

HEF4516B

Binary up/down counter

Rev. 7 — 11 November 2011

Product data sheet

1. General description

The HEF4516B is an edge-triggered synchronous 4-bit binary up/down counter with a clock input (CP), an up/down count control input (UP/DN), an active LOW count enable input (\overline{CE}), an asynchronous active HIGH parallel load input (PL), four parallel inputs (D0 to D3), four parallel outputs (Q0 to Q3), an active LOW terminal count output (\overline{TC}), and an overriding asynchronous master reset input (MR).

Information on D0 to D3 is loaded into the counter while PL is HIGH, independent of all other input conditions except for MR which must be LOW. When PL and \overline{CE} are LOW, the counter changes on the LOW-to-HIGH transition of CP. Input UP/DN determines the direction of the count, counting up when HIGH and counting down when LOW. When counting up, \overline{TC} is LOW when Q0 and Q3 are HIGH and \overline{CE} is LOW. When counting down, \overline{TC} is LOW when Q0 to Q3 and \overline{CE} are LOW. A HIGH on MR resets the counter (Q0 to Q3 = LOW) independent of all other input conditions.

It operates over a recommended V_{DD} power supply range of 3 V to 15 V referenced to V_{SS} (usually ground). Unused inputs must be connected to V_{DD} , V_{SS} , or another input.

2. Features and benefits

- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Specified from $-40\text{ }^{\circ}\text{C}$ to $+85\text{ }^{\circ}\text{C}$
- Complies with JEDEC standard JESD 13-B

3. Ordering information

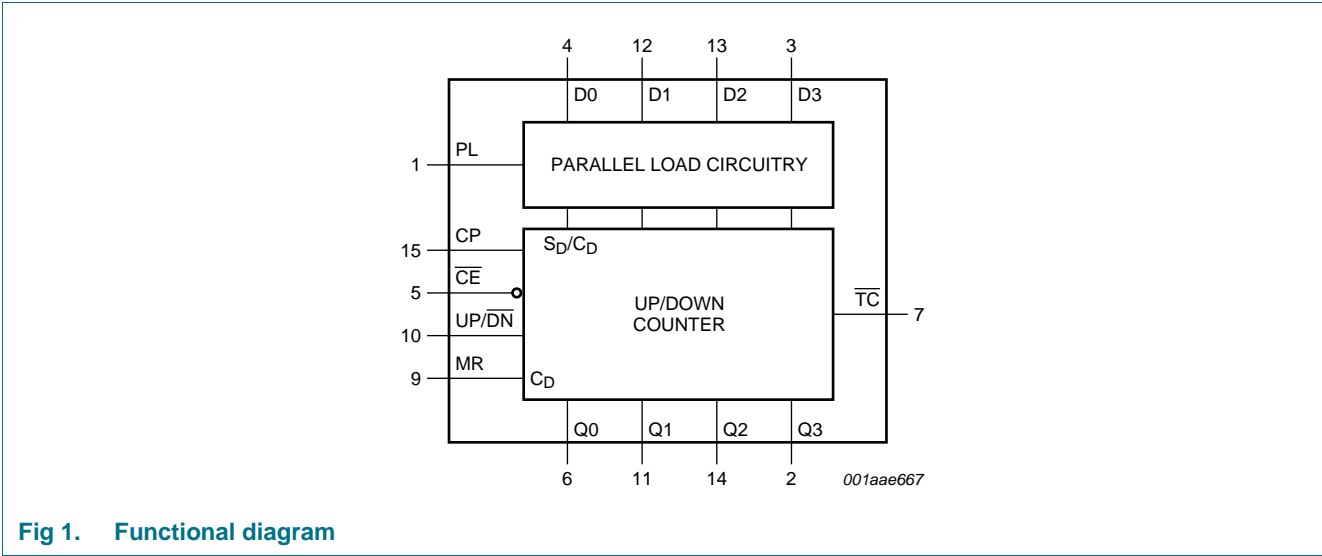
Table 1. Ordering information

All types operate from $-40\text{ }^{\circ}\text{C}$ to $+85\text{ }^{\circ}\text{C}$.

| Type number | Package | | |
|-------------|---------|--|----------|
| | Name | Description | Version |
| HEF4516BP | DIP16 | plastic dual in-line package; 16-leads (300 mil) | SOT38-4 |
| HEF4516BT | SO16 | plastic small outline package; 16 leads; body width 3.9 mm | SOT109-1 |



4. Functional diagram



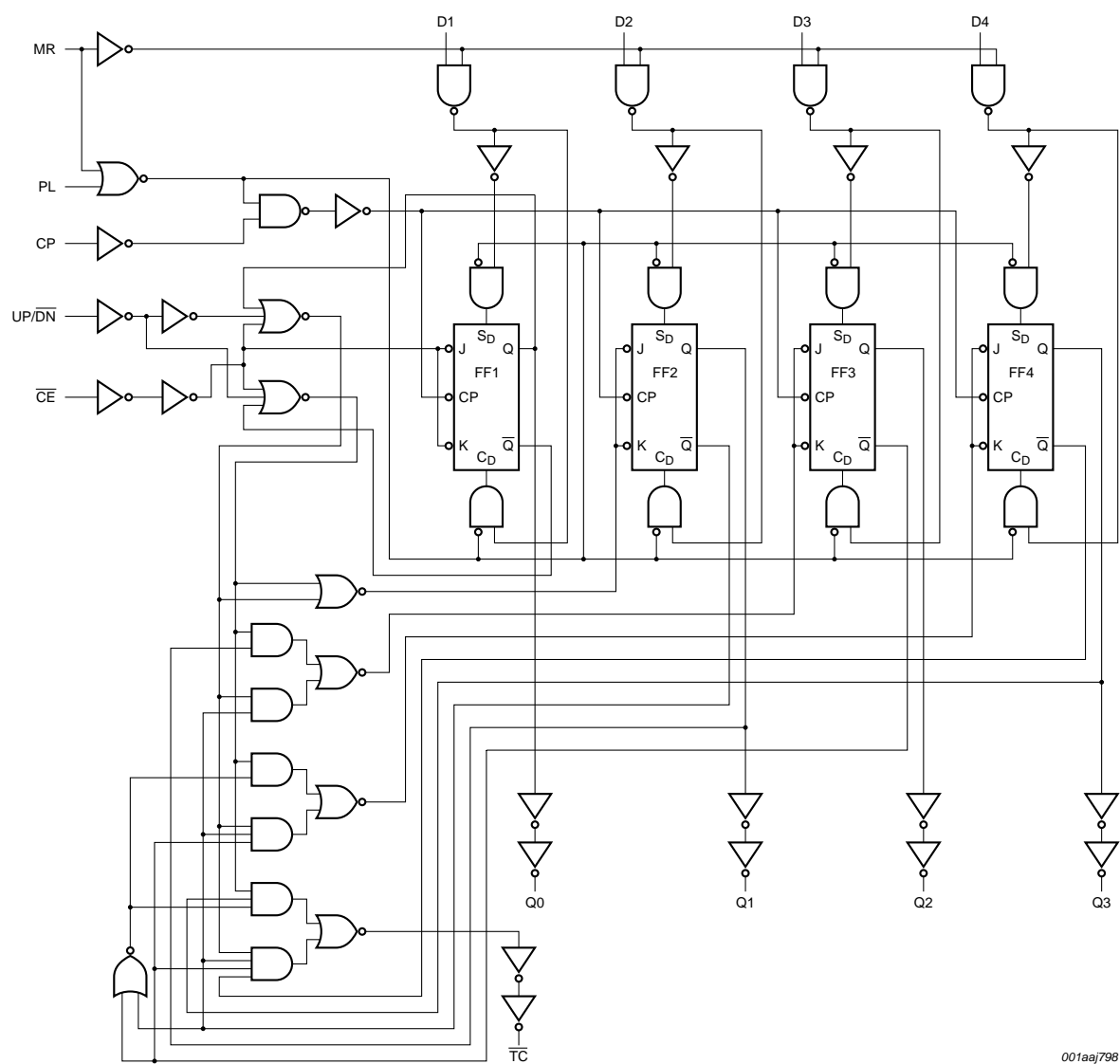


Fig 2. Logic diagram

5. Pinning information

5.1 Pinning

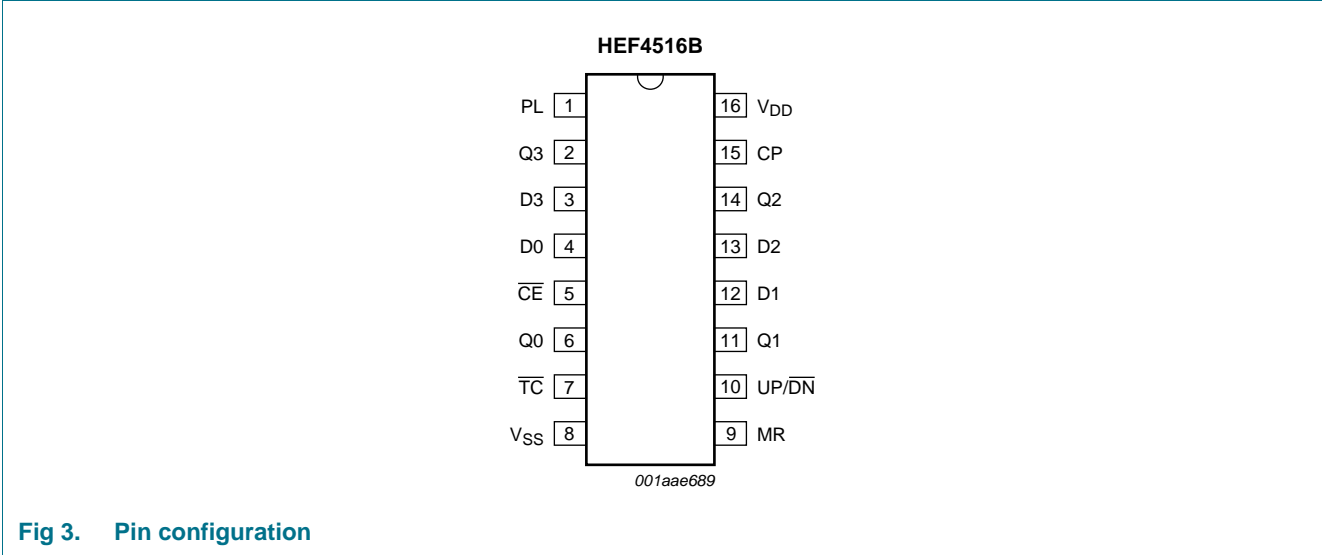


Fig 3. Pin configuration

5.2 Pin description

Table 2. Pin description

| Symbol | Pin | Description |
|---------------------|--------------|---|
| PL | 1 | parallel load input (active HIGH) |
| D0 to D3 | 4, 12, 13, 3 | parallel input |
| \overline{CE} | 5 | count enable input (active LOW) |
| Q0 to Q3 | 6, 11, 14, 2 | parallel output |
| V_{SS} | 8 | ground supply voltage |
| \overline{TC} | 7 | terminal count output (active LOW) |
| MR | 9 | master reset input |
| UP/ \overline{DN} | 10 | up/down count control input |
| CP | 15 | clock pulse input (LOW to HIGH, edge triggered) |
| V_{DD} | 16 | supply voltage |

6. Functional description

Table 3. Function table^[1]

| MR | PL | UP/DN | $\overline{\text{CE}}$ | CP | MODE |
|----|----|-------|------------------------|----|---------------|
| L | H | X | X | X | parallel load |
| L | L | X | H | X | no change |
| L | L | L | L | ↑ | count down |
| L | L | H | L | ↑ | count up |
| H | X | X | X | X | reset |

[1] H = HIGH voltage level; L = LOW voltage level; X = don't care; ↑ = positive-going transition.

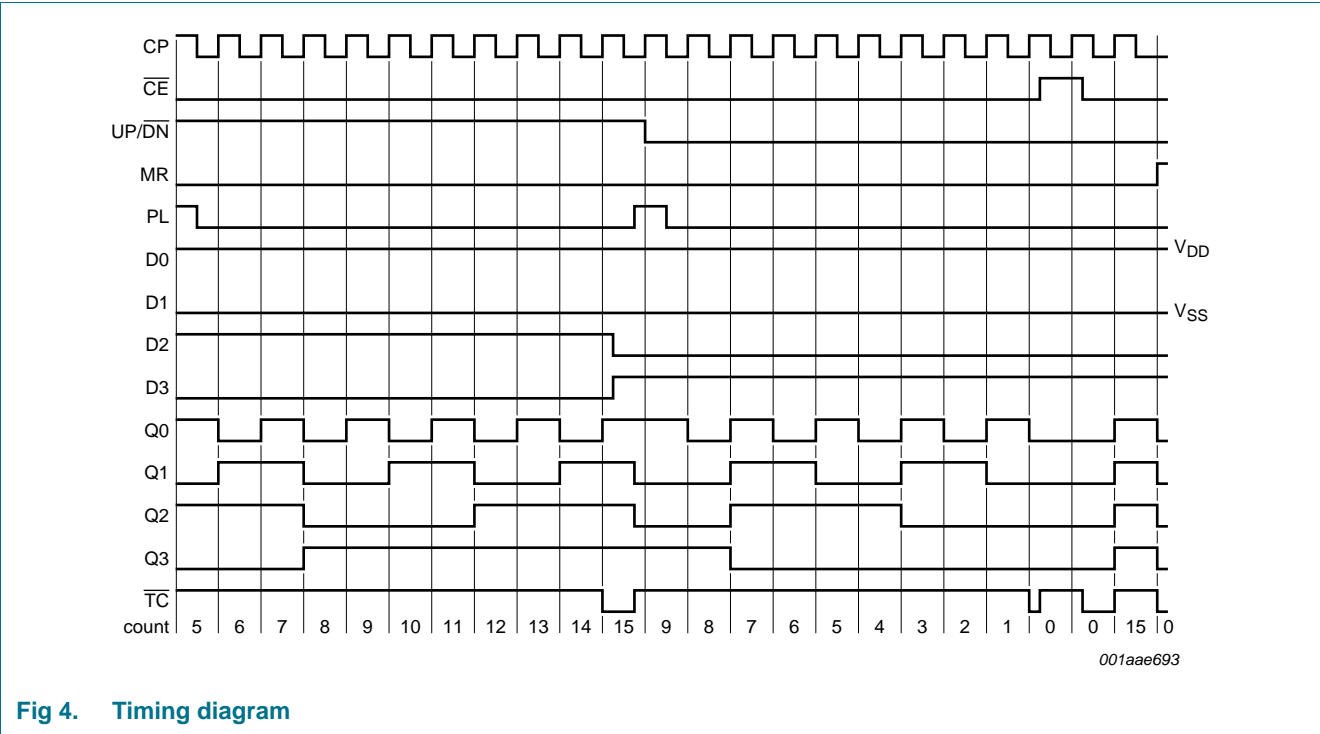
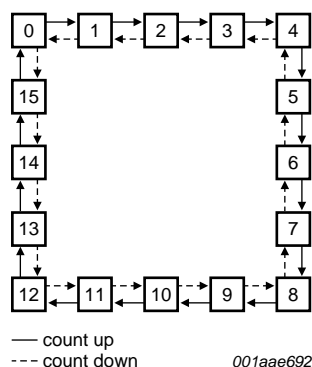


Fig 4. Timing diagram



Logic equation for terminal count:

$$\overline{TC} = \overline{CE} \cdot \{ (UP/\overline{DN}) \cdot Q0 \cdot Q1 \cdot Q2 \cdot Q3 + (\overline{UP}/\overline{DN}) \cdot \overline{Q0} \cdot \overline{Q1} \cdot \overline{Q2} \cdot \overline{Q3} \}.$$

Fig 5. State diagram

7. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|-----------|-------------------------|--|-------|----------------|------|
| V_{DD} | supply voltage | | -0.5 | +18 | V |
| I_{IK} | input clamping current | $V_I < -0.5 \text{ V}$ or $V_I > V_{DD} + 0.5 \text{ V}$ | - | ± 10 | mA |
| V_I | input voltage | | -0.5 | $V_{DD} + 0.5$ | V |
| I_{OK} | output clamping current | $V_O < -0.5 \text{ V}$ or $V_O > V_{DD} + 0.5 \text{ V}$ | - | ± 10 | mA |
| $I_{I/O}$ | input/output current | | - | ± 10 | mA |
| I_{DD} | supply current | | - | 50 | mA |
| T_{stg} | storage temperature | | -65 | +150 | °C |
| T_{amb} | ambient temperature | | -40 | +85 | °C |
| P_{tot} | total power dissipation | DIP16 package | [1] - | 750 | mW |
| | | SO16 package | [2] - | 500 | mW |
| P | power dissipation | per output | - | 100 | mW |

[1] For DIP16 package: P_{tot} derates linearly with 12 mW/K above 70 °C.

[2] For SO16 package: P_{tot} derates linearly with 8 mW/K above 70 °C.

8. Recommended operating conditions

Table 5. Recommended operating conditions

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-----------|---------------------|-------------|-----|-----|----------|------|
| V_{DD} | supply voltage | | 3 | - | 15 | V |
| V_I | input voltage | | 0 | - | V_{DD} | V |
| T_{amb} | ambient temperature | in free air | -40 | - | +85 | °C |

Table 5. Recommended operating conditions ...continued

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---------------------|-------------------------------------|------------------------|-----|-----|------|-----------------|
| $\Delta t/\Delta V$ | input transition rise and fall rate | $V_{DD} = 5\text{ V}$ | - | - | 3.75 | $\mu\text{s/V}$ |
| | | $V_{DD} = 10\text{ V}$ | - | - | 0.5 | $\mu\text{s/V}$ |
| | | $V_{DD} = 15\text{ V}$ | - | - | 0.08 | $\mu\text{s/V}$ |

9. Static characteristics

Table 6. Static characteristics

$V_{SS} = 0\text{ V}$; $V_I = V_{SS}$ or V_{DD} unless otherwise specified.

| Symbol | Parameter | Conditions | V_{DD} | $T_{amb} = -40\text{ }^{\circ}\text{C}$ | | $T_{amb} = 25\text{ }^{\circ}\text{C}$ | | $T_{amb} = 85\text{ }^{\circ}\text{C}$ | | Unit |
|----------|---------------------------|--|----------|---|-----------|--|-----------|--|-----------|---------------|
| | | | | Min | Max | Min | Max | Min | Max | |
| V_{IH} | HIGH-level input voltage | $ I_O < 1\text{ }\mu\text{A}$ | 5 V | 3.5 | - | 3.5 | - | 3.5 | - | V |
| | | | 10 V | 7.0 | - | 7.0 | - | 7.0 | - | V |
| | | | 15 V | 11.0 | - | 11.0 | - | 11.0 | - | V |
| V_{IL} | LOW-level input voltage | $ I_O < 1\text{ }\mu\text{A}$ | 5 V | - | 1.5 | - | 1.5 | - | 1.5 | V |
| | | | 10 V | - | 3.0 | - | 3.0 | - | 3.0 | V |
| | | | 15 V | - | 4.0 | - | 4.0 | - | 4.0 | V |
| V_{OH} | HIGH-level output voltage | $ I_O < 1\text{ }\mu\text{A}$; $V_I = V_{SS}$ or V_{DD} | 5 V | 4.95 | - | 4.95 | - | 4.95 | - | V |
| | | | 10 V | 9.95 | - | 9.95 | - | 9.95 | - | V |
| | | | 15 V | 14.95 | - | 14.95 | - | 14.95 | - | V |
| V_{OL} | LOW-level output voltage | $ I_O < 1\text{ }\mu\text{A}$; $V_I = V_{SS}$ or V_{DD} | 5 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| | | | 10 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| | | | 15 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| I_{OH} | HIGH-level output current | $V_O = 2.5\text{ V}$ | 5 V | - | -1.7 | - | -1.4 | - | -1.1 | mA |
| | | $V_O = 4.6\text{ V}$ | 5 V | - | -0.52 | - | -0.44 | - | -0.36 | mA |
| | | $V_O = 9.5\text{ V}$ | 10 V | - | -1.3 | - | -1.1 | - | -0.9 | mA |
| | | $V_O = 13.5\text{ V}$ | 15 V | - | -3.6 | - | -3.0 | - | -2.4 | mA |
| I_{OL} | LOW-level output current | $V_O = 0.4\text{ V}$ | 5 V | 0.52 | - | 0.44 | - | 0.36 | - | mA |
| | | $V_O = 0.5\text{ V}$ | 10 V | 1.3 | - | 1.1 | - | 0.9 | - | mA |
| | | $V_O = 1.5\text{ V}$ | 15 V | 3.6 | - | 3.0 | - | 2.4 | - | mA |
| I_I | input leakage current | $V_{DD} = 15\text{ V}$ | 15 V | - | ± 0.3 | - | ± 0.3 | - | ± 1.0 | μA |
| I_{DD} | supply current | $I_O = 0\text{ A}$; $V_I = V_{SS}$ or V_{DD} | 5 V | - | 20 | - | 20 | - | 150 | μA |
| | | | 10 V | - | 40 | - | 40 | - | 300 | μA |
| | | | 15 V | - | 80 | - | 80 | - | 600 | μA |
| C_I | input capacitance | | - | - | - | - | 7.5 | - | - | pF |

10. Dynamic characteristics

Table 7. Dynamic characteristics

$V_{SS} = 0\text{ V}$; $T_{amb} = 25\text{ }^{\circ}\text{C}$; for test circuit see [Figure 8](#); unless otherwise specified.

| Symbol | Parameter | Conditions | V_{DD} | Extrapolation formula | Min | Typ | Max | Unit |
|-----------|-------------------------------|------------------------------------|----------|--|-----|-----|-----|------|
| t_{PHL} | HIGH to LOW propagation delay | CP to Qn | 5 V | [1] $118\text{ ns} + (0.55\text{ ns/pF})C_L$ | - | 145 | 290 | ns |
| | | | 10 V | $49\text{ ns} + (0.23\text{ ns/pF})C_L$ | - | 60 | 120 | ns |
| | | | 15 V | $37\text{ ns} + (0.16\text{ ns/pF})C_L$ | - | 45 | 90 | ns |
| | | CP to \overline{TC} | 5 V | $233\text{ ns} + (0.55\text{ ns/pF})C_L$ | - | 260 | 525 | ns |
| | | | 10 V | $94\text{ ns} + (0.23\text{ ns/pF})C_L$ | - | 105 | 210 | ns |
| | | | 15 V | $67\text{ ns} + (0.16\text{ ns/pF})C_L$ | - | 75 | 150 | ns |
| | | PL to Qn | 5 V | $98\text{ ns} + (0.55\text{ ns/pF})C_L$ | - | 125 | 255 | ns |
| | | | 10 V | $44\text{ ns} + (0.23\text{ ns/pF})C_L$ | - | 55 | 110 | ns |
| | | | 15 V | $32\text{ ns} + (0.16\text{ ns/pF})C_L$ | - | 40 | 85 | ns |
| | | PL to \overline{TC} | 5 V | $223\text{ ns} + (0.55\text{ ns/pF})C_L$ | - | 250 | 500 | ns |
| | | | 10 V | $99\text{ ns} + (0.23\text{ ns/pF})C_L$ | - | 110 | 220 | ns |
| | | | 15 V | $72\text{ ns} + (0.16\text{ ns/pF})C_L$ | - | 80 | 160 | ns |
| | | \overline{CE} to \overline{TC} | 5 V | $138\text{ ns} + (0.55\text{ ns/pF})C_L$ | - | 165 | 330 | ns |
| | | | 10 V | $54\text{ ns} + (0.23\text{ ns/pF})C_L$ | - | 65 | 135 | ns |
| | | | 15 V | $42\text{ ns} + (0.16\text{ ns/pF})C_L$ | - | 50 | 100 | ns |
| | | MR to Qn, \overline{TC} | 5 V | $178\text{ ns} + (0.55\text{ ns/pF})C_L$ | - | 205 | 405 | ns |
| | | | 10 V | $54\text{ ns} + (0.23\text{ ns/pF})C_L$ | - | 65 | 130 | ns |
| | | | 15 V | $37\text{ ns} + (0.16\text{ ns/pF})C_L$ | - | 45 | 85 | ns |
| t_{PLH} | LOW to HIGH propagation delay | CP to Qn | 5 V | [1] $128\text{ ns} + (0.55\text{ ns/pF})C_L$ | - | 155 | 310 | ns |
| | | | 10 V | $54\text{ ns} + (0.23\text{ ns/pF})C_L$ | - | 65 | 130 | ns |
| | | | 15 V | $37\text{ ns} + (0.16\text{ ns/pF})C_L$ | - | 45 | 90 | ns |
| | | CP to \overline{TC} | 5 V | $153\text{ ns} + (0.55\text{ ns/pF})C_L$ | - | 180 | 360 | ns |
| | | | 10 V | $64\text{ ns} + (0.23\text{ ns/pF})C_L$ | - | 75 | 150 | ns |
| | | | 15 V | $47\text{ ns} + (0.16\text{ ns/pF})C_L$ | - | 55 | 115 | ns |
| | | PL to Qn | 5 V | $143\text{ ns} + (0.55\text{ ns/pF})C_L$ | - | 170 | 340 | ns |
| | | | 10 V | $59\text{ ns} + (0.23\text{ ns/pF})C_L$ | - | 70 | 140 | ns |
| | | | 15 V | $42\text{ ns} + (0.16\text{ ns/pF})C_L$ | - | 50 | 105 | ns |
| | | PL to \overline{TC} | 5 V | $223\text{ ns} + (0.55\text{ ns/pF})C_L$ | - | 250 | 500 | ns |
| | | | 10 V | $99\text{ ns} + (0.23\text{ ns/pF})C_L$ | - | 110 | 220 | ns |
| | | | 15 V | $72\text{ ns} + (0.16\text{ ns/pF})C_L$ | - | 80 | 160 | ns |
| | | \overline{CE} to \overline{TC} | 5 V | $118\text{ ns} + (0.55\text{ ns/pF})C_L$ | - | 145 | 290 | ns |
| | | | 10 V | $49\text{ ns} + (0.23\text{ ns/pF})C_L$ | - | 60 | 125 | ns |
| | | | 15 V | $37\text{ ns} + (0.16\text{ ns/pF})C_L$ | - | 45 | 95 | ns |
| | | MR to \overline{TC} | 5 V | $198\text{ ns} + (0.55\text{ ns/pF})C_L$ | - | 225 | 450 | ns |
| | | | 10 V | $64\text{ ns} + (0.23\text{ ns/pF})C_L$ | - | 75 | 150 | ns |
| | | | 15 V | $42\text{ ns} + (0.16\text{ ns/pF})C_L$ | - | 50 | 100 | ns |

Table 7. Dynamic characteristics ...continued $V_{SS} = 0\text{ V}$; $T_{amb} = 25\text{ }^{\circ}\text{C}$; for test circuit see [Figure 8](#); unless otherwise specified.

| Symbol | Parameter | Conditions | V_{DD} | Extrapolation formula | Min | Typ | Max | Unit |
|-----------|-------------------|--|----------|---|-----|-----|-----|------|
| t_t | transition time | | 5 V | [1] $10\text{ ns} + (1.00\text{ ns/pF})C_L$ | - | 60 | 120 | ns |
| | | | 10 V | $9\text{ ns} + (0.42\text{ ns/pF})C_L$ | - | 30 | 60 | ns |
| | | | 15 V | $6\text{ ns} + (0.28\text{ ns/pF})C_L$ | - | 20 | 40 | ns |
| f_{max} | maximum frequency | see Figure 6 | 5 V | | 3 | 6 | - | MHz |
| | | | 10 V | | 7 | 14 | - | MHz |
| | | | 15 V | | 9 | 18 | - | MHz |
| t_W | pulse width | CP input LOW; minimum width; see Figure 6 | 5 V | | 95 | 45 | - | ns |
| | | | 10 V | | 35 | 20 | - | ns |
| | | | 15 V | | 25 | 15 | - | ns |
| | | PL input HIGH; minimum width; see Figure 7 | 5 V | | 105 | 55 | - | ns |
| | | | 10 V | | 45 | 25 | - | ns |
| | | | 15 V | | 35 | 15 | - | ns |
| | | MR input HIGH; minimum width; see Figure 7 | 5 V | | 120 | 60 | - | ns |
| | | | 10 V | | 50 | 25 | - | ns |
| | | | 15 V | | 40 | 20 | - | ns |
| t_{rec} | recovery time | MR input; see Figure 7 | 5 V | | 130 | 65 | - | ns |
| | | | 10 V | | 45 | 20 | - | ns |
| | | | 15 V | | 30 | 15 | - | ns |
| | | PL input; see Figure 7 | 5 V | | 150 | 75 | - | ns |
| | | | 10 V | | 50 | 25 | - | ns |
| | | | 15 V | | 30 | 15 | - | ns |
| t_{su} | set-up time | Dn to PL; see Figure 7 | 5 V | | 100 | 50 | - | ns |
| | | | 10 V | | 50 | 25 | - | ns |
| | | | 15 V | | 40 | 20 | - | ns |
| | | UP/DN to CP; see Figure 6 | 5 V | | 250 | 125 | - | ns |
| | | | 10 V | | 100 | 50 | - | ns |
| | | | 15 V | | 75 | 35 | - | ns |
| | | \overline{CE} to CP; see Figure 6 | 5 V | | 120 | 60 | - | ns |
| | | | 10 V | | 40 | 20 | - | ns |
| | | | 15 V | | 25 | 10 | - | ns |
| t_h | hold time | Dn to PL; see Figure 7 | 5 V | | +10 | -40 | - | ns |
| | | | 10 V | | +5 | -20 | - | ns |
| | | | 15 V | | 0 | -20 | - | ns |
| | | UP/DN to CP; see Figure 6 | 5 V | | +35 | -90 | - | ns |
| | | | 10 V | | +15 | -35 | - | ns |
| | | | 15 V | | +15 | -25 | - | ns |
| | | \overline{CE} to CP; see Figure 6 | 5 V | | +20 | -40 | - | ns |
| | | | 10 V | | +5 | -15 | - | ns |
| | | | 15 V | | +5 | -10 | - | ns |

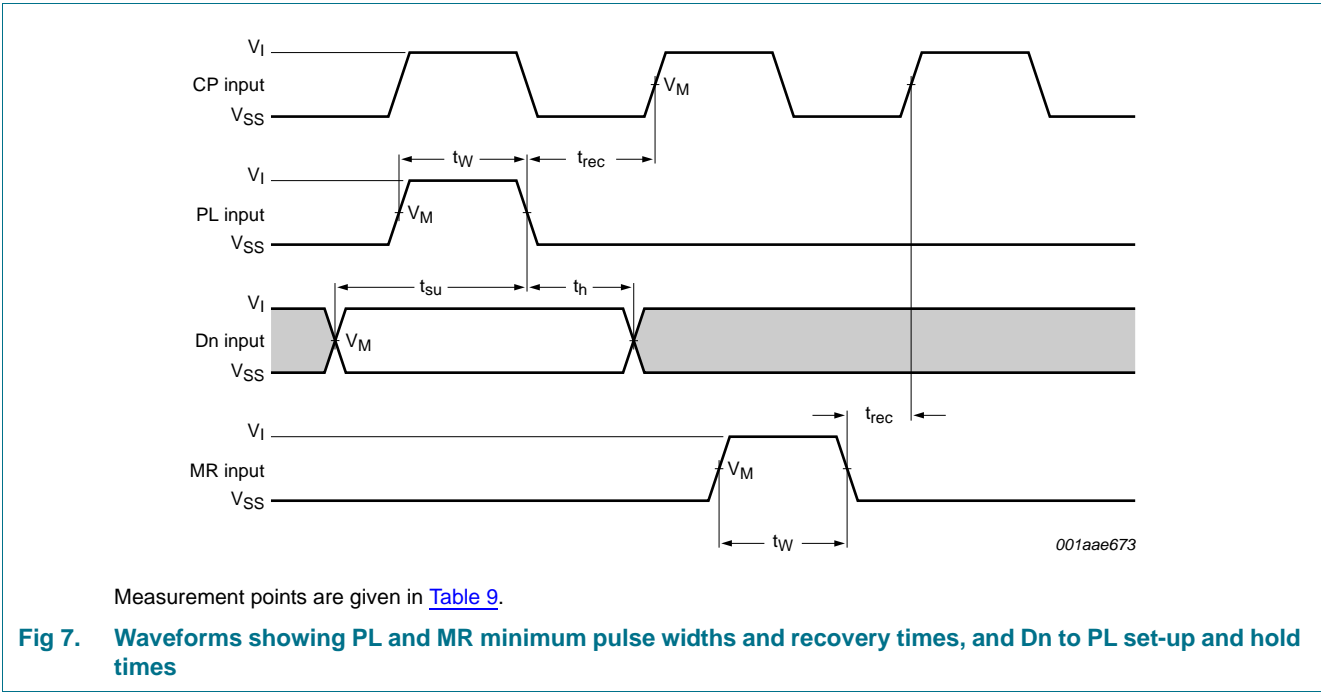
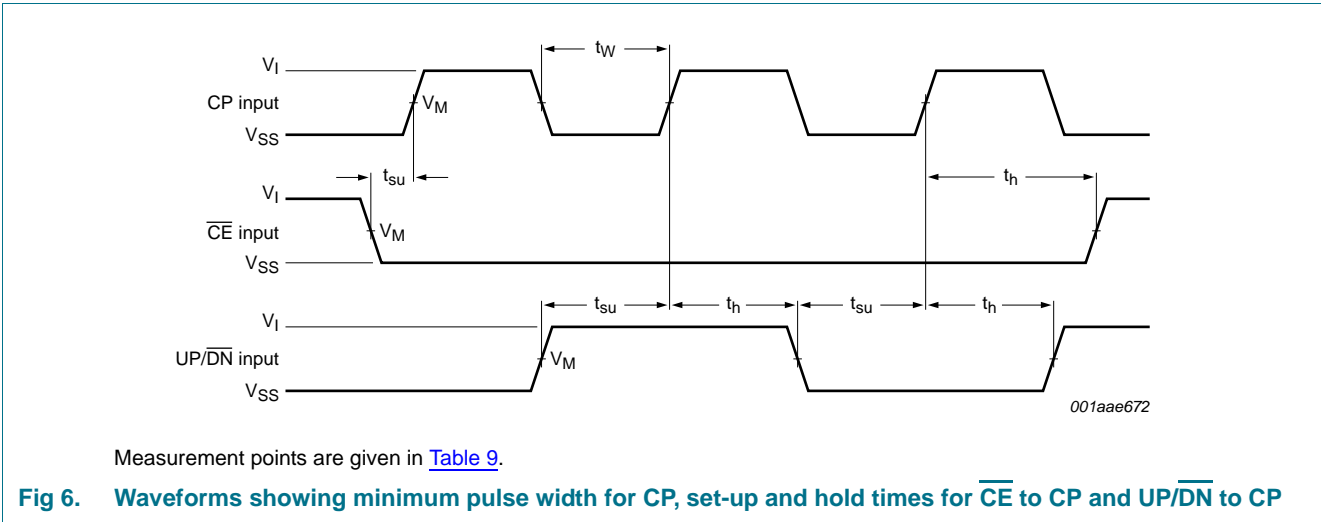
[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C_L in pF).

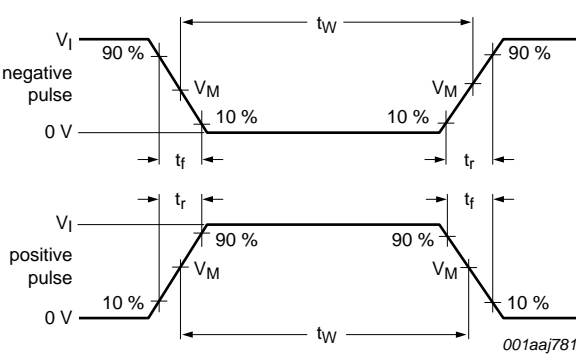
Table 8. Dynamic power dissipation P_D

P_D can be calculated from the formulas shown. $V_{SS} = 0\text{ V}$; $C_L = 50\text{ pF}$; $t_r = t_f \leq 20\text{ ns}$; $T_{amb} = 25\text{ }^\circ\text{C}$.

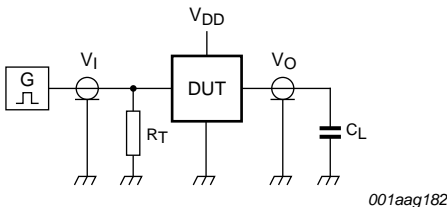
| Symbol | Parameter | V_{DD} | Typical formula for P_D (μW) | Where: |
|--------|---------------------------|----------|---|---|
| P_D | dynamic power dissipation | 5 V | $P_D = 1000 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | f_i = input frequency in MHz; |
| | | 10 V | $P_D = 4500 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | f_o = output frequency in MHz; |
| | | 15 V | $P_D = 11200 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | C_L = output load capacitance in pF; V_{DD} = supply voltage in V; $\Sigma(f_o \times C_L)$ = sum of the outputs. |

11. Waveforms





a. Input waveforms



b. Test circuit

Test data is given in [Table 9](#).

Definitions for test circuit:

DUT = Device Under Test

C_L = Load capacitance including jig and probe capacitance;

R_T = Termination resistance should be equal to output impedance Z_o of the pulse generator.

Fig 8. Test circuit for measuring switching times

Table 9. Measurement points and test data

| Supply voltage | Input | | | Load |
|----------------|----------|----------|----------------------|-------|
| | V_I | V_M | t_r, t_f | C_L |
| 5 V to 15 V | V_{DD} | $0.5V_I$ | $\leq 20 \text{ ns}$ | 50 pF |

12. Package outline

DIP16: plastic dual in-line package; 16 leads (300 mil)

SOT38-4

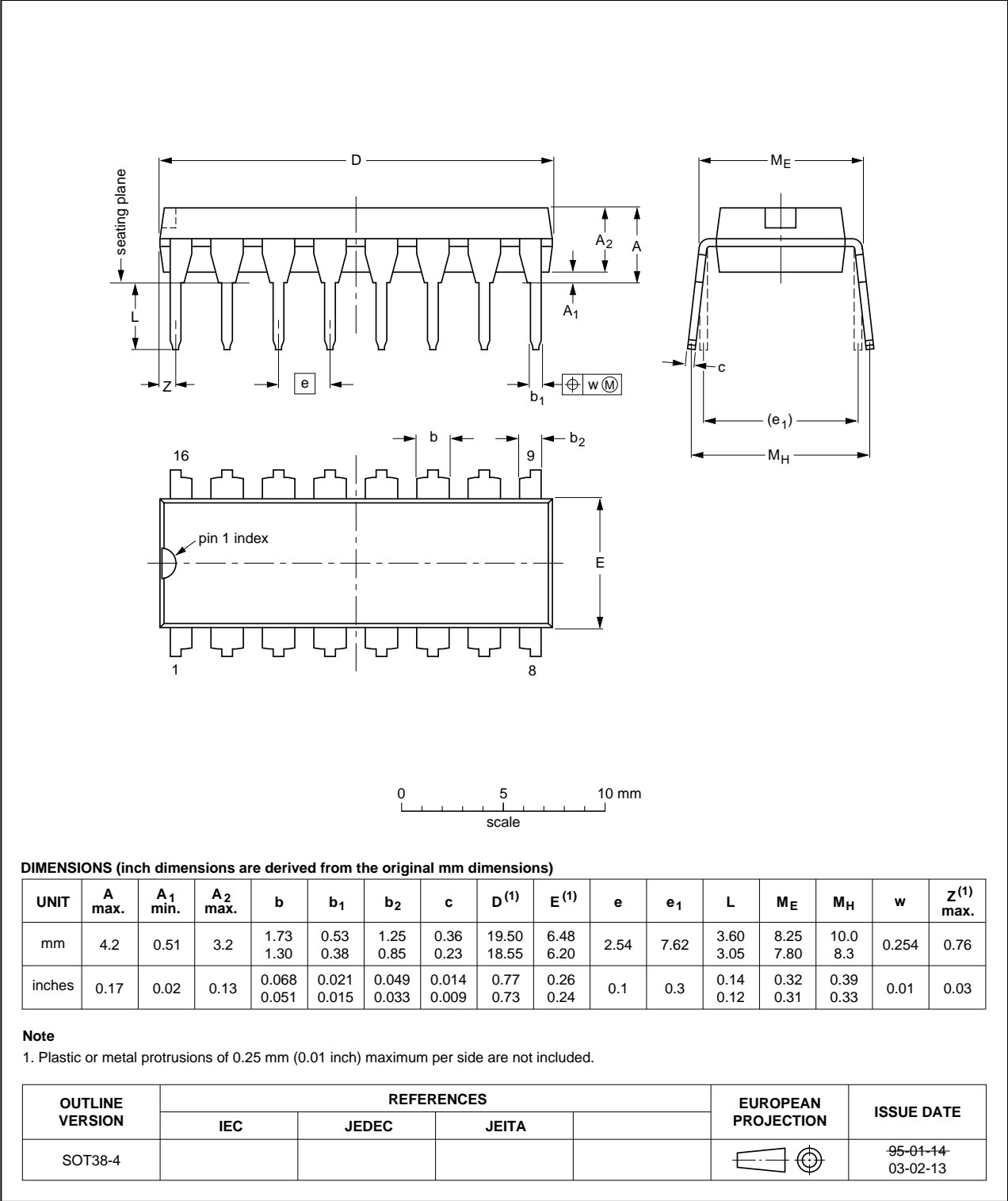


Fig 9. Package outline SOT38-4 (DIP16)

SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1

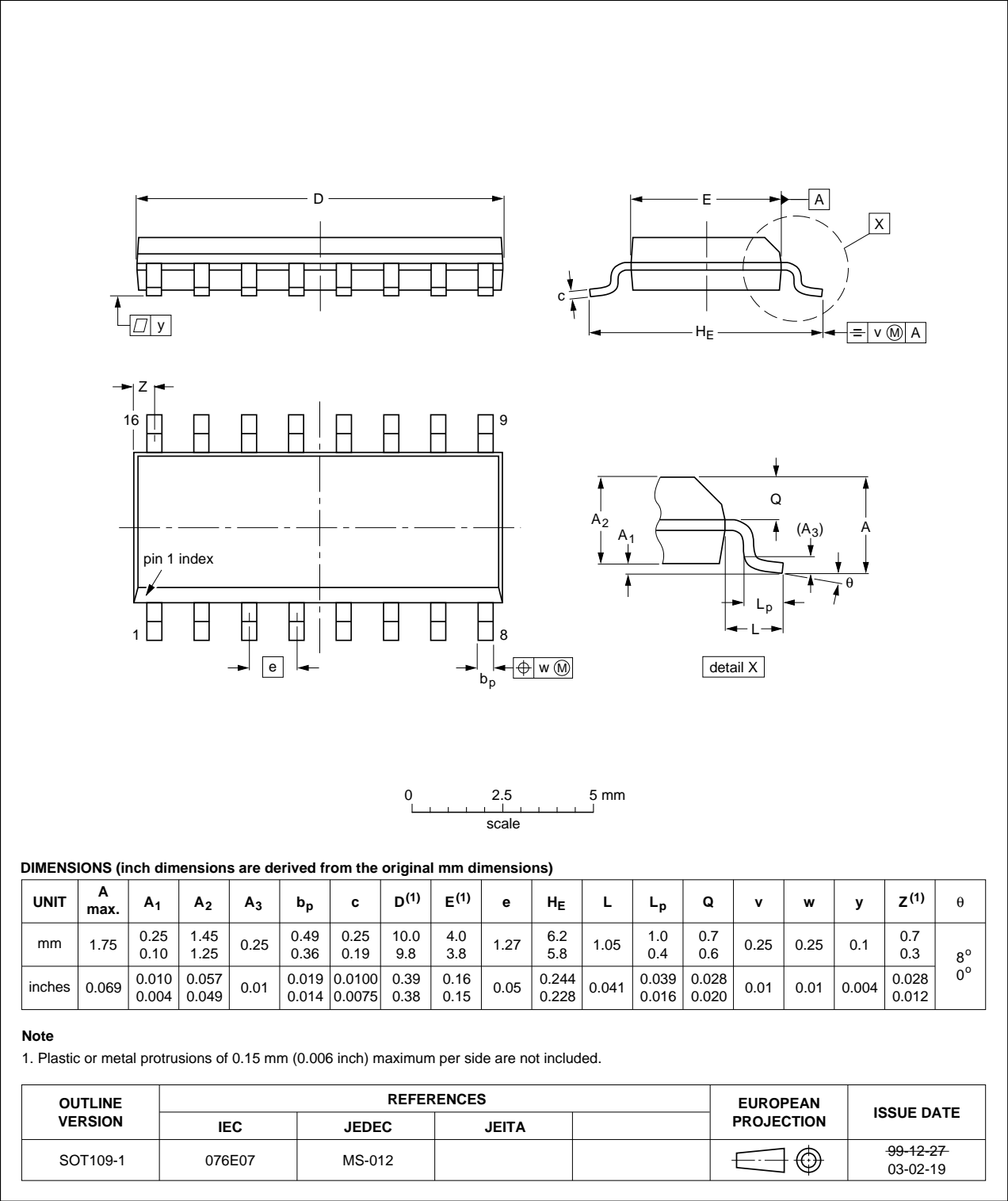


Fig 10. Package outline SOT109-1 (SO16)

13. Revision history

Table 10. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
|------------------|--|-----------------------|---------------|------------------|
| HEF4516B v.7 | 20111111 | Product data sheet | - | HEF4516B v.6 |
| Modifications: | <ul style="list-style-type: none">• Section Applications removed• Table 6: I_{OH} minimum values changed to maximum | | | |
| HEF4516B v.6 | 20091211 | Product data sheet | - | HEF4516B v.5 |
| HEF4516B v.5 | 20090812 | Product data sheet | - | HEF4516B v.4 |
| HEF4516B v.4 | 20090312 | Product data sheet | - | HEF4516B_CNV v.3 |
| HEF4516B_CNV v.3 | 19950101 | Product specification | - | HEF4516B_CNV v.2 |
| HEF4516B_CNV v.2 | 19950101 | Product specification | - | - |

14. Legal information

14.1 Data sheet status

| Document status ^{[1][2]} | Product status ^[3] | Definition |
|-----------------------------------|-------------------------------|---|
| Objective [short] data sheet | Development | This document contains data from the objective specification for product development. |
| Preliminary [short] data sheet | Qualification | This document contains data from the preliminary specification. |
| Product [short] data sheet | Production | This document contains the product specification. |

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <http://www.nxp.com>.

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