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#### **■**General Description

Combining low-power CMOS logic with high-current, high-voltage power FET outputs, the Series SLA706xM translator/drivers provide complete control and drive for a two-phase unipolar stepper motor with internal fixed off time and pulse-width modulation (PWM) control of the output current in a power multi-chip module (PMCM<sup>TM</sup>).

There are no phase-sequence tables, high-frequency control lines, or complex interfaces to program. The CMOS logic section provides the sequencing logic, direction, control, synchronous/asynchronous PWM operation, and a "sleep" function. The minimum CLOCK input is an ideal fit for applications where a complex  $\mu P$  is unavailable or overburdened. TTL or LSTTL may require the use of appropriate pull-up resistors to ensure a proper input-logic high. For PWM current control, the maximum output current is determined by the user's selection of a reference voltage and sensing resistor. The NMOS outputs are capable of sinking up to 1, 2, or 3 A (depending on device) and with standing 46 V in the off state.

Clamp diodes provide protection against inductive transients. Special power-up sequencing is not required.

Half-, quarter-, eighth-, and sixteenth-step operation are externally selectable for the SLA7060/61/62M. Full-, Half-, quarter-, and eighth-step operation are externally selectable for the SLA7065/66/67M

Half-step excitation alternates between the one-phase and two-phase modes (A-AB-B-AB-A-AB-BAB), providing an eight-step sequence.

#### ■ Applications

- $\bullet$ PPC
- Printer
- OA Equipment

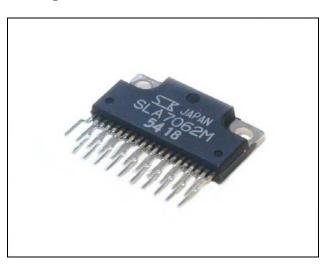
#### **■**Features

- •To 3 A Output Rating
- •Internal Sequencer for Microstepping Operation
- ●PWM Constant-Current Motor Drive
- $\bullet Cost\text{-}Effective, Multi-Chip Solution \\$
- •100 V, Avalanche-Rated NMOS Outputs
- •Low rDS(on) NMOS Outputs (150 milli-ohms typical)
- •Advanced, Improved Body Diodes
- •nputs Compatible with 3.3 V or 5 V Control Signals

S-GND

- •Sleep Mode
- •Internal Clamp Diodes

#### **■**Package



#### **■Key Specifications**

•Motor Supply Voltage (VM): 44V max

•Load Supply Voltage (Vs) : 10V∼44V

•Logic Supply Voltage (Vcc) : 3V∼5.5V

•Output Current (Io): 1A(SLA7060M,SLA7065M)

2A(SLA7061M,SLA7066M)

3A(SLA7062M,SLA7067M)

ullet Output Maximum Voltage (V<sub>DSS</sub>) : 100V min

# Typical Connection V<sub>BB</sub>=V<sub>M</sub>=10~44V V<sub>DD</sub>=3.0~5.5V Disable R<sub>1</sub> C<sub>1</sub> B<sub>2</sub> B<sub>3</sub> C<sub>4</sub> C<sub>5</sub> C<sub>6</sub> 16 1 2 3 4 18 19 20 21 Reset 8 CW/CCW 9 Clock 10 M2 13 M0 14 Sync 15 7 5 11 17 No R<sub>SB</sub> R<sub></sub>

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I03-003EA-051006

P-GND



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## Scope

The present specifications shall apply to a micro-stepping capable 2-phase unipolar stepper motor

driver IC, SLA706xM Series.

The present specifications shall apply to SLA706xM Series which is performed RoHS instructions.

Lead part solder: Pb free Inner solder: Lead content >85%

#### **Outline**

Type	Hybrid integrated circuit			
Structure	Plastic molded (transfer mold)			
Applications	To drive a 2-phase stepper motor. (Micro-Stepping Capable. PWM Constant-Current Control.)			

#### Absolute maximum ratings

Characteristic	Symbol	Ratings	Unit	Remarks
Load Supply Voltage	$V_{\mathrm{M}}$	46	V	
Main Power Supply Voltage	$V_{\mathrm{BB}}$	46	V	
Logic Supply Voltage	$V_{\mathrm{DD}}$	7	V	
		1.0		SLA7060M,SLA7065M
Output Current	$Io^*$	2.0	A	SLA7061M,SLA7066M
		3.0		SLA7062M,SLA7067M
Logic Input Voltage	$V_{\rm IN}$	-0.3∼V <sub>DD</sub> +0.3	V	
REF Input Voltage	$V_{\mathrm{REF}}$	-0.3∼V <sub>DD</sub> +0.3	V	
Sense Voltage	$V_{ m RS}$	±2	V	Tw<1µS doesn't contain it.
Dower Dissination	PD	3.5	W	at Ta=25℃
Power Dissipation	ΓD	16	W	at Tc=25°C
Junction Temperature	$T_{\rm j}$	150	°C	
Operating Temperature Range	$T_{a}$	-20~85	°C	
Storage Temperature Range	$T_{ m stg}$	-30~150	°C	

<sup>\*</sup>Output current rating may be limited by duty cycle, ambient temperature, and heat sinking.

Under any set of conditions, do not exceed the specified junction temperature(T<sub>i</sub>).



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#### **Electrical characteristics**

Recommendable Operating Range

Characteristic	Symbol	Ratings			Remarks
Characteristic	Symbol	MIN	MAX	Unit	Remarks
Load Supply Voltage	$V_{\mathrm{M}}$		44	V	
Main Power Supply Voltage Range	$V_{\mathrm{BB}}$	10	44	V	
Logic Supply Voltage Range	$V_{\mathrm{DD}}$	3.0	5.5	V	Please adjust the Vcc surge voltage to 0.5V or less.
REF Input Voltage Range	$ m V_{REF}$	0.1	1.0	V	The control current accuracy decreases in 0.1V or less.
Case Temperature	$T_{\mathrm{C}}$		90	°C	11Pin temperature (at No Fin)

Electrical Characteristic (T<sub>a</sub>=25°C,V<sub>BB</sub>=24V,V<sub>DD</sub>=5V Unless Otherwise Noted.)

Characteristic	Crashol	Limits		Unit	Test Condition	
Characteristic	Symbol	Min.	Тур.	Max.	Unit	lest Condition
Main Power Supply Current	${ m I}_{ m BB}$			15	mA	Regularity
Maii i ower Supply Current	$I_{\mathrm{BBS}}$			100	μΑ	at SLEEP operates
Logic Supply Current	${ m I}_{ m DD}$			4	mA	
Drain-Source Breakdown	V <sub>(BR)DS</sub>	100			V	$V_{BB}=44V$
Drain Source Breakdown	V (BR)DS	100			V	I <sub>D</sub> =1mA
Output On Resistance	R <sub>DS</sub> (on)		0.25	0.4	Ω	I <sub>D</sub> =2A
Body Diode Forward Voltage	$V_{\mathrm{F}}$		0.95	1.2	V	I <sub>F</sub> =2A
Maximum Clock Frequency	${ m f_{clk}}$	$250^{*}$			kHz	duty=50%
Logio Input Voltago	$V_{\rm IL}$			$0.25~\mathrm{V}_\mathrm{DD}$	V	
Logic Input Voltage	$V_{\mathrm{IH}}$	$0.75 V_{\rm DD}$			V	
	${ m I}_{ m IL}$		±1		μΑ	Clock, Reset,
Logio Irany et Commont	${ m I}_{ m IH}$		±1		μΑ	CW/CCW, Sync
Logic Input Current	${ m I}_{ m ILM}$	-75	-50	-25	μΑ	M1,M2
	$I_{IHM}$		±1		μΑ	1011,1012
REF Input Voltage Range	$V_{\mathrm{REF}}$	0		1.5	V	Stationary current control
KEF Input voltage Kange	$V_{\rm REFS}$	2.0		$V_{ m DD}$	V	at SLEEP operates
REF Input Current	$I_{ m REF}$		±10		μΑ	V <sub>REF</sub> =0~V <sub>DD</sub>
Ma Output Voltage	$V_{\mathrm{MOL}}$			1.25	V	$I_{MOL}$ =1.5mA
Mo Output Voltage	$V_{\mathrm{MOH}}$	$V_{\rm DD}$ –1.25			V	I <sub>MOH</sub> =-1.5mA
Mo Output Current	$I_{ m MOL}$			3	mA	
Ivio Output Current	Імон	-3			mA	

<sup>\*</sup>Operation at a step frequency greater than the specified minimum value is possible but not warranted.

Note.

Negative current is defined as coming out of the specified pin.



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Electrical Characteristic(continued) (T<sub>a</sub>=25°C,V<sub>BB</sub> =24V,V<sub>DD</sub> =5V Unless Otherwise Noted.)

Cl		20 C, V BB	Limits		TT '/	m + C 1'-
Characteristic	Symbol	Min.	Тур.	Max.	Unit	Test Condition
Sense Voltage	$V_{ m SENSE}$	0.95	1.00	1.05	V	V <sub>REF</sub> =1.0V
						at Mode F
Sense pins Sink Current	Isense		±10		μA	
	Mode F		100		%	
	Mode E		98.1		%	
	Mode D**		95.7		%	
	Mode C		92.4		%	
	Mode B <sup>™</sup>		88.2		%	
	Mode A		83.1		%	
	Mode 9**		77.3		%	1000/
Step Reference Current Ratio	Mode 8		70.7		%	$V_{\rm SENSE}$ =100% $V_{\rm REF}$ =0.1~1V
	Mode 7**		63.4		%	
	Mode 6		55.5		%	
	Mode 5**		47.1		%	
	Mode 4		38.2		%	
	Mode 3**		29.0		%	
	Mode 2		19.5		%	
	Mode 1**		9.8		%	
Wake-Up time	$t_{ m SE}$	100			μs	$V_{REF}: 2.0 \rightarrow 1.5V$
	$\mathrm{t}_{\mathrm{pdon}}$		2.0		μs	Clock→Out ON
Switching Time	$ m t_{pdoff}$		1.5		μs	$\begin{array}{ccc} \text{Clock} & \to & \text{Out} \\ \text{OFF} & & & \end{array}$
PWM Minimum On Time	ton(min)		1.8		μs	
	toff1		12		μs	Mode 8~F
PWM OFF Time	$t_{ m OFF2}$		9		μs	Mode 4~7
N-4-	t <sub>OFF3</sub>		7		μs	Mode 1~3

#### Note.

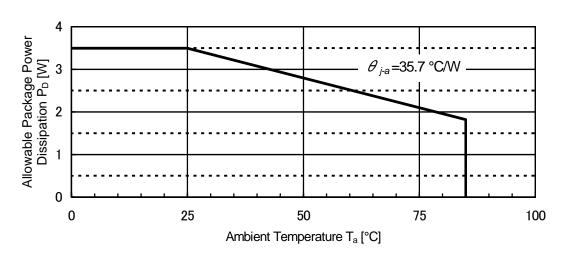
- Negative current is defined as coming out of the specified pin.
- SLA7065M, SLA7066M, and SLA7067M of the item of \* sign of Step Reference Current Ratio are off the subject.



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熱設計データ Thermal Design Data

#### Thermal Ratings



#### Truth Table

#### • Input Pin

Pin Name	Low Level	High Level	Clock
Reset	Run	Logic Reset	-
CW/CCW	Forward (CW)	Reverse (CCW)	<b>—</b>
M1 M2	Micro-Stepping Ope	Micro-Stepping Operation Mode Setting	
REF	Enable	Sleep Mode	
Sync	Asynchronous PWM operation	Synchronous PWM operation	-



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Micro-Stepping Operation Mode Setting

[SLA7060M, SLA7061M, SLA7062M]

Operation Mode	Input Level		
Operation Mode	M1	M2	
4W 1-2phase (1/16 Step)	L	L	
2W 1-2phase (1/8 Step)	L	Н	
W 1-2phase (1/4 Step)	Н	L	
1-2phase (1/2 Step)	Н	Н	

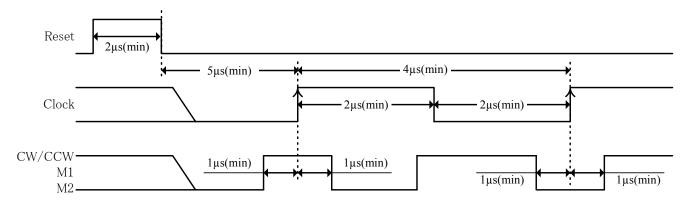
#### [SLA7065M, SLA7066M, SLA7067M]

Operation Made	Input Level		
Operation Mode	M1	M2	
2W 1-2phase (1/8 Step)	L	L	
W 1-2phase (1/4 Step)	L	Н	
1-2phase (1/2 Step)	Н	L	
2-2phase (Full Step)	Н	Н	

## • Output Pin

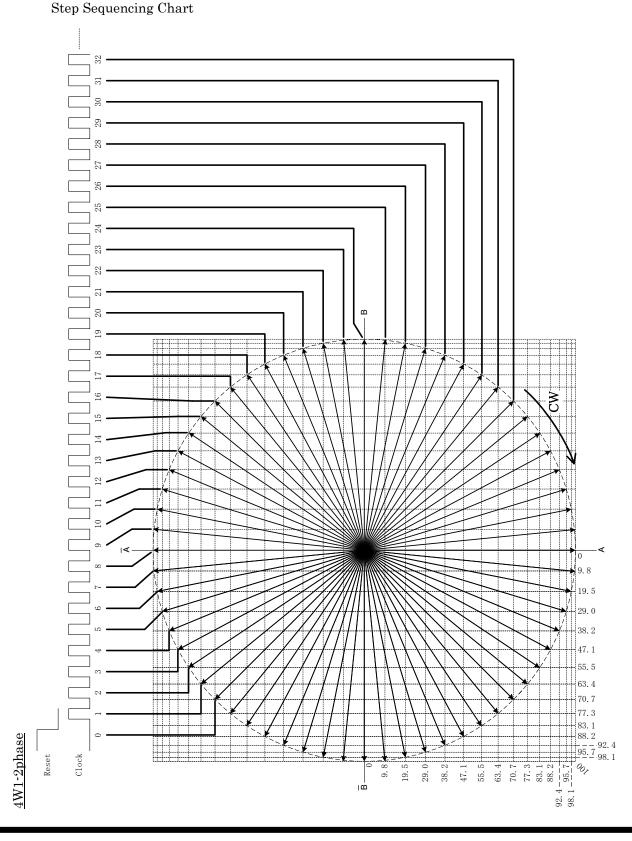
Pin Name	High Level	Low Level
Mo	Half-Step Position (Mode 8)	-

#### Logic Input Timing Requirements





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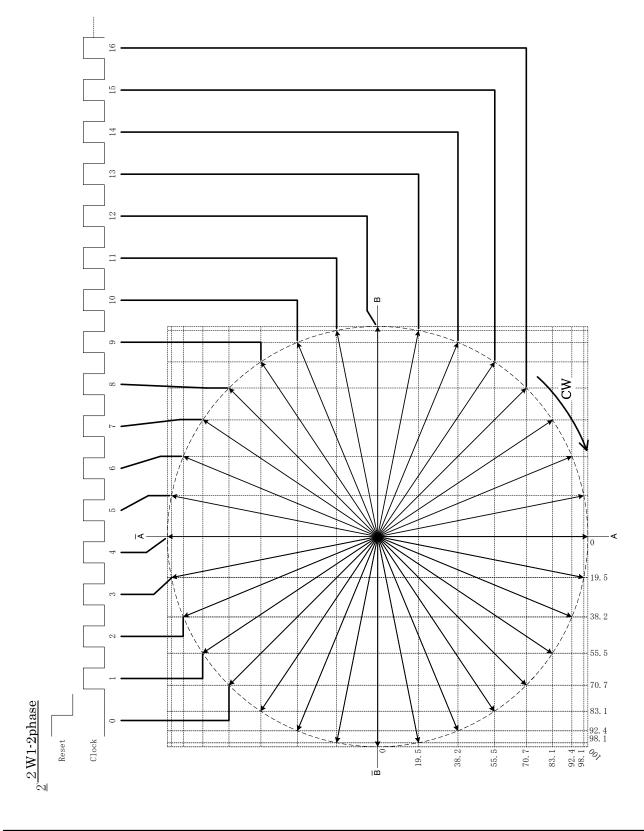
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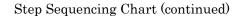
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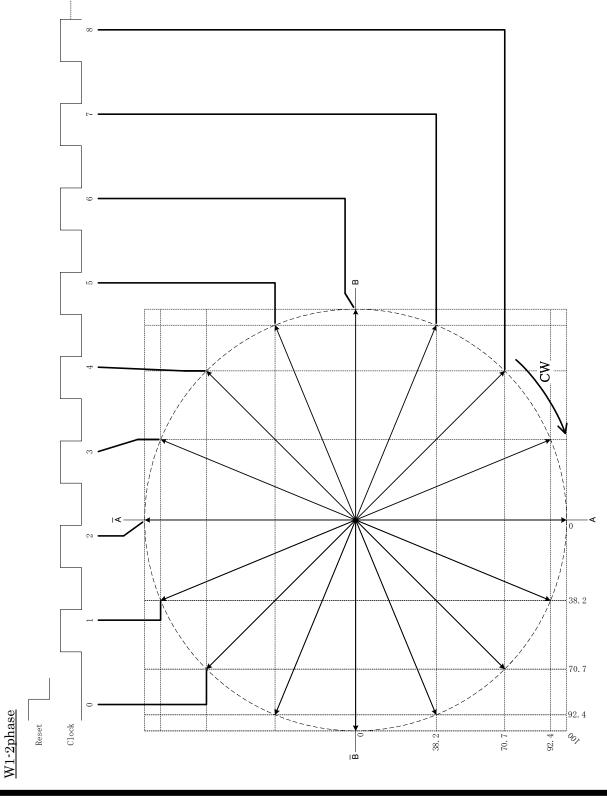
Step Sequencing Chart (continued)





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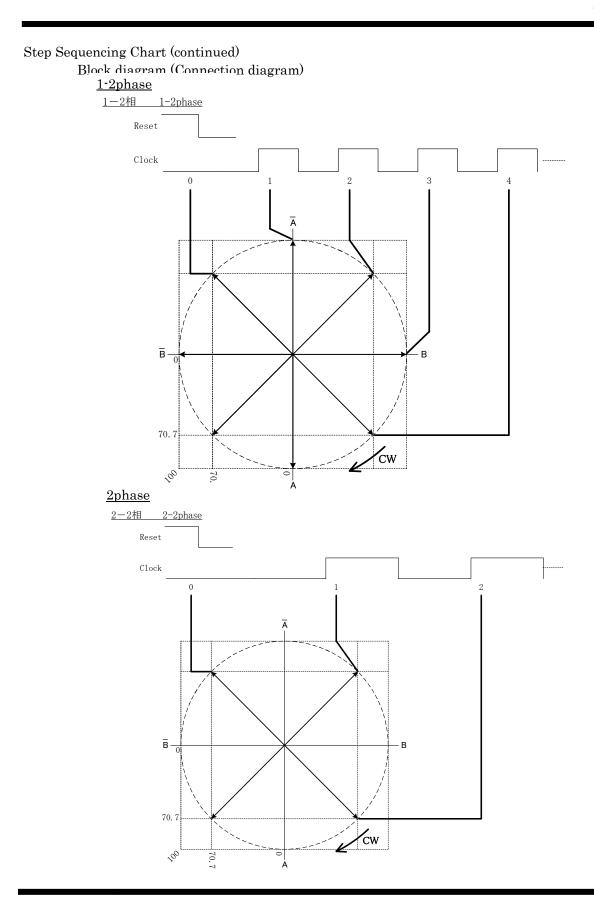


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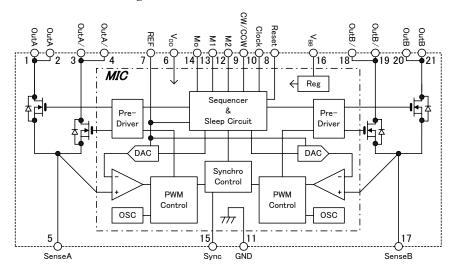
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## Internal functional block diagram



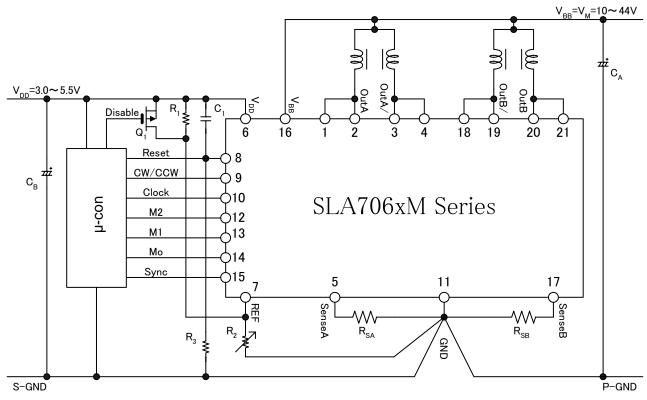
Pin Assignment (Terminal Functions)

Pin Assign	ment (1erm	ninal Functions)		
Pin No.	Symbol	Function		
1	OutA	Phase A Output		
2	Oddi	I hase it output		
3	OutA/	Phase A/ Output		
4	Odur	_		
5	SenseA	Phase A Current Sense		
6	$V_{ m DD}$	Logic Supply		
7	REF	Control Current Set & OFF Output		
8	Reset	Reset Input for Logic Circuit		
9	CW/CC	Forward / Reverse Switch Input		
	W	Forward / Reverse Switch input		
10	Clock	Step Clock Input		
11	GND	GND		
12	M2	Micro-Stepping Operation Mode		
13	M1	Setting Input		
14	Mo	Position Monitoring Output		
15	Sync	PWM Chopping Function Select		
10	Sync	Input		
16	$V_{\mathrm{BB}}$	Main Power Supply (For Motor)		
17	SenseB	Phase B Current Sense		
18	OutB/	Phase B/ Output		
19	Outbi	I hase Di Output		
20	OutB	B 相出力 Phase B Output		
21	Outb	Блаве в Output		



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## **Example application circuit**



Reference constant

 $R_{SA}$ ,  $R_{SB}$  = 0.1  $\sim$  2 $\Omega$  ( $\gtrsim$  Loss attention  $P = Io^2 \times R_S$ )

 $R_1 = 10 k\Omega$ 

 $R_2 = 5.1 k\Omega(VR)$ 

 $R_3 = 10 k\Omega$ 

 $C_A = 100 \mu F / 50 V$ 

 $C_B = 10 \mu F / 10 V$ 

 $C_1 = 0.1 \mu F$ 

 $\stackrel{\star}{\sim}$  Precaution to avoid the noise on  $V_{DD}$  line.

Switching noise from PCB traces, where high current flows, to the  $V_{\text{DD}}$  line should be minimized

because the noise level more than 0.5V on the  $V_{DD}$  line may cause malfunctioning operation.

The tip for avoiding such problem is to separate the logic GND (S-GND) and the power GND (P-GND) on a PCB,

and then connect them together at IC GND pin (#11).

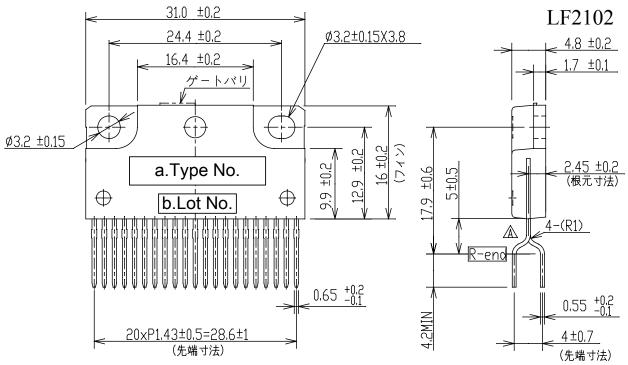
☆The loss of 'Rs' resistance will occur.



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#### **Package information**

Package type and physical dimensions



a. Type Number

SLA706xM

b.Lot Number

1st letter

The last digit of year

2nd letter

Month  $1{\sim}9$ 月:Arabic Numerals

10月:0

11月:N

12月:D

3rd &4th letter

Day

 $01 \sim 31$ : Arabic Numerals

Dimensions in millimeters Material of terminal: Cu

31.3 ±0.2

Treatment of terminal: Ni planting + solder dip (Pb Free)

7 9 11 13 15 17 19 21 6 8 10 12 14 16 18 20

#### Appearance

The body shall be clean and shall not bear any stain, rust or flaw.

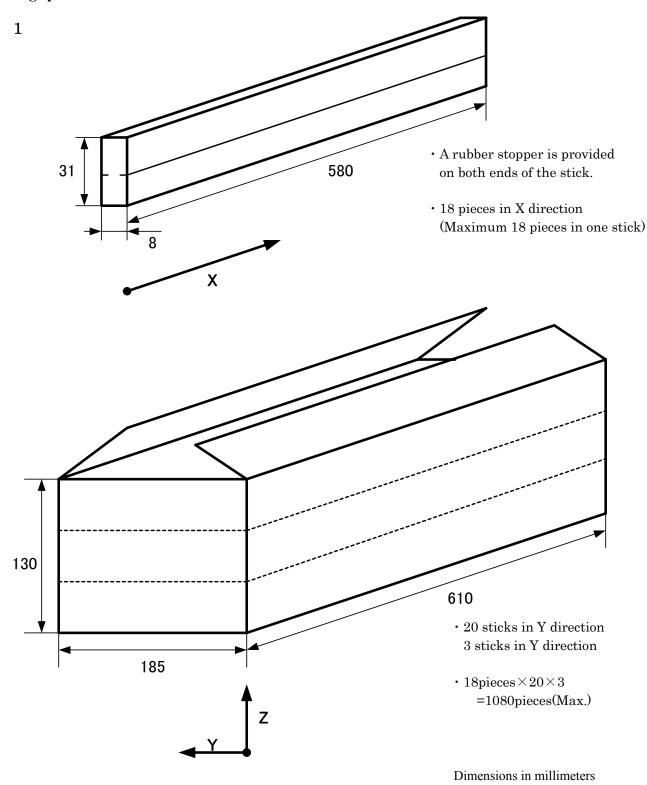
#### Marking

The type number and lot number shall be clearly marked in white.



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## **Packing specifications**





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#### Cautions and warnings

The calculation of control current

SLA706xM Series control current Io (at Mode F) is calculated as follow.

$$I_O = \frac{V_{REF}}{R_S}$$

REF voltage is recommended to be from 0.1 to 1.0V.

\*When the REF<0.1V, the accuracy of the current control becomes worst.

Moreover, setting the REF voltage more than 2V activates the sleep mode (all outputs is in OFF state).

However, the internal logic circuit is alive.

Logic inputs/output (RESET, CLOCK, CW/CCW, M1, M2, SYNC, Mo)

- Following timing should comply with the "Logic input timing".
  - -The rising edge timing of CW/CCW, M1, M2 and that of CLOCK input
  - -The RESET release timing(=the falling edge on RESET input) and the rising edge timing of CLOCK input
  - \*In case it does not comply with the "Logic input timing", it may operate at an unexpected sequence.
- Be sure to prevent the logic inputs(RESET, CLOCK, CW/CCW, M1, M2, SYNC) from being "OPEN".

If some of the logic inputs are not used, be sure to connect them to VDD or GND.

- \*In case some of the logic inputs stay "OPEN", a malfunction may occur due to external noises.
- When the logic output(Mo) is not used, be sure to keep it "OPEN".
  - \*In case it is connected to VDD or GND, it may cause the device's deterioration or/and breakdown.

Installation to a heat sink

- 1) Recommended Clamping Torque (to External Heat sink) 0.490~0.822N·m
- 2) Recommended Silicone G746 {SHIN-ETSU CHEMICAL}

YG6260 {TOSHIBA SILICONE}

SC102 {DOW CORNING TORAY SILICONE}

#### Notice

This driver has C-MOS inputs. Please notice as following contents.

- When static electricity is a problem, care should be taken to properly control
  the room humidity. This is particularly true in the winter when static
  electricity is most troublesome.
- Care should be taken with device leads and with assembly sequencing to avoid applying static charges to IC leads. PC board pins should be shorted together to keep them at the same potential to avoid this kind of trouble.



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