Current Sense Threshold	V _{OSENSE1, 2} = 0.7V, V _{SENSE1−, 2−} = 5V V _{OSENSE1, 2} = 0.7V, V _{SENSE1−, 2−} = 5V	●	65 62	75 75	85 88	mV mV
TG1, 2 t _r TG1, 2 t _f	TG Transition Time: Rise Time Fall Time	(Note 5) C _{LOAD} = 3300pF C _{LOAD} = 3300pF			55 55	100 100	ns ns
BG1, 2 t _r BG1, 2 t _f	BG Transition Time: Rise Time Fall Time	(Note 5) C _{LOAD} = 3300pF C _{LOAD} = 3300pF			45 45	100 90	ns ns
TG/BG t _{1D}	Top Gate Off to Bottom Gate On Delay Synchronous Switch-On Delay Time	C _{LOAD} = 3300pF Each Driver			80		ns
BG/TG t _{2D}	Bottom Gate Off to Top Gate On Delay Top Switch-On Delay Time	C _{LOAD} = 3300pF Each Driver			80		ns
t _{ON(MIN)}	Minimum On-Time	Tested with a Square Wave (Note 6)			100		ns
INTV _{CC} Linear Regulator							
V _{INTVCC}	Internal V _{CC} Voltage	6V < V _{IN} < 30V, V _{EXTVCC} = 4V		4.8	5.0	5.2	V
V _{LDO INT}	INTV _{CC} Load Regulation	I _{CC} = 0 to 20mA, V _{EXTVCC} = 4V			0.2	2.0	%
V _{LDO EXT}	EXTV _{CC} Voltage Drop	I _{CC} = 20mA, V _{EXTVCC} = 5V			100	200	mV
V _{EXTVCC}	EXTV _{CC} Switchover Voltage	I _{CC} = 20mA, EXTV _{CC} Ramping Positive	●	4.5	4.7		V
V _{LDOHYS}	EXTV _{CC} Hysteresis				0.2		V
Oscillator and Phase-Locked Loop							
f _{NOM}	Nominal Frequency	V _{PLLFLTR} = 1.2V		360	400	440	kHz
f _{LOW}	Lowest Frequency	V _{PLLFLTR} = 0V		230	260	290	kHz
f _{HIGH}	Highest Frequency	V _{PLLFLTR} ≥ 2.4V		480	550	590	kHz
R _{PLLIN}	PLLIN Input Resistance				50		kΩ

LTC3728L-1

ELECTRICAL CHARACTERISTICS

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25^\circ\text{C}$, $V_{IN} = 15\text{V}$, $V_{RUN/SS1, 2} = 5\text{V}$ unless otherwise noted.

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
$I_{PLLFLTR}$	Phase Detector Output Current Sinking Capability Sourcing Capability	$f_{PLLIN} < f_{OSC}$ $f_{PLLIN} > f_{OSC}$		-15 15		μA μA
3.3V Linear Regulator						
$V_{3.3OUT}$	3.3V Regulator Output Voltage	No Load	● 3.2	3.35	3.45	V
$V_{3.3IL}$	3.3V Regulator Load Regulation	$I_{3.3} = 0$ to 10mA		0.5	2	%
$V_{3.3VL}$	3.3V Regulator Line Regulation	$6\text{V} < V_{IN} < 30\text{V}$		0.05	0.2	%
$I_{3.3LEAK}$	Leakage Current in Shutdown	$V_{RUN/SS1} = 0\text{V}$; $V_{RUN/SS2} = 0\text{V}$, $V_{IN} = 3\text{V}$	●	10	50	μA
PGOOD Output						
V_{PGL}	PGOOD Voltage Low	$I_{PGOOD} = 2\text{mA}$		0.1	0.3	V
I_{PGOOD}	PGOOD Leakage Current	$V_{PGOOD} = 5\text{V}$			± 1	μA
V_{PG}	PGOOD Trip Level, Either Controller	V_{OSENSE} with Respect to Set Output Voltage V_{OSENSE} Ramping Negative V_{OSENSE} Ramping Positive	-6 6	-7.5 7.5	-9.5 9.5	% %

Note 1: Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

Note 2: T_J is calculated from the ambient temperature T_A and power dissipation P_D according to the following formulas:

$$\text{LTC3728LUH-1: } T_J = T_A + (P_D \cdot 34^\circ\text{C/W})$$

$$\text{LTC3728LGN-1: } T_J = T_A + (P_D \cdot 95^\circ\text{C/W})$$

Note 3: The IC is tested in a feedback loop that serves $V_{ITH1, 2}$ to a specified voltage and measures the resultant $V_{OSENSE1, 2}$.

Note 4: Dynamic supply current is higher due to the gate charge being delivered at the switching frequency. See Applications Information.

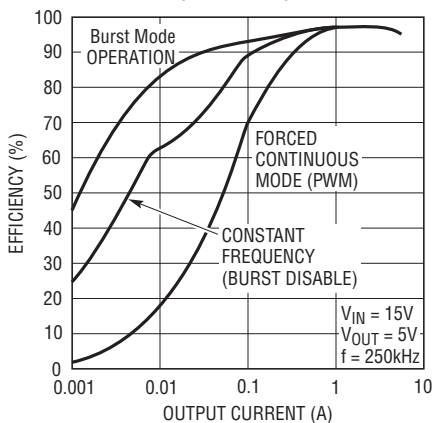
Note 5: Rise and fall times are measured using 10% and 90% levels. Delay times are measured using 50% levels.

Note 6: The minimum on-time condition is specified for an inductor peak-to-peak ripple current $\geq 40\%$ of I_{MAX} (see minimum on-time considerations in the Applications Information section).

Note 7: The LTC3728LE-1 are guaranteed to meet performance specifications from 0°C to 85°C . Specifications over the -40°C to 85°C operating temperature range are assured by design, characterization and correlation with statistical process controls. The LTC3728LI-1 is guaranteed to meet performance specifications over the full -40°C to 85°C operating temperature range.

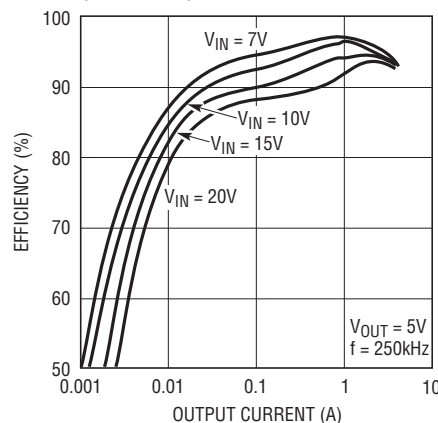
TYPICAL PERFORMANCE CHARACTERISTICS

Efficiency vs Output Current and Mode (Figure 13)



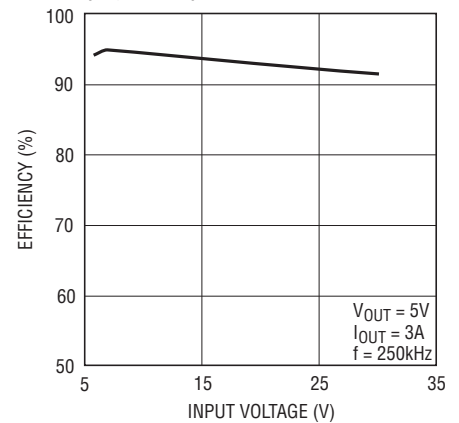
3728L1 G01

Efficiency vs Output Current (Figure 13)



3728L1 G02

Efficiency vs Input Voltage (Figure 13)

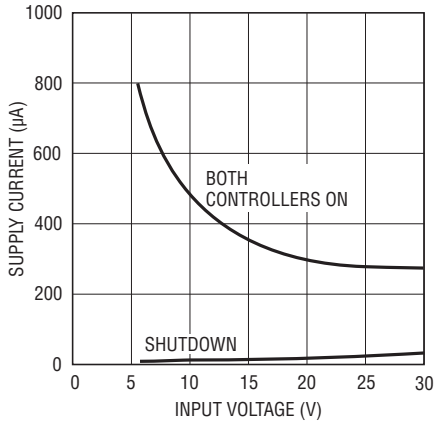


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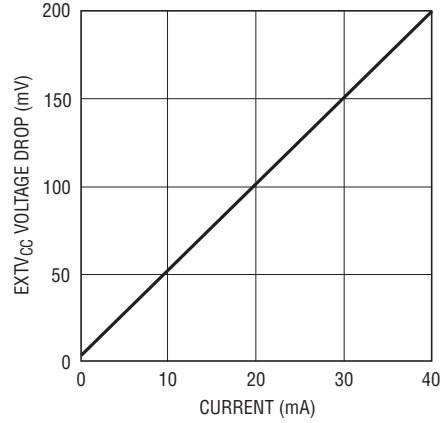
TYPICAL PERFORMANCE CHARACTERISTICS

Supply Current vs Input Voltage and Mode (Figure 13)



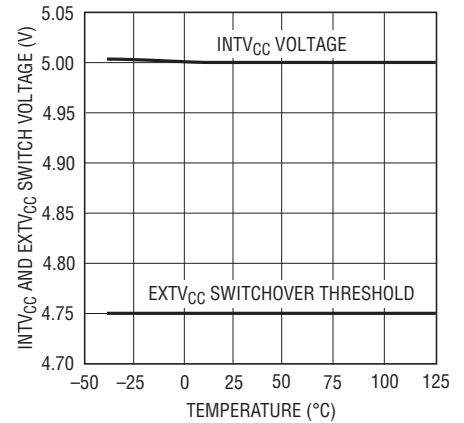
3728L1 G04

EXTV_{CC} Voltage Drop



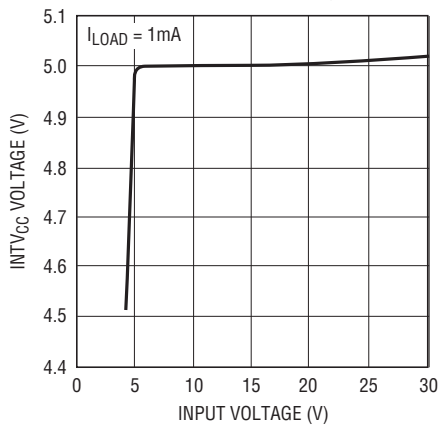
3728L1 G05

INTV_{CC} and EXTV_{CC} Switch Voltage vs Temperature



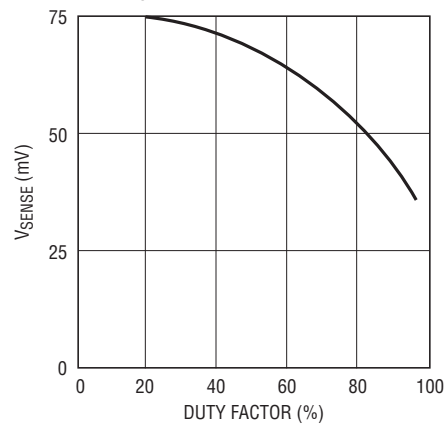
3728L1 G06

Internal 5V LDO Line Regulation



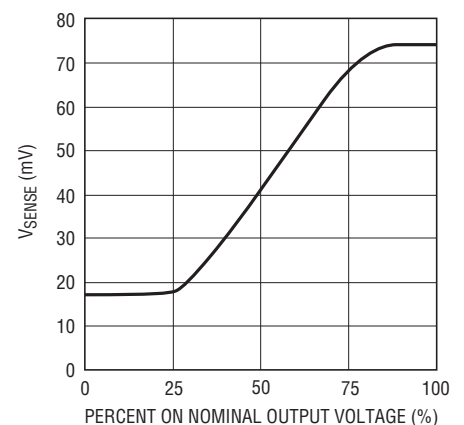
3728L1 G07

Maximum Current Sense Threshold vs Duty Factor



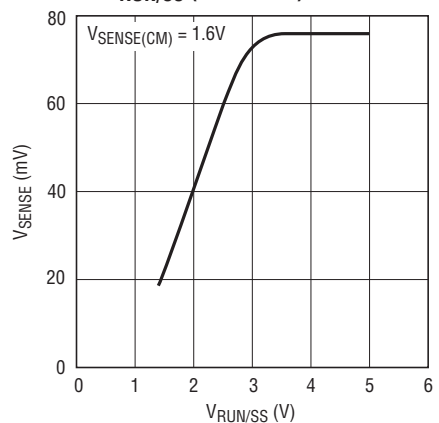
3728L1 G08

Maximum Current Sense Threshold vs Percent of Nominal Output Voltage (Foldback)



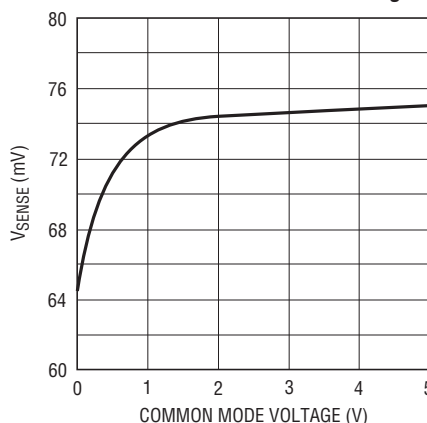
3728L1 G09

Maximum Current Sense Threshold vs V_{RUN/SS} (Soft-Start)



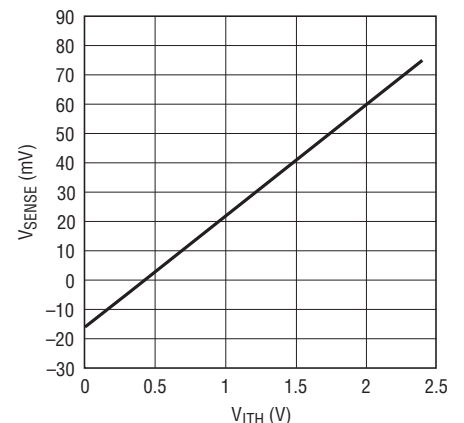
3728L1 G10

Maximum Current Sense Threshold vs Sense Common Mode Voltage



3728L1 G11

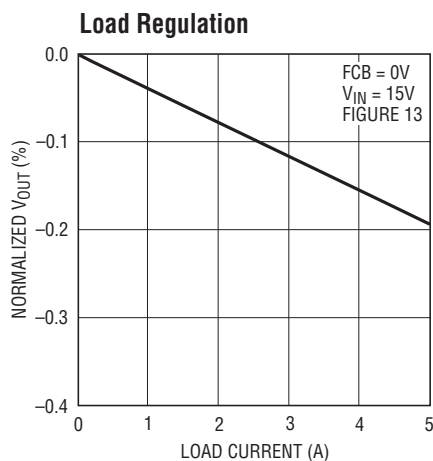
Current Sense Threshold vs I_{TH} Voltage



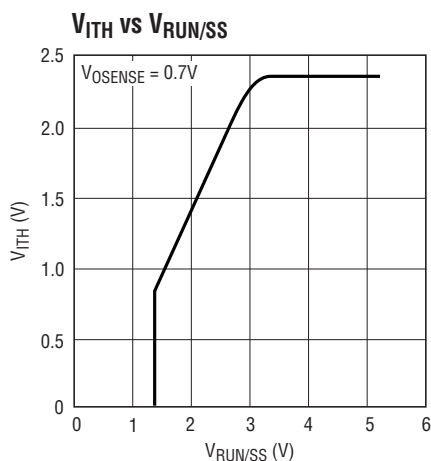
3728L1 G12

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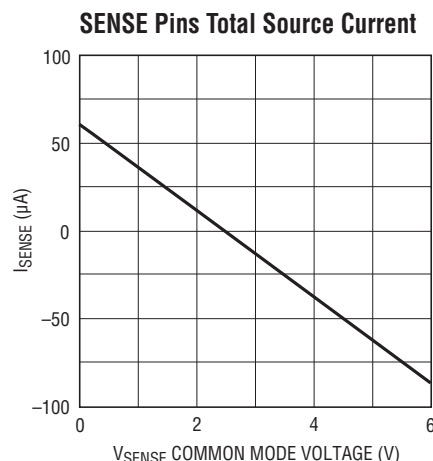
TYPICAL PERFORMANCE CHARACTERISTICS



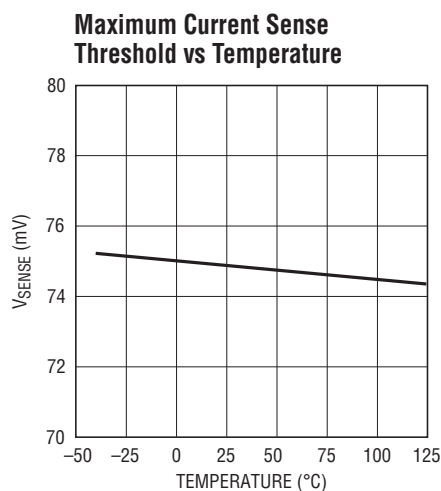
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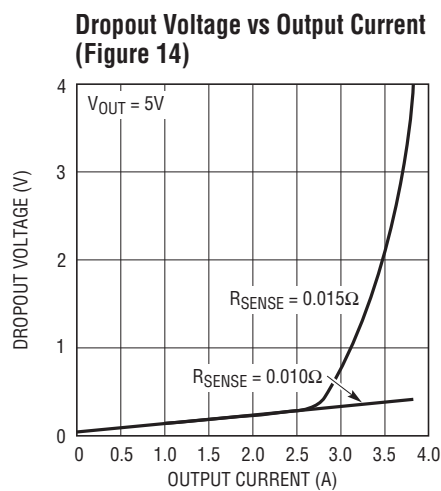
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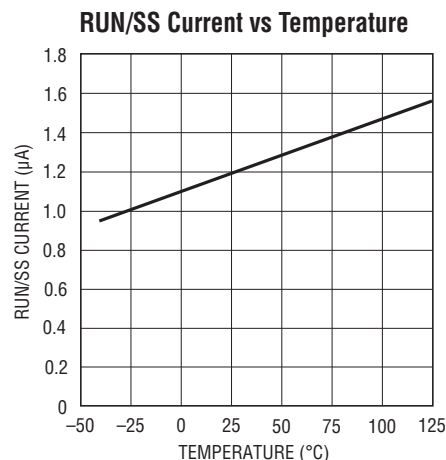
3728L1 G15



3728L1 G17

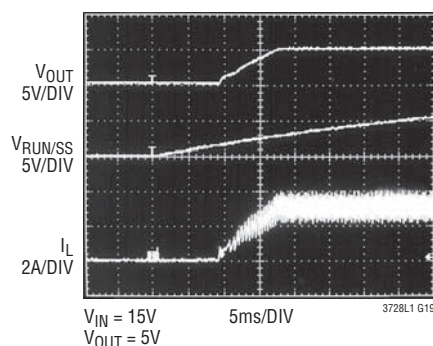


3728L1 G18



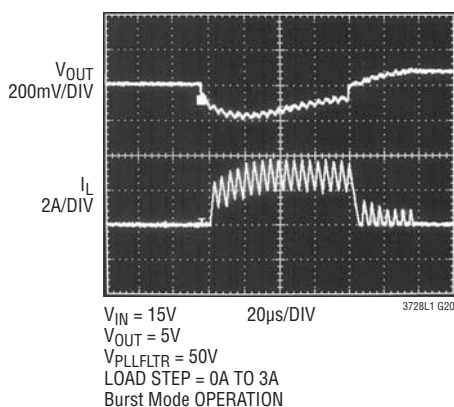
3728L1 G25

Soft-Start Up (Figure 13)



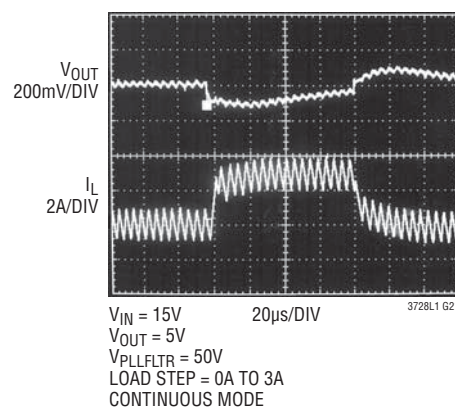
3728L1 G19

Load Step (Figure 13)



3728L1 G20

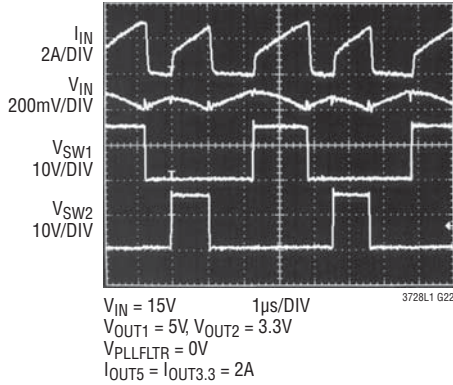
Load Step (Figure 13)



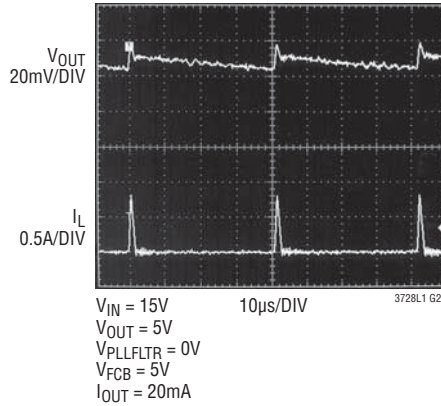
3728L1 G21

TYPICAL PERFORMANCE CHARACTERISTICS

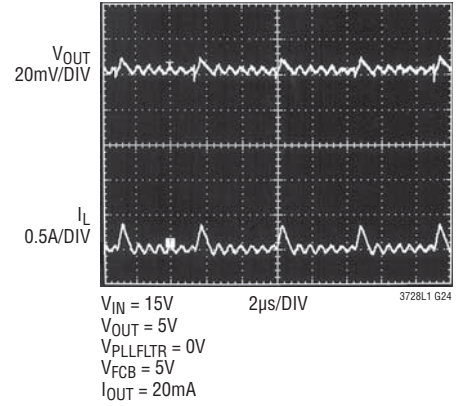
**Input Source/Capacitor
Instantaneous Current (Figure 13)**



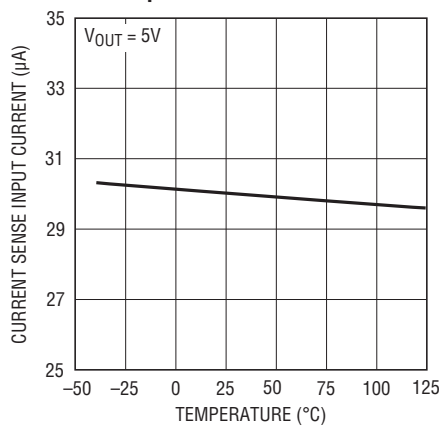
Burst Mode Operation (Figure 13)



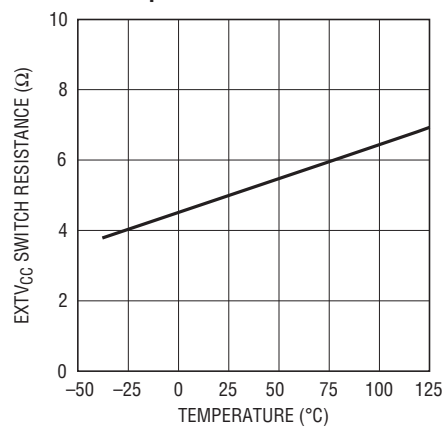
**Constant Frequency (Burst Inhibit)
Operation (Figure 13)**



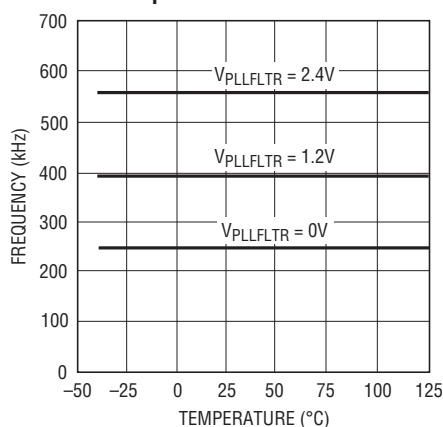
**Current Sense Pin Input Current
vs Temperature**



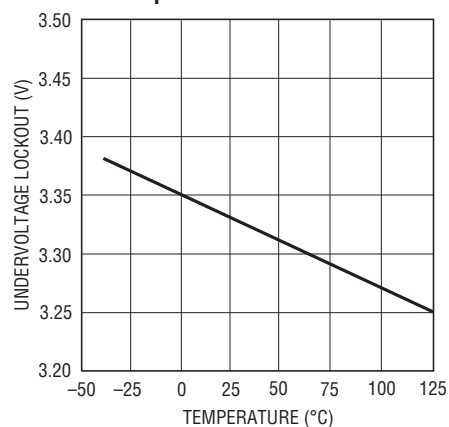
**EXTV_{CC} Switch Resistance
vs Temperature**



**Oscillator Frequency
vs Temperature**



**Undervoltage Lockout
vs Temperature**



PIN FUNCTIONS

VOSENSE1, VOSENSE2: Error Amplifier Feedback Input. Receives the remotely-sensed feedback voltage for each controller from an external resistive divider across the output.

PLLFLTR: Filter Connection for Phase-Locked Loop. Alternatively, this pin can be driven with an AC or DC voltage source to vary the frequency of the internal oscillator.

PLLIN: External Synchronization Input to Phase Detector. This pin is internally terminated to SGND with 50k Ω . The phase-locked loop will force the rising top gate signal of controller 1 to be synchronized with the rising edge of the PLLIN signal.

FCB: Forced Continuous Control Input. This input acts on both controllers and is normally used to regulate a secondary winding. Pulling this pin below 0.8V will force continuous synchronous operation.

ITH1, ITH2: Error Amplifier Output and Switching Regulator Compensation Point. Each associated channels' current comparator trip point increases with this control voltage.

SGND: Small Signal Ground. Common to both controllers, this pin must be routed separately from high current grounds to the common (–) terminals of the C_{OUT} capacitors.

3.3V_{OUT}: Linear Regulator Output. Capable of supplying 10mA DC with peak currents as high as 50mA.

NC: No Connect.

SENSE2[–], SENSE1[–]: The (–) Input to the Differential Current Comparators.

SENSE2⁺, SENSE1⁺: The (+) Input to the Differential Current Comparators. The I_{TH} pin voltage and controlled offsets between the SENSE[–] and SENSE⁺ pins in conjunction with R_{SENSE} set the current trip threshold.

RUN/SS2, RUN/SS1: Combination of soft-start and run control inputs. A capacitor to ground at each of these pins sets the ramp time to full output current. Forcing either of these pins back below 1.0V causes the IC to shut down the circuitry required for that particular controller.

TG2, TG1: High Current Gate Drives for Top N-Channel MOSFETs. These are the outputs of floating drivers with a voltage swing equal to INTV_{CC} – 0.5V superimposed on the switch node voltage SW.

SW2, SW1: Switch Node Connections to Inductors. Voltage swing at these pins is from a Schottky diode (external) voltage drop below ground to V_{IN}.

BOOST2, BOOST1: Bootstrapped Supplies to the Top Side Floating Drivers. Capacitors are connected between the boost and switch pins and Schottky diodes are tied between the boost and INTV_{CC} pins. Voltage swing at the boost pins is from INTV_{CC} to (V_{IN} + INTV_{CC}).

BG2, BG1: High Current Gate Drives for Bottom (Synchronous) N-Channel MOSFETs. Voltage swing at these pins is from ground to INTV_{CC}.

PGND: Driver Power Ground. Connects to the sources of bottom (synchronous) N-channel MOSFETs, anodes of the Schottky rectifiers and the (–) terminal(s) of C_{IN}.

INTV_{CC}: Output of the Internal 5V Linear Low Dropout Regulator and the EXTV_{CC} Switch. The driver and control circuits are powered from this voltage source. Must be decoupled to power ground with a minimum of 4.7 μ F tantalum or other low ESR capacitor.

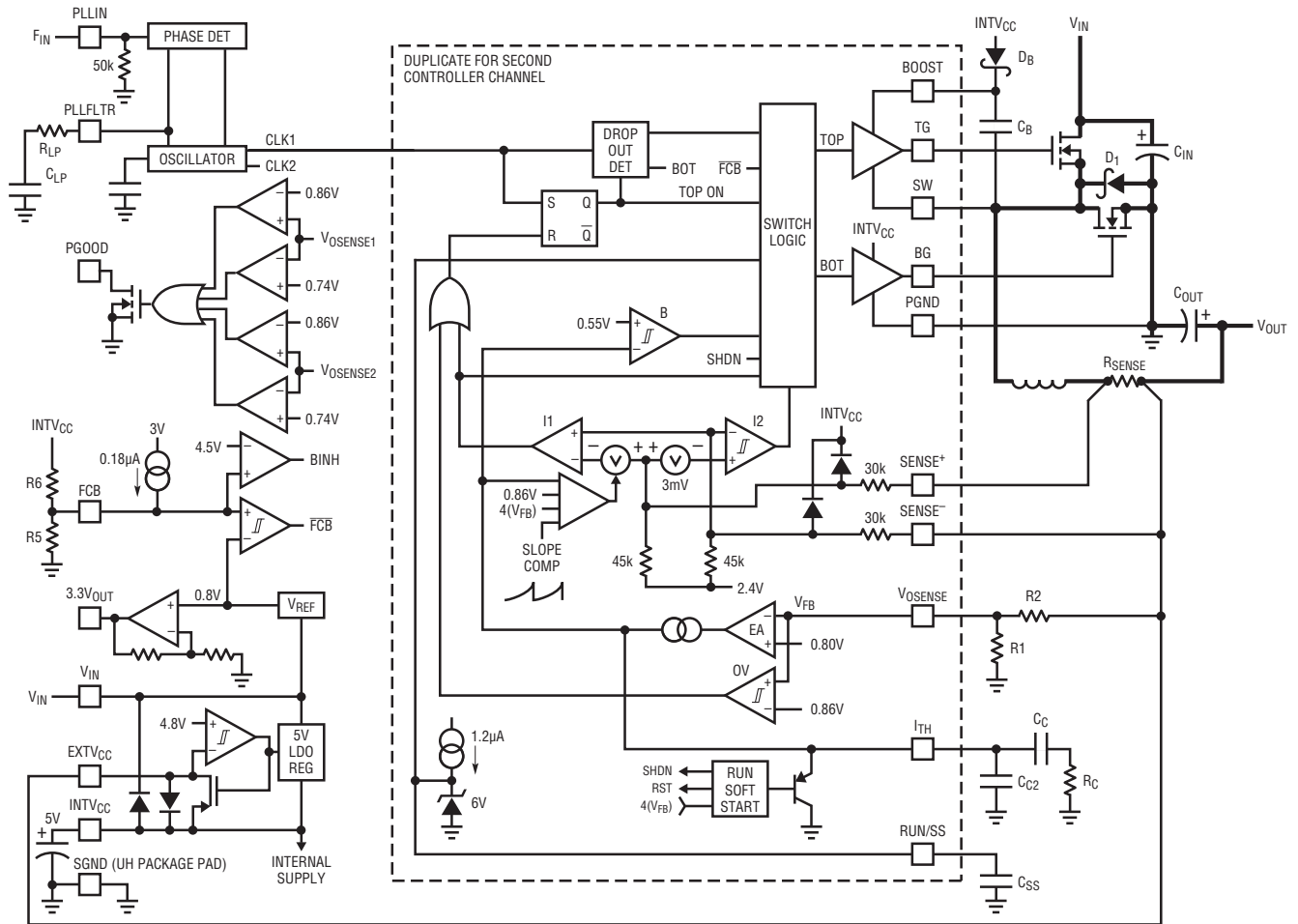
EXTV_{CC}: External Power Input to an Internal Switch Connected to INTV_{CC}. This switch closes and supplies V_{CC} power, bypassing the internal low dropout regulator, whenever EXTV_{CC} is higher than 4.7V. See EXTV_{CC} connection in Applications section. Do not exceed 7V on this pin.

V_{IN}: Main Supply Pin. A bypass capacitor should be tied between this pin and the signal ground pin.

PGOOD: Open-Drain Logic Output. PGOOD is pulled to ground when the voltage on either VOSENSE pin is not within $\pm 7.5\%$ of its set point.

Exposed Pad (UH Package Only): Signal Ground. Must be soldered to the PCB, providing a local ground for the control components of the IC, and be tied to the PGND pin under the IC.

FUNCTIONAL DIAGRAM



3728L1 F02

Figure 2

OPERATION (Refer to Functional Diagram)

Main Control Loop

The LTC3728L-1 is a constant frequency, current mode step-down controller with two channels operating 180 degrees out of phase. During normal operation, each top MOSFET is turned on when the clock for that channel sets the RS latch, and turned off when the main current comparator, I_1 , resets the RS latch. The peak inductor current at which I_1 resets the RS latch is controlled by the voltage on the I_{TH} pin, which is the output of each error amplifier EA. The V_{OSENSE} pin receives the voltage feedback signal, which is compared to the internal reference voltage by the EA. When the load current increases, it causes a slight decrease in V_{OSENSE} relative to the 0.8V reference, which in turn causes the I_{TH} voltage to increase until the average inductor current matches the new load current. After the top MOSFET has turned off, the bottom MOSFET is turned on until either the inductor current starts to reverse, as indicated by current comparator I_2 , or the beginning of the next cycle.

The top MOSFET drivers are biased from floating bootstrap capacitor C_B , which normally is recharged during each off cycle through an external diode when the top MOSFET turns off. As V_{IN} decreases to a voltage close to V_{OUT} , the loop may enter dropout and attempt to turn on the top MOSFET continuously. The dropout detector detects this and forces the top MOSFET off for about 400ns every tenth cycle to allow C_B to recharge.

The main control loop is shut down by pulling the RUN/SS pin low. Releasing RUN/SS allows an internal 1.2 μ A current source to charge soft-start capacitor C_{SS} . When C_{SS} reaches 1.5V, the main control loop is enabled with the I_{TH} voltage clamped at approximately 30% of its maximum value. As C_{SS} continues to charge, the I_{TH} pin voltage is gradually released allowing normal, full-current operation. When both RUN/SS1 and RUN/SS2 are low, all controller functions are shut down, including the 5V regulator.

Low Current Operation

The FCB pin is a multifunction pin providing two functions: 1) to provide regulation for a secondary winding

by temporarily forcing continuous PWM operation on both controllers; and 2) to select between *two* modes of low current operation. When the FCB pin voltage is below 0.8V, the controller forces continuous PWM current mode operation. In this mode, the top and bottom MOSFETs are alternately turned on to maintain the output voltage independent of direction of inductor current. When the FCB pin is below $V_{INTVCC} - 2V$ but greater than 0.8V, the controller enters Burst Mode operation. Burst Mode operation sets a minimum output current level before inhibiting the top switch and turns off the synchronous MOSFET(s) when the inductor current goes negative. This combination of requirements will, at low currents, force the I_{TH} pin below a voltage threshold that will temporarily inhibit turn-on of both output MOSFETs until the output voltage drops. There is 60mV of hysteresis in the burst comparator B tied to the I_{TH} pin. This hysteresis produces output signals to the MOSFETs that turn them on for several cycles, followed by a variable "sleep" interval depending upon the load current. The resultant output voltage ripple is held to a very small value by having the hysteretic comparator after the error amplifier gain block.

Frequency Synchronization

The phase-locked loop allows the internal oscillator to be synchronized to an external source via the PLLIN pin. The output of the phase detector at the PLLFLTR pin is also the DC frequency control input of the oscillator that operates over a 260kHz to 550kHz range corresponding to a DC voltage input from 0V to 2.4V. When locked, the PLL aligns the turn on of the top MOSFET to the rising edge of the synchronizing signal. When PLLIN is left open, the PLLFLTR pin goes low, forcing the oscillator to minimum frequency.

Constant Frequency Operation

When the FCB pin is tied to $INTV_{CC}$, Burst Mode operation is disabled and the forced minimum output current requirement is removed. This provides constant frequency, discontinuous current (preventing reverse inductor current) operation over the widest possible output current range. This constant frequency operation is not as efficient

OPERATION (Refer to Functional Diagram)

as Burst Mode operation, but does provide a lower noise, constant frequency operating mode down to approximately 1% of the designed maximum output current.

Continuous Current (PWM) Operation

Tying the FCB pin to ground will force continuous current operation. This is the least efficient operating mode, but may be desirable in certain applications. The output can source or sink current in this mode. When sinking current while in forced continuous operation, the controller will cause current to flow back into the input filter capacitor. If large enough, this element will prevent the input supply from boosting to unacceptably high levels; see C_{OUT} Selection in the Applications Information Section.

INTV_{CC}/EXTV_{CC} Power

Power for the top and bottom MOSFET drivers and most other internal circuitry is derived from the INTV_{CC} pin. When the EXTV_{CC} pin is left open, an internal 5V low dropout linear regulator supplies INTV_{CC} power. If EXTV_{CC} is taken above 4.7V, the 5V regulator is turned off and an internal switch is turned on connecting EXTV_{CC} to INTV_{CC}. This allows the INTV_{CC} power to be derived from a high efficiency external source such as the output of the regulator itself or a secondary winding, as described in the Applications Information section.

Output Overvoltage Protection

An overvoltage comparator, OV, guards against transient overshoots (>7.5%) as well as other more serious conditions that may overvoltage the output. In this case, the top MOSFET is turned off and the bottom MOSFET is turned on until the overvoltage condition is cleared.

Power Good (PGOOD) Pin

The PGOOD pin is connected to an open drain of an internal MOSFET. The MOSFET turns on and pulls the pin low when either output is not within $\pm 7.5\%$ of the nominal output level as determined by the resistive feedback divider. When both outputs meet the $\pm 7.5\%$ requirement, the MOSFET is

turned off within 10 μ s and the pin is allowed to be pulled up by an external resistor to a source of up to 7V.

Foldback Current

The RUN/SS capacitors are used initially to limit the inrush current of each switching regulator. Foldback current limiting is activated when the output voltage falls below 70% of its nominal level. If a short is present, a safe, low output current is provided due to the internal current foldback and actual power wasted is low due to the efficient nature of the current mode switching regulator.

THEORY AND BENEFITS OF 2-PHASE OPERATION

The LTC1628 and the LTC3728L-1 family of dual high efficiency DC/DC controllers brings the considerable benefits of 2-phase operation to portable applications for the first time. Notebook computers, PDAs, handheld terminals and automotive electronics will all benefit from the lower input filtering requirement, reduced electromagnetic interference (EMI) and increased efficiency associated with 2-phase operation.

Why the need for 2-phase operation? Up until the 2-phase family, constant-frequency dual switching regulators operated both channels in phase (i.e., single-phase operation). This means that both switches turned on at the same time, causing current pulses of up to twice the amplitude of those for one regulator to be drawn from the input capacitor and battery. These large amplitude current pulses increased the total RMS current flowing from the input capacitor, requiring the use of more expensive input capacitors and increasing both EMI and losses in the input capacitor and battery.

With 2-phase operation, the two channels of the dual-switching regulator are operated 180 degrees out of phase. This effectively interleaves the current pulses drawn by the switches, greatly reducing the overlap time where they add together. *The result is a significant reduction in total RMS input current, which in turn allows less expensive input capacitors to be used, reduces shielding requirements for EMI and improves real world operating efficiency.*

OPERATION (Refer to Functional Diagram)

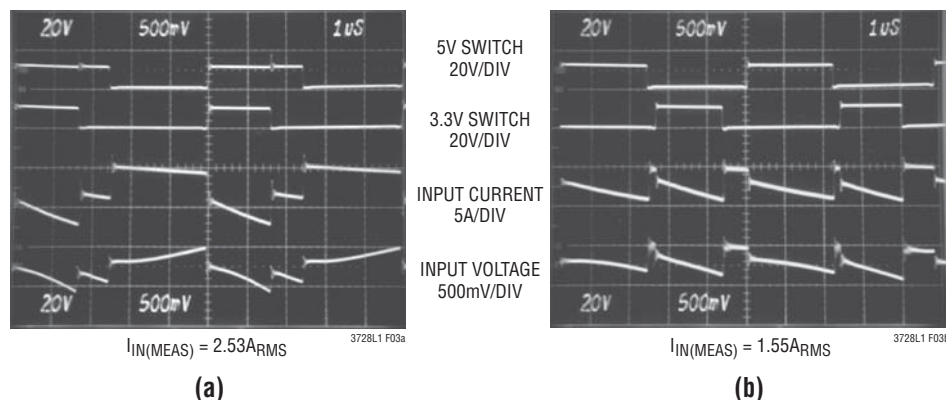


Figure 3. Input Waveforms Comparing Single-Phase (a) and 2-Phase (b) Operation for Dual Switching Regulators Converting 12V to 5V and 3.3V at 3A Each. The Reduced Input Ripple with the LTC1628 2-Phase Regulator Allows Less Expensive Input Capacitors, Reduces Shielding Requirements for EMI and Improves Efficiency

Figure 3 compares the input waveforms for a representative single-phase dual switching regulator to the LTC1628 2-phase dual switching regulator. An actual measurement of the RMS input current under these conditions shows that 2-phase operation dropped the input current from $2.53A_{RMS}$ to $1.55A_{RMS}$. While this is an impressive reduction in itself, remember that the power losses are proportional to I_{RMS}^2 , meaning that the actual power wasted is reduced by a factor of 2.66. The reduced input ripple voltage also means less power is lost in the input power path, which could include batteries, switches, trace/connector resistances and protection circuitry. Improvements in both conducted and radiated EMI also directly accrue as a result of the reduced RMS input current and voltage.

Of course, the improvement afforded by 2-phase operation is a function of the dual switching regulator's relative duty cycles which, in turn, are dependent upon the input voltage V_{IN} (Duty Cycle = V_{OUT}/V_{IN}). Figure 4 shows how the RMS input current varies for single-phase and 2-phase operation for 3.3V and 5V regulators over a wide input voltage range.

It can readily be seen that the advantages of 2-phase operation are not just limited to a narrow operating range, but in fact extend over a wide region. A good rule of thumb for most applications is that 2-phase operation will reduce the input capacitor requirement to that for just one channel operating at maximum current and 50% duty cycle.

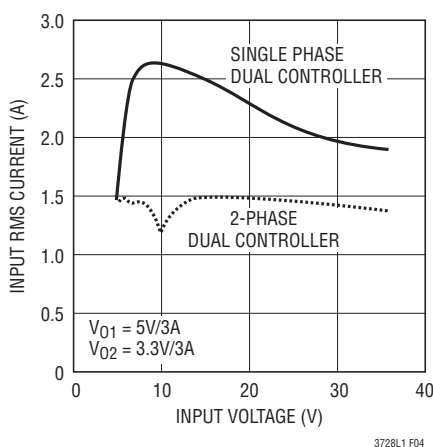


Figure 4. RMS Input Current Comparison

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Figure 1 on the first page is a basic LTC3728L-1 application circuit. External component selection is driven by the load requirement, and begins with the selection of R_{SENSE} and the inductor value. Next, the power MOSFETs and D1 are selected. Finally, C_{IN} and C_{OUT} are selected. The circuit shown in Figure 1 can be configured for operation up to an input voltage of 28V (limited by the external MOSFETs).

R_{SENSE} Selection For Output Current

R_{SENSE} is chosen based on the required output current. The current comparator has a maximum threshold of $75\text{mV}/R_{SENSE}$ and an input common mode range of SGND to $1.1(\text{INTV}_{CC})$. The current comparator threshold sets the peak of the inductor current, yielding a maximum average output current I_{MAX} equal to the peak value less half the peak-to-peak ripple current, ΔI_L .

Allowing a margin for variations in the IC and external component values yields:

$$R_{SENSE} = \frac{50\text{mV}}{I_{MAX}}$$

When using the controller in very low dropout conditions, the maximum output current level will be reduced due to the internal compensation required to meet stability criteria for buck regulators operating at greater than 50% duty factor. A curve is provided to estimate this reduction in peak output current level depending upon the operating duty factor.

Operating Frequency

The IC uses a constant frequency phase-lockable architecture with the frequency determined by an internal capacitor. This capacitor is charged by a fixed current plus an additional current which is proportional to the voltage applied to the PLLFLTR pin. Refer to Phase-Locked Loop and Frequency Synchronization in the Applications Information section for additional information.

A graph for the voltage applied to the PLLFLTR pin vs frequency is given in Figure 5. As the operating frequency is increased the gate charge losses will be higher, reducing

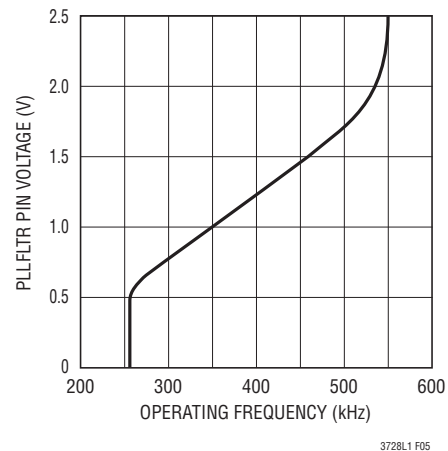


Figure 5. PLLFLTR Pin Voltage vs Frequency

efficiency (see Efficiency Considerations). The maximum switching frequency is approximately 550kHz.

Inductor Value Calculation

The operating frequency and inductor selection are inter-related in that higher operating frequencies allow the use of smaller inductor and capacitor values. So why would anyone ever choose to operate at lower frequencies with larger components? The answer is efficiency. A higher frequency generally results in lower efficiency because of MOSFET gate charge losses. In addition to this basic trade-off, the effect of inductor value on ripple current and low current operation must also be considered.

The inductor value has a direct effect on ripple current. The inductor ripple current ΔI_L decreases with higher inductance or frequency and increases with higher V_{IN} :

$$\Delta I_L = \frac{1}{(f)(L)} V_{OUT} \left(1 - \frac{V_{OUT}}{V_{IN}} \right)$$

Accepting larger values of ΔI_L allows the use of low inductances, but results in higher output voltage ripple and greater core losses. A reasonable starting point for setting ripple current is $\Delta I_L = 0.3(I_{MAX})$. The maximum ΔI_L occurs at the maximum input voltage.

The inductor value also has secondary effects. The transition to Burst Mode operation begins when the average inductor current required results in a peak current below

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25% of the current limit determined by R_{SENSE} . Lower inductor values (higher ΔI_L) will cause this to occur at lower load currents, which can cause a dip in efficiency in the upper range of low current operation. In Burst Mode operation, lower inductance values will cause the burst frequency to decrease.

Inductor Core Selection

Usually, high inductance is preferred for small current ripple and low core loss. Unfortunately, increased inductance requires more turns of wire or a smaller air gap in the inductor core, resulting in high copper loss or low saturation current. Once the value of L is known, the actual inductor must be selected. There are two popular types of core material of commercial available inductors. Ferrite core inductors usually have very low core loss and are preferred at high switching frequencies, so design goals can concentrate on copper loss and preventing saturation. However, ferrite core saturates “hard”, which means that inductance collapses abruptly when the peak design current is exceeded. This results in an abrupt increase in inductor ripple current and consequent output voltage ripple. One advantage of the LTC3728L-1 is its current mode control that detects and limits cycle-by-cycle peak inductor current. Therefore, accurate and fast protection is achieved if the inductor is saturated in steady state or during transient mode.

Powdered iron core inductors usually saturate “soft”, which means the inductance drops in a linear fashion when the current increases. However, the core loss of the powder iron inductor is usually higher than the ferrite inductor. So designs with high switching frequency should also address inductor core loss.

Inductor manufacturers usually provide inductance, DCR, (peak) saturation current and (DC) heating current ratings in the inductor data sheet. A good supply design should not exceed the saturation and heating current rating of the inductor.

Power MOSFET and D1 Selection

Two external power MOSFETs must be selected for each controller in the LTC3728L-1: One N-channel MOSFET for the top (main) switch, and one N-channel MOSFET for the

bottom (synchronous) switch.

The peak-to-peak drive levels are set by the $INTV_{CC}$ voltage. This voltage is typically 5V during start-up (see $EXTV_{CC}$ Pin Connection). Consequently, logic-level threshold MOSFETs must be used in most applications. The only exception is if low input voltage is expected ($V_{IN} < 5V$); then, sub-logic level threshold MOSFETs ($V_{GS(TH)} < 3V$) should be used. Pay close attention to the BV_{DSS} specification for the MOSFETs as well; most of the logic level MOSFETs are limited to 30V or less.

Selection criteria for the power MOSFETs include the “ON” resistance $R_{DS(ON)}$, Miller capacitance C_{MILLER} , input voltage and maximum output current. Miller capacitance, C_{MILLER} , can be approximated from the gate charge curve usually provided on the MOSFET manufacturers’ data sheet. C_{MILLER} is equal to the increase in gate charge along the horizontal axis while the curve is approximately flat divided by the specified change in V_{DS} . This result is then multiplied by the ratio of the application applied V_{DS} to the Gate charge curve specified V_{DS} . When the IC is operating in continuous mode the duty cycles for the top and bottom MOSFETs are given by:

$$\text{Main Switch Duty Cycle} = \frac{V_{OUT}}{V_{IN}}$$

$$\text{Synchronous Switch Duty Cycle} = \frac{V_{IN} - V_{OUT}}{V_{IN}}$$

The MOSFET power dissipations at maximum output current are given by:

$$P_{MAIN} = \frac{V_{OUT}}{V_{IN}} (I_{MAX})^2 (1 + \delta) R_{DS(ON)} + (V_{IN})^2 \left(\frac{I_{MAX}}{2} \right) (R_{DR}) (C_{MILLER}) \cdot \left[\frac{1}{V_{INTVCC} - V_{THMIN}} + \frac{1}{V_{THMIN}} \right] (f)$$

$$P_{SYNC} = \frac{V_{IN} - V_{OUT}}{V_{IN}} (I_{MAX})^2 (1 + \delta) R_{DS(ON)}$$

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where δ is the temperature dependency of $R_{DS(ON)}$ and R_{DR} (approximately 4Ω) is the effective driver resistance at the MOSFET's Miller threshold voltage. V_{THMIN} is the typical MOSFET minimum threshold voltage.

Both MOSFETs have I^2R losses while the topside N-channel equation includes an additional term for transition losses, which are highest at high input voltages. For $V_{IN} < 20V$ the high current efficiency generally improves with larger MOSFETs, while for $V_{IN} > 20V$ the transition losses rapidly increase to the point that the use of a higher $R_{DS(ON)}$ device with lower C_{MILLER} actually provides higher efficiency. The synchronous MOSFET losses are greatest at high input voltage when the top switch duty factor is low or during a short-circuit when the synchronous switch is on close to 100% of the period.

The term $(1+\delta)$ is generally given for a MOSFET in the form of a normalized $R_{DS(ON)}$ vs Temperature curve, but $\delta = 0.005/^\circ C$ can be used as an approximation for low voltage MOSFETs.

The Schottky diode D1 shown in Figure 1 conducts during the dead-time between the conduction of the two power MOSFETs. This prevents the body diode of the bottom MOSFET from turning on, storing charge during the dead-time and requiring a reverse recovery period that could cost as much as 3% in efficiency at high V_{IN} . A 1A to 3A Schottky is generally a good compromise for both regions of operation due to the relatively small average current. Larger diodes result in additional transition losses due to their larger junction capacitance. Schottky diodes should be placed in parallel with the synchronous MOSFETs when operating in pulse-skip mode or in Burst Mode operation.

C_{IN} and C_{OUT} Selection

The selection of C_{IN} is simplified by the multiphase architecture and its impact on the worst-case RMS current drawn through the input network (battery/fuse/capacitor). It can be shown that the worst case RMS current occurs when only one controller is operating. The controller with the highest $(V_{OUT})(I_{OUT})$ product needs to be used in the formula below to determine the maximum RMS current requirement. Increasing the output current, drawn from the other out-of-phase controller, will actually decrease the

input RMS ripple current from this maximum value (see Figure 4). The out-of-phase technique typically reduces the input capacitor's RMS ripple current by a factor of 30% to 70% when compared to a single phase power supply solution.

The type of input capacitor, value and ESR rating have efficiency effects that need to be considered in the selection process. The capacitance value chosen should be sufficient to store adequate charge to keep high peak battery currents down. $20\mu F$ to $40\mu F$ is usually sufficient for a 25W output supply operating at 200kHz. The ESR of the capacitor is important for capacitor power dissipation as well as overall battery efficiency. All of the power (RMS ripple current $\cdot$ ESR) not only heats up the capacitor but wastes power from the battery.

Medium voltage (20V to 35V) ceramic, tantalum, OS-CON and switcher-rated electrolytic capacitors can be used as input capacitors, but each has drawbacks: ceramics have very high voltage coefficients and may have audible piezoelectric effects; tantalums need to be surge-rated; OS-CONs suffer from higher inductance, larger case size and limited surface-mount applicability; electrolytics' higher ESR and dryout possibility require several to be used. Multiphase systems allow the lowest amount of capacitance overall. As little as one $22\mu F$ or two to three $10\mu F$ ceramic capacitors are an ideal choice in a 20W to 35W power supply due to their extremely low ESR. Even though the capacitance at 20V is substantially below their rating at zero-bias, very low ESR loss makes ceramics an ideal candidate for highest efficiency battery operated systems. Also consider parallel ceramic and high quality electrolytic capacitors as an effective means of achieving ESR and bulk capacitance goals.

In continuous mode, the source current of the top N-channel MOSFET is a square wave of duty cycle V_{OUT}/V_{IN} . To prevent large voltage transients, a low ESR input capacitor sized for the maximum RMS current of one channel must be used. The maximum RMS capacitor current is given by:

$$C_{IN} \text{ Required } I_{RMS} \approx I_{MAX} \frac{[V_{OUT}(V_{IN} - V_{OUT})]^{1/2}}{V_{IN}}$$

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This formula has a maximum at $V_{IN} = 2V_{OUT}$, where $I_{RMS} = I_{OUT}/2$. This simple worst case condition is commonly used for design because even significant deviations do not offer much relief. Note that capacitor manufacturer's ripple current ratings are often based on only 2000 hours of life. This makes it advisable to further derate the capacitor, or to choose a capacitor rated at a higher temperature than required. Several capacitors may also be paralleled to meet size or height requirements in the design. Always consult the manufacturer if there is any question.

The benefit of the LTC3728L-1 multiphase clocking can be calculated by using the equation above for the higher power controller and then calculating the loss that would have resulted if both controller channels switched on at the same time. The total RMS power lost is lower when both controllers are operating due to the interleaving of current pulses through the input capacitor's ESR. This is why the input capacitor's requirement calculated above for the worst-case controller is adequate for the dual controller design. Remember that input protection fuse resistance, battery resistance and PC board trace resistance losses are also reduced due to the reduced peak currents in a multiphase system. *The overall benefit of a multiphase design will only be fully realized when the source impedance of the power supply/battery is included in the efficiency testing.* The drains of the two top MOSFETs should be placed within 1cm of each other and share a common $C_{IN}(s)$. Separating the drains and C_{IN} may produce undesirable voltage and current resonances at V_{IN} .

The selection of C_{OUT} is driven by the required effective series resistance (ESR). Typically once the ESR requirement is satisfied the capacitance is adequate for filtering. The output ripple (ΔV_{OUT}) is determined by:

$$\Delta V_{OUT} \approx \Delta I_L \left(ESR + \frac{1}{8fC_{OUT}} \right)$$

Where f = operating frequency, C_{OUT} = output capacitance, and ΔI_L = ripple current in the inductor. The output ripple is highest at maximum input voltage since ΔI_L increases with input voltage. With $\Delta I_L = 0.3I_{OUT(MAX)}$ the output

ripple will typically be less than 50mV at the maximum V_{IN} assuming:

$$C_{OUT} \text{ Recommended ESR} < 2 R_{SENSE}$$

$$\text{and } C_{OUT} > 1/(8fR_{SENSE})$$

The first condition relates to the ripple current into the ESR of the output capacitance while the second term guarantees that the output capacitance does not significantly discharge during the operating frequency period due to ripple current. The choice of using smaller output capacitance increases the ripple voltage due to the discharging term but can be compensated for by using capacitors of very low ESR to maintain the ripple voltage at or below 50mV. The I_{TH} pin OPTI-LOOP compensation components can be optimized to provide stable, high performance transient response regardless of the output capacitors selected.

Manufacturers such as Nichicon, Nippon Chemi-Con and Sanyo can be considered for high performance through-hole capacitors. The OS-CON semiconductor dielectric capacitor available from Sanyo has the lowest (ESR)(size) product of any aluminum electrolytic at a somewhat higher price. An additional ceramic capacitor in parallel with OS-CON capacitors is recommended to reduce the inductance effects.

In surface mount applications multiple capacitors may need to be used in parallel to meet ESR, RMS current handling and load step requirements. Aluminum electrolytic, dry tantalum and special polymer capacitors are available in surface mount packages. Special polymer surface mount capacitors offer very low ESR but have lower storage capacity per unit volume than other capacitor types. These capacitors offer a very cost-effective output capacitor solution and are an ideal choice when combined with a controller having high loop bandwidth. Tantalum capacitors offer the highest capacitance density and are often used as output capacitors for switching regulators having controlled soft-start. Several excellent surge-tested choices are the AVX TPS, AVX TPSV or the KEMET T510 series of surface mount tantalums, available in case heights ranging from 2mm to 4mm. Aluminum electrolytic capacitors can be used

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in cost-driven applications providing that consideration is given to ripple current ratings, temperature and long term reliability. A typical application will require several to many aluminum electrolytic capacitors in parallel. A combination of the above mentioned capacitors will often result in maximizing performance and minimizing overall cost. Other capacitor types include Nichicon PL series, Panasonic SP, NEC Neocap, Cornell Dubilier ESRE and Sprague 595D series. Consult manufacturers for other specific recommendations.

INTV_{CC} Regulator

An internal P-channel low dropout regulator produces 5V at the INTV_{CC} pin from the V_{IN} supply pin. INTV_{CC} powers the drivers and internal circuitry within the IC. The INTV_{CC} pin regulator can supply a peak current of 50mA and must be bypassed to ground with a minimum of 4.7μF tantalum, 10μF special polymer, or low ESR type electrolytic capacitor. A 1μF ceramic capacitor placed directly adjacent to the INTV_{CC} and PGND IC pins is highly recommended. Good bypassing is necessary to supply the high transient currents required by the MOSFET gate drivers and to prevent interaction between channels.

Higher input voltage applications in which large MOSFETs are being driven at high frequencies may cause the maximum junction temperature rating for the IC to be exceeded. The system supply current is normally dominated by the gate charge current. Additional external loading of the INTV_{CC} and 3.3V linear regulators also needs to be taken into account for the power dissipation calculations. The total INTV_{CC} current can be supplied by either the 5V internal linear regulator or by the EXTV_{CC} input pin. When the voltage applied to the EXTV_{CC} pin is less than 4.7V, all of the INTV_{CC} current is supplied by the internal 5V linear regulator. Power dissipation for the IC in this case is highest: (V_{IN})(I_{INTVCC}), and overall efficiency is lowered. The gate charge current is dependent on operating frequency as discussed in the Efficiency Considerations section. The junction temperature can be estimated by using the equations given in Note 2 of the Electrical Characteristics. For example, the IC V_{IN} current is thermally limited to less than 67mA from a 24V supply when not using the EXTV_{CC}

pin as follows:

$$T_J = 70^{\circ}\text{C} + (67\text{mA})(24\text{V})(34^{\circ}\text{C/W}) = 125^{\circ}\text{C}$$

Use of the EXTV_{CC} input pin reduces the junction temperature to:

$$T_J = 70^{\circ}\text{C} + (67\text{mA})(5\text{V})(34^{\circ}\text{C/W}) = 81^{\circ}\text{C}$$

The absolute maximum rating for the INTV_{CC} Pin is 40mA. Dissipation should be calculated to also include any added current drawn from the internal 3.3V linear regulator. To prevent maximum junction temperature from being exceeded, the input supply current must be checked operating in continuous mode at maximum V_{IN}.

EXTV_{CC} Connection

The IC contains an internal P-channel MOSFET switch connected between the EXTV_{CC} and INTV_{CC} pins. When the voltage applied to EXTV_{CC} rises above 4.7V, the internal regulator is turned off and the switch closes, connecting the EXTV_{CC} pin to the INTV_{CC} pin thereby supplying internal power. The switch remains closed as long as the voltage applied to EXTV_{CC} remains above 4.5V. This allows the MOSFET driver and control power to be derived from the output during normal operation (4.7V < V_{OUT} < 7V) and from the internal regulator when the output is out of regulation (start-up, short-circuit). If more current is required through the EXTV_{CC} switch than is specified, an external Schottky diode can be added between the EXTV_{CC} and INTV_{CC} pins. Do not apply greater than 7V to the EXTV_{CC} pin and ensure that EXTV_{CC} ≤ V_{IN}.

Significant efficiency gains can be realized by powering INTV_{CC} from the output, since the V_{IN} current resulting from the driver and control currents will be scaled by a factor of (Duty Cycle)/(Efficiency). For 5V regulators this supply means connecting the EXTV_{CC} pin directly to V_{OUT}. However, for 3.3V and other lower voltage regulators, additional circuitry is required to derive INTV_{CC} power from the output.

The following list summarizes the four possible connections for EXTV_{CC}:

1. EXTV_{CC} Left Open (or Grounded). This will cause INTV_{CC} to be powered from the internal 5V regulator resulting in an efficiency penalty of up to 10% at high input voltages.

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stage is biased with internal resistors from an internal 2.4V source as shown in the Functional Diagram. This requires that current either be sourced or sunk from the SENSE pins depending on the output voltage. If the output voltage is below 2.4V current will flow out of both SENSE pins to the main output. The output can be easily preloaded by the V_{OUT} resistive divider to compensate for the current comparator's negative input bias current. The maximum current flowing out of each pair of SENSE pins is:

$$I_{SENSE^+} + I_{SENSE^-} = (2.4V - V_{OUT})/24k$$

Since V_{OSENSE} is servoed to the 0.8V reference voltage, we can choose R1 in Figure 2 to have a maximum value to absorb this current.

$$R1_{(MAX)} = 24k \left(\frac{0.8V}{2.4V - V_{OUT}} \right)$$

for $V_{OUT} < 2.4V$

Regulating an output voltage of 1.8V, the maximum value of R1 should be 32k. Note that for an output voltage above 2.4V, R1 has no maximum value necessary to absorb the sense currents; however, R1 is still bounded by the V_{OSENSE} feedback current.

Soft-Start/Run Function

The RUN/SS1 and RUN/SS2 pins are multipurpose pins that provide a soft-start function and a means to shut down the LTC3728L-1. Soft-start reduces the input power source's surge currents by gradually increasing the controller's current limit (proportional to V_{ITH}). This pin can also be used for power supply sequencing.

An internal 1.2 μ A current source charges up the C_{SS} capacitor. When the voltage on RUN/SS1 (RUN/SS2) reaches 1.5V, the particular controller is permitted to start operating. As the voltage on RUN/SS increases from 1.5V to 3.0V, the internal current limit is increased from 25mV/ R_{SENSE} to 75mV/ R_{SENSE} . The output current limit ramps up slowly,

taking an additional 1.25s/ μ F to reach full current. The output current thus ramps up slowly, reducing the starting surge current required from the input power supply. If RUN/SS has been pulled all the way to ground there is a delay before starting of approximately:

$$t_{DELAY} = \frac{1.5V}{1.2\mu A} C_{SS} = (1.25s / \mu F) C_{SS}$$

$$t_{IRAMP} = \frac{3V - 1.5V}{1.2\mu A} C_{SS} = (1.25s / \mu F) C_{SS}$$

By pulling both RUN/SS pins below 1V, the IC is put into low current shutdown ($I_Q = 20\mu A$). The RUN/SS pins can be driven directly from logic as shown in Figure 7. Diode D1 in Figure 7 reduces the start delay but allows C_{SS} to ramp up slowly providing the soft-start function. Each RUN/SS pin has an internal 6V zener clamp (See Functional Diagram). Because the LTC3728L-1 is designed for applications not requiring over current latchoff, no pull-up resistor is required on the RUN/SS pin to defeat latchoff. Refer to the LTC3728L/LTC3728LX datasheet if this feature is required.

Fault Conditions: Current Limit and Current Foldback

The current comparators have a maximum sense voltage of 75mV resulting in a maximum MOSFET current of 75mV/ R_{SENSE} . The maximum value of current limit generally occurs with the largest V_{IN} at the highest ambi-

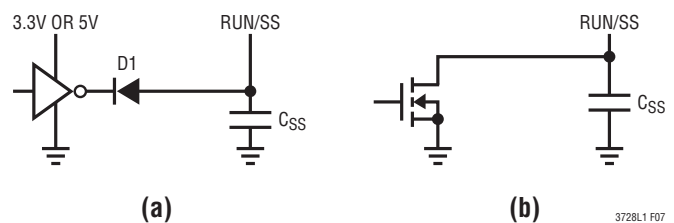


Figure 7. RUN/SS Pin Interfacing

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ent temperature, conditions that cause the highest power dissipation in the top MOSFET.

Each controller includes current foldback to help further limit load current when the output is shorted to ground. The foldback circuit is active even when the overload shutdown latch described above is overridden. If the output falls below 70% of its nominal output level, then the maximum sense voltage is progressively lowered from 75mV to 17mV. Under short-circuit conditions with very low duty cycles, the controller will begin cycle skipping in order to limit the short-circuit current. In this situation the bottom MOSFET will be dissipating most of the power but less than in normal operation. The short-circuit ripple current is determined by the minimum on-time $t_{ON(MIN)}$ of each controller (typically 100ns), the input voltage and inductor value:

$$\Delta I_{L(SC)} = t_{ON(MIN)} (V_{IN}/L)$$

The resulting short-circuit current is:

$$I_{SC} = \frac{25mV}{R_{SENSE}} - \frac{1}{2} \Delta I_{L(SC)}$$

Fault Conditions: Overvoltage Protection (Crowbar)

The overvoltage crowbar is designed to blow a system input fuse when the output voltage of the regulator rises much higher than nominal levels. The crowbar causes huge currents to flow, that blow the fuse to protect against a shorted top MOSFET if the short occurs while the controller is operating.

A comparator monitors the output for overvoltage conditions. The comparator (OV) detects overvoltage faults greater than 7.5% above the nominal output voltage. When this condition is sensed, the top MOSFET is turned off and the bottom MOSFET is turned on until the overvoltage condition is cleared. The output of this comparator is

only latched by the overvoltage condition itself and will therefore allow a switching regulator system having a poor PC layout to function while the design is being debugged. The bottom MOSFET remains on continuously for as long as the OV condition persists; if V_{OUT} returns to a safe level, normal operation automatically resumes. A shorted top MOSFET will result in a high current condition which will open the system fuse. The switching regulator will regulate properly with a leaky top MOSFET by altering the duty cycle to accommodate the leakage.

Phase-Locked Loop and Frequency Synchronization

The IC has a phase-locked loop comprised of an internal voltage controlled oscillator and phase detector. This allows the top MOSFET turn-on to be locked to the rising edge of an external source. The frequency range of the voltage controlled oscillator is $\pm 50\%$ around the center frequency f_0 . A voltage of 1.2V applied to the PLLFLTR pin corresponds to a frequency of approximately 400kHz. The nominal operating frequency range of the IC is 260kHz to 550kHz.

The phase detector used is an edge sensitive digital type which provides zero degrees phase shift between the external and internal oscillators. This type of phase detector will not lock up on input frequencies close to the harmonics of the VCO center frequency. The PLL hold-in range, Δf_H , is equal to the capture range, Δf_C :

$$\Delta f_H = \Delta f_C = \pm 0.5 f_0 \text{ (260kHz-550kHz)}$$

The output of the phase detector is a complementary pair of current sources charging or discharging the external filter network on the PLLFLTR pin.

If the external frequency (f_{PLLIN}) is greater than the oscillator frequency f_{OSC} , current is sourced continuously,

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pulling up the PLLFLTR pin. When the external frequency is less than f_{OSC} , current is sunk continuously, pulling down the PLLFLTR pin. If the external and internal frequencies are the same but exhibit a phase difference, the current sources turn on for an amount of time corresponding to the phase difference. Thus the voltage on the PLLFLTR pin is adjusted until the phase and frequency of the external and internal oscillators are identical. At this stable operating point the phase comparator output is open and the filter capacitor C_{LP} holds the voltage. The IC's PLLIN pin must be driven from a low impedance source such as a logic gate located close to the pin. When using multiple ICs for a phase-locked system, the PLLFLTR pin of the master oscillator should be biased at a voltage that will guarantee the slave oscillator(s) ability to lock onto the master's frequency. A DC voltage of 0.7V to 1.7V applied to the master oscillator's PLLFLTR pin is recommended in order to meet this requirement. The resultant operating frequency can range from 300kHz to 500kHz.

The loop filter components (C_{LP} , R_{LP}) smooth out the current pulses from the phase detector and provide a stable input to the voltage controlled oscillator. The filter components C_{LP} and R_{LP} determine how fast the loop acquires lock. Typically $R_{LP} = 10k\Omega$ and C_{LP} is 0.01 μ F to 0.1 μ F.

Minimum On-Time Considerations

Minimum on-time $t_{ON(MIN)}$ is the smallest time duration that each controller is capable of turning on the top MOSFET. It is determined by internal timing delays and the gate charge required to turn on the top MOSFET. Low duty cycle applications may approach this minimum on-time limit and care should be taken to ensure that

$$t_{ON(MIN)} < \frac{V_{OUT}}{V_{IN}(f)}$$

If the duty cycle falls below what can be accommodated by the minimum on-time, the controller will begin to skip cycles. The output voltage will continue to be regulated, but the ripple voltage and current will increase.

The minimum on-time for each controller is approximately 100ns. However, as the peak sense voltage decreases the minimum on-time gradually increases up to about 150ns. This is of particular concern in forced continuous applications with low ripple current at light loads. If the duty cycle drops below the minimum on-time limit in this situation, a significant amount of cycle skipping can occur with correspondingly larger current and voltage ripple.

FCB Pin Operation

The FCB pin can be used to regulate a secondary winding or as a logic level input. Continuous operation is forced on both controllers when the FCB pin drops below 0.8V. During continuous mode, current flows continuously in the transformer primary. The secondary winding(s) draw current only when the bottom, synchronous switch is on. When primary load currents are low and/or the V_{IN}/V_{OUT} ratio is low, the synchronous switch may not be on for a sufficient amount of time to transfer power from the output capacitor to the secondary load. Forced continuous operation will support secondary windings providing there is sufficient synchronous switch duty factor. Thus, the FCB input pin removes the requirement that power must be drawn from the inductor primary in order to extract power from the auxiliary windings. With the loop in continuous mode, the auxiliary outputs may nominally be loaded without regard to the primary output load.

The secondary output voltage V_{SEC} is normally set as shown in Figure 6a by the turns ratio N of the transformer:

$$V_{SEC} \cong (N + 1) V_{OUT}$$

However, if the controller goes into Burst Mode operation and halts switching due to a light primary load current, then V_{SEC} will droop. An external resistive divider from V_{SEC} to the FCB pin sets a minimum voltage $V_{SEC(MIN)}$:

$$V_{SEC(MIN)} \approx 0.8V \left(1 + \frac{R6}{R5} \right)$$

where $R5$ and $R6$ are shown in Figure 2.

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If V_{SEC} drops below this level, the FCB voltage forces temporary continuous switching operation until V_{SEC} is again above its minimum.

In order to prevent erratic operation if no external connections are made to the FCB pin, the FCB pin has a 0.18 μ A internal current source pulling the pin high. Include this current when choosing resistor values R5 and R6.

The following table summarizes the possible states available on the FCB pin:

Table 1

FCB PIN	CONDITION
0V to 0.75V	Forced Continuous Both Controllers (Current Reversal Allowed— Burst Inhibited)
$0.85V < V_{FCB} < 4.3V$	Minimum Peak Current Induces Burst Mode Operation No Current Reversal Allowed
Feedback Resistors	Regulating a Secondary Winding
$> 4.8V$	Burst Mode Operation Disabled Constant Frequency Mode Enabled No Current Reversal Allowed No Minimum Peak Current

Voltage Positioning

Voltage positioning can be used to minimize peak-to-peak output voltage excursions under worst-case transient loading conditions. The open-loop DC gain of the control loop is reduced depending upon the maximum load step specifications. Voltage positioning can easily be added to either or both controllers by loading the I_{TH} pin with a resistive divider having a Thevenin equivalent voltage source equal to the midpoint operating voltage range of the error amplifier, or 1.2V (see Figure 8).

The resistive load reduces the DC loop gain while maintaining the linear control range of the error amplifier. The maximum output voltage deviation can theoretically be reduced to half or alternatively the amount of output

capacitance can be reduced for a particular application. A complete explanation is included in Design Solutions 10. (See www.linear.com)

Efficiency Considerations

The percent efficiency of a switching regulator is equal to the output power divided by the input power times 100%. It is often useful to analyze individual losses to determine what is limiting the efficiency and which change would produce the most improvement. Percent efficiency can be expressed as:

$$\% \text{Efficiency} = 100\% - (L1 + L2 + L3 + \dots)$$

where L1, L2, etc. are the individual losses as a percent-

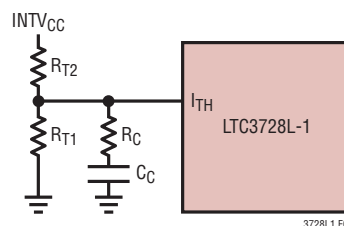


Figure 8. Active Voltage Positioning Applied to the LTC3728L-1

age of input power.

Although all dissipative elements in the circuit produce losses, four main sources usually account for most of the losses in LTC3728L-1 circuits: 1) IC V_{IN} current (including loading on the 3.3V internal regulator), 2) $INTV_{CC}$ regulator current, 3) I^2R losses, 4) Topside MOSFET transition losses.

1. The V_{IN} current has two components: the first is the DC supply current given in the Electrical Characteristics table, which excludes MOSFET driver and control currents; the second is the current drawn from the 3.3V linear regulator output. V_{IN} current typically results in a small ($< 0.1\%$) loss.

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2. $INTV_{CC}$ current is the sum of the MOSFET driver and control currents. The MOSFET driver current results from switching the gate capacitance of the power MOSFETs. Each time a MOSFET gate is switched from low to high to low again, a packet of charge dQ moves from $INTV_{CC}$ to ground. The resulting dQ/dt is a current out of $INTV_{CC}$ that is typically much larger than the control circuit current. In continuous mode, $I_{GATECHG} = f(Q_T + Q_B)$, where Q_T and Q_B are the gate charges of the topside and bottom side MOSFETs.

Supplying $INTV_{CC}$ power through the $EXTV_{CC}$ switch input from an output-derived source will scale the V_{IN} current required for the driver and control circuits by a factor of (Duty Cycle)/(Efficiency). For example, in a 20V to 5V application, 10mA of $INTV_{CC}$ current results in approximately 2.5mA of V_{IN} current. This reduces the mid-current loss from 10% or more (if the driver was powered directly from V_{IN}) to only a few percent.

3. I^2R losses are predicted from the DC resistances of the fuse (if used), MOSFET, inductor, current sense resistor, and input and output capacitor ESR. In continuous mode the average output current flows through L and R_{SENSE} , but is “chopped” between the topside MOSFET and the synchronous MOSFET. If the two MOSFETs have approximately the same $R_{DS(ON)}$, then the resistance of one MOSFET can simply be summed with the resistances of L , R_{SENSE} and ESR to obtain I^2R losses. For example, if each $R_{DS(ON)} = 30m\Omega$, $R_L = 50m\Omega$, $R_{SENSE} = 10m\Omega$ and $R_{ESR} = 40m\Omega$ (sum of both input and output capacitance losses), then the total resistance is 130m Ω . This results in losses ranging from 3% to 13% as the output current increases from 1A to 5A for a 5V output, or a 4% to 20% loss for a 3.3V output. Efficiency varies as the inverse square of V_{OUT} for the same external components and output power level. The combined effects of increasingly lower output voltages and higher currents required by high performance digital systems is not doubling but quadrupling the importance of loss terms in the switching regulator system!

4. Transition losses apply only to the topside MOSFET(s), and become significant only when operating at high input

voltages (typically 15V or greater). Transition losses can be estimated from:

$$\text{Transition Loss} = (V_{IN})^2 \cdot \left(\frac{I_{MAX}}{2} \right) (R_{DR}) \cdot (C_{MILLER})(f) \left(\frac{1}{5V - V_{TH}} + \frac{1}{V_{TH}} \right)$$

Other “hidden” losses such as copper trace and internal battery resistances can account for an additional 5% to 10% efficiency degradation in portable systems. It is very important to include these “system” level losses during the design phase. The internal battery and fuse resistance losses can be minimized by making sure that C_{IN} has adequate charge storage and very low ESR at the switching frequency. A 25W supply will typically require a minimum of 20 μ F to 40 μ F of capacitance having a maximum of 20m Ω to 50m Ω of ESR. The LTC3728L-1 2-phase architecture typically halves this input capacitance requirement over competing solutions. Other losses including Schottky conduction losses during dead-time and inductor core losses generally account for less than 2% total additional loss.

Checking Transient Response

The regulator loop response can be checked by looking at the load current transient response. Switching regulators take several cycles to respond to a step in DC (resistive) load current. When a load step occurs, V_{OUT} shifts by an amount equal to ΔI_{LOAD} (ESR), where ESR is the effective series resistance of C_{OUT} . ΔI_{LOAD} also begins to charge or discharge C_{OUT} generating the feedback error signal that forces the regulator to adapt to the current change and return V_{OUT} to its steady-state value. During this recovery time V_{OUT} can be monitored for excessive overshoot or ringing, which would indicate a stability problem. OPTI-LOOP compensation allows the transient response to be optimized over a wide range of output capacitance and ESR values. *The availability of the I_{TH} pin not only allows optimization of control loop behavior but also provides a DC coupled and AC filtered closed loop response test point. The DC step, rise time and settling*

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at this test point truly reflects the closed loop response. Assuming a predominantly second order system, phase margin and/or damping factor can be estimated using the percentage of overshoot seen at this pin. The bandwidth can also be estimated by examining the rise time at the pin. The I_{TH} external components shown in the Figure 1 circuit will provide an adequate starting point for most applications.

The I_{TH} series R_C - C_C filter sets the dominant pole-zero loop compensation. The values can be modified slightly (from 0.5 to 2 times their suggested values) to optimize transient response once the final PC layout is done and the particular output capacitor type and value have been determined. The output capacitors need to be selected because the various types and values determine the loop gain and phase. An output current pulse of 20% to 80% of full-load current having a rise time of 1 μ s to 10 μ s will produce output voltage and I_{TH} pin waveforms that will give a sense of the overall loop stability without breaking the feedback loop. Placing a power MOSFET directly across the output capacitor and driving the gate with an appropriate signal generator is a practical way to produce a realistic load step condition. The initial output voltage step resulting from the step change in output current may not be within the bandwidth of the feedback loop, so this signal cannot be used to determine phase margin. This is why it is better to look at the I_{TH} pin signal which is in the feedback loop and is the filtered and compensated control loop response. The gain of the loop will be increased by increasing R_C and the bandwidth of the loop will be increased by decreasing C_C . If R_C is increased by the same factor that C_C is decreased, the zero frequency will be kept the same, thereby keeping the phase shift the same in the most critical frequency range of the feedback loop. The output voltage settling behavior is related to the stability of the closed-loop system and will demonstrate the actual overall supply performance.

A second, more severe transient is caused by switching in loads with large (>1 μ F) supply bypass capacitors. The discharged bypass capacitors are effectively put in parallel with C_{OUT} , causing a rapid drop in V_{OUT} . No regulator can alter its delivery of current quickly enough to prevent this sudden step change in output voltage if the load switch resistance is low and it is driven quickly. If the ratio of

C_{LOAD} to C_{OUT} is greater than 1:50, the switch rise time should be controlled so that the load rise time is limited to approximately $25 \cdot C_{LOAD}$. Thus a 10 μ F capacitor would require a 250 μ s rise time, limiting the charging current to about 200mA.

Automotive Considerations: Plugging into the Cigarette Lighter

As battery-powered devices go mobile, there is a natural interest in plugging into the cigarette lighter in order to conserve or even recharge battery packs during operation. But before you connect, be advised: you are plugging into the supply from hell. The main power line in an automobile is the source of a number of nasty potential transients, including load-dump, reverse-battery, and double-battery.

Load-dump is the result of a loose battery cable. When the cable breaks connection, the field collapse in the alternator can cause a positive spike as high as 60V which takes several hundred milliseconds to decay. Reverse-battery is just what it says, while double-battery is a consequence of tow-truck operators finding that a 24V jump start cranks cold engines faster than 12V.

The network shown in Figure 9 is the most straightforward approach to protect a DC/DC converter from the ravages of an automotive power line. The series diode prevents current from flowing during reverse-battery, while the transient suppressor clamps the input voltage during load-dump. Note that the transient suppressor should not conduct during double-battery operation, but must still clamp the input voltage below breakdown of the converter. Although the LTC3728L-1 has a maximum input voltage of 30V, most applications will also be limited to 30V by the MOSFET BVD_{SS} .

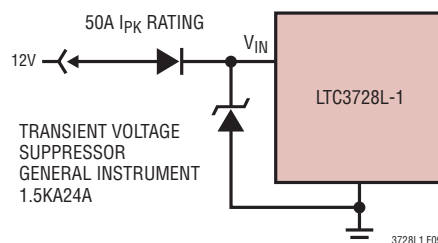


Figure 9. Automotive Application Protection

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Design Example

As a design example for one channel, assume $V_{IN} = 12V$ (nominal), $V_{IN} = 22V$ (max), $V_{OUT} = 1.8V$, $I_{MAX} = 5A$, and $f = 300kHz$.

The inductance value is chosen first based on a 30% ripple current assumption. The highest value of ripple current occurs at the maximum input voltage. Tie the PLLFLTR pin to a resistive divider from the INTV_{CC} pin, generating 0.7V for 300kHz operation. The minimum inductance for 30% ripple current is:

$$L \geq \frac{V_{IN} - V_{OUT}}{(f)(I_{RIPPLE})} \cdot \frac{V_{OUT}}{V_{IN}}$$

or 3.7μH. Using standard inductor values:

$$\Delta I_L = \frac{V_{OUT}}{(f)(L)} \left(1 - \frac{V_{OUT}}{V_{IN}} \right)$$

A 4.7μH inductor will produce 23% ripple current and a 3.3μH will result in 33%. The peak inductor current will be the maximum DC value plus one half the ripple current, or 5.84A, for the 3.3μH value. Increasing the ripple current will also help ensure that the minimum on-time of 100ns is not violated. The minimum on-time occurs at maximum V_{IN} :

$$t_{ON(MIN)} = \frac{V_{OUT}}{V_{IN(MAX)}f} = \frac{1.8V}{22V(300kHz)} = 273ns$$

The R_{SENSE} resistor value can be calculated by using the maximum current sense voltage specification with some accommodation for tolerances:

$$R_{SENSE} \leq \frac{60mV}{5.84A} \approx 0.01\Omega$$

Since the output voltage is below 2.4V the output resistive divider will need to be sized to not only set the output voltage but also to absorb the SENSE pin's specified input current.

$$\begin{aligned} R1_{(MAX)} &= 24k \left(\frac{0.8V}{2.4V - V_{OUT}} \right) \\ &= 24k \left(\frac{0.8V}{2.4V - 1.8V} \right) = 32k \end{aligned}$$

Choosing 1% resistors: $R1 = 25.5k$ and $R2 = 32.4k$ yields an output voltage of 1.816V.

The power dissipation on the top side MOSFET can be easily estimated. Choosing a Fairchild FDS6982S dual MOSFET results in: $R_{DS(ON)} = 0.035\Omega/0.022\Omega$, $C_{MILLER} = 215pF$. At maximum input voltage with T (estimated) = 50°C:

$$\begin{aligned} P_{MAIN} &= \frac{1.8V}{22V} (5)^2 [1 + (0.005)(50^\circ C - 25^\circ C)] \cdot \\ &(0.035\Omega) + (22V)^2 \left(\frac{5A}{2} \right) (4\Omega) (215pF) \cdot \\ &\left[\frac{1}{5 - 2.3} + \frac{1}{2.3} \right] (300kHz) = 332mW \end{aligned}$$

A short-circuit to ground will result in a folded back current of:

$$I_{SC} = \frac{25mV}{0.01\Omega} - \frac{1}{2} \left(\frac{120ns(22V)}{3.3\mu H} \right) = 2.1A$$

with a typical value of $R_{DS(ON)}$ and $\delta = (0.005/^\circ C)(20) = 0.1$. The resulting power dissipated in the bottom MOSFET is:

$$\begin{aligned} P_{SYNC} &= \frac{22V - 1.8V}{22V} (2.1A)^2 (1.125)(0.022\Omega) \\ &= 100mW \end{aligned}$$

which is less than under full-load conditions.

C_{IN} is chosen for an RMS current rating of at least 3A at temperature assuming only this channel is on. C_{OUT} is chosen with an ESR of 0.02Ω for low output ripple. The output ripple in continuous mode will be highest at the

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maximum input voltage. The output voltage ripple due to ESR is approximately:

$$V_{ORIPPLE} = R_{ESR} (\Delta I_L) = 0.02\Omega(1.67A) = 33mV_{P-P}$$

PC Board Layout Checklist

When laying out the printed circuit board, the following checklist should be used to ensure proper operation of the IC. These items are also illustrated graphically in the layout diagram of Figure 10. The Figure 11 illustrates the current waveforms present in the various branches of the 2-phase synchronous regulators operating in the continuous mode. Check the following in your layout:

1. Are the top N-channel MOSFETs M1 and M3 located within 1cm of each other with a common drain connection

at C_{IN} ? Do not attempt to split the input decoupling for the two channels as it can cause a large resonant loop.

2. Are the signal and power grounds kept separate? The combined IC signal ground pin and the ground return of C_{INTVCC} must return to the combined $C_{OUT} (-)$ terminals. The path formed by the top N-channel MOSFET, Schottky diode and the C_{IN} capacitor should have short leads and PC trace lengths. The output capacitor $(-)$ terminals of the input capacitor by placing the capacitors next to each other and away from the Schottky loop described above.

3. Do the LTC3728L-1 V_{OSENSE} pins' resistive dividers connect to the $(+)$ terminals of C_{OUT} ? The resistive divider must

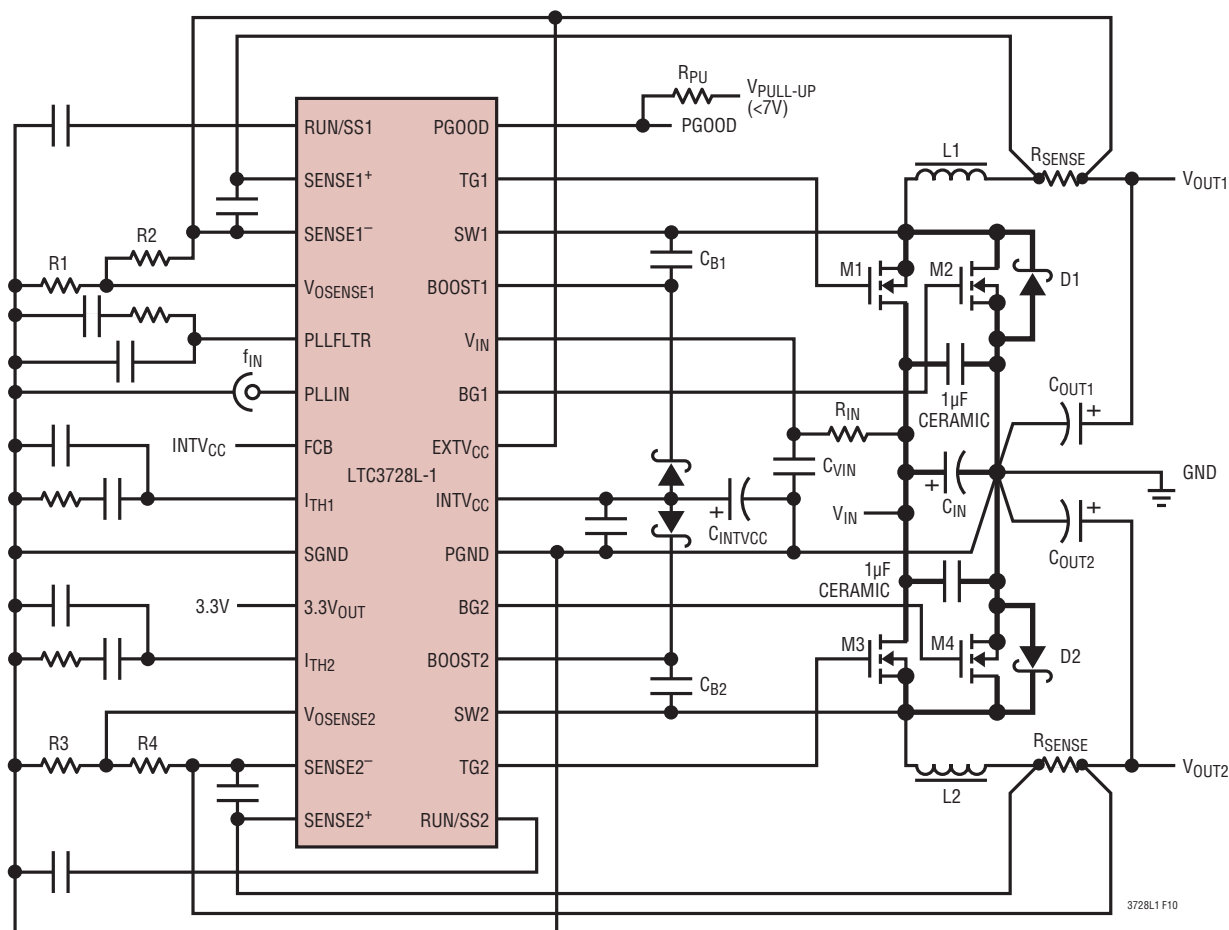


Figure 10. LTC3728L-1 Recommended Printed Circuit Layout Diagram

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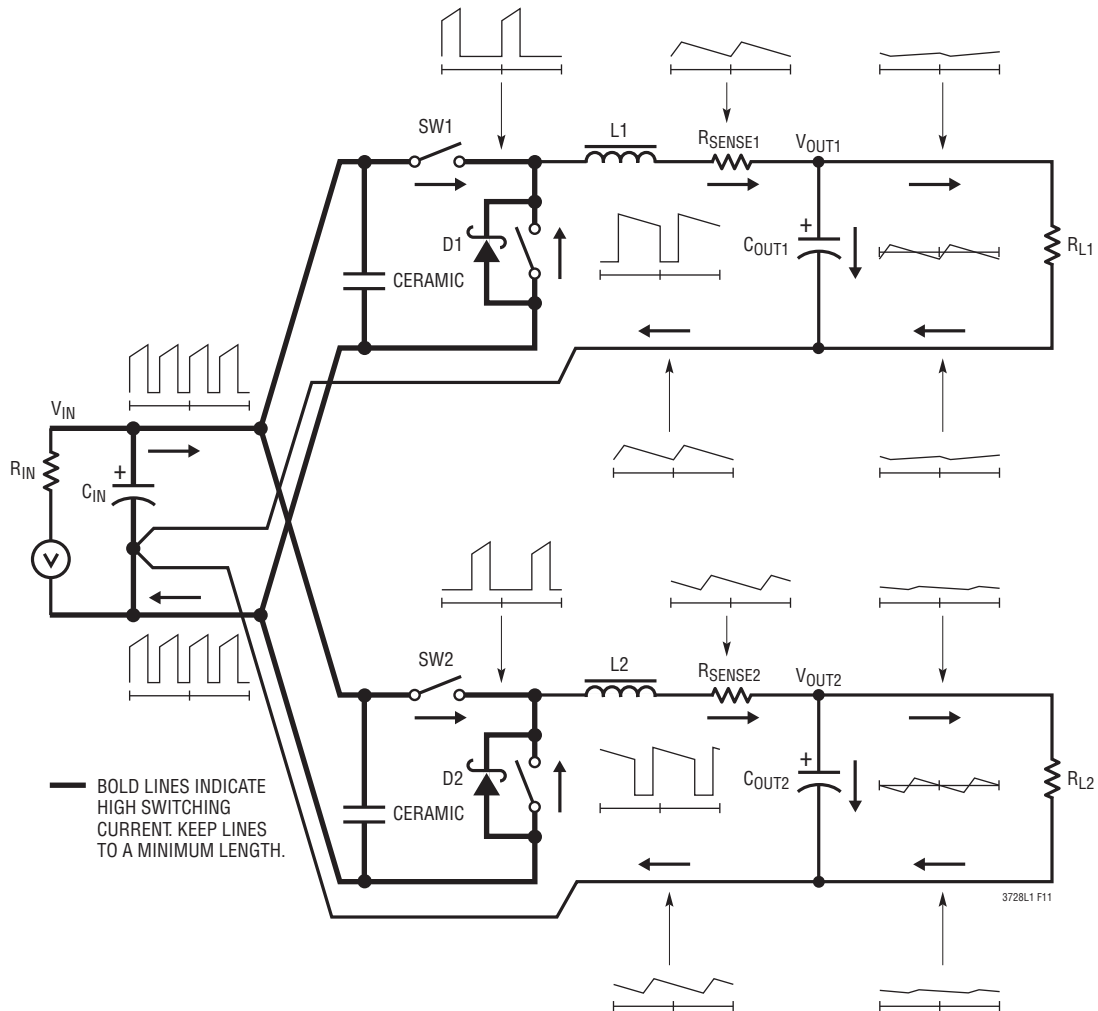


Figure 11. Branch Current Waveforms

be connected between the (+) terminal of C_{OUT} and signal ground. The R2 and R4 connections should not be along the high current input feeds from the input capacitor(s).

4. Are the SENSE⁻ and SENSE⁺ leads routed together with minimum PC trace spacing? The filter capacitor between SENSE⁺ and SENSE⁻ should be as close as possible to the IC. Ensure accurate current sensing with Kelvin connections at the SENSE resistor.

5. Is the INTV_{CC} decoupling capacitor connected close to the IC, between the INTV_{CC} and the power ground pins?

This capacitor carries the MOSFET drivers current peaks. An additional 1 μ F ceramic capacitor placed immediately next to the INTV_{CC} and PGND pins can help improve noise performance substantially.

6. Keep the switching nodes (SW1, SW2), top gate nodes (TG1, TG2), and boost nodes (BOOST1, BOOST2) away from sensitive small-signal nodes, especially from the opposites channel's voltage and current sensing feedback pins. All of these nodes have very large and fast moving signals and therefore should be kept on the "output side" of the LTC3728L-1 and occupy minimum PC trace area.

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7. Use a modified “star ground” technique: a low impedance, large copper area central grounding point on the same side of the PC board as the input and output capacitors with tie-ins for the bottom of the $INTV_{CC}$ decoupling capacitor, the bottom of the voltage feedback resistive divider and the SGND pin of the IC.

PC Board Layout Debugging

Start with one controller on at a time. It is helpful to use a DC-50MHz current probe to monitor the current in the inductor while testing the circuit. Monitor the output switching node (SW pin) to synchronize the oscilloscope to the internal oscillator and probe the actual output voltage as well. Check for proper performance over the operating voltage and current range expected in the application. The frequency of operation should be maintained over the input voltage range down to dropout and until the output load drops below the low current operation threshold—typically 10% to 20% of the maximum designed current level in Burst Mode operation.

The duty cycle percentage should be maintained from cycle to cycle in a well-designed, low noise PCB implementation. Variation in the duty cycle at a subharmonic rate can suggest noise pickup at the current or voltage sensing inputs or inadequate loop compensation. Overcompensation of the loop can be used to tame a poor PC layout if regulator bandwidth optimization is not required. Only after each controller is checked for its individual performance should both controllers be turned on at the same time. A particularly difficult region of operation is when one controller channel is nearing its current comparator trip point when the other channel is turning on its top MOSFET. This occurs around 50% duty cycle on either channel due

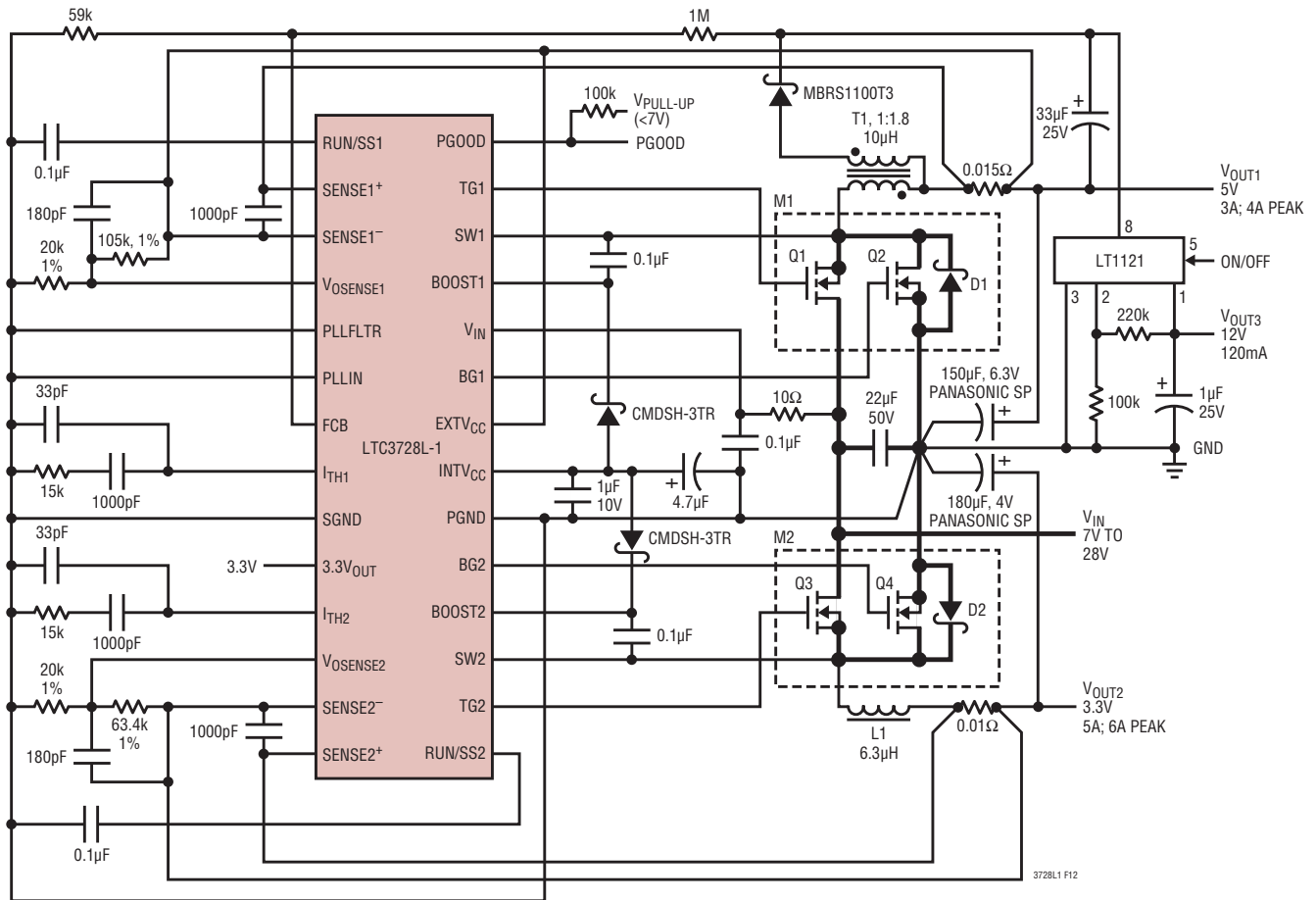
to the phasing of the internal clocks and may cause minor duty cycle jitter.

Reduce V_{IN} from its nominal level to verify operation of the regulator in dropout. Check the operation of the undervoltage lockout circuit by further lowering V_{IN} while monitoring the outputs to verify operation.

Investigate whether any problems exist only at higher output currents or only at higher input voltages. If problems coincide with high input voltages and low output currents, look for capacitive coupling between the BOOST, SW, TG, and possibly BG connections and the sensitive voltage and current pins. The capacitor placed across the current sensing pins needs to be placed immediately adjacent to the pins of the IC. This capacitor helps to minimize the effects of differential noise injection due to high frequency capacitive coupling. If problems are encountered with high current output loading at lower input voltages, look for inductive coupling between C_{IN} , Schottky and the top MOSFET components to the sensitive current and voltage sensing traces. In addition, investigate common ground path voltage pickup between these components and the SGND pin of the IC.

An embarrassing problem, which can be missed in an otherwise properly working switching regulator, results when the current sensing leads are hooked up backwards. The output voltage under this improper hookup will still be maintained but the advantages of current mode control will not be realized. Compensation of the voltage loop will be much more sensitive to component selection. This behavior can be investigated by temporarily shorting out the current sensing resistor—don't worry, the regulator will still maintain control of the output voltage.

TYPICAL APPLICATIONS



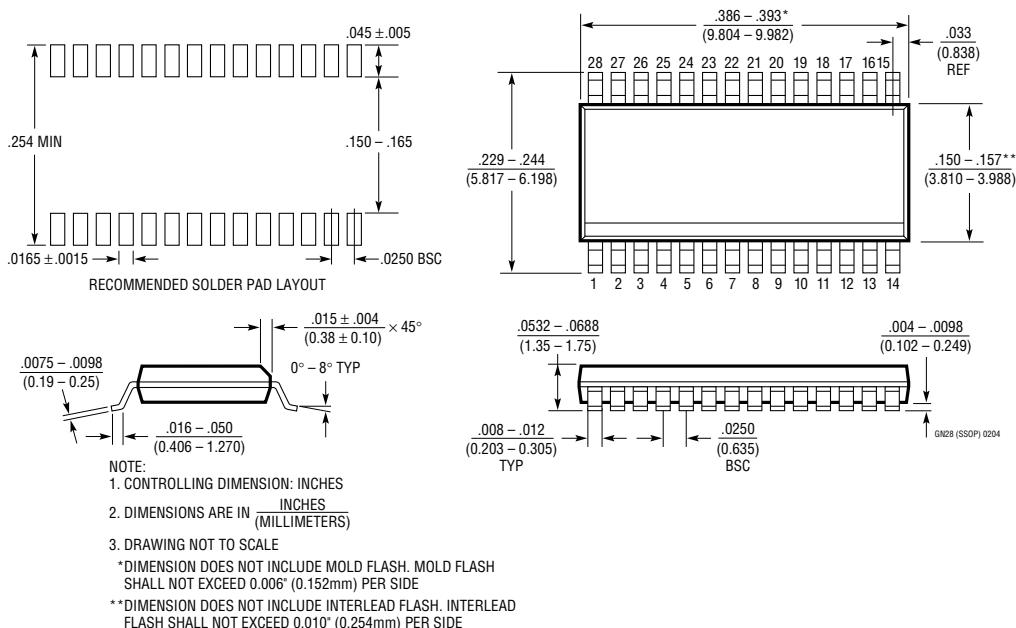
V_{IN} : 7V TO 28V
 V_{OUT} : 5V, 3A/3.3V, 6A/12V, 150mA
 SWITCHING FREQUENCY = 250kHz
 M1, M2: FDS6982S OR VISHAY Si4810DY
 L1: SUMIDA CEP123-6R3MC
 T1: 10μH 1:1.8 — DALE LPE6562-A262 GAPPED E-CORE OR BH ELECTRONICS #501-0657 GAPPED TOROID

Figure 12. LTC3728L-1 High Efficiency Low Noise 5V/3A, 3.3V/5A, 12V/120mA Regulator

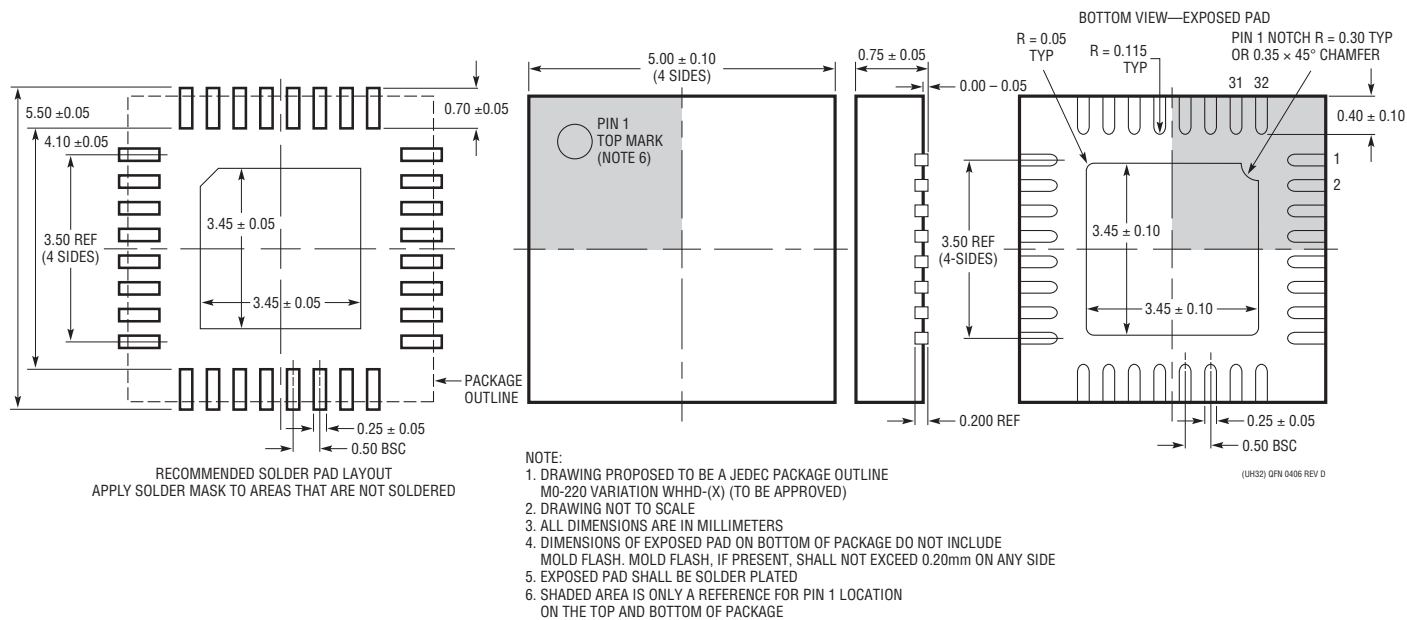


PACKAGE DESCRIPTION

GN Package 28-Lead Plastic SSOP (Narrow .150 Inch) (Reference LTC DWG # 05-08-1641)



UH Package 32-Lead Plastic QFN (5mm × 5mm) (Reference LTC DWG # 05-08-1693 Rev D)



TYPICAL APPLICATION

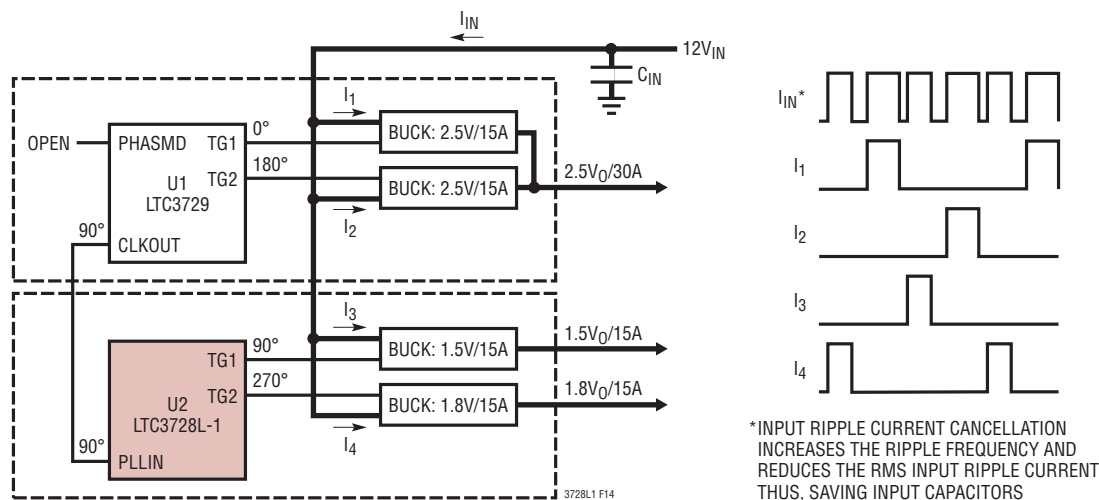


Figure 14. Multioutput PolyPhase Application

RELATED PARTS

PART NUMBER	DESCRIPTION	COMMENTS
LTC1628/LTC1628-PG/ LTC1628-SYNC	2-Phase, Dual Output Synchronous Step-Down DC/DC Controller	Reduces C_{IN} and C_{OUT} , Power Good Output Signal, Synchronizable, $3.5V \leq V_{IN} \leq 36V$, I_{OUT} up to 20A, $0.8V \leq V_{OUT} \leq 5V$
LTC1629/ LTC1629-PG	20A to 200A PolyPhase™ Synchronous Controllers	Expandable from 2-Phase to 12-Phase, Uses All Surface Mount Components, No Heat Sink, V_{IN} up to 36V
LTC1708-PG	2-Phase, Dual Synchronous Controller with Mobile VID	$3.5V \leq V_{IN} \leq 36V$, VID Sets V_{OUT1} , PG00D
LT1709/ LT1709-8	High Efficiency, 2-Phase Synchronous Step-Down Switching Regulators with 5-Bit VID	$1.3V \leq V_{OUT} \leq 3.5V$, Current Mode Ensures Accurate Current Sharing, $3.5V \leq V_{IN} \leq 36V$
LTC1735	High Efficiency Synchronous Step-Down Switching Regulator	Output Fault Protection, 16-Pin SSOP
LTC1736	High Efficiency Synchronous Controller with 5-Bit Mobile VID Control	Output Fault Protection, 24-Pin SSOP, $3.5V \leq V_{IN} \leq 36V$
LTC1778/LTC1778-1	No R_{SENSE} Current Mode Synchronous Step-Down Controllers	Up to 97% Efficiency, $4V \leq V_{IN} \leq 36V$, $0.8V \leq V_{OUT} \leq (0.9)(V_{IN})$, I_{OUT} up to 20A
LTC1929/ LTC1929-PG	2-Phase Synchronous Controllers	Up to 42A, Uses All Surface Mount Components, No Heat Sinks, $3.5V \leq V_{IN} \leq 36V$
LTC3708	Dual, 2-Phase, DC/DC Controller with Output Tracking	Current Mode, No R_{SENSE} , Up/Down Tracking, Synchronizable
LTC3711	No R_{SENSE} Current Mode Synchronous Step-Down Controller with Digital 5-Bit Interface	Up to 97% Efficiency, Ideal for Pentium® III Processors, $0.925V \leq V_{OUT} \leq 2V$, $4V \leq V_{IN} \leq 36V$, I_{OUT} up to 20A
LTC3728	Dual, 550kHz, 2-Phase Synchronous Step-Down Controller	Dual 180° Phased Controllers, V_{IN} 3.5V to 35V, 99% Duty Cycle, 5x5QFN, SSOP-28
LTC3729	20A to 200A, 550kHz PolyPhase Synchronous Controller	Expandable from 2-Phase to 12-Phase, Uses all Surface Mount Components, V_{IN} up to 36V
LTC3731	3- to 12-Phase Step-Down Synchronous Controller	60A to 240A Output Current, $0.6V \leq V_{OUT} \leq 6V$, $4.5V \leq V_{IN} \leq 32V$
LTC3802	No R_{SENSE} 2-Phase Dual Synchronous Step-Down Controller	330kHz to 750kHz, No Sense Resistor, Output Voltage Tracking, Synchronizable for 4-Phase Operation

No R_{SENSE} and PolyPhase are trademarks of Linear Technology Corporation.