

DATA SHEET

For a complete data sheet, please also download:

- The IC04 LOCMOS HE4000B Logic Family Specifications HEF, HEC
- The IC04 LOCMOS HE4000B Logic Package Outlines/Information HEF, HEC

HEF4017B

MSI

5-stage Johnson counter

Product specification
File under Integrated Circuits, IC04

January 1995

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DESCRIPTION

The HEF4017B is a 5-stage Johnson decade counter with ten spike-free decoded active HIGH outputs (O_0 to O_9), an active LOW output from the most significant flip-flop (\overline{O}_{5-9}), active HIGH and active LOW clock inputs (CP_0 , \overline{CP}_1) and an overriding asynchronous master reset input (MR).

The counter is advanced by either a LOW to HIGH transition at CP_0 while \overline{CP}_1 is LOW or a HIGH to LOW transition at \overline{CP}_1 while CP_0 is HIGH (see also function table).

When cascading counters, the \overline{O}_{5-9} output, which is LOW while the counter is in states 5, 6, 7, 8 and 9, can be used to drive the CP_0 input of the next counter.

A HIGH on MR resets the counter to zero ($O_0 = \overline{O}_{5-9} = \text{HIGH}$; O_1 to $O_9 = \text{LOW}$) independent of the clock inputs (CP_0 , \overline{CP}_1).

Automatic code correction of the counter is provided by an internal circuit: following any illegal code the counter returns to a proper counting mode within 11 clock pulses.

Schmitt-trigger action in the clock input makes the circuit highly tolerant to slower clock rise and fall times.

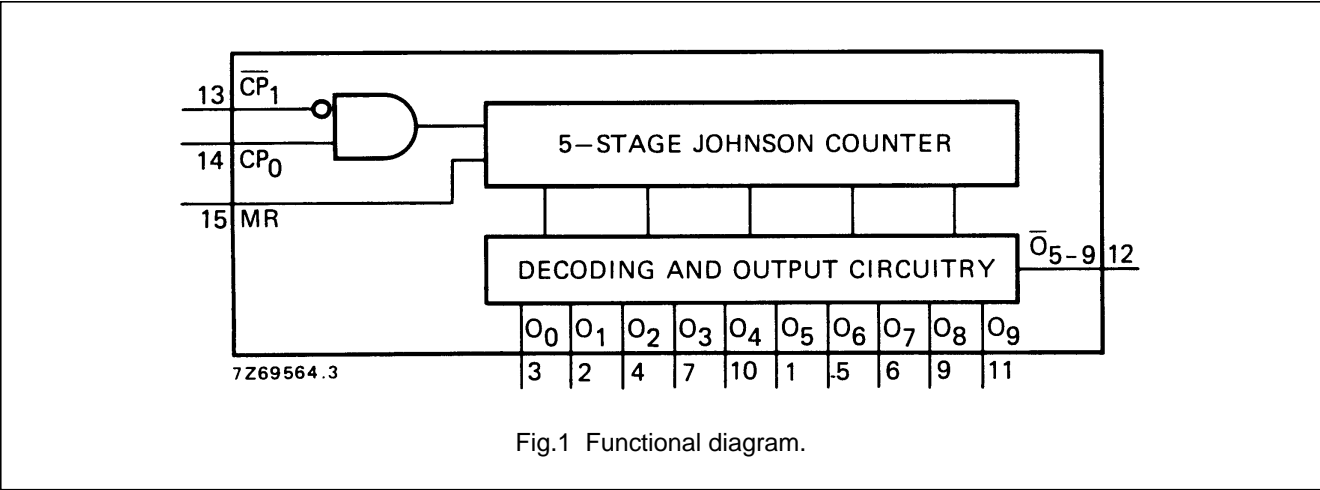


Fig.1 Functional diagram.

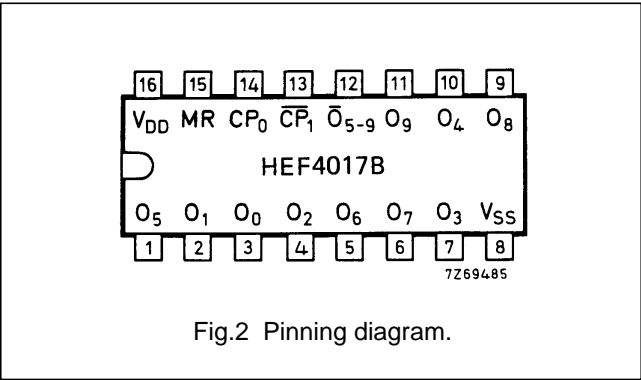


Fig.2 Pinning diagram.

PINNING

- CP₀
- clock input (LOW to HIGH triggered)
- \overline{CP}_1
- clock input (HIGH to LOW triggered)
- MR
- master reset input
- O_0 to O_9
- decoded outputs
- \overline{O}_{5-9}
- carry output (active LOW)

FAMILY DATA, I_{DD} LIMITS category MSI

See Family Specifications

- HEF4017BP(N): 16-lead DIL; plastic (SOT38-1)
- HEF4017BD(F): 16-lead DIL; ceramic (cerdip) (SOT74)
- HEF4017BT(D): 16-lead SO; plastic (SOT109-1)
- (): Package Designator North America

5-stage Johnson counter

HEF4017B
MSI

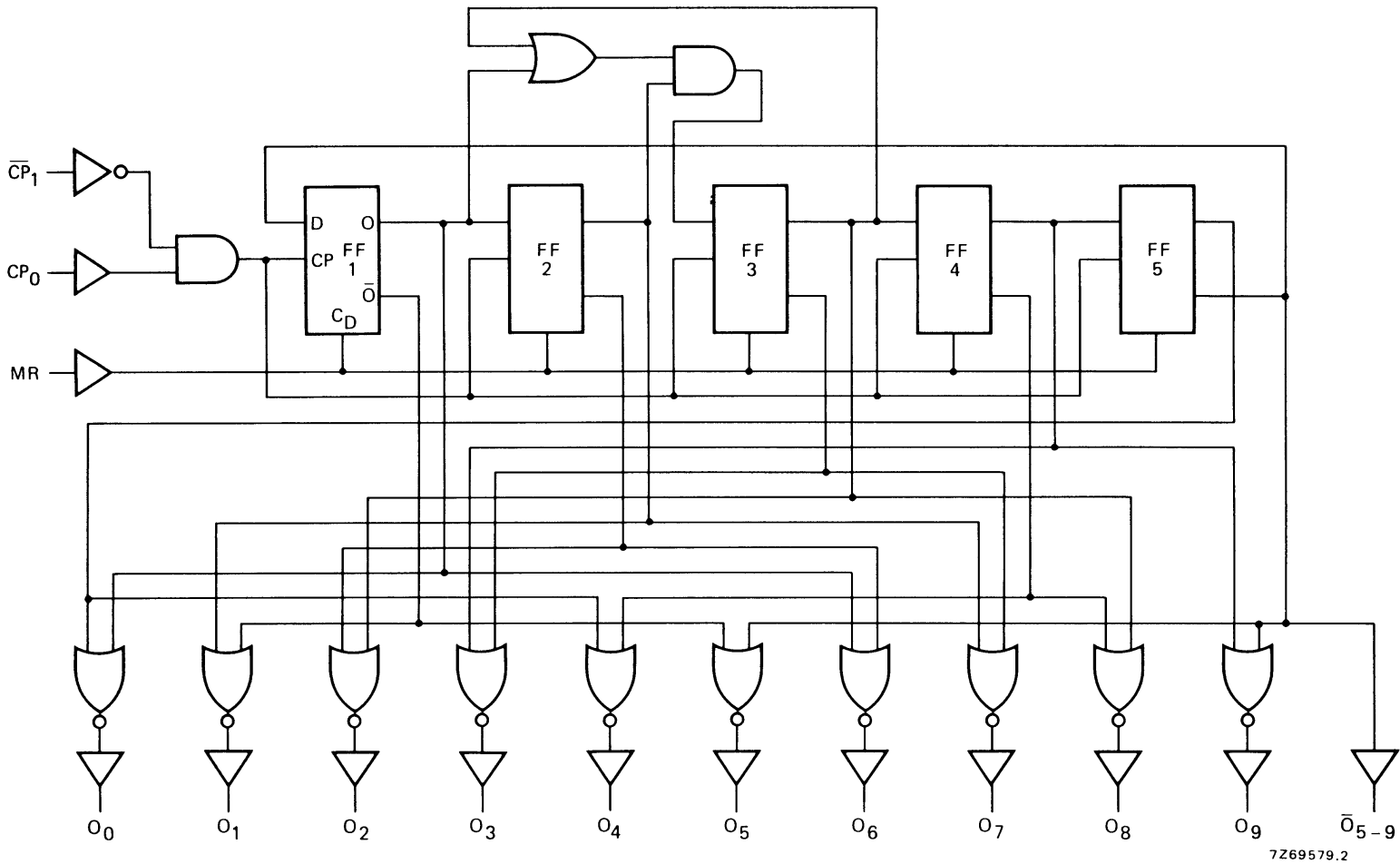






Fig.3 Logic diagram.



5-stage Johnson counter

HEF4017B
MSI

FUNCTION TABLE

MR	CP ₀	$\overline{\text{CP}}_1$	OPERATION
H	X	X	$O_0 = \overline{O}_{5-9} = \text{H}$; O_1 to $O_9 = \text{L}$
L	H		Counter advances
L		L	Counter advances
L	L	X	No change
L	X	H	No change
L	H		No change
L		L	No change

Notes

1. H = HIGH state (the more positive voltage)
2. L = LOW state (the less positive voltage)
3. X = state is immaterial
4.  = positive-going transition
5.  = negative-going transition

AC CHARACTERISTICS

 $V_{\text{SS}} = 0 \text{ V}$; $T_{\text{amb}} = 25 \text{ }^\circ\text{C}$; $C_L = 50 \text{ pF}$; input transition times $\leq 20 \text{ ns}$

	V _{DD} V	SYMBOL	MIN.	TYP.	MAX.	TYPICAL EXTRAPOLATION FORMULA	
Propagation delays							
CP ₀ , $\overline{\text{CP}}_1 \rightarrow \text{O}_0$ to O ₉	5	t _{PHL}		140	280	ns	113 ns + (0,55 ns/pF) C _L
HIGH to LOW	10			55	110	ns	44 ns + (0,23 ns/pF) C _L
	15			40	80	ns	32 ns + (0,16 ns/pF) C _L
LOW to HIGH	5	t _{PLH}		125	250	ns	98 ns + (0,55 ns/pF) C _L
	10			50	100	ns	39 ns + (0,23 ns/pF) C _L
	15			40	80	ns	32 ns + (0,16 ns/pF) C _L
CP ₀ , $\overline{\text{CP}}_1 \rightarrow \overline{\text{O}}_{5-9}$	5	t _{PHL}		145	290	ns	118 ns + (0,55 ns/pF) C _L
HIGH to LOW	10			55	110	ns	44 ns + (0,23 ns/pF) C _L
	15			40	80	ns	32 ns + (0,16 ns/pF) C _L
LOW to HIGH	5	t _{PLH}		125	250	ns	98 ns + (0,55 ns/pF) C _L
	10			50	100	ns	39 ns + (0,23 ns/pF) C _L
	15			40	80	ns	32 ns + (0,16 ns/pF) C _L
MR → O ₁ to O ₉	5	t _{PHL}		115	230	ns	88 ns + (0,55 ns/pF) C _L
HIGH to LOW	10			50	100	ns	39 ns + (0,23 ns/pF) C _L
	15			35	70	ns	27 ns + (0,16 ns/pF) C _L
MR → $\overline{\text{O}}_{5-9}$	5	t _{PLH}		110	220	ns	83 ns + (0,55 ns/pF) C _L
LOW to HIGH	10			45	90	ns	34 ns + (0,23 ns/pF) C _L
	15			35	70	ns	27 ns + (0,16 ns/pF) C _L
MR → O ₀	5	t _{PLH}		130	260	ns	103 ns + (0,55 ns/pF) C _L
LOW to HIGH	10			55	105	ns	44 ns + (0,23 ns/pF) C _L
	15			40	75	ns	32 ns + (0,16 ns/pF) C _L

5-stage Johnson counter

HEF4017B
MSI

	V _{DD} V	SYMBOL	MIN.	TYP.	MAX.	TYPICAL EXTRAPOLATION FORMULA	
Output transition times	5			60	120	ns	10 ns + (1,0 ns/pF) C _L
HIGH to LOW	10	t _{THL}		30	60	ns	9 ns + (0,42 ns/pF) C _L
	15			20	40	ns	6 ns + (0,28 ns/pF) C _L
LOW to HIGH	5			60	120	ns	10 ns + (1,0 ns/pF) C _L
	10	t _{TLH}		30	60	ns	9 ns + (0,42 ns/pF) C _L
	15			20	40	ns	6 ns + (0,28 ns/pF) C _L

AC CHARACTERISTICS

V_{SS} = 0 V; T_{amb} = 25 °C; C_L = 50 pF; input transition times ≤ 20 ns

	V _{DD} V	SYMBOL	MIN.	TYP.	MAX.	
Hold times	5		90	45	ns	see also waveforms Figs 4 and 5
CP ₀ → $\overline{\text{CP}}_1$	10	t _{hold}	40	20	ns	
	15		20	10	ns	
$\overline{\text{CP}}_1$ → CP ₀	5		80	40	ns	
	10	t _{hold}	40	20	ns	
	15		30	10	ns	
Minimum clock pulse width:	5		80	40	ns	
CP ₀ = LOW;	10	t _{WCPL} =	40	20	ns	
$\overline{\text{CP}}_1$ = HIGH	15	t _{WCPH}	30	15	ns	
Minimum MR pulse width; HIGH	5		50	25	ns	
	10	t _{WMRH}	30	15	ns	
	15		20	10	ns	
Recovery time for MR	5		60	30	ns	
	10	t _{RMR}	30	15	ns	
	15		20	10	ns	
Maximum clock pulse frequency	5		6	12	MHz	
	10	f _{max}	12	24	MHz	
	15		15	30	MHz	

	V _{DD} V	TYPICAL FORMULA FOR P (μW)	
Dynamic power dissipation per package (P)	5	500 f _i + Σ (f _o C _L) × V _{DD} ²	where f _i = input freq. (MHz) f _o = output freq. (MHz) C _L = load cap. (pF) Σ (f _o C _L) = sum of outputs V _{DD} = supply voltage (V)
	10	2200 f _i + Σ (f _o C _L) × V _{DD} ²	
	15	6000 f _i + Σ (f _o C _L) × V _{DD} ²	

5-stage Johnson counter

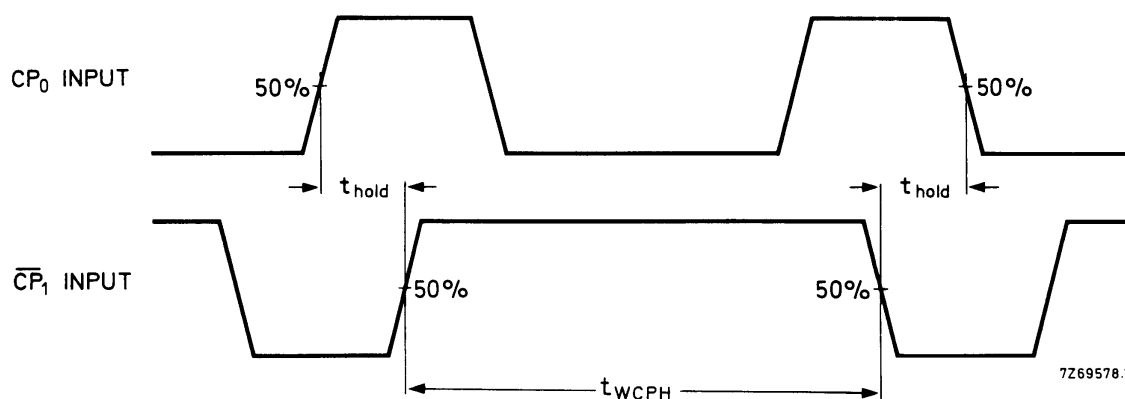
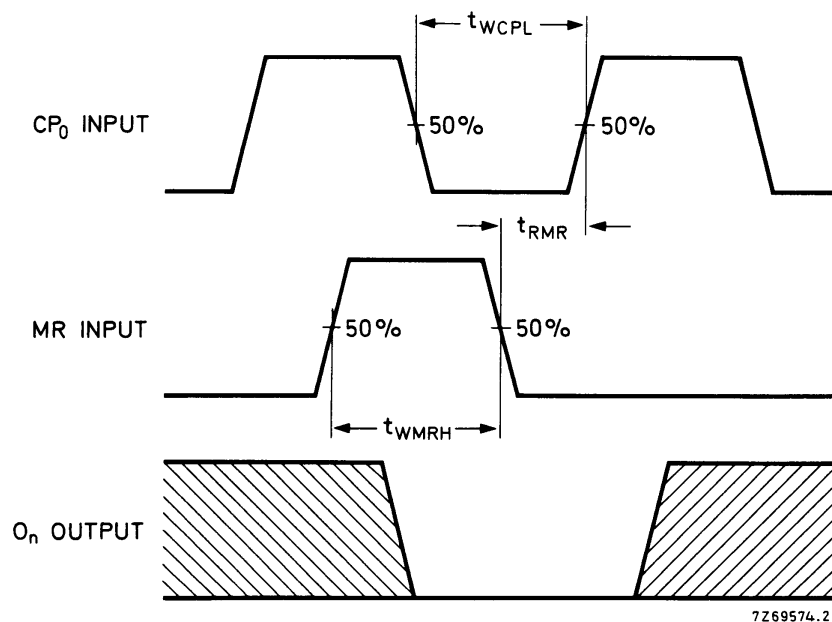
HEF4017B
MSI

Fig.4 Waveforms showing hold times for CP_0 to \overline{CP}_1 and \overline{CP}_1 to CP_0 . Hold times are shown as positive values, but may be specified as negative values.



Conditions: $\overline{CP}_1 = \text{LOW}$ while CP_0 is triggered on a LOW to HIGH transition. t_{WCP} and t_{RMR} also apply when $CP_0 = \text{HIGH}$ and CP_1 is triggered on a HIGH to LOW transition.

Fig.5 Waveforms showing recovery time for MR; minimum CP_0 and MR pulse widths.

5-stage Johnson counter

HEF4017B
MSI

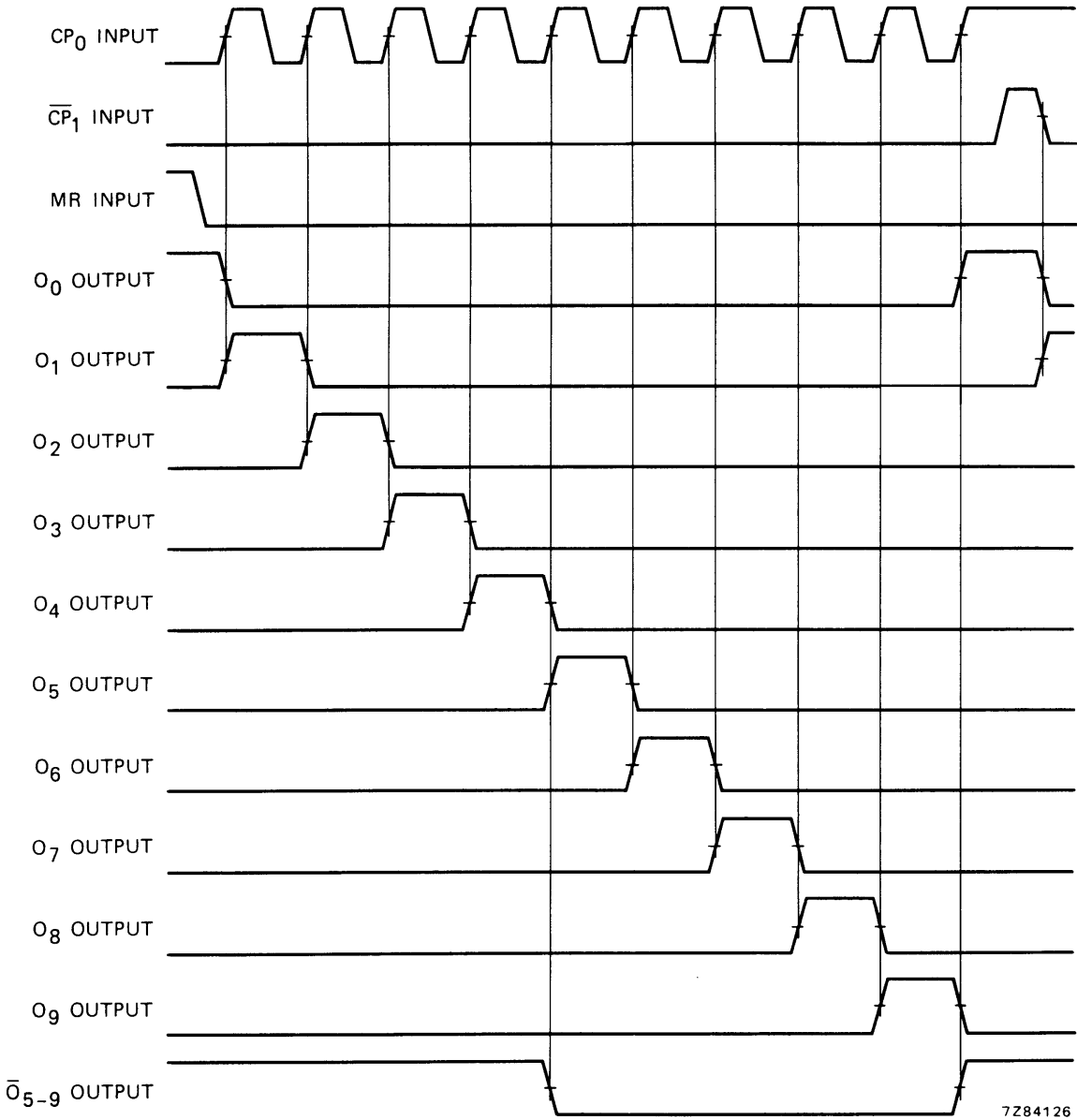


Fig.6 Timing diagram.

5-stage Johnson counter

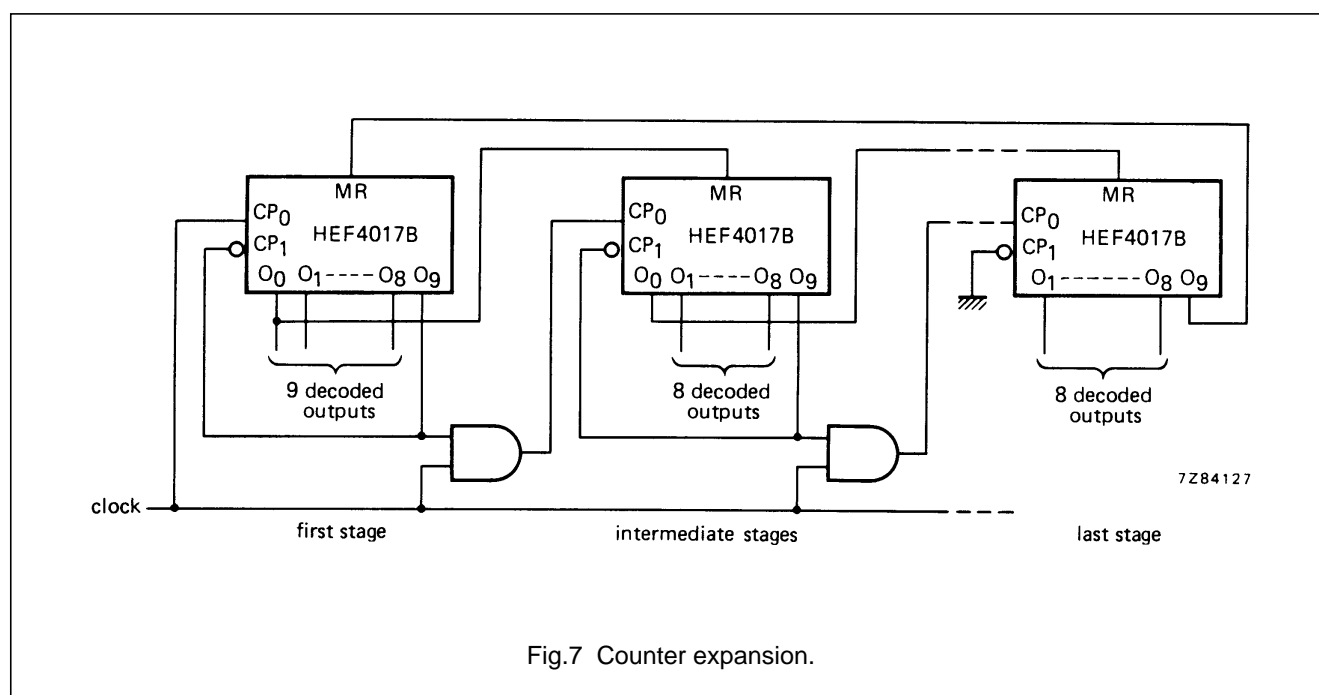
HEF4017B
MSI

APPLICATION INFORMATION

Some examples of applications for the HEF4017B are:

- Decade counter with decimal decoding
- 1 out of n decoding counter (when cascaded)
- Sequential controller
- Timer.

Figure 7 shows a technique for extending the number of decoded output states for the HEF4017B. Decoded outputs are sequential within each stage and from stage to stage, with no dead time (except propagation delay).



Note

It is essential not to enable the counter on $\overline{CP_1}$ when CP_0 is HIGH, or on CP_0 when $\overline{CP_1}$ is LOW, as this would cause an extra count.