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# HA13143

## Four-Channel BTL Driver for CD Players

# HITACHI

ADE-207-330 (Z)

1st Edition  
Dec. 2000

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### Description

HA13143 is a four-channel BTL driver IC for driving CD player actuators (focus and tracking) and motors (carriage and spindle). It is ideal for small-profile players, since it requires few external parts and adopts a compact, surface-mounting package (MP-26 DT).

### Functions

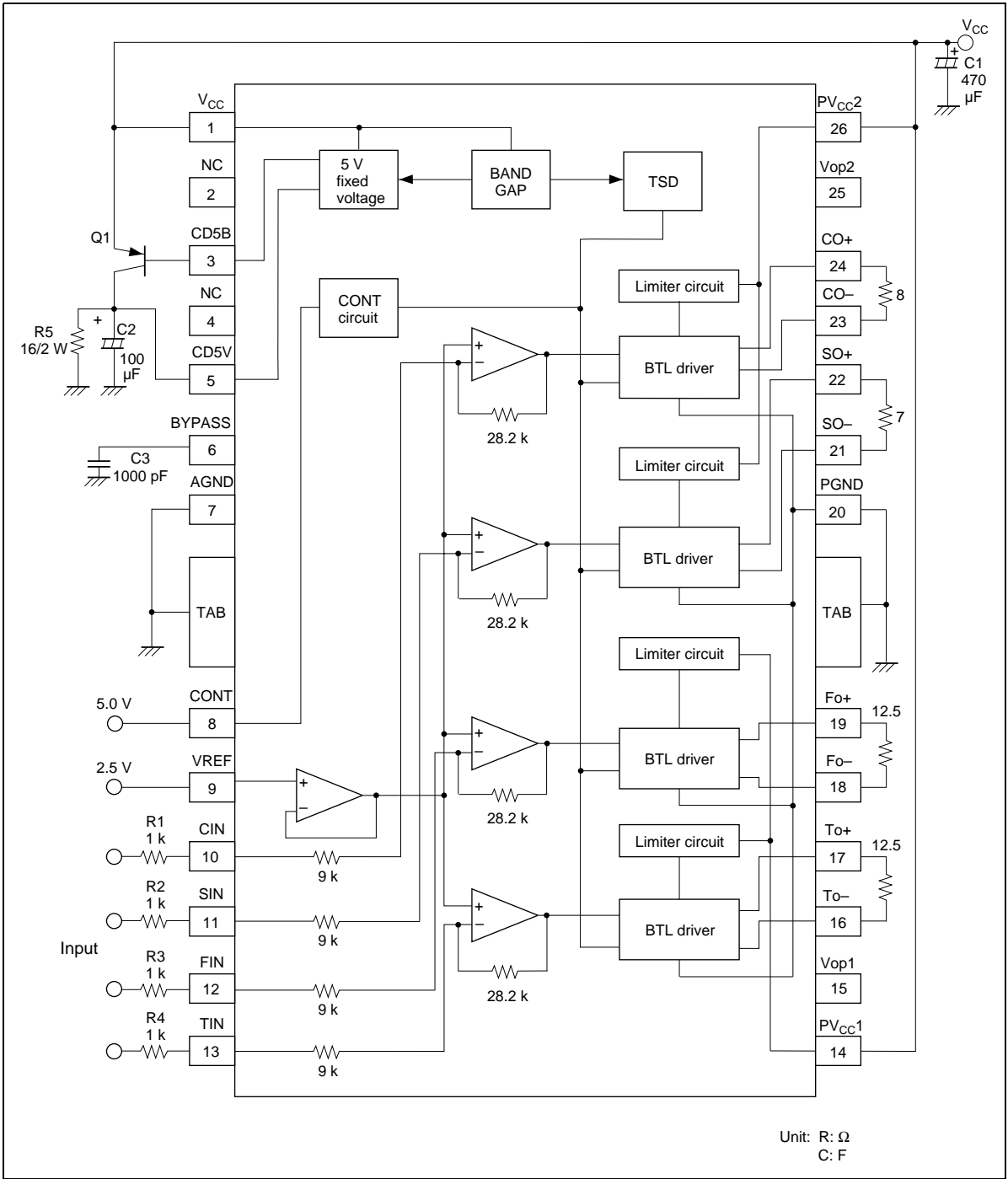
- 4-channel BTL driver
- 5 V power-supply circuit
- Standby circuit
- Built-in protection circuits (surge current, TSD)

### Features

- Four channels for driving the actuators and motors in a CD player
- High driving current
- Built-in protection against surge currents from other circuits or from short circuits
- Built-in thermal shutdown protection circuit with hysteresis
- Built-in 5 V power supply (uses external pnp transistor)
- Compact MP-26 DT surface-mounting package enabling use in small-profile players

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## Block Diagram



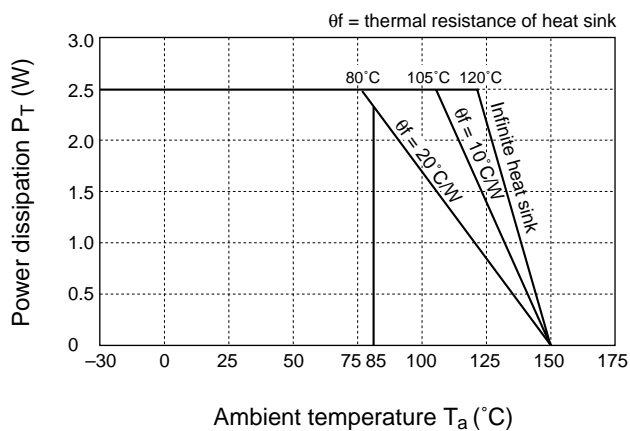
**Absolute Maximum Ratings** ( $T_a = 25^\circ\text{C}$ )

Item	Symbol	Rating	Unit	Remarks
Supply voltage	$V_{CC}$	18	V	
Output current	$I_o$ -Peak	See Note 1	A	1
Power dissipation	$P_T$	2.5	W	2
Operating temperature	$T_{opr}$	-30 to +85	$^\circ\text{C}$	
Storage temperature	$T_{stg}$	-55 to +125	$^\circ\text{C}$	
Junction temperature	$T_j$	150	$^\circ\text{C}$	

Notes: 1. Output current from each channel is as shown in table below.

	Focus	Tracking	Carriage	Spindle	Unit
Max. output current	1200	1200	1200	1400	mA

- In normal play mode.
- Usable operating voltage range  $V_{opr} = 7$  to  $10$  V.
- The derating curve is as shown in the graph below ( $\theta_{jc} = 8.0^\circ\text{C max.}$ ).



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## Electrical Characteristics (Ta = 25°C, V<sub>cc</sub> = 8.0 V)

Item	Symbol	Min	Typ	Max	Unit	Test Conditions	Applicable Pins
Output voltage with stable 5 V power supply	Vs	4.65	5.00	5.35	V	I <sub>L</sub> = 300 mA	5
Ripple rejection	SVR vs	40	—	—	dB		5
Output leakage current	Io L5B	—	—	1.0	μA	V <sub>cc</sub> = 0 V	3
Focus driver							
Output voltage	Vfo	3.75	3.95	4.15	V	R <sub>L</sub> = 12.5 Ω	19, 20
Output offset voltage	VooF fo	−110	0	+110	mV	R <sub>L</sub> = 12.5 Ω	19, 20
Gain	Gv fo	14	15	16	dB	R <sub>L</sub> = 12.5 Ω, fin = 1 kHz	19, 20
Max. output amplitude	Vo fo	5.2	—	—	V	R <sub>L</sub> = 12.5 Ω	19, 20
Ripple rejection	SVR fo	30	—	—	dB		19, 20
Cutoff frequency	Fc fo	50	100	200	kHz		19, 20
Tracking driver							
Output voltage	Vtr	3.75	3.95	4.15	V	R <sub>L</sub> = 12.5 Ω	16, 17
Output offset voltage	VooFtr	−110	0	+110	mV	R <sub>L</sub> = 12.5 Ω	16, 17
Gain	Gv tr	14	15	16	dB	R <sub>L</sub> = 12.5 Ω, fin = 1 kHz	16, 17
Max. output amplitude	Vo tr	5.2	—	—	V	R <sub>L</sub> = 12.5 Ω	16, 17
Ripple rejection	SVRtr	30	—	—	dB		16, 17
Cutoff frequency	fctr	50	100	200	kHz		16, 17
Spindle driver							
Output voltage	Vsp	3.80	4.00	4.20	V	R <sub>L</sub> = 7.0 Ω	21, 22
Output offset voltage	VooFsp	−110	0	+110	mV	R <sub>L</sub> = 7.0 Ω	21, 22
Gain	Gvsp	14	15	16	dB	R <sub>L</sub> = 7.0 Ω, fin = 1 kHz	21, 22
Max. output amplitude	Vo sp	4.2	—	—	V	R <sub>L</sub> = 7.0 Ω	21, 22
Ripple rejection	SVR sp	30	—	—	dB		21, 22
Cutoff frequency	fcsp	50	100	200	kHz		21, 22
Carriage driver							
Output voltage	Vcr	3.80	4.00	4.20	V	R <sub>L</sub> = 8.0 Ω	23, 24
Output offset voltage	VooF cr	−110	0	+110	mV	R <sub>L</sub> = 8.0 Ω	23, 24
Gain	Gvcr	14	15	16	dB	R <sub>L</sub> = 8.0 Ω, fin = 1 kHz	23, 24
Max. output amplitude	Vocr	4.2	—	—	V	R <sub>L</sub> = 8.0 Ω	23, 24
Ripple rejection	SVR cr	30	—	—	dB		23, 24
Cutoff frequency	Fccr	50	100	200	kHz		23, 24

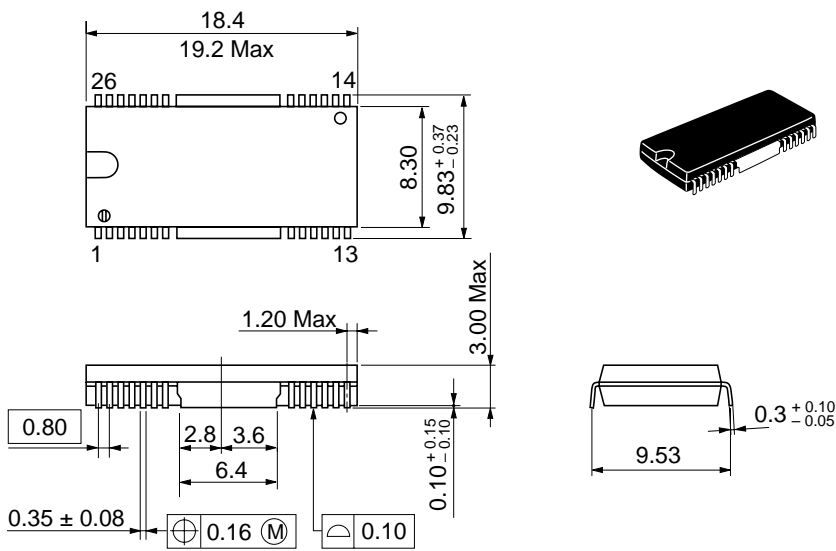
**Electrical Characteristics** ( $T_a = 25^{\circ}\text{C}$ ,  $V_{\text{CC}} = 8.0\text{ V}$ ) (cont)

Item	Symbol	Min	Typ	Max	Unit	Test Conditions	Applicable Pins
Channel crosstalk	CT	50	—	—	dB	fin = 1 kHz, 4 ch	16, 17, 18, 19, 21, 22, 23, 24
Operating voltage (1)	Vop1	3.75	3.95	4.15	V	Actuators	16
Operating voltage (2)	Vop2	3.80	4.00	4.20	V	Motors	25
Protection circuits							
Limiter operating current Focus	$I_{\text{LMTfo}}$	—	860	—	mA		18, 19
Limiter operating current Tracking	$I_{\text{LMTtr}}$	—	860	—	mA		16, 17
Limiter operating current Spindle	$I_{\text{LMTsp}}$	—	1100	—	mA		21, 22
Limiter operating current Carriage	$I_{\text{LMTcr}}$	—	930	—	mA		23, 24
TSD operating temperature	Ttsd	—	165	—	$^{\circ}\text{C}$		
TSD hysteresis temperature	Thys	—	30	—	$^{\circ}\text{C}$		
CONT circuit High-level input voltage	$V_{\text{IHcut}}$	—	—	3.0	V		8
Low-level input voltage	$V_{\text{ILcut}}$	2.0	—	—	V		8
High-level input current	$I_{\text{IHcut}}$	0.3	1.0	5.0	$\mu\text{A}$	CONT = 3.0 V	8
Low-level input current	$I_{\text{ILcut}}$	—	—	0.1	$\mu\text{A}$	CONT = 2.0 V	8
Circuit current when no signal (standby)	Istby 1	4.0	6.0	10.0	mA	CONT = 2.0 V BYPASS = OPEN	1, 14, 26
Circuit current when no signal (standby)	Istby 2	3.0	5.0	9.0	mA	CONT = 3.0 V BYPASS = "L"	1, 14, 26
Circuit current when no signal	Icc 1	10	20	30	mA	CONT = 3.0 V BYPASS = OPEN	1, 14, 26
Bypass voltage	Vbps	1.3	1.45	1.6	V		6
Driving performance Focus	Io fo	500	860	—	mA		18, 19
Driving performance Tracking	Io tr	500	860	—	mA		16, 17
Driving performance Spindle	Io sp	750	1100	—	mA		21, 22
Driving performance Carriage	Io cr	650	930	—	mA		23, 24

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## Package Dimensions

Unit: mm



Hitachi Code	MP-26DT
JEDEC	—
EIAJ	—
Mass (reference value)	0.98 g

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