

POWER MANAGEMENT

Description

The SC104 is a micro power dc-dc step-up converter which converts an input voltage, in the range of 1.55V to 10V, to a constant current. The part features a range of user programmable voltages and currents including dynamic adjustment of the “constant” current. The converter is capable of generating output voltages as low as the input supply voltage and up to 38V. During shutdown, the part draws a typical 500nA standby current.

The output current is set by the external resistor R1. Dynamic adjustment of the output current can be made by the application of an analog voltage to the ADJ input, or by PWMing this pin.

The peak switch current is programmable through the external resistor R_{LIM} enabling the use of a wide range of inductors and battery technologies.

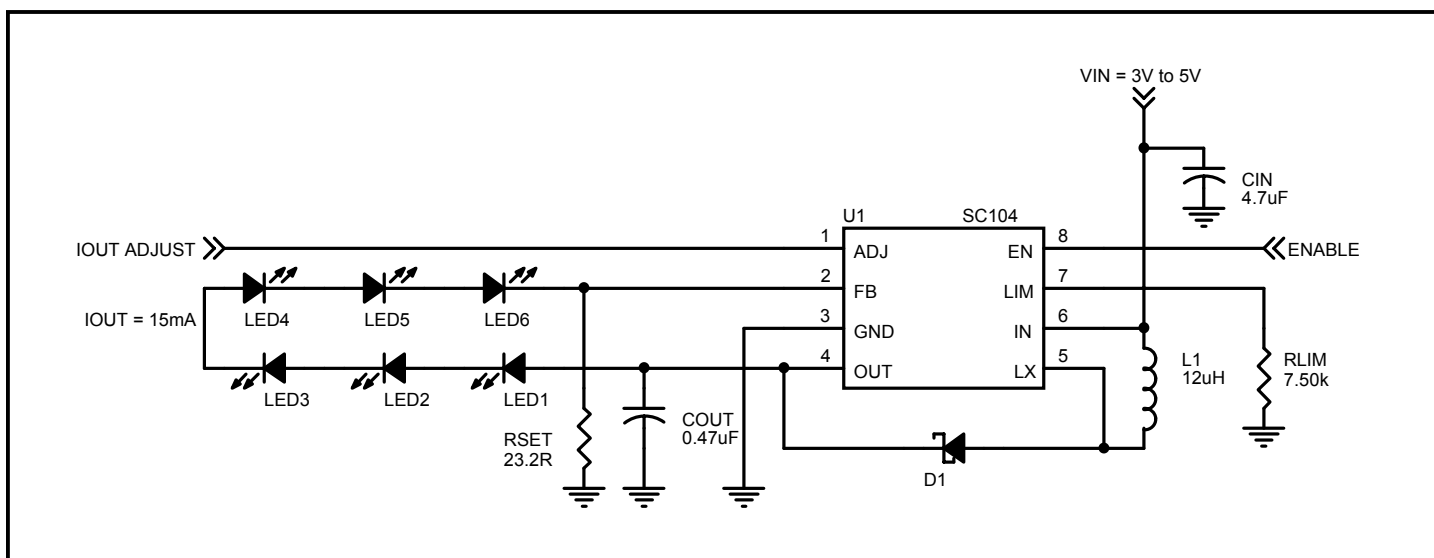
Features

- ◆ Adjustable output current using pulse width modulation or analog voltage input
- ◆ 38V output capability supports up to 10 white LEDs
- ◆ Wide range of input voltages 1.55V to 10V
- ◆ Low quiescent current
- ◆ 0.5 μ A standby current in shutdown
- ◆ Programmable cycle by cycle current limit
- ◆ Surface mount packaging (3x3mm 8pin MLP)
- ◆ Output voltage and over-temperature protection

Applications

- ◆ White LED supplies
- ◆ Color LED supplies
- ◆ Cellular phones
- ◆ PDAs
- ◆ Electronic books
- ◆ Handheld computers
- ◆ Wireless web appliances

Typical Application Circuit - 6 LEDs



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Absolute Maximum Ratings

Exceeding the specifications below may result in permanent damage to the device, or device malfunction. Operation outside of the parameters specified in the Electrical Characteristics section is not implied.

Parameter	Symbol	Maximum	Units
Input Supply Voltage	V_{IN}	-0.3 to 12	V
LX Pin Voltage (Power switch OFF)	V_{LX}	-0.3 to 55	V
FB Pin Voltage	V_{FB}	-0.3 to 6	V
EN Pin Voltage	V_{EN}	-0.3 to 6	V
LIM Pin Voltage	V_{LIM}	-0.3 to 6	V
ADJ Pin Voltage	V_{ADJ}	-0.3 to 2	V
OUT Pin Voltage	V_{OUT}	-0.3 to 55	V
Thermal Impedance Junction to Ambient	θ_{JA}	84	°C/W
Operating Ambient Temperature Range	T_A	-40 to +85	°C
Operating Junction Temperature Range	T_J	-40 to +125	°C
Storage Temperature Range	T_{STG}	-65 to +150	°C
Lead Temperature (Soldering) 10s - 30s	T_{LEAD}	240	°C
ESD Rating (Human Body Model)	V_{ESD}	2	kV

Electrical Characteristics

Unless specified: $V_{IN} = V_{EN} = 2V$, $-40 \leq T_A \leq 85^\circ C$, typical values are at room temperature.

Parameter	Symbol	Test Conditions	Min	Typ	Max	Units
Input Supply Voltage	V_{IN}	$T_A = 25^\circ C$	1.55		10	V
			1.75		10	
Shutdown Current	$I_{Q(OFF)}$	$V_{EN} = 0V$		0.5	3	μA
Feedback Voltage	V_{FB}		340	350	360	mV
Feedback Input Current	I_{FB}	$V_{FB} < 350mV$	200	700	1115	nA
Power Switch Saturation Voltage	$V_{CE(SAT)}$	$I_{LX} = 300mA$		150	250	mV
Junction Temperature at Thermal Shutdown ⁽¹⁾	T_{TSD}		140	150	160	°C
Over-Voltage Protection	V_{OVP}	Test current = 10 μA	36	38	44	V
Adjust Voltage	V_{ADJ}	$I_{ADJ} = 0A$	0.97	1.00	1.03	V
Adjust Voltage Switching Inhibit Threshold	$V_{TH(ADJ)}$				100	mV
Adjust Input Current	I_{ADJ}	$V_{ADJ} = 0V$	6	10	20	μA
		$V_{ADJ} = 1V$	-500	0	500	nA
		$V_{ADJ} = 1.25V$	-1.3	-2.3	-3.8	μA

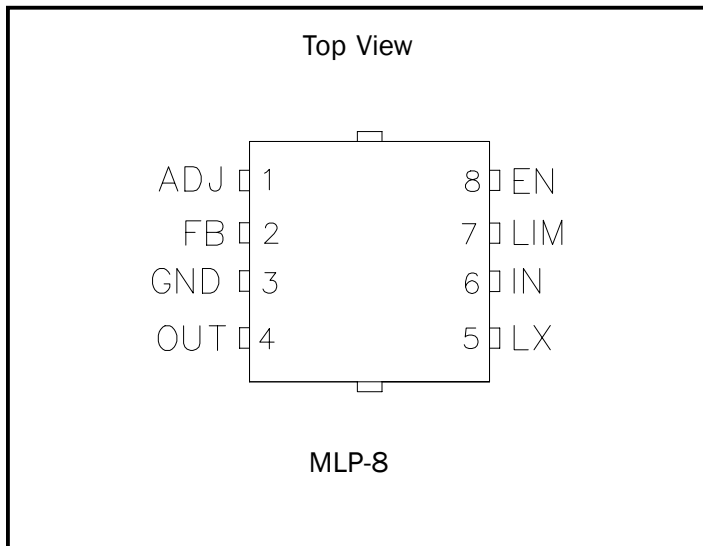
POWER MANAGEMENT
Electrical Characteristics (Cont.)

Unless specified: $V_{IN} = V_{EN} = 2V$, $-40 \leq T_A \leq 85^\circ C$, typical values are at room temperature.

Parameter	Symbol	Test Conditions	Min	Typ	Max	Units
Maximum Switch Current	I_{LX}	$I_{LIM} = 150\mu A$	-920			mA
Switch Off Time	t_{OFF}	$V_{FB} = 300mV$	0.60	0.76	1.00	μs
		$V_{FB} = 0V$	1.00	1.25	1.60	
Switch On Time	t_{ON}	excludes current limited conditions	1.8	2.25	2.7	μs
Maximum Duty Cycle	$\%_{DC}$		70			%
Switch Leakage	I_{LX}	switch off, $V_{LX} = 5V$		-0.01	-1.0	μA
Voltage Reference for Current Limit Setting Resistor	V_{LIM}	$I_{LIM} = 50\mu A$	385	400	410	mV
I_{LX} to I_{LIM} Ratio	I_{LX} / I_{LIM}	$I_{LIM} = 50\mu A$	7100	8150	8800	A/A
Logic Inputs						
Enable Input Voltage	V_{IH}	$I_{EN} > 300nA$	1.5			V
	V_{IL}				0.2	
Enable Input Bias Current	I_{IL}	$V_{EN} = 0.3V$			0.3	μA
	I_{IH}	$V_{EN} = 1.3V$			0.7	

Note:

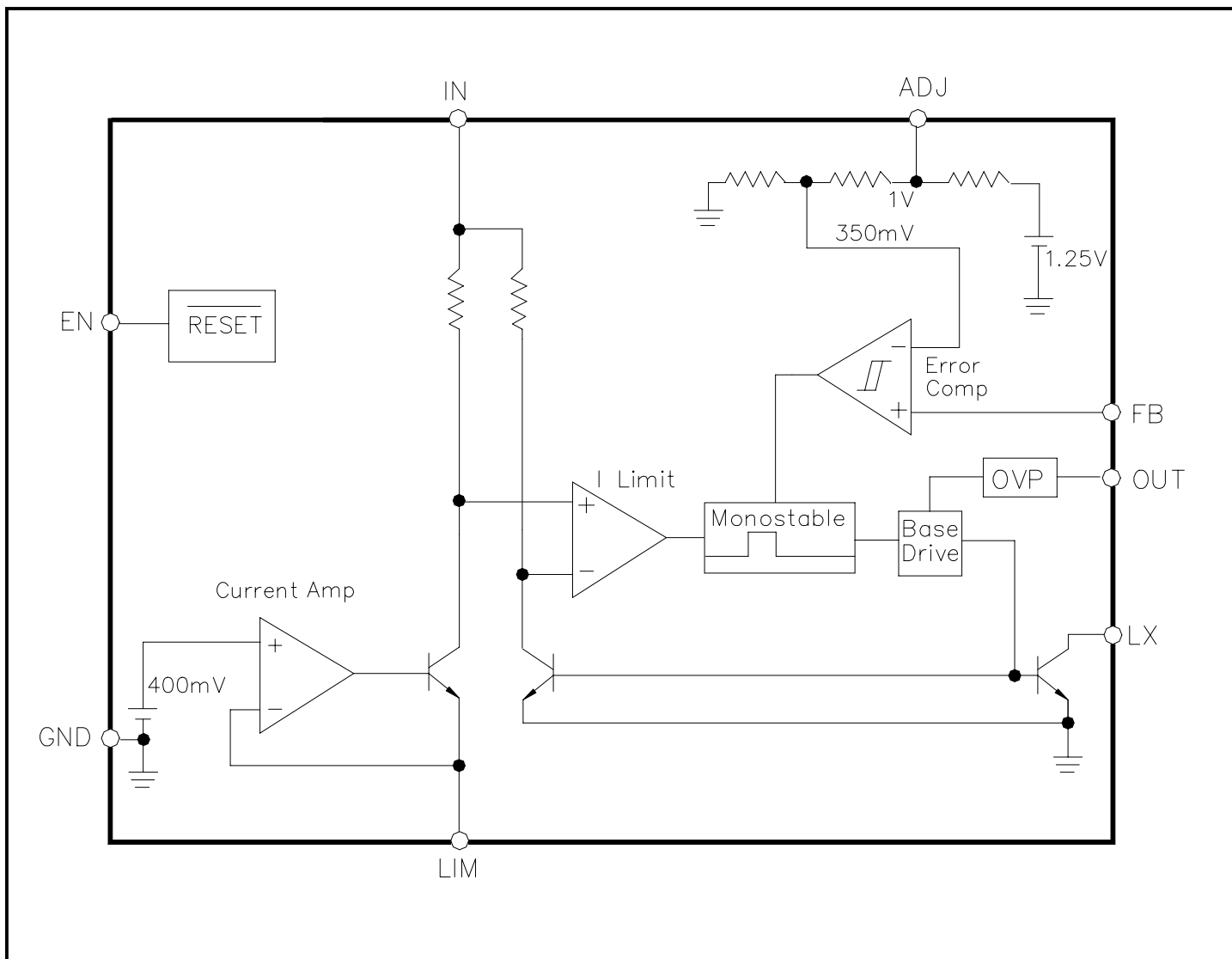
(1) Guaranteed by design.

POWER MANAGEMENT
Pin Configuration

Ordering Information

Part Number	Package
SC104IMLTR ⁽¹⁾	MLP-8
SC104EVB	Evaluation Board

Notes:

(1) Only available in tape and reel packaging. A reel contains 3000 devices.

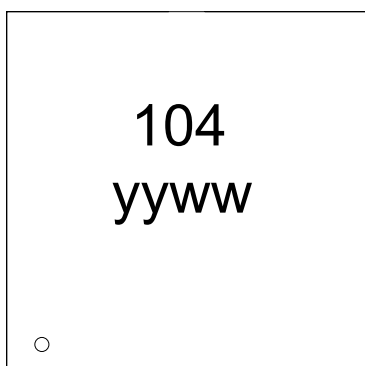
Block Diagram


POWER MANAGEMENT

Pin Descriptions

Pin	Pin Name	Pin Function
1	ADJ	Apply a PWM or analog voltage to this pin for dynamic output current adjustment.
2	FB	Connects to the resistor in the ground leg of the series LEDs (feedback for the constant load current).
3	GND	Ground pin.
4	OUT	Connect to the boost output at the cathode of the schottky diode. This pin is the input for the over-voltage protection circuit.
5	LX	Internal switch connection. Connect the inductor and the anode of the schottky diode to this pin.
6	IN	Input supply pin. Connect to a battery or power supply.
7	LIM	Current limit set pin. A resistor (R_{LIM}) connected from LIM to GND sets the peak inductor current limit threshold.
8	EN	Digital input for enable. Connect this pin to ground for shutdown or connect a voltage between 1.2V to 5.0V for enable. A 1M Ω pull-up resistor connecting to IN is also acceptable, provided $10\mu A > I_{EN} > 300nA$.

Marking Information



Marking for the MLP 8 Lead package:
yyww = Date Code (Example: 0012)

POWER MANAGEMENT

Applications Information

Component Selection - Introduction

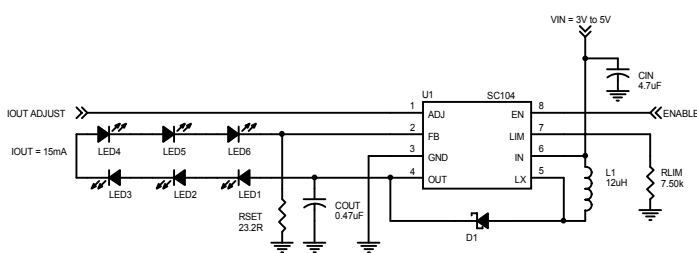
Referring to the 6 LED typical schematic below, there are three components that depend upon the application that need to be determined:

RSET - this resistor sets the output current for the device

RLIM - this resistor sets the peak inductor current

L - the output inductor

All the other components can be mostly generalized and are addressed below the following design steps.



Step 1: Continuous or Discontinuous?

The first thing to do when designing with the SC104 is to determine whether the output inductor will be operating in continuous mode (where the inductor current does not drop to zero while the device is switching) or discontinuous mode (where the inductor current drops to zero while switching). This determination can be made simply by calculating the required duty cycle needed for the target output voltage, and comparing it to the guaranteed minimum value for the maximum duty cycle from the Electrical Characteristics on Page 3. $\%DC_{(MIN)} = 70\%$ (or 0.7 duty). If DC is greater than 0.7 then discontinuous mode is required. The required duty cycle is calculated as follows:

$$DC = \frac{(V_{OUT} - V_{IN} + V_f)}{(V_{OUT} - V_{CE(SAT)} + V_f)}$$

Where:

V_{OUT} = output voltage, the sum of the total LED (max.) forward voltage drop at the required output voltage plus the feedback voltage, 0.35V.

V_{IN} = minimum input voltage

V_f = Schottky diode (D1) forward voltage drop

$V_{CE(SAT)}$ = power switch saturation voltage

Using the 6 LED example above:

$$V_{OUT} = (6 * 3.475) + 0.35 = 21.2V$$

$$V_{IN} = 3V$$

$$V_f = 0.35V$$

$$V_{CE(SAT)} = 0.25V$$

$$\text{thus } DC = 0.87$$

Since this value is greater than the guaranteed minimum value for maximum duty cycle, the device will be operating in discontinuous mode to provide the desired output. Note that the duty cycle does not depend upon the output current, and that unless the output to input ratio is low, the device will usually need to be in discontinuous mode, so we will cover that first (Step 1 through Step 5). Continuous mode calculations start at Step 6.

Step 2: Calculating the Inductor for Discontinuous Mode

Having determined that we need to be operating in discontinuous mode, we next need to calculate the maximum inductor value allowed that will permit the part to output the correct power. The maximum discontinuous inductor value, $L_{(D)}$ is given by:

$$L_{(D)} = \frac{t_{ON(MIN)}^2 \cdot V_{IN} \cdot (V_{IN} - V_{CE(SAT)})}{2 \cdot 1.4 \cdot V_{OUT} \cdot I_{OUT} \cdot (t_{ON(MIN)} + t_{OFF(MIN)})} \cdot \frac{(V_{OUT} - V_{CE(SAT)} + V_f)}{(V_{OUT} - V_{IN} + V_f)}$$

Where:

$t_{ON(MIN)}$ = minimum switch on-time = 1.8µs

I_{OUT} = required output current

$t_{OFF(MIN)}$ = minimum switch off-time = 0.6µs

Using our 6 LED example:

$$I_{OUT} = 15mA$$

$$\text{thus } L_{(D)} = 14.4\mu H$$

Selecting the next lower standard value gives us $L_{(D)} = 12\mu H$. Of course a lower value inductor may be used if desired, but may not necessarily be the most efficient choice.

Step 3: Calculating the Current Limit Required with this Inductor for Discontinuous Mode

Having determined the inductor value we are going to use, we next need to calculate the current limit required to meet the necessary output power. The discontinuous mode current limit, $I_{LIM(D)}$, is given by:

$$I_{LIM(D)} = \frac{(V_{IN} - V_{CE(SAT)}) \cdot t_{ON(MIN)}}{L_{(D)}}$$

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Applications Information (Cont.)

Step 3: (Cont.)

Using our 6 LED example:

$$L_{(D)} = 12\mu\text{H}$$

$$\text{thus } I_{\text{LIM}(D)} = 412\text{mA}$$

Step 4: Calculating the Current Limit Resistor for Discontinuous Mode

The current limit resistor value is calculated based upon the minimum ratio of the switch current to the current out of the LIM pin. It also takes into account the fact that there is a propagation delay during which time the inductor current ramps beyond the current limit trip point. Since I_{LIM} increases as R_{LIM} decreases, this value is a maximum. The maximum current limit resistor, $R_{\text{LIM}(D)}$, for discontinuous mode is therefore:

$$R_{\text{LIM}(D)} = \frac{V_{\text{LIM}(\text{MIN})} \cdot \text{Ratio}_{(\text{MIN})}}{\left(I_{\text{LIM}(D)} - \frac{t_{\text{plh}} \cdot (V_{\text{IN}} - V_{\text{CE}(\text{SAT})})}{L_{(D)}} \right)}$$

Where:

$V_{\text{LIM}(\text{MIN})}$ = the minimum value of the current limit voltage reference = 385mV

$\text{Ratio}_{(\text{MIN})}$ = the minimum value of the I_{LX} to I_{LIM} ratio = 7100 A/A

t_{plh} = propagation delay from reaching the current limit trip point to the power switch turning off = 200ns

Using our 6 LED example:

$$I_{\text{LIM}(D)} = 412\text{mA}$$

$$\text{thus } R_{\text{LIM}(D)} = 7.5\text{k}\Omega$$

Selecting this value or the next lower standard value in this case gives us 7.5k Ω . Of course a lower value resistor may be used if desired, but may not necessarily be the most efficient choice.

Step 5: Calculating the Current Set Resistor

The current set resistor is in series with the series LED string. Thus the voltage developed across it is proportional to the current flowing through the LEDs. The device will regulate this voltage so that its average value equals the feedback voltage, V_{FB} , which is typically 350mV. Thus the current set resistor value is given by the following

equation:

$$R_{\text{SET}} = \frac{V_{\text{FB}}}{I_{\text{OUT}}}$$

Using our 6 LED example:

$$I_{\text{OUT}} = 15\text{mA}$$

$$\text{thus } R_{\text{SET}} = 23.3\Omega$$

We will select the 1% resistor value 23.2 Ω .

Note: this calculation is applicable to both continuous and discontinuous modes.

Step 6: Calculating the Inductor for Continuous Mode

Having determined that we need to be operating in continuous mode, we next need to calculate the maximum inductor value allowed that will permit the part to output the correct power. The maximum continuous inductor value, $L_{(C)}$ is given by:

$$L_{(C)} = \frac{2 \cdot V_{\text{IN}} \cdot t_{\text{OFF}(\text{MIN})} \cdot (V_{\text{OUT}} + V_f - V_{\text{IN}})}{1.4 \cdot V_{\text{OUT}} \cdot I_{\text{OUT}}}$$

Where:

I_{OUT} = required output current

$t_{\text{OFF}(\text{MIN})}$ = minimum switch off-time = 0.6 μs

Selecting the next lower standard value gives us a safe value for this inductor.

Step 7: Calculating the Current Limit Required with this Inductor for Continuous Mode

Having determined the inductor value we are going to use, we next need to calculate the current limit required to meet the necessary output power. The continuous mode current limit, $I_{\text{LIM}(C)}$, is given by:

$$I_{\text{LIM}(C)} = \frac{(V_{\text{OUT}} + V_f - V_{\text{IN}}) \cdot t_{\text{OFF}(\text{MIN})}}{0.4 \cdot L_{(C)}}$$

Step 8: Calculating the Current Limit Resistor for Continuous Mode

The current limit resistor value is calculated based upon the minimum ratio of the switch current to the current out of the LIM pin. It also takes into account the fact that there is a propagation delay during which time the

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Applications Information (Cont.)

Step 8: (Cont.)

inductor current ramps beyond the current limit trip point. Since I_{LIM} increases as R_{LIM} decreases, this value is a maximum. The maximum current limit resistor, $R_{LIM(C)}$, for continuous mode is therefore:

$$R_{LIM(C)} = \frac{V_{LIM(MIN)} \cdot \text{Ratio}_{(MIN)}}{\left(I_{LIM(C)} - \frac{t_{plh} \cdot (V_{IN} - V_{CE(SAT)})}{L_{(C)}} \right)}$$

Where:

$V_{LIM(MIN)}$ = the minimum value of the current limit voltage reference = 385mV

$\text{Ratio}_{(MIN)}$ = the minimum value of the I_{LX} to I_{LIM} ratio = 7100 A/A

t_{plh} = propagation delay from reaching the current limit trip point to the power switch turning off = 200ns

Selecting the calculated value or the next lower standard value is recommended.

Component Selection - General

Capacitor Selection: the SC104 has been designed to be used with ceramic input and output capacitors. The input to the device should be bypassed using a 4.7μF ceramic capacitor rated for the maximum input voltage. The output capacitor should be a ceramic capacitor in the range of 0.22μF to 1μF. Care should be taken that the voltage rating of this capacitor meets the output voltage requirements, and if the part is going to be run open circuit during assembly testing using the OVP feature, then the capacitor should be rated 50V.

Schottky diode: any schottky diode rated for the average and peak currents being seen in the circuit will suffice. However a higher current rated schottky diode will result in lower forward voltage drops and hence higher efficiency. The selection of the schottky will depend upon the optimum choice between efficiency, board space, and cost.

Inductor: similarly, any inductor rated for the average and peak currents required by the design and capable of operating at the nominal switching frequency of 330kHz will suffice, but inductors with lower series resistance will result in lower losses. The selection of the inductor will depend upon the optimum choice between efficiency, board space, component height, and cost. Toko D62LCB and D63LCB series work very well.

LED Dimming

Dimming the LEDs (i.e. reducing the output current from the set level to reduce brightness) can be achieved a couple of ways:

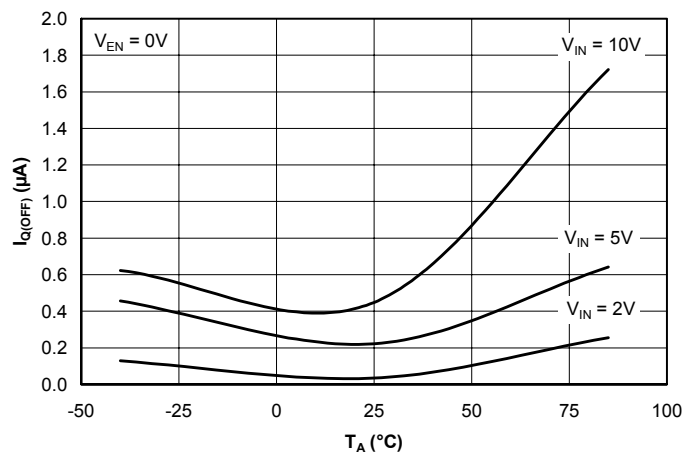
1) PWMing the ADJ pin using an open drain or open collector (with no pull-up). Using a PWM signal at this pin will reduce the output current by alternating between OFF ($ADJ < 100mV$) and switching normally. The lower the duty cycle, the lower the output current. A PWM frequency of 250Hz to 1kHz is recommended.

2) analog voltage applied to the ADJ pin: apply a DC voltage between 0V to 0.1V (OFF) and 1V (full current) to the ADJ pin. This pin should not be pulled above 1V under normal operation, and should never exceed the absolute maximum rating. Using a DC voltage will result in the modulation frequency of the inductor current ramp reducing and care must be taken to ensure that this does not become audible in sensitive applications.

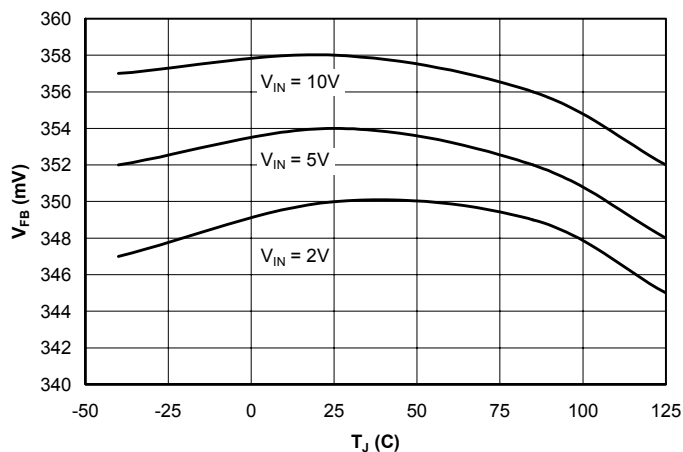
POWER MANAGEMENT

Typical Characteristics

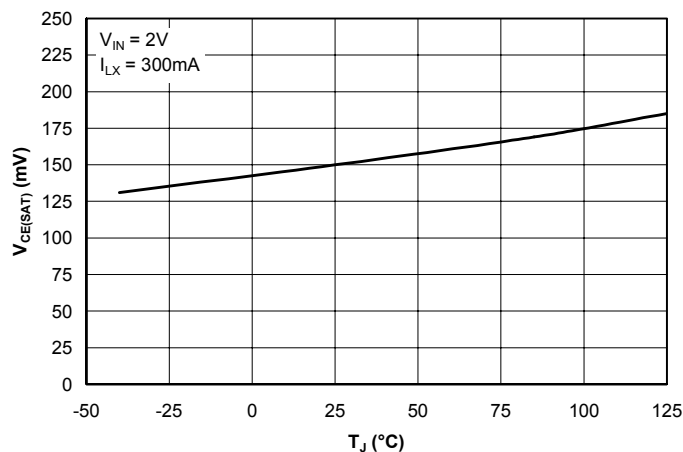
**Shutdown Current vs. Junction Temperature
vs. Input Voltage**



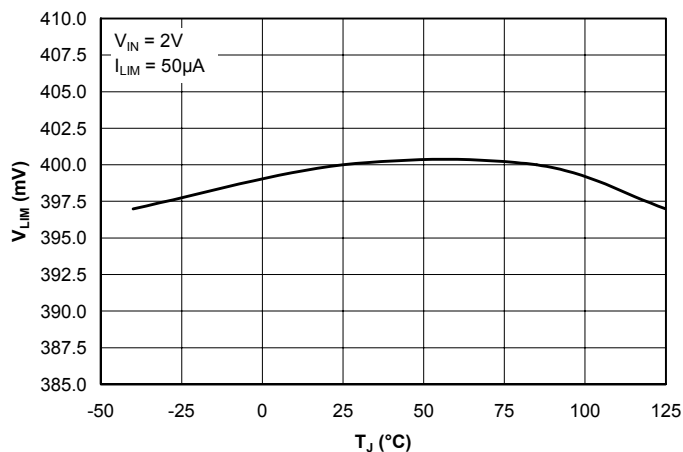
Average Feedback Voltage vs. Junction Temperature vs. Input Voltage



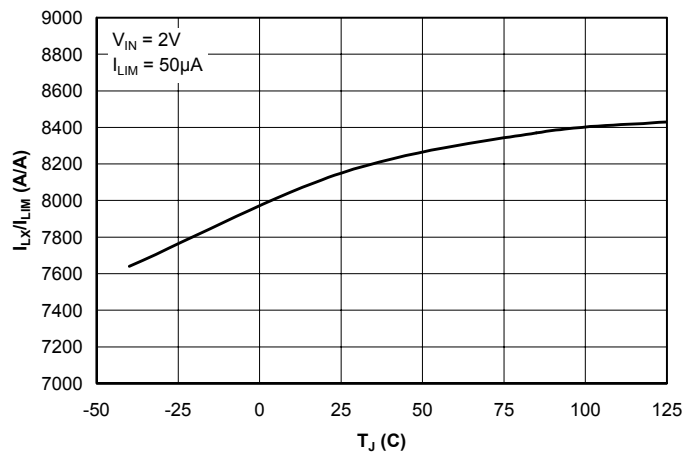
**Power Switch Saturation Voltage
vs. Junction Temperature**

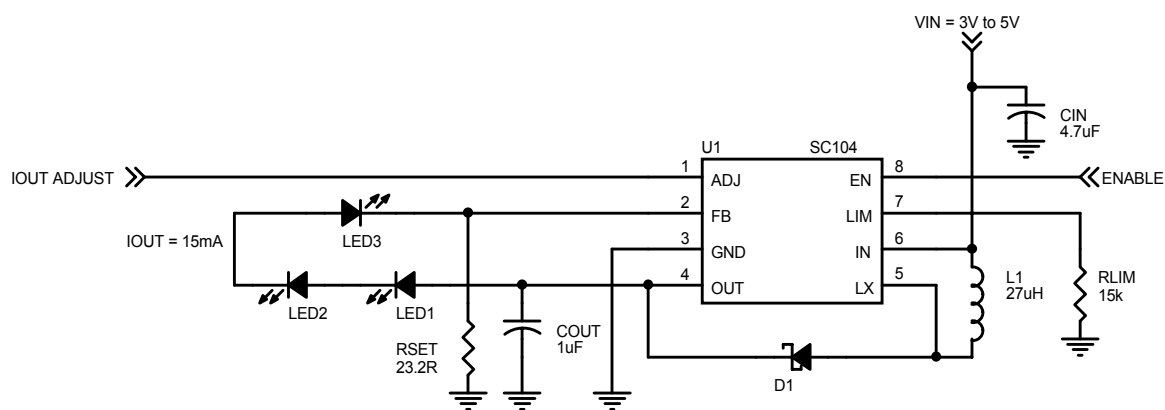
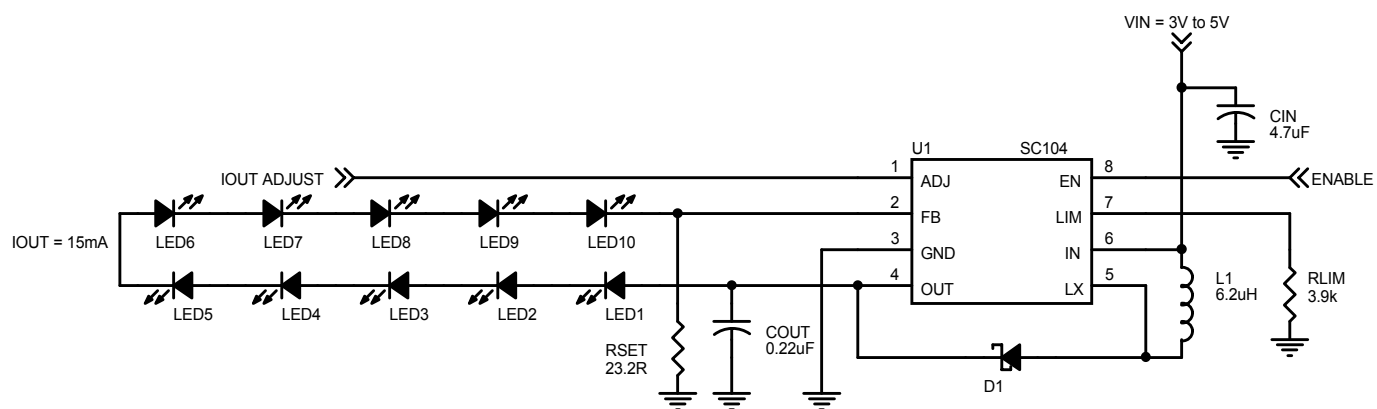


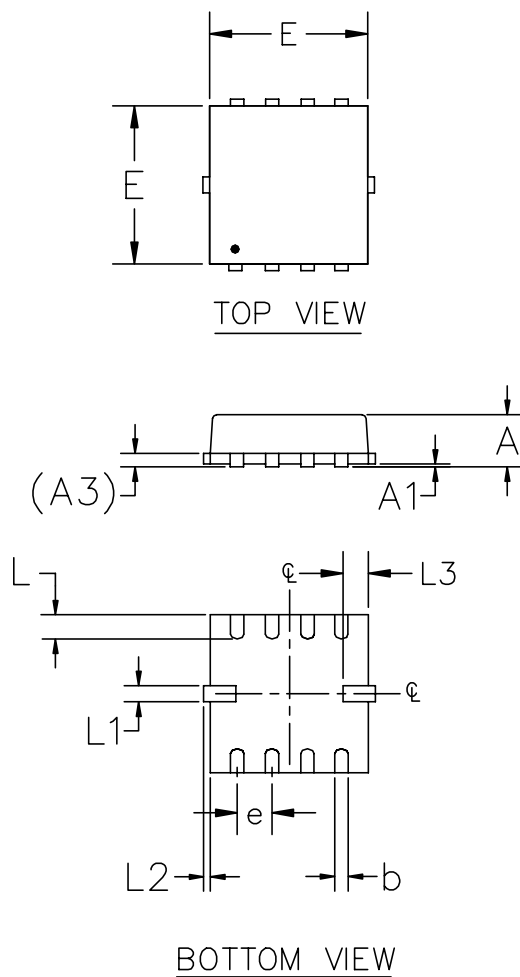
**Current Limit Reference Voltage
vs. Junction Temperature**



**I_{LX} to I_{LIM} Ratio vs.
Junction Temperature**

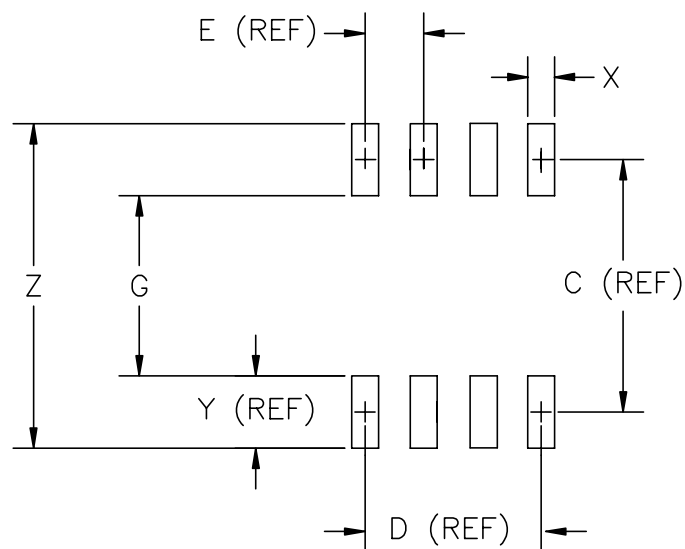


POWER MANAGEMENT
Typical Application Circuit - 3 LEDs

Typical Application Circuit - 10 LEDs


POWER MANAGEMENT
Outline Drawing - MLP-8


DIM ^N	INCHES		MM		NOTE
	MIN	MAX	MIN	MAX	
A	.032	.039	0.80	1.00	—
A1	0	.002	0	0.05	—
A3	.006	.010	0.15	0.25	REF
b	.008	.011	0.18	0.28	—
E	.118		3.00		NOM
e	.026	BSC	0.65	BSC	—
L	.008	.018	0.20	0.45	—
L1	.007	.012	0.17	0.30	—
L2	—	.005	—	0.125	—
L3	—	.019	—	0.48	—

1 CONTROLLING DIMENSIONS: MILLIMETERS.

POWER MANAGEMENT
Land Pattern - MLP-8


DIMENSIONS					
DIM ^N	INCHES		MM [1]		NOTE
	MIN	MAX	MIN	MAX	
C	—	.112	—	2.84	REF
D	—	.078	—	1.98	—
E	—	.026	—	0.65	REF
G	—	.080	—	2.03	REF
X	—	.012	—	0.30	—
Y	—	.032	—	0.81	REF
Z	—	.144	—	3.66	—

[1] CONTROLLING DIMENSION: MILLIMETERS

Contact Information

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