

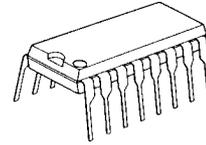
BRUSH LESS DC MOTOR PRE-DRIVER

■GENERAL DESCRIPTION

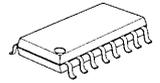
The **NJM2624A** is a 3-phase brushless DC motor pre-driver which requires external power-transistors suited to drive current of the motor.

The Run Enable function is used as PWM control besides of ON/OFF switched function.

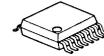
■PACKAGE OUTLINE



NJM2624AD



NJM2624AM

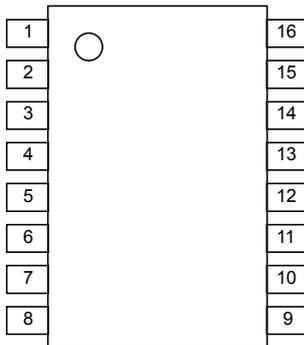


NJM2624AV

■FEATURES

- Operating Voltage (V⁺=4.5V to 18V)
- Low Operating Current (10mA max.)
- Run Enable
- Forward or Reverse Direction
- Output Switch Current (90mA typ.)
- Bipolar Technology
- Package Outline DIP16, DMP16, SSOP16

■PIN CONFIGURATION

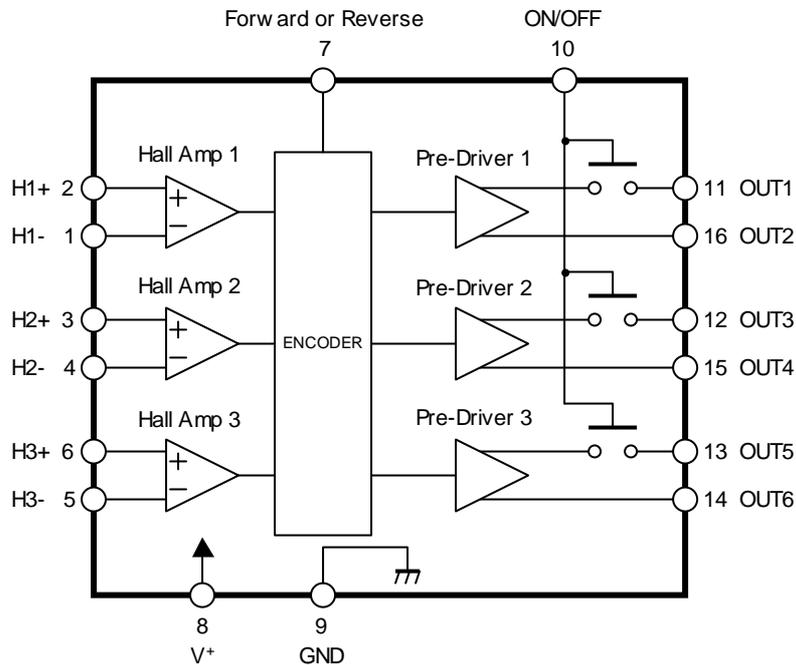


PIN FUNCTION

| | |
|------------------|-----------|
| 1.H1- | 9.GND |
| 2.H1+ | 10.ON/OFF |
| 3.H2+ | 11.OUT1 |
| 4.H2- | 12.OUT3 |
| 5.H3- | 13.OUT5 |
| 6.H3+ | 14.OUT6 |
| 7.FR | 15.OUT4 |
| 8.V ⁺ | 16.OUT2 |

NJM2624A

■ BLOCK DIAGRAM



■ ABSOLUTE MAXIMUM RATINGS (Ta=25°C)

| PARAMETER | SYMBOL | RATINGS | UNIT |
|-----------------------------|------------------|--|------|
| Supply Voltage | V ⁺ | 20 | V |
| Output Current | I _o | 100 | mA |
| Power Dissipation | P _D | (DIP16) 700 (DMP16) 350 (SSOP16) 300 | mW |
| Operating Temperature Range | T _{opr} | -25 to +85 | °C |
| Storage Temperature Range | T _{stg} | -40 to +150 | °C |

■ RECOMMENDED OPERATING CONDITIONS (Ta=25°C)

| PARAMETER | SYMBOL | MIN. | TYP. | MAX. | UNIT |
|--------------------------------------|------------------|------|------|----------------------|------|
| Input Common Mode Voltage Range (*1) | V _{ICM} | 1.5 | - | V ⁺ - 1.5 | V |

(*1) The input voltage should set within V_{ICM} range in consideration of the peak magnitude.
When the input voltage exceeds V_{ICM} range, unusual operation may be caused.

■ELECTRICAL CHARACTERISTICS (V⁺=12V, Ta=25°C)

Total Device

| PARAMETER | SYMBOL | TEST CONDITONS | MIN. | TYP. | MAX. | UNIT |
|----------------|-----------------|------------------------------|------|------|------|------|
| Supply Voltage | V ⁺ | | 4.5 | – | 18 | V |
| Supply Current | I _{CC} | RL=∞ ON/OFF Terminal=OPEN | – | 3.7 | 10 | mA |

Hall Sensor Section

| | | | | | | |
|---------------------------------|------------------|---------|------|---|------|----|
| Input Offset Voltage | V _{IO} | RL=470Ω | -4.2 | – | 4.2 | mV |
| Input Common mode Voltage range | V _{ICM} | RL=470Ω | 1.5 | – | 10.5 | V |
| Input Bias Current | I _B | | – | – | 600 | nA |

Output Section

| | | | | | | |
|--------------------------|-------------------|------------------------------|-----|-----|---|----|
| Output Voltage 1 | V _{OUT1} | RL=470Ω, V ⁺ =12V | 8.9 | 9.5 | – | V |
| Output Voltage 2 | V _{OUT2} | RL=470Ω, V ⁺ =5V | – | 3.5 | – | V |
| Maximum Output Current 1 | I _{OUT1} | RL=100Ω, V ⁺ =12V | 50 | 90 | – | mA |
| Maximum Output Current 2 | I _{OUT2} | RL=100Ω, V ⁺ =5V | – | 30 | – | mA |
| Output Leak Current | I _{LEAK} | | – | – | 5 | μA |

Run Enable Section

| | | | | | | |
|-------------------------------|----------------------|---------------------|------------------------|-------------------|------------------------|----|
| Run Enable Voltage | V _{ON} | RL=470Ω | 1/2V ⁺ +0.5 | – | – | V |
| Run Disable Voltage | V _{OFF} | RL=470Ω | – | – | 1/2V ⁺ -0.5 | V |
| Output Voltage Undefined Area | V _{O-undef} | RL=470Ω | 1/2V ⁺ -0.5 | 1/2V ⁺ | 1/2V ⁺ +0.5 | V |
| Source Current 1 | I _{ON1} | ON/OFF Terminal=GND | – | 250 | 400 | μA |

Forward or Reverse Direction Section

| | | | | | | |
|--------------------------|-----------------------|---------------------------------|------------------------|-------------------|------------------------|----|
| Forward Direction | V _F | RL=470Ω | 1/2V ⁺ +0.5 | – | – | V |
| Reverse Direction | V _R | RL=470Ω | – | – | 1/2V ⁺ -0.5 | V |
| F/R Logic Undefined Area | V _{SW-undef} | RL=470Ω | 1/2V ⁺ -0.5 | 1/2V ⁺ | 1/2V ⁺ +0.5 | V |
| Source Current 2 | I _{ON2} | Forward or Reverse Terminal=GND | – | 250 | 400 | μA |

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■ TERMINAL DESCRIPTION

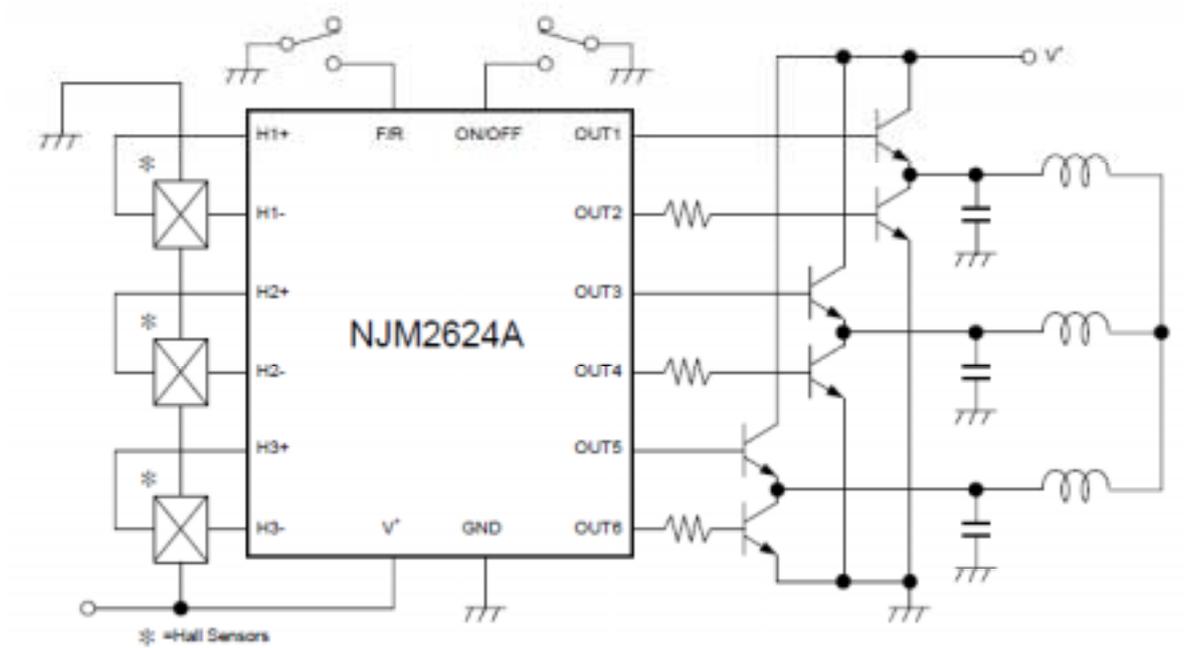
| Pin No, | SYMBOL | FUNCTION | INSIDE EQUIVALENT CIRCUIT |
|---------|--------|--|---------------------------|
| 2 | H1+ | Sensor Input 1 Non-Inverting Terminal | |
| 3 | H2+ | Sensor Input 2 Non-Inverting Terminal | |
| 6 | H3+ | Sensor Input 3 Non-Inverting Terminal | |
| 1 | H1- | Sensor Input 1 Inverting Terminal | |
| 4 | H2- | Sensor Input 2 Inverting Terminal | |
| 5 | H3- | Sensor Input 3 Inverting Terminal | |
| 7 | F/R | Forward or Reverse Direction Terminal | |

■ TERMINAL DESCRIPTION

| Pin No, | SYMBOL | FUNCTION | INSIDE EQUIVALENT CIRCUIT |
|---------|----------------|---|---------------------------|
| 8 | V ⁺ | Power Supply | - |
| 9 | GND | Ground | - |
| 10 | ON/OFF | Output Run Enable Terminal | |
| 11 | OUT1 | Internal Switching Transistor Emitter Follower | |
| 16 | OUT2 | | |
| 12 | OUT3 | | |
| 15 | OUT4 | | |
| 13 | OUT5 | | |
| 14 | OUT6 | | |

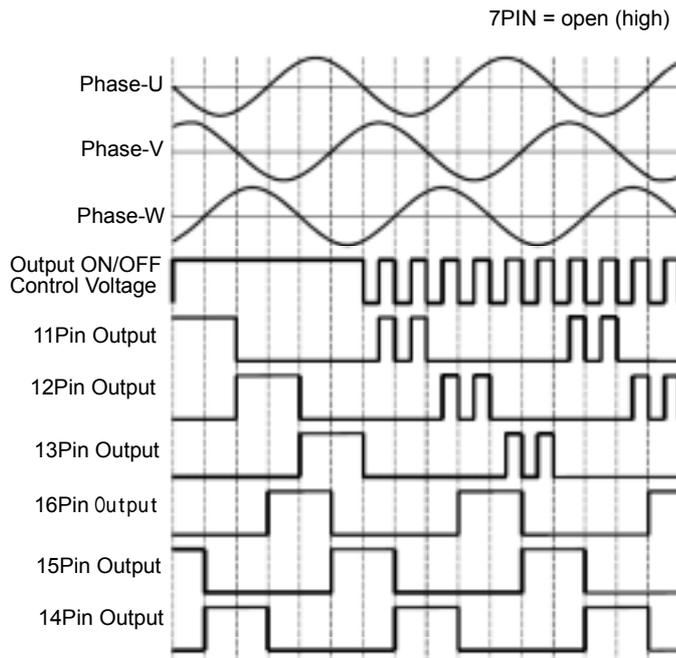
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■ TYPICAL APPLICATION

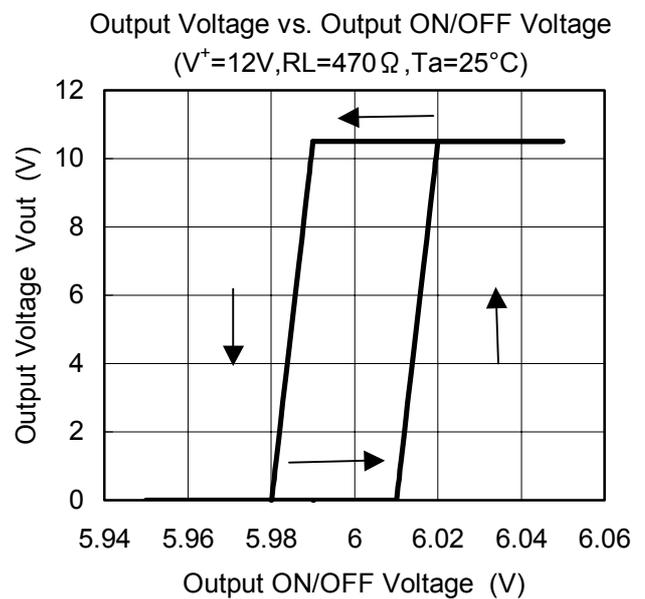
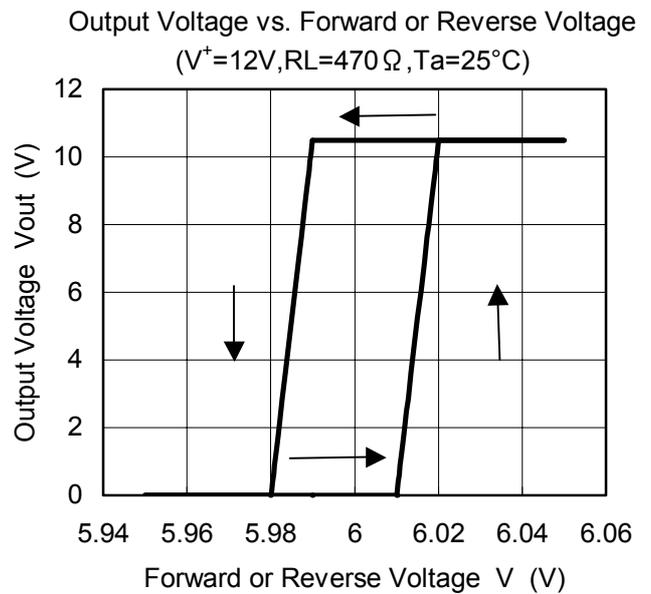
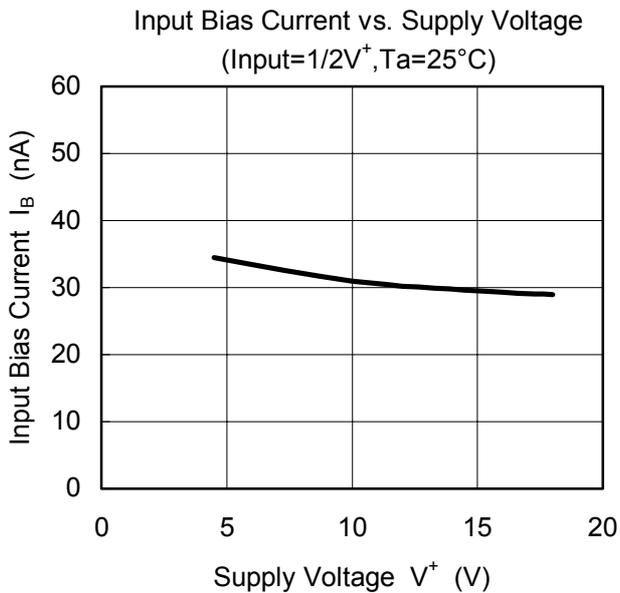
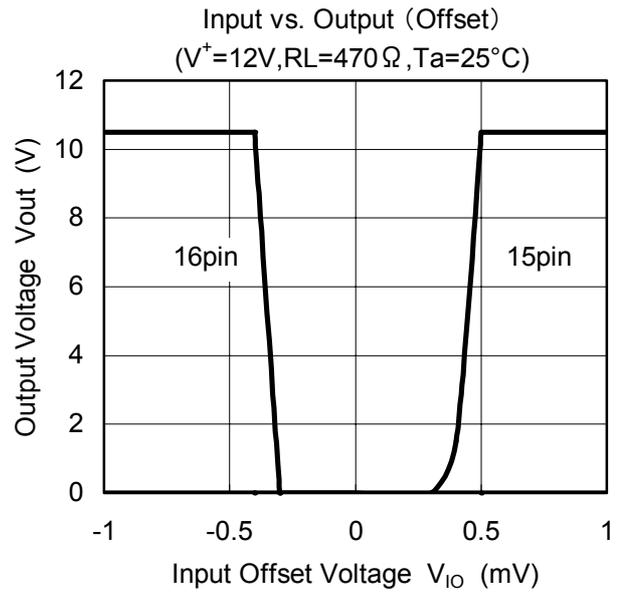
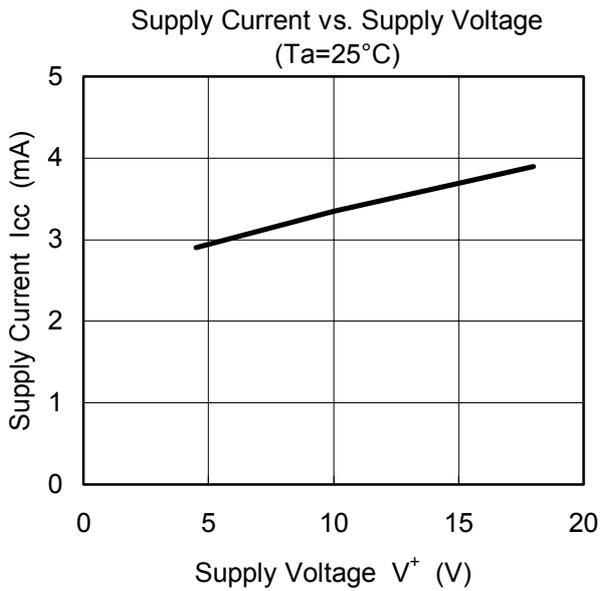


- A rotation direction change must be made after motor stopped completely.
- When PWM duty is extremely small, two or more switching elements can not be driven entirely. In such case, switching elements will generate excess heat and it may cause destruction of the switching devices. Therefore, extensive heat evaluation is necessary for switching device selection particularly in consideration of the area of safety operation (ASO).

■ TIMING CHART



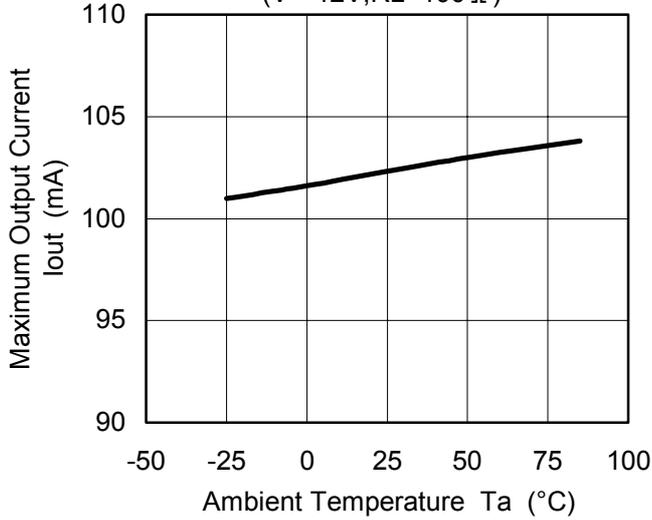
TYPICAL CHARACTERISTICS



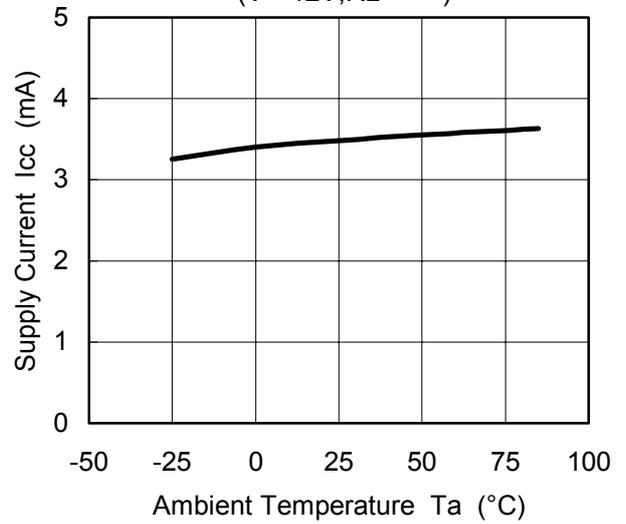
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TYPICAL CHARACTERISTICS

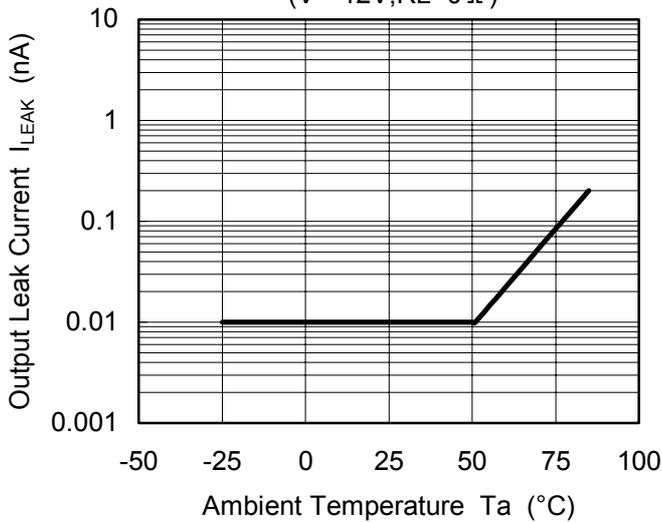
Maximum Output Current vs. Temperature
($V^+ = 12V, R_L = 100\Omega$)



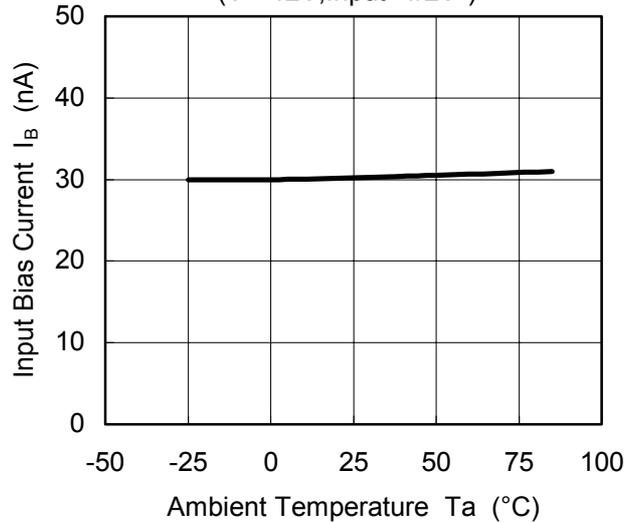
Supply Current vs. Temperature
($V^+ = 12V, R_L = \infty$)



Output Leak Current vs. Temperature
($V^+ = 12V, R_L = 0\Omega$)



Input Bias Current vs. Temperature
($V^+ = 12V, Input = 1/2V^+$)



[CAUTION]

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